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Generalized Impedance Boundary Conditions and Shape Derivatives for 3D Helmholtz Problems

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Abstract

This paper is concerned with the shape sensitivity analysis of the solution to the Helmholtz transmission problem for three dimensional sound-soft or sound-hard obstacles coated by a thin layer. This problem can be asymptotically approached by exterior problems with an improved condition on the exterior boundary of the coated obstacle, called Generalised Impedance Boundary Condition (GIBC). Using a series expansion of the Laplacian operator in the neighborhood of the exterior boundary, we retrieve the first order GIBCs characterizing the presence of an interior thin layer with either a constant or a variable thickness. The first shape derivative of the solution to the original Helmholtz transmission problem solves a new thin layer transmission problem with non vanishing jumps across the exterior and the interior boundary of the thin layer. In the special case of thin layers with a constant thickness, we show that we can interchange the first order differentiation with respect to the shape of the exterior boundary and the asymptotic approximation of the solution. Numerical experiments are presented to highlight the various theoretical results.

1 Introduction

This paper is devoted to the shape sensitivity analysis of the solution to time-harmonic acoustic scattering problems in the special case where the scattering object is a three-dimensional sound-soft or a sound-hard obstacle coated by a thin layer whose width $\varepsilon$ tends to zero. It is well known that boundary and finite elements methods fail since some numerical instabilities arise. Indeed, we face two kind of scalings : a big scale for the exterior of the obstacle and a very small one which corresponds to the thin layer. To avoid the phenomenon, we are led to approximate the original model by a new exterior boundary value problem with high order boundary conditions in terms of surfaces derivatives, called generalized impedance boundary conditions (GIBC). The exact solution is given through an asymptotic expansion in terms of the thickness parameter $\varepsilon$ where each coefficient function is the solution of a boundary value problem set on a geometry independent on $\varepsilon$. In practice, we are only interested by a finite number of terms in the asymptotic expansion. The GIBC satisfied by the approximate solution leads to an error estimates up to $O(\varepsilon^{N+1})$, where $N$ is the order of truncation in the asymptotic expansion of the exact solution. These conditions have been first derived by Bendali and Lemrabet in [3] in the case of thin layer with a constant thickness and more recently they were generalised to the 2D case of thin layer with a variable thickness in [2].

The work finds its motivation in the recent study of inverse scattering problems (see [6, 7, 8]) or shape optimization problems (see [13]). The authors take the approximation of order 1 of the original problem and present a theoretical analysis based on the shape derivative of the approximate solution. Our natural question is the following : what happens if we compute first the shape derivative of the original problem (with the coated context) and then take the corresponding GIBC of order 1. The purpose of the paper is to give here a general result about the norm of the difference of the shape derivatives for an approximation of order $N$. We show that the error is up to $O(\varepsilon^{N+1})$.

Let consider a simply connected bounded domain $\Omega$ in $\mathbb{R}^3$, with a closed orientable boundary $\Gamma$, as smooth as we need, representing a sound-soft or a sound-hard scatterer $\Omega^c$ coated by a thin layer denoted

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\( \Omega'_{\text{ext}} \). Let \( \varepsilon > 0 \) and \( h \) be a positive smooth function defined on \( \Gamma \). The thin layer with variable thickness surrounding the acoustic object is defined by:

\[
\Omega''_{\text{int}} = \{ x + \delta h(x) \mathbf{n}(x) | x \in \Gamma \text{ and } -\varepsilon < \delta < 0 \}.
\]

We set \( \Gamma'' = \partial \Omega'' \) so that we have \( \Omega = \Omega''_{\text{int}} \cup \Gamma'' \cup \Omega''_{\text{ext}} \). We denote by \( \mathbf{n} \) and \( \mathbf{n}_s \) the outward unit normal vectors to \( \Gamma \) and \( \Gamma'' \), respectively, and by \( \Omega''_{\text{ext}} = \mathbb{R}^3 \setminus \Omega \) the unbounded exterior domain. Throughout the paper we denote by \( H^1(\Omega''_{\text{int}}), H^1_{\text{loc}}(\Omega''_{\text{ext}}) \) and \( H^1(\Gamma) \) the standard (local in the case of the exterior domain) complex valued, Hilbertian Sobolev space of order \( t \in \mathbb{R} \) defined on \( \Omega''_{\text{int}}, \Omega''_{\text{ext}}, \Gamma \) and \( \Gamma'' \) respectively (with the convention \( H^0 = L^2 \)). The exterior wavenumber \( \kappa_s \), the interior wavenumber \( \kappa \), and the density ratio \( \rho \) are given positive constants.

We are concerned with the following transmission problem: Given any densities \( f_{\text{ext}} \in H^{1,2}(\Gamma) \) and \( g_{\text{ext}} \in H^{-1/2}(\Gamma) \), find the solution \( (u''_{\text{int}}, u''_{\text{ext}}) \in H^1(\Omega''_{\text{int}}) \times H^1(\Omega''_{\text{ext}}) \) satisfying

\[
\begin{align*}
\Delta u''_{\text{int}} + \kappa^2 u''_{\text{int}} &= 0 \quad \text{in } \Omega''_{\text{int}}, \\
\Delta u''_{\text{ext}} + \kappa_s^2 u''_{\text{ext}} &= 0 \quad \text{in } \Omega''_{\text{ext}}, \\
u''_{\text{int}} - u''_{\text{ext}} &= f''_{\text{ext}} \quad \text{on } \Gamma, \\
\rho \partial_n u''_{\text{int}} - \partial_n u''_{\text{ext}} &= g''_{\text{ext}} \quad \text{on } \Gamma,
\end{align*}
\]

and either a Dirichlet boundary condition on \( \Gamma'' \)

\[
u''_{\text{int}} = f''_{\text{int}},
\]

or a Neumann boundary condition on \( \Gamma'' \)

\[
\partial_n u''_{\text{int}} = \mathbf{n}_s \cdot (\nabla u''_{\text{int}})|_{\Gamma''} = g''_{\text{int}}.
\]

To ensure the uniqueness of the solution to either the problem \([1.1]-[1.2]\) or \([1.1]-[1.3]\), the scattered field \( u''_{\text{ext}} \) is assumed to solve the Sommerfeld radiation condition \( \lim_{|x| \to +\infty} |x| \left| \partial_n u''(x) - i \kappa u''(x) \right| = 0 \) uniformly in all directions \( x/|x| \). Following the proof of Theorem 2.1 in [23], one can prove that the thin-layer transmission problem has at most one solution. Existence of a solution can be proved using boundary integral equation methods [23] [38]. More details can be found in the Appendix. The radiation condition implies that the scattered field \( u''_{\text{ext}} \) has an asymptotic behavior of the form \( u''_{\text{ext}}(x) = u''_{\text{inc}}(x) + O \left( \frac{1}{|x|} \right), \ |x| \to \infty, \) uniformly in all directions \( x = \frac{x}{|x|} \). The far-field pattern \( u''_{\text{inc}} \) is a scalar function defined on the unit sphere \( S^2 \) of \( \mathbb{R}^3 \) and is always analytic.

The scattering problem of time-harmonic waves by the coated obstacle \( \Omega \) leads to special cases of the above transmission problems where the given densities \( f_{\text{ext}} \) and \( g_{\text{ext}} \) are the boundary data of an incident plane wave \( u''_{\text{inc}}(x) = e^{i \omega x \cdot d} \), \( d \in S^2 \). The total displacement field \( u''_{\text{ext}} + u''_{\text{inc}} \) is then given by the superposition of the incident field \( u''_{\text{inc}} \), which is an entire solution of the Helmholtz equation, and the scattered field \( u''_{\text{ext}} \), which solves the Helmholtz equation in \( \Omega''_{\text{ext}} \) and the Sommerfeld radiation condition. In this case, we assume \( f''_{\text{ext}} = 0 \) and \( g''_{\text{int}} = 0 \). In section 3 for small positive real values of \( \varepsilon \), we approach the solution \( u''_{\text{ext}} \) of \([1.1]\) by the solution \( v''_{[\varepsilon]} \) of some exterior boundary value problems of the form

\[
\begin{align*}
\Delta v''_{[\varepsilon]} + \kappa^2 v''_{[\varepsilon]} &= 0 \quad \text{in } \Omega''_{\text{ext}}, \\
C(\varepsilon, \partial_n (v''_{[\varepsilon]} + u''_{\text{inc}}), (v''_{[\varepsilon]} + u''_{\text{inc}})) &= 0 \quad \text{on } \Gamma, \\
\lim_{|x| \to +\infty} |x| \left| \partial_n v''_{[\varepsilon]}(x) - i \kappa v''_{[\varepsilon]}(x) \right| &= 0,
\end{align*}
\]

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where the linear condition on the boundary \( C ( \varepsilon, \partial_{\varepsilon} (v_{\infty}^{N} + u^{inc}), (v_{\infty}^{N} + u^{inc})) = 0 \) is the so-called Generalised Impedance Boundary Condition (GIBC). To construct the GIBCs, we extend to \( \mathbb{R}^3 \) the approach developed in [2] to model the 2D case of thin layers with variable thickness. The technique originates from the PhD thesis [29] and is based on an asymptotic expansion of the Helmholtz equation in \( \Omega_{ext} \) in terms of \( \varepsilon \) and surface derivatives on \( \Gamma \) presented in Section 2. We introduce a rapid variable \( S \) and thanks to the transformation of the thin layer into a band of thickness \( h \) we get \( u^{inc}_{\varepsilon} \) as a solution to a Sturm-Liouville type problem of variable \( S \). Once the differential equation is solved, then to boundary conditions and jump condition, we get the corresponding boundary condition corresponding to the exterior domain. The existence and uniqueness of a solution to these problems can be found in [10] for \( N = 1, 2 \). This approach leads first to estimate \( \| u^{ext}_{\varepsilon} - v_{\varepsilon}^{N} \| \mathcal{H}^{2}(\Gamma) = O(\varepsilon^{N+1}) \) and we deduce \( \| u^{ext}_{\varepsilon} - v_{\varepsilon}^{N} \| \mathcal{H}^{1}(\Omega_{ext} \cap B_R) = O(\varepsilon^{N+1}) \) for every ball \( B_R \) of radius \( R \) and \( \| u_{\varepsilon}^{inc} - v_{\varepsilon,inc}^{N} \| \mathcal{L}_{2}(\mathbb{S}^2) = O(\varepsilon^{N+1}) \) where \( v_{\varepsilon,inc}^{N} \) is the far-field pattern of the approximate solution \( v_{\varepsilon}^{N} \).

Then, assuming the thin layer having a constant thickness, we analyze the dependence of the solution, or equivalently its far-field pattern, to the transmission problem \( \{1\} \) with respect to the shape of the exterior boundary \( \Gamma \). The first shape derivative \( u^{ext}_{\varepsilon} \) solve the transmission problem \( \{2\} \) with non vanishing jumps across the exterior and the interior boundaries. On one hand, the shape derivative \( u^{ext}_{\varepsilon} \) is approached in Section 3 by the solution \( u_{\varepsilon}^{inc} \) of some exterior boundary value problems of the form

\[
\begin{aligned}
\Delta u_{\varepsilon}^{inc}[N] + k_{\varepsilon}^{2} u_{\varepsilon}^{inc}[N] &= 0 \quad \text{in } \Omega_{ext} \\
C(\varepsilon, \partial_{\varepsilon} u_{\varepsilon}^{inc}[N], u_{\varepsilon}^{inc}[N]) &= F_{ext}^{1,1} \quad \text{on } \Gamma \\
\lim_{|x| \to +\infty} |x| \partial_{n} u_{\varepsilon}^{inc}[N](x) - i k_{\varepsilon} u_{\varepsilon}^{inc}[N](x) &= 0 ,
\end{aligned}
\]

where the right-hand side \( F_{ext}^{1,1} \) can be expressed in terms of the boundary data of the exterior total field \( v_{\varepsilon}^{N} + u^{inc} \). In this case we naturally obtain \( \| u_{\varepsilon}^{inc} - w_{\varepsilon,inc}^{N} \| \mathcal{L}_{2}(\mathbb{S}^2) = O(\varepsilon^{N+1}) \) where \( w_{\varepsilon,inc}^{N} \) is the far-field pattern of the approximate solution \( u_{\varepsilon}^{inc} \). On the other hand, we provide in Section 4 the characterisation of the first shape derivative \( \tilde{v}_{\varepsilon}^{inc}[N] \) of the solution \( v_{\varepsilon}^{inc}[N] \) to the exterior problem \( \{3\} \) of the form

\[
\begin{aligned}
\Delta \tilde{v}_{\varepsilon}^{inc}[N] + k_{\varepsilon}^{2} \tilde{v}_{\varepsilon}^{inc}[N] &= 0 \quad \text{in } \Omega_{ext} \\
C(\varepsilon, \partial_{\varepsilon} \tilde{v}_{\varepsilon}^{inc}[N], \tilde{v}_{\varepsilon}^{inc}[N]) &= F_{ext}^{2,2} \quad \text{on } \Gamma \\
\lim_{|x| \to +\infty} |x| \partial_{n} \tilde{v}_{\varepsilon}^{inc}[N](x) - i k_{\varepsilon} \tilde{v}_{\varepsilon}^{inc}[N](x) &= 0 ,
\end{aligned}
\]

where the right-hand side \( F_{ext}^{2,2} \) can be expressed in terms of the boundary data of the exterior total field \( v_{\varepsilon}^{N} + u^{inc} \). In section 5 we prove for \( N = 0, 1, 2 \) that the two approaches are equivalent, which means \( \| \tilde{v}_{\varepsilon}^{inc}[N] - w_{\varepsilon,inc}^{N} \| \mathcal{H}^{2}(\mathbb{S}^2) = O(\varepsilon^{N+1}) \) and \( |\tilde{v}_{\varepsilon,inc}^{N} - w_{\varepsilon,inc}^{N}| \mathcal{L}_{2}(\mathbb{S}^2) = O(\varepsilon^{N+1}) \) where \( \tilde{v}_{\varepsilon,inc}^{N} \) is the far-field pattern of the derivative \( \tilde{v}_{\varepsilon}^{inc}[N] \). The various theoretical results are illustrated by some numerical experiments in chapter 7. The transmission problem and the exterior boundary value problems are solved using boundary integral equation methods [10] [30] (see the Appendix) and the high order spectral method [12]. Finally, we draw concluding remarks and we discuss possible research lines in Section 8.

2 Elementary differential geometry and asymptotic expansions

In this section, we derive the asymptotic expansion of the Laplacian operator in the neighborhood of \( \Gamma \) using the high-order material derivatives of some surface differential operators and Taylor-Young expansions. We use the surface differential operators: the tangential gradient \( \nabla_{\Gamma} \), the surface divergence \( \text{div}_{\Gamma} \) and the scalar Laplace-Beltrami operator \( \Delta_{\Gamma} \). For their definitions we refer to Nedelec’s book [29] (pp. 68-75). We use the notations of [25] and quote some useful results from [25] (pp. 67-78) and [12].

Since \( \Gamma \) is a smooth closed orientable boundary, there exists a tubular neighbourhood \( \tilde{\Gamma}_{s_0} \) of \( \Gamma \) in which any point \( y \) admits the unique expansion

\[
y = x + sn(x) , \text{ with } x \in \Gamma , \text{ and } s \in ] - s_0; s_0[ \text{ with } s_0 > 0 .
\]

For any \( s \in ] - s_0; s_0[ \), we set \( \Gamma_{s} := \{ y = x + sn(x) \mid x \in \Gamma \} \). We denote \( \nabla_{\Gamma} \) and \( \text{div}_{\Gamma} \) the tangential gradient and the surface divergence on \( \Gamma \), respectively, and we denote by \( n_{s} \) the outward unit normal vector to \( \Gamma_{s} \). For any scalar function \( u \) and vector function \( w \) defined in \( \tilde{\Gamma}_{s_0} \), the following expansions hold on \( \Gamma_{s} \):

\[
\nabla u = \nabla_{\Gamma_{s}} u + n_{s} \partial_{s} u ,
\]

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and
\[ \nabla \mathbf{w} = \text{div}_\Gamma \mathbf{w} + (\mathbf{n}_s \cdot \partial_s \mathbf{w}) . \]

We denote by \( \tau_s \) the transformation that maps the restriction \( u|\Gamma_s \) of \( u \) to \( \Gamma_s \) to the function defined on \( \Gamma \) by \( (\tau_s u|\Gamma_s)(x) = u|\Gamma_s(x + s \mathbf{n}(x)) \). Setting \( (\tau_s u|\Gamma_s)(x) = \mathbf{u}(x, s) \), we define an isomorphism between \( \Gamma_0 \) and \( \Gamma \times ]-s_0; 0[ \). The outward unit normal vector \( \mathbf{n}_s \) to the boundary \( \Gamma_s \) satisfies \( \mathbf{n}_s = \tau_s^* \mathbf{n} \). Using this change of coordinate system we can write for \( y \in \Gamma_1 \):

\[ (\nabla \mathbf{u})(y) = (\tau_s \nabla \mathbf{u})(x) = \tau_s \nabla_\Gamma \tau_s^{-1} \mathbf{u}(x, s) + \mathbf{n} \partial_s \mathbf{u}(x, s) , \]

and
\[ (\text{div} \mathbf{w})(y) = \tau_s (\text{div} \mathbf{w})(x) = \tau_s \text{div}_\Gamma \tau_s^{-1} \mathbf{w}(x, s) + \mathbf{n} \cdot \partial_s \mathbf{w}(x, s) . \]

The material derivatives of the surface differential operators has been extensively analysed in [12, Section 5] and we obtain the following result.

**Proposition 2.1.** The functions defined by \( s \in \mathcal{L}^2(\mathbb{R}; \mathbb{R}^3) \) and \( s \in [0, s_0[ \rightarrow \tau_s \nabla_\Gamma \tau_s^{-1} \in \mathcal{L}^2(\mathbb{R}; \mathbb{R}^3) \) and \( \text{div} \tau_s \nabla_\Gamma \tau_s^{-1} \in \mathcal{L}^2(\mathbb{R}; \mathbb{R}) \). To obtain the high order derivatives, it suffices to use the chain rule since we have \([25, \text{Eq.}(2.5.229)]\). To obtain the high order derivatives, it suffices to use the chain rule since we have \([25, \text{Eq.}(2.5.154)\) and \((2.5.155)]\).

