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STABILITY BY RESCALED WEAK CONVERGENCE FOR THE NAVIER-STOKES EQUATIONS

HAJER BAHOURI, JEAN-YVES CHEMIN, AND ISABELLE GALLAGHER

Abstract. We prove a weak stability result for the three-dimensional homogeneous incompressible Navier-Stokes system. More precisely, we investigate the following problem: if a sequence \((u_{0,n})_{n \in \mathbb{N}}\) of initial data, bounded in some scaling invariant space, converges weakly to an initial data \(u_0\) which generates a global regular solution, does \(u_{0,n}\) generate a global regular solution? A positive answer in general to this question would imply global regularity for any data, through the following examples \(u_{0,n} = n\varphi_0(n \cdot)\) or \(u_{0,n} = \varphi_0(\cdot - x_n)\) with \(|x_n| \to \infty\). We therefore introduce a new concept of weak convergence (rescaled weak convergence) under which we are able to give a positive answer. The proof relies on profile decompositions in anisotropic spaces and their propagation by the Navier-Stokes equations.

1. Introduction and statement of the main result

1.1. The Navier-Stokes equations. We are interested in the Cauchy problem for the three dimensional, homogeneous, incompressible Navier-Stokes system

\[
\begin{aligned}
\partial_t u + u \cdot \nabla u - \Delta u &= -\nabla p \quad \text{in } \mathbb{R}^+ \times \mathbb{R}^3 \\
\text{div } u &= 0 \\
\left. u \right|_{t=0} &= u_0,
\end{aligned}
\]

where \(p = p(t, x)\) and \(u = (u^1, u^2, u^3)(t, x)\) are respectively the pressure and velocity of an incompressible, viscous fluid.

We shall say that \(u \in L^2_{\text{loc}}([0, T] \times \mathbb{R}^3)\) is a weak solution of (NS) associated with the data \(u_0\) if for any compactly supported, divergence free vector field \(\phi\) in \(C^\infty([0, T] \times \mathbb{R}^3)\) the following holds for all \(t \leq T:\)

\[
\int_{\mathbb{R}^3} u \cdot \phi(t, x) dx = \int_{\mathbb{R}^3} u_0(x) \cdot \phi(0, x) dx + \int_0^t \int_{\mathbb{R}^3} (u \cdot \Delta \phi + u \otimes u : \nabla \phi + u \cdot \partial_t \phi) dx dt',
\]

with

\[
u \otimes u : \nabla \phi \overset{\text{def}}{=} \sum_{1 \leq j, k \leq 3} u^j u^k \partial_k \phi^j.
\]

As is well-known, the (NS) system enjoys two important features. First it formally conserves the energy, in the sense that smooth enough solutions satisfy the following equality for all times \(t \geq 0:\)

\[
\frac{1}{2} \|u(t)\|^2_{L^2(\mathbb{R}^3)} + \frac{1}{2} \|
abla u(t')\|^2_{L^2(\mathbb{R}^3)} dt' = \frac{1}{2} \|u_0\|^2_{L^2(\mathbb{R}^3)}.
\]

Weak solutions satisfying the energy inequality

\[
\frac{1}{2} \|u(t)\|^2_{L^2(\mathbb{R}^3)} + \frac{1}{2} \|
abla u(t')\|^2_{L^2(\mathbb{R}^3)} dt' \leq \frac{1}{2} \|u_0\|^2_{L^2(\mathbb{R}^3)}
\]
are said to be turbulent solutions, following the terminology of J. Leray [38]. The energy equality (1.1) can easily be obtained noticing that thanks to the divergence free condition, the nonlinear term is skew-symmetric in \(L^2\): one has indeed 
\[
(u(t) \cdot \nabla u(t) + \nabla p(t)|u(t)|)_{L^2} = 0.
\]

Second, (NS) enjoys a scaling invariance property: defining the scaling operators, for any positive real number \(\lambda\) and any point \(x_0\) of \(\mathbb{R}^3\),
\[
(1.3)\quad \Lambda_{\lambda,x_0} \phi(t,x) \overset{\text{def}}{=} \frac{1}{\lambda} \phi\left(\frac{t}{\lambda^2}, \frac{x-x_0}{\lambda}\right) \quad \text{and} \quad \Lambda_{\lambda} \phi(t,x) \overset{\text{def}}{=} \frac{1}{\lambda} \phi\left(\frac{t}{\lambda^2}, \frac{x}{\lambda}\right),
\]
if \(u\) solves (NS) with data \(u_0\), then \(\Lambda_{\lambda,x_0} u\) solves (NS) with data \(\Lambda_{\lambda,x_0} u_0\). We shall say that a family \((X_T)_{T>0}\) of spaces of distributions over \([0,T] \times \mathbb{R}^3\) is scaling invariant if for all \(T > 0\) one has
\[
\forall \lambda > 0, \forall x_0 \in \mathbb{R}^3, u \in X_T \iff \Lambda_{\lambda,x_0} u \in X_{\lambda^{-2}T} \quad \text{with} \quad \|u\|_{X_T} = \|\Lambda_{\lambda,x_0} u\|_{X_{\lambda^{-2}T}}.
\]

Similarly a space \(X_0\) of distributions defined on \(\mathbb{R}^3\) will be said to be scaling invariant if
\[
\forall \lambda > 0, \forall x_0 \in \mathbb{R}^3, u_0 \in X_0 \iff \Lambda_{\lambda,x_0} u_0 \in X_0 \quad \text{with} \quad \|u_0\|_{X_0} = \|\Lambda_{\lambda,x_0} u_0\|_{X_0}.
\]

This leads to the definition of a scaled solution, which will be the notion of solution we shall consider throughout this paper: high frequencies of the solution are required to belong to a scale invariant space. In the following we denote by \(\mathcal{F}\) the Fourier transform.

**Definition 1.1.** A vector field \(u\) is a (scaled) solution to (NS) associated with the data \(u_0\) if it is a weak solution, such that there is a compactly supported function \(\chi \in C^\infty(\mathbb{R}^3)\), equal to \(1\) near \(0\), such that
\[
\mathcal{F}^{-1}(1 - \chi) \mathcal{F} u \in X_T
\]
where \(X_T\) belongs to a family of scaling invariant spaces.

The energy conservation (1.1) is the main ingredient which enabled J. Leray to prove in [38] that any initial data in \(L^2(\mathbb{R}^3)\) gives rise to (at least) one global turbulent solution to (NS), belonging to the space \(L^\infty(\mathbb{R}^+; L^2(\mathbb{R}^3))\), with \(\nabla u\) in \(L^2(\mathbb{R}^+; L^2(\mathbb{R}^3))\). Along with that fundamental result, he could also prove that if the initial data is small enough in the sense that \(\|u_0\|_{L^2(\mathbb{R}^3)} \|\nabla u_0\|_{L^2(\mathbb{R}^3)}\) is small enough, then there is only one such solution, and if the data belongs also to \(H^1\) with no such smallness assumption then that uniqueness property holds at least for a short time (time at which the solution ceases to belong to \(H^1\)).

It is important to notice that the quantity \(\|u_0\|_{L^2(\mathbb{R}^3)} \|\nabla u_0\|_{L^2(\mathbb{R}^3)}\) is invariant by the scaling operator \(\Lambda_{\lambda,x_0}\). Actually in dimension 2 not only does the global existence of turbulent solutions hold, but linked to the fact that \(\|u(t)\|_{L^2(\mathbb{R}^2)}\) is both scale invariant and bounded globally in time thanks to the energy inequality (1.2), J. Leray proved in [39] that those solutions are actually unique, for all times whatever their size. In dimension three and more, the question of the uniqueness of Leray’s solutions is still an open problem, and in relation with that problem, a number of results have been proved concerning the existence, global in time, of solutions under a scaling invariant smallness assumption on the data. Without that smallness assumption, existence and uniqueness often holds in a scale invariant space for a short time but nothing is known beyond that time, at which some scale-invariant norm of the solution could blow up. The question of the possible blow up in finite time of solutions to (NS) is actually one of the Millenium Prize Problems in Mathematics.

We shall not recall all the results existing in the literature concerning the Cauchy problem for (NS), and refer for instance to [2], [37], [42] and the references therein, for recent surveys
on the subject. Let us simply recall the best result known to this day on the uniqueness of solutions to (NS), which is due to H. Koch and D. Tataru in [36]: if

$$\|u_0\|_{\text{BMO}^{-1}(\mathbb{R}^3)} \overset{\text{def}}{=} \|u_0\|_{B^{-1}_{\infty,\infty}(\mathbb{R}^3)} + \sup_{R > 0} \frac{1}{R^2} \left( \int_{[0,R^2] \times B(x,R)} |(e^{\epsilon \Delta} u_0)(t,y)|^2 \, dy \, dt \right)^{\frac{1}{2}}$$

is small enough, then there is a global, unique solution to (NS), lying in $\text{BMO}^{-1} \cap X$ for all times, with $X$ another scale invariant space to be specified – we shall not be using that space in the sequel. In the definition of $\text{BMO}^{-1}$ above, the norm in $B^{-1}_{\infty,\infty}(\mathbb{R}^3)$ denotes a Besov norm, which is the end-point Besov norm in which global existence and uniqueness is known to hold for small data, namely $B^{-1+\frac{2}{p}}_{p,\infty}$ for finite $p$ (see [45]). Let us note that (NS) is illposed for initial data in $B^{-\infty,\infty}_{\infty,\infty}(\mathbb{R}^3)$ (see [10] and [25]).

We are interested here in the stability of global solutions. Let us recall that it is proved in [1] (see [21] for the Besov setting) that the set of initial data generating a global solution is open in $\text{BMO}^{-1}$. More precisely, denoting by $\text{VMO}^{-1}$ the closure of smooth functions in $\text{BMO}^{-1}$, it is proved in [1] that if $u_0$ belongs to $\text{VMO}^{-1}$ and generates a global, smooth solution to (NS), then any sequence $(u_{0,n})_{n \in \mathbb{N}}$ converging to $u_0$ in the $\text{BMO}^{-1}$ norm also generates a global smooth solution as soon as $n$ is large enough.

In this paper we would like to address the question of weak stability:

If $(u_{0,n})_{n \in \mathbb{N}}$, bounded in some scale invariant space $X_0$, converges to $u_0$ in the sense of distributions, with $u_0$ giving rise to a global smooth solution, is it the case for $u_{0,n}$ when $n$ is large enough?

A first step in that direction was achieved in [4], under two additional assumptions to the weak convergence, one of which was an assumption on the asymptotic separation of the horizontal and vertical spectral supports: we shall come back to that assumption in Section 3, Remark 3.6. As remarked in [4], the first example that may come to mind of a sequence $(u_{0,n})_{n \in \mathbb{N}}$ bounded in a scale invariant space $X_0$ and converging weakly to 0 is

$$u_{0,n} = \lambda_n \Phi_0(\lambda_n \cdot) = \Lambda_{\lambda_n} \Phi_0 \quad \text{with} \quad \lim_{n \to \infty} \left( \lambda_n + \frac{1}{\lambda_n} \right) = \infty.$$  

with $\Phi_0$ an arbitrary divergence-free vector field. If the weak stability result were true, then since the weak limit of $(u_{0,n})_{n \in \mathbb{N}}$ is zero (which gives rise to the unique, global solution which is identically zero) then for $n$ large enough $u_{0,n}$ would give rise to a unique, global solution. By scale invariance then so would $\Phi_0$, and this for any $\Phi_0$, so that would solve the global regularity problem for (NS). Another natural example is the sequence

$$u_{0,n} = \Phi_0(\cdot - x_n) = \Lambda_{1,x_n} \Phi_0$$

with $(x_n)_{n \in \mathbb{N}}$ a sequence of $\mathbb{R}^3$ going to infinity. Thus sequences built by rescaling fixed divergence free vector fields according to the invariances of the equations have to be excluded from our analysis, since solving (NS) for any smooth initial data seems out of reach. This leads naturally to the following definition of rescaled weak convergence, which we shall call $R$-convergence.

**Definition 1.2** (R-convergence). We say that a sequence $(\varphi_n)_{n \in \mathbb{N}}$ $R$-converges to $\varphi$ if for all sequences $(\lambda_n)_{n \in \mathbb{N}}$ of positive real numbers and for all sequences $(x_n)_{n \in \mathbb{N}}$ in $\mathbb{R}^3$, the sequence $(\Lambda_{\lambda_n,x_n}(\varphi_n - \varphi))_{n \in \mathbb{N}}$ converges to zero in the sense of distributions, as $n$ goes to infinity.
Remark 1.3. Consider the sequences defined by (1.4) and (1.5): if it is assumed that they R-converge to zero, then clearly $\Phi_0 \equiv 0$. On the other hand the sequence

$$u_{0,n}(x) = \Phi_0(x_1, x_2, \frac{x_3}{n})$$

is easily seen to R-converge to zero for any $\Phi_0$ satisfying $\Phi_0(x_1, x_2, 0) \equiv 0$.

In this paper we solve the weak stability question under the R-convergence assumption instead of classical weak convergence. Actually following Remark 1.3, the choice of the function space in which to pick the sequence of initial data becomes crucial, as for instance contrary to the examples (1.4) and (1.5), the sequence of initial data defined in (1.6) is not bounded in $B_{p, \infty}^{-1, \frac{3}{p}}$ for finite $p$ (it can actually even be made arbitrarily large in BMO$^{-1}$, see [14]). On the other hand it is bounded in anisotropic spaces of the type $L^2(\mathbb{R}^2; L^\infty(\mathbb{R}))$. We are therefore led to describing sequences of initial data, bounded in anisotropic, homogeneous function spaces. A celebrated tool to this end are profile decompositions.

1.2. Profile decompositions and statement of the main result. The study of the defect of compactness in Sobolev embeddings originates in the works of P.-L. Lions (see [40] and [41]), L. Tartar (see [50]) and P. Gérard (see [23]) and earlier decompositions of bounded sequences into a sum of “profiles” can be found in the studies by H. Brézis and J.-M. Coron in [11] and M. Struwe in [49]. Our source of inspiration here is the work [24] of P. Gérard in which the defect of compactness of the critical Sobolev embedding $H^s \subset L^p$ is described in terms of a sum of rescaled and translated orthogonal profiles, up to a small term in $L^p$ (see Theorem 1 for a statement in the case when $s = 1/2$). This was generalized to other Sobolev spaces by S. Jaffard in [30], to Besov spaces by G. Koch [35], and finally to general critical embeddings by H. Bahouri, A. Cohen and G. Koch in [3] (see also [6, 7, 8] for Sobolev embeddings in Orlicz spaces and [19] for an abstract, functional analytic presentation of the concept in various settings).

In the pioneering works [5] (for the critical 3D wave equation) and [43] (for the critical 2D Schrödinger equation), this type of decomposition was introduced in the study of nonlinear partial differential equations. The ideas of [5] were revisited in [34] and [20] in the context of the Schrödinger equations and Navier-Stokes equations respectively, with an aim at describing the structure of bounded sequences of solutions to those equations. These profile decomposition techniques have since then been successfully used in order to study the possible blow-up of solutions to nonlinear partial differential equations, in various contexts; we refer for instance to [22], [28], [31], [32], [33], [46], [48].

Before stating our main result, let us analyze what profile decompositions can say about bounded sequences satisfying the assumptions of Definition 1.2. In dimension three, the scale-invariant Sobolev space associated with (NS) is $H^{\frac{1}{2}}(\mathbb{R}^3)$, defined by

$$\|f\|_{H^{\frac{1}{2}}(\mathbb{R}^3)} \overset{\text{def}}{=} \left( \int_{\mathbb{R}^3} |\xi| |\hat{f}(\xi)|^2 \, d\xi \right)^{\frac{1}{2}},$$

where $\hat{f}$ is the Fourier transform of $f$. The profile decomposition of P. Gérard [24] describing the lack of compactness of the embedding $H^{\frac{1}{2}}(\mathbb{R}^3) \subset L^3(\mathbb{R}^3)$ is the following.

**Theorem 1** ([24]). Let $(\varphi_n)_{n \in \mathbb{N}}$ be a sequence of functions, bounded in $H^{\frac{1}{2}}(\mathbb{R}^3)$ and converging weakly to some function $\varphi^0$. Then up to extracting a subsequence (which we denote in the same way), there is a family of functions $(\varphi^j)_{j \geq 1}$ in $H^{\frac{1}{2}}(\mathbb{R}^3)$, and a family $(x^j_n)_{j \geq 1}$ of sequences of points in $\mathbb{R}^3$, as well as a family of sequences of positive real numbers $(h^j_n)_{j \geq 1}$,
orthogonal in the sense that if \( j \neq k \) then
\[
either \frac{h_n^j}{h_n^k} + \frac{h_n^k}{h_n^j} \to \infty \quad \text{as} \quad n \to \infty, \quad \text{or} \quad h_n^j = h_n^k \quad \text{and} \quad \frac{|x_n^j - x_n^k|}{h_n^j} \to \infty \quad \text{as} \quad n \to \infty
\]
such that for all integers \( L \geq 1 \) the function \( \psi_n^L \overset{\text{def}}{=} \varphi_n - \varphi^0 - \sum_{j=1}^{L} \Lambda_{h_n^j,x_n^j}(\varphi) \) satisfies
\[
\limsup_{n \to \infty} \|\psi_n^L\|_{L^3(\mathbb{R}^3)} \to 0 \quad \text{as} \quad L \to \infty.
\]
Moreover one has
\[
(1.7) \quad \Lambda_{(h_n^j)^{-1},-(h_n^j)^{-1},x_n^j}(\varphi_n) \to \varphi^j, \quad \text{as} \quad n \to \infty.
\]
If a sequence of divergence free vector fields \( u_{0,n} \), bounded in \( H^{1/2}(\mathbb{R}^3) \), R-converges to some vector field \( u_0 \) as defined in Definition 1.2, then applying the result (1.7) of Theorem 1 implies that \( \varphi^j \) is identically zero for each \( j \), which in turn implies that there are no non zero profiles entering in the decomposition of \( u_{0,n} \). This means that \( \psi_n^L = u_{0,n} - u_0 \) and therefore the convergence of \( u_{0,n} \) to \( u_0 \) is in fact strong in \( L^3(\mathbb{R}^3) \). The strong stability result of [21] then implies immediately that for \( n \) large enough, \( u_{0,n} \) gives rise to a global unique solution to (NS) if that is the case for \( u_0 \). The same reasoning, using the profile decompositions of [3] and again the strong stability result [21], shows that if \( u_{0,n} \) is bounded in \( B_{p,q}^{1/2}(\mathbb{R}^3) \) for finite \( q \), and R-converges to some vector field \( u_0 \) then as soon as \( u_0 \) generates a global smooth solution, then so does \( u_{0,n} \) for \( n \) large enough.

In order to obtain a result which is not a direct consequence of profile decompositions and known strong stability results, the question of the function space in which to choose the initial data becomes a key ingredient in the analysis. As explained in the previous paragraph, one expects that under the R-convergence assumption, a relevant function space in which to choose the initial data should scale like \( L^2(\mathbb{R}^2; L^\infty(\mathbb{R})) \). To our knowledge there is no wellposedness result of any kind for (NS) in \( L^2(\mathbb{R}^2; L^\infty(\mathbb{R})) \) so we shall assume some regularity in the third direction, while keeping the \( L^\infty \) scaling, and this leads us naturally to introducing anisotropic Besov spaces. These spaces generalize the more usual isotropic Besov spaces, which are studied for instance in [2, 9, 47, 51, 52].

**Definition 1.4.** Let \( \hat{\chi} \) (the Fourier transform of \( \chi \)) be a radial function in \( \mathcal{D}(\mathbb{R}) \) such that \( \hat{\chi}(t) = 1 \) for \( |t| \leq 1 \) and \( \hat{\chi}(t) = 0 \) for \( |t| > 2 \). For \( (j,k) \in \mathbb{Z}^2 \), the horizontal truncations are defined by
\[
\overline{S}^h_k f(\xi) \overset{\text{def}}{=} \hat{\chi}(2^{-k}|(\xi_1, \xi_2)|)\hat{f}(\xi) \quad \text{and} \quad \Delta^h_k \overset{\text{def}}{=} S^h_{k+1} - S^h_k,
\]
and the vertical truncations by
\[
\overline{S}^v_j f \overset{\text{def}}{=} \hat{\chi}(2^{-j}|\xi_3|)\hat{f}(\xi) \quad \text{and} \quad \Delta^v_j \overset{\text{def}}{=} S^v_{j+1} - S^v_j.
\]
For all \( p \) in \([1, \infty]\) and \( q \) in \([0, \infty]\), and all \( (s, s') \) in \( \mathbb{R}^2 \), with \( s < 2/p, s' < 1/p \) (or \( s \leq 2/p \) and \( s' \leq 1/p \) if \( q = 1 \)), the anisotropic homogeneous Besov space \( B_{p,q}^{s,s'} \) is defined as the space of tempered distributions \( f \) such that
\[
\|f\|_{B_{p,q}^{s,s'}} \overset{\text{def}}{=} \|2^{ks+j s'}\|\Delta^h_k \Delta^v_j f\|_{L^p}\|_{l^q} < \infty.
\]
In all other cases of indexes \( s \) and \( s' \), the Besov space is defined similarly, up to taking the quotient with polynomials.
A family of sequences are orthogonal when \( j \) are introducing some definitions and notations.

Definition 2.1. Let \( u \) be a sequence of divergence free vector fields bounded in \( B_{1,q} \), such that \( u_0 \) belongs to \( B^0 \), then there is a unique solution (global in time if the data is small enough) in \( L^2([0,T]; B^1) \). That norm controls the equation, in the sense that as soon as the solution belongs to \( L^2([0,T]; B^1) \), then it lies in fact in \( L^r([0,T]; B^{\frac{1}{2}}) \) for all \( 1 \leq r \leq \infty \).

The Navier-Stokes equations in anisotropic spaces have been studied in a number of frameworks. We refer for instance, among others, to [4], [18], [27], [29], [44]. In particular in [4] it is proved that if \( u_0 \) belongs to \( B^0 \), then there is a unique solution (global in time if the data is small enough) in \( L^2([0,T]; B^1) \). That norm controls the equation, in the sense that as soon as the solution belongs to \( L^2([0,T]; B^1) \), then it lies in fact in \( L^r([0,T]; B^{\frac{1}{2}}) \) for all \( 1 \leq r \leq \infty \).

The space \( B^1 \) is included in \( L^\infty \) since the seminal work [38] of J. Leray, it is known that the \( L^2([0,T]; L^\infty) \) norm controls the propagation of regularity and also ensures weak uniqueness among turbulent solutions. Thus the space \( B^0 \) is natural in this context. Our main result is the following.

