Modeling and Frequency Performance Analysis of Through Silicon Capacitors in Silicon Interposers

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Abstract—The feasibility of cointegration of new capacitors, named “through silicon capacitors” (TSCs) with “through silicon vias” in silicon interposers has recently been demonstrated. Two architectures of TSC are extensively investigated in this paper: “axial TSC” whose electrodes are connected on either sides of the silicon interposer and “radial TSC” with electrodes both connected to the metal layers of the back end of line. A general modeling method based on distributed cell segmentation is proposed for both architectures. Validation is performed by measurements from 1 kHz to 40 GHz (above the resonance frequency of the components). A comparative study between radial and axial architectures is performed, leading to the prediction of the performances of those new components. Finally, design rules are established for future integration for power delivery networks decoupling applications.

Index Terms—High frequency modeling, integrated capacitor, measurements, power distribution network (PDN), silicon interposer.

I. INTRODUCTION

THE integration of high-value and high-frequency decoupling capacitors for power distribution network (PDN) applications in 3-D integrated circuits still remains a technological requirement [1]. As decoupling capacitors must be placed at the very close vicinity of the integrated devices, embedded MIM capacitors have been extensively used [2], [3]. However, since the overall dedicated area for the capacitors is constantly reduced, while capacitance value needs to be increased, their fabrication process has been improved in many ways (insulator thickness decrease, dielectric material permittivity enhancement). Those improvements are probably now reaching their limits [4], [5]. Furthermore, 2.5-D integration, with silicon interposers, provides alternative locations for efficient, high value and high density 3-D capacitors. Inspired from the through silicon vias (TSV), a very promising technology seems to be the “through silicon capacitors” (TSCs), i.e., vertical cylindrical capacitors embedded through the silicon interposer. They are investigated in [6] and present

high capacitance density (up to 35 nF/mm²). High capacitance values are given by the use of a large amount of TSCs connected in parallel as a matrix. Typical diameter of a TSC is 10 μ m, and depth is 100 μ m. A matrix can contain thousands of TSCs in parallel. On the top and bottom sides of the silicon interposer, metal layers (called lids) are used to connect them in parallel, and they present associated parasitic elements (for inductive and resistive effects) that limit the decoupling function. The parasitic effects have then to be modeled and measured from dc to several gigahertz (above the resonance frequency of the components) [7].

Using standard full-wave finite element analysis (FEA) software to model complete structure of hundreds of TSCs would necessitate huge resources and computing time, and such simulations seem to be unreachable in some cases. To overcome this issue and to be able to quantify the parasitic elements of large matrices of TSC, one developed two modeling methods for two architectures of TSC [8]. Those modeling methods, based on a segmented approach, make use of 2-D/3-D parasitic extraction software for the modeling of each part of the structure. The resulting lumped RLCG parameters are used to generate a global equivalent circuit composed of segments of coupled distributed cells. Section II gives an overview of the technological process for the integration of TSC. Section III presents the modeling methods for each architecture. Section IV provides a comparative study of those two architectures, with further investigation on the impact of the number of TSCs and the excitation.

II. TECHNOLOGICAL REALIZATION OF AXIAL AND RADIAL TSC MATRICES

TSCs are copper vertical cylindrical capacitors inspired from the TSV. The TSC technology is based on an MIM stack deposited in deep holes etched in a silicon interposer. Two kinds of structures are investigated in this paper: axial and radial structures; as described in Fig. 1. In the axial structure, the inner conductors of each TSC are connected together by a metal layer on the top side of the interposer, and the outer conductors are connected on the back side. On the contrary, in the radial structure, both the inner and the outer conductors are connected on the top side of the interposer.

The presented demonstrators have been realized using the radial process, as shown in Fig. 2. Matrices of deep holes have been filled with a standard capacitive stack TiN (200 nm)/Al₂O₃ (20 nm)/TiN (200 nm) as shown in Fig. 3. The integration of TSC shares many common steps with the integration of TSV: deep reactive ion etching, passivation, and copper filling. This cointegration with TSV leads to

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Fig. 1. Radial and axial TSC architectures.

Fig. 2. (a) Top view of a matrix of 1008 TSC (diameter 100 μm , depth 188 μm). (b) Tilted SEM cross section of TSC matrix (CEA LETI).

