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Comparison Between Numerical and Analytical Methods of AC Resistance Evaluation for Medium Frequency Transformers: Validation on a Prototype

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Abstract—In the future, Medium Frequency Transformers (MFT with a frequency range 5 kHz to 100 kHz) will be major components in DC-DC converter applications, for both Medium Voltage Direct Current (MVDC) and High Voltage Direct Current (HVDC) networks. Importantly, the corresponding power losses should be accurately calculated in order to reach performance targets (very high efficiency). This paper reviews the most known analytical models which are used to calculate the medium frequency resistance for several winding technologies. In order to qualify these models in a future design flow, we compare the analytical model results with measurements and 3D finite element (3DFE) electromagnetic simulations. The adopted design flow-chart has been tested on a 17 kHz – 180 kVA prototype transformer that will be used in a Dual Active Bridge (DAB).

Index Terms--DC-DC power converters, Numerical simulation, Power transformers, Proximity effects.

I. INTRODUCTION

One approach to limit global CO₂ emissions is to increase the generation of renewable energy, for example, by way of offshore wind farms or solar panels. The European Union has set as a target to increase 20% by 2020 the proportion of renewable energy generation (23% for France). New offshore wind projects are in development in order to help meet the renewable energy targets. The main drawback with renewable energy generation, when the generator is in a remote location, is that the power transmission distance can exceed an efficiency threshold (e.g. 80/100 km). In this last case, HVDC is the most promising solution to minimize the transmission losses [1].

Nowadays, the technological advances in the power electronics field, allows the voltage levels in HVDC networks to be adjusted. Indeed, recent researches showed that Silicon Carbide (SiC) semiconductors can operate at higher voltages than Silicon (Si) semiconductors [2].

The Dual Active Bridge (DAB) can be used to manage the energy transfer [3] between two DC voltage levels. It consists of two full-bridge converters separated by a medium frequency transformer (see Fig. 1). This type of converter allows power to flow bidirectionally. When designing an MFT with high efficiency, a design flow-chart, similar to the one presented in [4], can be used.

In many power electronic converter applications, the current waveform is non-sinusoidal, containing a fundamental component and also many harmonics. The DAB can be regulated with the phase shift between the voltages generated by the two full bridges, it corresponds to the rectangular modulation presented in Fig. 2 (using Simpler® [5]). This leads to an increase of the equivalent alternative resistance (1).

Many research studies [6]-[8] have been carried out to propose analytical models which able to predict accurately the AC resistance $R_{AC}$. But, the limits of the analytical models
must be established before incorporating them into the design flow-chart.

Many works [9], [10] have been carried out to determine the limits of the different theoretical models. These works changed only a limited number of parameters and the discrepancies between their measurements and analytical models suffered from a lack of explanations.

In this paper, several analytical models to calculate $R_{AC}$ are studied in section II.

In section III, some comparisons are carried out between numerical and analytical methods regarding the influence of different technological parameters.

Then, the analytical model results are compared with measurements results and with 3DFE calculations (using Maxwell 3D © with Eddy Current solver [5]) in section IV. These comparisons are also made in order to check and explain the differences observed between analytical models and measurements. And then, the most effective model (analytical or numerical), will be incorporated into the design flow-chart. Finally, in section V, in order to check the adopted design flow-chart, an MFT prototype has been designed. Magnetic losses, which are another important part of the design flow-chart are not studied in this paper.

II. ANALYTICAL MODELS FOR FOIL, ROUND WIRE WINDING

In many power electronic converter applications, the current waveform is non-sinusoidal containing a fundamental component and also many harmonics. In order to calculate the winding losses, for a non-sinusoidal current, the conductor losses can be estimated for each harmonic. By taking, $Fr = R_{AC}/R_{DC}$ corresponding to the increase of the alternative resistance compared to the continuous resistance for each harmonic. The $Fr_{total}$ which contains all the harmonics for a non-sinusoidal current is defined by (1).

$$Fr_{total} = \frac{l_{dc}^2 + \sum_{v=1}^{\infty} l_{v}^2}{l_{dc}^2 + \sum_{v=1}^{\infty} l_{v}^2} \quad (1)$$

Where $l_{dc}$ is the DC component and $v$ is the harmonic number.

The analytical models presented in this paper are based on the following assumptions:
- It is a one dimensional problem,
- The magnetic flux between two layers winding is parallel to the core column,
- The considered Magneto Motive Force (M.M.F) is as presented in Fig. 3,
- The permeability of the core is infinite.

