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Non-deterministic Semantics and the Undecidability of Boolean BI

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We solve the open problem of the decidability of Boolean BI logic (BBI), which can be considered as the core of Separation and Spatial Logics. For this, we define a complete phase semantics for BBI and characterize it as trivial phase semantics. We deduce an embedding between trivial phase semantics for intuitionistic linear logic (ILL) and Kripke semantics for BBI. We single out the elementary fragment of ILL which is both undecidable and complete for trivial phase semantics. Thus, we obtain the undecidability of BBI.

Categories and Subject Descriptors: F.4.1 [Mathematical Logic and Formal Languages]: Mathematical Logic—*Proof theory; Model Theory; Computability theory*

General Terms: Theory

Additional Key Words and Phrases: Linear Logic, Boolean BI, Minsky machines, decidability

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1. INTRODUCTION

The question of the decidability of the Boolean version of the logic of Bunched Implications (denoted BI) was a longstanding open problem. BI itself was proved decidable by Galmiche *et al.* [Galmiche et al. 2005] and Boolean BI was naively thought “simpler” than BI until a faithful embedding from BI into Boolean BI was discovered [Larchey-Wendling and Galmiche 2009]. Independently, Brotherston and Kanovich [Brotherston and Kanovich 2010] on the one hand and Larchey-Wendling and Galmiche [Larchey-Wendling and Galmiche 2010] on the other hand recently solved the issue by different techniques: the former by focusing mainly on the links between Boolean BI and Separation Logic, the later by establishing semantic links between Intuitionistic Linear Logic (ILL) and Boolean BI. This paper is an enriched and self-contained version of the results and proofs of [Larchey-Wendling and Galmiche 2010].

The logic BI of bunched implications [O’Hearn and Pym 1999] is a sub-structural logic which freely combines additive connectives \wedge , \vee , \rightarrow and multiplicative connectives $*$, $-*$. In BI, both the multiplicatives and the additives behave intuitionistically. From its inception, BI was given a nice bunched sequent proof-system enjoying cut-elimination [Pym 2002]. Later, [Galmiche et al. 2005] gave BI a sound and complete labeled tableaux system from which decidability was derived. The logic BI is sometimes called intuitionistic BI to distinguish it with other variants where either the multiplicatives or the additives include a negation and thus behave classically.

From a proof-theoretical perspective, Boolean BI (or simply BBI) can be considered as the first investigated variant of BI which contained a negation: BBI combines intuitionistic multiplicatives with Boolean additives. This focus on BBI is the consequence of the natural links between BBI and separation or spatial logics. Indeed, for instance, the pure part of separation logic is essentially obtained by considering a particular model of BBI, based on a (partial) monoid of heaps [Ishtiaq and O’Hearn 2001] (see [Larchey-Wendling and Galmiche 2009] for a more general discussion on these links). The Hilbert proof-system of BBI was proved complete w.r.t. *relational (or non-deterministic) Kripke semantics* [Galmiche and Larchey-Wendling 2006]. However, the proof-theory of BBI was rather poorly developed because it was difficult to conceive how the bunched sequent calculus of (intuitionistic) BI could be extended to BBI without losing key properties such as e.g. cut-elimination.

Two main families of results emerged giving a contrasted view of its proof-theory. On the one hand, [Brotherston 2010] adapted the Display proof-system of Classical BI to BBI, circumventing the difficulty of the multiplicatives of BBI lacking a negation. This system was proved sound and

complete w.r.t. relational Kripke semantics. Cut-elimination was also derived but, despite the expectations of Brotherston, no decidability result followed. On the other hand, [Larchey-Wendling and Galmiche 2009] proposed a labeled tableaux proof-system for (partial monoidal) BBI and by the study of the relations between the proof-search generated counter-models of BI and BBI, showed that (intuitionistic) BI could be faithfully embedded into BBI. This result, at first counter-intuitive, hinted that BBI, originally thought simpler than BI, could in fact be much more difficult to decide.

In this paper, we consider models of BBI belonging to different classes:

- ND. The class of non-deterministic monoids;
- PD. The class of partial (deterministic) monoids;
- TD. The class of total (deterministic) monoids;
- HM. The class of heaps monoids (i.e. separation logic models);
- FM. The class of free monoids.

Generally, each class of models defines a different notion of (universal Kripke) validity on the formulae of BBI. For instance, we recall the result that the set BBI_{ND} of BBI-formulae valid in every non-deterministic monoid is strictly included in the set BBI_{PD} of BBI-formulae valid in every partial deterministic monoid [Larchey-Wendling and Galmiche 2010]. The classification of these classes of models with respect to BBI Kripke validity is not finished though.

The principal result of this paper is the *undecidability of universal validity in BBI*, whichever class of models is chosen amongst ND, PD, TD, HM and FM. Although these classes of models generally define different notions of universal validity for the whole BBI, we have identified a fragment of BBI on which these semantics collapse to one. This fragment is the direct image of *the elementary fragment of ILL* (denoted eILL) by an *embedding of ILL into BBI*. This elementary fragment is different from the minimal fragment of Boolean BI identified in [Brotherston and Kanovich 2010] but has similar properties. In our case, undecidability is obtained by the following steps:

- we show that the embedding of eILL into BBI is *faithful for trivial phase semantics*;
- we show that the eILL fragment is *complete for trivial phase semantics*, whichever class of models is chosen amongst ND, PD, TD, HM and FM;
- we show how to encode the computations of two counter Minsky machines in eILL .

As a consequence, we derive the undecidability of the eILL fragment, from which we deduce the undecidability of BBI. We complete the pictures with additional results of undecidability on the models based on the free monoid $\mathbb{N} \times \mathbb{N}$ and the models based on the partial monoid $\mathbb{P}_f(\mathbb{N})$ (which is also the simplest heap monoid). This last result is obtained using bisimulation techniques.

Compared to the original LICS'10 paper [Larchey-Wendling and Galmiche 2010], this paper contains a more extensive study of the semantics of the eILL fragment with completeness results for various classes of models and the adaptation of our undecidability result of BBI to heaps models (i.e. to Separation Logic) using a bisimulation between free monoids and heap monoids.

2. CLASSES OF NON-DETERMINISTIC MONOIDS

In this section, we define the algebraic notion of non-deterministic (commutative) monoid. We denote algebraic structure by \mathcal{M} , \mathcal{N} ,... classes of structures by \mathcal{C} , \mathcal{D} ,... sets by X , Y ,... elements by x , y ,... and well known constructs like the powerset by $\mathbb{P}(X)$ or the set of (finite) multisets by $\mathbb{M}_f(X)$. The symbol $\mathbb{N} = \{0, 1, 2, \dots\}$ denotes the set of natural numbers. The symbol \emptyset is used either to denote the empty set, the empty multiset or the empty class.

2.1. Non-deterministic monoids

Let us consider a set M and its powerset $\mathbb{P}(M)$, i.e. the set of subsets of M . A *composition* is a binary function $\circ : M \times M \rightarrow \mathbb{P}(M)$ which naturally extended to a binary operator on $\mathbb{P}(M)$ by

$$X \circ Y = \bigcup \{x \circ y \mid x \in X \text{ and } y \in Y\} \quad (1)$$

for any subsets X, Y of M . Using this extension, we can view an element m of M as the singleton set $\{m\}$ and derive equations like $m \circ X = \{m\} \circ X$ and $a \circ b = \{a\} \circ \{b\}$ by a slight abuse of notation.

Definition 2.1. A *non-deterministic (or relational) monoid* is a triple (M, \circ, ϵ) where M is a set, $\epsilon \in M$ is the *neutral element* and $\circ : M \times M \rightarrow \mathbb{P}(M)$ is the *composition operator*. In addition, the following axioms are mandatory:

$$\begin{aligned} \forall a \in M, \epsilon \circ a = \{a\} & \quad (\text{neutrality}) \\ \forall a, b \in M, a \circ b = b \circ a & \quad (\text{commutativity}) \\ \forall a, b, c \in M, a \circ (b \circ c) = (a \circ b) \circ c & \quad (\text{associativity}) \end{aligned}$$

The class of non-deterministic monoids is denoted ND.

Associativity should be understood using the extension of \circ to $\mathbb{P}(M)$ as defined by Equation (1). The extension of \circ to $\mathbb{P}(M)$ induces a commutative monoidal structure with unit element $\{\epsilon\}$ on $\mathbb{P}(M)$. As a consequence, the structure $(\mathbb{P}(M), \circ, \{\epsilon\})$ is a (usual) commutative monoid.

The term *non-deterministic* was introduced in [Galmiche and Larchey-Wendling 2006] in order to emphasize the fact that the composition $a \circ b$ may yield not only one but an arbitrary number of results including the possible incompatibility of a and b in which case $a \circ b = \emptyset$. If $(M, +, 0)$ is a (usual) commutative monoid then, defining $a \circ b = \{a + b\}$ and $\epsilon = 0$ induces a non-deterministic monoid (M, \circ, ϵ) . Using the bijection $x \mapsto \{x\}$ mapping elements of M to singletons in $\mathbb{P}(M)$, we can view (usual) commutative monoids as a particular case of non-deterministic monoids (later called total deterministic monoids). Partial monoids can also be represented using the empty set \emptyset as the result of undefined compositions (see section 2.2).

The term *relational* is sometimes used because the map $\circ : M \times M \rightarrow \mathbb{P}(M)$ can equivalently be understood as a ternary relation $- \circ - \ni - : M \times M \times M \rightarrow \{0, 1\}$ through the Curry-Howard isomorphism and the axioms correspond to those of an internal monoid in the category of relations [Ghilardi and Meloni 1990]. The two presentations are equivalent but we rather use the monoidal presentation in this paper because it better suits the context and habits of phase semantics and Kripke semantics.

2.2. Sub-classes of non-deterministic monoids

Definition 2.2. Let (M, \circ, ϵ) be a non-deterministic monoid. It is a *partial deterministic monoid* if for all $x, y \in M$, the composition $x \circ y$ is either empty or a singleton. It is a *total deterministic monoid* if for all $x, y \in M$, the composition $x \circ y$ is a singleton. We use PD (resp. TD) to represent the sub-class of partial deterministic (resp. total deterministic) monoids.

The reader may have noticed that total deterministic monoids (of class TD) exactly correspond to those non-deterministic monoids derived from usual commutative monoids via the map $x \mapsto \{x\}$ because the composition \circ is a functional relation in this case (exactly one image for each pair of parameters).

Let us give an example of non-deterministic monoid which shows that the class ND contains structures that have properties which are fundamentally different from those of partial or total monoids. The non-deterministic monoid $(\{\epsilon, x, y\}, \circ, \epsilon)$ built over this 3 elements set and defined by the following composition operator:

\circ	ϵ	x	y
ϵ	$\{\epsilon\}$	$\{x\}$	$\{y\}$
x	$\{x\}$	$\{\epsilon, y\}$	$\{y\}$
y	$\{y\}$	$\{y\}$	$\{y\}$

is an example of such non-deterministic monoid. It is a witness that PD is a proper sub-class of ND. But also, we see that in this monoid, x is both self inverse ($\epsilon \in x \circ x$) and this same composition yields the absorbing element ($y \in x \circ x$). In Section 6.1, we will see that BBI is able to witness the difference between the class ND and the class PD.

A typical sub-class of partial deterministic monoids is obtained by considering disjoint union over the powerset. Given a set X , consider the partial deterministic monoid $(\mathbb{P}(X), \uplus, \emptyset)$ where \emptyset is the empty subset of X and \uplus is defined for $A, B \subseteq X$ by

$$A \uplus B = \begin{cases} \emptyset & \text{when } A \cap B \neq \emptyset \\ \{A \cup B\} & \text{when } A \cap B = \emptyset \end{cases}$$

One could even restrict to finite subsets of X by considering the partial monoid $(\mathbb{P}_f(X), \uplus, \emptyset)$ where $\mathbb{P}_f(X)$ is the set of finite subsets of X .

A (more general) sub-class of partial deterministic monoids is of particular importance to Separation Logic [Ishtiaq and O’Hearn 2001]. Given an (infinite) set L of *locations* and a (non-empty) set V of *values*, a *heap* is a partial function from locations to values defined only on a finite number of locations. We define

$$\mathbb{H}_{L,V} = \{h : L \rightarrow_f V \mid \text{def}(h) \text{ is finite}\} \quad \text{where } \text{def}(h) = \{l \in L \mid h(l) \text{ is defined}\}$$

so $\text{def}(h)$ is the (finite) set of locations on which h is defined. The binary composition $s \boxplus t$ of two heaps $s, t \in \mathbb{H}_{L,V}$ is defined by

$$s \boxplus t = \begin{cases} \emptyset & \text{when } \text{def}(s) \cap \text{def}(t) \neq \emptyset \\ \{r\} & \text{when } \text{def}(s) \cap \text{def}(t) = \emptyset \end{cases} \quad \text{with } \text{graph}(r) = \text{graph}(s) \cup \text{graph}(t)$$

The heap defined nowhere (i.e. with an empty graph) is denoted \emptyset . The heap monoid $(\mathbb{H}_{L,V}, \boxplus, \emptyset)$ is a partial deterministic monoid of class PD. We point out that when $V = \{*\}$ is a singleton set, then the heap monoid $(\mathbb{H}_{L,\{*\}}, \boxplus, \emptyset)$ is isomorphic to finite powerset monoid $(\mathbb{P}_f(L), \uplus, \emptyset)$. Hence, the class of heap monoids contains (an isomorphic copy of) the class of finite powersets. The class of heap monoids is denoted HM:

$$\text{HM} = \{(\mathbb{H}_{L,V}, \boxplus, \emptyset) \mid L \text{ is infinite and } V \text{ is not empty}\}$$

It is obviously a sub-class of PD. Since for any non-empty heap h we have $h \boxplus h = \emptyset$ (but $\emptyset \boxplus \emptyset = \{\emptyset\}$), it is clear that no heap monoid $\mathbb{H}_{L,V}$ is a total deterministic monoid (because neither L nor V is empty). Hence, HM and TD are two disjoint sub-classes of PD.

Another important sub-class of non-deterministic monoids is the class of FM of free (commutative) monoids $(\mathbb{M}_f(X), \star, \pi)$ where X is a set, $\mathbb{M}_f(X)$ denotes the set of (finite) multisets of elements of X , and \star (resp. π) denotes multiset addition (resp. the empty multiset). When X is not empty, $\mathbb{M}_f(X)$ contains an element $x \neq \pi$ and in this case, $x \star x \neq \{x\}$. Since there are total deterministic monoids satisfying the axiom $x \star x = \{x\}$ (for example lattices), we deduce that FM is a proper sub-class of TD.

$$\text{P} \quad 2.3. \quad \text{FM} \subsetneq \text{TD} \subsetneq \text{PD} \subsetneq \text{ND}, \text{HM} \subsetneq \text{PD} \text{ and } \text{HM} \cap \text{TD} = \emptyset.$$

3. SEQUENT CALCULUS AND PHASE SEMANTICS FOR ILL

Linear Logic and Intuitionistic Linear Logic (denoted ILL) are well know sub-structural logics introduced by Girard in [Girard 1987] to better study the impact of structural rules on the proof-theoretical as well as semantical properties of logics. The reader can consult [Troelstra 1992] for an overview on those topics.

The formulae of ILL are defined by the following grammar:

$$A ::= v \mid c \mid !A \mid A \boxtimes A \quad \text{with } v \in \text{Var}, c \in \{1, \top, \perp\}^1 \text{ and } \boxtimes \in \{\otimes, \multimap, \&, \oplus\}$$

A *sequent* is a pair denoted $\Gamma \vdash A$ where Γ is a (finite) multiset of formulae and A is a single formula. The *sequent calculus* S-ILL (see Figure 1) is provided for ILL and the *set of derivable sequents* is

¹Sometimes the neutral of \oplus is denoted 0, but we favor \perp as in [Troelstra 1992].

$$\begin{array}{c}
\frac{}{A \vdash A} \langle \text{id} \rangle \quad \frac{}{\Gamma, \perp \vdash A} \langle \perp_L \rangle \quad \frac{}{\Gamma \vdash \top} \langle \top_R \rangle \quad \frac{}{\vdash 1} \langle 1_R \rangle \quad \frac{\Gamma \vdash A \quad A, \Delta \vdash B}{\Gamma, \Delta \vdash B} \langle \text{cut} \rangle \\
\frac{\Gamma, A \vdash B}{\Gamma, !A \vdash B} \langle !L \rangle \quad \frac{! \Gamma \vdash B}{! \Gamma \vdash !B} \langle !R \rangle \quad \frac{\Gamma \vdash B}{\Gamma, !A \vdash B} \langle w \rangle \quad \frac{\Gamma, !A, !A \vdash B}{\Gamma, !A \vdash B} \langle c \rangle \quad \frac{\Gamma \vdash A}{\Gamma, 1 \vdash A} \langle 1L \rangle \\
\frac{\Gamma, A \vdash C}{\Gamma, A \& B \vdash C} \langle \&L^1 \rangle \quad \frac{\Gamma, B \vdash C}{\Gamma, A \& B \vdash C} \langle \&L^2 \rangle \quad \frac{\Gamma \vdash A \quad \Gamma \vdash B}{\Gamma \vdash A \& B} \langle \&R \rangle \\
\frac{\Gamma, A \vdash C \quad \Gamma, B \vdash C}{\Gamma, A \oplus B \vdash C} \langle \oplus_L \rangle \quad \frac{\Gamma \vdash A}{\Gamma \vdash A \oplus B} \langle \oplus_R^1 \rangle \quad \frac{\Gamma \vdash B}{\Gamma \vdash A \oplus B} \langle \oplus_R^2 \rangle \\
\frac{\Gamma, A, B \vdash C}{\Gamma, A \otimes B \vdash C} \langle \otimes_L \rangle \quad \frac{\Gamma \vdash A \quad \Delta \vdash B}{\Gamma, \Delta \vdash A \otimes B} \langle \otimes_R \rangle \quad \frac{\Gamma \vdash A \quad \Delta, B \vdash C}{\Gamma, \Delta, A \multimap B \vdash C} \langle \multimap_L \rangle \quad \frac{\Gamma, A \vdash B}{\Gamma \vdash A \multimap B} \langle \multimap_R \rangle
\end{array}$$

Fig. 1. Sequent calculus **S-ILL** for **ILL**

the least set closed under its rules. Notice that Γ, Δ denote multisets of formulae and A, B, C denote formulae. In rule $\langle !R \rangle$, $! \Gamma$ denotes the multiset $! \Gamma = !A_1, \dots, !A_k$ if $\Gamma = A_1, \dots, A_k$.²

The notion of sequent calculus proof is defined as usual: an ordered tree where each node together with its sons correspond to an instance of one of the rules of **S-ILL**. Hence, a sequent is derivable if and only if there exists a proof of it in **S-ILL**. By historical definition of **ILL** [Girard 1987], the sequents which are provable in **S-ILL** are exactly the *valid sequents* of **ILL**, and a formula A of **ILL** is valid if $\vdash A$ is a valid sequent.

