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Rémi Buffe

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A Carleman estimate in the neighborhood of a multi-interface and applications to control theory

Rémi Buffe
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Abstract

We prove a Carleman estimate in a neighborhood of a multi-interface, that is, near a point where \( n \) manifolds intersect, under compatibility assumptions between the Carleman weight \( e^{\tau \phi} \), the operators at the multi-interface, and the elliptic operators in the interior and the usual sub-ellipticity condition. The compatibility condition at the multi-interface is a version of the known covering condition for systems in the literature. This Carleman estimate is a generalization of the results obtained in [6, 7]. Applications in control theory for second-order transmission problems are also considered, and provide a generalization of the known results for one-dimensional networks of strings [4, 13, 19, 30] to higher dimensions.

Keywords : Carleman estimate, elliptic operators, multiple interfaces, control, stabilization, Lopatinskii condition.

AMS 2010 Subject Classification : 35B45, 35G45, 35S15, 35Q93

1 Introduction

We consider \( n \) smooth \( d \)-dimensional manifolds \( \Omega_k, d \geq 2, i \in \{1, \ldots, n\} \) with boundary \( \partial \Omega_k \). We assume that they share parts of their boundary. More precisely, we denote by \( \partial \Omega^i_k, i = 0, \ldots, n_k \), the different connected components of \( \partial \Omega_k \). We assume that one of these connected components is shared by all manifolds. For instance, we assume that we have

\[
\partial \Omega^0_1 = \cdots = \partial \Omega^0_n.
\]

We set \( \Omega = \Omega_1 \cup \cdots \cup \Omega_n \), and we call \( I \) the common connected component of their boundaries. Note that \( \Omega \) is not a manifold because of its topology near \( I \). We shall refer to \( I \) as an interface between the manifolds. It is itself a \( d-1 \) dimensional manifold. An example of such configuration is given in Figure 1. On each \( \Omega_k \), we consider an elliptic differential operator \( P_k \) of order \( 2m_k \). In local coordinates \( (x_1, \ldots, x_d) \) for \( \Omega_k \) near a point \( x^0 \in I \), where \( \Omega_k \) is given by \( \{x_d \geq 0\} \), the operator \( P_k \) reads

\[
P_k(x, D) = \sum_{|\alpha| \leq 2m_k} a^k_\alpha(x) D^\alpha,
\]

where the coefficients \( a^k_\alpha(x) \) are \( C^\infty \) complex valued functions, \( D_j = -i \partial_{x_j} \) and \( D = (D_1, \ldots, D_d) \), and \( \alpha \in \mathbb{N}^d \) is a multi-index. With their principal symbols given by

\[
p_k(x, \xi) = \sum_{|\alpha| = 2m_k} a^k_\alpha(x) \xi^\alpha, \xi \in \mathbb{R}^d, x \in \Omega_k, \tag{1.1}
\]
the ellipticity assumption reads \(|p_k(x, \xi)| \geq C|\xi|^{2m_k}\), with \(C > 0\). We set \(m = m_1 + \cdots + m_n\). For each manifold \(\Omega_k\), we also consider a set of boundary operators \(T^\ell_k\), \(l = 1, \ldots, m\), of order less than or equal to \(\beta^\ell_k < 2m_k\), that take the following form in local coordinates

\[
T^\ell_k(x, D) = \sum_{|\alpha| \leq \beta^\ell_k} t^\ell_{\alpha,k}(x)D^\alpha, \quad \ell \in \{1, \ldots, m\}, \quad k \in \{1, \ldots, n\},
\]

where the coefficients \(t^\ell_{\alpha,k}(x)\) are complex-valued functions defined in a neighborhood of \(I\) in \(\Omega_k\). We denote by

\[
t^\ell_k(x, \xi) = \sum_{|\alpha| = \beta^\ell_k} t^\ell_{\alpha,k} \xi^\alpha,
\]

the principal symbol of the operator \(T^\ell_k\), for \(k \in \{1, \ldots, n\} \) and \(\ell \in \{1, \ldots, m\}\). Note that we may have \(t^\ell_k = 0\) if the actual order of \(T^\ell_k\) is less than \(\beta^\ell_k\). We assume that the orders satisfy the relations

\[
\gamma_\ell := 2m_k - \beta^\ell_k = 2m_j - \beta^\ell_j, \quad \forall k, j \in \{1, \ldots, n\}, \ell \in \{1, \ldots, m\}. \tag{1.2}
\]

We shall consider the following elliptic system, coupled through the interface,

\[
\begin{aligned}
P^n_k u_k &= f_k & \text{in } \Omega_k, \quad k \in \{1, \ldots, n\}, \\
\sum_{k=1}^n T^\ell_k(x, D) u_k|_\nu &= g_\ell & \text{on } I, \quad \ell \in \{1, \ldots, m\}. \tag{1.3}
\end{aligned}
\]

The main purpose of this article is the proof of a Carleman estimate for solutions of such system in a neighborhood of a point \(x^0\) of the interface \(I\).

In [12], Carleman introduced weighted inequalities to prove uniqueness of the Cauchy problem associated with an elliptic operator. The method has been developed later by Hörmander [17]. Carleman estimates for general elliptic operators has been derived away from boundaries in [18]. Recently, for boundaries and interfaces problems, Carleman estimates has been obtained in [6, 7, 29], under Lopatinskii-type assumptions. The purpose of this article is to generalize these results to systems such as (1.3).

Many Carleman estimates near boundaries and interfaces has been already obtained. For instance, local Carleman estimates near boundaries for Dirichlet [25], Neumann [26], Ventcel [10] conditions has been already obtained by using pseudo-differential methods. Near smooth interfaces, away from boundaries, one can cite for instance [5, 15, 24, 20, 23, 14]. For interfaces that meet the boundary, very few are known. We mention out the works pof [8, 9] where the authors obtained a Carleman estimate for medias with a stratified structure. The Carleman estimate we prove, in a neighborhood of a point of the multi-interface \(I\), has the following form

\[
\tau^{-1} \sum_{k=1}^n |e^{r\varphi_k} u_k|^2 + \sum_{k=1}^n |e^{r\varphi_k} \text{tr } u_k|^2 \leq C \left( \sum_{k=1}^n |e^{r\varphi_k} P_k u_k|^2 + \sum_{\ell=1}^m \sum_{k=1}^n |T^\ell_k u_k|_\nu^2 \right).
\]

where \(\varphi_k\) is a weight function on \(\Omega_k\), \(\tau\) is the usual Carleman large parameter, and \(\text{tr } u_k\) denotes the successive normal derivatives of \(u_k\) at the multi-interface \(I\), that is \(\text{tr } u_k = (u_k|_\nu, \partial_n u_k|_\nu, \ldots, \partial_n^{2m_k-1} u_k|_\nu)\).

As usual with Carleman estimates, in the interior, some compatibility conditions between the operators \(P_k\) and the weight \(\varphi_k\) are introduced, the so-called sub-ellipticity condition (see Section 2.1). At the multi-interface, we also impose some compatibility conditions between the weights \(\varphi_k\), the boundary operators \(T^\ell_k\) and the interior operators \(P_k\). These conditions are a natural generalization of the well-known Lopatinskii condition (see Section 2.2).

Carleman estimates are a powerful tool to prove control and stabilization properties. In the last section of this article, we provide an application of the Carleman estimate we obtain to a natural transmission
problem. Under assumption on the control region, we prove the null-controllability result for the associated parabolic problem, and a stabilization result for the associated hyperbolic one. This generalizes what has been done for one-dimensional networks of strings in [4, 13, 19, 30], and the references therein, to higher dimensions.

This article is organized as follows. In Section 2 we introduce the geometrical setting and the relevant hypothesis on the operators and the weight functions. In Section 3 we prove that we can find proper weight functions for which these conditions are satisfied in the special case of second-order operators with transmission condition through the interface. The general Carleman estimate is proven in Section 4. Finally, we state in Section 5 some of the immediate applications of the Carleman estimate of Theorem 2.6 to null-controllability of heat equation and to logarithmic stabilization of the damped wave equation, provided a natural geometric condition is satisfied (see Section 5.1, and also Section 3.2).

2 Statement of the problem and geometrical configurations

Let $x^0 \in \mathcal{I}$ be a point of the interface. In each manifold $\Omega_k$, we consider an open bounded neighborhood $\tilde{U}_k$ of $x^0$ in $\Omega_k$ where local coordinates as above can be used. More precisely, for $k = 1, \ldots, n$, we use local charts:

$$\phi_k : \Omega_k \supset \tilde{U}_k \longrightarrow V_k^+ = V_k \cap \{x_d \geq 0\}, \quad \phi_k \text{ diffeomorphism, for all } k \in \{1, \ldots, n\},$$

(2.1)

with $V_k$ an open set of $\mathbb{R}^d$, satisfying $\phi_k(x^0) = 0$ and $\phi_k(\mathcal{I} \cap \tilde{U}_k) = \{x_d = 0\} \cap V_k$ for all $k \in \{1, \ldots, n\}$. Setting $V = \bigcap_{k=1}^n V_k$ on $\mathbb{R}^d$ and $V^+ = \{x_d \geq 0\} \cap V$, we consider $U_k = \phi_k^{-1}(V^+)$, and $U = \bigcup_{k=1}^n U_k$ in $\Omega$ so that we have

$$\phi_k : \Omega_k \supset U_k \longrightarrow V^+, \quad \phi_k \text{ diffeomorphism, for all } k \in \{1, \ldots, n\},$$

and $\phi_{k|x} = \phi_{\ell|x}$, as sketched in Figure 2.

Throughout this article, two assumptions shall play a central role. The first one is the sub-ellipticity assumption, that is classical when working with Carleman estimates, and the second one is the covering condition (also known as the Shapiro-Lopatinskii condition, or complementing condition).

2.1 The sub-ellipticity condition

For two functions $f(x, \xi)$ and $g(x, \xi)$ in $C^\infty(\mathbb{R}^d \times \mathbb{R}^d)$, we recall that their Poisson bracket is given by

$$\{f, g\}(x, \xi) = \partial_\xi f(x, \xi) \partial_x g(x, \xi) - \partial_x f(x, \xi) \partial_\xi g(x, \xi).$$

![Diagram](image.png)

Figure 1: A sphere meets a surface and creates 4 smooth manifolds with boundaries. The shared interface is a connected component of $\partial \Omega_i$, for all $i \in \{1, \ldots, n\}$. 

Figure 2: A sphere meets a surface and creates 4 smooth manifolds with boundaries. The shared interface is a connected component of $\partial \Omega_i$, for all $i \in \{1, \ldots, n\}$. 

From symbolic calculus, \( \{f, g\} \) is the principal symbol of the commutator \( i[\text{Op}(f), \text{Op}(g)] \). For \( k \in \{1,\ldots,n\} \), we let \( \varphi_k \) be a real \( C^\infty \) function on \( \Omega_k \), and we consider the conjugated operators

\[
P_{k,\varphi_k} = e^{\tau \varphi_k} P_k e^{-\tau \varphi_k},
\]

(2.2)

with principal symbol \( p_{k,\varphi}(x,\xi,\tau) = p_k(x,\xi + i\tau d\varphi_k(x)) \) in a semi-classical sense. In general, \( P_{k,\varphi_k} \) is not elliptic. The sub-ellipticity condition states that \([P^*_k,\varphi_k, P_k,\varphi_k]\) is elliptic positive where \( P_{k,\varphi_k} \) fails to be elliptic. More precisely, we write the following definition.

**Definition 2.1.** Let \( k \in \{1,\ldots,n\} \). We say that \( (P_k,\varphi_k) \) satisfies the sub-ellipticity condition on \( U_k \) if \( d\varphi_k \neq 0 \) on \( U_k \) and if

\[
p_{k,\varphi}(x,\xi,\tau) = 0 \implies \text{Re} p_{k,\varphi}, \text{Im} p_{k,\varphi}(x,\xi,\tau) = \frac{1}{2i} \{ p_{k,\varphi}, p_{k,\varphi} \}(x,\xi,\tau) > 0,
\]

(2.3)

for all \( x \in U_k, \tau > 0 \), and all \( \xi \in \mathbb{R}^d, \xi \neq 0 \).

For the case of elliptic operators of order two, it is well-known that the following lemma gives a construction of such a weight function.

**Lemma 2.2.** Let \( U \) be an open subset of \( \mathbb{R}^d \), \( M \) be an elliptic operator of order two, and \( \psi \) be a smooth function on \( U \) such that \( \nabla \psi \neq 0 \) on \( U \). We set \( \varphi_\lambda = e^{\lambda \psi} \), for \( \lambda > 0 \). Then, there exists \( \lambda_0 > 0 \) such that \( (M,\varphi_\lambda) \) satisfies the sub-ellipticity condition of Definition 2.1, for all \( \lambda \geq \lambda_0 \).

The proof of this lemma can be found for instance in [16]. Note that there exist operators such that the sub-ellipticity condition cannot be achieved, independently of the choice of \( \varphi \). This is for instance the case for the Bi-Laplace operator. Indeed, in this case, we have \( p_{k,\varphi} = q_k^2, \varphi \), where \( q_k \) is the principal symbol of the Laplace operator. The Poisson bracket is then given by

\[
\frac{1}{2i} \{ p_{k,\varphi}, p_{k,\varphi} \} = \frac{1}{2i} \left( \partial_\xi p_{k,\varphi} \partial_\xi p_{k,\varphi} - \partial_x p_{k,\varphi} \partial_x p_{k,\varphi} \right) = \frac{2|q_{k,\varphi}|^2}{i} \left( \partial_\xi \overline{q}_{k,\varphi} \partial_\xi q_{k,\varphi} - \partial_x \overline{q}_{k,\varphi} \partial_x q_{k,\varphi} \right),
\]
and we see that this cannot be positive on the characteristic set of $p_{k, \varphi}$.
In addition to the sub-ellipticity condition of the couples $(P_k, \varphi_k)$, when considering systems as (1.3) with
general operators and boundary conditions, we have to impose some compatibility properties between
the operators in the interior and at the boundary, even for well-posedness properties. For Carleman
estimates, this is also the case, for the conjugated operator.

2.2 The covering condition
For $x \in I$, we shall denote by $T_x(I)$ and $T_x^*(I)$ respectively the tangent and cotangent spaces to $I$ above
$x$, and $T^*(I) = \{(x, \nu), \ x \in I, \ \nu \in T_x^*(I)\}$. We moreover define the conormal spaces, for $x \in I$,
\[ N_x^*(I) = \{\nu \in T_x^*(\Omega_k), \ \nu(Y) = 0, \ \forall Y \in T_x(I)\}, \]
and
\[ N_k^*(I) = \{(x, \nu), \ x \in I, \ \nu \in N_x^*(I)\}. \]
For all $k \in \{1, \ldots, n\}$, we define a boundary quadruple $\rho_k = (x, Y, \nu_k, \tau)$, where
\[ x \in I \cap U, \ Y \in T_x^*(I), \ \nu_k \in N_x^*(I), \ \text{and} \ \tau > 0. \] (2.4)
Moreover, we impose $\nu_k$ to be an inward pointing conormal vector, that is, $\nu = (0, \ldots, 0, t)$ with $t > 0$
in the local chart $(U_k, \varphi_k)$ given in (2.1). We shall denote by $L^{*+}_k(I)$ the set of such $\rho_k$. We define for a
fixed $x \in I$,
\[ L^{*+}_k(I) := \{(x, \nu_1, \ldots, \nu_n, \tau), \ \forall \ k \in \{1, \ldots, n\}, \ \rho_k = (x, Y, \nu_k, \tau) \in L^{*+}_k(I)\}, \] (2.5)
and we also consider
\[ L^*(I) := \{(x, \nu_1, \ldots, \nu_n, \tau), \ (Y, \nu_1, \ldots, \nu_n, \tau) \in L^*_x(I), \ x \in I\}. \] (2.6)
We introduce a weight function $\varphi$ defined on $U$, which is smooth in each $\Omega_k$ and continuous across the
interface $I$. We shall denote $\varphi_k = \varphi|_{\Omega_k}$. For $\rho_k \in L^{*+}_k(I)$ we introduce, for all $\lambda \in \mathbb{C}$,
\[ \tilde{p}_{k, \varphi}(\rho_k, \lambda) = p_k(x, Y + \lambda \nu_k + i\tau d\varphi_k(x)). \]
Considering the following factorization, as a polynomial in $\lambda \in \mathbb{C}$,
\[ \tilde{p}_{k, \varphi}(\rho_k, \lambda) = c_k \tilde{p}_{k, \varphi}(\rho_k, \lambda) \tilde{n}_{k, \varphi}(\rho_k, \lambda), \] (2.7)
with $\tilde{n}_{k, \varphi}(\rho_k, \lambda) = \Pi_{\im \sigma_{k,j}(\rho_k) = 0}(\lambda - \sigma_{k,j}(\rho_k))^{\mu_{k,j}}$ and $\tilde{p}_{k, \varphi}(\rho_k, \lambda) = \Pi_{\im \sigma_{k,j}(\rho_k) > 0}(\lambda - \sigma_{k,j}(\rho_k))^{\mu_{k,j}}$, where $(\sigma_{k,j})$ are the complex roots of $\tilde{p}_{k, \varphi}$ as a polynomial in $\lambda$, with multiplicity $\mu_{k,j}$. It should be kept in mind that
this factorization depends heavily on the choice of $\rho_k$. We set
\[ \tilde{k}_{k, \varphi}(\rho_k, \lambda) := \tilde{p}_{k, \varphi}(\rho_k, \lambda) \tilde{n}_{k, \varphi}(\rho_k, \lambda). \]
We also define at the boundary, for all $\lambda$,
\[ t_{k, \varphi}(\rho_k, \lambda) = t_{k, \varphi}^0(x, Y + \lambda \nu_k + i\tau d\varphi_k(x)). \]

Definition 2.3. We say that $(T^t_k, \varphi)_{k \in \{1, \ldots, n\}, t \in \{1, \ldots, m\}}$ covers $(P_k, \varphi_k)_{k \in \{1, \ldots, n\}}$ at $p^0 \in L^{*}(I)$ if for
all polynomials $f_k \in \mathbb{C}[\lambda]$ there exists $c_1, \ldots, c_m \in \mathbb{C}$ and polynomials $q_k \in \mathbb{C}[\lambda]$ such that, for all
$k \in \{1, \ldots, n\}$,
\[ f_k(\lambda) = \sum_{l=1}^m c_l t^t_{k, \varphi}(p^0_k, \lambda) + q_k(\lambda) k_{k, \varphi}(p^0_k, \lambda). \]
We shall say that $(T^t_k, \varphi)_{k, \ell}$ covers $(P_k, \varphi)_{k}$ at $x$ if this holds for all $p^0 \in L^{*}_x(I)$, and we shall say that
$(T^t_k, \varphi)_{k, \ell}$ covers $(P_k, \varphi)_{k}$ if this holds for all $p^0 \in L^{*}(I)$
Observe that in the above definition, we can restrict the degree of the polynomials \( f_k \) to be less than or equal to \( 2m_k - 1 \), using the Euclidean division. If we write \( m_k^+ = d^+ N_k \) and \( m_k^- = 2m_k - m_k^+ \), then \( d^+ q_k \) is at most equal to \( 2m_k - m_k^+ - 1 = m_k^- - 1 \). We can reformulate the above definition as follows. Introducing, for \( k \in \{ 1, \ldots, n \} \)

\[
e^k_k(\rho_k, \lambda) = \begin{cases} t_k \rho_k \lambda^k, & \text{if } \ell \in \{ 1, \ldots, m \} \\ \lambda^{-1}(m+1) \rho_k \lambda^\ell, & \text{if } \ell \in \{ m+1, \ldots, m+m_k^- \} \end{cases}
\]

and the linear map

\[
\Phi : \mathbb{C}^m \times \mathbb{C}^{m_1^-} \times \cdots \times \mathbb{C}^{m_n^-} \rightarrow \mathbb{C}_{2m_1-1}[\lambda] \times \cdots \times \mathbb{C}_{2m_n-1}[\lambda]
\]

\[
\left( \begin{array}{c} c_1 \\
q_{1,1} \\
\vdots \\
q_{m,m_n^-} \end{array} \right) \mapsto \left( \sum_{\ell=1}^m c_\ell e_{1,\ell} + \sum_{\ell=m+1}^{m+m_1^-} q_{1,\ell-m} e_{1,\ell}, \ldots, \sum_{\ell=1}^m c_\ell e_n^{\ell} + \sum_{\ell=m+1}^{m+m_n^-} q_n,\ell-m e_n^{\ell} \right),
\]

Definition 2.3 is precisely equivalent to the surjectivity of the above map \( \Phi \).