**Theorem 2.** Let \( q \) be given in \([0,1]\) and let \( u_0 \) in \( B_{1,q} \) generate a unique global solution to (NS). Let \((u_{0,n})_{n\in\mathbb{N}}\) be a sequence of divergence free vector fields bounded in \( B_{1,q} \), such that \( u_{0,n} \) R-converges to \( u_0 \). Then for \( n \) large enough, \( u_{0,n} \) generates a unique, global solution to (NS) in the space \( L^2(\mathbb{R}^+; B^1) \).

**Acknowledgments.** We want to thank very warmly Pierre Germain for suggesting the concept of rescaled weak convergence.

2. Structure and main ideas of the proof

To prove Theorem 2, the first step consists in the proof of an anisotropic profile decomposition of the sequence of initial data. To state the result in a clear way, let us start by introducing some definitions and notations.

**Definition 2.1.** We say that two sequences of positive real numbers \((\lambda_n^1)_{n\in\mathbb{N}}\) and \((\lambda_n^2)_{n\in\mathbb{N}}\) are orthogonal if

\[
\frac{\lambda_n^1}{\lambda_n^2} + \frac{\lambda_n^2}{\lambda_n^1} \to \infty, \quad n \to \infty.
\]

A family of sequences \((\lambda_n^j)_{n\in\mathbb{N}}\) is said to be a family of scales if \( \lambda_n^0 \equiv 1 \) and if \( \lambda_n^j \) and \( \lambda_n^k \) are orthogonal when \( j \neq k \).

**Definition 2.2.** Let \( \mu \) be a positive real number less than \( 1/2 \), fixed from now on.

We define \( D_\mu \) by \([-2 + \mu, 1 - \mu] \times [1/2, 7/2] \) and \( \tilde{D}_\mu \) by \([-1 + \mu, 1 - \mu] \times [1/2, 3/2] \). We denote by \( \mathcal{S}_\mu \) the space of functions \( a \) belonging to \( \bigcap_{(s,s') \in D_\mu} B^{s,s'} \) such that

\[
\|a\|_{\mathcal{S}_\mu} \stackrel{\text{def}}{=} \sup_{(s,s') \in D_\mu} \|a\|_{B^{s,s'}} < \infty.
\]
Remark 2.3. Everything proved in this paper would work choosing for \(D_\mu\) any set of the type \([-2 + \mu, 1 - \mu] \times [1/2, A]\), with \(A \geq 7/2\). For simplicity we limit ourselves to the case when \(A = 7/2\).

**Notation.** For all points \(x = (x_1, x_2, x_3)\) in \(\mathbb{R}^3\) and all vector fields \(u = (u^1, u^2, u^3)\), we denote their horizontal parts by
\[
x_h \overset{\text{def}}{=} (x_1, x_2) \quad \text{and} \quad u_h \overset{\text{def}}{=} (u^1, u^2).
\]
We shall be considering functions which have different types of variations in the \(x_3\) variable and the \(x_h\) variable. The following notation will be used:
\[
[f]_\beta(x) \overset{\text{def}}{=} f(x_h, \beta x_3).
\]
Clearly, for any function \(f\), we have the following identity which will be of constant use all along this paper:
\[
\|[f]_\beta\|_{B^{1,q}_p} \sim \beta^{q-2-\frac{4}{p}}\|f\|_{B^{1,q}_p}.
\]
In all that follows, \(\theta\) is a given function in \(\mathcal{D}(B_{\mathbb{R}^3}(0,1))\) which has value 1 near \(B_{\mathbb{R}^3}(0,1/2)\). For any positive real number \(\eta\), we denote
\[
\theta_\eta(x) \overset{\text{def}}{=} \theta(\eta x) \quad \text{and} \quad \theta_{\eta,n}(x_h) \overset{\text{def}}{=} \theta_\eta(x_h, 0).
\]
In order to make notations as light as possible, the letter \(v\) (possibly with indices) will always denote a two-component divergence free vector field, which may depend on the vertical variable \(x_3\).

Finally we define horizontal differentiation operators \(\nabla_h \overset{\text{def}}{=} (\partial_1, \partial_2)\) and \(\text{div}_h \overset{\text{def}}{=} \nabla_h^*\), as well as \(\Delta_h \overset{\text{def}}{=} \partial_2^2 + \partial_2^2\), and we shall use the following shorthand notation: \(X_h Y_v := X(\mathbb{R}^2; Y(\mathbb{R}))\) where \(X\) is a function space defined on \(\mathbb{R}^2\) and \(Y\) is defined on \(\mathbb{R}\).

**Theorem 3.** Under the assumptions of Theorem 2 and up to the extraction of a subsequence, the following holds. There is a family of scales \((\lambda^j_n)_{n \in \mathbb{N}}\) in \(\mathbb{N}\) and for all \(L \geq 1\) there is a family of scales \((h^j_n)_{n \in \mathbb{N}}\) going to zero such that for any real number \(\alpha\) in \([0,1]\) and for all \(L \geq 1\), there are families of sequences of divergence-free vector fields (for \(j\) ranging from 1 to \(L\)), \((v^j_{n,\alpha,L})_{n \in \mathbb{N}}, (w^j_{n,\alpha,L})_{n \in \mathbb{N}}, (v^0_{n,\alpha,L}, w^0_{n,\alpha,L})_{n \in \mathbb{N}}, (v^0_{0,\alpha,L}, w^0_{0,\alpha,L})_{n \in \mathbb{N}}, (v^0_{0,\alpha,L})_{n \in \mathbb{N}}, (w^0_{0,\alpha,L})_{n \in \mathbb{N}}\) and \((u^0_{0,\alpha,L})_{n \in \mathbb{N}}\) all belonging to \(S_\mu\), and a smooth, compactly supported function \(u_{0,\alpha}\) such that the sequence \((u_{0,n})_{n \in \mathbb{N}}\) can be written under the form
\[
u_{0,n} \equiv u_{0,n} + [(v^0_{0,n,\alpha,L} + h^0_n w^0_{0,n,\alpha,L}; w^0_{0,n,\alpha,L})]_{h^0_n} + [(v^0_{0,n,\alpha,L} + h^0_n w^0_{0,n,\alpha,L}; w^0_{0,n,\alpha,L})]_{h^0_n} + \sum_{j=1}^L \Lambda^j_n [v^j_{n,\alpha,L} + h^0_n w^j_{n,\alpha,L}; w^j_{n,\alpha,L}]]_{h^0_n} + \rho_{n,\alpha,L}
\]
where \(u_{0,\alpha}\) approximates \(u_0\) in the sense that
\[
\lim_{\alpha \to 0} \|u_{0,\alpha} - u_0\|_{B^{1,q}} = 0,
\]
where the remainder term satisfies
\[
\lim_{L \to \infty} \lim_{\alpha \to 0} \limsup_{n \to \infty} \|e^{t_x} \rho_{n,\alpha,L}\|_{L^2(\mathbb{R}^+; S^1)} = 0.
\]
while the following uniform bounds hold:
\[
\mathcal{M} \overset{\text{def}}{=} \sup_{L \geq 1} \sup_{\alpha \in [0,1]} \sup_{n \in \mathbb{N}} \left( \left\| (v_{0,n,\alpha,L}^{0,\infty}, w_{0,n,\alpha,L}^{0,\infty,3}) \right\|_{B^0} + \left\| (v_{0,n,\alpha,L}^{0,\text{loc}}, w_{0,n,\alpha,L}^{0,\text{loc},3}) \right\|_{B^0} \right)
\]
\[
+ \left\| u_{0,\alpha} \right\|_{B^0} + \sum_{j=1}^{L} \left\| (v_{n,\alpha,L}^{j}, w_{n,\alpha,L}^{j,3}) \right\|_{B^0} < \infty
\]
(2.5)
and for all \( \alpha \) in \( ]0,1[ \),
\[
\mathcal{M}_\alpha \overset{\text{def}}{=} \sup_{L \geq 1} \sup_{1 \leq j \leq L} \sup_{n \in \mathbb{N}} \left( \left\| (v_{0,n,\alpha,L}^{0,\infty}, w_{0,n,\alpha,L}^{0,\infty,3}) \right\|_{S^\mu} + \left\| (v_{0,n,\alpha,L}^{0,\text{loc}}, w_{0,n,\alpha,L}^{0,\text{loc},3}) \right\|_{S^\mu} \right)
\]
\[
+ \left\| u_{0,\alpha} \right\|_{S^\mu} + \left\| (v_{n,\alpha,L}^{j}, w_{n,\alpha,L}^{j,3}) \right\|_{S^\mu} \right)
\]
is finite. Finally, we have
\[
\lim_{L \to \infty} \lim_{\alpha \to 0} \limsup_{n \to \infty} \left\| (v_{0,n,\alpha,L}^{0,\text{loc}}, w_{0,n,\alpha,L}^{0,\text{loc},3})(\cdot,0) \right\|_{B^0_{q,1}(\mathbb{R}^2)} = 0,
\]
(2.7)
\[
\forall (\alpha, L), \exists \eta(\alpha, L) / \forall \eta \leq \eta(\alpha, L), \forall n \in \mathbb{N}, (1 - \theta_{B,N})(v_{0,n,\alpha,L}^{0,\text{loc}}, w_{0,n,\alpha,L}^{0,\text{loc},3}) = 0, \text{ and}
\]
(2.8)
\[
\forall (\alpha, L, \eta), \exists n(\alpha, L, \eta) / \forall n \geq n(\alpha, L, \eta), \theta_{B,N}(v_{n,\alpha,L}^{0,\infty}, w_{n,\alpha,L}^{0,\infty,3}) = 0.
\]
(2.9)
The proof of this theorem is the purpose of Section 3.

Theorem 3 states that the sequence \( u_{0,n} \) is equal, up to a small remainder term, to a finite sum of orthogonal sequences of divergence-free vector fields. These sequences are obtained from the profile decomposition derived in [4] (see Proposition 3.2 in this paper) by grouping together all the profiles having the same horizontal scale \( \lambda_n \), and the form they take depends on whether the scale \( \lambda_n \) goes to 0 or infinity, these sequences are of the type \( \Lambda_{n,\alpha,L} \), \( \Lambda_{n,\alpha,L} \) is uniformed in the horizontal variable and vanishes at \( x_3 = 0 \), while the horizontal support of the third one \( \Lambda_{n,\alpha,L} \) goes to infinity.

Note that in contrast with classical profile decompositions (as stated in Theorem 1 for instance), cores of concentration do not appear in the profile decomposition given in Theorem 3 since all the profiles with the same horizontal scale are grouped together, and thus the decomposition is written in terms of scales only. The price to pay is that the profiles are no longer fixed functions, but bounded sequences.

Let us point out that the R-convergence of \( u_{0,n} \) to \( u_0 \) arises in a crucial way in the proof of Theorem 3. It excludes in the profile decomposition of \( u_{0,n} \) sequences of type (1.4) and (1.5).

The choice of the function space \( \mathcal{B}^p_q \) with \( p = 1 \) and \( q \leq 1 \) for the initial data is due to technical reasons. Indeed, the propagation of the profiles by (NS) is efficient in \( \mathcal{B}^p_q \) only if \( p \leq q \) (see also [22] in the isotropic case). Since the one-dimensional Besov space \( \mathcal{B}^p_q(\mathbb{R}) \) is an algebra (and a Banach space) only if \( q \leq 1 \), this forces the choice \( p = 1 \), and finally for the remainder term to be small in a space with index \( q \) equal to one, we need the original sequence to belong to a space with index \( q \) strictly smaller than one.

Once Theorem 3 is proved, the main step of the proof of Theorem 2 consists in proving that each individual profile involved in the decomposition of Theorem 3 does generate a global solution to (NS) as soon as \( n \) is large enough. This is mainly based on the following results
concerning respectively profiles of the type $\Lambda \lambda_j \left[\left(\int_{n \cdot A} + \lambda_j^3 \int_{n \cdot A} \right) \right]_{h_k}$, with $\lambda_j$ going to 0 or infinity, and the profiles of horizontal scale one, see respectively Theorems 4 and 5. Then, an orthogonality argument leads to the fact that the sum of the profiles also generates a global regular solution for large enough $n$.

In order to state the results, let us define the function spaces we shall be working with.

**Definition 2.4.** We define the space $A^s,s' = L^\infty(\mathbb{R}^+; B^{s,s'}) \cap L^2(\mathbb{R}^+; B^{s+1,s'})$ equipped with the norm

$$\|a\|_{A^s,s'} \overset{\text{def}}{=} \|a\|_{L^\infty(\mathbb{R}^+; B^{s,s'})} + \|a\|_{L^2(\mathbb{R}^+; B^{s+1,s'})},$$

and we denote $A^s = A^s\frac{s}{2}$.

- We denote by $F^{s,s'}$ any function space such that

$$\|L_0f\|_{L^2(\mathbb{R}^+; B^{s+1,s'})} \lesssim \|f\|_{F^{s,s'}},$$

where, for any non-negative real number $\tau$, $L_\tau f$ is the solution of $\partial_t L_\tau f - \Delta L_\tau f = f$ with $L_\tau f|_{t=0} = 0$. We denote $F^s = F^{s+\frac{s}{2}}$.

**Examples.** Using the smoothing effect of the heat flow as described by Lemma 6.2, it is easy to prove that the spaces $L^1(\mathbb{R}^+; B^{s,s'})$ and $L^1(\mathbb{R}^+; B^{s+1,s'-1})$ are continuously embedded in $F^{s,s'}$. We refer to Lemma 6.3 for a proof, along with other examples.

In the following we shall designate by $T_0(A,B)$ a generic constant depending only on the quantities $A$ and $B$. We shall denote by $T_1$ a generic non-decreasing function from $\mathbb{R}^+$ into $\mathbb{R}^+$ such that

$$\limsup_{r \to 0} \frac{T_1(r)}{r} < \infty,$$

and by $T_2$ a generic locally bounded function from $\mathbb{R}^+$ into $\mathbb{R}^+$. All those functions may vary from line to line. Let us notice that for any positive sequence $(a_n)_{n \in \mathbb{N}}$ belonging to $\ell^1$, we have

$$\sum_n T_1(a_n) \leq T_2\left(\sum_n a_n\right).$$

The notation $a \lesssim b$ means that an absolute constant $C$ exists such that $a \leq Cb$.

**Theorem 4.** A locally bounded function $\varepsilon_1$ from $\mathbb{R}^+$ into $\mathbb{R}^+$ exists which satisfies the following. For any $(v_0, w_0^3)$ in $S_\mu$ (see Definition 2.2), for any positive real number $\beta$ such that $\beta \leq \varepsilon_1(||(v_0, w_0^3)||_{S_\mu})$, the divergence free vector field

$$\Phi_0 \overset{\text{def}}{=} \left\langle (v_0 - \beta \nabla ^h \Delta^{-1} \partial_3 w_0^3, w_0^3)\right\rangle$$

generates a global solution $\Phi_\beta$ to (NS) which satisfies

$$\|\Phi_\beta\|_{A^0} \leq T_1(||(v_0, w_0^3)||_{B^0}) + \beta T_2(||(v_0, w_0^3)||_{S_\mu}).$$

Moreover, for any $(s,s')$ in $[-1+\mu, 1-\mu] \times [1/2, 7/2]$, we have, for any $r$ in $[1, \infty]$,

$$\|\Phi_\beta\|_{L^r(\mathbb{R}^+; B^{s,s'})} + \frac{1}{\beta^2} \|\Phi_\beta\|_{L^r(\mathbb{R}^+; B^{\frac{s}{2},s'})} \leq T_2(||(v_0, w_0^3)||_{S_\mu}).$$

The proof of this theorem is the purpose of Section 4. Let us point out that this theorem is a result of global existence for the Navier-Stokes system associated to a new class of arbitrarily large initial data generalizing the example consider in [14], and where the regularity is sharply estimated, in particular in anisotropic norms.
The existence of a global regular solution for the set of profiles associated with the horizontal scale 1 is ensured by the following theorem.

**Theorem 5.** Let us consider the initial data, with the notation of Theorem 3,

\[
\Phi_{0,n,a,L}^0 \overset{\text{def}}{=} u_{0,a} + \left( v_{0,n,a,L}^0 + h_n^0 w_{0,n,a,L}^0, w_{0,n,a,L}^0 \right)_{h_n^0} + \left( v_{0,n,a,L}^{0,\text{loc}}, h_n^0 w_{0,n,a,L}^{0,\text{loc}}, w_{0,n,a,L}^{0,\text{loc}} \right)_{h_n^0}.
\]

There is a constant \( \varepsilon_0 \), depending only on \( u_0 \) and on \( \mathcal{M}_\alpha \), such that if \( h_n^0 \leq \varepsilon_0 \), then the initial data \( \Phi_{0,n,a,L}^0 \) generates a global smooth solution \( \Phi_{n,a,L}^0 \) which satisfies for all \( s \) in \([-1+\mu, 1-\mu]\) and all \( r \) in \([1, \infty]\),

\[
\|\Phi_{n,a,L}^0\|_{L^r(\mathbb{R}^+; B^s_{\infty, 2})} \leq T_0(u_0, \mathcal{M}_\alpha).
\]

The proof of this theorem is the object of Section 5. As Theorem 4, this is also a global existence result for the Navier-Stokes system, generalizing Theorem 3 of [15] and Theorem 2 of [16], where we control regularity in a very precise way.

**Proof of Theorem 2.** Let us consider the profile decomposition given by Theorem 3. For a given positive (and small) \( \varepsilon \), Assertion (2.4) allows to choose \( \alpha, L \) and \( N_0 \) (depending of course on \( \varepsilon \)) such that

\[
\forall n \geq N_0, \|e^{t\Delta} \rho_{n,a,L}\|_{L^2(\mathbb{R}^+; B^s_{\infty, 2})} \leq \varepsilon.
\]

From now on the parameters \( \alpha \) and \( L \) are fixed so that (2.15) holds. Now let us consider the two functions \( \varepsilon_1, T_1 \) and \( T_2 (\text{resp. } \varepsilon_0 \text{ and } T_0) \) which appear in the statement of Theorem 4 (resp. Theorem 5). Since each sequence \((h_n^0)_{n \in \mathbb{N}}\), for \( 0 \leq j \leq L \), goes to zero as \( n \) goes to infinity, let us choose an integer \( N_1 \) greater than or equal to \( N_0 \) such that

\[
\forall n \geq N_1, \forall j \in \{0, \ldots, L\}, \ h_n^j \leq \min\left\{ \varepsilon_1(\mathcal{M}_\alpha), \varepsilon_0, \frac{\varepsilon}{L T_2(\mathcal{M}_\alpha)} \right\}.
\]

Then for \( 1 \leq j \leq L \) (resp. \( j = 0 \)), let us denote by \( \Phi_{n,\varepsilon}^j \) (resp. \( \Phi_{n,\varepsilon}^0 \)) the global solution of (NS) associated with the initial data

\[
\begin{align*}
&\left( v_{0,n,a,L}^j + h_n^j w_{0,n,a,L}^{j,h}, w_{0,n,a,L}^{j,3} \right)_{h_n^j} \quad \text{(resp. } u_{0,a} + \left( v_{0,n,a,L}^{0,\text{loc}}, h_n^0 w_{0,n,a,L}^{0,\text{loc}}, w_{0,n,a,L}^{0,\text{loc}} \right)_{h_n^0} \left)_{h_n^0} \right) \\
&\left( v_{0,n,a,L}^j + h_n^j w_{0,n,a,L}^{j,h}, w_{0,n,a,L}^{j,3} \right)_{h_n^j}
\end{align*}
\]

given by Theorem 4 (resp. Theorem 5). We look for the global solution associated with \( u_{0,n} \) under the form

\[
u_n = u_{n,\varepsilon}^{\text{app}} + R_{n,\varepsilon} \quad \text{with } u_{n,\varepsilon}^{\text{app}} \overset{\text{def}}{=} \sum_{j=0}^L \Lambda_{\lambda_j} \Phi_{n,\varepsilon}^j + e^{t\Delta} \rho_{n,a,L},
\]

recalling that \( \lambda_n^0 \equiv 1 \), see Definition 2.1. As recalled in the introduction, \( \Lambda_{\lambda_j} \Phi_{n,\varepsilon}^j \) solves (NS) with the initial data \( \Lambda_{\lambda_j}^0 \left( v_{0,n,a,L}^j + h_n^j w_{0,n,a,L}^{j,h}, w_{0,n,a,L}^{j,3} \right)_{h_n^j} \) by scaling invariance of the Navier-Stokes equations. Plugging this decomposition into the Navier-Stokes equation therefore
gives the following equation on $R_{n,\varepsilon}$:
\[
\partial_t R_{n,\varepsilon} - \Delta R_{n,\varepsilon} + \text{div}(R_{n,\varepsilon} \otimes R_{n,\varepsilon} + R_{n,\varepsilon} \otimes u_{n,\varepsilon}^{\text{app}} + u_{n,\varepsilon}^{\text{app}} \otimes R_{n,\varepsilon}) + \nabla p_{n,\varepsilon} = F_{n,\varepsilon} = F_{n,\varepsilon}^1 + F_{n,\varepsilon}^2 + F_{n,\varepsilon}^3
\]
with
\[
F_{n,\varepsilon}^1 \overset{\text{def}}{=} \text{div}(e^{t\Delta} \rho_{n,\alpha,L} \otimes e^{t\Delta} \rho_{n,\alpha,L})
\]
\[
F_{n,\varepsilon}^2 \overset{\text{def}}{=} \sum_{j=0}^L \text{div}(\Lambda_{\lambda_n^1} \Phi_{n,\varepsilon}^j \otimes e^{t\Delta} \rho_{n,\alpha,L} + e^{t\Delta} \rho_{n,\alpha,L} \otimes \Lambda_{\lambda_n^1} \Phi_{n,\varepsilon}^j)
\]
and
\[
F_{n,\varepsilon}^3 \overset{\text{def}}{=} \sum_{0 \leq j, k \leq L, j \neq k} \text{div}(\Lambda_{\lambda_n^1} \Phi_{n,\varepsilon}^j \otimes \Lambda_{\lambda_n^1} \Phi_{n,\varepsilon}^k),
\]
and where $\text{div}(u \otimes v) = \sum_{k=1}^3 \partial_k (u^j v^k)$.

