NEW REDUCED ORDER MODELS FOR REAL-TIME DATA ASSIMILATION USING FEW SENSORS

A. Moneyron, P. Jacquet, G. Le Pape, M. Ladvig,A. M. Picard, V. Resseguier,D. Heitz and G. Stabile





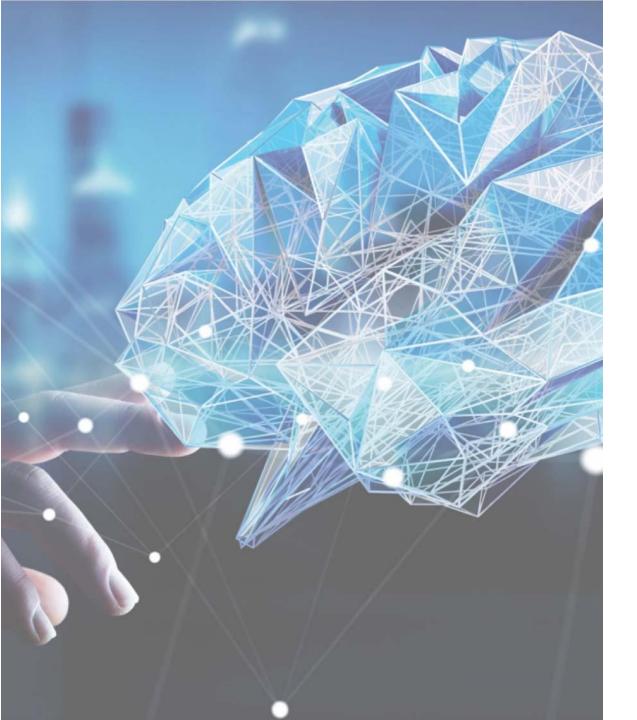
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CONTENT

- 1. Context : observer for unsteady aerodynamism
- 2. Physics, data & reduced order model (ROM)
- 3. Simulation, measurements & data assimilation
- Reduced order model under location uncertainty
 Results



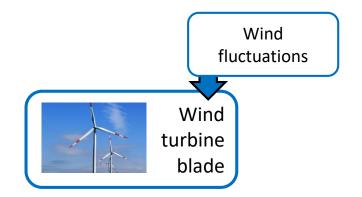
PART I

CONTEXT : OBSERVER FOR UNSTEADY AERODYNAMISM

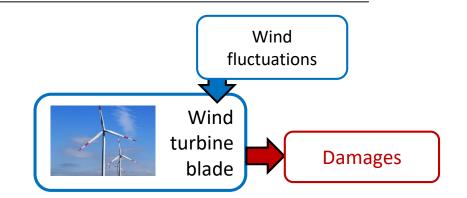
CONTEXT Observer for unsteady aerodynamism



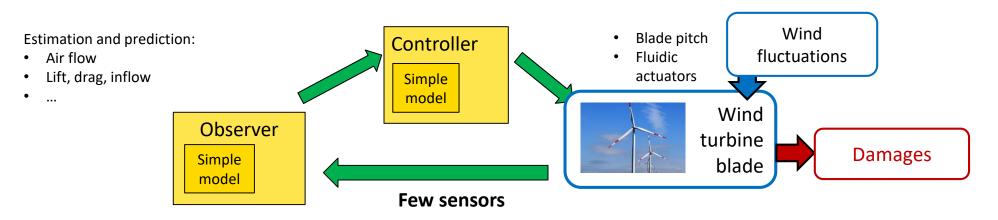
CONTEXT Observer for unsteady aerodynamism



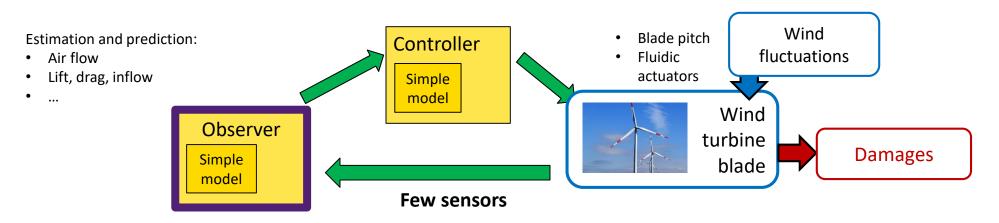
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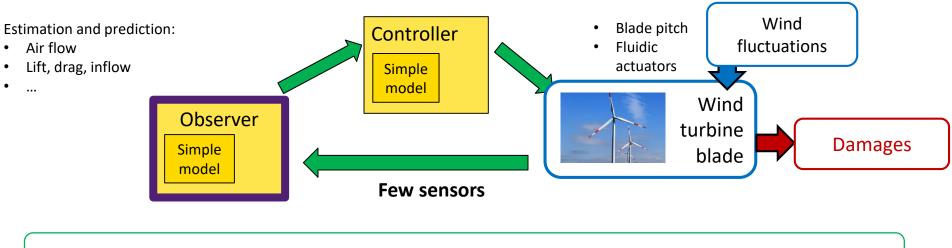


CONTEXT Observer for unsteady aerodynamism



CONTEXT Observer for unsteady aerodynamism

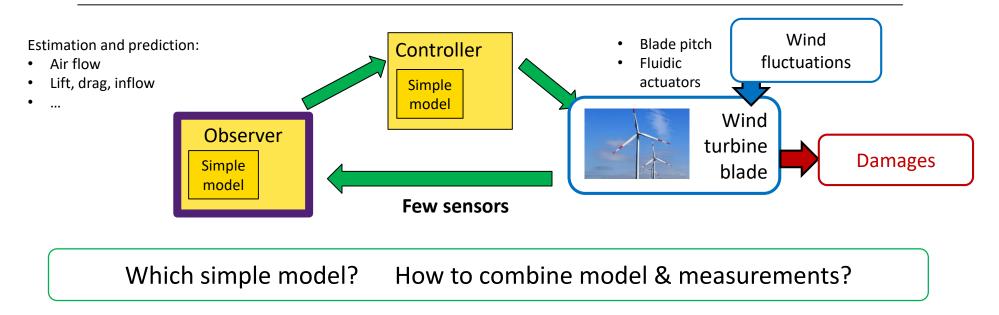
Application: Real-time estimation and prediction of 3D fluid flow using strongly-limited computational resources & few sensors



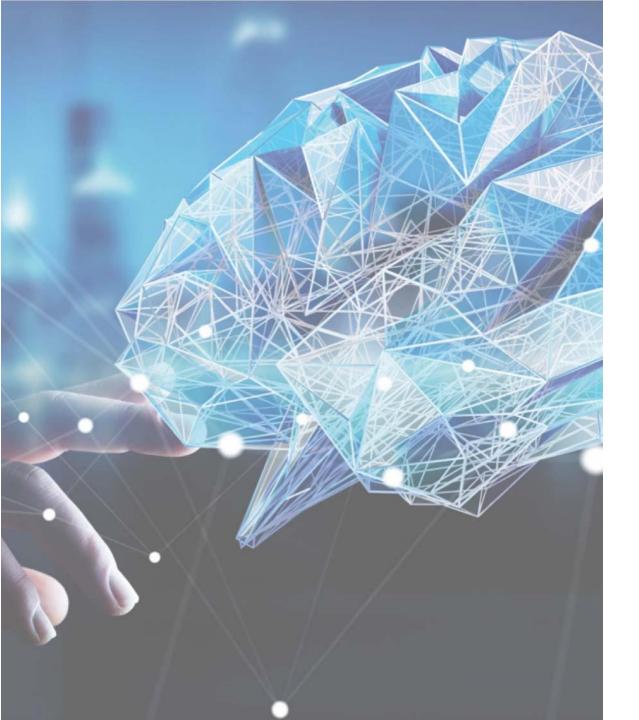
Which simple model? How to combine model & measurements?