The first order material derivatives corresponds to the commutators given in \([25, \text{Eqs.} (2.5.228)\) and \((2.229)]\). To obtain the high order derivatives, it suffices to use the chain rule since we have \([25, \text{Eq.}(2.5.154)\) and \((2.5.155)]\).

Further, we will use the gaussian curvature denoted by \( \mathcal{G} \), which satisfies
\[ \text{Trace}[\mathcal{R}^2] + 2\mathcal{G} = \mathcal{H}^2 . \]

and if we set \( \Pi_3 = 1 - \mathbf{n} \otimes \mathbf{n} \), then the Cayley Hamilton’s theorem implies
\[ \mathcal{R}^2 - \mathcal{H} \mathcal{R} + \mathcal{G} \Pi_3 = 0 . \]

Using the Taylor-Young formula in the neighbourhood of \( s = 0 \) and \([2.1] \), we can expand the gradient operator in the coordinate system \((x, s) \in \Gamma \times ]-s_0; s_0[ \) and we obtain for any \( N \in \mathbb{N} \)

\[ (\nabla \mathbf{u})(x + s \mathbf{n}(x)) = \mathbf{n}(x) \partial_s \mathbf{u}(x, s) + \nabla_\Gamma \mathbf{u}(x, s) + \sum_{\ell=0}^N \frac{1}{\ell!} \partial_s^\ell(\tau_s \nabla_\Gamma \tau_s^{-1})_{s=0} \mathbf{u}(x, s) + O(s^{N+1}) , \]

with \( \frac{1}{\ell!} \partial_s^\ell(\tau_s \nabla_\Gamma \tau_s^{-1})_{s=0} = (-1)^\ell \mathcal{R}^\ell \nabla_\Gamma \). In the same way, we write
\[ (\text{div} \mathbf{w})(x + s \mathbf{n}(x)) = \mathbf{n}(x) \cdot \partial_s \mathbf{w}(x, s) + \text{div}_\Gamma \mathbf{w}(x, s) + \sum_{\ell=0}^N \frac{1}{\ell!} \partial_s^\ell(\tau_s \text{div}_\Gamma \tau_s^{-1})_{s=0} \mathbf{w}(x, s) + O(s^{N+1}) , \]

with
\[ \partial_s(\tau_s \text{div}_\Gamma \tau_s^{-1})_{s=0} = -\text{div}_\Gamma \mathcal{R} \mathbf{w} + \nabla_\Gamma \mathcal{H} \cdot \mathbf{w} - \text{Trace}[\mathcal{R}^2](\mathbf{n} \cdot \mathbf{w}) = -\left( \text{div}_\Gamma \mathcal{R} - \mathcal{H} \right) \Pi_3 \mathbf{w} + \mathcal{H} \text{div}_\Gamma \Pi_3 \mathbf{w} + (\mathcal{H}^2 - 2\mathcal{G})(\mathbf{n} \cdot \mathbf{w}) , \]

where \( \Pi_3 = 1 - \mathbf{n} \otimes \mathbf{n} \) and using the chain rules we obtain the following high order terms
\[ \frac{1}{2!} \partial_s^2(\tau_s \text{div}_\Gamma \tau_s^{-1})_{s=0} = \mathcal{H} \text{div}_\Gamma \mathcal{R} - \mathcal{H} \Pi_3 \mathbf{w} + (\mathcal{H}^2 - 2\mathcal{G}) \text{div}_\Gamma \Pi_3 \mathbf{w} + (\mathcal{H}^3 - 3\mathcal{G}) \mathbf{n} \cdot \mathbf{w} , \]

and
\[ \frac{1}{3!} \partial_s^3(\tau_s \text{div}_\Gamma \tau_s^{-1})_{s=0} = -\left[ (\mathcal{H}^2 - 2\mathcal{G}) \text{div}_\Gamma \mathcal{R} - \mathcal{H} \Pi_3 \mathbf{w} + (\mathcal{H}^3 - 2\mathcal{G}\mathcal{H}) \text{div}_\Gamma \Pi_3 \mathbf{w} \right] - \text{Trace}[\mathcal{R}^4](\mathbf{n} \cdot \mathbf{w}) . \]
The formula (2.5) is in accordance with the formula (2.5.182) in \[25\].

Indeed, the Neumann series of \((1 + s R(x))^{-1}\) yields the infinite series given in \[25\]. We deduce that the divergence operator is equal to its Taylor series in the tubular \(\Gamma_\infty\). Since we have \(\text{div} \, w = \text{Trace}[\nabla w]\), we also deduce that the divergence operator is equal to its Taylor series in \(\Gamma_\infty\). However, the high-order terms are easier to obtain by computing the material derivatives than taking the trace of \([R^\ell \nabla w]\) for any \(\ell \in \mathbb{N}\).

Assuming \(\forall x \in \Gamma, 0 < \varepsilon h(x) < s_0\), then we use the change of variable \(s = \varepsilon \delta S\) with \(S \in [0; h(x)]\). We set \(\bar{u}(x, s) = u(x, -\varepsilon S) = U(x, S)\) and we have

\[
\partial_s \bar{u}(x, s) = -\frac{1}{\varepsilon} \partial S U(x, S).
\]

Combining (2.5) and (2.6), we obtain the asymptotic expansion of the Laplacian \(\Delta = \text{div} \nabla\)

\[
\Delta = \frac{1}{\varepsilon^2} \left( \partial^2_S + \sum_{\ell=1}^N \varepsilon^\ell \Lambda_\ell + O(\varepsilon^{N+1}) \right),
\]

where

\[
\begin{align*}
\Lambda_1 &= -H \partial_S , \quad \Lambda_2 = \Delta_T - S(H^2 - 2G) \partial_S , \\
\Lambda_3 &= S(\text{div}_T(2R - H) \nabla_T + \Delta_T) - \varepsilon^3 (H^3 - 3HG) \partial_S , \\
\Lambda_4 &= S^2 (\text{div}_T(2R^2 - H) \nabla_T + \varepsilon^4 (2R^2 - H) \Delta_T) - \varepsilon^4 \text{Trace}[R^4] \partial_S .
\end{align*}
\]

The following proposition gives an expression of the outward unit normal vector to the interior boundary \(\Gamma^\varepsilon = \{ y = x - \varepsilon h(x)n(x) \mid x \in \Gamma \}\) for any function \(h\).

**Proposition 2.2.** The outward unit normal vector to \(\Gamma^\varepsilon\) is given by

\[
n^\varepsilon = \frac{(1 - \varepsilon h + \varepsilon^2 h^2 G)n + \varepsilon(1 + \varepsilon h(R - H)) \nabla h}{\sqrt{(1 - \varepsilon h H + \varepsilon^2 h^2 G)^2 + \varepsilon^2 (1 + \varepsilon h(R - H)) \nabla h}^2}.
\]

**Proof.** Assume that the tangent plane to \(\Gamma\) at the point \(x\) is generated by the unit vectors \(e_1(x)\) and \(e_2(x)\) such that the outward unit normal vector to \(\Gamma\) is defined by \(n = e_1 \times e_2\). The cotangent vectors are given by \(e^1 = e_2 \times n\) and \(e^2 = n \times e_1\). We have \(e_1 \cdot e^1 = \delta^1_1\) where \(\delta^1_1\) is the Kronecker symbol. The tangent plane to \(\Gamma^\varepsilon\) at the point \(y = x - \varepsilon h(x)n(x)\) is generated by the vectors \(e_1(x, \varepsilon) = D[I - \varepsilon h(x)n(x)]e_1(x)\) and \(D[I - \varepsilon h(x)n(x)]e_2(x)\) and the outward unit normal vector to \(\Gamma^\varepsilon\) is given by

\[
n^\varepsilon(y) = \frac{e_1(x, \varepsilon) \times e_2(x, \varepsilon)}{\| e_1(x, \varepsilon) \times e_2(x, \varepsilon) \|}.
\]

It remains to compute \(N^\varepsilon n_\varepsilon(x) = e_1(x, \varepsilon) \times e_2(x, \varepsilon)\). We have

\[
N^\varepsilon n_\varepsilon = e_1 \times e_2 - \varepsilon (D[hn]e_1 \times e_2 + e_1 \times D[hn]e_2) + \varepsilon^2 (D[hn]e_1 \times D[hn]e_2)
\]

\[
= n - \varepsilon (\text{Re}_1 e_1 \times e_2 + e_1 \times \text{Re}_2) - \varepsilon ((\nabla h \cdot e_1) n \times e_2 + (\nabla h \cdot e_2) e_1 \times n) + \varepsilon^2 (\nabla h \cdot e_1) n \times \text{Re}_2 + (\nabla h \cdot e_2) (\text{Re}_1 e_1 \times n) .
\]

To conclude we use the following equalities

\[
\text{Re}_1 \times e_2 + e_1 \times \text{Re}_2 = (H - R) e_1 \times e_2 = (H - R) n = Hn ,
\]

\[
(\nabla h \cdot e_1) n \times e_2 + (\nabla h \cdot e_2) e_1 \times n = - (\nabla h \cdot e_1) e_1 - (\nabla h \cdot e_2) e_2 = - \nabla h ,
\]

\[
\text{Re}_1 \times \text{Re}_2 = \text{cof} [R] (e_1 \times e_2) = \hat{g} n ,
\]

\[
n \times \text{Re}_2 = n \times \text{Re}_2 + R n \times e_2 = - (H - R) e_1 ,
\]

\[
\text{Re}_1 \times n = \text{Re}_1 \times n + e_1 \times R n = - (H - R) e_2 .
\]
3 Construction of the GIBCs

The construction of the GIBC is based on the assumption that the interior and exterior fields admit the following expansion when \( \varepsilon \) tends zero:

\[
\begin{align*}
\psi^\varepsilon_{int}(y) &= U^\varepsilon_{int}(x, S) = \sum_{\ell \geq 0} \varepsilon^\ell U^\varepsilon_{int}(x, S) \quad \text{in } \Gamma \times [0, h(x)], \\
\psi^\varepsilon_{ext}(y) &= \sum_{\ell \geq 0} \varepsilon^\ell \psi^\varepsilon_{ext}(y) \quad \text{in } \Omega_{ext}.
\end{align*}
\]

The problem (1.1) can be rewritten as follows:

\[
\begin{align*}
\sum_{\ell \geq 0} \varepsilon^\ell (\Delta u^\varepsilon_{int} + \kappa_i^2 u^\varepsilon_{ext}) &= 0 \quad \text{in } \Omega_{int} \\
\sum_{\ell \geq 0} \varepsilon^\ell \partial_\nu U^\varepsilon_{int} &= -\sum_{\ell \geq 1} \varepsilon^\ell \partial_\nu U^\varepsilon_{int} - \sum_{\ell \geq 2} \varepsilon^\ell \partial_\nu U^\varepsilon_{int} \\
\sum_{\ell \geq 0} \varepsilon^\ell U^\varepsilon_{int}(x, 0) &= u^\varepsilon_{int}(x) + \sum_{\ell \geq 0} \varepsilon^\ell u^\varepsilon_{ext}(x) \quad \text{on } \Gamma \times \{0\} \\
\sum_{\ell \geq 0} \varepsilon^\ell \partial_\nu U^\varepsilon_{int}(x, 0) &= -\frac{1}{\rho} \left( \partial_n u^\varepsilon_{inc}(x) + \sum_{\ell \geq 1} \varepsilon^\ell \partial_n u^\varepsilon_{ext}(x) \right) \quad \text{on } \Gamma \times \{0\},
\end{align*}
\]

and the interior field satisfies either a Dirichlet boundary condition on \( \Gamma \times \{h\} \)

\[
\sum_{\ell \geq 0} \varepsilon^\ell U^\varepsilon_{int} = 0,
\]

or a Neumann boundary condition on \( \Gamma \times \{h\} \) that can be rewritten using Proposition 2.2 as follows

\[
\sum_{\ell \geq 0} \varepsilon^\ell \partial_\nu U^\varepsilon_{int} = h H \sum_{\ell \geq 1} \varepsilon^\ell \partial_\nu U^\varepsilon_{int} - \frac{h^2 G}{\varepsilon} \sum_{\ell \geq 2} \varepsilon^\ell \partial_\nu U^\varepsilon_{int} - \frac{h^2 G}{\varepsilon} \sum_{\ell \geq 2} \varepsilon^\ell \nabla \cdot \nabla U^\varepsilon_{int}
\]

We identify the right and left hand sides of each equations in (3.1) according to the power \( \ell \geq 0 \) of \( \varepsilon \) and we solve iteratively the new systems - that can be split into two systems of unknowns \( U^\varepsilon_{int} \) and \( U^\varepsilon_{ext} \) respectively - to compute first \( U^\varepsilon_{int} \) and then recover the boundary condition satisfied by \( U^\varepsilon_{ext} \). From these results we deduce the GIBC satisfied by \( \psi^\varepsilon_{N} \), which is an approximation of \( \sum_{\ell \geq 0} \varepsilon^\ell u^\varepsilon_{ext} \) up to \( O(\varepsilon^{N+1}) \). The final results are stated in the following two propositions. We obtain similar results than in the 2D case [2].

**Proposition 3.1.** The GIBCs modeling sound-soft obstacles coated by thin layers with a variable thickness are given for \( N = 0, 1, 2, 3 \) by

\[
(\psi^\varepsilon_{N} + u^\varepsilon_{inc}) + B^{\varepsilon,N} \partial_n (\psi^\varepsilon_{N} + u^\varepsilon_{inc}) = 0
\]

where

\[
B^{\varepsilon,0} = 0, \quad B^{\varepsilon,1} = -\frac{1}{\rho}(\varepsilon h)I, \quad B^{\varepsilon,2} = -\frac{1}{\rho}(\varepsilon h) \left[ 1 + \frac{(\varepsilon h)}{2} H \right] I \quad \text{and}
\]

\[
B^{\varepsilon,3} = -\frac{1}{\rho}(\varepsilon h) \left[ 1 + \frac{\varepsilon h}{2} H I - \frac{(\varepsilon h)^2}{6} \Delta r + \frac{\varepsilon h}{2} \Delta r + \frac{\varepsilon h}{3} (\Delta r - \frac{\varepsilon h}{2} H) I \right] \varepsilon h.
\]

**Proof.** Collecting the equations when \( \ell = 0 \), we obtain the two systems

\[
\begin{align*}
\partial_\nu^3 U^0_{int} &= 0 \quad \text{in } \Gamma \times (0, h(x)) \\
\partial_\nu^2 U^0_{int} &= 0 \quad \text{on } \Gamma \times \{0\} \quad \text{and} \\
U^0_{int} &= 0 \quad \text{on } \Gamma \times \{h(x)\}
\end{align*}
\]

and

\[
\begin{align*}
\Delta u^0_{ext} + \kappa_i^2 u^0_{ext} &= 0 \quad \text{in } \Omega_{ext} \\
u^0_{ext} + u^0_{inc} &= U^0_{int} \quad \text{on } \Gamma.
\end{align*}
\]
The first equation implies that \( U^0_{\text{int}}(\mathbf{x}, S) \) is a polynomial function of degree 1 in the variable \( S \). The second equation implies that the leading coefficient is 0 and the third equation gives the constant term. We conclude

\[
U^0_{\text{int}}(\mathbf{x}, S) = 0.
\]

In this case we approach \( u^0_{\text{ext}} \) by the function \( v_{[0]} = u^0_{\text{ext}} \) and then \( u^0_{\text{ext}} - v_{[0]} = O(\varepsilon) \). When \( \ell = 1 \), we obtain the two systems

\[
\begin{align*}
&\partial_S^2 U^1_{\text{int}} = -\Lambda_1 U^0_{\text{int}} \quad \text{in } \Gamma \times (0, h(\mathbf{x})) \\
&\partial_S U^1_{\text{int}} = -\frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right) \quad \text{on } \Gamma \times \{0\} \\
&U^1_{\text{int}} = 0 \quad \text{on } \Gamma \times \{h(\mathbf{x})\}
\end{align*}
\]

and the third equation gives the constant term. We conclude with similar arguments that

\[
U^1_{\text{int}}(\cdot, S) = -(S - h(\mathbf{x})) \frac{1}{2} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right).
\]

We compute \( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} = \varepsilon h \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right) \) on \( \Gamma \). In this case we approach the solution \( u^\ell_{\text{ext}} \) by the function \( v_{[1]} \) that satisfies the Helmholtz equation and the boundary condition \( (u^{inc} + v_{[1]}) = \varepsilon h \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + v_{[1]} \right) \) and we get \( u^\ell_{\text{ext}} - v_{[1]} = O(\varepsilon^2) \). When \( \ell = 2 \), we obtain the two systems

\[
\begin{align*}
&\partial_S^2 U^2_{\text{int}} = -\Lambda_1 U^1_{\text{int}} - (A_2 + \kappa^2) U^0_{\text{int}} \quad \text{in } \Gamma \times (0, h(\mathbf{x})) \\
&\partial_S U^2_{\text{int}} = -\frac{1}{\rho} \partial_n u^0_{\text{ext}} \quad \text{on } \Gamma \times \{0\} \\
&U^2_{\text{int}} = 0 \quad \text{on } \Gamma \times \{h(\mathbf{x})\}
\end{align*}
\]

and the third equation gives the constant term. We conclude

\[
U^2_{\text{int}}(\cdot, S) = -\mathcal{H} \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right),
\]

and we conclude

\[
U^2_{\text{int}}(\cdot, S) = -\left( \frac{S^2 - h^2(\mathbf{x})}{2} \right) \mathcal{H} \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right) - (S - h(\mathbf{x})) \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right).
\]

