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DEvIANT: Discovering Significant Exceptional (Dis-)Agreement Within Groups [Tech. Report]

Adnene Belfodil¹ (✉), Wouter Duivesteijn², Marc Plantevit³, Sylvie Cazalens¹, and Philippe Lamarre¹

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Abstract. We strive to find contexts (i.e., subgroups of entities) under which exceptional (dis-)agreement occurs among a group of individuals, in any type of data featuring individuals (e.g., parliamentarians, customers) performing observable actions (e.g., votes, ratings) on entities (e.g., legislative procedures, movies). To this end, we introduce the problem of discovering statistically significant exceptional contextual intra-group agreement patterns. To handle the sparsity inherent to voting and rating data, we use Krippendorff’s Alpha measure for assessing the agreement among individuals. We devise a branch-and-bound algorithm, named DEvIANT, to discover such patterns. DEvIANT exploits both closure operators and tight optimistic estimates. We derive analytic approximations for the confidence intervals (CIs) associated with patterns for a computationally efficient significance assessment. We prove that these approximate CIs are nested along specialization of patterns. This allows to incorporate pruning properties in DEvIANT to quickly discard non-significant patterns. Empirical study on several datasets demonstrates the efficiency and the usefulness of DEvIANT.

1 Introduction

Consider data describing voting behavior in the European Parliament (EP). Such a dataset records the votes of each member (MEP) in voting sessions held in the parliament, as well as the information on the parliamentarians (e.g., gender, national party, European party alliance) and the sessions (e.g., topic, date). This dataset offers opportunities to study the agreement or disagreement of coherent subgroups, especially to highlight unexpected behavior. It is to be expected that on the majority of voting sessions, MEPs will vote along the lines of their European party alliance. However, when matters are of interest to a specific nation within Europe, alignments may change and agreements can be formed or dissolved. For instance, when a legislative procedure on fishing rights is put before the MEPs, the island nation of the UK can be expected to agree on a specific course of action regardless of their party alliance, fostering an exceptional agreement where strong polarization exists otherwise.

We aim to discover such exceptional (dis-)agreements. This is not limited to just EP or voting data: members of the US congress also vote on bills, while
Amazon-like customers post ratings or reviews of products. A challenge when considering such voting or rating data is to effectively handle the absence of outcomes (sparsity), which is inherently high. For instance, in the European parliament data, MEPs vote on average on only $\frac{3}{4}$ of all sessions. These outcomes are not missing at random: special workgroups are often formed of MEPs tasked with studying a specific topic, and members of these workgroups are more likely to vote on their topic of expertise. Hence, present values are likely associated with more pressing votes, which means that missing values need to be treated carefully. This problem becomes much worse when looking at Amazon or Yelp rating data: the vast majority of customers will not have rated the vast majority of products/places.

We introduce the problem of discovering significantly exceptional contextual intra-group agreement patterns, rooted in the Subgroup Discover (SD) \cite{47}/ Exceptional Model Mining (EMM) \cite{8} framework. To tackle the data sparsity issue, we measure the agreement among groups with Krippendorff’s alpha, a measure developed in the context of content analysis \cite{28} which handles missing outcomes elegantly. We develop a branch-and-bound algorithm to find subgroups featuring statistically significantly exceptional (dis-)agreement among groups. This algorithm enables discarding non-significant subgroups by pruning unpromising branches of the search space (cf. Figure 1). Suppose that we are interested in subgroups of entities (e.g., voting sessions) whose sizes are greater than a support threshold $\sigma$. We gauge the exceptionality of a given subgroup of size $X \geq \sigma$, by its \textit{p-value}: the probability that for a random subset of entities, we observe an intra-agreement at least as extreme as the one observed for the subgroup.

\begin{figure}[h]
\centering
\includegraphics[width=\textwidth]{figure1.png}
\caption{Main DEvIANT properties for safe sub-search space pruning. A subgroup is reported as significant if its related Krippendorff’s Alpha falls in the critical region of the corresponding empirical distribution of random subsets (DFD). When traversing the search space downward (decreasing support size), the approximate confidence intervals are nested. If the optimistic estimates region falls into the confidence interval computed on the related DFD, the sub-search space can be safely pruned.}
\end{figure}
Thus we avoid reporting subgroups observing a low/high intra-agreement due to chance only. To achieve this, we estimate the empirical distribution of the intra-agreement of random subsets (DFD: Distribution of False Discoveries, cf. [9,33]) and establish, for a chosen critical value $\alpha$, a confidence interval $CI_X^{1-\alpha}$ over the corresponding distribution under the null hypothesis. If the subgroup intra-agreement is outside $CI_X^{1-\alpha}$, the subgroup is statistically significant ($p\text{-value} \leq \alpha$); otherwise the subgroup is a spurious finding. We prove that the analytic approximate confidence intervals are nested: $\sigma \leq Y \leq X \Rightarrow CI_X^{1-\alpha} \subseteq CI_Y^{1-\alpha}$ (i.e., when the support size grows, the confidence interval shrinks). Moreover, we compute a tight optimistic estimate (OE) [18] to define a lower and upper bounds of Krippendorff’s Alpha for any specialization of a subgroup having its size greater than $\sigma$. Combining these properties, if the OE region falls into the corresponding CI, we can safely prune large parts of the search space that do not contain significant subgroups. In summary, the main contributions are:

1) We introduce the problem of discovering statistically significant exceptional contextual intra-group agreement patterns (Section 3).

2) We derive an analytical approximation of the confidence intervals associated with subgroups. This allows a computationally efficient assessment of the statistical significance of the findings. Furthermore, we show that approximate confidence intervals are nested (Section 4). Particular attention is also paid to the variability of outcomes among raters (Section 5).

3) We devise a branch-and-bound algorithm to discover exceptional contextual intra-group agreement patterns (Section 6). It exploits tight optimistic estimates on Krippendorff’s alpha and the nesting property of approximate CIs.

2 Background and Related Work

The page limit, combined with the sheer volume of other material in this paper, compels us to restrict this section to one page containing only the most relevant research to this present work.

Measuring Agreement. Several measures of agreement focus on two targets (Pearson’s $\rho$, Spearman’s $\rho$, Kendall’s $\tau$, Association): most cannot handle missing values well. As pointed out by Krippendorff [28, p.244], using association and correlation measures to assess agreement leads to particularly misleading conclusions: when all data falls along a line $Y = aX + b$, correlation is perfect, but agreement requires that $Y = X$. Cohen’s $\kappa$ is a seminal measure of agreement between two raters who classify items into a fixed number of mutually exclusive categories. Fleiss’ $\kappa$ extends this notion to multiple raters and requires that each item receives the exact same number of ratings. Krippendorff’s alpha generalizes these measures while handling multiple raters, missing outcomes and several metrics [28, p.232].

Discovering Significant Patterns. Statistical assessment of patterns has received attention for a decade [44,21], especially for association rules [20,35]. Some work focused on statistical significance of results in SD/EMM during enumeration [9,33] or a posteriori [10] for statistical validation of the found subgroups.
Voting and Rating Data Analysis. Previous work [3] proposed a method to
discover exceptional inter-group agreement in voting or rating data. This method
does not allow to discover intra-group agreement. In rating datasets, groups are
uncovered whose members exhibit an agreement or discord [6] or a specific rating
distribution [1] (e.g., polarized, homogeneous) given upfront by the end-user.
This is done by aggregating the ratings through an arithmetic mean or a rating
distribution. However, these methods do not allow to discover exceptional (dis-
)agreement within groups. Moreover, they may output misleading hypotheses
over the intra-group agreement, since aggregating ratings in a distribution (i)
is highly affected by data sparsity (e.g., two reviewers may significantly differ
in their number of expressed ratings) and (ii) may conceal the true nature of
the underlying intra-group agreement. For instance, a rating distribution com-
puted for a collection of movies may highlight a polarized distribution of ratings
(interpreted as a disagreement) while ratings over each movie may describe a
consensus between raters (movies are either highly or lowly rated or by the
majority of the group). These two issues are addressed by Krippendorff’s alpha.

3 Problem Definition

Our data consists of a set of individuals (e.g., social network users, parliamentar-
ians) who give outcomes (e.g., ratings, votes) on entities (e.g., movies, ballots).
We call this type of data a behavioral dataset (cf. Table 1).

Definition 1 (Behavioral Dataset). A behavioral dataset \( \mathcal{B} = (G_I, G_E, O, o) \)
is defined by (i) a finite collection of Individuals \( G_I \), (ii) a finite collection of
Entities \( G_E \), (iii) a domain of possible Outcomes \( O \), and (iv) a function \( o : G_I \times G_E \to O \) that gives the outcome of an individual \( i \) over an entity \( e \).

The elements from \( G_I \) (resp. \( G_E \)) are augmented with descriptive attributes
\( A_I \) (resp. \( A_E \)). Attributes \( a \in A_I \) (resp. \( A_E \)) may be Boolean, numerical or cat-
egorical, potentially organized in a taxonomy. Subgroups (subsets) of \( G_I \) (resp.
\( G_E \)) are defined using descriptions from \( D_I \) (resp. \( D_E \)). These descriptions are
formalized by conjunctions of conditions on the values of the attributes. Descrip-
tions of \( D_I \) are called groups, denoted \( g \). Descriptions of \( D_E \) are called contexts.

<table>
<thead>
<tr>
<th>(a) Entities</th>
<th>(b) Individuals</th>
<th>(c) Outcomes</th>
</tr>
</thead>
<tbody>
<tr>
<td>ide</td>
<td>themes</td>
<td>date</td>
</tr>
<tr>
<td><strong>e(_1)</strong></td>
<td>1.20 Citizen’s rights</td>
<td>20/04/16</td>
</tr>
<tr>
<td><strong>e(_2)</strong></td>
<td>5.05 Economic growth</td>
<td>16/05/16</td>
</tr>
<tr>
<td><strong>e(_3)</strong></td>
<td>1.20 Citizen’s rights; 7.30 Judicial Coop</td>
<td>04/06/16</td>
</tr>
<tr>
<td><strong>e(_4)</strong></td>
<td>7.30 Judicial Coop</td>
<td>11/06/16</td>
</tr>
<tr>
<td><strong>e(_5)</strong></td>
<td>7.30 Judicial Coop</td>
<td>03/07/16</td>
</tr>
<tr>
<td><strong>e(_6)</strong></td>
<td>7.30 Judicial Coop</td>
<td>29/07/16</td>
</tr>
</tbody>
</table>

Table 1: Example of behavioral dataset - European Parliament Voting dataset

The problem is addressed by aggregating the ratings through an arithmetic mean or a rating
distribution. However, these methods do not allow to discover exceptional (dis-
)agreement within groups. Moreover, they may output misleading hypotheses
over the intra-group agreement, since aggregating ratings in a distribution (i)
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formalized by conjunctions of conditions on the values of the attributes. Descrip-
tions of \( D_I \) are called groups, denoted \( g \). Descriptions of \( D_E \) are called contexts,
denoted \(c\). From now on, \(G\) (resp. \(D\)) denotes both collections \(G_i\) (resp. \(D_i\)) and \(G_E\) (resp. \(D_E\)) if no confusion can arise. We denote by \(G^d\) the subset of records characterized by the description \(d \in D\). Descriptions from \(D\) are partially ordered by a specialization operator denoted \(\sqsubseteq\). A description \(d_2\) is a specialization of \(d_1\), denoted \(d_1 \sqsubseteq d_2\), if and only if \(d_2 \Rightarrow d_1\) from a logical point of view. It follows that \(G^{d_2} \subseteq G^{d_1}\).

### 3.1 Intra-group Agreement Measure: Krippendorff’s Alpha (A)

Krippendorff’s Alpha (denoted \(A\)) measures the agreement among raters. This measure has several properties that make it attractive in our setting, namely: (i) it is applicable to any number of observers; (ii) it handles various domains of outcomes (ordinal, numerical, categorical, time series); (iii) it handles missing values; (iv) it corrects for the agreement expected by chance. \(A\) is defined as:

\[
A = 1 - \frac{D_{\text{obs}}}{D_{\text{exp}}} \tag{1}
\]

where \(D_{\text{obs}}\) (resp. \(D_{\text{exp}}\)) is a measure of the observed (resp. expected) disagreement. Hence, when \(A = 1\), the agreement is as large as it can possibly be (given the class prior), and when \(A = 0\), the agreement is indistinguishable to agreement by chance. We can also have \(A < 0\), where disagreement is larger than expected by chance and which corresponds to systematic disagreement.