Remark 2.4. Like the sub-ellipticity condition, the covering condition is invariant under a change of coordinates. In particular, this definition does not depend on the sizes of the conormal vectors \( \nu_k \).

2.3 On the well-posedness of systems satisfying the covering condition

The well-posedness of elliptic systems satisfying the covering condition is a known fact for a non-conjugated system (that is, in the case \( \tau \varphi = 0 \)). We refer for instance to [1, 2]. In their setting, they consider a more general system. It can be related to our problem as explained as follows. Near a point of \( \mathcal{I} \), we can choose a coordinates system for each \( \Omega_k \) and thus the problem can be reformulated in \( \mathbb{R}_d^+ \) as in Section 2. This choice of coordinates has no impact on the covering condition as it is invariant under a change of coordinates. In [1, 2], the authors consider systems of mixed-order elliptic operators in the half-space, that are said to be properly elliptic, i.e. the roots \( \sigma_i \) of \( \det(A(x, \Theta_1 + z\Theta_2)) \), viewed as a polynomial in \( z \in \mathbb{C} \) satisfies

\[
\# \{ \text{Im} \sigma_i > 0 \} = \# \{ \text{Im} \sigma_i < 0 \}, \quad \text{for } \Theta_1, \Theta_2 \in \mathbb{R}^d, \text{ linearly independant}.
\]

In our case, the considered matrix \( A \) is diagonal, thus the determinant is the product of the symbols \( p_k(x, \Theta_1 + z\Theta_2) \). If the system is properly elliptic, we obtain that \( m = m_1^+ + \cdots + m_n^+ = m_1^- + \cdots + m_n^- \). Hence,

\[
\dim(\mathbb{C}^m \times \mathbb{C}^{m_1^-} \times \cdots \times \mathbb{C}^{m_n^-}) = \dim(\mathbb{C}_{2m_1-1}[\lambda] \times \cdots \times \mathbb{C}_{2m_n-1}[\lambda]),
\]

and then \( \Phi \) is onto if and only if \( \Phi \) is one-to-one. The covering condition stated in [1, 2] precisely implies that the map \( \Phi \) is one-to-one, and the covering condition in the present work implies that the map \( \Phi \) is onto. Thus, in the setting of properly elliptic diagonal system of operators, those two conditions are consistent. However, in the present article, we ask for the conjugated operator to satisfy the covering condition, and moreover, as we shall see, the conjugated system may not be elliptic anymore. We give the following definition.

Definition 2.5. Let \( (T^d_k, P_k) \) be a system of operators such as (1.3) satisfying

\[
(T^d_k, 0)_{k,\ell} \text{ covers } (P_k, 0)_k.
\]

We say that the weight function \( \varphi \) preserves the covering condition for \( (T^d_k, P_k) \) if we also have

\[
(T^d_k, \varphi)_{k,\ell} \text{ covers } (P_k, \varphi)_k.
\]

An interesting question then arises: given a system \( (T^d_k, P_k) \) that satisfies (2.9), can we always find a weight function that preserve the covering condition for \( (T^d_k, P_k) \)? We give a positive answer for the special case of transmission conditions for Laplace-Beltrami operators in Section 3.
We shall often use the notation \(x\) for all \(\phi\) the interface. We define the following space of smooth functions defined in a neighborhood of the point of interest at the interface.

\[
C_0^\infty(U_k) = \{ w \in C^\infty(\Omega_k), \text{supp}(w) \subset U_k \text{ is compact in } \Omega_k \}. \tag{2.10}
\]

**Theorem 2.6.** Let \(x_0 \in \mathcal{I}\) and let \(\phi\) be a weight function on \(U\) such that \(\phi \in C^0(U)\) and such that \(\phi|_{U_k} \in C^\infty(U_k)\). In addition, assume that \((P_k, \phi_k)\) satisfies the sub-ellipticity condition of Definition 2.1 in a neighborhood of \(x_0\) in \(\Omega_k\), for all \(k \in \{1, \ldots, n\}\), and assume that \((T_{k}^\ell, \phi_{k})_{k \in \{1, \ldots, n\}, \ell \in \{1, \ldots, m\}}\) covers \((P_k, \phi)_{k \in \{1, \ldots, n\}}\) at \(x_0 \in \mathcal{I}\) (see Definition 2.3). Then, there exists a neighborhood \(U\) of \(x_0\) in \(\Omega\), \(C > 0\), and \(\tau_0 > 0\) such that

\[
\tau^{-1} \sum_{k=1}^{n} \| e^{\tau \Phi_k x} u_k \|^2_{L^2_{m_k, \tau}} + \sum_{k=1}^{n} \| e^{\tau \Phi_k x} \text{tr} u_k \|^2_{L^2_{m_k-1, 1/2, \tau}} \leq C \left( \sum_{k=1}^{n} \| e^{\tau \Phi_k x} P_k u_k \|^2_{L^2(\Omega_k)} + \sum_{\ell=1}^{m} \left( \sum_{k=1}^{n} T_{k}^\ell u_k \right)^2_{L^2_{m_k-1/2, \tau}} \right), \tag{2.11}
\]

for all \(\tau \geq \tau_0\), for all \(u \in C_0^\infty(\bar{U})\) such that \(u_k := u|_{U_k \cap \partial \Omega} \in C_0^\infty(U_k \cap \bar{U})\).

This Carleman estimate is local in a neighborhood of a point of the interface. Local Carleman estimates can be generally patched together to obtain a global one. For such issue, we refer to Section 5.1. The various norms are presented in Section 4.1.3. Let us simply mention that

1. \(\| \cdot \|_{r, s, \tau}\) is equivalent to \(\tau^r\| \cdot \|_{L^2} + \| \cdot \|_{H^s}\) in some \(\Omega_k\);
2. \(\| \cdot \|_{s, \tau}\) is equivalent to \(\tau^s\| \cdot \|_{L^2(\mathcal{I})} + \| \cdot \|_{H^s(\mathcal{I})}\). Norms on the interface are denoted by \(\| \cdot \|\) for easier reading;
3. on \(\mathcal{I}\), for \(r \in \mathbb{N}\) and \(s \in \mathbb{R}\), we mean

\[
| \text{tr} w |_{r, s, \tau} = \sum_{\ell=0}^{r} | \partial_{\nu}^s w |_{r+s-\ell, \tau},
\]

using the notation of 2).

### 2.5 Conditions in a neighborhood of the interface

Let \(x_0 \in \mathcal{I}\). We use the local chart introduced in (2.1) and the neighborhood \(V^+ = \{ x_d \geq 0 \} \cap V \) in \(\mathbb{R}^d\). We shall often use the notation \(x = (x', x_d)\) and \(\xi = (\xi', \xi_d)\). We also introduce

\[
C_0^\infty(V^+) = \{ u_{\xi'} \in C_0^\infty(V), u \in C_0^\infty(V) \}, \tag{2.12}
\]

the set of restrictions to \(V^+\) of smooth and compactly supported functions in \(V\). Note that Definition (2.12) is consistent with (2.10).

In this coordinate system, the operators \(P_k\) reads

\[
P_k = \sum_{|\alpha| \leq 2m_k} a_{k}^{\alpha}(x) D^\alpha, \; \; k = 1, \ldots, n,
\]

for \(x \in V^+\), and near the boundary \(V \cap \{ x_d = 0 \}\), the boundary operators read

\[
T_k^\ell = \sum_{|\alpha| \leq \beta_k^\ell} t_{k}^{\ell \alpha} D^\alpha, \; \; k = 1, \ldots, n, \; \; \ell = 1, \ldots, m,
\]
with $\beta'_k \in \{1, \ldots, 2m_k - 1\}$ and $m = m_1 + \cdots + m_n$. We call $p_k(x, \xi)$ and $t'_k(x, \xi)$ their principal symbols. We also introduce the symbols

$$p_k,\varphi(x, \xi, \tau) = p_k(x, \xi + i\tau d\varphi_k), \quad t'_k(x, \xi, \tau) = t'_k(x, \xi + i\tau d\varphi_k),$$

which are respectively the principal symbols of the conjugated operators $P_{k,\varphi} := e^{\tau \varphi \xi} P_k e^{-\tau \varphi \xi}$ and $T'_k,\varphi := e^{\tau \varphi \xi} T'_k e^{-\tau \varphi \xi}$. In this coordinate system, we make the following identification

$$\mathcal{L}_{k,\varphi}^*(I) \cong \{ \rho = (x, \xi, \tau) \in (\{ x_d = 0 \} \cap \overline{V}) \times \mathbb{R}_+^d \times \mathbb{R}^+ \}.$$ 

We furthermore allow one to identify all the $\mathcal{L}_{k,\varphi}^*(I)$ to one another. Moreover, as Definition 2.3 is coordinate invariant (see Remark 2.4) we can identify $\mathcal{L}'(I)$ with $\mathcal{L}_{k,\varphi}^*(I)$ for all $k \in \{1, \ldots, n\}$. We also set the cotangent bundle over $I$ with parameter $\tau$ as

$$\mathcal{L}'(I) \cong \{ \rho' = (x, \xi', \tau) \in (\{ x_d = 0 \} \cap \overline{V}) \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \}.$$ 

For $\rho' \in \overline{V} \times \mathbb{R}^{d-1} \times \mathbb{R}^+$, we consider the complex roots $\sigma_{k,1}(\rho'), \ldots, \sigma_{k,l_k}(\rho')$ of multiplicity $\mu_{k,\varphi}$ of the symbol $p_{k,\varphi}(\rho', \xi_d)$, viewed as a polynomial in $\xi_d$. Let $\rho_0' \in \overline{V} \times \mathbb{R}^{d-1} \times \mathbb{R}^+$ be fixed in what follows. From Lemma A.2 in [Bellassoud-Le Rousseau], there exists a conic neighborhood $\mathcal{V}$ of $\rho_0'$ in $\overline{V} \times \mathbb{R}^d \times \mathbb{R}^+$ and three smooth and homogeneous polynomials $p^+_k(\rho', \xi_d)$, $p^-_k(\rho', \xi_d)$ in $\xi_d$, such that

1. each polynomial is of constant degree for $\rho' \in \mathcal{V}$;
2. we have the following factorization
   $$p_{k,\varphi}(\rho', \xi_d) = a(\rho') p^+_k(\rho', \xi_d) p^-_k(\rho', \xi_d) p^0_k(\rho', \xi_d), \quad \rho' \in \mathcal{V},$$
   where $a(\rho')$ is the leading coefficient;
3. the roots of $p^+_k(\rho', \xi_d)$ and $p^-_k(\rho', \xi_d)$ have positive and negative imaginary parts respectively for all $\rho' \in \mathcal{V}$;
4. at $\rho' = \rho_0'$ we have
   $$p^\pm_{k,\varphi}(\rho_0', \xi_d) = \prod_{\text{Im} \sigma_{k,j}(\rho_0') = 0} (\xi_d - \sigma_{k,j}(\rho_0'))^{\mu_{k,j}}, \quad p^0_{k,\varphi}(\rho_0', \xi_d) = \prod_{\text{Im} \sigma_{k,j}(\rho_0') > 0} (\xi_d - \sigma_{k,j}(\rho_0'))^{\mu_{k,j}}.$$ 

Note that the decomposition thus depends on $\rho_0'$. Note also that for $\rho' \in \mathcal{V}$, the sign of the imaginary part of the roots of $p^\pm_{k,\varphi}(\rho', \xi_d)$ is not prescribed. However, at $\rho' = \rho_0'$ those imaginary parts vanish.

We set $\kappa_{k,\varphi}(\rho', \xi_d) = p^0_{k,\varphi}(\rho', \xi_d) p^-_{k,\varphi}(\rho', \xi_d)$. In fact, while the roots $\sigma_{k,j}(\rho')$ are only continuous, since they can cross each other, we shall work with the polynomials given in (2.13); they are smooth, which permits the use of semi-classical calculus. We can reformulate the covering condition at $\rho_0'$ as follows: for all family of polynomials $(f_k)_{k \in \{1, \ldots, n\}} \in \mathbb{C}[\xi_d]^n$, there exists $(c_1, \ldots, c_m) \in \mathbb{C}^m$ and a family of polynomials $(q_k)_{k \in \{1, \ldots, n\}} \in \mathbb{C}[\xi_d]^n$ such that

$$f_k(\xi_d) = \sum_{l=1}^m c_l t'_{k,\varphi}(\rho_0', \xi_d) + q_k(\xi_d) \kappa_{k,\varphi}(\rho_0', \xi_d), \quad \forall k \in \{1, \ldots, n\}.$$ 

In this setting, the covering condition can also be stated in a more convenient way, such as follows. Setting $m := d^2 p_{k,\varphi}$, we write

$$\kappa_{k,\varphi}(\rho', \xi_d) = \sum_{\ell=0}^{2m_k - 1} \kappa_{k,\varphi}^{\ell}(\rho') \xi_d^\ell.$$ 

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where $\kappa_{k,\varphi}^i$ is homogeneous of degree $2m_k - m^-_k - i$ in $(\xi', \tau)$. Similarly, we write

$$t_{k,\varphi}^\ell(\rho', \xi_d) = \sum_{i=0}^{\beta_k^\ell} t_{k,\varphi}^{\ell, i}(\rho')\xi_d^i,$$

where $t_{k,\varphi}^{\ell, i}$ is homogeneous of degree $\beta_k^\ell - i$ in $(\xi', \tau)$. Arguing as in (2.8), we introduce

$$e_k^\ell(\rho', \xi_d) = \begin{cases} t_{k,\varphi}^\ell(\rho', \xi_d) & \text{if } \ell \in \{1, \ldots, m\} \\ t_{k,\varphi}^{\ell-m+1}(\rho') & \text{if } \ell \in \{m+1, \ldots, m+m^-_k\}, \end{cases}$$

and the covering condition is equivalent to the surjectivity at $\rho' = \rho_0$ of the map

$$\Phi : \mathbb{C}^m \times \mathbb{C}^{m^-} \times \cdots \times \mathbb{C}^{m^-} \longrightarrow \mathbb{C}_{2m_1 - 1}[\xi_d] \times \cdots \times \mathbb{C}_{2m_n - 1}[\xi_d]$$

$$\begin{pmatrix} e_1 \\ q_{1,1} \\ \vdots \\ q_{m,m^-} \end{pmatrix} \mapsto \begin{pmatrix} \sum_{\ell=1}^{m} c_\ell e_\ell^1 + \sum_{\ell=m+1}^{m+m^-} q_{1,\ell-m} e_\ell^1, \ldots, \sum_{\ell=1}^{m} c_\ell e_\ell^n + \sum_{\ell=m+1}^{m+m^-} q_{n,\ell-m} e_\ell^n \end{pmatrix}.$$

If we write $e_k^\ell(\rho', \xi_d) = \sum_{i=0}^{2m^- - 1} e_{k,\varphi}^{\ell, i}(\rho')\xi_d^i$, the coefficients $e_{k,\varphi}^{\ell, i}$ (that are homogeneous in $(\xi', \tau)$) are given by

- if $\ell \in \{1, \ldots, m\}$, $e_{k,\varphi}^{\ell, i}(\rho') = \begin{cases} t_{k,\varphi}^{\ell, i}(\rho') & \text{if } i \in \{0, \ldots, \beta_k^\ell\} \\ 0 & \text{otherwise}, \end{cases}$
- if $\ell \in \{m+1, \ldots, m+m^-_k\}$, $e_{k,\varphi}^{\ell, i}(\rho') = \begin{cases} \kappa_{k,\varphi}^{i-\ell+m+1}(\rho') & \text{if } i \in \ell - (m+1) + \{0, \ldots, 2m_k - m^-_k\} \\ 0 & \text{otherwise.} \end{cases}$

If moreover $m^-_k > 0$, then for $k \in \{1, \ldots, n\}$, we set the $2m_k \times m$ matrix

$$M_1^k(\rho') = \begin{pmatrix} e_{k,\varphi}^{\ell, i}(\rho') \end{pmatrix}_{(i, \ell) \in \{1, \ldots, 2m_k\} \times \{1, \ldots, m\}}.$$

If moreover $m^-_k > 0$, we set the $2m_k \times m^-_k$ matrix

$$M_2^k(\rho') = \begin{pmatrix} e_{k,\varphi}^{m+\ell, i+1}(\rho') \end{pmatrix}_{(i, \ell) \in \{1, \ldots, 2m_k\} \times \{1, \ldots, m^-_k\}}.$$

With $M_1^k$ and $M_2^k$, we define the $2m \times (m + m^-_1 + \cdots + m^-_n)$ matrix

$$M(\rho') = \begin{pmatrix} M_1^1(\rho') & M_1^2(\rho') & 0 & \cdots & 0 \\ M_1^2(\rho') & 0 & M_2^1(\rho') & \cdots & 0 \\ \vdots & \vdots & \ddots & \ddots & \vdots \\ M_1^n(\rho') & 0 & \cdots & 0 & M_2^n(\rho') \end{pmatrix}.$$

(2.16)

where the column associated with $M_2^k(\rho')$ only occurs if $m^-_k > 0$. For convenience, we shall say that $M_2^k(\rho') = \emptyset$ if $m^-_k = 0$. With this matrix, the covering condition at $\rho' = \rho_0$ is equivalent to

$$\text{Rank } M(\rho'_0) = 2m.$$

(2.17)

**Remark 2.7.** Considering the size of $M(\rho')$, a necessary condition for the covering condition to holds is $m + m^-_1 + \cdots + m^-_n \geq 2m$.  