Fig. 3. SEM cross section of a $\text{SiO}_2/\text{TiN}/\text{Al}_2\text{O}_3/\text{TiN}$ stack deposited in a deep hole (CEA LETI).

an overall cost reduction of the process. The full fabrication process is detailed in [9]. These first demonstrators are intended to prove the technological feasibility of TSC components and to evaluate their performances in terms of capacitance density, parasitic resistance, and parasitic inductance compared to planar MIM components.

III. MODELING METHOD FOR AXIAL AND RADIAL TSCS

Numerous TSC coaxial bodies connected in parallel by lids constitute a matrix. Capacitances much higher than 10 nF for decoupling applications can be achieved by large matrices of TSCs (more than 1000 TSCs), but the full simulation of such matrices still remains a challenge due to the number of elements and to their aspect ratio. The two modeling methods developed in this paper allow the estimation of the performances of large matrices of TSCs. The obtained frequency response is valid up to a decade above the serial resonance frequency (SRF) as all electromagnetic effects are taken into account, i.e., inductive and resistive parasites in conductors and capacitive effect as well as conductive losses in dielectrics. The decoupling of electrical and magnetic simulations considerably reduces the computing time, thus allowing the simulation of very large matrices that are unreachable with standard full-wave FEA software.

The first modeling method, described in part A, is dedicated to “axial TSC,” whereas the second modeling method, described in part B, is dedicated to “radial TSC.” The two topologies are presented in Fig. 1. For both topologies, the whole component is composed of horizontal metal plates, named “lids,” and vertical coaxial cylindrical electrodes, named TSC bodies. Both methods consider that the entire structure can be considered as cascaded subcircuits under the assumption that there is no coupling between each subcircuit. The inductive coupling between lids and TSC bodies is null since the current densities are perpendicular one to another. The capacitive and conductive coupling is negligible, except in axial case, where it has been modeled analytically with Z coupling (see Fig. 4).

A. Axial TSC

The structural electrical circuit equivalent to the axial architecture is presented in Fig. 4. The full component is composed of five main subcircuits: the coaxial bodies, the top and bottom lids, and two parallel connection stages. The principle of the modeling method is to determine separately the ABCD matrix of each subcircuit (see Sections III-A.1 and III-A.2) and to take the matrix product of them, then to use the admittance representation to make the parallel connections and finally obtain the equivalent impedance of the system (see Section III-A.3).

1) *TSC Coaxial Bodies Contribution:* The N coaxial TSC bodies can be viewed as $2N$ coupled transmission lines (N inner conductors and N outer conductors). The departure point of the proposed approach is that no conductor is considered as a “return path,” and that a virtual ground conductor is therefore defined.

As it is based on the resolution of field integral equations, the magnetic 3-D solver of Ansys Q3D Extractor allows the resolution of magneto-quasi-static problems including portions of loops of currents, thus leading to the evaluation of partial inductances. In the same manner, the electric 3-D solver allows the resolution of electro-quasi-static problems including voltage drops between conductors in partial influence without defined ground, thus leading to the evaluation of partial capacitances. The losses are also included in simulations, and the output matrices of the two solvers are then $\mathbf{Z}_M$ ($2N \times 2N$ dense matrix modeling the inductive and resistive coupled effects in the $2N$ conductors) and $\mathbf{Y}_E$ ($2N \times 2N$ dense matrix modeling the capacitive and conductive effects between the $2N$ conductors). For the sake of clearness, vector and matrix names have been bolded.

Given $\mathbf{Z}_M$ and $\mathbf{Y}_E$, one can compute the generalized ABCD matrix, named $\mathbf{A}_{BODIES}$, of the coaxial TSC bodies, thanks to the method presented in [10]

$$\begin{bmatrix} V_A \\ V_B \\ I_A \\ I_B \end{bmatrix} = \underbrace{\begin{bmatrix} \mathbf{Y}_E^{-1} \cdot \cosh(\boldsymbol{\Gamma}) \cdot \mathbf{Y}_E & \mathbf{Z}_C \cdot \sinh(\boldsymbol{\Gamma}) \\ \sinh(\boldsymbol{\Gamma}) \cdot \mathbf{Z}_C^{-1} & \cosh(\boldsymbol{\Gamma}) \end{bmatrix}}_{\mathbf{A}_{BODIES}} \begin{bmatrix} V_C \\ V_D \\ -I_C \\ -I_D \end{bmatrix} \quad (1)$$

where

$$\boldsymbol{\Gamma} = \text{sqr}tm(\mathbf{Y}_E \cdot \mathbf{Z}_M) \quad (2)$$

$$\mathbf{Z}_C = \text{sqr}tm(\mathbf{Y}_E^{-1} \cdot \mathbf{Z}_M) \quad (3)$$

Fig. 4. Axial TSC structural electrical model.