Given a behavioral dataset \(B\), we want to measure Krippendorff’s alpha for a given context \(c \in D_E\) characterizing a subset of entities \(G^c_E \subseteq G_E\), which indicates to what extent the individuals who comprise some selected group are in agreement \(g \in D_I\). From Equation (1), we have: \(A(S) = 1 - \frac{D_{\text{obs}}(S)}{D_{\text{exp}}}\) for any \(S \subseteq G_E\). Note that the measure only considers entities having at least two outcomes; we assume the entities not fulfilling this requirement to be removed upfront by a preprocessing phase. We capture observed disagreement by:

\[
D_{\text{obs}}(S) = \frac{1}{\sum_{e \in S} m_e} \sum_{o_1, o_2 \in O^2} \sum_{e \in S} m_{o_1}^e \cdot m_{o_2}^e \cdot \delta_{o_1 o_2} \cdot \frac{1}{m_e - 1} \tag{2}
\]

Where \(m_e\) is the number of expressed outcomes for the entity \(e\) and \(m_{o_1}^e\) (resp. \(m_{o_2}^e\)) represents the number of outcomes equal to \(o_1\) (resp. \(o_2\)) expressed for the entity \(e\). \(\delta_{o_1 o_2}\) is a distance measure between outcomes, which can be defined according to the domain of the outcomes (e.g., \(\delta_{o_1 o_2}\) can correspond to the Iverson bracket indicator function \([o_1 \neq o_2]\) for categorical outcomes or distance between ordinal values for ratings. Choices for the distance measure are discussed in [28]). The disagreement expected by chance is captured by:

\[
D_{\text{exp}} = \frac{1}{m \cdot (m - 1)} \sum_{o_1, o_2 \in O^2} \delta_{o_1 o_2} \cdot m_{o_1} \cdot m_{o_2} \tag{3}
\]

Where \(m\) is the number of all expressed outcomes, \(m_{o_1}\) (resp. \(m_{o_2}\)) is the number of expressed outcomes equal to \(o_1\) (resp. \(o_2\)) observed in the entire behavioral dataset. This corresponds to the disagreement by chance observed on the overall marginal distribution of outcomes.
Example: Table 2 summarizes the behavioral data from Table 1. The disagreement expected by chance equals (given: $m^F = 8$, $m^A = 6$): $D_{exp} = 48/91$. To evaluate intra-agreement among the four individuals in the global context (considering all entities), first we need to compute the observed disagreement $D_{obs}(G_E)$. This equals the weighted average of the two last lines by considering the quantities $m_e$ as the weights: $D_{obs}(G_E) = \frac{4}{13}$. Hence, for the global context, $A(G_E) = 0.46$. Now, consider the context $c = \{ \text{themes} \supseteq \{7.30 \text{ Judicial Coop.}\} \}$, having as support: $G_E^c = \{e_3,e_5,e_6\}$. The observed disagreement is obtained by computing the weighted average, only considering the entities belonging to the context: $D_{obs}^c(G_E) = \frac{4}{7}$. Hence, the contextual intra-agreement is: $A(G_E^c) = -0.08$.

Comparing $A(G_E^c)$ and $A(G_E)$ leads to the following statement: “while parliamentarians are slightly in agreement in overall terms, matters of judicial cooperation create systematic disagreement among them”.

3.2 Mining Significant Patterns with Krippendorff’s Alpha

We are interested in finding patterns of the form $(g,c) \in \mathcal{P}$ (with $\mathcal{P} = \mathcal{D}_I \times \mathcal{D}_E$), highlighting an exceptional intra-agreement between members of a group of individuals $g$ over a context $c$. We formalize this problem using the well-established framework of SD/EMM [8], while giving particular attention to the statistical significance and soundness of the discovered patterns [21].

Given a group of individuals $g \in \mathcal{D}_I$, we strive to find contexts $c \in \mathcal{D}_E$ where the observed intra-agreement, denoted $A^g(G_E^c)$, significantly differs from the expected intra-agreement occurring due to chance alone. In the spirit of [9,33,44], we evaluate pattern interestingness by statistical significance of the contextual intra-agreement: we estimate the probability to observe the intra-agreement $A^g(G_E^c)$ or a more extreme value, which corresponds to the $p$-value for some null hypothesis $H_0$. The pattern is said to be significant if the estimated probability is low enough (i.e., under some critical value $\alpha$). The relevant null hypothesis $H_0$ is: the observed intra-agreement is generated by the distribution of intra-agreements observed on a bag of i.i.d. random subsets drawn from the entire collection of entities (DFD: Distributions of False Discoveries, cf. [9]).

<table>
<thead>
<tr>
<th>[F] or [A]</th>
<th>against</th>
<th>[e]</th>
</tr>
</thead>
<tbody>
<tr>
<td>$i_1$</td>
<td>A</td>
<td>F A</td>
</tr>
<tr>
<td>$i_2$</td>
<td>F</td>
<td>A F F</td>
</tr>
<tr>
<td>$i_3$</td>
<td>F A F A</td>
<td></td>
</tr>
<tr>
<td>$i_4$</td>
<td>F</td>
<td>F A</td>
</tr>
<tr>
<td>$m_e$</td>
<td>3 2 2 3 2</td>
<td></td>
</tr>
<tr>
<td>$D_{obs}(c)$</td>
<td>0 0 1 0 0</td>
<td></td>
</tr>
</tbody>
</table>

**Table 2:** Summarized Behavioral Data: $D_{obs}(c) = \sum_{o_1,o_2 \in O^2} \delta_{o_1,o_2} m_e^{o_1} \cdot m_e^{o_2} / m_e \cdot (m_e - 1)$

**Problem Statement.** (Discovering Exceptional Contextual Intra-group Agreement Patterns). Given a behavioral dataset $\mathcal{B} = (\mathcal{G}_I, \mathcal{G}_E, O, o)$, a minimum group support threshold $\sigma_I$, a minimum context support threshold $\sigma_E$, a significance critical value $\alpha \in [0,1]$, and the null hypothesis $H_0$ (the observed intra-agreement is generated by the DFD); find the pattern set $P \subseteq \mathcal{P}$ such that:

$P = \{(g,c) \in \mathcal{D}_I \times \mathcal{D}_E : |G_E^c| \geq \sigma_I \text{ and } |G_E^c| \geq \sigma_E \text{ and } p\mbox{-value}^g(c) \leq \alpha\}$

where $p\mbox{-value}^g(c)$ is the probability (under $H_0$) of obtaining an intra-agreement $A$ at least as extreme as $A^g(G_E^c)$, the one observed over the current context.
4 Exceptional Contexts: Evaluation and Pruning

From now on we omit the exponent \(g\) if no confusion can arise, while keeping in mind a selected group of individuals \(g \in D_I\) related to a subset \(G^g_I \subseteq G_I\).

To evaluate the extent to which our findings are exceptional, we follow the significant pattern mining paradigm\(^4\): we consider each context \(c\) as a hypothesis test which returns a \(p\)-value. The \(p\)-value is the probability of obtaining an intra-agreement at least as extreme as the one observed over the current context \(A(G^c_E)\), assuming the truth of the null hypothesis \(H_0\). The pattern is accepted if \(H_0\) is rejected. This happens if the \(p\)-value is under a critical significance value \(\alpha\) which amounts to test if the observed intra-agreement \(A(G^c_E)\) is outside the confidence interval \(CI^{1-\alpha}\) established using the distribution assumed under \(H_0\).

\(H_0\) corresponds to the baseline finding: the observed contextual intra-agreement is generated by the distribution of random subsets equally likely to occur, a.k.a. Distribution of False Discoveries (DFD, cf. [9]). We evaluate the \(p\)-value of the observed \(A\) against the distribution of random subsets of a cardinality equal to the size of the observed subgroup \(G^c_E\). The subsets are issued by uniform sampling without replacement (since the observed subgroup encompasses distinct entities only) from the entity collection. Moreover, drawing samples only from the collection of subsets of size equal to \(|G^c_E|\) allows to drive more judicious conclusions: the variability of the statistic \(A\) is impacted by the size of the considered subgroups, since smaller subgroups are more likely to observe low/high values of \(A\). The same reasoning was followed in [33].

We define \(\theta_k : F_k \rightarrow R\) as the random variable corresponding to the observed intra-agreement \(A\) of \(k\)-sized subsets \(S \in G_E\). I.e., for any \(k \in [1,n]\) with \(n = |G_E|\), we have \(\theta_k(S) = A(S)\) and \(F_k = \{S \in G_E \text{ s.t. } |S| = k\}\). \(F_k\) is then the set of possible subsets which are equally likely to occur under the null hypothesis \(H_0\). That is, \(\mathbb{P}(S \in F_k) = \left(\binom{n}{k}\right)^{-1}\). We denote by \(CI_k^{1-\alpha}\) the \((1 - \alpha)\) confidence interval related to the probability distribution of \(\theta_k\) under the null hypothesis \(H_0\). To easily manipulate \(\theta_k\), we reformulate \(A\) using Equations (1)-(3):

\[
A(S) = \frac{\sum_{e \in S} v_e}{\sum_{e \in S} w_e} \bigg| w_e = m_e \text{ and } v_e = m_e - \frac{1}{D_{\exp o_1,o_2 \in O^2}} \sum_{o_1,o_2 \in O^2} \delta_{o_1,o_2} m_e^{o_1} \cdot m_e^{o_2} (m_e - 1) \bigg)
\]

Under the null hypothesis \(H_0\) and the assumption that the underlying distribution of intra-agreements is a Normal distribution\(^5\) \(N(\mu_k, \sigma^2_k)\), one can define

\(^4\)This paradigm naturally raises the question of how to address the multiple comparisons problem [23]. This is a non-trivial task in our setting, and solving it requires an extension of the significant pattern mining paradigm as a whole: its scope is bigger than this paper. We provide a brief discussion in Appendix C.

\(^5\)In the same line of reasoning of [7], one can assume that the underlying distribution can be derived from what prior beliefs the end-user may have on such distribution. If only the observed expectation \(\mu\) and variance \(\sigma^2\) are given as constraints which must hold for the underlying distribution, the maximum entropy distribution (taking into account no other prior information than the given constraints) is known to be the Normal distribution \(N(\mu, \sigma^2)\) [5, p.413].
by computing $\mu_k = E[\theta_k]$ and $\sigma_k^2 = \text{Var}[\theta_k]$. Doing so requires either empirically calculating estimators of such moments by drawing a large number $r$ of uniformly generated samples from $F_k$, or analytically deriving the formula of $E[\theta_k]$ and $\text{Var}[\theta_k]$. In the former case, the confidence interval $CI_k^{1-\alpha}$ endpoints are given by [17, p.9]: $\mu_k \pm t_{1-\frac{\alpha}{2}, r-1} \sigma_k \sqrt{1 + (1/r)}$, with $\mu_k$ and $\sigma_k$ empirically estimated on the $r$ samples, and $t_{1-\frac{\alpha}{2}, r-1}$ the $(1 - \frac{\alpha}{2})$ percentile of Student's $t$-distribution with $r-1$ degrees of freedom. In the latter case, ($\mu_k$ and $\sigma_k$ are known/derived analytically), the $(1-\alpha)$ confidence interval can be computed in its most basic form, that is $CI_k^{1-\alpha} = [\mu_k - z(1-\frac{\alpha}{2})\sigma_k, \mu_k + z(1-\frac{\alpha}{2})\sigma_k]$ with $z(1-\frac{\alpha}{2})$ the $(1 - \frac{\alpha}{2})$ percentile of $\mathcal{N}(0,1)$.