Figure 3. Transformer magneto motive force diagram

A. DOWELL’s model

The most known analytical equation to evaluate $R_{AC}$ is the one given in [6]. Dowell introduced the concept of porosity coefficient in order to take into account the filling of the height of the winding window. Moreover, thanks to this coefficient, we can use this method to calculate losses in conductors for different winding technologies, by doing some transformations presented in Fig. 4. The equation (4) calculates $Fr$ for each harmonic. In (4), some of the parameters have to be calculated before with (2) and (3).

$$Fr = \frac{\sinh(2X') + \sin(2X')}{\cosh(2X') - \cos(2X')} + \frac{2}{3} \left( \frac{\sinh(2X') - \sin(2X')}{\cosh(2X') + \cos(2X')} \right) \quad (4)$$

Where $X' = d/\delta, \sqrt{\eta_w}$ is the ratio between the conductor or foil thickness $(d)$, the skin depth $(\delta)$ and $m$ is the number of layers.

B. FERREIRA’s model

In [7], Ferreira proposes another equation to calculate the $Fr$ coefficient, this new equation is based on solving Maxwell’s equations using the Kelvin-Bessel functions. The proposed equation is:

$$Fr = \frac{y}{2} \left[ \frac{ber(y)be'i(y) - bei(y)ber'(y)}{ber'^2(y) + bei'^2(y)} \right] - 2\pi (2m - 1)^2, \left( \frac{ber_2(y)ber'(y) + bei_2(y)be'i(y)}{ber^2(y) + bei^2(y)} \right) \quad (5)$$

Figure 4. Round wire transformation to an equivalent foil

The first step is to transform the round wire into a square one while keeping the same effective area of the conductor:

$$d_w = \frac{\sqrt{\pi}}{\sqrt[4]{d}} \quad (2)$$

The second step is to transform the square wire into an equivalent foil, always keeping the same effective area of the foil. Following this, the $\eta_w$ porosity coefficient is defined by (3).

$$\eta_w = \frac{h_w}{h} \quad (3)$$

Finally, the DOWELL’s equation is:

$$Fr = X', \left[ \frac{\sinh(2X') + \sin(2X')}{\cosh(2X') - \cos(2X')} \right] + \frac{2}{3} \left( \frac{\sinh(2X') - \sin(2X')}{\cosh(2X') + \cos(2X')} \right) \quad (4)$$
Where \( \gamma = \frac{a}{\delta \sqrt{2}} \) and \( d \) is the wire diameter. We can note that this author does not take into account the porosity coefficient.

C. REATTI’s and KAZIMIERCZUK’s model

In [8], the authors propose another equation based on solving Maxwell’s equations using the Kelvin-Bessel functions. This equation is often called the FERREIRA modified equation. The proposed equation is as follows:

\[
Fr = \frac{\gamma}{2} \left[ \frac{\text{ber}(\gamma)\text{bei}'(\gamma) - \text{bei}(\gamma)\text{ber}'(\gamma)}{	ext{ber}^2(\gamma) + \text{bei}^2(\gamma)} \right.
- \left. 2\pi \eta w^2 \left( \frac{4(2m-1)}{3} \right) \left[ \frac{\text{ber}_2(\gamma)\text{bei}'(\gamma) + \text{bei}_2(\gamma)\text{ber}'(\gamma)}{	ext{ber}^2(\gamma) + \text{bei}^2(\gamma)} \right] \right]
\]

Where \( \gamma = \frac{a}{\delta \sqrt{2}} \) and \( d \) is the wire diameter. We can note that this author uses the porosity coefficient.

III. INFLUENCE OF DIFFERENT TECHNOLOGICAL PARAMETERS

For this section, different technological parameters were studied: influence of the connection, influence of the porosity coefficient and the distance between primary and secondary winding. For these preliminary calculations, the frequency range is DC to 20 kHz.

A. Influence of the connections

In order to study the influence of the connections, 3D finite element simulations were carried out with and without connections with a foil. The characteristics of the windings are: \( h_w = 50 \) mm and 200 mm, \( d = 0.15 \) mm and \( m = 3 \) turns.

1) Without connections

In this case, there are no connections; each turn is modelled by an independent coil. Thus, the current is imposed in each turn. This modelling is presented in Fig. 5.

Figure 5. Global view of the transformer (left), top view of the transformer (middle) and a zoom on where the current is injected (right)

These simulation conditions are the ones that respect the most the analytical models assumptions, because the current is directly imposed and is the same in each layer. For a foil, with \( h_w = 50 \) mm and 200 mm, the relative errors between 3DFE simulations and theoretical models are less than 1%, with a small distance between primary and secondary winding (1 mm), DC to 20 kHz.

