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Cauchy-Gelfand problem for quasilinear conservation law.

G.M. Henkin\textsuperscript{a,1,*} and A.A. Shaninin\textsuperscript{b,1}

**Abstract.** We obtain the precise asymptotic ($t \to \infty$) for solution $f(x,t)$ of Cauchy-Gelfand problem for quasilinear conservation law \( \frac{\partial f}{\partial t} + \varphi(f) \frac{\partial f}{\partial x} = 0 \) with initial data of bounded variation $f(x,0) = f^0(x)$. The main theorem develops results of T.-P. Liu (1981), Kruzhkov, Petrosjan (1987), Henkin, Shaninin (2004), Henkin (2012). Proofs are based on vanishing viscosity method and localized Maxwell type conservation laws. The main application consists in the reconstruction of parameters of initial data responsible for location of inviscid shock waves in the solution $f(x,t)$.

AMS subject classification: 35K55; 35L65; 35Q20; 35R10; 39A; 76D

Key words: Riemann-Burgers type equations, fluid mechanics, quasilinear conservation law, Cauchy-Gelfand problem, difference-differential equations, vanishing viscosity method, shock waves

\textsuperscript{a} Université Pierre et Marie Curie, case 247, 75252, Paris, France and CEMI, Academy of Science, 117418, Moscow, Russia

\textsuperscript{*} corresponding author: e-mail address: henkin@math.jussieu.fr

\textsuperscript{b} Moscow Institute of Physics and Technology, 141700, Dolgoprudny, Russia, e-mail address: alexshan@yandex.ru

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Introduction.

We study Cauchy (and inverse Cauchy) problem for equation

\[ \frac{\partial f}{\partial t} + \varphi(f) \frac{\partial f}{\partial x} = 0, \quad x \in \mathbb{R}, \quad t \geq 0 \]  

(*)

with initial data \( f(x,0) = f^0(x) \). The most natural (not equivalent) definitions for solutions of problem (*) consists in the existence of solutions \( f \overset{\text{def}}{=} f_\varepsilon(x,t) \) for equations

\[ \frac{\partial f}{\partial t} + \varphi(f) \frac{\partial f}{\partial x} = \varepsilon \frac{\partial^2 f}{\partial x^2}, \quad \varepsilon > 0, \quad x \in \mathbb{R}, \]  

(1a) or

\[ \frac{df}{dt} + \varphi(f) \frac{f(x,t) - f(x-\varepsilon,t)}{\varepsilon} = 0, \quad x \in \mathbb{R}, \]  

(1b)

with property

\[ f_\varepsilon(x,0) = f^0(x), \quad \varepsilon \geq 0, \]  

(2)

such that \( f_\varepsilon(x,t) \rightarrow f_0(x,t) \), when \( \varepsilon \rightarrow +0 \).

Equation (1a) with linear \( f \mapsto \varphi(f) \) was introduced at first by Riemann (1860) (for \( \varepsilon = +0 \)) and later by Bateman (1915), Burgers (1939) and Hopf (1950) (for \( \varepsilon > 0 \)) as the simplest approximation to the equations of fluid dynamics.

Equation (1a) for general \( \varphi(f) \) was introduced later in a very different models: displacements of oil by water (Buckley, Leverett, 1942), consolidation of wet soil (Florin, 1948), the road traffic (Lighthill, Whitham, 1955) etc. Equation (1b) was introduced by Polterovich, Henkin, 1988, for description of a Schumpeterian evolution of industry. In physical applications of (1a) the main interest has the inviscid case, when \( \varepsilon = +0 \), but the application of (1a) in the transport flow theory and of (1b) in Schumpeterian dynamics the main interest presents the viscid case, when \( \varepsilon > 0 \).

It is important to remark that behavior of solutions of (1b) with \( \varepsilon = +0 \) is not the same as the behavior of solutions of (1a) with \( \varepsilon = +0 \), in spite that for \( \varepsilon = 0 \) the both equations (1a), (1b) look identical.

In fact, equation (1b) is a semi-discrete approximation of the non conservative equation

\[ \frac{\partial f}{\partial t} + \varphi(f) \frac{\partial f}{\partial x} = \varepsilon \frac{\varphi(f)}{2} \frac{\partial^2 f}{\partial x^2}. \]

Assumption 1.

Let \( \alpha^- < \alpha^+ \), \( f^0(x) \) be real-valued function of bounded variation on \( \mathbb{R} \) such that \( f^0(x) = \alpha^\pm \), if \( \pm x \geq \pm x^\pm \), \( x^- < x^+ \). Let \( \varphi(f) \) be a positive, continuous differentiable function of real variable \( f \) such that \( \varphi'(f) \) has only isolated zeros.

Theorem ([5], [19], [10], [11]).

Under assumption 1 and \( \forall \varepsilon > 0 \) the following general properties of Cauchy problems (1a,b) are valid.
a) Cauchy problem (1a), (2) has a unique (weak) solution \( f(x,t), x \in \mathbb{R}, t \in \mathbb{R}_+ \). This solution satisfies Rankine-Hugoniot conservation laws for \( t \geq 0 \):

\[
f(x,t) \to \alpha^\pm, \text{ if } x \to \pm\infty, \text{ and } \int_{-\infty}^{0} (\alpha^- - f(x,t))dx + \int_{0}^{\infty} (\alpha^+ - f(x,t))dx = \int_{\alpha^-}^{\alpha^+} \varphi(y)dy.
\]

Moreover, if the initial data \( f^0(x) \) is nondecreasing in \( x \) then \( f(x,t) \) is nondecreasing in \( x \forall t \geq 0 \).

b) Cauchy problem (1b), (2) has a unique (weak) solution \( f(x,t), x \in \mathbb{R}, t \in \mathbb{R}_+ \). This solution satisfies the following conservation laws for \( t \geq 0 \) and \( \theta \in [0,1) \):

\[
f(k \varepsilon + \theta \varepsilon, t) \to \alpha^\pm, \text{ if } k \to \pm\infty, \ k \in \mathbb{Z}, \text{ and } \int_{-\infty}^{0} \sum_{f(k \varepsilon + \theta \varepsilon, t)} \int_{\alpha^-}^{\alpha^+} \frac{dy}{\varphi(y)} + \int_{0}^{\infty} \sum_{f(k \varepsilon + \theta \varepsilon, t)} \frac{dy}{\varphi(y)} = \frac{1}{\varepsilon} (\alpha^+ - \alpha^-).
\]

Moreover, if for some \( \theta \in [0,1) \) the initial data \( f^0(k \varepsilon + \theta \varepsilon, t) \) is nondecreasing in \( k \in \mathbb{Z} \), then \( f(k \varepsilon + \theta \varepsilon, t) \) is nondecreasing in \( k \in \mathbb{Z} \) with the same \( \theta \).

Put

\[
\psi(u) = -\int_{\alpha^-}^{u} \varphi(y)dy, \ u \in [\alpha^-,\alpha^+], \text{ for (1.a)}, \quad (3a)
\]

\[
\psi(u) = \int_{\alpha^-}^{u} \frac{dy}{\varphi(y)}, \ u \in [\alpha^-\alpha^+], \text{ for (1.b)}, \quad (3b)
\]

Let us introduce respectively for (3a) and for (3b) the concave function \( \hat{\psi}(u) \) as the upper bound of the convex hull of the set

\[
\{(u,v): \ v \leq \psi(u), \ u \in [\alpha^-,\alpha^+]\}.
\]

**Assumption 2.** Suppose that for (3a) and respectively for (3b) the set

\[
S = \{u \in [\alpha^-,\alpha^+]: \ \psi(u) < \hat{\psi}(u)\}
\]

has the following form

\[
S = (\alpha_0^-,\alpha_0^+) \cup (\alpha_1^-,\alpha_1^+) \cup \ldots (\alpha_L^-,\alpha_L^+), \text{ where } \alpha^- = \alpha_0^- < \alpha_0^+ < \alpha_1^- < \alpha_1^+ < \ldots < \alpha_{L-1}^- < \alpha_{L-1}^+ < \alpha_L^- < \alpha_L^+ = \alpha^+.
\]

