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Low Complexity Tail-biting Trellises for Some Extremal Self-Dual Codes

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Abstract

We obtain low complexity tail-biting trellises for some extremal self-dual codes for various lengths and fields such as the [12,6,6] ternary Golay code and a [24,12,8] Hermitian self-dual code over $GF(4)$. These codes are obtained from a particular family of cyclic Tanner graphs called necklace factor graphs.

Keywords : self-dual codes, tail-biting trellises, necklace factor graph.

1 Introduction

The representation of linear block codes by trellises is a very powerful description which allows an efficient soft decision decoding. We consider a family of codes introduced in [2] based on the use of short length codes and interleavers. From this family it is possible to extract a sub-family of codes adapted to iterative decoding. Indeed every code of this sub-family is associated with a necklace factor from which a tail-biting trellis can be deduced. Among this family, it is interesting to find codes with the best minimal distance as in [3]. Herein, we obtained some extremal self-dual codes over $GF(2)$ and \mathbb{Z}_4 .

In this paper, we extend the construction [2] to several fields and we formalize the constraints on the necklace graph given in [3] to get codes with the best minimum distances. By this way, we have low complexity tail-biting trellises for several codes like the [12,6,6] ternary Golay code and a [24,12,8] Hermitian self-dual code over $GF(4)$.

2 Necklace Factor Graph

For an introduction to factor graphs we refer the reader to [4]. We recall that a factor graph of a code C over $GF(q)$ consists of *check nodes* representing local constraints of C , and *variable nodes* which take values in an alphabet. We distinguish between two types of variable nodes: *symbol nodes* which are associated with the symbol of the codewords of C and *state nodes* which are used for computing the codewords of C but which are not transmitted. A variable node is *adjacent* to a check node if the corresponding variable is involved in the corresponding local constraint.

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lemma 1 Any necklace factor graph $N_t(C)$ of a code C can be put into the form of a t -section tail-biting trellis $T_t(C)$.

Proof It is sufficient to group together variable nodes and check nodes of the same level (see Figure 2) to obtain a new factor graph which is basically a tail-biting trellis. □

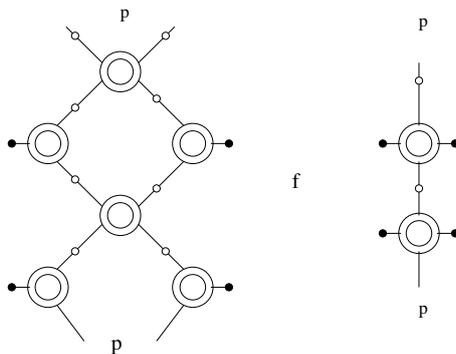


Figure 2: Transformation of a necklace graph into a tail-biting trellis.

There exist several types of complexity for a tail-biting trellis ([1]). We are only interested in the maximum state complexity.

Definition 1 Let T be a t -section tail-biting trellis with state spaces S_0, \dots, S_{t-1} . The maximum state complexity \mathcal{S}_{max} of T is defined as

$$\mathcal{S}_{max} = \max\{|S_0|, \dots, |S_{t-1}|\}.$$

lemma 2 Let C be a $[N, K, D]$ linear code over $GF(q)$ with necklace graph $N_t(C)$ obtained from a $[n, k, d]$ linear code B . Each states space of the tail-biting trellis $T_t(C)$ deduced from $N_t(C)$ is of size q^k and therefore \mathcal{S}_{max} is equal to q^k states.

The following table gathers the parameters of the obtained codes along with the complexities of their associated tail-biting trellises.

q	B	C	t	$\mathcal{S}_{max}(T_t(C))$
3	[4,2,3]	[8,4,3]	2	3^2
3	[4,2,3]	[12,6,6]	3	3^2
3	[4,2,3]	[16,8,6]	4	3^2
3	[4,2,3]	[20,10,6]	4	3^2
3	[12,6,6]	[24,12,9]	2	3^6
4 Euclidean	[4,2,3]	[8,4,3]	2	4^2
4 Euclidean	[4,2,3]	[12,6,6]	3	4^2
4 Euclidean	[4,2,3]	[16,8,6]	4	4^2
4 Hermitian	[6,3,4]	[12,6,4]	2	4^3
4 Hermitian	[8,4,4]	[24,12,8]	3	4^4
5	[6,3,4]	[18,9,6]	3	5^3
5	[8,4,4]	[24,12,8]	3	5^4

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