and where the voltage and current vectors of the TSC coaxial bodies

$$\begin{aligned} \mathbf{V}_A &= \begin{bmatrix} V_{A1} \\ \vdots \\ V_{AN} \end{bmatrix} & \mathbf{I}_A &= \begin{bmatrix} I_{A1} \\ \vdots \\ I_{AN} \end{bmatrix} & \mathbf{V}_B &= \begin{bmatrix} V_{B1} \\ \vdots \\ V_{BN} \end{bmatrix} \\ \mathbf{I}_B &= \begin{bmatrix} I_{B1} \\ \vdots \\ I_{BN} \end{bmatrix} & \mathbf{V}_C &= \begin{bmatrix} V_{C1} \\ \vdots \\ V_{CN} \end{bmatrix} & \mathbf{I}_C &= \begin{bmatrix} I_{C1} \\ \vdots \\ I_{CN} \end{bmatrix} \\ \mathbf{V}_D &= \begin{bmatrix} V_{D1} \\ \vdots \\ V_{DN} \end{bmatrix} & \text{and } \mathbf{I}_D &= \begin{bmatrix} I_{D1} \\ \vdots \\ I_{DN} \end{bmatrix} \end{aligned}$$

are defined in Fig. 4. Furthermore, sqrtn , sinhm , and coshm , respectively, denote the matrix square root, matrix hyperbolic cosine, and matrix hyperbolic sine functions. It is interesting to note that the simulation directly gives the extensive matrix $\mathbf{\Gamma}$, i.e., the equivalent line length does not need to be known as it is included in $\mathbf{\Gamma}$.

2) *Top and Bottom Lids Contribution*: The ABCD matrices $\mathbf{A}_{TOP}$ ($\mathbf{A}_{BOTTOM}$) of the top lid (bottom lid) are computed thanks to the following:

- 1) the magnetic simulation of the inductive effects in the lids that provides $\mathbf{Z}_{TopLid}$ ($\mathbf{Z}_{BottomLid}$);
- 2) the analytical evaluation of the coupling effect between the TSC coaxial body and the lid that lid to the high-impedance diagonal matrix $\mathbf{Z}_{Coupling}$

$$\begin{bmatrix} \mathbf{V}'_A \\ \mathbf{V}'_B \\ \mathbf{I}'_A \\ \mathbf{I}'_B \end{bmatrix} = \underbrace{\begin{bmatrix} \mathbb{I}_N & \mathbb{O}_N & \mathbf{Z}_{TopLid} & \mathbb{O}_N \\ \mathbb{O}_N & \mathbb{I}_N & \mathbb{O}_N & \mathbf{Z}_{Coupling} \\ \mathbb{O}_N & \mathbb{O}_N & \mathbb{I}_N & \mathbb{O}_N \\ \mathbb{O}_N & \mathbb{O}_N & \mathbb{O}_N & \mathbb{I}_N \end{bmatrix}}_{\mathbf{A}_{TOP}} \cdot \begin{bmatrix} \mathbf{V}_A \\ \mathbf{V}_B \\ \mathbf{I}_A \\ \mathbf{I}_B \end{bmatrix} \quad (4)$$

$$\begin{bmatrix} \mathbf{V}_C \\ \mathbf{V}_D \\ -\mathbf{I}_C \\ -\mathbf{I}_D \end{bmatrix} = \underbrace{\begin{bmatrix} \mathbb{I}_N & \mathbb{O}_N & \mathbf{Z}_{Coupling} & \mathbb{O}_N \\ \mathbb{O}_N & \mathbb{I}_N & \mathbb{O}_N & \mathbf{Z}_{BottomLid} \\ \mathbb{O}_N & \mathbb{O}_N & \mathbb{I}_N & \mathbb{O}_N \\ \mathbb{O}_N & \mathbb{O}_N & \mathbb{O}_N & \mathbb{I}_N \end{bmatrix}}_{\mathbf{A}_{BOTTOM}} \cdot \begin{bmatrix} \mathbf{V}'_C \\ \mathbf{V}'_D \\ -\mathbf{I}'_C \\ -\mathbf{I}'_D \end{bmatrix} \quad (5)$$

where $\mathbb{I}_N$ is the N -D identity matrix and $\mathbb{O}_N$ the N -D null matrix.

