



**HAL**  
open science

# ON THE DYNAMICS OF SHALLOW ICE SHEETS. MODELLING AND ANALYSIS

Paolo Piersanti, Roger Temam

► **To cite this version:**

Paolo Piersanti, Roger Temam. ON THE DYNAMICS OF SHALLOW ICE SHEETS. MODELLING AND ANALYSIS. 2022. hal-03613966

**HAL Id: hal-03613966**

**<https://hal.science/hal-03613966>**

Preprint submitted on 19 Mar 2022

**HAL** is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

# ON THE DYNAMICS OF SHALLOW ICE SHEETS. MODELLING AND ANALYSIS.

PAOLO PIERSANTI AND ROGER TEMAM

ABSTRACT. In this paper we formulate a model describing the evolution of thickness of a shallow ice sheet. The thickness of the ice sheet is constrained to be nonnegative. This renders the problem under consideration an obstacle problem. A rigorous analysis shows that the model is thus governed by a set of variational inequalities that involve nonlinearities in the time derivative and in the elliptic term, and that it admits solutions, whose existence is established by means of a semi-discrete scheme and the penalty method.

## CONTENTS

1. Introduction	1
2. Analytical notation and formal derivation of the model	2
3. Weak formulation of the unilateral boundary value problem	8
4. Existence of weak solutions and variational formulation for Problem (2.33)	15
Conclusions	34
Acknowledgements	35
References	35

## 1. INTRODUCTION

The study of ice sheets melting and its correlation with the global warming problem has been attracting the interest of experts from all over the branches of science. The mathematical literature related to ice sheets and glaciers is vast and abundant; in this direction we mention, for instance, the papers [25, 26, 28, 29, 34, 41, 42], and the celebrated article by W.D. Hibler [23] to which we refer later on. The existence of solutions to Hibler's model has recently been established by Titi and his associates in the pre-print [33] and by Brandt and his associates in the pre-print [5].

In the recent pre-print [18], Figalli, Ros-Oton and Serra studied the phase transition of ice melting to water as a Stefan problem. The results established in this paper provide a refined understanding of the Stefan problem's singularities and answer some long-standing open questions in the field of free-boundary problems.

In this article we propose and study a mathematical model describing the evolution of the thickness of a shallow ice sheet. The ice thickness of a shallow ice sheet evolves as a consequence of many factors like, for instance, the rate at which snow deposits, the rate at which melting occurs, as well as the velocity at which the glacier slides along the lithosphere. Since the ice thickness level is constrained to remain on or above the lithosphere at all times, the problem under consideration can be regarded as a time-dependent obstacle problem.

In 2002 Calvo, Díaz, Durany, Schiavi and Vázquez [9] studied a simplified version of the evolution of the thickness of a shallow ice sheet. Indeed, in their article, the authors only considered one spatial direction, they assumed the basal velocity to be smooth, and assumed the lithosphere to be flat.

Ten years later, in 2012, Jouvét and Bueler [27] studied the steady (i.e., time-independent) version of the problem considered in [9] where, this time, two spatial directions and a more general lithosphere topography were taken into account.

It appears that the ice thickness evolution as a time-dependent obstacle problem over a two-dimensional spatial domain has not been addressed in the literature yet. The purpose of this article is exactly to address this problem.

This paper is divided into four sections (including this one). In section 2 we present the main notations we shall be using throughout the manuscript, and we formally derive the governing equations for our model.

In section 3 we formulate the “penalized” version corresponding to the obstacle problem introduced in section 2, and we establish the existence of solutions to this model by resorting to a series of new preparatory results as well as the Dubinskii’s compactness theorem.

Finally, in section 4, we pass to the limit in the penalty parameter and we recover the actual model corresponding to the model we formally derived in section 2. This model, for which we also define the rigorous concept of solution, will take the form of a set of variational inequalities. The presence of the constraint, which adds a further nonlinearity to the two already considered (the first nonlinearity appears in the evolutionary term, while the second nonlinearity is the  $p$ -Laplacian), requires new strategies to be adopted in the limit passage in order to overcome the arising mathematical difficulties. In particular, we will see that vector-valued measure will play a critical role in the analysis.

## 2. ANALYTICAL NOTATION AND FORMAL DERIVATION OF THE MODEL

We denote by  $(\mathbb{R}^n, \cdot)$  the  $n$ -dimensional Euclidean space equipped with its standard inner product. Given an open subset  $\Omega$  of  $\mathbb{R}^n$  notations such as  $L^2(\Omega)$ ,  $H^m(\Omega)$ , or  $H_0^m(\Omega)$ ,  $m \geq 1$ , designate the usual Lebesgue and Sobolev spaces, and the notation  $\mathcal{D}(\Omega)$  designates the space of all functions that are infinitely differentiable over  $\Omega$  and have compact support in  $\Omega$ . The notation  $\|\cdot\|_X$  designates the norm in a normed vector space  $X$ . The dual space of a vector space  $X$  is denoted by  $X^*$  and the duality pair between  $X^*$  and  $X$  is denoted by  $\langle \cdot, \cdot \rangle_{X^*, X}$ . Spaces of vector-valued functions are denoted with boldface letters. Lebesgue spaces defined over a bounded open interval  $I$  (cf. [30]), are denoted  $L^p(I; X)$ , where  $X$  is a Banach space and  $1 \leq p \leq \infty$ . The notation  $\|\cdot\|_{L^p(I; X)}$  designates the norm of the Lebesgue space  $L^p(I; X)$ . Sobolev spaces defined over a bounded open interval  $I$  (cf. [30]), are denoted  $W^{m,p}(I; X)$ , where  $X$  is a Banach space,  $m \geq 1$  and  $1 \leq p \leq \infty$ . The notation  $\|\cdot\|_{W^{m,p}(I; X)}$  designates the norm of the Sobolev space  $W^{m,p}(I; X)$ .

A *domain in  $\mathbb{R}^n$*  is a bounded and connected open subset  $\Omega$  of  $\mathbb{R}^n$ , whose boundary  $\partial\Omega$  is Lipschitz-continuous, the set  $\Omega$  being locally on a single side of  $\partial\Omega$ , viz. [10].

Let  $\Omega$  be a domain in  $\mathbb{R}^2$  and let  $x = (x_1, x_2)$  be a generic point in  $\bar{\Omega}$ . Let  $\nu$  denote the outer unit vector field along the boundary of  $\Omega$ . Let  $\nabla$  denote the gradient operator with respect to the coordinates  $x_1$  and  $x_2$ , namely,

$$\nabla = \left( \frac{\partial}{\partial x_1}, \frac{\partial}{\partial x_2} \right),$$

and let the symbol  $(\nabla \cdot)$  denote the divergence operator, namely, for any vector field  $\mathbf{v} = (v_1, v_2) : \Omega \rightarrow \mathbb{R}^2$

$$\nabla \cdot \mathbf{v} := \frac{\partial v_1}{\partial x_1} + \frac{\partial v_2}{\partial x_2}.$$

Let  $T > 0$  be given and let us consider the time interval  $(0, T)$ , any time instant in which is denoted by the letter  $t$ .

The lithosphere elevation is described by the function  $b : \bar{\Omega} \rightarrow \mathbb{R}$ . Positive values of  $b$  are associated with altitudes above the sea level, whereas negative values of  $b$  are associated with altitudes below the sea level. We assume, without loss of generality, that the lithosphere topography does not change throughout the observation time.

The elevation of the upper ice surface is described by the function  $h : [0, T] \times \bar{\Omega} \rightarrow \mathbb{R}$ . It is immediate to observe that

$$(2.1) \quad h \geq b \quad \text{in } [0, T] \times \bar{\Omega}.$$

The ice thickness  $H := h - b$  is thus nonnegative in  $[0, T] \times \bar{\Omega}$ . This consideration implies that the problem of studying the evolution of the sea ice thickness can be regarded as an obstacle problem, where the *obstacle* is represented by the lithosphere.

This constraint implies the existence of a *free boundary* [6, 8, 17]. For all, or possibly almost every (a.e. in what follows)  $t \in (0, T)$ , we define the set  $\Omega_t^+$  by:

$$(2.2) \quad \Omega_t^+ := \{x \in \Omega; h(t, x) > b(x)\} = \{x \in \Omega; H(t, x) > 0\}.$$

The set  $\Omega_t^+$  denotes the region of  $\Omega$  which is covered with ice at the time instant  $t$ . The corresponding free boundary is the set

$$(2.3) \quad \Gamma_{f,t} := \Omega \cap \partial\Omega_t^+.$$

The variation of the ice thickness  $H$  is influenced by two source terms: the surface-mass balance  $a_s$ , which is associated with ice accumulation and ablation rate, and the basal melting rate  $a_b$ . The function  $a_b$  is equal to zero when the basal temperature is smaller than the ice melting point; otherwise, it is greater than zero. The functions  $a_s$  and  $a_b$ , in general, solely depend on the horizontal location and the surface elevation. The terms  $a_s$  and  $a_b$  can thus be regarded as functions

$$\begin{aligned} a_s &: [0, T] \times \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}_0^+, \\ a_b &: [0, T] \times \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}_0^+. \end{aligned}$$

We define the function  $a : [0, T] \times \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$  by:

$$a := a_s - a_b,$$

and we recall that this function is *assumed* to be continuous in  $[0, T] \times \bar{\Omega}$ , strictly positive in a subset of  $\Omega_t^+$ , strictly negative in  $\Omega_t^- := \Omega \setminus (\Omega_t^+ \cup \Gamma_{f,t})$ , and nonnegative in the complementary region of  $\Omega_t^+$  characterised by ablation [22, 27]. Ice sheets are incompressible, non-Newtonian, gravity driven flows [19, 22]. Ice flows from areas of  $\Omega_t^+$  characterised by accumulation (i.e., regions where  $a_s > 0$ ) to areas of  $\Omega_t^+$  characterised by ablation (i.e., regions where  $a_s \leq 0$ ).

Ice thickness is also influenced by the basal sliding velocity  $\mathbf{U}_b$ , which can be regarded as a given vector field in  $\mathbb{R}^2$  solely depending on the horizontal position, i.e.,

$$\mathbf{U}_b : \bar{\Omega} \rightarrow \mathbb{R}^2.$$

and we recall that (cf., e.g., [22]), when the ice base is frozen, we have  $\mathbf{U}_b = \mathbf{0}$ .

The vector field  $\mathbf{U} : [0, T] \times \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}^2$  denotes the horizontal ice flow velocity; the vector field  $\mathbf{Q}$  denotes the *volume flux*, defined as the integral of the horizontal ice flow velocity  $\mathbf{U}$  with respect to the vertical direction (cf., e.g., equation (5.47) of [22]), namely:

$$(2.4) \quad \mathbf{Q} : [0, T] \times \bar{\Omega} \rightarrow \mathbb{R}^2 \quad \text{and} \quad \mathbf{Q} := \int_b^h \mathbf{U} \, dz.$$

In the same spirit as Jouvét & Bueler [27], we *assume* that for each  $t \in (0, T)$  there is no volume ice flow towards  $\Omega_t^-$ , i.e.,

$$(2.5) \quad \mathbf{Q} \cdot \boldsymbol{\nu} = 0 \quad \text{on } \Gamma_{f,t}.$$

In view of (2.5), we can naturally extend the volume flux  $\mathbf{Q}$  by zero outside  $\Omega_t^+$ , i.e.,

$$(2.6) \quad \mathbf{Q} = \mathbf{0} \quad \text{in } \Omega_t^-.$$

Besides, once again in the spirit of [27], we have that

$$(2.7) \quad H = 0 \text{ on } \Gamma_{f,t} \quad \text{and} \quad H = 0 \text{ on } \partial\Omega.$$

The evolution of the ice thickness is governed by the *ice thickness equation* (cf., e.g., equation (5.55) in [22]), that we recall here below:

$$(2.8) \quad \frac{\partial H}{\partial t} = -\nabla \cdot \mathbf{Q} + a.$$

The free boundary  $\Gamma_{f,t}$  and the region  $\Omega_t^+$  are correctly described *only* through a weak formulation of the problem under consideration. Prior to rigorously stating the weak formulation of the problem under consideration, we have to *formally* recover the boundary value problem associated with (2.8). To this aim we *first* fix a *smooth enough* test function  $v$  such that  $v \geq b$  in  $[0, T] \times \bar{\Omega}$  and, *second*, we multiply (2.8) by  $(v - h)$  and integrate over  $\Omega$ . As a result of this manipulation of (2.8), the following identity holds for all  $t \in (0, T)$ :

$$(2.9) \quad \int_{\Omega} \frac{\partial H}{\partial t} (v - h) \, dx + \int_{\Omega} \nabla \cdot \mathbf{Q} (v - h) \, dx = \int_{\Omega} a (v - h) \, dx.$$

By virtue of the fact that  $h \geq b$  in  $[0, T] \times \bar{\Omega}$ , we can specialise  $v = h$ . The definition of  $\Omega_t^-$  in turn implies that  $\Omega = \Omega_t^+ \sqcup \Omega_t^- \cup \Gamma_{f,t}$ , where the symbol  $\sqcup$  denotes the union of two disjoint sets. An application of (2.6) and of the Gauss-Green theorem to (2.9) gives

$$(2.10) \quad \begin{aligned} & \int_{\Omega_t^+} \frac{\partial H}{\partial t} (v - h) \, dx + \int_{\Omega_t^-} \frac{\partial H}{\partial t} (v - h) \, dx \\ & + \int_{\Omega_t^+} \nabla \cdot \mathbf{Q} (v - h) \, dx + \int_{\Omega_t^-} \nabla \cdot \mathbf{Q} (v - h) \, dx \\ & - \int_{\Omega_t^+} a (v - h) \, dx - \int_{\Omega_t^-} a (v - h) \, dx \\ & = \int_{\Omega_t^+} \left( \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \right) (v - h) \, dx + \int_{\Omega_t^-} \frac{\partial H}{\partial t} (v - h) \, dx \\ & + \underbrace{\int_{\Omega_t^-} \mathbf{Q} \cdot \boldsymbol{\nu} (v - h) \, d\Gamma - \int_{\partial\Omega_t^-} \mathbf{Q} \cdot \nabla (v - h) \, dx - \int_{\Omega_t^-} a (v - h) \, dx}_{=0 \text{ by (2.6) and the fact that } \partial\Omega_t^+ = \partial\Omega_t^-}. \end{aligned}$$

In order to work out the following step of the boundary value problem recovery, let us recall that  $\Omega_t^-$  denotes the region in  $\Omega$  where the lithosphere is *not* covered with ice, i.e., we have  $H = 0$  in  $\Omega_t^-$ . Moreover, the ice thickness  $H$  in  $\Omega_t^-$  *either* does not change ( $\partial H/\partial t = 0$ ) *or* increases ( $\partial H/\partial t > 0$ ); equivalently, the ice thickness  $H$  *cannot* diminish in  $\Omega_t^-$ .

On the one hand, in the region  $\Omega_t^+$  the ice thickness evolution is governed by (2.8), so that we have

$$(2.11) \quad \int_{\Omega_t^+} \left( \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \right) (v - h) \, dx = 0, \quad \text{for all } t \in (0, T).$$

On the other hand, specialising  $v = h + \varphi$  in (2.10), where  $\varphi \in \mathcal{D}((0, T) \times \Omega)$ ,  $\varphi \geq 0$  in  $[0, T] \times \Omega$ , recalling that  $a \leq 0$  in  $\Omega_t^-$ , and recalling the remark made above about the nonnegativeness of  $\partial H/\partial t$  in  $\Omega_t^-$ , we obtain

$$(2.12) \quad \int_{\Omega_t^-} \left( \frac{\partial H}{\partial t} - a \right) \varphi \, dx \geq 0, \quad \text{for all } t \in (0, T).$$

Putting together (2.9)–(2.12) gives

$$(2.13) \quad \int_{\Omega} \left( \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \right) \varphi \, dx \geq 0, \quad \text{for all } \varphi \in \mathcal{D}((0, T) \times \Omega), \varphi \geq 0 \text{ in } [0, T] \times \bar{\Omega}.$$

The latter can be straightforwardly changed into:

$$(2.14) \quad \begin{aligned} & \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a = 0, \quad \text{in } \Omega_t^+ = \{x \in \Omega; H(t, x) > 0\} \text{ for all } t \in (0, T), \\ & \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \geq 0, \quad \text{in } \Omega_t^- = \Omega \setminus (\Omega_t^+ \cup \Gamma_{f,t}) \text{ for all } t \in (0, T). \end{aligned}$$

Define  $H_0 := h(0) - b$ , and observe that  $H_0 \geq 0$  by virtue of the observation made at the beginning of this section (section 2). Putting together (2.7) and (2.14) gives the sought free boundary value problem: *Find  $H \geq 0$  satisfying:*

$$(2.15) \quad \left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a = 0, \quad \text{in } \Omega_t^+ = \{x \in \Omega; H(t, x) > 0\} \text{ for all } t \in (0, T), \\ \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \geq 0, \quad \text{in } \Omega_t^- = \Omega \setminus (\Omega_t^+ \cup (\Omega \cap \partial\Omega_t^+)) \text{ for all } t \in (0, T), \\ H(t, \cdot) = 0, \quad \text{on } \partial\Omega \text{ for all } t \in (0, T), \\ H(0, \cdot) = H_0 \geq 0. \end{array} \right.$$

Multiplying the equation in the boundary value problem (2.15) by  $(h - b)$ , integrating over  $(0, T) \times \Omega$ , and observing that  $h(t, \cdot) = b$  in  $\Omega_t^-$  gives:

$$(2.16) \quad \int_0^T \int_{\Omega} \left( \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \right) (h - b) \, dx \, dt = 0.$$

Let  $v = v(t, x)$  be any test function such that  $v(t, x) \geq b(x)$  for a.e.  $(t, x) \in (0, T) \times \Omega$ . Multiplying the equations in the boundary value problem (2.15) by  $(v - b)$ , and integrating over  $(0, T) \times \Omega$  gives:

$$(2.17) \quad \int_0^T \int_{\Omega} \left( \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \right) (v - b) \, dx \, dt \geq 0.$$

Combining (2.16) and (2.17) gives:

$$(2.18) \quad \int_0^T \int_{\Omega} \left( \frac{\partial H}{\partial t} + \nabla \cdot \mathbf{Q} - a \right) (v - h) \, dx \, dt \geq 0.$$

The arbitrariness of the test function  $v$  taken as above finally allows us to write down the weak variational formulation associated with the boundary value problem (2.15): *Find  $H \geq 0$  satisfying the variational inequalities:*

$$(2.19) \quad \int_0^T \int_{\Omega} \frac{\partial H}{\partial t} (v - h) \, dx \, dt - \int_0^T \int_{\Omega} \mathbf{Q} \cdot \nabla (v - h) \, dx \, dt \geq \int_0^T \int_{\Omega} a (v - h) \, dx \, dt,$$

for all test function  $v$  such that  $v \geq b$  for a.e.  $(t, x) \in (0, T) \times \Omega$ , and satisfying the following boundary conditions along  $\partial\Omega$

$$H = 0 \quad \text{on } \partial\Omega,$$

and satisfying the following initial condition

$$H(0, x) = H_0(x), \quad \text{for a.e. } x \in \Omega,$$

where  $H_0 = h(0) - b$  is given, nonnegative and nonzero (see (2.1)).

Note that, at least for the time being, the rigorous concept of solution has not been defined yet as we did not specify the regularity of  $H$  and of the data. This task will be postponed to forthcoming sections.

Ice is viscous too; its viscosity is described in terms of the Glen power law (cf., e.g., equation (4.16) in [22]) with ice softness coefficient  $A(x, z)$  and exponent  $2.8 \leq p \leq 5$ . The attainable values for  $p$  are suggested by laboratory experiments [21]. Regarding the ice softness as a function is motivated by the idea of coupling the ice thickness equation with a thermodynamic model [22, 24].

By equation (5.84) in [22], the horizontal ice flow velocity  $\mathbf{U}$  can be expressed in terms of the elevation of the upper ice surface  $h$  via the following formula:

$$(2.20) \quad \mathbf{U}(\cdot, \cdot, z) = -2(\rho g)^{p-1} \left( \int_b^z A(s)(h-s)^{p-1} \, ds \right) |\nabla h|^{p-2} \nabla h + \mathbf{U}_b.$$

Plugging formula (2.20) into (2.4) gives:

$$(2.21) \quad \begin{aligned} \mathbf{Q}(\cdot, \cdot, z) &= -2(\rho g)^{p-1} \left( \int_b^h \int_b^z A(s)(h-s)^{p-1} ds dz \right) |\nabla h|^{p-2} \nabla h + (h-b)\mathbf{U}_b \\ &= -2(\rho g)^{p-1} \left( \int_b^h A(s)(h-s)^p ds \right) |\nabla h|^{p-2} \nabla h + (h-b)\mathbf{U}_b, \end{aligned}$$

where the latter equality is obtained by an integration by parts with respect to the variable  $z$ .

