



On the dimensionless parameters governing some extended Bagnold models

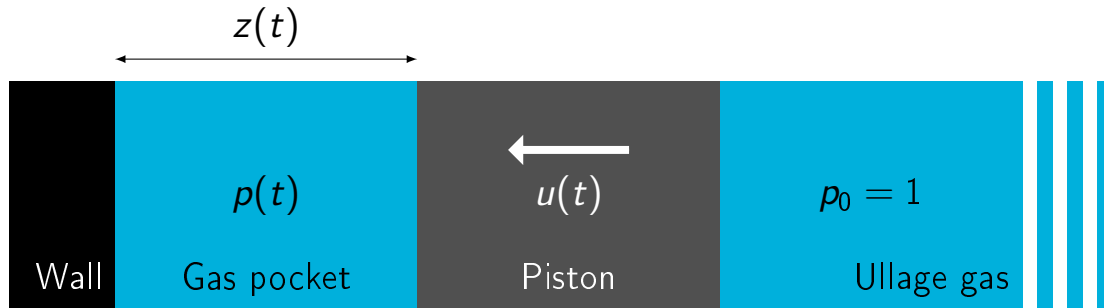
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with **Laurent Brosset** and **Jean-Michel Ghidaglia**

International Workshop on [...] Multiphase Flows, Cachan

16th October 2017

Bagnold model



► Dimensionless Bagnold ODE model

$$\frac{d^2 z}{dt^2} = p - 1, \quad p = z^{-\gamma},$$
$$z(0) = 1, \quad \left. \frac{dz}{dt} \right|_{t=0} = \pm \sqrt{S}.$$

Dimensionless parameters

Impact number S

Violence of the impact.

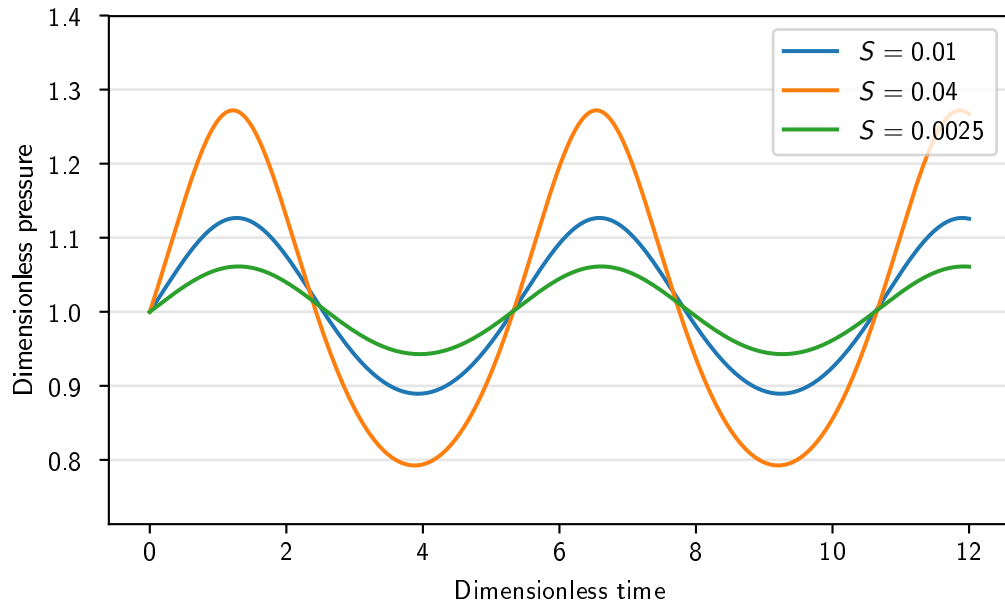
$$S = \frac{\text{Kinetic energy of piston}}{\text{Internal energy of the gas}}$$

Gas adiabatic index γ

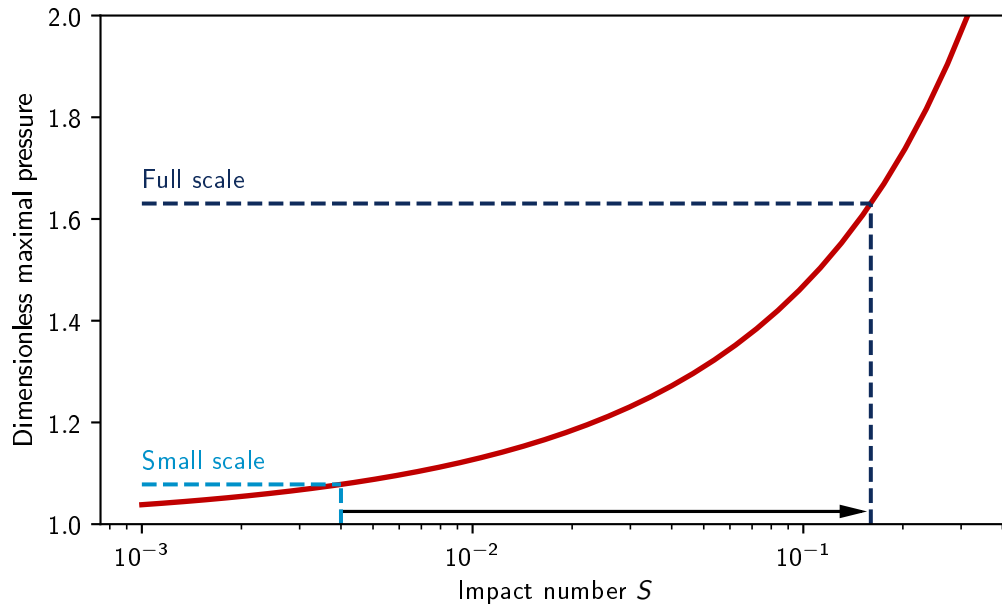
Compressibility of the gas.

(Not discussed here.)

Pressure evolution



Maximal pressure



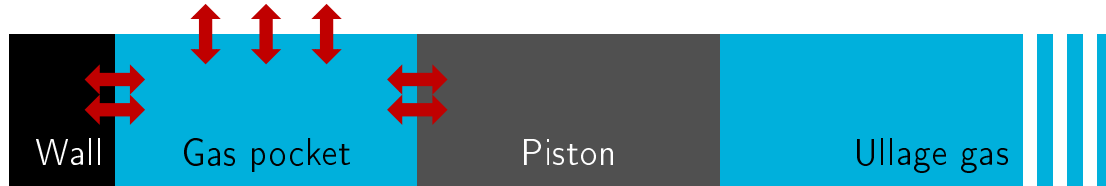
Objectives

- ▶ **Influence of phase change on maximal pressure?**
 - ▶ Experimental results predict damping of the oscillations [Maillard and Brosset 2009].
 - ▶ Extended Bagnold model proposed in [Ancellin, Brosset, and Ghidaglia 2012]
- ▶ **What role do the parameters of the model play?**
- ▶ **Content of this presentation:**
 1. Extended Bagnold model with heat exchange
 2. Extended Bagnold model with mass exchange through a porous wall
 3. Extended Bagnold model with phase change (mass and energy exchange)

