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Abstract. The principles and application of Generation-Recombination (GR) noise spectroscopy will be outlined and illustrated for the case of traps in Ultra-Thin Buried Oxide Silicon-On-Insulator nMOSFETs and for vertical polycrystalline silicon nMOSFETs. It will be shown that for scaled devices the GR noise is originating from a single defect, giving rise to a so-called Random Telegraph Signal (RTS). Several methods will be described for an accurate extraction of the RTS parameters (amplitude, up and down time constant). It will be demonstrated that besides the deep-level parameters also the position of the trap in the channel can be derived from a numerical modeling of the RTS amplitude.

Introduction

Performing defect spectroscopy in nano-scaled structures is a challenging endeavor. One technique which appears to be very suitable for this task is Generation-Recombination (GR) noise spectroscopy [1]. Originally, the method has been developed for rather large area semiconductor devices, like, e.g., MOSFETs [1-4], Charge-Coupled Devices [5] or Junction Field-Effect Transistors [6] to study deep levels in the semiconductor depletion region. It is an alternative to the popular Deep Level Transient Spectroscopy (DLTS) technique [2], the main difference being that the GR centers are studied in dynamic equilibrium, i.e., the noise is due to subsequent capture and emission of free carriers, while in DLTS an emission transient is monitored after trap filling. If the GR events are mainly related to either the valence (p-type) or conduction band (n-type material), the corresponding low-frequency (LF) noise spectrum is a Lorentzian as a function of the frequency and it is the result of fluctuations in the current through the device by alternating carrier capture and emission from a deep-level trap. The advantage of GR noise spectroscopy compared with DLTS is that it can be applied to any device size, since the LF noise Power Spectral Density (PSD) generally scales with 1/A [7], with A the active device area, implying that the relative noise amplitude becomes higher for smaller devices. As a consequence, GR noise may become the dominant LF noise source in small-area MOSFETs and can be caused by a single defect [8]. At the same time, discrete switching of the device current as a function of time becomes visible and corresponds in the most simple case to the charging (carrier capture) and discharging (emission) of a single trap. Such
behavior in the time domain is called a Random Telegraph Signal (RTS) and its parameters (amplitude, up and down times) can equally be used for deep-level characterization [8].

In this paper, an overview will be given regarding GR noise and RTS spectroscopy in MOSFETs. It will be outlined how the main defect level parameters (activation energy $E_T$; capture cross section for holes (electrons) $\sigma_{p,n}$ and trap concentration $N_T$) can be derived from the Lorentzian noise spectrum as a function of temperature $T$. In the case of single-defect RTSs, the same information can be extracted from time domain measurements. In addition, it will be shown that studying the gate voltage ($V_G$) or drain voltage ($V_D$) dependence of the RTS amplitude yields in many cases information on the position of the trap. Criteria will be proposed to distinguish Lorentzian noise belonging to an ensemble of traps in the depletion region of a semiconductor material or to a single defect in the gate dielectric. The methods will be illustrated for processing-induced defects present in the silicon film of Ultra-Thin Buried Oxide (UTBOX) Silicon-on-Insulator (SOI) MOSFETs and for RTSs present in the polysilicon layer of a vertical transistor for Non-Volatile Memory (NVM) applications [9,10].

**Principle of GR Noise and RTS Spectroscopy**

**GR Noise.** As schematically shown in Fig. 1, the GR noise power spectral density (PSD) ($S_I$) exhibits a plateau $A_0$ at low frequency ($f$) and a $1/f^2$ roll-off, corresponding to [1-4]:

$$S_I = A_0/[1+(f/f_0)^2]$$  \(1\)

with $f_0=1/2\pi\tau_0$ the characteristic frequency of the GR center and $\tau_0$ the characteristic time constant, given by the Shockley-Read-Hall (SRH) expression [1-4]:

$$\tau_0 = 1/(2\pi f_0) = [c_n(n(x,y)+n_i) + c_p(p(x,y)+p_i)]^{-1}$$  \(2\)

with $c_n$, $c_p$ the capture coefficient for electrons and holes at position $(x,y)$ in the channel, respectively, given by the product of the corresponding capture cross section and thermal velocity, i.e., $c_n = \sigma_n v_{thn}$. Further, we have that $n(x,y)$ and $p(x,y)$ are the free electron and hole densities and $n_i$ and $p_i$ is the free electron or hole density when the Fermi level $E_F$ coincides with the trap level $E_T$. In the depletion region of a bulk or a partially depleted MOSFET, one can neglect the minority carrier terms in Eq. (2) so that the characteristic time constant can be approximated by the sum of an emission ($\tau_e$) and a capture term ($\tau_c$):

$$1/\tau_0 = 1/\tau_e + 1/\tau_c$$  \(3\)