We shall prove that there is an integer $N \geq N_1$ such that with the notation of Definition 2.4,
\[
\forall n \geq N, \quad \|F_{n,\varepsilon}\|_{F^0} \leq C\varepsilon,
\]
where $C$ only depends on $L$ and $\mathcal{M}_\alpha$. In the next estimates we omit the dependence of all constants on $\alpha$ and $L$, which are fixed.

Let us start with the estimate of $F_{n,\varepsilon}^1$. Using the fact that $\mathcal{B}^1$ is an algebra, we have
\[
\left\| e^{t\Delta} \rho_{n,\alpha,L} \otimes e^{t\Delta} \rho_{n,\alpha,L} \right\|_{L^1(\mathbb{R}^+; \mathcal{B}^1)} \lesssim \left\| e^{t\Delta} \rho_{n,\alpha,L} \right\|_{L^2(\mathbb{R}^+; \mathcal{B}^1)}^2,
\]
so
\[
\| \text{div}_h(e^{t\Delta} \rho_{n,\alpha,L} \otimes e^{t\Delta} \rho_{n,\alpha,L}) \|_{L^1(\mathbb{R}^+; \mathcal{B}^0)} \lesssim \left\| e^{t\Delta} \rho_{n,\alpha,L} \right\|_{L^2(\mathbb{R}^+; \mathcal{B}^1)}^2
\]
and
\[
\| \partial_3(e^{t\Delta} \rho_{n,\alpha,L} e^{t\Delta} \rho_{n,\alpha,L}) \|_{L^1(\mathbb{R}^+; \mathcal{B}^1, -\frac{1}{2})} \lesssim \left\| e^{t\Delta} \rho_{n,\alpha,L} \right\|_{L^2(\mathbb{R}^+; \mathcal{B}^1)}^2.
\]
According to the examples page 9, we infer that
\[
\|F_{n,\varepsilon}^1\|_{F^0} \lesssim \left\| e^{t\Delta} \rho_{n,\alpha,L} \right\|_{L^2(\mathbb{R}^+; \mathcal{B}^1)}^2.
\]
In view of Inequality (2.15), Estimate (2.19) ensures that
\[
\forall n \geq N_1, \quad \|F_{n,\varepsilon}^1\|_{F^0} \lesssim \varepsilon^2.
\]
Now let us consider $F_{n,\varepsilon}^2$. By the scaling invariance of the operators $\Lambda_{\lambda_n^1}$ in $L^2(\mathbb{R}^+; \mathcal{B}^1)$ and again the fact that $\mathcal{B}^1$ is an algebra, we get
\[
\left\| \Lambda_{\lambda_n^1} \Phi_{n,\varepsilon}^j \otimes e^{t\Delta} \rho_{n,\alpha,L} + e^{t\Delta} \rho_{n,\alpha,L} \otimes \Lambda_{\lambda_n^1} \Phi_{n,\varepsilon}^j \right\|_{L^1(\mathbb{R}^+; \mathcal{B}^1)} \lesssim \|\Phi_{n,\varepsilon}^j\|_{L^2(\mathbb{R}^+; \mathcal{B}^1)} \|\rho_{n,\alpha,L}\|_{L^2(\mathbb{R}^+; \mathcal{B}^1)}.
\]
Next we write, thanks to Estimates (2.12) and (2.14),
\[
\sum_{j=0}^L \|\Phi_{n,\varepsilon}^j\|_{L^2(\mathbb{R}^+; \mathcal{B}^1)} \leq T_0(u_0, \mathcal{M}_\alpha)
\]
\[
+ \sum_{j=1}^L \left(T_1(\|v_j^{n,\alpha,L}\|_{\mathcal{B}^0}) + h_n^2 T_2(\|v_j^{n,\alpha,L}\|_{S_0})\right),
\]
Using the fact that \( N \) and \( \gamma \) are orthogonal (see Definition 2.1), we have for any \( j \) and \( k \) such that \( j \neq k \).

We deduce that
\[
\lim_{n \to \infty} \min \{ \frac{\lambda_n}{\lambda_k} \} = 0.
\]

As the sequences \( (\lambda_n)_{n \in \mathbb{N}} \) and \( (\lambda_k)_{k \in \mathbb{N}} \) are orthogonal, we have for any \( j \) and \( k \) such that \( j \neq k \).

Using the fact that \( \Phi_{j} \) is an algebra along with the Hölder inequality, we infer that for a small enough \( \gamma \) in \([0,1]\).

Finally, let us consider \( \Phi_{j} \). Recalling that \( \alpha \) and \( L \) are fixed, it suffices to prove in view of the examples page 9 that there is \( N \geq N_{0} \) such that for all \( \alpha \leq N \), and for all \( 0 \leq j \neq k \leq L \).

It follows (of course up to a change of \( T_{j} \)) that for small enough \( \gamma \).

Using Condition (2.16) on the sequences \( (\lambda_{n})_{n \in \mathbb{N}} \), implies that
\[
\sum_{j=0}^{L} \| \Phi_{j} \|_{L^{p}(\mathbb{R}^d)} \leq T_{0}(\alpha, M_{0}) + T_{0}(M) + T_{0}(W) + \varepsilon.
\]

which can be written due to (2.11)
Now, in order to conclude the proof of Theorem 2, we need the following result.

**Proposition 2.5.** A constant $C_0$ exists such that, if $U$ is in $L^2(\mathbb{R}^+; B^1)$, $u_0$ in $B^0$ and $f$ in $F^0$ such that
\[
\|u_0\|_{B^0} + \|f\|_{F^0} \leq \frac{1}{C_0} \exp\left(-C_0 \int_0^\infty \|U(t)\|_{B^1}^2 dt\right),
\]
then the problem
\[
(\text{NS}_U) \quad \begin{cases}
\partial_t u + \text{div}(u \otimes u + u \otimes U + U \otimes u) - \Delta u = -\nabla p + f \\
d\text{div} u = 0 \quad \text{and} \quad u|_{t=0} = u_0
\end{cases}
\]
has a unique global solution in $L^2(\mathbb{R}^+; B^1)$ which satisfies
\[
\|u\|_{L^2(\mathbb{R}^+; B^1)} \lesssim \|u_0\|_{B^0} + \|f\|_{F^0}.
\]
The proof of this proposition can be found in Section 6.

**Conclusion of the proof of Theorem 2.** By definition of $u_{\text{app}}^{n,\varepsilon}$ we have
\[
\|u_{\text{app}}^{n,\varepsilon}\|_{L^2(\mathbb{R}^+; B^1)} \leq \left\| \sum_{j=0}^L \Lambda_k^j \Phi_{n,\varepsilon}^j \right\|_{L^2(\mathbb{R}^+; B^1)} + \|\varepsilon \Delta \rho_{n,\alpha,L}\|_{L^2(\mathbb{R}^+; B^1)}.
\]
Inequalities (2.15) and (2.22) imply that for $n$ sufficiently large
\[
\|u_{\text{app}}^{n,\varepsilon}\|_{L^2(\mathbb{R}^+; B^1)} \leq T_0(u_0, \mathcal{M}_\alpha) + T_2(\mathcal{M}) + C\varepsilon.
\]
Because of (2.18), it is clear that, if $\varepsilon$ is small enough,
\[
\|F_{n,\varepsilon}\|_{F^0} \leq \frac{1}{C_0} \exp\left(\frac{-C_0 \|u_{\text{app}}^{n,\varepsilon}\|_{L^2(\mathbb{R}^+; B^1)}^2}{C_0}\right)
\]
which ensures that $u_{0,n}$ generates a global regular solution and thus concludes the proof of Theorem 2. \qed

The paper is structured as follows. In Section 3 we prove Theorem 3. Theorems 4 and 5 are proved in Sections 4 and 5 respectively. Section 6 is devoted to the recollection of some material on anisotropic Besov spaces. We also prove Proposition 2.5 and an anisotropic propagation of regularity result for the Navier-Stokes system (Proposition 4.8).

3. **Profile decomposition of the sequence of initial data: proof of Theorem 3**

The proof of Theorem 3 is structured as follows. First, in Section 3.1 we write down the profile decomposition of any bounded sequence of divergence free vector fields R-converging to zero, following the results of [4]. Next we reorganize the profile decomposition by grouping together all profiles having the same horizontal scale and we check that all the conclusions of Theorem 3 hold: that is performed in Section 3.2.

3.1. **Profile decomposition of divergence free vector fields, R-converging to zero.**
In this section we start by recalling the result of [4], where an anisotropic profile decomposition of sequences of $B_{1,q}$ is introduced. Then we use the assumption of R-convergence (see Definition 1.2) to eliminate from the profile decomposition all isotropic profiles. Finally we study the particular case of divergence free vector fields. Under this assumption, we are able to restrict our attention to (rescaled) vector fields with slow vertical variations.
3.1.1. The case of bounded sequences. Before stating the result proved in [4], let us give the definition of anisotropic scaling operators: for any two sequences of positive real numbers \((\varepsilon_n)_{n \in \mathbb{N}}\) and \((\gamma_n)_{n \in \mathbb{N}}\), and for any sequence \((x_n)_{n \in \mathbb{N}}\) of points in \(\mathbb{R}^3\), we denote

\[
\Lambda_{\varepsilon_n, \gamma_n, x_n} \phi(x) \overset{\text{def}}{=} \frac{1}{\varepsilon_n} \left( \frac{x_n - x_{n, h}}{\varepsilon_n} \frac{x_3 - x_{n, 3}}{\gamma_n} \right).
\]

Observe that the operator \(\Lambda_{\varepsilon_n, \gamma_n, x_n}\) is an isometry in the space \(B_{p,q}\) for any \(1 \leq p \leq \infty\) and any \(0 < q \leq \infty\). Notice also that when the sequences \(\varepsilon_n\) and \(\gamma_n\) are equal, then the operator \(\Lambda_{\varepsilon_n, \gamma_n, x_n}\) reduces to the isotropic scaling operator \(\Lambda_{\varepsilon_n, x_n}\) defined in (1.3), and such isotropic profiles will be the ones to disappear in the profile decomposition thanks to the assumption of \(R\)-convergence. We also have a definition of orthogonal triplets of sequences, analogous to Definition 2.1.

**Definition 3.1.** We say that two triplets of sequences \((\varepsilon_n^\ell, \gamma_n^\ell, x_n^\ell)_{n \in \mathbb{N}}\) with \(\ell\) belonging to \(\{1, 2\}\), where \((\varepsilon_n^\ell, \gamma_n^\ell)_{n \in \mathbb{N}}\) are two sequences of positive real numbers and \(x_n^\ell\) are sequences in \(\mathbb{R}^3\), are orthogonal if, when \(n\) tends to infinity,

\[
either \frac{\varepsilon_1^n}{\varepsilon_2^n} + \frac{\gamma_1^n}{\gamma_2^n} \rightarrow \infty \quad \text{or} \quad (\varepsilon_1^n, \gamma_1^n) \equiv (\varepsilon_2^n, \gamma_2^n) \quad \text{and} \quad |(x_1^n)^{\varepsilon_1^n, \gamma_1^n} - (x_2^n)^{\varepsilon_2^n, \gamma_2^n}| \rightarrow \infty,
\]

where we have denoted \((x_n^\ell)^{\varepsilon_n^\ell, \gamma_n^\ell} \overset{\text{def}}{=} \left( \frac{x_{n, h}^\ell}{\varepsilon_n^\ell} \frac{x_{n, 3}^\ell}{\gamma_n^\ell} \right).

We recall without proof the following result.

**Proposition 3.2 ([4]).** Let \((\varphi_n)_{n \in \mathbb{N}}\) be a sequence belonging to \(B_{1,q}\) for some \(0 < q \leq 1\), with \(\varphi_n\) converging weakly to \(\phi^0\) in \(B_{1,q}\) as \(n\) goes to infinity. For all integers \(\ell \geq 1\) there is a triplet of orthogonal sequences in the sense of Definition 3.1, denoted by \((\varepsilon_n^\ell, \gamma_n^\ell, x_n^\ell)_{n \in \mathbb{N}}\) and functions \(\phi^\ell\) in \(B_{1,q}\) such that up to extracting a subsequence, one can write the sequence \((\varphi_n)_{n \in \mathbb{N}}\) under the following form, for each \(L \geq 1\):

\[
(3.1) \quad \varphi_n = \phi^0 + \sum_{\ell=1}^L \Lambda_{\varepsilon_n^\ell, \gamma_n^\ell, x_n^\ell} \phi^\ell + \psi_n^L,
\]

where \(\psi_n^L\) satisfies

\[
(3.2) \quad \limsup_{n \to \infty} \|\psi_n^L\|_{B_{1,q}} \to 0, \quad L \to \infty.
\]

Moreover the following stability result holds:

\[
(3.3) \quad \sum_{\ell \geq 1} \|\phi^\ell\|_{B_{1,q}} \lesssim \sup_n \|\varphi_n\|_{B_{1,q}} + \|\phi^0\|_{B_{1,q}}.
\]

**Remark 3.3.** As pointed out in [4, Section 2], if two scales appearing in the above decomposition are not orthogonal, then they can be chosen to be equal. We shall therefore assume from now on that is the case: two sequences of scales are either orthogonal, or equal.

**Remark 3.4.** By density of smooth, compactly supported functions in \(B_{1,q}\), one can write

\[
\phi^\ell = \phi_\alpha^\ell + r_\alpha^\ell \quad \text{with} \quad \|r_\alpha^\ell\|_{B_{1,q}} \leq \alpha
\]

where \(\phi_\alpha^\ell\) are arbitrarily smooth and compactly supported, and moreover

\[
(3.4) \quad \sum_{\ell \geq 1} (\|\phi_\alpha^\ell\|_{B_{1,q}} + \|r_\alpha^\ell\|_{B_{1,q}}) \lesssim \sup_n \|\varphi_n\|_{B_{1,q}} + \|\phi^0\|_{B_{1,q}}.
\]
Next we consider the particular case when \( \varphi_n \) R-converges to \( \varphi^0 \), in the sense of Definition 1.2. Let us prove the following result.

**Proposition 3.5.** Let \( \varphi_n \) and \( \varphi^0 \) belong to \( B_{1,q} \) for some \( 0 < q \leq \infty \), with \( \varphi_n \) R-converging to \( \varphi^0 \) as \( n \) goes to infinity. Then with the notation of Proposition 3.2, the following result holds:

\[
\forall \ell \geq 1, \quad \lim_{n \to \infty} \left( \frac{\gamma_n}{\gamma_n} \right)^{-1} \varepsilon_{n,\ell} \in \{0, \infty\}.
\]

**Remark 3.6.** This proposition shows that if one assumes that the weak convergence is actually an R-convergence, then the only profiles remaining in the decomposition are those with truly anisotropic horizontal and vertical scales. This eliminates profiles of the type \( n \varphi(nx) \) and \( \varphi(\cdot - x_n) \) with \( |x_n| \to \infty \), for which clearly the conclusion of Theorem 2 is unknown in general. This also shows that the assumption of R-convergence is equivalent to the one of \( \varepsilon \) if \( \varepsilon \) and \( \phi \) truly anisotropic horizontal and vertical scales. This eliminates profiles of the type \( \varepsilon \cdot \). Now let us take the weak limit of both sides of the equality as \( n \) tends to infinity, for any value of the sequences \( n, k, j \). Concerning the right-hand side, we start by noticing that

\[
\left( \frac{\gamma_n}{\gamma_n} \right)^{-1} \varepsilon_{n,\ell} \to 0 \quad \text{or} \quad \left( \frac{\gamma_n}{\gamma_n} \right)^{-1} \varepsilon_{n,\ell} \to \infty \quad \implies \quad \left( \frac{\gamma_n}{\gamma_n} \right)^{-1} \varepsilon_{n,\ell} \Delta^{h^k}_{n} f_{n} = C > 0 \quad \implies \quad \lim_{n \to \infty} |j_n - k_n| = \infty.
\]

**Proof of Proposition 3.5.** To prove (3.5) we consider the decomposition provided in Proposition 3.2 and we assume that there is \( k \in \mathbb{N} \) such that \( \left( \frac{\gamma_n}{\gamma_n} \right)^{-1} \varepsilon_{n,\ell} \) goes to 1 as \( n \) goes to infinity. We rescale the decomposition (3.1) to find, choosing \( L \geq k \),

\[
\varepsilon_{n}(\varphi_n - \varphi^0)(\varepsilon_n, x_n) = \sum_{\ell=1}^{L} \frac{\Lambda_{1,\ell,\ell,k}}{\varepsilon_n} \varepsilon_n \Delta^{h^k}_{n} f_{n} + \Lambda_{1,\ell,\ell,k} \frac{1}{\varepsilon_n} \varepsilon_n \Delta^{h^k}_{n} f_{n},
\]

where

\[
x_n \defeq \frac{x_n - x_k}{\varepsilon_n}.
\]

Now let us take the weak limit of both sides of the equality as \( n \) goes to infinity. By Definition 1.2 we know that the left-hand side goes weakly to zero. Concerning the right-hand side, we start by noticing that

\[
\frac{\varepsilon_{n}}{\varepsilon_n} \to 0 \quad \text{or} \quad \frac{\varepsilon_{n}}{\varepsilon_n} \to \infty \quad \implies \quad \frac{\varepsilon_{n}}{\varepsilon_n} \varepsilon_n \Delta^{h^k}_{n} f_{n} = \frac{\varepsilon_{n}}{\varepsilon_n} \Delta^{h^k}_{n} f_{n} \to 0,
\]

as \( n \) tends to infinity, for any value of the sequences \( \varepsilon_{n}, x_n, x_k \). So we can restrict the sum on the right-hand side to the case when \( \varepsilon_{n}/\varepsilon_n \to 1 \). Then we write similarly

\[
\frac{\varepsilon_{n}}{\varepsilon_n} \to \infty \quad \implies \quad \Lambda_{1,\ell,\ell,k} \frac{1}{\varepsilon_n} \varepsilon_n \Delta^{h^k}_{n} f_{n} \to 0,
\]

so there only remain indexes \( \ell \) such that \( \varepsilon_{n}/\varepsilon_n \to 0 \) or 1. Finally we use the fact that if \( \varepsilon_{n}/\gamma_n \ell \to 1 \), then the weak limit of \( \Lambda_{1,\ell,\ell,k} \phi_{\ell} \) can be other than zero only if \( x_{n,\ell,k} \to a_{\ell,k} \in \mathbb{R}^3 \), and similarly if \( \varepsilon_{n}/\gamma_n \ell \to 0 \), then the weak limit of \( \Lambda_{1,\ell,\ell,k} \phi_{\ell} \) can be other than zero only if \( x_{n,\ell,h} \to a_{\ell,h} \in \mathbb{R}^2 \), and \( (x_{n,\ell,j} - x_{n,\ell,j})/\gamma_n \ell \to a_{\ell,j} \in \mathbb{R} \). So let us define

\[
\begin{eqnarray*}
S^{1,L}(k) & \defeq & \left\{ 1 \leq \ell \leq L \mid \varepsilon_{n} = \varepsilon_n, x_{n,k} \to a_{\ell,k} \in \mathbb{R}^3, \frac{\varepsilon_{n}}{\varepsilon_n} \to 1 \right\}, \\
S^{0,L}(k) & \defeq & \left\{ 1 \leq \ell \leq L \mid \varepsilon_{n} = \varepsilon_n, x_{n,h} \to a_{\ell,h} \in \mathbb{R}^2, \frac{\varepsilon_{n,3}}{\varepsilon_n} \to 1 \right\}.
\end{eqnarray*}
\]
Actually by orthogonality the set \( S^1(k) \) only contains one element, which is \( k \). So for each \( L \geq 1 \), as \( n \) goes to infinity we have finally
\[
- \Lambda \frac{1}{\varepsilon^h_n} e_k = \frac{a^L_n}{\varepsilon^h_n} - \frac{e_k^L}{\varepsilon^h_n} \psi_n^{L} \rightarrow \phi_k + \sum_{\ell \in S^0(k)} \phi^\ell (\gamma_n - a^\ell_n, -a^\ell_n).
\]
Since the left-hand side tends to 0 in \( B^0 \) as \( L \) tends to infinity, uniformly in \( n \in \mathbb{N} \), we deduce that \( \psi_k \) must be independent of \( x_3 \). That means that there is no vertical scale \( \gamma_n^k \), which proves the result.

### 3.1.2. The case of divergence free vector fields

Putting together Propositions 3.2 and 3.5 along with Remark 3.4 and the fact that \( u_{0,n} \) is divergence free we obtain the following result.