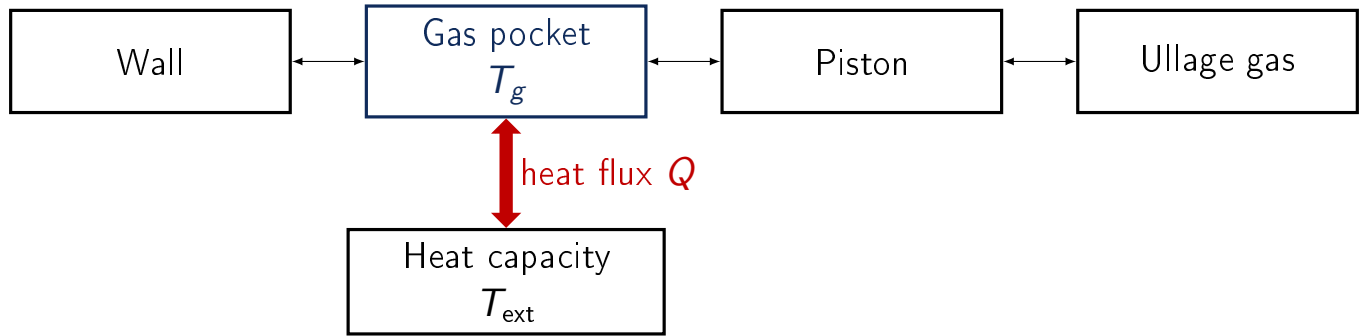


Heat exchange

Extending the Bagnold model



Extending the Bagnold model



Classical heat flux:

$$Q \propto T_{\text{ext}} - T_g,$$

Chosen to respect the second law of thermodynamics:

$$\frac{dS^{\text{created}}}{dt} = Q \frac{T_{\text{ext}} - T_g}{T_{\text{ext}} T_g} \geq 0.$$

Heat exchange model

ODE system:

$$\frac{d^2 z}{dt^2} = p - 1,$$

$$\frac{d\mathcal{E}_g}{dt} = +\Omega_q(T_{\text{ext}} - T_g) - p \frac{dz}{dt},$$

$$\frac{d\mathcal{E}_{\text{ext}}}{dt} = -\Omega_q(T_{\text{ext}} - T_g),$$

Equations of state:

$$p = \frac{T_g}{z},$$

$$T_g = 1 + \mathcal{E}_g(\gamma - 1),$$

$$T_{\text{ext}} = 1 + \frac{\mathcal{E}_{\text{ext}}}{\mathfrak{C}_{\text{ext}}},$$

Initial conditions:

$$z(0) = 1, \quad \frac{dz}{dt}(0) = \pm\sqrt{S}, \quad T_g(0) = 1, \quad T_{\text{ext}}(0) = 1.$$

Dimensionless parameters

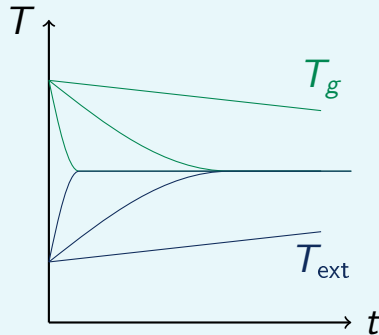
Impact number S

Gas adiabatic index γ

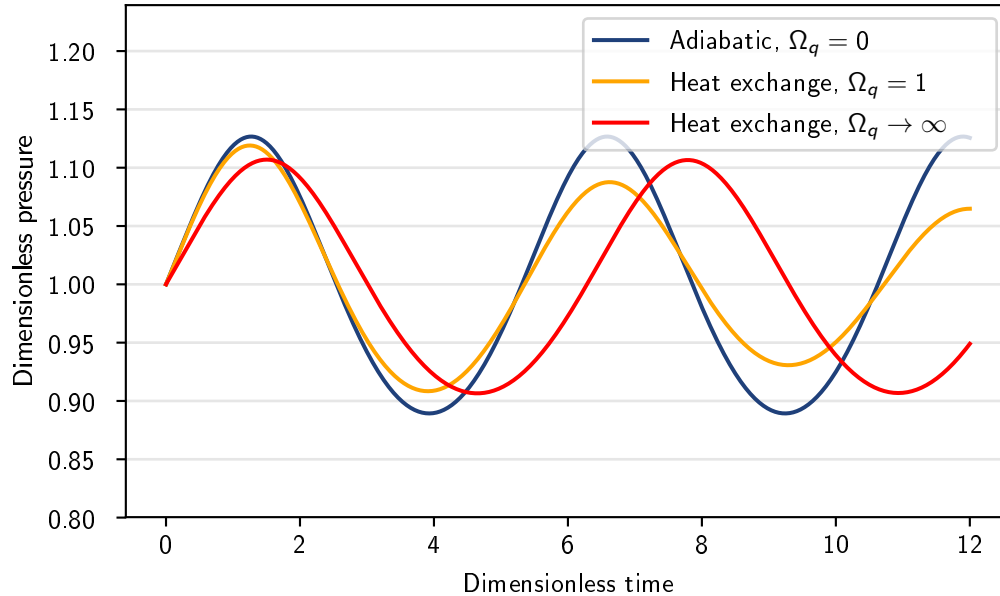
Relaxation rate Ω_q

Thermal inertia \mathcal{C}_{ext}

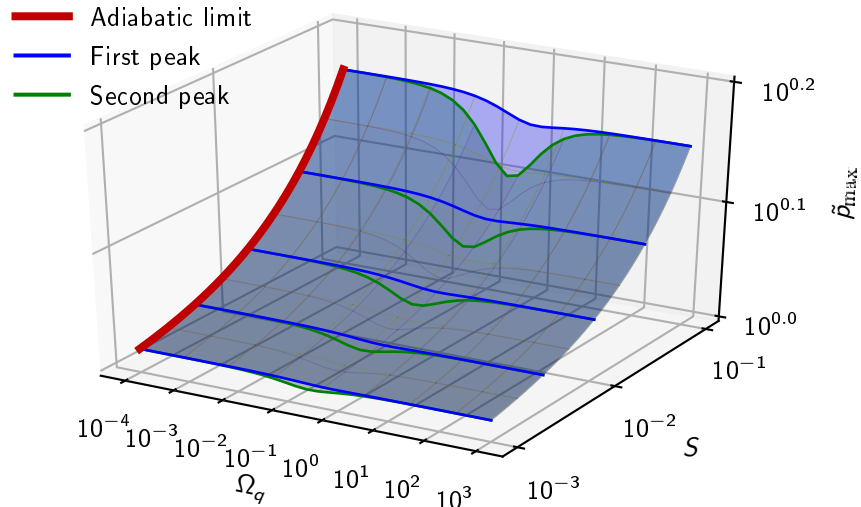
How fast do the temperatures reach equilibrium?
(with respect to the piston oscillations)