3.1. Non-deterministic phase spaces for **ILL**

We extend the notion of intuitionistic phase space [Girard 1987] to non-deterministic monoids and show that this semantic interpretation is sound and complete w.r.t. **S-ILL**, and thus equivalent to the original notion (see Corollary 3.6).

Definition 3.1. A non-deterministic (intuitionistic) phase space is given by a non-deterministic monoid $\mathcal{M} = (M, \circ, \epsilon)$ together with a stable closure operator $(\cdot)^\circ : \mathbb{P}(M) \rightarrow \mathbb{P}(M)$ and a sub-monoid K included in $J = \{x \in M \mid x \in \{\epsilon\}^\circ \cap (x \circ x)^\circ\}$.

— the *closure property* corresponds to the condition

$$X \subseteq Y^\circ \text{ iff } X^\circ \subseteq Y^\circ \quad \text{for any } X, Y \in \mathbb{P}(M)$$

We recall that the monoidal composition \circ is naturally extended to $\mathbb{P}(M)$ by Equation (1) providing a (commutative) monoidal structure on $\mathbb{P}(M)$ with unit $\{\epsilon\}$. A subset X of M is $(\cdot)^\circ$ -closed (or simply closed when the closure operator is obvious from the context) if $X^\circ = X$ or equivalently $X^\circ \subseteq X$. The set of closed subsets is denoted $\mathcal{M}^\circ = \{X \in \mathbb{P}(M) \mid X^\circ = X\}$, not to be confused with M° where M is viewed as the (total) subset of M (and in this case, $M^\circ = M$). Any intersection of closed subsets is a closed subset and thus \mathcal{M}° is invariant under arbitrary intersections, inducing a complete lattice structure on $(\mathcal{M}^\circ, \subseteq)$.

— the *stability property*³ corresponds to the condition

$$X^\circ \circ Y^\circ \subseteq (X \circ Y)^\circ \quad \text{for any } X, Y \in \mathbb{P}(M)$$

²Notice that when multisets are considered as syntactic objects, it is usual to denote the composition of multisets by a comma whereas when they are considered as semantic objects, then the denotation of the composition operator (and the neutral element) might differ. For example, we will use \star and π in this paper.

³A stable closure is a *quantic nucleus* in quantale theory [Yetter 1990]. The “stability” property itself seems to have no well established terminology.

Let \multimap be the adjoint of \circ as a binary operator on $\mathbb{P}(M)$. It is defined by $X \multimap Y = \{k \in M \mid k \circ X \subseteq Y\}$ for any $X, Y \in \mathbb{P}(M)$. In the lattice $(\mathbb{P}(M), \subseteq)$, the operator \multimap is contra-variant in its first parameter and co-variant in its second and the following adjoint property holds

$$Z \subseteq X \multimap Y \text{ iff } Z \circ X \subseteq Y \quad \text{for any } X, Y, Z \in \mathbb{P}(M)$$

By stability of the closure operator $(\cdot)^\circ$, the subset $X \multimap Y$ is closed as soon as Y is closed and $X \multimap Y^\circ = X^\circ \multimap Y$ holds for any $X, Y \in \mathbb{P}(M)$.

— the set K is a given *sub-monoid* of M included in J , i.e. K verifies both

$$\epsilon \in K \subseteq J \quad \text{and} \quad K \circ K \subseteq K$$

We see that we have a (quite direct) generalization of the usual notion of phase space in the case where the monoid is neither supposed to be total nor deterministic. In the particular case of total deterministic monoids, we recover the usual notion of phase space.

The interpretation of ILL connectives is done in the following way. Given an *interpretation* of logical variables as closed subsets $\llbracket \cdot \rrbracket : \text{Var} \rightarrow \mathcal{M}^\circ$, this interpretation is extended to all the formulae of ILL by structural induction as follows:

$$\begin{aligned} \llbracket \perp \rrbracket &= \emptyset^\circ & \llbracket A \oplus B \rrbracket &= (\llbracket A \rrbracket \cup \llbracket B \rrbracket)^\circ \\ \llbracket \top \rrbracket &= M & \llbracket A \& B \rrbracket &= \llbracket A \rrbracket \cap \llbracket B \rrbracket \\ \llbracket 1 \rrbracket &= \{\epsilon\}^\circ & \llbracket A \otimes B \rrbracket &= (\llbracket A \rrbracket \circ \llbracket B \rrbracket)^\circ \\ \llbracket !A \rrbracket &= (K \cap \llbracket A \rrbracket)^\circ & \llbracket A \multimap B \rrbracket &= \llbracket A \rrbracket \multimap \llbracket B \rrbracket \end{aligned}$$

When the interpretation is done in a total deterministic monoid, we obtain *exactly the same value* for $\llbracket A \rrbracket$ as in the usual phase semantics interpretation.

Definition 3.2. A sequent $A_1, \dots, A_k \vdash B$ of ILL is *valid in the interpretation* $\llbracket \cdot \rrbracket$ if the inclusion $\llbracket A_1 \rrbracket \circ \dots \circ \llbracket A_k \rrbracket \subseteq \llbracket B \rrbracket$ holds.

We recall the soundness theorem which states that provability in S-ILL entails semantic validity in non-deterministic intuitionistic phase semantics.

T 3.3 (S P S). *If the sequent $A_1, \dots, A_k \vdash B$ has a proof in S-ILL then the inclusion relation $\llbracket A_1 \rrbracket \circ \dots \circ \llbracket A_k \rrbracket \subseteq \llbracket B \rrbracket$ holds.*

P. The proof of this theorem can be done directly by generalizing the soundness proof of usual phase semantics [Girard 1987], or else, as done in Appendix A by using the algebraic semantic characterization of ILL of [Troelstra 1992]. \square

Definition 3.4. We denote by ILL_p the set of sequents which have a proof in S-ILL. We denote by ILL_X the set of sequents which are valid in every non-deterministic phase semantic interpretation where the base monoid is of the class X .

In this paper, the class X ranges over the following set of classes $\{\text{ND}, \text{PD}, \text{TD}, \text{HM}, \text{FM}\}$. Let us consider the following inclusion sequence:

$$\text{ILL}_p \subseteq \text{ILL}_{\text{ND}} \subseteq \text{ILL}_{\text{PD}} \subseteq \text{ILL}_{\text{TD}} \subseteq \text{ILL}_{\text{FM}} \subseteq \text{ILL}_p \quad (2)$$

The first inclusion $\text{ILL}_p \subseteq \text{ILL}_{\text{ND}}$ is given by Theorem 3.3. The following inclusions $\text{ILL}_{\text{ND}} \subseteq \text{ILL}_{\text{PD}} \subseteq \text{ILL}_{\text{TD}} \subseteq \text{ILL}_{\text{FM}}$ are obvious consequences of the inclusions $\text{FM} \subseteq \text{TD} \subseteq \text{PD} \subseteq \text{ND}$ between classes of non-deterministic monoids. The last inclusion $\text{ILL}_{\text{FM}} \subseteq \text{ILL}_p$ is just a reformulation of the completeness of the phase semantics w.r.t. S-ILL:

T 3.5 (C P S). *If the sequent $\Gamma \vdash A$ is valid in every free monoidal phase semantic interpretation $(M, \circ, \epsilon, (\cdot)^\circ, K, \llbracket \cdot \rrbracket)$ (i.e. with (M, \circ, ϵ) of the class FM), then $\Gamma \vdash A$ has a proof in S-ILL.*

P . The proof is based on a very nice semantic argument first introduced by Okada [Okada 2002]. Nevertheless, as its understanding is not really critical to the developments of this paper, it is postponed to Appendix B. \square

C 3.6. $\text{ILL}_p = \text{ILL}_{\text{ND}} = \text{ILL}_{\text{PD}} = \text{ILL}_{\text{TD}} = \text{ILL}_{\text{FM}}$ and non-deterministic phase semantics is both sound and complete w.r.t. S-ILL.

P . With Theorem 3.5, we have closed the circular inclusion sequence (2). In particular $\text{ILL}_p = \text{ILL}_{\text{ND}}$. \square

Remark: we let the question of determining whether $\text{ILL}_{\text{HM}} = \text{ILL}_p$ or else $\text{ILL}_{\text{HM}} \not\subseteq \text{ILL}_p$ as an open question.

3.2. Trivial phase semantics for ILL

In this section, we define trivial phase semantics which is a particular case of phase semantics where the choice of the least closure operator is mandatory.

Definition 3.7. Given a non-deterministic monoid $\mathcal{M} = (M, \circ, \epsilon)$, the *trivial phase space* is defined by taking the identity map on $\mathbb{P}(M)$ as closure operator (i.e. for all $X \in \mathbb{P}(M)$, $X^\circ = X$) and by taking $K = \{\epsilon\}$.

It is clear that the identity on $\mathbb{P}(M)$ is both a closure and stable. Obviously also, $K = \{\epsilon\}$ verifies the conditions $\epsilon \in K \subseteq J$ and $K \circ K \subseteq K$.⁴ In a trivial phase space, every subset of M is closed and thus $\mathcal{M}^\circ = \mathbb{P}(M)$. The interpretation of ILL connectives simplifies to:

$$\begin{array}{ll} \llbracket \perp \rrbracket = \emptyset & \llbracket A \oplus B \rrbracket = \llbracket A \rrbracket \cup \llbracket B \rrbracket \\ \llbracket \top \rrbracket = M & \llbracket A \& B \rrbracket = \llbracket A \rrbracket \cap \llbracket B \rrbracket \\ \llbracket 1 \rrbracket = \{\epsilon\} & \llbracket A \otimes B \rrbracket = \llbracket A \rrbracket \circ \llbracket B \rrbracket \\ \llbracket !A \rrbracket = \{\epsilon\} \cap \llbracket A \rrbracket & \llbracket A \multimap B \rrbracket = \llbracket A \rrbracket \multimap \llbracket B \rrbracket \end{array}$$

Trivial phase semantics is *not complete* for the whole ILL. Indeed, the additive operators \oplus and $\&$ become distributive over each other in trivial phase semantics. This is not the case in (general) phase semantics. In particular, the formula $A \& (B \oplus C) \multimap (A \& B) \oplus (A \& C)$ is valid in trivial phase semantics but has no proof in S-ILL.

However not complete for the whole ILL, we are now going to introduce the elementary fragment of ILL which is complete for trivial phase semantics and nevertheless sufficiently expressive to be able to encode computations of Minsky machines.

4. ELEMENTARY INTUITIONISTIC LINEAR LOGIC AND TRIVIAL PHASE SEMANTICS

We define and characterize *elementary* ILL (denoted eILL), an extension of the fragment s-IMELL₀[◦] of ILL [de Groote et al. 2004]. We provide a simple goal-directed proof system, denoted G-eILL, which is itself an extension of the goal-directed proof system of s-IMELL₀[◦], obtained by the addition of a new additive rule. Then we show that the proof system G-eILL and trivial phase semantics are both sound and complete w.r.t. the fragment eILL. We also show that validity in trivial phase semantics does not depend on a particular class of models on the elementary fragment: all classes among {ND, PD, TD, FM} define the same set of (universally) valid elementary sequents.

4.1. The eILL fragment of ILL

Definition 4.1. A formula of ILL is ($\multimap, \&$)-*elementary* if it is of the form $u \multimap v$, $(u \multimap v) \multimap w$, $u \multimap (v \multimap w)$ or $(u \& v) \multimap w$ where u , v and w are logical variables in Var . The *sequents of the fragment eILL* are those of the form $! \Sigma, \Gamma \vdash c$ where Γ is a multiset of variables, c is a variable and Σ is a multiset of ($\multimap, \&$)-elementary formulae.

⁴In fact, there is no other possible choice for K because $J = \{x \in M \mid x \in \{\epsilon\}^\circ \cap (x \circ x)^\circ\} = \{\epsilon\}$ when $(\cdot)^\circ$ is the identity map on $\mathbb{P}(M)$.

$$\begin{array}{c}
\frac{}{! \Sigma, u \vdash u} \langle Ax \rangle \quad \frac{! \Sigma, \Gamma \vdash u}{! \Sigma, \Gamma \vdash v} u \multimap v \in \Sigma \quad \frac{! \Sigma, \Gamma, u \vdash v}{! \Sigma, \Gamma \vdash w} (u \multimap v) \multimap w \in \Sigma \\
\frac{! \Sigma, \Gamma \vdash u \quad ! \Sigma, \Delta \vdash v}{! \Sigma, \Gamma, \Delta \vdash w} u \multimap (v \multimap w) \in \Sigma \quad \frac{! \Sigma, \Gamma \vdash u \quad ! \Sigma, \Gamma \vdash v}{! \Sigma, \Gamma \vdash w} (u \& v) \multimap w \in \Sigma
\end{array}$$

Fig. 2. G-eILL: a goal-directed sequent calculus for eILL

From this definition, it is obvious that membership in the fragment eILL is a recursive property. Compared to s-IMELL₀[→], the only new form is $(u \& v) \multimap w$. The validity of sequents in eILL can be established using the proof system S-ILL but we rather provide an alternative goal-directed proof system called G-eILL in Figure 2. Apart for the axiom rule $\langle Ax \rangle$, each other rule $\langle \multimap \rangle$, $\langle (\multimap) \multimap \rangle$, $\langle \multimap (\multimap) \rangle$ or $\langle (\&) \multimap \rangle$ is named according to the form of its side condition. Compared to s-IMELL₀[→], the only new rule is $\langle (\&) \multimap \rangle$ (see [de Groote et al. 2004]). In this paper, the authors did not provide a proof of soundness/completeness of the system s-IMELL₀[→], leaving it to the reader. Here we present a full proof of soundness/completeness for our extension G-eILL not only to please the reader but also to derive completeness of the fragment w.r.t. trivial phase semantics.

4.2. Completeness results for eILL

Even though validity in eILL is the same as in the whole ILL (established for instance by a proof in S-ILL), here we show that in this specific fragment, validity is also sound and complete both w.r.t. the system G-eILL and w.r.t. free monoidal trivial phase semantics.

L 4.2. *Every proof of a sequent in G-eILL can be transformed into a proof (of the same sequent) which uses only rules $\langle id \rangle$, $\langle w \rangle$, $\langle c \rangle$, $\langle \multimap_L \rangle$, $\langle \multimap_R \rangle$, $\langle !_L \rangle$ and $\langle \&_R \rangle$ of S-ILL.*

P . We proceed by induction on the proofs in G-eILL and by case analysis, depending on the last rule applied. Let n be the cardinal of the multiset Σ . For each rule of G-eILL, we propose the corresponding (open) proof tree in S-ILL:

— case of rule $\langle Ax \rangle$:

$$\begin{array}{c}
\frac{}{u \vdash u} \langle id \rangle \\
\frac{}{w} \langle w \rangle \\
\vdots \text{ applied } n \text{ times} \\
\frac{}{! \Sigma, u \vdash u} \langle w \rangle
\end{array}$$

— case of rule $\langle \multimap \rangle$:

$$\begin{array}{c}
\frac{}{v \vdash v} \langle id \rangle \\
\frac{! \Sigma, \Gamma \vdash u \quad v \vdash v}{! \Sigma, \Gamma, u \multimap v \vdash v} \langle \multimap_L \rangle \\
\frac{}{!(u \multimap v) \vdash v} \langle !_L \rangle \\
\frac{! \Sigma, \Gamma, !(u \multimap v) \vdash v}{! \Sigma, \Gamma \vdash v} \langle c \rangle
\end{array}$$

— case of rule $\langle (\multimap) \multimap \rangle$:

$$\begin{array}{c}
\frac{! \Sigma, \Gamma, u \vdash v}{! \Sigma, \Gamma \vdash u \multimap v} \langle \multimap_R \rangle \quad \frac{}{w \vdash w} \langle id \rangle \\
\frac{}{!(u \multimap v) \multimap w \vdash w} \langle \multimap_L \rangle \\
\frac{}{!(u \multimap v) \multimap w \vdash w} \langle !_L \rangle \\
\frac{! \Sigma, \Gamma, !((u \multimap v) \multimap w) \vdash w}{! \Sigma, \Gamma \vdash w} \langle c \rangle
\end{array}$$

— if $\sigma_i = u \multimap (v \multimap w)$. We have $\pi \in \llbracket u \multimap (v \multimap w) \rrbracket$ iff $\llbracket u \rrbracket \star \llbracket v \rrbracket \subseteq \llbracket w \rrbracket$. Let us choose $[\Gamma] \in \llbracket u \rrbracket$ and $[\Delta] \in \llbracket v \rrbracket$ and let us prove $[\Gamma] \star [\Delta] \subseteq \llbracket w \rrbracket$. Both $!\Sigma, \Gamma \vdash u$ and $!\Sigma, \Delta \vdash v$ have a proof in **G-eILL**. By rule $\langle \multimap \multimap \rangle$, the sequent $!\Sigma, \Gamma, \Delta \vdash w$ has a proof in **G-eILL**. Thus $[\Gamma] \star [\Delta] = \{[\Gamma], [\Delta]\} \subseteq \llbracket w \rrbracket$. We deduce $\llbracket u \rrbracket \star \llbracket v \rrbracket \subseteq \llbracket w \rrbracket$ and thus conclude $\pi \in \llbracket \sigma_i \rrbracket$.