**Proposition 3.7.** Under the assumptions of Theorem 2, the following holds. For all integers \( \ell \geq 1 \) there is a triplet of orthogonal sequences in the sense of Definition 2.1, denoted by \( (\varepsilon^\ell_n, \gamma_n^\ell, x^\ell_n)_{n \in \mathbb{N}} \) and for all \( \alpha \in [0,1] \) there are arbitrarily smooth divergence free vector fields \( \tilde{\phi}^\ell_n, 0 \) and \( \tilde{\psi}^\ell_n(0) \) with \( \tilde{\phi}^\ell_n \) and \( \tilde{\psi}^\ell_n \) compactly supported, and such that up to extracting a subsequence, one can write the sequence \( (u_{0,n})_{n \in \mathbb{N}} \) under the following form, for each \( L \geq 1 \):

\[
u_{0,n} = u_0 + \sum_{\ell=1}^{L} \Lambda \varepsilon_n^{\ell, n} \gamma_n^{\ell, n} \left( \tilde{\phi}^\ell_n + \tilde{\psi}^\ell_n - \varepsilon_n^\ell - \Delta^\ell_n \partial_3 (\tilde{\phi}^\ell_n + r^\ell_n, \tilde{\phi}^\ell_n + r^\ell_n) \right)
+ \left( \tilde{\psi}^\ell_n - \Delta^\ell_n \partial_3 (\tilde{\phi}^\ell_n, \tilde{\psi}^\ell_n) \right),
\]

where \( \tilde{\phi}^\ell_n \) and \( \tilde{\psi}^\ell_n \) are independent of \( \alpha \) and satisfy
\[
\lim_{n \to \infty} \left( \| \tilde{\psi}^\ell_n \|_{B^0} + \| \tilde{\psi}^\ell_n \|_{B^0} \right) \rightarrow 0, \quad L \to \infty,
\]
while \( \tilde{r}^\ell_n \) and \( r^\ell_n \) are independent of \( n \) and \( L \) and satisfy for each \( \ell \in \mathbb{N} \)
\[
\| \tilde{r}^\ell_n \|_{B_{1,q}} + \| r^\ell_n \|_{B_{1,q}} \leq \alpha.
\]
Moreover the following properties hold:
\[
\forall \ell \geq 1, \quad \lim_{n \to \infty} (\gamma_n^\ell)^{-1} \varepsilon_n^\ell \in \{0, \infty\},
\]
\[
\gamma_n^\ell^{-1} \varepsilon_n^\ell = 0 \quad \Rightarrow \quad \phi_n^\ell \equiv \tilde{r}^\ell_n \equiv 0,
\]
as well as the following stability result, which is uniform in \( \alpha \):
\[
\sum_{\ell \geq 1} (\| \tilde{\phi}^\ell_n \|_{B_{1,q}} + \| \tilde{r}^\ell_n \|_{B_{1,q}} + \| r^\ell_n \|_{B_{1,q}} + \| \tilde{r}^\ell_n \|_{B_{1,q}}) \lesssim \sup_n \| u_{0,n} \|_{B_{1,q}} + \| u_0 \|_{B_{1,q}}.
\]

**Proof of Proposition 3.7.** Note that due to Proposition 3.5 which asserts that the hypothesis of R-convergence is equivalent to the one of anisotropic oscillations required in [4] (see Remark 3.6), Proposition 3.7 is nothing else than Proposition 2.4 in [4]. Let us recall the argument. First we decompose the third component \( u_{0,n}^3 \) according to Proposition 3.2 and Remark 3.4: with the above notation, this gives rise to
\[
u_{0,n}^3 = u_0^3 + \sum_{\ell=1}^{L} \Lambda \varepsilon_n^{\ell, n} \gamma_n^{\ell, n} \left( \phi^\ell_n + r^\ell_n \right) + \psi_n^L,
\]
with \( \lim_{n \to \infty} \| \psi_n^L \|_{B^0}^{L \to \infty} \rightarrow 0 \). Moreover thanks to Proposition 3.5, we know that for all \( \ell \geq 1 \), we have \( \lim_{n \to \infty} (\gamma_n^\ell)^{-1} \varepsilon_n^\ell \) belongs to \( \{0, \infty\} \).
Next thanks to the divergence-free assumption we recover the profile decomposition for $u^h_{0,n}$.
Indeed there is a two-component, divergence-free vector field $\nabla^h C_{0,n}$ such that
$$u^h_{0,n} = \nabla^h C_{0,n} - \nabla^h \Delta^h_0 \partial_3 u^3_{0,n},$$
where $\nabla^h = (-\partial_1, \partial_2)$, and some function $\varphi$ such that
$$u^h_0 = \nabla^h \varphi - \nabla^h \Delta^h_0 \partial_3 u^3_0.$$

Now since $\partial_3 u^3_{0,n} = -\text{div}_h u^h_{0,n}$ and $u^h_{0,n}$ is bounded in $B_{1,q}$, we deduce that $\nabla^h C_{0,n}$ is a bounded sequence in $B_{1,q}$ and similarly for $\nabla^h \varphi$. Thus, applying again the profile decomposition of Proposition 3.2 and Remark 3.4, we get

$$\nabla^h C_{0,n} - \nabla^h \varphi = \sum_{\ell=1}^L \Lambda_{x^\ell_n, x^\ell_n} (\tilde{\varphi}^h_{\alpha} + r^h_{\alpha}) + \tilde{\psi}^{h,L},$$

with $\limsup_{n \to \infty} \|\tilde{\psi}^{h,L}\|_{g^0} \xrightarrow{L \to \infty} 0$. Moreover Proposition 3.5 ensures that for all $\ell \geq 1$, we have $\lim_{n \to \infty} (\gamma_n^0)^{-1} \varepsilon_n^\ell \in \{0, \infty\}$.

Finally, by the divergence free assumption, $u^3_{0,n}$ is bounded in $B^0_{1,2}$ which implies that necessarily $\varphi_n^\ell \equiv r_n^\ell \equiv 0$ in the case when $\lim_{n \to \infty} (\gamma_n^0)^{-1} \varepsilon_n^\ell = \infty$ (see Lemma 5.3 in [4]).

Up to relabelling the various sequences appearing in (3.12) and (3.13), Proposition 3.7 follows.

3.2. Regrouping of profiles according to horizontal scales. With the notation of Proposition 3.7, let us define the following scales: $\varepsilon_n^0 \equiv \gamma_n^0 \equiv 1$, and $x_n^0 \equiv 0$, so that one has $u_0 \equiv \Lambda_{x_n^0, \gamma_n^0} u_0$.

In order to proceed with the re-organization of the profile decomposition provided in Proposition 3.7, we introduce some more definitions, keeping the notation of Proposition 3.7. For a given $L \geq 1$ we define recursively an increasing (finite) sequence of indexes $\ell_k \in \{1, \ldots, L\}$ by

$$\ell_0 \overset{\text{def}}{=} 0, \quad \ell_{k+1} \overset{\text{def}}{=} \min \left\{ \ell \in \{\ell_k + 1, \ldots, L\} / \frac{\varepsilon_n^\ell}{\gamma_n^0} \to 0 \quad \text{and} \quad \ell \notin \bigcup_{k'=0}^k \Gamma^L(\varepsilon_n^{\ell'}) \right\},$$

where for $0 \leq \ell \leq L$, we define (recalling that by Remark 3.3 if two scales are not orthogonal, then they are equal),

$$\Gamma^L(\varepsilon_n^\ell) \overset{\text{def}}{=} \left\{ \ell' \in \{1, \ldots, L\} / \frac{\varepsilon_n^{\ell'}}{\gamma_n^0} \equiv \varepsilon_n^\ell \quad \text{and} \quad \varepsilon_n^{\ell'} (\gamma_n^0)^{-1} \to 0, \ n \to \infty \right\}.$$

We call $\mathcal{L}(L)$ the largest index of the sequence $(\ell_k)$ and we may then introduce the following partition:

$$\left\{ \ell \in \{1, \ldots, L\} / \frac{\varepsilon_n^\ell (\gamma_n^0)^{-1}}{\gamma_n^0} \to 0 \right\} = \bigcup_{k=0}^{\mathcal{L}(L)} \Gamma^L(\varepsilon_n^{\ell_k}).$$

We shall now regroup profiles in the decomposition (3.7) of $u_{0,n}$ according to the value of their horizontal scale. We fix from now on an integer $L \geq 1$. 
3.2.1. Construction of the profiles for $\ell = 0$. Before going into the technical details of the construction, let us discuss an example explaining the computations of this paragraph. Consider the particular case when $u_{0,n}$ is given by

$$u_{0,n}(x) = u_0(x) + (v_0^n(xh, 2^{-n}x_3) + u_0^{0,h}(xh, 2^{-2n}x_3), 0) + (v_0^0(x_1 + n, x_2, 2^{-n}x_3), 0),$$

with $v_0^n$ and $u_0^{0,h}$ smooth (say in $B_{1,q}^{s,s'}$ for all $s, s'$ in $\mathbb{R}$) and compactly supported. Let us assume that $(u_{0,n})_{n \in \mathbb{N}}$ R-converges to $u_0$, as $n$ tends to infinity. Then we can write

$$u_{0,n}(x) = u_0(x) + (v_{0,n}^{0,loc}(xh, 2^{-n}x_3), 0) + (v_{0,n}^{0,\infty}(xh, 2^{-n}x_3), 0),$$

with $v_{0,n}^{0,loc}(y) := v_0^n(y) + u_0^{0,h}(y, 2^{-n}y_3)$ and $v_{0,n}^{0,\infty}(y) = v_0^n(y_1 + 2^n, y_2, y_3)$. We notice that $v_{0,n}^{0,loc}$ and $v_{0,n}^{0,\infty}$ are uniformly bounded in $B_{1,q}$, but also in $B_{1,q}^{s,s'}$ for any $s$ in $\mathbb{R}$ and $s' \geq 1/2$. Moreover since $u_{0,n} \rightharpoonup u_0$ as $n$ goes to infinity, we have that $v_0^n(xh, 0) + u_0^{0,h}(xh, 0) \equiv 0$, hence $v_{0,n}^{0,loc}(xh, 0) = 0$. The initial data $u_{0,n}$ has therefore been re-written as

$$u_{0,n}(x) = u_0(x) + (v_{0,n}^{0,loc}(xh, 2^{-n}x_3), 0) + (v_{0,n}^{0,\infty}(xh, 2^{-n}x_3), 0) \text{ with } v_{0,n}^{0,loc}(xh, 0) = 0$$

and where the support in $x_h$ of $v_{0,n}^{0,loc}(xh, 2^{-n}x_3)$ is in a fixed compact set whereas the support in $x_h$ of $v_{0,n}^{0,\infty}(xh, 2^{-n}x_3)$ escapes to infinity. This is of the same form as in the statement of Theorem 3.

When considering all the profiles having the same horizontal scale (1 here), the point is therefore to choose the smallest vertical scale ($2^n$ here) and to write the decomposition in terms of that scale only. Of course that implies that contrary to usual profile decompositions, the profiles are no longer fixed functions in $B_{1,q}$, but sequences of functions, bounded in $B_{1,q}$.

In view of the above example, let $\ell_0^\gamma$ be an integer such that $\gamma_n^{\ell_0^\gamma}$ is the smallest vertical scale going to infinity, associated with profiles for $1 \leq \ell \leq L$, having 1 for horizontal scale. More precisely we ask that

$$\gamma_n^{\ell_0^\gamma} = \min_{\ell \in \Gamma^L(1)} \gamma_n^{\ell},$$

where according to (3.15),

$$\Gamma^L(1) = \left\{ \ell^\gamma \in \{1, \ldots, L\} / \varepsilon_{n}^{\ell^\gamma} \equiv 1 \text{ and } \gamma_n^{\ell^\gamma} \to \infty, n \to \infty \right\}.$$

Notice that the minimum of the sequences $\gamma_n^{\ell^\gamma}$ is well defined in our context thanks to the fact that due to Remark 3.3, either two sequences are orthogonal in the sense of Definition 2.1, or they are equal. Remark also that $\ell_0^\gamma$ is by no means unique, as several profiles may have the same horizontal scale as well as the same vertical scale (in which case the concentration cores must be orthogonal). Now we denote

$$h_n^{\ell_0^\gamma} \overset{\text{def}}{=} (\gamma_n^{\ell_0^\gamma})^{-1},$$

and we notice that $h_n^{\ell_0^\gamma}$ goes to zero as $n$ goes to infinity for each $L$. Note also that $h_n^{\ell_0^\gamma}$ depends on $L$ through the choice of $\ell_0^\gamma$, since if $L$ increases then $\ell_0^\gamma$ may also increase; this dependence is omitted in the notation for simplicity. Let us define (up to a subsequence extraction)

$$a^\ell \overset{\text{def}}{=} \lim_{n \to \infty} \left( x_{n,h}^\ell, \frac{x_{n,3}^\ell}{\gamma_n^\ell} \right).$$
We then define the divergence-free vector fields

\[ v_{0,0,n,a,L}^{\text{loc},h}(y) \overset{\text{def}}{=} \sum_{\ell \in \Gamma^{(1)}_h} \left( \phi_{0,\ell}^h \left( y_h - x_{n,h}^{\ell}, \frac{y^3}{h \gamma_n} \right) \right) \]

and

\[ w_{0,0,n,a,L}^{\text{loc}}(y) \overset{\text{def}}{=} \sum_{\ell \in \Gamma^{(1)}_h \cap \mathbb{Z}^2} \left( -\frac{1}{h^\gamma_n} \nabla_h \Delta_h^{-1} \partial_{\beta} \phi_{0,\ell}^h, \phi_{0,\ell}^h \right) \left( y_h - x_{n,h}^{\ell}, \frac{y^3}{h \gamma_n} \right). \]

By construction we have

\[ w_{0,0,n,a,L}^{\text{loc},h} = -\nabla_h \Delta_h^{-1} \partial_{\beta} w_{0,0,n,a,L}^{\text{loc}}. \]

Similarly we define

\[ v_{0,0,n,a,L}^{\text{loc},\infty}(y) \overset{\text{def}}{=} \sum_{\ell \in \Gamma^{(1)}_h \cap \mathbb{Z}^2} \left( \phi_{0,\ell}^h \left( y_h - x_{n,h}^{\ell}, \frac{y^3}{h \gamma_n} \right) \right) \]

and

\[ w_{0,0,n,a,L}^{\text{loc},\infty}(y) \overset{\text{def}}{=} \sum_{\ell \in \Gamma^{(1)}_h \cap \mathbb{Z}^2} \left( -\frac{1}{h^\gamma_n} \nabla_h \Delta_h^{-1} \partial_{\beta} \phi_{0,\ell}^h, \phi_{0,\ell}^h \right) \left( y_h - x_{n,h}^{\ell}, \frac{y^3}{h \gamma_n} \right). \]

By construction we have again

\[ w_{0,0,n,a,L}^{\text{loc},\infty} = -\nabla_h \Delta_h^{-1} \partial_{\beta} w_{0,0,n,a,L}^{\text{loc},\infty}. \]

Moreover recalling the notation

\[ \left[ f \right]_{h_0}^n(x) \overset{\text{def}}{=} f(x_h, h_0 x_3) \]

and

\[ A_{\varepsilon_n,0,n,a,x_n}^{\gamma_n,0,n,a,x_n} \phi(x) \overset{\text{def}}{=} \frac{1}{\varepsilon_n} \left( \frac{x_h - x_{n,a}^{\ell}}{\varepsilon_n}, \frac{x_{3,n,a}^{\ell} - x_{3,n,a}^{\ell}}{\gamma_n} \right), \]

one can compute that

\[ \sum_{\ell \in \Gamma^{(1)}_h \cap \mathbb{Z}^2} A_{\varepsilon_n,0,n,a,x_n}^{\gamma_n} \left( \phi_{0,\ell}^h - \frac{1}{\gamma_n} \nabla_h \Delta_h^{-1} \partial_{\beta} \phi_{0,\ell}^h, \phi_{0,\ell}^h \right) = \left[ \left( v_{0,0,n,a,L}^{\text{loc},h} + h_n^{0,n,a,L} \right) \right]_{h_n} \]

and

\[ \sum_{\ell \in \Gamma^{(1)}_h \cap \mathbb{Z}^2} A_{\varepsilon_n,0,n,a,x_n}^{\gamma_n} \left( \phi_{0,\ell}^h - \frac{1}{\gamma_n} \nabla_h \Delta_h^{-1} \partial_{\beta} \phi_{0,\ell}^h, \phi_{0,\ell}^h \right) = \left[ \left( v_{0,0,n,a,L}^{\text{loc},\infty} + h_n^{0,n,a,L} \right) \right]_{h_n}. \]

Let us now check that \( v_{0,0,n,a,L}, w_{0,0,n,a,L}^{\text{loc}} \) and \( w_{0,0,n,a,L}^{\text{loc}} \) satisfy the bounds given in the statement of Theorem 3. We shall only study \( v_{0,0,n,a,L}^{\text{loc}} \) and \( w_{0,0,n,a,L}^{\text{loc}} \) as the other study is very similar. On the one hand, by translation and scale invariance of \( \mathcal{B}_{1,q} \) and using definitions (3.19) and (3.20), we get

\[ \| v_{0,0,n,a,L}^{\text{loc},h} \|_{\mathcal{B}_{1,q}} \leq \sum_{\ell \geq 1} \| \phi_{0,\ell}^h \|_{\mathcal{B}_{1,q}} \quad \text{and} \quad \| w_{0,0,n,a,L}^{\text{loc},\infty} \|_{\mathcal{B}_{1,q}} \leq \sum_{\ell \geq 1} \| \phi_{0,\ell}^h \|_{\mathcal{B}_{1,q}}. \]
By (3.11), we infer that
\begin{equation}
\|v_{0,n,a,L}^{0,\text{loc},h}\|_{B_{1,q}} + \|w_{0,n,a,L}^{0,\text{loc},3}\|_{B_{1,q}} \leq C \quad \text{uniformly in } \alpha, L, n.
\end{equation}
Moreover for each given \(\alpha\), the profiles are as smooth as needed, and since in the above sums by construction \(\gamma_{n,L}^{\ell} \leq \gamma_{n,L}^{\ell}\), one gets also after an easy computation
\begin{equation}
\forall s \in \mathbb{R}, \forall s' \geq 1/2, \quad \|v_{0,n,a,L}^{0,\text{loc},h}\|_{B_{1,q}^{s'}} + \|v_{0,n,a,L}^{0,\text{loc},3}\|_{B_{1,q}^{s'}} \leq C(\alpha) \quad \text{uniformly in } n, L.
\end{equation}
Estimates (3.26) and (3.27) give easily (2.5) and (2.6).

Finally let us estimate \(v_{0,n,a,L}^{0,\text{loc},h}(\cdot,0)\) and \(u_{0,n,a,L}^{0,\text{loc},3}(\cdot,0)\) in \(B_{2,1}^{0}(\mathbb{R}^{2})\) and prove (2.7). On the one hand by assumption we know that \(u_{0,n} \rightharpoonup u_{0}\) in the sense of distributions. On the other hand we can take weak limits in the decomposition of \(u_{0,n}\) provided by Proposition 3.7. We recall that by (3.10), if \(\varepsilon_{n}^{\ell}/\gamma_{n}^{\ell} \to \infty\) then \(\phi_{n}^{\ell} \equiv r_{n}^{\ell} \equiv 0\). Then we notice that clearly
\begin{align*}
\varepsilon_{n}^{\ell} \to 0 \quad \text{or} \quad \varepsilon_{n}^{\ell} \to \infty \implies \Lambda_{\varepsilon_{n}^{\ell},\gamma_{n}^{\ell},x_{n}^{\ell}} f \to 0
\end{align*}
for any value of the sequences \(\gamma_{n}^{\ell}, x_{n}^{\ell}\) and any function \(f\). Moreover
\begin{align*}
\gamma_{n}^{\ell} \to 0 \implies \Lambda_{1,\gamma_{n}^{\ell},x_{n}^{\ell}} f \to 0
\end{align*}
for any sequence of cores \(x_{n}^{\ell}\) and any function \(f\), so we are left with the study of profiles such that \(\varepsilon_{n}^{\ell} \equiv 1\) and \(\gamma_{n}^{\ell} \to \infty\). Then we also notice that if \(\gamma_{n}^{\ell} \to \infty\), then with Notation (3.18),
\begin{equation}
|a_{n}^{\ell}| = 0 \implies \Lambda_{1,\gamma_{n}^{\ell},x_{n}^{\ell}} f \to 0.
\end{equation}
Consequently for each \(L \geq 1\) and each \(\alpha\) in \([0,1]\[, we have in view of (3.12) and (3.13), as \(n\) goes to infinity
\begin{align*}
v_{0,n}^{3} - \psi_{n}^{L} - \sum_{\ell \in \Gamma^{b}(1)} r_{\alpha}(\cdot, x_{n,h}^{\ell}, \cdot, \frac{-x_{n,3}^{\ell}}{\gamma_{n}^{\ell}}) \to \psi_{0}^{3} + \sum_{\ell \in \Gamma^{b}(1)} \phi_{\alpha}(\cdot, -a_{h}^{\ell}, 0) \\
\nabla_{h}^{L} C_{0,n} - \psi_{n}^{h,L} - \sum_{\ell \in \Gamma^{l}(1)} \phi_{\alpha}(\cdot, x_{n,h}^{\ell}, \cdot, \frac{-x_{n,3}^{\ell}}{\gamma_{n}^{\ell}}) \to \nabla_{h}^{L} \varphi + \sum_{\ell \in \Gamma^{l}(1)} \phi_{\alpha}(\cdot, -a_{h}^{\ell}, 0).
\end{align*}
By hypothesis the sequence \((u_{n}^{3})_{n \in \mathbb{N}}\) converges weakly to \(u_{0}^{3}\) and the sequence \((\nabla_{h}^{L} C_{0,n})_{n \in \mathbb{N}}\) converges weakly to \(\nabla_{h}^{L} \varphi\), so for each \(L \geq 1\) and all \(\alpha\) in \([0,1]\[, we have as \(n\) goes to infinity
\begin{align}
\psi_{n}^{L} - \sum_{\ell \in \Gamma^{l}(1)} r_{\alpha}(\cdot, x_{n,h}^{\ell}, \cdot, \frac{-x_{n,3}^{\ell}}{\gamma_{n}^{\ell}}) \to \sum_{\ell \in \Gamma^{l}(1)} \phi_{\alpha}(\cdot, -a_{h}^{\ell}, 0) \\
\psi_{n}^{h,L} - \sum_{\ell \in \Gamma^{l}(1)} \phi_{\alpha}(\cdot, x_{n,h}^{\ell}, \cdot, \frac{-x_{n,3}^{\ell}}{\gamma_{n}^{\ell}}) \to \sum_{\ell \in \Gamma^{l}(1)} \phi_{\alpha}(\cdot, -a_{h}^{\ell}, 0).
\end{align}
Now let \(\eta > 0\) be given. Then thanks to (3.8) and (3.9), there is \(L_{0} \geq 1\) such that for all \(L \geq L_{0}\) there is \(\alpha_{0} \leq 1\) (depending on \(L\)) such that for all \(L \geq L_{0}\) and \(\alpha \leq \alpha_{0}\), uniformly in \(n \in \mathbb{N}\)
\[\left\| \left(\psi_{n}^{L}, \psi_{n}^{h,L}\right) \right\|_{G_{0}} + \left\| \sum_{\ell \in \Gamma^{l}(1)} \left(\phi_{\alpha}^{h,L}, r_{\alpha}^{\ell}(\cdot, x_{n,h}^{\ell}, \cdot, \frac{-x_{n,3}^{\ell}}{\gamma_{n}^{\ell}})\right) \right\|_{G_{0}} \leq \eta.\]
Using the fact that \( B^0 \) is embedded in \( L^\infty(\mathbb{R};B^0_{2,1}(\mathbb{R}^2)) \), we infer from (3.29) that for \( L \geq L_0 \) and \( \alpha \leq \alpha_0 \)

\[
\sum_{\ell \in \Gamma^L(1)} \phi_\alpha^\ell (\cdot - a_h^\ell, 0) \bigg|_{B^0_{2,1}(\mathbb{R}^2)} \leq \eta \tag{3.30}
\]

and

\[
\sum_{\ell \in \Gamma^L(1)} \phi_\alpha^\ell (\cdot - a_h^\ell, 0) \bigg|_{B^0_{2,1}(\mathbb{R}^2)} \leq \eta . \tag{3.31}
\]

But by (3.19), we have

\[
v^0_{0,n,\alpha,L}(\cdot, 0) = \sum_{\ell \in \Gamma^L(1)} \phi_\alpha^\ell (\cdot - x_{n,h}^\ell - \frac{x_{n,3}^\ell}{\gamma_n^\ell})
\]

and by (3.20) we have also

\[
w^{0,\text{loc,}3}_{0,n,\alpha,L}(\cdot, 0) = \sum_{\ell \in \Gamma^L(1)} \phi_\alpha^\ell (\cdot - x_{n,h}^\ell - \frac{x_{n,3}^\ell}{\gamma_n^\ell}).
\]

It follows that we can write for all \( L \geq L_0 \) and \( \alpha \leq \alpha_0 \),

\[
\limsup_{n \to \infty} \| v^0_{0,n,\alpha,L}(\cdot, 0) \|_{B^0_{2,1}(\mathbb{R}^2)} \leq \left\| \sum_{\ell \in \Gamma^L(1)} \phi_\alpha^\ell (\cdot - a_h^\ell, 0) \right\|_{B^0_{2,1}(\mathbb{R}^2)} \leq \eta
\]

thanks to (3.30). A similar estimate for \( w^{0,\text{loc,}3}_{0,n,\alpha,L}(\cdot, 0) \) using (3.31) gives finally

\[
\lim_{L \to \infty} \lim_{\alpha \to 0} \limsup_{n \to \infty} \left( \| v^0_{0,n,\alpha,L}(\cdot, 0) \|_{B^0_{2,1}(\mathbb{R}^2)} + \| w^{0,\text{loc,}3}_{0,n,\alpha,L}(\cdot, 0) \|_{B^0_{2,1}(\mathbb{R}^2)} \right) = 0 .
\]

The results (2.8) and (2.9) involving the cut-off function \( \theta \) are simply due to the fact that the profiles are compactly supported.