Let

\[
c_l = \frac{1}{\alpha_l^+ - \alpha_l^-} \int_{\alpha_l^-}^{\alpha_l^+} \varphi(y)dy, \text{ for (1a), } \ l = 0,\ldots, L, \quad (5a)
\]

\[
c_l = (\alpha_l^+ - \alpha_l^-) \left( \int_{\alpha_l^-}^{\alpha_l^+} \frac{dy}{\varphi(y)} \right)^{-1}, \text{ for (1b), } \ l = 0,\ldots, L. \quad (5b)
\]
Assumptions 1, 2 and notation (5a,b) imply the following important inequalities (for (1a)) and respectively for (1b):

\[
\varphi(\alpha_i^+) \leq c_l \leq \varphi(\alpha_i^-), \quad l = 0, \ldots, L,
\]

\[
c_l = \varphi(\alpha_i^-), \quad l = 1, \ldots, L,
\]

\[
c_l = \varphi(\alpha_i^+), \quad l = 0, \ldots, L - 1.
\]

(6)

Let us remark that the inequalities above are, in fact, equalities except for the cases \(l = 0\) and \(l = L\).

Motivated by models of fluid mechanics Gelfand, [5], had formulated the following problem:

\(\forall \varepsilon \geq 0\) to find asymptotic \((t \to \infty)\) of solution \(f(x,t)\) of equation (1a) with initial condition (2).

Gelfand had found solution of this problem for the case \(\varepsilon = +0\) with special (Riemann type) initial conditions

\[f(x,0) = \begin{cases} 
\alpha^-, & \text{if } x < x_0 \\
\alpha^+, & \text{if } x > x_0
\end{cases}
\]

and had noted that it would be interesting to prove that the main term of the asymptotic \((t \to \infty)\) of \(f(x,t)\), satisfying (1a),(2), coincides with the solution of (1a), (2) with \(\varepsilon = +0\).

Motivated by models of economical development similar problems were considered later [11], [12] for equation (1b).

**Theorem.** (Gelfand, 1959).

Under assumptions 1, 2, solution of (1a) with \(\varepsilon = +0\) with initial condition (2):

\(f(x,0) = \alpha^\pm,\) if \(\pm(x-x_0) > 0,\) has the following form:

\[f(x,t) = \begin{cases} 
\alpha^-, & \text{if } x - x_0 < c_0 t \\
\alpha^+, & \text{if } x - x_0 \geq c_L t \\
\varphi^{-1}(\frac{x-x_0}{t}), & \text{if } c_l t \leq x - x_0 < c_{l+1} t, \quad 0 \leq l < L.
\end{cases}
\]

The Gelfand problem for (1a), (2) with \(\varepsilon \geq 0\) and with monotonic \(\varphi(f)\) was solved by Iljin and Oleinik [16].

**Theorem** (Iljin, Oleinik, 1960).

Let under assumptions 1, 2 \(f\) be solution of (1a), (2), \(\varepsilon = +0\) and \(\varphi'(f) < 0\). Then \(\exists t_0 > 0\) such that

\[f(x,t) = \begin{cases} 
\alpha^-, & \text{if } x < ct + x_0 \\
\alpha^+, & \text{if } x > ct + x_0, \quad t \geq t_0
\end{cases}
\]

where shift parameter \(x_0\) is determined by Maxwell formula:

\[
\int_{-\infty}^{x_0} (f^0(x) - \alpha^-) dx + \int_{x_0}^{\infty} (f^0(x) - \alpha^+) dx = 0.
\]
and $c$ is determined by Rankine-Hugoniot formula

$$c = \frac{1}{\alpha^+ - \alpha^-} \int_{\alpha^-}^{\alpha^+} \varphi(y) dy.$$ 

For semi-discrete initial problem (1b), (2) with $\varepsilon \geq 0$ the analogues of the Iljin-Oleinik results had been obtained in [11].

The following result of Kruzhkov and Petrosjan [17] gives solution of Gelfand problem for equation (1a) with $\varepsilon = +0$ and with nondecreasing initial data (2).

**Theorem** (Kruzhkov, Petrosjan, 1987).

Let under assumptions 1, 2, $f(x,t)$ be solution of the Cauchy problem (1a), (2) with $\varepsilon = +0$ and with nondecreasing initial data function $f_0(x)$. Let $\tilde{f}(x,t)$ be solution of the Cauchy problem (1a), (2) with $\varepsilon = +0$, where the function $\varphi \overset{def}{=} -\psi'$ is replaced by the function $\tilde{\varphi} = -\hat{\psi}'$ and the initial function $f_0(x)$ is replaced by the function

$$\tilde{f}_0(x) = u_1 \chi(-\infty,x_1)(x) + u_2 \chi(x_1,x_2)(x) + \ldots + u_m \chi(x_{m-1},+\infty)(x),$$

where

$$x_i = \frac{F_0^*(u_{i+1}) - F_0^*(u_i)}{u_{i+1} - u_i}, \quad i = 1, \ldots, m - 1, m = 2L + 2,$$

$$u_1 = \alpha_0^-, \quad u_2 = \alpha_0^+, \ldots, \quad u_{m-1} = \alpha_L^-, \quad u_m = \alpha_L^+,$$

$$F_0(y) = \int_0^y f_0(x) dx, \quad F_0^*(p) = \sup_{p \in \mathbb{R}} \{py - F_0(y)\},$$

$$\chi(a,b) \text{ is the characteristic function of } (a,b) \subset \mathbb{R}.$$ 

Then $\|f(\cdot,t) - \tilde{f}(\cdot,t)\|_{L_1(\mathbb{R})} \to 0$, $t \to \infty$ and the asymptotic locations

$$\{c_l t + d_l, \quad l = 0, 1, \ldots, L\}$$

of shock waves for $f(x,t)$ coincide with the asymptotic locations of shock waves for $\tilde{f}(x,t)$, and so the shifts $d_l$, $l = 0, \ldots, L$, can be found explicitly.

**Remark 1.**

The proof of Theorem in [17] is based on the explicit formula of E.Hopf [15] and M.Bardi, L.C.Evans [2] for the solutions of (1a), (2) with $\varepsilon = +0$ and nondecreasing initial data $f_0(x)$

$$f(x,t) = \frac{\partial}{\partial x} \sup_{p \in \mathbb{R}} I(t,x,p),$$

where

$$I(t,x,p) = (px + \psi(p)t) - \sup_{y \in \mathbb{R}} \{py - F_0(y)\}, \quad F_0(y) = \int_0^y f_0(x) dx.$$ 

**Remark 2.**
initial data valid for piecewise smooth solutions of the problem (1a), (2) with not necessary monotonic
valid

Assumption 3. Let for (1a) and respectively for (1b) the following inequalities be valid

\[ \varphi'(\alpha_l^-) \neq 0, \quad l = 1, \ldots, L, \]
\[ \varphi'(\alpha_l^+) \neq 0, \quad l = 0, 1, \ldots, L - 1, \]
\[ \varphi(\alpha_0^-) \neq c_0, \quad \text{if} \quad \alpha_0^- < \alpha_0^+, \]
\[ \varphi(\alpha_L^-) \neq c_L, \quad \text{if} \quad \alpha_L^- < \alpha_L^+. \]

By developing of [17] and of [7], we obtain here the following

Main theorem.

i) Under the assumptions 1, 2, 3, the solutions \( f(x, t) \) of the Cauchy-Gelfand problem

\[ (1a,b), (2) \]

with \( \varepsilon = +0 \) have the following asymptotic structure

\[ \| f(\cdot, t) - \tilde{f}(\cdot, t) \|_{L^1(\mathbb{R})} \to 0, \quad t \to \infty, \]

\[ \tilde{f}(x, t) = \begin{cases} 
\alpha^-, & \text{if} \ x < c_0t + d_0 \\
\varphi^{(-1)}(x/t), & \text{if} \ c_l t + d_l \leq x < c_{l+1} t + d_{l+1}, \ l = 0, 1, \ldots, L - 1 \\
\alpha^+, & \text{if} \ x \geq c_L t + d_L, 
\end{cases} \]

where parameters \( \{c_l\} \) determined by (5a) (respectively by (5b)), parameters \( \{d_l\} \) are determined by the respective equations (1a,b) and initial data (2a, 2b).