CONTEXT Observer for unsteady aerodynamism

Application: Real-time estimation and prediction of 3D fluid flow using strongly-limited computational resources & few sensors



Scientific problem : Simulation & data assimilation under severe dimensional reduction typically, $10^7 \rightarrow O(10)$ degrees of freedom

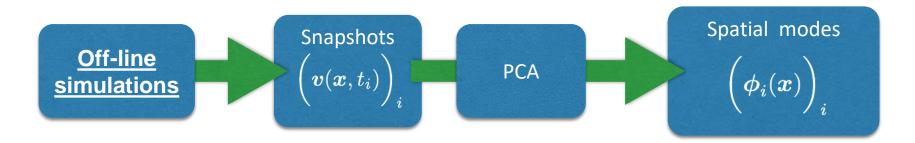


PART II

PHYSICS, DATA & REDUCED ORDER MODEL

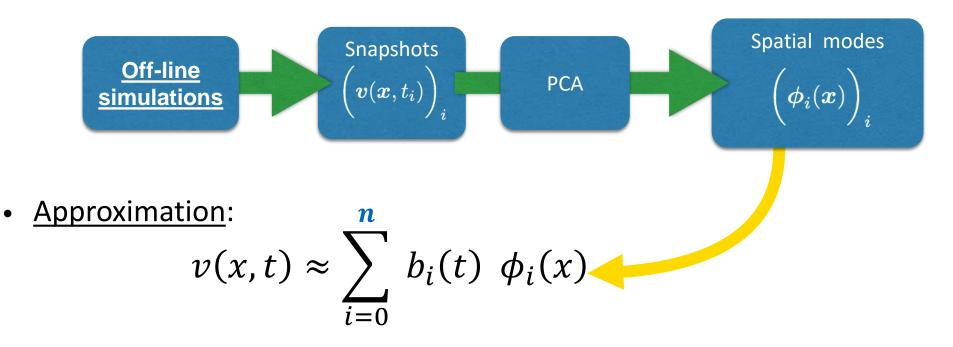


• <u>Principal Component Analysis (PCA)</u> on a *dataset* to reduce the dimensionality:

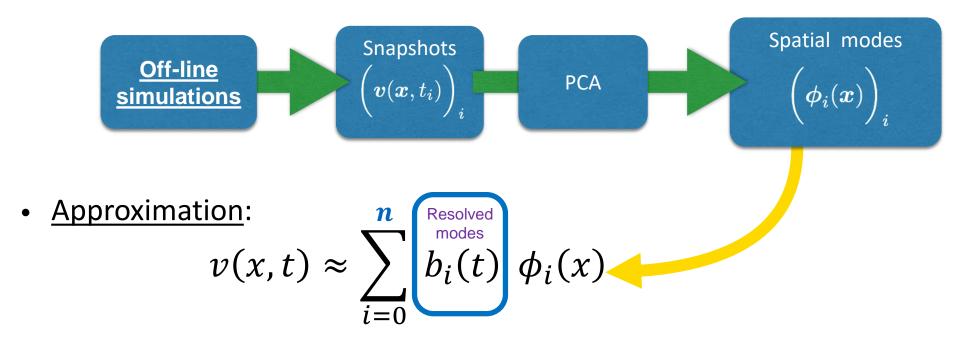


• <u>Approximation</u>: $v(x,t) \approx \sum_{i=0}^{n} b_i(t) \phi_i(x)$

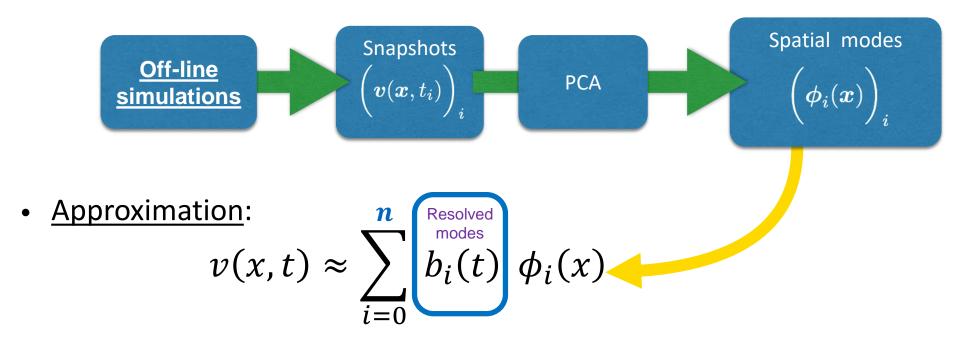




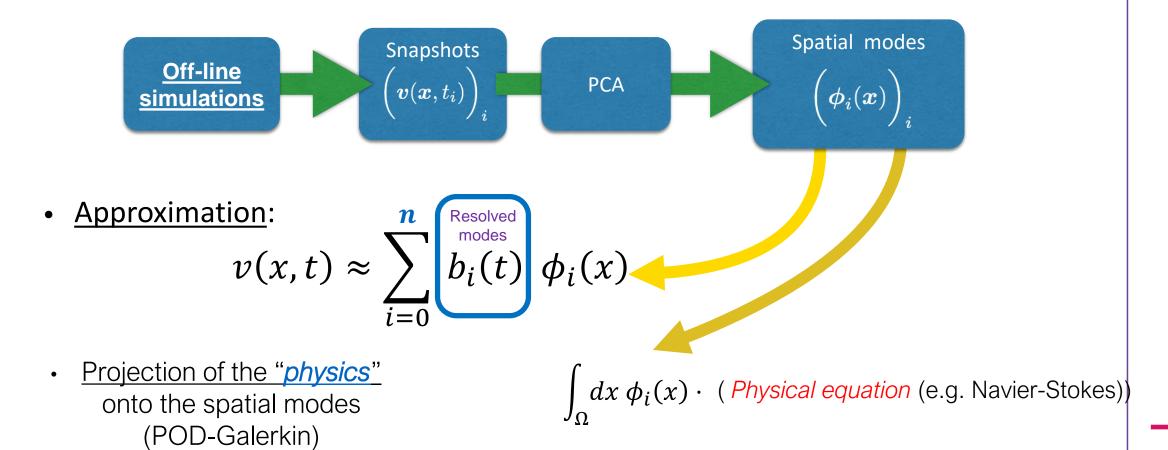




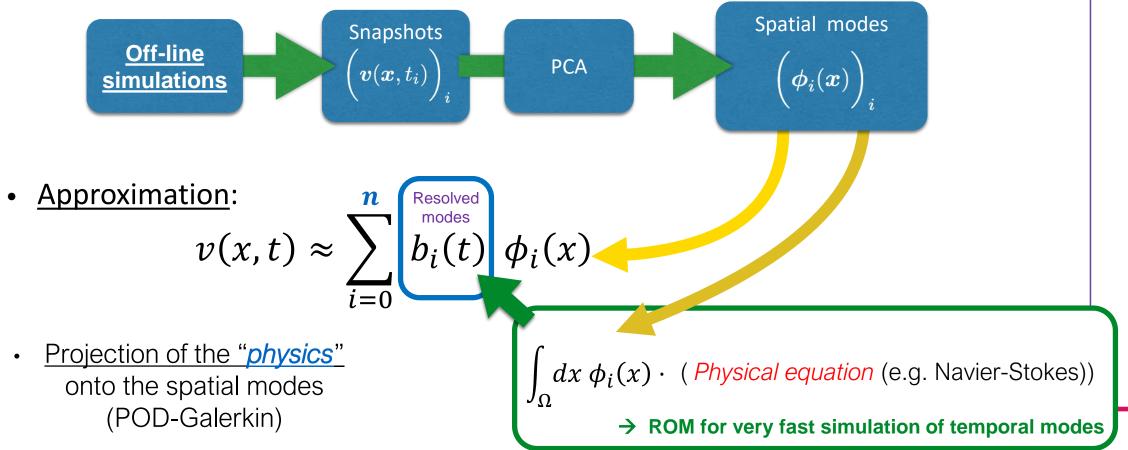




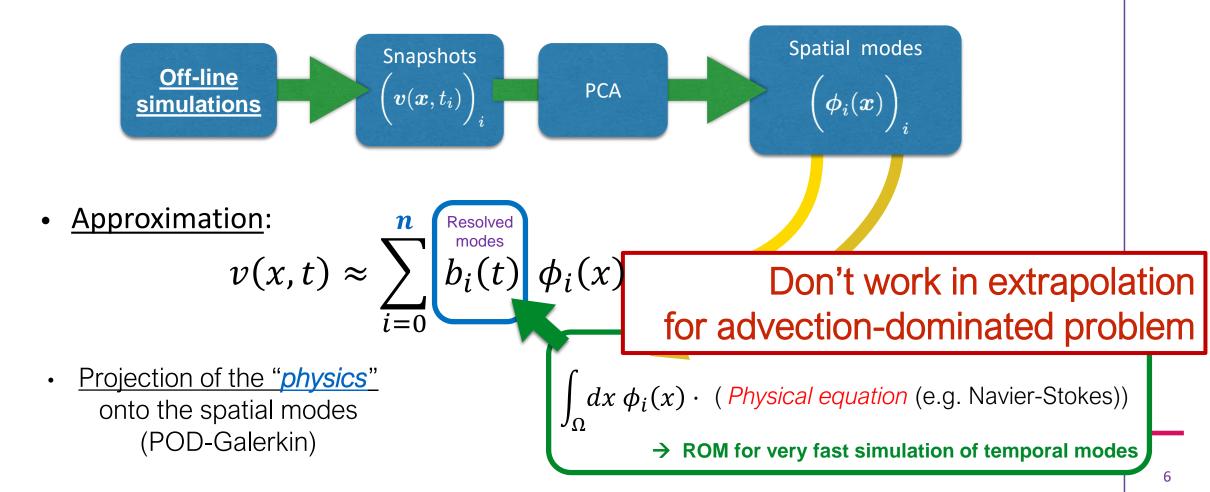




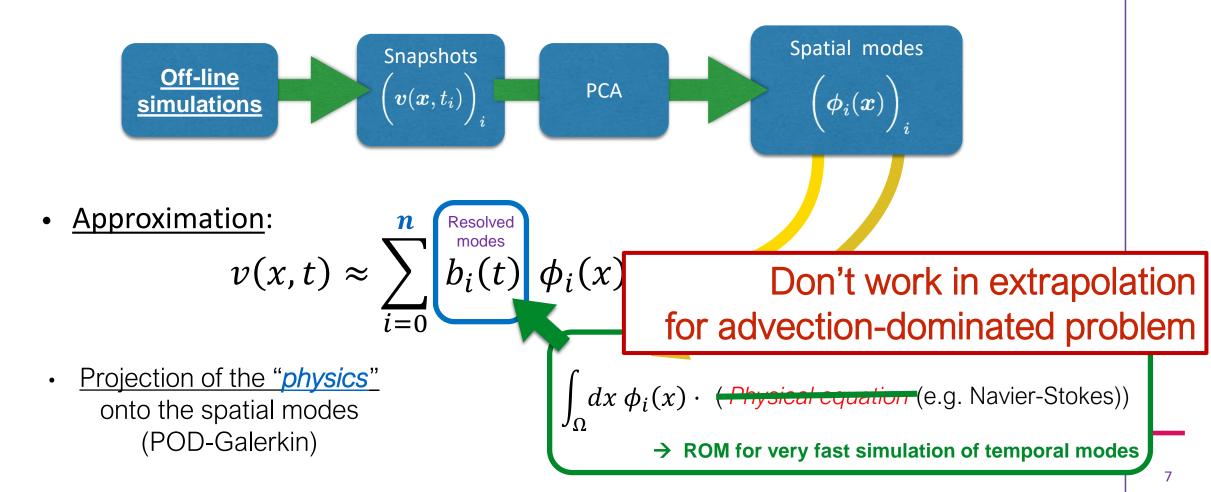




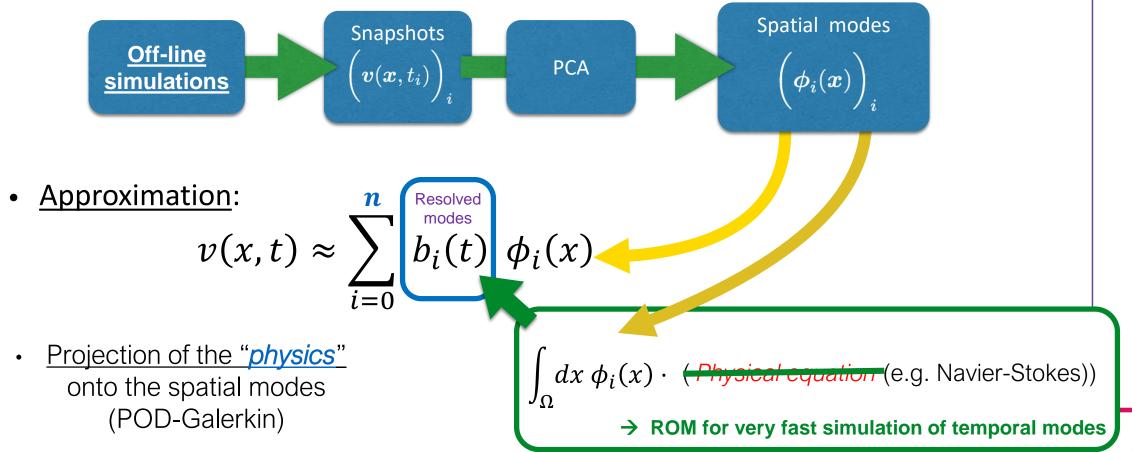




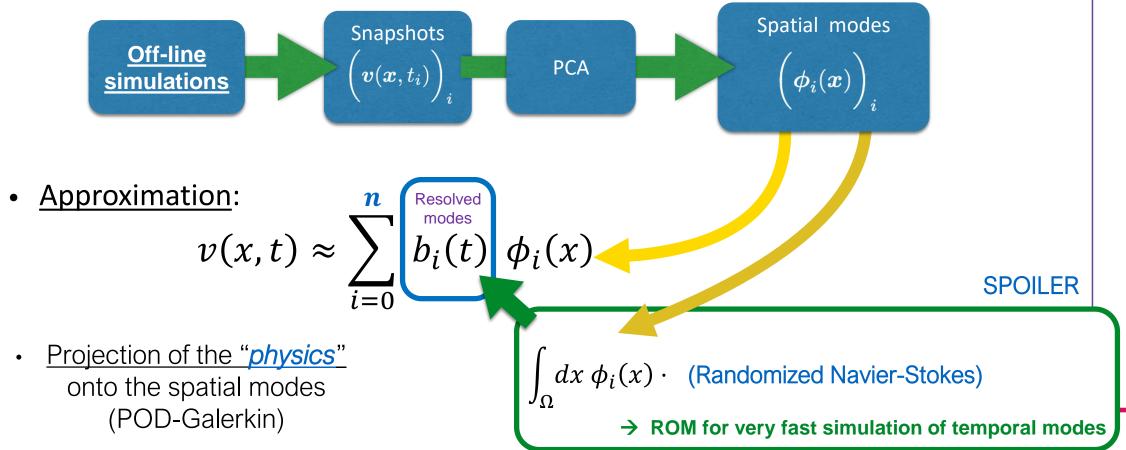


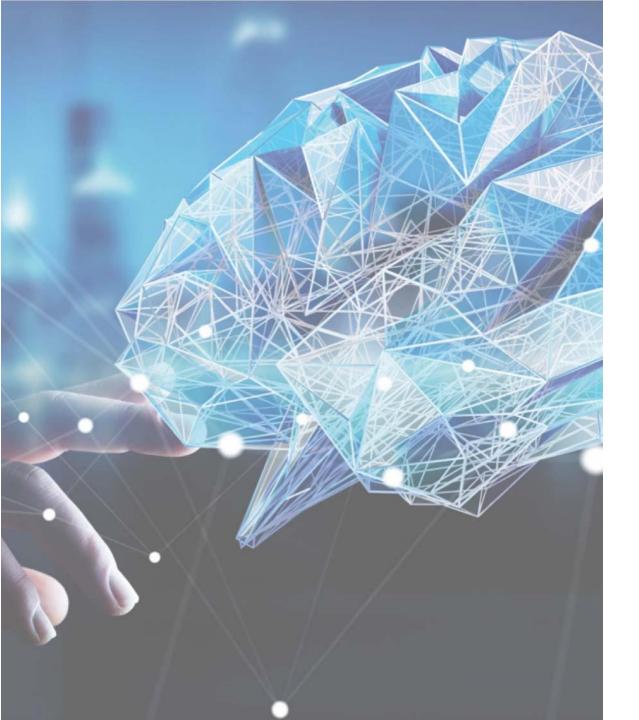












PART III