— if $\sigma_i = (u \& v) \multimap w$. We have $\pi \in \llbracket (u \& v) \multimap w \rrbracket$ iff $\llbracket u \rrbracket \cap \llbracket v \rrbracket \subseteq \llbracket w \rrbracket$. If $[\Gamma] \in \llbracket u \rrbracket \cap \llbracket v \rrbracket$ then both $!\Sigma, \Gamma \vdash u$ and $!\Sigma, \Gamma \vdash v$ have a proof in **G-eILL**. By rule $\langle (\&) \multimap \rangle$, the sequent $!\Sigma, \Gamma \vdash w$ has a proof in **G-eILL**. Thus $[\Gamma] \in \llbracket w \rrbracket$. We have proved that $\llbracket u \rrbracket \cap \llbracket v \rrbracket \subseteq \llbracket w \rrbracket$ and we conclude $\pi \in \llbracket \sigma_i \rrbracket$.

So, for any $i \in [1, k]$ the inclusion $\pi \in \llbracket \sigma_i \rrbracket$ holds and as a consequence, $\pi \in \llbracket !\sigma_i \rrbracket$ because the identity $\llbracket !\sigma_i \rrbracket = \{\pi\} \cap \llbracket \sigma_i \rrbracket$ holds in trivial phase semantics. Let us consider $\Gamma = \{a_1, \dots, a_p\}$ and suppose that the sequent $!\Sigma, \Gamma \vdash c$ of **eILL** is valid in every free monoidal trivial phase semantics interpretation. As a particular case, it is valid in the interpretation $(M, \star, \pi, \llbracket \cdot \rrbracket)$ and thus the inclusion

$$\llbracket !\sigma_1 \rrbracket \star \dots \star \llbracket !\sigma_k \rrbracket \star \llbracket a_1 \rrbracket \star \dots \star \llbracket a_p \rrbracket \subseteq \llbracket c \rrbracket$$

holds. By rule $\langle Ax \rangle$, for any $i \in [1, p]$ the sequent $!\Sigma, a_i \vdash a_i$ has a proof in **G-eILL** and thus the relation $[a_i] \in \llbracket a_i \rrbracket$ holds. Also remember that for any $i \in [1, k]$, we have $[\emptyset] = \pi \in \llbracket !\sigma_i \rrbracket$. So

$$[\Gamma] \in \{[a_1], \dots, [a_p]\} = [\emptyset] \star \dots \star [\emptyset] \star [a_1] \star \dots \star [a_p] \subseteq \llbracket c \rrbracket$$

holds and we conclude that $!\Sigma, \Gamma \vdash c$ has a proof in **G-eILL**. \square

T 4.4. *The system **G-eILL** is sound and complete for the fragment **eILL**. Given a class $X \in \{\text{ND}, \text{PD}, \text{TD}, \text{FM}\}$, the trivial phase semantics over the class X is sound and complete for the fragment **eILL**.*

P . Consider the following inclusion sequence

$$\text{eILL}_g \subseteq \text{eILL}_p \subseteq \text{eILL}_{\text{ND}}^t \subseteq \text{eILL}_{\text{PD}}^t \subseteq \text{eILL}_{\text{TD}}^t \subseteq \text{eILL}_{\text{FM}}^t \subseteq \text{eILL}_g$$

where eILL_g denotes the set of sequents of **eILL** which have a proof in **G-eILL** and eILL_X^t denotes the set of sequents which are valid in every trivial phase semantic interpretation of the class X . The inclusion $\text{eILL}_g \subseteq \text{eILL}_p$ is a direct consequence of Lemma 4.2. The inclusion $\text{eILL}_p \subseteq \text{eILL}_{\text{ND}}^t$ is a particular case of Theorem 3.3. The inclusion sequence $\text{eILL}_{\text{ND}}^t \subseteq \text{eILL}_{\text{PD}}^t \subseteq \text{eILL}_{\text{TD}}^t \subseteq \text{eILL}_{\text{FM}}^t$ is an obvious consequence of the inclusions $\text{FM} \subseteq \text{TD} \subseteq \text{PD} \subseteq \text{ND}$ between classes of non-deterministic monoids. The last inclusion $\text{eILL}_{\text{FM}}^t \subseteq \text{eILL}_g$ is the result of Lemma 4.3. \square

Remark: the problem of the completeness of the fragment **eILL** w.r.t. trivial heap semantics requires bisimulating free monoids with heap monoids and will be addressed in Section 7.2.

5. THE UNDECIDABILITY OF ELEMENTARY INTUITIONISTIC LINEAR LOGIC

We propose an encoding of two counter Minsky machines in the fragment **eILL** of **ILL**. The first encoding of Minsky machines in Linear Logic was done by Kanovich in the $(!, \oplus)$ -Horn fragment of **ILL** [Kanovich 1994; 1995]. In this encoding, the recovery of computations from proofs is obtained through some form of proof normalization and the \oplus additive connective is used to simulate forking. Lafont later showed that the use of proof normalization can be avoided and replaced by a phase semantics argument [Lafont 1996; Lafont and Scedrov 1996]. In our encoding of Minsky machines in **eILL**, the $\&$ connective is used to simulate forking and we will show that a trivial phase semantics argument is sufficient to recover computability from provability.

5.1. Two counter Minsky machines

Let a and b be two distinct counter symbols. A (deterministic) two counter Minsky machine is a pair $\mathfrak{M} = (l, \psi)$ where $l > 0$ is a strictly positive natural number of instructions and

$$\psi : [1, l] \longrightarrow \{+\} \times \{a, b\} \times [0, l] \mid \{-\} \times \{a, b\} \times [0, l] \times [0, l]$$

is a total map representing the *list of instructions*. Here, $|$ represents the (disjoint) set sum. Minsky machines instructions (incrementation, zero test/decrementation) are encoded as illustrated in the two following examples:

$$\begin{aligned}\psi(1) &= (+, a, 3) \iff 1: a := a + 1; \text{ goto } 3 \\ \psi(2) &= (-, b, 4, 5) \iff 2: \text{ if } b = 0 \text{ then goto } 4 \text{ else } b := b - 1; \text{ goto } 5\end{aligned}$$

Given a two counter Minsky machine $\mathfrak{M} = (l, \psi)$, we define the set $\mathcal{S}(\mathfrak{M})$ of *states* of the machine by $\mathcal{S}(\mathfrak{M}) = [0, l] \times \mathbb{N} \times \mathbb{N}$ which collects the current instruction and the values of the counters a and b . With the following notations:

$$\bar{a} = (1, 0) \quad \bar{b} = (0, 1) \quad (m, n)_a = m \quad (m, n)_b = n$$

we define a (binary) transition relation between states $\rightarrow_{\mathfrak{M}} \subseteq \mathcal{S}(\mathfrak{M}) \times \mathcal{S}(\mathfrak{M})$. For any two states (i, m, n) and (i', m', n') , the relation $(i, m, n) \rightarrow_{\mathfrak{M}} (i', m', n')$ holds if

$$\begin{aligned}\psi(i) &= (+, x, i') \text{ and } (m', n') = (m, n) + \bar{x} \\ \text{or } \psi(i) &= (-, x, i', k), (m, n)_x = 0 \text{ and } (m', n') = (m, n) \\ \text{or } \psi(i) &= (-, x, j, i'), (m, n)_x \neq 0 \text{ and } (m', n') + \bar{x} = (m, n)\end{aligned}$$

holds for some $x \in \{a, b\}$ and some $j, k \in [0, l]$. Notice that $(i, m, n) \rightarrow_{\mathfrak{M}} (i', m', n')$ does not hold if $i = 0$ because $\psi(0)$ is not defined. Let $\rightarrow_{\mathfrak{M}}^*$ be the reflexive and transitive closure of the relation $\rightarrow_{\mathfrak{M}}$. We say that the machine \mathfrak{M} *accepts* the input (m, n) if starting from the state $(1, m, n)$, there exists a sequence of transitions leading to the state $(0, 0, 0)$ and we define the set $A(\mathfrak{M})$ of accepted inputs:

$$A(\mathfrak{M}) = \{(m, n) \in \mathbb{N} \times \mathbb{N} \mid (1, m, n) \rightarrow_{\mathfrak{M}}^* (0, 0, 0)\}$$

T 5.1 (Minsky). *There exists a two counter Minsky machine \mathfrak{M} for which the set $A(\mathfrak{M})$ of accepted inputs is not recursive [Minsky 1961].*

5.2. The encoding of two counter Minsky machines

Let us consider the two counter symbols a and b as two (different) logical variables and let us choose two new variables \underline{a} and \underline{b} so that the set $\{a, b, \underline{a}, \underline{b}\} \subseteq \text{Var}$ has cardinal four. Let us choose an infinite set⁶ of new logical variables $\{q_i \mid i \in \mathbb{N}\}$ such that $q_i \neq q_j$ unless $i = j$ and $\{a, b, \underline{a}, \underline{b}\} \cap \{q_i \mid i \in \mathbb{N}\} = \emptyset$. Let Σ_0 be the following multiset composed of five $(\neg, \&)$ -elementary formulae:

$$\Sigma_0 = \{a \neg (\underline{a} \neg \underline{a}), b \neg (\underline{b} \neg \underline{b}), (a \neg a) \neg \underline{a}, (a \neg a) \neg \underline{b}, (a \neg a) \neg q_0\}$$

Given a Minsky machine $\mathfrak{M} = (l, \psi)$, for $i \in [1, l]$, we define the multisets $\Sigma_1, \dots, \Sigma_l$ of $(\neg, \&)$ -elementary formulae by:

$$\begin{aligned}\Sigma_i &= \{(x \neg q_j) \neg q_i\} && \text{when } \psi(i) = (+, x, j) \\ \text{and } \Sigma_i &= \{(\underline{x} \& q_j) \neg q_i, x \neg (q_k \neg q_i)\} && \text{when } \psi(i) = (-, x, j, k)\end{aligned}$$

Let $\Sigma_{\mathfrak{M}}$ be the multiset $\Sigma_{\mathfrak{M}} = \Sigma_0, \Sigma_1, \dots, \Sigma_l$. Given a natural number n and a logical variable $x \in \{a, b\}$, we define $x^n = x, x, \dots, x$ as the multiset composed of n occurrences of the variable x . Then, it is trivial to verify that for any natural numbers m, n and any $i \in [0, l]$, the sequent $! \Sigma_{\mathfrak{M}}, a^m, b^n \vdash q_i$ belongs to the fragment eILL.

Let us now consider a fixed Minsky machine $\mathfrak{M} = (l, \psi)$. Then we denote $\Sigma_{\mathfrak{M}}$ (resp. $\rightarrow_{\mathfrak{M}}$) simply by Σ (resp. \rightarrow). We prove four main intermediate results.

P 5.2. *For any $m, n \in \mathbb{N}$, the sequents $! \Sigma, a^m \vdash \underline{a}$ and $! \Sigma, b^n \vdash \underline{b}$ are provable in G-eILL.*

⁶For our particular purpose, we only need as many q_i 's as there are instructions in the Minsky machine obtained from Theorem 5.1.

$! \Sigma, b^n \vdash q_i$:

$$\frac{\frac{Q}{! \Sigma, b^n \vdash \underline{b}} \quad \frac{P}{! \Sigma, b^n \vdash q_{i'}}}{! \Sigma, b^n \vdash q_i} (\underline{b} \& q_{i'}) \multimap q_i \in \Sigma$$

— if $\psi(i) = (-, b, i', k)$, $m = m'$ and $n = n' = 0$. Let Q be a proof tree for $! \Sigma, a^m \vdash \underline{a}$ according to Proposition 5.2. Here is a proof tree for $! \Sigma, b^n \vdash q_i$:

$$\frac{\frac{Q}{! \Sigma, a^m \vdash \underline{a}} \quad \frac{P}{! \Sigma, a^m \vdash q_{i'}}}{! \Sigma, a^m \vdash q_i} (\underline{a} \& q_{i'}) \multimap q_i \in \Sigma$$

— if $\psi(i) = (-, a, j, i')$, $(m, n)_a \neq 0$ and $(m', n') + \bar{a} = (m, n)$. Then $m = m' + 1$ and $n = n'$. We provide the following proof tree for $! \Sigma, a, a^{m'}, b^{n'} \vdash q_i$:

$$\frac{\frac{}{! \Sigma, a \vdash a} \langle Ax \rangle \quad \frac{P}{! \Sigma, a^{m'}, b^{n'} \vdash q_{i'}}}{! \Sigma, a, a^{m'}, b^{n'} \vdash q_i} a \multimap (q_{i'} \multimap q_i) \in \Sigma$$

— if $\psi(i) = (-, b, j, i')$, $m' = m$ and $n' + 1 = n$. Here is a proof tree for $! \Sigma, a^{m'}, b, b^{n'} \vdash q_i$:

$$\frac{\frac{}{! \Sigma, b \vdash b} \langle Ax \rangle \quad \frac{P}{! \Sigma, a^{m'}, b^{n'} \vdash q_{i'}}}{! \Sigma, a^{m'}, b, b^{n'} \vdash q_i} b \multimap (q_{i'} \multimap q_i) \in \Sigma$$

In any case we obtain a proof tree for $! \Sigma, a^m, b^n \vdash q_i$ which fulfills the induction step. Again, but this is left to the reader, it can be demonstrated that the proof tree recursively build from the transition sequence $(i, m, n) \rightarrow^r (0, 0, 0)$ is the unique proof tree for the sequent $! \Sigma, a^m, b^n \vdash q_i$. \square

Let us now consider the following trivial phase semantics interpretation. Consider the product monoid $(\mathbb{N} \times \mathbb{N}, +, (0, 0))$. We define $x \circ y = \{x + y\}$ and thus $(\mathbb{N} \times \mathbb{N}, \circ, (0, 0))$ is a total deterministic monoid. Every subset of $\mathbb{N} \times \mathbb{N}$ is closed in trivial phase semantics and we define

$$\begin{aligned} \llbracket \underline{a} \rrbracket &= \{(1, 0) = \bar{a}\} & \llbracket \underline{a} \rrbracket &= \mathbb{N} \times \{0\} & \llbracket q_i \rrbracket &= \{(m, n) \in \mathbb{N} \times \mathbb{N} \mid (i, m, n) \rightarrow^* (0, 0, 0)\} \\ \llbracket \underline{b} \rrbracket &= \{(0, 1) = \bar{b}\} & \llbracket \underline{b} \rrbracket &= \{0\} \times \mathbb{N} \end{aligned}$$

It is crucial that variables $a, b, \underline{a}, \underline{b}, q_0, q_1, \dots, q_l$ were chosen distinct from one another for this definition to be valid. Let us now consider the trivial phase semantics interpretation of the compound formulae of Σ .

P 5.4. For any $\sigma \in \Sigma$, $\llbracket ! \sigma \rrbracket = \{(0, 0)\}$ holds.

P . As the identity $\llbracket ! \sigma \rrbracket = \{(0, 0)\} \cap \llbracket \sigma \rrbracket$ holds in trivial phase semantics, it is necessary and sufficient to prove that $(0, 0) \in \llbracket \sigma \rrbracket$ holds for any $\sigma \in \Sigma$.

First let us prove that $\llbracket a \multimap a \rrbracket = \{(0, 0)\}$. Indeed, $(m, n) \in \llbracket a \multimap a \rrbracket$ iff $(m, n) \circ \llbracket a \rrbracket \subseteq \llbracket a \rrbracket$ iff $(m, n) \circ \{(1, 0)\} \subseteq \{(1, 0)\}$ iff $\{(m + 1, n)\} \subseteq \{(1, 0)\}$ iff $(m, n) = (0, 0)$. Then $\llbracket (a \multimap a) \multimap x \rrbracket = \{(0, 0)\} \multimap \llbracket x \rrbracket = \llbracket x \rrbracket$ for any variable x , in particular for $x \in \{\underline{a}, \underline{b}, q_0\}$. Also $(m, n) \in \llbracket a \multimap (\underline{a} \multimap \underline{a}) \rrbracket$ iff $(m, n) \circ \{(1, 0)\} \circ \mathbb{N} \times \{0\} \subseteq \mathbb{N} \times \{0\}$ iff $n = 0$. Thus $\llbracket a \multimap (\underline{a} \multimap \underline{a}) \rrbracket = \mathbb{N} \times \{0\}$. By a similar argument, we get $\llbracket b \multimap (\underline{b} \multimap \underline{b}) \rrbracket = \{0\} \times \mathbb{N}$. So for any formula $\sigma \in \Sigma_0$, we have $(0, 0) \in \llbracket \sigma \rrbracket$.