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Lemma 2.8. If the covering condition is satisfied in a point \( \rho_0 \in \mathcal{L}^T(I) \), then there exists a conic neighborhood \( V \) of \( \rho_0 \) in \( \mathcal{L}^T(I) \) such that the rank condition (2.17) is fulfilled for every \( \rho' \in V \).

Proof. If \( \text{Rank} M(\rho_0) \geq 2m \), then there exists a \( 2m \times 2m \) submatrix \( S(\rho_0) \) such that \( \det S(\rho_0) \neq 0 \). As the symbols of \( \det \) result, and \( 2i \) satisfying \( \rho \) Section 2, in Remark 2.9. Note that we proved that if the covering condition is satisfied in some point \( S \) where \( A \) k 3.1 The transmission problem

\[
\begin{align*}
  \text{Proof.} \quad & (2.17), \text{in a neighborhood of a point}\ y \in I \text{ we can use coordinates} \ x' = (x_1, \ldots, x_{d-1}) \text{ on} \ I \ 	ext{and coordinates} \ x = (x', x_d) \text{ on} \ \Omega_k \text{ such that locally} I = \{x_d = 0\} \text{ and} \ \Omega_k = \{x_d \geq 0\}. \text{In this set of coordinates, System (3.1) reads} \\
  & \begin{cases}
    A_k u_k = 0, & k = 1, \ldots, n \text{ in the interior of } \Omega_k \\
    u_{1|z} = \cdots = u_{n|z} & \text{on } I \\
    \sum_{k=1}^{n} \partial_{x_k} u_k|z = 0 & \text{on } I,
  \end{cases} \tag{3.1}
\end{align*}
\]

where \( A_k = -\Delta g_k + \text{lower order terms} \), where \( (\Omega_k, g_k) \) are Riemannian manifolds with boundary \( I_k \) satisfying \( I := I_1 = \cdots = I_n \), where \( \Delta g_k \) is the Laplace-Beltrami operator associated with the metric \( g_k \), and \( \nu_k \) denotes the unit outward pointing normal vector of \( I_k \) with respect to the metric \( g_k \). Following Section 2, in \( \Omega = \bigcup_{k=1}^{n} \Omega_k \), in a neighborhood of a point \( y \in I \) we use coordinates \( x' = (x_1, \ldots, x_{d-1}) \) on \( I \) and coordinates \( x = (x', x_d) \) on \( \Omega_k \) such that locally \( I = \{x_d = 0\} \) and \( \Omega_k = \{x_d \geq 0\} \). In this set of coordinates, System (3.1) reads

\[
\begin{align*}
  & \begin{cases}
    P_k(x, D) u_k = 0, & k = 1, \ldots, n \text{ in } \Omega_k \cap \{x_d > 0\} \\
    u_{1|z} = \cdots = u_{n|z} & \text{on } I \\
    \sum_{k=1}^{n} \partial_{x_k} u_k|z = 0 & \text{on } I,
  \end{cases} \tag{3.2}
\end{align*}
\]

where the principal part of \( P_k(x, D) \) is of the form \( \sum_{1 \leq i,j \leq d} D_i a_{i,j}^k D_j \), where \( a_{i,j}^k \) are coefficients dependent on the metric \( g_k \). These transmission conditions can be rewritten as the following equations

\[
  u_{1|z} - u_{2|z} = 0, \quad u_{2|z} - u_{3|z} = 0, \quad \ldots, \quad u_{n-1|z} - u_{n|z} = 0, \quad \sum_{k=1}^{d} \sum_{j=1}^{n} a_{d,j}^k(x) \partial_{x_j} u_k|z = 0.
\]

Here \( m = n \). With the notation of System (1.3), we consider the following set of operators

\[
\begin{align*}
  T_k^\ell & = \delta_{k,\ell} - \delta_{k,\ell+1}, & k \in \{1, \ldots, n\}, \ \ell \in \{1, \ldots, n-1\}, \\
  T_k^\ell & = \sum_{j=1}^{d} a_{d,j}^k(x) D_j, & k \in \{1, \ldots, n\}. \tag{3.3}
\end{align*}
\]

This type of transmission condition across an interface has a natural physical meaning. It simply implies continuity of the solution at \( I \) and that the fluxes add up to zero. We shall conjugate the operators with
where $q$ and $\varphi$ have Observe that $\phi(2.17)$. In this particular case, we have

$$t_k^j(x, \xi, \tau) = t_k^j(x, \xi), \quad k = 1, \ldots, n, \; j = 1, \ldots, n - 1,$$

as these operators do not involve any derivative, and

$$t_k^0(x, \xi, \tau) = \sum_{j=1}^{d} a_{d,j}^k(x)(\xi_j + i\tau\partial_{x_j}\varphi_k)$$

$$= a_{d,d}^k(x)(\xi_d + \zeta_k),$$

where

$$\zeta_k = i\tau\partial_{x_d}\varphi_k(x) + \sum_{j=1}^{d-1} a_{d,j}^k(x)(\xi_j + i\tau\partial_{x_j}\varphi_k).$$

(3.4)

Observe that $\text{Im} \zeta_k$ is a function of $d\varphi_k$ near $I$, but not of $\varphi_k$ itself. As the operators $p_k$ are elliptic, we have $a_{d,d} \neq 0$. We also have, as $a_{i,j} = a_{j,i},$

$$p_k(x, \xi, \tau) = \sum_{j,d=1}^{d} a_{d,j}^k(x)(\xi_j + i\tau\partial_{x_j}\varphi_k)(\xi_d + i\tau\partial_{x_d}\varphi_k)$$

$$= a_{d,d}^k(x)(\xi_d + i\tau\partial_{x_d}\varphi)^2 + 2(\xi_d + i\tau\partial_{x_d}\varphi_k)\sum_{\ell=1}^{d-1} a_{d,\ell}^k(x)(\xi_\ell + i\tau\partial_{x_\ell}\varphi_k)$$

$$+ \sum_{j,\ell=1}^{d-1} a_{d,j}^k(x)(\xi_j + i\tau\partial_{x_j}\varphi_k)(\xi_\ell + i\tau\partial_{x_\ell}\varphi_k)$$

$$= a_{d,d}^k(x)((\xi_d + \zeta_k(x, \xi', \tau))^2 + q_k(x, \xi', \tau))$$

$$= a_{d,d}^k(x)(\xi_d + \zeta_k(x, \xi', \tau) + i\alpha_k(x, \xi', \tau))(\xi_d + \zeta_k(x, \xi', \tau) - i\alpha_k(x, \xi', \tau)),

$$

where $q_k(x, \xi', \tau)$ is homogeneous of order 2 in $(\xi', \tau)$, and $\alpha_k(x, \xi', \tau) \in \mathbb{C}$ is chosen so that $\text{Re} \alpha_k \geq 0$ and $\alpha_k^2(x, \xi', \tau) = q_k(x, \xi', \tau)$. Defining

$$\sigma_k^+(x, \xi', \tau) = -\zeta_k(x, \xi', \tau) + i\alpha_k(x, \xi', \tau), \quad \sigma_k^- = -\zeta_k(x, \xi', \tau) - i\alpha_k(x, \xi', \tau),$$

we can factorize the principal symbols of the operators

$$p_{k, \varphi}(x, \xi, \tau) = a_{d,d}^k(x)(\xi_d - \sigma_k^-(x, \xi', \tau))(\xi_d - \sigma_k^+(x, \xi', \tau)).$$

Observe that $\text{Im} \sigma_k^+ \geq \text{Im} \sigma_k^-$ always holds. Several cases can occur, depending on the sign of the imaginary part of the roots of the $p_{k, \varphi}$, viewed as polynomials in $\xi_d$. To discuss the sign of the imaginary parts of the roots $\sigma_k^\pm$, we introduce the following sets

$$\Sigma^+ = \Sigma^+(\rho') = \{ k \in \{1, \ldots, n\}, \; \text{Im} \sigma_k^+, \text{Im} \sigma_k^- \geq 0 \},$$

$$\Sigma^- = \Sigma^-(\rho') = \{ k \in \{1, \ldots, n\}, \; \text{Im} \sigma_k^+ \text{Im} \sigma_k^- < 0 \},$$

$$\Sigma^0 = \Sigma^0(\rho') = \{ k \in \{1, \ldots, n\}, \; \text{Im} \sigma_k^+ \geq 0, \; \text{Im} \sigma_k^- < 0 \},$$

(3.6)

We recall that the covering condition holds if the matrix $M$ built in (2.16) satisfies the rank condition (2.17). In this particular case, we have $m = n$. The $2 \times n$ sub-matrices $M_k^l$ are only related to operators at the boundary, and do not depend on the sign of the imaginary parts of the roots of the operators in
the interior. We detail here how to construct those matrices in the present example. The coefficients $t_{k,\varphi}^{\ell,i}$ of $M_k^1$ correspond to the coefficients of the principal symbols of the $t_{k,\varphi}^{\ell}$. The operators that acts on $u_1$ for $\ell \in \{1, \ldots, m\}$ are respectively (see (3.3))

$$T_{1,\varphi}^1 = 1, \quad T_{1,\varphi}^2 = 0, \quad \ldots, \quad T_{1,\varphi}^{n-1} = 0, \quad \text{and} \quad T_{1}^{n} = \sum_{j=1}^{n} a_{d,j}^{1}(x)(D_j + i\tau\partial_{x,j}\varphi_1(x)), $$

and the coefficients of their principal symbols written in the form (2.14) are given by

$$t_{1,0}^{1,0} = 1, \quad t_{1,1}^{1,1} = 0, \quad \ldots, \quad t_{n-1,0}^{n-1,0} = 0, \quad t_{n,0}^{n,0} = a_{d,d}^{1}\zeta, \quad t_{n,1}^{n,1} = a_{d,d}^{1}(x),$$

with $\zeta$ defined in (3.4) for $k = 1$. Then, we obtain

$$M_k^1 = \begin{pmatrix} 1 & 0 & \cdots & 0 & a_{d,d}^{1}\zeta \\ 0 & 0 & \cdots & 0 & a_{d,d}^{1} \end{pmatrix}. \quad (3.7)$$

Arguing the same way we have, for $k \in \{2, \ldots, n-1\}$, we find

$$M_k^1 = \begin{pmatrix} 0 & \cdots & 0 & (k-1)\text{th} & k\text{th} \\ 0 & \cdots & 0 & -1 & 1 & 0 & \cdots & 0 & a_{d,d}^{k}\zeta_k \\ 0 & \cdots & 0 & 0 & 0 & 0 & \cdots & 0 & a_{d,d}^{k} \end{pmatrix}$$

and

$$M_k^1 = \begin{pmatrix} 0 & 0 & \cdots & 0 & -1 & a_{d,d}^{n}\zeta_n \\ 0 & 0 & \cdots & 0 & 0 & a_{d,d}^{n} \end{pmatrix}.$$

We also detail the structure of the matrices $M_k^2$ in different situations depending on the cardinal of the sets given in (3.6).

- For $k \in \Sigma^0$, we have $m_k^-=1$ and then $M_k^2 = \begin{pmatrix} 1 & (\cdot - \sigma_k^+) \end{pmatrix}$.
- For $k \in \Sigma^-$, we have $m_k^-=2$ and then $M_k^2 = \text{Id}_2$.
- For $k \in \Sigma^+$, we have $m_k^-=0$ and then $M_k^2 = \emptyset$, with the meaning given below (2.16).

We now investigate what configurations yield (2.17).

**First case.** We first focus on the case where Card $\Sigma^+ \geq 2$. Without any loss of generality, we may assume that $\{1, 2\} \subseteq \Sigma^+$, that is $\text{Im} \sigma_1^+ \geq 0$ and $\text{Im} \sigma_2^+ \geq 0$. In this case the matrices $M_1^2$ and $M_2^2$ are empty, and the matrix $M$ reads

$$M = \begin{pmatrix} 1 & 0 & 0 & \cdots & a_{d,d}^{1}\zeta_1 & \cdots & a_{d,d}^{2}\zeta_2 \\ 0 & 0 & 0 & \cdots & a_{d,d}^{1} \\ -1 & 1 & 0 & \cdots & a_{d,d}^{1}\zeta_2 \\ 0 & 0 & 0 & \cdots & a_{d,d}^{2} \end{pmatrix} \begin{pmatrix} N \\ \star \end{pmatrix}$$

with either $N = 0$ or $N = \emptyset$ (in the sense given after (2.16)). We then see that the second and the fourth rows are linearly dependent. As the number of lines of $M$ is equal to $2m$, this implies that the rank
condition (2.17) fails to hold.

**Second case.** Here, we assume that $\Sigma^+ = \emptyset$. Consider $\ell \in \{1, \ldots, n\}$. Without any loss of generality, we may assume that $\{1, \ldots, \ell\} \subset \Sigma^0$ and $\{\ell + 1, \ldots, n\} \subset \Sigma^-$. The matrix $M$ then reads

$$M = \begin{pmatrix} A_{2\ell}^1 & B_\ell & 0 \\ A_{2(n-\ell)}^2 & 0 & \text{Id}_{2(n-\ell)} \end{pmatrix},$$

where,

$$B_\ell = \begin{pmatrix} -\sigma^+_1 & 0 & \ldots & 0 & 0 \\ 1 & 0 & \ldots & 0 & 0 \\ 0 & -\sigma^+_2 & \ldots & 0 & 0 \\ 0 & 1 & \ldots & 0 & 0 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \ldots & 0 & -\sigma^+_\ell & 0 \\ 0 & \ldots & 0 & 0 & 1 \end{pmatrix} \in \mathcal{M}_{2\ell,\ell}(\mathbb{C}),$$

and $\text{Id}_{2(n-\ell)}$ denotes the identity matrix of dimension $2(n-\ell)$. If $\ell = n$ we set $\text{Id}_0 = \emptyset$ in the sense given below (2.16). Moreover, for $\ell \neq 1, n$, we have

$$A_{2\ell}^1 = \begin{pmatrix} 1 & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_1 \\ 0 & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_2 \\ -1 & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_3 \\ 0 & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_4 \\ \vdots & \ddots & \ddots & \ddots & \vdots \\ 0 & \ldots & -1 & 1 & \ldots & 0 \\ 0 & \ldots & 0 & 0 & \ldots & 0 \end{pmatrix} \in \mathcal{M}_{2\ell,n}(\mathbb{C}),$$

and

$$A_{2(n-\ell)}^2 = \begin{pmatrix} 0 & \ldots & -1 & 1 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+1} \\ 0 & \ldots & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+2} \\ 0 & \ldots & 0 & -1 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+3} \\ 0 & \ldots & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+4} \\ \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & \ldots & 0 & 0 & \ldots & -1 & a_{d,d}^1 \zeta_{n} \\ 0 & \ldots & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{n} \end{pmatrix} \in \mathcal{M}_{2(n-\ell),n}(\mathbb{C}).$$

For $\ell = 1$, we have

$$A_{2\ell}^1 = \begin{pmatrix} 1 & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_1 \\ 0 & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_2 \\ -1 & 1 & \ldots & 0 & \ldots & 0 \\ 0 & 0 & \ldots & 0 & \ldots & 0 \end{pmatrix} \in \mathcal{M}_{2,n}(\mathbb{C}),$$

$$A_{2(n-\ell)}^2 = \begin{pmatrix} 0 & 1 & \ldots & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+1} \\ 0 & 0 & \ldots & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+2} \\ 0 & 0 & \ldots & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+3} \\ 0 & 0 & \ldots & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{\ell+4} \\ \vdots & \vdots & \ddots & \ddots & \ddots & \ddots & \vdots \\ 0 & 0 & \ldots & -1 & a_{d,d}^1 \zeta_{n} \\ 0 & 0 & \ldots & 0 & \ldots & 0 & a_{d,d}^1 \zeta_{n} \end{pmatrix} \in \mathcal{M}_{2(n-\ell),n}(\mathbb{C}).$$
Finally, for $\ell = n$, we have

$$A_{2n}^1 = \begin{pmatrix}
1 & 0 & 0 & 0 & \ldots & 0 & a_{d,d}^1 \zeta_1 \\
0 & 0 & 0 & 0 & \ldots & 0 & a_{d,d}^2 \\
-1 & 1 & 0 & 0 & \ldots & 0 & a_{d,d}^2 \zeta_2 \\
0 & 0 & 0 & 0 & \ldots & 0 & a_{d,d} \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \ldots & -1 & a_{d,d}^n \zeta_n \\
0 & 0 & 0 & 0 & \ldots & 0 & a_{d,d}
\end{pmatrix} \in M_{2n,n}(\mathbb{C}), \quad A_{2(n-\ell)}^2 = \emptyset.$$

Note that we have

$$\text{Rank}(M) = \text{Rank}(T) + 2(n-\ell), \quad \text{with } T = \text{Rank}(A_{2\ell}^1 B_{\ell}). \quad (3.8)$$

By operations on the lines and columns of the $2\ell \times (n+\ell)$ matrix $T$ we can obtain:

- If $\ell < n$, it is of maximal rank. Indeed, from (3.8), this is equivalent to have $\text{Rank}(M) = \text{Rank}(A_{2\ell}^1 B_{\ell}) = 2\ell$. Yet, by reorganizing columns, we have

$$\text{Rank}(A_{2\ell}^1 B_{\ell}) = \text{Rank} \begin{pmatrix}
1 & -\sigma_1^+ & 0 & 0 & \ldots & 0 & 0 & a_{d,d}^1 \zeta_1 \\
0 & 1 & 0 & 0 & \ldots & 0 & 0 & a_{d,d}^2 \\
-1 & 0 & 1 & -\sigma_2^+ & \ldots & 0 & 0 & a_{d,d}^2 \zeta_2 \\
0 & 0 & 0 & 1 & \ldots & 0 & 0 & a_{d,d} \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \ldots & 1 & -\sigma_\ell^+ & a_{d,d}^\ell \zeta_\ell \\
0 & 0 & 0 & 0 & \ldots & 0 & 1 & a_{d,d}
\end{pmatrix} \geq \text{Rank} \begin{pmatrix}
1 & 0 & 0 & 0 & \ldots & 0 & 0 & a_{d,d}^1 (\zeta_1 + \sigma_1^+) \\
0 & 1 & 0 & 0 & \ldots & 0 & 0 & a_{d,d}^1 \\
-1 & 0 & 1 & 0 & \ldots & 0 & 0 & a_{d,d}^2 (\zeta_2 + \sigma_2^+) \\
0 & 0 & 0 & 1 & \ldots & 0 & 0 & a_{d,d}^2 \\
\vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots \\
0 & 0 & 0 & 0 & \ldots & 1 & 0 & a_{d,d}^\ell (\zeta_\ell + \sigma_\ell^+) \\
0 & 0 & 0 & 0 & \ldots & 0 & 1 & a_{d,d}
\end{pmatrix} = 2\ell,$$

as the final matrix is in $M_{2\ell}(\mathbb{C})$.