ii) Moreover, \( \exists \ t^* \geq 0 \) such that parameters \( \{d_l\} \) for problem (1a), (2a) are determined for \( t \geq t^* \) by Maxwell type formulas

\[ c_l t + d_l(t) \]

\[ \int_{x = y_l^- (t)}^{y_l^+ (t)} (f(x, t) - \alpha_l^-) dx + \int_{x = c_l t + d_l(t)} (f(x, t) - \alpha_l^+) dx = 0, \]

\[ f(y_l^- (t), t) = \alpha_l^-, \quad f(y_l^+ (t), t) = \alpha_l^+, \quad \text{where} \quad d_l(t) = d_l(t^*) \quad \text{if} \quad t \geq t^*, \]

and parameters \( \{d_l\} \) for problem (1b), (2b) are determined for \( t \geq t^* \) by formulas

\[ c_l t + d_l(t) \]

\[ \int_{x = y_l^- (t)}^{y_l^+ (t)} [\Psi(f(x, t)) - \Psi(\alpha_l^-)] dx + \int_{x = c_l t + d_l(t)} [\Psi(f(x, t)) - \Psi(\alpha_l^+)] dx = 0, \]

where \( \Psi(f) = \int_{-}^{f} \frac{dy}{\varphi(y)}, \quad d_l(t) = d_l(t^*) \quad \text{if} \quad t \geq t^*. \)

The crucial statement of main theorem consists in the equalities \( d_l(t) = d_l(t^*) \), if \( t \geq t^*. \)
Remark 3.
Theorem of Kruzhkov, Petrosjan [17] is the corollary of main theorem, because for nondecreasing initial data parameter \( t^* \) in the part ii) of main theorem can be taken by zero.

Remark 4.
Early T.-P.Liu [18] and A.V.Gasnikov [4] had obtained (only under assumption 1) a rough versions of part i) of main theorem with shift functions \( d_i(t) = o(t) \) instead of constant shifts \( d_i \).

1. Comparison result.
For the proof of the main theorem we need the following comparison result developing Proposition 1 from [6].

Theorem 1.
Under the assumptions 1-3 and definitions (3a,b)-(5a,b) \( \forall \) solution \( f = f_\varepsilon(x,t) \) of (1b), (2) (respectively (1a), (2)) \( \exists t_0 > 0 \) such that \( \forall t \geq t_0, \forall \varepsilon > 0 \) and for \( \gamma > 0 \), \( b_1 > O(1/\gamma) \), \( l = 0, \ldots, L \), the following estimate is valid:

\[
\varphi^{-1}\left(\frac{x - \gamma \sqrt{\varepsilon} t}{t}\right) \leq f_\varepsilon(x,t) \leq \varphi^{-1}\left(\frac{x + \gamma \sqrt{\varepsilon} t}{t}\right),
\]  

(1.1)
for \( x \in [c_1 t + b_1 \sqrt{\varepsilon} t, c_{l+1} t - b_{l+1} \sqrt{\varepsilon} t] \).

For the proof of Theorem 1 we can not just apply rescaling of corresponding Proposition 1 from [6], because now we must take into account that under conditions of Theorem 1 initial function \( f^0(x) = f(x,0) \) is independent of \( \varepsilon > 0 \). So, we will follow the scheme of the proof of Proposition 1 from [6], precising the dependence of all parameters on \( \varepsilon > 0 \). We will give detailed proof only for the case of equation (1b), (2) with \( \varepsilon > 0 \), \( L = 1 \),

\[
\varphi(\alpha_0^-) > c_0 = \varphi(\alpha_0^+), \quad \varphi(\alpha_1^-) = c_1 > \varphi(\alpha_1^+).
\]

The following statement generalizes essentially Proposition 1 of [8].

Lemma 1. Under assumptions of Theorem 1, let \( L = 1 \); \( \alpha_0^- < \alpha_0^+ < \alpha_1^- < \alpha_1^+ \); and let \( c_0, c_1 \) be the parameters defined by (3b), (4b), (5b). Put

\[
\Delta_\varepsilon f(x,t) = \frac{f_\varepsilon(x,t) - f_\varepsilon(x, - \varepsilon t)}{\varepsilon}.
\]

Let \( \tilde{f}_i(x - c_1 t) \) be travelling wave solutions of (1b) such that \( \tilde{f}_i(x) \to \alpha_i^\pm, \; l = 0, 1, \; x \to \pm \infty \) and \( \tilde{f}_i(0) = \frac{\alpha_i^- + \alpha_i^+}{2} \) (see Prop. 0 in [6]). Consider the following functions \( f^\pm(x,t) \), depending also on parameters \( \{\alpha_i^\pm\}, \{c_l\}, \; l = 0, 1 \), positive small parameters \( \gamma \) and \( \delta \) and positive bounded functions \( b_0^\pm(t), b_1^\pm(t) \):

\[
f^-(x,t) = \begin{cases} 
 f_0^-(x,t) = \tilde{f}_0\left(\frac{x - c_0 t}{\varepsilon}\right), & -\infty < x < c_0 t + b_0^- \sqrt{\varepsilon} t, \\
 f_1^-(x,t) = \varphi^{-1}\left(\frac{x - \gamma \sqrt{\varepsilon} t}{t}\right) - \varphi'(\alpha_0^+)(x - c_0 t), & \text{where } c_0 t + b_0^- \sqrt{\varepsilon} t \leq x \leq c_1 t + b_1^- \sqrt{\varepsilon} t, \\
 f_1^-(x,t) = \tilde{f}_1\left(\frac{x - c_1 t - (2\sqrt{\varepsilon} t + \gamma + 2\delta) \sqrt{\varepsilon} t}{\varepsilon}\right), & c_1 t + b_1^- \sqrt{\varepsilon} t < x < +\infty.
\end{cases}
\]  

(1.2)
Then the following statements are valid:
i) \( \forall \gamma, \delta > 0 \ \exists \ \text{functions} \)

\[
\begin{align*}
b_0^{-}(t) &= \gamma + o(1), \\
b_1^{-}(t) &= \gamma + \sqrt{c_1} + \delta + \sqrt{\delta^2 + 2\delta \sqrt{c_1}} + o(1), \\
b_0^{+}(t) &= \gamma + \sqrt{c_0} + \delta + \sqrt{\delta^2 + 2\delta \sqrt{c_0}} + o(1), \\
b_1^{+}(t) &= \gamma + o(1),
\end{align*}
\]

satisfying for \( t \geq \tilde{t}_0 \varepsilon = t_0 \) and \( \theta \in [0, 1] \) relations:

\[
\begin{align*}
f_0^{-}(c_0 t + b_0^{-} \sqrt{\varepsilon} t, t) &= f_0^{-}(c_0 t + b_0^{+} \sqrt{\varepsilon} t, t) \\
\Delta_x f_0^{-}(c_0 t + b_0^{-} \sqrt{\varepsilon} t + \varepsilon \theta, t) &= \Delta_x f_0^{-}(c_0 t + b_0^{+} \sqrt{\varepsilon} t + \varepsilon \theta, t) \\
f_0^{-}(c_1 t + b_1^{-} \sqrt{\varepsilon} t, t) &= f_0^{-}(c_1 t + b_1^{+} \sqrt{\varepsilon} t, t) \\
\Delta_x f_0^{-}(c_1 t + b_1^{-} \sqrt{\varepsilon} t + \varepsilon \theta, t) &= \Delta_x f_0^{-}(c_1 t + b_1^{+} \sqrt{\varepsilon} t + \varepsilon \theta, t); \\
f_0^{+}(c_0 t - b_0^{-} \sqrt{\varepsilon} t, t) &= f_0^{+}(c_0 t - b_0^{+} \sqrt{\varepsilon} t, t) \\
\Delta_x f_0^{+}(c_0 t - b_0^{-} \sqrt{\varepsilon} t + \varepsilon \theta, t) &= \Delta_x f_0^{+}(c_0 t - b_0^{+} \sqrt{\varepsilon} t + \varepsilon \theta, t) \\
f_0^{+}(c_1 t - b_1^{-} \sqrt{\varepsilon} t, t) &= f_0^{+}(c_1 t - b_1^{+} \sqrt{\varepsilon} t, t) \\
\Delta_x f_0^{+}(c_1 t - b_1^{-} \sqrt{\varepsilon} t + \varepsilon \theta, t) &= \Delta_x f_0^{+}(c_1 t - b_1^{+} \sqrt{\varepsilon} t + \varepsilon \theta, t).
\end{align*}
\]

ii) \( \forall \gamma, \delta > 0 \) and with \( b_0^{\pm}, b_1^{\pm} \) from i) \( \exists \tilde{t}_0 > 0 \) such that the functions \( f^\pm(x, t), \)

\( x \in \mathbb{R}, \ t \geq \tilde{t}_0 \varepsilon, \) are sub(super)solutions for (1b), i.e.

\[
\pm \left[ \frac{df^\pm}{dt} + \varphi(f^\pm) \left( \frac{f^\pm(x, t) - f^\pm(x - \varepsilon, t)}{\varepsilon} \right) \right] \geq 0. \tag{1.6}
\]

**Complement.** Lemma 1 is also valid for equation (1a) if in definitions of \( f_0^{\pm}(x, t) \)

numerators \( c_0, c_1 \) are replaced by 2, the differences \( \Delta_x f_0^{\pm}, \Delta_x f_1^{\pm} \) by derivatives \( \frac{\partial f_0^{\pm}}{\partial x}, \frac{\partial f_0^{\pm}}{\partial x}, \frac{\partial f_1^{\pm}}{\partial x} \) and inequality (1.6) in ii) by inequality

\[
\pm \left[ \frac{\partial f^\pm}{\partial t} + \varphi(f^\pm) \frac{\partial f^\pm}{\partial x} - \varepsilon \frac{\partial^2 f^\pm}{\partial x^2} \right] \geq 0.
\]
Proof.
Lemma 1 of this paper follows from Lemma 1 of [6], by simple rescaling
\[ \tilde{t} \to \frac{t}{\varepsilon}, \quad \tilde{x} \to \frac{x}{\varepsilon}, \quad \tilde{t}_0 \to \frac{t_0}{\varepsilon}. \]

Lemma 1 is proved.

Let further function \( f \mapsto \varphi(f) \) be extended outside \([\alpha^-, \alpha^+]\) keeping assumption 1 and the condition \( \varphi'(f) < 0 \), if \( f \leq \alpha^- \) or \( f \geq \alpha^+ \).

By results of [5], [19], [11], (see Prop. 0 in [6]) \( \forall \) small \( \sigma > 0 \) \( \exists \) travelling type sub(super)solutions of (1b) (resp. of (1a)) of the form
\[ \tilde{f}_{l,\sigma}^\pm \left( \frac{x - c_l^\pm t}{\varepsilon} \mp d\left( \frac{t}{\varepsilon} \right) \right) \] (1.7)

with overfalls \([\alpha_l^- \mp (-1)^l \sigma, \alpha_l^+ \pm (-1)^l \sigma] \) and \( \tilde{f}_{l,\sigma}^\pm (0) = \frac{1}{2}(\alpha_l^- + \alpha_l^+), l = 0, 1. \)

For parameters \( c_{l,\sigma}^\pm \) we have \( c_{l,\sigma}^\pm = c_l(1 \pm O_+ (\sigma)) \).

Let us replace in the definitions of \( f^\mp (x, t) \) in the statement of Lemma 1 the travelling waves \( \tilde{f}_l(x - c_l t) \), \( l = 0, 1, \) by \( \sigma \)-modified travelling sub(super)solutions (1.7) and rare type functions \( f_{01}^\mp (x, t) \) by the \( \sigma \)-modified rare type sub(super)solutions for (1b) (resp. (1a)) of the form
\[ f_{01,\sigma}^\pm (x, t) = \varphi(-1) \left( \frac{x - \gamma \sqrt{\varepsilon} t}{t} \right) - \frac{c_{0,\sigma}^\pm \varepsilon}{\varphi'(\alpha_{0,\sigma}^-)(x - c_{0,\sigma}^- t)} \] (1.8)

\[ f_{01,\sigma}^\pm (x, t) = \varphi(-1) \left( \frac{x + \gamma \sqrt{\varepsilon} t}{t} \right) + \frac{c_{1,\sigma}^\pm \varepsilon}{\varphi'(\alpha_{1,\sigma}^-)(c_{1,\sigma}^- t - x)}. \]

Lemma 2.
Let \( f_{l,\sigma}^\mp (x, t) \) be functions of the form (1.2), (1.3), where parameters \( \alpha_l^\pm, \) \( c_l, \) \( b_l^\pm, l = 0, 1, \)
are replaced by the \( \sigma \)-modified parameters:
\[ \alpha_{l,\sigma}^\pm = \alpha_l^- \mp (-1)^l \sigma, \quad \alpha_{l,\sigma}^\pm = \alpha_l^+ \pm (-1)^l \sigma, \]
\[ b_{l,\sigma}^\pm = b_l^\pm \pm O_+ (\sigma), \]
\[ c_{l,\sigma}^\pm = c_l(1 \pm O_+ (\sigma)). \] (1.9)

Put \( \sigma \left( \frac{t}{\varepsilon} \right) = \frac{\rho}{\varepsilon} \) and \( d\left( \frac{t}{\varepsilon} \right) = \rho (\ln \frac{t}{\varepsilon}), \rho \geq \rho_0. \) Then functions \( f_{l,\sigma}^\mp (x, t) \) satisfy \( \sigma \)-modified relations i), ii) from Lemma 1, if parameter \( \tilde{t}_0 = \frac{t_0}{\varepsilon} \) are big enough.

Proof. \( \sigma \)-modified relation i) for \( f_{l,\sigma}^\mp (x, t) \) follows from non-modified relations (1.4), (1.5), taking into account that modified parameters (1.9) coincide with non-modified parameters up to \( O\left( \frac{t}{\varepsilon} \right) \). Taking parameter \( \tilde{t}_0 = \frac{t_0}{\varepsilon} \) big enough permits to keep sense of strict inequalities in modified relations (1.4), (1.5), i.e. in i). \( \sigma \)-modified relation ii) follows from \( \sigma \)-modified relation i), from non-modified estimates (1.6) and from estimates of derivatives
\[ \frac{\partial}{\partial t} d\left( \frac{t}{\varepsilon} \right) > 0, \quad \frac{\partial}{\partial t} \sigma\left( \frac{t}{\varepsilon} \right) < 0. \]
permitting to keep sense of \( \sigma \)-modified inequalities (1.6), if parameter \( \tilde{t}_0 = \frac{t_0}{\varepsilon} \) is big enough.