3.2.2. Construction of the profiles for \( \ell \geq 1 \). The construction is very similar to the previous one. We start by considering a fixed integer \( j \in \{1,\ldots,L(L)\} \). Then we define an integer \( \ell^*_j \) so that, up to a sequence extraction,

\[
\gamma^j_n = \min_{\ell \in \Gamma^L(\varepsilon^j_n)} \gamma^\ell_n ,
\]

where as in (3.15)

\[
\Gamma^L(\varepsilon^\ell_n) = \left\{ \ell \in \{1,\ldots,L\} / \varepsilon^\ell_n \equiv \varepsilon^\ell_n \quad \text{and} \quad \varepsilon^\ell_n (\gamma^\ell_n)^{-1} \to 0 , \ n \to \infty \right\}.
\]

Notice that necessarily \( \varepsilon^j_n \neq 1 \). Finally we define

\[
h^j_n = \varepsilon^j_n (\gamma^j_n)^{-1} .
\]
By construction we have that $h_n^j \to 0$ as $n \to \infty$ (recall that $\varepsilon_n^j \equiv \varepsilon_n^L$). Then we define for $j \leq L$ 

\begin{equation}
(3.33) \quad v_{n,\alpha,L}^{j,h}(y) \overset{\text{def}}{=} \sum_{\ell \in \Gamma^L(\varepsilon_n^L)} \tilde{\phi}_h^\ell \left( y_n - \frac{x_n^{\ell,h}}{\varepsilon_n^j} y - \frac{x_n^{\ell,3}}{\gamma_n^L} \right)
\end{equation}

and

\begin{equation}
(3.34) \quad w_{n,\alpha,L}^j(y) \overset{\text{def}}{=} \sum_{\ell \in \Gamma^L(\varepsilon_n^L)} \left( - \frac{x_n^{\ell,h}}{h_n^j \gamma_n^L} \Delta_n^{1} \partial_3 \phi^\ell \right) \left( y_n - \frac{x_n^{\ell,h}}{\varepsilon_n^j} y - \frac{x_n^{\ell,3}}{\gamma_n^L} \right)
\end{equation}

and we choose

\begin{equation}
(3.35) \quad \mathcal{L}(L) < j \leq L \quad \Rightarrow \quad v_{n,\alpha,L}^{j,h} \equiv 0 \quad \text{and} \quad w_{n,\alpha,L}^j \equiv 0.
\end{equation}

We notice that

\begin{equation}
(3.36) \quad \forall s \in \mathbb{R}, \quad \forall s' \geq 1/2, \quad \sum_{j \geq 1} \left( \|v_{n,\alpha,L}^{j,h}\|_{B_{1,q}} + \|w_{n,\alpha,L}^{j,3}\|_{B_{1,q}} \right) \leq C(\alpha).
\end{equation}

We shall detail the argument for the first inequality only, and in the case of $v_{n,\alpha,L}^{j,h}$ as the study of $w_{n,\alpha,L}^{j,3}$ is similar. We write, using the definition of $v_{n,\alpha,L}^{j,h}$ in (3.33),

\begin{equation}
\sum_{j=1}^{L} \|v_{n,\alpha,L}^{j,h}\|_{B_{1,q}} = \sum_{j=1}^{\mathcal{L}(L)} \left\| \sum_{\ell \in \Gamma^L(\varepsilon_n^L)} \tilde{\phi}_h^\ell \left( y_n - \frac{x_n^{\ell,h}}{\varepsilon_n^j} y - \frac{x_n^{\ell,3}}{\gamma_n^L} \right) \right\|_{B_{1,q}},
\end{equation}

so by definition of the partition (3.16) and by scale and translation invariance of $B_{1,q}$ we find thanks to (3.11), that there is a constant $C$ independent of $L$ such that

\begin{equation}
\sum_{j=1}^{L} \|v_{n,\alpha,L}^{j,h}\|_{B_{1,q}} \leq \sum_{\ell=1}^{L} \|\tilde{\phi}_h^\ell\|_{B_{1,q}} \leq C.
\end{equation}

The result is proved.
3.2.3. Construction of the remainder term. With the notation of Proposition 3.7, let us first define the remainder terms

\[
\rho_{n,\alpha,L}^{(1)} \overset{\text{def}}{=} \sum_{\ell=1}^{L} \Lambda_{x_{n}^{\ell},x_{n}^{\ell}} \nabla_h \Delta_h^{-1} \partial_3 \phi_{\alpha}^{\ell} - \nabla_h \Delta_h^{-1} \partial_3 \psi_{n}^{L} \nabla \nabla_h \Delta_h^{-1} \partial_3 \psi_{n}^{L} \nabla
\]

and

\[
\rho_{n,\alpha,L}^{(2)} \overset{\text{def}}{=} \sum_{\ell=1}^{L} \Lambda_{x_{n}^{\ell},x_{n}^{\ell}} \nabla h \Delta_h^{-1} \partial_3 \phi_{\alpha}^{\ell} + \sum_{\ell=1}^{L} \Lambda_{x_{n}^{\ell},x_{n}^{\ell}} (0, r_{\alpha}^{\ell} + \nabla h \Delta_h^{-1} \partial_3 \psi_{n}^{L}).
\]

Observe that by construction, thanks to (3.2) and (3.9) and to the fact that if \( r_{\alpha}^{\ell} \neq 0 \), then \( \varepsilon_{n}^{\ell}/\gamma_{n}^{\ell} \) goes to zero as \( n \) goes to infinity, we have

\[
\lim_{L \to \infty} \lim_{\alpha \to 0} \sup_{n \to \infty} \| \rho_{n,\alpha,L}^{(1)} \|_{B^{rac{1}{2},-1}} = 0,
\]

and

\[
\lim_{L \to \infty} \lim_{\alpha \to 0} \sup_{n \to \infty} \| \rho_{n,\alpha,L}^{(2)} \|_{B^{rac{1}{2},-1}} = 0.
\]

Then we notice that for each \( \ell \in \mathbb{N} \) and each \( \alpha \in [0,1] \), we have by a direct computation

\[
\| \Lambda_{x_{n}^{\ell},x_{n}^{\ell}} (\nabla h \Delta_h^{-1} \partial_3 \phi_{\alpha}^{\ell}, 0) \|_{B^{rac{1}{2},-1}} \sim \left( \frac{\gamma_{n}^{\ell}}{\varepsilon_{n}^{\ell}} \right)^{\frac{1}{2}} \| \nabla h \Delta_h^{-1} \partial_3 \phi_{\alpha}^{\ell} \|_{B^{rac{1}{2},-1}}.
\]

We deduce that if \( \varepsilon_{n}^{\ell}/\gamma_{n}^{\ell} \to \infty \), then \( \Lambda_{x_{n}^{\ell},x_{n}^{\ell}} (\nabla h \Delta_h^{-1} \partial_3 \phi_{\alpha}^{\ell}, 0) \) goes to zero in \( B^{rac{1}{2},-1} \) as \( n \) goes to infinity, hence so does the sum over \( \ell \in \{1, \ldots, L\} \). It follows that for each given \( \alpha \in [0,1[ \) and \( L \geq 1 \) we may define

\[
\rho_{n,\alpha,L} \overset{\text{def}}{=} \rho_{n,\alpha,L}^{(1)} + \sum_{\ell=1}^{L} \Lambda_{x_{n}^{\ell},x_{n}^{\ell}} \nabla h \Delta_h^{-1} \partial_3 \phi_{\alpha}^{\ell}, \quad \alpha \neq 0,
\]

and we have

\[
\lim_{L \to \infty} \lim_{\alpha \to 0} \sup_{n \to \infty} \| \rho_{n,\alpha,L}^{(1)} \|_{B^{rac{1}{2},-1}} = 0.
\]

Finally, as \( D(\mathbb{R}^{3}) \) is dense in \( B_{1,q} \), let us choose a family \( (u_{0,\alpha})_{\alpha} \) of functions in \( D(\mathbb{R}^{3}) \) such that \( \| u_0 - u_{0,\alpha} \|_{B_{1,q}} \leq \alpha \) and let us define

\[
\rho_{n,\alpha,L} \overset{\text{def}}{=} \rho_{n,\alpha,L}^{(1)} + \rho_{n,\alpha,L}^{(2)} + u_0 - u_{0,\alpha}.
\]

Inequalities (3.39) and (3.40) give

\[
\lim_{L \to \infty} \lim_{\alpha \to 0} \sup_{n \to \infty} \| e^{t \Delta} \rho_{n,\alpha,L} \|_{L^{2}(\mathbb{R}^{+};B^{1})} = 0.
\]

3.2.4. End of the proof of Theorem 3. Let us return to the decomposition given in Proposition 3.7, and use definitions (3.37), (3.38) and (3.41) which imply that

\[
u_{0,n} = u_{0,\alpha} + \sum_{\ell=1}^{L} \Lambda_{x_{n}^{\ell},x_{n}^{\ell}} \nabla h \Delta_h^{-1} \partial_3 \phi_{\alpha}^{\ell} + \rho_{n,\alpha,L}.
\]

We recall that for all \( \ell \in \mathbb{N} \), we have \( \lim_{\alpha,\gamma_{n}^{\ell} \to \infty} (\gamma_{n}^{\ell})^{-1} \varepsilon_{n}^{\ell} \in [0, \infty) \) and in the case where the ratio \( \varepsilon_{n}^{\ell}/\gamma_{n}^{\ell} \) goes to infinity then \( \phi_{\alpha}^{\ell} \equiv 0 \). Next we separate the case when the horizontal scale
is one, from the others: with the notation (3.15) we write

\[ u_{0,n} = u_{0,\alpha} + \sum_{\ell \in \Gamma^l(1)} \Lambda_{\epsilon_n, \alpha, x_n}(\phi_{\alpha} - \frac{1}{\gamma_n} \nabla^h \Delta_n^{-1} \partial_3 \phi_{\alpha}, \phi_{\alpha}) \]

\[ + \sum_{\ell = 1}^{L} \sum_{\epsilon_n \neq 1} \sum_{\alpha_n \neq 0} \Lambda_{\epsilon_n, \alpha, x_n}(\tilde{\phi}_{\alpha} - \frac{\epsilon_n}{\gamma_n} \nabla^h \Delta_n^{-1} \partial_3 \phi_{\alpha}, \phi_{\alpha}) + \rho_{n,\alpha,L}. \]

With (3.23) this can be written

\[ u_{0,n} = u_{0,\alpha} + \left[ (v_{0, n,\alpha,L} + h_{0} w_{0, n,\alpha,L}, w_{0, n,\alpha,L}) \right] h_{0} + \left[ (v_{0, n,\alpha,L} + h_{0} w_{0, n,\alpha,L}, w_{0, n,\alpha,L}) \right] h_{0} \]

\[ + \sum_{\ell = 1}^{L} \sum_{\epsilon_n \neq 1} \sum_{\alpha_n \neq 0} \Lambda_{\epsilon_n, \alpha, x_n}(\tilde{\phi}_{\alpha} - \frac{\epsilon_n}{\gamma_n} \nabla^h \Delta_n^{-1} \partial_3 \phi_{\alpha}, \phi_{\alpha}) + \rho_{n,\alpha,L}. \]

Next we use the partition (3.16), so that with notation (3.14) and (3.15),

\[ u_{0,n} = u_{0,\alpha} + \left[ (v_{0, n,\alpha,L} + h_{0} w_{0, n,\alpha,L}, w_{0, n,\alpha,L}) \right] h_{0} + \left[ (v_{0, n,\alpha,L} + h_{0} w_{0, n,\alpha,L}, w_{0, n,\alpha,L}) \right] h_{0} \]

\[ + \sum_{j = 1}^{L} \sum_{\ell \in \Gamma^l(\epsilon_{n,j})} \sum_{\alpha_n \neq 0} \Lambda_{\epsilon_n, \alpha, x_n}(\tilde{\phi}_{\alpha} - \frac{\epsilon_n}{\gamma_n} \nabla^h \Delta_n^{-1} \partial_3 \phi_{\alpha}, \phi_{\alpha}) + \rho_{n,\alpha,L}. \]

Then we finally use the identity (3.35) which gives

\[ u_{0,n} = u_{0,\alpha} + \left[ (v_{0, n,\alpha,L} + h_{0} w_{0, n,\alpha,L}, w_{0, n,\alpha,L}) \right] h_{0} + \left[ (v_{0, n,\alpha,L} + h_{0} w_{0, n,\alpha,L}, w_{0, n,\alpha,L}) \right] h_{0} \]

\[ + \sum_{j = 1}^{L} \sum_{\ell \in \Gamma^l(\epsilon_{n,j})} \sum_{\alpha_n \neq 0} \Lambda_{\epsilon_n, \alpha, x_n}(\tilde{\phi}_{\alpha} - \frac{\epsilon_n}{\gamma_n} \nabla^h \Delta_n^{-1} \partial_3 \phi_{\alpha}, \phi_{\alpha}) + \rho_{n,\alpha,L}. \]

The end of the proof follows from the estimates (3.26), (3.27), (3.32), (3.36), along with (3.42). Theorem 3 is proved. \( \square \)

4. Propagation of profiles: proof of Theorem 4

The goal of this section is the proof of Theorem 4. Let us consider \((v_0, w_0, h_0, \beta_0)\) satisfying the assumptions of that theorem. In order to prove that the initial data defined by

\[ \Phi_0 \overset{\text{def}}{=} \left[ (v_0 - \beta \nabla^h \Delta_n^{-1} \partial_3 w_0, w_0^3) \right] \]

generates a global smooth solution for small enough \(\beta\), let us look for the solution under the form

\[ \Phi = \Phi^{\text{app}} + \psi \quad \text{with} \quad \Phi^{\text{app}} \overset{\text{def}}{=} \left[ (v - \beta w^h, w^3) \right] \]

where \(v\) solves the two-dimensional Navier-Stokes equations

\[ (NS2D)_{x_3} \quad \begin{cases} \partial_t v + v \cdot \nabla v - \Delta v = -\nabla p & \text{in } \mathbb{R}^+ \times \mathbb{R}^2 \\ \text{div}_h v = 0 \\ v|_{t=0} = v_0(\cdot, x_3) \end{cases} \]

while \(w^3\) solves the transport-diffusion equation

\[ (T_\beta) \quad \begin{cases} \partial_t w^3 + v \cdot \nabla w^3 - \Delta w^3 - \beta^2 \partial^2_t w^3 = 0 & \text{in } \mathbb{R}^+ \times \mathbb{R}^3 \\ w^3|_{t=0} = w_0^3 \end{cases} \]
and \( w^h \) is determined by the divergence free condition on \( w \) which gives \( u^h \overset{\text{def}}{=} -\nabla^h \Delta^{-1}_h \partial_3 w^3 \).

In Section 4.1 (resp. 4.2), we prove a priori estimates on \( v \) (resp. \( w \)), and Section 4.3 is devoted to the conclusion of the proof of Theorem 4, studying the perturbed Navier-Stokes equation satisfied by \( \psi \).

Before starting the proof we recall the following definitions of space-time norms, first introduced by J.-Y. Chemin and N. Lerner in [17], and which are very useful in the context of the Navier-Stokes equations:

\[
\|f\|_{L^r_t([0,T];B^{s,s'}_{p,q})} \overset{\text{def}}{=} \|2^{ks+j's'} \|\Delta^k_0 \Delta^j_0 f\|_{L^r([0,T];L^p)} .
\]

Notice that of course \( L^r_t([0,T];B^{s,s'}_{p,q}) = L^r_t([0,T];B^{s,s'}_{p,\infty}) \), and by Minkowski’s inequality, we have the embedding \( L^r_t([0,T];B^{s,s'}_{p,q}) \subset L^r_t([0,T];B^{s,s'}_{p,\infty}) \) if \( r \geq q \).

### 4.1. Two dimensional flows with parameter

Let us prove the following result on \( v \), the solution of \( (\text{NS}2D)_{x_3} \).

**Proposition 4.1.** Let \( v_0 \) be a two-component divergence free vector field depending on the vertical variable \( x_3 \), and belonging to \( S^\mu_{\mu} \). Then the unique, global solution \( v \) to \( (\text{NS}2D)_{x_3} \) belongs to \( \mathcal{A}^0 \) and satisfies the following estimate:

\[
\|v\|_{\mathcal{A}^0} \leq \mathcal{T}_1(\|v_0\|_{\mathcal{A}^0}) .
\]

Moreover, for all \( (s,s') \) in \( D_{\mu} \), we have

\[
\forall r \in [1,\infty], \quad \|v\|_{L^r_t([0,\infty];B^{s+s'}_{p+\frac{s}{2},q})} \leq \mathcal{T}_2(\|v_0\|_{S^\mu}) .
\]

**Proof.** This proposition is a result about the regularity of the solution of \( (\text{NS}2D) \) when the initial data depends on a real parameter \( x_3 \), measured in terms of Besov spaces with respect to the vertical variable \( x_3 \). Its proof is structured as follows. First, we deduce from the classical energy estimate for the two dimensional Navier-Stokes system, a stability result in the spaces \( L^r([0,\infty];H^{s+s'}_{1,2}(\mathbb{R}^2)) \) with \( r \) in \([2,\infty]\) and \( s \) in \([-1,1]\). This is the purpose of Lemma 4.2, the proof of which uses essentially energy estimates together with paraproduct laws.

Then we have to translate the stability result of Lemma 4.2 in terms of Besov spaces with respect to the third variable (seen before simply as a parameter), namely by propagating the vertical regularity. First of all, this requires to deduce from the stability in the spaces \( L^r([0,\infty];H^{s+s'}_{1,2}(\mathbb{R}^2)) \) with \( r \) in \([2,\infty]\), the fact that the vector field \( v \), now seen as a function of three variables, belongs to \( L^r_t([0,\infty];L^\infty_t(H^{s+s'}_{1,2}(\mathbb{R}^2))) \) again for \( r \) in \([2,\infty]\). This is the purpose of Lemma 4.3, the proof of which relies on the equivalence of two definitions of Besov spaces with regularity index in \([0,1]\): the first one involving the dyadic decomposition of the frequency space, and the other one consisting in estimating integrals in physical space. Finally for \( s \) in \([-\frac{1}{3},\frac{1}{3}]\) and \( s' > 0 \) a Gronwall type lemma enables us to propagate the regularities. When \( s' \geq \frac{1}{2} \), product laws enable us to gain horizontal regularity up to \([-2,1]\) and to conclude the proof of Proposition 4.1.

Let us state the first lemma in this proof.

**Lemma 4.2.** For any compact set \( I \) included in \([-1,1]\), a constant \( C \) exists such that, for any \( r \) in \([2,\infty]\) and any \( s \) in \( I \), we have for any two solutions \( v_1 \) and \( v_2 \) of the two-dimensional Navier-Stokes equations

\[
\|v_1 - v_2\|_{L^r_t([0,\infty];H^{s+s'}_{1,2}(\mathbb{R}^2))} \lesssim \|v_1(0) - v_2(0)\|_{H^s(\mathbb{R}^2)} E_{12}(0) ,
\]
where we define
\[ E_{12}(0) \overset{\text{def}}{=} \exp C(\|v_1(0)\|_{L^2}^2 + \|v_2(0)\|_{L^2}^2). \]

**Proof.** In the proof of this lemma, all the functional spaces are over \( \mathbb{R}^2 \) and we no longer mention this fact in notations. Moreover, the constant which appears in the definition of \( E_{12}(0) \) can change along the proof. Defining \( v_{12}(t) \overset{\text{def}}{=} v_1(t) - v_2(t) \), we get
\[ \partial_t v_{12} + v_2 \cdot \nabla^h v_{12} - \Delta_h v_{12} = -v_2 \cdot \nabla^h v_1 - \nabla^h p. \tag{4.6} \]

In order to establish (4.5), we shall resort to an energy estimate making use of product laws and of the following estimate proved in [12, Lemma 1.1]:
\[ (v \cdot \nabla^h a)_{H^s} \lesssim \|\nabla^h v\|_{L^2} \|a\|_{H^s} \|\nabla^h a\|_{H^s}, \tag{4.7} \]
available uniformly for any \( s \) in \([-2 + \mu, 1 - \mu]\).