We compute \( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} = \varepsilon h^\frac{1}{2} \mathcal{H} \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right) + \varepsilon h \frac{1}{\rho} \partial_n \left( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} \right) \) on \( \Gamma \). In this case we approach the solution \( u^\ell_{\text{ext}} \) by the function \( v_{[2]} \) that satisfies the Helmholtz equation and the boundary condition \( (u^{inc} + v_{[2]}) = (\varepsilon h) \left( 1 + \frac{\varepsilon h}{2} \mathcal{H} \right) \frac{1}{\rho} \partial_n \left( u^{inc} + v_{[2]} \right) \) and we get \( u^\ell_{\text{ext}} - v_{[2]} = O(\varepsilon^3) \). When \( \ell = 3 \), we obtain the two systems

\[
\begin{align*}
&\partial_S^2 U^3_{\text{int}} = -\Lambda_1 U^2_{\text{int}} - (A_2 + \kappa^2) U^1_{\text{int}} \quad \text{in } \Gamma \times (0, h(\mathbf{x})) \\
&\partial_S U^3_{\text{int}} = -\frac{1}{\rho} \partial_n u^0_{\text{ext}} \quad \text{on } \Gamma \times \{0\} \\
&U^3_{\text{int}} = 0 \quad \text{on } \Gamma \times \{h(\mathbf{x})\}
\end{align*}
\]

and the third equation gives the constant term. We conclude

\[
U^3_{\text{int}}(\cdot, S) = -S(2\mathcal{H}^2 - 2\mathcal{G}) \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right) - \mathcal{H} \frac{1}{\rho} \partial_n u^1_{\text{ext}} + (\Delta \mathcal{G} + \kappa^2)(S - h(\mathbf{x})) \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right),
\]

and we conclude

\[
U^3_{\text{int}}(\cdot, S) = -S^2 \frac{h^2(\mathbf{x})}{6} \left[ (2\mathcal{H}^2 - 2\mathcal{G}) \mathcal{H} \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right) \right. - (\Delta \mathcal{G} + \kappa^2) \mathcal{H} \frac{1}{\rho} \partial_n \left( u^0_{\text{ext}} + u^{inc} \right) \left. - \frac{S^2 - h^2(\mathbf{x})}{2} \right] \mathcal{H} \frac{1}{\rho} \partial_n \left( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} \right)
\]

and the third equation gives the constant term. We conclude

\[
U^3_{\text{int}}(\cdot, S) = S(2\mathcal{H}^2 - 2\mathcal{G}) \frac{1}{\rho} \partial_n \left( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} \right) + \frac{1}{2}(\varepsilon h)^2 \mathcal{H} \frac{1}{\rho} \partial_n \left( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} \right) + \frac{1}{2}(\varepsilon h)^2 \mathcal{H} \frac{1}{\rho} \partial_n \left( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} \right) \text{ on } \Gamma.
\]

We compute \( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} = (\varepsilon h) \left( \frac{1}{2}(\varepsilon h)(\kappa^2 + \mathcal{H}^2 - \mathcal{G}) \right) \mathcal{H} \frac{1}{\rho} \partial_n \left( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^{\ell}_{\text{ext}} \right) \) on \( \Gamma \). In this case we approach the solution \( u^\ell_{\text{ext}} \) by the function \( v_{[3]} \) that satisfies the Helmholtz equation and the boundary condition \( u^{inc} + v_{[3]} = \mathcal{H} \frac{1}{\rho} \partial_n \left( u^{inc} + v_{[3]} \right) \) and we get \( u^\ell_{\text{ext}} - v_{[3]} = O(\varepsilon^3) \).
Proposition 3.2. The GIBCs modeling sound-hard obstacles coated by thin layers with a variable thickness are given for \( N = 0, 1, 2 \) by

\[
\begin{align*}
\partial_n (v^h \| u^{inc}) + B^{ch, N} (v^h \| u^{inc}) &= 0 \\
\partial_n (v^h \| u^{inc}) + B^{ch, N} (v^h \| u^{inc}) &= 0
\end{align*}
\]

where

\[
B^{ch, 0} = 0, \quad B^{ch, 1} = \rho \left[ \text{div}_T (\varepsilon h) \nabla_T + (\varepsilon h) \kappa_T^2 I \right],
\]

\[
B^{ch, 2} = \rho \left[ \text{div}_T (\varepsilon h) (1 + (\varepsilon h) (R - \frac{1}{2} H)) \nabla_T + (\varepsilon h) (1 - \frac{1}{2} (\varepsilon h) H) \kappa_T^2 I \right],
\]

\[
B^{ch, 3} = \text{div}_T (\varepsilon h) \left( 1 + \frac{\varepsilon h}{2} (2 R - H) + \frac{(\varepsilon h)^2}{3} (2 R^2 - H R) \right) \nabla_T + \varepsilon h \left( 1 - \frac{\varepsilon h}{2} H + \frac{(\varepsilon h)^2}{3} G \right) \kappa_T^2 I
\]

\[
- \frac{(\varepsilon h)^3}{6} \left[ \Delta_T + \kappa_T^2 I \right]^2 + \frac{(\varepsilon h)^2}{2} \left[ \Delta_T + \kappa_T^2 I \right] \text{div}_T (\varepsilon h) \nabla_T + \varepsilon h \kappa_T (\varepsilon h) I
\]

\[
+ \frac{1}{2} \nabla_T (\varepsilon h) \cdot \nabla_T \left( \text{div}_T (\varepsilon h) \nabla_T + \varepsilon h \kappa_T (\varepsilon h) I \right).
\]

Proof. The rank \( \ell = 0 \) allows us to compute \( \mathbf{U}^0_{int} \) only. We obtain the system

\[
\begin{align*}
\partial_\mathbf{x} \mathbf{U}^0_{int} &= 0 \quad \text{in } \Gamma \times (0, h(x)) \\
\partial_\mathbf{y} \mathbf{U}^0_{int} &= 0 \quad \text{on } \Gamma \times \{ h(x) \} \\
\mathbf{U}^0_{int} &= (u^{inc} + u^0_{ext}) \quad \text{on } \Gamma \times \{ 0 \}.
\end{align*}
\]

The first equation implies that \( \mathbf{U}^0_{ext}(x, S) \) is a polynomial function of degree 1 in the variable \( S \). The second equation implies that the leading coefficient is 0 and the third equation gives the constant term. We conclude that

\[
\mathbf{U}^0_{int} (\cdot, S) = (u^{inc} + u^0_{ext}).
\]

When \( \ell = 1 \), we obtain the two systems

\[
\begin{align*}
\partial_\mathbf{x} \mathbf{U}^1_{int} &= - \Lambda_1 \mathbf{U}^0_{int} = 0 \quad \text{in } \Gamma \times (0, h(x)) \\
\partial_\mathbf{y} \mathbf{U}^1_{int} &= \delta \partial_\mathbf{x} \mathbf{U}^0_{int} = 0 \quad \text{on } \Gamma \times \{ h(x) \} \\
\mathbf{U}^1_{int} &= u^1_{ext} \quad \text{on } \Gamma \times \{ 0 \}.
\end{align*}
\]

We conclude with similar arguments that

\[
\mathbf{U}^1_{int} (\cdot, S) = u^1_{ext}.
\]

We compute \( \partial_n (u^{inc} + u^0_{ext}) = 0 \) on \( \Gamma \). In this case we approach \( u^1_{ext} \) by the function \( v^0_0 = u^0_{ext} \) and then \( \partial_n (u^1_{ext} - v^0_0) = O(\varepsilon) \). When \( \ell = 2 \), we obtain the two systems

\[
\begin{align*}
\partial_\mathbf{x} \mathbf{U}^2_{int} &= - \Lambda_1 \mathbf{U}^1_{int} - (\Lambda_2 + \kappa_2^2) \mathbf{U}^0_{int} \quad \text{in } \Gamma \times (0, h(x)) \\
\partial_\mathbf{y} \mathbf{U}^2_{int} &= \nabla_T h \cdot \nabla_T (u^{inc} (x) + u^0_{ext} (x)) \quad \text{on } \Gamma \times \{ h(x) \} \\
\mathbf{U}^2_{int} &= u^2_{ext} \quad \text{on } \Gamma \times \{ 0 \}.
\end{align*}
\]

We compute

\[
\partial_\mathbf{x} \mathbf{U}^2_{int} = - (\Delta_T + \kappa_T^2) (u^{inc} + u^0_{ext}),
\]

and we conclude

\[
\mathbf{U}^2_{int} (\cdot, S) = - \left( \frac{S^2}{2} - S h(x) \right) (\Delta_T + \kappa_T^2) (u^{inc} + u^0_{ext}) + S \nabla_T h \cdot \nabla_T (u^{inc} + u^0_{ext}) + u^2_{ext},
\]

We compute \( \partial_n \left( u^{inc} + \sum_{\ell=0}^2 \varepsilon^\ell u^\ell_{ext} \right) = - \rho \left( \text{div}_T (\varepsilon h) \nabla_T + (\varepsilon h) \kappa_T^2 \right) (u^{inc} + u^0_{ext}) \) on \( \Gamma \). In this case we approach the solution \( u^3_{ext} \) by the function \( v^3_1 \) that satisfies the Helmholtz equation and the boundary condition \( \partial_n (u^{inc} + v^3_1) = - \rho \left( \text{div}_T (\varepsilon h) \nabla_T + (\varepsilon h) \kappa_T^2 \right) (u^{inc} + v^3_1) \) and we get \( \partial_n (u^3_{ext} - v^3_1) = O(\varepsilon^2) \). When \( \ell = 3 \), we obtain the two systems

\[
\begin{align*}
\partial_\mathbf{x} \mathbf{U}^3_{int} &= - \Lambda_1 \mathbf{U}^2_{int} - (\Lambda_2 + \kappa_2^2) \mathbf{U}^1_{int} - \Lambda_3 \mathbf{U}^0_{int} \quad \text{in } \Gamma \times (0, h(x)) \\
\partial_\mathbf{y} \mathbf{U}^3_{int} &= h \partial_\mathbf{x} \mathbf{U}^2_{int} - h^2 \partial_\mathbf{x} \mathbf{U}^1_{int} + \nabla_T h \cdot \nabla_T \mathbf{U}^1_{int} + \Gamma \times \{ h(x) \} \\
\mathbf{U}^3_{int} &= u^3_{ext} \quad \text{on } \Gamma \times \{ 0 \}.
\end{align*}
\]
and
\[
\begin{align*}
\Delta u_{ext}^3 + \kappa^2 \nu_{ext}^3 &= 0 & \text{in } \Omega_{ext} \\
\partial_n u_{ext}^3 &= -\rho \partial_n U^3_{int} \text{ on } \Gamma.
\end{align*}
\]

We compute
\[
\partial^2 S U^3_{int}(\cdot, S) = -(S - \kappa^2 \nu_{ext}^3 + \kappa^2 \nu_{ext}^3) + \mathcal{H}_x^R \cdot \nabla \cdot (u_{inc}^3 + u_{ext}^3) + \mathcal{H}_x \nabla \cdot \nabla \Gamma \nabla (u_{inc}^3 + u_{ext}^3)
\]
and
\[
\partial_S U^3_{int}(\cdot, h(x)) = h \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) + \nabla \nu \cdot \nabla \nu_{ext}^3 + h \nabla \nabla \cdot (2R - h) \nabla \nabla \Gamma \nabla (u_{inc}^3 + u_{ext}^3).
\]

We conclude
\[
U^3_{int}(\cdot, S) = \frac{S^3}{3} \left[ \mathcal{H}_x \Delta \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) + (\nabla \nabla \cdot \nabla \nabla \Gamma \nabla (u_{inc}^3 + u_{ext}^3)
\]
\[
\left. + \frac{S^2}{2} \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) \right] \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) - \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) \right] \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) + \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3).
\]

We compute
\[
\partial_S U^3_{int}(\cdot, S) = \frac{S^3}{6} \left[ \mathcal{H}_x \Delta \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) + (\nabla \nabla \cdot \nabla \nabla \Gamma \nabla (u_{inc}^3 + u_{ext}^3)
\]
\[
\left. + \frac{S^2}{2} \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) \right] \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) - \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) \right] \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) + \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3).
\]

We approach the solution \( \nu_{ext}^3 \) by the function \( \nu_{ext}^3 \) that satisfies the Helmholtz equation and the boundary condition
\[
\partial_n (u_{inc}^3 + \nu_{ext}^3) = -\rho \left( \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + \nu_{ext}^3) \right) \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + \nu_{ext}^3).
\]

When \( \ell = 4 \), we obtain the two systems
\[
\begin{align*}
\partial_S U^4_{int}(\cdot, S) &= -(S - h) \mathcal{H}_x \Delta \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) + (\nabla \nabla \cdot \nabla \nabla \Gamma \nabla (u_{inc}^3 + u_{ext}^3)
\]
\[
\left. + (S - h) \mathcal{H}_x \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) \right] \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) - (S - h) \mathcal{H}_x \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3).
\]

We obtain
\[
\partial_S U^4_{int}(\cdot, S) = -(S - h) \left[ \mathcal{H}_x \Delta \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) + (\nabla \nabla \cdot \nabla \nabla \Gamma \nabla (u_{inc}^3 + u_{ext}^3)
\]
\[
\left. + (S - h) \mathcal{H}_x \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) \right] \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3) - (S - h) \mathcal{H}_x \nabla \nabla \cdot \nabla \nabla (u_{inc}^3 + u_{ext}^3).
\]

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We compute \( \partial_n u^3_{ext} = -\rho \partial_\gamma U^3_{int}(\cdot, 0) \) and obtain on \( \Gamma \)

\[
\partial_n u^3_{ext} = -\rho \left( \nabla \cdot \nabla_{\Gamma} h \nabla_{\Gamma} + \kappa^2 \right) u^2_{ext} - \rho \left( \nabla \cdot \nabla_{\Gamma} \left( \frac{1}{2} \mathcal{H} \right) \nabla_{\Gamma} + \frac{1}{2} \mathcal{H} \kappa_{\Gamma}^2 \right) u^1_{ext}
- \frac{\kappa^2}{\rho} \nabla \cdot \nabla_{\Gamma} \left( \nabla_{\Gamma} h \nabla_{\Gamma} + \kappa^2 \right) \left( u^{inc} + u^0_{ext} \right)
+ \frac{\kappa^2}{\rho} \left( \Delta_{\Gamma} + \kappa^2 \right) \left( u^{inc} + u^0_{ext} \right)
- \frac{\kappa^2}{\rho} \nabla \cdot \nabla_{\Gamma} \left( \nabla \cdot \nabla_{\Gamma} h \nabla_{\Gamma} + \kappa^2 \right) \left( u^{inc} + u^0_{ext} \right).
\]

We construct the approximate solution \( v^\varepsilon_{[3]} \) in the same way as previously and we get \( \partial_n (u^3_{ext} - v^\varepsilon_{[3]}) = O(\varepsilon^3) \).

4 Construction of GIBCs for the shape derivatives

In the remaining of the paper, we assume that the layer \( \Omega^\varepsilon_{int} \) has a constant thickness \( \varepsilon > 0 \) which means \( \forall x \in \Gamma, h(x) = 1 \). This section is devoted to the shape derivative analysis of the solution to the thin layer transmission problem. In paragraph 4.1.3 we give a characterization of the shape derivative as a solution to a new transmission problem with non vanishing jumps. In paragraphs 4.2 we construct the GIBC satisfied by the approximate shape derivative \( w_{[N]}^\varepsilon \) for \( N = 0, 1, 2 \).

4.1 Characterization of the shape derivative

From now on, we choose a fixed reference domain \( \Omega \) with a closed and orientable boundary \( \Gamma \) of class \( \mathcal{C}^3 \), with \( k \) as great as we need, and we consider variations generated by transformations of the form \( x \mapsto x + \theta(x) \) of point \( x \) in the space \( \mathbb{R}^3 \), where \( \theta \) is a smooth vector function defined in a neighborhood of \( \Gamma \). The functions \( \theta \) are assumed to be sufficiently small elements in an open subset \( \Gamma \) of the Banach space \( \mathcal{C}^2(\Gamma, \mathbb{R}^3) \) in order that \( (I + \theta) \) is a diffeomorphism from \( \Gamma \) to \( \Gamma_\theta := \{ x_\theta = x + \theta(x); x \in \Gamma \} \). By \( n_\theta \) we denote the outward unit normal vector to \( \Gamma_\theta \) and we set

\[ \Gamma_\theta := \{ y_\theta = x_\theta - \varepsilon n_\theta(x_\theta) \mid x_\theta \in \Gamma_\theta \}. \]

The transformation \( \tau^{-1} \) maps the restriction \( \theta_\Gamma \) of \( \theta \) to \( \Gamma \) to the function defined on \( \Omega^\varepsilon \) by \( \tau^{-1}(\theta_\Gamma)(x) + \varepsilon n(x) = \theta(x) \). We have \( \Gamma_\theta = (I + \theta)\Gamma \) but in general \( \Gamma_\theta \neq (I + \tau^{-1} \theta)\Gamma^\varepsilon \). Indeed, let \( y_\theta \in \Gamma_\theta \) and \( y \in \Gamma^\varepsilon \), then

\[
y_\theta - y = x_\theta - \varepsilon n_\theta(x_\theta) - (x - \varepsilon n(x)) = \theta(x) - \varepsilon (n_\theta(x + \theta(x)) - n(x)) = \theta(x) - \varepsilon \nabla_\theta \theta(x)\left| n(x) \right| + O(\|\theta\|_{\mathcal{C}^2}) \nonumber.
\]

The following theorem is a direct consequence of the Theorem 4.2 in [22] (see also [18, 19]).