**Lemma 3.**
Let \( f = f(x,t) \) be solution of (1b), (2) (resp. (1a),(2)) with \( L = 1 \). Let \( \sigma(t) = \frac{\varepsilon}{t} \), \( d(t) = \rho(\ln \frac{\varepsilon}{t}) \). If parameters \( \tilde{t}_0 = \frac{t_0}{\varepsilon} \) and \( \rho \) are big enough, then function \( f(x,t) \) satisfies for all \( c > c_1 \) the following inequalities:

\[
\begin{align*}
    f_\sigma^-(x,t) &< f(x,t) < f_\sigma^+(x,t), \quad x \leq 0, \quad t \geq t_0, \\
    f_\sigma^-(ct,t) &< f(ct,t) < f_\sigma^+(ct,t), \quad x = ct, \quad t \geq t_0.
\end{align*}
\]

**Proof.**
For proving (1.10) it is sufficient to prove inequalities

\[
\begin{align*}
    f_\sigma^-(x,t) &< \alpha_0^-, \quad f_\sigma^+(x,t) > \alpha_0^-, \quad \text{if} \quad x \leq 0, \quad t \geq \tilde{t}_0\varepsilon, \\
    f_\sigma^-(ct,t) &< \alpha_1^-, \quad f_\sigma^+(ct,t) > \alpha_1^-, \quad \text{if} \quad t \geq \tilde{t}_0\varepsilon.
\end{align*}
\]

If \( x \leq 0 \) and parameters \( \tilde{t}_0 = \frac{t_0}{\varepsilon} \) and \( \rho \) are big enough, then definitions above imply existence of \( \lambda_0 > 0 \) independent of \( \varepsilon \) such that

\[
\begin{align*}
    f_\sigma^-(x,t) = \tilde{f}_{0,\sigma}^-(x - c_0^-\varepsilon t - d(\varepsilon)) &\leq \tilde{f}_{0,\sigma}^-(c_0^-\varepsilon - d(\varepsilon)) - \lambda_0\varepsilon \ln \frac{t}{\varepsilon} \\
    \alpha^- - \sigma &+ O(\exp [-\lambda_0 c_0^+\varepsilon - \lambda_0\rho \ln \frac{t}{\varepsilon}]) \leq \\
    \alpha^- - \varepsilon \frac{\rho}{\lambda_0} + O(\exp [-(\lambda_0 c_0^-\varepsilon)^{\rho\lambda_0}])(\frac{\varepsilon}{t_0})^{\rho\lambda_0} &< \alpha^-,
\end{align*}
\]

if \( \rho > \frac{1}{\lambda_0} \) and \( \tilde{t}_0 = \frac{t_0}{\varepsilon} - \text{big enough} \).

Note, that by estimate (6.3) from [13], parameter \( \lambda_0 \) can be chosen up to \( O(\frac{\varepsilon}{t}) \) equal to solution \( \lambda_0 \) of the equation

\[
\lambda_0 = \varphi(\alpha^-_0)\psi(\alpha^-_0, \alpha^+_0)(1 - e^{-\lambda_0}),
\]

where

\[
\psi(\alpha^-_0, \alpha^+_0) = \left(\frac{1}{\alpha^+_0 - \alpha^-_0}\right) \int_{\alpha^-_0}^{\alpha^+_0} \frac{dy}{\varphi(y)}.
\]

For \( f_\sigma^+(x,t), \ x \leq 0 \), estimate follows more easily

\[
\begin{align*}
    f_\sigma^+(x,t) = \tilde{f}_{0,\sigma}^+(x - c_0^+\varepsilon t + 2(\sqrt{c_0^+\varepsilon} + \gamma + 2\delta)(\frac{t}{\varepsilon})^{1/2} + d(\varepsilon)) &\geq \alpha^-_0 + \sigma > \alpha^-_0,
\end{align*}
\]

if \( \tilde{t}_0 \) big enough.

Inequalities (1.11) are proved.
Let us prove (1.12) by the similar way.
For $c > c_1$, $x = ct$ and $\tilde{t}_0 = \frac{t_0}{\varepsilon}$ we have

$$f^-_{\sigma}(ct, t) = \tilde{f}_{1, \sigma}(\frac{x}{\varepsilon} - c_{1, \sigma} \frac{t}{\varepsilon} - d(\frac{t}{\varepsilon})) < \alpha^+_{1} - \sigma < \alpha^+_{1},$$

$$f^+_{\sigma}(ct, t) = \tilde{f}^+_{1, \sigma}(c(\frac{t}{\varepsilon} - c_{1, \sigma} \frac{t}{\varepsilon}) + d(\frac{t}{\varepsilon})) = \tilde{f}^+_{1, \sigma}(c(\frac{t}{\varepsilon} - c_{1}(1 - O(\frac{\varepsilon}{t})) \frac{t}{\varepsilon} + \rho \ln \frac{t}{\varepsilon}) \geq$$

$$\alpha^+_{1} + \sigma - O(\exp [(-\lambda_1(c - c_1) \frac{t}{\varepsilon} + \lambda_1 \rho \ln \frac{t}{\varepsilon}]) \geq$$

$$\alpha^+_{1} + \frac{\varepsilon}{t} - O(\exp [(-\lambda_1(c - c_1) \frac{t}{\varepsilon}) O((\frac{\varepsilon}{t})^{\rho \lambda_1}) > \alpha^+_{1},$$

if $\rho > \frac{1}{\lambda^2_1}$ and $\tilde{t}_0 = \frac{t_0}{\varepsilon}$ big enough.

Inequalities (1.12) are proved.

Lemma 3 is proved.

**Lemma 4.**
Under conditions of Lemmas 1, 2 $\exists T > 0$ (independent of $\varepsilon > 0$) such that for $t \geq T$ function $f = f_\varepsilon(x, t)$ satisfies inequalities

$$f^-_{\sigma}(x, t + T) < f_\varepsilon(x, t) < f^+_{\sigma}(x, t - T), \ x \in \mathbb{R}. \quad (1.13)$$

**Proof.**
From Lemma 3 and from results of [22] (section 2) it follows the existence of $T > 0$ such that initial values $f(x, t_0) = f^0(x)$ satisfy (1.13) with $t_0 = T$.

From this and comparison principle for solutions of (1b) (see Lemma 7.3 in [13]) we deduce inequality (1.13) for $t \geq t_0 = T$ with $T$ and $\tilde{t}_0$ big enough. Lemma 4 is proved.

**Proof of Theorem 1.**
From $\sigma$- modified versions (1.8) of (1.2), (1.3) for $f^\pm(x, t)$ we have

$$f^\pm_{01, \sigma}(x, t) = \varphi(-1)(\frac{x - \gamma\sqrt{\varepsilon}t}{t}) - \frac{c^-_{0, \sigma} \varepsilon}{\varphi'(\alpha^+_{0, \sigma})(x - c^-_{0, \sigma} t)},$$

if $c^-_{0, \sigma} t + b^-_{0, \sigma} \sqrt{\varepsilon}t \leq x \leq c^-_{1, \sigma} t + b^-_{1, \sigma} \sqrt{\varepsilon}t,$

where

$$c^-_{0, \sigma} = \varphi(\alpha^+_{0, \sigma}) = c_0(1 + O_+(\frac{\varepsilon}{t})), \ c_0 = \varphi(\alpha^+_{0, \sigma}),$$

$$c^-_{1, \sigma} = \varphi(\alpha^+_{1, \sigma}) = c_1(1 + O_+(\frac{\varepsilon}{t})), \ c_1 = \varphi(\alpha^+_{1, \sigma}),$$

$$b^-_1 = \gamma + \sqrt{c_1} + \delta + \sqrt{\delta^2 + 2\delta \sqrt{c_1} + o(1)},$$

$$b^-_{0, \sigma} = b^-_0 + O_+(\frac{\varepsilon}{t}), \ b^-_0 = \gamma + o(1), \ b^-_{1, \sigma} = b^-_1 + O_+(\frac{\varepsilon}{t}).$$

$$f^\pm_{01, \sigma}(x, t) = \varphi(-1)(\frac{x + \gamma\sqrt{\varepsilon}t}{t}) + \frac{c^+_{1, \sigma} \varepsilon}{\varphi'(\alpha^+_1)(c^+_{1, \sigma} t - x)},$$

if $c^+_{0, \sigma} t - b^+_{0, \sigma} \sqrt{\varepsilon}t \leq x \leq c^+_{1, \sigma} t - b^+_{1, \sigma} \sqrt{\varepsilon}t,$
where
\[ c_{0,\sigma}^+ = c_0(1 - O_+(\frac{\varepsilon}{t})), \quad c_{1,\sigma}^+ = c_1(1 - O_+(\frac{\varepsilon}{t})), \]

\[ b_{0,\sigma}^+ = b_0^+ - O_+(\frac{\varepsilon}{t}); b_0^+ = \gamma + \sqrt{c_0} + \delta + \sqrt{\delta^2 + 2\delta \sqrt{c_0}}; \]

\[ b_{1,\sigma}^+ = b_1^+ - O_+(\frac{\varepsilon}{t}); b_1^+ = \gamma + o(1). \]