Let us notice that thanks to the divergence free condition, taking the \( H^s \) scalar product with \( v_{12} \) in Equation (4.6) implies that
\[ \frac{1}{2} \frac{d}{dt} \|v_{12}(t)\|_{H^s}^2 + \|\nabla^h v_{12}(t)\|_{H^s}^2 = -\left( v_2(t) \cdot \nabla^h v_{12}(t) \right)_{H^s} - \left( v_{12}(t) \cdot \nabla^h v_1(t) \right)_{H^s}. \]

Whence, by time integration we get
\[ \|v_{12}(t)\|_{H^s}^2 + 2 \int_0^t \|\nabla^h v_{12}(t')\|_{H^s}^2 dt' = \|v_{12}(0)\|_{H^s}^2 - 2 \int_0^t \left( v_2(t') \cdot \nabla^h v_{12}(t') \right)_{H^s} dt' - 2 \int_0^t \left( v_{12}(t') \cdot \nabla^h v_1(t') \right)_{H^s} dt'. \]

Now using Estimate (4.7), we deduce that there is a positive constant \( C \) such that for any \( s \) in \( I \), we have
\[ \frac{1}{2} \left| \int_0^t \left( v_2(t') \cdot \nabla^h v_{12}(t') \right)_{H^s} dt' \right| \]
\[ \leq C \int_0^t \left\| v_{12}(t') \right\|_{H^s} \left\| \nabla^h v_2(t') \right\|_{L^2} \left\| \nabla^h v_{12}(t') \right\|_{H^s} dt' \]
\[ \leq \frac{1}{2} \int_0^t \left\| \nabla^h v_{12}(t') \right\|_{H^s}^2 dt' + \frac{C^2}{2} \int_0^t \left\| v_{12}(t') \right\|_{H^s}^2 \left\| \nabla^h v_2(t') \right\|_{L^2}^2 dt'. \tag{4.8} \]

Noticing that
\[ \int_0^t \left( v_{12}(t') \cdot \nabla^h v_1(t') \right)_{H^s} dt' \leq \int_0^t \left\| \nabla^h v_{12}(t') \right\|_{H^s} \left\| v_{12}(t') \right\|_{H^{-1}} \left\| \nabla^h v_1(t') \right\|_{H^s} dt', \]
we deduce by Cauchy-Schwarz inequality and product laws in Sobolev spaces on \( \mathbb{R}^2 \) that as long as \( s \) is in \([0, 1] \),
\[ \frac{1}{2} \left| \int_0^t \left( v_{12}(t') \cdot \nabla^h v_1(t') \right)_{H^s} dt' \right| \]
\[ \leq C \int_0^t \left\| \nabla^h v_{12}(t') \right\|_{H^s} \left\| v_{12}(t') \right\|_{H^s} \left\| \nabla^h v_1(t') \right\|_{L^2} dt' \]
\[ \leq \frac{1}{2} \int_0^t \left\| \nabla^h v_{12}(t') \right\|_{H^s}^2 dt' + \frac{C^2}{2} \int_0^t \left\| v_{12}(t') \right\|_{H^s}^2 \left\| \nabla^h v_1(t') \right\|_{L^2}^2 dt'. \tag{4.9} \]
When \( s = 0 \) we simply write, by product laws and interpolation,

\[
2 \left| \int_0^t (v_{12}(t') \cdot \nabla^h v_1(t'))_{L^2} dt' \right|
\]

\[
\leq C \int_0^t \| v_{12}(t') \|_{H^s} \| v_{12}(t') \cdot \nabla^h v_1(t') \|_{H^{-s}} dt'
\]

\[
\leq \frac{1}{2} \int_0^t \| \nabla^h v_{12}(t') \|_{L^2}^2 dt' + \frac{C^2}{2} \int_0^t \| v_{12}(t') \|_{H^s}^2 \| \nabla^h v_1(t') \|_{L^2}^2 dt'.
\]

Finally in the case when \( s \) belongs to \([-1, 0[, \) we have

\[
2 \left| \int_0^t (v_{12}(t') \cdot \nabla^h v_1(t'))_{H^s} dt' \right|
\]

\[
\leq C \int_0^t \| v_{12}(t') \|_{H^s} \| v_{12}(t') \cdot \nabla^h v_1(t') \|_{H^{-s}} dt'
\]

\[
\leq \frac{1}{2} \int_0^t \| \nabla^h v_{12}(t') \|_{H^s}^2 dt' + \frac{C^2}{2} \int_0^t \| v_{12}(t') \|_{H^s}^2 \| \nabla^h v_1(t') \|_{L^2}^2 dt'.
\]

Combining (4.8) and (4.9)-(4.11), we infer that for \( s \) in \([-1, 1[, \)

\[
\| v_{12}(t) \|_{H^s} + \int_0^t \| \nabla^h v_{12}(t') \|_{L^2}^2 dt' \lesssim \| v_{12}(0) \|_{H^s}^2 + \int_0^t \| v_{12}(t') \|_{H^s}^2 \| \nabla^h v_1(t') \|_{L^2}^2 + \| \nabla^h v_2(t') \|_{L^2}^2 dt'.
\]

Gronwall’s lemma implies that there exists a positive constant \( C \) such that

\[
\| v_{12}(t) \|_{H^s}^2 + \int_0^t \| \nabla^h v_{12}(t') \|_{L^2}^2 dt' \lesssim \| v_{12}(0) \|_{H^s}^2 \exp C \int_0^t \| \nabla^h v_1(t') \|_{L^2}^2 + \| \nabla^h v_2(t') \|_{L^2}^2 dt'.
\]

But for any \( i \) in \( \{1, 2\} \), we have by the classical \( L^2 \) energy estimate

\[
\int_0^t \| \nabla^h v_i(t') \|_{L^2}^2 dt' \leq \frac{1}{2} \| v_i(0) \|_{L^2}^2.
\]

Consequently for \( s \) in \([-1, 1[, \)

\[
\| v_{12}(t) \|_{H^s}^2 + \int_0^t \| \nabla^h v_{12}(t') \|_{L^2}^2 dt' \lesssim \| v_{12}(0) \|_{H^s}^2 E_{12}(0),
\]

which leads to the result by interpolation.

\[\square\]

**Continuation of the proof of Proposition 4.1.** Using Lemma 4.2, we are going to establish the following result, which will be of great help to control all norms of \( v \) of the type \( \tilde{L}^r(\mathbb{R}^+; \mathcal{B}^\gamma) \) for \( r \) in \([4, \infty)\) thanks to a Gronwall type argument.

**Lemma 4.3.** For any compact set \( I \) included in \([-1, 1[, \) a constant \( C \) exists such that, for any \( r \) in \([2, \infty] \) and any \( s \) in \( I \), we have for any solution \( v \) to (NS2D)_{x_5},

\[
\| v \|_{L^r(\mathbb{R}^+; L^\infty(H_{h}^{s+\frac{\gamma}{2}}))) \lesssim \| v_0 \|_{B^\gamma E(0)} \quad \text{with} \quad E(0) \overset{\text{def}}{=} \exp(C\| v(0) \|_{\tilde{L}^\infty H_{h}^{s}}}^2).$$

\[\text{Proof.}\] We shall use the characterization of Besov spaces via differences in physical space: as is well-known (see for instance Theorem 2.36 of [2]), for any Banach space \( X \) of distributions one has

\[
\left\| (2^\frac{s}{2}\| \Delta^s u \|_{L^2(X)}) \right\|_{\ell^2(\mathbb{Z})} \sim \int_{\mathbb{R}} \frac{\| u - (\tau_{-\frac{s}{2}} u) \|_{L^2(X)} dz}{|z|^{\frac{s}{2}}}
\]

\[
(4.13)
\]
where the translation operator $\tau_z$ is defined by 
\[(\tau_z f)(t, x_h, x_3) \overset{\text{def}}{=} f(t, x_h, x_3 + z).
\]
The above Lemma 4.2 implies in particular that, for any $r$ in $[2, \infty]$, any $s$ in $I$ and any couple $(x_3, z)$ in $\mathbb{R}^2$, if $v$ solves $(\text{NS2D})_{x_3}$ then 
\[\|v - \tau_z v\|_{Y^r_s} \lesssim \|v_0 - \tau_z v_0\|_{H^s_t} E(0) \quad \text{with} \quad Y^s_r \overset{\text{def}}{=} L^r(\mathbb{R}^+, H^{s+\frac{2}{r}}).
\]
Taking the $L^2$ norm of the above inequality with respect to the $x_3$ variable and then the $L^1$ norm with respect to the measure $|z|^{-\frac{3}{r}}dz$ gives 
\[
\int_{\mathbb{R}} \frac{\|v - \tau_z v\|_{L^2_3(Y^r_s)}}{|z|^{-\frac{3}{r}}} \, dz \lesssim \int_{\mathbb{R}} \frac{\|v_0 - \tau_z v_0\|_{L^2_3(H^s_r)}}{|z|^{-\frac{3}{r}}} \, dz E(0).
\]
Returning to the characterization (4.13) with $X = Y^s_r$, we find that 
\[
\int_{\mathbb{R}} \frac{\|v - \tau_z v\|_{L^2_3(Y^r_s)}}{|z|^{-\frac{3}{r}}} \, dz \sim \sum_{j \in Z} 2^{\frac{j}{2}} \big\|\big(2^{k} \|\Delta^j \Delta^h v(t, \cdot, z)\|_{L^2_3} \big)_{k}\big\|_{L^2_3}.
\]
Similarly we have 
\[
\int_{\mathbb{R}} \frac{\|v_0 - \tau_z v_0\|_{L^2_3(H^s_r)}}{|z|^{-\frac{3}{r}}} \, dz \sim \sum_{j \in Z} 2^{\frac{j}{2}} \big\|\big(2^{k} \|\Delta^j \Delta^h v_0\|_{L^2_3} \big)_{k}\big\|_{L^2_3},
\]
so by the embedding from $\ell^1(Z)$ to $\ell^2(Z)$, we get 
\[
\int_{\mathbb{R}} \frac{\|v_0 - \tau_z v_0\|_{L^2_3(H^s_r)}}{|z|^{-\frac{3}{r}}} \, dz \lesssim \sum_{(j,k) \in Z^2} 2^{\frac{j}{2}} 2^{ks} \|\Delta^j \Delta^h v_0\|_{L^2_3}.
\]
Therefore, we deduce from Estimate (4.14) that 
\[
\sum_{j \in Z} 2^{\frac{j}{2}} \big\|\big(2^{k} \|\Delta^j \Delta^h v(t, \cdot, z)\|_{L^2_3} \big)_{k}\big\|_{L^2_3} \lesssim \|v_0\|_{B^s} E(0).
\]
As $r \geq 2$, Minkowski’s inequality implies that 
\[
\sum_{j \in Z} 2^{\frac{j}{2}} \big\|\big(2^{k} \|\Delta^j \Delta^h v(t, \cdot, z)\|_{L^2_3} \big)_{k}\big\|_{L^2_3} \lesssim \|v_0\|_{B^s} E(0).
\]
Bernstein’s inequality as stated in Lemma 6.1 implies that 
\[
\|\Delta^j \Delta^h v(t, \cdot, \cdot)\|_{L^\infty_3} \lesssim 2^{\frac{j}{2}} \|\Delta^j \Delta^h v(t, \cdot, \cdot)\|_{L^2_3},
\]
thus we infer that 
\[
\big\|\big(2^{k} \|\Delta^h v\|_{L^\infty_3} \big)_{k}\big\|_{L^2_3} \lesssim \|v_0\|_{B^s} E(0).
\]
Permuting the $\ell^2$ norm and the $L^\infty_3$ norm thanks to Minkowski’s inequality again, concludes the proof of the lemma. \qed

**Remark 4.4.** Let us remark that thanks to the Sobolev embedding of $H^{\frac{3}{4}}_t(\mathbb{R}^2)$ into $L^4(\mathbb{R}^2)$, we have, choosing $s = 0$ and $r = 4$ or $r = 2$, 
\[
\|v\|_{L^4(\mathbb{R}^+; L^\infty_3(H^s_r))} + \|v\|_{L^2(\mathbb{R}^+; L^\infty_3(H^s_r))} \lesssim \|v_0\|_{B^0} E(0).
\]
Continuation of the proof of Proposition 4.1. Now our purpose is the proof of the following inequality: for any \( v \) solving (NS2D)\(_\alpha\), for any \( r \) in \([4, \infty]\) and any \( s \) in \([\frac{1}{2}, \frac{3}{2}]\) and any positive \( s'\),

\[
\|v\|_{L^r_t(B^s; B^{s'}_{s'})} \lesssim \|v_0\|_{B^{s'}_{s'}} \exp\left(\int_0^\infty C\left(\|v(t)\|_{L^2_t(L^4_x)}^4 + \|v(t)\|_{L^2_t(H^1_x)}^2\right) dt\right).
\]

The case when \( r \) is in \([2, 4]\) will be dealt with later. We are going to use a Gronwall-type argument. Let us introduce, for any nonnegative \( \lambda \), the following notation: for any function \( F \) we define

\[
F_\lambda(t) \overset{\text{def}}{=} F(t) \exp\left(-\lambda \int_0^t \phi(t')dt'\right) \quad \text{with} \quad \phi(t) \overset{\text{def}}{=} \|v(t)\|_{L^\infty_t(L^4_x)}^4 + \|v(t)\|_{L^\infty_t(H^1_x)}^2.
\]

Notice that thanks to Remark 4.4, we know that Lemma 6.2, that

\[
\int_0^t \phi(t')dt' \lesssim E(0)(\|v_0\|_{B^0}^2 + \|v_0\|_{B^0}).
\]

Then we write, using the Duhamel formula and the action of the heat flow described in Lemma 6.2, that

\[
\|\Delta_j \Delta_k^b v_\lambda(t)\|_{L^2} \leq C e^{-c 2^k t} \|\Delta_j \Delta_k^b v_0\|_{L^2} + C 2^k \int_0^t \exp\left(-c(t-t')2^k - \lambda \int_{t'}^t \phi(t'')dt''\right) \|\Delta_j \Delta_k^b (v \otimes v)_\lambda(t')\|_{L^2} dt'.
\]

Notice that \((v \otimes v)_\lambda = v \otimes v_\lambda\). In order to study the term \(\|\Delta_j \Delta_k^b (v \otimes v)_\lambda(t')\|_{L^2}\), we need an anisotropic version of Bony’s paraproduct decomposition. Let us write that

\[
\begin{align*}
ab &= \sum_{\ell=1}^4 T^\ell(a, b) \quad \text{with} \\
T^1(a, b) &= \sum_{j,k} \sum_{a} S_j^a S_k^b a \Delta_j^b \Delta_k^b, \\
T^2(a, b) &= \sum_{j,k} \sum_{a} S_j^a \Delta_k^b a \Delta_j^b S_k^b, \\
T^3(a, b) &= \sum_{j,k} \sum_{a} \Delta_j^b S_k^b a S_j^{\lambda} \Delta_k^b, \\
T^4(a, b) &= \sum_{j,k} \sum_{a} \Delta_j^b \Delta_k^b a S_j^{\lambda} S_k^b.
\end{align*}
\]

We shall only estimate \(T^1\) and \(T^2\), the other two terms being strictly analogous. By definition of \(T^1\), using the definition of horizontal and vertical truncations together with the fact that the support of the Fourier transform of the product of two functions is included in the sum of the two supports, and Bernstein’s and Hölder’s inequalities, there is some fixed nonzero integer \(N_0\) such that

\[
\begin{align*}
\|\Delta_j^b \Delta_k^b T^1(v(t), v_\lambda(t))\|_{L^2} &\lesssim 2^j \|\Delta_j^b \Delta_k^b T^1(v(t), v_\lambda(t))\|_{L^2_t(L^4_x)} \\
&\lesssim 2^j \sum_{k', j' \geq j-N_0 \atop k' \geq k-N_0} \|S_j^{a} S_k^{b} v(t)\|_{L^\infty_t(L^4_x)} \|\Delta_j^b \Delta_k^b v_\lambda(t)\|_{L^2} \\
&\lesssim 2^j \|v(t)\|_{L^\infty_t(L^4_x)} \sum_{k', j' \geq j-N_0 \atop k' \geq k-N_0} \|\Delta_j^b \Delta_k^b v_\lambda(t)\|_{L^2}.
\end{align*}
\]
By definition of $\tilde{L}^k(\mathbb{R}^+; B^{s+\frac{1}{2}})$ we get

$$\| \Delta_j^y \Delta_k^h T^1 (v(t), v_\lambda(t)) \|_{L^2} \lesssim 2^k \| v_\lambda \|_{\tilde{L}^4(\mathbb{R}^+; B^{s+\frac{1}{2}})} \| v(t) \|_{L^\infty(L^4_k)} \sum_{j' \geq j - N_0 \atop k' \geq k - N_0} 2^{-k'(s+\frac{1}{2})} 2^{-j' s'} \tilde{f}_{j', k'}(t),$$

where $\tilde{f}_{j', k'}(t)$, defined by

$$\tilde{f}_{j', k'}(t) \overset{\text{def}}{=} \| v_\lambda \|_{\tilde{L}^4(\mathbb{R}^+; B^{s+\frac{1}{2}})} 2^{k'(s+\frac{1}{2})} 2^{j' s'} \| \Delta_j^y \Delta_k^h v_\lambda(t) \|_{L^2},$$

is on the sphere of $\ell^1(\mathbb{Z}^2; L^4(\mathbb{R}^+))$. This implies that

$$2^{j' s'} 2^{ks} \| \Delta_j^y \Delta_k^h T^1 (v(t), v_\lambda(t)) \|_{L^2} \lesssim \| v_\lambda \|_{\tilde{L}^4(\mathbb{R}^+; B^{s+\frac{1}{2}})} \| v(t) \|_{L^\infty(L^4_k)} \sum_{j' \geq j - N_0 \atop k' \geq k - N_0} 2^{-(j' - j) s'} 2^{-((k'-k)(s+\frac{1}{2}))} \tilde{f}_{j', k'}(t).$$

Since $s > -\frac{1}{2}$ and $s' > 0$, it follows by Young’s inequality on series, that

$$2^{j' s'} 2^{ks} \| \Delta_j^y \Delta_k^h T^1 (v(t), v_\lambda(t)) \|_{L^2} \lesssim \| v_\lambda \|_{\tilde{L}^4(\mathbb{R}^+; B^{s+\frac{1}{2}})} \| v(t) \|_{L^\infty(L^4_k)} f_{j, k}(t)$$

where $f_{j, k}(t)$ is on the sphere of $\ell^1(\mathbb{Z}^2; L^4(\mathbb{R}^+))$. As $\phi(t)$ is greater than $\| v(t) \|_{L^\infty(L^4_k)}^4$, we infer that

$$T_{j, k, v_\lambda}(t) \overset{\text{def}}{=} 2^{k' j' s'} 2^{ks} \int_0^t \exp(-c(t-t')2^{2k} - \lambda \int_{t'}^t \phi(t'')dt'') \times \| \Delta_j^y \Delta_k^h T^1 (v(t'), v_\lambda(t')) \|_{L^2}dt' \lesssim \| v_\lambda \|_{\tilde{L}^4(\mathbb{R}^+; B^{s+\frac{1}{2}})} \| v(t) \|_{L^\infty(L^4_k)} f_{j, k}(t')$$

Using Hölder’s inequality, we deduce that

$$T_{j, k, v_\lambda}(t) \lesssim \| v_\lambda \|_{\tilde{L}^4(\mathbb{R}^+; B^{s+\frac{1}{2}})} \left( \int_0^t e^{-c(t-t')2^{2k}} f_{j, k}(t')dt' \right)^{\frac{1}{2}} \times 2^{k} \left( \int_0^t \exp(-c(t-t')2^{2k} - \lambda \int_{t'}^t \phi(t''')dt''') \phi(t')^4 dt' \right)^{\frac{1}{4}}.$$}

Then Hölder’s inequality in the last term of the above inequality ensures that

$$T_{j, k, v_\lambda}(t) \lesssim \frac{1}{\lambda^{\frac{1}{4}}} \left( \int_0^t e^{-c(t-t')2^{2k}} f_{j, k}(t')dt' \right)^{\frac{1}{2}} \| v_\lambda \|_{\tilde{L}^4(\mathbb{R}^+; B^{s+\frac{1}{2}})} \| v(t) \|_{L^\infty(L^4_k)}.$$}

Now let us study the term with $T^2$. Using again that the support of the Fourier transform of the product of two functions is included in the sum of the two supports, let us write that

$$\| \Delta_j^y \Delta_k^h T^2 (v(t), v_\lambda(t)) \|_{L^2} \lesssim \sum_{j' \geq j - N_0 \atop k' \geq k - N_0} \| S_j^y \Delta_k^h v(t) \|_{L^\infty(L^4_k)} \| \Delta_j^y S_{k+1}^h v_\lambda(t) \|_{L^2(L^4_k)}.$$}

Combining Lemma 6.1 with the definition of the function $\phi$, we get

$$\| S_j^y \Delta_k^h v(t) \|_{L^\infty(L^4_k)} \lesssim 2^{-k'} \| v(t) \|_{L^\infty(H^4_k)} \lesssim 2^{-k'} \phi_\frac{1}{4}(t).$$
Now let us observe that using again the Bernstein inequality, we have

\[ \| \Delta_j^\gamma S_{k',1}^h v_\lambda(t) \|_{L^2_t(L^\infty_x)} \lesssim \sum_{k'' \leq k'} \| \Delta_j^\gamma \Delta_j^h v_\lambda(t) \|_{L^2_t(L^\infty_x)} \]

\[ \lesssim \sum_{k'' \leq k'} 2^{k''} \| \Delta_j^\gamma \Delta_j^h v_\lambda(t) \|_{L^2} . \]

By definition of the \( \tilde{L}^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'}) \) norm, we have

\[ 2^{j'} 2^{k'(s-\frac{1}{2})} \| \Delta_j^\gamma S_{k',1}^h v_\lambda(t) \|_{L^2_t(L^\infty_x)} \lesssim \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} \sum_{k'' \leq k'} 2^{(k'-k'')(s-\frac{1}{2})} \tilde{f}_{j',k'}(t) \]

where \( \tilde{f}_{j',k'}(t) \), on the sphere of \( \ell^1(\mathbb{Z}^2; L^4(\mathbb{R}^+)) \), is defined by

\[ \tilde{f}_{j',k'}(t) \overset{\text{def}}{=} \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} 2^{j'} 2^{k'(s-\frac{1}{2})} \| \Delta_j^\gamma \Delta_j^h v_\lambda(t) \|_{L^2} . \]

Since \( s < \frac{1}{2} \), this ensures by Young’s inequality that

\[ \| \Delta_j^\gamma S_{k',1}^h v_\lambda(t) \|_{L^2_t(L^\infty_x)} \lesssim 2^{-j'} 2^{-k'(s-\frac{1}{2})} \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} \tilde{f}_{j',k'}(t) \]

where \( \tilde{f}_{j',k'}(t) \) is on the sphere of \( \ell^1(\mathbb{Z}^2; L^4(\mathbb{R}^+)) \). Together with Inequality (4.21), this gives

\[ 2^{j'} 2^{k'(s+\frac{1}{2})} \| \Delta_j^\gamma \Delta_j^h T^2(v(t), v_\lambda(t)) \|_{L^2} \lesssim \phi(t)^{\frac{1}{2}} \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} \tilde{f}_{j,k}(t) , \]

where \( f_{j,k}(t) \) is on the sphere of \( \ell^1(\mathbb{Z}^2; L^4(\mathbb{R}^+)) \). We deduce that

\[ T_{j,k,\lambda}^2(t) \overset{\text{def}}{=} 2^k 2^{j} 2^k s \int_0^t \exp(-c(t-t') 2^{2k} - \lambda \int_{t'}^t \phi(t'') dt'') \times \| \Delta_j^\gamma \Delta_j^h T^2(v(t), v_\lambda(t)) \|_{L^2} dt' \]

\[ \lesssim \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} \times 2^{\frac{1}{4}} \int_0^t \exp(-c(t-t') 2^{2k} - \lambda \int_{t'}^t \phi(t'') dt'') \phi(t')^{\frac{1}{2}} f_{j,k}(t') dt' . \]