Let us consider the formulae in Σ_i for $i \in [1, l]$. Let us prove that the relation $(0, 0) \in \llbracket \sigma \rrbracket$ holds for any $\sigma \in \Sigma_i$ by case analysis:

— if $\psi(i) = (+, x, j)$. Let us show $(0, 0) \in \llbracket (x \multimap q_j) \multimap q_i \rrbracket$, i.e. $\llbracket x \multimap q_j \rrbracket \subseteq \llbracket q_i \rrbracket$. Let us consider $(m, n) \in \llbracket x \multimap q_j \rrbracket$. Then $\{(m, n) + \bar{x}\} = \{(m, n)\} \circ \llbracket x \rrbracket \subseteq \llbracket q_j \rrbracket$ and thus $(m', n') = (m, n) + \bar{x} \in \llbracket q_j \rrbracket$. Thus we have $(i, m, n) \rightarrow (j, m', n') \rightarrow^* (0, 0, 0)$. We conclude $(m, n) \in \llbracket q_i \rrbracket$.

— if $\psi(i) = (-, x, j, k)$. Let us first show that $(0, 0) \in \llbracket (\underline{x} \& q_j) \multimap q_i \rrbracket$, i.e. $\llbracket \underline{x} \rrbracket \cap \llbracket q_j \rrbracket \subseteq \llbracket q_i \rrbracket$. Let us consider $(m, n) \in \llbracket \underline{x} \rrbracket \cap \llbracket q_j \rrbracket$. Then $(m, n)_x = 0$ and $(j, m, n) \rightarrow^* (0, 0, 0)$. Thus $(i, m, n) \rightarrow (j, m, n) \rightarrow^* (0, 0, 0)$ and $(m, n) \in \llbracket q_i \rrbracket$. Hence $\llbracket \underline{x} \rrbracket \cap \llbracket q_j \rrbracket \subseteq \llbracket q_i \rrbracket$ holds. Let us finally show that $(0, 0) \in \llbracket x \multimap (q_k \multimap q_i) \rrbracket$, i.e. $\llbracket x \rrbracket \circ \llbracket q_k \rrbracket \subseteq \llbracket q_i \rrbracket$. As $\llbracket x \rrbracket = \{\bar{x}\}$ for $x \in \{a, b\}$, let us choose an arbitrary pair $(m', n') \in \llbracket q_k \rrbracket$ and define $(m, n) = \bar{x} + (m', n')$. Then $(m, n)_x = 1 + (m', n')_x \neq 0$ and $(i, m, n) \rightarrow (k, m', n') \rightarrow^* (0, 0, 0)$. We obtain $(m, n) \in \llbracket q_i \rrbracket$ and thus conclude $\bar{x} + (m', n') \in \llbracket q_i \rrbracket$. Hence, for any $(m', n') \in \llbracket q_k \rrbracket$ we get $\llbracket x \rrbracket \circ (m', n') \subseteq \llbracket q_i \rrbracket$. Thus $\llbracket x \rrbracket \circ \llbracket q_k \rrbracket \subseteq \llbracket q_i \rrbracket$ holds.

As a consequence, for any $\sigma \in \Sigma$, we obtain $(0, 0) \in \llbracket \sigma \rrbracket$. The identity $\llbracket !\sigma \rrbracket = \{(0, 0)\}$ holds for any $\sigma \in \Sigma$. \square

L 5.5. For any $m, n \in \mathbb{N}$, if $!\Sigma, a^m, b^n \vdash q_1$ is provable in **G-eILL** then $(m, n) \in A(\mathfrak{M})$ holds.

P. Let $\Sigma = \{\sigma_1, \dots, \sigma_r\}$. We suppose that the sequent $!\Sigma, a^m, b^n \vdash q_1$ has a proof in **G-eILL**. By the soundness part of Theorem 4.4, in our particular total deterministic trivial phase semantics interpretation, we have

$$\llbracket !\sigma_1 \rrbracket \circ \dots \circ \llbracket !\sigma_r \rrbracket \circ \llbracket a \rrbracket \circ \dots \circ \llbracket a \rrbracket \circ \llbracket b \rrbracket \circ \dots \circ \llbracket b \rrbracket \subseteq \llbracket q_1 \rrbracket$$

where a occurs m times and b occurs n times. By Proposition 5.4, we deduce $(m, n) = r.(0, 0) + m.(1, 0) + n.(0, 1) \in \llbracket q_1 \rrbracket$ and thus $(1, m, n) \rightarrow^* (0, 0, 0)$ holds. \square

From Lemma 5.3 and Lemma 5.5, we obtain as a direct consequence the following theorem which characterizes Minsky machine acceptance in terms of provability in **G-eILL**.

T 5.6. For any two counter Minsky machine \mathfrak{M} and for any pair $m, n \in \mathbb{N}$, we have $(m, n) \in A(\mathfrak{M})$ if and only if the sequent $!\Sigma_{\mathfrak{M}}, a^m, b^n \vdash q_1$ is provable in **G-eILL**.

We point out that the form $(\&)\multimap$ is used here to encode *forking* in a way similar Kanovich does with \oplus (see [Kanovich 1995]). The reader may have noticed that more than the simple encoding of computability with provability, we can even show that computations and proofs match one to one. Even though this result is not necessary to our argumentation, this suggests that the system **G-eILL** is a natural choice to illustrate the relations between Minsky machines and linear logic, and may be more straightforward than the $(!, \oplus)$ -Horn fragment [Kanovich 1995].

5.3. The undecidability of eILL

Whereas the decidability of **s-IMELL**₀^o is still unclear (but nevertheless known to be equivalent to the decidability of **MELL** [de Groote et al. 2004]), we have proved that the simple addition of the form $(\&)\multimap$ to **s-IMELL**₀^o is sufficient to encode forking and thus, computations of Minsky machines.

T 5.7. Validity is undecidable in the elementary fragment of **ILL**.

P. By Theorem 5.1, let \mathfrak{M} be a two counter Minsky machine such that $A(\mathfrak{M})$ is not recursive. Compute $\Sigma_{\mathfrak{M}}$. If there is an algorithm that discriminates between provable and unprovable sequents of **eILL**, use it to decide

$$A(\mathfrak{M}) = \{(m, n) \in \mathbb{N} \times \mathbb{N} \mid !\Sigma, a^m, b^n \vdash q_1 \text{ is provable in G-eILL}\}$$

This identity is a direct consequence of Theorem 5.6. Thus $A(\mathfrak{M})$ would be recursive. We obtain a contradiction. \square

We point out that the model through which the faithfulness of the encoding is obtained (see Lemma 5.5) is based on the free monoid $\mathbb{N} \times \mathbb{N}$. So let us denote by **eILL** _{$\mathbb{N} \times \mathbb{N}$} ^t the set of sequents which are valid in every trivial phase semantic interpretation over the free monoid $(\mathbb{N} \times \mathbb{N}, +, (0, 0))$. We obtain the following stronger theorem:

T 5.8. *Let X be a set of sequents in-between eILL_p and $\text{eILL}_{\mathbb{N} \times \mathbb{N}}^t$, i.e. which satisfies $\text{eILL}_p \subseteq X \subseteq \text{eILL}_{\mathbb{N} \times \mathbb{N}}^t$. Then the set X is not a recursive set of sequents.*

P . It is sufficient to prove the following equivalence:

$$(m, n) \in A(\mathfrak{M}) \quad \text{iff} \quad !\Sigma, a^m, b^n \vdash q_1 \text{ belongs to } X$$

For the *if part*, if $!\Sigma, a^m, b^n \vdash q_1$ belongs to X then, it belongs to $\text{eILL}_{\mathbb{N} \times \mathbb{N}}^t$ and hence, using the *same proof* as in Lemma 5.5, we deduce that $(m, n) \in A(\mathfrak{M})$. For the *only if part*, if $(m, n) \in A(\mathfrak{M})$, then by Lemma 5.3, we obtain that $!\Sigma, a^m, b^n \vdash q_1$ is provable in G-eILL . Thus, by definition, it belongs to eILL_p , and as a consequence, the sequent $!\Sigma, a^m, b^n \vdash q_1$ belongs to X . \square

Remark: we leave the question of the strictness of the inclusion $\text{eILL}_p \subseteq \text{eILL}_{\mathbb{N} \times \mathbb{N}}^t$ as a remaining open problem.

6. THE SEMANTICS OF BOOLEAN BI

Boolean BI (denoted **BBI**) is the variant of intuitionistic BI [O’Hearn and Pym 1999] where the additive connectives are interpreted as Boolean connectives, contrary to (intuitionistic) BI where the additive connectives are interpreted as in propositional intuitionistic logic. The linear connectives are both interpreted as those of multiplicative intuitionistic linear logic, i.e. the multiplicative fragment of ILL. When the connectives of **BBI** are given a Kripke semantics (see Section 6.1) and the model belongs to the class of heap monoids HM , then we recover the core logic behind Separation Logic [Ishtiaq and O’Hearn 2001].

The syntax of **BBI** is exactly the syntax of BI augmented with negation, although negation could be defined by $\neg A = A \rightarrow \perp$ like in classical logic. Thus, the formulae of **BBI** are defined as follows. Starting from a set Var , they are freely built using the *logical variables* in Var , the *logical constants* in $\{\perp, \top, \perp\}$, the unary connective \neg or the binary connectives in $\{*, \multimap, \wedge, \vee, \rightarrow\}$. Formally, the set of formulae is described by the following grammar:

$$A ::= v \mid c \mid \neg A \mid A \boxtimes A \quad \text{with } v \in \text{Var}, c \in \{\perp, \top, \perp\} \text{ and } \boxtimes \in \{*, \multimap, \wedge, \vee, \rightarrow\}$$

Validity in **BBI** has not always been unequivocally defined. Indeed, the initial proposition of Pym [Pym 2002] was simply to add a double negation principle to the cut-free bunched proof system of BI. But of course, this does not lead to a proof-theoretically well behaved proof-system for **BBI**: it does not enjoy cut-elimination, sub-formula property, etc. Then, the syntax of **BBI** has been used as a foundation for numerous variants of Separation Logic with the common property that the additive operator \rightarrow is interpreted classically whereas it is interpreted intuitionistically in BI [Ishtiaq and O’Hearn 2001; Calcagno et al. 2005]. The removal of the pre-order in the Kripke semantics is moreover necessary for the interpretation of classical negation \neg .

6.1. Kripke Semantics for BBI

In this paper, we choose to present **BBI** as a family of logics defined by their Kripke semantics rather than proof-systems. Given a non-deterministic monoid (M, \circ, ϵ) and an interpretation of propositional variables $\delta : \text{Var} \rightarrow \mathbb{P}(M)$, we define the Kripke forcing relation \Vdash_δ by induction on the structure of formulae:

$$\begin{array}{ll} m \Vdash_\delta \perp & \text{iff never} & m \Vdash_\delta A \vee B & \text{iff } m \Vdash_\delta A \text{ or } m \Vdash_\delta B \\ m \Vdash_\delta \top & \text{iff always} & m \Vdash_\delta A \wedge B & \text{iff } m \Vdash_\delta A \text{ and } m \Vdash_\delta B \\ m \Vdash_\delta \neg A & \text{iff } m \not\Vdash_\delta A & m \Vdash_\delta A \rightarrow B & \text{iff } m \not\Vdash_\delta A \text{ or } m \Vdash_\delta B \\ m \Vdash_\delta \mid & \text{iff } m = \epsilon & m \Vdash_\delta A * B & \text{iff } \exists a, b, m \in a \circ b \text{ and } a \Vdash_\delta A \text{ and } b \Vdash_\delta B \\ m \Vdash_\delta \nu & \text{iff } m \in \delta(\nu) & m \Vdash_\delta A \multimap B & \text{iff } \forall a, b (b \in a \circ m \text{ and } a \Vdash_\delta A) \Rightarrow b \Vdash_\delta B \end{array}$$

Definition 6.1. A formula F is *valid* in a non-deterministic monoid (M, \circ, ϵ) if for any interpretation $\delta : \text{Var} \rightarrow \mathbb{P}(M)$ of propositional variables, the relation $m \Vdash_\delta F$ holds for any $m \in M$. A *counter-model* of the formula F is given by a non-deterministic monoid (M, \circ, ϵ) , an interpretation $\delta : \text{Var} \rightarrow \mathbb{P}(M)$ and an element $m \in M$ such that $m \not\Vdash_\delta F$.

When the interpretation of variables is obvious from the context, we may simply omit the δ subscript and write \Vdash instead of \Vdash_δ . In some papers, you might find **BBI** defined by non-deterministic monoidal Kripke semantics [Brotherston 2010; Galmiche and Larchey-Wendling 2006], in other papers it is defined by partial but deterministic monoidal Kripke semantics and generally Separation Logic models are particular instances of partial (deterministic) monoids. See [Larchey-Wendling and Galmiche 2009] for a general discussion about these issues.

Definition 6.2. We denote by \mathbf{BBI}_X the set of formulae of **BBI** which are valid in every monoid of the class X . The class X ranges over $\{\text{ND}, \text{PD}, \text{TD}, \text{HM}, \text{FM}\}$.

On the proof-theoretic side, we briefly recall that \mathbf{BBI}_{ND} has been proved sound and complete w.r.t. a Hilbert proof-system [Galmiche and Larchey-Wendling 2006] and also, more recently w.r.t. a Display Logic based proof-system [Brotherston 2010] enjoying cut-elimination. \mathbf{BBI}_{PD} can be proved sound and complete w.r.t. the semantic constraints based tableaux proof-system presented in [Larchey-Wendling and Galmiche 2009] (although only the soundness proof is presented in that particular paper) and the adaptation of this tableaux system to \mathbf{BBI}_{TD} should be straightforward (contrary to \mathbf{BBI}_{ND}).

As it turns out, the three different classes of models ND, PD and TD define three different logics, i.e. universally valid formulae differ from one class of models to another. The relation of *strict inclusion* between \mathbf{BBI}_{ND} and \mathbf{BBI}_{PD} was, to our knowledge, an undecided proposition.

T 6.3. $\mathbf{BBI}_{\text{ND}} \subsetneq \mathbf{BBI}_{\text{PD}} \subsetneq \mathbf{BBI}_{\text{TD}}$

P . The following inclusion relations $\text{TD} \subseteq \text{PD} \subseteq \text{ND}$ hold between the classes of models which respectively define those three logics. Hence, only the strictness of the inclusion of validities is not obvious. This strictness is established by upcoming Theorem 6.4 and Proposition 6.5. \square

Consider the formula $I = \neg(\top \multimap \neg \text{I})$ and a non-deterministic monoid (M, \circ, ϵ) . Since I does not contain any variable, its Kripke interpretation does not depend on the choice of δ . One can check that for any $x \in M$, $x \Vdash I$ iff there exists $x' \in M$ s.t. $\epsilon \in x \circ x'$. So I expresses “invertibility” in Kripke semantics. The formula $(I * I) \rightarrow I$ expresses stability of invertibility by monoidal composition.

T 6.4. *With $I = \neg(\top \multimap \neg \text{I})$, the formula $(I * I) \rightarrow I$ is valid in every partial deterministic monoid. There exists a non-deterministic monoid which is a counter-model to $(I * I) \rightarrow I$.*

P . First the counter-model. Consider the non-deterministic monoid $(\{\epsilon, x, y\}, \circ, \epsilon)$ uniquely defined by $x \circ x = \{\epsilon, y\}$, $y \circ \alpha = \{y\}$ for any $\alpha \in \{\epsilon, x, y\}$ and the axioms 1 & 2 of Definition 2.1.⁷ Then $x \Vdash I$ because there exists α ($\alpha = x$) such that $\epsilon \in x \circ \alpha$. On the other hand, $y \not\Vdash I$ because there is no α such that $\epsilon \in y \circ \alpha$ holds. So, as $y \in x \circ x$, we have $y \Vdash I * I$. Thus $y \not\Vdash (I * I) \rightarrow I$.

Now let us prove that $(I * I) \rightarrow I$ is valid in every partial deterministic monoid. Let (M, \circ, ϵ) be a partial deterministic monoid. Let us choose $a \in M$ and let us prove that $a \Vdash (I * I) \rightarrow I$. So we suppose $a \Vdash I * I$ holds and we have to prove $a \Vdash I$. As $a \Vdash I * I$, there exist $b, c \in M$ such that $a \in b \circ c$, $b \Vdash I$ and $c \Vdash I$. Thus there exist $b', c' \in M$ such that $\epsilon \in b \circ b'$ and $\epsilon \in c \circ c'$. As M is (partial) deterministic, we have $b \circ b' = \{\epsilon\}$, $c \circ c' = \{\epsilon\}$ and $b \circ c = \{a\}$. Thus we have $(b \circ b') \circ (c \circ c') = \{\epsilon\} \circ \{\epsilon\} = \{\epsilon\}$.

If $b' \circ c' = \emptyset$ then we would have $(b \circ c) \circ (b' \circ c') = \{a\} \circ \emptyset = \emptyset$ but also $(b \circ b') \circ (c \circ c') = \{\epsilon\}$ and thus $\emptyset = \{\epsilon\}$ by associativity/commutativity, which is absurd. Thus $b' \circ c' = \{a'\}$ and we obtain $(b \circ c) \circ (b' \circ c') = \{a\} \circ \{a'\} = a \circ a'$ and then $a \circ a' = \{\epsilon\}$ by associativity/commutativity. Hence, $\epsilon \in a \circ a'$ and $a \Vdash I$. \square

The formula $(\neg \text{I} \multimap \perp) \rightarrow \text{I}$ is inspired from the example given to establish the incompleteness of (total) monoidal Kripke semantics w.r.t. (intuitionistic) BI (see [Pym 2002] page 63).

⁷This non-deterministic monoid was presented in Section 2.2 as a witness that the class ND is strictly larger than PD.