- If $\ell = n$, it is of maximal rank if and only if

$$\sum_{j=1}^n a_{d,d}^j (\zeta_j + \sigma_j^+) \neq 0. \quad (3.9)$$
Indeed, from (3.8), this is equivalent to have \( \text{Rank} \left( A_{2n} \right) = 2n \). Yet,

\[
\begin{align*}
\text{Rank} & (A_{2n}^1, B_n) \\
= & \begin{pmatrix}
1 & 0 & 0 & 0 & \ldots & 0 & a^1_{d,d} \zeta_1 & -\sigma_1^+ & 0 & \ldots & 0 & 0 \\
0 & 0 & 0 & 0 & \ldots & 0 & a^1_{d,d} & 1 & 0 & \ldots & 0 & 0 \\
-1 & 1 & 0 & 0 & \ldots & 0 & a^2_{d,d} \zeta_2 & 0 & -\sigma_2^+ & \ldots & 0 & 0 \\
0 & 0 & 0 & 0 & \ldots & 0 & a^2_{d,d} & 0 & 1 & \ldots & 0 & 0 \\
\vdots & & & & & \vdots & & & & \vdots & & \ddots \\
0 & \ldots & -0 & 0 & \ldots & -1 & a^n_{d,d} \zeta_n & 0 & \ldots & 0 & -\sigma_n^+ \\
0 & \ldots & 0 & 0 & \ldots & 0 & a^n_{d,d} & 0 & \ldots & 0 & 0 & 1 \\
\end{pmatrix}
\end{align*}
\]

and we see that (3.9) is a necessary and sufficient condition to obtain the rank condition (2.17).

Let us prove that (3.9) is always satisfied. If not, we have

\[
\sum_{j=1}^{n} a^j_{d,d} \text{Im} \zeta_j = - \sum_{j=1}^{n} a^j_{d,d} \text{Im} \sigma_j^+.
\]

Yet, \( \text{Im} \sigma_j^+ = - \text{Im} \zeta_j + \text{Re} \alpha_j \). This implies \( \sum_{j=1}^{n} a^j_{d,d} \text{Re} \alpha_j = 0 \). As \( \text{Re} \alpha_j \geq 0 \) and \( a^j_{d,d} > 0 \) for all \( j \in \{1, \ldots, n\} \), then \( \text{Re} \alpha_j = 0 \). Hence, both roots \( \sigma_j^+ \) and \( \sigma_j^- \) have the same imaginary part, for all \( j \in \{1, \ldots, n\} \), in contradiction with having \( \{1, \ldots, n\} \subset \Sigma^0 \).

As a result, the covering condition holds in this case.

**Third case.** In this case, we assume that \( \text{Card} \Sigma^+ = 1 \) and \( \text{Card} \Sigma^0 = n - 1 \). In such a situation, the matrix has only \( 2n - 1 \) columns, and from Remark 2.7, the covering condition fails to hold.

**Fourth case.** We finally assume \( \text{Card} \Sigma^+ = 1 \) and \( \text{Card} \Sigma^0 < n - 1 \) (or equivalently \( \text{Card} \Sigma^- \geq 1 \)). Let \( \ell = \text{Card} \Sigma^0 \) and assume, without any loss of generality, \( \{1, \ldots, \ell\} = \Sigma^0 \), \( \{\ell + 1, \ldots, n - 1\} = \Sigma^- \), and \( \{n\} = \Sigma^+ \). Then the matrix \( M \) reads

\[
M = (A \quad B)
\]
where

\[
A = \begin{pmatrix}
M_1^1 & \cdots & M_1^n \\
\vdots & \ddots & \vdots \\
M_n^1 & \cdots & M_n^n
\end{pmatrix} =
\begin{pmatrix}
1 & 0 & 0 & \cdots & 0 & a_{d,d}^1 \\
0 & 0 & 0 & \cdots & 0 & a_{d,d}^1 \\
-1 & 1 & 0 & \cdots & 0 & a_{d,d}^2 \\
0 & 0 & 0 & \cdots & 0 & a_{d,d}^2 \\
\vdots & \ddots & \ddots & \vdots & \vdots & \vdots \\
0 & \cdots & 0 & 0 & -1 & a_{d,d}^n \\
0 & \cdots & 0 & 0 & 0 & a_{d,d}^n
\end{pmatrix} \in \mathcal{M}_{2n,n}(\mathbb{C}),
\]

and

\[
B = \begin{pmatrix}
M_1^2 & \cdots & M_{n-1}^2 \\
0 & \cdots & 0 \\
0 & \cdots & 0
\end{pmatrix} =
\begin{pmatrix}
\begin{pmatrix}
\begin{pmatrix}
-\sigma_1^* & 0 & 0 & \cdots & 0 & 0 \\
1 & \ddots & 0 & \vdots & \vdots & \vdots \\
0 & \ddots & -\sigma_1^* & 0 & \cdots & 0 \\
0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
0 & \cdots & 0 & 0 & -1 & 0 \\
0 & \cdots & 0 & 0 & 0 & 0 \\
0 & \cdots & 0 & 0 & 0 & 0
\end{pmatrix}
\end{pmatrix} \in \mathcal{M}_{2n,2n-\ell-2}(\mathbb{C}),
\]

as \(M_n^2 = \emptyset\). We shall make operations on lines and columns to compute the rank of \(M\). First, note that using the last line of \(M\), we obtain \(\text{Rank } M = \text{Rank } (A' B)\), with

\[
A' = \begin{pmatrix}
1 & 0 & 0 & \cdots & 0 & 0 \\
0 & 0 & 0 & \cdots & 0 & 0 \\
-1 & 1 & 0 & \cdots & 0 & 0 \\
0 & 0 & 0 & \cdots & 0 & 0 \\
\vdots & \ddots & \ddots & \vdots & \vdots & \vdots \\
0 & \cdots & 0 & 0 & -1 & 0 \\
0 & \cdots & 0 & 0 & 0 & 1
\end{pmatrix},
\]

Then using the even lines of \(B\), as the associated lines of \(A'\) are only made of zeros, we obtain \(\text{Rank } M = \text{Rank } (A' B')\), with

\[
B' = \begin{pmatrix}
0 & 0 & 0 & \cdots & 0 & 0 \\
1 & \ddots & 0 & \vdots & \vdots & \vdots \\
0 & \ddots & 0 & \cdots & 0 & 0 \\
0 & 0 & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 & 0 & 0 \\
\vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\
0 & \cdots & 0 & 1 & 0 & 0 \\
0 & \cdots & 0 & 0 & -1 & 0 \\
0 & \cdots & 0 & 0 & 0 & 0 \\
0 & \cdots & 0 & 0 & 0 & 0
\end{pmatrix},
\]

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and we see that the rank of \((A' B')\), is equal to 2n.

**Conclusion.** As the four cases we considered are exhaustive, we find that we have to construct a weight function \(\varphi\) such that the first and third cases described above do not occur, meaning that we require

\[
\text{Card } \Sigma^+(\rho') \leq 1, \quad \forall \rho' \in I, \tag{3.10}
\]

and moreover

\[
\text{Card } \Sigma(\rho') = 1 \implies \text{Card } \Sigma^0(\rho') < n - 1 \quad \text{(or equivalently Card } \Sigma^-(\rho') \geq 1). \tag{3.11}
\]

Let \(i_0 \in \{1, \ldots, n\}\) be fixed. First note that if we have, for all \(i \neq i_0\),

\[
-\tau(\partial_{x_d} \varphi_i + \sum_{j=1}^{d-1} a_{d,j}^i / a_{d,d}^i \partial_{x_j} \varphi_i) < 0, \tag{3.12}
\]

then (3.10) is satisfied as \(\text{Im } \sigma^i_{-\tau} = -\tau(\partial_{x_d} \varphi_i + \sum_{j=1}^{d-1} a_{d,j}^i / a_{d,d}^i \partial_{x_j} \varphi_i) - \text{Re } \alpha_i\), with \(\text{Re } \alpha_i \geq 0\). Second, observe that \(\text{Im } \sigma^i_{-\tau} \geq 0\) implies

\[
-\tau(\partial_{x_d} \varphi_{i_0} + \sum_{j=1}^{d-1} a_{d,j}^{i_0} / a_{d,d}^{i_0} \partial_{x_j} \varphi_{i_0}) \geq \text{Re } \alpha_{i_0} \geq 0.
\]

Hence, if we construct a weight function \(\varphi\) satisfying

\[
-\tau(\partial_{x_d} \varphi_{i_0} + \sum_{j=1}^{d-1} a_{d,j}^{i_0} / a_{d,d}^{i_0} \partial_{x_j} \varphi_{i_0}) \geq \text{Re } \alpha_{i_0}
\]

\[
\implies \left\{ \begin{array}{l}
-\tau(\partial_{x_d} \varphi_{i_1} + \sum_{j=1}^{d-1} a_{d,j}^{i_1} / a_{d,d}^{i_1} \partial_{x_j} \varphi_{i_1}) < -\text{Re } \alpha_{i_1}, \\
-\tau(\partial_{x_d} \varphi_{i} + \sum_{j=1}^{d-1} a_{d,j}^{i} / a_{d,d}^{i} \partial_{x_j} \varphi_{i}) < \text{Re } \alpha_{i}, \quad \forall i \neq i_0, i_1,
\end{array} \right. \tag{3.13}
\]

for some \(i \neq i_0\), then both (3.10) and (3.11) hold. Observe that (3.13) can be achieved by requiring (3.12) and additionally

\[
\left(\text{Re } \alpha_{i_0}\right) \frac{\partial_{x_d} \varphi_{i_0} + \sum_{j=1}^{d-1} a_{d,j}^{i_0} / a_{d,d}^{i_0} \partial_{x_j} \varphi_{i_0}}{\partial_{x_d} \varphi_{i_1} + \sum_{j=1}^{d-1} a_{d,j}^{i_1} / a_{d,d}^{i_1} \partial_{x_j} \varphi_{i_1}} < \text{Re } \alpha_{i_0}. \tag{3.14}
\]

In order to fix ideas, assume that \(\varphi_k = \varphi_k(x_d)\) does not depend on the variable \(x'\). Then, conditions (3.12) and (3.14) read

\[
\forall i \neq i_0, \partial_{x_d} \varphi_i > 0, \text{ and } \frac{\partial_{x_d} \varphi_{i_0}}{\partial_{x_d} \varphi_{i_1}} < K,
\]

where \(K\) is a positive constant that only depends on the coefficients \(a_{d,j}^{i_0}\) and \(a_{d,j}^{i_1}\). Hence, if we choose a weight function \(\varphi\) such that, near the interface,

\[
\partial_{x_d} \varphi_{i_0} < 0, \text{ and } \partial_{x_d} \varphi_i > 0, \quad \forall i \neq i_0, \text{ and moreover satisfying } \partial_{x_d} \varphi_{i} \gg \partial_{x_d} \varphi_{i_0} \text{ for some } i_1 \neq i_0,
\]

then the covering condition is satisfied. Allowing back a dependance with respect to the variable \(x'\) is possible, for instance, if we impose \(|\nabla' \varphi_k| \ll |\partial_{x_d} \varphi_k|\), for all \(k \neq i_0\).

**Remark 3.1.** In applications, this means that if we want to observe the interface, according to Theorem 2.6, the observation has to be made from at least \(n - 1\) sides of \(I\) (we recall that in Carleman estimates and applications, the observation region corresponds to regions where the weight function is the largest).

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3.2 On the optimality of the observation regions for the transmission problem

In this section, we discuss the optimality of the above conditions on the weight function. First, observe that in the case of two operators \( n = 2 \), we precisely recover the condition of [7], which is proven to be optimal in the case of operators with constant coefficients in [22]. Second, in some particular geometric configurations, note that if we observe from only \( n - 2 \) sides of \( I \), then the unique continuation property may fail, which prevents the possibility of proving a Carleman estimate. We consider \( \Omega_k = (\mathbb{R}/2\pi \mathbb{Z}) \times (0, \pi) \), for \( k \in \{1, \ldots, n\} \), \( n \in \mathbb{N}^* \), \( n \geq 3 \), and \( I = (\mathbb{R}/2\pi \mathbb{Z}) \times \{0\} \). Take \( C_k = \begin{pmatrix} 1 & 0 \\ 0 & c_k \end{pmatrix} \), such that \( c_k^{-1/2} \in \mathbb{N}^* \), and consider the diagonal operator

\[
Q = \begin{pmatrix}
-\text{div} (C_1 \nabla) & 0 & \ldots & 0 \\
0 & -\text{div} (C_2 \nabla) & 0 & 0 \\
\vdots & \ddots & \ddots & 0 \\
0 & 0 & \ldots & -\text{div} (C_n \nabla)
\end{pmatrix}
\]

with domain

\[
D(Q) = \left\{ (u_1, \ldots, u_n) \in \bigoplus_{k=1}^n H^2(\Omega_k), u_1 = \cdots = u_n \text{ on } I, \sum_{k=1}^n c_k \partial_{x_2} u_k|_{x_2=0} = 0 \text{ on } I \right\}.
\]

We have the following proposition on the eigenfunctions of \( Q \).

**Proposition 3.2.** For all \( j \in \mathbb{N} \) and \( \ell \in \{2, \ldots, n-1\} \), the function

\[
\phi_j = \begin{pmatrix}
0 \\
\vdots \\
0 \\
e^{ijx_1} \sin(c_{\ell}^{-1/2} jx_2) \\
e^{ijx_1} \sin(c_{\ell+1}^{-1/2} jx_2) \\
\vdots \\
e^{ijx_1} \sin(c_{n-1}^{-1/2} jx_2) \\
-c_n^{1/2} \sum_{k=\ell}^{n-1} c_k^{1/2} e^{ijx_1} \sin(c_k^{-1/2} jx_2)
\end{pmatrix}
\]

where the first \( \ell - 1 \) components are equal to zero, is an eigenfunction for System (3.16) associated with the eigenvalues \( j^2 \).

If \( \ell \in \{1, \ldots, n-1\} \), the eigenfunction has \( \ell - 1 \) vanishing components. In the particular case \( \ell = n - 1 \), the eigenfunction has \( n - 2 \) vanishing components. Thus, Proposition 3.2 shows that the unique continuation property fails to hold from less than \( n - 1 \) sides of the interface, due to the presence of such invisible modes. Since a Carleman estimate near the interface as in Theorem 2.6 implies the unique continuation property, the derivation of the Carleman estimate cannot be achieved in this geometrical configuration. Using Remark 3.1, this means that in (3.15), having \( \partial_{x_2} \phi_{i_0} > 0 \), for \( i \in J \subset \{1, \ldots, n\} \) with \( \text{Card} J \geq n - 1 \), is necessary. However, in the example (3.16), this is mainly due to the symmetry of the domains \( \Omega_k \). The investigation of general configurations where the unique continuation property holds true remains an interesting question.
4 Carleman estimate in a neighborhood of the interface

4.1 Semi-classical calculus

4.1.1 Classes of symbols

We recall some classes of pseudo-differential operators that we use in what follows. This allows us to introduce some important notation. As above, we write \( \rho = (x, \xi, \tau) \in \overline{U} \times \mathbb{R}^d \times \mathbb{R}^+ \) and \( \rho' = (x', \xi', \tau) \in \overline{U} \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \).

**Definition 4.1.** The symbol class \( S^m_r \) is the space of \( a(\rho) \in C^\infty(\mathbb{R}^d \times \mathbb{R}^d) \) that depends on the large parameter \( \tau \geq 1 \) satisfying for all multi-indices \( \alpha, \beta \in \mathbb{N}^d \)

\[
|\partial_\xi \partial_\xi a(\rho)| \leq C_{\alpha, \beta} \lambda^{m-|\beta|}, \quad \text{for all } x \in \mathbb{R}^d, \xi \in \mathbb{R}^d, \tau \geq 1,
\]

where \( \lambda \) is the order function \( \lambda = (\tau^2 + |\xi|^2)^{1/2} \). The principal symbol of such \( a \), denoted by \( \sigma(a)(\rho) \) is the class of \( a \) in the quotient space \( S^m_r/S^{m-1}_r \).

We also introduce the tangential symbol class \( S^m_{r, \tau} \) as the space of \( a(\rho') \in C^\infty(\mathbb{R}^d \times \mathbb{R}^{d-1}) \) that depends on the large parameter \( \tau \geq 1 \) satisfying for all multi-indices \( \alpha \in \mathbb{N}^d, \beta \in \mathbb{N}^{d-1} \)

\[
|\partial_\xi \partial_\xi a(\rho)| \leq C_{\alpha, \beta} \lambda^{m-|\beta|}_T, \quad \text{for all } x \in \mathbb{R}^d, \xi' \in \mathbb{R}^{d-1}, \tau \geq 1,
\]

where \( \lambda_T \) is the order function \( \lambda_T = (\tau^2 + |\xi|^2)^{1/2} \). The principal symbol of such \( a \), also denoted by \( \sigma(a)(\rho) \) is the class of \( a \) in the quotient space \( S^m_{r, \tau}/S^{m-1}_{r, \tau} \).

We shall consider symbols that are polynomials in the \( \xi_d \)-variable with coefficients in the class of tangential symbols. More precisely, we consider \( S^m_{r, \tau} \) the space of \( a(\rho) \in C^\infty(\mathbb{R}^d \times \mathbb{R}^d) \) that depends on the large parameter \( \tau \geq 1 \), and such that

\[
a(\rho) = \sum_{j=0}^{m} a_j(\rho') \xi_d^j, \quad a_j \in S^{m-j}_{T, \tau}.
\]

The principal symbol of such \( a \), denoted by \( \sigma(a)(\rho) \) is defined by

\[
\sigma(a)(\rho) = \sum_{j=1}^{m} \sigma(a_j)(\rho') \xi_d^j.
\]

It can be understood as a representative of \( a \) in \( S^m_{r, \tau}/S^{m-1}_{r, \tau} \).

We also introduce poly-homogeneous symbols.