3) *Equivalent Impedance*: Once we have determined the ABCD matrices of the TSC bodies and of the lids, the ABCD matrix of the N TSC component is given by

$$\mathbf{A}_{NTSC} = \mathbf{A}_{TOP} \cdot \mathbf{A}_{BODIES} \cdot \mathbf{A}_{BOTTOM}. \quad (6)$$

Defining $\mathbf{Y}_{NTSC}$ such as $\mathbf{I}' = \mathbf{Y}_{NTSC} \cdot \mathbf{V}'$, one can obtain $\mathbf{Y}_{NTSC}$ from $\mathbf{A}_{NTSC}$ using the well-known circuit matrix conversion relations [11].

In order to connect the four sets of branches A, B, C, and D in parallel as shown in Fig. 4, one defines the incidence matrix $\mathbf{P}$

$$\mathbf{P} = \begin{bmatrix} 1 & \cdots & 1 & 0 & \cdots & \cdots & \cdots & 0 \\ 0 & \cdots & 0 & 1 & \cdots & 1 & 0 & \cdots & 0 \\ 0 & \cdots & \cdots & 0 & 1 & \cdots & 1 & 0 & \cdots & 0 \\ 0 & \cdots & \cdots & \cdots & \cdots & \cdots & 1 & \cdots & 1 \end{bmatrix}. \quad (7)$$

Kirchhoff's circuit laws at nodes A, B, C, and D imply $\mathbf{I}'' = \mathbf{P}\mathbf{I}'$ and $\mathbf{V}' = \mathbf{P}^T \mathbf{V}''$, with $\mathbf{P}^T$ the transpose of $\mathbf{P}$. Furthermore, defining the admittance matrix $\mathbf{Y}_R$ such as $\mathbf{I}'' = \mathbf{Y}_R \mathbf{V}''$, one can establish the following relation for the computation of $\mathbf{Y}_R$:

$$\mathbf{Y}_R = \mathbf{P} \cdot \mathbf{Y}_{NTSC} \cdot \mathbf{P}^T. \quad (8)$$

The elements of this resulting reduced matrix $\mathbf{Y}_R$ are then permuted in order to obtain the admittance $\tilde{\mathbf{Y}}_R$ defined between the points A and D. This permutation transforms the current vector $\mathbf{I}''$ into $\tilde{\mathbf{I}}''$ and the voltage vector $\mathbf{V}''$ into $\tilde{\mathbf{V}}''$

$$\mathbf{I}'' = \begin{bmatrix} I''_A \\ I''_B \\ I''_C \\ I''_D \end{bmatrix} \quad \mathbf{V}'' = \begin{bmatrix} V''_A \\ V''_B \\ V''_C \\ V''_D \end{bmatrix} \quad \tilde{\mathbf{I}}'' = \begin{bmatrix} I''_A \\ I''_D \\ I''_B \\ I''_C \end{bmatrix}$$

$$\tilde{\mathbf{V}}'' = \begin{bmatrix} V''_A \\ V''_D \\ V''_B \\ V''_C \end{bmatrix}. \quad (9)$$

Defining the permutation matrix $\mathbf{B}$ as

$$\mathbf{B} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \end{bmatrix} \quad (10)$$

Fig. 5. Radial TSC structural electrical model.

one can relate old and new currents and voltages by writing, respectively, $\tilde{\mathbf{I}}' = \mathbf{B} \cdot \mathbf{I}''$ and $\tilde{\mathbf{V}}' = \mathbf{B} \cdot \mathbf{V}''$. The admittance matrix becomes, after permutation

$$\tilde{\mathbf{Y}}_R = \mathbf{B} \cdot \mathbf{Y}_R \cdot \mathbf{B}^{-1}. \quad (11)$$