However, due to the problem setting, empirically establishing the confidence interval is computationally expensive, since it must be calculated for each enumerated context. Even for relatively small behavioral datasets, this quickly becomes intractable. Alternatively, analytically deriving a computationally efficient form of $E[\theta_k]$ is notoriously difficult, given that $E[\theta_k] = (\frac{n}{k})^{-1} \sum_{S \subseteq F_k} \sum_{\theta \in S} \theta = E[\theta_k]$. Doing so requires either empirically calculating estimators of such moments by drawing a large number $r$, or analytically deriving a computationally efficient form of $E[\theta_k]$. For small datasets, this quickly becomes intractable. Alternatively, analytically deriving a computationally efficient form of $E[\theta_k]$ in its most basic form, that is $CI_k^{1-\alpha} = [\mu_k - z(1-\frac{\alpha}{2})\sigma_k, \mu_k + z(1-\frac{\alpha}{2})\sigma_k]$ with $z(1-\frac{\alpha}{2})$ the $(1 - \frac{\alpha}{2})$ percentile of $\mathcal{N}(0,1)$.

Proposition 1 (An Approximate Confidence Interval $\hat{CI}_k^{1-\alpha}$ for $\theta_k$).

Given $k \in [1, n]$ and $\alpha \in [0, 1]$ (significance critical value), $\hat{CI}_k^{1-\alpha}$ is given by:

$$\hat{CI}_k^{1-\alpha} = \left[\hat{E}[\theta_k] - z_{1-\frac{\alpha}{2}} \sqrt{\hat{\text{Var}}[\theta_k]}, \hat{E}[\theta_k] + z_{1-\frac{\alpha}{2}} \sqrt{\hat{\text{Var}}[\theta_k]}\right]$$

with $\hat{E}[\theta_k]$ a Taylor approximation for the expectation $E[\theta_k]$ expanded around $(\mu_v, \mu_w)$, and $\hat{\text{Var}}[\theta_k]$ a Taylor approximation for $\text{Var}[\theta_k]$ given by:

$$\hat{E}[\theta_k] = \left(\frac{n}{k} - 1\right) \frac{\mu_v}{\mu_w} \beta_v + \frac{\mu_v}{\mu_w} \beta_w$$

$$\text{Var}[\theta_k] = \left(\frac{n}{k} - 1\right) \frac{\mu_v^2}{\mu_w^2} (\beta_v + \beta_w)$$

with:

$$\mu_v = \frac{1}{n} \sum_{e \in G_E} v_e$$

$$\mu_w = \frac{1}{n} \sum_{e \in G_E} w_e$$

$$\mu_v^2 = \frac{1}{n} \sum_{e \in G_E} v_e^2$$

$$\mu_w^2 = \frac{1}{n} \sum_{e \in G_E} w_e^2$$

$$\mu_v w = \frac{1}{n} \sum_{e \in G_E} v_e w_e$$

$$\beta_v = \frac{1}{n - 1} \left(\frac{\mu_v^2}{\mu_v^2} - \frac{\mu_v w}{\mu_v \mu_w}\right)$$

$$\beta_w = \frac{1}{n - 1} \left(\frac{\mu_w^2}{\mu_w^2} - \frac{\mu_v w}{\mu_v \mu_w}\right)$$

For a proof of these equations, see Appendix A.

Note that the complexity of the computation of the approximate confidence interval $\hat{CI}_k^{1-\alpha}$ is $O(n)$, with $n$ the size of entities collection $G_E$. 


4.1 Pruning the Search Space

Optimistic Estimate on Krippendorff’s Alpha. To quickly prune unpromising areas of the search space, we define a tight optimistic estimate [18] on Krippendorff’s alpha. Eppstein and Hirschberg [14] propose a smart linear algorithm Random-SMWA⁶ to find subsets with maximum weighted average. Recall that \( A \) can be seen as a weighted average (cf. Equation (4)).

In a nutshell, Random-SMWA seeks to remove \( k \) values to find a subset of \( S \) having \(|S| - k\) values with maximum weighted average. The authors model the problem as such: given \(|S|\) values decreasing linearly with time, find the time at which the \(|S| - k\) maximum values add to zero. In the scope of this work, given a user-defined support threshold \( \sigma_E \) on the minimum allowed size of context extents, \( k \) is fixed to \(|S| - \sigma_E\). The obtained subset corresponds to the smallest allowed subset having support \( \geq \sigma_E \) maximizing the weighted average quantity \( A \). The Random-SMWA algorithm can be tweaked⁷ to retrieve the smallest subset of size \( \geq \sigma_E \) having analogously the minimum possible weighted average quantity \( A \). We refer to the algorithm returning the maximum (resp. minimum) possible weighted average by RandomSMWA^{max} (resp. RandomSMWA^{min}).

Proposition 2 (Upper and Lower Bounds for \( A \)). Given \( S \subseteq G_E \), minimum context support threshold \( \sigma_E \), and the following functions:

\[
UB(S) = A\left(\text{RandomSMWA}^{\text{max}}(S, \sigma_E)\right) \quad LB(S) = A\left(\text{RandomSMWA}^{\text{min}}(S, \sigma_E)\right)
\]

we know that \( LB \) (resp. \( UB \)) is a lower (resp. upper) bound for \( A \), i.e.:

\[
\forall c, d \in D_E : c \subseteq d \land |G_E^c| \geq |G_E^d| \geq \sigma_E \Rightarrow LB(G_E^c) \leq A(G_E^c) \leq UB(G_E^c)
\]

Using these results, we define the optimistic estimate for \( A \) as an interval bounded by the minimum and the maximum \( A \) measure that one can observe from the subsets of a given subset \( S \subseteq G_E \), that is: \( OE(S, \sigma_E) = [LB(S), UB(S)] \).

Nested Confidence Intervals for \( A \). The desired property between two confidence intervals of the same significance level \( \alpha \) related to respectively \( k_1, k_2 \) with \( k_1 \leq k_2 \) is that \( CI_{k_1}^{1-\alpha} \) encompasses \( CI_{k_2}^{1-\alpha} \). Colloquially speaking, larger samples lead to “narrower” confidence intervals. This property is intuitively plausible, since the dispersion of the observed intra-agreement for smaller samples is likely to be higher than the dispersion for larger samples. However, such a property allows to prune the search subspace related to a context \( c \) when traversing the search space downward if \( OE(G_E^c, \sigma_E) \subseteq CI_{|G_E|}^{1-\alpha} \).

Proving \( CI_{k_2}^{1-\alpha} \subseteq CI_{k_1}^{1-\alpha} \) for \( k_1 \leq k_2 \) for the exact confidence interval is nontrivial, since it requires to analytically derive \( E[\theta_k] \) and \( \text{Var}[\theta_k] \) for any \( 1 \leq k \leq n \). Note that the expected value \( E[\theta_k] \) varies when \( k \) varies. We study such a property for the approximate confidence interval \( \hat{CI}_{k}^{1-\alpha} \).

---

⁶Random-SMWA: Randomized algorithm - Subset with Maximum Weighted Average.
⁷Finding the subset having the minimum weighted average is a dual problem to finding the subset having the maximum weighted average. To solve the former problem using Random-SMWA, we modify the values of \( v_i \) to \(-v_i \) and keep the same weights \( w_i \).
Proposition 3 (Minimum Cardinality Constraint for Nested Approximate Confidence Intervals). Given a context support threshold $\sigma_E$ and $\alpha$.

\[
\text{If } \sigma_E \geq C^\alpha = \frac{4n \beta^2_w}{\frac{1}{2} - \frac{1}{2} (\beta_v + \beta_w) + 4 \beta^2_w},
\]

then $\forall k_1, k_2 \in \mathbb{N}: \sigma_E \leq k_1 \leq k_2 \Rightarrow \hat{CI}_{k_2}^{1-\alpha} \subseteq \hat{CI}_{k_1}^{1-\alpha}$

Combining Propositions 1, 2 and 3, we formalize the pruning region property which answers: when to prune the sub-search space under a context $c$?

Corollary 1 (Pruning Regions). Given a behavioral dataset $B$, a context support threshold $\sigma_E \geq C^\alpha$, and a significance critical value $\alpha \in [0, 1]$. For any $c, d \in D_E$ such that $c \sqsubseteq d$ with $|G_E^c| \geq |G_E^d| \geq \sigma_E$, we have:

\[
OE(G_E^c, \sigma_E) \subseteq \hat{CI}^{1-\alpha}_{|G_E^d|} \Rightarrow A(G_E^d) \in \hat{CI}^{1-\alpha}_{|G_E^d|} \Rightarrow p\text{-value}(d) > \alpha
\]

Proofs. All proofs of propositions and properties can be found in Appendix A.

5 On Handling Variability of Outcomes Among Raters

In Section 4, we defined the confidence interval $CI^{1-\alpha}$ established over the DFD. By taking into consideration the variability induced by the selection of a subset of entities, such a confidence interval enables to avoid reporting subgroups indicating an intra-agreement likely (w.r.t. the critical value $\alpha$) to be observed by a random subset of entities. For more statistically sound results, one should not only take into account the variability induced by the selection of subsets of entities, but also the variability induced by the outcomes of the selected group of individuals. This is well summarized by Hayes and Krippendorff [22]: “The obtained value of $A$ is subject to random sampling variability—specifically variability attributable to the selection of units (i.e., entities) in the reliability data (i.e., behavioral data) and the variability of their judgments”. To address these two questions, they recommend to employ a standard Efron & Tibshirani bootstrapping approach [13] to empirically generate the sampling distribution of $A$ and produce an empirical confidence interval $CI^{1-\alpha}_{\text{bootstrap}}$.

Recall that we consider here a behavioral dataset $B$ reduced to the outcomes of a selected group of individuals $g$. Following the bootstrapping scheme proposed by Krippendorff [22,28], the empirical confidence interval is computed by repeatedly performing the following steps: (1) resample $n$ entities from $G_E$ with replacement; (2) for each sampled entity, draw uniformly $m_e \cdot (m_e - 1)$ pairs of outcomes according to the distribution of the observed pairs of outcomes; (3) compute the observed disagreement and calculate Krippendorff’s alpha on the resulting resample. This process, repeated $b$ times, leads to a vector of bootstrap estimates (sorted in ascending order) $\hat{B} = [\hat{A}_1, \ldots, \hat{A}_b]$. Given the empirical distribution $\hat{B}$, the empirical confidence interval $CI^{1-\alpha}_{\text{bootstrap}}$ is defined by the percentiles of $\hat{B}$, i.e., $CI^{1-\alpha}_{\text{bootstrap}} = [\hat{A}_{\frac{1}{2} - \frac{1}{2} \cdot (1 - \alpha) \cdot b}], [\hat{A}_{\frac{1}{2} \cdot (1 - \alpha) \cdot b}]$. We denote by $MCI^{1-\alpha}$ (Merged CI) the confidence interval that takes into consideration both $CT^{1-\alpha} = [le_1, re_1]$ and $CI^{1-\alpha}_{\text{bootstrap}} = [le_2, re_2]$. We have $MCI^{1-\alpha} = [\min(le_1, le_2), \max(re_1, re_2)]$. 
6 A Branch-and-bound Solution: Algorithm DEvIANT

To detect exceptional contextual intra-group agreement patterns, we need to enumerate candidates \( p = (g, c) \in (D_I, D_E) \). Both heuristic (e.g., beam search [31]) and exhaustive (e.g., GP-growth [32]) enumeration algorithms exist. We exhaustively enumerate all candidate subgroups while leveraging closure operators [15] (since \( A \) computation only depends on the extent of a pattern). This makes it possible to avoid redundancy and to substantially reduce the number of visited patterns. With this aim in mind, and since the data we deal with are of the same format as those handled in the previous work [3], we apply EnumCC to enumerate subgroups \( g \) (resp. \( c \)) in \( D_I \) (resp. \( D_E \)). EnumCC follows the line of algorithm CloseByOne [29]. Given a collection \( G \) of records (\( G_E \) or \( G_I \)), EnumCC traverses the search space depth-first and enumerates only once all closed descriptions fulfilling the minimum support constraint \( \sigma \). EnumCC follows a yield and wait paradigm (similar to Python’s generators) which at each call yield the following candidate and wait for the next call. See Appendix B for details.