**Definition 4.2.** We say that \( a \in S^m_{r, \text{cl}} \) (resp. \( S^m_{T, \tau, \text{cl}} \)) if there exist \( a_j \in S^{m-j}_{r}, \) (resp. \( S^{m-j}_{T, \tau} \)), \( j \in \mathbb{N} \), homogeneous of degree \( m - j \) in \((\xi, \tau)\) (resp. \((\xi', \tau)\)) such that, for all \( j_0 \in \mathbb{N} \),

\[
a - \sum_{j=0}^{j_0} a_j \in S^{m-j_0-1}_r, \quad \text{(resp. } S^{m-j_0-1}_{T, \tau}) \).
\]

We say that \( a \in S^m_{r, \text{cl}} \) if

\[
a(\rho) = \sum_{j=0}^{m} a_j(\rho') \xi_d^j, \quad \text{with } a_j \in S^{m-j}_{T, \tau, \text{cl}}.
\]
4.1.2 Semi-classical pseudo-differential operators

For \( u \) in the Schwartz space \( \mathcal{S}(\mathbb{R}^d) \), we denote by \( \hat{u} \) the Fourier transform, that is,
\[
\hat{u}(\xi) = \int_{\mathbb{R}^d} e^{-ix \cdot \xi} u(x)dx.
\]

**Definition 4.3.** For \( a \in \mathcal{S}_T^m \) (resp. \( \mathcal{S}_{T,cl}^m \)) we define the pseudo-differential operator
\[
\text{Op}(a)u(x) = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{ix \cdot \xi} a(x, \xi, \tau) \hat{u}(\xi)d\xi = \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} e^{i(x-y) \cdot \xi} a(x, \xi, \tau)u(y)dyd\xi,
\]
for all \( u \in \mathcal{S}(\mathbb{R}^d) \), and we write \( \text{Op}(a) \in \Psi_T^m \) (resp. \( \Psi_{T,cl}^m \)). The principal symbol of the pseudo-differential operator \( \text{Op}(a) \) is \( \sigma(\text{Op}(a)) = \sigma(a) \) (see Definition 4.1 and 4.2). We also define tangential pseudo-differential associated with a symbol \( b \in \mathcal{S}_{T,\tau}^m \) (resp. \( \mathcal{S}_{T,\tau,cl}^m \)) by
\[
\text{Op}_{T,\tau}(b)u(x) = \frac{1}{(2\pi)^{d-1}} \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^{d-1}} e^{i(x-y) \cdot \xi} b(x, \xi', \tau)u(y', \xi)d\xi'd\xi,
\]
for \( u \in \mathcal{S}(\mathbb{R}^d) \) and \( x \in \mathbb{R}^d \), and we write \( \text{Op}_{T,\tau}(b) \in \Psi_{T,\tau}^m \) (resp. \( \Psi_{T,\tau,cl}^m \)). The principal symbol of the pseudo-differential operator \( \text{Op}_{T,\tau}(b) \) is \( \sigma(\text{Op}_{T,\tau}(b)) = \sigma(b) \) (see Definition 4.1 and 4.2).

4.1.3 Sobolev norms

For \( s \in \mathbb{N}^* \) and \( \tau \geq 1 \) we introduce the following parameter dependent Sobolev norms
\[
|||\cdot|||_{s,\tau}^2 = \sum_{l=0}^{s} \tau^{2l} |||\cdot|||_{H^l(\Omega_k)}^2, \quad \text{and} \quad |||\cdot|||_{s,\tau}^2 = \sum_{l=0}^{s} \tau^{2l} |||\cdot|||_{H^l(\mathcal{I})}^2,
\]
where \( |||\cdot|||_{H^l(\Omega_k)} \) and \( |||\cdot|||_{H^l(\mathcal{I})} \) denotes the standard Sobolev spaces in \( \Omega_k \) and on the interface \( \mathcal{I} \) respectively. We define the Sobolev spaces \( H^m_{s,\tau}(\Omega_k) \) and \( H^m_{s,\tau}(\mathcal{I}) \) as the completion of \( C^\infty(\Omega_k) \) and \( C^\infty(\mathcal{I}) \), the spaces of smooth functions, with respect to the norms (4.2). Algebraically, the spaces \( H^m_{s,\tau}(\Omega_k) \) and \( H^m_{s,\tau}(\mathcal{I}) \) are equal to the standard Sobolev spaces. However, they are not endowed with equivalent norm in the semi-classical limit \( \tau \to +\infty \). As we deal with operators with orders \( 2m_k \geq 2 \), we shall need to estimate traces of the solution and its iterated normal derivatives at \( \mathcal{I} \). Hence, we introduce the Hilbert sum
\[
H^m_{s,\tau} = \bigoplus_{j=0}^{m} H^{m-j+s}_{s,\tau}(\mathcal{I}),
\]
edowed with the norm
\[
|||U|||_{m,s,\tau}^2 = \sum_{j=0}^{m} |||u_j|||_{m-j+s,\tau}^2, \quad \text{with} \quad U = (u_0, \ldots, u_m).
\]

We shall also apply this norm to the following vectors composed of the various traces of iterated normal derivatives of a function \( u \in C^\infty(\Omega_k) \) as
\[
\text{tr}^m(u) = (u_{iz}, D_{iz}u_{iz}, \ldots, D_{\nu}^m u_{iz}), \quad \text{where} \quad D_{\nu} = -i\partial_{\nu} \text{ and } \nu \in N^*_k(\mathcal{I}),
\]
(for the definition of \( N^*_k(\mathcal{I}) \) we refer to the beginning of Section 2.2). However, for the sake of simplicity, we shall write \( |\text{tr}^m u|_{m,s,\tau} \) instead of \( |||\text{tr}^m(u)|||_{m,s,\tau} \), whenever no ambiguity may occur.
We introduce the space of smooth functions in the half space, with rapid decay at infinity
\[ \mathcal{S}^d(\mathbb{R}^d_+) = \{ u |_{x_d > 0}, u \in \mathcal{S}(\mathbb{R}^d) \}, \]
that is the space of restrictions to the half space of functions in the Schwartz space. Pseudo-differential operators that behave polynomially in the \( \xi_d \) direction such as (4.1) may act on functions of \( \mathcal{S}(\mathbb{R}^d_+) \).

Hence, we introduce the norms in \( \mathbb{R}^d_+ \)
\[ ||u||^2_{m,s,\tau} = ||\text{Op}_T(\lambda^s_T)u||^2_{m,\tau}, \quad u \in \mathcal{S}^d(\mathbb{R}^d_+), \]
with \( ||.||_{m,s,\tau} \) introduced in (4.2), and the norm at the interface \( \mathcal{I} = \{ x_d = 0 \} \simeq \mathbb{R}^{d-1} \)
\[ |U|^2_{m,s,\tau} = \sum_{j=0}^m |\text{Op}_T(\lambda^s_T)u_j|^2_{m-j,\tau}, \quad U = (u_0, \ldots, u_m) \in (\mathcal{S}(\mathbb{R}^{d-1}))^{m+1}, \]
with \( |.|_{m-j,\tau} \) given by (4.2). In what follows, we shall denote the inner product of \( L^2(\mathbb{R}^d_+) \) and \( L^2(\mathbb{R}^{d-1}) \) by
\[ (f,g) = \int_{\mathbb{R}^d_+} f \overline{g}, \quad (u,v)_\partial = \int_{\mathbb{R}^{d-1}} u\overline{v}, \]
respectively, for \( f, g \in L^2(\mathbb{R}^d_+) \) and \( u, v \in L^2(\mathbb{R}^{d-1}) \simeq L^2(\mathcal{I}) \). We shall also write
\[ ||f||^2_+ := \int_{\mathbb{R}^d_+} |f|^2. \]
We state the following continuity results for the classes of pseudo-differential operators introduced in Section 4.1.2.

**Proposition 4.4.** Let \( a(\rho) \in \mathcal{S}_c^{m,s} \). Then, for every \( m' \in \mathbb{N} \) and \( s' \in \mathbb{R} \) there exists a constant \( C > 0 \) such that
\[ ||\text{Op}(a)u||_{m',s',\tau} \leq C ||u||_{m'+m,s'+s,\tau}, \]
for all \( u \in \mathcal{S}^d(\mathbb{R}^d_+) \).

### 4.2 Sub-elliptic estimate near the interface

The following estimation is classical and based on integration by parts. It describes how the sub-ellipticity property yields an estimation, here with the case of a quadratic form \( \text{Re} \left( \text{Av}, iBv \right)_+ \).

**Lemma 4.5.** Let \( U \) be an open subset of \( \nabla^+ \). Let \( a \in \mathcal{S}^{m,0}_c \) and \( b \in \mathcal{S}^{-1,1}_c \) be real symbols homogeneous of degree \( m \) in \( (\xi, \tau) \). Set
\[ Q_{a,b}(v) = 2 \text{Re} \left( \text{Av}, iBv \right)_+, \quad A = \text{Op}(a), \ B = \text{Op}(b). \]

Assume that
\[ a(\rho) = b(\rho) = 0 \implies \{ a, b \} > 0 \]
for \( x \in \overline{U} \), for \( (\xi, \tau) \neq 0 \). Then there exists \( C, C', \tau_0 > 0 \) such that
\[ C||v||^2_{m,\tau} \leq C' \left( ||Av||^2_+ + ||Bv||^2_+ + ||\text{tr}v||^2_{m-1,1/2,\tau} + \tau ||Q_{a,b}(v) - \text{Re} B_{a,b}(v)|| \right), \]
for \( \tau \geq \tau_0 \), for all \( v \in \mathcal{C}^\infty(\mathbb{R}^d_+) \) with \( \text{supp} \ v \subset U \), and where \( B_{a,b} \) is a quadratic form at the interface \( \{ x_d = 0 \} \), satisfying
\[ |B_{a,b}(v)| \leq C' ||\text{tr}v||^2_{m-1,1/2,\tau}. \]
A proof of this result can be found in [6].
4.3 An elliptic estimate near the interface

We consider, on \( \mathbb{R}^d_+ \),

\[
P_{k,\varphi} = e^{\tau \varphi_k} P_k e^{-\tau \varphi_k} \in \Psi^{2m_k,0},
\]

of principal symbol \( p_{k,\varphi}(\rho) = p_k(x, \xi + i\tau d\varphi_k(x)) \in \mathcal{S}^{2m_k,0} \), where \( p_k \) denotes the principal symbol of \( P_k \).

We also define at the boundary

\[
T_{k,\varphi}^i = e^{\tau \varphi_k} T_k^i e^{-\tau \varphi_k} \in \Psi^{\beta_k,0},
\]

of principal symbol \( t_{k,\varphi}^i(\rho) = t_k^i(x, \xi + i\tau d\varphi_k(x)) \in \mathcal{S}^{\beta_k,0} \), where \( t_k^i \) denotes the principal symbol of \( T_k^i \).

Considering an operator with principal symbol with roots that have negative imaginary parts, we may obtain an estimate of all the relevant traces at the boundary without the use of any boundary condition. This is the result of the following lemma, which proof can be found in [6].

**Lemma 4.6.** Let \( h(\rho', \xi_d) \in \mathcal{S}(\mathbb{R}^d_+)^k \), with \( k \geq 1 \), be a monic polynomial function in \( \xi_d \) with homogeneous coefficients in \( (\xi', \tau) \) and \( H = \text{Op}(h) \). Let \( U \) be a conic open subset of \( \mathcal{V}^+ \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \). Assume that all the roots of \( h \) have negative imaginary part for all \( \rho' \in U \). Then \( \chi(\rho') \in \mathcal{S}(\mathbb{R}^d_+)^0 \), homogeneous, be such that \( \text{supp} \chi \subset U \), and let \( N \in \mathbb{N} \). There exist \( C > 0 \) and \( \tau_0 > 0 \) such that

\[
\| \text{Op}_\tau(\chi) w \|_{k,\tau}^2 + | \text{tr}(\text{Op}_\tau(\chi) w) |_{k-1,1/2,\tau}^2 \leq C ( \| H \text{Op}_\tau(\chi) w \|_{\tau}^2 + \| w \|_{k-N,\tau}^2 + | \text{tr}(w) |_{k-1-N,\tau}^2 ),
\]

for all \( w \in \mathcal{J}(\mathbb{R}^d_+) \) and \( \tau \geq \tau_0 \).

Observe that this lemma provides an estimate on all the traces at the boundary, up to microlocal remainder terms, which will be absorbed when patching all the microlocal estimates on the whole phase-space, by taking \( \tau \) sufficiently large.

Below, we consider operators that admit roots with non-negative imaginary parts. The covering condition imposed at the multi-interface \( I \) on the set of operators \( (P_k, T_k^j, \varphi) \) is then a key element to obtain an estimation.

4.4 Interface quadratic forms

**Definition 4.7.** For \( w = (w_1, \ldots, w_n) \in (\mathcal{J}(\mathbb{R}^d_+))^n \), \( N \in \mathbb{N} \) we define the following quadratic forms

\[
G(w) := \sum_{s=1}^N \sum_{k=1}^n A_k^s w_k_{|\varepsilon_d=0} \sum_{k=1}^n B_k^s w_k_{|\varepsilon_d=0} ,
\]

with \( A_k^s = \text{Op}(a_k^s) \), and \( B_k^s = \text{Op}(b_k^s) \). We say that \( G \) is an interface quadratic form of type \((2m_1 - 1, \ldots, 2m_n - 1, \sigma)\) if, for each \( s \in \{1, \ldots, N\} \) we have \( a_k^s, b_k^s \in \mathcal{S}^{2m_k-1,\sigma_k} \), for all \( k \in \{1, \ldots, n\} \), with \( \sigma_1 + \cdots + \sigma_n = 2\sigma \). Moreover, for \( z = (z_1, \ldots, z_n), \tilde{z} = (\tilde{z}_1, \ldots, \tilde{z}_n) \in \mathbb{C}^{2m_1} \times \cdots \times \mathbb{C}^{2m_n} \), where \( z_k = (z_k^0, z_k^1, \ldots, z_k^{2m_k-1}) \) and \( \tilde{z}_k = (\tilde{z}_k^0, \tilde{z}_k^1, \ldots, \tilde{z}_k^{2m_k-1}) \), we define

\[
\Sigma_G(\rho', z, \tilde{z}) = \sum_{s=1}^N \sum_{k=1}^n \sum_{j=1}^n a_{k,j}^s \rho'_{j,k} + \sum_{k=1}^n \sum_{j=1}^n b_{k,j}^s \rho'_{j,k},
\]

where, for a symbol \( a(\rho) = \sum_{j=0}^p a_j(\rho') \xi_d^j \in \mathcal{S}_{r,cl}^{p,s} \), we set

\[
\Sigma_a(\rho', z) = \sum_{j=0}^p \sum_{s=1}^N \sum_{k=1}^n a_{j,k} \rho'_{j,k}, \quad \text{for } z = (z_0, \ldots, z_p) \in \mathbb{C}^{p+1}.
\]
Definition 4.8. Let \( W \) be an open conic set in \( \mathbb{R}^{d-1} \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \) and let \( \mathcal{G} \) be an interface quadratic form of type \( (2m_1 - 1, \ldots, 2m_n - 1, \sigma) \) associated with the bilinear symbol \( \Sigma_\mathcal{G}(\rho', z, \bar{z}) \). We say that \( \mathcal{G} \) is positive definite in \( W \) if there exists \( C > 0 \) and \( R > 0 \) such that

\[
\Re \Sigma_\mathcal{G}(\rho'|_{z=0}, z, \bar{z}) \geq C \sum_{k=1}^{n} \sum_{j=0}^{2m_k-1} \lambda_T^{2m_k-1-j+\sigma_k}|z_k|^2,
\]

for \( z = (z_1, \ldots, z_n) \in \mathbb{C}^{2m}, \ z_k = (z_0^k, \ldots, z_{2m_k-1}^k) \in \mathbb{C}^{2m_k}, \tau \geq 0, \lambda_T \geq R, \rho'|_{z=0} \in W. \)

We have the following Gårding-type inequality. The proof follows [7].

Lemma 4.9. Let \( W \) be an open conic set in \( \mathbb{R}^{d-1} \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \) and let \( \mathcal{G} \) be an interface quadratic form of type \( (2m_1 - 1, \ldots, 2m_n - 1, \sigma) \) that is positive definite in \( W \). Let \( \chi \in \mathcal{S}_T^0, \tau \) be a homogeneous symbol satisfying \( \text{supp} \chi|_{z=0} \subset W \) and let \( M \in \mathbb{N} \). There exists \( C > 0, C' > 0 \) and \( \tau_0 > 0 \) such that

\[
\Re \mathcal{G}(\text{Op}_T(\chi)u) \geq C \sum_{k=1}^{n} |\text{tr} \text{Op}_T(\chi)u|^2_{2m_k-1, \sigma_k, \tau} - C' \sum_{k=1}^{n} |\text{tr} u_k|^2_{2m_k-1, \sigma_k-M, \tau}, \tag{4.5}
\]

for \( u = (u_1, \ldots, u_k) \in (\mathcal{G}(\mathcal{S}_+^d))^n, \tau \geq \tau_0. \)

Proof. Using Definition 4.7, \( \mathcal{G} \) reads

\[
\mathcal{G}(u) = \sum_{s=1}^{N} \left( \sum_{k=1}^{n} A_k^s u_{k|_{z=0}} \sum_{k=1}^{n} B_k^s u_{k|_{z=0}} \right)_{\partial}, \quad \text{with} \ A_k^s, B_k^s \in \Psi^{2m_k-1, \sigma_k}.
\]

Using tangential pseudo-differential calculus, with classical symbols, there exist \( a_{k,j}^s, b_{k,j}^s \in \mathcal{S}_T^{0, \tau, \text{cl}} \) such that

\[
A_k^s = \sum_{j=0}^{2m_k-1} \text{Op}_T(a_{k,j}^s) \text{Op}_T(\lambda_T^{2m_k-1-j+\sigma_k})D_d^j, \quad B_k^s = \sum_{j=0}^{2m_k-1} \text{Op}_T(b_{k,j}^s) \text{Op}_T(\lambda_T^{2m_k-1-j+\sigma_k})D_d^j.
\]

Denoting \( a \# b, a \in \mathcal{S}_T^{m, \tau, \text{cl}}, b \in \mathcal{S}_T^{m', \tau, \text{cl}} \) the product of symbols, that is, for all \( M \in \mathbb{N} \),

\[
a \# b(\rho') = \sum_{|\alpha|<N} \frac{(-i)^{|\alpha|}}{\alpha!} \partial_\xi^\alpha a(\rho') \partial_\xi^\alpha b(\rho') + r_M, \quad r_M \in \mathcal{S}_T^{m+m'-M},
\]

and \( a^* \) the adjoint symbol, that is, for all \( M \in \mathbb{N} \),

\[
a^*(\rho') = \sum_{|\alpha|<M} \frac{(-i)^{|\alpha|}}{\alpha!} \partial_\xi^\alpha \partial_\xi^\alpha a(\rho') + r_M, \quad r_M \in \mathcal{S}_T^{m-M},
\]

the quadratic form \( \mathcal{G} \) can be written as

\[
\mathcal{G}(u) = \sum_{s=1}^{N} \left( \sum_{k=1}^{n} \sum_{j=0}^{2m_k-1} \text{Op}_T(u_{k,j}) \text{Op}_T(\lambda_T^{2m_k-1-j+\sigma_k})D_d^j u_{k|_{z=0}} \sum_{k=1}^{n} \sum_{j=0}^{2m_k-1} \text{Op}_T(b_{k,j}) \text{Op}_T(\lambda_T^{2m_k-1-j+\sigma_k})D_d^j u_{k|_{z=0}} \right)_{\partial}
\]

\[
\quad = \sum_{k,\lambda=1}^{n} \sum_{j=0}^{2m_k-1} \sum_{j'=0}^{2m_{\lambda'}-1} \left( \text{Op}_T(\gamma_{j,j'}) \text{Op}_T(\lambda_T^{2m_k-1-j+\sigma_k})D_d^j u_{k|_{z=0}} \right)_{\partial} \quad \text{with} \quad \gamma_{j,j'} \in \mathcal{S}_T^{0, \tau, \text{cl}}.
\]
Then, by continuity, (4.7) is true in a neighborhood of 

\[ g_{j,j'} = \sum_{s=1}^{N} (b_{k,j})^* a_{k,j}'. \]

We recast this equality into a system formalism. We then consider the following matrix symbol

\[
G(\rho') = \left( \begin{array}{ccc}
g^{1,1}(\rho') & \cdots & g^{1,n}(\rho') \\
\vdots & \ddots & \vdots \\
g^{n,1}(\rho') & \cdots & g^{n,n}(\rho')
\end{array} \right),
\]

\[
g^{i,i'} = \left( g^{i,i'}_{k,h}(\rho') \right)_{0 \leq i, i' \leq m_1 - 1}.
\]

It is then sufficient to follow the proof of Lemma 3.3 in [7].