Pressure evolution



Maximal pressure



Dimensionless parameters

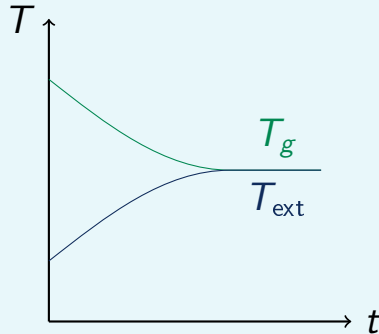
Impact number S

Gas adiabatic index γ

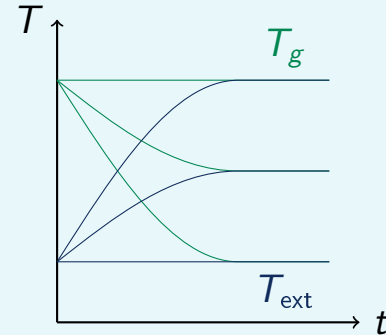
Relaxation rate Ω_q

Thermal inertia \mathcal{C}_{ext}

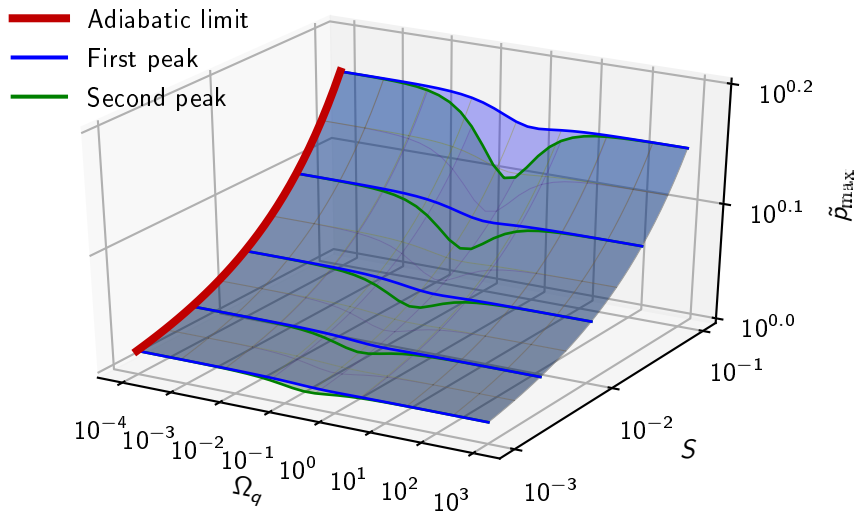
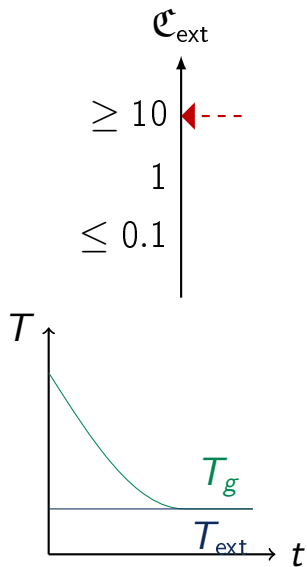
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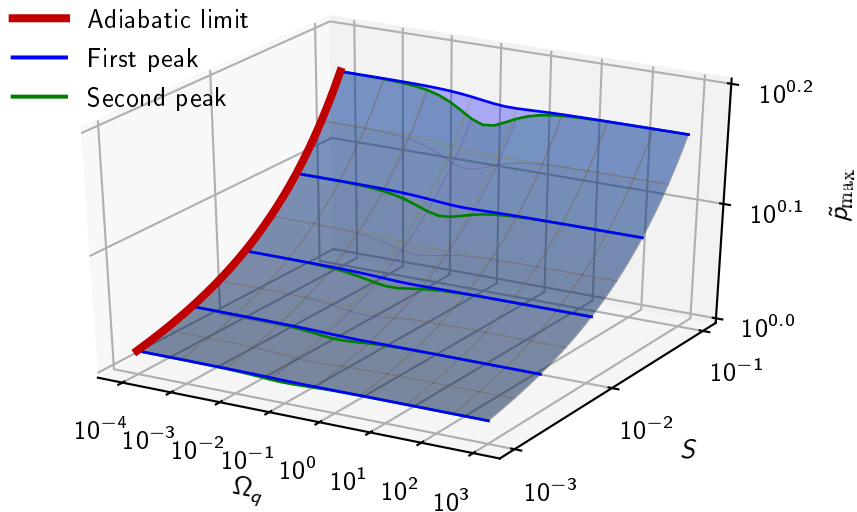
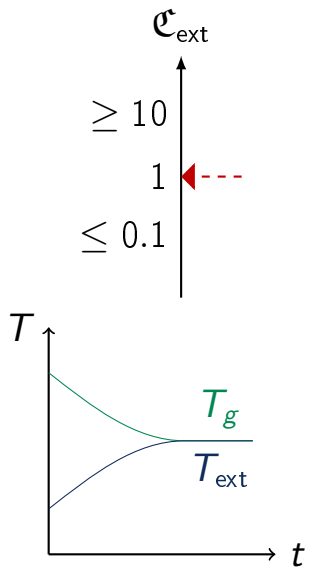
How hard is it to change T_{ext} ?
(with respect to changing T_g)



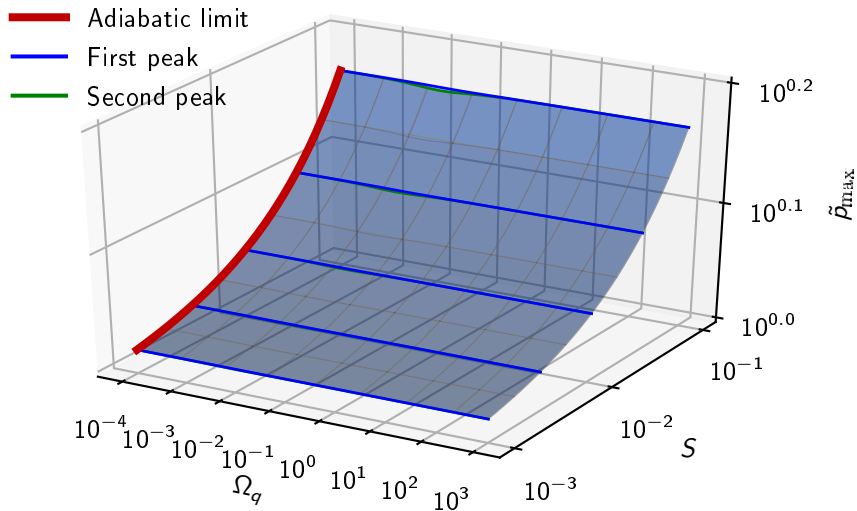
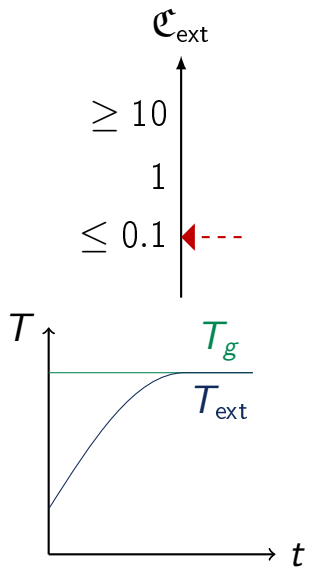
Maximal pressure