Let \( \tilde{\gamma} = \gamma + \Gamma \) be such that

\[ \varphi(-1)\left(\frac{x - \tilde{\gamma}\sqrt{\varepsilon t}}{t}\right) \leq \varphi(-1)\left(\frac{x - \gamma\sqrt{\varepsilon t}}{t}\right) - \frac{c_{0,\sigma}^-}{\varphi'(\alpha_{0}^+)\varepsilon} \]

and

\[ \frac{c_{0,\sigma}^-}{\varphi'(\alpha_{1}^+)\varepsilon} \leq \varphi(-1)\left(\frac{x + \tilde{\gamma}\sqrt{\varepsilon t}}{t}\right), \]

where

\[ c_{0,\sigma}^- t + b_{0,\sigma}^- \sqrt{\varepsilon t} \leq x \leq c_{1,\sigma}^+ t - b_{1,\sigma}^+ \sqrt{\varepsilon t} \quad (1.15) \]

To obtain (1.14) we must have under condition (1.15) the following inequalities for \( \Gamma > 0: \)

\[ -\frac{1}{(\sup \varphi')} \frac{\Gamma \sqrt{\varepsilon t}}{t} \leq -\frac{c_{0,\sigma}^-}{\varphi'(\alpha_{0}^+)\varepsilon} \]

and

\[ \frac{c_{0,\sigma}^+}{\varphi'(\alpha_{1}^+)\varepsilon} \leq \frac{1}{(\sup \varphi')} \frac{\Gamma \sqrt{\varepsilon t}}{t}, \]

where

\[ \varphi' = \varphi'\left(\frac{x}{t} \pm (\gamma + \theta \Gamma)\sqrt{\frac{\varepsilon}{t}}\right), \quad \theta \in [0, 1], \quad t \geq t_0. \]

From (1.15) and (1.16) we obtain the following condition for parameter \( \Gamma: \)

\[ \frac{\Gamma}{(\sup \varphi')} > \frac{c_{0,\sigma}^-}{\varphi'(\alpha_{0}^+)b_{0,\sigma}^-} \]

and

\[ \frac{\Gamma}{(\sup \varphi')} \geq \frac{c_{0,\sigma}^+}{\varphi'(\alpha_{0}^+)b_{1,\sigma}^+}. \]

(1.17)

To satisfy (1.17) it is sufficient to take \( \Gamma \) such that

\[ \Gamma > (\sup \varphi') \frac{c_{0,\sigma}^-}{\varphi'(\alpha_{0}^+)b_{0,\sigma}^-} \quad \text{and} \]

\[ \Gamma > (\sup \varphi') \frac{c_{0,\sigma}^+}{\varphi'(\alpha_{0}^+)b_{1,\sigma}^+}. \]

From Lemma 4 and inequalities (1.14), (1.15) for \( t \geq T \) and
such that for $t$ increasing functions on the intervals $x$, we obtain

$$
\varphi^{-1}\left(\frac{x - \bar{\gamma} \sqrt{\varepsilon}(t + T)}{t + T}\right) \leq f_\varepsilon(x, t) \leq \varphi^{-1}\left(\frac{x + \bar{\gamma} \sqrt{\varepsilon}(t - T)}{t - T}\right),
$$

(1.18)

where $b_0 > \gamma + o(1)$, $b_1 > \gamma + O(1)$, $\bar{\gamma} = \gamma + O\left(\frac{1}{b_0}\right)$.

Theorem 1 is proved.


Theorem 1, incorporated in the proof of Proposition 2 from [7], implies the following improved version of this proposition as well as of Theorem 2 of [9].

**Theorem 2.**

Let under assumptions and notations of Theorem 1, $\bar{b}_l > b_l > O(1/\gamma)$, $l = 0, \ldots, L$, $\gamma > 0$. Then $\exists t_0 > 0$ such that $\forall t \geq t_0$ and $\varepsilon > 0$ the difference $\Delta f = f(x,t) - f(x,\varepsilon,t)$ for a solution $f = f_\varepsilon(x,t)$ of (1b), (2) and the derivative $\frac{\partial f}{\partial x}(x,t)$ for a solution $f = f_\varepsilon(x,t)$ of (1a), (2) satisfy the following estimates

$$
\left(\frac{\Delta f}{\partial x}\right) = \frac{1}{\varphi'(\alpha_i^\varepsilon)} \cdot t + O\left(\frac{\gamma}{\varphi'(\alpha_i^\varepsilon)} \cdot t\right)
$$

(2.1)

for $x \in [c_i + b_1 \sqrt{\varepsilon}t, c_i + \bar{b}_i \sqrt{\varepsilon}t], l = 0, \ldots, L - 1, t \geq t_0$, and

$$
\left(\frac{\Delta f}{\partial x}\right) = \frac{1}{\varphi'(\alpha_i^\varepsilon)} \cdot t + O\left(\frac{\gamma}{\varphi'(\alpha_i^\varepsilon)} \cdot t\right)
$$

(2.2)

for $x \in [c_i - \bar{b}_i \sqrt{\varepsilon}t, c_i - b_i \sqrt{\varepsilon}t], l = 1, \ldots, L, t \geq t_0$.

**Corollary.**

Under conditions of Theorem 2 $\exists \gamma_0 > 0$ small enough and $\exists t_0 > 0$ big enough such that for $t \geq t_0$, $\gamma \leq \gamma_0$ and $\varepsilon > 0$ functions $x \rightarrow f_\varepsilon(x,t)$ from (1a,b), (2) are increasing functions on the intervals $x \in [c_i + b_1 \sqrt{\varepsilon}t, c_i + \bar{b}_i \sqrt{\varepsilon}t], l = 0, \ldots, L - 1, and x \in [c_i - \bar{b}_i \sqrt{\varepsilon}t, c_i - b_i \sqrt{\varepsilon}t], l = 1, \ldots, L$.

From theorem 1 and from corollary of theorem 2 $\forall \varepsilon > 0$ and for big enough $t_0 > 0$ and $\Gamma > 0$ we deduce existence of functions $t \rightarrow y_i^{\pm}(t,\varepsilon), l = 0, \ldots, L, t \geq t_0$, with properties

$$
\begin{align*}
f_\varepsilon(y_0^+, t) = \alpha_0^+ + \sqrt{\frac{\varepsilon \Gamma}{t}}, & \quad f_\varepsilon(y_L^+, t) = \alpha_L^- - \sqrt{\frac{\varepsilon \Gamma}{t}}, \\
f_\varepsilon(y_l^+, t) = \alpha_l^+ \pm \sqrt{\frac{\varepsilon \Gamma}{t}}, & \quad l = 1, \ldots, L - 1, \\
l_0^- < f_\varepsilon(x,t) < \alpha_0^+ + \sqrt{\frac{\varepsilon \Gamma}{t}}, & \quad \text{if } x < y_0^+(t,\varepsilon), \\
\alpha_L^- - \sqrt{\frac{\varepsilon \Gamma}{t}} < f_\varepsilon(x,t) < \alpha_L^+, & \quad \text{if } x > y_L^-(t,\varepsilon), \\
\alpha_l^- - \sqrt{\frac{\varepsilon \Gamma}{t}} < f_\varepsilon(x,t) < \alpha_l^+ \pm \sqrt{\frac{\varepsilon \Gamma}{t}}, & \quad l = 1, \ldots, L - 1, \quad \text{if } y_l^+(t,\varepsilon) < x < y_l^+(t,\varepsilon).
\end{align*}
$$
This implies correctness of the following definition of Maxwell type shift-functions $d_l(t, \varepsilon)$ for solutions of (1a,b), (2) with $\varepsilon > 0$.