For sake of clarity, the magnitudes involved in the model are listed in the following table.

Variable	Description
$A = A(s)$	Ice softness in the Glen power law
$b$	Lithosphere elevation
$g$	Gravitational acceleration
$H$	Ice thickness
$h$	Upper ice surface elevation
$a_s$	Accumulation rate function
$a_b$	Ablation rate function
$a$	$a = a_s - a_b$ Balance function
$\mathbf{U}_b$	Basal sliding velocity
$\mathbf{U}$	Horizontal ice flow velocity
$\mathbf{Q}$	Ice volume flux
$\rho$	Ice density
$p$	Index in the Glen power law

TABLE 1. Quantities entering the model

As already observed by Jouvét & Bueler [27], the expression of  $\mathbf{Q}$  in (2.21) exhibits a degenerate behaviour at the free boundary, in the sense that the gradient norm power blows up as  $h$  gets close to the free boundary of  $\Omega$ . This degeneracy does not manifest in other large-scale models like the one proposed by Hibler in the seminal paper [23].

By contrast with the model we are considering, the model proposed by Hibler couples the shallow ice equation with a *mechanical* (hyperbolic) equation whose unknown is the horizontal ice flow velocity  $\mathbf{U}$ . The model we are considering follows the formulation originally proposed by J.W. Glen [20], according to which ice was regarded as a viscous fluid. The model proposed by Hibler, itself inspired by the article of M.D. Coon [12], is on the one hand *less precise* than Glen's model as the ice velocity  $\mathbf{U}$  has a simplified expression. On the other hand, it achieves the goal of describing in the same instance the behaviours of ice as a solid and as a fluid.

The operation of averaging considerably simplifies the expression of the ice volume flux  $\mathbf{Q}$ , while the coupling of the shallow ice equation for the averaged ice thickness with the mechanical equation spares the effort of expressing the ice flow velocity  $\mathbf{U}$  in terms of the ice thickness.

In order to overcome the difficulty arising as a result of the gradient degeneracy in the vicinity of the free boundary, we introduce the following transformation, originally suggested in [9]:

$$(2.22) \quad H := u^{(p-1)/2p}.$$

Observe that  $H \geq 0$  in  $[0, T] \times \bar{\Omega}$  if and only if  $u \geq 0$  in  $[0, T] \times \bar{\Omega}$ . As a result of the transformation (2.22), we *first* obtain, formally,

$$(2.23) \quad \frac{\partial H}{\partial t} = \frac{\partial}{\partial t} (|u|^{\frac{3p-1}{2p}-2} u),$$

*secondly*, we obtain

$$(2.24) \quad \int_b^h A(s)(h-s)^p ds = u^{\frac{(p+1)(p-1)}{2p}} \int_0^1 A(b + u^{\frac{p-1}{2p}} s')(1-s')^p ds',$$

and, *third*, we obtain:

$$(2.25) \quad |\nabla h|^{p-2} \nabla h = \left( \frac{p-1}{2p} \right)^{p-1} u^{\frac{(-p-1)(p-2)}{2p}} \left| \nabla u + u^{(p+1)/2p} \nabla b \right|^{p-2} u^{\frac{-p-1}{2p}} \left( \nabla u + u^{(p+1)/2p} \nabla b \right).$$

For all  $x \in \Omega$  and all  $u = u(t, x) \in \mathbb{R}$ , we define the vector field  $\Phi : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}^2$  by:

$$(2.26) \quad \Phi = \Phi(x, u) := -\frac{2p}{p-1} u^{(p+1)/2p} \nabla b.$$

Plugging (2.26) into (2.25) gives:

$$(2.27) \quad |\nabla h|^{p-2} \nabla h = \left( \frac{p-1}{2p} \right)^{p-1} u^{\frac{(-p-1)(p-2)}{2p}} \left| \nabla u - \Phi \right|^{p-2} u^{\frac{-p-1}{2p}} (\nabla u - \Phi).$$

Finally, for all  $x \in \Omega$  and all  $u = u(t, x) \in \mathbb{R}$ , we define the vector field  $\Psi : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}^2$  by,

$$(2.28) \quad \Psi = \Psi(x, u) := (h-b) \mathbf{U}_b,$$

and the function  $\tilde{a} : [0, T] \times \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$  by:

$$(2.29) \quad \tilde{a}(t, x, u) := a(t, x, b + u^{(p-1)/2p}).$$

Inserting (2.24)–(2.29) into (2.21) gives:

$$(2.30) \quad -\mathbf{Q} = 2 \left( \rho g \frac{p-1}{2p} \right)^{p-1} \left[ \int_0^1 A(b + u^{(p-1)/2p} s') (1-s')^p ds' \right] |\nabla u - \Phi|^{p-2} (\nabla u - \Phi) - \Psi.$$

For sake of brevity, we define the function  $\mu : \bar{\Omega} \times \mathbb{R} \rightarrow \mathbb{R}$  along  $u = u(x, t)$  by:

$$(2.31) \quad \mu(x, u) := 2 \left( \rho g \frac{p-1}{2p} \right)^{p-1} \left[ \int_0^1 A(b + u^{(p-1)/2p} s') (1-s')^p ds' \right].$$

Observe that plugging (2.31) into (2.30) gives:

$$(2.32) \quad -\mathbf{Q} = \mu(x, u) |\nabla u - \Phi|^{p-2} (\nabla u - \Phi) - \Psi.$$

Plugging (2.23)–(2.29) and (2.32) into the boundary value problem (2.15), gives that the *new* unknown  $u$  satisfies the following unilateral boundary value problem: *Find*  $u \geq 0$  defined on  $[0, T] \times \bar{\Omega}$  *satisfying*:

$$(2.33) \quad \left\{ \begin{array}{l} \frac{\partial}{\partial t} (|u|^{\frac{3p-1}{2p}-2} u) - \nabla \cdot (\mu(x, u) |\nabla u - \Phi|^{p-2} (\nabla u - \Phi) - \Psi) = \tilde{a}, \text{ in } \Omega_t^+ \text{ for all } t \in (0, T), \\ \frac{\partial}{\partial t} (|u|^{\frac{3p-1}{2p}-2} u) - \nabla \cdot (\mu(x, u) |\nabla u - \Phi|^{p-2} (\nabla u - \Phi) - \Psi) \geq \tilde{a}, \text{ in } \Omega_t^- \text{ for all } t \in (0, T), \\ u(t, \cdot) = 0, \quad \text{on } \partial\Omega \text{ for all } t \in (0, T), \\ u(0, \cdot) = u_0 := H_0^{(2p/(p-1))} \geq 0. \end{array} \right.$$

Similarly to (2.19), the weak formulation associated with the boundary value problem (2.33) is expected to take the following form: *Find*  $u \geq 0$  *satisfying the variational inequality*:

$$(2.34) \quad \begin{aligned} & \int_0^T \int_{\Omega} \left( \frac{\partial}{\partial t} (|u|^{\frac{3p-1}{2p}-2} u) \right) (v - u) dx dt \\ & - \int_0^T \int_{\Omega} \mu(x, u) |\nabla u - \Phi|^{p-2} (\nabla u - \Phi) \cdot \nabla (v - u) dx dt \\ & \geq \int_0^T \int_{\Omega} \tilde{a} (v - u) dx dt + \int_0^T \int_{\Omega} \Psi \cdot \nabla (v - u) dx dt, \end{aligned}$$

for all test functions  $v$  such that  $v \geq b$  for a.e.  $(t, x) \in (0, T) \times \Omega$ , and satisfying the following boundary conditions along  $\partial\Omega$

$$u = 0 \quad \text{on } \partial\Omega,$$

and satisfying the following initial condition

$$u(0, x) = u_0(x) = [H_0(x)]^{(2p/(p-1))}, \quad \text{for a.e. } x \in \Omega.$$

Once again, note that, at least for the time being, the rigorous concept of solution has not been defined yet. This task will be carried out in Section 3, where the function spaces where the solutions are going to be sought will be defined as well as the requirements a function has to meet in order to be regarded as a solution.

### 3. WEAK FORMULATION OF THE UNILATERAL BOUNDARY VALUE PROBLEM

Let  $\Omega \subset \mathbb{R}^2$  be a domain. Let  $2.8 \leq p \leq 5$  as suggested by the experimental results in [21]. For the sake of brevity, let

$$(3.1) \quad \alpha := \frac{3p-1}{2p},$$

and observe that  $1 < \alpha < 2 < p + 1$ . By the Rellich-Kondrachov theorem (cf., e.g., Lions & Magenes [32] and the references therein) the following chain of embeddings hold:

$$(3.2) \quad W_0^{1,p}(\Omega) \hookrightarrow \hookrightarrow C^0(\bar{\Omega}) \hookrightarrow L^\alpha(\Omega).$$

Define the set

$$(3.3) \quad K := \{v \in W_0^{1,p}(\Omega); v \geq 0 \text{ in } \bar{\Omega}\}.$$

The weak formulation of the unilateral boundary value problem and the definition of the concept of solution will be recovered as a result of a constructive proof, based on the penalty method. The idea of using the penalty method to derive the existence of solutions of time-dependent contact problems was first used by Bock and Jarusek in [2, 3] and was improved by Bock, Jarusek and Silhavy in the recent paper [4].

For sake of simplicity, we make the following assumptions on the geometry of the problem:

- (H1)  $b = 0$  in  $\bar{\Omega}$ , i.e., the lithosphere is flat;
- (H2) The ice softness  $A$  is assumed to be independent of the ice sheet height and time. As a result, the function  $\mu$  defined in (2.31) is independent of the ice sheet height as well. Moreover, there exist two positive constants  $\mu_1$  and  $\mu_2$  such that  $\mu_1 \leq \mu(x) \leq \mu_2$  for all  $x \in \bar{\Omega}$ ;
- (H3) The basal velocity  $U_b = \mathbf{0}$ ;
- (H4) The function  $\tilde{a}$  defined in (2.29) is independent of the ice sheet height and is of class  $W^{1,p}(0, T; C^0(\bar{\Omega}))$ .

Let us now establish some preparatory results. The first result collects some properties of the negative part operator.

**Lemma 3.1.** *Let  $\omega \subset \mathbb{R}^m$ , with  $m \geq 1$  an integer, be an open set. The operator  $-\{\cdot\} : L^2(\omega) \rightarrow L^2(\omega)$  defined by*

$$f \in L^2(\omega) \mapsto -\{f\}^- := -\min\{f, 0\} \in L^2(\omega),$$

*is monotone, bounded and Lipschitz continuous with Lipschitz constant equal to 1.*

*Proof.* Let  $f$  and  $g$  be arbitrarily given in  $L(\omega)$ . In what follows, sets of the form  $\{f \geq 0\}$  read

$$\{x \in \omega; f(x) \geq 0\}.$$

Recall that the negative part of a function is also given by

$$f^- = \frac{|f| - f}{2}.$$

We have that

$$\begin{aligned} & \int_{\omega} \{(-\{f\}^-) - (-\{g\}^-)\} (f - g) \, dx \\ & \geq \int_{\omega} |-\{f\}^-|^2 \, dx + \int_{\omega} |-\{g\}^-|^2 \, dx - 2 \int_{\{f \leq 0\} \cap \{g \leq 0\}} (-\{f\}^-)(-\{g\}^-) \, dx \\ & \geq \int_{\{f \leq 0\} \cap \{g \leq 0\}} |(-\{f\}^-) - (-\{g\}^-)|^2 \, dx \geq 0, \end{aligned}$$

and the monotonicity is thus established.

Let us show that the operator under consideration is bounded, in the sense that maps bounded sets onto bounded sets. Let  $\mathcal{F} \subset L^2(\omega)$  be bounded. By Hölder's inequality, we have that for each  $f \in \mathcal{F}$ ,

$$\sup_{\substack{v \in L^2(\omega) \\ v \neq 0}} \frac{|\int_{\omega} (-\{f\}^-) v \, dx|}{\|v\|_{L^2(\omega)}} \leq \|f\|_{L^2(\omega)},$$

and the boundedness of  $\mathcal{F}$  implies the boundedness of the supremum. The boundedness property is thus established.

Finally, to establish the Lipschitz continuity property, evaluate

$$\begin{aligned} & \left( \int_{\omega} |(-\{f\}^-) - (-\{g\}^-)|^2 \, dx \right)^{1/2} = \left( \int_{\omega} \left| \frac{f - |f|}{2} - \frac{g - |g|}{2} \right|^2 \, dx \right)^{1/2} \\ & = \frac{1}{2} \left( \int_{\omega} |(f - g) - (|f| - |g|)|^2 \, dx \right)^{1/2} \leq \frac{1}{2} \{ \|f - g\|_{L^2(\omega)} + \| |f| - |g| \|_{L^2(\omega)} \} \\ & = \frac{1}{2} \|f - g\|_{L^2(\omega)} + \frac{1}{2} \left( \int_{\omega} \| |f| - |g| \|^2 \, dx \right)^{1/2} \leq \frac{1}{2} \|f - g\|_{L^2(\omega)} + \frac{1}{2} \left( \int_{\omega} |f - g|^2 \, dx \right)^{1/2} \\ & = \|f - g\|_{L^2(\omega)}, \end{aligned}$$

where the inequality holds thanks to the Minkowski inequality. In conclusion, we have shown that

$$\|(-\{f\}^-) - (-\{g\}^-)\|_{L^2(\omega)} \leq \|f - g\|_{L^2(\omega)},$$

and the arbitrariness of  $f$  and  $g$  gives the desired Lipschitz continuity property. This completes the proof.  $\square$

The following lemma, which was originally proved using  $C^*$ -algebras (cf., e.g., [36]), plays a crucial role in the forthcoming analysis. We hereby provide an alternative proof, which solely makes use of convex analysis tools.

**Lemma 3.2.** *Let  $\alpha > 1$ . Then*

$$|x - y|^\alpha \leq |x|^\alpha - |y|^\alpha, \quad \text{for all } x, y \in \mathbb{R}.$$

*Proof.* Assume, without loss of generality, that  $x \geq y \neq 0$ , and let

$$t := \frac{x}{y} \geq 1.$$

Therefore, the sought inequality is equivalent to proving that

$$(t - 1)^\alpha \leq t^\alpha - 1, \quad \text{for all } t \geq 1.$$

Consider the function  $f : [1, \infty) \rightarrow \mathbb{R}$  defined by

$$f(t) := (t - 1)^\alpha - t^\alpha + 1.$$

Observe that

$$f'(t) = \alpha(t - 1)^{\alpha-1} - \alpha t^{\alpha-1} = \alpha((t - 1)^{\alpha-1} - t^{\alpha-1}).$$

Since  $\alpha - 1 > 0$  and since  $0 \leq t - 1 < t$ , the monotonicity of the power operator gives that  $(t - 1)^{\alpha-1} \leq t^{\alpha-1}$ , so that  $f'(t) \leq 0$  for all  $t > 1$ . Since  $f(1) = 0$ , we infer that  $f(t) \leq 0$  for all  $t \geq 1$  and the proof is complete.  $\square$

Thanks to Lemma 3.2, we can establish the following result, thanks to which we will be able to define a sound initial condition for the variational formulation we will be considering.

**Lemma 3.3.** *Let  $\Omega$  be a domain in  $\mathbb{R}^2$ , let  $T > 0$  be given, let  $1 < \alpha < 2$ , and let  $u \in L^\infty(0, T; L^\alpha(\Omega))$  be such that*

$$\frac{d}{dt} \left( |u|^{\frac{\alpha-2}{2}} u \right) \in L^2(0, T; L^2(\Omega)).$$

*Then, we have that  $|u|^{\frac{\alpha-2}{2}} u$  is of class  $\mathcal{C}^0([0, T]; L^2(\Omega))$  and  $u$  is of class  $\mathcal{C}^0([0, T]; L^\alpha(\Omega))$ .*

*Proof.* Observe that

$$\int_0^T \int_\Omega \left| |u|^{\frac{\alpha-2}{2}} u \right|^2 dx dt = \int_0^T \int_\Omega |u|^\alpha dx dt.$$

Since it was assumed that  $u \in L^\infty(0, T; L^\alpha(\Omega))$ , then the latter integral is finite. Hence, combining the latter with the assumption on the distributional derivative in time gives

$$\left( |u|^{\frac{\alpha-2}{2}} u \right) \in H^1(0, T; L^2(\Omega)) \hookrightarrow \mathcal{C}^0([0, T]; L^2(\Omega)).$$

To show that  $u \in \mathcal{C}^0([0, T]; L^\alpha(\Omega))$ , we have to show that for each  $t_0 \in [0, T]$ ,

$$\lim_{t \rightarrow t_0} \int_\Omega |u(t) - u(t_0)|^\alpha dx = 0.$$

By Lemma 3.2, we have that the Cauchy-Schwarz inequality and the triangle inequality give

$$\begin{aligned} \int_\Omega |u(t) - u(t_0)|^\alpha dx &\leq \int_\Omega \left| |u(t)|^\alpha - |u(t_0)|^\alpha \right| dx \\ &= \int_\Omega \left| \left| |u(t)|^{\frac{\alpha-2}{2}} u(t) \right|^{2/\alpha} \right|^\alpha - \left| \left| |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right|^{2/\alpha} \right|^\alpha dx = \int_\Omega \left| \left| |u(t)|^{\frac{\alpha-2}{2}} u(t) \right|^2 - \left| |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right|^2 \right| dx \\ &= \int_\Omega \left| \left( \left| |u(t)|^{\frac{\alpha-2}{2}} u(t) \right| - \left| |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right| \right) \cdot \left( \left| |u(t)|^{\frac{\alpha-2}{2}} u(t) \right| + \left| |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right| \right) \right| dx \\ &\leq \left\| \left| |u(t)|^{\frac{\alpha-2}{2}} u(t) \right| - \left| |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right| \right\|_{L^2(\Omega)} \left\| \left| |u(t)|^{\frac{\alpha-2}{2}} u(t) \right| + \left| |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right| \right\|_{L^2(\Omega)} \\ &\leq \left\| |u(t)|^{\frac{\alpha-2}{2}} u(t) - |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right\|_{L^2(\Omega)} \left\| \left| |u(t)|^{\frac{\alpha-2}{2}} u(t) \right| + \left| |u(t_0)|^{\frac{\alpha-2}{2}} u(t_0) \right| \right\|_{L^2(\Omega)}. \end{aligned}$$

Observe that the continuity in  $[0, T]$  of  $\left( |u|^{\frac{\alpha-2}{2}} u \right)$  implies the uniform boundedness of the second factor, as well as that the first factor tends to zero as  $t \rightarrow t_0$ . This completes the proof.  $\square$

The next lemma establishes that the supremum can be interchanged with a monotonically increasing continuous extended-real-valued function.

**Lemma 3.4.** *Let  $f : \mathbb{R} \rightarrow \overline{\mathbb{R}}$  be a monotonically increasing and continuous function. Then, given any  $S \subset \mathbb{R}$ ,*

$$\sup_{x \in S} f(x) = f(\sup S).$$

*Proof.* By the definition of supremum, we can find a maximizing sequence  $\{s_k\}_{k=1}^\infty \subset S$  for which

$$s_k \rightarrow \sup S, \quad \text{as } k \rightarrow \infty.$$

By the assumed continuity of  $f$ , we have that

$$\lim_{k \rightarrow \infty} f(s_k) = f(\sup S).$$

Since  $f(s_k) \leq \sup_{x \in S} f(x)$  then the inequality  $f(\sup S) \leq \sup_{x \in S} f(x)$  is obviously true, on the one hand. On the other hand, since  $f$  is monotone, we have that

$$f(x) \leq f(\sup S), \quad \text{for all } x \in S.$$

Therefore, passing to the supremum on the left-hand side, we obtain that

$$\sup_{x \in S} f(x) \leq \sup_{x \in S} f(\sup S) = f(\sup S),$$

and the proof is complete.  $\square$

The next lemma establishes a convergence property for sequences of functions enjoying the regularities announced in Lemma 3.3.