P 6.5. *The formula $(\neg \vdash * \perp) \rightarrow \top$ is valid in every total deterministic monoid. There exists a partial deterministic monoid which is a counter-model to $(\neg \vdash * \perp) \rightarrow \top$.*

P . First the counter-model. Consider the following partial deterministic monoid $(\{\epsilon, \mathbf{x}\}, \circ, \epsilon)$ where $\mathbf{x} \circ \mathbf{x} = \emptyset$ and $\epsilon \circ \alpha = \alpha \circ \epsilon = \{\alpha\}$ for any $\alpha \in \{\epsilon, \mathbf{x}\}$. Then $\mathbf{x} \neq \epsilon$ and thus $\mathbf{x} \not\vdash \top$. Let us prove that $\mathbf{x} \Vdash \neg \vdash * \perp$. Let a, b such that $b \in \mathbf{x} \circ a$ and $a \Vdash \neg$. Then $a \neq \epsilon$ and thus $a = \mathbf{x}$. Then $\mathbf{x} \circ a = \mathbf{x} \circ \mathbf{x} = \emptyset$. We get a contradiction with $b \in \mathbf{x} \circ a$. From this contradiction, we deduce $b \Vdash \perp$. Hence, $\mathbf{x} \Vdash \neg \vdash * \perp$ and we conclude $\mathbf{x} \not\vdash (\neg \vdash * \perp) \rightarrow \top$ and we have the counter-model.

Now let us prove that $(\neg \vdash * \perp) \rightarrow \top$ is valid in every total deterministic monoid. Let (M, \circ, ϵ) be a total deterministic monoid. Let us choose $a \in M$. There are two cases. Either $a = \epsilon$ or $a \neq \epsilon$. In the case $a = \epsilon$, we obviously have $a \Vdash (\neg \vdash * \perp) \rightarrow \top$. In the case $a \neq \epsilon$, let us prove $a \not\vdash \neg \vdash * \perp$. Suppose $a \Vdash \neg \vdash * \perp$. As $a \neq \epsilon$ we have $a \Vdash \neg$. Also $a \circ a$ is not empty because \circ is total. Let $b \in a \circ a$. As $a \Vdash \neg \vdash * \perp$, $b \in a \circ a$ and $a \Vdash \neg$, we must have $b \Vdash \perp$ which is impossible. Hence $a \not\vdash \neg \vdash * \perp$ and we conclude that $a \Vdash (\neg \vdash * \perp) \rightarrow \top$ holds also in the case $a \neq \epsilon$. \square

Remark: we point out the inclusion sequences $\text{ILL}_{\text{ND}}^t \subseteq \text{ILL}_{\text{PD}}^t \subseteq \text{ILL}_{\text{TD}}^t$ as a remaining open question where ILL_X^t is defined by trivial phase semantics with the monoid belonging to the class $X \in \{\text{ND}, \text{PD}, \text{TD}\}$. The question is of course: *are these two inclusions strict?* We remark that the counter-examples of Theorem 6.4 and Proposition 6.5 cannot be used as is because both formulae contain a negation.

6.2. Heap models vs. free monoidal models of BBI

In this section, we briefly explain how free monoidal models are less general than heap model, at least with respect to BBI. The core of the argument is based on the bisimulation of multisets by heaps, a technique that was already (implicitly) used in [Brotherston and Kanovich 2010]. In Appendix C, we explicitly show how the bisimulation argument works.

L 6.6. *Let X be a set. There exists a heap monoid $\mathbb{H}_{L,V}$ of class HM and a surjective map $\varphi : \mathbb{H}_{L,V} \rightarrow \mathbb{M}_f(X)$ such that for any Kripke interpretation $\delta : \text{Var} \rightarrow \mathbb{P}(\mathbb{M}_f(X))$ in the free monoid $(\mathbb{M}_f(X), \star, \pi)$, the Kripke interpretation $\delta' : \text{Var} \rightarrow \mathbb{P}(\mathbb{H}_{L,V})$ in the heap monoid $(\mathbb{H}_{L,V}, \boxplus, \emptyset)$ defined by $\delta' = v \mapsto \varphi^{-1}(\delta(v))$ satisfies the following property:*

$$h \Vdash_{\delta'} F \text{ if and only if } \varphi(h) \Vdash_{\delta} F \quad \text{for any } F \in \text{BBI}$$

P . The proof of this technical lemma is postponed in Appendix C. \square

T 6.7. *The inclusion $\text{BBI}_{\text{HM}} \subseteq \text{BBI}_{\text{FM}}$ holds. Validity in heap monoids is stronger than validity in free monoids.*

P . Let $F \in \text{BBI}_{\text{HM}}$ be a BBI-formula which is valid in every heap model. Then let $(\mathbb{M}_f(X), \star, \pi, \delta)$ be a Kripke interpretation in a model of class FM. Let us consider $m \in \mathbb{M}_f(X)$ and let us show that $m \Vdash_{\delta} F$ holds. Let us consider $\mathbb{H}_{L,V}$ and $\varphi : \mathbb{H}_{L,V} \rightarrow \mathbb{M}_f(X)$ as obtained from Lemma 6.6. Since φ is surjective, let us pick an $h \in \mathbb{H}_{L,V}$ such that $\varphi(h) = m$. Since $F \in \text{BBI}_{\text{HM}}$ and $(\mathbb{H}_{L,V}, \boxplus, \emptyset, \delta')$ is a Kripke model of class HM, we deduce $h \Vdash_{\delta'} F$. By Lemma 6.6, we conclude $m = \varphi(h) \Vdash_{\delta} F$. Thus F belongs to BBI_{FM} . \square

Let us consider two particular models of BBI. First, the simplest heap model $(\mathbb{H}_{\mathbb{N},\{\star\}}, \boxplus, \emptyset)$ which is isomorphic to the partial monoid of finite subsets of \mathbb{N} , i.e. the partial deterministic monoid $(\mathbb{P}_f(\mathbb{N}), \boxplus, \emptyset)$. Then the free monoid over two elements which is isomorphic to the total deterministic monoid $(\mathbb{N} \times \mathbb{N}, +, (0, 0))$. We denote by $\text{BBI}_{\mathbb{P}_f(\mathbb{N})}$ (resp. $\text{BBI}_{\mathbb{N} \times \mathbb{N}}$) the set of BBI formulae which are valid in every Kripke interpretation over the heap model $(\mathbb{P}_f(\mathbb{N}), \boxplus, \emptyset)$ (resp. free monoid $(\mathbb{N} \times \mathbb{N}, +, (0, 0))$). Then we obtain the following result:

T 6.8. *The inclusion $\text{BBI}_{\mathbb{P}_f(\mathbb{N})} \subseteq \text{BBI}_{\mathbb{N} \times \mathbb{N}}$ holds.*

P . The proof is postponed in Appendix C. It is mainly a particular instance of the proofs of Lemma 6.6 and Theorem 6.7. \square

Remark: the strictness of the inclusion $\text{BBI}_{\mathbb{P}_f(\mathbb{N})} \subseteq \text{BBI}_{\mathbb{N} \times \mathbb{N}}$ remains an open question.

7. THE UNDECIDABILITY OF BOOLEAN BI

Having defined the Kripke semantics of BBI within the framework of non-deterministic monoids, let us explore its relations with non-deterministic trivial phase semantics for ILL.

7.1. Trivial Phase vs. Kripke Semantics

Let us compare the trivial phase semantic interpretation of ILL connectives and the Kripke interpretation of BBI connectives. Given a non-deterministic monoid $\mathcal{M} = (M, \circ, \epsilon)$, a trivial phase semantic interpretation $\llbracket \cdot \rrbracket^t : \text{Var} \mapsto \mathcal{M}^\circ$ and an interpretation of variable in Kripke semantics $\delta : \text{Var} \mapsto \mathbb{P}(M)$, we compare the trivial phase semantic interpretation of ILL-formulae and the Kripke interpretation of BBI-formulae. Recall that in trivial phase semantics all subsets of M are closed and thus $\mathcal{M}^\circ = \mathbb{P}(M)$. To better compare the two semantics, we use the notation

$$\llbracket F \rrbracket^k = \{m \mid m \Vdash F\}$$

Then, using the equations defining Kripke semantics (see Section 6.1), we easily obtain the following correspondance between the interpretations of ILL and BBI connectives:

$$\begin{array}{ll|ll} \llbracket \perp \rrbracket^t = \emptyset & \llbracket \perp \rrbracket^k = \emptyset & \llbracket !A \rrbracket^t = \{\epsilon\} \cap \llbracket A \rrbracket^t & \llbracket !A \rrbracket^k = \{\epsilon\} \cap \llbracket A \rrbracket^k \\ \llbracket \top \rrbracket^t = M & \llbracket \top \rrbracket^k = M & \llbracket A \oplus B \rrbracket^t = \llbracket A \rrbracket^t \cup \llbracket B \rrbracket^t & \llbracket A \vee B \rrbracket^k = \llbracket A \rrbracket^k \cup \llbracket B \rrbracket^k \\ \llbracket 1 \rrbracket^t = \{\epsilon\} & \llbracket 1 \rrbracket^k = \{\epsilon\} & \llbracket A \& B \rrbracket^t = \llbracket A \rrbracket^t \cap \llbracket B \rrbracket^t & \llbracket A \wedge B \rrbracket^k = \llbracket A \rrbracket^k \cap \llbracket B \rrbracket^k \\ & & \llbracket A \otimes B \rrbracket^t = \llbracket A \rrbracket^t \circ \llbracket B \rrbracket^t & \llbracket A * B \rrbracket^k = \llbracket A \rrbracket^k \circ \llbracket B \rrbracket^k \\ & & \llbracket A \multimap B \rrbracket^t = \llbracket A \rrbracket^t \multimap \llbracket B \rrbracket^t & \llbracket A \multimap B \rrbracket^k = \llbracket A \rrbracket^k \multimap \llbracket B \rrbracket^k \end{array}$$

Thus, there is an obvious embedding of the connectives of ILL into BBI, which can be formalized with the following inductively defined map $(\cdot)^\circ : \text{ILL} \rightarrow \text{BBI}$:

$$\begin{array}{ll} v^\circ = v & \text{for } v \in \text{Var} \\ \perp^\circ = \perp & (A \oplus B)^\circ = A^\circ \vee B^\circ \\ \top^\circ = \top & (A \& B)^\circ = A^\circ \wedge B^\circ \\ 1^\circ = 1 & (A \otimes B)^\circ = A^\circ * B^\circ \\ (!A)^\circ = ! \wedge A^\circ & (A \multimap B)^\circ = A^\circ \multimap B^\circ \end{array}$$

L 7.1. *If the trivial phase semantics interpretation $\llbracket \cdot \rrbracket^t : \text{Var} \rightarrow \mathcal{M}^\circ$ and the Kripke interpretation $\delta : \text{Var} \rightarrow \mathbb{P}(M)$ are identical maps then the trivial phase semantics and the Kripke semantics are in the following relation:*

$$\forall F \in \text{ILL}, \forall m \in M, m \in \llbracket F \rrbracket \text{ iff } m \Vdash F^\circ \quad (3)$$

P. Using the previous notations $\llbracket \cdot \rrbracket^t$ and $\llbracket \cdot \rrbracket^k$, we show that $\llbracket F \rrbracket^t = \llbracket F^\circ \rrbracket^k$ by induction on the structure of F . We consider the case $F = A \otimes B$ as a typical example. Using the inductions hypotheses $\llbracket A \rrbracket^t = \llbracket A^\circ \rrbracket^k$ and $\llbracket B \rrbracket^t = \llbracket B^\circ \rrbracket^k$, we compute $\llbracket A \otimes B \rrbracket^t = \llbracket A \rrbracket^t \circ \llbracket B \rrbracket^t = \llbracket A^\circ \rrbracket^k \circ \llbracket B^\circ \rrbracket^k = \llbracket A^\circ * B^\circ \rrbracket^k = \llbracket (A \otimes B)^\circ \rrbracket^k$. \square

So if the interpretation of logical variables coincide, trivial phase semantics and Kripke semantics correspond to each other through the map $(\cdot)^\circ$. Given a sequence A_1, \dots, A_k of formulae of ILL, we define $(A_1, \dots, A_k)^\circ$ by structural induction:

$$()^\circ = 1 \quad (A_1, \dots, A_{k+1})^\circ = A_1^\circ * (A_2, \dots, A_{k+1})^\circ$$

When $\llbracket \cdot \rrbracket$ and δ are identical maps on propositional variables, it is then straightforward to prove this equivalence by induction on k :

$$m \in \llbracket A_1 \rrbracket \circ \dots \circ \llbracket A_k \rrbracket \text{ iff } m \Vdash (A_1, \dots, A_k)^\circ \quad (4)$$

7.2. Faithfully embedding (trivial) ILL into BBI

We define a reverse map from multisets of formulae of ILL into lists of formulae by choosing an arbitrary *decidable total order* among the formulae of ILL (e.g. lexicographic ordering). For any multiset Γ of formulae of ILL, there exists a unique and computable ordered sequence of formulae A_1, \dots, A_k such that $\Gamma = \{A_1, \dots, A_k\}$ and we define $\Gamma^\circledast = (A_1, \dots, A_k)^\circledast$.

P 7.2. *The function $(\cdot)^\circledast : \text{ILL} \rightarrow \text{BBI}$ mapping the ILL-sequent $\Gamma \vdash C$ to the BBI-formula $\Gamma^\circledast \rightarrow C^\circledast$ is a computable map from sequents of ILL to formulae of BBI.*

P . The only thing to prove here is that the map is computable and this is done using any sorting algorithm based on the decidable total order previously chosen. \square

P 7.3. *Let $\mathcal{M} = (\mathcal{M}, \circ, \epsilon)$ be a non-deterministic monoid. Let $\Gamma \vdash C$ be a sequent of ILL. Then the sequent $\Gamma \vdash C$ is valid in every trivial phase semantics interpretation based on \mathcal{M} if and on if the formula $\Gamma^\circledast \rightarrow C^\circledast$ is valid in every Kripke interpretation based on \mathcal{M} .*

P . Let us pick the ordered sequence A_1, \dots, A_k such that the identity $\Gamma = [A_1, \dots, A_k]$ holds as a multiset equation. Let us first suppose that $A_1, \dots, A_k \vdash C$ is valid in every trivial phase semantics interpretation based on \mathcal{M} . Let $\delta : \text{Var} \rightarrow \mathbb{P}(\mathcal{M})$ be a Kripke interpretation of variables in the model \mathcal{M} . We choose the trivial phase semantics interpretation $[[\cdot]] : \text{Var} \rightarrow \mathbb{P}(\mathcal{M})$ defined by $[[v]] = \delta(v)$ for any variable $v \in \text{Var}$. By hypothesis, $A_1, \dots, A_k \vdash C$ is valid in the interpretation $[[\cdot]]$ and we deduce $[[A_1]] \circ \dots \circ [[A_k]] \subseteq [[C]]$. Then, by Equations (3) and (4), for any $m \in \mathcal{M}$ we have $m \Vdash (A_1, \dots, A_k)^\circledast \rightarrow C^\circledast$. Thus the formula $(A_1, \dots, A_k)^\circledast \rightarrow C^\circledast$ is valid in the model $(\mathcal{M}, \circ, \epsilon, \delta)$.

Now, let us suppose that $(A_1, \dots, A_k)^\circledast \rightarrow C^\circledast$ is valid in every Kripke interpretation based on \mathcal{M} . Let $[[\cdot]] : \text{Var} \rightarrow \mathbb{P}(\mathcal{M})$ be a trivial phase semantic interpretation of variables in the model \mathcal{M} . We choose the Kripke interpretation $\delta : \text{Var} \rightarrow \mathbb{P}(\mathcal{M})$ defined by $\delta(v) = [[v]]$ for any variable $v \in \text{Var}$. By hypothesis, the formula $(A_1, \dots, A_k)^\circledast \rightarrow C^\circledast$ is valid in the interpretation δ and we deduce that for any $m \in \mathcal{M}$ we have $m \Vdash (A_1, \dots, A_k)^\circledast \rightarrow C^\circledast$. As a consequence of Equations (3) and (4), we obtain $[[A_1]] \circ \dots \circ [[A_k]] \subseteq [[C]]$. Hence, the sequent $A_1, \dots, A_k \vdash C$ is valid in the trivial phase model $(\mathcal{M}, \circ, \epsilon, [[\cdot]])$. \square

T 7.4 (E). *Let $X \in \{\text{ND}, \text{PD}, \text{TD}, \text{HM}, \text{FM}\}$ be a class of non-deterministic monoids. For any sequent $\Gamma \vdash C$ of ILL, the following equivalence holds:*

$$\Gamma \vdash C \in \text{ILL}_X^t \quad \text{if and only if} \quad \Gamma^\circledast \rightarrow C^\circledast \in \text{BBI}_X$$

P . Obvious consequence of Proposition 7.3. \square

T 7.5. *Trivial phase semantics restricted to heap models is complete for eILL.*

P . Consider the inclusion sequence $\text{eILL}_g = \text{eILL}_{\text{PD}}^t \subseteq \text{eILL}_{\text{HM}}^t \subseteq \text{eILL}_{\text{FM}}^t = \text{eILL}_g$. Using Theorem 4.4, the only inclusions left to be proved are $\text{eILL}_{\text{PD}}^t \subseteq \text{eILL}_{\text{HM}}^t$ and $\text{eILL}_{\text{HM}}^t \subseteq \text{eILL}_{\text{FM}}^t$. The first one is obvious because $\text{HM} \subseteq \text{PD}$ as classes of non-deterministic monoids. We prove the second inclusion. Let $\Gamma \vdash C$ be a sequent of eILL. We suppose $\Gamma \vdash C$ belongs to $\text{eILL}_{\text{HM}}^t$. Thus, it also belongs to ILL_{HM}^t . Then, by Theorem 7.4, we have $\Gamma^\circledast \rightarrow C^\circledast \in \text{BBI}_{\text{HM}}$. Thus by Theorem 6.7, we obtain $\Gamma^\circledast \rightarrow C^\circledast \in \text{BBI}_{\text{FM}}$. Thus by Theorem 7.4 again, we obtain $\Gamma \vdash C \in \text{ILL}_{\text{FM}}^t$. Since $\Gamma \vdash C$ is an elementary sequent, we conclude $\Gamma \vdash C \in \text{eILL}_{\text{FM}}^t$. \square

7.3. The Undecidability Results

From the preceding developments, we establish the undecidability of BBI w.r.t. Kripke semantics in any class belonging to $\{\text{ND}, \text{PD}, \text{TD}, \text{HM}, \text{FM}\}$. Indeed, we have a faithful embedding from trivial ILL into BBI. But trivial ILL contains eILL as a complete and undecidable fragment. Thus the embedding transfers the undecidability to BBI.