With the covering condition, we have the following positivity result, at the symbol level. In the following section, this positivity property will yield an actual estimate at the interface by means of Lemma 4.9.

**Proposition 4.10.** Assume the covering condition of Definition 2.3 holds at \( \rho_0 \in \mathcal{L}^T (\mathcal{I}) \). There exist a conical neighborhood \( U \) of \( \rho_0 \) in \( \mathbb{V}^+ \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \), \( C > 0 \) such that

\[
C \sum_{j=1}^{m} t^{2(\gamma_j - 1/2)} \sum_{k=1}^{n} |\Sigma_{t,k}^{j}(\rho', z_k)|^2 + \sum_{k=1}^{n} \sum_{j=m+1}^{m_k} t^{2(m+m_k - j + 1/2)} |\Sigma_{c,\rho',z}^{j}(\rho', z_k)|^2 \\
\geq C \sum_{k=1}^{n} \sum_{j=0}^{m_k-1} t^{2(2m_k - 2 - j)} \|z_k\|^2,
\]

for all \( \rho' \in U \), for all \( z_k = (z_k^0, \ldots, z_k^{2m_k-1}) \in \mathbb{C}^{m_k} \).

**Proof.** As the covering condition is fulfilled at \( \rho_0 \in \mathcal{L}^T (\mathcal{I}) \), there exist an open conic neighborhood \( U \) of \( \rho_0 \) in \( \mathbb{V}^+ \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \) such that the rank condition (2.17) is satisfied at \( \rho' \), for every \( \rho' \in U \). Yet, consider the compact set \( \mathcal{K} := U \cap \mathbb{S}_{1}(|\xi'|^2 + \tau^2 = 1} \).

Let \( \rho' \in \mathcal{K} \). in view of (2.17), we have that \( M(\rho') \) is of maximal rank, that is \( M(\rho') = 2m \). Taking \( z = (z_1, \ldots, z_n) \) with \( z_k = (z_k^0, \ldots, z_k^{2m_k-1}) \in \mathbb{C}^{2m_k} \), we have

\[
\langle \sum_{k=1}^{m} \sum_{j=1}^{n} t^{2(\gamma_j - 1/2)} |\Sigma_{t,k}^{j}(\rho', z_k)|^2 + \sum_{j=m+1}^{m_k} t^{2(m+m_k - j + 1/2)} |\Sigma_{c,\rho',z}^{j}(\rho', z_k)|^2 \\
\geq C \sum_{k=1}^{n} \sum_{j=0}^{m_k-1} t^{2(2m_k - 2 - j)} \|z_k\|^2,
\]

Recalling the form of \( M \) in (2.16), we have

\[
\langle t^{i} M(\rho') z, t^{i} M(\rho') z \rangle \geq \|z\|^2 \|z\|_{\mathbb{C}^{2m}}.
\]

Then, by continuity, (4.7) is true in a neighborhood of \( \rho' \), and with a compactness argument, is true for all \( \rho' \in \mathcal{K} \). Yet, we define

\[
H_{\lambda_T}(\rho') = (x, \lambda_T \xi', \lambda_T \tau),
\]

where \( g_{j,j'}^{k,k'} \in \mathcal{S}_{T,\pi,cl}^0 \) is given by

\[
g_{j,j'}^{k,k'} = \sum_{s=1}^{N} (b_{k,j})^* a_{k,j}'.
\]
and thus for every $\rho' \in C$, we have $\tilde{\rho}' = H^\omega_{m'}\rho'$ with $\rho' := H_{m'}\tilde{\rho}'$. We set $\tilde{z}_k^j = \lambda_{m_k}^{2m_k-1/2-j} z_k^j$, $\tilde{z}_k = (\tilde{z}_k^0, \ldots, \tilde{z}_k^{2n_k-1})$ and $\tilde{z} = (\tilde{z}_1, \ldots, \tilde{z}_n)$. By homogeneity of the symbols, (4.7) yields

$$\sum_{j=1}^m | \sum_{k=1}^n \Sigma_{t_k, \nu}(\rho', \tilde{z}_k)|^2 + \sum_{j=0}^{n-1} | \sum_{k=1}^n \Sigma_{t_k, \nu}(\rho', \tilde{z}_k)|^2 \gtrsim \|\tilde{z}\|_{C^{2m}}^2,$$

which reads

$$\sum_{j=1}^m | \sum_{k=1}^n \lambda_T^{2m_k+1/2-\beta_j} \Sigma_{t_k, \nu}(\rho', \tilde{z}_k)|^2 + \sum_{j=0}^{n-1} | \sum_{k=1}^n \lambda_T^{m_k+1/2-j} \Sigma_{t_k, \nu}(\rho', \tilde{z}_k)|^2 \gtrsim \sum_{k=1}^n | \lambda_{m_k}^{2m_k-1/2-j} \tilde{z}_k^j|^2.$$

Using assumption (1.2), this yields the result. \hfill \Box

### 4.5 Estimate with the covering condition

The following proposition shows how the covering condition allows one to estimate all the traces at the interface. The estimate is microlocal near a point where the covering condition holds.

**Proposition 4.11.** Let $\rho'_0 = (x_0, \xi_0, \tau_0)$, $x_0 \in I$, such that the covering condition of Definition 2.3 holds at $\rho'_0$. Then, there exists a conic neighborhood $V$ of $\rho'_0$ in $V^+ \times \mathbb{R}^{d-1} \times \mathbb{R}^+$ such that for $\chi \in S^0_{T,\tau}$ homogeneous in $(\zeta', \tau)$ with supp $\chi \subset V$, there exist $C > 0$ and $\tau_1 > 0$ such that

$$C \sum_{k=1}^n | \text{tr} \, Op_T(\chi) v_k |^2_{2m_k-1,1/2,\tau} \leq \sum_{j=1}^m | \sum_{k=1}^n T_{k, \nu} v_k|_{x_k = 0}^2 | \gamma_j - 1/2, \tau| + \sum_{k=1}^n | P_{k, \nu} v_k |^2_{x_k = 0} | \gamma_j - 1/2, \tau| + \sum_{k=1}^n \left( | v_k |^2_{2m_k-1,1,\tau} + | \text{tr} v_k |^2_{2m_k,1,1/2,\tau} \right),$$

for all $\tau \geq \tau_1$, $v = (v_1, \ldots, v_k) \in (\mathcal{S}(\mathbb{R}^d))^n$.

**Proof.** Consider the factorization described in Section 2.5

$$p_{k, \nu}(\rho', \xi_\nu) = p_{k, \nu}(\rho', \xi_\nu) \kappa(\rho', \xi_\nu),$$

(4.9)

for $\rho'$ in a conic neighborhood $V_0$ of $\rho'$, with $p_{k, \nu}$, $\kappa_{k, \nu}$ polynomials with homogeneous coefficients, $p_{k, \nu}$ being monic. Using Proposition 4.10, there exists a conic neighborhood $V_1$ of $\rho'_0$, $V_1 \subset V_0$, such that

$$\sum_{j=1}^m \lambda_T^{2(j-1/2)} | \sum_{k=1}^n \Sigma_{t_k, \nu}(\rho', \tilde{z}_k)|^2 + \sum_{j=0}^{n-1} | \sum_{k=1}^n \lambda_T^{2(m_k-j+1/2)} | \Sigma_{t_k, \nu}(\rho', \tilde{z}_k)|^2 \gtrsim C \sum_{k=1}^n \sum_{j=0}^{n-1} \lambda_T^{2(2m_k-1/2-j)} | \tilde{z}_k^j|^2,$$

(4.10)

holds for all $\rho' \in V_1$ and for all $z = (z_1, \ldots, z_n) \in C^{2m}$, with $z_k = (z_k^0, \ldots, z_k^{2m_k-1}) \in C^{2m_k}$. Now we consider a conic neighborhood $V$ of $\rho'_0$ satisfying $V \subset V_1$, and $\chi \in S^0_{T,\tau}$ homogeneous such that
supp $\chi \in \mathcal{V}$, and $\tilde{\chi} \in \mathcal{S}_0^{d,\tau}$ homogeneous such that supp $\tilde{\chi} \subset \mathcal{V}_1$, and $\tilde{\chi} = 1$ in a neighborhood of $\mathcal{V}$. Consider a smooth extension $\tilde{p}_{k,\varphi}$ outside $\mathcal{V}_0$. Note that by symbolic calculus, we have $\text{Op}_T(\chi)P_{k,\varphi} = \text{Op}(\tilde{p}_{k,\varphi}) \text{Op}_T(\chi) \text{Op}(\tilde{\chi} \kappa_{k,\varphi}) + R_k$, and $R_k \in \Psi^{2m_{k,1^{-1}}}$. Take also $v = (v_1, \ldots, v_n) \in (\mathcal{S}(\mathbb{R}^d))^n$. By definition, $p_{k,\varphi}$ has only roots with negative imaginary parts. Thus we can apply Lemma 4.6 to the function $w_k := \text{Op}(\tilde{\chi} \kappa_{k,\varphi}) v_k \in \mathcal{S}(\mathbb{R}^d)$, and we obtain, for all $k \in \{1, \ldots, n\}$, for any $N \in \mathbb{N}$,

\[
\mathcal{G}(u) = \sum_{j=1}^{m} \left| \sum_{k=1}^{m_{j+1}} T_{j,\varphi}^k u_k |_{\tau = \gamma_j - 1/2, \tau} \right|^2 + \sum_{k=1}^{m_{j+1}} \left| \sum_{j=m+1}^{m} \text{Op}(\tilde{\chi} \kappa_{j,\varphi}) u_k |_{\tau = \gamma_j - 1/2, \tau} \right|^2
\]

which symbol is given by

\[
\Sigma_{\mathcal{G}}(\rho', z, \tilde{z}) = \sum_{j=1}^{m} \lambda^{2(\gamma_j - 1/2)} \left( \sum_{k=1}^{m_{j+1}} \Sigma_{T_{j,\varphi}^k} (\rho', z_k) \right) \left( \sum_{k=1}^{m_{j+1}} \Sigma_{p_{k,\varphi}} (\rho', \tilde{z}_k) \right) + \sum_{k=1}^{m_{m+1}} |\tilde{\chi}(\rho')|^2 \lambda^{2(m_{m+1} + 1/2 - j)} \sum_{k=1}^{m_{j+1}} \Sigma_{\chi_{k,\varphi}} (\rho', z_k) \sum_{k=1}^{m_{j+1}} \Sigma_{\chi_{j,\varphi}} (\rho', \tilde{z}_k),
\]

From (4.10), as $\tilde{\chi} = 1$ on $\mathcal{V}$, we have for all $\rho' \in \mathcal{V}$,
with \( z = (z_1, \ldots, z_n) \), where \( z_k \in \mathbb{C}^{2m_k} \). With (4.15), and the Gårding inequality of Lemma 4.9, for \( N \in \mathbb{N} \), there exists \( \tau_0, C, C' > 0 \) such that

\[
\mathcal{G}(\text{Op}_T(\chi)v) \geq C \sum_{k=1}^{n} |\text{tr}(\text{Op}(\chi))v_k|^2_{2m_k-1,1/2,\tau} - C' \sum_{k=1}^{n} |\text{tr} v_k|^2_{2m_k-1,-N,\tau},
\]

for \( \tau \geq \tau_0 \). Hence, inserting (4.16) in (4.14), we obtain

\[
\sum_{k=1}^{n} \left| \text{tr}(\text{Op}(\chi)v_k) \right|^2_{2m_k-1,1/2,\tau} \leq \sum_{j=1}^{m} \sum_{k=1}^{n} T^j_{k,\varphi} \text{Op}_T(\chi)v_k|_{x = 0}|^2_{\gamma_j-1/2,\tau}
+ \sum_{k=1}^{n} \left( \| P_{k,\varphi} v_k \|^2_{\tau} + \| v_k \|^2_{2m_k-1,\tau} + |\text{tr} v_k|^2_{2m_k-1,1/2,\tau} \right).
\]

It remains to see that \( T^j_{k,\varphi} \text{Op}_T(\chi) = \text{Op}_T(\chi) T^j_{k,\varphi} + [T^j_{k,\varphi}, \text{Op}_T(\chi)] \) to obtain

\[
\sum_{j=1}^{m} \left| \sum_{k=1}^{n} T^j_{k,\varphi} \text{Op}_T(\chi)v_k|_{x = 0} \right|^2_{\gamma_j-1/2,\tau} \leq \sum_{j=1}^{m} \sum_{k=1}^{n} T^j_{k,\varphi} v_k |_{x = 0}|^2_{\gamma_j-1/2,\tau}
+ \sum_{j=1}^{m} \sum_{k=1}^{n} |\text{tr} v_k|^2_{\beta_k^j 2m_k-\beta_k^j-3/2,\tau}.
\]

Using the definition of the norms on the traces (4.3), we have

\[
|\text{tr} v_k|^2_{\beta_k^j 2m_k-\beta_k^j-3/2,\tau} = \sum_{\ell=0}^{\beta_k^j} |D^\ell v_k|_{x = 0}|^2_{2m_k-\ell-3/2,\tau} \leq \sum_{\ell=0}^{2m_k-1} |D^\ell v_k|_{x = 0}|^2_{2m_k-\ell-3/2,\tau} = |\text{tr} v_k|^2_{2m_k-1,-1/2,\tau},
\]

and the proof is complete. \( \Box \)

4.6 Microlocal estimate with operators satisfying both sub-ellipticity and covering condition

Using both the covering condition (by means of Proposition 4.11) and the sub-ellipticity condition (by means of Lemma 4.5), we are ready to prove the following microlocal Carleman estimate, in a conic neighborhood of a point in \( \mathcal{L}_T^\rho(I) \).

**Theorem 4.12.** Let \( x_0 \in I \cap \nabla^+ \). Assume that \( (P_k, \varphi_k) \) satisfies the sub-ellipticity condition in a neighborhood of \( x_0 \) in \( \nabla^+ \), and that \( (T^j_{k,\varphi}) \) covers \( (P_k, \varphi) \) on \( \rho' \in \mathcal{L}_T^\rho(I) \). Then, there exists \( V \) a conic neighborhood of \( \rho' \) in \( \nabla^+ \times \mathbb{R}^{d-1} \times \mathbb{R}^+ \) such that for \( \chi \in S_{T,\tau}^0 \) homogeneous of degree 0 satisfying \( \text{supp} \chi \subset V \), there exist \( C, \tau_0 > 0 \) such that

\[
\tau^{-1} \sum_{k=1}^{n} \| \text{Op}_T(\chi)v_k \|^2_{2m_k,\tau}
+ \sum_{k=1}^{n} |\text{tr}(\text{Op}(\chi)v)|^2_{2m_k-1,1/2,\tau}
\leq C \left( \sum_{k=1}^{n} \| P_k, \varphi |v_k| \|^2_{\tau} + \sum_{j=1}^{m} \sum_{k=1}^{n} T^j_{k,\varphi} v_k |_{x = 0}|^2_{\gamma_j-1/2,\tau}
+ \sum_{k=1}^{n} |v_k|^2_{2m_k-1,\tau} + \sum_{k=1}^{n} |\text{tr} v_k|^2_{2m_k-1,1/2,\tau} \right),
\]

for \( \tau \geq \tau_0 \), for \( v = (v_1, \ldots, v_n) \in (\mathcal{S}(\mathbb{R}^d_+))^n \).
Proof. Consider a neighborhood $U$ of $x_0$ in $\mathbb{V}^+$ such that the sub-ellipticity condition holds in $U$. First we write

$$P_{k,\psi} = P_{k,2} + iP_{k,1}, \quad \text{with } P_{k,2} = \frac{1}{2} (P_{k,2} + P_{k,2}^*), \quad P_{k,1} = \frac{1}{2i} (P_{k,2} - P_{k,2}^*).$$

(4.19)

We shall denote by $p_{k,\psi} \in S^{m_0}_{\mathbb{R}^+}$, $p_{k,2} \in S^{m_0}_{\mathbb{R}^+}$, $p_{k,1} \in S^{m_k-1}_{\mathbb{R}^+}$ their principal symbols, respectively. Let $U$ be a conical neighborhood of $\rho_0$ given by Proposition 4.11. We have from (4.19)

$$\|v_k\|_2^{m_k-1,\tau} + \|P_{k,\psi}v_k\|_2^{2} \geq \|\text{Op}_T(\chi)v_k\|_2^{2} \geq \|\text{Op}(p_{k,2})\text{Op}_T(\chi)v_k\|_2^{2} + \|\text{Op}(p_{k,1})\text{Op}_T(\chi)v_k\|_2^{2} + Q_{p_{k,2},p_{k,1}}(\text{Op}_T(\chi)v_k)$$

$$\geq \tau^{-1} \|\text{Op}(p_{k,2})\text{Op}_T(\chi)v_k\|_2^{2} + \tau^{-1} \|\text{Op}(p_{k,1})\text{Op}_T(\chi)v_k\|_2^{2} + Q_{p_{k,2},p_{k,1}}(\text{Op}_T(\chi)v_k),$$