The characteristic frequency can be determined from a plot of $f \times S_I$ versus $f$, resulting in a peak with a maximum occurring at $f_0$. In general, a LF noise spectrum may consist of different Lorentzians, occurring at different $f_0$, a $1/f$ noise component $K_f/f$ and frequency-independent white noise (PSD $B_w$) [11,12]. Fitting of the following expression:

$$S_I f = B_w f + K_f + \sum_{i=1}^{j} A_{0i}/f[1+(f/f_{0i})^2]$$  \(4\)

gives accurate values for the parameters $A_{0i}$ and $f_{0i}$ of the $i=1,j$ Lorentzians in the spectrum [11,12]. Measuring the $f_{0i}$ values at different sample temperatures enables to construct an Arrhenius law like in Fig. 2 [11,12]:

$$ln(T \tau_0^2) = \frac{E_g - E_F}{kT} + ln \left( \frac{h^8}{4\pi^2 \sigma_{mn} \sqrt{6\pi^3 M e^{-1} m^*/m^*}} \right)$$  \(5\)
In Eq. (5) \( k \) is the Boltzmann constant, \( h \) Planck’s constant, \( M_c \) the equivalent minima in the conduction band, \( m_e^* \) and \( m_h^* \) the transport effective mass for electrons and holes, respectively. It is clear that from the slope of an Arrhenius plot one derives the activation energy \( E_C-E_T \) and from the intercept the (electron) capture cross section. An example of an Arrhenius plot obtained on an UTBOX SOI nMOSFET is given in Fig. 2, showing an electron trap with activation energy \( \Delta E = E_C-E_T = 0.42 \) eV and 0.45 eV, respectively.

Finally, the trap concentration \( N_t \) can be derived from [1,4,12]:

\[
A_{0t} = \frac{q^2 N_{eff}}{W L C_{ox}^2} \tau_{0t} = \frac{B q^2 W_d N_t}{W L C_{ox}^2} \tau_{0t}
\]  

(6)
with $WL$ the effective width times the length of the transistor; $C_{ox}$ the oxide capacitance density of the gate, $q$ the elementary charge and $W_d$ the width of the depletion region. In the case of a bulk or partially depleted SOI transistor, the empirical factor $B$ is given by $1/3$ [1,4].

**RTS.** A typical time trace of a two-level RTS in a small-area MOSFET is given in Fig. 3, defining the main parameters: the current amplitude $\Delta I_D$, the up time $t_{up}$ and the down time $t_{down}$. From the histogram of the drain current ($I_D$) values, an average amplitude $\Delta I_D$ can be derived, while the time constant ratio $\tau_c/\tau_e$ can be found from the ratio of the area under the two peaks in the amplitude histogram of Fig. 4 [13]. The inverse sum of the time constants can be obtained from the corner frequency of the corresponding Lorentzian spectrum [8,13] or by constructing the probability distribution of the up ($t_{up}$) and the down ($t_{down}$) time constants. They usually follow an exponential distribution, given by [8,13]:

$$P(t)=\frac{1}{\tau}\exp\left(-\frac{t}{\tau}\right)$$

whereby the average value corresponds to the capture (up time) or emission (down time) constant. Performing time domain analysis at different temperatures enables constructing an Arrhenius diagram from which the activation energy of carrier capture and emission is obtained [8].