**Theorem 4.1.** Assume that \( (u^3_{int}, u^3_{ext}) \) is the solution to the transmission problem \( (\ref{4.1}) \) where \( f_{ext} \) and \( g_{int} \) are the boundary data of \( u_{inc} \) on \( \Gamma_\theta \) and \( f_{int} = 0 = g_{int} \) on \( \Gamma_\theta \). Then the mappings \( \theta \mapsto u^3_{int} \) and \( \theta \mapsto u^3_{ext} \) are Fréchet differentiable at \( \theta = 0 \) and the derivative \( (u^3_{int}, u^3_{ext}) \) in the direction \( \theta \in \mathcal{C}^3(\Gamma, \mathbb{R}^3) \) is the radiating solution to the transmission problem

\[
\begin{cases}
\Delta u^3_{int} + \kappa^2 u^3_{int} = 0 & \text{in } \Omega^\varepsilon_{int} \\
\Delta u^3_{ext} + \kappa^2 u^3_{ext} = 0 & \text{in } \Omega^\varepsilon_{ext} \\
\rho \partial_n u^3_{int} - \partial_n u^3_{ext} = \left( \rho - 1 \right) \nabla_\Gamma (\theta \cdot n)\nabla_{\Gamma} + \left( \theta \cdot n \right) \left( \rho \kappa^2 - \kappa^2 \right) \left( u^{inc} + u^0_{ext} \right) & \text{on } \Gamma^\varepsilon \\
u^3_{int} - u^3_{ext} = -\left( \theta \cdot n \right) \left( \frac{1}{\rho} - 1 \right) \partial_n \left( u^{inc} + u^0_{ext} \right) & \text{on } \Gamma^\varepsilon,
\end{cases}
\]

with either a non vanishing Dirichlet boundary condition on \( \Gamma^\varepsilon \)

\[
u^3_{int} = -\left( \tau^{-1} \varepsilon (\theta \cdot n) \right) \partial_n u^3_{int},
\]

or a non vanishing Neumann boundary condition on \( \Gamma^\varepsilon \)

\[
\partial_n u^3_{int} = \left( \nabla_\Gamma \left( \tau^{-1} \varepsilon (\theta \cdot n) \right) \right) \nabla_{\Gamma} + \left( \tau^{-1} \varepsilon (\theta \cdot n) \kappa^2 \right) u^3_{int}.
\]

**Proof.** Among all the already existing techniques to prove the Fréchet differentiability of the solution we can consider the boundary integral equation approach. Using the results detailed in Appendix B the material derivative analysis of boundary integral operators presented in [12] we deduce the Fréchet differentiability of the solution. It remains to compute the boundary condition satisfied by the solution. The boundary conditions fulfilled by the derivative \( \theta \) are given in Theorem 4.2 in [22]. It remains to compute the boundary data of the derivative on \( \Gamma^\varepsilon \).
• In the case of a Dirichlet boundary condition on \( \Gamma^c \), we have

\[
\vec{u}_{\text{int}}^\varepsilon(x + \theta(x) - \varepsilon n_\theta(x + \theta(x))) = 0, \quad \text{for all } x \in \Gamma \text{ and for all } \theta \in \mathcal{O}.
\]

The material derivative of the normal vector is given in [12] Lemma 4.3 by \( \partial_k n_\varepsilon(1+\xi)\). By differentiation with respect to the normal vector, we have

\[
0 = \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x)) + \theta(x) + \varepsilon[\tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} \theta(x)]n(x) \cdot (\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
= \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x)) + (\theta(x) \cdot n(x))\partial_n \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x))
\]

since \( \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x)) = 0 \) for all \( x \in \Gamma \).

• In the case of a Neumann boundary condition on \( \Gamma^c \), we have

\[
\partial_n \vec{u}_{\text{int}}^\varepsilon(x + \theta(x) - \varepsilon n_\theta(x + \theta(x))) = 0, \quad \text{for all } x \in \Gamma \text{ and for all } \theta \in \mathcal{O}.
\]

By differentiation with respect to the boundary parameterization, we have

\[
0 = \partial_n \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x)) - \tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} (\theta(x) + \varepsilon[\tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} \theta(x)]n(x)) \cdot n(x) \cdot (\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
+ n(x) \cdot \left[ (\theta(x) + \varepsilon[\tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} \theta(x)]n(x)) \cdot \nabla \vec{u}_{\text{int}}^\varepsilon \right]_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
= \partial_n \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x)) - \tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} (\theta(x) + \varepsilon[\tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} \theta(x)]n(x)) \cdot n(x) \cdot (\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
+ (\theta(x) \cdot n(x))(n(x) \cdot \partial_n \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
+ n(x) \cdot \left[ (\theta(x) + \varepsilon[\tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} \theta(x)]n(x)) \cdot \nabla \vec{u}_{\text{int}}^\varepsilon \right]_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
= \partial_n \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x)) - \tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} (\theta(x) + \varepsilon[\tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} \theta(x)]n(x)) \cdot n(x) \cdot (\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
+ (\theta(x) \cdot n(x))(-\kappa_\varepsilon^2 \vec{u}_{\text{int}}^\varepsilon - \Delta_{\Gamma^c} \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
- (\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x)) \cdot (\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
= \partial_n \vec{u}_{\text{int}}^\varepsilon(x + \varepsilon n(x)) - \tau_{e} \nabla_{\Gamma} \tau_{e}^{-1} (\theta(x) \cdot n(x)) \cdot (\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
- (\theta(x) \cdot n(x))(-\kappa_\varepsilon^2 \vec{u}_{\text{int}}^\varepsilon - \Delta_{\Gamma^c} \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x))
\]

\[
- \text{div}_{\Gamma^c} \tau_{e}^{-1} (\theta \cdot n)(\nabla \vec{u}_{\text{int}}^\varepsilon)_{\Gamma^c}(x + \varepsilon n(x)).
\]

Now, we assume \( \vec{u}_{\text{ext}}^\varepsilon(y) = \vec{U}_{\text{ext}}^\varepsilon(x, S) = \sum_{\ell \geq 0} \varepsilon^\ell \vec{U}_{\text{int}}^\varepsilon(x, S) \) in \( \Gamma \times [0, 1] \) and \( \vec{u}_{\text{ext}}^\varepsilon(y) = \sum_{\ell \geq 0} \varepsilon^\ell \vec{U}_{\text{ext}}^\varepsilon(y) \) in \( \Omega_{\text{ext}} \). If we use the asymptotic expansions of the gradient \( \text{(2.5)} \) and the divergence \( \text{(2.6)} \) we obtain

\[
(\tau_{e} \text{div}_{\Gamma^c} \tau_{e}^{-1})(\theta \cdot n)(\tau_{e} \nabla_{\Gamma} \tau_{e}^{-1}) = \text{div}_{\Gamma}(\theta \cdot n)\nabla_{\Gamma} + \sum_{\ell \geq 1} \varepsilon^\ell B_{1}^\varepsilon.
\]

with

\[
B_{1}^\varepsilon = \text{div}_{\Gamma}(\theta \cdot n)(2R - H)\nabla_{\Gamma} + H\text{div}_{\Gamma}(\theta \cdot n)\nabla_{\Gamma}.
\]

and

\[
B_{2}^\varepsilon = \text{div}_{\Gamma}(\theta \cdot n)(2R^2 - HR)\nabla_{\Gamma} + H\text{div}_{\Gamma}(\theta \cdot n)(2R - H)\nabla_{\Gamma} + (H^2 - \ell)\text{div}_{\Gamma}(\theta \cdot n)\nabla_{\Gamma}.
\]
The transmission problem (4.1) can be rewritten as follows:
\[
\begin{aligned}
\sum_{\ell \geq 0} \varepsilon^\ell (\Delta \mathcal{U}_{\text{ext}}^\ell + \kappa_2^2 \mathcal{U}_{\text{ext}}^{\ell^2}) &= 0 \quad \text{in } \Omega_{\text{ext}} \\
\sum_{\ell \geq 0} \varepsilon^\ell \partial_3^2 \mathcal{U}_{\text{int}}^\ell &= - \sum_{\ell \geq 1} \varepsilon^\ell \Lambda_1 \mathcal{U}_{\text{int}}^{\ell-1} - \sum_{\ell \geq 2} \varepsilon^\ell (\Lambda_2 + \kappa_1^2) \mathcal{U}_{\text{int}}^{\ell-2} \\
&- \sum_{k \geq 3} \sum_{\ell \geq k} \varepsilon^\ell \Lambda_k \mathcal{U}_{\text{int}}^{\ell-k} \\
\sum_{\ell \geq 0} \varepsilon^\ell \mathcal{U}_{\text{int}}^\ell &= \sum_{\ell \geq 0} \varepsilon^\ell \mathcal{U}_{\text{ext}}^\ell \\
&\quad - (\theta \cdot n)(\frac{1}{p} - 1) \left( \partial_n (u_{\text{ext}}^0 + u_{\text{inc}}) + \sum_{\ell \geq 1} \varepsilon^\ell \partial_n u_{\text{ext}}^\ell \right) \quad \text{on } \Gamma \times \{0\} \\
\sum_{\ell \geq 0} \varepsilon^\ell \partial_3 \mathcal{U}_{\text{int}}^\ell &= - \frac{1}{p} \sum_{\ell \geq 1} \varepsilon^\ell \partial_3 u_{\text{ext}}^{\ell-1} \\
&\quad - \varepsilon \left[ (1 - \frac{1}{p}) \mathrm{div}_\Gamma (\theta \cdot n) \nabla_\Gamma + (\theta \cdot n) (\kappa_1^2 - \frac{1}{p} \kappa_2^2) \right] (u_{\text{ext}}^0 + u_{\text{inc}}) \\
&\quad - \left[ (1 - \frac{1}{p}) \mathrm{div}_\Gamma (\theta \cdot n) \nabla_\Gamma + (\theta \cdot n) (\kappa_1^2 - \frac{1}{p} \kappa_2^2) \right] \sum_{\ell \geq 2} \varepsilon^\ell u_{\text{ext}}^{\ell-1} \quad \text{on } \Gamma \times \{0\} ,
\end{aligned}
\]
with either the Dirichlet condition on $\Gamma \times \{1\}$ that can be written
\[
\sum_{\ell \geq 0} \varepsilon^\ell \mathcal{U}_{\text{int}}^{\ell-1} (\cdot, 1) = (\theta \cdot n) \sum_{\ell \geq 0} \varepsilon^\ell \partial_3 \mathcal{U}_{\text{int}}^\ell (\cdot, 1)
\]
or the Neumann condition on $\Gamma \times \{1\}$ that can be written
\[
\sum_{\ell \geq 0} \varepsilon^\ell \partial_3 \mathcal{U}_{\text{int}}^\ell (\cdot, 1) = \sum_{\ell \geq 1} \varepsilon^\ell \left[ \mathrm{div}_\Gamma (\theta \cdot n) \nabla_\Gamma + (\theta \cdot n) \kappa_1^2 \right] \mathcal{U}_{\text{int}}^{\ell-1} (\cdot, 1) - \sum_{\ell \geq 2} \varepsilon^\ell B_1^\ell \mathcal{U}_{\text{int}}^{\ell-2} (\cdot, 1) + \cdots
\]

4.2 Construction of the GIBC for the shape derivative

The following two theorems give the GIBCs satisfied by the function $u_{\text{inc}}^\ell$, for $N = 0, 1, 2$, which is an approximation of $u_{\text{ext}}^\ell$ up to $O(\varepsilon^{N+1})$.

**Theorem 4.2.** The GIBCs associated to the transmission problem characterising the first shape derivative of the solution in the Dirichlet case can be written for $N = 0, 1, 2$ as follows
\[
w_{\text{inc}}^\ell = B_{\text{inc}}^N \partial_n u_{\text{inc}}^\ell = S_{\text{inc}}^{\ell, N} (u_{\text{inc}}^\ell + u_{\text{inc}}) + S_{\text{inc}}^{\ell, N} \partial_n (u_{\text{inc}}^\ell + u_{\text{inc}})
\]
where
\[
S_{\text{inc}}^{0} = 0 \quad \text{and} \quad S_{\text{inc}}^{2} = - (\theta \cdot n) I ,
\]
\[
S_{\text{inc}}^{1,1} = \varepsilon \left[ (1 - \frac{1}{p}) \mathrm{div}_\Gamma (\theta \cdot n) \nabla_\Gamma + (\theta \cdot n) (\kappa_1^2 - \frac{1}{p} \kappa_2^2) I \right] \quad \text{and} \quad S_{\text{inc}}^{2} = -(\theta \cdot n) \left( 1 + \varepsilon \frac{1}{p} H \right) I
\]
and
\[
S_{\text{inc}}^{1,2} = \varepsilon (1 + \varepsilon \frac{1}{p} H) \left[ (1 - \frac{1}{p}) \mathrm{div}_\Gamma (\theta \cdot n) \nabla_\Gamma + (\theta \cdot n) (\kappa_1^2 - \frac{1}{p} \kappa_2^2) I \right] \\
S_{\text{inc}}^{2,2} = -(\theta \cdot n) \left( 1 + \varepsilon \frac{1}{p} H + \varepsilon^2 \frac{1}{p} (H^2 - \nabla_\Gamma) \right) I - \frac{1}{p} \varepsilon^2 (\theta \cdot n) [\Delta_\Gamma + \kappa_1^2] \|
\]

**Proof.** When $\ell = 0$, we obtain the following equations that can be split into two systems
\[
\begin{aligned}
\partial_3^2 \mathcal{U}_{\text{int}}^0 &= 0 \quad \text{in } \Gamma \times \{0\} \\
\partial_3 \mathcal{U}_{\text{int}}^0 &= 0 \quad \text{on } \Gamma \times \{0\} \\
\mathcal{U}_{\text{int}}^0 &= (\theta \cdot n) \partial_3 \mathcal{U}_{\text{int}}^0 \quad \text{on } \Gamma \times \{1\}
\end{aligned}
\]
and
\[
\begin{aligned}
\Delta u_{\text{ext}}^0 + \kappa_2^2 u_{\text{ext}}^0 &= 0 \quad \text{in } \Omega_{\text{ext}} \\
u_{\text{ext}}^0 &= u_{\text{ext}}^0 + (\theta \cdot n) (\frac{1}{p} - 1) \partial_n (u_{\text{ext}}^0 + u_{\text{inc}}) \quad \text{on } \Gamma .
\end{aligned}
\]
We deduce
\[
\mathcal{U}_{\text{int}}^0 (x, S) = -(\theta \cdot n) \frac{1}{p} \partial_n (u_{\text{ext}}^0 + u_{\text{inc}})
\]
and $\psi^0_{ext} = -(\theta \cdot n)\partial_n (u^0_{ext} + u^{inc})$ on $\Gamma$. In this case we approach $\tilde{u}^\varepsilon_{ext}$ by the function $w^\varepsilon_{[1]} = u^0_{ext}$ and then $\tilde{u}^\varepsilon_{ext} - w^\varepsilon_{[1]} = O(\varepsilon)$. When $\ell = 1$, we obtain the two systems

$$
\begin{cases}
\partial_2^2 \mathbf{U}^\varepsilon_{int} &= - \Lambda \mathbf{U}^0_{int} = 0 \\
\partial_3 \mathbf{U}^\varepsilon_{int} &= - \frac{1}{\rho} \partial_n u^0_{ext} \\
\mathbf{U}^1_{int} &= (\theta \cdot n) \partial_3 \mathbf{U}^\varepsilon_{ext} \\
\mathbf{U}^0_{ext} &= (\theta \cdot n) \partial_n u^0_{ext}
\end{cases}
$$

in $\Gamma \times (0,1)$.

We compute $\mathbf{U}^1_{int} (\cdot, 1) = - (\theta \cdot n) \frac{1}{\rho} (\partial_n u^0_{ext} + \mathcal{H} \partial_n (u^0_{ext} + u^{inc}))$ and we deduce

$$
\mathbf{U}^1_{int} (\cdot, S) = - (S - 1) \left[ \frac{1}{\rho} \partial_n u^0_{ext} + \mathcal{H} \partial_n (u^0_{ext} + u^{inc}) \right] + \left[ 1 - \frac{1}{\rho} \right] \partial_n u^0_{ext} + u^{inc}.
$$

We have on $\Gamma$

$$
\psi^1_{ext} - \frac{1}{\rho} \partial_n \psi^0_{ext} = -(\theta \cdot n) \left( \partial_n \psi^1_{ext} + \mathcal{H} \frac{1}{\rho} \partial_n \psi^0_{ext} \right) + \left[ 1 - \frac{1}{\rho} \right] \partial_n \psi^0_{ext} + u^{inc}.
$$

and

$$
\sum_{\ell = 0}^1 \varepsilon^\ell \psi^\ell_{ext} - \frac{1}{\rho} \varepsilon \partial_n \psi^0_{ext} = -(\theta \cdot n) \left( \partial_n \psi^0_{ext} + \mathcal{H} \frac{1}{\rho} \partial_n \psi^0_{ext} \right) + \left[ 1 - \frac{1}{\rho} \right] \partial_n \psi^0_{ext} + u^{inc}.
$$

In this case we approach $\tilde{u}^\varepsilon_{int}$ by the function $w^\varepsilon_{[1]}$ which solves the Helmholtz equation and the boundary condition

$$
w^\varepsilon_{[1]} + B^{ext} \partial_n w^\varepsilon_{[1]} = -(\theta \cdot n) \left( \partial_n (u^{inc} + v^\varepsilon_{[1]}) + \mathcal{H} \frac{1}{\rho} \partial_n (v^\varepsilon_{[1]} + u^{inc}) \right) + \left[ 1 - \frac{1}{\rho} \right] \partial_n (u^{inc} + v^\varepsilon_{[1]}).
$$

and then $\tilde{u}^\varepsilon_{ext} - w^\varepsilon_{[1]} = O(\varepsilon^2)$ on $\Gamma$.

When $\ell = 2$, we obtain the two systems

$$
\begin{cases}
\partial_2^2 \mathbf{U}^2_{int} &= - \Lambda \mathbf{U}^1_{int} - (A_2 + \kappa_2^2) \mathbf{U}^0_{int} \\
\partial_3 \mathbf{U}^2_{int} &= - \frac{1}{\rho} \partial_n u^1_{ext} \\
\mathbf{U}^2_{ext} &= (\theta \cdot n) \partial_3 \mathbf{U}^\varepsilon_{ext} \\
\mathbf{U}^0_{ext} &= (\theta \cdot n) \partial_n u^0_{ext}
\end{cases}
$$

in $\Gamma \times (0,1)$.