SIMULATION, MEASUREMENTS & DATA ASSIMILATION

= Coupling simulations and measurements y

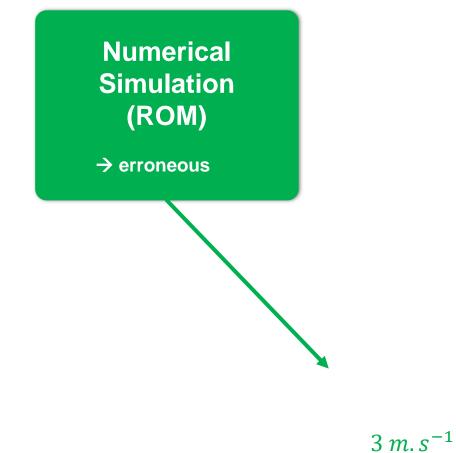


On-line measurements

→ incomplete
→ possibly noisy



= Coupling simulations and measurements y

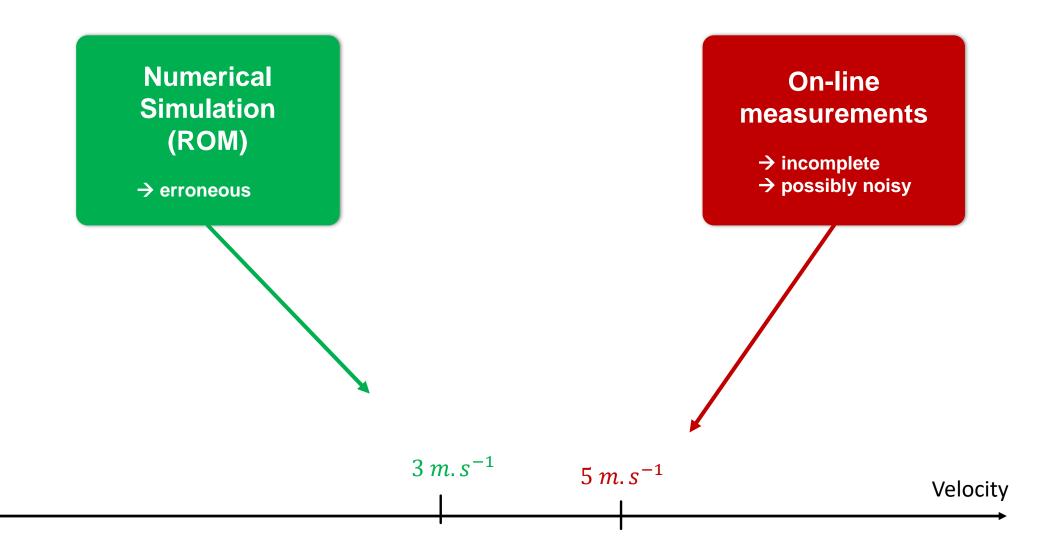




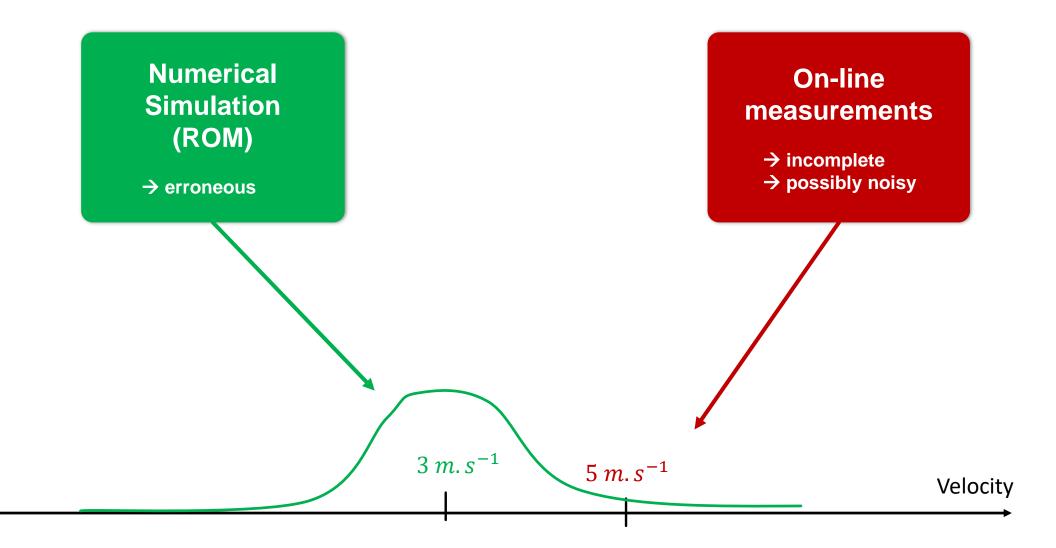
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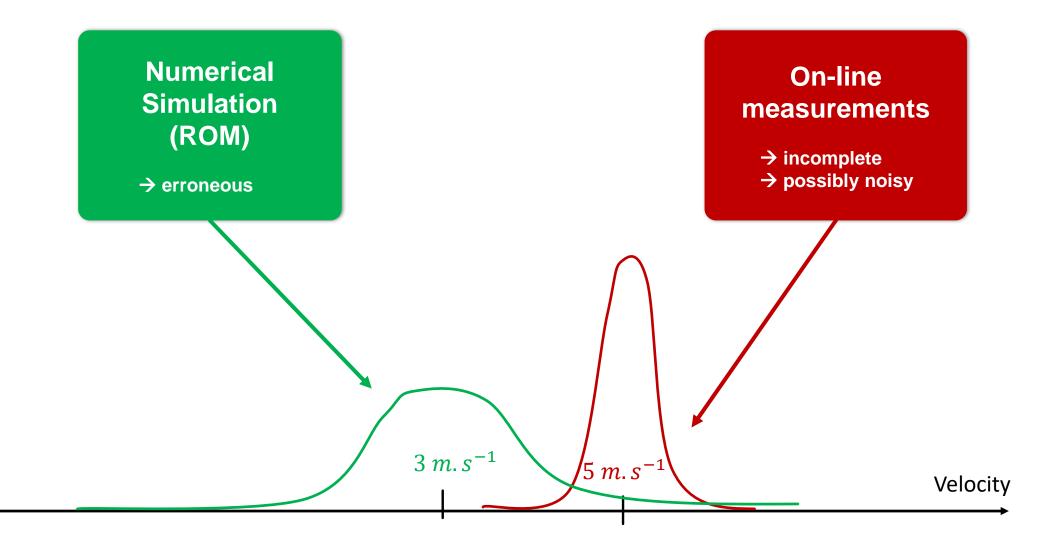


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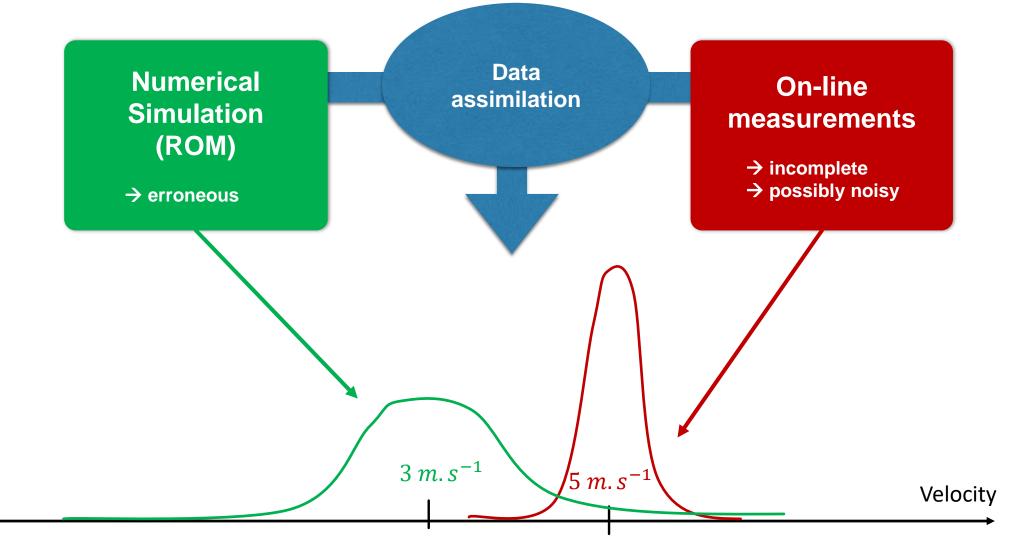