The matrix $\tilde{\mathbf{Y}}_R$ is then divided into four blocks (of dimension 2×2) $\tilde{\mathbf{Y}}_{R_I}$, $\tilde{\mathbf{Y}}_{R_{II}}$, $\tilde{\mathbf{Y}}_{R_{III}}$, and $\tilde{\mathbf{Y}}_{R_{IV}}$ as follows:

$$\tilde{\mathbf{Y}}_R = \begin{bmatrix} \tilde{Y}_{R_{11}} & \tilde{Y}_{R_{12}} & \tilde{Y}_{R_{13}} & \tilde{Y}_{R_{14}} \\ \tilde{Y}_{R_{21}} & \tilde{Y}_{R_{22}} & \tilde{Y}_{R_{23}} & \tilde{Y}_{R_{24}} \\ \tilde{Y}_{R_{31}} & \tilde{Y}_{R_{32}} & \tilde{Y}_{R_{33}} & \tilde{Y}_{R_{34}} \\ \tilde{Y}_{R_{41}} & \tilde{Y}_{R_{42}} & \tilde{Y}_{R_{43}} & \tilde{Y}_{R_{44}} \end{bmatrix} = \begin{bmatrix} \tilde{\mathbf{Y}}_{R_I} & \tilde{\mathbf{Y}}_{R_{II}} \\ \tilde{\mathbf{Y}}_{R_{III}} & \tilde{\mathbf{Y}}_{R_{IV}} \end{bmatrix}. \quad (12)$$

The (2×2) input impedance matrix $\mathbf{Z}_{in}$ defined between A and D is given by

$$\mathbf{Z}_{in} = (\tilde{\mathbf{Y}}_{R_I} - \tilde{\mathbf{Y}}_{R_{II}} \cdot \tilde{\mathbf{Y}}_{R_{IV}}^{-1} \cdot \tilde{\mathbf{Y}}_{R_{III}})^{-1}. \quad (13)$$

Finally, the equivalent scalar impedance Z_{eq} of the whole TSC matrix is the off-diagonal element of $\mathbf{Z}_{in}$

$$Z_{eq} = Z_{in_{12}}. \quad (14)$$

B. Radial TSC

Considering a matrix of radial TSCs, one can describe the one-port capacitive component as two parallel metallic conductors on the top side of the interposer, named lids, separated by a very thin dielectric layer on which the coaxial bodies of the TSCs are connected in parallel. The bottom end of the coaxial bodies consists in capacitive bases. Fig. 5 presents the structural equivalent electrical circuit of such devices.

The principle of the modeling method for radial TSC is to determine the admittance matrix of the whole set of bases (see Section III-B.1) and to compute the resulting input admittance matrix of the device, stage after stage (coaxial bodies in Section III-B.2, then lids in Section III-B.3). Each segment is then considered as coupled distributed cells analog to coupled transmission lines, and a matrix formula derived from [10] is proposed. In the following development, the notations are the ones presented in Fig. 5.

1) *TSC Bases Contribution:* For the considered components, an analytic formulation of the admittance of the back side of the TSCs has turned out to be sufficient. Considering the real permittivity ϵ' and the conductivity σ of the dielectric material, the equivalent admittance $\mathbf{Y} = \mathbf{I}\mathbf{V}^{-1}$ of the back side of a single TSC can be written as

$$\mathbf{Y} = j\omega \frac{(\epsilon' - j\frac{\sigma}{\omega})S}{t} \mathbb{I}_N \quad (15)$$

where S is the surface of parallel metallic plates of the back side, t the distance between them, and $\mathbb{I}_N$ the identity matrix of dimension $N \times N$.

2) *TSC Coaxial Bodies Contribution:* The coaxial bodies can be considered as (weakly) coupled coaxial lines in the case of radial TSC because the inner conductor and the outer conductor are flowed by opposite currents. Their contribution, the primary matrix parameters of coupled lines $(\mathbf{R}, \mathbf{L}, \mathbf{C}, \mathbf{G})$, can thus be easily computed with a 2-D electromagnetic solver, which is very computing-time effective. One then defines the “magnetic” impedance matrix $\mathbf{Z}_M^{bodies}$ and the “electrical” admittance matrix $\mathbf{Y}_E^{bodies}$ as follows:

$$\mathbf{Z}_M^{bodies} = \mathbf{R}l + j\omega \mathbf{L}l \quad (16)$$

$$\mathbf{Y}_E^{bodies} = \mathbf{G}l + j\omega \mathbf{C}l \quad (17)$$

thus allowing the computation of the input admittance matrix $\mathbf{Y}' = \mathbf{I}'\mathbf{V}'^{-1}$