DEvIANT implements an efficient branch-and-bound algorithm to Discover statistically significant Exceptional Intra-group Agreement patterns while leveraging closure, tight optimistic estimates and pruning properties. DEvIANT starts by selecting a group \( g \) of individuals. Next, the corresponding behavioral dataset \( B^g \) is established by reducing the original dataset \( B \) to elements concerning solely the individuals comprising \( G^g \) and entities having at least two outcomes. Subsequently, the bootstrap confidence interval \( CI_{\text{bootstrap}}^{1-\alpha} \) is calculated.

---

**Algorithm 1: DEvIANT(\( B, \sigma_E, \sigma_I, \alpha \))**

**Inputs**: Behavioral dataset \( B = (G_I, G_E, O, o) \), minimum support threshold \( \sigma_E \) of a context and \( \sigma_I \) of a group, and critical significance value \( \alpha \).

**Output**: Set of exceptional intra-group agreement patterns \( P \).

```
1 P ← {}
2 foreach (\( g, G^g_I, \text{cont}_g \)) ∈ EnumCC(\( G_I, *, \sigma_I, 0, \text{True} \)) do
3     \( G_E^g = \{ e ∈ E \text{ s.t. } m_e(g) ≥ 2 \} \) \( \triangleright \) \( m_e(g) \) : number of individuals of group \( g \)
4     \( B^g = (G_E^g, G^g_I, O, o) \) who expressed an outcome on \( e \)
5     \( CI_{\text{bootstrap}}^{1-\alpha} = [\hat{A}_{\frac{1}{2}}_b, \hat{A}_{\frac{1}{2}}_1(1-\frac{1}{2})_b] \) \( \triangleright \) With \( B = [\hat{A}^1_1, ..., \hat{A}^n_1] \) computed on respectively \( b \) resamples of \( B^g \)
6     \( \sigma^g_E = \text{max} (C^n(a, \sigma_E)) \) respectively \( \sigma^g_E \)
7     foreach (\( e, G^g_E, \text{cont}_e \)) ∈ EnumCC(\( G_E^g(e), *, \sigma^g_E, 0, \text{True} \)) do
8         \( \text{MCI}^{1-\alpha}_{|G^g_E|} = \text{merge} (\hat{G}^{1-\alpha}_{|G^g_E|}, CI_{\text{bootstrap}}^{1-\alpha}) \)
9         if OE(\( G^g_E, \sigma^g_E \)) ≤ MCI^{1-\alpha}_{|G^g_E|} then
10            \( \triangleright \) \( \text{cont}_e \) ← False \( \triangleright \) Prune the unpromising search subspace under \( c \)
11        else if \( A^o(G^g_E) \notin \text{MCI}^{1-\alpha}_{|G^g_E|} \) then
12            \( p_{\text{new}} ← (g, c) \)
13            if \( \hat{\text{ext}}_{\text{old}}(p_{\text{new}}) \subseteq \text{ext}(p_{\text{old}}) \) then
14                \( P ← (P \cup p_{\text{new}}) \setminus \{ p_{\text{old}} ∈ P \mid \text{ext}(p_{\text{old}}) \subseteq \text{ext}(p_{\text{new}}) \} \)
15                \( \text{cont}_e \) ← False \( \triangleright \) Prune the sub search space (generality concept)
16 return \( P \)
```
Table 3: Main characteristics of the behavioral datasets. $C^{0.05}$ represents the minimum context support threshold over which we have nested approximate CI property.

| Dataset | $|G_E|$ | $A_E$ (Items-Scaling) | $|G_I|$ | $A_I$ (Items-Scaling) | Outcomes | Sparsity $C^{0.05}$ |
|---------|--------|------------------------|--------|------------------------|----------|---------------------|
| EPDS$^8$ | 4704 | 1H + 1N + 1C (447) | 848 | 3C (82) | 3.1M (C) | 78.6% | $\simeq 10^{-6}$ |
| CHUS$^9$ | 17350 | 1H + 2N (307) | 1373 | 2C (261) | 3M (C) | 31.2% | $\simeq 10^{-4}$ |
| Movielens$^{10}$ | 1681 | 1H + 1N (161) | 943 | 3C (27) | 100K (O) | 66.3% | $\simeq 0.065$ |
| Yelp$^{11}$ | 127K | 1H + 1C (581) | 1M | 3C (6) | 4.15M (O) | 0.003% | $\simeq 1.14$ |

Before searching for exceptional contexts, the minimum context support threshold $\sigma_E$ is adjusted to $C^\alpha(g)$ (cf. Proposition 3) if it is lower than $C^\alpha(g)$. While in practice $C^\alpha(g) \ll \sigma_E$, we keep this correction for algorithm soundness.

Next, contexts are enumerated by EnumCC. For each candidate context $c$, the optimistic estimate interval $OE(G_E^c)$ is computed (cf. Proposition 2). According to Corollary 1, if $OE(G_E^c, \sigma_E^p) \subseteq MC_{Ic}^{1-\alpha}$, the search subspace under $c$ can be pruned. Otherwise, $A^p(G_E^c)$ is computed and evaluated against $MC_{Ic}^{1-\alpha}$. If $A^p(G_E^c) \notin MC_{Ic}^{1-\alpha}$, then $(g, c)$ is significant and kept in the result set $P$. To reduce the number of reported patterns, we keep only the most general patterns while ensuring that each significant pattern in $P$ is represented by a pattern in $P$. This formally translates to: $\forall p' = (g', c') \in P \setminus P : p-value^g(c') \leq \alpha \Rightarrow \exists p = (g, c) \in P$ s.t. $ext(q) \subseteq ext(p)$, with $ext(q = (g', c')) \subseteq ext(p = (g, c))$ defined by $G_I^q \subseteq G_I^p$ and $G_E^q \subseteq G_E^p$. This is based on the following postulate: the end-user is more interested by exceptional (dis-)agreement within larger groups and/or for larger contexts rather than local exceptional (dis-)agreement. Moreover, the end-user can always refine their analysis to obtain more fine-grained results by re-launching the algorithm starting from a specific context or group.

7 Empirical Evaluation

Our experiments aim to answer the following questions: (Q1) How well does the Taylor-approximated CI approach the empirical CI? (Q2) How efficient is the Taylor-approximated CI and the pruning properties? (Q3) Does DEvIANT provide interpretable patterns? Source code and data are available on our companion page: https://github.com/Adnene93/Deviant.

Datasets. Experiments were carried on four real-world behavioral datasets (cf. Table 3): two voting (EPDS and CHUS) and two rating datasets (Movielens and Yelp). Each dataset features entities and individuals described by attributes that are either categorical (C), numerical (N), or categorical augmented with a taxonomy (H). We also report the equivalent number of items (in an itemset language) corresponding to the descriptive attributes (ordinal scaling [16]).

$^8$Eighth European Parliament Voting Dataset (04/10/18).
$^{10}$Movie review dataset - https://grouplens.org/datasets/movielens/100k/.
Table 4: Coverage error between empirical CIs and Taylor CIs.

<table>
<thead>
<tr>
<th>B</th>
<th>µerr</th>
<th>σerr</th>
<th>B</th>
<th>µerr</th>
<th>σerr</th>
<th>B</th>
<th>µerr</th>
<th>σerr</th>
<th>B</th>
<th>µerr</th>
<th>σerr</th>
</tr>
</thead>
<tbody>
<tr>
<td>CHUS</td>
<td>0.007</td>
<td>0.004</td>
<td>EPD8</td>
<td>0.007</td>
<td>0.004</td>
<td>Movielens</td>
<td>0.0075</td>
<td>0.0045</td>
<td>Yelp</td>
<td>0.007</td>
<td>0.004</td>
</tr>
</tbody>
</table>

Fig. 2: Comparison between DEvIANT and Naive when varying the size of the description space $D_I$. Lines correspond to the execution time and bars correspond to the number of output patterns. Parameters: $\sigma_E = \sigma_I = 1\%$ and $\alpha = 0.05$.

Q1. First, we evaluate to what extent the empirically computed confidence interval approximates the confidence interval computed by Taylor approximations. We run 1000 experiments for subset sizes $k$ uniformly randomly distributed in $[1, n = |G_E|]$. For each $k$, we compute the corresponding Taylor approximation $\hat{C}_k^{1-\alpha} = [a^T, b^T]$ and empirical confidence interval $E\hat{C}_k^{1-\alpha} = [a^E, b^E]$. The latter is calculated over $10^4$ samples of size $k$ from $G_E$, on which we compute the observed $A$ which are then used to estimate the moments of the empirical distribution required for establishing $E\hat{C}_k^{1-\alpha}$. Once both CIs are computed, we measure their distance by Jaccard index. Table 4 reports the average $\mu_{err}$ and the standard deviation $\sigma_{err}$ of the observed distances (coverage error) over the 1000 experiments. Note that the difference between the analytic Taylor approximation and the empirical approximation is negligible ($\mu_{err} < 10^{-2}$). Therefore, the CIs approximated by the two methods are so close that it does not matter which method is used. Hence, the choice is guided by the computational efficiency.

Q2. To evaluate the pruning properties’ efficiency ((i) Taylor-approximated CI, (ii) optimistic estimates and (iii) nested approximated CIs), we compare DEvIANT with a Naive approach where the three aforementioned properties are disabled. For a fair comparison, Naive pushes monotonic constraints (minimum support threshold) and employs closure operators while empirically estimating the CI by successive random trials from $F_k$. In both algorithms we disable the bootstrap $C_k^{1-\alpha}$ computation, since its overhead is equal for both algorithms. We vary the description space size related to groups of individuals $D_I$ while considering the full entity description space. Figure 2 displays the results: DEvIANT outperforms Naive in terms of runtime by nearly two orders of magnitude while outputting the same number of the desired patterns.

Figure 3 reports the performance of DEvIANT in terms of runtime and number of output patterns. When varying the description space size, DEvIANT requires more time to finish. Note that the size of individuals search space $D_I$ substantially affects the runtime of DEvIANT. This is mainly because larger
**Fig. 3:** Effectiveness of DEvIANT on EPD8 when varying sizes of both search spaces $\mathcal{D}_E$ and $\mathcal{D}_I$, minimum context support threshold $\sigma_E$ and the critical value $\alpha$. Default parameters: full search spaces $\mathcal{D}_E$ and $\mathcal{D}_I$, $\sigma_E = 0.1\%$, $\sigma_I = 1\%$ and $\alpha = 0.05$.

**Table 5:** All the exceptional consensual/conflictual subjects among Republican Party representatives (selected upfront, i.e. $G_I$ restricted over members of Republican party) in the 115\textsuperscript{th} congress of the US House of Representatives. $\alpha = 0.01$.

<table>
<thead>
<tr>
<th>id</th>
<th>group ($g$)</th>
<th>context ($c$)</th>
<th>$A^p(c)$</th>
<th>$A^q(c)$</th>
<th>p-value</th>
<th>IA</th>
</tr>
</thead>
<tbody>
<tr>
<td>$p_1$</td>
<td>Republicans 20.11</td>
<td>Government and Administration issues</td>
<td>0.83</td>
<td>0.32</td>
<td>&lt;.001</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_2$</td>
<td>Republicans 5</td>
<td>Labor</td>
<td>0.83</td>
<td>0.63</td>
<td>&lt;.01</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_3$</td>
<td>Republicans 20.05</td>
<td>Nominations and Appointments</td>
<td>0.83</td>
<td>0.92</td>
<td>&lt;.001</td>
<td>Consensus</td>
</tr>
</tbody>
</table>

$\mathcal{D}_I$ leads to more candidate groups of individuals $g$ which require DEvIANT to: (i) generate $\mathcal{C}_I^{1-\alpha}$ bootstrap and (ii) mine for exceptional contexts $c$ concerning the candidate group $g$. Finally, when $\alpha$ decreases, the execution time required for DEvIANT to finish increases while returning more patterns. This may seem counter-intuitive, since fewer patterns are significant when $\alpha$ decreases. It is a consequence of DEvIANT considering only the most general patterns. Hence, when $\alpha$ decreases, DEvIANT goes deeper in the context search space: much more candidate patterns are tested, enlarging the result set. The same conclusions are found on the Yelp, Movielens, and CHUS datasets (cf. Appendix D).