Maximal pressure

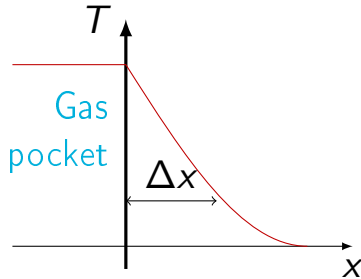


Maximal pressure



Estimating $\mathfrak{C}_{\text{ext}}$

- Penetration depth of heat equation during Δt .



$$\Delta x \simeq \sqrt{\frac{k_{\text{ext}}}{\rho_{\text{ext}} C_{v,\text{ext}}} \Delta t}$$

$$\mathfrak{C}_{\text{ext}} \simeq \frac{\sqrt{\Delta t}}{z_0} \times 10^{-2} \text{ m s}^{-1}$$

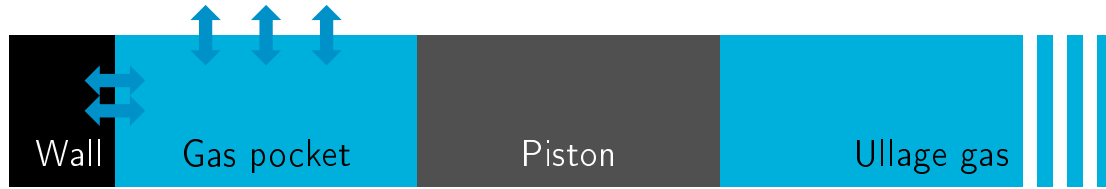
- For macroscopic ($z_0 > 10^{-2} \text{ m}$) gas pocket

$$\mathfrak{C}_{\text{ext}} < 10^{-4}.$$

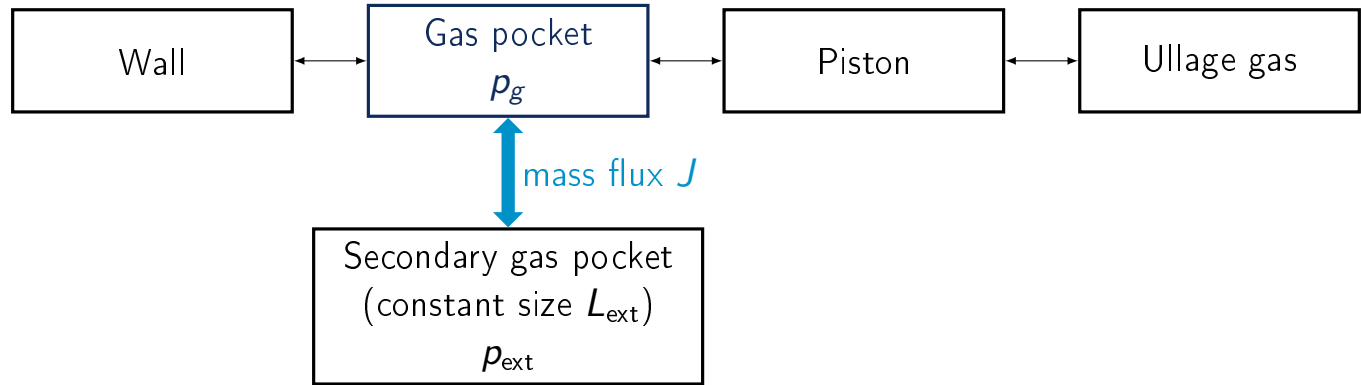


Mass exchange through porous wall

Porous wall model and mass flux



Porous wall model and mass flux



Mass flow rate at the porous wall:

$$J \propto p_{\text{ext}} - p.$$

Mass exchange model

ODE system

$$\begin{aligned}\frac{d^2 z}{dt^2} &= p_g - 1, \\ \frac{dM_g}{dt} &= -\Omega_p(p_g - p_{\text{ext}}), \\ \frac{dM_{\text{ext}}}{dt} &= +\Omega_p(p_g - p_{\text{ext}}),\end{aligned}$$

Equations of state

$$\begin{aligned}p_g &= \left(\frac{M_g}{z}\right)^\gamma \\ p_{\text{ext}} &= \left(\frac{M_{\text{ext}}}{L_{\text{ext}}}\right)^\gamma\end{aligned}$$

Initial conditions

$$z(0) = 1, \quad \frac{dz}{dt}(0) = \pm\sqrt{S}, \quad p_g(0) = 1, \quad p_{\text{ext}}(0) = 1.$$

Dimensionless parameters

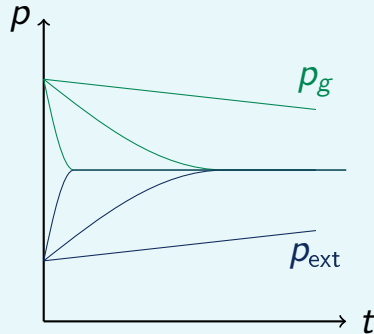
Impact number S

Gas adiabatic index γ

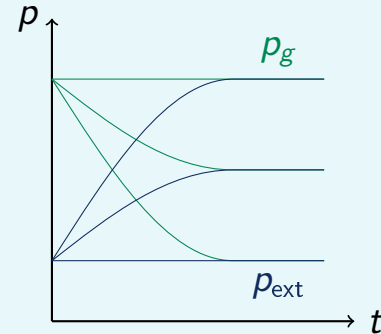
Relaxation rate Ω_p

Size of the secondary pocket L_{ext}

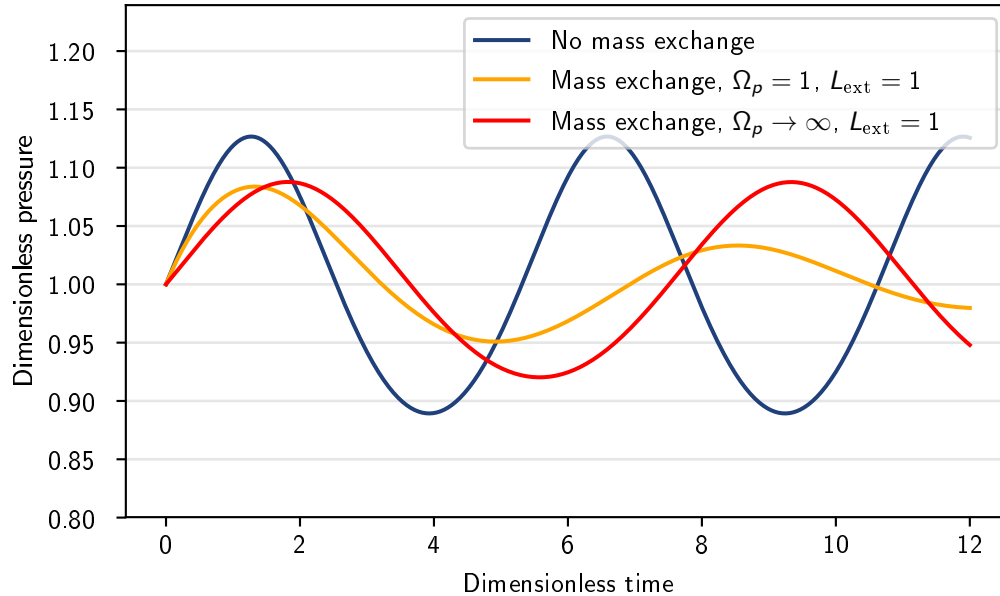
How fast do the pressures reach equilibrium?
(with respect to the piston oscillations)