**Lemma 3.5.** *Let  $\Omega$  be a domain in  $\mathbb{R}^2$ , let  $T > 0$  be given, let  $1 < \alpha < 2$ , and let  $\{u_k\}_{k=1}^\infty \subset L^\infty(0, T; W_0^{1,p}(\Omega))$  be such that*

$$\left\{ |u_k|^{\frac{\alpha-2}{2}} u_k \right\}_{k=1}^\infty \text{ strongly converges in } \mathcal{C}^0([0, T]; L^2(\Omega)).$$

*Then  $\{u_k\}_{k=1}^\infty$  strongly converges in  $\mathcal{C}^0([0, T]; L^\alpha(\Omega))$ .*

*Proof.* Since the space  $\mathcal{C}^0([0, T]; L^\alpha(\Omega))$  is complete, it suffices to show that the sequence  $\{u_k\}_{k=1}^\infty$  is a Cauchy sequence in  $\mathcal{C}^0([0, T]; L^\alpha(\Omega))$ , i.e., we have to show that

$$(3.4) \quad \lim_{k, \ell \rightarrow \infty} \sup_{t \in [0, T]} \left( \int_{\Omega} |u_k(t) - u_\ell(t)|^\alpha dx \right)^{1/\alpha} = 0.$$

Using Lemma 3.2, Hölder's inequality and Lemma 3.4, we have that

$$\begin{aligned} & \sup_{t \in [0, T]} \left( \int_{\Omega} |u_k(t) - u_\ell(t)|^\alpha dx \right)^{1/\alpha} \leq \sup_{t \in [0, T]} \left( \int_{\Omega} \left| |u_k(t)|^\alpha - |u_\ell(t)|^\alpha \right| dx \right)^{1/\alpha} \\ &= \sup_{t \in [0, T]} \left( \int_{\Omega} \left| \left| |u_k(t)|^{\frac{\alpha-2}{2}} u_k(t) \right|^2 - \left| |u_\ell(t)|^{\frac{\alpha-2}{2}} u_\ell(t) \right|^2 \right| dx \right)^{1/\alpha} \\ &\leq \sup_{t \in [0, T]} \left\{ \left( \int_{\Omega} \left| |u_k(t)|^{\frac{\alpha-2}{2}} u_k(t) - |u_\ell(t)|^{\frac{\alpha-2}{2}} u_\ell(t) \right|^2 dx \right)^{1/2} \left( \int_{\Omega} \left| |u_k(t)|^{\frac{\alpha-2}{2}} u_k(t) + |u_\ell(t)|^{\frac{\alpha-2}{2}} u_\ell(t) \right|^2 dx \right)^{1/2} \right\}^{1/\alpha} \\ &= \left\{ \sup_{t \in [0, T]} \left[ \left\| |u_k(t)|^{\frac{\alpha-2}{2}} u_k(t) - |u_\ell(t)|^{\frac{\alpha-2}{2}} u_\ell(t) \right\|_{L^2(\Omega)} \left\| |u_k(t)|^{\frac{\alpha-2}{2}} u_k(t) + |u_\ell(t)|^{\frac{\alpha-2}{2}} u_\ell(t) \right\|_{L^2(\Omega)} \right] \right\}^{1/\alpha}. \end{aligned}$$

The assumed strong convergence implies that the second factor is uniformly bounded with respect to  $t \in [0, T]$ . Hence, the latter term is less or equal than

$$\left\{ \left[ \sup_{t \in [0, T]} \left\| |u_k(t)|^{\frac{\alpha-2}{2}} u_k(t) - |u_\ell(t)|^{\frac{\alpha-2}{2}} u_\ell(t) \right\|_{L^2(\Omega)} \right] \cdot \left[ \sup_{t \in [0, T]} \left\| |u_k(t)|^{\frac{\alpha-2}{2}} u_k(t) + |u_\ell(t)|^{\frac{\alpha-2}{2}} u_\ell(t) \right\|_{L^2(\Omega)} \right] \right\}^{1/\alpha}.$$

Since the second factor is uniformly bounded with respect to  $t \in [0, T]$  and since the first factor tends to zero as  $k, \ell \rightarrow \infty$ , by the assumed strong convergence, we finally obtain the sought convergence (3.4). This completes the proof.  $\square$

The next lemma establishes an immersion that will be used in the proof of the existence of the solution.

**Lemma 3.6.** *Let  $T > 0$  be given and let  $X$  be a normed vector space with the Radon-Nikodym property (cf., e.g., [40]). Let  $\langle\langle \cdot, \cdot \rangle\rangle$  denote the duality between  $(\mathcal{C}^0([0, T]; X))^*$  and  $\mathcal{C}^0([0, T]; X)$ , and let  $\langle \cdot, \cdot \rangle$  denote the duality between  $X^*$  and  $X$ .*

*The mapping*

$$\Upsilon : L^1(0, T; X^*) \rightarrow (\mathcal{C}^0([0, T]; X))^*$$

defined by

$$\langle\langle \Upsilon u, v \rangle\rangle := \int_0^T \langle u, v \rangle dt, \quad \text{where } u \in L^1(0, T; X^*) \text{ and } v \in \mathcal{C}^0([0, T]; X),$$

is linear, continuous and injective. Besides, if  $\{u_k\}_{k=1}^\infty$  is bounded in  $L^1(0, T; X^*)$  then  $\{\Upsilon u_k\}_{k=1}^\infty$  is bounded in  $(\mathcal{C}^0([0, T]; X))^*$ .

*Proof.* Let us check that  $\Upsilon$  is linear. For each  $u_1, u_2 \in L^1(0, T; X^*)$  we have that

$$\langle\langle \Upsilon(u_1+u_2), v \rangle\rangle = \int_0^T \langle u_1+u_2, v \rangle dt = \int_0^T \langle u_1, v \rangle dt + \int_0^T \langle u_2, v \rangle dt = \langle\langle \Upsilon u_1, v \rangle\rangle + \langle\langle \Upsilon u_2, v \rangle\rangle = \langle\langle \Upsilon u_1 + \Upsilon u_2, v \rangle\rangle,$$

for all  $v \in \mathcal{C}^0([0, T]; X)$ .

Similarly, for each  $\alpha \neq 0$  (for  $\alpha = 0$  the conclusion is immediate) and each  $u \in L^1(0, T; X^*)$ , we have that

$$\langle\langle \Upsilon(\alpha u), v \rangle\rangle = \int_0^T \alpha \langle u, v \rangle dt = \langle\langle \Upsilon u, \alpha v \rangle\rangle = \langle\langle \alpha \Upsilon u, v \rangle\rangle,$$

for all  $v \in \mathcal{C}^0([0, T]; X)$ , and the sought linearity property is thus proved.

To show the continuity of the mapping  $\Upsilon$ , let  $\{u_k\}_{k=1}^\infty$  be such that  $u_k \rightarrow u$  in  $L^1(0, T; X^*)$ . By Hölder's inequality in Lebesgue-Bochner spaces (cf., e.g., [45]), we have that

$$|\langle\langle \Upsilon u_k - \Upsilon u, v \rangle\rangle| \leq \int_0^T |\langle u_k - u, v \rangle| dt \leq \|u_k - u\|_{L^1(0, T; X^*)} \|v\|_{L^\infty(0, T; X)} \rightarrow 0 \text{ as } k \rightarrow \infty.$$

To prove that  $\Upsilon$  is injective, assume that  $\Upsilon u_1 = \Upsilon u_2$  in  $(\mathcal{C}^0([0, T]; X))^*$  then, for each  $v \in \mathcal{C}^0([0, T]; X)$ , we have that

$$\int_0^T \langle u_1 - u_2, v \rangle dt = 0.$$

In particular, if we consider functions of the form  $v(t) := \varphi(t)w$ , with  $\varphi \in \mathcal{D}(0, T)$  and  $w \in X$ . Fix  $\varphi \in \mathcal{D}(0, T)$  and let  $w \in X$  vary arbitrarily. Since  $X$  has the Radon-Nikodym property, we have that (cf., e.g., Theorem 8.13 of [30]) the latter becomes

$$0 = \int_0^T \langle u_1 - u_2, v \rangle dt = \left\langle \int_0^T (u_1(t) - u_2(t))\varphi(t) dt, w \right\rangle, \quad \text{for all } w \in X.$$

This in turn implies that

$$\int_0^T (u_1(t) - u_2(t))\varphi(t) dt = 0 \text{ in } X^*.$$

Since this conclusion is independent of the choice of  $\varphi \in \mathcal{D}(0, T)$ , an application of the Fundamental Lemma of the Calculus of Variations (cf., e.g., [45]) gives that  $u_1 = u_2$  in  $L^1(0, T; X^*)$  and the injectivity is thus proved.

Let  $\{u_k\}_{k=1}^\infty$  be bounded in  $L^1(0, T; X^*)$ . For each  $v \in \mathcal{C}^0([0, T]; X)$ , the Hölder inequality in Lebesgue-Bochner spaces (cf. Theorem of [45]) and the assumed uniform boundedness of the sequence  $\{u_k\}_{k=1}^\infty$  give:

$$|\langle\langle \Upsilon u_k, v \rangle\rangle| = \left| \int_0^T \langle u_k(t), v(t) \rangle dt \right| \leq \int_0^T |\langle u_k(t), v(t) \rangle| dt \leq \|u_k\|_{L^1(0, T; X^*)} \|v\|_{L^\infty(0, T; X)} \leq C \|v\|_{L^\infty(0, T; X)},$$

for some  $C > 0$  independent of  $k$ . This shows that each operator  $\tilde{\Upsilon}_k : \mathcal{C}^0([0, T]; X) \rightarrow \mathbb{R}$  defined by  $\tilde{\Upsilon}_k := \Upsilon u_k$  for all integers  $k \geq 1$  is linear, continuous, and such that, for each  $v \in \mathcal{C}^0([0, T]; X^*)$

$$\sup_{k \geq 1} |\tilde{\Upsilon}_k(v)| \leq C_v,$$

for some constant  $C_v > 0$  that solely depends on  $v$ . An application of the Banach-Steinhaus theorem (cf., e.g., Theorem 2.2 of [7]) gives that there exists a constant  $C > 0$  for which

$$\sup_{k \geq 1} \|\tilde{\Upsilon}_k\|_{(\mathcal{C}^0([0, T]; X))^*} \leq C,$$

thus proving that the sequence  $\{\Upsilon u_k\}_{k=1}^\infty$  is uniformly bounded in  $(\mathcal{C}^0([0, T]; X))^*$ . The proof is complete.  $\square$

The conclusion of Lemma 3.6 is that the space  $L^1(0, T; X^*)$  can be identified with a subspace of  $(\mathcal{C}^0([0, T]; X))^*$ .

The proof of existence of solutions hinges on a compactness result proved by Dubinskii [15] (see also [1] for some improvements and corrections), as well as other results proved by Raviart in the paper [38] that we recall here below.

**Lemma 3.7** (Lemma 1.1 of [38]). *Let  $1 < r < \infty$  and let  $r'$  denote the Hölder conjugate exponent of  $r$ . The following inequalities hold*

$$\begin{aligned} (|\xi|^{r-2}\xi - |\eta|^{r-2}\eta)\xi &\geq \frac{1}{r'}(|\xi|^r - |\eta|^r), \\ (|\xi|^{r-2}\xi - |\eta|^{r-2}\eta)(\xi - \eta) &\geq C \left( |\xi|^{(r-2)/2}\xi - |\eta|^{(r-2)/2}\eta \right)^2, \text{ for some } C = C(r) > 0, \end{aligned}$$

for all  $\xi, \eta \in \mathbb{R}$ .  $\square$

The first inequality in this lemma is a direct consequence of Young's inequality (cf., e.g., [46]), while the second inequality was proved by Simon in the paper [43].

The next preliminary result we recall, is a generalized integration-by-parts formula, whose proof hinges on the Lebesgue theorem (cf., e.g., Theorem 2.11-3 of [11]).

**Lemma 3.8** (Lemma 1.2 of [38]). *Let  $\Omega$  be a domain in  $\mathbb{R}^2$ , and let  $T > 0$ . Let  $\alpha$  and  $p$  be two real numbers greater than 1, and let  $v$  be a function such that*

$$\begin{aligned} v &\in L^p(0, T; W_0^{1,p}(\Omega)) \cap \mathcal{C}^0([0, T]; L^\alpha(\Omega)), \\ \frac{d}{dt}(|v|^{\alpha-2}v) &\in L^{p'}(0, T; W^{-1,p'}(\Omega)). \end{aligned}$$

Therefore, the following formula holds

$$\int_0^T \left\langle \frac{d}{dt}(|v|^{\alpha-2}v), v \right\rangle dt = \frac{\|v(T)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'} - \frac{\|v(0)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'},$$

where  $\langle \cdot, \cdot \rangle$  denotes the duality product between  $W^{-1,p'}(\Omega)$  and  $W_0^{1,p}(\Omega)$ .  $\square$

Finally, we recall Dubinskii's compactness theorem.

**Theorem 3.9.** *Let  $A_0$  and  $A_1$  be normed linear spaces such that  $A_0 \hookrightarrow A_1$ . Let  $S \subset A_0$  be such that  $\lambda S \subset S$ , for all  $\lambda \in \mathbb{R}$ .*

*Assume that the set  $S$  is endowed with the semi-norm  $M : S \rightarrow \mathbb{R}$ , having the following properties:*

- (1)  $M(v) \geq 0$ , for all  $v \in S$ ,
- (2)  $M(\lambda v) = |\lambda|M(v)$ , for all  $v \in S$  and all  $\lambda \in \mathbb{R}$ .

*Assume that the set  $\mathcal{M} := \{v \in S; M(v) \leq 1\}$  is relatively compact in  $A_0$ . Consider the semi-normed set*

$$Y := \left\{ u \in L_{\text{loc}}^1(0, T; A_1); \int_0^T [M(u(t))]^{q_0} dt < \infty \text{ and } \int_0^T \left\| \frac{du}{dt} \right\|_{A_1}^{q_1} dt < \infty \right\},$$

*with  $1 \leq q_0 \leq \infty$  and  $1 \leq q_1 \leq \infty$ , and the pairs  $(q_0, q_1) = (1, \infty)$  and  $(q_0, q_1) = (\infty, 1)$  cannot be attained.*

*Then  $Y$  is relatively compact in  $L^{q_0}(0, T; A_0)$ .*  $\square$

A discrete version of this compactness result has been established by Raviart in the paper [37].

**Theorem 3.10** (Lemma 1.4 of [38]). *Let  $A_0$  and  $A_1$  be normed linear spaces such that  $A_0 \hookrightarrow A_1$ . Let  $S \subset A_0$  be such that  $\lambda S \subset S$ , for all  $\lambda \in \mathbb{R}$ .*

*Assume that the set  $S$  is endowed with the semi-norm  $M : S \rightarrow \mathbb{R}$ , having the following properties:*

- (1)  $M(v) \geq 0$ , for all  $v \in S$ ,

(2)  $M(\lambda v) = |\lambda| M(v)$ , for all  $v \in S$  and all  $\lambda \in \mathbb{R}$ .

Assume that the set  $\mathcal{M} := \{v \in S; M(v) \leq 1\}$  is relatively compact in  $A_0$ .

For each  $\ell > 0$ , consider the vector  $\mathbf{v}_\ell := (v_\ell^n)_{n=0}^N$  of elements of  $S$  such that

$$\ell \sum_{n=0}^N [M(v_\ell^n)]^{q_0} \leq c_0, \quad \text{for some constants } c_0 \geq 0,$$

and

$$\ell \sum_{n=0}^{N-1} \left\| \frac{v_\ell^{n+1} - v_\ell^n}{k} \right\|_{A_1}^{q_1} \leq c_1, \quad \text{for some constants } c_1 \geq 0,$$

where  $1 \leq q_0 \leq \infty$  and  $1 \leq q_1 \leq \infty$ , and the pairs  $(q_0, q_1) = (1, \infty)$  and  $(q_0, q_1) = (\infty, 1)$  cannot be attained.

Then, it is possible to extract a subsequence of the sequence  $(\Pi_\ell \mathbf{v}_\ell)$  that strongly converges in  $L^{q_0}(0, T; A_0)$ , where

$$\Pi_k \mathbf{u}_k : (0, T) \rightarrow A_0 \quad \text{with} \quad (\Pi_\ell \mathbf{v}_\ell)(t) := v_\ell^{n+1}, \text{ for a.a. } n\ell < t \leq (n+1)\ell.$$

□

Let us also recall a result on vector-valued measures proved by Zinger in the paper [47] and later improved by Dinculeanu (see also, e.g., page 182 of [13], and page 380 of [14]).

**Theorem 3.11** (Dinculeanu-Zinger theorem). *Let  $\omega$  be a compact Hausdorff space and let  $X$  be a Banach space satisfying the Radon-Nikodym property. Let  $\mathcal{F}$  be the collection of Borel sets of  $\omega$ .*

*There exists an isomorphism between  $(C^0(\omega; X))^*$  and the space of the regular Borel measures with finite variation taking values in  $X^*$ . In particular, for each  $F \in (C^0(\omega; X))^*$ , there exists a unique regular Borel measure  $\mu : \mathcal{F} \rightarrow X^*$  in  $\mathcal{M}(\omega; X^*)$  with finite variation such that*

$$\langle \langle \alpha, F \rangle \rangle_X = \int_{\omega} X^* \langle d\mu, \alpha \rangle_X,$$

for all  $\alpha \in C^0(\omega; X)$ .

□

We now state the penalized problem, which is suggested by the formal model (2.33). Note that the initial condition makes sense thanks to Lemma 3.3.

**Problem  $\mathcal{P}_\kappa$ .** Find a function  $u_\kappa$  that satisfies

$$\begin{aligned} u_\kappa &\in L^\infty(0, T; W_0^{1,p}(\Omega)), \\ \frac{d}{dt} \left( |u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa \right) &\in L^2(0, T; L^2(\Omega)), \\ \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa) &\in L^\infty(0, T; W^{-1,p'}(\Omega)), \end{aligned}$$

satisfying the following variational equations:

$$(3.5) \quad \int_{\Omega} \frac{d}{dt} (|u|^{\alpha-2} u) v \, dx + \int_{\Omega} \mu(x, u) |\nabla u|^{p-2} \nabla u \cdot \nabla v \, dx - \frac{1}{\kappa} \int_{\Omega} \{u_\kappa\}^- v \, dx = \int_{\Omega} \tilde{a}(t, x) v \, dx,$$

for all  $v \in W_0^{1,p}(\Omega)$  in the sense of distributions on  $(0, T)$ , as well as the following initial condition

$$u_\kappa(0) = u_0,$$

for some nonzero prescribed  $u_0 \in K$ . ■

## 4. EXISTENCE OF WEAK SOLUTIONS AND VARIATIONAL FORMULATION FOR PROBLEM (2.33)

The recovery of the variational formulation for Problem (2.33) and the existence of solutions for this problem are broken into three parts. We first establish the existence of solutions for Problem  $\mathcal{P}_\kappa$  by means of a semi-discrete scheme. For each  $0 \leq n \leq N-1$ , consider the semi-discrete problem:

**Problem  $\mathcal{P}_\kappa^{n+1}$ .** Given  $u_{\kappa,\ell}^n \in W_0^{1,p}(\Omega)$ , find a function  $u_{\kappa,\ell}^{n+1} \in W_0^{1,p}(\Omega)$  that satisfies the following variational equations:

$$(4.1) \quad \begin{aligned} & \frac{1}{\ell} \{ |u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n \} - \nabla \cdot \left( \mu |\nabla u_{\kappa,\ell}^{n+1}|^{p-2} \nabla u_{\kappa,\ell}^{n+1} \right) - \frac{\{u_{\kappa,\ell}^{n+1}\}^-}{\kappa} \\ & = \frac{1}{\ell} \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) dt \text{ in } W^{-1,p'}(\Omega), \end{aligned}$$

where  $u_{\kappa,\ell}^0 := u_0 \in K$ , and  $u_0$  is the prescribed element appearing in Problem  $\mathcal{P}_\kappa$ . ■

The following existence-and-uniqueness result can be established.