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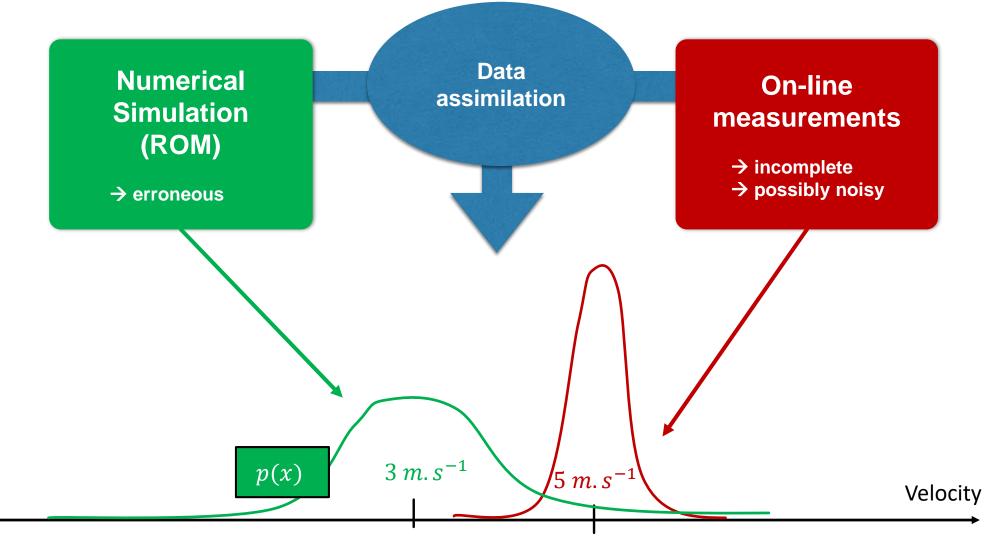
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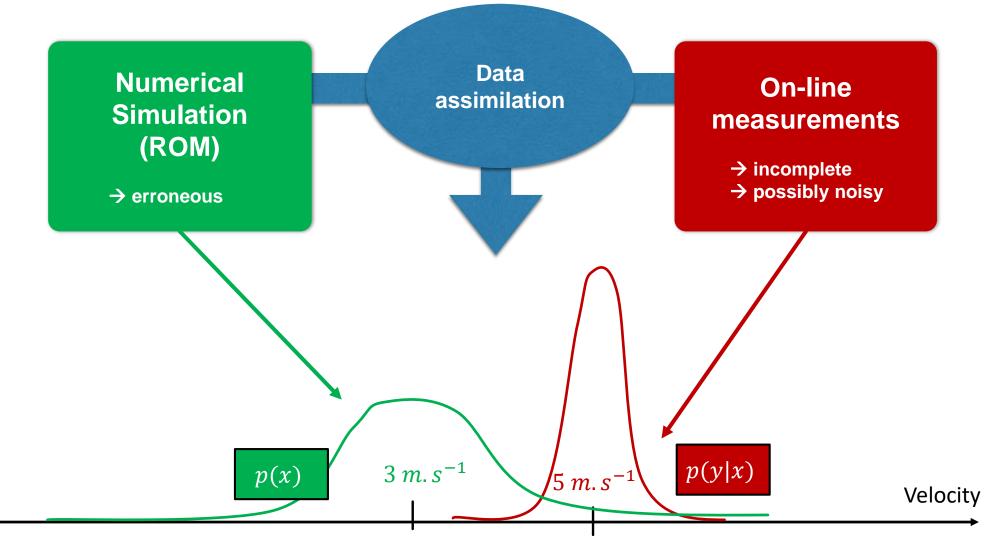
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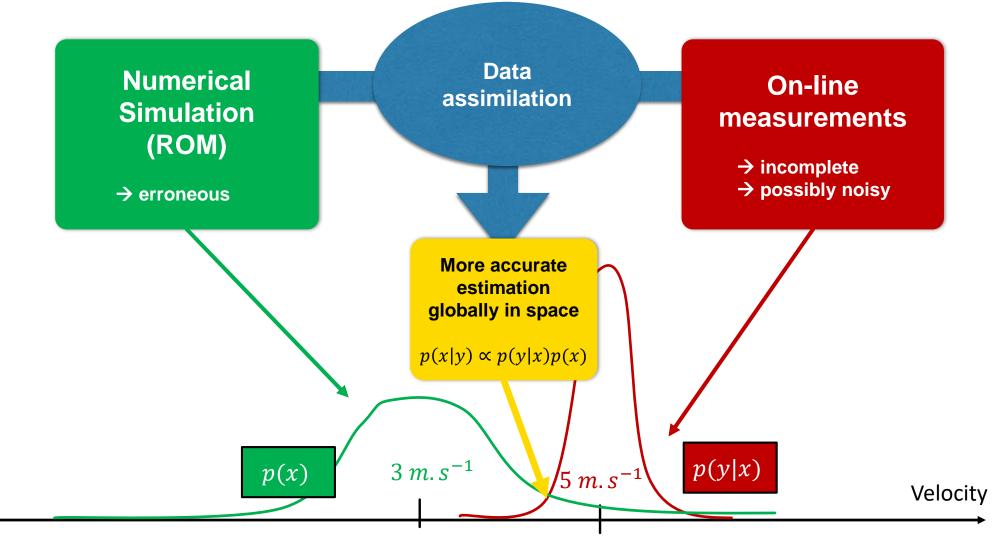


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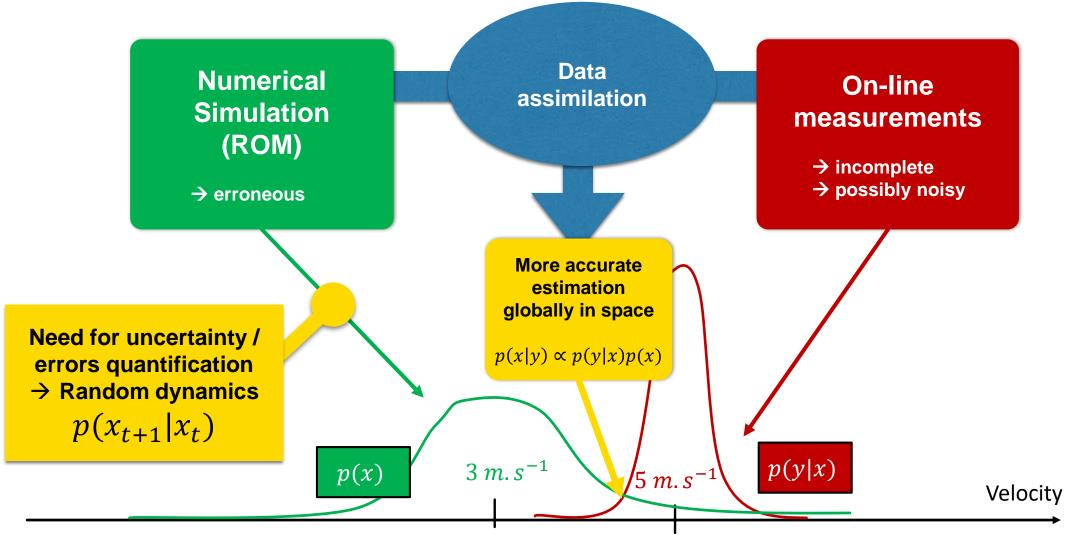
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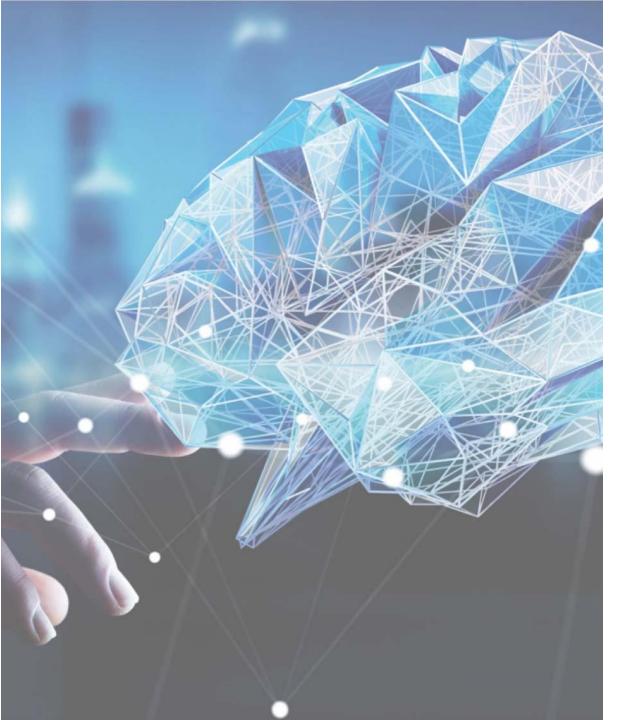
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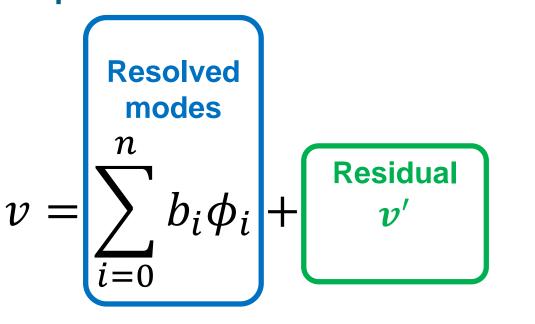




