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To cite this version:

HAL Id: hal-01889155
https://hal.archives-ouvertes.fr/hal-01889155
Submitted on 5 Oct 2018

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Shape-Diverse DSLs: Languages without Borders (Vision Paper)

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Abstract

Domain-Specific Languages (DSLs) manifest themselves in remarkably diverse shapes, ranging from internal DSLs embedded as a mere fluent API within a programming language, to external DSLs with dedicated syntax and tool support. Although different shapes have different pros and cons, combining them for a single language is problematic: language designers usually commit to a particular shape early in the design process, and it is hard to reconsider this choice later. In this new ideas paper, we envision a language engineering approach enabling (i) language users to manipulate language constructs in the most appropriate shape according to the task at hand, and (ii) language designers to combine the strengths of different technologies for a single DSL. We report on early experiments and lessons learned building Prism, our prototype approach to this problem. We illustrate its applicability in the engineering of a simple shape-diverse DSL implemented conjointly in Rascal, EMF, and Java. We hope that our initial contribution will raise the awareness of the community and encourage future research.

CCS Concepts • Software and its engineering → Domain specific languages;

ACM Reference Format:

1 Introduction & Motivating Example

One of the first steps in designing a new Domain-Specific Language (DSL) is to choose which language vehicle (LV) will be used to engineer it. We define a LV as the technological means for implementing a language. This includes language workbenches as well as programming languages and ontology languages, to name a few. The notion of language vehicle is orthogonal to the distinction between technological spaces (e.g., grammarware, modelware [9]); between graphical and textual syntax; between internal, embedded, and external DSLs. For instance, we consider Rascal [8] and Spoofax [6] as two distinct language vehicles within the broader technological space of grammarware and meta-programming; EMF [13] and UML [5] (using Profiles [11]) as two distinct language vehicles within the broader technological space of modelware. LVs usually come with their own meta-languages for expressing the various aspects of a DSL: abstract syntax, concrete syntax, static and execution semantics, tools, etc. As implementation techniques differ radically from one LV to another, this initial design choice commits the development of a DSL in a set direction that can hardly be reconsidered later.

From the language designer’s point of view, however, every LV has its own strengths. The ecosystem around EMF excels in the definition of user-friendly editors and persistence frameworks for large models, while the Rascal environment excels in the definition of interpreters and refactoring tools. The benefits of various LVs are also visible from the language users’ point of view. While domain experts may prefer to manipulate domain concepts through a dedicated syntax, advanced users (e.g., system integrators) may favor the flexibility of a fluent API in their favorite programming language to manipulate the very same constructs.

Let us consider a simple Finite-State Machine (FSM) language as a motivating example. As depicted in Figure 1, one would like to combine the strengths of multiple LVs to engineer this DSL. Rascal could be used to develop its interpreter, a set of refactoring tools (e.g., state collapsing and minimization), and a textual editor; EMF to develop a graphical animator for debugging FSM models and a persistence layer;
Java to offer a fluent API for advanced users who focus on its integration with other system concerns.

Using today’s techniques, it is possible to define the same FSM language in these three LVs separately. It is not possible, however, to apply the tools of a given LV on the models or programs created in another LV—for instance, animating a FSM model written in EMF using the Rascal interpreter, or synchronizing a textual FSM model in Rascal with its equivalent incarnation as a Java AST. Achieving this goal requires to efficiently synchronize the different representations of the same model in different LVs; for instance to let the FSM interpreter written in Rascal update its own representation of an FSM model after each execution step and synchronize it with the representation of the same model in EMF for animation purposes.

In this paper, we envision a language engineering approach enabling (i) language designers to combine tools from multiple LVs to engineer diverse shapes for a single DSL and (ii) language users to manipulate language constructs in the most appropriate shape. We present the notion of shape-diverse DSL in Section 2. We then present our prototype approach, Prism, in Section 3, and discuss our implementation of a shape-diverse FSM language in Section 4. Finally, we discuss open questions and next steps in Section 5.

2 Shape-Diverse DSLs

The cornerstone artifact defining a DSL in any LV is its abstract syntax. The way abstract syntax is expressed differs drastically from one LV to another: GEMOC [4] and Xtext [3] use Ecore metamodels [13], MPS uses concepts [16], Rascal [8] uses Algebraic Data Types (ADT), etc. Language embedding techniques, on the other hand, use the constructs of a host language to materialize the constructs of a DSL in the host language itself (e.g., a set of Java classes). Concrete models are then built as instances of the corresponding abstract syntax formalism: Ecore models, ADT values, Java ASTs, etc. The tools defined within a particular LV (an interpreter in Rascal, an editor in EMF) manipulate models in the corresponding formalism (respectively, ADT values and Ecore models). These formalisms radically differ in many ways [7]: object-oriented vs. functional, graphs vs. trees, mutable vs. immutable datatypes, cross-references vs. symbolic names, etc. As LVs are developed by independent groups of people and rely on different underlying theories, it is neither possible nor desirable to establish a common foundation upon which all LVs would agree.