T 7.6 (U BBI). *For any class $X \in \{\text{ND}, \text{PD}, \text{TD}, \text{HM}, \text{FM}\}$, the set of (universally valid) formulae BBI_X is not recursive.*

P . Suppose that there is an algorithm which decides membership in BBI_X . We propose the following algorithm which would then decide validity in the fragment eILL .

For a given elementary sequent $\Gamma \vdash C$ of eILL , compute the BBI formula $\Gamma^\circ \rightarrow C^\circ$. Decide if $\Gamma^\circ \rightarrow C^\circ$ belong to BBI_X . If true, then by Theorem 7.4, the sequent $\Gamma \vdash C$ belongs to ILL_X^t . By Theorems 4.4 and 7.5, the fragment eILL is complete w.r.t. trivial phase semantics in class X , $\Gamma \vdash C$ is a valid sequent of ILL . On the contrary, if the formula $\Gamma^\circ \rightarrow C^\circ$ does not belong to BBI_X , then by Theorem 7.4 the sequent $\Gamma \vdash C$ has a trivial phase semantics counter-model of class X . Hence, it is an invalid sequent of ILL .

By Theorem 5.7, there is no algorithm which decide the validity of sequent of the fragment eILL . We obtain a contradiction and thus no algorithm decides membership in BBI_X . \square

T 7.7. *The sets of formulae $\text{BBI}_{\mathbb{P}_f(\mathbb{N})}$ and $\text{BBI}_{\mathbb{N} \times \mathbb{N}}$ are not recursive.*

P . For $\text{BBI}_{\mathbb{N} \times \mathbb{N}}$, it is simply a consequence of the undecidability of membership in $\text{eILL}_{\mathbb{N} \times \mathbb{N}}^t$ (see Theorem 5.8) and of Proposition 7.3. For $\text{BBI}_{\mathbb{P}_f(\mathbb{N})}$, let us first prove the two inclusions

$$\text{eILL}_p \subseteq \text{eILL}_{\mathbb{P}_f(\mathbb{N})}^t \subseteq \text{eILL}_{\mathbb{N} \times \mathbb{N}}^t$$

For $\text{eILL}_p \subseteq \text{eILL}_{\mathbb{P}_f(\mathbb{N})}^t$, this is simply a consequence of the soundness of (trivial) phase semantics (see Theorem 3.3). For $\text{eILL}_{\mathbb{P}_f(\mathbb{N})}^t \subseteq \text{eILL}_{\mathbb{N} \times \mathbb{N}}^t$, we use our embedding via Proposition 7.3 and the inclusion $\text{BBI}_{\mathbb{P}_f(\mathbb{N})} \subseteq \text{BBI}_{\mathbb{N} \times \mathbb{N}}$ of Theorem 6.8.

Then, by Theorem 5.8, membership in the set $\text{eILL}_{\mathbb{P}_f(\mathbb{N})}^t$ is not decidable, and thus, by Proposition 7.3, the set $\text{BBI}_{\mathbb{P}_f(\mathbb{N})}$ is not recursive. \square

Remark: the result that $\text{BBI}_{\mathbb{P}_f(\mathbb{N})}$ is not recursive is the core result of [Brotherston and Kanovich 2010]. The indirect proof we provide here explicits the use of bisimulation to transform a model based on $\mathbb{N} \times \mathbb{N}$ into a model based on $\mathbb{P}_f(\mathbb{N})$.

8. CONCLUSION AND RELATED WORKS

In this extended version of [Larchey-Wendling and Galmiche 2010], we give a full proof of the result of the undecidability of Boolean BI by identifying a fragment of BBI on which the semantics defined by different classes of models collapse to one. This fragment is the direct image by a faithful embedding of the elementary fragment of ILL . By studying the phase and trivial phase semantics of eILL , we establish its completeness with respect to trivial phase semantics whichever class of models is chosen amongst ND, PD, TD, HM and FM. Undecidability follows from an encoding of two counter Minsky machines computations. The faithfulness of the encoding is obtained using a trivial phase model build on the free monoid $\mathbb{N} \times \mathbb{N}$, hence we can even derive the undecidability of eILL (and later BBI) restricted to the interpretations in the model $\mathbb{N} \times \mathbb{N}$.

We also bisimulate free monoids with heap monoids and thus prove that eILL is complete (and thus undecidable) for heap monoid semantics. Using a bisimulation between $\mathbb{N} \times \mathbb{N}$ and $\mathbb{P}_f(\mathbb{N})$, we also deduce the undecidability of eILL (and thus BBI) restricted to the interpretations in the model $\mathbb{P}_f(\mathbb{N})$, which is the simplest heap model conceivable. This is basically the core result of [Brotherston and Kanovich 2010].

The question of the decidability for interpretations restricted to \mathbb{N} remains open because one counter Minsky machines are a special case of pushdown automata for which accessibility is a decidable problem [Bouajjani et al. 1997].

In [Brotherston and Kanovich 2010], the authors show that undecidability also holds for Classical BI [Brotherston and Calcagno 2009] which is another variant of BI containing both an additive and a multiplicative negation. The encoding presented of [Larchey-Wendling and Galmiche 2010] which we keep in this paper would not fit for classical BI. But in [Larchey-Wendling 2010], the author proposes a modified version of our encoding which is suitable for both Boolean BI and Classical BI with a faithfulness argument based on an interpretation in the free abelian group $\mathbb{Z} \times \mathbb{Z}$. Hence he obtains another proof of undecidability suitable for both Boolean and Classical BI.

We left remaining open problems. In particular, the classification of eILL and BBI with respect to validity in particular classes of models, or in particular models is unfinished. Solving this requires finding eILL sequents or BBI formulae which distinguish the classes of models. This may be a difficult task which might need a better understanding of the expressive power of those two logics.

A. SOUNDNESS OF NON-DETERMINISTIC PHASE SEMANTICS FOR ILL

We recall Theorem 3.3. The proof we provide is really just an adaptation of a standard proof in Linear Logic semantics to the more general context of non-deterministic monoids.

T 3.3. *Let $\mathcal{M} = (\mathcal{M}, \circ, \epsilon, (\cdot)^\circ, \mathcal{K})$ be a non-deterministic intuitionistic phase space and $\llbracket \cdot \rrbracket : \text{Var} \rightarrow \mathcal{M}^\circ$ be an interpretation of logical variables. If the sequent $A_1, \dots, A_k \vdash B$ has a proof in S-ILL , then the inclusion $\llbracket A_1 \rrbracket \circ \dots \circ \llbracket A_k \rrbracket \subseteq \llbracket B \rrbracket$ holds.*

P . It could be done by induction on ILL proof trees but we rather use the algebraic semantic characterization of ILL of [Troelstra 1992]. We prove that

$$(\mathcal{M}^\circ, \cap, (\cdot \cup \cdot)^\circ, \emptyset^\circ, \multimap, (\cdot \circ \cdot)^\circ, \{\epsilon\}^\circ, (\mathcal{K} \cap \cdot)^\circ)$$

is an *IL-algebra with storage operator* (where \multimap is defined by $X \multimap Y = \{k \in \mathcal{M} \mid k \circ X \subseteq Y\}$).

First, it is obvious that $(\mathcal{M}^\circ, \cap, (\cdot \cup \cdot)^\circ, \emptyset^\circ)$ is a complete lattice with bottom \emptyset° . This is the *same proof* as in the usual (monoidal) case because the (non-deterministic) monoidal structure does not play any role in this part of the proof. The principal argument is that $(\cdot)^\circ$ is a closure operator on $\mathbb{P}(\mathcal{M})$.

Let us prove that $(\mathcal{M}^\circ, (\cdot \circ \cdot)^\circ, \{\epsilon\}^\circ)$ is a commutative monoid. Obviously the set \mathcal{M}° is stable under the operator $(\cdot \circ \cdot)^\circ$ which thus induces a binary operation on \mathcal{M}° . By stability, we obtain the inclusion $\{\epsilon\}^\circ \circ X^\circ \subseteq (\{\epsilon\} \circ X)^\circ = X^\circ$ and we deduce that for any closed subset X (i.e. $X = X^\circ$), we have $(\{\epsilon\}^\circ \circ X)^\circ \subseteq X$. Also $X = \{\epsilon\} \circ X \subseteq \{\epsilon\}^\circ \circ X \subseteq (\{\epsilon\}^\circ \circ X)^\circ$ by monotonicity of \circ and $(\cdot)^\circ$. Thus $(\{\epsilon\}^\circ \circ X)^\circ = X$ for any closed subset $X \in \mathcal{M}^\circ$ and thus $\{\epsilon\}^\circ$ is a (left) unit for $(\cdot \circ \cdot)^\circ$. Then, it is obvious that $(\cdot \circ \cdot)^\circ$ is a commutative operation because \circ is itself commutative. We deduce that $\{\epsilon\}^\circ$ is a unit for $(\cdot \circ \cdot)^\circ$.

Let us prove that $(\cdot \circ \cdot)^\circ$ is associative. Let $A, B, C \in \mathcal{M}^\circ$. Then, by stability of $(\cdot)^\circ$, we have $A \circ (B \circ C)^\circ \subseteq A^\circ \circ (B \circ C)^\circ \subseteq (A \circ (B \circ C))^\circ = (A \circ B \circ C)^\circ$. Thus $(A \circ (B \circ C))^\circ \subseteq (A \circ B \circ C)^\circ$ holds. As $A \circ B \circ C = A \circ (B \circ C) \subseteq A \circ (B \circ C)^\circ \subseteq (A \circ (B \circ C))^\circ$, we deduce $(A \circ B \circ C)^\circ \subseteq (A \circ (B \circ C))^\circ$. By double inclusion, we conclude that $(A \circ B \circ C)^\circ = (A \circ (B \circ C))^\circ$. Associativity of $(\cdot \circ \cdot)^\circ$ follows from this last identity and associativity/commutativity of \circ on $\mathbb{P}(\mathcal{M})$.

It is obvious that $(\cdot \circ \cdot)^\circ$ is monotonic in both parameters because it is obtained by composition of two monotonic operators, namely \circ and $(\cdot)^\circ$. Let us now prove that \multimap is a right-adjoint $(\cdot \circ \cdot)^\circ$. First, $X \multimap Y$ is closed as soon as Y is closed and $X \multimap Y^\circ = X^\circ \multimap Y^\circ$ holds for any $X, Y \in \mathbb{P}(\mathcal{M})$ just as in the usual (monoidal) case. Now let $A, B, C \in \mathcal{M}^\circ$. We have $(A \circ B)^\circ \subseteq C$ iff $A \circ B \subseteq C$ iff $A \subseteq B \multimap C$. Thus \multimap is indeed right-adjoint to $(\cdot \circ \cdot)^\circ$. The fact that \multimap is contra-variant w.r.t. its first operand and co-variant w.r.t. its second operand is deducible from the monotonicity of \circ and the fact that \multimap is right adjoint to \circ .

We finish by proving that $X \mapsto (\mathcal{K} \cap X)^\circ$ is a *modality*. First, for any $X \in \mathcal{M}^\circ$, as $\mathcal{K} \cap X \subseteq X = X^\circ$, we obtain $(\mathcal{K} \cap X)^\circ \subseteq X$. Then for $X, Y \in \mathcal{M}^\circ$, if we suppose that $(\mathcal{K} \cap Y)^\circ \subseteq X$, then $\mathcal{K} \cap Y \subseteq X$ and thus $\mathcal{K} \cap Y \subseteq \mathcal{K} \cap X$. Thus we obtain $(\mathcal{K} \cap Y)^\circ \subseteq (\mathcal{K} \cap X)^\circ$. Then, as $\epsilon \in \mathcal{K} \subseteq \{\epsilon\}^\circ$, we deduce $\{\epsilon\}^\circ \subseteq \mathcal{K}^\circ = (\mathcal{K} \cap \mathcal{M})^\circ$.⁸ The last condition to check is $((\mathcal{K} \cap X)^\circ \circ (\mathcal{K} \cap Y)^\circ)^\circ = (\mathcal{K} \cap X \cap Y)^\circ$ for any $X, Y \in \mathcal{M}^\circ$. First we have $(\mathcal{K} \cap X)^\circ \circ (\mathcal{K} \cap Y)^\circ \subseteq ((\mathcal{K} \cap X) \circ (\mathcal{K} \cap Y))^\circ$. As $\mathcal{K} \subseteq \{\epsilon\}^\circ$, we have $(\mathcal{K} \cap X) \circ (\mathcal{K} \cap Y) \subseteq \{\epsilon\}^\circ \circ Y \subseteq Y^\circ = Y$. We also have $(\mathcal{K} \cap X) \circ (\mathcal{K} \cap Y) \subseteq X$. As $\mathcal{K} \circ \mathcal{K} \subseteq \mathcal{K}$ we have $(\mathcal{K} \cap X) \circ (\mathcal{K} \cap Y) \subseteq \mathcal{K}$ and hence, we deduce $(\mathcal{K} \cap X) \circ (\mathcal{K} \cap Y) \subseteq \mathcal{K} \cap X \cap Y$. Using stability, we compute $(\mathcal{K} \cap X)^\circ \circ (\mathcal{K} \cap Y)^\circ \subseteq ((\mathcal{K} \cap X) \circ (\mathcal{K} \cap Y))^\circ \subseteq (\mathcal{K} \cap X \cap Y)^\circ$ and thus $((\mathcal{K} \cap X)^\circ \circ (\mathcal{K} \cap Y)^\circ)^\circ \subseteq (\mathcal{K} \cap X \cap Y)^\circ$. Now let us prove the reverse inclusion. Let $z \in \mathcal{K} \cap X \cap Y$. As

⁸Recall the identity $\emptyset^\circ \multimap \emptyset^\circ = \emptyset \multimap \emptyset^\circ = \mathcal{M}$.

$z \in K$ then $z \in J$ and we have $z \in (z \circ z)^\circ \subseteq ((K \cap X) \circ (K \cap Y))^\circ \subseteq ((K \cap X)^\circ \circ (K \cap Y)^\circ)^\circ$. Hence, $K \cap X \cap Y \subseteq ((K \cap X)^\circ \circ (K \cap Y)^\circ)^\circ$ and we deduce $(K \cap X \cap Y)^\circ \subseteq ((K \cap X)^\circ \circ (K \cap Y)^\circ)^\circ$.

We can then apply Theorem 8.21 (page 80) from [Troelstra 1992]. If $A_1, \dots, A_k \vdash B$ has a proof in ILL, then the inclusion $\llbracket A_1, \dots, A_k \rrbracket \subseteq \llbracket B \rrbracket$ holds. It is obvious to prove that $\llbracket A_1 \rrbracket \circ \dots \circ \llbracket A_k \rrbracket \subseteq \llbracket A_1, \dots, A_k \rrbracket$ by induction on k for example. So we deduce $\llbracket A_1 \rrbracket \circ \dots \circ \llbracket A_k \rrbracket \subseteq \llbracket B \rrbracket$. \square

B. COMPLETENESS OF NON-DETERMINISTIC PHASE SEMANTICS FOR ILL

Let Form denote the set of formulae of ILL build from Var as set of logical variables, as defined in Section 3. Let $\text{Ctx} = \mathbb{M}_f(\text{Form})$ denote the set of *contexts* build from the formulae of ILL, i.e. the set of finite multisets of ILL-formulae. Recall that a sequent is a pair $(\Gamma, C) \in \text{Ctx} \times \text{Form}$ denoted $\Gamma \vdash C$ and that ILL_p denotes the set of sequents for which there exists a proof in the S-ILL.

Given a set of contexts $X \subseteq \text{Ctx}$, a context $\Delta \in \text{Ctx}$ and a formula $C \in \text{Form}$, we denote by $\Delta, X \vdash C$ the following set of sequents:

$$\Delta, X \vdash C = \{\Delta, \Gamma \vdash C \mid \Gamma \in X\}$$

We consider the following free (commutative) monoid (Ctx, \star, π) where the composition \star is defined by $\Gamma \star \Delta = \{[\Gamma, \Delta]\}^9$ for any $\Gamma, \Delta \in \text{Ctx}$ and $\pi = [\emptyset]$ is the empty context. This non-deterministic monoid (Ctx, \star, π) obviously belongs to the class FM. The adjoint of \star is denoted $\rightarrow \star$. We define the closure operator $(\cdot)^\circ$ on $\mathbb{P}(\text{Ctx})$ and the set $K \subseteq \text{Ctx}$ by

$$\begin{aligned} X^\circ &= \{\Gamma \in \text{Ctx} \mid \forall \Delta \in \text{Ctx}, \forall C \in \text{Form} \quad \Delta, X \vdash C \subseteq \text{ILL}_p \Rightarrow \Delta, \Gamma \vdash C \in \text{ILL}_p\} \\ K &= \{!\Gamma \in \text{Ctx} \mid \Gamma \in \text{Ctx}\} \end{aligned}$$

P B.1. $(\text{Ctx}, \star, \pi, (\cdot)^\circ, K)$ is a non-deterministic phase space of class FM.