**Definition 1.**

Under assumptions and notations of Theorem 1 for Cauchy problem (1a), (2) $\forall t_0 > 0$ and $\Gamma > 0$ big enough $\exists!$ well defined functions $d_l(t, \varepsilon)$ and $y_{l}(t, \varepsilon), \ l = 0, \ldots, L, \ t \geq t_0, \ \varepsilon > 0$ such that

$$
c_{0}t + d_{0}(t, \varepsilon) \int_{-\infty}^{\varepsilon} (f_{\varepsilon}(x, t) - \alpha^{0}_{-}) dx + \int_{c_{0}t + d_{0}(t, \varepsilon)}^{y_{0}^{+}(t, \varepsilon)} (f_{\varepsilon}(x, t) - \alpha^{+}_{0} - \sqrt{\frac{\varepsilon \Gamma}{t}}) dx = 0, \tag{2.3}
$$

$$
f_{\varepsilon}(y_{0}^{+}, t) = \alpha^{+}_{0} + \sqrt{\frac{\varepsilon \Gamma}{t}},
$$

$$
c_{l}t + d_{l}(t, \varepsilon) \int_{y_{l}^{-}(t, \varepsilon)}^{y_{l}^{+}(t, \varepsilon)} (f_{\varepsilon}(x, t) - \alpha^{-}_{l} + \sqrt{\frac{\varepsilon \Gamma}{t}}) dx + \int_{c_{l}t + d_{l}(t, \varepsilon)}^{\infty} (f_{\varepsilon}(x, t) - \alpha^{+}_{l} - \sqrt{\frac{\varepsilon \Gamma}{t}}) dx = 0, \tag{2.4}
$$

$$
f_{\varepsilon}(y_{l}^{+}, t) = \alpha^{+}_{l} \pm \sqrt{\frac{\varepsilon \Gamma}{t}}, \ l = 1, \ldots, L - 1,
$$

$$
c_{L}t + d_{L}(t, \varepsilon) \int_{y_{L}^{-}(t, \varepsilon)}^{y_{L}^{+}(t, \varepsilon)} (f_{\varepsilon}(x, t) - \alpha^{-}_{L} + \sqrt{\frac{\varepsilon \Gamma}{t}}) dx + \int_{c_{L}t + d_{L}(t, \varepsilon)}^{\infty} (f_{\varepsilon}(x, t) - \alpha^{+}_{L}) dx = 0, \tag{2.5}
$$

$$
f_{\varepsilon}(y_{L}^{+}, t) = \alpha^{+}_{L} - \sqrt{\frac{\varepsilon \Gamma}{t}}.
$$

To define Maxwell type shift-functions for Cauchy problem (1b), (2) it is sufficient to replace in definition 1 function $f_{\varepsilon}(x, t)$ and parameters $\alpha^{+}_{l}$ by functions $\Psi(f_{\varepsilon}(x, t))$ and parameters $\Psi(\alpha^{+}_{l})$, where $\Psi(f) = \int_{f}^{y} \frac{y}{\varphi(y)}$.

**Theorem 3.**

Let $\Phi(f)$ be such that $\varphi(f) \frac{df}{dx} = \frac{\partial \Phi(f)}{\partial x}$. Then under notations of Theorem 1 and definition 1 $\forall t \geq t_0$ and $\varepsilon > 0$ the following formulas for Maxwell type shift-functions $d_l(t, \varepsilon)$ for solutions of Cauchy problem (1a), (2) are valid:

$$
(\alpha^{+}_{l} - \alpha^{-}_{l} + 2\sqrt{\frac{\varepsilon \Gamma}{t}} \frac{d}{dt}(c_{l}t + d_{l}(t, \varepsilon))) = \Phi(\alpha^{+}_{l} + \sqrt{\frac{\varepsilon \Gamma}{t}}) - \Phi(\alpha^{-}_{l} - \sqrt{\frac{\varepsilon \Gamma}{t}}) - \\
\varepsilon(\frac{\partial f_{\varepsilon}}{\partial x}(y_{l}^{+}(t, \varepsilon), t) - \frac{\partial f_{\varepsilon}}{\partial x}(y_{l}^{-}(t, \varepsilon), t)) - \\
\frac{1}{t} \sqrt{\frac{\varepsilon \Gamma}{t}} \frac{y_{l}^{+}(t, \varepsilon) + y_{l}^{-}(t, \varepsilon)}{2} - c_{l}t - d_{l}(t, \varepsilon)), \ \text{if} \ l = 1, \ldots, L - 1, \tag{2.6}
$$
\[
\begin{align*}
(\alpha_0^+ - \alpha_0^-) + \sqrt{\frac{\varepsilon \Gamma}{t}} \frac{d}{dt}(c_0 t + d_0(t, \varepsilon)) &= \Phi(\alpha_0^+ + \sqrt{\frac{\varepsilon \Gamma}{t}}) - \Phi(\alpha_0^-) - \\
\varepsilon \left( \frac{\partial f_\varepsilon}{\partial x}(y_0^+(t, \varepsilon), t) - \frac{1}{2t} \sqrt{\frac{\varepsilon \Gamma}{t}}(y_0^+(t, \varepsilon) - c_0 t - d_0(t, \varepsilon)) \right), & \text{if } l = 0,
\end{align*}
\]
\[
\begin{align*}
(\alpha_L^+ - \alpha_L^-) + \sqrt{\frac{\varepsilon \Gamma}{t}} \frac{d}{dt}(c_L t + d_L(t, \varepsilon)) &= \Phi(\alpha_L^+) - \Phi(\alpha_L^- - \sqrt{\frac{\varepsilon \Gamma}{t}}) + \\
\varepsilon \left( \frac{\partial f_\varepsilon}{\partial x}(y_L^-(t, \varepsilon)) - \frac{1}{2t} \sqrt{\frac{\varepsilon}{t}}(y_L^- - c_L t - d_L(t, \varepsilon)) \right), & \text{if } l = L.
\end{align*}
\]

**Proof.**

Let us consider firstly the case \( l = 1, \ldots, L - 1 \). Derivation of equality (2.4) from definition 1 gives equality

\[
\begin{align*}
\frac{d}{dt}(c_l t + d_l(t, \varepsilon))(f_\varepsilon(c_l t + d_l(t, \varepsilon), t) - \alpha_l^- + \sqrt{\frac{\varepsilon \Gamma}{t}}) - \\
\frac{d}{dt}(c_l t + d_l(t, \varepsilon))(f_\varepsilon(c_l t + d_l(t, \varepsilon), t) - \alpha_l^+ - \sqrt{\frac{\varepsilon \Gamma}{t}}) + \\
\int_{y_l^-}^{y_l^+}(t, \varepsilon) \frac{\partial f_\varepsilon(x, t)}{\partial t} dx + 2(c_l t + d_l - \frac{y_l^- + y_l^+}{2}) \frac{d}{dt}\sqrt{\frac{\varepsilon \Gamma}{t}} = 0.
\end{align*}
\]

This equality and equation (1a) imply

\[
\begin{align*}
(\alpha_l^+ - \alpha_l^-) + 2\sqrt{\frac{\varepsilon \Gamma}{t}} \frac{d}{dt}(c_l t + d_l(t, \varepsilon)) + \\
\int_{y_l^-}^{y_l^+}(t, \varepsilon) \left( \varepsilon \frac{\partial^2 f_\varepsilon}{\partial x^2} - \varphi(f) \frac{\partial f_\varepsilon}{\partial x} \right) dx - \frac{1}{t} \sqrt{\frac{\varepsilon \Gamma}{t}}(c_l t + d_l - \frac{y_l^- + y_l^+}{2}) = 0.
\end{align*}
\]