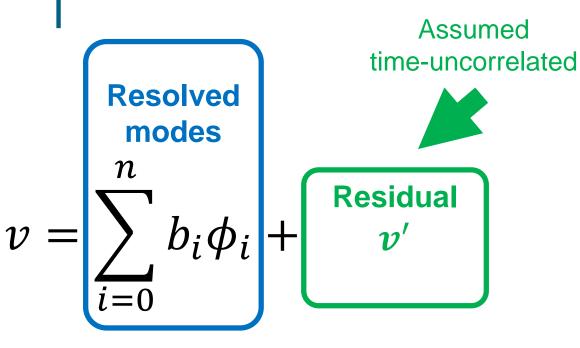
PART IV

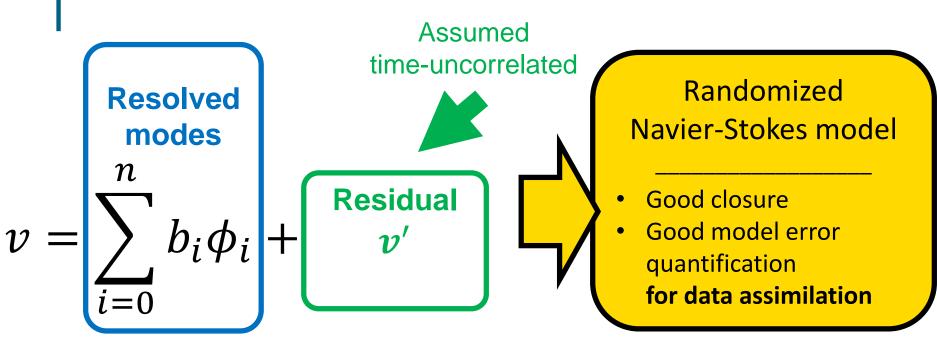
REDUCED ORDER MODELS UNDER LOCATION UNCERTAINTY

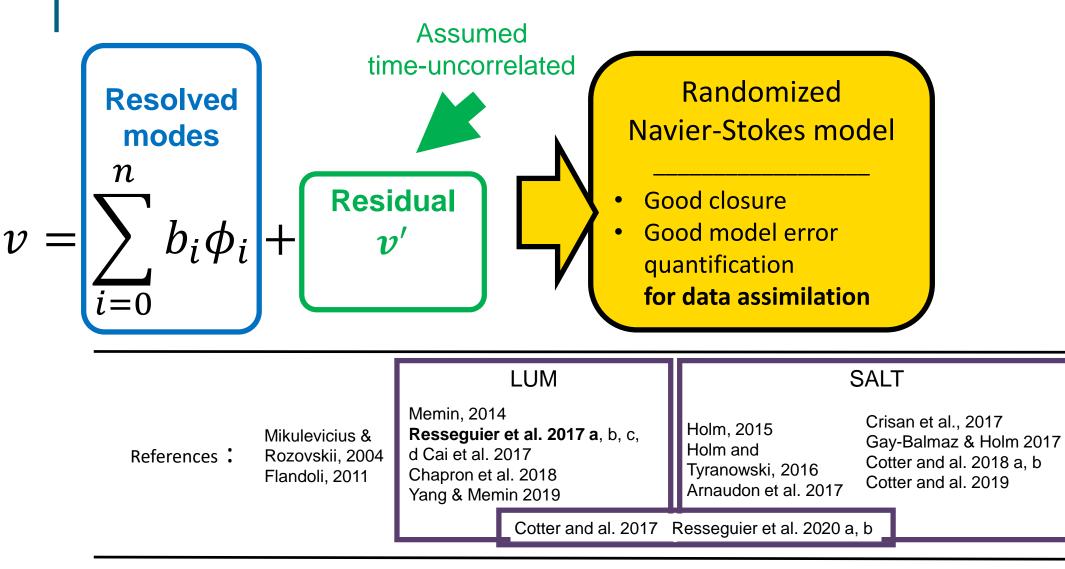
LOCATION UNCERTAINTY MODELS (LUM)



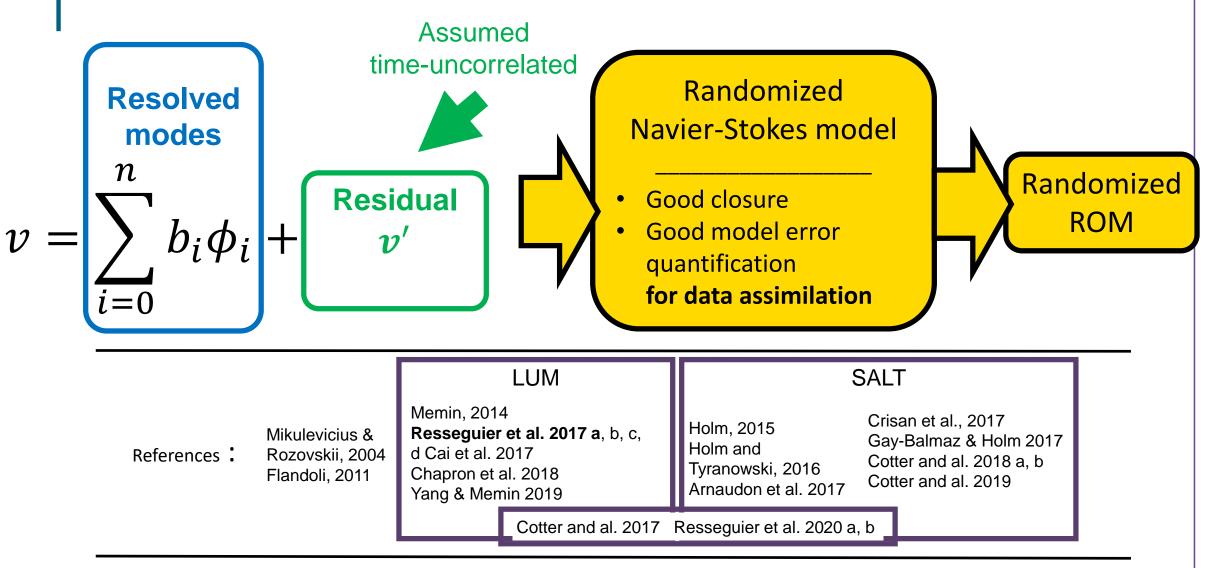
LOCATION UNCERTAINTY MODELS (LUM)