(4.20)

where $Q_{p_{k,2},p_{k,1}}$ is the quadratic form defined in (4.4). We have from Lemma 4.5, as the sub-ellipticity condition holds,

$$C\tau^{-1} \|\text{Op}_T(\chi)v_k\|_2^{2} \leq C' \tau^{-1} \left( \|\text{Op}(p_{k,2})\text{Op}_T(\chi)v_k\|_2^{2} + \|\text{Op}(p_{k,1})\text{Op}_T(\chi)v_k\|_2^{2} + \text{Re} B_{p_{k,2},p_{k,1}}(\text{Op}_T(\chi)v_k) \right),$$

(4.21)

where $B_{p_{k,2},p_{k,1}}$ satisfies

$$B_{p_{k,2},p_{k,1}}(\text{Op}_T(\chi)v_k) \leq C \left| \text{tr}(\text{Op}_T(\chi)v_k) \right|_2^{2}.$$}

From Proposition 4.11, with the covering condition, we have

$$C \sum_{k=1}^{n} \left| \sum_{j=1}^{n} T_{k,\psi}^{j}v_k|_{2}\gamma_j-1/2,\tau \right| + \sum_{k=1}^{n} \|P_{k,\psi}v_k\|_2^{2} + \sum_{k=1}^{n} \|v_k\|_2^{2} + \sum_{k=1}^{n} \left| \text{tr}(v_k) \right|_2^{2}.$$}

(4.22)

Combining estimates (4.21) and (4.22), we obtain, with $C'$ taken sufficiently large

$$C\tau^{-n} \sum_{k=1}^{n} \|\text{Op}_T(\chi)v_k\|_2^{2} + C \sum_{k=1}^{n} \left| \text{tr}(\text{Op}_T(\chi)v_k) \right|_2^{2} \leq C' \left( \tau^{-n} \sum_{k=1}^{n} \|\text{Op}(p_{k,2})\text{Op}_T(\chi)v_k\|_2^{2} + \tau^{-n} \sum_{k=1}^{n} \|\text{Op}(p_{k,1})\text{Op}_T(\chi)v_k\|_2^{2} + \sum_{j=1}^{n} \left| T_{k,\psi}^{j}v_k|_{2}\gamma_j-1/2,\tau \right| + \sum_{k=1}^{n} \|P_{k,\psi}v_k\|_2^{2} + \sum_{k=1}^{n} \left| \text{tr}(v_k) \right|_2^{2} + \sum_{k=1}^{n} Q_{p_{k,2},p_{k,1}}(\text{Op}_T(\chi)v_k).$$

(4.23)

It remains to use (4.20) to obtain the sought result.

4.7 Proof of the main result.

Let $x_0 \in \mathcal{I}$ and $\mathbb{V}$ be like in Theorem 4.12. By assumption the covering condition holds for all $(x_0, Y, \nu_1, \ldots, \nu_n, \tau) \in \mathcal{L}^{m}_\mathbb{R}(\mathcal{I})$. Using the local coordinates introduced in Section 2, we can only consider $\rho = (x, \xi', \xi_d, \tau)$, with $(x, \xi', \tau) \in S_{[(\xi', \tau)]=1}$. According to Theorem 4.12, for all $\rho' = (x, \xi'', \tau)$, there
exists a conic neighborhood $U_{\rho'} = O_{\rho'} \times C_{\rho'}$ of $\rho'$ in $\nabla \times \mathbb{R}^{d-1} \times \mathbb{R}^+$ such that the Carleman estimate (4.18) holds in $U_{\rho'}$. By a compactness argument, we can extract from the family of the $U_{\rho'}$ a finite number of conical subsets $U_j := O_j \times C_j$, $j \in J$ such that $S((\xi', \tau)) = U_j \cup_{j \in J} C_j$. First we set $W = \cap_{j \in J} O_j$ and $\mathcal{V}_j = W \times C_j$. We construct a partition of unity $(\chi_j)_{j \in J}$, $\chi_j \in \mathcal{S}_{T, \tau}^\wedge$, homogeneous of degree $0$ in $(\xi', \tau) \geq C > 0$ such that

$$\sum_{j \in J} \chi_j(\rho') = 1, \text{ for } (\xi', \tau) \geq C > 0, \quad \text{supp}(\chi_j) \subset \mathcal{V}_j.$$ 

Applying Theorem 4.12, we have

$$\tau^{-1} \sum_{j \in J} \sum_{k=1}^n \| \operatorname{Op}_{T}(\chi_j)v_k \|^2_{2m_k, \tau} + \sum_{j \in J} \sum_{k=1}^n \| \operatorname{tr}(\operatorname{Op}(\chi_j)v_k) \|^2_{2m_k - 1, 1/2, \tau} \leq C \left( \sum_{k=1}^n \| P_k, \varphi v_k \|_\tau^2 \right) + \sum_{j=1}^m \sum_{k=1}^n \| T_k^j v_k \|^2_{a=0, 1/2, \tau} \leq \left( \sum_{k=1}^n \| P_k, \varphi v_k \|_\tau^2 \right) + \sum_{j=1}^m \sum_{k=1}^n \| T_k^j v_k \|^2_{a=0, 1/2, \tau}, \quad (4.24)$$

for all $v_k \in \mathcal{C}_0^\infty(W)$, $k = 1, \ldots, n$. From the fact that $\tilde{\chi} := 1 - \sum_{j \in J} \chi_j$ belongs to $\mathcal{S}_{T, \tau}^\wedge$ in $W \times \mathbb{R}^{d-1} \times \mathbb{R}^+$, for all $N \in \mathbb{N}$, we have that

$$\tau^{-1} \sum_{k=1}^n \| v_k \|^2_{2m_k, \tau} + \sum_{k=1}^n \| \operatorname{tr}(v_k) \|^2_{2m_k - 1, 1/2, \tau} \leq \tau^{-1} \sum_{j \in J} \sum_{k=1}^n \| \operatorname{Op}_{T}(\chi_j)v_k \|^2_{2m_k, \tau} + \sum_{j=1}^m \sum_{k=1}^n \| \operatorname{tr}(\chi_j)v_k \|^2_{2m_k - 1, 1/2, \tau} + \sum_{k=1}^n \| v_k \|^2_{2m_k - 1, 1/2, \tau} + \sum_{k=1}^n \| v_k \|^2_{2m_k - 1, 1/2, \tau}, \quad (4.25)$$

as $\text{supp}(v_k) \subset W$. Combining (4.24) and (4.25), we obtain by taking $\tau$ large,

$$\tau^{-1} \sum_{k=1}^n \| v_k \|^2_{2m_k - 1, 1/2, \tau} + \sum_{k=1}^n \| \operatorname{tr}(v_k) \|^2_{2m_k - 1, 1/2, \tau} \leq C \left( \sum_{k=1}^n \| P_k, \varphi v_k \|_\tau^2 \right) + \sum_{j=1}^m \sum_{k=1}^n \| T_k^j v_k \|^2_{a=0, 1/2, \tau}.$$

Going back with the original variable $u_k = e^{\tau \varphi_k} v_k$ yields the result, taking into account of the change of variable described in (2.1). With the notation introduced there, the open set $\tilde{U}$ can be chosen as $\tilde{U} = \cap_{k=1}^n \phi_k^{-1}(W)$. \hfill \Box

5 Applications to control theory for the transmission problem

In this section, we shall place ourselves in the following setting. We consider $p$ smooth compact Riemannian manifolds $(\Omega_k, g_k)$ of dimension $d \geq 2$, $k = 1, \ldots, p$, with boundary $\partial \Omega_k$. We set $\Omega := \cup_{k=1}^p \Omega_k$. We assume that $\Omega$ is connected and that $\partial \Omega_k$ has $n_k$ connected component, with $n_k \geq 1$. We further assume that the manifolds shares some of the connected component of their boundary with others. More precisely, we shall denote by $I_\ell$, $\ell \in \{1, \ldots, L\}$ the set of interfaces that are shared by at least two manifolds, and we shall denote by $B_k$, $k \in \{1, \ldots, K\}$ the remaining connected components of the boundaries. As in Section 3, we shall consider the Laplace-Beltrami operator on each $\Omega_k$ and a transmission problem as in (3.1) at each interface $I_\ell$, $\ell \in \{1, \ldots, L\}$. The case $d = 1$, corresponds to the case of elliptic problems on a connected graph. However, as we prove our Carleman estimates only for $d \geq 2$, we do not consider the case $d = 1$ is what follows. For such issues, we refer to [4, 13, 19, 30] and the references therein.
5.1 Observable domains

We propose a method to describe the global geometrical configuration we can deal with. Indeed, due to the discussion made at the end of Section 3.1, locally, we have to observe any $n$-interface from at least $(n-1)$-sides. Let $\omega$ be an open subset of $\Omega$. We shall write $\omega_\ell = \Omega_\ell \cap \omega$, and $L = \{\ell \in \{1,\ldots,p\}, \omega_\ell \neq \emptyset\}$. For $k \in \{1,\ldots,p\}$, we define the following map
\[
N_k : I_\ell \mapsto \begin{cases} 1 & \text{if } \Omega_k \cap I_\ell \neq \emptyset \\ 0 & \text{otherwise.} \end{cases} \tag{5.1}
\]
In other words, this map returns 1 if $I_\ell$ is an interface shared by $\Omega_k$. We set $V^\ell := \{k \in \{1,\ldots,p\}, N_k(I_\ell) = 1\}$, that is, the set of manifolds that share the interface $I_\ell$. Conversely, we define $W^\ell := \{\ell \in \{1,\ldots,L\}, N_k(I_\ell) = 1\}$, that is, the set of indices of interfaces that are shared by the manifold $\Omega_k$.

We consider the following construction, with $O_0 := L$,
\[
O_{j+1} = O_j \cup \left(\bigcup_{\ell \in V_j} V_j^\ell \right), \quad V_j^\ell := \begin{cases} \tilde{V}_j^\ell & \text{if } \text{Card } \tilde{V}_j^\ell \leq 1 \\ \emptyset & \text{otherwise,} \end{cases}
\]
and where $\tilde{V}_j^\ell = V^\ell \setminus O_j$. \tag{5.2}
In other words, at each step, for all $\ell \in \{1,\ldots,L\}$, we count the number of sides of $I_\ell$ that belongs to $O_j$. If this number corresponds to an observation from at least $(n-1)$-sides, we add to $O_j$ the remaining side. Observe that $\text{Card } V_j^\ell \leq 1$ at each step. Note also that if $O_j = O_{j+1}$ for some $j$, then $O_{j'} = O_j$, for all $j' \geq j$. With this construction, we have the following definition.

**Definition 5.1.** We say that $(\Omega, \omega)$ is observable, if there exists $j_0 \in \mathbb{N}$ such that $O_{j_0} = \{1,\ldots,p\}$ in the iterated construction described in (5.2).

In the example given on the left-hand-side of Figure 3, assume $L = \{2,4,5,6\}$. Then
1. \( \mathcal{O}_0 = \mathcal{L}, \cup_{\ell=1}^{\mathcal{L}} V_0^\ell = \{1, 3, 7, 8\}, \cup_{\ell=1}^{\mathcal{L}} V_0^\ell = \{1, 8\} \)

2. \( \mathcal{O}_1 = \{1, 2, 4, 5, 6, 8\}, \cup_{\ell=1}^{\mathcal{L}} V_1^\ell = \{3, 7\}, \cup_{\ell=1}^{\mathcal{L}} V_1^\ell = \{3\} \)

3. \( \mathcal{O}_2 = \{1, 2, 3, 4, 5, 6, 8\}, \cup_{\ell=1}^{\mathcal{L}} V_2^\ell = \{7\}, \cup_{\ell=1}^{\mathcal{L}} V_2^\ell = \{7\} \)

4. \( \mathcal{O}_3 = \{1, 2, 3, 4, 5, 6, 7, 8\} \).

As a result, according to Definition 5.1, we have that \((\Omega, \omega)\) is observable. In the example given on the right hand side of Figure 3, assume \(\mathcal{L} = \{2, 4, 5, 6\} \). Then

1. \( \mathcal{O}_0 = \mathcal{L}, \cup_{\ell=1}^{\mathcal{L}} V_0^\ell = \{1, 3, 7, 8\}, \cup_{\ell=1}^{\mathcal{L}} V_0^\ell = \{8\} \)

2. \( \mathcal{O}_1 = \{2, 4, 5, 6, 8\}, \cup_{\ell=1}^{\mathcal{L}} V_1^\ell = \{3, 4, 7\}, \cup_{\ell=1}^{\mathcal{L}} V_1^\ell = \emptyset \)

3. \( \mathcal{O}_1 = \mathcal{O}_2 \neq \{1, \ldots, 8\} \).

Hence, \((\Omega, \omega)\) is not observable in this particular case.

### 5.2 Setting

Consider \( Z := (0, X_0) \times \Omega \), where \( X_0 > 0 \) (resp. \( Z_k := (0, X_0) \times \Omega_k \)). Let \( \alpha \in \{0, X_0/2\} \), and define \( Y := (\alpha, X_0 - \alpha) \times \Omega \) (resp. \( Y_k := (\alpha, X_0 - \alpha) \times \Omega_k \)). For \( z \in (z_0, x) \in Z \) (resp. \( Y \)), we shall mean \( z_0 \in (0, X_0) \) (resp. \( z_0 \in (\alpha, X_0 - \alpha) \)) and \( x \in \Omega \). For \( \ell \in \{1, \ldots, L\} \) (see the beginning of this section for the notation), we also set \( S_\ell = (0, X_0) \times I_\ell \) and \( S_\ell = (\alpha, X_0 - \alpha) \times I_\ell \). For \( k \in \{1, \ldots, K\} \), we consider \( R_k = (0, X_0) \times B_k \) and \( R_k = (\alpha, X_0 - \alpha) \times B_k \). We finally set \( \mathcal{W}_k = \{i \in \{1, \ldots, p\}, \Omega_i \cap B_k \neq \emptyset\} \), that is the set of the indices of the manifold that has \( B_k \) as a boundary. We consider the following transmission problem for a general domain \( \Omega \), with Dirichlet boundary condition:

\[
\begin{cases}
-\partial_{x_i}^2 u_k - \Delta_{x_i} u_k = f_k & \text{in } Z_k, \quad k = 1, \ldots, p \quad \text{on } S_i, \quad \forall i \in \{1, \ldots, L\}, \quad \forall i, j \in \mathcal{V}_k, \\
\sum_{k \in \mathcal{W}} \partial_{x_i} u_k |_{S_i} = 0 & \text{on } S_i, \quad \forall i \in \{1, \ldots, L\}, \\
u_i |_{S_i} = 0 & \text{on } R_k, \quad \forall j \in \{1, \ldots, K\} \quad i \in \mathcal{W}_j,
\end{cases}
\]

(5.3)

where \( \Delta_{x_i} \) stands for the Laplace-Beltrami operator on \( \Omega_k \). Other boundary conditions can also be considered satisfying the Lopatinskii condition. For the sake of simplicity, we only consider Dirichlet boundary conditions here. We define \( u(x) = u_k(x) \), and \( f(x) = f_k(x) \) if \( x \in Z_k \). Similarly, for \( v \) defined on \( \Omega \) (resp. \( Z \) or \( Y \)), we set \( v_k \) on \( \Omega_k \) (resp. \( Z_k \) or \( Y_k \) as \( v_k(x) = v(x) \) for \( x \in \Omega_k \) (resp. \( v_k(s, x) = v(s, x) \) for \( (s, x) \in Z_k \) or \( Y_k \)). We also define the Sobolev spaces, for \( m \in \mathbb{N} \),

\[
H^m(\Omega) = \{ u, u_k \in H^m(\Omega_k) \},
\]

and on \( Z \) (resp. \( Y \)), we define

\[
H^m(Z) = \{ u(x) := u_k(x), \quad x \in Z_k, \quad u_k \in H^m(Z_k) \}, \quad H^m(Y) = \{ u(x) := u_k(x), \quad x \in Y_k, \quad u_k \in H^m(Y_k) \}.
\]

### 5.3 An interpolation inequality

By standard arguments, [28], [25], [26], local Carleman estimates are used to prove interpolation inequalities.

**Theorem 5.2.** Let \( \omega \) be a subset of \( \Omega \) such that \((\Omega, \omega)\) is observable, in the sense of Definition 5.1. There exist \( C > 0 \) and \( \delta > 0 \) such that

\[
\| u \|_{H^1(Y)} \leq C \| u \|_{L^2(Z)}^{1-\delta} \left( \| f \|_{L^2(Z)} + |u|_{L^{\infty}(\omega)} + |\partial_{x_0} u|_{L^{\infty}(\omega)} \right)^{\delta}, \quad (5.4)
\]

for all \( u \in H^1(Y) \) solution of (5.3), with \( f \in L^2(Z) \).
It is classical that the proof of Theorem 5.2 can be reduced to proving the following lemma, which is a local version of Theorem 5.2, in a neighborhood of an interface. For $\ell \in \{1, \ldots, L\}$ and $k \in \mathcal{V}^\ell$, define $Y_k^\ell = \{x \in Y_k, d(x, U_{\ell-1}^L, \ldots, U_0^L, R^\ell_k) > \eta\}$. Here, $d$ denotes the Riemannian distance.

**Lemma 5.3.** Let $\ell \in \{1, \ldots, L\}$. Let $y \in S^\ell_0$, and let $\eta > 0$. For all $k_0 \in \mathcal{V}^\ell$, there exist a neighborhood $V$ of $y$ in $Z_{k_0}$, $C > 0$ and $\delta \in (0, 1)$ such that

$$\|u\|_{H^1(V)} \leq C\|u\|_{H^1(Z_0)}^{1-\delta} \left( \sum_{k \in \mathcal{V}^\ell} \|f_k\|_{L^2(Z_k)} + \sum_{k \neq k_0} \|u\|_{H^1(Y_k)} \right)^\delta,$$

for all $u \in H^1(Z)$ solution of (5.3), with $f \in L^2(Z)$.

This result corresponds to an observation from $(n - 1)$-sides of the interface $S^\ell_0$, where $n = \text{Card} \mathcal{V}^\ell$, and quantifies the unique continuation property.

The following lemmas are classical. The first one allows one to propagate interpolation inequalities away from boundaries and interfaces.