**Q3.** Table 5 reports exceptional contexts observed among House Republicans during the 115\textsuperscript{th} Congress. Pattern $p_1$, illustrated in Figure 4, highlights a collection of voting sessions addressing Government and Administrative issues where a clear polarization is observed between two clusters of Republicans. A roll call vote in this context featuring significant disagreement between Republicans is “House Vote 417” (cf. https://projects.propublica.org/represent/votes/115/house/1/417) which was closely watched by the media (Washington Post: https://wapo.st/2W32I9c; Reuters: https://reut.rs/2TF0dgV).

Table 6 depicts patterns returned by DEvIANT on the Movielens dataset. Pattern $p_2$ reports that “Middle-aged Men” observe an intra-group agreement significantly higher than overall, for movies labeled with both adventure and musical genres (e.g., The Wizard of Oz (1939)).

**8 Conclusion and Future Directions**

We introduce the task to discover statistically significant exceptional contextual intra-group agreement patterns. To efficiently search for such patterns, we devise DEvIANT, a branch-and-bound algorithm leveraging closure operators,
**Fig. 4:** Similarity matrix between Republicans, illustrating Pattern $p_1$ from Table 5. Each cell represents the ratio of voting sessions in which Republicans agreed. Green cells report strong agreement; red cells highlight strong disagreement.

**Table 6:** Top-3 exceptionally consensual/conflictual genres between Movielens raters, $\alpha=0.01$. Patterns are ranked by absolute difference between $A^p(c)$ and $A^p(\ast)$.

<table>
<thead>
<tr>
<th>id</th>
<th>group $(g)$</th>
<th>context $(c)$</th>
<th>$A^p(\ast)$</th>
<th>$A^p(c)$</th>
<th>$p$-value</th>
<th>IA</th>
</tr>
</thead>
<tbody>
<tr>
<td>$p_1$</td>
<td>Old</td>
<td>1.Action &amp; 2.Adventure &amp; 6.Crime Movies</td>
<td>-0.06</td>
<td>-0.29</td>
<td>&lt; 0.01</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_2$</td>
<td>Middle-aged Men</td>
<td>2.Adventure &amp; 12.Musical Movies</td>
<td>0.05</td>
<td>0.21</td>
<td>&lt; 0.01</td>
<td>Consensus</td>
</tr>
<tr>
<td>$p_3$</td>
<td>Old</td>
<td>4.Children &amp; 12.Musical Movies</td>
<td>-0.06</td>
<td>-0.21</td>
<td>&lt; 0.01</td>
<td>Conflict</td>
</tr>
</tbody>
</table>

approximate confidence intervals, tight optimistic estimates on Krippendorff’s Alpha measure, and the property of nested CIs. Experiments demonstrate DEvIANT’s performance on behavioral datasets in domains ranging from political analysis to rating data analysis. In future work, we plan to (i) investigate how to tackle the multiple comparison problem [21], (ii) investigate intra-group agreement which is exceptional w.r.t. all individuals over the same context, and (iii) integrate the option to choose which kind of exceptional consensus the end-user wants: is the exceptional consensus caused by common preference or hatred for the context-related entities? All this is to be done within a comprehensive framework and tool (prototype available at [http://contentcheck.liris.cnrs.fr](http://contentcheck.liris.cnrs.fr)) for behavioral data analysis alongside exceptional inter-group agreement pattern discovery implemented in [3].

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A Appendix: Proofs

Recall that $\theta_k : F_k \to \mathbb{R}$ is the random variable corresponding to the observed intra-agreement $A$ (Krippendorff’s alpha) of subsets $S \in G_E$ of size $k$. I.e., for any $k \in [1,n]$ with $n = |G_E|$ we have $\theta_k(S \in F_k) = A(S)$ and $F_k = \{S \in G_E \text{ s.t. } |S| = k\}$. Then, $F_k$ is the set of possible outcomes which are equally likely to occur under the null hypothesis $H_0$. We let $n$ denote the number of records in $G_E$ (i.e., $|G_E| = n$). Each record $e \in G_E$ is associated with a value $v_e$ and $w_e$. The quantity $\theta_k$ can be expressed as a ratio $\frac{V_k}{W_k}$, where $V_k, W_k$ are two random variables $V_k : F_k \to \mathbb{R}$ and $W_k : F_k \to \mathbb{R}$ with $V_k(S) = \frac{1}{k} \sum_{e \in S} v_e$ and $W_k(S) = \frac{1}{k} \sum_{e \in S} w_e$.

Proof (Proposition 1). For any $f(x,y)$, the bivariate second order Taylor expansion about any $\lambda = (\lambda_x; \lambda_y)$ is:

$$ f(x,y) = f(\lambda) + f'_x(\lambda)(x - \lambda_x) + f'_y(\lambda)(y - \lambda_y) $$

$$ + \frac{1}{2} \left( f''_x(\lambda)(x - \lambda_x)^2 + 2f''_{xy}(\lambda)(x - \lambda_x)(y - \lambda_y) + f''_y(\lambda)(y - \lambda_y)^2 \right) + \epsilon $$

(7)

where $\epsilon$ is a remainder of smaller order than the term of the equation.

An approximation of the expectation $E[f(x,y)]$ expanded around $\lambda = (\lambda_x; \lambda_y)$ is:

$$ E[f(x,y)] \approx f(\lambda) + \frac{1}{2} \left[ f''_x(\lambda)\text{Var}[X] + 2f''_{xy}(\lambda)\text{Cov}[X,Y] + f''_y(\lambda)\text{Var}[Y] \right] $$

Given that $f(x,y) = \frac{v}{w}$ and using the fact that $E[X - \mu_x] = 0$ (which is valid for both $V$ and $W$), we have: $\text{Var}[X] = E[(X - \mu_x)^2]$ and $\text{Cov}[X,Y] = (X - \mu_x)(Y - \mu_y)$. We can derive an approximation of $E[\theta_k] = E[\frac{V_k}{W_k}]$ around $(\mu_{V_k}, \mu_{W_k})$:

$$ E[\theta_k] = E[\frac{V_k}{W_k}] = E[f(V_k, W_k)] \approx \frac{\mu_{V_k}}{\mu_{W_k}} - \frac{\text{Cov}[V_k, W_k]}{\mu_{W_k}^2} + \frac{\text{Var}[W_k] \mu_{V_k}}{\mu_{W_k}^3} $$

(8)

The formulas of $E[V_k]$ (resp. $E[W_k]$) and $\text{Var}[V_k]$ (resp. $V[W_k]$) can be derived analytically. We denote by $\mu_v$ (resp. $\mu_w$) the arithmetic mean of the values (resp. weights) corresponding to each entity $e \in G_E$, i.e., $\mu_v = \frac{1}{n} \sum_{e \in G_E} v_e$ and $\mu_w = \frac{1}{n} \sum_{e \in G_E} w_e$ with $n = |G_E|$.

$$ E[V_k] = \frac{1}{(n)} \sum_{S \in F_k} \frac{1}{k} \sum_{e \in S} v_e = \frac{1}{n} \sum_{e \in G_E} v_e = \mu_v $$

(9)

$$ \text{Var}[V_k] = \frac{1}{(n)} \sum_{S \in F_k} \left( \frac{1}{k} \sum_{e \in S} v_e - E[V_k] \right)^2 = \frac{1}{(n)} \sum_{S \in F_k} \left( \frac{1}{k} \sum_{e \in S} v_e - \mu_v \right)^2 $$

$$ = \frac{1}{k} \left( \frac{n}{n - 1} (\mu_{v^2} - \mu_v^2) \right) - \frac{1}{n - 1} (\mu_{v^2} - \mu_v^2) \text{ with } \mu_{v^2} = \frac{1}{n} \sum_{e \in G_E} v_e^2 $$

(10)

\footnote{A concise lecture note follows the same reasoning and explains the derivations; see http://www.stat.cmu.edu/~hseltman/files/ratio.pdf}
The same reasoning applies to compute the expected value and the variance related to $W_k$:

$$E[W_k] = \frac{1}{n} \sum_{e \in G_E} w_e = \mu_w \quad (11)$$

$$\text{Var}[W_k] = \frac{1}{\binom{n}{k}} \sum_{S \in F_k} \left( \frac{1}{k} \sum_{e \in S} w_e - E[W_k] \right)^2$$

$$= \frac{1}{k} \left( \frac{n}{n-1} (\mu_{w^2} - \mu_w^2) \right) - \frac{1}{n-1} (\mu_{w^2} - \mu_w^2) \quad \text{with } \mu_{w^2} = \frac{1}{n} \sum_{e \in G_E} w_e^2 \quad (12)$$

We now derive the formula for $\text{Cov}(V_k, W_k)$. The same line of reasoning for the computation of the variance of $V_k$ and $W_k$ applies. We obtain:

$$\text{Cov}[V_k, W_k] = \frac{1}{\binom{n}{k}} \sum_{S \in F_k} \left( \frac{1}{k} \sum_{e \in S} v_e - E[V_k] \right) \left( \frac{1}{k} \sum_{e \in S} w_e - E[W_k] \right)$$

$$= \frac{1}{k} \left( \frac{n}{n-1} (\mu_{vw} - \mu_v \mu_w) \right) - \frac{1}{n-1} (\mu_{vw} - \mu_v \mu_w) \quad (13)$$

with $\mu_{vw} = \frac{1}{n} \sum_{e \in G_E} w_e v_e$

Using Equations (9), (10), (11), (12), (13), we derive the approximation of $E[\theta_k]$ after simplifications of (8):

$$E[\theta_k] \approx \hat{E}[\theta_k] = \left( \frac{n}{k} - 1 \right) \frac{\mu_v}{\mu_w} \beta_v + \frac{\mu_v}{\mu_w} \beta_w \quad \text{with } \beta_v = \frac{1}{n-1} \left( \frac{\mu_{w^2}}{\mu_w^2} - \frac{\mu_{vw}}{\mu_v \mu_w} \right) \quad (14)$$

The same reasoning applies to approximate $\text{Var}[\theta_k]$ using Taylor expansions. We will confine ourselves to a first-order Taylor expansion around $(\mu_v, \mu_w)$ to make the analytic derivation of the approximation of $\text{Var}[\theta_k]$ feasible. The same observation has been made by [25,12] and [26, p. 351] to approximate the variance for a ratio random variable. We obtain:

$$\text{Var}[\theta_k] = \text{Var}[f(V_k, W_k)] \approx \frac{\text{Var}[V_k]}{\mu_{W_k}^4} - 2 \frac{\mu_{W_k} \text{Cov}[V_k, W_k]}{\mu_{W_k}^4} + \frac{\mu_{W_k}^2 \text{Var}[W_k]}{\mu_{W_k}^4} \quad (15)$$

After simplifications and by using the same line of reasoning when deriving the expected value approximation reported in Equation (14), we obtain:

$$\text{Var}[\theta_k] \approx \hat{\text{Var}}[\theta_k] = \left( \frac{n}{k} - 1 \right) \frac{\mu_v^2}{\mu_w^2} \beta_v + \beta_w$$

with $\beta_v = \frac{1}{n-1} \left( \frac{\mu_{w^2}}{\mu_w^2} - \frac{\mu_{vw}}{\mu_v \mu_w} \right)$ and $\beta_v = \frac{1}{n-1} \left( \frac{\mu_{w^2}}{\mu_w^2} - \frac{\mu_{vw}}{\mu_v \mu_w} \right) \quad (16)$
We denote by $\tilde{CI}_k^{-\alpha}$ the approximate confidence interval calculated using the approximations from Equations (14) and (16) of the expected value $\tilde{E}[\theta_k]$ and the variance $\tilde{\text{Var}}[\theta_k]$, respectively. This results in:

$$\tilde{CI}_k^{-\alpha} = \left[ \tilde{E}[\theta_k] - z_{1-\frac{\alpha}{2}} \sqrt{\tilde{\text{Var}}[\theta_k]}, \tilde{E}[\theta_k] + z_{1-\frac{\alpha}{2}} \sqrt{\tilde{\text{Var}}[\theta_k]} \right]$$

It is worth mentioning that the complexity of the computation of this approximate confidence interval is linear to the size $n$. □

Proof (Proposition 2). To simplify the text, we will omit $\sigma_E$ as a parameter in the proof and keep in mind that we consider the minimum support threshold $\sigma_E$. Given that $c \subseteq d$, with $c,d$ two descriptions from $D$, we have $G^d \subseteq G^c$. The proposition stems from the fact that:

1. $A(G^c) \leq UB(G^d)$, since RandomSMWA$_{\text{max}}$ computes the subset $S^c_{\text{max}}$ having the maximum weighted average $A$ as proven by Epstein and Hirschberg [14].
2. $UB$ is monotonic w.r.t. the partial order $\subseteq$ between sets. That is:

$$\forall S, S' \subseteq G_E : S' \subseteq S \Rightarrow UB(S') \leq UB(S)$$

This can be proven by reductio ad absurdum. We denote by $S'_{\text{max}} \subseteq S'$ (resp. $S_{\text{max}} \subseteq S$) the optimal subset of $S'$ (resp. $S$) having its size $\geq \sigma_E$ and the maximum possible weighted average $A$. Suppose that $\exists S, S' \subseteq G_E : S' \subseteq S \land UB(S') > UB(S) (A(S'_{\text{max}}) > A(S_{\text{max}}))$. Since $S' \subseteq S$, this means that there is another subset in $S$, namely $S'_{\text{max}}$, that observes a greater weighted average $A$ than the actual optimal subset $S_{\text{max}}$, which is absurd.