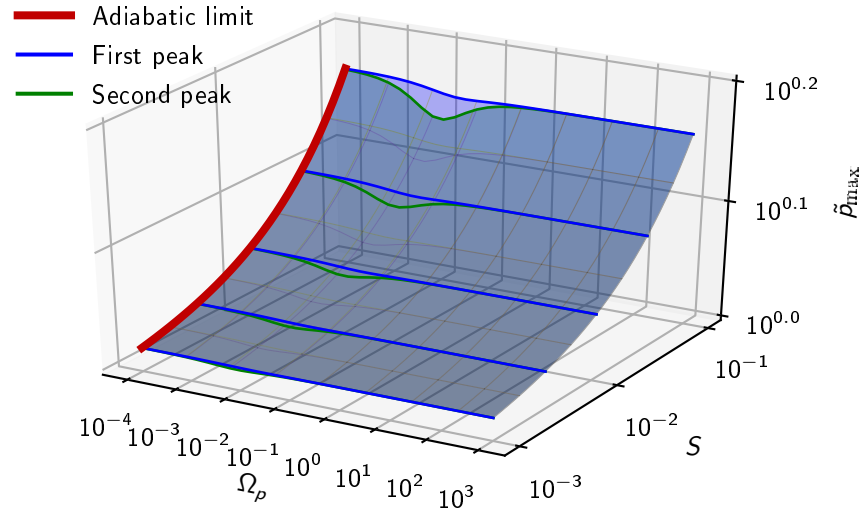
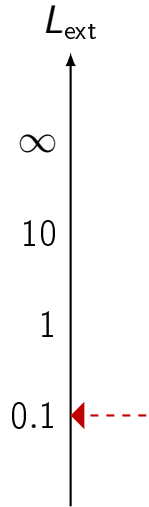
How hard is it to change p_{ext} ?
(with respect to changing p_g)



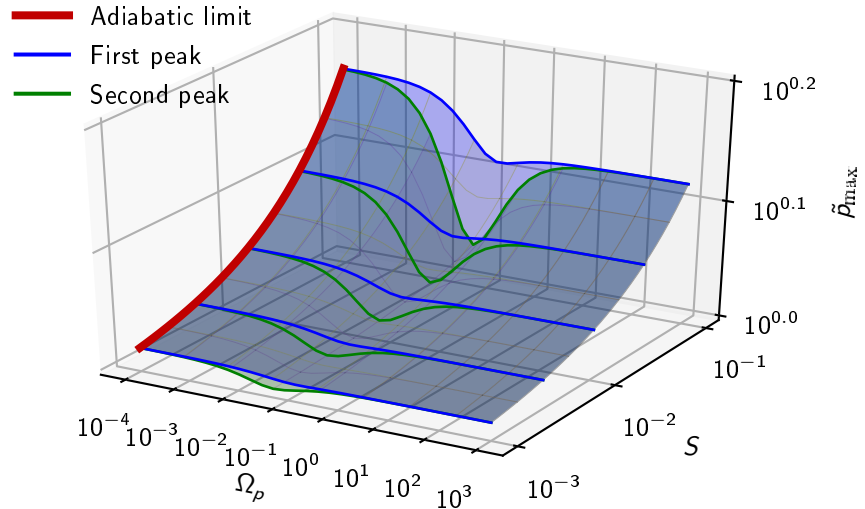
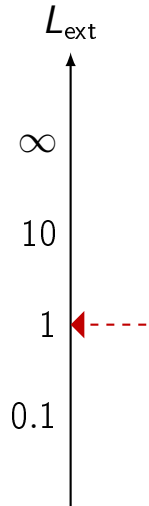
Pressure evolution



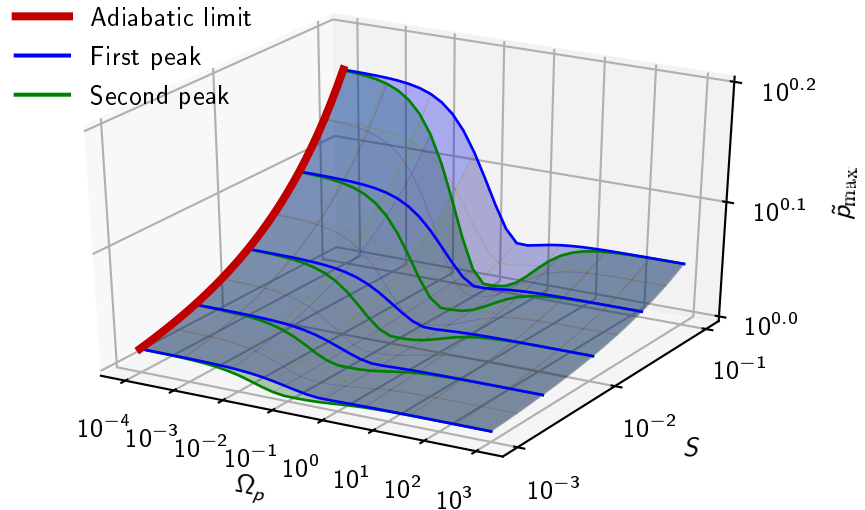
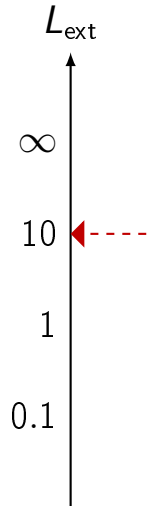
Maximal pressure