We compute

$$
\begin{align*}
\partial_2^2 \mathbf{U}^2_{int} (\cdot, S) &= - \mathcal{H} \left[ \frac{1}{\rho} \partial_n u^0_{ext} + \left[ 1 - \frac{1}{\rho} \right] \partial_n u^0_{ext} + \mathcal{H} \frac{1}{\rho} \partial_n u^0_{ext} \right] \\
\mathbf{U}^2_{int} (\cdot, 1) &= - \frac{1}{2} (\theta \cdot n) \left[ (2 \mathcal{H}^2 - 2 \mathcal{G}) \frac{1}{\rho} \partial_n u^0_{ext} + u^{inc} \right] + \left[ 1 - \frac{1}{\rho} \right] \partial_n u^0_{ext} + u^{inc}
\end{align*}
$$

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and we conclude
\[
U_{\text{int}}^2(\cdot, S) = -\left(\frac{S^2 - 1}{2}\right)H\left[\frac{1}{2}\partial_\nu u^0_{\text{ext}} + \left[(1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right](u^0_{\text{ext}} + u^{inc})\right]
\]
\[
+ \left(\frac{S^2 - 1}{2}\right)(\Delta\Gamma + \kappa^2_e)(\theta \cdot n)\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc})
\]
\[
+ (S - 1)\left[-\frac{1}{p}\partial_\nu u^1_{\text{ext}} - \left[(1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right]u^1_{\text{ext}}\right]
\]
\[
- \frac{1}{2}(\theta \cdot n)\left[(2H^2 - 2\mathcal{G})\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc}) + (\Delta\Gamma + \kappa^2_e)\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc})\right]
\]
\[
- (\theta \cdot n)H\frac{1}{p}\partial_\nu u^1_{\text{ext}} - (\theta \cdot n)\frac{1}{p}\partial_\nu u^2_{\text{ext}}.
\]

We have on \(\Gamma\)
\[
y^2_{\text{ext}} - \frac{1}{p}\partial_\nu u^2_{\text{ext}} - \frac{1}{2}H\partial_\nu u^0_{\text{ext}} = - (\theta \cdot n)\left(\partial_\nu u^2_{\text{ext}} + H\frac{1}{p}\partial_\nu u^1_{\text{ext}}\right)
\]
\[
+ \left[(1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right]u^1_{\text{ext}}
\]
\[
- \frac{1}{2}\Delta\Gamma + \kappa^2_e(\theta \cdot n)\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc}) - \frac{1}{2}(\theta \cdot n)(\Delta\Gamma + \kappa^2_e)\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc})
\]
\[
+ \frac{1}{2}H\left[(1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right](u^0_{\text{ext}} + u^{inc})
\]
\[
- (\theta \cdot n)(\mathcal{H}^2 - \mathcal{G})\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc}) \text{ on } \Gamma.
\]

and
\[
\sum_{\ell=0}^2 \varepsilon^\ell y^\ell_{\text{ext}} - \varepsilon\frac{1}{p}\partial_\nu \sum_{\ell=0}^2 \varepsilon^\ell y^\ell_{\text{ext}} - \frac{1}{2}H\partial_\nu u^0_{\text{ext}} = - (\theta \cdot n)\left(\partial_\nu \left(u^{inc} + \sum_{\ell=0}^{\infty} \varepsilon^\ell y^\ell_{\text{ext}}\right)\right)
\]
\[
+ \varepsilon\left[(1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right]\left(u^{inc} + \sum_{\ell=0}^{\infty} \varepsilon^\ell y^\ell_{\text{ext}}\right)
\]
\[
- \frac{1}{2}\varepsilon^2\left[\Delta\Gamma + \kappa^2_e(\theta \cdot n)\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc}) - \frac{1}{2}\varepsilon^2(\theta \cdot n)\Delta\Gamma + \kappa^2_e\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc})\right]
\]
\[
+ \frac{1}{2}\varepsilon^2H\left[1 - (1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right](u^0_{\text{ext}} + u^{inc})
\]
\[
- \varepsilon^2(\theta \cdot n)(\mathcal{H}^2 - \mathcal{G})\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc}) \text{ on } \Gamma.
\]

In this case we approach \(u^\varepsilon_{\text{ext}}\) by the function \(u^\varepsilon_{[2]}\) which solves the Helmholtz equation and the boundary condition
\[
u^\varepsilon_{[2]} + B_e^{-2}\partial_\nu w^\varepsilon_{[2]} = - (\theta \cdot n)\left(\partial_\nu \left(u^{inc} + v^\varepsilon_{[2]}\right) + H\frac{1}{p}\partial_\nu (v^\varepsilon_{[2]} + u^{inc})\right)
\]
\[
+ \varepsilon\left[(1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right](v^\varepsilon_{[2]} + u^{inc})
\]
\[
- \frac{1}{2}\varepsilon^2\left[\Delta\Gamma + \kappa^2_e(\theta \cdot n)\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc}) - \frac{1}{2}\varepsilon^2(\theta \cdot n)\Delta\Gamma + \kappa^2_e\frac{1}{p}\partial_\nu (u^0_{\text{ext}} + u^{inc})\right]
\]
\[
+ \frac{1}{2}\varepsilon^2H\left[1 - (1 - \frac{1}{2})\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)(\kappa^2_e - \frac{1}{p}\kappa_e^2)\right](v^\varepsilon_{[2]} + u^{inc})
\]
\[
- \varepsilon^2(\theta \cdot n)(\mathcal{H}^2 - \mathcal{G})\frac{1}{p}\partial_\nu (v^\varepsilon_{[2]} + u^{inc}) \text{ on } \Gamma.
\]

and then \(u^\varepsilon_{\text{ext}} - w^\varepsilon_{[2]} = O(\varepsilon^3)\) on \(\Gamma\).

\[\square\]

**Theorem 4.3.** The GIBCs associated to the transmission problem characterising the first shape derivative of the solution in the Neumann case can be written for \(N = 0, 1, 2\) as follows
\[
\partial_\nu w^\varepsilon_{[N]} + B_e^{-N}w^\varepsilon_{[N]} = S^\varepsilon_{[1]}(\nu^\varepsilon_{[N]} + u^{inc}) + S^\varepsilon_{[2]}\partial_\nu (v^\varepsilon_{[N]} + u^{inc})
\]
where
\[
S^\varepsilon_{[1]} = \left[\text{div}_\Gamma (\theta \cdot n)\nabla \Gamma + (\theta \cdot n)\kappa^2_e\mathcal{I} \right] \text{ and } S^\varepsilon_{[2]} = 0,
\]
\[
S^\varepsilon_{[1]} = \left[\text{div}_\Gamma (\theta \cdot n)(1 + \rho e(2\mathcal{R} - H))\nabla \Gamma + (\theta \cdot n)\kappa^2_e\mathcal{I} \right] - (\theta \cdot n)\rho e H\kappa^2_1 \text{ and } S^\varepsilon_{[2]} = \varepsilon(1 - \rho)|\Delta\Gamma + \kappa^2_e\mathcal{I}|((\theta \cdot n)\mathcal{I})
\]

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and
\[ S_1^{\ell - 2} = \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) (1 + \rho \varepsilon (2R - H) + \rho \varepsilon^2 (2R^2 - H^2)) \right] \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{n}^2 + (\mathbf{\theta} \cdot \mathbf{n}) \varepsilon(\mathbf{H} - i \mathbf{G}) \kappa_1^2 \mathbf{I} + \frac{\varepsilon^2}{2} [\Delta \Gamma + \kappa_1^2] [\text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I}] + \frac{\varepsilon^2}{2} [\text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I}] [\Delta \Gamma + \kappa_1^2] \right) ;
\]
\[ S_2^{\ell - 2} = \varepsilon (1 - \rho) \left[ \text{div}_\Gamma (1 + \varepsilon (2R - H)) \right] \nabla \Gamma + (1 - \frac{i \varepsilon}{2} \mathbf{H}) \kappa_1^2 \mathbf{I} \right]. \]

**Proof.** We detail the computations of the functions \( u_0^\ell \) only. The rank \( \ell = 0 \) allows us to compute \( \mathbf{U}^0 \) only. We obtain the system
\[
\begin{aligned}
\frac{\partial S^0 U^0}{\partial n} &= 0 \quad \text{in } \Gamma \times (0, 1) \\
\frac{\partial S^0 U^0}{\partial n} &= 0 \quad \text{on } \Gamma \times \{1\} \\
U^0_{\text{int}} &= u^0_{\text{ext}} - (\mathbf{\theta} \cdot \mathbf{n}) \left( \frac{1}{\rho} - 1 \right) \partial_n (u^0_{\text{ext}} + u^{inc}) \quad \text{on } \Gamma \times \{0\}.
\end{aligned}
\]
We conclude that
\[ U^0_{\text{int}} (\cdot, S) = u^0_{\text{ext}} - (\mathbf{\theta} \cdot \mathbf{n}) \left( \frac{1}{\rho} - 1 \right) \partial_n (u^0_{\text{ext}} + u^{inc}) . \]

When \( \ell = 1 \), we obtain the two systems
\[
\begin{aligned}
\frac{\partial S^0 U^1}{\partial n} &= -\Lambda_1 U^0_{\text{int}} = 0 \quad \text{in } \Gamma \times (0, 1) \\
\frac{\partial S^0 U^1}{\partial n} &= -\left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] U^0_{\text{int}} \quad \text{on } \Gamma \times \{1\} \\
U^1_{\text{int}} &= u^1_{\text{ext}} - (\mathbf{\theta} \cdot \mathbf{n}) \left( \frac{1}{\rho} - 1 \right) \partial_n u^1_{\text{ext}} \quad \text{on } \Gamma \times \{0\},
\end{aligned}
\]
and
\[
\begin{aligned}
\frac{\Delta u^1_{\text{ext}}}{\partial n} &= 0 \quad \text{in } \Omega_{\text{ext}} \\
\frac{\partial S^0 U^1}{\partial n} &= -\rho \partial_S U^1_{\text{int}} + \left[ (1 - \rho) \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] (u^0_{\text{ext}} + u^{inc}) \quad \text{on } \Gamma.
\end{aligned}
\]

We deduce
\[ U^1_{\text{int}} (\cdot, S) = -\mathbf{S} \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] (u^0_{\text{ext}} + u^{inc}) + u^1_{\text{ext}} - (\mathbf{\theta} \cdot \mathbf{n}) \left( \frac{1}{\rho} - 1 \right) \partial_n u^1_{\text{ext}} . \]

and
\[ \frac{\partial S^0 U^1}{\partial n} = \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] (u^0_{\text{ext}} + u^{inc}) \quad \text{on } \Gamma.
\]

When \( \ell = 2 \), we obtain the two systems
\[
\begin{aligned}
\frac{\partial S^0 U^2}{\partial n} &= -\Lambda_1 U^1_{\text{int}} - (\Lambda_2 + \kappa_1^2) U^0_{\text{int}} \quad \text{in } \Gamma \times (0, 1) \\
\frac{\partial S^0 U^2}{\partial n} &= -\left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] U^1_{\text{int}} \\
\frac{\partial S^0 U^2}{\partial n} &= -\left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) (2R - H) \nabla \Gamma + \mathbf{H} \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma \right] U^1_{\text{int}} \quad \text{on } \Gamma \times \{1\} \\
U^2_{\text{int}} &= u^2_{\text{ext}} - (\mathbf{\theta} \cdot \mathbf{n}) \left( \frac{1}{\rho} - 1 \right) \partial_n u^2_{\text{ext}} \quad \text{on } \Gamma \times \{0\},
\end{aligned}
\]
and
\[
\begin{aligned}
\frac{\Delta u^2_{\text{ext}}}{\partial n} &= 0 \quad \text{in } \Omega_{\text{ext}} \\
\frac{\partial S^0 U^2}{\partial n} &= -\rho \partial_S U^2_{\text{int}} + \left[ (1 - \rho) \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] (u^0_{\text{ext}} + u^{inc}) \quad \text{on } \Gamma.
\end{aligned}
\]

We compute
\[ \frac{\partial S^0 U^2}{\partial n} (\cdot, S) = -\mathbf{H} \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] (u^0_{\text{ext}} + u^{inc}) \]

and
\[ \frac{\partial S^0 U^2}{\partial n} (\cdot, 1) = -\left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] u^2_{\text{ext}} \]

\[ - \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) (2R - H) \nabla \Gamma + \mathbf{H} \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma \right] (u^0_{\text{ext}} + u^{inc}) . \]

We deduce
\[ U^2_{\text{int}} (\cdot, S) = -\left( \frac{S^2}{2} - S \right) \mathbf{H} \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] (u^0_{\text{ext}} + u^{inc}) \]

\[ - \left( \frac{S^2}{2} - S \right) \left( \Delta \Gamma + \kappa_1^2 \right) \left( u^0_{\text{ext}} - (\mathbf{\theta} \cdot \mathbf{n}) \left( \frac{1}{\rho} - 1 \right) \partial_n (u^0_{\text{ext}} + u^{inc}) \right) \]

\[ - S \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma + (\mathbf{\theta} \cdot \mathbf{n}) \kappa_1^2 \mathbf{I} \right] u^2_{\text{ext}} \]

\[ - S \left[ \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) (2R - H) \nabla \Gamma + \mathbf{H} \text{div}_\Gamma (\mathbf{\theta} \cdot \mathbf{n}) \nabla \Gamma \right] (u^0_{\text{ext}} + u^{inc}) \]

\[ + u^2_{\text{ext}} (x) - (\mathbf{\theta} \cdot \mathbf{n}) \left( \frac{1}{\rho} - 1 \right) \partial_n u^2_{\text{ext}} . \]
and
\[\partial_n u^3_{\text{ext}} + \rho (\Delta \Gamma + \kappa^2_3) u^3_{\text{ext}} = \left[ \text{div}_r(\theta \cdot n)\nabla u + (\theta \cdot n)\kappa^2_3 u \right]_{\text{ext}} + \rho \text{div}_r(\theta \cdot n) [2R - H] \nabla u - (\theta \cdot n) H \kappa^2_3] (u^0_{\text{ext}} + u^{\text{inc}}) + (\Delta \Gamma + \kappa^2_3) (\theta \cdot n)(1 - \rho) \partial_n (u^0_{\text{ext}} + u^{\text{inc}}) \text{ on } \Gamma.\]

When \(\ell = 3\), we obtain the two systems
\[
\begin{cases}
\partial^2_{\text{ext}} U^3_{\text{ext}} &= -\Lambda_3 U^3_{\text{ext}} - (\alpha_3 + \kappa^2_3) U^3_{\text{ext}} + \Lambda_3 U^3_{\text{int}} \\
\partial^3_{\text{int}} U^3_{\text{int}} &= -\text{div}_r(\theta \cdot n) \nabla u + (\theta \cdot n) \kappa^2_3 U^3_{\text{int}} \\
\partial^3_{\text{int}} &= u^3_{\text{ext}} - (\theta \cdot n)(1 - \rho) \partial_n u^3_{\text{ext}} \text{ on } \Gamma \times \{0\}.
\end{cases}
\]

We deduce
\[
U^3_{\text{int}}(\cdot, S) = - \left( \frac{S^3}{2} - \frac{1}{2} \right) H \left[ \text{div}_r(\theta \cdot n) \nabla u + (\theta \cdot n) \kappa^2_3 \right] (u^0_{\text{ext}} + u^{\text{inc}}) + \rho \text{div}_r(\theta \cdot n) \nabla u - (\theta \cdot n) H \kappa^2_3] (u^0_{\text{ext}} + u^{\text{inc}})
\]
\[
\partial_n u^3_{\text{ext}} + \rho (\Delta \Gamma + \kappa^2_3) u^3_{\text{ext}} = f \text{ on } \Gamma,
\]
with
\[f = [\text{div}_r(\theta \cdot n) \nabla u + (\theta \cdot n) \kappa^2_3 u]_{\text{ext}} + \rho \text{div}_r(\theta \cdot n) [2R - H] \nabla u - (\theta \cdot n) H \kappa^2_3] (u^0_{\text{ext}} + u^{\text{inc}}) + (\Delta \Gamma + \kappa^2_3)(\theta \cdot n)(1 - \rho) \partial_n (u^0_{\text{ext}} + u^{\text{inc}}).
\]
5 Shape derivatives of the approximate solution

This section is devoted to the shape derivative analysis of the approximate solution $u_{n \ell}^{\text{ext}}$ of $u^{\text{ext}}$. It provides a second way to compute an approximation of the shape derivative of $u^{\text{ext}}$. It suffices to determine the exterior boundary value problem characterising the shape derivative $\delta_{n \ell}^e$ of $u_{n \ell}^{\text{ext}}$. Since $u_{n \ell}^{\text{ext}} \simeq (u_{n \ell}^{\text{ext}} + u^{\text{inc}}) + \sum_{\ell=1}^N \varepsilon^\ell u_{n \ell}^{\text{ext}}$, it is equivalent to determine, in a first step, the equations satisfied by every derivatives $\delta_n^{e,\ell}$ of the functions occurring in the sum. In a second step, we obtain the equation satisfied by the desired approximation $\delta_n^{e}$ for $N = 0, 1, 2$ as in the proofs of Propositions 3.1 and 3.2. This is realized in the following two theorems.