**Theorem 4.1.** *Let  $T > 0$ ,  $\Omega \subset \mathbb{R}^2$  and  $p$  be as in section 3 and let  $\alpha$  be as in (3.1). Let  $\kappa > 0$  be given, let  $N \geq 1$  be an integer, and define  $\ell := T/N$ . Assume that (H1)–(H4) hold.*

*For each  $0 \leq n \leq N-1$ , Problem  $\mathcal{P}_\kappa^{n+1}$  admits a unique solution  $u_{\kappa,\ell}^{n+1} \in W_0^{1,p}(\Omega)$ .*

*Proof.* For sake of brevity, define

$$(4.2) \quad \tilde{a}_\ell^n := \frac{1}{\ell} \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) dt.$$

Consider the operator  $A_\kappa : W_0^{1,p}(\Omega) \rightarrow W^{-1,p'}(\Omega)$  defined by

$$(4.3) \quad A_\kappa(v) := |v|^{\alpha-2} v - \nabla \cdot \left( \mu |\nabla v|^{p-2} \nabla v \right) - \frac{\{v\}^-}{\kappa}, \quad \text{for all } v \in W_0^{1,p}(\Omega).$$

Consider the operator  $B_\kappa : W_0^{1,p}(\Omega) \rightarrow W^{-1,p'}(\Omega)$  defined by

$$(4.4) \quad B_\kappa(v) := -\nabla \cdot \left( \mu |\nabla v|^{p-2} \nabla v \right) - \frac{\{v\}^-}{\kappa}, \quad \text{for all } v \in W_0^{1,p}(\Omega).$$

The operators  $A_\kappa$  and  $B_\kappa$  are hemi-continuous, as each of their terms is hemi-continuous. By Lemma 3.2 and Lemma 3.7, the operators  $A_\kappa$  and  $B_\kappa$  are strictly monotone. Finally, an application of the Poincaré-Friedrichs inequality and the monotonicity of the negative part operator (Lemma 3.2) give:

$$\frac{\langle A_\kappa v, v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)}}{\|v\|_{W_0^{1,p}(\Omega)}} \geq \frac{\|v\|_{L^\alpha(\Omega)}^\alpha + \mu_1 \|\nabla v\|_{L^p(\Omega)}^p}{\|v\|_{W_0^{1,p}(\Omega)}} \geq \mu_1 c_0 \|v\|_{W_0^{1,p}(\Omega)}^{p-1},$$

and the term on the right diverges as  $\|v\|_{W_0^{1,p}(\Omega)} \rightarrow \infty$ . This means that the operator  $A_\kappa$  is coercive. With the same reasoning, it can be proved that the operator  $B_\kappa$  is coercive too. An application of the Minty-Browder theorem (cf., e.g., Theorem 9.14-1 of [10]) ensures that the numerical scheme in (4.1) admits a unique solution  $u_{\kappa,\ell}^{n+1} \in W_0^{1,p}(\Omega)$ . The proof is complete. □

Define the mapping  $\Pi_\ell \mathbf{u}_\kappa : (0, T) \rightarrow W_0^{1,p}(\Omega)$  by

$$(4.5) \quad \Pi_\ell \mathbf{u}_\kappa(t) := u_{\kappa,\ell}^{n+1}, \quad \text{if } n\ell < t \leq (n+1)\ell.$$

Next, we discuss the convergence of the sequence  $\{\Pi_\ell \mathbf{u}_\kappa\}_{\ell>0}$  as  $\ell \rightarrow 0^+$  or, equivalently, as  $N \rightarrow \infty$ . To this aim, we need to establish some *a priori* estimates.

**Theorem 4.2.** *Let  $T > 0$ ,  $\Omega \subset \mathbb{R}^2$  and  $p$  be as in section 3 and let  $\alpha$  be as in (3.1). Let  $\kappa > 0$  be given, let  $N \geq 1$  be an integer, and define  $\ell := T/N$ . Assume that (H1)–(H4) hold.*

*Assume that the following stability condition holds: There exists a constant  $C_1 > 0$  independent of  $\kappa$  and  $N$  for which*

$$(4.6) \quad \frac{1}{\kappa} \sum_{n=0}^{N-1} \int_{\Omega} \{u_{\kappa,\ell}^{n+1}\}^{-} (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) \, dx \leq C_1,$$

for all integers  $N \geq 1$ .

*Then, the following a priori estimates hold:*

$$(4.7) \quad \max_{0 \leq n \leq N} \|u_{\kappa,\ell}^n\|_{L^\alpha(\Omega)} \leq C,$$

$$(4.8) \quad \ell \sum_{n=0}^N \|u_{\kappa,\ell}^n\|_{W_0^{1,p}(\Omega)}^p \leq C,$$

$$(4.9) \quad \ell \sum_{n=0}^{N-1} \left\| \frac{|u_{\kappa,\ell}^{n+1}|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n}{\ell} \right\|_{L^2(\Omega)}^2 \leq C,$$

$$(4.10) \quad \max_{0 \leq n \leq N} \left\| |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n \right\|_{L^2(\Omega)} \leq C,$$

$$(4.11) \quad \max_{0 \leq n \leq N} \|u_{\kappa,\ell}^n\|_{W_0^{1,p}(\Omega)} \leq C,$$

$$(4.12) \quad \max_{0 \leq n \leq N-1} \left\| \frac{|u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n}{\ell} \right\|_{W^{-1,p'}(\Omega)} \leq C \left(1 + \frac{1}{\kappa}\right),$$

$$(4.13) \quad \max_{0 \leq n \leq N} \left\| |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n \right\|_{L^{\alpha'}(\Omega)} \leq C,$$

for some  $C > 0$  independent of  $\kappa$  and  $N$ .

*Proof.* Multiply (4.1) by  $u_{\kappa,\ell}^{n+1}$  in the sense of the duality between  $W^{-1,p'}(\Omega)$  and  $W_0^{1,p}(\Omega)$ . We obtain

$$\begin{aligned} & \frac{1}{\ell} \langle |u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n, u_{\kappa,\ell}^{n+1} \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} + \int_{\Omega} \mu(x) |\nabla u_{\kappa,\ell}^{n+1}|^{p-2} \nabla u_{\kappa,\ell}^{n+1} \cdot \nabla u_{\kappa,\ell}^{n+1} \, dx \\ & - \frac{1}{\kappa} \int_{\Omega} \{u_{\kappa,\ell}^{n+1}\}^{-} u_{\kappa,\ell}^{n+1} \, dx = \frac{1}{\ell} \int_{\Omega} \left( \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) \, dt \right) u_{\kappa,\ell}^{n+1} \, dx. \end{aligned}$$

Using the first estimate in Lemma 3.7 with  $r = \alpha$ ,  $\xi = u_{\kappa,\ell}^{n+1}$  and  $\eta = u_{\kappa,\ell}^n$ , the Poincaré–Friedrichs inequality, Bochner’s theorem (Theorem 8.9 of [30]) and Young’s inequality (cf., e.g., [46]) we get:

$$\begin{aligned} & \frac{1}{\alpha' \ell} (\|u_{\kappa,\ell}^{n+1}\|_{L^\alpha(\Omega)}^\alpha - \|u_{\kappa,\ell}^n\|_{L^\alpha(\Omega)}^\alpha) + c_0 \mu_1 \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p + \frac{1}{\kappa} \|\{u_{\kappa,\ell}^{n+1}\}^{-}\|_{L^2(\Omega)}^2 \\ & \leq \frac{1}{\ell \varepsilon p'} \left( \int_{n\ell}^{(n+1)\ell} \|\tilde{a}(t)\|_{W^{-1,p'}(\Omega)}^{p'} \, dt \right) + \frac{\varepsilon}{p} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p. \end{aligned}$$

Multiplying by  $(\ell\alpha')$  both sides and summing over  $1 \leq n \leq s-1$ , where  $1 \leq s \leq N$ , we have that

$$\begin{aligned} & \sum_{n=0}^{s-1} \left\{ \|u_{\kappa,\ell}^{n+1}\|_{L^\alpha(\Omega)}^\alpha + \left(c_0\mu_1 - \frac{\varepsilon}{p}\right) \ell\alpha' \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p + \frac{\ell\alpha'}{\kappa} \|\{u_{\kappa,\ell}^{n+1}\}^{-1}\|_{L^2(\Omega)}^2 \right\} \\ & \leq \frac{\alpha'}{\varepsilon p'} \sum_{n=0}^{s-1} \left( \int_{n\ell}^{(n+1)\ell} \|\tilde{a}(t)\|_{W^{-1,p'}(\Omega)}^{p'} dt \right) + \sum_{n=0}^{s-1} \|u_{\kappa,\ell}^n\|_{L^\alpha(\Omega)}^\alpha, \end{aligned}$$

and we finally obtain

$$\begin{aligned} & \|u_{\kappa,\ell}^s\|_{L^\alpha(\Omega)}^\alpha + \left(c_0\mu_1 - \frac{\varepsilon}{p}\right) \ell\alpha' \sum_{n=0}^{s-1} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p + \frac{\ell\alpha'}{\kappa} \sum_{n=0}^{s-1} \|\{u_{\kappa,\ell}^{n+1}\}^{-1}\|_{L^2(\Omega)}^2 \\ & \leq \frac{\alpha'}{\varepsilon p'} \sum_{n=0}^{s-1} \left( \int_{n\ell}^{(n+1)\ell} \|\tilde{a}(t)\|_{W^{-1,p'}(\Omega)}^{p'} dt \right). \end{aligned}$$

Therefore, there exists  $C = C(u_0, \alpha, \varepsilon, p, \Omega) > 0$  such that:

$$(4.14) \quad \begin{aligned} & \max_{0 \leq n \leq N} \|u_{\kappa,\ell}^n\|_{L^\alpha(\Omega)} \leq C, \\ & \ell \sum_{n=0}^N \|u_{\kappa,\ell}^n\|_{W_0^{1,p}(\Omega)}^p \leq C, \\ & \frac{\ell}{\kappa} \sum_{n=1}^N \|\{u_{\kappa,\ell}^n\}^{-}\|_{L^2(\Omega)}^2 \leq C, \end{aligned}$$

so that the estimates (4.7) and (4.8) are proved.

By (4.7), for each  $0 \leq n \leq N$ , we have that

$$\|u_{\kappa,\ell}^n\|_{L^\alpha(\Omega)}^\alpha = \int_{\Omega} \left| |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n \right|^2 dx = \left\| |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n \right\|_{L^2(\Omega)}^2.$$

Since the left-hand side of the previous equation is uniformly bounded with respect to  $N$  and  $\kappa$ , we immediately infer that

$$\max_{0 \leq n \leq N} \left\| |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n \right\|_{L^2(\Omega)} \leq C,$$

for some  $C > 0$  independent of  $N$  and  $\kappa$ , thus establishing the estimate (4.10).

In order to recover the estimates (4.9) and (4.11), let us multiply (4.1) by  $(u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n)$  in the sense of the duality between  $W^{-1,p'}(\Omega)$  and  $W_0^{1,p}(\Omega)$ . We get

$$(4.15) \quad \begin{aligned} & \frac{1}{\ell} \langle |u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n, u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \\ & + \int_{\Omega} \mu(x) |\nabla u_{\kappa,\ell}^{n+1}|^{p-2} \nabla u_{\kappa,\ell}^{n+1} \cdot \nabla (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) dx \\ & - \frac{1}{\kappa} \int_{\Omega} \{u_{\kappa,\ell}^{n+1}\}^{-} (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) dx = \frac{1}{\ell} \int_{\Omega} \left( \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) dt \right) (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) dx. \end{aligned}$$

For each  $1 \leq s \leq N$ , we have that the following identity holds:

$$(4.16) \quad \begin{aligned} & \sum_{n=0}^{s-1} \int_{\Omega} \tilde{a}_\ell^n (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) dx = - \sum_{n=0}^{s-2} \int_{\Omega} (\tilde{a}_\ell^{n+1} - \tilde{a}_\ell^n) u_{\kappa,\ell}^{n+1} dx + \int_{\Omega} \tilde{a}_\ell^{s-1} u_{\kappa,\ell}^s dx - \int_{\Omega} \tilde{a}_\ell^0 u_0 dx \\ & = \sum_{n=0}^{s-2} \int_{n\ell}^{(n+1)\ell} \int_{\Omega} \left( \frac{\tilde{a}(t+\ell) - \tilde{a}(t)}{\ell} \right) u_{\kappa,\ell}^{n+1} dx dt + \int_{\Omega} \tilde{a}_\ell^{s-1} u_{\kappa,\ell}^s dx - \int_{\Omega} \tilde{a}_\ell^0 u_0 dx. \end{aligned}$$

An application of Lebesgue's inequality, the triangle inequality and Young's inequality [46] gives

$$\begin{aligned}
(4.17) \quad & \left| \sum_{n=0}^{s-2} \int_{\Omega} (\tilde{a}_{\ell}^{n+1} - \tilde{a}_{\ell}^n) u_{\kappa,\ell}^{n+1} dx \right| = \left| \sum_{n=0}^{s-2} \int_{n\ell}^{(n+1)\ell} \int_{\Omega} \left( \frac{\tilde{a}(t+\ell) - \tilde{a}(t)}{\ell} \right) u_{\kappa,\ell}^{n+1} dx dt \right| \\
& \leq \sum_{n=0}^{s-2} \int_{n\ell}^{(n+1)\ell} \left| \int_{\Omega} \frac{\tilde{a}(t+\ell) - \tilde{a}(t)}{\ell} u_{\kappa,\ell}^{n+1} dx \right| dt \\
& \leq \sum_{n=0}^{s-2} \int_{n\ell}^{(n+1)\ell} \left\| \frac{\tilde{a}(t+\ell) - \tilde{a}(t)}{\ell} \right\|_{W^{-1,p'}(\Omega)} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)} dt \\
& \leq \sum_{n=0}^{s-2} \left[ \frac{1}{p'\varepsilon} \int_{n\ell}^{(n+1)\ell} \left\| \frac{\tilde{a}(t+\ell) - \tilde{a}(t)}{\ell} \right\|_{W^{-1,p'}(\Omega)}^{p'} dt + \frac{\varepsilon\ell}{p} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p \right].
\end{aligned}$$

Since  $\tilde{a} \in W^{1,p}(0, T; C^0(\bar{\Omega}))$  (see assumption (H4)), an application of the finite difference quotients theory (cf., e.g., Chapter 5 in [16]), we have that the latter term can be estimated as follows:

$$\begin{aligned}
(4.18) \quad & \sum_{n=0}^{s-2} \left[ \frac{1}{p'\varepsilon} \int_{n\ell}^{(n+1)\ell} \left\| \frac{\tilde{a}(t+\ell) - \tilde{a}(t)}{\ell} \right\|_{W^{-1,p'}(\Omega)}^{p'} dt + \frac{\varepsilon\ell}{p} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p \right] \\
& \leq \frac{C}{p'\varepsilon} \sum_{n=0}^{s-2} \int_{n\ell}^{(n+1)\ell} \left\| \frac{d\tilde{a}}{dt}(t) \right\|_{W^{-1,p'}(\Omega)}^{p'} dt + C \frac{\varepsilon\ell}{p} \sum_{n=0}^{s-2} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p \\
& = \frac{C}{p'\varepsilon} \int_0^{(s-1)\ell} \left\| \frac{d\tilde{a}}{dt}(t) \right\|_{W^{-1,p'}(\Omega)}^{p'} dt + C \frac{\varepsilon\ell}{p} \sum_{n=0}^{s-2} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p.
\end{aligned}$$

Putting together (4.16)–(4.18) thus gives

$$\begin{aligned}
(4.19) \quad & \left| \sum_{n=0}^{s-1} \int_{\Omega} \tilde{a}_{\ell}^n (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) dx \right| \leq \left| \sum_{n=0}^{s-2} \int_{n\ell}^{(n+1)\ell} \int_{\Omega} \left( \frac{\tilde{a}(t+\ell) - \tilde{a}(t)}{\ell} \right) u_{\kappa,\ell}^{n+1} dx dt \right| \\
& \quad + \left| \int_{\Omega} \tilde{a}_{\ell}^{s-1} u_{\kappa,\ell}^s dx \right| + \left| \int_{\Omega} \tilde{a}_{\ell}^0 u_0 dx \right| \\
& \leq \frac{C}{p'\varepsilon} \int_0^{(s-1)\ell} \left\| \frac{d\tilde{a}}{dt}(t) \right\|_{W^{-1,p'}(\Omega)}^{p'} dt + C \frac{\varepsilon\ell}{p} \sum_{n=0}^{s-2} \|u_{\kappa,\ell}^{n+1}\|_{W_0^{1,p}(\Omega)}^p \\
& \quad + \frac{1}{p'\varepsilon} \|\tilde{a}\|_{L^\infty(0,T;W^{-1,p'}(\Omega))}^{p'} + \frac{\varepsilon}{p} \|u_{\kappa,\ell}^s\|_{W_0^{1,p}(\Omega)}^p \\
& \quad + \frac{1}{p'\varepsilon} \|\tilde{a}\|_{L^\infty(0,T;W^{-1,p'}(\Omega))}^{p'} + \frac{\varepsilon}{p} \|u_0\|_{W_0^{1,p}(\Omega)}^p \\
& \leq \left[ \frac{C}{p'\varepsilon} \int_0^{s\ell} \left\| \frac{d\tilde{a}}{dt}(t) \right\|_{W^{-1,p'}(\Omega)}^{p'} dt + \frac{2}{p'\varepsilon} \|\tilde{a}\|_{L^\infty(0,T;W^{-1,p'}(\Omega))}^{p'} \right] \\
& \quad \cdot \left[ \underbrace{C \frac{\varepsilon\ell}{p} \left( \sum_{n=0}^{s-2} \|u_{\kappa,\ell}^n\|_{W_0^{1,p}(\Omega)}^p \right)}_{\text{bounded by (4.8)}} + \frac{\varepsilon}{p} \|u_{\kappa,\ell}^s\|_{W_0^{1,p}(\Omega)}^p + \frac{\varepsilon}{p} \|u_0\|_{W_0^{1,p}(\Omega)}^p \right] \\
& \leq C(1 + \varepsilon \|u_{\kappa,\ell}^s\|_{W_0^{1,p}(\Omega)}^p).
\end{aligned}$$

Summing (4.15) over  $0 \leq n \leq s-1$ , with  $1 \leq s \leq N$ , applying Lemma 3.7, exploiting (4.19), the assumed stability condition (4.6) and the Poincaré-Friedrichs inequality gives

$$\begin{aligned} & \ell \sum_{n=0}^{s-1} \left\| \frac{|u_{\kappa,\ell}^{n+1}|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n}{\ell} \right\|_{L^2(\Omega)}^2 + \frac{\mu_1 c_0}{p} \|u_{\kappa,\ell}^s\|_{W_0^{1,p}(\Omega)}^p \\ & \leq \ell \sum_{n=0}^{s-1} \left\| \frac{|u_{\kappa,\ell}^{n+1}|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n}{\ell} \right\|_{L^2(\Omega)}^2 + \frac{\mu_1}{p} \sum_{n=0}^{s-1} \left\{ \|\nabla u_{\kappa,\ell}^{n+1}\|_{L^p(\Omega)}^p - \|\nabla u_{\kappa,\ell}^n\|_{L^p(\Omega)}^p \right\} \\ & \leq C(1 + \varepsilon \|u_{\kappa,\ell}^s\|_{W_0^{1,p}(\Omega)}^p), \end{aligned}$$

so that, in the end, we obtain the following estimate

$$\ell \sum_{n=0}^{s-1} \left\| \frac{|u_{\kappa,\ell}^{n+1}|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\frac{\alpha-2}{2}} u_{\kappa,\ell}^n}{\ell} \right\|_{L^2(\Omega)}^2 + \left( \frac{\mu_1 c_0}{p} - C\varepsilon \right) \|u_{\kappa,\ell}^s\|_{W_0^{1,p}(\Omega)}^p \leq C,$$

and the estimates (4.9) and (4.11) straightforwardly follow.

In order to establish the estimate (4.12), we exploit the boundedness of the  $p$ -Laplace operator (cf., e.g., Chapter 9 in [10]) and (4.11) so as to be in a position to evaluate

$$\begin{aligned} & \left\| \frac{|u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n}{\ell} \right\|_{W^{-1,p'}(\Omega)} \\ & \leq \left\| \nabla \cdot \left( \mu |\nabla u_{\kappa,\ell}^{n+1}|^{p-2} \nabla u_{\kappa,\ell}^{n+1} \right) \right\|_{W^{-1,p'}(\Omega)} + \frac{1}{\kappa} \|\{u_{\kappa,\ell}^{n+1}\}^-\|_{W^{-1,p'}(\Omega)} + \|\tilde{a}\|_{W^{1,p}(0,T;C^0(\bar{\Omega}))} \\ & \leq C \left( 1 + \frac{1}{\kappa} \right), \quad \text{for some } C > 0 \text{ independent of } N, \end{aligned}$$

for all  $0 \leq n \leq N-1$ , thus establishing the estimate (4.12).