2) With connections

In this case, there are connections; the coil is modelled by a “real” winding. Thus, the current is imposed in the connection. This modelling is presented in Fig. 6. The current distribution is not the same in each layer due to the connections.

Figure 6. Construction of primary and secondary winding (orange and red) and core (grey) for different porosity factor respectively 0.93 (left) and 0.7 (right)

For a foil, with \( h_w = 50 \) mm and 200 mm, the relative errors are presented in Table I.

<table>
<thead>
<tr>
<th>( h_w ) (mm)</th>
<th>Relative error</th>
</tr>
</thead>
<tbody>
<tr>
<td>50</td>
<td>~ 5%</td>
</tr>
<tr>
<td>200</td>
<td>~ 60% (Maximum @ 20 kHz)</td>
</tr>
</tbody>
</table>

For a given foil thickness, if the height of the foil increases, the discrepancies between 3DFE and theoretical model results increases. The reason is that the current cannot spread uniformly throughout the height of the foil (See Fig. 7).

Figure 7. The current density @ 20 kHz. \( h_w = 200 \) mm (left) and 50 mm (right) with the same scale (Imposed current density is equal to 33 kA.m\(^{-2}\))

B. Influence of the porosity coefficient and the distance between primary and secondary winding

In our applications, the medium frequency transformer is destined for high power and high voltage, so it requires high
voltage insulation between the primary and the secondary and also between the windings and the magnetic circuit. This could result in a "high" distance between the two windings and between the magnetic circuit and the coils. The distance between the primary and the secondary winding is not taken into account in the different analytical equations. In order to study the influence of these parameters, 3D finite element simulations were carried out with a foil: \( h_w = 50 \text{ mm}, d = 0.15 \text{ mm}, m = 3 \text{ turns} \) with connections and \( h \) is various to adjust the porosity coefficient.

Thus, discrepancies between analytical and numerical methods can occur. Indeed, if the distance between the primary and secondary increases therefore, the leakage flux near the coil increases. It causes an increase of the eddy currents, and the current density of the internal layers becomes non-uniform, and hence \( Fr \) increases (see Fig. 8).

Moreover, if the coefficient of porosity decreases, the leakage flux is more important and so the eddy currents in the coil increase. Thus \( Fr \) increases. This is particularly true when both parameters are taken into account simultaneously (see Fig. 9).

\[ F_r = \frac{R_{AC}}{R_{DC}} \]

The Figs. 10 and 11 show the comparison between measurement results at different distances between primary and secondary winding, the theoretical models (Dowell [6], Ferreira [7] and Reatti [8]) and 3DFE results.

The curves \( Fr = \frac{R_{AC}}{R_{DC}} \), in function of frequency plotted in Fig. 10, show high discrepancies between analytical models (dashed lines) and measurements (solid curves).

The equations in [6]-[8] do not take into account the connections. For the F1 case, the number of turns is low (3 turns), then the resistance of the connections are of the same order of magnitude as the resistance foil.
Increasing the number of turns reduces the discrepancies, as shown in Fig. 11. In the case of F3 with 10 turns, the resistance connections can be neglected.

The current cannot spread uniformly throughout the height of the foil. Indeed, in Fig. 12, for F3, the current density of the intern layers is close to the input imposed current density value (33 kA.m^{-2}). This is not the case for the F1 winding. This last phenomenon is not taken into account in the analytical models.

It leads us to think that analytical models are not suitable for high power medium frequency transformers because some of the assumptions are not respected (due to parameters that are not taken into account in the analytical models). However, 3DFE calculations are in good agreement with measurements for foil windings. That means that 3DFE calculations have to be made instead of the analytical ones in order to predict accurately \( R_{\text{ac}} \) in the design flow-chart.

V. APPLICATION FOR A MEDIUM FREQUENCY TRANSFORMER

To check our design flow-chart, an MFT was designed. The chosen power converter is the Dual Active Bridge (DAB). The specifications of the converter are summarized in Table III. In order to manage the transfer of power, it exists several modulations to control a DAB non-resonant and resonant [11]-[13]. The TMF 180 kVA is a core type transformer in ferrite 3C90, the characteristics are presented in Table IV.

![Graph](image)

**Figure 11.** \( Fr = R_{\text{ac}}/R_{\text{dc}} \) as a function of frequency for different distances between primary and secondary for F3: theoretical models, measurements and 3DFE.