$$\mathbf{\Gamma}^{bodies} = \text{sqrtrm}(\mathbf{Y}_E^{bodies} \cdot \mathbf{Z}_M^{bodies}) \quad (18)$$

$$\mathbf{Z}_C^{bodies} = \text{sqrtrm}(\mathbf{Y}_E^{bodies^{-1}} \cdot \mathbf{Z}_M^{bodies}) \quad (19)$$

$$\mathbf{Y}' = \left[\sinhm(\mathbf{\Gamma}^{bodies}) \cdot \mathbf{Z}_C^{bodies^{-1}} \cdot \mathbf{Y}^{-1} + \coshm(\mathbf{\Gamma}^{bodies}) \right] \cdot \left[\mathbf{Y}_E^{bodies^{-1}} \cdot \coshm(\mathbf{\Gamma}^{bodies}) \mathbf{Y}_E^{bodies} \cdot \mathbf{Y}^{-1} + \mathbf{Z}_C^{bodies} \cdot \sinhm(\mathbf{\Gamma}^{bodies}) \right]^{-1}. \quad (20)$$

The previous formula has been derived from [10].

3) *Lids Contribution:* Since the number of TSCs connected in parallel by the two lids can reach several thousands, very special care has to be taken of the computation of the contribution of that stage. The classical full-wave approach leads to prohibitive computing time or even unsolvable problems, and simulations must be performed with quasi-static solvers.

Fig. 6. Illustration of impedance matrix reduction from raw simulation results.

The lids have been modeled with Ansys Q3D quasi-static 3-D electromagnetic solver. In this approach, magnetic and electrical fields are computed separately, and the proposed method provides the following:

- 1) a $2N \times 2N$ “magnetic impedance matrix” $\mathbf{Z}_M^{\text{lidsimu}}$ that corresponds to the impedance of the lids from the contact points to the $2N$ conductors of the TSC (N inner and N outer);
- 2) a 2×2 “electrical admittance matrix” $\mathbf{Y}_E^{\text{lidsimu}}$ that corresponds to the admittance between the two lids.

The raw simulation matrix $\mathbf{Z}_M^{\text{lidsimu}}$ (of size $2N \times 2N$) must be reduced to $\mathbf{Z}_M^{\text{lids}}$ (of size $N \times N$) thanks to the following relation (illustrated in Fig. 6):

$$\forall i, j \in \{1, \dots, N\}$$

$$\mathbf{Z}_{Mij}^{\text{lids}} = \mathbf{Z}_{(2i-1)(2j-1)}^{\text{lidsimu}} + \mathbf{Z}_{(2i)(2j)}^{\text{lidsimu}} - \mathbf{Z}_{(2i-1)(2j)}^{\text{lidsimu}} - \mathbf{Z}_{(2i)(2j-1)}^{\text{lidsimu}}. \quad (21)$$

The raw admittance matrix $\mathbf{Y}_E^{\text{lidsimu}}$ (of size 2×2) must be reduced, assuming that the computed coupling admittance between the two lid plates can be evenly distributed among all TSC contact points. As there are N TSCs, an $N \times N$ admittance matrix $\mathbf{Y}_E^{\text{lids}}$ is built. Furthermore, since the two metallic plates are very close one from another, the N subparts are supposed to be in total influence. $\mathbf{Y}_E^{\text{lids}}$ is thus a diagonal matrix with equal diagonal coefficients

$$\mathbf{Y}_E^{\text{lids}} = -\frac{\mathbf{Y}_{E12}^{\text{lidsimu}} + \mathbf{Y}_{E21}^{\text{lidsimu}}}{2N} \mathbf{I}_N. \quad (22)$$

