Ultrasound-induced encapsulated microbubble phenomena

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Abstract

When encapsulated microbubbles are subjected to high-amplitude ultrasound, the following phenomena have been reported: oscillation, translation, coalescence, fragmentation, sonic cracking, and jetting.

In this paper, we explain these phenomena, based on theories that were validated for relatively big, free (not encapsulated) gas bubbles. These theories are compared to high-speed optical observations of insonified contrast agent microbubbles. Furthermore, the potential clinical applications of the bubble–ultrasound interaction are explored.

We conclude that most of the results obtained are consistent with free gas bubble theory. Similar to cavitation theory, the number of fragments after bubble fission is in agreement with the dominant spherical harmonical oscillation mode. Remarkable are our observations of jetting through contrast agent microbubbles. This is high enough to penetrate any human cell. Hence, liquid jets may act as remote-controlled microsyringes, delivering a drug to a region of interest.

Encapsulated microbubbles have (potential) clinical applications in both diagnostics and therapeutics.

Key words

Encapsulated microbubbles, ultrasound contrast agent, radiation forces, coalescence, fragmentation, jets.

Introduction

Blood does not reflect ultrasound well, but its response may be enhanced by gas microbubbles of a few micrometers in diameter that are introduced into the blood pool (Goldberg et al., 2001). These microbubbles oscillate upon insonification, and generate as such a characteristic acoustic response.

An ultrasound contrast agent (UCA) is a liquid containing gas microbubbles which are encapsulated by a shell. UCAs are widely used in clinical diagnostic imaging (Becher and Burns, 2000; Goldberg et al., 2001). The intravascular use of UCA enhances the quantification of perfusion and blood flow (Klibanov, 1999; Wei, 2001), and lowers the detectability threshold of tumor and tissue vascularization, using conventional Doppler instruments (Burns et al., 1990). An overview of UCA detection procedures in ultrasound imaging has been presented by de Jong et al. (2000b), and an overview of UCA imaging innovations has been put forward by Chiou et al. (2000).

To understand encapsulated microbubble behavior better in order to develop or enhance applications in diagnostics and therapeutics, UCA microbubbles have

been subjected to high-speed photography. Postema et al. (2003a) gave an overview of publications on high-speed optical observations of insonified UCA.

Observations of dynamic UCA microbubble behavior have resulted in new insights and novel approaches in diagnostics and therapeutics: The nonlinear behavior of oscillating bubbles has led to the development of contrast harmonic imaging (Schrope and Newhouse, 1993; de Jong et al., 1994, 2002; Bouakaz et al., 2002a,b), whereas observations of bubble destruction have led to the development of high-MI imaging techniques (Uhlendorf and Hoffmann, 1994; Frinking et al., 2001).

Targeted UCA delivery is based on microbubbles with ligands attached to them (Klibanov, 1999; Unger et al., 2001). These bubbles circulate through vessels and accumulate at a target tissue, thereby marking the target in ultrasound images. Klibanov (1999) put forward that targeted microbubbles may be applied for selective delivery to the areas where selective enhancement of the action of ultrasound would be required, and if such a bubble would contain plasmid DNA, enzyme, or another therapeutic agent, it might be released at the site of interest during insonification. Another means of targeting was suggested by Dayton et al. (2001b). They provided optical verification that microbubbles oscillate differently when inside neutrophils in response to insonification, and emit acoustic signals that are distinct from free microbubbles. Thus, microbubbles within neutrophils might be detected, providing a potential method to image activated neutrophils as

they accumulate at sites of inflammation.

Recently, Unger et al. (2002) gave an overview of the therapeutic applications of UCA microbubbles. They presented experimental results using UCAs for thrombolysis, drug delivery, and gene delivery. Other recent advances in local drug and gene delivery include the *in vivo* delivery of a virus vector, attached to albumin microbubbles (Shohet et al., 2000), the *in vitro* and *in vivo* transfection of endothelial cells with plasmid DNA mixed with UCA (Taniyama et al., 2002), and the accelerated cellular drug uptake *in vitro* when UCA microbubbles are present (van Wamel et al., 2002). Tachibana et al. (1999) subjected cells in the presence of a photosensitive drug to continuous ultrasound, and noticed surface pores on the cells. Inducing porosities in cells with ultrasound, generally referred to as sonoporation, has potential applications in (tumor) cell lysis and selective delivery of drugs and genes into cells. Independently, it was demonstrated that moderate microbubble oscillations are sufficient to achieve rupture of lipid membranes, in a regime in which the bubble dynamics can be accurately controlled (Marmottant and Hilgenfeldt, 2003). This might enable the transport of drugs through the cell membrane.

At high acoustic amplitudes, destructive effects of UCA microbubbles have been observed, such as hemorrhaging (Skyba et al., 1998; Maruvada and Hynynen, 2002), and lysis (van Wamel et al., 2002). Kudo et al. (2002) performed an *in vitro* study on bovine arterial cell damage by ultrasound in combination with

microbubbles. They found that the locations of damaged cells were similar to the locations where violent bubble collapse was observed, suggesting that bubble collapse is responsible for cell membrane damage.

In this paper, we present an overview of dynamic encapsulated microbubble behavior observed at high acoustic amplitudes. The mechanisms for each type of behavior, found in literature on free (not encapsulated) gas bubbles, acoustics, and cavitation, are correlated to our high-speed optical observations. Furthermore, we address the potential clinical applications of the phenomena.