By (4.7), for each  $0 \leq n \leq N$ , we have that

$$\begin{aligned} \|u_{\kappa,\ell}^n\|_{L^\alpha(\Omega)} &= \left( \int_{\Omega} |u_{\kappa,\ell}^n|^\alpha dx \right)^{1/\alpha} = \left( \int_{\Omega} |u_{\kappa,\ell}^n|^{\alpha-2} |u_{\kappa,\ell}^n|^{\frac{\alpha}{\alpha-1}} dx \right)^{1/\alpha} = \left( \int_{\Omega} |u_{\kappa,\ell}^n|^{\alpha-2} |u_{\kappa,\ell}^n|^{\alpha'} dx \right)^{\alpha'(\alpha-1)} \\ &= \| |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n \|_{L^{\alpha'}(\Omega)}^{\alpha'/\alpha}. \end{aligned}$$

Since the first term is uniformly bounded with respect to  $N$  and  $\kappa$ , we immediately infer that

$$(4.20) \quad \max_{0 \leq n \leq N} \| |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n \|_{L^{\alpha'}(\Omega)} \leq C,$$

for some  $C > 0$  independent of  $N$  and  $\kappa$ , thus establishing (4.13), and completing the proof.  $\square$

*Remark 4.3.* Observe that the following stability condition is sufficient to (4.6):

$$(4.21) \quad \{u_{\kappa,\ell}^{n+1}\}^- \geq \{u_{\kappa,\ell}^n\}^-, \quad \text{for all } 0 \leq n \leq N-1.$$

Indeed, by Lemma 3.2, we have that for all  $0 \leq n \leq N-1$

$$\begin{aligned} & \int_{\Omega} \{u_{\kappa,\ell}^n\}^- (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) dx = \int_{\{u_{\kappa,\ell}^n \geq 0\}} \left( \{u_{\kappa,\ell}^{n+1}\}^- - \{u_{\kappa,\ell}^n\}^- \right) (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) dx \\ & \quad + \int_{\{u_{\kappa,\ell}^n \leq 0\}} \{u_{\kappa,\ell}^{n+1}\}^- (u_{\kappa,\ell}^{n+1} + \{u_{\kappa,\ell}^n\}^-) dx \\ (4.22) \quad & \leq \int_{\{u_{\kappa,\ell}^n \leq 0\}} \{u_{\kappa,\ell}^{n+1}\}^- (\{u_{\kappa,\ell}^{n+1}\}^+ - \{u_{\kappa,\ell}^{n+1}\}^- + \{u_{\kappa,\ell}^n\}^-) dx \\ & = \int_{\{u_{\kappa,\ell}^n \leq 0\}} \{u_{\kappa,\ell}^{n+1}\}^- (-\{u_{\kappa,\ell}^{n+1}\}^- + \{u_{\kappa,\ell}^n\}^-) dx \leq 0, \end{aligned}$$

where the last inequality holds thanks to (4.21). Thanks to (4.22) and the positiveness of  $\kappa$ , we have that :

$$\frac{1}{\kappa} \sum_{n=0}^{s-1} \int_{\Omega} \{u_{\kappa,\ell}^n\}^- (u_{\kappa,\ell}^{n+1} - u_{\kappa,\ell}^n) \, dx \leq 0,$$

for all  $1 \leq s \leq N$ , which is a special case of the stability condition (4.6) appearing in the statement of Theorem 4.2.

The condition (4.21) is physically more realistic than the “abstract” stability condition (4.6). The stability condition (4.21) describes a regime of pure melting, which is a common regime glaciers undergo during Spring and Summer.  $\blacksquare$

Given  $\mathbf{v}_{\kappa,\ell} = \{v_{\kappa,\ell}^n\}_{n=0}^N$ , the function  $D_{\ell}(\Pi_{\ell}\mathbf{v}_{\kappa,\ell}) : (0, T) \rightarrow W_0^{1,p}(\Omega)$  is defined by

$$(4.23) \quad D_{\ell}(\Pi_{\ell}\mathbf{v}_{\kappa,\ell})(t) := \frac{v_{\kappa,\ell}^{n+1} - v_{\kappa,\ell}^n}{\ell}, \quad \text{for all } n\ell < t \leq (n+1)\ell, \quad 0 \leq n \leq N-1.$$

As a result of the estimates (4.7)-(4.13), we have that

$$(4.24) \quad \begin{aligned} & \{\Pi_{\ell}\mathbf{u}_{\kappa,\ell}\}_{\ell>0} \text{ is bounded in } L^{\infty}(0, T; W_0^{1,p}(\Omega)), \\ & \{B_{\kappa}(\Pi_{\ell}\mathbf{u}_{\kappa,\ell})\}_{\ell>0} \text{ is bounded in } L^{\infty}(0, T; W^{-1,p'}(\Omega)), \\ & \{|\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\frac{\alpha-2}{2}} \Pi_{\ell}\mathbf{u}_{\kappa,\ell}\}_{\ell>0} \text{ is bounded in } L^{\infty}(0, T; L^2(\Omega)), \\ & \{D_{\ell}(|\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\frac{\alpha-2}{2}} \Pi_{\ell}\mathbf{u}_{\kappa,\ell})\}_{\ell>0} \text{ is bounded in } L^{\infty}(0, T; L^2(\Omega)), \\ & \{|\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\alpha-2} \Pi_{\ell}\mathbf{u}_{\kappa,\ell}\}_{\ell>0} \text{ is bounded in } L^{\infty}(0, T; L^{\alpha'}(\Omega)), \\ & \{D_{\ell}(|\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\alpha-2} \Pi_{\ell}\mathbf{u}_{\kappa,\ell})\}_{\ell>0} \text{ is bounded in } L^{\infty}(0, T; W^{-1,p'}(\Omega)). \end{aligned}$$

Thanks to (4.24), we can establish the existence of solutions for Problem  $(\mathcal{P}_{\kappa})$ .

**Theorem 4.4.** *Let  $T > 0$ ,  $\Omega \subset \mathbb{R}^2$  and  $p$  be as in section 3 and let  $\alpha$  be as in (3.1). Let  $\kappa > 0$  be given, let  $N \geq 1$  be an integer, and define  $\ell := T/N$ . Assume that (H1)–(H4) hold. The a priori estimates (4.24) imply that the following convergence process takes place (recall that  $B_{\kappa}$  has been defined in (4.4)):*

$$(4.25) \quad \begin{aligned} & \Pi_{\ell}\mathbf{u}_{\kappa,\ell} \xrightarrow{*} u_{\kappa} \text{ in } L^{\infty}(0, T; W_0^{1,p}(\Omega)), \\ & B_{\kappa}(\Pi_{\ell}\mathbf{u}_{\kappa,\ell}) \xrightarrow{*} g_{\kappa} \text{ in } L^{\infty}(0, T; W^{-1,p'}(\Omega)), \\ & |\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\frac{\alpha-2}{2}} \Pi_{\ell}\mathbf{u}_{\kappa,\ell} \xrightarrow{*} v_{\kappa} \text{ in } L^{\infty}(0, T; L^2(\Omega)), \\ & D_{\ell}(|\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\frac{\alpha-2}{2}} \Pi_{\ell}\mathbf{u}_{\kappa,\ell}) \rightharpoonup \frac{dv_{\kappa}}{dt} \text{ in } L^2(0, T; L^2(\Omega)), \\ & |\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\alpha-2} \Pi_{\ell}\mathbf{u}_{\kappa,\ell} \xrightarrow{*} w_{\kappa} \text{ in } L^{\infty}(0, T; L^{\alpha'}(\Omega)), \\ & D_{\ell}(|\Pi_{\ell}\mathbf{u}_{\kappa,\ell}|^{\alpha-2} \Pi_{\ell}\mathbf{u}_{\kappa,\ell}) \xrightarrow{*} \frac{dw_{\kappa}}{dt} \text{ in } L^{\infty}(0, T; W^{-1,p'}(\Omega)), \\ & |u_{\kappa,\ell}^N|^{\alpha-2} u_{\kappa,\ell}^N \rightharpoonup \chi_{\kappa} \text{ in } L^{\alpha'}(\Omega). \end{aligned}$$

Besides, the weak-star limit  $u_{\kappa}$  recovered in the first convergence of (4.25) is a solution for Problem  $\mathcal{P}_{\kappa}$ , and the weak-star limits  $v_{\kappa}$  and  $w_{\kappa}$  satisfy

$$\begin{aligned} v_{\kappa} &= |u_{\kappa}|^{\frac{\alpha-2}{2}} u_{\kappa}, \\ w_{\kappa} &= |u_{\kappa}|^{\alpha-2} u_{\kappa}. \end{aligned}$$

*Proof.* The convergence process (4.25) holds by virtue of an application of the Banach-Alaoglu-Bourbaki theorem (cf., e.g., Theorem 3.6 of [7]) to the estimates (4.24) and (4.20). The nontrivial part of the proof amounts to identifying the weak-star limits  $v_{\kappa}$  and  $w_{\kappa}$  and to showing that the weak-star limit  $u_{\kappa}$  solves Problem  $\mathcal{P}_{\kappa}$ .

To begin with, we show that  $w_\kappa = |u_\kappa|^{\alpha-2}u_\kappa$ . Given any  $u \in W_0^{1,p}(\Omega)$ , we look for a number  $\beta \in \mathbb{R}$  for which

$$||u|^{\alpha-2}u|^{\beta-2}|u|^{\alpha-2}u = u.$$

Simple algebraic manipulations transform the latter into

$$|u|^{(\alpha-2)(\beta-2)+(\beta-2)+(\alpha-2)}u = u,$$

and we observe that a sufficient condition insuring this is that  $\beta$  satisfies

$$(\alpha - 1)(\beta - 2) + (\alpha - 2) = 0,$$

which is equivalent to writing

$$\beta = 2 + \frac{2 - \alpha}{\alpha - 1} = \frac{2\alpha - 2 + 2 - \alpha}{\alpha - 1} = \frac{\alpha -}{\alpha - 1} = \alpha'.$$

Let  $v := |u|^{\alpha-2}u$  and observe that if  $\beta = \alpha'$  then  $|v|^{\beta-2}v \in W_0^{1,p}(\Omega)$  so that the set

$$S := \{v; (|v|^{\alpha'-2}v) \in W_0^{1,p}(\Omega)\}$$

is non-empty. define the semi-norm

$$M(v) := \left\| \nabla(|v|^{\alpha'-2}v) \right\|_{L^p(\Omega)}^{\frac{1}{\alpha'-1}}, \quad \text{for all } v \in S,$$

and define the set

$$\mathcal{M} := \{v \in S; M(v) \leq 1\}.$$

An application of the Poincaré-Friedrichs inequality gives that there exists a constant  $c_0 = c_0(\Omega) > 0$  such that

$$\begin{aligned} 1 \geq M(v) &\geq c_0^{\frac{1}{\alpha'-1}} \left\| |v|^{\alpha'-2}v \right\|_{W_0^{1,p}(\Omega)}^{\frac{1}{\alpha'-1}} \geq c_0^{\frac{1}{\alpha'-1}} \left\| |v|^{\alpha'-2}v \right\|_{L^p(\Omega)}^{\frac{1}{\alpha'-1}} \\ &= c_0^{\frac{1}{\alpha'-1}} \left( \int_{\Omega} |v|^{\alpha'-2}v \right)^{1/(p(\alpha'-1))} = c_0^{\frac{1}{\alpha'-1}} \left( \int_{\Omega} |v|^{(\alpha'-1)p} dx \right)^{1/(p(\alpha'-1))} = c_0^{\frac{1}{\alpha'-1}} \|v\|_{L^{(\alpha'-1)p}(\Omega)}. \end{aligned}$$

Let  $\{v_k\}_{k=1}^{\infty}$  be a sequence in  $\mathcal{M}$ . Since, by the Rellich-Kondrašov theorem, we have that  $W_0^{1,p}(\Omega) \hookrightarrow L^p(\Omega)$  we obtain that, up to passing to a subsequence, there exists an element  $w \in L^p(\Omega)$  such that

$$(4.26) \quad (|v_k|^{\alpha'-2}v_k) \rightarrow w, \quad \text{in } L^p(\Omega), \quad \text{as } k \rightarrow \infty.$$

Since  $1 < \alpha < 2$  and  $2.8 \leq p \leq 5$ , then  $\alpha' > 2$  and it thus results that  $1 < p' < p < (\alpha' - 1)p < \infty$  and that  $\{v_k\}_{k=1}^{\infty}$  is bounded in  $L^{p'}(\Omega)$ . The reflexivity of  $L^{p'}(\Omega)$  puts us in a position to apply the Banach-Eberlein-Smulian theorem (cf., e.g., Theorem 5.14-4 of [10]) and extract a subsequence, still denoted  $\{v_k\}_{k=1}^{\infty}$ , that weakly converges to an element  $v \in L^{p'}(\Omega)$ . Consider the mapping

$$v \in L^{p'}(\Omega) \mapsto (|v|^{\alpha'-2}v) \in L^p(\Omega),$$

and observe that this mapping is hemi-continuous and monotone, being the mapping  $\xi \in \mathbb{R} \rightarrow (|\xi|^{\alpha'-2}\xi) \in \mathbb{R}$ , with  $\alpha' > 2$  thanks to (3.1), continuous and monotone. Therefore, an application of Theorem 9.13-2 of [10] gives that  $w = |v|^{\alpha'-2}v \in L^p(\Omega)$ . Therefore, the convergence (4.26) reads:

$$(4.27) \quad (|v_k|^{\alpha'-2}v_k) \rightarrow w = (|v|^{\alpha'-2}v), \quad \text{in } L^p(\Omega), \quad \text{as } k \rightarrow \infty.$$

In order to show that  $\mathcal{M}$  is relatively compact in  $L^{(\alpha'-1)p}(\Omega)$ , we have to show that every sequence  $\{v_k\}_{k=1}^{\infty} \subset \mathcal{M}$  admits a convergent subsequence in  $L^{(\alpha'-1)p}(\Omega)$ . We will see that any of the subsequences satisfying (4.27) will serve for this purpose. In this direction, let  $\{v_k\}_{k=1}^{\infty}$  denote one of the subsequences satisfying (4.27) and let  $v \in L^{(\alpha'-1)p}(\Omega)$  be the weak limit. Since  $1 < \alpha < 2$

by (3.1), then  $\alpha' > 2$  and, therefore, an application of Lemma 3.2, the triangle inequality and (4.27) gives:

$$\begin{aligned} & \left( \int_{\Omega} |v_k - v|^{(\alpha'-1)p} dx \right)^{1/((\alpha'-1)p)} \leq \left( \int_{\Omega} \left| |v_k|^{\alpha'-1} - |v|^{\alpha'-1} \right|^p dx \right)^{1/((\alpha'-1)p)} \\ & = \left( \int_{\Omega} \left| \left| |v_k|^{\alpha'-2} v_k \right| - \left| |v|^{\alpha'-2} v \right| \right|^p dx \right)^{1/((\alpha'-1)p)} \leq \left( \int_{\Omega} \left| |v_k|^{\alpha'-2} v_k - |v|^{\alpha'-2} v \right|^p dx \right)^{1/((\alpha'-1)p)} \\ & = \left\| |v_k|^{\alpha'-2} v_k - |v|^{\alpha'-2} v \right\|_{L^p(\Omega)}^{1/(\alpha'-1)} \rightarrow 0 \text{ as } k \rightarrow \infty. \end{aligned}$$

The latter shows that

$$v_k \rightarrow v, \quad \text{in } L^{(\alpha'-1)p}(\Omega) \text{ as } k \rightarrow \infty,$$

in turn implying that the set  $\mathcal{M}$  is relatively compact in  $L^{(\alpha'-1)p}(\Omega)$ , as it was to be proved. The established relative compactness of the set  $\mathcal{M}$  in  $L^{(\alpha'-1)p}(\Omega)$  and the sixth convergence in the process (4.25) (which in turn implies that the time-derivatives in the sense of distributions are uniformly bounded) allow us apply Dubinskii's compactness theorem (Theorem 3.10) with  $A_0 = L^{(\alpha'-1)p}(\Omega)$ ,  $A_1 = W^{-1,p'}(\Omega)$ ,  $q_0 = q_1 = 2$ , so that

$$(4.28) \quad |\Pi_{\ell} \mathbf{u}_{\kappa, \ell}|^{\alpha-2} \Pi_{\ell} \mathbf{u}_{\kappa, \ell} \rightarrow w_{\kappa}, \quad \text{in } L^2(0, T; L^{(\alpha'-1)p}(\Omega)) \text{ as } \ell \rightarrow 0,$$

where, once again, the monotonicity of  $\xi \in \mathbb{R} \mapsto |\xi|^{\alpha-2} \xi$ , the first convergence in the process (4.25) and Theorem 9.13-2 of [10] imply that

$$w_{\kappa} = |u_{\kappa}|^{\alpha-2} u_{\kappa}.$$

Second, we show that  $v_{\kappa} = |u_{\kappa}|^{\frac{\alpha-2}{2}} u_{\kappa}$ . Given any  $u \in W_0^{1,p}(\Omega)$ , we look for a number  $\beta \in \mathbb{R}$  for which

$$\left| |u|^{\frac{\alpha-2}{2}} u \right|^{\frac{\beta-2}{2}} |u|^{\frac{\alpha-2}{2}} u = u.$$

We observe that a sufficient condition insuring this is that  $\beta$  satisfies

$$\left( \frac{\alpha-2}{2} + 1 \right) \frac{\beta-2}{2} + \frac{\alpha-2}{2} = 0,$$

which is equivalent to writing

$$\beta = 2 + 2 \left( \frac{2-\alpha}{2} \frac{2}{\alpha} \right) = \frac{4}{\alpha}.$$

Let  $v := |u|^{\frac{\alpha-2}{2}} u$  and observe that if  $\beta = 4/\alpha$  then  $|v|^{\frac{\beta-2}{2}} v \in W_0^{1,p}(\Omega)$  so that the set

$$\tilde{S} := \{v; (|v|^{\frac{(4/\alpha)-2}{2}} v) \in W_0^{1,p}(\Omega)\}$$

is non-empty. define the semi-norm

$$\tilde{M}(v) := \left\| \nabla (|v|^{\frac{(4/\alpha)-2}{2}} v) \right\|_{L^p(\Omega)}^{\frac{\alpha}{2}} = \left\| \nabla (|v|^{\frac{2-\alpha}{\alpha}} v) \right\|_{L^p(\Omega)}^{\frac{\alpha}{2}}, \quad \text{for all } v \in \tilde{S},$$

and define the set

$$\tilde{\mathcal{M}} := \{v \in \tilde{S}; \tilde{M}(v) \leq 1\}.$$

An application of the Poincaré-Friedrichs inequality gives that there exists a constant  $c_0 = c_0(\Omega) > 0$  such that

$$\begin{aligned} 1 \geq \tilde{M}(v) & \geq c_0^{\frac{\alpha}{2}} \left\| |v|^{\frac{2-\alpha}{\alpha}} v \right\|_{W_0^{1,p}(\Omega)}^{\frac{\alpha}{2}} \geq c_0^{\frac{\alpha}{2}} \left\| |v|^{\frac{2-\alpha}{\alpha}} v \right\|_{L^p(\Omega)}^{\frac{\alpha}{2}} = c_0^{\frac{\alpha}{2}} \left( \int_{\Omega} \left| |v|^{\frac{2-\alpha}{\alpha}} v \right|^p dx \right)^{\alpha/(2p)} \\ & = c_0^{\frac{\alpha}{2}} \left( \int_{\Omega} |v|^{\frac{2p}{\alpha}} dx \right)^{\alpha/(2p)} = c_0^{\frac{\alpha}{2}} \|v\|_{L^{\frac{2p}{\alpha}}(\Omega)}. \end{aligned}$$

Let  $\{v_k\}_{k=1}^\infty$  be a sequence in  $\tilde{\mathcal{M}}$ . Since, by the Rellich-Kondrašov theorem, we have that  $W_0^{1,p}(\Omega) \hookrightarrow L^p(\Omega)$  we obtain that, up to passing to a subsequence, there exists an element  $w \in L^p(\Omega)$  such that

$$(4.29) \quad (|v_k|^{\frac{2-\alpha}{2}} v_k) \rightarrow w, \quad \text{in } L^p(\Omega), \quad \text{as } k \rightarrow \infty.$$

Since  $1 < \alpha < 2$  and  $2.8 \leq p \leq 5$ , it thus results that  $1 \leq p' < 2 < p < \frac{2p}{\alpha} < 2p < \infty$  and that  $\{v_k\}_{k=1}^\infty$  is bounded in  $L^{\frac{2p}{\alpha}}(\Omega)$ . The reflexivity of  $L^{\frac{2p}{\alpha}}(\Omega)$  puts us in a position to apply the Banach-Eberlein-Smulian theorem (cf., e.g., Theorem 5.14-4 of [10]) and extract a subsequence, still denoted  $\{v_k\}_{k=1}^\infty$ , that weakly converges to an element  $v \in L^{p'}(\Omega)$ . Consider the mapping

$$v \in L^{p'}(\Omega) \mapsto (|v|^{\frac{2-\alpha}{2}} v) \in L^p(\Omega),$$

and observe that this mapping is hemi-continuous and monotone, being the mapping  $\xi \in \mathbb{R} \rightarrow (|\xi|^{\frac{2-\alpha}{2}} \xi) \in \mathbb{R}$  continuous and monotone. Therefore, an application of Theorem 9.13-2 of [10] gives that  $w = |v|^{\frac{2-\alpha}{\alpha}} v \in L^p(\Omega)$ . Therefore, the convergence (4.26) reads:

$$(4.30) \quad (|v_k|^{\frac{2-\alpha}{\alpha}} v_k) \rightarrow w = (|v|^{\frac{2-\alpha}{\alpha}} v), \quad \text{in } L^p(\Omega), \quad \text{as } k \rightarrow \infty.$$