![Fig. 3. Time series of the drain current obtained on a small-area MOSFET operated in weak inversion, showing a random two-level switching between a low and a high drain current state.](image)

![Fig. 4. Histogram of the amplitudes derived from the time series of Fig. 3.](image)
In the case of a complex multilevel RT signal, like in Fig. 5 containing a small and a large amplitude signal, the usual time series analysis method may become inadequate. In order to discriminate multiple RTSs in the same time trace, one can rely on the statistical analysis of a so-called Time Lag Plot (TLP) which consists in the representation of the current at $n^{th}$ sample $I_D(n)$ versus the current at $(n+1)^{th}$ sample $I_D(n+1)$ [13-15], taking into account the autocorrelation in time series data. One normally expects the TLP points to align along a diagonal, with higher intensity clouds corresponding with each discrete drain current level present in the time series. Improved TLP can be utilized to extract the centre of the data clouds, as shown in Fig. 6, by obtaining a value related to the probability of each data point in the cloud, which means the probability of observing the $(n+1)^{th}$ sample after the $n^{th}$ sample. Moreover, a combination of the TLP with a so-called Hidden Markov modeling (HMM) approach can yield accurate RTS amplitude and time constants, even for RTSs hidden in large random noise [16].

![Fig. 5. Time series containing a large and a small RTS.](image1)

![Fig. 6. Improved Time Lag Plot (TLP) analysis of the time series, revealing four drain current levels corresponding with two RTSs.](image2)

Finally, it can be shown that for an RTS due to a trap in the gate oxide, the analysis of the time constant ratio versus gate voltage [8,17] or drain voltage [18] yields the trap position in the gate oxide with respect to the silicon/dielectric interface or along the transistor channel, respectively.
GR Noise and RTS in UTBOX SOI MOSFETs

The structure of an UTBOX SOI MOSFET is schematically represented in Fig. 7a. The study of GR noise in such devices offers some unique opportunities given the fully-depleted nature of the ~10 nm thick silicon film [11,13,19]. Usually, it is assumed that Lorentzians which do not shift markedly with gate voltage in strong inversion belong to GR centers in the silicon depletion region [1-4]. An example is given in Fig. 7b. In that case, T-dependent GR noise spectroscopy as presented above can be applied [11,13,19]. Conversely, the Lorentzians corresponding with a gate-oxide RTS exhibit a clear gate-voltage dependence, like in Fig. 7c [13]. However, as pointed out recently [20], GR noise due to defects in the fully depleted film of an UTBOX SOI transistor can also show a strong variation of the corner frequency $f_0$ with gate bias in linear operation. This is related to the fact that both the Fermi level and the free carrier concentrations undergo a strong variation with front- ($V_{GS}$) and back-gate bias ($V_{BS}$), resulting in a gate-bias dependent change in the SRH time constant of Eq. (2).

Fig. 7. (a) Schematic representation of a FD UTBOX SOI nMOSFET. (b) Lorentzian GR noise spectra for different front-gate biases in linear operation at a $V_{DS}=50$ mV and back-gate bias $V_{BS}=0$ V, showing little shift of the corner frequency and (c) showing a clear increase of the corner frequency with increasing front-gate voltage $V_{GS}$.

As a consequence, the distinction between RTS and GR noise becomes more complicated in the case of FD SOI transistors and more refined criteria have to be worked out [13,21]. A first possibility is to measure the noise in the front channel with the back channel biased in accumulation and next in the back channel current with the front channel accumulated [21]. In this way, the impact of the opposite interface and oxide is screened. When the Lorentzians are only present in one type of spectra, one may assume that they originate from traps in the corresponding oxide, while if the Lorentzians are present in both cases, there is a strong probability that the GR noise is due to defects in the fully depleted silicon film [21]. However, for ultra-thin films (<10 nm) the strong front-back coupling prevents accumulation of either of the interfaces so that this method may break down for deeply scaled technology nodes.

A second method relies on combining noise measurements with time domain measurements. At first sight, the presence of RTS in the drain current points to single traps in one of the gate oxides. Unfortunately, this criterion is also not sufficient for typical UTBOX SOI transistor sizes (i.e.,
L=0.1 \, \mu m; W=1 \, \mu m and t_{film}=10 \, nm), since the GR noise in such devices corresponds with only a few similar traps [19], as has also been derived from charge retention time measurements and modeling [22]. As a result, RTS has been found which could be ascribed to the capture and emission by a single GR center in the silicon film [19]. This has led to the development of a set of criteria, which are based on the RTS parameters and summarized in Table I [13]. One of the most important guidelines is based on the gate voltage behavior of the capture and emission time constant and their ratio. At sufficiently high drain currents, \( \tau_c \) and \( \tau_e \) become independent on \( V_{GS} \) and show a ratio close to 1, which is in strong contrast with the exponential dependence of \( \tau_c \) on \( V_{GS} \) for an oxide RTS [8,17]. An additional benefit of the exploitation of film-related RTSs is that one can derive the position of the trap in the silicon film when combining with 2D or 3D device simulations [13].