Previously, some UCA microbubble destruction phenomena were categorized by Chomas et al. (2001a) and Postema et al. (2002a). From our optical observations, we discriminate the following categories: oscillation, translation, coalescence, fragmentation, sonic cracking, and jetting.

In the following subsections, we give a brief overview of these phenomena, and an explanation of their occurrence. Most theories on bubble behavior were validated for big, free (not encapsulated) microbubbles.

Oscillation

When a microbubble is exposed to an oscillating acoustic signal, it undergoes alternate expansions and contractions with the same amplitude and duration at low driving pressures (Strasberg, 1956). This regime of pulsation amplitudes has been referred to as *moderate* (Vokurka, 1986). Bubble activity which may

occur at relatively low-amplitude pressures has been denoted as *stable cavitation* (Miller and Nyborg, 1983). As the driving pressure increases, more complex nonlinear interactions occur: greater bubble expansion amplitude than contraction amplitude, and relatively slow expansion followed by rapid contraction (collapse). This behavior has been referred to as *violent* (Vokurka, 1986) or *inertial* (or *transient*) *cavitation* (Miller and Nyborg, 1983; Flynn and Church, 1988; Barnett, 1998). It has been associated with the production of harmonic signals (Postema et al., 2003a).

The transition from the *moderate* to the *violent* regime is rather abrupt: For any driving pressure, there exists a transitional equilibrium microbubble radius R_0^{tr} , above which microbubbles pulsate like *inertial cavities* (Flynn, 1975; Flynn and Church, 1988; Hilgenfeldt et al., 1998). This transition is referred to as the *cavitation threshold*. A bubble is judged to have grown into an *inertial cavity* when its maximum radius is greater than approximately twice its equilibrium radius (Flynn, 1975; Flynn and Church, 1988).

A number of models for computing radius-time curves of insonified gas bubbles has been developed. These models differ both in complexity and in the range of acoustic amplitudes for which they can be used (Vokurka, 1986).

To model the behavior of UCA microbubbles, the presence of an encapsulation around the gas core has to be accounted for. Hence, we have to introduce parameters that describe the dynamic behavior of the shell.

Presently, two models have been used for modeling UCA microbubble oscillations. de Jong et al. (1994) used a modified RPNNP equation, named after its developers Rayleigh, Plesset, Neppiras, Noltingk, and Poritsky. They accounted for the presence of a shell by introducing a shell stiffness and a shell friction parameter. Morgan et al. (2000) used a modified Herring equation. They introduced the shell properties thickness, elasticity modulus, and viscosity. Both models are consistent with optical observations at low driving pressures (de Jong et al., 2000a; Morgan et al., 2000; Postema et al., 2003a). Currently, models on UCA microbubble oscillating behavior at high driving pressures have been under investigation (Stride and Saffari, 2003).

Translation

Translations of UCA microbubbles in the direction of the sound field and towards each other have been frequently observed with high-speed cameras (Dayton et al., 1996, 1997b, 1999, 2001a; Postema et al., 2003c). Microbubble translation in the direction of the sound field has been attributed to a primary radiation force resulting from a pressure gradient across the bubble surface. The translation is maximal in contraction phase (Reddy and Szeri, 2002). It was demonstrated that the velocity v of a bubble in a steady fluid subjected to an ultrasound field can be

expressed by the following ordinary differential equation (Tortoli et al., 2001):

$$m \frac{dv}{dt} = F_{\text{rad}} + F_{\text{d}}, \quad (1)$$

where F_{rad} is the primary radiation force, F_{d} is the drag force, $m \approx \frac{2\pi}{3}\rho R_0^3$ is the mass of the translating bubble, equivalent to half the mass of the displaced surrounding fluid (Leighton, 1994), in which R_0 is the ambient bubble radius, and ρ is the density of the surrounding fluid. The primary radiation force is given by (Tortoli et al., 2001):

$$F_{\text{rad}} = \frac{p_{\text{ac}}^2 R_0}{\rho c f} \frac{\delta_t \frac{f_r}{f}}{\left[\left(\frac{f_r}{f} \right)^2 - 1 \right]^2 + \left(\delta_t \frac{f_r}{f} \right)^2}, \quad (2)$$

where c is the speed of sound, p_{ac} is the peak rarefactional acoustic pressure, δ_t is the dimensionless total damping coefficient (Medwin, 1977), and f_r is the bubble resonant frequency (Medwin, 1977). The drag force is given by (Tortoli et al., 2001):

$$F_{\text{d}} = -\frac{\pi\eta}{4} C_{\text{d}} \text{Re} R_0 v(t), \quad (3)$$

where η is the shear viscosity of the fluid, $\text{Re} = \frac{2\rho R_0}{\eta} |v(t)|$ represents the Reynolds number, and $C_{\text{d}} = \frac{24}{\text{Re}} + \frac{6}{1+\sqrt{\text{Re}}} + 0.4$ is the drag coefficient.

The microbubble translations towards each other have been attributed to secondary radiation forces: oscillating bubbles generate spatially varying pressure fields. If two bubbles are either both below or both above the resonant size, this results in attraction. However, if one bubble is below and the other is above the

resonant size, they oscillate out of phase (Pain, 1992; Leighton, 1994; Reddy and Szeri, 2002), causing the bubbles to recede from each other. The mean approach velocity v_a of two identical bubbles is given by Dayton et al. (1997b):

$$v_a = -\frac{(2\pi f p_{ac})^2}{27\eta} \rho \kappa^2 \frac{R_0^5}{d_0^2}, \quad (4)$$

where κ is the compressibility of the bubble, and d_0 is the initial distance between the centers of the two bubbles.