In order to show that  $\tilde{\mathcal{M}}$  is relatively compact in  $L^{\frac{2p}{\alpha}}(\Omega)$ , we have to show that every sequence  $\{v_k\}_{k=1}^\infty \subset \tilde{\mathcal{M}}$  admits a convergent subsequence in  $L^{\frac{2p}{\alpha}}(\Omega)$ . We will see that any of the subsequences satisfying (4.27) will serve for this purpose. In this direction, let  $\{v_k\}_{k=1}^\infty$  denote one of the subsequences satisfying (4.27) and let  $v \in L^{\frac{2p}{\alpha}}(\Omega)$  be the weak limit. An application of Lemma 3.2, the triangle inequality and (4.27) gives:

$$\begin{aligned} & \left( \int_{\Omega} |v_k - v|^{\frac{2p}{\alpha}} dx \right)^{\alpha/(2p)} \leq \left( \int_{\Omega} \left| |v_k|^{\frac{2}{\alpha}} - |v|^{\frac{2}{\alpha}} \right|^p dx \right)^{\alpha/(2p)} \\ & = \left( \int_{\Omega} \left| \left| |v_k|^{\frac{2-\alpha}{\alpha}} v_k \right| - \left| |v|^{\frac{2-\alpha}{\alpha}} v \right| \right|^p dx \right)^{\alpha/(2p)} \leq \left( \int_{\Omega} \left| |v_k|^{\frac{2-\alpha}{\alpha}} v_k - |v|^{\frac{2-\alpha}{\alpha}} v \right|^p dx \right)^{\alpha/(2p)} \\ & = \left\| |v_k|^{\frac{2-\alpha}{\alpha}} v_k - |v|^{\frac{2-\alpha}{\alpha}} v \right\|_{L^p(\Omega)}^{\alpha/2} \rightarrow 0 \text{ as } k \rightarrow \infty. \end{aligned}$$

The latter shows that

$$v_k \rightarrow v, \quad \text{in } L^{\frac{2p}{\alpha}}(\Omega) \text{ as } k \rightarrow \infty,$$

in turn implying that the set  $\tilde{\mathcal{M}}$  is relatively compact in  $L^{\frac{2p}{\alpha}}(\Omega)$ , as it was to be proved. The established relative compactness of the set  $\tilde{\mathcal{M}}$  in  $L^{\frac{2p}{\alpha}}(\Omega)$  and the fourth convergence in the process (4.25) (which in turn implies that the time-derivatives in the sense of distributions are uniformly bounded) allow us apply Dubinskii's compactness theorem (Theorem 3.10) with  $A_0 = L^{\frac{2p}{\alpha}}(\Omega)$ ,  $A_1 = L^2(\Omega)$ ,  $q_0 = q_1 = 2$ , so that

$$(4.31) \quad |\Pi_{\ell} \mathbf{u}_{\kappa, \ell}|^{\frac{\alpha-2}{2}} \Pi_{\ell} \mathbf{u}_{\kappa, \ell} \rightarrow v_{\kappa}, \quad \text{in } L^2(0, T; L^{\frac{2p}{\alpha}}(\Omega)) \text{ as } \ell \rightarrow 0,$$

where, once again, the monotonicity of  $\xi \in \mathbb{R} \mapsto |\xi|^{\frac{\alpha-2}{2}} \xi$ , the first convergence in the process (4.25) and Theorem 9.13-2 of [10] imply that

$$v_{\kappa} = |u_{\kappa}|^{\frac{\alpha-2}{2}} u_{\kappa}.$$

We are left to show that the weak-star limit  $u_\kappa$  is a solution for Problem  $\mathcal{P}_\kappa$ . Let  $v \in \mathcal{D}(\Omega)$  and let  $\psi \in \mathcal{C}^1([0, T])$ . For each  $0 \leq n \leq N - 1$ , multiply (4.1) by  $\{\psi(n\ell)\}$ , getting

$$\begin{aligned}
(4.32) \quad & \frac{\psi(n\ell)}{\ell} \int_{\Omega} \{|u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n\} v \, dx \\
& + \psi(n\ell) \int_{\Omega} \mu |\nabla u_{\kappa,\ell}^{n+1}|^{p-2} \nabla u_{\kappa,\ell}^{n+1} \cdot \nabla v \, dx - \psi(n\ell) \int_{\Omega} \frac{\{u_{\kappa,\ell}^{n+1}\}^-}{\kappa} v \, dx \\
& = \int_{\Omega} \left( \frac{1}{\ell} \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) \, dt \right) v \psi(n\ell) \, dx.
\end{aligned}$$

Multiplying (4.32) by  $\ell$  and summing over  $0 \leq n \leq N - 1$ , we obtain

$$\begin{aligned}
(4.33) \quad & \sum_{n=0}^{N-1} \ell \int_{\Omega} \frac{|u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n}{\ell} v \psi(n\ell) \, dx \\
& + \sum_{n=0}^{N-1} \ell \int_{\Omega} \mu |\nabla u_{\kappa,\ell}^{n+1}|^{p-2} \nabla u_{\kappa,\ell}^{n+1} \cdot \nabla (\psi(n\ell)v) \, dx \\
& - \frac{1}{\kappa} \sum_{n=0}^{N-1} \ell \int_{\Omega} \{u_{\kappa,\ell}^{n+1}\}^- v \psi(n\ell) \, dx = \sum_{n=0}^{N-1} \ell \int_{\Omega} \left( \frac{1}{\ell} \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) \, dt \right) v \psi(n\ell) \, dx.
\end{aligned}$$

For the sake of brevity, define  $\psi_\ell(t) := \psi(n\ell)$ ,  $n\ell \leq t \leq (n+1)\ell$  and  $0 \leq n \leq N - 1$ . Equation (4.33) can be thus re-arranged as follows:

$$\begin{aligned}
(4.34) \quad & \int_0^T \int_{\Omega} D_\ell(|\Pi_\ell \mathbf{u}_{\kappa,\ell}|^{\alpha-2} \Pi_\ell \mathbf{u}_{\kappa,\ell}) v \, dx \psi_\ell(t) \, dt \\
& - \int_0^T \int_{\Omega} \nabla \cdot (\mu |\nabla(\Pi_\ell \mathbf{u}_{\kappa,\ell})|^{p-2} \nabla(\Pi_\ell \mathbf{u}_{\kappa,\ell})) v \, dx \psi_\ell(t) \, dt \\
& - \frac{1}{\kappa} \int_0^T \int_{\Omega} \{\Pi_\ell \mathbf{u}_{\kappa,\ell}\}^- v \, dx \psi_\ell(t) \, dt = \int_0^T \left( \int_{\Omega} \tilde{a}(t) v \, dx \right) \psi_\ell(t) \, dt.
\end{aligned}$$

Letting  $\ell \rightarrow 0$  and exploiting the convergence process (4.25) and the Riemann integrability of  $\psi$ , we obtain:

$$\begin{aligned}
(4.35) \quad & \int_0^T \left\langle \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa), v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \psi(t) \, dt + \int_0^T \int_{\Omega} g_\kappa(t) v \, dx \psi(t) \, dt \\
& = \int_0^T \int_{\Omega} \tilde{a}(t) v \, dx \psi(t) \, dt.
\end{aligned}$$

Let us rearrange the first term on the left-hand side of equation (4.33) as follows:

$$\begin{aligned}
& \frac{1}{\ell} \sum_{n=0}^{N-1} \ell \int_{\Omega} \{ |u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} - |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n \} v \psi(n\ell) \, dx \\
&= \int_{\Omega} \left\{ [ |u_{\kappa,\ell}^1|^{\alpha-2} u_{\kappa,\ell}^1 - |u_0|^{\alpha-2} u_0 ] v \psi(0) \right. \\
&\quad + [ |u_{\kappa,\ell}^2|^{\alpha-2} u_{\kappa,\ell}^2 - |u_{\kappa,\ell}^1|^{\alpha-2} u_{\kappa,\ell}^1 ] v \psi(\ell) \\
&\quad + \dots \\
&\quad + [ |u_{\kappa,\ell}^{N-1}|^{\alpha-2} u_{\kappa,\ell}^{N-1} - |u_{\kappa,\ell}^{N-2}|^{\alpha-2} u_{\kappa,\ell}^{N-2} ] v \psi((N-1)\ell) \\
&\quad \left. [ |u_{\kappa,\ell}^N|^{\alpha-2} u_{\kappa,\ell}^N - |u_{\kappa,\ell}^{N-1}|^{\alpha-2} u_{\kappa,\ell}^{N-1} ] v \psi(T) \right\} dx \\
&= \int_{\Omega} -|u_0|^{\alpha-2} u_0 v \psi(0) \, dx \\
&\quad + \int_{\Omega} \left\{ [ -|u_{\kappa,\ell}^1|^{\alpha-2} u_{\kappa,\ell}^1 v (\psi(\ell) - \psi(0)) ] + [ -|u_{\kappa,\ell}^2|^{\alpha-2} u_{\kappa,\ell}^2 v (\psi(2\ell) - \psi(\ell)) ] \right. \\
&\quad + \dots \\
&\quad + [ -|u_{\kappa,\ell}^{N-2}|^{\alpha-2} u_{\kappa,\ell}^{N-2} v (\psi((N-1)\ell) - \psi((N-2)\ell)) ] \\
&\quad \left. + [ -|u_{\kappa,\ell}^{N-1}|^{\alpha-2} u_{\kappa,\ell}^{N-1} v (\psi(T) - \psi((N-1)\ell)) ] \right\} dx \\
&\quad + \int_{\Omega} |u_{\kappa,\ell}^N|^{\alpha-2} u_{\kappa,\ell}^N v \psi(T) \, dx \\
&= - \sum_{n=0}^{N-1} \ell \int_{\Omega} |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n v \left[ \frac{\psi(n\ell) - \psi((n-1)\ell)}{\ell} \right] \, dx \\
&\quad + \int_{\Omega} |u_{\kappa,\ell}^N|^{\alpha-2} u_{\kappa,\ell}^N v \psi(T) \, dx - \int_{\Omega} |u_0|^{\alpha-2} u_0 v \psi(0) \, dx.
\end{aligned}$$

Therefore, equation (4.33) can be thoroughly re-arranged as follows:

$$\begin{aligned}
& \int_{\Omega} |u_{\kappa,\ell}^N|^{\alpha-2} u_{\kappa,\ell}^N v \psi(T) \, dx - \int_{\Omega} |u_0|^{\alpha-2} u_0 v \psi(0) \, dx \\
&\quad - \sum_{n=0}^{N-1} \ell \int_{\Omega} |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n v \left[ \frac{\psi(n\ell) - \psi((n-1)\ell)}{\ell} \right] \, dx \\
(4.36) \quad & + \sum_{n=0}^{N-1} \ell \int_{\Omega} \mu |\nabla u_{\kappa,\ell}^{n+1}|^{p-2} \nabla u_{\kappa,\ell}^{n+1} \cdot \nabla (\psi(n\ell) v) \, dx \\
& - \frac{1}{\kappa} \sum_{n=0}^{N-1} \ell \int_{\Omega} \{ u_{\kappa,\ell}^{n+1} \}^- v \psi(n\ell) \, dx = \sum_{n=0}^{N-1} \ell \int_{\Omega} \left( \frac{1}{\ell} \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) \, dt \right) v \psi(n\ell) \, dx.
\end{aligned}$$

Letting  $\ell \rightarrow 0$  in (4.36) thus gives:

$$\begin{aligned}
(4.37) \quad & - \int_0^T \int_{\Omega} |u_{\kappa}|^{\alpha-2} u_{\kappa} v \, dx \frac{d\psi}{dt} \, dt + \int_0^T \langle g_{\kappa}(t), v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \psi(t) \, dt \\
& + \int_0^T \int_{\Omega} [\chi_{\kappa} \psi(T) - |u_0|^{\alpha-2} u_0 \psi(0)] v \, dx = \int_0^T \int_{\Omega} \tilde{a}(t) v \, dx \psi(t) \, dt.
\end{aligned}$$

Observe that an application of the Sobolev embedding theorem (cf., e.g., Theorem 6.6-1 of [10]) and an integration by parts in (4.35) give:

$$\begin{aligned}
(4.38) \quad & - \int_0^T \int_{\Omega} |u_{\kappa}|^{\alpha-2} u_{\kappa} v \, dx \frac{d\psi}{dt} \, dt + \langle |u_{\kappa}(T)|^{\alpha-2} u_{\kappa}(T), \psi(T)v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \\
& - \int_{\Omega} |u_{\kappa}(0)|^{\alpha-2} u_{\kappa}(0) \psi(0) v \, dx + \int_0^T \langle g_{\kappa}(t), v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \psi(t) \, dt \\
& = \int_0^T \int_{\Omega} \tilde{a}(t) v \, dx \psi(t) \, dt.
\end{aligned}$$

Comparing equations (4.37) and (4.38) gives

$$\begin{aligned}
(4.39) \quad & \langle |u_{\kappa}(T)|^{\alpha-2} u_{\kappa}(T), \psi(T)v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} - \int_{\Omega} |u_{\kappa}(0)|^{\alpha-2} u_{\kappa}(0) \psi(0) v \, dx \\
& = \int_0^T \int_{\Omega} [\chi_{\kappa} \psi(T) - |u_0|^{\alpha-2} u_0 \psi(0)] v \, dx
\end{aligned}$$

Since  $\psi \in \mathcal{C}^1([0, T])$  is arbitrarily chosen, let us specialize  $\psi$  in (4.39) in a way such that  $\psi(0) = 0$ . We obtain

$$(4.40) \quad \langle |u_{\kappa}(T)|^{\alpha-2} u_{\kappa}(T) - \chi_{\kappa}, \psi(T)v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} = 0, \quad \text{for all } v \in \mathcal{D}(\Omega).$$

Since the duality in (4.40) is continuous with respect to  $v$ , and since  $\mathcal{D}(\Omega)$  is, by definition, dense in  $W_0^{1,p}(\Omega)$ , we immediately infer that:

$$(4.41) \quad |u_{\kappa}(T)|^{\alpha-2} u_{\kappa}(T) = \chi_{\kappa} \in L^{\alpha'}(\Omega).$$

Thanks to Lemma 3.3, it is immediate to observe that

$$|\chi_{\kappa}|^{\alpha'-2} \chi_{\kappa} = ||u_{\kappa}(T)|^{\alpha-2} u_{\kappa}(T)|^{\alpha'-2} \chi_{\kappa} = |u_{\kappa}(T)|^{2-\alpha} [|u_{\kappa}(T)|^{\alpha-2} u_{\kappa}(T)] = u_{\kappa}(T) \in L^{\alpha}(\Omega).$$

Let us now specialize  $\psi$  in (4.39) in a way such that  $\psi(T) = 0$ . We obtain

$$(4.42) \quad \int_{\Omega} (|u_{\kappa}(0)|^{\alpha-2} u_{\kappa}(0) - |u_0|^{\alpha-2} u_0) \psi(0) v \, dx = 0, \quad \text{for all } v \in \mathcal{D}(\Omega).$$

Since the integration in (4.42) is continuous with respect to  $v$ , and since  $\mathcal{D}(\Omega)$  is, by definition, dense in  $W_0^{1,p}(\Omega)$ , we immediately infer that:

$$|u_{\kappa}(0)|^{\alpha-2} u_{\kappa}(0) = |u_0|^{\alpha-2} u_0,$$

so that the injectivity of the monotone and hemi-continuous operator  $\xi \mapsto |\xi|^{\alpha-2} \xi$  in turn implies that:

$$(4.43) \quad u_{\kappa}(0) = u_0 \in K.$$

The last thing to check is that  $g_{\kappa} = B_{\kappa}(u_{\kappa})$ . For each  $0 \leq n \leq N-1$ , multiply (4.1) by  $u_{\kappa,\ell}^{n+1}$  and apply Lemma 3.7, thus getting

$$\begin{aligned}
& \frac{1}{\alpha'} \sum_{n=0}^{N-1} \left\{ \left\| |u_{\kappa,\ell}^{n+1}|^{\alpha-2} u_{\kappa,\ell}^{n+1} \right\|_{L^{\alpha'}(\Omega)}^{\alpha'} - \left\| |u_{\kappa,\ell}^n|^{\alpha-2} u_{\kappa,\ell}^n \right\|_{L^{\alpha'}(\Omega)}^{\alpha'} \right\} \\
& + \sum_{n=0}^{N-1} \ell \left\langle B_{\kappa}(u_{\kappa,\ell}^{n+1}), u_{\kappa,\ell}^{n+1} \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \\
& \leq \sum_{n=0}^{N-1} \ell \int_{\Omega} \left( \frac{1}{\ell} \int_{n\ell}^{(n+1)\ell} \tilde{a}(t) \, dt \right) u_{\kappa,\ell}^{n+1} \, dx,
\end{aligned}$$

which in turn implies:

$$\begin{aligned}
(4.44) \quad & \frac{1}{\alpha'} \left\| |u_{\kappa,\ell}^N|^{\alpha-2} u_{\kappa,\ell}^N \right\|_{L^{\alpha'}(\Omega)}^{\alpha'} \\
& + \int_0^T \langle B_\kappa(\Pi_\ell \mathbf{u}_{\kappa,\ell}), \Pi_\ell \mathbf{u}_{\kappa,\ell} \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \\
& \leq \int_0^T \int_\Omega \tilde{a}(t) \Pi_\ell \mathbf{u}_{\kappa,\ell} \, dx \, dt \frac{1}{\alpha'} \left\| |u_0|^{\alpha-2} u_0 \right\|_{L^{\alpha'}(\Omega)}^{\alpha'}.
\end{aligned}$$

We now exploit a trick developed by Minty [35] which is, by now, classical. Passing to the  $\liminf$  as  $\ell \rightarrow 0$  in (4.44) and keeping in mind the convergence process (4.25) as well as the identities (4.41)–(4.43) gives, on the one hand:

$$\begin{aligned}
(4.45) \quad & \frac{1}{\alpha'} \|u_\kappa(T)\|_{L^\alpha(\Omega)}^\alpha + \liminf_{\ell \rightarrow 0} \int_0^T \langle B_\kappa(\Pi_\ell \mathbf{u}_{\kappa,\ell}), \Pi_\ell \mathbf{u}_{\kappa,\ell} \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \, dt \\
& = \frac{1}{\alpha'} \left\| |u_\kappa(T)|^{\alpha-2} u_\kappa(T) \right\|_{L^{\alpha'}(\Omega)}^{\alpha'} + \liminf_{\ell \rightarrow 0} \int_0^T \langle B_\kappa(\Pi_\ell \mathbf{u}_{\kappa,\ell}), \Pi_\ell \mathbf{u}_{\kappa,\ell} \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \, dt \\
& \leq \int_0^T \int_\Omega \tilde{a}(t) u_\kappa \, dx \, dt + \frac{1}{\alpha'} \left\| |u_0|^{\alpha-2} u_0 \right\|_{L^{\alpha'}(\Omega)}^{\alpha'} = \int_0^T \int_\Omega \tilde{a}(t) v \, dx \, \psi(t) \, dt + \frac{1}{\alpha'} \|u_0\|_{L^\alpha(\Omega)}^\alpha.
\end{aligned}$$

On the other hand, the specializations  $v = u_\kappa$  and  $\psi \equiv 1$  in (4.35), and an application of Lemma 3.8 give:

$$\begin{aligned}
(4.46) \quad & \frac{1}{\alpha'} \|u_\kappa(T)\|_{L^\alpha(\Omega)}^\alpha + \int_0^T \langle g_\kappa(t), v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \psi(t) \, dt \\
& = \int_0^T \int_\Omega \tilde{a}(t) v \, dx \, \psi(t) \, dt + \frac{1}{\alpha'} \|u_0\|_{L^\alpha(\Omega)}^\alpha.
\end{aligned}$$

Combining (4.45) and (4.46) gives:

$$(4.47) \quad \liminf_{\ell \rightarrow 0} \int_0^T \langle B_\kappa(\Pi_\ell \mathbf{u}_{\kappa,\ell}), \Pi_\ell \mathbf{u}_{\kappa,\ell} \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \leq \int_0^T \langle g_\kappa(t), v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \psi(t) \, dt,$$

Let  $w \in L^p(0, T; W_0^{1,p}(\Omega))$ . An application of the strict monotonicity of the operator  $B_\kappa$  defined in (4.4) and (4.47) gives:

$$\begin{aligned}
(4.48) \quad & \int_0^T \langle g_\kappa - B_\kappa w, u_\kappa - w \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \, dt \\
& \geq \liminf_{\ell \rightarrow 0} \int_0^T \langle B_\kappa(\Pi_\ell \mathbf{u}_{\kappa,\ell}) - B_\kappa w, \Pi_\ell \mathbf{u}_{\kappa,\ell} - w \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \, dt \geq 0.
\end{aligned}$$

Let  $\lambda > 0$  and specialize  $w = u_\kappa - \lambda v$  in (4.48), where  $v$  is arbitrarily chosen in  $L^p(0, T; W_0^{1,p}(\Omega))$ . We obtain that:

$$(4.49) \quad \int_0^T \langle g_\kappa - B_\kappa(u_\kappa - \lambda v), \lambda v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \, dt \geq 0.$$

Dividing (4.49) by  $\lambda > 0$  and letting  $\lambda \rightarrow 0^+$  gives:

$$(4.50) \quad \int_0^T \langle g_\kappa - B_\kappa u_\kappa, v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \, dt \geq 0.$$

By the arbitrariness of  $v \in L^p(0, T; W_0^{1,p}(\Omega))$ , we obtain that:

$$(4.51) \quad g_\kappa = B_\kappa u_\kappa \in L^\infty(0, T; W^{-1,p'}(\Omega)),$$

which thus implies that  $u_\kappa$  is a solution of Problem  $\mathcal{P}_\kappa$ . This completes the proof.  $\square$

The next step, which constitutes the main novelty of this paper, is the passage to the limit as  $\kappa \rightarrow 0^+$  as well as the recovery of the actual model governing the variation of shallow ice sheets in time.