**Theorem 5.1.** The boundary conditions characterising the first shape derivative of the approximate solution $u_{n \ell}^{\text{ext}}$, for $N = 0, 1, 2$, to the transmission problem with a Dirichlet condition on the interior boundary can be written as follows

$$\delta_{n \ell}^{e,0} + B_{\text{ext}}^{e,0} \partial_n \delta_{n \ell}^{e,0} = T_1^{e,0} (u_{n \ell}^{\text{ext}} + u^{\text{inc}}) + T_2^{e,0} \partial_n (u_{n \ell}^{\text{ext}} + u^{\text{inc}})$$

where

$$T_1^{e,0} = 0 \quad \text{and} \quad T_2^{e,0} = - (\nabla \cdot n) I,$$

and

$$T_1^{e,1} = - \frac{1}{\varepsilon} \partial_n [\text{div}(\nabla \cdot n)] - (\nabla \cdot n) \kappa_1^2 I \quad \text{and} \quad T_2^{e,1} = - (\nabla \cdot n) \left( 1 + \varepsilon \frac{1}{\rho} \nabla \right) I.$$

Proof. The result for the order $N = 0$ is well-known [20]

$$\begin{cases} \Delta u_{n \ell}^{\text{ext}} + \rho_1 n \cdot \nabla (u_{n \ell}^{\text{ext}} + u^{\text{inc}}) = 0 & \text{in } \Omega_{n \ell} \\ \partial_n (u_{n \ell}^{\text{ext}} + u^{\text{inc}}) = - (\nabla \cdot n) \partial_n (u_{n \ell}^{\text{ext}} + u^{\text{inc}}) & \text{on } \Gamma \end{cases}$$

and using straightforward calculation we obtain the characterisation at the order $N = 1$

$$\Delta u_{n \ell}^{1} + \rho_1 n \cdot \nabla u_{n \ell}^{1} = 0 \quad \text{in } \Omega_{n \ell}$$

with, on $\Gamma$, the boundary condition

$$\begin{aligned} \partial_n (u_{n \ell}^{1} + u^{\text{inc}}) &= - (\nabla \cdot n) \left( \partial_n u_{n \ell}^{1} + \rho_1 n \cdot \nabla (u_{n \ell}^{1} + u^{\text{inc}}) \right) \\ &\quad - \frac{1}{\rho} \partial_n \left( \nabla \partial_n (u_{n \ell}^{0} + u^{\text{inc}}) \right) \\ &\quad - \frac{1}{\rho} \partial_n \left( \nabla (H \partial_n (u_{n \ell}^{0} + u^{\text{inc}})) \right) \\ &= \partial_n (u_{n \ell}^{1} + u^{\text{inc}}) - \rho_1 n \cdot \nabla u_{n \ell}^{1} - \frac{1}{\rho} \partial_n \left( \nabla \partial_n (u_{n \ell}^{0} + u^{\text{inc}}) \right) - \frac{1}{\rho} \partial_n \left( \nabla (H \partial_n (u_{n \ell}^{0} + u^{\text{inc}})) \right). 
\end{aligned}$$

Let us detail the computations for the order $N = 2$ only. We know that the derivative $u_{n \ell}^{2}$ satisfies

$$\Delta u_{n \ell}^{2} + \rho_1 n \cdot \nabla u_{n \ell}^{2} = 0 \quad \text{in } \Omega_{n \ell}.$$

We essentially need to differentiate the boundary condition. We have for all $x \in \Gamma$ and for all $\theta \in \mathcal{O}$

$$u_{n \ell}^{\theta,0} (x + \theta (x)) - \frac{1}{\rho} \partial_n (u_{n \ell}^{\theta,0} (x + \theta (x))) + \rho_1 n \cdot \nabla (u_{n \ell}^{\theta,0} (x + \theta (x))) = 0.$$

We use $H = - \Delta H (\nabla \cdot n) = 0$ [13] and we obtain

$$0 = u_{n \ell}^{2,0} + \theta \nabla (u_{n \ell}^{2,0}) - \frac{1}{\rho} \partial_n u_{n \ell}^{2,0} + \frac{1}{\rho} \nabla (H \partial_n (u_{n \ell}^{0} + u^{\text{inc}})) - \frac{1}{\rho} \partial_n (\nabla (H \partial_n (u_{n \ell}^{0} + u^{\text{inc}}))).$$

We use $\partial_n H = \rho_1 n \cdot \nabla H$ and $\partial_n \partial_n = - \text{trace}[\nabla^2 \partial_n] = (H^2 - 2G)$ to conclude

$$\begin{aligned} u_{n \ell}^{2,0} &= - \theta \nabla (u_{n \ell}^{2,0}) - \frac{1}{\rho} \partial_n u_{n \ell}^{2,0} - \frac{1}{\rho} \partial_n \partial_n (u_{n \ell}^{2,0}) \\ &= - \theta \nabla (u_{n \ell}^{2,0}) - \frac{1}{\rho} \partial_n u_{n \ell}^{2,0} - \frac{1}{\rho} \partial_n \partial_n (u_{n \ell}^{2,0}) - \frac{1}{\rho} \partial_n \partial_n (u_{n \ell}^{2,0}) \nabla (H \partial_n (u_{n \ell}^{0} + u^{\text{inc}})). 
\end{aligned}$$

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Theorem 5.2. The boundary conditions characterising the first shape derivative of the approximate solution \( v^e_{N} \), for \( N = 0, 1, 2 \), to the transmission problem with a Neumann condition on the interior boundary can be written as follows

\[
\partial_n v^e_{N} + B^s N v^e_{N} = \Gamma^e N (v^e_{N} + u^{inc}) + T^e_{1,0} \partial_n (v^e_{N} + u^{inc})
\]

\[
T^e_{1,0} = \{ \text{div}_N(\theta \cdot n)\nabla_T + (\theta \cdot n)\kappa^2_{T} I \} \quad \text{and} \quad T^e_{2,0} = 0,
\]

\[
T^e_{1,1} = \{ \text{div}_N(\theta \cdot n)(1 + \rho(2\mathcal{R} - \mathcal{H}))\nabla_T + (\theta \cdot n)\kappa^2_{T} I \} -(\theta \cdot n)\rho \varepsilon(\mathcal{H} - \varepsilon \mathcal{G})\kappa^2_{T} I \text{ and } T^e_{2,1} = -\rho \varepsilon[\Delta_T + \kappa^2_{T} I]((\theta \cdot n)l)
\]

and

\[
T^e_{1,2} = \{ \text{div}_N(\theta \cdot n)(1 + \rho\varepsilon(2\mathcal{R} - \mathcal{H}) + \rho (2\mathcal{R}^2 - \mathcal{H}\mathcal{R})))\nabla_T + (\theta \cdot n)\kappa^2_{T} I \} - (\theta \cdot n)\rho \varepsilon(\mathcal{H} - \varepsilon \mathcal{G})\kappa^2_{T} I + \frac{\varepsilon}{2}\text{div}_N(2D^2_N(\theta \cdot n) - [\Delta_T + \kappa^2_{T} I])\nabla_T - \frac{\varepsilon}{2}\varepsilon^2\kappa^2_{T}[\Delta_T + \kappa^2_{T} I]
\]

\[
T^e_{2,2} = -\rho \varepsilon \left[ \text{div}_N (1 + \varepsilon(\mathcal{R} - \frac{1}{2}\mathcal{H}))\nabla_T (1 + \frac{1}{2}\varepsilon \mathcal{H})\kappa^2_{T} I (\theta \cdot n)l \right].
\]

Proof. The results for the order \( N = 0 \) is well-known [20].

\[
\left\{ \begin{array}{c}
\Delta u^0_{ext} + \kappa^2_{T} u^0_{ext} = 0 \\
\partial_n u^0_{ext} = \text{div}_N(\theta \cdot n)(u^0_{ext} + u^{inc}) + \kappa^2_{T} (\theta \cdot n)(u^0_{ext} + u^{inc}) \quad \text{on } \Gamma,
\end{array} \right.
\]

and the characterisation at the order \( N = 1 \) is obtained in [13]. We have

\[
\Delta u^1_{ext} + \kappa^2_{T} u^1_{ext} = 0 \quad \text{in } \Omega_{ext}
\]

with, on \( \Gamma \), the boundary condition

\[
\partial_n u^1_{ext} + \rho[\Delta_T + \kappa^2_{T} I]u^1_{ext} = \left\{ \begin{array}{c}
\text{div}_N((\theta \cdot n)\nabla_T) + \kappa^2_{T} (\theta \cdot n)I \nabla_{ext} \\
-\rho \text{div}_N(\theta \cdot n)(\mathcal{R} - 2\mathcal{H})\nabla_T + \kappa^2_{T} (\theta \cdot n)I \nabla_{inc} \\
-\rho \Delta_T ((\theta \cdot n)\partial_n(u^0_{ext} + u^{inc})) + \kappa^2_{T} (\theta \cdot n)\partial_n(u^0_{ext} + u^{inc})
\end{array} \right.
\]

Let us details the computations for the order \( N = 2 \) only. The shape derivative \( u^1_{ext} \) satisfies

\[
\Delta u^2_{ext} + \kappa^2_{T} u^2_{ext} = 0 \quad \text{in } \Omega_{ext}.
\]

On the boundary \( \Gamma \), some difficulties arise. We have for all \( x \in \Gamma \) and for all \( \theta \in \mathcal{O} \)

\[
\partial_{\theta} u^2_{ext}(x + \theta(x)) + \rho[\Delta_{\theta} + \kappa^2_{T} I]u^0_{ext}(x + \theta(x)) + \rho \text{div}_{\theta}[(\mathcal{R} - \frac{1}{2}\mathcal{H})\mathcal{I}]\nabla_{\theta} - \frac{1}{2}\mathcal{H} \kappa^2_{T} I(u^0_{ext} + u^{inc})(x + \theta(x)) = 0.
\]

We focus on the shape derivative of the third boundary term. For any small real value \( t \), let us denote

\[
v_t = \frac{\rho}{2} \text{div}_{\theta} \left( (2\mathcal{R} - \mathcal{H})\mathcal{I}\nabla_{\theta}(u^0_{ext} + u^{inc}) \right)
\]

and

\[
w_t = -\frac{\rho}{2} \kappa^2_{T} \mathcal{H} \mathcal{I}(u^0_{ext} + u^{inc})
\]

Denote \( z_t = u^0_{ext} + u^{inc} \) and \( \dot{z} = u^0_{ext} \). We take a test function \( \phi \in \mathcal{D}(\Gamma) \) which is supposed to be the restriction on \( \Gamma \) of a function \( \Phi \in \mathcal{D}(\mathbb{R}^3) \) satisfying \( \partial_n \Phi = 0 \). We are led to compute \( \frac{d}{dt} \int_{\Gamma} v_t + w_t \phi \, d\sigma \) as follows:

\[
\frac{d}{dt} \left[ \int_{\Gamma} v_t \phi \, d\sigma \right] = -\frac{\rho}{2} \frac{d}{dt} \left[ \int_{\Gamma} (2\mathcal{R} - \mathcal{H})\mathcal{I}\nabla_{\theta}z_t \cdot \nabla_{\theta} \phi \right] d\sigma \bigg|_{t=0} = -\frac{\rho}{2}(I + (II))
\]

where [26] Eq. (4.44), pp. 192

\[
(I) = \int_{\Gamma} \frac{d}{dt} \left[ (2\mathcal{R} - \mathcal{H})\mathcal{I}\nabla_{\theta}z_t \cdot \nabla_{\theta} \phi \right] d\sigma,
\]

and

\[
(II) = \int_{\Gamma} \theta \cdot n \partial_n \left[ (2\mathcal{R} - \mathcal{H})\n\nabla_{\theta} \cdot \nabla \phi \right] d\sigma + \int_{\Gamma} \theta \cdot n \mathcal{H} \left[ (2\mathcal{R} - \mathcal{H})\n\nabla_{\theta} \cdot \nabla \phi \right] d\sigma
\]

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Concerning (I), we get \[13\]

\[
(I) = \int_{\Gamma} \nabla \phi \cdot \left[ - (2D^2(\theta \cdot n)) + \Delta_{\Gamma}(\theta \cdot n) I \right] \nabla \right. \varepsilon d \sigma + \int_{\Gamma} \nabla \phi \cdot \left[ (2R - \mathcal{H}I) \nabla \varepsilon + \partial_n \varepsilon \nabla_{\Gamma}(\theta \cdot n) \right] d \sigma
\]

Indeed, set \(A = (2R - \mathcal{H}I)\) and \(A = (a_{ij})_{1 \leq i, j \leq 3}\). We have \[22\] pp. 69]

\[
(\partial_n a_{ij})_{1 \leq i, j \leq 3} = \text{Trace}(R^2) I - 2R^2.
\]

It comes that

\[
\begin{align*}
\partial_n (A \nabla_{\Gamma} z, \nabla_{\Gamma} \phi) &+ A \mathcal{H} \nabla_{\Gamma} z, \nabla_{\Gamma} \phi = \\
&= \partial_n (A \nabla_{\Gamma} z, \nabla_{\Gamma} \phi + (\mathcal{H}A - 2R A) \nabla_{\Gamma} z, \nabla_{\Gamma} \phi) + \left[ \text{Trace}(R^2) I - 2R^2 \right] \nabla_{\Gamma} z, \nabla_{\Gamma} \phi
\end{align*}
\]

Finally, gathering all the terms we get

\[
(II) = \int_{\Gamma} \phi \div \left[ \theta \cdot n (4R^2 - 2R \mathcal{H} I) \nabla_{\Gamma} z \right]
\]

From (I) + (II) we obtain

\[
d\left[ \int_{\Gamma,0} v_{\Gamma} \phi d \sigma \right]_{t=0} = -\rho \int_{\Gamma} \phi \div \left[ (2D(\nabla_{\Gamma}(\theta \cdot n)) - \Delta_{\Gamma} \theta \cdot n I) \nabla_{\Gamma} z \right] d \sigma
\]

Following the same lines as before, we get the following

\[
d\left[ \int_{\Gamma,0} w_{\Gamma} \phi d \sigma \right]_{t=0} = -\rho \int_{\Gamma} \phi \div \left[ \theta \cdot n \left( 2R^2 - 2R \mathcal{H} I \right) \nabla_{\Gamma} z \right] d \sigma
\]

We finally get on \(\Gamma\)

\[
\begin{align*}
\partial_n u_{ext}^2 + \rho (\Delta_{\Gamma} + \kappa^2_{\Gamma}) u_{ext}^2 &+ \rho \left[ \text{div} (\mathcal{R} - \frac{1}{2} \mathcal{H} \nabla_{\Gamma}) - \frac{1}{2} \mathcal{H} \kappa^2_{\Gamma} \right] u_{ext}^0 = \\
&= \left[ \text{div} \Phi \theta \cdot n \nabla_{\Gamma} + \kappa^2_{\Gamma} \theta \cdot n I \right] u_{ext}^2 - \rho \left[ \text{div} \theta \cdot n (\mathcal{H} - 2R) \nabla_{\Gamma} + \kappa^2_{\Gamma} \theta \cdot n \mathcal{H} I \right] u_{ext} + u_{inc}^0
\end{align*}
\]
6 Comparison of the two approaches

In this section, we focus on the remainder \( r^N_y = v^N_y - u^N_y \) for \( N = 0, 1, 2 \). Our main result is the following.

**Theorem 6.1.** Let \( N = 0, 1, 2 \). There exists some constants \( C_\Gamma, C_R \) and \( C_\infty \) independent on \( \varepsilon \) such that

\[
\| r^N_y \|_{H^2(\Gamma)} \leq C_\varepsilon^{N+1}, \\
\| r^N_y \|_{H^2(\Omega \setminus \Omega \cap B_R)} \leq C_R \varepsilon^{N+1}, \\
\| r^N_y \|_{L^2(B_2^2)} \leq C_\infty \varepsilon^{N+1},
\]

where \( R \) is sufficiently large such that \( \Omega \subset B_R \).

It is sufficient to prove the results for \( N = 2 \) in the Neumann. It relies on the fact that the difference between the right-hand sides \( (F^N_y)^1 - F^N_y^2 \) is up to \( O(\varepsilon^{N+1}) \). We need the following two propositions.

**Proposition 6.2.** We have

\[
\frac{1}{2} \text{div} \left[ (2D^2_y(\theta \cdot n) - \Delta_y(\theta \cdot n))\nabla_y u \right] - \frac{1}{2} \Delta_y (2D^2_y(\theta \cdot n)) - \frac{1}{2} \Delta_y (\theta \cdot n) + \frac{1}{2} \Delta_y (\theta \cdot n)\nabla_y u,
\]

\[
= \frac{1}{2} \text{div} \left[ (2D^2_y(\theta \cdot n) - \Delta_y(\theta \cdot n))\nabla_y u \right] - \frac{1}{2} \Delta_y (\theta \cdot n)\nabla_y u.
\]

**Proof.** It is straightforward to verify that the summation of the coefficients in \( \kappa_i^2 \) and \( \kappa_i^4 \) is zero. Then we have

\[
\frac{1}{2} \text{div} \left[ (2D^2_y(\theta \cdot n) - \Delta_y(\theta \cdot n))\nabla_y u \right] - \frac{1}{2} \Delta_y (\theta \cdot n)\nabla_y u.
\]

We end the proof once we use the following two relations

\[
\text{div} \left[ D^2_y(\theta \cdot n)\nabla_y u \right] = \Delta_y (\theta \cdot n)\nabla_y u + D^2_y(\theta \cdot n) : D^2_y u,
\]

where for two \((3 \times 3)\) matrices \( A \) and \( B \) whose columns are denoted by \((a_1, a_2, a_3)\) and \((b_1, b_2, b_3)\), respectively, we set \( A : B = a_1 b_1 + a_2 b_2 + a_3 b_3 \) and,

\[
\frac{1}{2} \Delta_y (\theta \cdot n)\nabla_y u = \frac{1}{2} \Delta_y (\theta \cdot n)\nabla_y u + \frac{1}{2} \nabla_y u\cdot \nabla_y (\Delta_y (\theta \cdot n)) + D^2_y(\theta \cdot n) : D^2_y u.
\]

The second result concerns the GIBC satisfied by \( r^N_y \) on \( \Gamma \).

**Lemma 6.3.** In the Neuman case, we have

\[
\partial_y r^N_y + \rho \varepsilon (\Delta_y + \kappa_i^2) r^N_y + \varepsilon^2 \rho \left[ (\text{div} \nabla (R - \frac{1}{2} H)\nabla) - \frac{1}{2} H \kappa_i^2 \right] r^N_y = O(\varepsilon^3) \quad \text{on } \Gamma
\]

where \( O(x) \) stands for a generic distribution belonging to \( H^{-\frac{3}{2}}(\Gamma) \).