Coalescence

Ultrasound-induced microbubble coalescence is the fusion of two or more microbubbles. As adjacent bubbles expand, the pressure in the film between them increases, resulting in a deformation (flattening) of the bubble surfaces. The continuing bubble expansion causes drainage of the interposed film. This thinning continues until a critical thickness below $0.1 \mu\text{m}$ is reached, at which the Van der Waals attractive forces results in film rupture and the coalescence of the bubbles (Duineveld, 1994). Thinning and rupture of thin liquid films have been described by Sheludko (1967), Kralchevsky et al. (1996), and Narsimhan and Ruckenstein (1996).

Flattening of the adjacent bubble surfaces occurs if and only if the bubble system has a Weber number $We > 0.5$ (Chesters and Hoffmann, 1982). The Weber number for a fluid containing two bubbles with radii R_1 and R_2 ,

respectively, is given by the inertial force relative to the surface tension force:

$$\text{We} = \frac{\rho u^2}{\frac{\sigma}{R_m}}, \quad (5)$$

where u is the relative approach velocity of the bubble walls: $u \approx \dot{R}_1 + \dot{R}_2$, ρ is the fluid density, σ is the surface tension, and R_m is the mean bubble radius for which holds: $\frac{2}{R_m} = \frac{1}{R_1} + \frac{1}{R_2}$. In our results, Weber numbers are relatively high because of the rapid bubble expansions, with maximal radius increases of several m s^{-1} . If the Weber number is lower than 0.5, bubble coalescence will always occur, without flattening of the adjacent surfaces prior to contact (Chesters and Hoffmann, 1982).

In a separate paper, we investigated the coalescence mechanism of microbubbles, based on high-speed optical observations of insonified UCA (Postema et al., 2003c). We investigated the mechanism of film drainage by comparing the observed coalescence times with calculated film drainage times from the Reynolds equation (6). The Reynolds drainage time τ_d of the interposed film until a critical thickness h_c is given by:

$$\tau_d = \frac{3\eta R_f^2 R_m}{8\sigma h_c^2}, \quad (6)$$

where R_f is the film radius, and R_m is the mean bubble radius.

The calculated drainage times prove too long to be compatible with the observations. Stated differently, if the film between bubbles thinned by Reynolds drainage alone during the observed time span, it would only reach a minimum

thickness h_m that is much larger than that needed to induce film rupture. Hence, a mechanism for film rupture must be at work that overrules the drainage. We suggest that shape instabilities of the bubble can cause local corrugations that bridge the film and rupture it, before thinning of the whole film. We show that small perturbations on the bubble surface may grow tremendously, a phenomenon known as parametric instability. The initial perturbations may come from thermal undulations and external radiation forces. We show that the latter are dominant, and lead to sufficiently large undulations to bridge the minimum thickness h_m within half an ultrasonic cycle.

Bounce is the process where bubbles approach and flatten, but do not coalesce (Postema et al., 2003c). This behavior has been attributed to the drainage given in eq. (6) taking more time than the expansion phase.

Fragmentation

Fragmentation is the fission of a bubble into smaller bubbles (Postema et al., 2002a). Although acoustical observations have been associated with microbubble destruction (Shi et al., 2000), fragmentation of UCA microbubbles was first visualized with high-speed cameras in 2001 (Chomas et al., 2001a; Postema et al., 2001). In the same year, Brennen (2001) computed the number of fragments for a cavitation bubble distorted by spherical harmonics. He demonstrated that for any positive $\Gamma = \frac{\rho R^2 \ddot{R}}{\sigma}$, where $\ddot{R}$ denotes the second time derivative of R , there

must be a mode n for which the spherical harmonic distortion has a maximum. This mode depends on Γ as $n = \frac{1}{3}\sqrt{7 + 3\Gamma} - \frac{2}{3}$. The number of fragments N is estimated $N \approx n^3$.

Chomas et al. (2001b) showed that fragmentation occurs around peak contraction, when the bubble collapse is driven by inertial forces, since the inward acceleration continues to increase as the bubble approaches its minimum radius and suddenly changes sign as the bubble begins a rebound. They suggest that if the energy that is transferred during collapse is not sufficiently dissipated during one ultrasonic cycle, the bubble will become unstable and fragment.

Longuet-Higgins (1992) related the intrinsic energy of a bubble fragment population with a size distribution $P(R)$ to the initial intrinsic energy of the mother-bubble with equilibrium radius R_0 :

$$E^* = \int_0^\infty \left(\frac{R}{R_0}\right)^2 P(R) dR, \quad (7)$$

where E^* is the intrinsic energy ratio, and R is the radius of a fragment. For bubble fragments of equal sizes, $E^* = \frac{R_0}{R} = \sqrt[3]{N}$. Longuet-Higgins (1992) also presented an elegant method to compute the size distribution of bubbles generated by “shattering a single air cavity”.