The estimates (4.7), (4.10), (4.12) and (4.13) in turn imply that there exists a constant  $C > 0$  independent of  $\kappa$  such that

$$\begin{aligned} \|u_\kappa\|_{L^\infty(0,T;W_0^{1,p}(\Omega))} &\leq C, \\ \left\| |u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa \right\|_{L^\infty(0,T;L^2(\Omega))} &\leq C, \\ \left\| \frac{d}{dt} (|u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa) \right\|_{L^2(0,T;L^2(\Omega))} &\leq C, \\ \| |u_\kappa|^{\alpha-2} u_\kappa \|_{L^\infty(0,T;L^{\alpha'}(\Omega))} &\leq C, \\ \left\| \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa) \right\|_{L^\infty(0,T;W^{-1,p'}(\Omega))} &\leq C \left( 1 + \frac{1}{\kappa} \right). \end{aligned}$$

By the Banach-Alaoglu-Bourbaki theorem (cf., e.g., Theorem 3.6 of [7]) we infer that, up to passing to a subsequence still denoted by  $\{u_\kappa\}_{\kappa>0}$ , the following convergences hold:

$$(4.52) \quad \begin{aligned} u_\kappa &\overset{*}{\rightharpoonup} u, \text{ in } L^\infty(0,T;W_0^{1,p}(\Omega)), \\ |u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa &\overset{*}{\rightharpoonup} v, \text{ in } L^\infty(0,T;L^2(\Omega)), \\ \frac{d}{dt} (|u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa) &\rightharpoonup \frac{dv}{dt}, \text{ in } L^\infty(0,T;L^2(\Omega)), \\ |u_\kappa|^{\alpha-2} u_\kappa &\overset{*}{\rightharpoonup} w, \text{ in } L^\infty(0,T;L^{\alpha'}(\Omega)). \end{aligned}$$

Using the same argument as in Theorem 4.4, an application of Dubinskii's theorem (Theorem 3.9) with  $A_0 := L^{\frac{2p}{\alpha}}(\Omega)$ ,  $A_1 := L^2(\Omega)$ ,  $q_0 = \infty$  and  $q_1 = 2$  gives that:

$$\left\{ |u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa \right\}_{\kappa>0} \text{ strongly converges in } L^\infty(0,T;L^{\frac{2p}{\alpha}}(\Omega)).$$

Moreover, by Lemma 2 of [1], it can be established that:

$$\left\{ |u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa \right\}_{\kappa>0} \text{ strongly converges in } C^0([0,T];L^2(\Omega)).$$

Therefore, an application of Lemma 3.5 gives that:

$$(4.53) \quad u_\kappa \rightarrow u, \quad \text{in } C^0([0,T];L^\alpha(\Omega)).$$

The monotonicity argument in Theorem 4.4 and the third convergence in (4.52) in turn imply that:

$$v = |u|^{\frac{\alpha-2}{2}} u \in H^1(0,T;L^2(\Omega)).$$

Define the linear and continuous operator  $L_0 : C^0([0,T];L^\alpha(\Omega)) \rightarrow L^\alpha(\Omega)$  by:

$$L_0(v) := v(0), \quad \text{for all } v \in C^0([0,T];L^\alpha(\Omega)).$$

By (4.53) and the continuity of  $L_0$ , we have that  $u_\kappa(0) \rightarrow u(0)$  in  $L^\alpha(\Omega)$ . However, since  $u_\kappa(0) = u_0$  for all  $\kappa > 0$ , we immediately deduce that  $u(0) = u_0 \in K$  and so that the weak-star limit  $u$  satisfies the expected initial condition.

Note that the variational equations in Problem  $\mathcal{P}_\kappa$  take the following equivalent form:

$$(4.54) \quad \frac{d}{dt} (|u_\kappa(t)|^{\alpha-2} u_\kappa(t)) - \nabla \cdot (\mu |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t)) - \frac{1}{\kappa} \{u_\kappa(t)\}^- = \tilde{a}(t), \quad \text{in } W^{-1,p'}(\Omega).$$

Integrating (4.54) in  $(0, T)$  gives:

$$\begin{aligned}
& -\frac{1}{\kappa} \int_0^T \{u_\kappa(t)\}^- dt = \int_0^T \tilde{a}(t) dt + \int_0^T \nabla \cdot (\mu |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t)) dt - \int_0^T \frac{d}{dt} (|u_\kappa(t)|^{\alpha-2} u_\kappa(t)) dt \\
& = \int_0^T \tilde{a}(t) dt + \int_0^T \nabla \cdot (\mu |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t)) dt - [|u_\kappa(T)|^{\alpha-2} u_\kappa(T) - |u_0|^{\alpha-2} u_0] \\
& = \int_0^T \tilde{a}(t) dt + \int_0^T \nabla \cdot (\mu |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t)) dt - [|u_\kappa(T)|^{\alpha-2} u_\kappa(T) - u_0^{\alpha-1}], \quad \text{in } W^{-1,p'}(\Omega),
\end{aligned}$$

where the last equality holds since  $u_0 \geq 0$  in  $\bar{\Omega}$ , being  $u_0 \in K$  by assumption.

Let  $v \in W_0^{1,p}(\Omega)$  be arbitrarily chosen in a way such that  $\|v\|_{W_0^{1,p}(\Omega)} = 1$ . By Stampacchia's theorem (cf. the seminal paper [44]) we have that  $|v| \in W_0^{1,p}(\Omega)$  as well. We have that:

$$\begin{aligned}
& \frac{1}{\kappa} \left| \left\langle \int_0^T \{u_\kappa(t)\}^- dt, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| \leq \left| \left\langle \int_0^T \tilde{a}(t) dt, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| \\
& \quad + \left| \left\langle \int_0^T \nabla \cdot (\mu |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t)) dt, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| \\
& \quad + \left| \int_\Omega \underbrace{|u_\kappa(T)|^{\alpha-2} u_\kappa(T)}_{\in L^{\alpha'}(\Omega) \text{ by (4.41)}} v dx \right| + \int_\Omega u_0^{\alpha-1} |v| dx \\
& \leq \int_0^T \|\tilde{a}(t)\|_{W^{-1,p'}(\Omega)} \|v\|_{W_0^{1,p}(\Omega)} dt + T \|\nabla \cdot (\mu |\nabla u_\kappa|^{p-2} \nabla u_\kappa)\|_{L^\infty(0,T;W^{-1,p'}(\Omega))} \|v\|_{W_0^{1,p}(\Omega)} \\
& \quad + \| |u_\kappa(T)|^{\alpha-2} u_\kappa(T) \|_{L^{\alpha'}(\Omega)} \|v\|_{L^\alpha(\Omega)} + \|u_0^{\alpha-1}\|_{L^{\alpha'}(\Omega)} \|v\|_{L^\alpha(\Omega)} \\
& \leq \|\tilde{a}\|_{W^{1,p}(0,T;C^0(\bar{\Omega}))} + T \|\nabla \cdot (\mu |\nabla u_\kappa|^{p-2} \nabla u_\kappa)\|_{L^\infty(0,T;W^{-1,p'}(\Omega))} + \|u_\kappa(T)\|_{L^\alpha(\Omega)}^{\alpha-1} + \|u_0\|_{L^\alpha(\Omega)}^{\alpha-1}.
\end{aligned}$$

Thanks to Lemma 3.5 and the boundedness of the  $p$ -Laplacian, the latter term is uniformly bounded with respect to  $\kappa$ . By the arbitrariness of  $v \in W_0^{1,p}(\Omega)$  with  $\|v\|_{W_0^{1,p}(\Omega)} = 1$ , we deduce that:

$$\sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)} = 1}} \frac{1}{\kappa} \left| \left\langle \int_0^T \{u_\kappa(t)\}^- dt, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| \leq C, \quad \text{for all } \kappa > 0,$$

for some  $C > 0$  independent of  $\kappa$  or, equivalently,

$$(4.55) \quad \left\| \frac{1}{\kappa} \int_0^T \{u_\kappa(t)\}^- dt \right\|_{W^{-1,p'}(\Omega)} \leq C, \quad \text{for all } \kappa > 0,$$

for some  $C > 0$  independent of  $\kappa$ . By Bochner's theorem (cf., e.g., Theorem 8.9 of [30]), we have that the following inequality is always true:

$$\left\| \frac{1}{\kappa} \int_0^T \{u_\kappa(t)\}^- dt \right\|_{W^{-1,p'}(\Omega)} \leq \frac{1}{\kappa} \int_0^T \|\{u_\kappa(t)\}^-\|_{W^{-1,p'}(\Omega)} dt.$$

We now show that the inverse inequality holds true too. Observe that, by Stampacchia's theorem, we have that  $\{u_\kappa(t)\}^- \in W_0^{1,p}(\Omega)$ , so that  $\{u_\kappa(t)\}^- \geq 0$  in  $\bar{\Omega}$ , for a.a.  $t \in (0, T)$ . Therefore, we have:

$$\langle \{u_\kappa(t)\}^-, v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} = \int_\Omega \{u_\kappa(t)\}^- v dx \leq \int_\Omega \{u_\kappa(t)\}^- |v| dx, \quad \text{for all } v \in W_0^{1,p}(\Omega),$$

for a.a.  $t \in (0, T)$ . Therefore, for a.a.  $t \in (0, T)$ , the supremum

$$\sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \{u_\kappa(t)\}^-, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right|$$

is attained for functions  $v \in W_0^{1,p}(\Omega)$  with unitary norm that are either greater or equal than zero in  $\bar{\Omega}$ , or less or equal than zero in  $\bar{\Omega}$ . In view of this remark, we have that:

$$\begin{aligned} & \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \int_0^T \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt = \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1 \\ v \geq 0 \text{ in } \bar{\Omega}}} \int_0^T \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt \\ &= \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1 \\ v \geq 0 \text{ in } \bar{\Omega}}} \int_0^T \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt \leq \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \int_0^T \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt \right| \\ &\leq \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \int_0^T \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt, \end{aligned}$$

so that the last two inequalities are, actually, equalities.

Let us now show that

$$(4.56) \quad \int_0^T \left( \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| \right) dt \leq \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \int_0^T \left| \frac{\{u_\kappa(t)\}^-}{\kappa} \right| dt.$$

Let  $\{v_k\}_{k=1}^\infty \subset W_0^{1,p}(\Omega)$ ,  $\|v_k\|_{W_0^{1,p}(\Omega)} = 1$  be such that the following convergence in  $\mathbb{R}$  holds

$$(4.57) \quad \lim_{k \rightarrow \infty} \left| \left\langle \frac{\{u_\kappa\}^-}{\kappa}, v_k \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| = \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \frac{u_\kappa}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right|,$$

for a.a.  $t \in (0, T)$ . Observe that, for each  $k \geq 1$ , we always have that

$$(4.58) \quad \int_0^T \left| \left\langle \frac{u_\kappa}{\kappa}, v_k \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt \leq \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \int_0^T \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt.$$

Since the convergence in (4.57) holds for a.a.  $t \in (0, T)$ , we are in a position to apply Fatou's lemma (cf., e.g., [39]). A subsequent application of (4.58) gives:

$$\begin{aligned} & \int_0^T \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt \leq \liminf_{k \rightarrow \infty} \int_0^T \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v_k \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt \\ &\leq \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \int_0^T \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt, \end{aligned}$$

and this proves (4.56). As a result of (4.56) and the properties of the Bochner integral (cf., e.g., Theorem 8.13 of [30]), we have that:

$$\begin{aligned}
& \int_0^T \left\| \frac{\{u_\kappa(t)\}^-}{\kappa} \right\|_{W^{-1,p'}(\Omega)} dt = \int_0^T \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt \\
& \leq \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \int_0^T \left| \left\langle \frac{\{u_\kappa(t)\}^-}{\kappa}, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt \\
& = \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \int_0^T \frac{\{u_\kappa(t)\}^-}{\kappa} dt, v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| = \left\| \int_0^T \frac{\{u_\kappa(t)\}^-}{\kappa} dt \right\|_{W^{-1,p'}(\Omega)}.
\end{aligned}$$

In conclusion, we have shown that:

$$(4.59) \quad \left\| \frac{1}{\kappa} \int_0^T \{u_\kappa(t)\}^- dt \right\|_{W^{-1,p'}(\Omega)} = \frac{1}{\kappa} \int_0^T \|\{u_\kappa(t)\}^-\|_{W^{-1,p'}(\Omega)} dt.$$

Combining (4.55) and (4.59), we obtain that

$$\frac{1}{\kappa} \int_0^T \|\{u_\kappa(t)\}^-\|_{W^{-1,p'}(\Omega)} dt \leq C, \quad \text{for all } \kappa > 0,$$

for some  $C > 0$  independent of  $\kappa$  or, equivalently, that

$$(4.60) \quad \left\{ \frac{\{u_\kappa\}^-}{\kappa} \right\}_{\kappa>0} \text{ is uniformly bounded in } L^1(0, T; W^{-1,p'}(\Omega)).$$

Therefore, we can derive the following estimate plugging (4.60) into (4.54):

$$\begin{aligned}
(4.61) \quad & \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa)(t), v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| \\
& \leq \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \langle \mu |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t), v \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| \\
& \quad + \frac{1}{\kappa} \|\{u_\kappa(t)\}^-\|_{W^{-1,p'}(\Omega)} + \|\tilde{a}(t)\|_{W^{-1,p'}(\Omega)}, \text{ for a.a. } t \in (0, T).
\end{aligned}$$

Applying the boundedness of  $\mu$  assumed in (H2), the boundedness of  $\{u_\kappa\}_{\kappa>0}$  established in (4.52), the boundedness of  $\tilde{a}$  assumed in (H4), the boundedness of the  $p$ -Laplacian, (4.60) and the monotonicity of the integral to (4.61) gives:

$$(4.62) \quad \int_0^T \sup_{\substack{v \in W_0^{1,p}(\Omega) \\ \|v\|_{W_0^{1,p}(\Omega)}=1}} \left| \left\langle \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa)(t), v \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} \right| dt \leq C,$$

for some  $C > 0$  independent of  $\kappa$ . This means that

$$\left\{ \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa) \right\}_{\kappa>0} \text{ is bounded in } L^1(0, T; W^{-1,p'}(\Omega)).$$

Therefore, there exists a vector-valued measure  $\tilde{w}_t \in \mathcal{M}([0, T]; W^{-1,p'}(\Omega))$  such that

$$(4.63) \quad \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa) \overset{*}{\rightharpoonup} \tilde{w}_t, \quad \text{in } \mathcal{M}([0, T]; W^{-1,p'}(\Omega)) \text{ as } \kappa \rightarrow 0^+.$$

The latter together with the fourth convergence in (4.52) allow us to apply Dubinskii's theorem (Theorem 3.9) with  $A_0 = L^{(\alpha'-1)p}(\Omega)$ ,  $A_1 = W^{-1,p'}(\Omega)$ ,  $q_0 = (\alpha' - 1)p > 1$  and  $q_1 = 1$ . The monotonicity of the mapping  $\xi \mapsto |\xi|^{\alpha-2}\xi$  finally gives us:

$$(4.64) \quad |u_\kappa|^{\alpha-2}u_\kappa \rightarrow w = |u|^{\alpha-2}u, \quad \text{in } L^{(\alpha'-1)p}(0, T; L^{(\alpha'-1)p}(\Omega)),$$

and  $w = |u|^{\alpha-2}u \in L^\infty(0, T; L^{\alpha'}(\Omega))$  by the fourth convergence in (4.52).

Thanks to Lemma 3.5 and the Dinculeanu-Zinger theorem (Theorem 3.11), we have that the following chain of embeddings holds:

$$L^1(0, T; W^{-1,p'}(\Omega)) \hookrightarrow \left( \mathcal{C}^0([0, T]; W_0^{1,p}(\Omega)) \right)^* \simeq \mathcal{M}([0, T]; W^{-1,p'}(\Omega)).$$

Thanks to Lemma 3.5 and Lemma 3.8, we have that:

$$(4.65) \quad \int_0^T \left\langle \frac{d}{dt} (|u_\kappa(t)|^{\alpha-2}u_\kappa(t)), u_\kappa(t) \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt = \frac{\|u_\kappa(T)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'} - \frac{\|u_0\|_{L^\alpha(\Omega)}^\alpha}{\alpha'}$$

$$\rightarrow \frac{\|u(T)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'} - \frac{\|u_0\|_{L^\alpha(\Omega)}^\alpha}{\alpha'}, \quad \text{as } \kappa \rightarrow 0^+.$$

Observe that the first convergence of (4.52), namely  $u_\kappa \xrightarrow{*} u$  in  $L^\infty(0, T; W_0^{1,p}(\Omega))$ , implies that

$$u_\kappa \rightharpoonup u, \quad \text{in } L^2(0, T; L^2(\Omega)) \simeq L^2((0, T) \times \Omega) \text{ as } \kappa \rightarrow 0^+.$$

The continuity of the negative part established in Lemma 3.2 and the third estimate in (4.14) give:

$$\|\{u\}^-\|_{L^2(0,T;L^2(\Omega))} \leq \liminf_{\kappa \rightarrow 0} \|\{u_\kappa\}^-\|_{L^2(0,T;L^2(\Omega))} = 0,$$

which means that  $u(t) \geq 0$  a.e. in  $\Omega$ , for a.a.  $t \in (0, T)$ .