**Lemma 5.4.** Let $U_k$ be an open subset compactly embedded in $(0, X_0) \times \Omega_k$ and $\eta' > 0$. There exist $C > 0$ and $\delta > 0$ such that

$$\|u\|_{H^1(Y_k')} \leq C\|u\|_{H^1(Z_k)}^{1-\delta} \left( \|\partial^2_{zz_k} + \Delta_{z_k} u\|_{L^2(Z_k)} + \|u\|_{L^2(U_k)} \right)^\delta,$$

for all $u \in H^1(Z_k)$ such that $(\partial^2_{zz_k} + \Delta_{z_k})u \in L^2(Z_k)$.

The second one allows one to propagate interpolation inequalities up to the boundaries. We also have the following estimate, in a neighborhood of the boundary $\{x_0 = 0\} \times \omega$, where no boundary conditions are known. We refer to [27] for a proof.

**Lemma 5.5.** Let $x_0 \in \omega_k$, $k \in \mathcal{L}$. There exist $V$ a neighborhood of the point $(0, x_0)$ in $\mathbb{R} \times \mathbb{R}^d$, $\delta \in (0, 1)$ and $C > 0$ such that

$$\|u\|_{H^1(V \cap Z)} \leq C\|u\|_{H^1(Z_k)}^{1-\delta} \left( \|\partial^2_{zz_k} + \Delta_{z_k} u\|_{L^2(Z_k)} + \|u\|_{L^2(U_k)} \right)^\delta,$$

for all $u \in H^1(Z_k)$ such that $(\partial^2_{zz_k} + \Delta_{z_k})u \in L^2(Z_k)$.

**Proof of Lemma 5.3.** This lemma is a consequence of the Carleman estimate. We shall place ourselves in a system of coordinates as given in Section 2, in a neighborhood $U$ of a point $z^0 = (z_0^0, x_0^0) \in S^\ell_0$, with $x_0^0 = 0$. We shall write $U^+ = U \cap \mathbb{R}^{d+1}_+$. We define two anisotropic distances in $\mathbb{R}^{d+1}$, for all $z^1, z^2 \in \mathbb{R}^{d+1}$,

$$d_1(z^1, z^2)^2 = \gamma ((z_0^1, (z_1^1)' - (z_0^2, (z_2^1)')^2 + |z_1^1 - z_2^2|^2,$$

$$d_2(z^1, z^2)^2 = \gamma((z_0^1, (z_1^1)' - (z_0^2, (z_2^1)')^2 + \beta |z_1^1 - z_2^2|^2).$$

(5.7) (5.8)

For $k \in \mathcal{V}^\ell \setminus \{k_0\}$, we define with $z^1 \in \mathbb{R}^{d+1}$, the weight function $\varphi_k(z^1, z) = e^{\lambda \delta_k(z^1, z)^2}$, and for $k = k_0$ we define $\varphi_{k_0}(z^1, z) = e^{\lambda \delta_k(z^1, z)^2}$, with $z^1 = (z_0^1, (z_1^1)' - z_2^1)$, that is, the symmetric of $z^1$ with respect to the axis $\{x_d = 0\}$. Note first that for $\lambda > 0$ sufficiently large, this family of weight functions satisfies the sub-ellipticity property (see Lemma 2.2) in $\omega^+$. For $z^1 \in \mathbb{R}^{d+1}_+$, it satisfies also conditions (3.15). Indeed, we have

$$\partial_{x_d} \varphi_k|_{z_d = 0} = 2 \lambda x_d \varphi_k(z^1, z)|_{z_d = 0} > 0, \text{ for } k \neq k_0 \text{ and, } \partial_{x_d} \varphi_{k_0}|_{z_d = 0} = -2 \lambda x_d \varphi_k(z^1, z)|_{z_d = 0} < 0,$$

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and moreover, by choosing \( \gamma > 0 \) and \( \beta > 0 \) sufficiently small, we can ensure that the covering condition is fulfilled. It is now classical that, using the Carleman estimate of Theorem 2.6, we can obtain the interpolation inequality of Lemma 5.3. We choose \( r_0 > 0 \) such that\( z^1 = (0, r_0) \in \mathbb{R}^{d+1}_+ \). We define the following cut-off functions \( \chi_0, \chi_1 \in C_0^\infty(\mathbb{R}^{d+1}) 
\)
\[
\chi_0(x) = \begin{cases} 0 & \text{in } x_d > r_1 \\ 1 & \text{in } x_d \in [0, r_1/2] \end{cases} \quad ; \quad \chi_1(x) = \begin{cases} 0 & \text{if } d_1(z, z^1) \leq r_2 \text{ or } d_1(y, y_0) > r_5 \\ 1 & \text{in } d_1(z, z^1) \in [r_3, r_4] \end{cases},
\]
and
\[
\mathcal{X}_1(x) = \begin{cases} 0 & \text{if } d^2(z, z^1) \leq r_2 \text{ or } d^3(z, z^1) > r_5 \\ 1 & \text{in } d^3(z, z^1) \in [r_3, r_4] \end{cases},
\]
with \( 0 < r_1 < r_0 \) and \( 0 < r_2 < r_3 < r_4 < r_5 \) such that
\begin{itemize}
  \item \( r_3 \) is small enough to have \( B_1(z^1, r_3) \cap \bar{U}^+ = \emptyset \), where \( B_r \) denotes the open ball associated with the distance \( d_r \); 
  \item \( r_1 \) small enough and \( r_0 < r_4 < r_5 \) are such that \( \{ z = (z_0, x) \in \mathbb{R}^{d+1} \mid x_d \leq r_1 \} \cap \{ r_4 \leq d_r(z, z^1) \leq r_5 \} \subset \bar{U}^+ \).
\end{itemize}

We can apply the Carleman estimate of Theorem 2.6 on \( \bar{U}^+ \) to \( w_k = \chi_0 \chi_1 u_k \), for \( k \neq k_0 \), and \( w_{k_0} = \mathcal{X}_1 u_{k_0} \); there exist \( \tau_0 > 0 \) such that
\[
\sum_{k \in V^d} \tau^{-1} \| e^{\tau \varphi_k} w_k \|_{L^2}^2 \leq C \left( \sum_{k \in V^d} \| e^{\tau \varphi_k} (\partial_{y_0} + \Delta g_k) u_k \|_{L^2(Z_k)}^2 + \| e^{\tau \varphi_k} \|_{L^2(Z_k)} \right),
\]
for all \( \tau \geq \tau_0 \). For \( k \neq k_0 \), the right hand side can be estimated as follows
\[
\| e^{\tau \varphi_k} (\partial_{y_0}^2 + \Delta g_k) u \|_{L^2(Z_k)} \lesssim \| e^{\tau \varphi} (\partial_{y_0}^2 + \Delta g_0) u \|_{L^2(Z_k)} + \| e^{\tau \varphi} [(\partial_{y_0}^2 + \Delta g_0), \chi_0 \chi_1] u \|_{L^2(Z_k)}
\]
\[
\lesssim e^{c_3 \tau} \| e^{\tau \varphi} (\partial_{y_0}^2 + \Delta g_0) u \|_{L^2(Z_k)} + e^{c_1 \tau} \| u \|_{H^1(Z_k)},
\]
with \( C_3 = e^{-\lambda (r_0 - r_1)} \) and \( C_1 = e^{-\lambda r_4} \). Note that we have \( C_1 < C_3 \). Here, we use that the weight function \( \varphi \) is radial with respect to the distance \( d_r \) to \( z^1 \) and decreasing as \( z \) moves away from \( z^1 \), and the commutator \( [(\partial_{y_0}^2 + \Delta g_0), \chi_0 \chi_1] \) is a differential operator of order 1 supported in the region were \( \chi_0 \chi_1 \) varies. For \( k = k_0 \), we have
\[
\| e^{\tau \varphi_k} (\partial_{y_0}^2 + \Delta g_{k_0}) u \|_{L^2(Z_{k_0})} \lesssim \| e^{\tau \varphi} (\partial_{y_0}^2 + \Delta g_0) u \|_{L^2(Z_{k_0})} + \| e^{\tau \varphi} [(\partial_{y_0}^2 + \Delta g_0), \chi_0 \chi_1] u \|_{L^2(Z_{k_0})}
\]
\[
\lesssim e^{c_3 \tau} \| e^{\tau \varphi} \|_{L^2(Z_{k_0})} + e^{c_1 \tau} \| u \|_{H^1(Z_{k_0})}.
\]
In the same spirit,
\[
\| e^{\tau \varphi_k} u_k \|_{L^2} \lesssim e^{c_3 \tau} \| e^{\tau \varphi} \|_{L^2(Z_k)}.
\]
Finally, we can restrict the left hand side of the Carleman estimate to \( \tilde{V} := B(0, r_6) \cap \{ y_d > 0 \} \) with \( r_6 > 0 \) taken sufficiently small to have \( \chi_0 \chi_1 = 1 \) on \( B(0, r_6) \) and this yields, for \( \tau \geq 1 \),
\[
\sum_{k \in V^d} \tau^{-1} \| e^{\tau \varphi_k} w_k \|_{L^2} \gtrsim e^{c_2 \tau} \| u \|_{H^1(\tilde{V})},
\]
where \( C_2 > \inf_{k} \inf_{\varphi_k} \varphi_k \), and \( \tau \geq \tau_0 \), with \( \tau_0 \) taken sufficiently large. Note that we have \( 0 < C_1 < C_2 < C_3 \). We finally obtain, coming back to the original coordinates, for some \( \eta > 0 \),
\[
\| u \|_{H^1(V)} \lesssim e^{(C_3 - C_2) \eta} \left( \sum_{k \in V^d} \| (\partial_{y_0}^2 + \Delta g_k) u_k \|_{L^2(Z_k)} + \sum_{k \in V^d, k \neq k_0} \| u \|_{H^1(V^d_{k_0})} + \| \sum_{k \in V^d} \partial_{y_0} u_k \|_{L^2(S_{k_0})} \right)
\]
\[
+ e^{-\tau(C_2 - C_1)} \| u \|_{H^1(Z)},
\]
where $V$ is an open neighborhood of $y_0$ in $\mathbb{Z}$. It remains to optimize this inequality with respect to $\tau$ to obtain the result. \hfill \Box

### 5.4 A spectral inequality

Define $L^2 := \bigoplus_{k=1}^p L^2(\Omega_k)$, and more generally $H^s := \bigoplus_{k=1}^p H^s(\Omega_k)$. We consider the operator defined on $\Omega$ by

$$A(u_1, \ldots, u_p) = (-\Delta_{y_1} u_1, \ldots, -\Delta_{y_p} u_p),$$

with domain

$$D(A) = \{u = (u_1, \ldots, u_p) \in H^1, A(u) \in L^2, \forall \ell \in \{1, \ldots, L\}, u_1|_{\Omega_1} = \cdots = u_p|_{\Omega_p} = 0, \sum_{k \in \mathcal{V}_\ell} \partial_{\nu_k} u_k|_{\Omega_\ell} = 0, \forall j \in \{1, \ldots, K\}, \forall i \in \mathcal{W}_j \}$$

where $\nu_k$ is the outward unit vector on $\mathcal{I}_\ell$ in the sense of the metric $g_k$. This operator admits an orthonormal basis of eigenfunctions.

**Proposition 5.6.** There exists a Hilbert basis of $L^2$ composed by eigenfunctions $\phi_k = (\phi_{k1}, \ldots, \phi_{kp}) \in L^2$ of the operator $A$, associated with eigenvalues $0 < \gamma_0 \leq \gamma_1 \leq \ldots$ with $\lim_{j \to \infty} \gamma_j = +\infty$.

The following spectral inequality that measures the loss of orthogonality of the eigenfunctions $\phi_j$, $j \in \mathbb{N}$, when they are restricted to an open subset $\omega \subset \Omega$ such that $\mathcal{W} \neq \Omega$. It also quantifies how linear combinations of these eigenfunctions can be observed from a subdomain. It is a natural consequence of the interpolation inequality if Theorem 5.2 (see [21]).

**Theorem 5.7 (Spectral inequality).** Let $\omega \subset \Omega$ be an open subset such that $(\omega, \Omega)$ is observable in the sense of Definition 5.1. There exists $C > 0$ such that for all $\gamma \geq 0$ we have

$$||w||_{L^2(\Omega)} \leq e^{C\sqrt{\gamma}} ||w||_{L^2(\omega)}, \quad w \in \text{span}(\phi_j; \gamma_j \leq \gamma).$$

By the Lebeau-Robbiano method (see for instance the survey [21] for an exposition of the method, and the references therein), from the above spectral inequality, we can construct a control for the following heat equation. Let $\omega$ be an open subset of $\Omega$.\[
\begin{aligned}
\partial_t u_k - \Delta_{y_k} u_k &= \chi_k f_k & \text{in } (0, T) \times \Omega_k, k \in \{1, \ldots, p\} \\
u_k|_{\Omega_\ell} &= u_j|_{\Omega_\ell} & \text{at } (0, T) \times \mathcal{I}_\ell, \ell \in \{1, \ldots, L\}, i, j \in \mathcal{V}_\ell \\
\sum_{k \in \mathcal{V}_\ell} \partial_{\nu_k} u_k|_{\Omega_\ell} &= 0 & \text{at } (0, T) \times \mathcal{I}_\ell, \ell \in \{1, \ldots, L\} \\
u_i|_{\mathcal{W}_j} &= 0 & \text{at } (0, T) \times \mathcal{B}_j, j \in \{1, \ldots, K\}, i \in \mathcal{W}_j \\
(u_1|_{\Omega_1}, \ldots, u_p|_{\Omega_p}) &= (u^0_1, \ldots, u^0_p) & \text{in } [0] \times \Omega, \\
\end{aligned}
\]

where $\chi_k$ is a cut-off function such that $\text{supp } \chi_k \Subset \omega$. We state the null-controllability result of the heat equation 5.12.

**Theorem 5.8.** Let $\omega \subset \Omega$ such that $(\omega, \Omega)$ is observable in the sense of Definition 5.1. For any $T > 0$, there exists a constant $C > 0$ such that, for all initial data $(u^0_1, \ldots, u^0_p) \in L^2$, there exists a control $f := (f_1, \ldots, f_p) \in L^2((0, T), L^2)$, such that the solution $u = (u_1, \ldots, u_n)$ of (5.12) satisfies $u(T) = 0$. Moreover the controls satisfy the bound

$$||f||_{L^2(0, T), L^2} \leq C \sum_{k=1}^p ||u^0_k||_{L^2(\Omega_k)}.$$

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5.5 Stabilization of the wave equation

Let $\omega \subset \Omega$ be an open subset. We consider the following damped wave equation.

\begin{align}
\begin{cases}
\partial_t^2 u_k - \Delta_{g_k} u_k + a_k(x) \partial_t u_k &= 0 &\text{in } (0,T) \times \Omega_k, \; k \in \{1, \ldots, p\} \\
u_{ij|\ell} = u_{ij|\ell} &\text{at } (0,T) \times \mathcal{I}_\ell, \; \ell \in \{1, \ldots, L\}, \; i, j \in \mathcal{V}^\ell \\
\sum_{k \in \mathcal{N}_\ell} \partial_{\nu_k} u_k|_{\mathcal{I}_\ell} &= 0 &\text{at } (0,T) \times \mathcal{I}_\ell, \; \ell \in \{1, \ldots, L\} \\
u_{ij|\ell} &= 0 &\text{at } (0,T) \times B_j, \; j \in \{1, \ldots, K\}, \; i \in \mathcal{M}_k \\
(u_{1|\ell=0}, \ldots, u_p|_{\ell=0}) &= (u^0_1, \ldots, u^0_p) &\text{in } \{0\} \times \Omega \\
(\partial_t u_{1|\ell=0}, \ldots, \partial_t u_p|_{\ell=0}) &= (v^0_1, \ldots, v^0_p) &\text{in } \{0\} \times \Omega,
\end{cases}
\end{align}

(5.13)

where $a_k$ is a non-negative compactly supported function satisfying $a_k \geq C > 0$ on $\omega$, a non-empty subset of $\Omega$. Observe that in the above wave equation, the damping terms are only directly effective on parts of $\Omega$ that intersect $\omega$. We shall see that it is sufficient to ensure stabilization properties. We define the energy of the waves, solution to System (5.13) by

$$E(U,t) := \sum_{k=1}^p (||u_k||^2_{H^1(\Omega_k)} + ||\partial_t u_k||^2_{L^2(\Omega_k)}).$$

We can recast System (5.13) into a semi-group formalism

$$\dot{U} + BU = 0,$$

(5.14)

where $B = \begin{pmatrix} B_1 & 0 \\ \vdots & \ddots \\ 0 & B_p \end{pmatrix}$, with $B_k = \begin{pmatrix} 0 & -1 \\ -\Delta_{g_k} & a_k(x) \end{pmatrix}$. We define the norm

$$||(u_1, v_1, \ldots, u_p, v_p)||^2_{W} = ||(u_1, \ldots, u_p)||^2_{H^1} + ||(v_1, \ldots, v_p)||^2_{L^2}.$$

We have the following result, that states that the energy of the strong solutions of (5.13) decays with a logarithmic speed.

**Theorem 5.9.** Assume that $(\Omega, \omega)$ is observable in the sense of Definition 5.1. There exists $C > 0$ such that

$$E(U,t)^{1/2} \leq \log(2 + t)^{-k} ||B^kU_0||_W,$$

for all solutions $U = (u_1, \partial_t u_1, \ldots, u_p, \partial_t u_p)$ of (5.14), with initial data $U_0 = (u^0_1, v_1, \ldots, u^0_p, v_p)$.

It is well known [11, 3] that Theorem 5.9 follows from the following resolvent estimate. We define $\mathbb{H}^{1\sigma}_0$ the space of functions of $\mathbb{H}^1$ that satisfies at the boundary

$$u_{i|\sigma_j} = 0 \text{ at } B_j, \; j \in \{1, \ldots, K\}, \; i \in \mathcal{M}_k.$$

**Proposition 5.10.** Let $\omega$ be a nonempty open subset of $\Omega$ and $\alpha$ be such that $\alpha > 0$ on $\omega$. Then, the unbounded operator $i\sigma \text{Id} - B$ is invertible on $\mathbb{H} = \mathbb{H}^{1\sigma}_0 \times L^2$ for all $\sigma \in \mathbb{R}$ and there exist $K > 0$ and $\sigma_0 > 0$ such that

$$||(i\sigma \text{Id} - B)^{-1}||_{L(\mathbb{H},\mathbb{H})} \leq K e^{K|\sigma|}, \quad \sigma \in \mathbb{R}, \; |\sigma| \geq \sigma_0.$$

As in [26]), this is a consequence of the interpolation inequality of Theorem 5.2, using a propagation of interpolation inequalities arguments trough the whole domain up to boundaries and trough interfaces.

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References