Sonic cracking

Sonic cracking is the ultrasound-induced formation of a shell defect causing gas to escape from UCA microbubbles. It has been observed with rigid-shelled UCA microbubbles (Dayton et al., 1997a; Takeuchi, 1999; Postema et al., 2002a). The physical mechanism behind sonic cracking is yet not known. Tiny flaws in the shells may account for the fact that certain bubbles crack while others stay intact (Postema et al., 2002a).

Jetting

When a bubble rapidly contracts (collapses) near a boundary, this collapse will be asymmetrical. A high-speed liquid jet may form which projects through the bubble towards the boundary (Barnett, 1998), pulling a slight volume of the bubble content along. This remarkable phenomenon is called jetting.

The jetting phenomenon for cavitation bubbles was described by Philipp and Lauterborn (1998) and depicted by Ory (*cf.* Figure 1): The asymmetric collapse causes the velocity of the upper bubble wall to exceed the velocity of the lower wall in order to conserve the impulse of the bubble/fluid system. Consequently, the fluid volume above the bubble is accelerated and focused during collapse, leading to the formation of a liquid jet directed towards the boundary. This jet hits the lower bubble wall, causing a funnel-shaped protrusion and finally impacts on

the boundary.

Jets have regularly been observed with cavitation bubbles (Lauterborn, 1976; Philipp and Lauterborn, 1998). An illustrative enlargement of a high-speed photograph of a cavitation jet in the millimeter range was published by Lauterborn and Ohl (1997). Ohl and Ory (2000) calculated the shapes of asymmetrically collapsing bubbles. Their results are consistent with photographs of a collapsing cavitation bubble developing a jet. Kodama and Takayama (1998) studied the impact of jets on gelatin surfaces. They found that the radius of the jet R_j is approximately related to the radius of the bubble on the verge of collapsing R_c as $\frac{R_j}{R_c} \approx 0.1$ (Kodama and Takayama, 1998; Ohl and Ikink, 2003). The length of the jet l_j , defined as the full travel path of the propelled liquid, is approximately related to R_c as $\frac{l_j}{R_c} \approx 3$ (Ohl and Ikink, 2003). From these two ratios the amount of liquid within the jet, V_j , is estimated $V_j \approx 0.1R_c^3$ (Ohl and Ikink, 2003).

The impact of a jet on a surface generates a high-pressure region. The pressure in this region was dubbed *water-hammer pressure* by Cook (1928). For a perfectly plastic impact, the water-hammer pressure of a cavitation jet was estimated by de Haller (1933) and Ohl and Ory (2000):

$$p_{\text{wh}} \approx \frac{1}{2} \rho c v_j, \quad (8)$$

where p_{wh} is the water-hammer pressure, v_j is the jet velocity, ρ is the fluid density, and c is the speed of sound.

The damage caused by a jet can be estimated by comparing the water-hammer pressure to the maximum stress the impact surface can withstand before rupture. The maximum stress $\tau_{\max}$ is given by:

$$\tau_{\max} = E\varepsilon_r, \quad (9)$$

where E is the elastic (Young's) modulus of the material, and ε_r is the relative deformation of the surface before rupture.

Clinical applications

UCA microbubble oscillating behavior is the basis of most diagnostic imaging techniques (Becher and Burns, 2000; Goldberg et al., 2001). Since oscillating microbubbles provide a means to discriminate blood from tissue, they are applicable in perfusion and flow imaging, and tumor detection (Burns et al., 1990; Wei et al., 1998; Wei, 2001).

Medical applications of the manipulation of the movement of UCA microbubbles by means of acoustic energy will be primarily in directing UCA toward cells (Dayton et al., 2001a).

If small UCA microbubbles, having passed through the narrowest vessels, coalesce, they may be controlled to obtain resonant sizes. Especially for subharmonic imaging (Shankar et al., 1999), where twice the resonant bubble size is needed, and for tracking the diffusion of free gas bubbles with subharmonics, a

promising technique in noninvasive blood pressure measurements (Postema et al., 2003b), controlled microbubble coalescence may be applicable. If coalescence of a lipid-shelled microbubble and a cell membrane can be induced, this will imply a promising technique in targeted drug delivery.

Bouncing behavior of UCA microbubbles has got no potential medical application yet.

UCA microbubble fragmentation has been associated with violent effects, such as cell membrane permeabilization and lysis. The reason for this may lie in the fact that fragmenting bubbles produce shock-waves. Because of the strong acoustic signal generated, fragmentation finds applications in high-MI imaging. The applicability of microbubble fragmentation for local drug delivery is fully dependent of the presence of a shell after fragmentation. If the shell is absent after fragmentation, the fragments will behave as released gas bubbles. Thus, the potential therapeutic applications will then be identical to those for sonic cracking.

Sonic cracking may find applications in drug delivery, if the released bubble content has therapeutic properties (Frinking et al., 1998). Frinking et al. (2001) suggested a technique they called release burst imaging: Upon transmission of a high-MI ultrasound burst, there will be a strong scattering response from the released gas bubbles. The free gas will rapidly dissolve, and with it the strong scattering response will fade away. Wei et al. (1998) proposed that the acoustical

measurement of the reappearance of UCA microbubbles may provide a means for determining tissue perfusion in any organ accessible to ultrasound.

The diffusion rate of a gas bubble with a certain size is known for every hydrostatic pressure. By making use of the changing acoustic properties of the dissolving gas bubbles, hydrostatic pressures may be determined in a minimally invasive clinical setting (Bouakaz et al., 2000; Postema et al., 2003b).