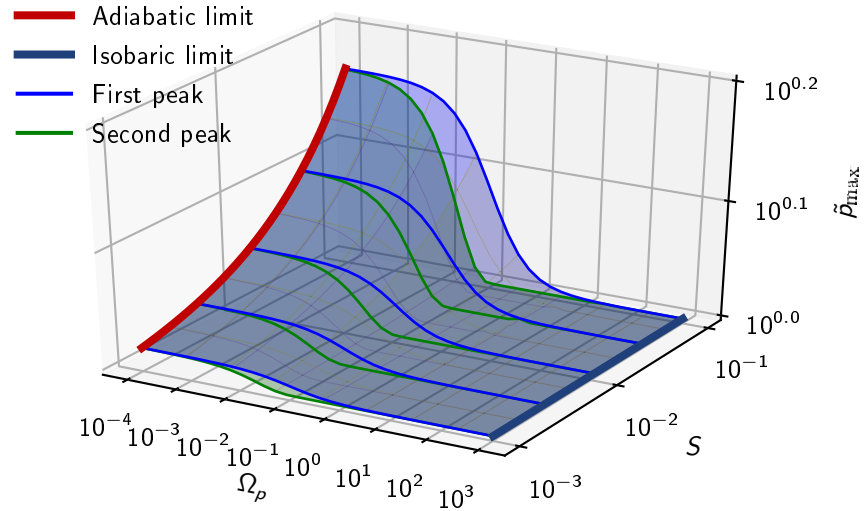
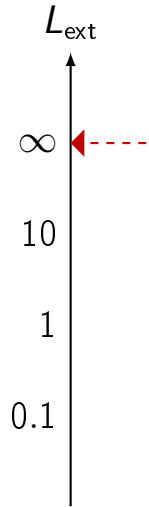
Maximal pressure



Maximal pressure



Maximal pressure



Partial conclusion

- ▶ **Not a model for gas escape before the impact...**
 - ▶ Not very well suited for the incompressible part of the gas escape.
- ▶ **... but a minimal example of phase change modelling.**

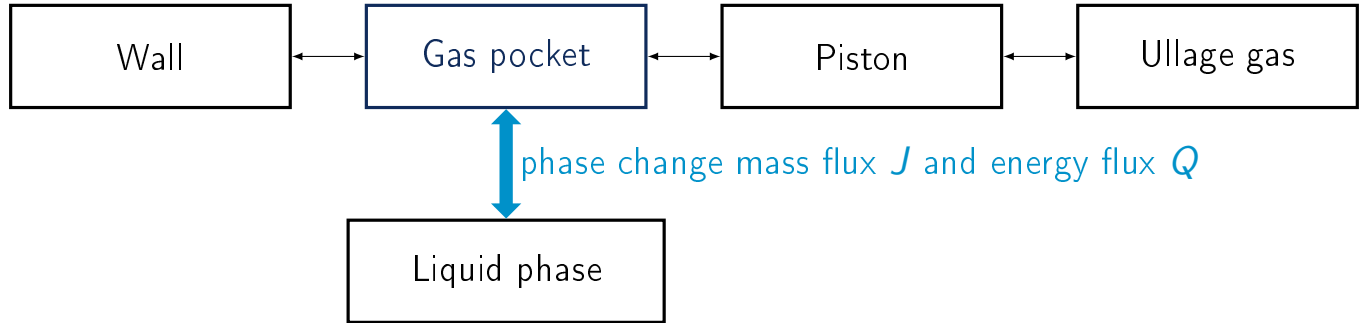


Phase change (mass and energy exchanges)

Extending Bagnold model



Extending Bagnold model



Second law of thermodynamics:

$$\frac{dS^{\text{created}}}{dt} = \left(\frac{1}{T_g} - \frac{1}{T_l} \right) (Q - h_g J) + \left(\frac{\mu_l(T_l) - \mu_g(T_l)}{T_l} \right) J,$$

Energy and mass flow:

$$Q = h_g J, \quad J \propto \frac{\mu_l(T_l) - \mu_g(T_l)}{T_l} \propto p^{\text{sat}}(T_l) - p$$

Model with phase change

ODE system

$$\begin{aligned}\frac{d^2 z}{dt^2} &= p - 1, \\ \frac{d\mathcal{E}_g}{dt} &= +h_g \frac{dM_g}{dt} - p \frac{dz}{dt}, \\ \frac{d\mathcal{E}_\ell}{dt} &= -h_g \frac{dM_g}{dt}, \\ \frac{dM_g}{dt} &= +\Omega_m(p^{\text{sat}}(T_\ell) - p), \\ \frac{dM_\ell}{dt} &= -\frac{1}{\mathfrak{M}_{\ell,0}} \Omega_m(p^{\text{sat}}(T_\ell) - p),\end{aligned}$$

Equations of state

$$\begin{aligned}p &= \frac{M_g}{z} T_g, & h_g &= \frac{\mathcal{E}_g + pz}{M_g}, \\ p^{\text{sat}}(T) &= \exp\left(\Lambda\left(1 - \frac{1}{T}\right)\right), \\ T_g &= 1 + \left(\frac{\mathcal{E}_g}{M_g} - \Lambda + 1\right)(\gamma - 1), \\ T_\ell &= 1 + \frac{\mathcal{E}_\ell}{M_\ell \mathfrak{C}_\ell},\end{aligned}$$

Initial conditions

$$z(0) = 1, \quad \frac{dz}{dt}(0) = \pm\sqrt{S}, \quad T_g(0) = 1, \quad T_\ell(0) = 1, \quad M_g(0) = 1, \quad M_\ell(0) = 1.$$

Dimensionless parameters

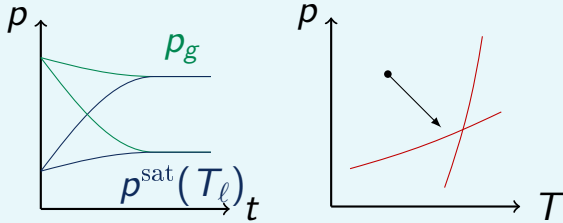
Impact number S

Relaxation rate Ω_m

Do you really want me to explain it again?

Dimensionless latent heat Λ

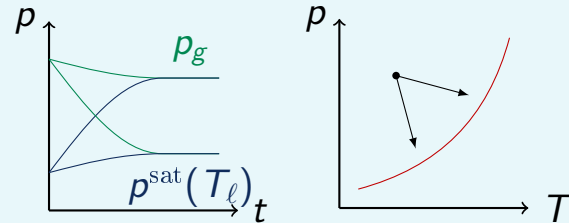
How hard is it to change p^{sat} ?
(with respect to p_g and T_g)