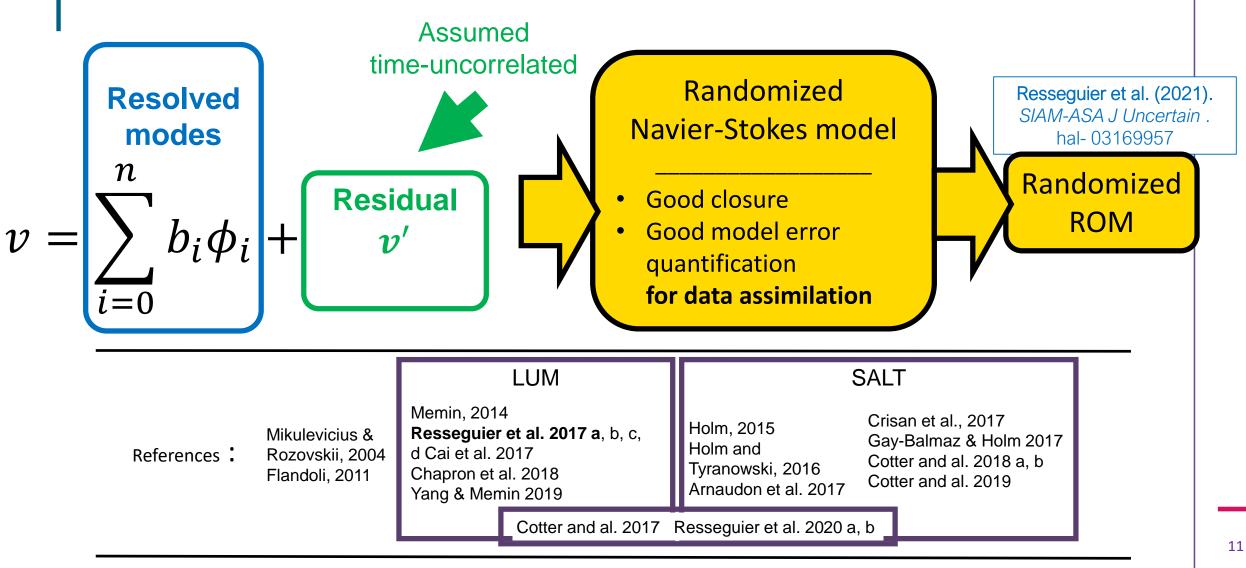


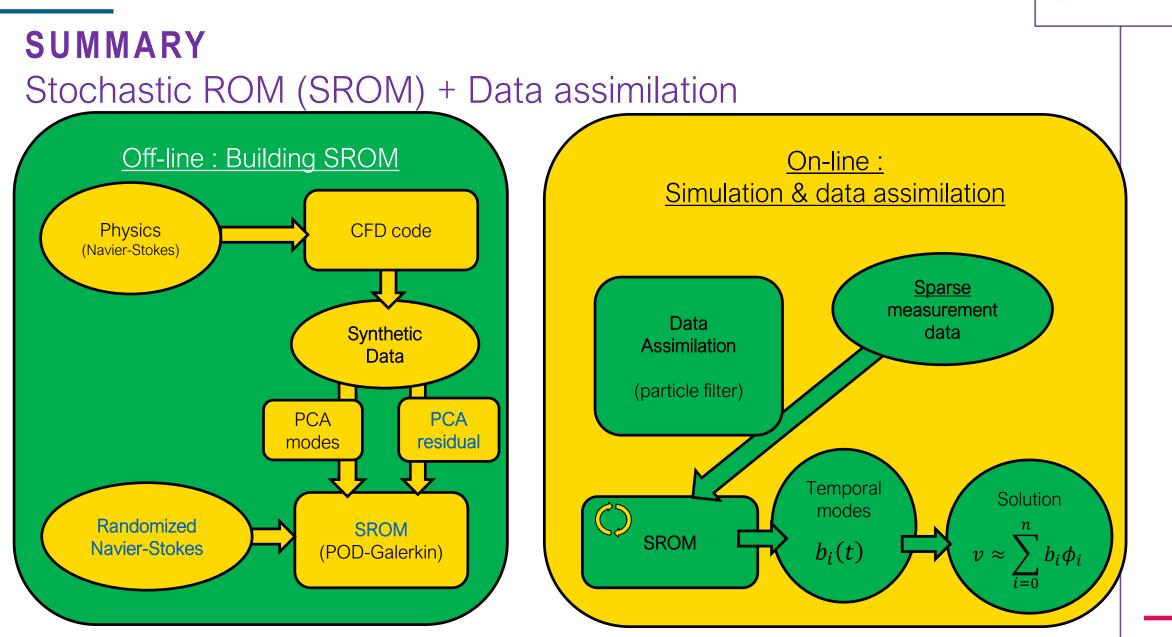




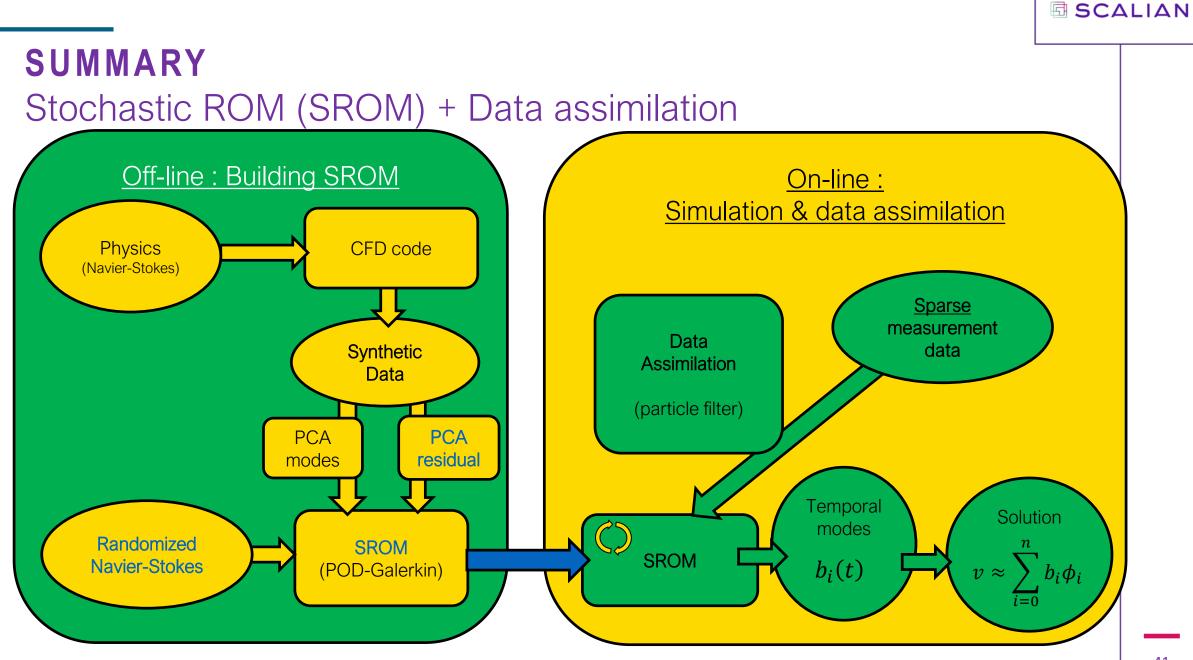
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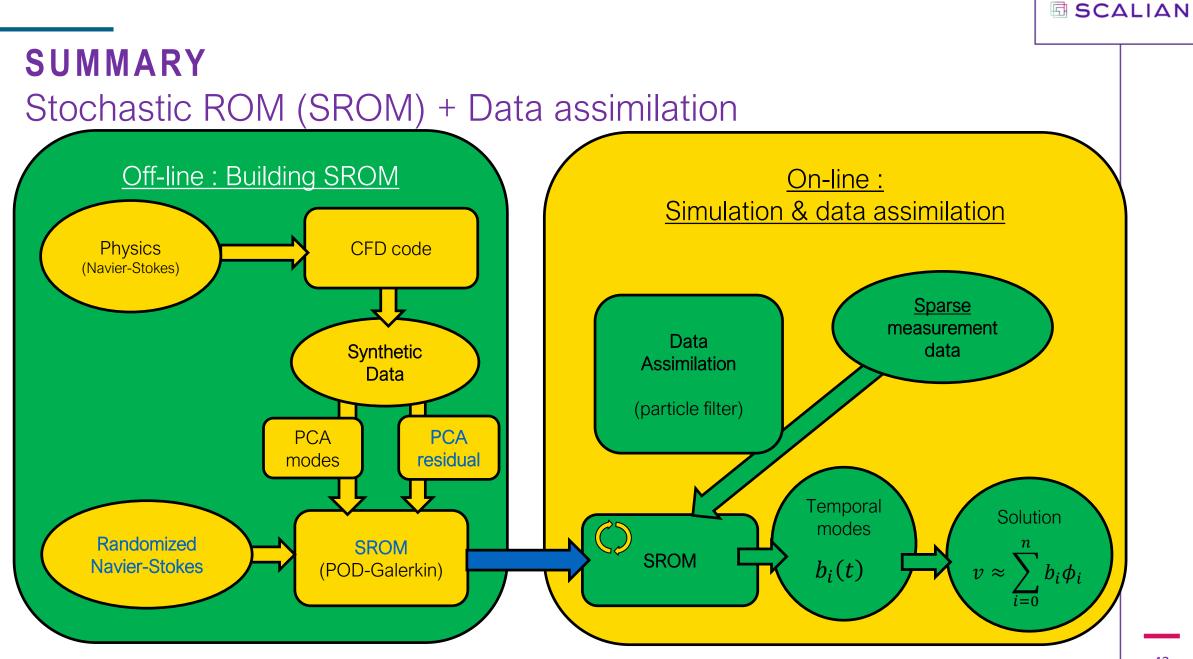