It has been speculated that jets may be formed when UCA microbubbles in the bloodstream are insonified with high enough acoustic pressures. These jets would be directed towards a boundary like a cell or a capillary wall with adjacent cells. As such, jets might function as microsyringes (Miller, 2000; Ohl and Ikink, 2003), if they could penetrate cells. The maximum extension measured in human cells is less than 50% ($\varepsilon_r < 0.5$) (Lendon et al., 1991). Therefore, we may assume that for any human cell or cell part, $\varepsilon_r \ll 1$. Elastic moduli of human cells were measured $E \lesssim 7.3$ kPa for endothelial cells (Mathur et al., 2000), and $E \lesssim 12$ kPa for fibroblasts (Rotsch et al., 1999): less than half the elastic modulus of murine skeletal muscle cells ($E \approx 24$ kPa) (Mathur et al., 2001). Rabbit cardiac cells are among the stiffest, with $E \approx 100$ kPa (Mathur et al., 2001). It is safe to assume that even for the stiffest human cell $E \ll 200$ kPa. Combining both assumptions in eq. (9) gives $\tau_{\max} \ll 200$ kPa. If the water-hammer pressure of a jet exceeds this stress, the jet will be able to penetrate any human cell.

The porosities observed on cell-membranes by Tachibana et al. (1999)

may well be attributed to jets. Probably, particles that were present in the photosensitive drug acted as cavitation nuclei, whereas the cell-membranes acted as the boundaries towards which the jets were directed.

Experimental setup

Overview

For the high-speed observations, we made use of the Brandaris-128 system (Chin et al., 2003) and an Imacon 468 fast framing camera. An overview of this experimental setup is shown in Figure 2. A computer controlled the triggering of a waveform generator, a Xenon flash source, and the cameras.

The electrical signal was generated by an AWG 520 arbitrary waveform generator (Tektronix, Inc., Beaverton, OR), or by an LW 420A arbitrary waveform generator (LeCroy Corp., Chestnut Ridge, NY). The signal was adjusted by two variable 355C/D attenuators (Hewlett Packard Company, Palo Alto, CA) in series, and an A-500 60 dB linear power amplifier (ENI technology, Inc., Rochester, NY). It was converted to ultrasound by a v389-SU 500 kHz, or by a v397-SU 2.25 MHz single-element transducer (Panametrics Inc., Waltham, MA), both spherically focused at 7.5 cm. The transducers were mounted in a Perspex container at an angle of 45° relative to the top of the container. This container was filled with saturated water. A $\varnothing$ 200 μ m cellulose Cuprophan® capillary

tube (Membrana GmbH, Wuppertal, Germany) was fixed in the focal area of the transducer, through which contrast agent was flowing. Because the capillary tube was watersoaked and much smaller in diameter than the acoustic wavelength, it was not expected to interfere with the ultrasound transmitted. Without contrast agent inserted, we did not observe reflections from the tube.

Optics

Underneath the capillary tube an optic fiber was mounted. This fiber was connected to an MVS-7010 Fiber Optic Strobe (PerkinElmer Optoelectronics, Salem, MA), and to a KLS-201 continuous fiber light source (Olympus KMI (KeyMed Ltd), Southend-on-Sea, UK). The pulsed light source was triggered by a PM 5716 pulse/delay generator (Koninklijke Philips Electronics N.V., Eindhoven, The Netherlands). The container was positioned beneath a customized BXFM microscope system (Olympus Optical Co., Ltd., Tokyo, Japan) with a U-CA magnification changer (Olympus Optical Co., Ltd.), switched to $2\times$ magnification and a LUMPlanFl $60\times$ water immersion objective lens (Olympus Optical Co., Ltd.). For the measurements with the Imacon 468 camera, we made use of a BH-2 model (Olympus Optical Co., Ltd.) with an SPlan 100 oil immersion objective lens (Olympus Optical Co., Ltd.). For image control purposes, an LCL-902K or a WAT-902HS CCD camera (Watec Co., Ltd., Yamagata, Japan) was fitted to the microscope. Focusing was done manually at the middle of the cellulose tube.

Because the tube was wide compared to the contrast microbubbles measured, its upper half was considered a flat surface between contrast microbubbles and object lens, not causing aberrations but lowering the dynamic range of the images.

Camera

The optical observations were recorded with a Brandaris-128 fast framing camera system Chin et al. (2003). The Brandaris-128 captured sequences of 128 image frames at an average speed of 13 million frames per second. Typical frame sizes correspond to $89 \times 68 \mu\text{m}^2$. In all observations, image frames were captured before, during, and after ultrasound insonification. A line drawing of the optical observation part of the setup is shown in Figure 3 and 4.

Furthermore, we made use of an Imacon 468 fast framing camera (DRS Hadland, Ltd., Tring, UK), capturing eight two-dimensional frames at 3 MHz. In all observations, the first frame was taken a few microseconds before ultrasound waves reached the contrast agent. The other seven frames were taken during ultrasound insonification, with 330 ns interframe time for 500 kHz ultrasound, spanning a full ultrasound cycle. Frame exposure times ranged from 10 ns to 70 ns. A line drawing of the optical observation part of this setup is shown in Figure 5.