**Proof.** We have on \( \Gamma \)

\[
\partial_y r^N_y + \rho \varepsilon (\text{div} \nabla (R + \kappa_i^2)) r^N_y + \varepsilon^2 \rho \left[ (\text{div} \nabla (R - \frac{1}{2} H)\nabla) - \frac{1}{2} H \kappa_i^2 \right] r^N_y = F^N_y - F^N_y^2 = R_1 + R_2,
\]

where \( R_1 \) and \( R_2 \) are the residual terms due to \( \varepsilon \) and \( \kappa_i^2 \), respectively.
where
\[ R^1_t = \varepsilon^2 \frac{\partial}{\partial t} \text{div} \left( \left( 2D^2(\theta \cdot n) - \Delta r(\theta \cdot n) \right) \nabla (v^e_{[2]} + u^inc) \right) - \varepsilon^2 \frac{\partial}{\partial t} \Delta r(\theta \cdot n)(v^e_{[2]} + u^inc) \]
and where
\[ R^2_t = -\varepsilon^2 \rho \text{div} \left( \left( \theta \cdot n \right)(R - \frac{1}{2} H) \nabla \right) - \frac{1}{2} \kappa^2_r(\theta \cdot n) \nabla \partial_r(v^e_{[2]} + u^inc) \]

Thanks to the relation
\[ \partial_r(v^e_{[2]} + u^inc) = -B^t v^e_{[2]} + u^inc, \]
where
\[ B^t = \varepsilon^2 \left( \theta \cdot n \right)(R - \frac{1}{2} H) \nabla \]
we can rewrite \( R^2_t \) as
\[ R^2_t = \varepsilon^2 \rho \left( \Delta r + \kappa^2_r \right) \left( (\theta \cdot n) \nabla + \kappa^2_r \right)(v^e_{[2]} + u^inc) + O(\varepsilon^3) \]

where \( O(x) \) stands for a generic distribution belonging to \( H^{-\frac{3}{2}}(\Gamma) \). Thanks to the Proposition 6.2, we conclude
\[ F^t_{[2]} - F^{i,1}_{[2]} = \varepsilon^2 \rho \text{div} \left( \left( 2D^2(\theta \cdot n) - \Delta r(\theta \cdot n) \right) \nabla \right) - \varepsilon^2 \frac{\partial}{\partial t} \Delta r(\theta \cdot n)(v^e_{[2]} + u^inc) \]

**Proof of Theorem 6.1.** We can easily verify that \( r^e_{[2]} \) is solution of the following boundary value problem:
\[ \left\{ \begin{array}{c}
\Delta r^e_{[2]} + \kappa^2 r^e_{[2]} = 0 \quad \text{in} \quad \Omega_{\text{ext}} \\
\lim_{R \to +\infty} \int_{\partial B_r} \left| \frac{\partial r^e_{[2]}}{\partial r} - ikr^e_{[2]} \right|^2 dr = 0
\end{array} \right. \]

with the GIBC on \( \Gamma \)
\[ \partial_n r^e_{[2]} + \rho \varepsilon^2 (\text{div} v \nabla + \kappa^2_r r^e_{[2]}) = 0 \quad \text{on} \quad \Gamma \]

which we can rewrite as
\[ \partial_n r^e_{[2]} + \rho \varepsilon^2 \left( (\text{div} v \nabla + \kappa^2_r r^e_{[2]}) \right) = O(\varepsilon^3) \quad \text{on} \quad \Gamma \]

We follows ideas of [28] Lemma 1. We begin to introduce the Dirichlet to Neumann operator \( A_r : H^{s+\frac{1}{2}}(\Gamma) \to H^{s-\frac{1}{2}}(\Gamma), \quad s \in \mathbb{R} \) defined as follows : for \( g \in H^{s+\frac{1}{2}}(\Gamma) \) we set \( A_r(g) = \partial_n v \) the normal derivative of \( v \) solution of
\[ \left\{ \begin{array}{c}
\frac{\partial v}{\partial n} + \kappa^2 v = 0 \quad \text{in} \quad \Omega_{\text{ext}} \\
\lim_{R \to +\infty} \int_{\partial B_r} \left| \frac{\partial r^e_{[2]}}{\partial r} - ikr^e_{[2]} \right|^2 dr = 0.
\end{array} \right. \]

\[ \| A_r u \|_{L^2(\Gamma)} \leq c_{s} || u ||_{H^1} \]

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Let $Z_T$ be the operator defined by

$$Z_T w = \rho \varepsilon \left( \text{div}_T \left[ \left( \mathcal{I} + \varepsilon (\mathcal{R} - \frac{1}{2} \mathcal{H}) \right) \nabla_T w \right] \right) + \rho (1 - \varepsilon) \frac{c}{2} \mathcal{H} w$$

Set

$$B_T = A_T + Z_T.$$

We study first $B_T^\alpha = A_T + \rho \varepsilon \left( \text{div}_T \left[ \left( \mathcal{I} + \varepsilon (\mathcal{R} - \frac{1}{2} \mathcal{H}) \right) \nabla_T w \right] \right) - \Lambda u$ where $\Lambda$ is a positive constant chosen sufficiently large. Denote $E = \rho \varepsilon (1 - \frac{H}{2}) I + \rho \varepsilon^2 \mathcal{R}$. Supposing $\varepsilon > 0$ sufficiently small such that the spectrum of the matrix $E$ belongs to $(c_1, c_2)$ for some $c_1, c_2 > 0$. We have for $u \in H^1(\Gamma)$

$$- \text{Re}(B_T^\alpha (u, u)) = - (A_T u, u) + (\nabla_T u, E \nabla_T u) + \Lambda \| u \|_{L^2(\Gamma)}^2 \geq - \| A_T u \|_{L^2(\Gamma)} \| u \|_{L^2(\Gamma)} + c_1 \| u \|_{H^1(\Gamma)}^2 + (c_3 + \Lambda) \| u \|_{L^2(\Gamma)}^2 \geq - c_3 \| u \|_{H^1(\Gamma)} + \frac{c_4}{2} (\| u \|_{L^2(\Gamma)}^2 + c_1 + \Lambda) \| u \|_{L^2(\Gamma)}^2 \geq \left( c_1 - \frac{c_3}{c_4} \right) \| u \|_{H^1(\Gamma)}^2 + (c_3 + \Lambda - \frac{c_4}{2c_1}) \| u \|_{L^2(\Gamma)}^2$$

The last two inequalities are obtained thanks to the Young’s inequality. Setting $\delta = \frac{c_1}{c_3}$ we then get

$$- \text{Re}(B_T^\alpha (u, u)) \geq \frac{c_1}{2} \| u \|_{H^1(\Gamma)}^2 + (\Lambda + c_1 - \frac{c_4}{2c_1}) \| u \|_{L^2(\Gamma)}^2.$$

Hence coercivity is obtained whenever $\Lambda \geq \frac{c_4^2}{2c_1} c_1$. We have shown that $-B_T = -B_T^\alpha + K_T$ where $-K_T = \Lambda u$ is compact. Then $B_T^\alpha$ is of Fredholm of index zero. Furthermore, one can easily show that $-B_T$ is injective. The trick is classical : we combine the Rellich theorem and the analytic continuation principle. Then it is invertible. Since $B_T$ is bounded from $H^s(\Gamma)$ to $H^{-s}(\Gamma)$, we deduce from the closed graph theorem, that if $B_T u = h$ then there exists $C > 0$ such that

$$\| u \|_{H^1(\Gamma)} \leq C \| h \|_{H^{-s}(\Gamma)}.$$

Doing the same analysis for $h \in H^s(\Gamma)$ when $s > -1$, we deduce that the problem has a unique solution $u \in H^1(\Gamma)$. Hence $-B_T^\alpha u + u = h + A_T u + (1 - \Lambda) u \in H^{\min(s,0)}(\Gamma)$ and since $\Gamma$ is $C^\infty$ we get $u \in H^{s+2}(\Gamma)$ thanks to bootstrap procedure. We conclude from the closed graph theorem that there exists $C > 0$ such that

$$\| u \|_{H^{s+2}(\Gamma)} \leq C \| h \|_{H^s(\Gamma)}.$$

The case $s < -1$ is treated by transposition. Indeed, for any $s \in \mathbb{R}$ the operator $B_T$ continuously maps $H^{s+2}(\Gamma)$ to $H^s(\Gamma)$. Its $L^2$-adjoint is $B_T^*: H^{-s}(\Gamma) \to H^{s+2}(\Gamma)$, which is bijective as $s - 2 > -1$ by previous case. The proof is then completed as in previous case. If $s = -3/2$ we get the first estimate. We obtain the two other estimates by potential theory.

Similar bounds can be obtained in the Dirichlet case. Indeed, we can prove again that $(F_{\lambda}^{1} - F_{\lambda}^{-1})$ is up to $O(\varepsilon^{N+1})$ in the following lemma.

**Lemma 6.4. **In the Dirichlet case, we have

$$r_{\varepsilon}^{\alpha} - \frac{1}{2} \varepsilon \left( 1 + \frac{\varepsilon}{2} \mathcal{H} \right) \partial_n r_{\varepsilon}^{\alpha} = O(\varepsilon^3) \quad \text{on} \quad \Gamma$$

where $O(x)$ stands for a generic distribution belonging to $H^{-\frac{3}{2}}(\Gamma)$.

**Proof.** We have on $\Gamma$

$$r_{\varepsilon}^{\alpha} - \frac{1}{2} \varepsilon \left( 1 + \frac{\varepsilon}{2} \mathcal{H} \right) \partial_n r_{\varepsilon}^{\alpha} = F_{\varepsilon}^{\alpha}_2 - F_{\varepsilon}^{\alpha}_1 = R_1^\alpha + R_2^\alpha,$$

where

$$R_1^\alpha = \varepsilon (1 + \frac{\varepsilon}{2} \mathcal{H}) \left[ \text{div}_T (\theta \cdot n) \nabla_T + (\theta \cdot n) \kappa_1^2 \right] (v_{\varepsilon}^{[\alpha]} + u^{inc}) $$

and

$$R_2^\alpha = \frac{1}{2 \varepsilon} \left[ (\theta \cdot n) \kappa_1^2 \left( \partial_n (v_{\varepsilon}^{[\alpha]} + u^{inc}) \right) - \frac{1}{2 \varepsilon} (\theta \cdot n) |\Delta_T + \kappa_1^2| \partial_{n} (v_{\varepsilon}^{[\alpha]} + u^{inc}) \right] + \frac{1}{2 \varepsilon} |\Delta_T (\theta \cdot n)| \partial_{n} (v_{\varepsilon}^{[\alpha]} + u^{inc}).$$
Thanks to the relation
\[(v_ε^2 + u^{inc}) = -B^ε \partial_n (v_ε^2 + u^{inc}),\]
where
\[B^ε = -\frac{1}{\rho} ε I - \frac{1}{\rho} ε^2 H\]
we can rewrite \(R_1^ε\) as
\[R_1^ε = ε^2 \left[ \text{div}_Γ (\theta \cdot n) \nabla Γ + (\theta \cdot n) \kappa_1^2 \right] \partial_n (v_ε^2 + u^{inc}) + O(ε^3),\]
where \(O(x)\) stands for a generic distribution belonging to \(H^{-\frac{1}{2}}(Γ)\). We also simplify the expression of \(R_2^ε\) as
\[R_2^ε = -\frac{1}{\rho} ε^2 \partial_Γ (θ \cdot n) \cdot \nabla Γ \partial_n (v_ε^2 + u^{inc}) - \frac{1}{\rho} ε^2 (θ \cdot n) \Delta Γ + \kappa_1^2 |\Delta_Γ| \partial_n (v_ε^2 + u^{inc}).\]
We finally get \(F_2^ε - F_1^ε = O(ε^3).\)

7 Numerical experiments

We discuss in this section the numerical accuracy of the GIBCs to approximate the solution to the original transmission problem and its shape derivatives. We evaluate the \(L^2\) error of the far-field pattern associated to the exact and approximate fields. The far-field pattern are computed by solving the boundary integral equations given in the Appendix thanks to the high-order spectral algorithm presented in [16]. The numerical scheme applies to boundaries which are globally parameterised by spherical coordinates and consists in transforming the integral equation on the surface Γ to an integral equation on the unit sphere using a change of variable and then by expanding the integrand and looking for a scalar solution in terms of series of scalar spherical harmonics.

We denote by \(\{Y_{ℓ}^j\}_{0 ≤ |j| ≤ ℓ}\) the orthonormal system of scalar spherical harmonics. In all our experiments we set \(κ_ε = π\) so that the object size is roughly \(1λ_e\) (where \(λ_e = \frac{2π}{κ_ε}\) is the exterior wavelength) and \(κ_i = 2κ_ε,\ ρ = 1.3\).

As a first test, we consider a spherical coating of an acoustic object whose boundary \(Γ_1^ε\) is parameterised by the unit sphere \(S^2\) as follows and the visualisation is given in Figure 1.

\[x \in Γ_1^ε ⇔ \exists \hat{x} \in S^2, x = r(\hat{x}) \hat{x} \text{ with } r_1 = 0.99\sqrt{4π}Y_0^0 + 0.11Y_5^0 + 0.11Y_5^{-1}.\]

The width is then \(εh = 1 - r_1\). In Table 1 we indicate the \(L^2\) relative error, denoted by \(\text{err}_2\) between the

![Figure 1: Interior boundary of the spherical coating with a variable thickness \(εh\) varying between 0.05\(λ_e\) and 0.15\(λ_e\).](image-url)
far-field patterns of the exact exterior field $u_{\infty}^{\varepsilon}$ and the approximated field $v_{\infty}^{\varepsilon}[N]$.

$$\text{err}_2^2 = \left( \frac{\int_{S^2} |v_{\infty}^{\varepsilon}[N] - u_{\infty}^{\varepsilon}|^2 \, ds}{\int_{S^2} |u_{\infty}^{\varepsilon}|^2 \, ds} \right)^{\frac{1}{2}}.$$  

In Figures 2 and 3 we compare the amplitude of the far-field patterns of the exact solution and the approximate solution on the cut $\phi = 0^\circ$.

Table 1: Scattering of an incident plane wave by the spherical coating with either a Dirichlet or a Neumann boundary condition on the interior boundary: relative $L^2$-errors between the true scattered field and the approximate field.

<table>
<thead>
<tr>
<th>$N$</th>
<th>Dirichlet $\text{err}_2^2$</th>
<th>Neumann $\text{err}_2^2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>2.9132E − 01</td>
<td>1.1004E − 00</td>
</tr>
<tr>
<td>1</td>
<td>5.0567E − 02</td>
<td>2.1414E − 01</td>
</tr>
<tr>
<td>2</td>
<td>2.9561E − 02</td>
<td>1.3574E − 01</td>
</tr>
<tr>
<td>3</td>
<td>7.5691E − 03</td>
<td>4.5420E − 02</td>
</tr>
</tbody>
</table>

Figure 2: Amplitude of the farfield patterns $u_{\infty}^{\varepsilon}$ and $v_{\infty}^{\varepsilon}[N]$ of the scattered field associated to the original transmission problems for the spherical coating and its approximate fields in the case of a Dirichlet interior boundary condition.

As a second task, we consider an axisymmetrical coating with a constant thickness where the exterior boundary $\Gamma_2$ is parameterised by the unit sphere as follows and the visualisation is given in Figure 4.

$$x \in \Gamma_2 \Leftrightarrow \exists \hat{x} \in S^2, x = r(\hat{x}) \hat{x} \text{ with } r_2 = \frac{\sqrt{4\pi}}{4\pi} Y_0^0 + \frac{1}{4} Y_1^0 + \frac{1}{4} Y_2^0.$$

The curvature operator $\mathcal{R}$, the mean curvature $H$ and the gauss curvature $G$ are computed analytically. The surface differential operators are computed using integration by parts, projection onto the spherical harmonics and the various formulas stated in [21].

To attest the shape derivative formulas of $u_{\infty}^{\varepsilon}$ and its approximate field $v_{\infty}^{\varepsilon}[N]$ given by Theorems 4.1, 5.1 and 5.2, we compare them with the Gateaux derivative typically defined by

$$\dot{u}_{\infty}^{\varepsilon,t} = \frac{u_{\infty}^{\varepsilon,t\theta} - u_{\infty}^{\varepsilon}}{t} \quad \text{and} \quad \dot{v}_{\infty}^{\varepsilon,t}[N] = \frac{v_{\infty}^{\varepsilon,t\theta}[N] - v_{\infty}^{\varepsilon}}{t}.$$  

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for different values of $t$ and $N = 2$. The direction $\theta$ is described by the spherical coordinates of any point $\hat{x} \in S^2$ denoted by $(\psi, \phi) \in (0; \pi) \times (0; 2\pi) \cup \{(0, 0); (0, \pi)\}$ by

$$\theta(\hat{x}) = r(\hat{x})\hat{x}, \quad r(\hat{x}) = \frac{1}{5} \cos \psi \sin \phi + \frac{2}{5} \cos 2\psi \sin 3\phi.$$  

We set $\varepsilon = 0.15\lambda_e$. As expected, we observe linear convergence rate.

In Figure 5, we numerically verify the accuracy and effectiveness of the two approaches presented in Section 4 and 5 to compute of the shape derivatives. The curves represents the $L^2$ error between the shape derivative of the true far-field $u_\infty$ and the approximate shape derivatives $w_{\infty, [N]}$ or $v_{\infty, [N]}$ for $N = 1, 2$ and various values on the thickness $\varepsilon$ in a log log scale. In view of the error bound given in the introduction and

Figure 3: Amplitude of the farfield patterns $u_\infty^e$ and $v_\infty^e, [N]$ of the scattered field associated to the original transmission problems for the spherical coating and its approximate fields in the case of a Neumann interior boundary condition.

Figure 4: Exterior boundary of a coated object with a constant thickness $\varepsilon = 0.15\lambda_e$. 
for the transmission problem and in \cite{16} for impedance-like problems. In this appendix we present the boundary integral equation methods used to solve both the thin layer derivatives of the GIBCs.

A general observation is that for the error estimates is up to \(O(\varepsilon^N)\), where \(N\) is the order of truncation in the asymptotic expansion of the exact shape derivative. We explain the results by the fact that the first shape derivative depends only on the normal deformation of the exterior boundary. A general observation is that for \(N \geq 2\), the first approach is simpler than computing the shape derivatives of the GIBCs.