From properties 1. and 2. we have: $A(G^d_E) \leq UB(G^d_E) \leq UB(G^c_E)$. The same reasoning holds to prove that $LB$ is a lower bound. □

Proof (Proposition 3). In order to prove the desired property for the approximate confidence intervals, we first must determine if the variance decreases when $k$ increases.

$$k_1, k_2 \in \mathbb{N} : \text{if } k_1 \leq k_2 \Rightarrow \tilde{\text{Var}}[\theta_{k_1}] \geq \tilde{\text{Var}}[\theta_{k_2}] \quad (17)$$

From Equation (16), $\tilde{\text{Var}}[\theta_k] = \left( \frac{n}{k} - 1 \right) \frac{n^2}{k^2} (\beta_v + \beta_w)$. Given that $\frac{n}{k} - 1$ is a decreasing function w.r.t. $k$, proving Equation (17) requires that $\beta_v + \beta_w$ is a positive quantity. This stems from the fact that the original formula of the approximate variance given in Equation (15) is positive. This can be proved by a direct application of the Covariance inequality [36, p. 149], which itself is an application of the Cauchy-Schwarz inequality [38]. Since $\beta_v + \beta_w$ is of the same sign of Equation (16), we have $\beta_v + \beta_w \geq 0$. For the sake of a self-contained proof. We give the proof of this assertion below:

From Equations (15) and (16), we have: $\beta_v + \beta_w$ is of the same sign of:

$$\frac{\text{Var}[V_k]}{\mu^2_{V_k}} - 2 \frac{\text{Cov}[V_k, W_k]}{\mu_{V_k} \mu_{W_k}} + \frac{\text{Var}[W_k]}{\mu^2_{W_k}} \quad (18)$$
From the Covariance inequality, we have \( \text{Cov}[V_k, W_k] \leq \sigma[V_k] \sigma[W_k] \) with \( \sigma^2[V_k] = \text{Var}[V_k] \) and \( \sigma^2[W_k] = \text{Var}[W_k] \), hence Equation (18) is greater than:

\[
\frac{\sigma^2[V_k]}{\mu^2_{V_k}} - 2 \frac{\sigma[V_k] \sigma[W_k]}{\mu_{V_k} \mu_{W_k}} + \frac{\sigma^2[W_k]}{\mu^2_{W_k}} = \frac{\sigma[V_k]}{\mu_{V_k}} \left( \frac{\sigma[V_k]}{\mu_{V_k}} - \frac{\sigma[W_k]}{\mu_{W_k}} \right) - \frac{\sigma[W_k]}{\mu_{W_k}} \left( \frac{\sigma[V_k]}{\mu_{V_k}} - \frac{\sigma[W_k]}{\mu_{W_k}} \right) = \left( \frac{\sigma[V_k]}{\mu_{V_k}} - \frac{\sigma[W_k]}{\mu_{W_k}} \right)^2 \geq 0
\]

Hence \( \beta_v + \beta_w \geq 0 \), which confirms that the variance is decreasing under increasing size \( k \), as stated in Equation (17).

Recall that, by approximation, we want to ensure that for \( \sigma_E \leq k_1 \leq k_2 \) with \( \sigma_E \) a threshold on the context support, we have \( \hat{C}I_{1, k_2} \subseteq \hat{C}I_{1, k_1} \). Hence, we need to find the minimum \( \sigma_E \) above which such property is valid. This amounts to finding a lower bound for \( \sigma_E \) such that:

\[
z_{1-\frac{\alpha}{2}} \sqrt{\text{Var}[\theta_{k_1}]} - z_{1-\frac{\alpha}{2}} \sqrt{\text{Var}[\theta_{k_2}]} \geq \left| \hat{E}[\theta_{k_1}] - \hat{E}[\theta_{k_2}] \right| \tag{19}
\]

Using the definitions of \( \text{Var}[\theta_k] \) and \( \hat{E}[\theta_k] \) from Equations (14) and (16), the Equation (19) can be rewritten to:

\[
\left( \sqrt{\frac{n}{k_1}} - 1 + \sqrt{\frac{n}{k_2}} - 1 \right) \leq z_{1-\frac{\alpha}{2}} \sqrt{\frac{\beta_v + \beta_w}{\beta^2_w}}
\]

Since \( \sigma_E \leq k_1 \leq k_2 \), we require that:

\[
2 \sqrt{\frac{n}{\sigma_E}} - 1 \leq z_{1-\frac{\alpha}{2}} \sqrt{\frac{\beta_v + \beta_w}{\beta^2_w}}
\]

After simplifications, we obtain that \( \sigma_E \) must satisfy the following constraint:

\[
\sigma_E \geq C^0 = \sqrt[2]{\frac{4n \beta^2_w}{z_{1-\frac{\alpha}{2}} (\beta_v + \beta_w) + 4 \beta^2_w}}
\]

**Proof (Corollary 1).** The proof is straightforward. From Proposition 2, we have that for any \( c, d \in D_E \text{ s.t. } c \subseteq d \), if \( G^c \geq G^d \geq \sigma_E \) then:

\[
A \left( G^d_E \right) \in \text{OE} \left( G^c_E, \sigma_E \right) \tag{20}
\]

From Proposition 3, if \( \sigma_E \geq C^0 \) we have:

\[
\hat{C}I^{1-\alpha}_{[G^c_E]} \subseteq \hat{C}I^{1-\alpha}_{[G^d_E]} \tag{21}
\]

From Equations (20) and (21) and the fact that \( \text{OE}(G^c_E, \sigma_E) \subseteq \hat{C}I^{1-\alpha}_{[G^c_E]} \), it follows that \( A \left( G^d_E \right) \in \text{OE} \left( G^c_E, \sigma_E \right) \subseteq \hat{C}I^{1-\alpha}_{[G^c_E]} \subseteq \hat{C}I^{1-\alpha}_{[G^d_E]} \), hence \( p\text{-value}(d) > \alpha. \)
Appendix: Enumeration Algorithm

Given a collection of records $G$ whose descriptive attributes are $A = \{a_1, \ldots, a_l\}$ which can be Boolean, numerical, or categorical, potentially organized among a taxonomy. Attributes $A$ allow to structure the search space $D$ by considering descriptions $d \in D$, which are conjunctions of conditions over the attributes’ domains of interpretation. A condition over a categorical attribute is an equality test while a condition over a numerical attributes is a membership test in an interval. By $G^d$ we denote the set of records of $G$ covered by the description $d$.

The EnumCC algorithm enumerates once and only once all closed descriptions whose associated subgroups fulfill the minimum support constraint $\sigma$. The algorithm follows the same reasoning of most common SD algorithms and goes in the same line of the CloseByOne Algorithm (CbO) [30] and the Divide-And-Conquer Algorithm [4]. It traverses the search lattice $D$ in a top-down, DFS fashion starting from the most general description $*$ whose support is the entire collection $G$. It proceeds by atomic refinements to progress, step by step, toward more specific descriptions. This is enabled by a refinement operator denoted $\eta_j$ for the $j$th attribute. $\eta_j$ keeps all conditions related to attributes $a_i$ for $i \neq j$ intact, and refines only the $j$th condition. If the condition is related to a numerical attribute, a minimal change to the left or right is performed [24]. If the condition is related to a categorical attribute, return an equality test for all possible values of the domain (if the condition was never refined before), otherwise no refinement is possible. If the attribute is an HMT (categorical attribute augmented with a taxonomy) only one tag is refined to its child or an additional tag is appended [3]. In a nutshell, for each parameter description $d$, EnumCC starts by assessing if the subgroup $G^d$ is valid ($|G^d| \geq \sigma$). In this case, the closed description $\text{closure}_d$ is computed and returned only if the canonicity test is passed (cf. [16, p.66-68]). The description $\text{closure}_d$ corresponds to the tightest description of $G^d$ (maximal in terms of the partial order $\sqsubseteq$ on descriptions in $D$).

Algorithm 2: EnumCC($G$, $d$, $\sigma_G$, $f$, $cnt$)

\begin{algorithm}
\begin{algorithmic}
    \Input $G$ is the collection of records, each encompassing $m$ attributes,
    $d$ is a description from $D$, $\sigma_G$ is a support threshold,
    $f \in [1, m]$ is a refinement flag, $cnt$ is a Boolean.
    \Output yields all closed descriptions, i.e. $\text{clo}[D] = \{\text{clo}(d) \text{ s.t. } d \in D\}$
    \If {$|G^d| \geq \sigma$}
    \State $\text{closure}_d \leftarrow \delta(G^d)$ \Comment compute the most specific description of $G^d$
    \If {$d \ll_j \text{closure}_d$}
    \State $\text{cnt}_c \leftarrow \text{copy}(cnt)$ \Comment $\text{cnt}_c$ value can be modified by a caller algorithm
    \State $\text{yield} (\text{closure}_d, G^{\text{closure}_d}, \text{cnt}_c)$ \Comment yield results and wait for next call
    \If {$\text{cnt}_c$}
    \ForEach $j \in [f, l]$
    \State $\text{foreach } d' \in \eta_j(\text{closure}_d)$
    \State $\text{foreach } (\text{nc}, G^{\text{nc}}, \text{cnt}_\text{nc}) \in \text{EnumCC}(G, d', \sigma_G, j, \text{cnt}_c)$
    \State $\text{yield} (\text{nc}, G^{\text{nc}}, \text{cnt}_\text{nc})$
    \EndFor
    \EndIf
    \EndIf
    \EndIf
\end{algorithmic}
\end{algorithm}
which is the conjunction of all descriptions (conjunction of conditions) related to the records \( g \in G^d \). Next, if the caller-algorithm allows the algorithm to continue (Boolean \( \text{cnt} \) kept True), the description \( \text{closure}_d \) is refined by starting from the last refined attribute (pointed out by the flag \( f \in [1..l] \)), since refining preceding attributes will certainly cause the next canonicity test to fail causing the algorithm to backtrack. Eventually, a recursive call is done to explore the sub-search space related to \( d \) (\( \text{closure}_d \)).
C Appendix: Multiple Comparisons Problem

In what follows, each pattern $H_i = (g_i, c_i)$ is seen as a hypothesis test which returns a p-value $p_i$. Recall that, in this paper, the list of hypotheses to test corresponds to the full search space $L = \{(g, c) \in \mathcal{D}_I \times \mathcal{D}_E : |G^g_I| \geq \sigma_I \text{ and } |G^c_E| \geq \sigma_E \}$ where $g$ (resp. $c$) is a closed description (i.e. the maximum description w.r.t. $\sqsubseteq$) in the equivalence class $[g]$ (resp. $[c]$) of descriptions having their extent equal to $G^g_I$ (resp. $G^c_E$), i.e. $[g] = \{g' \in \mathcal{D}_I \text{ s.t. } G^{g'}_I = G^g_I\}$ (resp. $[c] = \{c' \in \mathcal{D}_E \text{ s.t. } G^{c'}_E = G^c_E\}$). Having this in mind, in what follows, the content of $L$ is shortly denoted by $L = \{H_1, \ldots, H_\omega\}$ and comprises $\omega$ hypotheses. Hypotheses in $L$ are ordered by their p-values $\{p_1, \ldots, p_\omega\}$ where $p_i = p\text{-value}^{g_i}(c_i)$.

