

A Proximal Approach for Solving Matrix Optimization Problems Involving a Bregman Divergence

Alessandro Benfenati, Emilie Chouzenoux, Jean-Christophe Pesquet

► **To cite this version:**

Alessandro Benfenati, Emilie Chouzenoux, Jean-Christophe Pesquet. A Proximal Approach for Solving Matrix Optimization Problems Involving a Bregman Divergence. BASP 2017 - International Biomedical and Astronomical Signal Processing Frontiers workshop, Jan 2017, villars-sur-oulon, Switzerland. 2017. <hal-01613292>

HAL Id: hal-01613292

<https://hal.archives-ouvertes.fr/hal-01613292>

Submitted on 10 Oct 2017

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

A Proximal Approach for Solving Matrix Optimization Problems Involving a Bregman Divergence

Alessandro Benfenati*, Emilie Chouzenoux*[†], and Jean-Christophe Pesquet[†],

* LIGM, University Paris-Est Marne-la-Vallée

[†] Center for Visual Computing, CentraleSupélec, University Paris-Saclay

Abstract—In recent years, there has been a growing interest in problems such as shape classification, gene expression inference, inverse covariance estimation. Problems of this kind have a common underlining mathematical model, which involves the minimization in a matrix space of a Bregman divergence function coupled with a linear term and a regularization term. We present an application of the Douglas-Rachford algorithm which allows to easily solve the optimization problem.

In recent years, some applications such as shape classification models [1], gene expression [2], or inverse covariance estimation [3] have led to matrix variational formulations of the form:

$$\underset{C \in \mathcal{S}_+}{\text{minimize}} \quad D_f(C, S) + g(C) \quad (1)$$

where \mathcal{S}_+ is the cone of symmetric semidefinite positive matrices of size $n \times n$, S is a given matrix in \mathcal{S}_+ , f and g are proper lower-semicontinuous (lsc) convex functions defined on the space of $n \times n$ matrices, and D_f is the Bregman divergence associated with f . Recall that

$$D_f(C, S) = f(C) - f(S) - \text{tr}(T(C - S)) \quad (2)$$

where $T \in \partial f(S) \neq \emptyset$. Note also that solving (1) amounts to computing the proximity operator of $g + \iota_{\mathcal{S}_+}$ at S ,¹ with respect to the divergence D_f , which has also been found to be useful in a number of recent works [4], [5].

Very often, due to the nature of the problems, the regularization functional g has to promote the sparsity of C . A generic class of regularization is obtained by assuming that $g = g_0 + g_1$ where

$$g_0(C) = \begin{cases} \psi(d) & \text{if } C \in \mathcal{S}_+ \\ +\infty & \text{otherwise,} \end{cases} \quad (3)$$

where $\psi: \mathbb{R}^n \rightarrow]-\infty, +\infty]$ is a proper lsc function and d is the vector of eigenvalues of C , whereas g_1 is a function which cannot be expressed under this form. Typical examples are the nuclear norm $\|\cdot\|_*$ (or any Schatten norm) for g_0 and the ℓ_1 norm $\|\cdot\|_1$ (of the matrix elements) for g_1 [6].

In this paper, we will assume that function f can be expressed similarly to g_0 as $f(C) = \varphi(d)$ if $C \in \mathcal{S}_+$, $f(C) = +\infty$ otherwise, where $\varphi: \mathbb{R}^n \rightarrow]-\infty, +\infty]$ is a proper lsc convex function. In particular, this assumption is satisfied when

$$f(C) = \begin{cases} -\log \det(C) & \text{if } C \succ 0 \\ +\infty & \text{otherwise.} \end{cases} \quad (4)$$

Various algorithm have been proposed to solve Problem (1) when f is the above function and some specific choices of the function g are made: the popular GLASSO algorithm [3], a Gradient Projection method [1], and a splitting technique on the regularization term [6]. Here we propose to employ the Douglas-Rachford algorithm [7], which enables us to solve (1) in a fast manner, as soon as an efficient procedure for the eigenvalue decomposition is provided. The