P . As mentioned earlier, (Ctx, \star, π) is a non-deterministic monoid of class FM. We first prove that $(\cdot)^\circ$ is a stable closure, then we show that K verifies $\pi \in K \subseteq \{\Gamma \in \text{Ctx} \mid \Gamma \in \{\pi\}^\circ \cap (\Gamma \circ \Gamma)^\circ\}$ and $K \star K \subseteq K$.

Let X and Y be two subsets of Ctx . Let us prove $X \subseteq X^\circ$. Let $\Gamma \in X$. Then for any Δ, C we have $\{\Delta, \Gamma \vdash C\} \subseteq \Delta, X \vdash C$. Hence, if $\Delta, X \vdash C \subseteq \text{ILL}_p$ holds, the property $\Delta, \Gamma \vdash C \in \text{ILL}_p$ also holds. Thus, $\Gamma \in X^\circ$ holds. We have proved $X \subseteq X^\circ$. From the definition of $(\cdot)^\circ$, $X \subseteq Y$ obviously entails $X^\circ \subseteq Y^\circ$. Let us now prove that $X^{\circ\circ} \subseteq X^\circ$. Let $\Gamma \in X^{\circ\circ}$ and let us prove $\Gamma \in X^\circ$. We consider Δ, C such that the property $\Delta, X \vdash C \subseteq \text{ILL}_p$ holds. By definition of $(\cdot)^\circ$, we deduce that $\Delta, X^\circ \vdash C \subseteq \text{ILL}_p$ holds. Since $\Gamma \in X^{\circ\circ}$, we deduce that $\Delta, \Gamma \vdash C \in \text{ILL}_p$ holds. From $\Delta, X \vdash C \subseteq \text{ILL}_p$ we derived $\Delta, \Gamma \vdash C \in \text{ILL}_p$, so we have proved that $\Gamma \in X^\circ$. Hence, $X^{\circ\circ} \subseteq X^\circ$ and then $(\cdot)^\circ$ is a closure operator on $\mathbb{P}(\text{Ctx})$.

Let us now prove that the closure $(\cdot)^\circ$ is stable, i.e. satisfies the axiom $X^\circ \star Y^\circ \subseteq (X \star Y)^\circ$ for any two subsets X, Y of Ctx . Since \star is commutative and $(\cdot)^\circ$ is a closure, it is sufficient to prove the property $X \star Y^\circ \subseteq (X \star Y)^\circ$ for any two subsets X, Y of Ctx (the proof of this simplification is left to the reader). Now let us consider $\Gamma_1 \in X$ and $\Gamma_2 \in Y^\circ$ and let us prove that $[\Gamma_1, \Gamma_2] \in (X \star Y)^\circ$. So let us introduce Δ, C such that $\Delta, X \star Y \vdash C \subseteq \text{ILL}_p$. Since $\Gamma_1 \in X$ holds, we deduce $\{\Gamma_1\} \star Y \subseteq X \star Y$ and thus $[\Delta, \Gamma_1], Y \vdash C \subseteq \text{ILL}_p$ holds. Since $\Gamma_2 \in Y^\circ$ holds, we deduce $[\Delta, \Gamma_1], \Gamma_2 \vdash C \in \text{ILL}_p$. Hence, $\Delta, [\Gamma_1, \Gamma_2] \vdash C \in \text{ILL}_p$ holds. We conclude $[\Gamma_1, \Gamma_2] \in (X \star Y)^\circ$. We have proved that $X \star Y^\circ \subseteq (X \star Y)^\circ$ holds for any $X, Y \subseteq \text{Ctx}$. As a consequence, the closure $(\cdot)^\circ$ is stable.

Now let us finish by checking the axioms corresponding to K . Since $\pi = [\emptyset] = [!\emptyset]$, it is obvious that $\pi \in K$. Let us prove that $K \subseteq \{\Gamma \in \text{Ctx} \mid \Gamma \in \{\pi\}^\circ \cap (\Gamma \star \Gamma)^\circ\}$. Let $\Gamma \in K$. There exists Γ_0 such that $\Gamma = !\Gamma_0$. Let us prove that $!\Gamma_0 \in \{\pi\}^\circ$. We consider Δ, C such that $\Delta, \{\pi\} \vdash C \subseteq \text{ILL}_p$, which reduces to $\Delta \vdash C \in \text{ILL}_p$. Hence $\Delta \vdash C$ has a proof in S-ILL and by multiple applications of rule $\langle w \rangle$, we obtain a proof of $\Delta, !\Gamma_0 \vdash C$ in S-ILL. Hence $\Delta, !\Gamma_0 \vdash C \in \text{ILL}_p$. We conclude that $\Gamma = !\Gamma_0$ belongs to $\{\pi\}^\circ$. Since $\Gamma \star \Gamma = \{[!\Gamma_0, !\Gamma_0]\}$, we prove that $!\Gamma_0 \in \{[!\Gamma_0, !\Gamma_0]\}^\circ$ using a similar argument, replacing rule $\langle w \rangle$ by rule $\langle c \rangle$. We finish with a proof of $K \star K \subseteq K$. Let $\Gamma \in K \star K$. By definition (1)

⁹Recall that $\Gamma \mapsto [\Gamma]$ is the identity map on Ctx but the extra notation $[\cdot]$ in $\{[\Gamma, \Delta]\}$ is used to here to remove the ambiguity on the denotation of the comma: here it denotes the composition of multisets, not the addition of elements in a set.

of the extension of \star on $\mathbb{P}(\text{Ctx})$, there exists $!\Gamma_0 \in \mathbf{K}$ and $!\Gamma_1 \in \mathbf{K}$ such that $\Gamma \in \Gamma_0 \star \Gamma_1$. We deduce $\Gamma = [!\Gamma_0, !\Gamma_1]$ and, as a consequence $\Gamma \in \mathbf{K}$ holds. \square

For any formula F of ILL, we denote by $\downarrow F$ the *section below* F defined by

$$\downarrow F = \{\Gamma \in \text{Ctx} \mid \Gamma \vdash F \in \text{ILL}_p\}$$

It is easy to prove that sections are closed subsets of $\mathbb{P}(\text{Ctx})$.

P B.2. *For any formula F of ILL, the inclusion $(\downarrow F)^\circ \subseteq \downarrow F$ holds.*

P . For the following values of $\Delta = [\emptyset]$ and $C = F$, we obtain $\Delta, \downarrow F \vdash C \in \text{ILL}_p$. Hence, if we pick $\Gamma \in (\downarrow F)^\circ$, we deduce $\Delta, \Gamma \vdash C \in \text{ILL}_p$ by definition of $(\cdot)^\circ$. We conclude $\Gamma \vdash F \in \text{ILL}_p$ and thus $\Gamma \in \downarrow F$. Hence the inclusion $(\downarrow F)^\circ \subseteq \downarrow F$ holds. \square

As sections are closed, it is legitimate to interpret logical variables by their section, i.e. we define the interpretation $\llbracket v \rrbracket = \downarrow v$ for every variable $v \in \text{Var}$. The following lemma which is the core of the completeness argument was first explicated by Okada [Okada 2002] (but not for exactly the same closure operator we use here).

L B.3 (O .). *For any formula F of ILL, the relation $\llbracket F \rrbracket \in \llbracket F \rrbracket \subseteq \downarrow F$ holds.*

P . The proof is done by (mutual) induction of the formula F . The beauty of the argument is that the semantic properties $\llbracket F \rrbracket \in \llbracket F \rrbracket$ and $\llbracket F \rrbracket \subseteq \downarrow F$ correspond one to one with the rules of the (cut)-free S-ILL calculus.

— for a variable $v \in \text{Var}$, the property $\llbracket v \rrbracket \in \llbracket v \rrbracket$ reduces to $\llbracket v \rrbracket \in \downarrow v$ which is an instance of the identity axiom $\langle \text{id} \rangle$. The property $\llbracket v \rrbracket \subseteq \downarrow v$ reduces to $\downarrow v \subseteq \downarrow v$ which is trivial;

— if F is a formula of type $F = A \otimes B$, then we observe that rule $\langle \otimes_L \rangle$ corresponds to the relation $\llbracket A \otimes B \rrbracket \in \{\llbracket A, B \rrbracket\}^\circ$ and rule $\langle \otimes_R \rangle$ corresponds to the relation $\downarrow A \star \downarrow B \subseteq \downarrow A \otimes B$. Thus, using the induction hypotheses $\llbracket A \rrbracket \in \llbracket A \rrbracket \subseteq \downarrow A$ and $\llbracket B \rrbracket \in \llbracket B \rrbracket \subseteq \downarrow B$, we compute $\llbracket A \otimes B \rrbracket \in \{\llbracket A, B \rrbracket\}^\circ \subseteq (\llbracket A \rrbracket \star \llbracket B \rrbracket)^\circ \subseteq (\llbracket A \rrbracket \star \llbracket B \rrbracket)^\circ \subseteq \llbracket A \otimes B \rrbracket$ and $\llbracket A \otimes B \rrbracket \subseteq (\llbracket A \rrbracket \star \llbracket B \rrbracket)^\circ \subseteq (\downarrow A \star \downarrow B)^\circ \subseteq (\downarrow A \otimes \downarrow B)^\circ \subseteq \downarrow A \otimes B$;

— if $F = A \multimap B$, then we use the relations $\llbracket A \multimap B \rrbracket \in (\downarrow A) \multimap \{\llbracket B \rrbracket\}^\circ$ and $\{\llbracket A \rrbracket\} \multimap \downarrow B \subseteq \downarrow A \multimap B$ corresponding to rules $\langle \multimap_L \rangle$ and $\langle \multimap_R \rangle$ respectively. We compute $\llbracket A \multimap B \rrbracket \in (\downarrow A) \multimap \{\llbracket B \rrbracket\}^\circ \subseteq \llbracket A \rrbracket \multimap \{\llbracket B \rrbracket\}^\circ = \llbracket A \multimap B \rrbracket$ and $\llbracket A \multimap B \rrbracket = \llbracket A \rrbracket \multimap \{\llbracket B \rrbracket\}^\circ \subseteq \{\llbracket A \rrbracket\} \multimap \downarrow B \subseteq \downarrow A \multimap B$;

— if $F = 1$, we obtain the relations $\llbracket 1 \rrbracket \in \{\llbracket \emptyset \rrbracket\}^\circ$ and $\llbracket \emptyset \rrbracket \in \downarrow 1$ for rules $\langle 1_L \rangle$ and $\langle 1_R \rangle$ respectively. Thus $\llbracket 1 \rrbracket \in \{\llbracket \emptyset \rrbracket\}^\circ = \{\pi\}^\circ = \llbracket 1 \rrbracket$ and $\llbracket 1 \rrbracket = \{\llbracket \emptyset \rrbracket\}^\circ \subseteq (\downarrow 1)^\circ \subseteq \downarrow 1$;

— if $F = A \& B$, we obtain the relations $\llbracket A \& B \rrbracket \in \{\llbracket A \rrbracket\}^\circ$, $\llbracket A \& B \rrbracket \in \{\llbracket B \rrbracket\}^\circ$ and $\downarrow A \cap \downarrow B \subseteq \downarrow A \& B$ for rules $\langle \&_L^1 \rangle$, $\langle \&_L^2 \rangle$ and $\langle \&_R \rangle$ respectively. Thus $\llbracket A \& B \rrbracket \in \{\llbracket A \rrbracket\}^\circ \cap \{\llbracket B \rrbracket\}^\circ \subseteq \llbracket A \rrbracket^\circ \cap \llbracket B \rrbracket^\circ \subseteq \llbracket A \rrbracket \cap \llbracket B \rrbracket = \llbracket A \& B \rrbracket$ and $\llbracket A \& B \rrbracket = \llbracket A \rrbracket \cap \llbracket B \rrbracket \subseteq \downarrow A \cap \downarrow B \subseteq \downarrow A \& B$;

— if $F = \top$, we obtain the relation $\text{Ctx} \subseteq \downarrow \top$ for rule $\langle \top_R \rangle$. Thus $\llbracket \top \rrbracket \in \text{Ctx} = \llbracket \top \rrbracket$ and $\llbracket \top \rrbracket = \text{Ctx} \subseteq \downarrow \top$;

— if $F = A \oplus B$, we obtain the relations $\llbracket A \oplus B \rrbracket \in \{\llbracket A \rrbracket, \llbracket B \rrbracket\}^\circ$, $\downarrow A \subseteq \downarrow A \oplus B$ and $\downarrow B \subseteq \downarrow A \oplus B$ for rules $\langle \oplus_L \rangle$, $\langle \oplus_R^1 \rangle$ and $\langle \oplus_R^2 \rangle$ respectively. Thus $\llbracket A \oplus B \rrbracket \in \{\llbracket A \rrbracket, \llbracket B \rrbracket\}^\circ = (\{\llbracket A \rrbracket\} \cup \{\llbracket B \rrbracket\})^\circ \subseteq (\llbracket A \rrbracket \cup \llbracket B \rrbracket)^\circ = \llbracket A \oplus B \rrbracket$ and $\llbracket A \oplus B \rrbracket = (\llbracket A \rrbracket \cup \llbracket B \rrbracket)^\circ \subseteq (\downarrow A \cup \downarrow B)^\circ \subseteq (\downarrow A \oplus \downarrow B)^\circ \subseteq \downarrow A \oplus B$;

— if $F = \perp$, we obtain the relation $\llbracket \perp \rrbracket \in \emptyset^\circ$ for rule $\langle \perp_L \rangle$. Thus $\llbracket \perp \rrbracket \in \emptyset^\circ = \llbracket \perp \rrbracket$ and $\llbracket \perp \rrbracket = \emptyset^\circ \subseteq (\downarrow \perp)^\circ \subseteq \downarrow \perp$;

— if $F = !A$, we obtain the relations $\llbracket !A \rrbracket \in \{\llbracket A \rrbracket\}^\circ$ and $\mathbf{K} \cap \downarrow A \subseteq \downarrow (!A)$ for rules $\langle !_L \rangle$ and $\langle !_R \rangle$ respectively. Since $\llbracket !A \rrbracket \in \mathbf{K}$ by definition of \mathbf{K} , we deduce $\llbracket !A \rrbracket \in \mathbf{K} \cap \{\llbracket A \rrbracket\}^\circ \subseteq \mathbf{K} \cap \llbracket A \rrbracket \subseteq \llbracket !A \rrbracket$ and $\llbracket !A \rrbracket = (\mathbf{K} \cap \llbracket A \rrbracket)^\circ \subseteq (\mathbf{K} \cap \downarrow A)^\circ \subseteq (\downarrow (!A))^\circ \subseteq \downarrow (!A)$.

\square

T 3.5. *If the sequent $\Gamma \vdash A$ is valid in every free monoidal phase semantic interpretation $(M, \circ, \epsilon, (\cdot)^\circ, K, \llbracket \cdot \rrbracket)$ (i.e. with (M, \circ, ϵ) of the class FM), then $\Gamma \vdash A$ has a proof in S-ILL.*

P. Let $A_1, \dots, A_k \vdash B$ be a sequent which is valid in every free monoidal phase semantic interpretation. In particular, it is valid in our current interpretation (Ctx, \star, π) and we deduce that the inclusion $\llbracket A_1 \rrbracket \star \dots \star \llbracket A_k \rrbracket \subseteq \llbracket B \rrbracket$ holds. By Okada's lemma B.3, we obtain

$$\llbracket A_1, \dots, A_k \rrbracket \in \llbracket A_1 \rrbracket \star \dots \star \llbracket A_k \rrbracket \subseteq \llbracket A_1 \rrbracket \star \dots \star \llbracket A_k \rrbracket \subseteq \llbracket B \rrbracket \subseteq \downarrow B$$

and we conclude $A_1, \dots, A_k \vdash B \in \text{ILL}_p$. Hence, the sequent $A_1, \dots, A_k \vdash B$ has a proof in S-ILL. \square

Remark: this proof does not use the cut rule $\langle \text{cut} \rangle$ so it can also be used as an argument for *strong completeness* from which it is easy to derive a semantic proof of cut-elimination for S-ILL.

C. BISIMULATING FREE MONOIDS WITH HEAP MONOIDS

In this section, we give a detailed proof of Lemma 6.6. Let us fix a set X . We denote by $(\mathbb{M}_f(X), +, 0)$ the (usual) free commutative generated by X , i.e. $\mathbb{M}_f(X)$ is the set of finite multisets of elements of X . Multiset composition is denoted additively, so for example we denote by $m = \sum_{x \in X} m_x \cdot x$ the multiset which contains exactly $m_x \in \mathbb{N}$ occurrences of the variable x for each $x \in X$. In case X is infinite, it is assumed that the value of m_x is non-zero for only a finite subset of X . Recall that there is an associated (total deterministic) free monoid of class FM which is denoted $(\mathbb{M}_f(X), \star, \pi)$ with the identities $m \star n = \{m + n\}$ and $\pi = 0$.