Contrast agents

We investigated the ultrasound contrast agent Quantison™ (Upperton Limited). It consists of human serum albumin-encapsulated air bubbles with a mean diameter of $3.2\ \mu\text{m}$. Shell thicknesses are between 0.2 and $0.3\ \mu\text{m}$ (Frinking and de Jong, 1998). The content of a Quantison™ vial was resuspended in 5 ml of Isoton® II (Beckman Coulter, Inc., Fullerton, CA), and shaken gently for 20 seconds before further dilution. The agent was inserted through the capillary tube using a syringe pressed by hand.

We also investigated an experimental UCA (supplied by Bracco Research SA, Geneva, Switzerland). It consists of phospholipid-encapsulated gas bubbles ranging in diameter from 1 to $6\ \mu\text{m}$ with a median of $2\ \mu\text{m}$. The acoustic behavior of a very similar contrast agent was modeled and described in Gorce et al. (2000). Undiluted UCA (5ml of a 0.9% sodium chloride dilution, added to a 25 mg UCA vial) was inserted through the capillary tube using either a syringe pressed by hand or a hose operated by a gravity fed or pumped infusion.

Ultrasound

For the experiments with the Brandaris-128 camera system, the UCA bubbles were insonified by 8 cycles of 1.7 MHz ultrasound at a peak rarefactional acoustic pressure of 2 MPa, corresponding to a mechanical index of $MI = 1.5$. For

the experiments with the Imacon 468 camera, the UCA bubbles were insonified by 10 cycles of 500 kHz ultrasound at peak rarefactional acoustic pressures between 0.66 and 0.85 MPa, corresponding to mechanical indices in the range $0.9 < \text{MI} < 1.2$. The mechanical index is defined as $\text{MI} = p_{\text{ac}} / \sqrt{f}$, where p_{ac} is the peak rarefactional acoustic pressure in MPa and f is the center frequency of the ultrasound in MHz.

Acoustic pressures applied were measured with a calibrated MH28-10 hydrophone (FORCE Technology, Brøndby, Denmark) in a separate water tank. An example of the acoustic signal measured at the transducer focus has been published in Postema et al. (2003a). The *in-situ* reverberant component due to the presence of the microscopic lens was observed to be less than -14 dB. Thus, it is assumed the *in-situ* acoustic signal is the same as the signal measured.

Procedure

We recorded 277 image sequences with the Brandaris-128 system. We performed 527 experiments at high acoustic amplitudes with the Imacon-468 camera. Bubble sizes and distances were measured manually or by using a segmentation method described by Postema et al. (2003a).

Results and discussion

The following types of ultrasound-induced UCA microbubble behavior have been distinctly observed and categorized: oscillation, translation, coalescence, fragmentation, sonic cracking, and jetting.

Oscillation

Figure 6(i) shows an optical image sequence of two identical $\varnothing 6 \mu\text{m}$ moderately oscillating experimental UCA microbubbles freely flowing through a capillary tube. The frames have been taken during one cycle of ultrasound insonification, with a center frequency of 0.5 MHz and a mechanical index $MI = 0.09$. Inter-frame times for frames b to h are $0.33 \mu\text{s}$. Each frame corresponds to a $88 \times 58 \mu\text{m}^2$ area. Frame a has been taken prior to ultrasound arrival. Maximal sizes are reached in frame d with bubble diameters of $7.6 \mu\text{m}$, whereas minimal sizes are displayed in frame f with bubble diameters of $4.4 \mu\text{m}$. Thus, the expansion and contraction of the bubbles are symmetric. We do not expect a violent collapse in this regime, since the maximum bubble radius is less than twice its equilibrium radius. The oscillating amplitude is represented in the left frame of Figure 6(iii). The solid line represents the radius–period curve of a free gas bubble (de Jong et al., 1994). Apparently, the UCA bubbles have comparable excursions to a free gas bubble.

Figure 6(ii) and the right frame of Figure 6(iii) show a similar situation for a $\odot 1.5 \mu\text{m}$ strongly oscillating microbubble insonified at $\text{MI} = 0.67$. Again, the UCA bubble excursion is comparable to a free gas bubble. At the acoustic amplitude applied there may be some energy loss in the shell, causing increased thermal damping. Maximum size is reached in frame e with a bubble diameter of $10.0 \mu\text{m}$, whereas minimum size is displayed in frame g with a bubble diameter of $0.57 \mu\text{m}$. The bubble oscillates highly asymmetric. We expect the microbubble to grow into an *inertial cavity* in this regime, since the maximum bubble radius is much greater than its equilibrium radius.

Translation

Figure 7 shows a high-speed optical image sequence of QuantisonTM insonified by 8 cycles of 1.7 MHz ultrasound with a mechanical index $\text{MI} = 1.5$. The ultrasound travels from the lower side of the frames to the upper side. Frame times are indicated in ns. Each frame corresponds to a $30 \times 16 \mu\text{m}^2$ area. In Figure 7(b,c,d) gas escapes from a $\odot 4 \mu\text{m}$ bubble. This free gas bubble expands and contracts, and translates towards the upper side of the frames. The displacement of the free gas bubble center has been measured $14 \mu\text{m}$ over 4 periods (frames e–h). The resting diameter of the released bubble after insonification was $1.3 \mu\text{m}$. The theoretical mean bubble displacement over time has been computed by integrating eq. (1) over 4 periods, taking $c = 1480 \text{ m s}^{-1}$, $\rho = 998 \text{ kg m}^{-3}$, $R_0 = 0.65 \mu\text{m}$,

$f = 1.7 \text{ MHz}$, $f_r = 5.3 \text{ MHz}$, $\delta_t = 1.0$, $p_{ac}(t) = [2 \text{ MPa}] \sin 2\pi ft$, and $\eta = 0.001 \text{ Pa s}$. The damping was computed using the parameters stated in Medwin (1977) and de Jong (1993). The theoretical displacement is $18 \mu\text{m}$. The measured displacement is lower than the theoretical value. At the acoustic pressure applied, the expansion phase is longer than the contraction phase, which may account for this difference.