**Table III. Converter Specifications**

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Apparent power</td>
<td>180 kVA</td>
</tr>
<tr>
<td>Active power</td>
<td>100 kW</td>
</tr>
<tr>
<td>Input voltage DC</td>
<td>1.2 kV</td>
</tr>
<tr>
<td>Rated current AC</td>
<td>150 A</td>
</tr>
<tr>
<td>Switching frequency</td>
<td>17 kHz</td>
</tr>
<tr>
<td>Turns ratio</td>
<td>N2:N1 = 1:2</td>
</tr>
<tr>
<td>Leakage inductance ( L_\sigma )</td>
<td>As low as possible</td>
</tr>
</tbody>
</table>

**Table IV. Transformer Characteristics**

<table>
<thead>
<tr>
<th>Specification</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>Windings</td>
<td>( N_1 = 14 ) per column in series</td>
</tr>
<tr>
<td></td>
<td>( N_2 = 14 ) per column in parallel</td>
</tr>
<tr>
<td>Current density</td>
<td>2.77 A/mm²</td>
</tr>
<tr>
<td>Leakage inductance ( L_\sigma )</td>
<td>6.14 ( \mu )H (measured)</td>
</tr>
<tr>
<td></td>
<td>5 ( \mu )H (calculated with 3DFE)</td>
</tr>
<tr>
<td>Winding losses ((@ 150 \text{ A and } 17 \text{ kHz}))</td>
<td>560 W (measured)</td>
</tr>
<tr>
<td></td>
<td>532 W (calculated with 3DFE)</td>
</tr>
</tbody>
</table>

For the purpose of knowing \( Fr = R_{\text{ac}}/R_{\text{dc}} \) as a function of frequency, we carried out primary side short circuit measurements. In our case, we suppose that the \( Fr \) is the same for the primary and the secondary windings, because for each transformer column the number of layers (turns) is the same. So the resistance measured primary \( R1(f) \) side short circuit is equal to (7).
\[ R_1(f) = Fr(f) \cdot \left[ R_{1DC} + \left( \frac{N_1}{N_2} \right)^2 R_{2DC} \right] \]  

(7)

Where \( R_{1DC} \) and \( R_{2DC} \) are respectively the primary and secondary resistance in continuous. In order to calculate the \( Fr \), we use (8), the \( Fr \) is plotted in Fig. 13.

\[ Fr(f) = \frac{R_1(f)}{R_{1DC} + \left( \frac{N_1}{N_2} \right)^2 R_{2DC}} \]  

(8)

![Figure 13. Fr = R_ac/R_dc as a function of frequency with the short circuit primary side measurements, theoretical models and 3DFE](image)

For our type of application (high voltage transformers), we show high discrepancies between theoretical models and measurements. However, the results of 3DFE are in good agreement with measurements for the MFT. In our design flow-chart, if we were simply calculating the \( R_{ac} \) only with the analytical models, then we would have underestimated the winding losses by 100% at 17 kHz. This error could lead to a mismatch with the rated efficiency and, moreover, it could lead to thermal problems.

VI. CONCLUSION

In this paper, several analytical models have been tested applying them to the case of foil windings for high power medium frequency transformers.

In this case, the limits of different analytical models have been pointed out thanks to measurement and 3DFE calculations results. Indeed, the most critical parameters (connections, porosity coefficient and distance between the primary and secondary windings) to apply the analytical models were defined. Thanks to 3DFE simulations, the main causes of the discrepancies (i.e. connection resistance, number of turns, current distribution homogeneity ...) were examined.

In order to validate our design flow-chart, an MFT prototype was designed for a high voltage and high power DC-DC application. We obtained the same kind of results. It leads us to think that for this application, if we use foil windings, the analytical models underestimate the alternative resistance. So engineers have to use 3DFE calculations to predict accurately the \( R_{ac} \) for high power medium frequency transformers.

The increase of the relative error observed between Fr 3D and Dowell (which is a factor of the distance between primary and secondary and the porosity coefficient) also depends on the foil height, on the geometry of the windings and on the coupling magnetic coefficient. All these parameters are not taken into account in the different analytical models reviewed. In the next phase of research, some rules (e.g. safety factor, chart ...) to take into account these parameters will have to be developed.

The computing resources to solve these simulations are huge (e.g. in order to calculate the stars in Fig. 13, the simulation time is around one week to solve a mesh with 3 million elements). So, in the future, some rules to optimise the calculation time will also have to be developed.

REFERENCES