Gas adiabatic index γ

Thermal inertia of the liquid \mathfrak{C}_ℓ

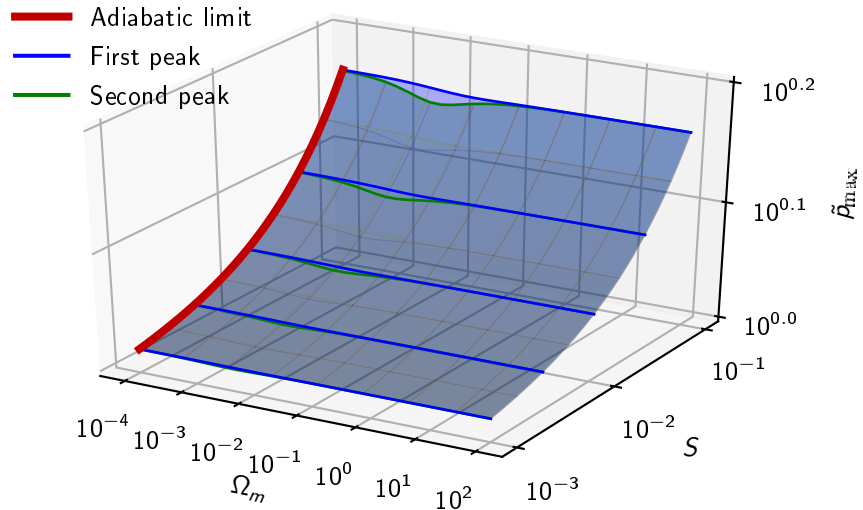
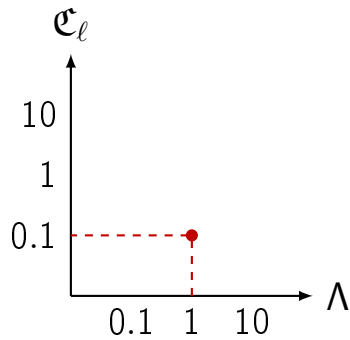
How hard is it to change T_ℓ ?
(with respect to p_g and T_g)



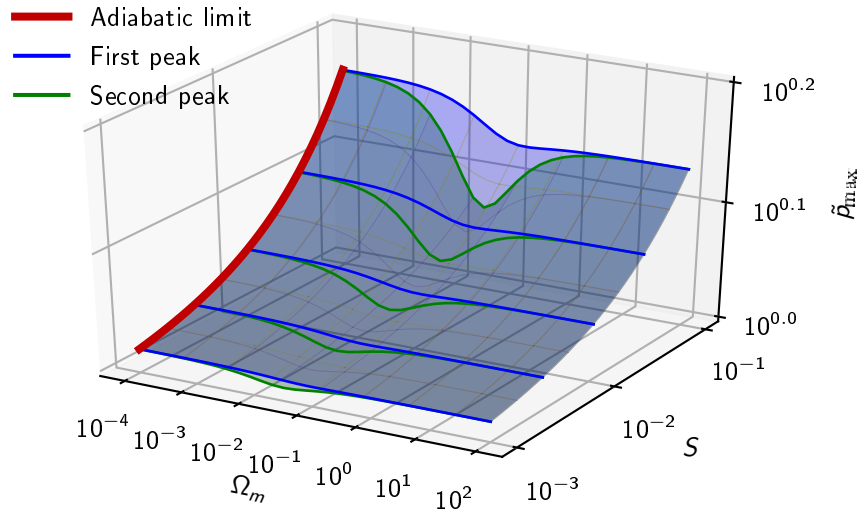
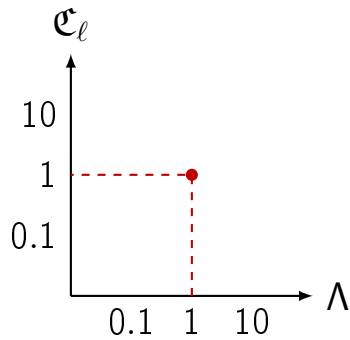
Dimensionless mass of liquid $\mathfrak{M}_{l,0}$

Variation of \mathfrak{C}_ℓ due to mass exchange.

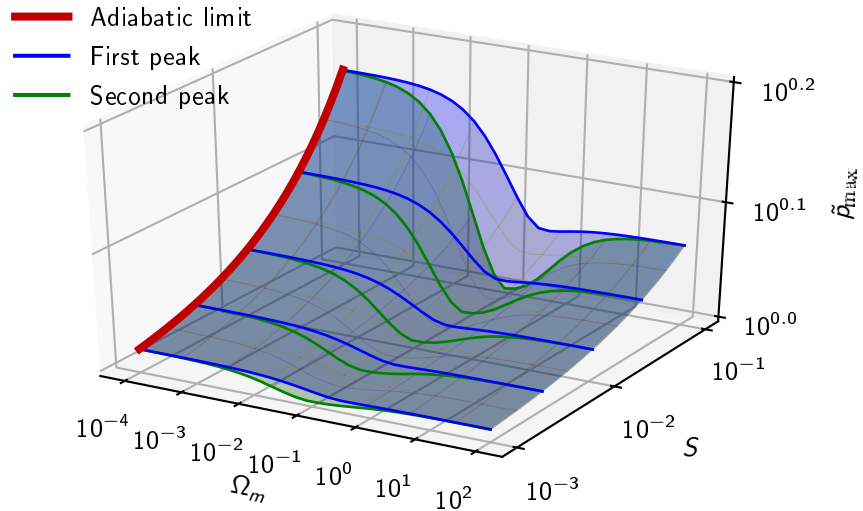
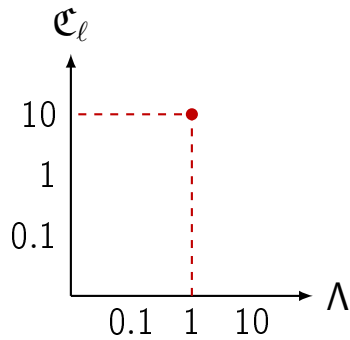
Maximal pressure



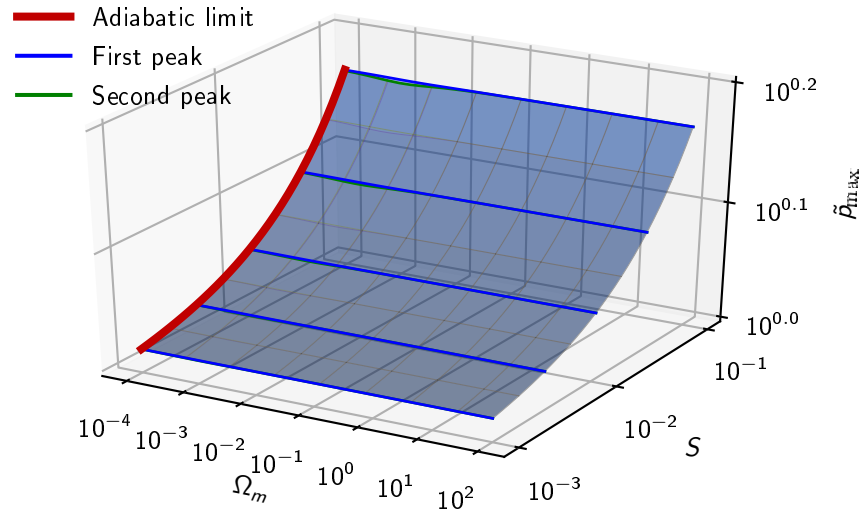
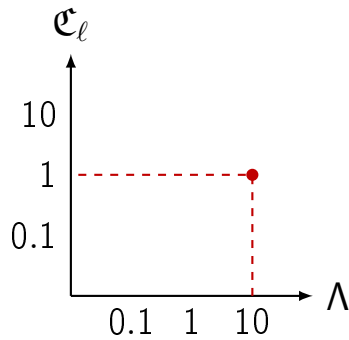
Maximal pressure