Given $\mathbf{Z}_M^{\text{lids}}$ and $\mathbf{Y}_E^{\text{lids}}$, one can compute the input admittance $\mathbf{Y}'' = \mathbf{I}'' \mathbf{V}''^{-1}$ as follows:

$$\mathbf{\Gamma}^{\text{lids}} = \text{sqrtn}(\mathbf{Y}_E^{\text{lids}} \mathbf{Z}_M^{\text{lids}}) \quad (23)$$

$$\mathbf{Z}_C^{\text{lids}} = \text{sqrtn}(\mathbf{Y}_E^{\text{lids}} \mathbf{Z}_M^{\text{lids}}) \quad (24)$$

$$\mathbf{Y}'' = \left[\sinhm(\mathbf{\Gamma}^{\text{lids}}) \cdot \mathbf{Z}_C^{\text{lids}} \cdot \mathbf{Y}'^{-1} + \coshm(\mathbf{\Gamma}^{\text{lids}}) \right] \cdot \left[\mathbf{Y}_E^{\text{lids}} \cdot \coshm(\mathbf{\Gamma}^{\text{lids}}) \cdot \mathbf{Y}_E^{\text{lids}} \cdot \mathbf{Y}'^{-1} + \mathbf{Z}_C^{\text{lids}} \cdot \sinhm(\mathbf{\Gamma}^{\text{lids}}) \right]^{-1}. \quad (25)$$

4) *Equivalent Impedance*: At this step, all the ports of the lids input plane are connected together in parallel. One defines the incidence matrix $\mathbf{P}$

$$\mathbf{P} = \begin{bmatrix} 1 & \dots & 1 \end{bmatrix} \quad (26)$$

Fig. 7. (a) Cross section of measured radial TSC devices. (b) Equivalent electrical circuit.

Fig. 8. Measured and modeled impedance response of radial TSC components.

and the equivalent scalar impedance of the whole system $\mathbf{Z}_{\text{eq}} = \mathbf{V}''' \cdot \mathbf{I}'''^{-1}$ can finally be written as

$$\mathbf{Z}_{\text{eq}} = (\mathbf{P} \cdot \mathbf{Y}'' \cdot \mathbf{P}^T)^{-1}. \quad (27)$$

5) *Experimental Validation*: The previously presented modeling method for radial TSC has been experimentally validated by measurements from 1 kHz to 40 GHz. Large matrices of radial TSC ($N > 100$ TSCs) realized with a first generation of MIM stack (TiN 200 nm/ Al_2O_3 20 nm/TiN 200 nm) had been measured and modeled in [12]. New prototypes realized with a second generation of MIM stack (TiN 80 nm/ Ta_2O_5 40 nm/TiN 80 nm/Cu 1.5 μm) have been realized and measured [13]. A cross section of such components is presented in Fig. 7.

The components have been characterized from 1 kHz to 110 MHz using Agilent 4294A impedance analyzer and from 10 MHz to 40 GHz with Agilent N5247A PNA-X vector network analyzer. Fig. 8 shows measurement and modeling results of two small components with 1 and 8 TSCs presented as equivalent parallel capacitance $C_p = \text{imag}(\mathbf{Z}(f)^{-1}/2\pi f)$ and conductance $G_p(f) = \text{real}(\mathbf{Z}(f)^{-1})$.

The low-frequency part of $C_p(f)$ gives the capacitance of the component. A first cutoff frequency occurs at 100 kHz

Fig. 9. Four studied configurations of TSC: axial or radial structure and side or equipotential excitation.

due to a high equivalent serial resistance (ESR). The lack of copper layer in the bottom electrode of the measured prototypes is responsible for this performance limitation. Indeed, in that generation of components, only low-conductivity TiN ($\sigma_{\text{TiN}} = 460 \text{ kS} \cdot \text{m}^{-1}$) has been deposited. However, the final components, including copper in each electrode stack, will be drastically enhanced. C_p and G_p curves show very good agreement between models and measurements on the whole frequency range, except the underestimation of C_p in midrange frequency, which is attributed to the not-well-known resistivity of TiN inside the TSC bodies ([9] presents the technological process and describes the nonconformal densification process of TiN, resulting in an inhomogeneous electrical conductivity). These measurements validate the modeling method for the taking into account of electromagnetics effects in the TSC components.

IV. COMPARATIVE STUDY OF TSC ARCHITECTURES

The two modeling methods presented in Section III have been used to perform simulations of realistic, application-oriented components. The objective of this paper is to point out clear design rules based on electrical performance optimization. The designer will then have to make tradeoffs between electrical performances and technological feasibility. One has considered four integration possibilities for TSC components that are presented in Fig. 9. They are a combination of: 1) axial or radial architecture, and 2) side or equipotential excitation.