Figure 8 shows 5 image frames of two $\odot 4 \mu\text{m}$ experimental UCA microbubbles, each captured after insonification by 10 cycles of 0.5 MHz ultrasound (duration $T_p = 20 \mu\text{s}$). Each image frame corresponds to a $30 \times 20 \mu\text{m}^2$ area. During every ultrasound burst the bubbles draw nearer to each other. For each center-to-center distance d_0 measured the mean approach velocity v_a has been computed from eq. (4), taking $\kappa = 5 \times 10^{-6} \text{ m}^2 \text{ N}^{-1}$. By combining d_0 with v_a , the theoretical distances $\Delta d_{th} = v_a T_p$ have been computed. These were compared to the distance Δd_m measured from Figure 8. The results are summarized in Table 1. The measured values Δd are consistent with theory.

Coalescence

Figure 9(i) shows an example of microbubble coalescence. The first frame has been captured prior to ultrasound arrival. In Figure 9(i)b), the main bubble with an initial diameter of $4 \mu\text{m}$ has split up, into several fragments with diameters below or around optical resolution, and these fragments have started to coalesce

upon expansion. As the resulting two bubbles have expanded to mean diameters of approximately $2.7 \mu\text{m}$, shown in Figure 9(i)c), the flattening of the adjacent bubble surfaces is clearly visible. After the bubbles have expanded further to mean diameters of $4.6 \mu\text{m}$, as demonstrated in Figure 9(i)d), the interposed film has drained to a critical thickness to rupture (Figure 9(i)e), which has resulted in the formation of a single bubble (Figure 9(i)f).

The flattening of the adjacent bubble surfaces in Figure 9(i)b) is supported by a conservative estimate of the Weber number. Based on our analysis of the optical system (Postema et al., 2003a), we may assume that the optical resolution $\mathcal{R} \ll 0.5 \mu\text{m}$, and fragment diameters in Figure 9(i)b) $< 0.5 \mu\text{m}$. Even if the bubbles would expand linearly to the sizes observed in Figure 9(i)c), the approach velocity would still have to be $u = 2 \frac{\Delta R_m}{\Delta t} > \frac{2.7 \mu\text{m} - 0.5 \mu\text{m}}{0.33 \mu\text{s}} = 6.7 \text{ ms}^{-1}$. By taking $\rho = 998 \text{ kg m}^{-3}$ and $\sigma = 0.072 \text{ N m}^{-1}$, we obtain a Weber number $We > 0.84$. As stated before, flattening of the adjacent bubble surfaces will occur if $We > 0.5$.

From eq. (6), it is expected that the drainage time of the film shown in Figure 9(i)c) until a critical thickness $h_c = 0.1 \mu\text{m}$ is $t_d = 0.6 \mu\text{s}$, taking $\eta = 0.001 \text{ Pa s}$ and $R_f \approx \frac{2}{3} R_m$ (Postema et al., 2003c). However, Figure 9(i)d) shows not only film drainage, but also continuing bubble expansion. For these bubble diameters of $4.6 \mu\text{m}$, the interposed film would take $2.8 \mu\text{s}$ to drain. Still, $0.66 \mu\text{s}$ later the bubbles have coalesced, although the bubbles have continued to expand. This supports the theory that a mechanism for film rupture must be at

work that overrules the drainage.

Fragmentation

Figure 9(ii) shows the repeated fragmentation, coalescence, and re-fragmentation of an experimental UCA microbubble with an initial diameter $\mathcal{D} = 6 \mu\text{m}$. Each frame corresponds to a $23 \times 23 \mu\text{m}^2$ area. Figure 9(ii)a was captured prior to ultrasound arrival. In Figure 9(ii)b the bubble has broken up into 8 discernable fragments, suggesting a mode $n = \sqrt[3]{8} = 2$ spherical harmonical instability. The fragments coalesce and form an ellipsoidal bubble in Figure 9(ii)e. Because the ellipsoidal shape can be discriminated, we may conclude that the second spherical harmonic mode is dominant. After collapse, the fragments in Figure 9(ii)f are too small to be counted, but in Figure 9(ii)g, captured while the fragments have begun to expand, 8 fragments can be discerned, which confirms the second mode instability.

Sonic cracking

Figure 9(iii) shows the sonic cracking of a $\oslash 3 \mu\text{m}$ QuantisonTM microbubble. Each frame corresponds to a $23 \times 23 \mu\text{m}^2$ area. In Figure 9(iii)d gas starts to escape from the bubble in the middle of the frame. It expands to approximately $\oslash 8 \mu\text{m}$ in Figure 9(iii)g, and then begins to contract in Figure 9(iii)h.