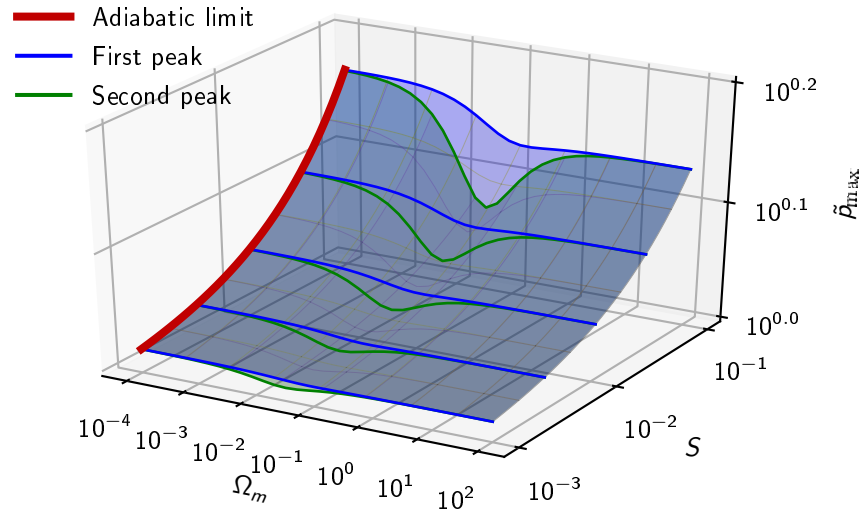
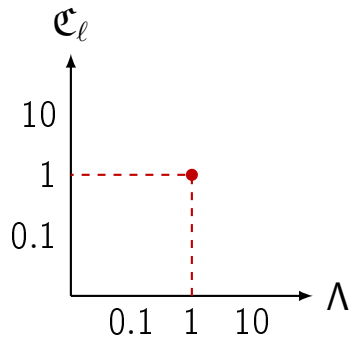
Maximal pressure



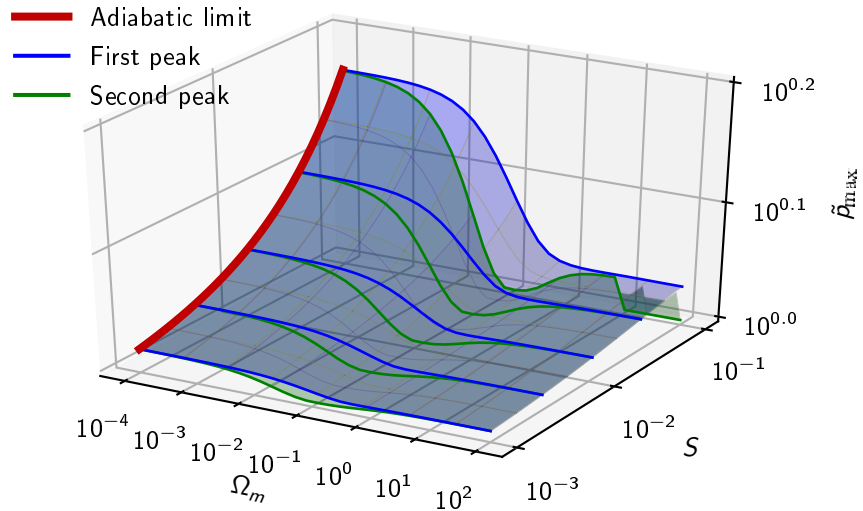
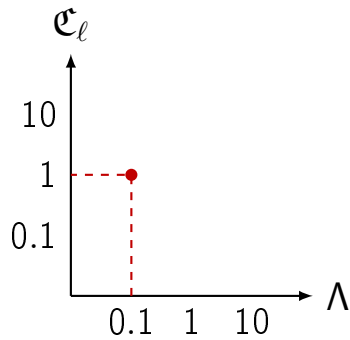
Maximal pressure



Maximal pressure



Maximal pressure



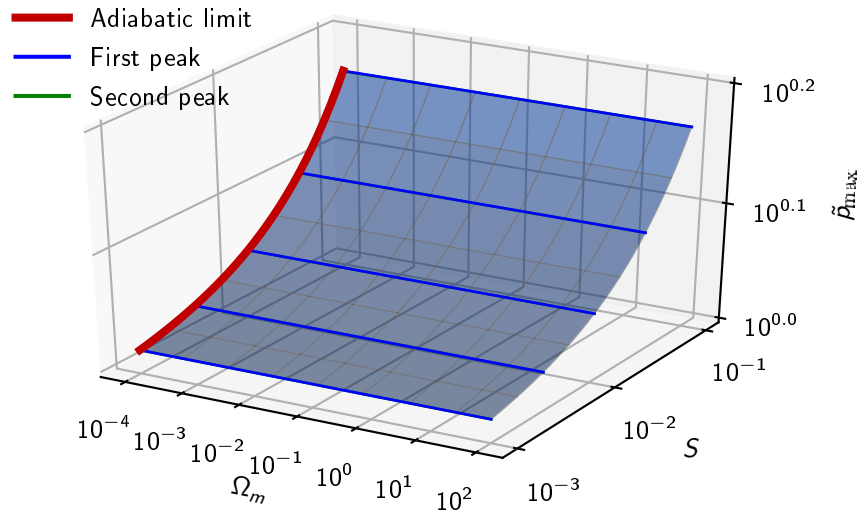
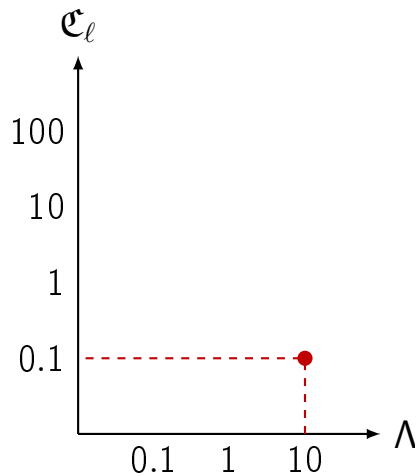
Estimating the parameters

- ▶ Ω_m is unknown
 - ▶ Could be close to 1, thus explaining the experimentally observed damping.
- ▶ Λ is intrinsic to a chemical species.
 - ▶ $\Lambda \simeq 20$ for water, $\Lambda \simeq 7$ for methane.
- ▶ \mathfrak{C}_ℓ : How much liquid is interacting with the gas?
 - ▶ Same arguments as for heat exchange.

$$\mathfrak{C}_\ell \simeq \frac{\sqrt{\Delta t}}{z_0} \times 10^{-2} \text{ m s}^{-1}$$

- ▶ Phase change negligible for macroscopic gas pockets.

Maximal pressure





Conclusion

Conclusion

- ▶ **Two main parameters for the extended Bagnold models:**
 - ▶ Relaxation rate (cause of the oscillation damping);
 - ▶ Distance to equilibrium (may limit the quantitative effect).

- ▶ **Phase change = simple gas escape + fancy thermodynamics.**

- ▶ **To be generalized to all phase change during wave impacts?**

Thank you for your attention!

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