The Multiple Comparisons Problem (MCP) [23] is a critical issue in significant pattern mining [21]. In a nutshell, given the critical value $\alpha$ which roughly corresponds to the probability of type 1 error (rejecting a true null hypothesis which is equivalent to accepting a spurious pattern), it is to be expected that $\omega \cdot \alpha$ hypotheses will erroneously pass the test, i.e., $\omega \cdot \alpha$ hypotheses suffer a type 1 error. The classic approach to deal with the MCP is to control the family wise error rate (FWER), which is the probability of accepting at least one false discovery. Other approaches control the false discovery rate (FDR), which corresponds to the expected proportion of false discoveries. We give an overview of relevant existing approaches that deal with the MCP and point out why using them in our setting is a non-trivial task. For a survey on methods dealing with the MCP, we refer the interested reader to [21].

The most famous method to control FWER at $\leq \gamma$ (typically 0.05) is Bonferroni adjustments [11]. The critical $\alpha$ used to test the significance of a pattern is adjusted to $\frac{\alpha}{\omega}$ so as to have FWER at $\leq \gamma$ with $\omega$ the number of all patterns to test in $L$. The problem with this approach is that when $\omega$ is huge, Bonferroni adjusts $\alpha$ to a value very close to 0. This leads to a high number of false negatives as most interesting pattern will be considered spurious (high Type 2 error rate). Clearly, $\omega$ is unknown and needs, in the most trivial way, to be bounded by a quantity $\omega_0$ which is larger than $\omega$. Usually, $\omega_0$ corresponds to the maximum size of the search space: it is equal to $2^{\#\text{items}}$ in the case of an itemset dataset. Webb gives a bound [44] on the size of the search space when dealing with the MCP in attribute-value datasets when the description length is bounded. Using this reasoning without bounding the description length and considering the specification of each attribute (numerical, categorical, ...), in the smallest of our datasets (Movielens; see Table 3) we have $\omega_0 = 72,349,200$. This requires $\alpha$ to be equal to $6.92 \times 10^{-10}$ for the FWER to be at $\leq 0.05$. All the other datasets require $\alpha$ to be $\leq 10^{-76}$ when bounding $\omega$ with the size of the search space. Clearly, such settings for $\alpha$ prohibit the discovery of any meaningful information from the datasets, which cannot possibly be the desired effect of attempts at solving the MCP.

\[16\] Which is the case in the general setting of pattern mining even if we consider only closed patterns satisfying the support size threshold constraint.
Several techniques exist in the literature to relax the requirements on $\alpha$ while ensuring a FWER at $\leq \gamma$ in order to increase the statistical power:

1. Terada et al. [41,40] propose the LAMP technique, relying on Tarone’s Exclusion Principle (TEP) [39]. This principle stipulates that in the list of $m$ hypotheses in $L$ to be tested, one must ignore untestable patterns for multiple comparisons. A pattern $H_i$ is said to be untestable if the lower bound of its p-value, denoted $p^*_i$, is under the adjusted $\alpha = \frac{\gamma}{m}$. Terada et al. [41] proposed this lower bound $p^*_i$ for the particular task of finding significant rules\[43\] where significance is commonly assessed using a Fisher exact test [19,20], since a $2 \times 2$ contingency table is available. The lower bound $p^*_i$ computation depends on this contingency table. Clearly, there is no trivial mapping of our problem to the problem of finding significant rules. Hence, adapting the LAMP algorithm to have an efficient branch and bound technique, incorporating both the proposed bounds in this work (the DEvIANT algorithm) and LAMP reasoning, is clearly a daunting task that requires an in-depth investigation and a new devoted approach which is beyond the scope of this work.

2. Similarly, most of the existing work measuring the interestingness of patterns with statistical significance while efficiently handling the MCP, deals with the significant rule discovery setting [42,27,34,37]. Some of these methods [42,34,37] rely on the Westfall-Young permutation testing method [46] to increase statistical power. Still, no straightforward application of these techniques in our setting is possible; these methods perform random permutations on the class label, and no class label is given in the problem addressed in our work.

3. Other state-of-the-art techniques follow a multi-stage procedure [21] to tackle the MCP. A first step constrains $L$ to a subset of patterns (e.g., testable under TEP). A subsequent post-processing phase controls the FWER [44] or FDR [44,27]. For example, Webb [44] proposes to divide the data into Exploratory and Holdout data. Hypotheses are sought by analyzing solely the exploratory data. Eventually, a constrained number of patterns are found which are validated against the holdout data. In our setting, one needs to investigate how to divide the data into these two parts, since we have two dimensions: context space and group space. In this configuration, a question of crucial importance must be answered: do we need to consider each group independently and divide the entities dataset (defining the context space) into exploratory vs holdout data for each group? Or do we need to jointly consider both these dimensions? This clearly requires a thorough investigation to avoid proposing a naive solution.

4. Layered critical values [45,2] propose to consider a varying adjustment factor for each level of the search space as long as the sum of all critical values is not above $\gamma$. This requires:

\[17\] Each record in the underlying dataset is associated with a binary target label and the objective is to find rules that have significant association with one of the two labels.
– estimating the size of each level (which could be done by following the reasoning of Webb in [45]);
– identifying what is a level of the search space: do we consider levels jointly between group and context search space?
Choosing joint consideration in the latter bullet point implies ignoring (most of the time) the level-1 groups in the search space: the level will grow in size after considering all the contexts corresponding to the group characterizing the whole collection of individuals. Otherwise, the question raised in the former bullet point needs to be answered to provide an appropriate algorithm.
Furthermore, combining the layered critical values along with DEvIANT is not straightforward as it requires re-investigation of the proposed pruning properties.

As we can see, several fundamental questions remain to be answered before one could incorporate a solution to the MCP in the task of finding significant exceptional contextual intra-group agreement patterns. We argue that the scope of this problem is bigger than the ECMLPKDD 2019 publication at hand; it is a non-trivial task that deserves proper attention in the wider context of the significant pattern mining paradigm. We plan to investigate this in future work, and expect that the scope is too wide to fit within a single conference paper; a proper exploration probably requires a journal-length publication.
D Appendix: Additional Experiments

D.1 Performance evaluation

Additional experiments reporting the execution time and the number of reported significant patterns by DEvIANT on Movielens, Yelp, CHUS, and EPD8. In these experiments we also study the overhead induced by the computation of the bootstrapping confidence interval required to handle the variability of outcomes and evaluated for each generated group of individuals.

Fig. 5: Effectiveness of DEvIANT on Movielens when varying sizes of both search spaces $D_E$ and $D_I$, minimum context support threshold $\sigma_E$ and the critical value $\alpha$. Default parameters: full search spaces $D_E$ and $D_I$, $\sigma_E = 0.1\%$, $\sigma_I = 1\%$ and $\alpha = 0.05$. Bootstrapping Confidence intervals for handling variability of outcomes is disabled in the figures on the top row, and enabled in the figures on the bottom row.

Fig. 6: Effectiveness of DEvIANT on Yelp when varying sizes of both search spaces $D_E$ and $D_I$, minimum context support threshold $\sigma_E$ and the critical value $\alpha$. Default parameters: full search spaces $D_E$ and $D_I$, $\sigma_E = 0.1\%$, $\sigma_I = 1\%$ and $\alpha = 0.05$. Bootstrapping Confidence intervals for handling variability of outcomes is disabled in the figures on the top row, and enabled in the figures on the bottom row.
Fig. 7: Effectiveness of DEvIANT on CHUS when varying sizes of both search spaces $\mathcal{D}_E$ and $\mathcal{D}_I$, minimum context support threshold $\sigma_E$ and the critical value $\alpha$. Default parameters: full search spaces $\mathcal{D}_E$ and $\mathcal{D}_I$, $\sigma_E = 0.1\%$, $\sigma_I = 1\%$ and $\alpha = 0.05$. Bootstrapping Confidence intervals for handling variability of outcomes is disabled in the figures on the top row, and enabled in the figures on the bottom row.

Fig. 8: Effectiveness of DEvIANT on EPD8 when varying sizes of both search spaces $\mathcal{D}_E$ and $\mathcal{D}_I$, minimum context support threshold $\sigma_E$ and the critical value $\alpha$. Default parameters: full search spaces $\mathcal{D}_E$ and $\mathcal{D}_I$, $\sigma_E = 0.1\%$, $\sigma_I = 1\%$ and $\alpha = 0.05$. Bootstrapping Confidence intervals for handling variability of outcomes is disabled in the figures on the top row, and enabled in the figures on the bottom row.
D.2 Qualitative evaluation

Here, we report additional illustrative examples depicting the significant patterns discovered by DEvIANT when carried on the Eighth European Parliament (EPD8) dataset and Yelp dataset.

Table 7: Top-5 exceptional consensual/conflictual subjects among European Political Groups in the 8th EU parliament. $\alpha = 0.01$. Patterns are ranked by the absolute difference between $A^\theta(c)$ and $A^\theta(\ast)$.

<table>
<thead>
<tr>
<th>id</th>
<th>group (g) context (c)</th>
<th>$A^\theta(\ast)$</th>
<th>$A^\theta(c)$</th>
<th>p-value</th>
<th>IA</th>
</tr>
</thead>
<tbody>
<tr>
<td>p1</td>
<td>S&amp;D</td>
<td>8.10 Revision of the Treaties and intergovernmental conferences</td>
<td>0.81</td>
<td>0.44</td>
<td>&lt; 0.001</td>
</tr>
<tr>
<td>p2</td>
<td>*</td>
<td>2 Internal market, single market</td>
<td>0.27</td>
<td>0.54</td>
<td>&lt; 0.001</td>
</tr>
<tr>
<td>p3</td>
<td>S&amp;D</td>
<td>8.30 Treaties in general</td>
<td>0.81</td>
<td>0.55</td>
<td>&lt; 0.001</td>
</tr>
<tr>
<td>p4</td>
<td>*</td>
<td>2 Internal market, single market, 4.15 Employment policy, act. combat unemployment</td>
<td>0.27</td>
<td>0.53</td>
<td>&lt; 0.001</td>
</tr>
<tr>
<td>p5</td>
<td>ALDE</td>
<td>1.20.09 Protection of privacy and data protection</td>
<td>0.73</td>
<td>0.48</td>
<td>&lt; 0.001</td>
</tr>
</tbody>
</table>

Table 8: Top-10 exceptional consensual/conflictual subjects among countries’ parliamentarians in the 8th EU parliament. $\alpha = 0.01$. Patterns are ranked by the absolute difference between $A^\theta(c)$ and $A^\theta(\ast)$.