For each of the four cases, matrices of 64 and 100 TSCs have been modeled, leading to 8 comparable frequency responses. The MIM stack consists in a 40-nm-thick Ta_2O_5 layer between copper electrodes. In axial TSC architecture, the front-side metal 1 (M1) layer is 150 nm thick, and the back-side redistribution layer is 7 μm thick. In radial

Fig. 10. Simulated impedance magnitude frequency response of 64 TSC.

Fig. 11. Simulated impedance magnitude frequency response of 100 TSC.

TABLE I
ELECTRICAL DATA OF RADIAL EQUIPOTENTIAL TSC COMPONENTS

Number of TSC (N)	Surface [μm^2]	Capacitance [pF]	Capacitance density [nF/mm^2]	ESR [m Ω]	ESR*N [m Ω]	ESL [fH]	ESL*N [pH]	SRF [GHz]
1	285	11.8	41.4	296	296	1349	1349	39.9
2	623	23.6	37.9	147	294	672	1344	39.9
64	22842	730	31.9	4.50	288	20	1280	39.7
100	35765	1180	33.0	2.92	292	13.5	1350	39.6
256	90506	3008	33.2	1.14	292	5.1	1305	39.6
400	141138	4689	33.2	0.73	292	3.4	1360	39.6

architectures, M1 and M2 are, respectively, 150 and 340 nm thick. Each 64 TSC component is 730 pF for 0.022 mm^2 , and each 100 TSC component is 1.18 nF for 0.035 mm^2 . These values correspond to a 33–34 nF/mm^2 capacitance density in both cases. As demonstrated in [5], the maximum capacitance density obtainable with planar MIM capacitors for PDN decoupling capacitors, considering the breakdown voltage and the dielectric permittivity of available materials, is also 30 nF/mm^2 , which is comparable to the performances of the TSC presented in this paper.

Figs. 10 and 11, respectively, plot the impedance magnitude responses of 64 and 100 TSC matrices.

Radial architectures provide a one-decade-higher SRF compared to axial architectures, whether the excitation is on side or equipotential. This result is due to the coaxial configuration of the radial architecture that minimizes the overall

inductance on the current path, thus reducing the equivalent serial inductance (ESL) and then increasing the SRF. As the maximum decoupling frequency strongly depends on a high SRF, radial architectures should be preferred for applications around 4 GHz and higher.

The equipotential excitation is also preferable over the side excitation because the current path in lids is reduced, leading to the reduction of the ESL and of the ESR. The impact of ESL reduction is more visible on the radial architecture because the coaxial bodies have a little contribution. In that case, the SRF is increased by almost another decade.

Finally, the comparative study leads to the election of the radial architecture with equipotential excitation as the best candidate decoupling capacitors integration with TSC. The radial architecture with equipotential excitation has then been further investigated. Matrices of 1, 2, 64, 100, 256, and 400 TSCs have been modeled, and electrical data have been extracted and are reported in Table I.

The mean capacitance density is about 35 nF/mm². This value is a good middle point between planar MIM capacitors (around 5 nF/mm² [14]) and optimized double trench capacitors (which can reach several hundred nF/mm² [15], [16]). The main advantage of this technology is then the cointegration of high-value capacitors with the standard TSV process in interposers.

The ESR and ESL values multiplied by the number N of TSCs are almost constant values, indicating that the coaxial bodies are responsible for them: As all coaxial bodies are connected in parallel, ESR and ESL are inversely proportional to N . In the case of $N = 400$ TSCs, the ESR is 0.73 m Ω and the ESL is 3.4 fH, for a capacitance of 4.6 nF. The low ESR value has been enabled by the use of thick copper electrodes, while the radial topology allows low ESL. Finally, the SRF is almost a constant value of 39 GHz, which is due to the inverse proportionality relationship between the capacitance value C and the ESL (as N increases, C increases and ESL decreases). This high-value SRF even for large matrices of TSC is also a promising result for TSC integration.

V. CONCLUSION

Two powerful predictive modeling methods for axial and radial architectures of TSC have been proposed and validated. Measurements of radial TSC have been reported on Ta₂O₅ radial components, and simulations of various TSC configurations, with axial or radial architecture, with side or equipotential excitation of the electrodes and with up to 400 TSC have been performed. The final comparative study concludes to the election of radial architecture with equipotential excitation for TSC components integration. The electrical performances of the modeled components are very promising for decoupling applications in power delivery networks.

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