### Appendix: boundary integral equation methods

In this appendix we present the boundary integral equation methods used to solve both the thin layer transmission problem and the boundary value problems with GIBCs. We follow the procedure described in \cite{20} for the thin layer problem and in \cite{10} for impedance-like problems.

For \(a = i, e\), let \(G(\kappa_a, z) = \frac{e^{\kappa_a |z|}}{4\pi |z|}\) be the fundamental solution of the Helmholtz equation \(\Delta u + \kappa_a^2 u = 0\). We denote by \(S_1^{a}\) and \(D_1^{a}\) the single layer and double layer potential operators related to the boundary \(\Gamma\). They are defined by

\[
S_1^{a}\varphi(x) = \int_{\Gamma} G(\kappa_a, x - y)\varphi(y) d\sigma(y) \quad \text{and} \quad D_1^{a}\psi(x) = \int_{\Gamma} \partial_n G(\kappa_a, x - y)\psi(y) d\sigma(y).
\]

The functions \(\varphi\) and \(\psi\) are some distributions in the Sobolev spaces of fractional order \(H^{\frac{1}{2}}(\Gamma)\) and \(H^{-\frac{1}{2}}(\Gamma)\), respectively. We define in the same way the potential operators related to the boundary \(\Gamma^e\). The transmission problem \cite{1.1} can be reduced in several different ways to a system of uniquely solvable boundary integral equations. We present two different approaches. The indirect approach is based on the layer ansätz

\[
w^e = \rho D_1^e\psi - S_1^e\varphi, \quad \text{in} \quad \Omega_{ext}, \quad (A.1)
\]

\[
u^e = \left( D_1^e\psi - S_1^e\varphi + \partial_n S_1^e\xi^e \right), \quad \text{in} \quad \Omega^e_{int}, \quad (A.2)
\]

where \(\eta\) is a given positive constant and \(\xi^e \in H^{\frac{1}{2}}(\Gamma^e)\). Using the transmission conditions on \(\Gamma\) and the boundary condition on \(\Gamma^e\), the thin-layer transmission problem can be reduced to a uniquely solvable system.

### Table 2: Numerical computation of the Fréchet derivative : comparison with the finite difference method

<table>
<thead>
<tr>
<th>(t)</th>
<th>Dirichlet</th>
<th>Neumann</th>
</tr>
</thead>
<tbody>
<tr>
<td>(E - 01)</td>
<td>1.1892E - 01</td>
<td>1.2944E - 01</td>
</tr>
<tr>
<td>(E - 02)</td>
<td>1.1899E - 02</td>
<td>1.2969E - 02</td>
</tr>
<tr>
<td>(E - 03)</td>
<td>1.2997E - 03</td>
<td>1.2970E - 03</td>
</tr>
</tbody>
</table>

Theorem 6.1 taking the logarithm to both sides we obtain

\[
\log_{10} \left( ||u^e_\infty - u^e_\infty, N||_{L^2} \right) \approx \log_{10}(c_N) + m_N \log_{10}(\varepsilon), \quad (7.1)
\]

where \(c_N\) is a constant and \(m_N \approx N + 1\). The positive real values \(m_N\) are the slope of the linear curves and are indicated on the Figure 5. We observe that similar speed of convergence of \(v^e_\infty, N\) to \(u^e_\infty\) and of \(\dot{v}^e_\infty, N\) to \(\dot{u}^e_\infty\) are obtained. The speed of convergence of \(w^e_\infty, N\) to \(\dot{u}^e_\infty\) is close to \(N + 1\) but slower than the one of \(v^e_\infty, N\) to \(\dot{u}^e_\infty\).

### Conclusion and perspectives

In this work we proposed a new way to construct GIBCs for elliptic problems in \(\mathbb{R}^3\) extending previous work realised in \(\mathbb{R}^2\) \cite{20} \cite{2}. The method allows the possibility to obtain, in future works, the high order GIBCs modelling thin coatings in electromagnetics and elastodynamics with variable thickness, generalising the already existing results \cite{1} \cite{1} \cite{9} \cite{15} \cite{17}.

Using these results, we investigate the asymptotic behaviour of the shape derivatives of the solution to thin layer transmission problems. We present two different ways to approach the shape derivatives. On one hand, we construct the GIBCs associated to the thin layer transmission problem characterising the shape derivative of the solution. On the other hand, we compute the shape derivatives of the approximate solution. We show that the two approaches are equivalent in the sense that the error estimates is up to \(O(\varepsilon^{N+1})\), where \(N\) is the order of truncation in the asymptotic expansion of the exact shape derivative. We explain the results by the fact that the first shape derivative depends only on the normal deformation of the exterior boundary. A general observation is that for \(N \geq 2\), the first approach is simpler than computing the shape derivatives of the GIBCs.
of boundary integral equations of unknowns $\phi$, $\psi$ and $\xi^e$. For any distribution $\varphi \in H^{-\frac{1}{2}}(\Gamma)$, the potential

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**Figure 5:** Numerical convergence, when $\varepsilon \to 0$, of the approximate far-field $v^{\varepsilon}_{\infty,N}$ to $u^{\infty}_{\infty}$ and of the approximate shape derivatives $w^{\varepsilon}_{\infty,N}$ or $\dot{v}^{\varepsilon}_{\infty,N}$ to $\dot{u}^{\infty}_{\infty}$ in the Dirichlet (left) and Neumann (right) cases.
$S^\varphi_T$ is analytical in any subdomain of $\mathbb{R}^3 \setminus \Gamma$ and is continuous across $\Gamma$. We have
\[
(S^\varphi_T)_{|\Gamma} = S^\varphi_T \quad \text{and} \quad \lim_{s \to 0} n(x) \cdot (\nabla S^\varphi_T)(x \pm sn(x)) = \left( \mp \frac{1}{2} + D_\Gamma^\varphi \right) \varphi(x),
\]
where $I$ is the identity operator and the involved boundary integral operators are defined for $x \in \Gamma$ by
\[
S^\varphi_T \varphi(x) = \int_{\Gamma} G(\kappa, x - y) \varphi(y) \, d\sigma(y),
\]
\[
D_\Gamma^\varphi \varphi(x) = \int_{\Gamma} \partial_n G(\kappa, x - y) \varphi(y) \, d\sigma(y).
\]
For any distribution $\psi \in H^{\frac{1}{2}}(\Gamma)$, the potential $D_\Gamma^\varphi \psi$ is analytical in any subdomain of $\mathbb{R}^3 \setminus \Gamma$ and is discontinuous across $\Gamma$. We have
\[
\lim_{s \to 0} (D_\Gamma^\varphi \psi)(x \pm sn(x)) = \left( \pm \frac{1}{2}I + D_\Gamma^\varphi \right) \psi(x) \quad \text{and} \quad \partial_n D_\Gamma^\varphi \psi = N^\varphi_T \psi,
\]
where the involved boundary integral operators are defined for $x \in \Gamma$ by
\[
D_\Gamma^\varphi \psi(x) = \int_{\Gamma} \partial_n^\varphi G(\kappa, x - y) \psi(y) \, d\sigma(y),
\]
\[
N^\varphi_T \psi(x) = \int_{\Gamma} \partial_n^\varphi \partial_n^\varphi G(\kappa, x - y) \psi(y) \, d\sigma(y).
\]
The operator $S^\varphi_T$ is bounded from $H^{-\frac{1}{2}}(\Gamma)$ to $H^{\frac{1}{2}}(\Gamma)$ and compact from $H^{-\frac{1}{2}}(\Gamma)$ to itself. The operators $D_\Gamma^\varphi : H^{\frac{1}{2}}(\Gamma) \to H^{\frac{3}{2}}(\Gamma)$ and $D_\Gamma^\varphi : H^{\frac{3}{2}}(\Gamma) \to H^{-\frac{1}{2}}(\Gamma)$ are compact and the operator $N^\varphi_T : H^{\frac{1}{2}}(\Gamma) \to H^{-\frac{1}{2}}(\Gamma)$ is bounded and has a hypersingular kernel. Using these results, we obtain the following system of second kind Fredholm boundary integral equations when a Dirichlet boundary condition is fulfilled on $\Gamma^i$
\[
\begin{bmatrix}
(\frac{1+\rho^i}{2})I & 0 & 0 \\
0 & (\frac{1+\rho^i}{2})I & 0 \\
0 & 0 & N^\varphi_T
\end{bmatrix}
+ \begin{bmatrix}
\rho D_\Gamma^\varphi - D_\Gamma^\varphi & S^\varphi_T - S^\varphi_T \\
\rho (N^\varphi_T - N^\varphi_T) & \rho D_\Gamma^\varphi - D_\Gamma^\varphi \\
(\partial_n D_\Gamma^\varphi)_{|\Gamma^i} & -(S^\varphi_T)_{|\Gamma^i}
\end{bmatrix}
\begin{bmatrix}
\psi \\
\psi \\
\psi
\end{bmatrix}
= \begin{bmatrix}
-f_{\text{ext}} \\
-g_{\text{ext}} \\
-g_{\text{int}}
\end{bmatrix}.
\]
The associated integral equation operator is invertible from $H^{\frac{3}{2}}(\Gamma) \times H^{-\frac{3}{2}}(\Gamma) \times H^{\frac{1}{2}}(\Gamma)^2$ to itself. When a Neumann boundary condition is fulfilled on $\Gamma^i$, we obtain the following system of boundary integral equations
\[
\begin{bmatrix}
(\frac{1+\rho^i}{2})I & 0 & 0 \\
0 & (\frac{1+\rho^i}{2})I & 0 \\
0 & 0 & N^\varphi_T
\end{bmatrix}
+ \begin{bmatrix}
\rho D_\Gamma^\varphi - D_\Gamma^\varphi & S^\varphi_T - S^\varphi_T \\
\rho (N^\varphi_T - N^\varphi_T) & \rho D_\Gamma^\varphi - D_\Gamma^\varphi \\
(\partial_n D_\Gamma^\varphi)_{|\Gamma^i} & -(S^\varphi_T)_{|\Gamma^i}
\end{bmatrix}
\begin{bmatrix}
\psi \\
\psi \\
\psi
\end{bmatrix}
= \begin{bmatrix}
-f_{\text{ext}} \\
-g_{\text{ext}} \\
-g_{\text{int}}
\end{bmatrix}.
\]
Using regularization technique for the third case, we can prove that the associated integral equation operator is invertible from $H^{\frac{3}{2}}(\Gamma) \times H^{-\frac{3}{2}}(\Gamma) \times H^{\frac{1}{2}}(\Gamma)^2$ to $H^{\frac{3}{2}}(\Gamma) \times H^{-\frac{3}{2}}(\Gamma) \times H^{\frac{1}{2}}(\Gamma)^2$. The farfield pattern associated to the exterior field is then given by
\[
u^\infty = \rho D_\Gamma^\varphi \psi - S^\varphi_T \varphi, \quad \text{on} \quad S^2, \quad \text{(A.3)}
\]
with
\[
D_\Gamma^\varphi \psi(\tilde{x}) = -\frac{i\kappa_o}{4\pi} \int_{\Gamma} (\tilde{x} \cdot n(y)) e^{-i\kappa_o \tilde{x} \cdot y} \psi(y) \, ds(y),
\]
\[
S^\varphi_T \varphi(\tilde{x}) = \frac{1}{4\pi} \int_{\Gamma} e^{-i\kappa_o \tilde{x} \cdot y} \varphi(y) \, ds(y).
\]
The direct approach is used when $f_{\text{ext}}$ and $g_{\text{ext}}$ are the boundary data of the time-harmonic incident plane wave $u^{\text{inc}}$ and $f_{\text{int}} = 0 = g_{\text{int}}$. Then we have the following integral representation
\[
u^\text{inc} = D_\Gamma^\varphi (u_{\text{ext}}^\text{inc} + u^{\text{inc}}) - S^\varphi_T \partial_n (u_{\text{ext}}^\text{inc} + u^{\text{inc}}), \quad \text{in} \quad \Omega_{\text{ext}}, \quad \text{(A.4)}
\]
\[
u^\text{inc} = \left( -D_\Gamma^\varphi (u_{\text{ext}}^\text{inc} + u^{\text{inc}}) + \rho S^\varphi_T \partial_n (u_{\text{ext}}^\text{inc} + u^{\text{inc}}) + \left( D_\Gamma^\varphi u_{\text{int}}^\text{inc} - S^\varphi_T \partial_n u_{\text{int}}^\text{inc} \right) \right), \quad \text{in} \quad \Omega_{\text{int}}, \quad \text{(A.5)}
\]
The transmission conditions and the Dirichlet condition $u_{\text{int}}^\text{inc} = 0$ yield
\[
\begin{bmatrix}
(\frac{1+\rho^i}{2})I & 0 & 0 \\
0 & (\frac{1+\rho^i}{2})I & 0 \\
0 & 0 & N^\varphi_T
\end{bmatrix}
+ \begin{bmatrix}
\rho D_\Gamma^\varphi - D_\Gamma^\varphi & S^\varphi_T - S^\varphi_T \\
\rho (N^\varphi_T - N^\varphi_T) & \rho D_\Gamma^\varphi - D_\Gamma^\varphi \\
(\partial_n D_\Gamma^\varphi)_{|\Gamma^i} & -(S^\varphi_T)_{|\Gamma^i}
\end{bmatrix}
\begin{bmatrix}
(u_{\text{ext}}^\text{inc} + u^{\text{inc}}) \\
\partial_n (u_{\text{ext}}^\text{inc} + u^{\text{inc}}) \\
0
\end{bmatrix}
= \begin{bmatrix}
(u_{\text{ext}}^\text{inc} + u^{\text{inc}}) \\
\partial_n (u_{\text{ext}}^\text{inc} + u^{\text{inc}}) \\
0
\end{bmatrix}.
\]
The transmission conditions and the Neumann condition $\partial_n u^\varepsilon_{int} = 0$ yield
\[
\begin{pmatrix}
(1+\rho)_I & 0 & 0 \\
0 & (1+\rho)_I & 0 \\
0 & 0 & N_f
\end{pmatrix}
+ \begin{pmatrix}
\rho D^e_I - D^e_I & S^e_T - S^e_T & \rho (D^e_I)^T\Gamma \\
\rho (N_i - N_e) & \rho D^e_I - D^e_I & \rho (\partial_n D^e_I)^T\Gamma \\
-(D^e_I)^T\Gamma + \nu \partial_n (D^e_I)^T\Gamma & \frac{1}{2}((D^e_I)^T\Gamma + \nu \partial_n (D^e_I)^T\Gamma) & \nu D^e_{f+} - \nu^T I
\end{pmatrix}
\begin{pmatrix}
u u^\varepsilon_{ext} + u^{inc} \\
\partial_n (u^\varepsilon_{ext} + u^{inc}) \\
\partial_n u^{inc}
\end{pmatrix} = \begin{pmatrix} u^{inc} \\
0 \\
0
\end{pmatrix}.
\]

The farfield pattern associated to the exterior field is then given by
\[
\begin{align*}
    u^\infty &= D^\infty_T (u^\varepsilon_{ext} + u^{inc}) - S^\infty_T \partial_n (u^\varepsilon_{ext} + u^{inc}), & \text{on } S^2, \\
\end{align*}
\]  \hspace{1cm} (A.6)

The direct method is used to compute the solution to the forward problem while the indirect one is required to compute the shape derivatives of the solution. The direct method has the advantage to provide the boundary data which are needed to compute the boundary data of the shape derivatives (see Theorem 4.1).

The exterior problems (3.1) can be solved, for $N = 1, 2, 3$, using boundary integral equation methods. Here again we consider two approaches. The indirect one is based on the layer ansatz
\[
u^\varepsilon = S^\varepsilon T \varphi \quad \text{in } \Omega_{ext}
\]
and can be used for solving the exterior problems (3.1) when the boundary condition is written in the form $C(\varepsilon, \partial_n (v_{[N]}), (v_{[N]})) = F$. The exterior problem can be reduced to the following boundary integral equation for the unknown $\varphi$
\[
C(\varepsilon, -\frac{1}{4} I + D^e_T S^e_T)\varphi = -C(\varepsilon, \partial_n u^{inc}, u^{inc}).
\]
The farfield pattern associated to the exterior field is then given by $u^\infty = S^\infty_T \varphi$.

The direct one is based on the integral representation formula of the exterior wave
\[
v_{[N]}^\varepsilon = D^e_T (v_{[N]}^\varepsilon + u^{inc}) - S^e_T \partial_n (v_{[N]} + u^{inc}), \quad \text{in } \Omega_{ext}, \quad \text{(A.7)}
\]
In the case of a Dirichlet boundary condition, the GIBCs given in Theorem 3.1 yield the boundary integral equation
\[
\left[ \left( \frac{1}{4} I - D^e_I \right) \left( -B^{\varepsilon,N} - S^e_T \right) \partial_n (v_{[N]}^\varepsilon + u^{inc}) \right] = u^{inc}.
\]
We obtain the other boundary data by computing $(v_{[N]}^\varepsilon + u^{inc}) = -B^{\varepsilon,N} \partial_n (v_{[N]}^\varepsilon + u^{inc})$. In the case of a Neumann boundary condition, the GIBCs given in Theorem 3.1 yield the boundary integral equation
\[
\left[ \left( \frac{1}{4} I - D^e_I \right) - S^e_T \left( -B^{\varepsilon,N} \right) \right] (v_{[N]}^\varepsilon + u^{inc}) = u^{inc}.
\]
We obtain the other boundary data by computing $\partial_n (v_{[N]}^\varepsilon + u^{inc}) = -B^{\varepsilon,N} (v_{[N]}^\varepsilon + u^{inc})$. The farfield pattern associated to the exterior field is then given by (A.6).

Here again, the direct method is used to compute the solution to the forward problem while the indirect one is required to compute the shape derivatives of the solution. The direct method has the advantage to provide the boundary data which are needed to compute the boundary data of the shape derivatives.

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References