Douglas-Rachford approach alternates proximity steps on $D_f(\cdot, S) + g_0 + \iota_{\mathcal{S}_+}$ and on g_1 . For many functions g_1 of practical interest, the proximity operator of g_1 (e.g, $g_1 = \|\cdot\|_1$) has a closed form solution [7]. Let us define $F(C) = f(C) + g_0(C)$. Let $\gamma \in]0, +\infty[$. It can be noted that computing the proximity operator of $\gamma(D_f(\cdot, S) + g_0 + \iota_{\mathcal{S}_+})$ w.r.t. the Frobenius metric $\|\cdot\|_F$, at some symmetric matrix \bar{C} , is equivalent to find

$$\hat{C} = \underset{C \in \mathbb{R}^{n \times n}}{\text{argmin}} \left(F(C) - \text{tr}(TC) + \frac{1}{2\gamma} \|C - \bar{C}\|_F^2 \right).$$

Classical properties of the proximity operator [7] state that

$$\hat{C} = \text{prox}_{\gamma F - \gamma \text{tr}(T \cdot)}(\bar{C}) = \text{prox}_{\gamma F}(\bar{C} + \gamma T).$$

Moreover, if $\bar{C} + \gamma T = U \text{Diag}(\sigma) U^T$ where U is an orthogonal matrix and $\sigma \in \mathbb{R}^n$, then $\hat{C} = U D U^T$ with $D = \text{Diag}(\text{prox}_{\gamma(\varphi+\psi)}(\sigma))$. For example, if f is the log-det function (4) and $g_0 = \mu \|\cdot\|_*$ where $\mu \in [0, +\infty[$, according to [8], the diagonal matrix of eigenvalues of \hat{C} is given by

$$D = \frac{1}{2} \left(\Sigma - \gamma \mu I_n + \sqrt{(\Sigma - \gamma \mu I_n)^2 + 4\gamma I_n} \right)$$

where $\Sigma = \text{Diag}(\sigma)$. The operations to compute $\text{prox}_{\gamma(\varphi+\psi)}$ are thus component-wise.

The proposed Douglas-Rachford approach is easy to implement: if an efficient procedure for the eigenvalue decomposition is available, according to our numerical experiments, it is also very fast.

Acknowledgements: This work was supported by the Agence Nationale de la Recherche under grant ANR-14-CE27-0001 GRAPHISIP.

REFERENCES

- [1] J. Duchi, S. Gould, and D. Koller, "Projected subgradient methods for learning sparse gaussians," in *Proceedings of the Twenty-fourth Conference on Uncertainty in AI (UAI)*, 2008.
- [2] S. Ma, L. Xue, and H. Zou, "Alternating direction methods for latent variable gaussian graphical model selection." *Neural Computation*, vol. 25, no. 8, pp. 2172–2198, 2013.
- [3] J. Friedman, T. Hastie, and R. Tibshirani, "Sparse inverse covariance estimation with the graphical lasso," *Biostatistics*, vol. 9, no. 3, pp. 432–441, jul 2008.
- [4] H. H. Bauschke, P. L. Combettes, and D. Noll, "Joint minimization with alternating bregman proximity operators," *Pacific Journal of Optimization*, vol. 2, no. 3, pp. 401–424, 2006.
- [5] A. Benfenati and V. Ruggiero, "Inexact Bregman iteration with an application to Poisson data reconstruction," *Inverse Problems*, vol. 29, no. 6, pp. 1–32, 2013.
- [6] V. Chandrasekaran, P. Parrilo, and A. S. Willsky, "Latent variable graphical model selection via convex optimization," *Ann. Statist.*, vol. 40, no. 4, pp. 1935–1967, 08 2012.
- [7] P. Combettes and J.-C. Pesquet, "Proximal Splitting Methods in Signal Processing," in *Fixed-Point Algorithms for Inverse Problems in Science and Engineering*, B. B. C. E. L. W. (Eds.), Ed. Springer, 2011, pp. 185–212.
- [8] C. Chau, P. L. Combettes, J.-C. Pesquet, and V. R. Wajs, "A variational formulation for frame-based inverse problems," *Inverse Problems*, vol. 23, no. 4, p. 1495, 2007.

¹ ι_E designates the indicator function of a set E .