Using Hölder’s inequality twice, we get

\[ T_{j,k,\lambda}^2(t) \lesssim \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} \left( \int_0^t e^{-c(t-t') 2^{2k}} f_{j,k}(t') dt' \right)^{\frac{1}{2}} \]

\[ \times 2^{\frac{1}{4}} \left( \int_0^t \exp(-c(t-t') 2^{2k} - \lambda \int_{t'}^t \phi(t'') dt'') \phi(t')^{\frac{1}{2}} dt' \right)^{\frac{1}{2}} \]

\[ \lesssim \frac{1}{\lambda^2} \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} \left( \int_0^t e^{-c(t-t') 2^{2k}} f_{j,k}(t') dt' \right)^{\frac{1}{2}} . \]

As \( T^3 \) is estimated like \( T^1 \) and \( T^4 \) is estimated like \( T^2 \), this implies finally that

\[ 2^{j'} 2^{k'} 2^{k} \| \Delta_j^\gamma \Delta_j^h v_\lambda(t) \|_{L^2} \lesssim 2^{j'} 2^{k'} 2^{k} e^{-c 2^{2k}} \| \Delta_j^\gamma \Delta_j^h v_0 \|_{L^2} \]

\[ + \left( \int_0^t e^{-c(t-t') 2^{2k}} f_{j,k}(t') dt' \right)^{\frac{1}{2}} \left( \frac{1}{\lambda^2} + \frac{1}{\lambda^2} \right) \| v_\lambda \|_{L^4(\mathbb{R}^+; \mathcal{B}^{s+\frac{1}{2},s'})} . \]
As we have
\[
\left( \int_0^\infty \left( \int_0^t e^{-c(t-t')2^{2k}f_{j,k}'(t')dt'} \right)^{\frac{1}{2}} dt \right) \leq c^{-1}d_{j,k}2^{-\frac{k}{2}}
\]
and \( \sup_{t \in \mathbb{R}^+} \left( \int_0^t e^{-c(t-t')2^{2k}f_{j,k}'(t')dt'} \right)^{\frac{1}{2}} = d_{j,k}, \) with \( d_{j,k} \in l^1(\mathbb{Z}^2), \)
we infer that
\[
2^{j}2^{ks} \left( \| \Delta_j^h \|_{L^\infty(\mathbb{R}^+;L^2)} + 2^{\frac{k}{2}} \| \Delta_j^h \|_{L^1(\mathbb{R}^+;L^2)} \right)
\leq 2^{j}2^{ks} \left( \| \Delta_j^h \|_{L^\infty} + d_{j,k} \left( \frac{1}{\lambda^2} + \frac{1}{\lambda^2} \right) \right) \| v \|_{L^1(\mathbb{R}^+;B^{+\frac{3}{2}})}.
\]

Taking the sum over \( j \) and \( k \) and choosing \( \lambda \) large enough, we have proved (4.15).

Let us gain \( L^2 \)-integrability in \( t \). Using (4.19) and (4.22) with \( \lambda = 0 \), we find that
\[
2^{j}2^{ks} \| \Delta_j^h \|_{L^2} \leq 2^{j}2^{ks} \| \Delta_j^h \|_{L^2} \leq 2^{j}2^{ks} \| \Delta_j^h \|_{L^2} + \| h_{j,k} \|_{L^2(\mathbb{R}^+)} \| v \|_{L^2(\mathbb{R}^+;L^2)}
\]
and (4.15) imply that
\[
\| v \|_{L^2(\mathbb{R}^+;B^{+\frac{3}{2}})} \leq \| v \|_{B^{+\frac{3}{2}}} \exp \left( C \int_0^\infty \phi(t)dt \right).
\]

This implies by interpolation in view of (4.15) that for all \( r \in [2, \infty] \), all \( s \in [ -\frac{1}{2}, \frac{1}{2}] \), and all positive \( s' \)
\[
\| v \|_{L^r(\mathbb{R}^+;B^{+\frac{3}{2}})} \leq \| v \|_{B^{+\frac{3}{2}}} \exp \left( C \int_0^\infty \phi(t)dt \right),
\]
which in view of (4.16) ensures Inequality (4.3) and achieves the proof of Estimate (4.4) in the case when \( s \) belongs to \( [ -\frac{1}{2}, \frac{1}{2}] \).

Now we are going to double the interval, namely prove that for any \( s \in [-1,1] \), any \( s' \geq 1/2 \) and any \( r \in [2, \infty] \) we have
\[
\| v \|_{L^r(\mathbb{R}^+;B^{+\frac{3}{2}})} \leq \| v \|_{B^{+\frac{3}{2}}} \exp \left( C \| v \|_{B^{0}E(0)} \right).
\]

Proposition 6.4 implies that for any \( s \in [-1,1] \) and any \( s' \geq 1/2 \), we have
\[
\| v(t) \otimes v(t) \|_{B^{s'}} \leq \| v(t) \|_{B^{s'+1}} \| v(t) \|_{B^{s'+1}}.
\]

The smoothing effect of the horizontal heat flow described in Lemma 6.2 implies therefore that, for any \( s \) belonging to \( [-1,1] \), any \( s' \geq 1/2 \) and any \( r \in [2, \infty] \),
\[
\| v \|_{L^r(\mathbb{R}^+;B^{+\frac{3}{2}})} \leq \| v \|_{B^{s'+1}} + \| v \|_{L^2(\mathbb{R}^+;B^{+\frac{3}{2}})}
\leq \| v \|_{B^{s'+1}} + \| v \|_{L^2(\mathbb{R}^+;B^{+\frac{3}{2}})} \| v \|_{L^2(\mathbb{R}^+;B^{+\frac{3}{2}})}
\]
Finally Inequality (4.15) ensures that for any \( s \in [-1,1] \), any \( s' \geq 1/2 \) and any \( r \in [2, \infty] \),
\[
\| v \|_{L^r(\mathbb{R}^+;B^{+\frac{3}{2}})} \leq \| v \|_{B^{s'}} + \| v \|_{B^{+\frac{3}{2}}} \| v \|_{B^{+\frac{3}{2}}} \exp \left( C \| v \|_{B^{0}E(0)} \right).
\]

This concludes the proof of Inequality (4.25).
Now let us conclude the proof of Estimate (4.4). Again Proposition 6.4 implies that, for any \( s \) in \( ]-2,0] \) and any \( s' \geq 1/2 \), we have
\[
\|v(t) \otimes v(t)\|_{\dot{B}^{s+1,s'}} \lesssim \|v(t)\|_{\dot{B}^{s+1}} \|v(t)\|_{\dot{B}^{s+1,s'}}.
\]

This gives rise to
\[
\|v \otimes v\|_{L^1([\mathbb{R}^+; \dot{B}^{s+1,s'})} \lesssim \|v\|_{L^2([\mathbb{R}^+; \dot{B}^{s+1})} \|v\|_{L^2([\mathbb{R}^+; \dot{B}^{s+1,s'})}.
\]
The smoothing effect of the heat flow gives, for any \( r \) in \([1, \infty)\) and any \( s \in ]-2,0] \),
\[
\|v\|_{L^r([\mathbb{R}^+; \dot{B}^{s+1,s'})} \lesssim \|v_0\|_{\dot{B}^{s'}} + \|v\|_{L^2([\mathbb{R}^+; \dot{B}^{s+1})} \|v\|_{L^2([\mathbb{R}^+; \dot{B}^{s+1,s'})}.
\]
Inequality (4.26) implies that, for any \( r \) in \([1, \infty)\) and any \( s \) in \( ]-2,0] \) and \( s' \geq 1/2 \),
\[
(4.27) \quad \|v\|_{L^r([\mathbb{R}^+; \dot{B}^{s+1,s'})} \lesssim \|v_0\|_{\dot{B}^{s'}} + \|v_0\|_{\dot{B}^{s+1}} \|v_0\|_{\dot{B}^{s+1,s'}} \exp(C\|v_0\|_{\dot{B}^{s'}} E_0).
\]
This proves the estimate (4.4) and thus Proposition 4.1. \( \square \)

4.2. Propagation of regularity by a 2D flow with parameter. Now let us estimate the norm of the function \( w^3 \) defined as the solution of \((T_\beta)\) defined page 24. This is described in the following proposition.

**Proposition 4.5.** Let \( v_0 \) and \( v \) be as in Proposition 4.1. For any non negative real number \( \beta \), let us consider \( w^3 \) the solution of
\[
(T_\beta) \quad \partial_t w^3 + v \cdot \nabla h w^3 - \Delta_h w^3 - \beta^2 \partial^2_\beta w^3 = 0 \quad \text{and} \quad w^3_{|t=0} = w_0^3.
\]
Then \( w^3 \) satisfies the following estimates where all the constants are independent of \( \beta \):
\[
(4.28) \quad \|w^3\|_{A^\gamma} \lesssim \|w_0^3\|_{\dot{B}^0} \exp(T_1(\|v_0\|_{\dot{B}^0})),
\]
and for any \( s \) in \([-2+\mu, 0] \) and any \( s' \geq 1/2 \), we have
\[
(4.29) \quad \|w^3\|_{A^{s\cdot s'}} \lesssim (\|w_0^3\|_{\dot{B}^{s'}} + \|w_0^3\|_{\dot{B}^0} T_2(\|v_0\|_{\dot{B}^0})) \exp(T_1(\|v_0\|_{\dot{B}^0})).
\]

**Proof.** This is a question of propagating anisotropic regularity by a transport-diffusion equation. This propagation is described by the following lemma, which will easily lead to Proposition 4.5.

**Lemma 4.6.** Let us consider \((s,s')\) a couple of real numbers, and \( Q \) a bilinear operator which maps continuously \( B^s \times B^{s+1,s'} \) into \( B^{s,s'} \). A constant \( C \) exists such that for any two-component vector field \( v \) in \( L^2([\mathbb{R}^+; B^s]) \), any \( f \) in \( L^1([\mathbb{R}^+; B^{s,s'}]) \), any \( a_0 \) in \( B^{s,s'} \) and for any non negative \( \beta \), if \( \Delta_\beta^a = \Delta_h + \beta^2 \partial^2_\beta \) and \( a \) is the solution of
\[
\partial_t a - \Delta_\beta a + Q(v,a) = f \quad \text{and} \quad a_{|t=0} = a_0,
\]
then \( a \) satisfies
\[
\forall r \in [1, \infty], \quad \|a\|_{L^r([\mathbb{R}^+; B^{s\cdot s'}])} \leq C(\|a_0\|_{B^{s'}} + \|f\|_{L^1([\mathbb{R}^+; B^{s,s'}])}) \exp(C \int_0^\infty \|v(t)\|_{B^1}^2 dt) .
\]

**Proof.** This is a Gronwall type estimate. However the fact that the third index of the Besov spaces is one, induces some technical difficulties which lead us to work first on subintervals \( I \) of \( \mathbb{R}^+ \) on which \( \|v\|_{L^2(I; B^1)} \) is small.

Let us first consider any subinterval \( I = [\tau_0, \tau_1] \) of \( \mathbb{R}^+ \). The Duhamel formula and the smoothing effect of the heat flow described in Lemma 6.2 imply that
\[
\|\Delta_\beta^a \Delta_j a(t)\|_{L^2} \leq e^{-c2^2(\tau-\tau_0)} \|\Delta_\beta^a \Delta_j a(\tau_0)\|_{L^2} + C \int_{\tau_0}^t e^{-c2^2(t-\tau')} \|\Delta_\beta^a \Delta_j (Q(v(t'),a(t')) + f(t'))\|_{L^2} dt'.
\]

Thus the number $T$ and $c$ for some given $t$ and the fact that $f(t)$ is finite is less than $2^k$.

Let us define the increasing sequence $(T_m)_{0 \leq m \leq M+1}$ by induction such that $T_0 = 0$, $T_{M+1} = \infty$ and

$$\forall m < M, \quad \int_{T_m}^{T_{m+1}} \|v(t)\|_{B^s}^2 dt = c_0 \quad \text{and} \quad \int_{T_m}^{T_{M+1}} \|v(t)\|_{B^s}^2 dt \leq c_0,$$

for some given $c_0$ which will be chosen later on. Obviously, we have

$$\int_0^\infty \|v(t)\|_{B^s}^2 dt \geq \int_0^{T_m} \|v(t)\|_{B^s}^2 dt = Mc_0.$$

Thus the number $M$ of $T_m$'s such that $T_m$ is finite is less than $c_0^{-1} \|v\|_{L^2(\mathbb{R}^+; B^s)}$. Applying Estimate (4.30) to the interval $[T_m, T_{m+1}]$, we get

$$\|a\|_{L^\infty([T_m, T_{m+1}; B^{s+1}, s')} \leq \|a\|_{L^2([T_m, T_{m+1}; B^{s+1}, s'])} \leq \|a\|_{L^2([T_m, T_{m+1}; B^{s+1}, s'])} + C\|a(T_m)\|_{B^{s+1}, s'} + \|f\|_{L^1([T_m, T_{m+1}; B^{s+1}, s'])}$$

if $c_0$ is chosen such that $C\sqrt{c_0} \leq 1$. As

$$\|a\|_{L^2([T_m, T_{m+1}; B^{s+1}, s'])} \leq \|a\|_{L^2([T_m, T_{m+1}; B^{s+1}, s'])},$$

we infer that

$$\|a\|_{L^\infty([T_m, T_{m+1}; B^{s+1}, s'])} \leq 2C\|a(T_m)\|_{B^{s+1}, s'} + \|f\|_{L^1([T_m, T_{m+1}; B^{s+1}, s'])}.$$

Now let us prove by induction that

$$\|a\|_{L^\infty([0, T_m]; B^{s+1}, s')} \leq (2C)^m (\|a_0\|_{B^{s+1}, s'} + \|f\|_{L^1([0, T_m]; B^{s+1}, s')}).$$

Using (4.32) and the induction hypothesis we get

$$\|a\|_{L^\infty([T_m, T_{m+1}; B^{s+1}, s'])} \leq 2C\|a\|_{L^\infty([0, T_m]; B^{s+1}, s')} + \|f\|_{L^1([T_m, T_{m+1}; B^{s+1}, s'])} \leq \|a_0\|_{B^{s+1}, s'} + \|f\|_{L^1([T_m, T_{m+1}; B^{s+1}, s'])},$$

provided that $2C \geq 1$. This proves in view of (4.31) that

$$\|a\|_{L^\infty(\mathbb{R}^+; B^{s+1}, s')} \leq C(\|a_0\|_{B^{s+1}, s'} + \|f\|_{L^1(\mathbb{R}^+; B^{s+1}, s')}) \exp(C \int_0^\infty \|v(t)\|_{B^s}^2 dt).$$

We deduce from (4.32) that

$$\|a\|_{L^1([T_m, T_{m+1}; B^{s+2}, s'])} \leq C(\|a_0\|_{B^{s+2}, s'} + \|f\|_{L^1(\mathbb{R}^+; B^{s+2}, s')}) \exp(C \int_0^\infty \|v(t)\|_{B^s}^2 dt) + C\|f\|_{L^1([T_m, T_{m+1}; B^{s+2}, s'])}.$$
Conclusion of the proof of Proposition 4.5. We apply Lemma 4.6 with \( Q(v, a) = \text{div}_h(av) \), 
\( f = 0 \), \( a = w^3 \), and \( (s, s') = (0, 1/2) \). Indeed since \( B^1 \) is an algebra we have
\[
\|Q(v, a)\|_{B^0} \lesssim \|av\|_{B^1} \lesssim \|a\|_{B^1} \|v\|_{B^1}.
\]
So Lemma 4.6 gives
\[
\|w^3\|_{A^0} \lesssim \|w_0^3\|_{B^0} \exp\left( C \int_0^\infty \|v(t)\|_{B^3}^3 \, dt \right).
\]
Thanks to Estimate (4.3) of Proposition 4.1 we deduce (4.28).
Now for \( s \) belonging to \([-2 + \mu, 0]\), we apply Lemma 4.6 with \( a = w^3 \), \( Q(v, a) = \text{div}_h(T^v_a) \), and \( f = \text{div}_h(T^v_a) \), where with the notations of Definition 1.4
\[
T^v_a \overset{\text{def}}{=} \sum_j S^v_j v \Delta^v_j a, \quad R^v(a, v) \overset{\text{def}}{=} \sum_{-1 \leq j \leq 1} \Delta^v_{j-1} a \Delta^v_{j} v \quad \text{and} \quad \tilde{T}^v_a \overset{\text{def}}{=} T^v_a + R^v(a, v).
\]
Lemma 6.5 implies that for any \( s \) in \([-2 + \mu, 0]\) and any \( s' \geq 1/2 \),
\[
\|T^v_a w^3\|_{B^{s+1}, s'} \lesssim \|v\|_{B^s} \|w^3\|_{B^{s+1}, s'}.
\]
We infer from Lemma 4.6 that, for any \( r \) in \([1, \infty)\),
\[
\|w^3\|_{L^r(R^+, B^{s+1}, s')} \lesssim (\|w_0^3\|_{B^{s+1}, s'} + \|\text{div}_h(T^v_a)\|_{L^1(R^+, B^{s+1}, s')}) \exp\left( T_1(\|v_0\|_{B^0}) \right).
\]
But we have, using laws of anisotropic paraproduct given in Lemma 6.5,
\[
\|\text{div}_h(T^v_a)\|_{L^1(R^+, B^{s+1}, s')} \overset{\text{def}}{=} \|\tilde{T}^v_a\|_{L^1(R^+, B^{s+1}, s')} \lesssim \|w^3\|_{L^2(R^+, B^1)} \|v\|_{L^2(R^+, B^{s+1}, s')}.
\]
Applying (4.28) and (4.4) gives (4.29). Proposition 4.5 is proved.

As \( w^h \) is defined by \( w^h = -\nabla_h \Delta_h^{-1} \partial_3 w^3 \), we deduce from Proposition 4.5, Lemma 6.1 and the scaling property (2.1), the following corollary.

**Corollary 4.7.** For any \( s \) in \([-2 + \mu, 0]\) and any \( s' \geq 1/2 \),
\[
\|w^h\|_{A^{s+1}, s'} \lesssim (\|w_0^3\|_{B^{s+1}, s'} + \|w_0^3\|_{B^0} T_2(\|v_0\|_{B^0})) \exp\left( T_1(\|v_0\|_{B^0}) \right).
\]

**4.3. Conclusion of the proof of Theorem 4.** Using the definition of the approximate solution \( \Phi^{\text{app}} \) given in (4.1), we infer from Propositions 4.1 and 4.5 and Corollary 4.7 that
\[
\|\Phi^{\text{app}}\|_{L^2(R^+, B^4)} \leq T_1(\|v_0\|_{B^0}) + \beta T_2(\|v_0\|_{B^0}^3) + \beta T_2(\|v_0\|_{B^0}^3)\|s_\mu\|.
\]
Moreover, the error term \( \psi \) satisfies the following modified Navier-Stokes equation, with zero initial data:
\[
\partial_t \psi + \text{div} (\psi \otimes \psi + \Phi^{\text{app}} \otimes \psi + \psi \otimes \Phi^{\text{app}}) - \Delta \psi = -\nabla q_\beta + \sum_{\ell=1}^4 E_\beta^\ell \quad \text{with}
\]
\[
E_\beta^1 \overset{\text{def}}{=} \partial_\beta^3 (\|v, 0\|_B) + \beta (0, [\partial_3 p]_B),
\]
\[
E_\beta^2 \overset{\text{def}}{=} \beta \left[ w^3 \partial_3 (v, w^3) + (\nabla h \Delta_h^{-1} \partial_3 (v w^3), 0) \right]_B,
\]
\[
E_\beta^3 \overset{\text{def}}{=} \beta \left[ (w^h, \nabla_h (v, w^3) + v \cdot \nabla_h (w^h, 0)) \right]_B \quad \text{and}
\]
\[
E_\beta^4 \overset{\text{def}}{=} \beta^2 \left[ (w^h, \nabla_h (w^h, 0) + w^3 \partial_3 (w^h, 0)) \right]_B.
\]
If we prove that

\begin{equation}
\left\| \sum_{\ell=1}^{4} E_{\beta}^{\ell} \right\|_{F_{0}} \leq \beta T_{2} \left( \| (v_{0}, w_{0}^{3}) \|_{S_{\mu}} \right),
\end{equation}

then according to the fact $\psi_{|t=0} = 0$, Proposition 2.5 implies that $\psi$ exists globally and satisfies

\begin{equation}
\left\| \psi \right\|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{1})} \lesssim \beta T_{2} \left( \| (v_{0}, w_{0}^{3}) \|_{S_{\mu}} \right).
\end{equation}

This in turn implies that $\Phi_{0}$ generates a global regular solution $\Phi_{\beta}$ in $L^{2}(\mathbb{R}^{+}; \mathcal{B}^{1})$ which satisfies

\begin{equation}
\| \Phi_{\beta} \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{1})} \leq T_{1} \left( \| (v_{0}, w_{0}^{3}) \|_{\mathcal{B}^{0}} \right) + \beta T_{2} \left( \| (v_{0}, w_{0}^{3}) \|_{S_{\mu}} \right).
\end{equation}

Once this bound in $L^{2}(\mathbb{R}^{+}; \mathcal{B}^{1})$ is obtained, the bound in $\mathcal{A}^{0}$ follows by heat flow estimates, and in $\mathcal{A}^{s,s'}$ by propagation of regularity for the Navier-Stokes equations as stated in Proposition 4.8 below.