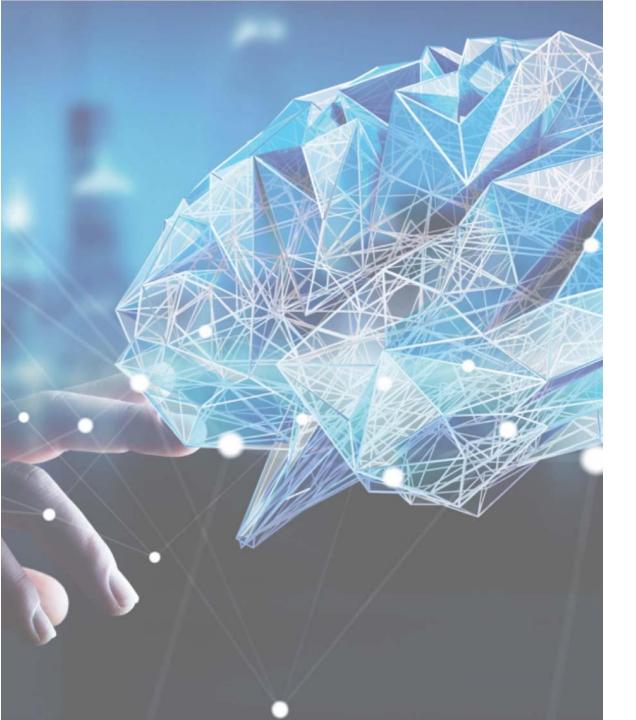


Resseguier et al. (2022). J Comp. Phys . hal-03445455



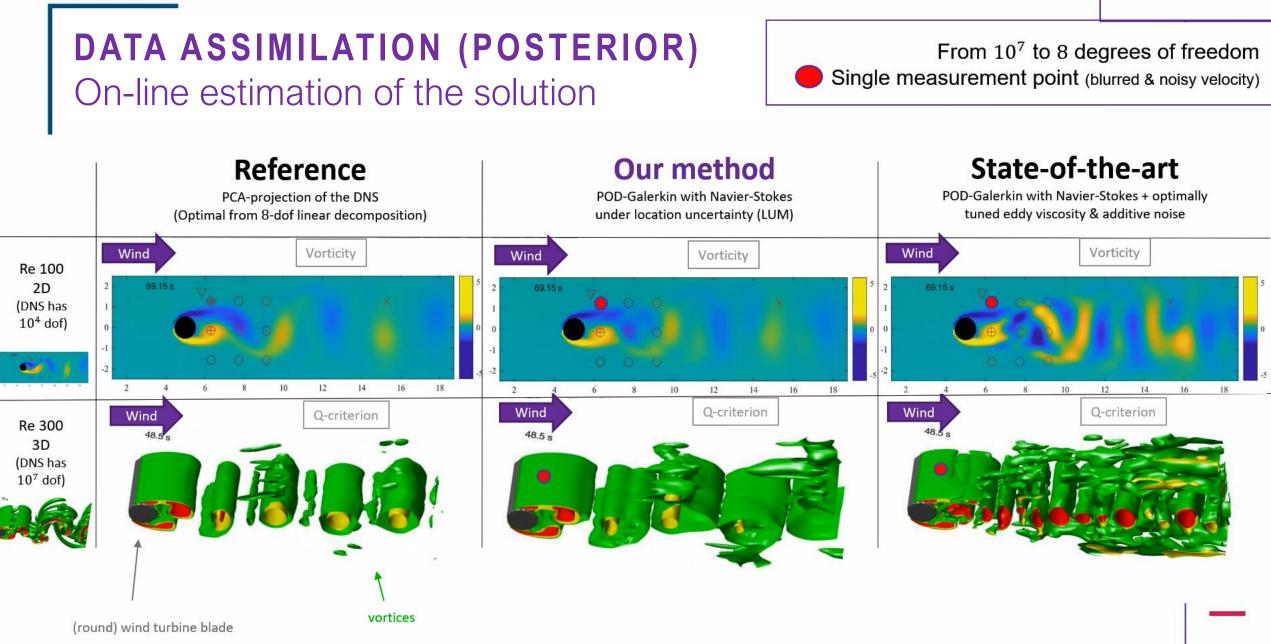
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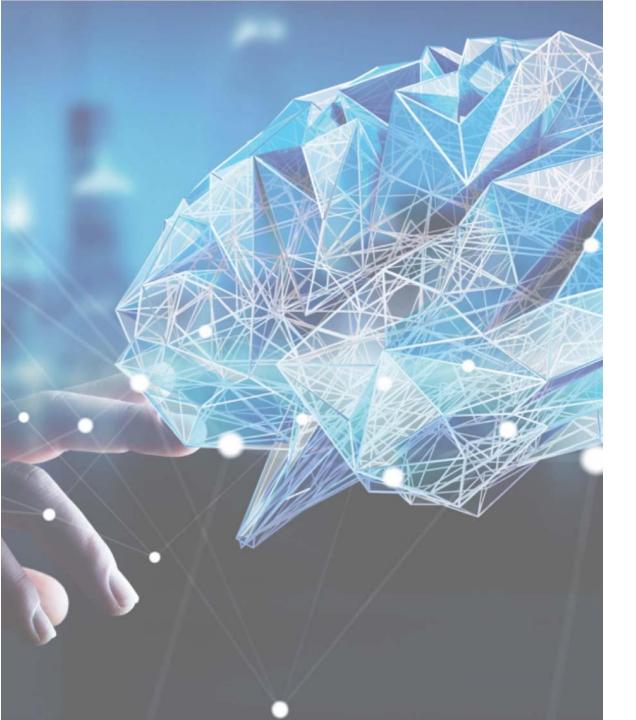




PART V

RESULTS : UQ & FAST OBSERVER OF THE FLOW





CONCLUSION

20/10/2022

Présentation ...

CONCLUSION

- ▶ Reduced order model (ROM) : for very fast and robust CFD $(10^7 \rightarrow 8 \text{ degrees of freedom.})$
 - Combine data & physics (built off-line)
 Now implemented in OpenFOAM / ITHACA-FV
 - Closure problem handled by LUM
- Data assimilation : to correct the fast simulation on-line by incomplete/noisy measurements
 - Model error quantification handled by LUM
- First results
 - Optimal unsteady 3D flow estimation/prediction in the whole spatial domain (large-scale structures)
 - Robust far outside the training set (time extrapolation / out of sample)

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WORK IN PROGRESS:

- Increasing Reynolds (ROM of LES, DDES)
 - Hyperreduction (=interpolation with a POD basis) of turbulence model terms

