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## COEO Phase locking and performance optimisation

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actuator (biasing current of SOA), respectively. In the first step, a simulation on MATLAB Simulink is presented in order to model the phase locking conditions of the COEO from a system point of view.

In the second part of this paper, a dispersion compensation technique using a chirped Bragg filter is presented. Using this technique, the phase noise of the COEO is reduced by 10 dB at 10 kHz offset frequency. The advantage of using a Bragg filter is that the group velocity dispersion of the optical fiber can be compensated independently without changing the optical cavity length. Whereas in the techniques based on dispersion compensating fibers (DCF), one needs to add some meters of DCF fiber in the optical loop. Therefore, the free spectral range (FSR) of the optical cavity will be changed.

## II. SIMULATION OF LONG TERM STABILIZATION

The schematic diagram of the system is presented in Fig. 2. The coupled optoelectronic oscillator (COEO) system is considered as a first order system with the response time of one millisecond. The gain of this system is measured and is equal to 50 Hz/mA (current actuator). The output frequency of the COEO is set to an arbitrary value (for example 9.9 GHz) and the aim is to reach to the frequency of the Quartz (for example 10 GHz). An integrator is placed just after the COEO frequency in order to transform frequency to phase. An integrator is also used for the Quartz to transform the output frequency to phase. We need to mention that these integrators are not needed in real experimental realization. However, since in real experiments we use phase detector to phase lock the two oscillators we need to transform frequency to phase. The phase detector constant is 200 mV/rad.

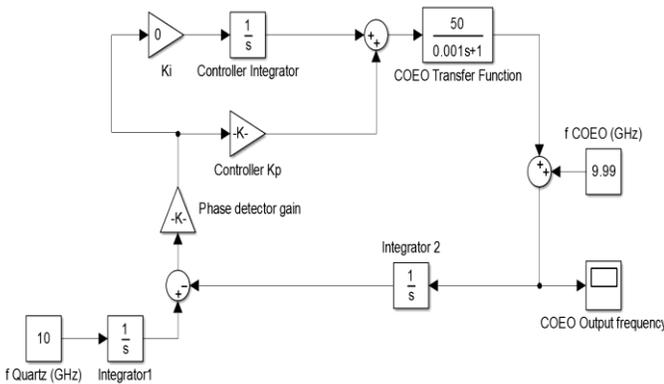


Fig. 2. Schematic diagram of COEO phase locking simulation MATLAB Simulink.

The simulation results for different proportional gain values ( $K_p$ ) are presented in Fig. 2. In this simulation the integrator gain is set to zero. As can be seen in this figure, the COEO oscillator frequency reaches 10 GHz, which means that it is smoothly locked to the quartz.

## III. EXPERIMENTAL SETUP OF LONG TERM STABILIZATION

Fig.1 presents the architecture of the COEO. In this figure, the optical parts and the RF parts are shown by black lines and violet lines, respectively. The SOA is chosen because of its

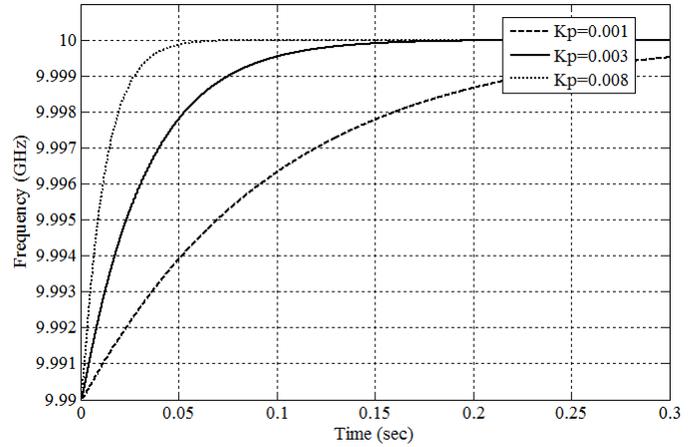


Fig. 3. COEO phase locking simulation MATLAB Simulink results.

compact size and low close to carrier phase noise. The SOA features an output saturation power of 16 dBm and a 30 dB small signal gain. In order to reduce the spontaneous emission of the SOA a 2 nm optical filter is placed in the optical loop. The optical delay line (L1) is a dispersion compensating fiber (DCF) of 100 m combined with 400 m standard single mode fiber (SMF). The optical delay line (L2) is a single mode fiber of 150 m. The second fiber delay (L2) before the fast photodiode enables both the filtering of side modes through Vernier effect and the increase of the optoelectronic loop quality factor. A polarization controller is placed before the modulator to control the polarization of the light at the input of the 40 GHz bandwidth MZM. The RF beat note is amplified, filtered and sent back to the MZM using the RF feedback part. The filter used in this work is a dielectric resonator centered at 10 GHz and features a loaded quality factor of 2500. The varactor placed in the RF part can be used either to adjust the RF phase with a DC voltage (compensation of a drift) or to phase lock the COEO.

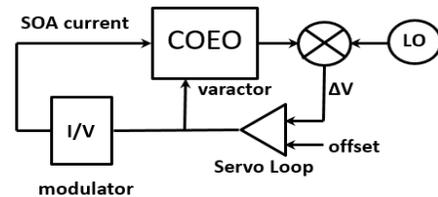


Fig. 4. Schematic diagram of the phase locking system. LO: Local oscillator.