A third possibility is to analyze the gate voltage dependence of the Lorentzian parameters based on 2D numerical simulations of the FD SOI UTBOX nMOSFET characteristics including a dedicated GR noise model [20]. This enables to perform GR noise spectroscopy at room temperature.

Table 1 Variation of RTS and Lorentzian parameters for a gate oxide and a film trap with front gate voltage in UTBOX SOI nMOSFETs, at constant \( V_{DS} \).

<table>
<thead>
<tr>
<th>Parameter</th>
<th>gate oxide RTN</th>
<th>film RTN</th>
</tr>
</thead>
<tbody>
<tr>
<td>( \tau_c )</td>
<td>expon. decrease</td>
<td>moderate decrease</td>
</tr>
<tr>
<td>( \tau_e )</td>
<td>~constant</td>
<td>~constant</td>
</tr>
<tr>
<td>( \tau_c/\tau_e )</td>
<td>expon. decrease</td>
<td>~1</td>
</tr>
<tr>
<td>( \Delta I_D/I_D )</td>
<td>certain variation + nearly constant</td>
<td>decrease</td>
</tr>
<tr>
<td>( S_I(0) )</td>
<td>decrease</td>
<td>const.+ increase</td>
</tr>
</tbody>
</table>

Application of standard T-dependent GR noise spectroscopy to the UTBOX SOI nMOSFETs has revealed the presence of around ten different deep level centers [11,23,24], which are believed to be processing-related, e.g., by ion implantation of the source/drain regions or by dry etching damage. Moreover, it has recently been shown that the empirical B factor in Eq. (5) is most likely smaller for FD transistors, compared with \(~1/3\) for PD or bulk devices [24].

**GR Noise and RTS in Vertical Polysilicon MOSFETs**

Vertical polysilicon n-channel transistors are potentially of interest for 3D Non-Volatile Memory (NVM)) applications [9,10]. The structure is schematically represented in Fig. 8a, whereby the grain boundaries are a likely source of RTS in the drain current (Fig. 8b). Detailed noise measurements have indicated that there are two types of RTS present [10]: slow, large-amplitude signals, which are predominantly related to traps in the gate oxide or at the GBs and smaller amplitude signals, with faster time constants, which are believed to reside in the polysilicon channel. In order to validate this assumption, 3D device simulations have been executed, using the structure of Fig. 9, whereby the GR center location was varied along the channel between source and drain (positions A to C) and at the Si/SiO\(_2\) interface or in the center of the cylinder (primed positions A', B' and C'). The RTS amplitude \( \Delta I_D \) has been calculated as the difference in the current without \( I_D(0) \) or with \( I_D(-) \) a negatively charged electron trap present. As can be seen from Fig. 10, the RTS amplitude is a sensitive function of the trap location, so that a comparison with actually measured data should reveal the position of the trap along the channel and in diameter [10]. Again, as for oxide-related RTSs the study of the trap time constants as a function of temperature should provide the activation energy and can then be compared with DLTS results obtained on similar devices [9].
Fig. 9. (a) Schematic structure of a vertical polysilicon nMOSFET and (b) input characteristics ($I_D$-$V_G$) at fixed drain voltage $V_D=0.5$ V, showing the presence of small-amplitude RTS fluctuations.

Fig. 9. Schematic structure of a polysilicon nMOSFET with bulk trap positions.

Fig. 10. Simulated RTS amplitude as a function of gate voltage corresponding with the different trap positions between source (S) and drain (D) defined in Fig. 9.
Summary

In this paper, it has been shown that Lorentzian noise, associated with trap-assisted GR events and measured on different kinds of MOSFETs enables the study of deep levels in deeply scaled devices. Traps either in the semiconductor, at its interface(s) or in the oxide can in principle be distinguished. The advantage of employing time domain measurements is that the RTS parameters can also be exploited for deriving the trap location of the single defect responsible for it. At the same time, scaling of the device dimensions leads to small active volumes, so that RTSs in the semiconductor itself start to contribute to the noise, which opens up new perspectives for deep-level studies.

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