<table>
<thead>
<tr>
<th>id</th>
<th>group (g) context (c)</th>
<th>$A^\theta(\ast)$</th>
<th>$A^\theta(c)$</th>
<th>p-value</th>
<th>IA</th>
</tr>
</thead>
<tbody>
<tr>
<td>p1</td>
<td>Sweden</td>
<td>4 Economic, social and territorial cohesion 6.30 Development cooperation</td>
<td>0.3</td>
<td>0.84</td>
<td>&lt; 0.0001</td>
</tr>
<tr>
<td>p2</td>
<td>Finland</td>
<td>4 Economic, social and territorial cohesion 6.30 Development cooperation</td>
<td>0.36</td>
<td>0.87</td>
<td>&lt; 0.0001</td>
</tr>
<tr>
<td>p3</td>
<td>Finland</td>
<td>8.20.04 Pre-accession and partnership</td>
<td>0.36</td>
<td>0.75</td>
<td>&lt; 0.01</td>
</tr>
<tr>
<td>p4</td>
<td>Sweden</td>
<td>8.20 Enlargement of the Union</td>
<td>0.3</td>
<td>0.66</td>
<td>&lt; 0.0001</td>
</tr>
<tr>
<td>p5</td>
<td>Slovakia</td>
<td>1.10 Fundamental rights in the EU, Charter</td>
<td>0.48</td>
<td>0.13</td>
<td>&lt; 0.0001</td>
</tr>
<tr>
<td>p6</td>
<td>Malta</td>
<td>4.60.06 Consumers economic and legal interests</td>
<td>0.63</td>
<td>0.97</td>
<td>&lt; 0.0001</td>
</tr>
<tr>
<td>p7</td>
<td>Malta</td>
<td>2.10 Free movement of goods</td>
<td>0.63</td>
<td>0.34</td>
<td>&lt; 0.0001</td>
</tr>
<tr>
<td>p8</td>
<td>Latvia</td>
<td>4.60.06 Consumers economic and legal interests</td>
<td>0.42</td>
<td>0.69</td>
<td>&lt; 0.0001</td>
</tr>
<tr>
<td>p9</td>
<td>Luxembourg</td>
<td>1.20 Citizen’s rights, 8 State and evolution of the Union</td>
<td>0.51</td>
<td>0.23</td>
<td>&lt; 0.01</td>
</tr>
<tr>
<td>p10</td>
<td>*</td>
<td>2 Internal market, single market 6 External relations of the Union</td>
<td>0.27</td>
<td>0.54</td>
<td>&lt; 0.001</td>
</tr>
</tbody>
</table>
Table 9: Top-10 exceptional consensual/conflictual subjects among German national parties in the 8th EU parliament. $\alpha = 0.01$. Patterns are ranked by the absolute difference between $A^g(c)$ and $A^g(*)$.

<table>
<thead>
<tr>
<th>id</th>
<th>group $(g)$</th>
<th>context $(c)$</th>
<th>$A^g(*)$</th>
<th>$A^g(c)$</th>
<th>p-value</th>
<th>IA</th>
</tr>
</thead>
<tbody>
<tr>
<td>$p_1$</td>
<td>Sozialdemokratische Partei Deutschlands</td>
<td>1 European citizenship, 3 Community Policies</td>
<td>0.91</td>
<td>0.31</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_2$</td>
<td>*</td>
<td>3.70.11 Natural disasters, Solidarity Fund</td>
<td>0.38</td>
<td>0.93</td>
<td>&lt;0.0001</td>
<td>Consensus</td>
</tr>
<tr>
<td>$p_3$</td>
<td>*</td>
<td>6.20.05 Multilateral economic and trade agreements and relations</td>
<td>0.38</td>
<td>0.85</td>
<td>&lt;0.0001</td>
<td>Consensus</td>
</tr>
<tr>
<td>$p_4$</td>
<td>*</td>
<td>3.50 Research and technological development 4 Economic, social and territorial cohesion</td>
<td>0.38</td>
<td>0.78</td>
<td>&lt;0.001</td>
<td>Consensus</td>
</tr>
<tr>
<td>$p_5$</td>
<td>*</td>
<td>3.30.03 Telecommunications, data transmission, telephone</td>
<td>0.38</td>
<td>0.92</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_6$</td>
<td>Liberal-Conservative Refomists</td>
<td>3.50.15 Intellectual property, copyright</td>
<td>0.91</td>
<td>0.57</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_7$</td>
<td>*</td>
<td>3.30.06 Information and communication tech. 4 Economic, social and territorial cohesion</td>
<td>0.38</td>
<td>0.04</td>
<td>&lt;0.001</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_8$</td>
<td>DIE LINKE.</td>
<td>3.15 Fisheries policy</td>
<td>0.88</td>
<td>0.56</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_9$</td>
<td>*</td>
<td>3.50.20 Scientific and technological cooperation and agreements</td>
<td>0.38</td>
<td>0.7</td>
<td>&lt;0.001</td>
<td>Consensus</td>
</tr>
<tr>
<td>$p_{10}$</td>
<td>*</td>
<td>3.30.05 Electronic and mobile communications, personal communications</td>
<td>0.38</td>
<td>0.07</td>
<td>&lt;0.001</td>
<td>Conflict</td>
</tr>
</tbody>
</table>

Table 10: Top-10 exceptional consensual/conflictual places/categories/states among Yelp users. $\alpha = 0.01$. Patterns are ranked by the absolute difference between $A^g(c)$ and $A^g(*)$.

<table>
<thead>
<tr>
<th>id</th>
<th>group $(g)$</th>
<th>context $(c)$</th>
<th>$A^g(*)$</th>
<th>$A^g(c)$</th>
<th>p-value</th>
<th>IA</th>
</tr>
</thead>
<tbody>
<tr>
<td>$p_1$</td>
<td>03 Automotive</td>
<td>0.14</td>
<td>-0.16</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
<td></td>
</tr>
<tr>
<td>$p_2$</td>
<td>10 Health &amp; Medical</td>
<td>0.14</td>
<td>-0.14</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
<td></td>
</tr>
<tr>
<td>$p_3$</td>
<td>08 Financial Services</td>
<td>0.14</td>
<td>-0.11</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
<td></td>
</tr>
<tr>
<td>$p_4$</td>
<td>newcomer</td>
<td>09.38.07 Health Markets, 09.47 Juice Bars &amp; Smoothies</td>
<td>0.14</td>
<td>-0.07</td>
<td>&lt;0.01</td>
<td>Conflict</td>
</tr>
<tr>
<td>$p_5$</td>
<td>El Dorado Hills, California</td>
<td>0.14</td>
<td>0.35</td>
<td>&lt;0.0001</td>
<td>Consensus</td>
<td></td>
</tr>
<tr>
<td>$p_6$</td>
<td>14 Local Services</td>
<td>0.14</td>
<td>-0.06</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
<td></td>
</tr>
<tr>
<td>$p_7$</td>
<td>04 Beauty &amp; Spas</td>
<td>0.14</td>
<td>-0.06</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
<td></td>
</tr>
<tr>
<td>$p_8$</td>
<td>15 Mass Media</td>
<td>0.14</td>
<td>-0.05</td>
<td>&lt;0.01</td>
<td>Conflict</td>
<td></td>
</tr>
<tr>
<td>$p_9$</td>
<td>11 Home Services’</td>
<td>0.14</td>
<td>-0.05</td>
<td>&lt;0.0001</td>
<td>Conflict</td>
<td></td>
</tr>
<tr>
<td>$p_{10}$</td>
<td>Midlothian, Edinburgh</td>
<td>0.14</td>
<td>0.31</td>
<td>&lt;0.0001</td>
<td>Consensus</td>
<td></td>
</tr>
</tbody>
</table>
E Appendix: Empirical DFDs

Here, we give an overview of the empirical distributions of Krippendorff’s Alpha for 1000 draws from $F_k$ equally likely to occur. Recall that $F_k$ represents the subsets of the entire collection of entities of size $k$ over which we define the random variable $\theta_k : F_k \to \mathbb{R}$. Thus, the distributions presented here illustrate the values observed on 1000 trials of $\theta_k$. To illustrate the fact that the confidence intervals associated with $\theta_k$ (considering its distribution under the null hypothesis) are nested (when $k$ grows, the confidence interval shrinks), we perform the experiments for various valuations of $k$.

Fig. 9: Empirical distribution of the observed values of 1000 trials of $\theta_k$ for four valuations of $k$ (DFD). The top figure displays experiments on EPD8; the bottom figure displays experiments on CHUS (US House of representatives). We observe that the distributions are encapsulated when $k$ decreases. Also, the dispersion of A increases and the corresponding empirical confidence interval grows in size.
Fig. 10: Empirical distribution of the observed values of 1000 trials of \( \theta_k \) for four valuations of \( k \) (DFD). The top figure displays experiments on Movielens; the bottom figure displays experiments on Yelp. We observe that the distributions are encapsulated when \( k \) decreases. Also, the dispersion of \( A \) increases and the corresponding empirical confidence interval grows in size.
Table 11: Symbol table

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Definition</th>
</tr>
</thead>
<tbody>
<tr>
<td>$G_E$</td>
<td>A finite collection of records depicting entities</td>
</tr>
<tr>
<td>$G_I$</td>
<td>A finite collection of records depicting individuals</td>
</tr>
<tr>
<td>$O$</td>
<td>The domain of possible outcomes</td>
</tr>
<tr>
<td>$o$</td>
<td>Function returning the outcome of an individual over an entity</td>
</tr>
<tr>
<td>$B = (G_I, G_E, O, o)$; A behavioral dataset</td>
<td></td>
</tr>
<tr>
<td>$A_E$ (resp. $A_I$): Descriptive attributes of entities (resp. individuals)</td>
<td></td>
</tr>
<tr>
<td>$D$ (resp. $D_I$): The description domain of contexts (resp. groups)</td>
<td></td>
</tr>
<tr>
<td>$G_E^g$</td>
<td>A subgroup of entities supporting a context $c$ in $D_E$</td>
</tr>
<tr>
<td>$G_I^g$</td>
<td>A subgroup of individuals supporting a group $g$ in $D_I$</td>
</tr>
<tr>
<td>$g = g \in D_I$; a description of a group of individuals characterizing $G_I^g \subseteq G_I$</td>
<td></td>
</tr>
<tr>
<td>$c = c \in D_E$; a context characterizing a subset of entities $G_E^c \subseteq G_E$</td>
<td></td>
</tr>
<tr>
<td>$P \subseteq P$: The returned pattern set</td>
<td></td>
</tr>
<tr>
<td>read “less restrictive than” is a partial order between descriptions in some descriptions space $D$ (in $D_E$ or $D_I$)</td>
<td></td>
</tr>
</tbody>
</table>

- $B^0$: The reduced behavioral dataset for individuals comprising $G_I^g$ |
- $A$: Intra-group agreement measure - Krippendorff’s Alpha |
- $A^g(G_E^c)$: Intra-group agreement of a group $g$ over a context $c$ |

We omit the exponent $g$ in the notations and we assume that we have a group of individuals $g$ in mind (we use $B^0$)

- $D_{\text{exp}}$: Expected disagreement (via marginal distribution) between individuals |
- $D_{\text{obs}}$: Observed disagreement between individuals |
- $n$: Number of entities in $G_E$, i.e., $|G_E|$ |
- $m$: Number of all expressed outcomes |
- $m^{e_1}$: Number of expressed outcomes equal to $e_1$ |
- $m^{e_2}$: Number of expressed outcomes for entity $e_2$ (also denoted $w_e$) |
- $m^{e_2}_e$: Number of expressed outcomes equal to $e_1$ for entity $e$ |
- $\delta_{e_1,e_2}$: Distance between two outcomes in $O$ |

- DFD: Distribution of False discoveries |
- $F_k$: $\{S \subseteq G_E \text{ s.t. } |S| = k\}$ |
- $\theta_k$: Random variable $\theta_k : F_k \rightarrow \mathbb{R}$ with $S \mapsto A(S)$. Also $\theta_k = \frac{\hat{V}_k}{\hat{w}_k}$ |
- $\hat{V}_k$: Intra-group agreement (Krippendorff’s Alpha) for one entity, given by: $m_e - \frac{1}{D_{\text{exp}}} \sum_{o_1,o_2 \in O} \delta_{o_1,o_2} \cdot \frac{m^{o_1} \cdot m^{o_2}}{(m_e-1)}$ |
- $\hat{w}_k$: Random variable $\hat{w}_k : F_k \rightarrow \mathbb{R}$ with $S \mapsto \frac{1}{k} \sum_{e \in S} w_e$ |
- $\alpha$: Critical value |
- $CI_{1-\alpha}^{\theta_k}$: The $1 - \alpha$ confidence interval associated with the DFD of $\theta_k$. |
- $\hat{CI}_{1-\alpha}^{\theta_k}$: The $1 - \alpha$ Taylor-approximated confidence interval of $CI_{1-\alpha}^{\theta_k}$. |
- $\hat{CI}_{\text{bootstrap}}^{1-\alpha}$: The bootstrap confidence interval. |
- $LB(S, \sigma_E)$: Lower bound of $A$ for any specialization of a subgroup having its size greater than $\sigma_E$ |
- $UB(S, \sigma_E)$: Upper bound of $A$ for any specialization of a subgroup having its size greater than $\sigma_E$ |
- $OE(S, \sigma_E) = [LB(S, \sigma_E), UB(S, \sigma_E)]$: Optimistic estimate region of $A$
References