Fig. 4 shows the schematic diagram of the COEO phase locking system. The local oscillator (LO) is a low phase noise Anritsu signal generator. The error signal ( $\Delta V$ ) at the output of the mixer (phase detector) is added to an offset signal and sent to a variable gain servo loop ( $0 < G < 40$  dB) and the control signal at the output of the servo loop is sent to one of the two actuators. In case of using current actuator, the command signal is sent to the current modulator of the current controller module (ILX LDC3900). The COEO tuning coefficient obtained with the current is measured and is equal to 50 Hz/mA. The tuning coefficient obtained with the varactor

diode is not linear. It is of 450 Hz/V near 0 V, and drops to 150 Hz/V near 4 V offset.

#### IV. RESULTS AND DISCUSSION

Fig. 5 depicts the measured phase noise for three different scenarios. The black curve presents the phase noise of the free running COEO. The grey curve shows the measured phase noise of the COEO locked on low noise LO using current modulation of the SOA and the brown curve shows the phase noise results for the COEO locked on LO using varactor. As it is shown in this figure, the phase noise value for the locking scenarios at close-in offset frequencies are hugely reduced. This phase noise reduction at 10 Hz offset frequency for the scenario in which the current is used as the actuator is more than 30 dB and for the scenario in which the varactor is used is more than 20 dB. The locking bandwidth for the current actuator is around 500 Hz and around 100 Hz for the varactor approach. In any case, the locking bandwidth is limited by the Q factor of the COEO. The measured microwave Q of this system is in the range of  $2 \cdot 10^6$ , which corresponds to a half-bandwidth of 2.6 kHz.

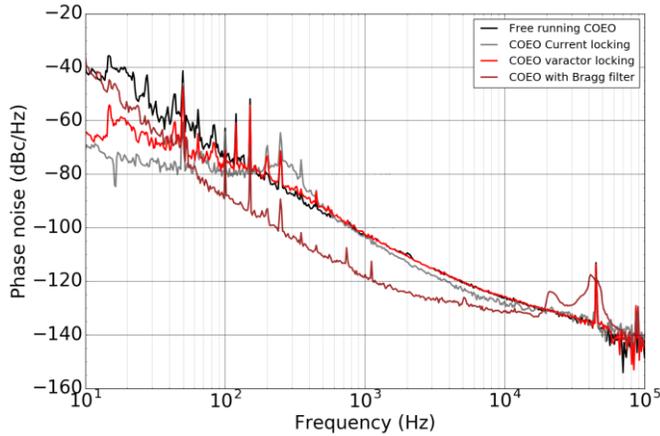


Fig. 5. Phase noise measurement results: free running COEO (black curve), COEO phase locked on LO using current modulation of SOA (gray curve), COEO phase locked on LO using varactor (red curve) and COEO using Bragg filter (brown curve).

#### V. DISPERSION OPTIMIZATION

Fig. 6 presents the schematic diagram of the experimental COEO based on chirped Bragg filter. As can be seen in this figure, the OBPF and DCF are replaced by a chirped fiber Bragg grating (CFBG) filter with chromatic dispersion of -7 ps/nm and . Considering 400 m SMF fiber with chromatic dispersion of 17 ps/(nm.km) in the optical cavity, we can compensate the GVD utilizing the mentioned CFBG. Another advantage of using a CFBG is that one can remove the spontaneous emission of the SOA which is a large band amplifier.

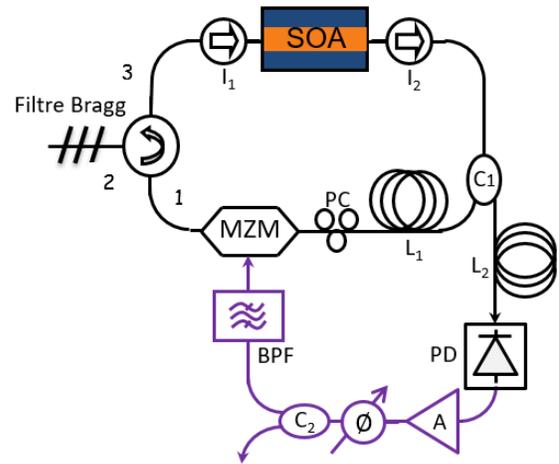


Fig. 6 Experimental setup of the COEO with a chirped Bragg filter.

The phase noise measurement result for the COEO based on Bragg filter is presented in Fig. 5 (brown curve). As can be seen in this figure, the phase noise PSD close to the carrier is hugely reduced. For example at 1 kHz offset frequency the phase noise value of -120 dBc/ Hz is obtained which is 15 dB better than the previous results.

#### VI. CONCLUSION

In this work, a 10 GHz COEO is phase locked to a low noise RF oscillator using two different actuators from optical and RF parts of the COEO. The optical actuator is the bias current of the SOA and the RF actuator is a varactor that is placed in the RF feedback part of the COEO. The optical actuator approach appears to be the more efficient one. It is also readily available on any system of this type, and thus very easy to set-up. A dispersion compensation technique utilizing a chirped Bragg filter is also presented in order to optimize the performance of the COEO. Using this technique, a phase noise reduction of more than 15 dB at 1 kHz off-set frequency is observed.

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