Clearly, the gas bubble has been released from its rigid shell. However, in the

image sequence, the pixel size ($0.15 \times 0.15 \mu\text{m}^2$) corresponds in approximation to the shell thickness. Thus, even if the optical resolution were of the order of the shortest wavelength of the light, the presence of tiny flaws in the rigid shell would not have been detectable.

Jetting

We recorded two optical sequences showing jet development in UCA microbubbles (Postema et al., 2002b), one of which is shown in Figure 10. Figure 10(a) shows a microbubble with a radius $R_c = 8.43 \mu\text{m}$. Figure 10(b) has been captured $0.33 \mu\text{s}$ later. Liquid is propelled through the lower left and escapes from the upper right of the bubble. The jet has traveled over a length $l_j = 26.2 \mu\text{m}$ in $0.33 \mu\text{s}$, giving an average jet velocity $v_j = 79.4 \text{ m s}^{-1}$. The ratio $\frac{l_j}{R_c}$ is in agreement with the ratio put forward by Ohl and Ikink (2003). The volume of the jet is approximately $V_j \approx 0.1 R_c^3 = 60 \text{ femtoliter}$.

Taking $\rho = 998 \text{ kg m}^{-3}$ and $c = 1480 \text{ m s}^{-2}$, the water-hammer pressure is around 60 MPa. Since $p_{\text{wh}} \gg 200 \text{ kPa} \gg \tau_{\text{max}}$, such a jet may penetrate any cell.

Influence of the capillary tube

Ishida et al. (2001) demonstrated with simulations and high-speed optical observations, that if the distance between the walls of their solid test vessel was

greater than 5 times the maximum free-field expansion radius of a cavitation bubble, the bubble would remain spherical while expanding. In our setup, the diameter of the water-soaked capillary tube is approximately 20 times the largest microbubble radius measured. Thus, the phenomena described other than jetting cannot be attributed to the boundaries imposed by the capillary tube, since our imaging plane is at the center of the tube.

Conclusions

An overview of dynamic behavior of ultrasound insonified encapsulated microbubbles has been presented. The following types of behavior have been observed and categorized: oscillation, translation, coalescence & bounce, fragmentation, sonic cracking, and jetting.

Oscillation is the expanding and contracting bubble response to an oscillating acoustic signal. At low acoustic amplitudes bubbles pulsate moderately, at high amplitudes their longer expansion phase is followed by a violent collapse. Microbubble translation has been associated with primary and secondary radiation forces. Our optical observations of translating bubbles are consistent with theory. Coalescence, the fusion of two or more bubbles, is mainly caused by the drainage of the liquid film separating expanding bubbles, whereas bounce — unsuccessful coalescence — is caused by the drainage taking longer than the expansion of

the bubbles. Fragmentation is the fission of a bubble into smaller bubbles. The number of fragments has been related to the dominant spherical harmonical oscillation mode of a bubble. In our observations, the second spherical harmonical mode appears to be the dominant mode. Remarkable are our observations of jetting through encapsulated microbubbles. For an observed jet, we computed a volume of approximately 60 femtoliter, generating a pressure at the tip of the jet around 60 MPa. This is high enough to penetrate any human cell. Hence, liquid jets may act as microsyringes, delivering a drug to a region of interest.

Table 2 gives an overview of potential clinical applications related to the encapsulated microbubble phenomena discussed. The phenomena have potential clinical applications in imaging, pressure measurements, tumor detection, permeabilization, lysis, targeting, and drug delivery.

Acknowledgments

This work has been supported by the Technology Foundation STW (RKG.5104). We thank Kees Slager for the data on cell elasticity, Emmanuel Ory (Laboratory of Applied Thermodynamics, Helsinki University of Technology) for computing Figure 1, Leo Bekkering and Elmer Koene for technical assistance, and Cees Pakvis for drawing Figures 3, 4, and 5.

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Tables

Table 1: Traveled distances and mean velocities of approaching bubbles.

frame	d_0 (μm)	v_a (cm s^{-1})	Δd_{th} (μm)	Δd_{m} (μm)
a	21.2	15	3.0	3.2
b	18.0	20	4.0	3.9
c	14.1	33	6.6	6.4
d	7.7	111	> 7.7	7.7
e	0			

Table 2: Potential clinical applications for encapsulated microbubble phenomena observed.

	oscillation	translation	coalescence	fragmentation	sonic cracking	jetting
imaging	★		★	★	★	
pressure measurements			★	?	★	
tumor detection	★					
permeabilization and lysis				★		★
targeting		★	★			
drug delivery			★	?	★	★

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Figure 8: The approach of two $\varnothing 4 \mu\text{m}$ experimental UCA bubbles induced by a secondary radiation force. Each image frame corresponds to a $30 \times 20 \mu\text{m}^2$ area. Frames are each captured after insonification by 10 cycles of 0.5 MHz ultrasound ($\text{MI} = 0.67$).

Figure 9: Experimental UCA microbubbles showing (i) coalescence, (ii) second mode spherical harmonical fragmentation, (iii) sonic cracking. Frames a have been captured prior to ultrasound arrival. Inter-frame times for frames b to h are $0.33 \mu s$. Each image frame corresponds to a $23 \times 23 \mu m^2$ area.

Figure 10: Ultrasound-induced jet development in an experimental UCA microbubble ($MI = 1.2$). Each image frame corresponds to a $38 \times 30 \mu\text{m}^2$ area. Inter-frame time is $0.33 \mu\text{s}$ and exposure time is 10 ns .