We define the following set of locations $L = X \times \mathbb{N}$, and $L_x = \{x\} \times \mathbb{N}$ is a section of L for each $x \in X$. We also define $l_x^i = (x, i) \in L$ and thus we obtain the following identities:

$$L = \bigsqcup_{x \in X} L_x \quad \text{and} \quad L_x = \{l_x^0, l_x^1, l_x^2, \dots\} \quad \text{for } x \in X$$

We define the set of values $V = \{*\}$ as a singleton set. Considering the heap monoid $(\mathbb{H}_{L,V}, \boxplus, \emptyset)$, we define a map $\varphi : \mathbb{H}_{L,V} \rightarrow \mathbb{M}_f(X)$ by

$$\varphi(h) = \sum_{x \in X} \text{card}(\text{def}(h) \cap L_x) \cdot x$$

P. C.1. *The map $\varphi : \mathbb{H}_{L,V} \rightarrow \mathbb{M}_f(X)$ satisfies the following properties:*

- (1) φ is a surjective map;
- (2) if $m_1, m_2 \in \mathbb{M}_f(X)$ and $h \in \mathbb{H}_{L,V}$ satisfy $\varphi(h) = m_1 + m_2$ then there exists $h_1, h_2 \in \mathbb{H}_{L,V}$ such that $\varphi(h_1) = m_1$, $\varphi(h_2) = m_2$ and $h_1 \boxplus h_2 = \{h\}$;
- (3) for any $m_1 \in \mathbb{M}_f(X)$ and any $h_2 \in \mathbb{H}_{L,V}$ there exists $h_1 \in \mathbb{H}_{L,V}$ such that $\text{def}(h_1) \cap \text{def}(h_2) = \emptyset$ and $\varphi(h_1) = m_1$;
- (4) $\varphi(h_1 \boxplus h_2) = \varphi(h_1) \star \varphi(h_2)$ when $\text{def}(h_1) \cap \text{def}(h_2) = \emptyset$;
- (5) $\varphi(h) = 0$ if and only if $h = \emptyset$ for any $h \in \mathbb{H}_{L,V}$;
- (6) $\varphi^{-1}(A) \boxplus \varphi^{-1}(B) = \varphi^{-1}(A \star B)$ for any $A, B \subseteq \mathbb{M}_f(X)$.

P. Let us prove Property (1) and show that φ is a surjective map. Let $m = \sum_{x \in X} m_x \cdot x$ be a finite multiset. Then the set $\{(l_x^i, *) \mid 0 \leq i < m_x\}$ is the graph of a partial function and we denote this function by h_m . It can be easily be checked that $\text{def}(h_m)$ is a finite subset of L and that

$$\varphi(h_m) = \sum_{x \in X} \text{card}\{l_x^i \mid 0 \leq i < m_x\} \cdot x = \sum_{x \in X} m_x \cdot x = m$$

Let us prove Property (2). Let $m, n \in \mathbb{M}_f(X)$ and $h \in \mathbb{H}_{L,V}$ be such that $\varphi(h) = m + n$. For each $x \in X$, we have $\text{card}(\text{def}(h) \cap L_x) = m_x + n_x$. Let us partition $\text{def}(h) \cap L_x$ in $\text{def}(h) \cap L_x = L_x^1 \cup L_x^2$ such that $\text{card}(L_x^1) = m_x$ and $\text{card}(L_x^2) = n_x$. Then let h_1 (resp. h_2) be the partial function with graph $\{(l_x^i, *) \mid l_x^i \in L_x^1\}$ (resp. $\{(l_x^i, *) \mid l_x^i \in L_x^2\}$). The reader can check that $\varphi(h_1) = m_1$, $\varphi(h_2) = m_2$ and $h_1 \boxplus h_2 = \{h\}$ hold.

Let us prove Property (3). Let us write $m_1 = \sum_{x \in X} m_x^1 \cdot x$. For $x \in \text{Var}$, since $L_x \setminus \text{def}(h_2)$ is an infinite set, let us choose L_x^1 such that $L_x^1 \subseteq L_x \setminus \text{def}(h_2)$ and $\text{card}(L_x^1) = m_x^1$. Now let us consider

the partial function h_1 defined by the graph $\{(l_x^i, *) \mid l_x^i \in L_x^1\}$. It is obvious that $\text{def}(h_1)$ is finite, $\text{def}(h_1) \cap \text{def}(h_2) = \emptyset$ and $\varphi(h_1) = m_1$.

Let us prove Property (4). Let $h_1, h_2 \in \mathbb{H}_{L,V}$ such that $\text{def}(h_1) \cap \text{def}(h_2) = \emptyset$. Let h be the result of the composition of h_1 and h_2 , i.e. $h_1 \uplus h_2 = \{h\}$. Then $\text{card}(\text{def}(h) \cap L_x) = \text{card}(\text{def}(h_1) \cap L_x) + \text{card}(\text{def}(h_2) \cap L_x)$ and we deduce $\varphi(h) = \varphi(h_1) + \varphi(h_2)$, hence $\varphi(h_1 \uplus h_2) = \{\varphi(h_1) + \varphi(h_2)\}$.

Property (5) is obvious. Let us prove Property (6). First let us consider the inclusion $\varphi^{-1}(A \star B) \subseteq \varphi^{-1}(A) \uplus \varphi^{-1}(B)$. Let us pick $h \in \varphi^{-1}(A \star B)$. Then $\varphi(h) \in A \star B$ so there exists $m_1 \in A$ and $m_2 \in B$ such that $\varphi(h) = m_1 + m_2$. By Property (2), there exists h_1, h_2 such that $\varphi(h_1) = m_1$, $\varphi(h_2) = m_2$ and $h_1 \uplus h_2 = \{h\}$. Hence $h_1 \in \varphi^{-1}(A)$ and $h_2 \in \varphi^{-1}(B)$. As $h_1 \uplus h_2 = \{h\}$, we get $h \in \varphi^{-1}(A) \uplus \varphi^{-1}(B)$. Let us consider the reverse inclusion $\varphi^{-1}(A) \uplus \varphi^{-1}(B) \subseteq \varphi^{-1}(A \star B)$. Let $h \in \varphi^{-1}(A) \uplus \varphi^{-1}(B)$. Then there exists $h_1 \in \varphi^{-1}(A)$ and $h_2 \in \varphi^{-1}(B)$ such that $h \in h_1 \uplus h_2$. Then we have $\text{def}(h_1) \cap \text{def}(h_2) = \emptyset$ (otherwise $h_1 \uplus h_2 = \emptyset$) and by Property (4), we deduce $\varphi(h) = \varphi(h_1) + \varphi(h_2) \in A \star B$. Hence $h \in \varphi^{-1}(A \star B)$. \square

L C.2 (B) . Let $R_\varphi \subseteq \mathbb{H}_{L,V} \times \mathbb{M}_f(X)$ be the binary relation defined by the graph of φ , i.e. $h R_\varphi m$ iff $\varphi(h) = m$. Then R_φ is a bisimulation between non-deterministic monoids, i.e. it satisfies the following property for any $h \in \mathbb{H}_{L,V}$ and any $m \in \mathbb{M}_f(X)$

$$h R_\varphi m \Rightarrow \begin{cases} h = \emptyset \text{ iff } m = \pi \\ \forall h_1, h_2 \ h \in h_1 \uplus h_2 \Rightarrow \exists m_1, m_2 \ m \in m_1 \star m_2 \text{ and } h_1 R_\varphi m_1 \text{ and } h_2 R_\varphi m_2 \\ \forall m_1, m_2 \ m \in m_1 \star m_2 \Rightarrow \exists h_1, h_2 \ h \in h_1 \uplus h_2 \text{ and } h_1 R_\varphi m_1 \text{ and } h_2 R_\varphi m_2 \\ \forall h_1, h_2 \ h_2 \in h_1 \uplus h \Rightarrow \exists m_1, m_2 \ m_2 \in m_1 \star m \text{ and } h_1 R_\varphi m_1 \text{ and } h_2 R_\varphi m_2 \\ \forall m_1, m_2 \ m_2 \in m_1 \star m \Rightarrow \exists h_1, h_2 \ h_2 \in h_1 \uplus h \text{ and } h_1 R_\varphi m_1 \text{ and } h_2 R_\varphi m_2 \end{cases}$$

P . Let us first prove that $h R_\varphi m \Rightarrow (h = \emptyset \text{ iff } m = \pi)$. Let h and m such that $h R_\varphi m$ holds. Then by definition, we obtain $\varphi(h) = m$. If $m = \pi (= 0)$, then by Property (5) of Proposition C.1, we obtain $h = \emptyset$ and thus $(h, m) \in \{(\emptyset, \pi)\}$. If $m \neq 0$ then by Property (5) of Proposition C.1, we obtain $h \neq \emptyset$ and thus $(h, m) \in \mathbb{M}_f(X) \setminus \{\pi\}$.

Let us now prove the four co-induction properties. Let h and m such that $h R_\varphi m$ holds. Then $\varphi(h) = m$ holds.

— Let $h_1, h_2 \in \mathbb{H}_{L,V}$ such that $h \in h_1 \uplus h_2$. Let $m_1 = \varphi(h_1)$ and $m_2 = \varphi(h_2)$. By Property (4) of Proposition C.1, we obtain $m = \varphi(h) \in \varphi(h_1) \star \varphi(h_2) = m_1 \star m_2$, $h_1 R_\varphi m_1$ and $h_2 R_\varphi m_2$;

— Let $m_1, m_2 \in \mathbb{M}_f(X)$ such that $m = m_1 + m_2$. Property (2) of Proposition C.1, there exists $h_1, h_2 \in \mathbb{H}_{L,V}$ such that $\varphi(h_1) = m_1$, $\varphi(h_2) = m_2$ and $h_1 \uplus h_2 = \{h\}$. Hence, $h \in h_1 \uplus h_2$, $h_1 R_\varphi m_1$ and $h_2 R_\varphi m_2$;

— Let $h_1, h_2 \in \mathbb{H}_{L,V}$ such that $h_2 \in h_1 \uplus h$. Let $m_1 = \varphi(h_1)$ and $m_2 = \varphi(h_2)$. By Property (4) of Proposition C.1, we obtain $m_2 = \varphi(h_2) \in \varphi(h_1) \star \varphi(h) = m_1 \star m$, $h_1 R_\varphi m_1$ and $h_2 R_\varphi m_2$;

— Let $m_1, m_2 \in \mathbb{M}_f(X)$ such that $m_2 = m_1 + m$. By Property (3) of Proposition C.1, let us choose h_1 such that $\text{def}(h_1) \cap \text{def}(h) = \emptyset$ and $\varphi(h_1) = m_1$. Hence, $h_1 R_\varphi m_1$ holds. Since $\text{def}(h_1) \cap \text{def}(h) = \emptyset$, let h_2 be the unique heap such that $h_2 \in h_1 \uplus h$. By Property (4) of Proposition C.1, we obtain $\varphi(h_2) = \varphi(h_1) + \varphi(h) = m_1 + m = m_2$. Hence $h_2 R_\varphi m_2$ holds.

\square

L 6.6 . Let X be a set. There exists a heap monoid $\mathbb{H}_{L,V}$ of class HM and a surjective map $\varphi : \mathbb{H}_{L,V} \rightarrow \mathbb{M}_f(X)$ such that for any Kripke interpretation $\delta : \text{Var} \rightarrow \mathbb{P}(\mathbb{M}_f(X))$ in the free monoid $(\mathbb{M}_f(X), \star, \pi)$, the Kripke interpretation $\delta' : \text{Var} \rightarrow \mathbb{P}(\mathbb{H}_{L,V})$ in the heap monoid $(\mathbb{H}_{L,V}, \uplus, \emptyset)$ defined by $\delta' = v \mapsto \varphi^{-1}(\delta(v))$ satisfies the following property:

$$h \Vdash_{\delta'} F \text{ if and only if } \varphi(h) \Vdash_{\delta} F \quad \text{for any } F \in \text{BBI}$$

P . By induction on the structure of F , we prove the following property:

$$\forall h, m \ h R_\varphi m \Rightarrow (h \Vdash_{\delta'} F \text{ iff } m \Vdash_{\delta} F)$$

Let us proceed by case analysis on the structure of F :

- if F is reduced to a logical variable $v \in \text{Var}$, then $h R_\varphi m$ implies $\varphi(h) = m$ and thus we compute: $h \Vdash_{\delta'} v$ iff $h \in \delta'(v)$ iff $h \in \varphi^{-1}(\delta(v))$ iff $\varphi(h) \in \delta(v)$ iff $m \in \delta(v)$ iff $m \Vdash_\delta v$;
- if F is the multiplicative unit $\mathbb{1}$ then the relation reduces to $h R_\varphi m \Rightarrow (h = \emptyset \text{ iff } m = \pi)$ which is a consequence of Lemma C.2;
- if $F = A * B$, let us suppose $h \Vdash_{\delta'} A * B$ and let us prove $m \Vdash_\delta A * B$. By definition of Kripke semantics, there exists h_1, h_2 such that $h \in h_1 \uplus h_2$, $h_1 \Vdash_{\delta'} A$ and $h_2 \Vdash_{\delta'} B$. Since $h R_\varphi m$, by Lemma C.2, we obtain m_1, m_2 such that $m \in m_1 \star m_2$, $h_1 R_\varphi m_1$ and $h_2 R_\varphi m_2$. By induction, we get $m_1 \Vdash_\delta A$ and $m_2 \Vdash_\delta B$. Hence, by definition of Kripke semantics, we deduce $m \Vdash_\delta A * B$. We proceed in a perfectly symmetric way for $m \Vdash_\delta A * B \Rightarrow h \Vdash_{\delta'} A * B$;
- if $F = A \multimap B$, let us suppose $h \Vdash_{\delta'} A \multimap B$ and let us prove $m \Vdash_\delta A \multimap B$. So let us m_1, m_2 consider such that $m_2 \in m_1 \star m$ and $m_1 \Vdash_\delta A$ and let us prove that $m_2 \Vdash_\delta B$. Since $h R_\varphi m$, by Lemma C.2, we obtain h_1, h_2 such that $h_2 \in h_1 \uplus h$, $h_1 R_\varphi m_1$ and $h_2 R_\varphi m_2$. By induction, we get $h_1 \Vdash_{\delta'} A$. Hence, by definition of Kripke semantics for \multimap , we deduce $h_2 \Vdash_{\delta'} B$. By induction again, we derive $m_2 \Vdash_\delta B$. Symmetrically we obtain $m \Vdash_\delta A \multimap B \Rightarrow h \Vdash_{\delta'} A \multimap B$;
- if the outermost connective of F is not multiplicative, i.e. belongs to $\{\perp, \top, \neg, \vee, \wedge, \rightarrow\}$, then the equivalence is trivially obtained from the induction hypothesis because of the pointwise definition of the Kripke semantics of non-linear connectives.

□

Let us consider the following map between the heap monoid $(\mathbb{P}_f(\mathbb{N}), \uplus, \emptyset)$ and the free monoid $(\mathbb{N} \times \mathbb{N}, +, (0, 0))$. Let us split \mathbb{N} into two infinite parts such as $\mathbb{N} = \mathbb{E} \uplus \mathbb{O}$ where $\mathbb{O} = \{2n+1 \mid n \in \mathbb{N}\}$ and $\mathbb{E} = \{2n \mid n \in \mathbb{N}\}$. We define the map $\psi : \mathbb{P}_f(\mathbb{N}) \longrightarrow \mathbb{N} \times \mathbb{N}$ by

$$\psi(K) = (\text{card}(K \cap \mathbb{E}), \text{card}(K \cap \mathbb{O})) \quad \text{for } K \text{ finite subset of } \mathbb{N}$$

The map ψ is just a particular case of the map φ where the set X has two elements like for example $X = \{0, 1\}$. Then the map ψ is surjective and the binary relation defined by its graph is a bisimulation between non-deterministic monoids as defined in Lemma C.2. Hence, we immediately derive the following result:

L C.3. *There exists a surjective map $\psi : \mathbb{P}_f(\mathbb{N}) \longrightarrow \mathbb{N} \times \mathbb{N}$ such that for any Kripke interpretation $\delta : \text{Var} \longrightarrow \mathbb{P}(\mathbb{N} \times \mathbb{N})$ in the free monoid $(\mathbb{N} \times \mathbb{N}, +, (0, 0))$, the Kripke interpretation $\delta' : \text{Var} \longrightarrow \mathbb{P}(\mathbb{P}_f(\mathbb{N}))$ in the heap monoid $(\mathbb{P}_f(\mathbb{N}), \uplus, \emptyset)$ defined by $\delta' = v \mapsto \psi^{-1}(\delta(v))$ satisfies the following property:*

$$h \Vdash_{\delta'} F \quad \text{if and only if} \quad \psi(h) \Vdash_\delta F \quad \text{for any } F \in \text{BBI}$$

We deduce a proof of Theorem 6.8

T 6.8. *The inclusion $\text{BBI}_{\mathbb{P}_f(\mathbb{N})} \subseteq \text{BBI}_{\mathbb{N} \times \mathbb{N}}$ holds.*

P . Let $F \in \text{BBI}_{\mathbb{P}_f(\mathbb{N})}$ be a BBI-formula which is valid in the heap model $(\mathbb{P}_f(\mathbb{N}), \uplus, \emptyset)$. Then let $\delta : \text{Var} \longrightarrow \mathbb{P}(\mathbb{N} \times \mathbb{N})$ be a Kripke interpretation in the free monoid $(\mathbb{N} \times \mathbb{N}, +, (0, 0))$. Let us consider $(a, b) \in \mathbb{N} \times \mathbb{N}$ and let us show that $(a, b) \Vdash_\delta F$ holds. Since ψ is surjective, let us pick $K \in \mathbb{P}_f(\mathbb{N})$ such that $\psi(K) = (a, b)$ (for instance, $K = \{0, \dots, 2a-2\} \cup \{1, \dots, 2b-1\}$ would fit). Since $F \in \text{BBI}_{\mathbb{P}_f(\mathbb{N})}$, we deduce $K \Vdash_{\delta'} F$. By Lemma C.3, we conclude $(a, b) = \psi(K) \Vdash_\delta F$. Thus F belongs to $\text{BBI}_{\mathbb{N} \times \mathbb{N}}$. □

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