Specializing  $v = u_\kappa - u$  in (4.1), we obtain:

$$(4.66) \quad \int_0^T \left\langle \frac{d}{dt} (|u_\kappa|^{\alpha-2}u_\kappa), u_\kappa - u \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt + \int_0^T \int_\Omega \mu(x) |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t) \cdot \nabla (u_\kappa(t) - u(t)) dx dt$$

$$- \frac{1}{\kappa} \int_0^T \int_\Omega \{u_\kappa(t)\}^- (u_\kappa(t) - u(t)) dx dt = \int_0^T \int_\Omega \tilde{a}(t) (u_\kappa(t) - u(t)) dx dt.$$

Since  $u_\kappa \in \mathcal{C}^0([0, T]; L^\alpha(\Omega))$ , we define the extension  $\tilde{u}_\kappa : [-T, 2T] \rightarrow L^\alpha(\Omega)$  by:

$$\tilde{u}_\kappa(t) := \begin{cases} u_\kappa(-t), & \text{if } -T \leq t < 0, \\ u_\kappa(t), & \text{if } 0 \leq t < T, \\ u_\kappa(2T - t), & \text{if } T \leq t \leq 2T. \end{cases}$$

Since  $u \in \mathcal{C}^0([0, T]; L^\alpha(\Omega))$ , we define the extension  $\tilde{u} : [-T, 2T] \rightarrow L^\alpha(\Omega)$  by:

$$\tilde{u}(t) := \begin{cases} u(-t), & \text{if } -T \leq t < 0, \\ u(t), & \text{if } 0 \leq t < T, \\ u(2T - t), & \text{if } T \leq t \leq 2T. \end{cases}$$

For each  $-T < \tau < T$  and all  $\kappa > 0$ , define

$$Y_\tau^\kappa := \frac{1}{\tau} \int_0^T \langle |\tilde{u}_\kappa(t + \tau)|^{\alpha-2} \tilde{u}_\kappa(t + \tau) - |\tilde{u}_\kappa(t)|^{\alpha-2} \tilde{u}_\kappa(t), \tilde{u}(t) \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt.$$

By Lemma 3.7 with  $\xi = \tilde{u}_\kappa(t)$ ,  $\eta = \tilde{u}_\kappa(t + \tau)$  and  $r = \alpha$  and (4.53), we have that:

$$Y_\tau^\kappa \rightarrow \frac{1}{\tau} \int_0^T \langle |\tilde{u}(t + \tau)|^{\alpha-2} \tilde{u}(t + \tau) - |\tilde{u}(t)|^{\alpha-2} \tilde{u}(t), \tilde{u}(t) \rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt$$

$$\leq -\frac{1}{2\tau\alpha'} \int_{T-\tau}^{T+\tau} \|\tilde{u}(t)\|_{L^\alpha(\Omega)}^\alpha dt + \frac{1}{2\tau\alpha'} \int_{-\tau}^\tau \|\tilde{u}(t)\|_{L^\alpha(\Omega)}^\alpha dt,$$

as  $\kappa \rightarrow 0^+$ . Letting  $\tau \rightarrow 0$  in the latter term, we obtain that:

$$-\frac{1}{2\tau\alpha'} \int_{T-\tau}^{T+\tau} \|\tilde{u}(t)\|_{L^\alpha(\Omega)}^\alpha dt + \frac{1}{2\tau\alpha'} \int_{-\tau}^{\tau} \|\tilde{u}(t)\|_{L^\alpha(\Omega)}^\alpha dt \rightarrow -\frac{\|u(T)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'} + \frac{\|u_0\|_{L^\alpha(\Omega)}^\alpha}{\alpha'}.$$

In the special case where  $|u|^{\alpha-2}u$  is differentiable a.e. in  $(0, T)$  (this constitutes another *stability assumption*) then it results:

$$(4.67) \quad \lim_{\kappa \rightarrow 0^+} \int_0^T \left\langle \frac{d}{dt} (|u_\kappa|^{\alpha-2}u_\kappa), u \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt = \lim_{\tau \rightarrow 0} \lim_{\kappa \rightarrow 0^+} Y_\tau^\kappa \leq -\frac{\|u(T)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'} + \frac{\|u_0\|_{L^\alpha(\Omega)}^\alpha}{\alpha'}.$$

Combining (4.65) and (4.67) and the convergence (4.53), we obtain that (4.66) gives:

$$(4.68) \quad \limsup_{\kappa \rightarrow 0^+} \int_0^T \int_\Omega \mu(x) |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t) \cdot \nabla (u_\kappa(t) - u(t)) dx dt \leq 0.$$

Since the  $p$ -Laplacian in divergence form is pseudo-monotone (cf., e.g., Proposition 2.5 of [31]), as it is hemi-continuous, strictly monotone and bounded, an application of (4.68) gives:

$$(4.69) \quad \begin{aligned} & \int_0^T \int_\Omega \mu(x) |\nabla u(t)|^{p-2} \nabla u(t) \cdot \nabla (u(t) - v(t)) dx dt \\ & \leq \liminf_{\kappa \rightarrow 0^+} \int_0^T \int_\Omega \mu(x) |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t) \cdot \nabla (u_\kappa(t) - v(t)) dx dt, \end{aligned}$$

for all  $v \in L^2(0, T; W_0^{1,p}(\Omega))$ . Observe that the latter space is suitable for treating pseudo-monotonicity, as it is reflexive.

Let us now consider arbitrary functions  $v \in \mathcal{C}^0([0, T]; W_0^{1,p}(\Omega))$  such that  $v(t) \geq 0$  in  $\bar{\Omega}$  for all  $t \in [0, T]$ . Evaluate the variational equations (4.1) at  $w_\kappa := v - u_\kappa$ , obtaining:

$$\begin{aligned} & \int_0^T \left\langle \frac{d}{dt} (|u_\kappa(t)|^{\alpha-2}u_\kappa(t)), v(t) - u_\kappa(t) \right\rangle_{W^{-1,p'}(\Omega), W_0^{1,p}(\Omega)} dt \\ & + \int_0^T \int_\Omega \mu(x) |\nabla u_\kappa(t)|^{p-2} \nabla u_\kappa(t) \cdot \nabla (v(t) - u_\kappa(t)) dx dt \\ & - \frac{1}{\kappa} \int_0^T \int_\Omega \{u_\kappa(t)\}^- (v(t) - u_\kappa(t)) dx dt \\ & = \int_0^T \int_\Omega \tilde{a}(t) (v(t) - u_\kappa(t)) dx dt. \end{aligned}$$

Let  $\kappa \rightarrow 0^+$  and exploit the convergence process (4.52), (4.69) and the fact that the integral associated with the negative part is  $\leq 0$ , being  $u(t) \geq 0$  a.e. in  $\bar{\Omega}$  for a.a.  $t \in (0, T)$ , gives:

$$\begin{aligned} & \langle \langle \tilde{w}_t, v \rangle \rangle_{\mathcal{M}([0, T]; W^{-1,p'}(\Omega)), \mathcal{C}^0([0, T]; W_0^{1,p}(\Omega))} + \int_0^T \int_\Omega \mu(x) |\nabla u(t)|^{p-2} \nabla u(t) \cdot \nabla (v(t) - u(t)) dx dt \\ & \geq \int_0^T \int_\Omega \tilde{a}(t) (v - u) dx dt + \frac{\|u(T)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'} - \frac{\|u_0\|_{L^\alpha(\Omega)}^\alpha}{\alpha'}. \end{aligned}$$

We are thus in a position to write down the model governing the evolution of the thickness of a shallow ice sheet, and to assert that this model admits at least one solution.

**Theorem 4.5.** *Let  $\Omega$  be a domain in  $\mathbb{R}^2$ . Assume that (H1)–(H4) hold. Let  $\{u_\kappa\}_{\kappa>0}$  be a family of solutions of Problem  $\mathcal{P}_\kappa$ . Then, the following convergences hold:*

$$\begin{aligned} u_\kappa &\overset{*}{\rightharpoonup} u, \text{ in } L^\infty(0, T; W_0^{1,p}(\Omega)), \\ |u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa &\overset{*}{\rightharpoonup} |u|^{\frac{\alpha-2}{2}} u, \text{ in } L^\infty(0, T; L^2(\Omega)), \\ \frac{d}{dt} \left( |u_\kappa|^{\frac{\alpha-2}{2}} u_\kappa \right) &\rightharpoonup \frac{d}{dt} \left( |u|^{\frac{\alpha-2}{2}} u \right), \text{ in } L^\infty(0, T; L^2(\Omega)), \\ |u_\kappa|^{\alpha-2} u_\kappa &\overset{*}{\rightharpoonup} |u|^{\alpha-2} u, \text{ in } L^\infty(0, T; L^{\alpha'}(\Omega)), \\ \frac{d}{dt} (|u_\kappa|^{\alpha-2} u_\kappa) &\overset{*}{\rightharpoonup} \frac{d}{dt} |u|^{\alpha-2} u, \text{ in } \mathcal{M}([0, T]; W^{-1,p'}(\Omega)). \end{aligned}$$

Moreover, if the following stability condition holds

$$(4.70) \quad |u|^{\alpha-2} u \text{ is differentiable a.e. in } (0, T),$$

then  $u$  is a solution of the following variational problem:

**Problem  $\mathcal{P}$ .** Find  $u \in \mathcal{K} := \{v \in L^\infty(0, T; W_0^{1,p}(\Omega)); v(t) \in K \text{ a.e. in } (0, T)\}$  such that

$$\begin{aligned} u &\in L^\infty(0, T; W_0^{1,p}(\Omega)), \\ \frac{d}{dt} \left( |u|^{\frac{\alpha-2}{2}} u \right) &\in L^2(0, T; L^2(\Omega)), \\ \frac{d}{dt} (|u|^{\alpha-2} u) &\in \mathcal{M}([0, T]; W^{-1,p'}(\Omega)), \end{aligned}$$

satisfying the following variational inequalities:

$$\begin{aligned} &\left\langle \left\langle \frac{d}{dt} (|u|^{\alpha-2} u), v \right\rangle \right\rangle_{\mathcal{M}([0, T]; W^{-1,p'}(\Omega)), \mathcal{C}^0([0, T]; W_0^{1,p}(\Omega))} + \int_0^T \int_\Omega \mu(x) |\nabla u|^{p-2} \nabla \cdot \nabla (v - u) \, dx \, dt \\ &\geq \int_0^T \int_\Omega \tilde{a}(t) (v - u) \, dx \, dt + \frac{\|u(T)\|_{L^\alpha(\Omega)}^\alpha}{\alpha'} - \frac{\|u_0\|_{L^\alpha(\Omega)}^\alpha}{\alpha'}, \end{aligned}$$

for all  $v \in \mathcal{C}^0([0, T]; W_0^{1,p}(\Omega))$  such that  $v(t) \geq 0$  in  $\bar{\Omega}$  for all  $t \in [0, T]$ , as well as the following initial condition

$$u(0) = u_0,$$

for some prescribed  $u_0 \in K$ . ■

□

We conclude the paper with a remark where we propose an alternative stability condition, which is more physically realistic than the abstract stability condition (4.70).

*Remark 4.6.* Observe that the following condition is sufficient to (4.70): There exists a constant  $C > 0$  independent of  $\kappa$  such that

$$(4.71) \quad \frac{\|\{u_\kappa\}^-\|_{W^{-1,p'}}}{\kappa} \leq C.$$

This stability condition, which is more physically realistic than (4.70), strengthens the convergence of the derivative of the nonlinear term and saves us the effort of resorting to vector-valued measures. ■

## CONCLUSIONS

In this paper we formulated a time-dependent model governing the evolution of the thickness of a shallow ice sheet undergoing regimes of melting and ablation. The shallow ice sheet varying height, that is the unknown the model is described in terms of, is subjected to obey the constraint of being nonnegative. For this reason, the problem under consideration can be regarded as an obstacle problem.

First, we recovered the formal model, based on Glen’s power law.

Second, we incorporated the constraint, in the form of a monotone term, in the model. By so doing it was possible to write down variational formulation of the model under consideration in terms of a set of variational equations posed over a vector space. The existence of solutions for the penalized model was established thanks to the Dubinskii’s compactness theorem and a series of preliminary results, that we stated in the form of Lemmas.

Third, we let the penalty parameter approach zero and we recovered the actual model, which takes the form of a set of variational inequalities tested over a nonempty, closed, and convex subset of the space  $C^0([0, T]; W_0^{1,p}(\Omega))$ .

It is worth noticing that the proofs hinge on two *stability conditions*, i.e., (4.6) and (4.70) that, in the same spirit as [37], we were able to replace by the corresponding more realistic ones (4.21) and (4.71).

At a first glance, the time-dependent model we studied appears to be very challenging and it is not clear whether it is possible to establish the existence of solutions to it without resorting to the stability conditions (4.6) and (4.70) (or the more physically realistic stability conditions (4.21) and (4.71)).

#### ACKNOWLEDGEMENTS

The first author is greatly indebted to Professor Philippe G. Ciarlet for his encouragement and guidance.

#### REFERENCES

- [1] J. Barrett and E. Süli. Reflections on Dubinskii’s nonlinear compact embedding theorem. *Publications de l’Institut Mathématique*, 91, 01 2011. doi: 10.2298/PIM1205095B.
- [2] I. Bock and J. Jarušek. On hyperbolic contact problems. *Tatra Mt. Math. Publ.*, 43:25–40, 2009.
- [3] I. Bock and J. Jarušek. Dynamic contact problem for viscoelastic von Kármán–Donnell shells. *ZAMM Z. Angew. Math. Mech.*, 93:733–744, 2013.
- [4] I. Bock, J. Jarušek, and M. Šilhavý. On the solutions of a dynamic contact problem for a thermoelastic von Kármán plate. *Nonlinear Anal. Real World Appl.*, 32:111–135, 2016.
- [5] F. Brandt, K. Disser, R. Haller-Dintelmann, and M. Hieber. Rigorous analysis and dynamics of hiber’s sea ice model. URL <https://arxiv.org/abs/2104.01336>.
- [6] H. Brézis. Problèmes unilatéraux. *J. Math. Pures Appl. (9)*, 51:1–168, 1972.
- [7] H. Brezis. *Functional Analysis, Sobolev Spaces and Partial Differential Equations*. Springer, New York, 2011.
- [8] L. Caffarelli and S. Salsa. *A geometric approach to free boundary problems*, volume 68 of *Graduate Studies in Mathematics*. American Mathematical Society, Providence, RI, 2005.
- [9] N. Calvo, J. I. Díaz, J. Durany, E. Schiavi, and C. Vázquez. On a doubly nonlinear parabolic obstacle problem modelling ice sheet dynamics. *SIAM J. Appl. Math.*, 63(2):683–707, 2002.
- [10] P. G. Ciarlet. *Linear and Nonlinear Functional Analysis with Applications*. Society for Industrial and Applied Mathematics, Philadelphia, 2013.
- [11] P. G. Ciarlet. *Locally Convex Spaces and Harmonic Analysis. An Introduction*. Society for Industrial and Applied Mathematics (SIAM), Philadelphia, PA, 2021.
- [12] M. D. Coon, G. A. Maykut, R. S. Pritchard, D. A. Rothrock, and T. A. S. Modeling the pack ice as an elastic-plastic material. *AIDJEX Bull.*, 24:1–105, 1974.
- [13] J. Diestel and J. J. Uhl. *Vector measures*. American Mathematical Society, Providence, R.I., 1977.
- [14] N. Dinculeanu. *Vector measures*. Pergamon Press, Oxford-New York-Toronto, Ont.; VEB Deutscher Verlag der Wissenschaften, Berlin, 1967.
- [15] J. A. Dubinskii. Weak convergence for nonlinear elliptic and parabolic equations. *Mat. Sb. (N.S.)*, 67 (109):609–642, 1965.

- [16] L. C. Evans. *Partial Differential Equations*. American Mathematical Society, Providence, Second edition, 2010.
- [17] G. Fichera. Problemi unilaterali nella statica dei sistemi continui. *Atti Accad. Sci. Torino Cl. Sci. Fis. Mat. Natur.*, 111:169–178, 1977.
- [18] A. Figalli, X. Ros-Oton, and J. Serra. The singular set in the stefan problem. URL <https://arxiv.org/abs/2103.13379>.
- [19] A. C. Fowler. *Mathematical Models in the Applied Sciences*. Cambridge University Press, Cambridge, UK, 2005.
- [20] J. W. Glen. Thoughts on a vicious model for sea ice. *AIDJEX Bull.*, 2:18–27, 1970.
- [21] D. L. Goldsby and D. L. Kohlstedt. Superplastic deformation of ice: Experimental observations. *J. Geophys. Res.*, 106:11017–11030, 2001.
- [22] R. Greve and H. Blatter. *Dynamics of Ice Sheets and Glaciers*. Springer-Verlag, Berlin Heidelberg, 2009.
- [23] W. D. Hibler. A dynamic thermodynamic ice sheet model. *J. Phys. Oceanogr.*, 9:815–846, 1979.
- [24] R. L. Hooke. *Principles of Glacier Mechanics*. Cambridge University Press, Cambridge, UK, 2005.
- [25] G. Jouvét. Multilayer shallow shelf approximation: Minimisation formulation, finite element solvers and applications. *J. Comput. Phys.*, 287:60–76, 2015.
- [26] G. Jouvét. A multilayer ice-flow model generalising the shallow shelf approximation. *J. Fluid Mech.*, 764:26–51, 2015.
- [27] G. Jouvét and E. Bueller. Steady, shallow ice sheets as obstacle problems: well-posedness and finite element approximation. *SIAM J. Appl. Math.*, 72(4):1292–1314, 2012.
- [28] G. Jouvét and J. Rappaz. Numerical analysis and simulation of the dynamics of mountain glaciers. In *Modeling, simulation and optimization for science and technology*, volume 34 of *Comput. Methods Appl. Sci.*, pages 83–92. Springer, Dordrecht, 2014.
- [29] G. Jouvét, E. Bueller, C. Gräser, and R. Kornhuber. A nonsmooth Newton multigrid method for a hybrid, shallow model of marine ice sheets. In *Recent advances in scientific computing and applications*, volume 586 of *Contemp. Math.*, pages 197–205. Amer. Math. Soc., Providence, RI, 2013.
- [30] G. Leoni. *A First Course in Sobolev Spaces*, volume 181 of *Graduate Studies in Mathematics*. American Mathematical Society, Providence, Second edition, 2017.
- [31] J.-L. Lions. *Quelques méthodes de résolution des problèmes aux limites non linéaires*. Dunod; Gauthier-Villars, Paris, 1969.
- [32] J.-L. Lions and E. Magenes. *Non-homogeneous boundary value problems and applications. Vol. I*. Springer-Verlag, New York-Heidelberg, 1972.
- [33] X. Liu, M. Thomas, and E. S. Titi. Well-posedness of hibler’s dynamical sea-ice model. URL <https://arxiv.org/abs/2104.09264>.
- [34] L. Michel, M. Picasso, D. Farinotti, A. Bauder, M. Funk, and H. Blatter. Estimating the ice thickness of mountain glaciers with a shape optimization algorithm using surface topography and mass-balance. *J. Inverse Ill-Posed Probl.*, 22(6):787–818, 2014.
- [35] G. Minty. Monotone (non linear) operators in hilbert spaces. *Duke Math. J.*, 29:341–346, 1962.
- [36] G. K. Pedersen. *C\*-algebras and their automorphism groups*. Pure and Applied Mathematics (Amsterdam). Academic Press, London, 2018.
- [37] P. A. Raviart. Sur la résolution et l’approximation de certaines équations paraboliques non linéaires dégénérées. *Arch. Rational Mech. Anal.*, 25:64–80, 1967.
- [38] P. A. Raviart. Sur la résolution de certaines équations paraboliques non linéaires. *J. Functional Analysis*, 5:299–328, 1970.
- [39] H. L. Royden. *Real analysis*. Macmillan Publishing Company, New York, third edition, 1988.
- [40] R. A. Ryan. *Introduction to tensor products of Banach spaces*. Springer Monographs in Mathematics. Springer-Verlag London, Ltd., London, 2002.
- [41] C. Schoof. A variational approach to ice stream flow. *J. Fluid Mech.*, 556:227–251, 2006.

- [42] C. Schoof. Variational methods for glacier flow over plastic till. *J. Fluid Mech.*, 555:299–320, 2006.
- [43] J. Simon. Régularité de la solution d’une équation non linéaire dans  $\mathbf{R}^N$ . In *Journées d’Analyse Non Linéaire (Proc. Conf., Besançon, 1977)*, volume 665 of *Lecture Notes in Math.*, pages 205–227. Springer, Berlin, 1978.
- [44] G. Stampacchia. équations elliptiques du second ordre à coefficients discontinus. *Séminaire Jean Leray*, (3):1–77, 1963–1964.
- [45] K. Yosida. *Functional analysis*. Classics in Mathematics. Springer-Verlag, Berlin, 1995. Reprint of the sixth (1980) edition.
- [46] W. H. Young. On Classes of Summable Functions and their Fourier Series. *Proc. R. Soc. Lond. Ser. A Math. Phys. Eng. Sci.*, 87:225–229, 1912.
- [47] I. Zinger. Linear functionals on the space of continuous mappings of a compact Hausdorff space into a Banach space. *Rev. Math. Pures Appl.*, 2:301–315, 1957.

DEPARTMENT OF MATHEMATICS, INDIANA UNIVERSITY BLOOMINGTON, 831 EAST THIRD STREET, BLOOMINGTON, INDIANA, USA

*Email address:* ppiersan@iu.edu

DEPARTMENT OF MATHEMATICS AND INSTITUTE FOR SCIENTIFIC COMPUTING AND APPLIED MATHEMATICS, INDIANA UNIVERSITY BLOOMINGTON, 729 EAST THIRD STREET, BLOOMINGTON, INDIANA, USA

*Email address:* temam@indiana.edu