Figure 2 gives an overview of the concept of shape-diverse language and the terminology we use throughout the paper. A shape-diverse language \( L \) (e.g., the FSM language of Figure 1) is a language that is implemented in multiple LVs through multiple shapes \( S_i \). As mentioned earlier, Ecore metamodels, ADT definitions, and Java APIs, along with their associated tooling, are examples of shapes. Similarly, a “conceptual” model \( m \) that uses the constructs of \( L \) (e.g., the simple \texttt{Button} machine) is projected\(^1\) as an incarnation \( I_i \) conforming to the shape \( S_i \) in a LV: an Ecore model, an ADT value, or a Java AST.

As the same model is incarnated many times, each of its incarnations \( I_i \) must remain synchronized. This synchronization mechanism must ensure three essential properties. First, it must be efficient. This rules out any synchronization mechanism that would require a full traversal or full (de)serialization of the incarnations after every update. Second, it must account for any extra shape-specific information the various LVs have to maintain to function properly, such as layout information in a textual or graphical editor, or runtime state in a simulation environment. The synchronization mechanism must thus isolate the information that relates to the model itself from the information that is specific to a particular shape. Third, the synchronization mechanism must be language-agnostic, meaning it should not have to be re-implemented for every shape-diverse DSL.

\(^1\)The notion of projection here is unrelated to the notion of projectional editing [17] as there is no underlying AST to project from.
3 Synchronizing Incarnations with PrISM

Figure 3 depicts our prototype approach to the problem of synchronizing various incarnations of a model, PrISM. PrISM acts as a communication bus between LVs that remain fully independent. The key idea is that every change occurring on one incarnation is shipped to all other incarnations of the same model in the form of a patch. This patch represents the exact set of changes that occurred on one incarnation. It allows synchronizing incarnations online efficiently without requiring serialization or a full traversal of any of the incarnation. PrISM keeps track of a matrix that associates every conceptual model to its incarnations in various LVs. When a change occurs on one incarnation, for instance resulting from a user edit or an execution step of an interpreter, the LV hosting this incarnation generates a patch describing the change as a set of CRUD-like operations. In our prototype implementation, the structure of this patch is prescribed by the Rascal ADT shown in Listing 1, largely inspired by edit scripts [15]. Essentially, patches consist of a set of operations attached to identities [7] that represent particular objects in the model. To ensure that every LV can apply the operations on the right elements, identities are preserved across LVs and, in our case, they are represented by URIs [2].

Every LV then interprets the patch in its own way to keep its incarnations synchronized. In EMF, for instance, the patch is interpreted as a set of changes that impact an ADT value. The way changes are detected in an incarnation and patches are produced is not prescribed by our approach. For instance, our Rascal implementation computes patches from a diff operation between two ADT values, while our EMF implementation captures the result of transactions on an Ecore model to produce the patches. The produce and apply operations are implemented once for every LV and do not have to be re-implemented for every language.

A cornerstone artifact in PrISM is the dispatch mechanism that routes patches to the appropriate incarnations. When receiving a patch, PrISM looks up its internal matrix to determine which other incarnations of the same model should be updated. The patch is then copied and routed accordingly. Our current implementation of the dispatch mechanism is kept simple, and we leave for future work the support of concurrent edits on different incarnations of the same model. This will allow PrISM to scale to advanced scenarios that go beyond the scope of this paper, such as collaborative editing.

4 A Shape-Diverse FSM Language

To illustrate PrISM, we build a shape-diverse FSM language jointly in Rascal, EMF, and Java, available on a companion webpage [14]. Figure 4 depicts the implementation of the abstract syntax of this FSM language in the three LVs. The corresponding incarnations are those given in Figure 1.

We use Rascal to define a textual editor and a simple transformation that inserts a new state in a machine. We use EMF to define two graphical editors: a classical tree editor and a domain-specific representation with Sirius. We build the Java API following a simple systematic convention, so as to easily pinpoint which parts of the Java AST have changed (to compute a patch) or need to be updated (to apply a patch).

Using PrISM, the Rascal and EMF shapes synchronize seamlessly, but we noticed a number of challenges with the
In this paper, we have stressed the importance of shape-diverse DSLs and have proposed a first prototype approach, Prism. We hope that our initial contribution will raise the awareness of the community regarding these notions and that the challenges we identify encourage future research.

Acknowledgments
This work is partially supported by the associate team ALE (http://gemoc.org/ale/), the bilateral collaboration Kaulua (http://gemoc.org/kaulua/) between Inria & Obeo, and the EU’s Horizon 2020 Project No. 732223 CROSSMINER.
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