Using equality \( \varphi(f) \frac{\partial f}{\partial x} = \frac{\partial \Phi(f)}{\partial x} \), we obtain further

\[
\begin{align*}
(\alpha_l^+ - \alpha_l^-) + 2\sqrt{\frac{\varepsilon \Gamma}{t}} \frac{d}{dt}(c_l t + d_l(t, \varepsilon)) &= -\varepsilon \left( \frac{\partial f_\varepsilon}{\partial x}(y_l^+(t, t)) - \frac{\partial f_\varepsilon}{\partial x}(y_l^-(t, t)) \right) + \\
\Phi(f_\varepsilon(y_l^+(t, t))) - \Phi(f_\varepsilon(y_l^-(t, t))) - \frac{1}{t} \sqrt{\frac{\varepsilon \Gamma}{t}}(\frac{y_l^+ + y_l^-}{2} - c_l t - d_l).
\end{align*}
\]

This gives (2.6), taking into account equality

\[
f_\varepsilon(y_l^\pm, t) = \alpha_l^\pm \pm \sqrt{\frac{\varepsilon \Gamma}{t}}.
\]
If \( l = 0 \) then derivation of (2.3) implies
\[
\frac{d}{dt}(c_0 t + d_0(t, \varepsilon))(f_{\varepsilon}(c_0 t + d_0(t, \varepsilon), t) - \alpha_0^- - \sqrt{\varepsilon \Gamma}) + \frac{d}{dt}(c_0 t + d_0(t, \varepsilon))(f_{\varepsilon}(c_0 t + d_0(t, \varepsilon), t) - \alpha_0^+ + \sqrt{\varepsilon \Gamma}) + \frac{\partial f_{\varepsilon}(x, t)}{\partial t} dx + (c_0 t + d_0(t, \varepsilon) - y_0^+) \frac{d}{dt} \frac{\sqrt{\varepsilon \Gamma}}{t} = 0.
\]

Using (1a) we have further
\[
(\alpha_0^+ - \alpha_0^- + \sqrt{\varepsilon \Gamma} \frac{d}{dt}(c_0 t + d_0(t, \varepsilon)) + \int_{-\infty}^{y_0^+} (\varepsilon \frac{\partial^2 f_{\varepsilon}}{\partial x^2} - \varphi(f) \frac{\partial f_{\varepsilon}}{\partial x}) dx - \sqrt{\varepsilon \Gamma} \frac{d}{dt} (c_0 t + d_0(t) - y_0^+)) = 0.
\]

Finally,
\[
(\alpha_0^+ - \alpha_0^- + \sqrt{\varepsilon \Gamma} \frac{d}{dt}(c_0 t + d_0(t, \varepsilon)) = -\varepsilon \frac{\partial f_{\varepsilon}}{\partial x}(y_0^+, t) - 0) + \Phi(f_{\varepsilon}(y_0^-)) - \Phi(f_{\varepsilon}(-\infty)) - \sqrt{\varepsilon \Gamma} \frac{d}{dt} (y_0^+ - c_0 t + d_0(t)).
\]

This gives (2.7). Equality (2.8) can be proved by a similar way.

Theorem 3 is proved.

**Remark 5.**

Result similar to Theorem 3 is valid also for shift-functions for Cauchy problem (1b), (2).

From Theorems 1, 2, 3 we can deduce the following.

**Theorem 4.**

Under assumptions and notations of Theorem 1 and definition 1 Maxwell type shift-functions \( d_l(t, \varepsilon) \) for solutions of Cauchy problem (1a,b), (2) have the following small viscosity estimate:
\[
\frac{d}{dt} d_l(t, \varepsilon) = O(\sqrt{\varepsilon/t}), \quad \varepsilon > 0, \quad t \geq t_0, \quad l = 0, \ldots, L.
\]

**Proof (for problem (1a), (2)).**

Let us consider the case \( l = 1, \ldots, L - 1 \). In order to obtain estimate (2.9) for this case we must estimate all terms of (2.6). For these estimates we note that equalities
\[
f_{\varepsilon}(y_l^\pm, t) = \alpha_l^\pm \pm \sqrt{\varepsilon \Gamma} \frac{d}{dt} \] and Theorem 1 for \( \Gamma \) big enough imply the following inequality
\[
c_l t - \Gamma \sqrt{\varepsilon t} \leq y_l^- \leq y_l^+ \leq c_l t + \Gamma \sqrt{\varepsilon t}, \quad t \geq t_0.
\]
Using (2.10) and Theorem 2 we obtain the following equality
\[
\varepsilon \left( \frac{\partial f(x)}{\partial x} (y^+_l(t, \varepsilon), t) - \frac{\partial f(x)}{\partial x} (y^-_l(t, \varepsilon), t) \right) = \\
\varepsilon \left( \frac{1}{t} \frac{\partial f}{\partial x} (\alpha^+_l) - \frac{1}{t} \frac{\partial f}{\partial x} (\alpha^-_l) \right) (1 + O \left( \frac{\gamma}{\varphi' (\alpha^+_l) t + \gamma}{\varphi' (\alpha^-_l) t} \right)).
\]

(2.11)

Definition 1 and (2.10) imply inequality
\[
\frac{1}{t} \sqrt{\frac{\varepsilon \Gamma}{t}} \left( \frac{y^+_l(t, \varepsilon) + y^-_l(t, \varepsilon)}{2} - c_l t - d_l(t, \varepsilon) \right) = O \left( \frac{1}{t} \sqrt{\varepsilon/t} \sqrt{\varepsilon t} \right) = O(\varepsilon/t).
\]

(2.12)

Formula (5a) gives equality
\[
(\alpha^+_l - \alpha^-_l) c_l = \Phi(\alpha^+_l) - \Phi(\alpha^-_l).
\]

(2.13)

Using (2.13), we obtain
\[
(\alpha^+_l - \alpha^-_l) + 2 \sqrt{\frac{\varepsilon \Gamma}{t}} \frac{d}{dt} (c_l t + d_l(t, \varepsilon)) - \Phi(\alpha^+_l + \sqrt{\frac{\varepsilon \Gamma}{t}}) + \Phi(\alpha^-_l - \sqrt{\frac{\varepsilon \Gamma}{t}}) = \\
\frac{d}{dt} d_l(t, \varepsilon) + O(\sqrt{\varepsilon/t}).
\]

(2.14)

Finally, (2.11), (2.12), (2.14) imply (2.9). The cases \( l = 0 \) and \( l = L \) can be obtained by a similar way.

Theorem 4 is proved.

**Corollary.**

Under conditions of Theorem 1 \( \forall \ t \geq t_0 \)
\[
\exists \lim_{\varepsilon \to 0} d_l(t, \varepsilon) = d_l(t, 0) = d_l(t_0, 0), \ \ l = 0, \ldots, L.
\]

**Proof of the main theorem.**

The first statement of the main theorem was obtained in [7], theorem 1. The second statement of the main theorem follows directly from the first statement and corollary of Theorem 4.

**Remark 6.**

Note that in [7] in the proof of theorem 1 there are misprints, which we correct here:

"From (10) and (11) of [7], Proposition 3 with \( A = \left( \frac{\varepsilon}{t} \right)^{1/4} \) we obtain
\[
\frac{dA}{dt} = -\frac{\varepsilon}{4} A, \\
\frac{\partial}{\partial A} d_l(t, \varepsilon, A) = \begin{cases} 
O(\frac{1}{t}), & \text{if } A \geq \sqrt{\frac{\varepsilon}{t}} \\
O(\frac{1}{t}), & \text{if } A \leq \sqrt{\frac{\varepsilon}{t}}.
\end{cases}
\]
\[
\frac{d}{dt} d_t \left( \frac{t}{\varepsilon} (\varepsilon^3 t)^{1/4} \right) = O\left( \frac{\varepsilon}{t} \right) + O\left( \frac{\varepsilon^3}{t} \right)^{3/4}.
\]

This gives property (28) in [7] and as a consequence a strong version of theorem 1 in [7].

References.

[14] E. Hopf, The partial differential equation \( u_t + uu_x = \mu u_{xx} \), Comm. Pure Appl. Math. 3 (1950), 201-230