So all we need to do is to prove Inequality (4.37). Let us first estimate the term $\partial_{3}^{2} [(v, 0)]_{\beta}$. This requires the use of some $L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0, s'})$ norms. We get

\begin{equation}
\| \partial_{3}^{2} [v]_{\beta} \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0, s'})} \lesssim \| [v]_{\beta} \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0, \frac{s'}{2}})}.
\end{equation}

Using the vertical scaling property (2.1) of the space $\mathcal{B}^{0, \frac{s'}{2}}$, this gives

\begin{equation}
\| \partial_{3}^{2} [v]_{\beta} \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0, s'})} \lesssim \beta \| v \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0, \frac{s'}{2}})}.
\end{equation}

Using Proposition 4.1, we get

\begin{equation}
\| \partial_{3}^{2} [v]_{\beta} \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0, s'})} \leq \beta T_{2} \left( \| v_{0} \|_{S_{\mu}} \right).
\end{equation}

Now let us study the pressure term. By applying the horizontal divergence to the equation satisfied by $v$ we get, thanks to the fact that $\text{div}_{h} v = 0$,

\begin{equation*}
\partial_{3} p = -\partial_{3} \Delta_{h}^{-1} \sum_{\ell, m=1}^{2} \partial_{\ell} \partial_{m} (v^{\ell} v^{m}).
\end{equation*}

Using the fact that $\Delta_{h}^{-1} \partial_{3} \partial_{m}$ is a zero-order horizontal Fourier multiplier (since $\ell$ and $m$ belong to $\{1, 2\}$), we infer that

\begin{equation*}
\| [\partial_{3} p]_{\beta} \|_{L^{1}(\mathbb{R}^{+}; \mathcal{B}^{0})} = \| \partial_{3} p \|_{L^{1}(\mathbb{R}^{+}; \mathcal{B}^{0})} \lesssim \| v \partial_{3} v \|_{L^{1}(\mathbb{R}^{+}; \mathcal{B}^{0})}.
\end{equation*}

Laws of product in anisotropic Besov as described by Proposition 6.4 imply that

\begin{equation*}
\| v(t) \partial_{3} v(t) \|_{\mathcal{B}^{0}} \lesssim \| v(t) \|_{\mathcal{B}^{1}} \| \partial_{3} v(t) \|_{\mathcal{B}^{0}},
\end{equation*}

which gives rise to

\begin{equation}
\| [\partial_{3} p]_{\beta} \|_{L^{1}(\mathbb{R}^{+}; \mathcal{B}^{0})} \lesssim \| v \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{1})} \| \partial_{3} v \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0})} \lesssim \| v \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{1})} \| v \|_{L^{2}(\mathbb{R}^{+}; \mathcal{B}^{0, \frac{3}{2}})}.
\end{equation}

Combining (4.40) and (4.41), we get by virtue of Proposition 4.1 and Lemma 6.3

\begin{equation}
\| E_{\beta}^{4} \|_{F_{0}} \leq \beta T_{2} \left( \| v_{0} \|_{S_{\mu}} \right).
\end{equation}
Now we estimate $E^2_\beta$. Applying again the laws of product in anisotropic Besov spaces (see Proposition 6.4) together with the action of vertical derivatives, we obtain

\[
\|w^3(t)\partial_3(v,w^3)(t)\|_{B^0} \lesssim \|w^3(t)\|_{B^1}\|\partial_3(v,w^3)(t)\|_{B^0} \\
\lesssim \|w^3(t)\|_{B^1}\|(v,w^3)(t)\|_{B^{0,\frac{1}{2}}}.
\]

Thus we infer that

\begin{equation}
\|w^3\partial_3(v,w^3)\|_{L^1(\mathbb{R}^+;B^0)} \lesssim \|w^3\|_{L^2(\mathbb{R}^+;B^1)}\|(v,w^3)\|_{L^2(\mathbb{R}^+;B^{0,\frac{1}{2}})}.
\end{equation}

For the other term of $E^2_\beta$, using the fact that $\nabla^h\Delta_h^{-1}\text{div}_h$ is an order 0 horizontal Fourier multiplier and the Leibniz formula, we infer from Lemma 6.1 that

\[
\|\nabla^h\Delta_h^{-1}\text{div}_h\partial_3(vw^3)(t)\|_{B^0} \lesssim \|\partial_3(vw^3)(t)\|_{B^0} \\
\lesssim \|v(t)\|_{B^1}\|w^3(t)\|_{B^0} + \|w^3(t)\|_{B^1}\|v(t)\|_{B^{0,\frac{1}{2}}}.
\]

In view of laws of product in anisotropic Besov spaces and the action of vertical derivatives, this gives rise to

\[
\|\nabla^h\Delta_h^{-1}\text{div}_h\partial_3(vw^3)(t)\|_{B^0} \lesssim \|v(t)\|_{B^1}\|w^3(t)\|_{B^0,\frac{1}{2}} + \|w^3(t)\|_{B^1}\|v(t)\|_{B^{0,\frac{1}{2}}}.
\]

Together with (4.43), this leads to

\[
\|E^2_\beta\|_{L^1(\mathbb{R}^+;B^0)} \lesssim \beta \|w^3\|_{L^2(\mathbb{R}^+;B^1)}\|(v,w^3)\|_{L^2(\mathbb{R}^+;B^{0,\frac{1}{2}})} \\
+ \beta \|w^3\|_{L^2(\mathbb{R}^+;B^{0,\frac{1}{2}})}\|v\|_{L^2(\mathbb{R}^+;B^1)}.
\]

hence by Propositions 4.1 and 4.5 along with Lemma 6.3

\begin{equation}
\|E^2_\beta\|_{F^0} \leq \beta T_2\left((v_0,w^3_0)\|_{S^\mu}\right).
\end{equation}

Let us estimate $E^3_\beta$. Again by laws of product and the action of horizontal derivatives, we obtain

\[
\|w^h \cdot \nabla^h(v,w^3)\|_{L^1(\mathbb{R}^+;B^0)} \lesssim \|w^h\|_{L^2(\mathbb{R}^+;B^1)}\|\nabla^h(v,w^3)\|_{L^2(\mathbb{R}^+;B^0)} \\
\lesssim \|w^h\|_{L^2(\mathbb{R}^+;B^1)}\|(v,w^3)\|_{L^2(\mathbb{R}^+;B^1)}.
\]

Corollary 4.7 and Propositions 4.1 and 4.5 imply that

\begin{equation}
\|w^h \cdot \nabla^h(v,w^3)\|_{L^1(\mathbb{R}^+;B^0)} \leq T_2\left((v_0,w^3_0)\|_{S^\mu}\right).
\end{equation}

Following the same lines we get

\[
\|v \cdot \nabla^h(w^h,0)\|_{L^1(\mathbb{R}^+;B^0)} \leq T_2\left((v_0,w^3_0)\|_{S^\mu}\right).
\]

Together with (4.45), this gives thanks to Lemma 6.3

\begin{equation}
\|E^3_\beta\|_{F^0} \lesssim \|E^3_\beta\|_{L^1(\mathbb{R}^+;B^0)} \leq \beta T_2\left((v_0,w^3_0)\|_{S^\mu}\right).
\end{equation}

Now let us estimate $E^4_\beta$. Laws of product and the action of derivations give

\[
\|w^h \cdot \nabla^h w^h\|_{L^1(\mathbb{R}^+;B^0)} \lesssim \|w^h\|_{L^2(\mathbb{R}^+;B^1)}\|\nabla^h w^h(t)\|_{L^2(\mathbb{R}^+;B^0)} \\
\lesssim \|w^h\|^2_{L^2(\mathbb{R}^+;B^1)}.
\]

In the same way, we get

\[
\|w^3(t)\partial_3 w^h\|_{L^1(\mathbb{R}^+;B^0)} \lesssim \|w^3\|_{L^2(\mathbb{R}^+;B^0)}\|w^h\|_{L^2(\mathbb{R}^+;B^{1,\frac{1}{2}})}.
\]

Together with (4.47), this gives thanks to Corollary 4.7 and Propositions 4.5

\[
\|E^4_\beta\|_{L^1(\mathbb{R}^+;B^0)} \leq \beta^2 T_2\left((v_0,w^3_0)\|_{S^\mu}\right).
\]
Lemma 6.3 implies that
\[ \|E_\beta^4\|_{L^0} \leq \beta^2 T_2(\|(v_0, w_0^3)\|_{S_\alpha}). \]
Together with Inequalities (4.42), (4.44) and (4.46), this gives
\[ \|E_\beta\|_{L^0} \leq \beta^2 T_2(\|(v_0, w_0^3)\|_{S_\alpha}). \]
Thanks to Proposition 2.5 we obtain that the solution \(\Phi_\beta\) of (NS) with initial data
\[ \Phi_0 = [(v_0 - \beta \nabla h^\alpha \Delta_{\alpha}^{-1} \partial_3 w_0^3, w_0^3)]_\beta \]
is global and belongs to \(L^2(\mathbb{R}^+; B^1)\). The whole Theorem 4 follows from the next propagation result proved in Section 6. \(\Box\)

**Proposition 4.8.** Let \(u\) be a solution of (NS) which belongs to \(L^2(\mathbb{R}^+; B^1)\) and with initial data \(u_0\) in \(B^0\). Then \(u\) belongs to \(A^0\) and satisfies
\[ (4.48) \quad \|u\|_{L^1(\mathbb{R}^+; B^1)} + \|u\|_{L^1(\mathbb{R}^+; B^1)^{1/2}} \leq \|u_0\|_{B^0} + \|u\|_{L^2(\mathbb{R}^+; B^1)}. \]
Moreover, if the initial data \(u_0\) belongs in addition to \(B^s\) for some \(s\) in \([-1 + \mu, 1 - \mu]\), then
\[ (4.49) \quad \forall r \in [1, \infty], \quad \|u\|_{L^r(\mathbb{R}^+; B^s + \beta)} \leq \mathcal{T}_1(\|u_0\|_{B^s}) \mathcal{T}_0(\|u_0\|_{B^0}, \|u\|_{L^2(\mathbb{R}^+; B^1)}). \]
Finally, if \(u_0\) belongs to \(B^{0,s'}\) for some \(s'\) greater than \(1/2\), then
\[ (4.50) \quad \forall r \in [1, \infty], \quad \|u\|_{L^r(\mathbb{R}^+; B^{0,s'})} \leq \mathcal{T}_1(\|u_0\|_{B^{0,s'}}) \mathcal{T}_0(\|u_0\|_{B^0}, \|u\|_{L^2(\mathbb{R}^+; B^1)}). \]

**5. Interaction between profiles of scale 1: proof of Theorem 5.**

The goal of this section is to prove Theorem 5. In the next paragraph we define an approximate solution, using results proved in the previous section, and Paragraph 5.2 is devoted to the proof of useful localization results on the different parts entering the definition of the approximate solution. Paragraph 5.3 concludes the proof of the theorem, using those localization results.

### 5.1. The approximate solution.

Consider the divergence free vector field
\[ \Phi_{0,n,\alpha,L}^0 \overset{\text{def}}{=} u_{0,\alpha} + [(v_{0,n,\alpha,L}^0, h_{0,n,\alpha,L}^0, 0_{0,n,\alpha,L}^3)]_{h_0^0} + [(v_{0,n,\alpha,L}^{0,\text{loc}}, h_{0,n,\alpha,L}^{0,\text{loc}}, w_{0,n,\alpha,L}^{0,\text{loc},3})]_{h_0^0}, \]
with the notation of Theorem 3. We want to prove that for \(h_0^0\) small enough, depending only on \(u_0\) and on \(\|(v_{0,n,\alpha,L}^0, h_{0,n,\alpha,L}^0, 0_{0,n,\alpha,L}^3)\|_{S_\alpha}\) as well as \(\|(v_{0,n,\alpha,L}^{0,\text{loc}}, h_{0,n,\alpha,L}^{0,\text{loc}}, w_{0,n,\alpha,L}^{0,\text{loc},3})\|_{S_\alpha}\), there is a unique, global smooth solution to (NS) with data \(\Phi_{0,n,\alpha,L}^0\).

Let us start by solving globally (NS) with the data \(u_{0,\alpha}\). By using the global strong stability of (NS) in \(B_{1,1}\) (see [4], Corollary 3) and the convergence result (2.3) we deduce that for \(\alpha\) small enough there is a unique, global solution to (NS) associated with \(u_{0,\alpha}\), which we shall denote by \(u_\alpha\) and which lies in \(L^2(\mathbb{R}^+; B_{1,1}^{2/3})\). Moreover by the embedding of \(B_{1,1}^{2/3}\) into \(B^1\) we have \(u_\alpha \in L^2(\mathbb{R}^+; B^1)\).

Next let us define
\[ \Phi_{0,n,\alpha,L}^{0,\infty} \overset{\text{def}}{=} [(v_{0,n,\alpha,L}^0, h_{0,n,\alpha,L}^0, w_{0,n,\alpha,L}^{0,\infty})]_{h_0^0}. \]
Thanks to Theorem 4, we know that for \(h_0^0\) smaller than \(\varepsilon_1(\|(v_{0,n,\alpha,L}^0, h_{0,n,\alpha,L}^0, w_{0,n,\alpha,L}^{0,\infty})\|_{S_\alpha})\) there is a unique global smooth solution \(\Phi_{0,n,\alpha,L}^{0,\infty}\) associated with \(\Phi_{0,n,\alpha,L}^{0,\infty}\), which belongs to \(A_0\), and
using the notation and results of Section 4, in particular (4.1) and (4.38), we can write

\[ \phi_{\infty}^{n,\alpha,L} \equiv \phi_{\infty,app}^{n,\alpha,L} + \psi_{\infty,\alpha,L} \quad \text{with} \]

\[ (5.1) \]

\[ \phi_{\infty,app}^{n,\alpha,L} \equiv [v_{\infty,n,\alpha,L} + h^n_\infty w_{\infty,\alpha,L}]_{h^n_\infty} \quad \text{and} \]

\[ \|\psi_{\infty,n,\alpha,L}\|_{L^2(\mathbb{R}^+;B^1)} \lesssim h^n_\infty T_2\left(\left\|\left(\phi_{\infty,n,\alpha,L}^{0},0\right)\right\|_{S_\mu}\right), \]

where \(v_{\infty,n,\alpha,L}\) solves (NS2D) with data \(v_{\infty,n,\alpha,L}^{0}\) and \(w_{\infty,\alpha,L}^{0}\) solves the transport-diffusion equation \((T_{h^n_\infty})\) defined page 24 with data \(w_{\infty,\alpha,L}^{0}\). Finally we recall that

\[ w_{\infty,n,\alpha,L}^{0} = -\nabla^h \Delta^1 h \partial_3 w_{\infty,\alpha,L}. \]

Similarly defining

\[ \phi_{0,loc}^{n,\alpha,L} \equiv [v_{0,loc,n,\alpha,L} + h^n_0 w_{0,loc,\alpha,L}]_{h^n_0}, \]

then for \(h^n_0\) smaller than \(\varepsilon_{(1)}\left(\|v_{0,loc,n,\alpha,L}\|_{L^2(\mathbb{R}^+;B^1)}\right)\) there is a unique global smooth solution \(\phi_{0,loc,n,\alpha,L}\) associated with \(\phi_{0,loc,n,\alpha,L}\), which belongs to \(A_0\), and

\[ (5.2) \]

\[ \phi_{n,\alpha,L}^{loc,app} \equiv [v_{n,\alpha,L}^{loc} + h^n_0 w_{0,loc,\alpha,L}, w_{0,loc,3}]_{h^n_0} \quad \text{and} \]

\[ \|\psi_{0,loc,n,\alpha,L}\|_{L^2(\mathbb{R}^+;B^1)} \lesssim h^n_0 T_2\left(\left\|\left(\phi_{0,loc,n,\alpha,L}^{0},0\right)\right\|_{S_\mu}\right), \]

where \(v_{0,loc,n,\alpha,L}\) solves (NS2D) with data \(v_{0,loc,n,\alpha,L}^{0}\) and \(w_{0,loc,\alpha,L}^{0}\) solves \((T_{h^n_0})\) with data \(w_{0,loc,3}^{0}\). Finally we recall that \(w_{n,\alpha,L}^{0,loc} = -\nabla^h \Delta^1 h \partial_3 w_{0,loc,3}\).

Now we look for the solution under the form

\[ \phi_{n,\alpha,L}^{0,loc} \equiv u_{\alpha} + \phi_{0,\infty,\alpha,L}^{n,\alpha,L} + \phi_{0,loc,\alpha,L} + \psi_{\infty,\alpha,L}. \]

In the next section we shall prove localization properties on \(\phi_{n,\alpha,L}^{0,\infty}\) and \(\phi_{n,\alpha,L}^{0,loc}\), namely the fact that \(\phi_{n,\alpha,L}^{0,\infty,app}\) escapes to infinity in the space variable, while \(\phi_{n,\alpha,L}^{0,loc,app}\) remains localized (approximately), and we shall also prove that \(\phi_{n,\alpha,L}^{0,loc,app}\) remains small near \(x_3 = 0\). Let us recall that as claimed by (2.7), (2.8) and (2.9), those properties are true for their respective initial data. Those localization properties will enable us to prove, in Paragraph 5.3, that the function \(u_{\alpha} + \phi_{0,\infty,\alpha,L}^{n,\alpha,L} + \phi_{0,loc,\alpha,L}\) is itself an approximate solution to (NS) for the Cauchy data \(u_{0,\alpha} + \phi_{0,\infty,\alpha,L}^{0,n,\alpha,L} + \phi_{0,loc,\alpha,L}\).

5.2. Localization properties of the approximate solution. One important step in the proof of Theorem 5 consists in the following result.

**Proposition 5.1.** Under the assumptions of Proposition 4.1, the control of the value of \(v\) at the point \(x_3 = 0\) is given by

\[ \forall r \in [1, \infty], \quad \|v(\cdot, 0)\|_{L^r(\mathbb{R}^+;B^2_2(\mathbb{R}^2))} \lesssim \|v(\cdot, 0)\|_{B^2_2(\mathbb{R}^2)} + \|v(\cdot, 0)\|_{L^r(\mathbb{R}^2)}^2. \]  

Moreover we have for all \(\eta\) in \([0,1]\) and \(\gamma\) in \((0,1)\),

\[ \|\gamma - \theta_{n,\eta}\|_{A^1} \leq \|\gamma - \theta_{n,\eta}\|_{B^0} \exp T_1(\|v_0\|_{H^0}) + \eta T_2(\|v_0\|_{S_\mu}), \]

with \(\theta_{n,\eta}\) is the truncation function defined by (2.2).
Proof. In this proof we omit for simplicity the dependence of the function spaces on the space $\mathbb{R}^2$. Let us remark that the proof of Lemma 1.1 of [12] claims that for all $x_3$ in $\mathbb{R}$,

\[(\Delta^h_k(v(t, \cdot, x_3) \cdot \nabla^h v(t, \cdot, x_3))|\Delta^h_k(v(t, \cdot, x_3))|)_{L^2} \lesssim d_k(t, x_3)\|\nabla^h v(t, \cdot, x_3)\|_{L^2}^2\|\Delta^h_k v(t, \cdot, x_3)\|_{L^2}
\]

where $(d_k(t, x_3))_{k \in \mathbb{Z}}$ is a generic element of the sphere of $\ell^1(\mathbb{Z})$. A $L^2$ energy estimate in $\mathbb{R}^2$ gives therefore, taking $x_3 = 0$,

\[
\frac{1}{2} \frac{d}{dt}\|\Delta^h_k v(t, \cdot, 0)\|_{L^2}^2 + c 2^{2k}\|\Delta^h_k v(t, \cdot, 0)\|_{L^2}^2 \lesssim d_k(t)\|\nabla^h v(t, \cdot, 0)\|_{L^2}^2\|\Delta^h_k v(t, \cdot, 0)\|_{L^2},
\]

where $(d_k(t))_{k \in \mathbb{Z}}$ belongs to the sphere of $\ell^1(\mathbb{Z})$. After division by $\|\Delta^h_k v(t, \cdot, 0)\|_{L^2}$ and time integration, we get

\[
\|\Delta^h_k v(\cdot, 0)\|_{L^\infty(\mathbb{R}^+; L^2)} + c 2^{2k}\|\Delta^h_k v(\cdot, 0)\|_{L^1(\mathbb{R}^+; L^2)} \leq \|\Delta_k v_0(\cdot, 0)\|_{L^2} + C \int_0^\infty d_k(t)\|\nabla^h v(t, \cdot, 0)\|_{L^2}^2 dt.
\]

By summation over $k$ and in view of (4.12), we obtain Inequality (5.3) of Proposition 5.1.

In order to prove Inequality (5.4), let us define $v_{\gamma, \eta} \overset{\text{def}}{=} (\gamma - \theta_{h, \eta})v$ and write that

\[
\partial_t v_{\gamma, \eta} - \Delta_h v_{\gamma, \eta} + \text{div}_h(v \otimes v_{\gamma, \eta}) = E_{\eta}(v) = \sum_{i=1}^3 E_{\eta}^i(v) \quad \text{with}
\]

\[
E_{\eta}^1(v) \overset{\text{def}}{=} -2\eta(\nabla^h \theta)_{h, \eta} \nabla^h v - \eta^2(\Delta_h \theta)_{h, \eta} v,
\]

\[
E_{\eta}^2(v) \overset{\text{def}}{=} \eta \cdot (\nabla^h \theta)_{h, \eta} v \quad \text{and}
\]

\[
E_{\eta}^3(v) \overset{\text{def}}{=} -(\gamma - \theta_{h, \eta})\nabla^h \Delta_h^{-1} \sum_{1 \leq \ell, m \leq 2} \partial_\ell \partial_m (v^\ell v^m).
\]

Let us prove that

\[
\|E_{\eta}(v)\|_{L^1(\mathbb{R}^+; B^s_{\omega})} \lesssim \eta\mathcal{T}_2(\|v_0\|_{S^s_{\omega}}).
\]

Using Inequality (4.27) applied with $r = 1$ and $s = -1$ (resp. $r = 2$ and $s = -1/2$) this will follow from

\[
\|E_{\eta}(v)\|_{L^1(\mathbb{R}^+; B^s_{\omega})} \lesssim \eta\|v\|_{L^1(\mathbb{R}^+; B^s_{\omega})} + \|v\|_{L^2(\mathbb{R}^+; B^{s+1}_{\omega})}^2.
\]

Proposition 6.6 and the scaling properties of homogeneous Besov spaces give

\[
\|((\nabla^h \theta)_{h, \eta} \nabla^h v(t))\|_{B^s_{\omega}} \lesssim \|((\nabla^h \theta)_{h, \eta} \nabla^h v(t))\|_{B^s_{\omega}} \lesssim \|\nabla^h \theta\|_{B^1_{\omega}}\|v(t)\|_{B^s_{\omega}}.
\]

Following the same lines, we get

\[
\|((\Delta_h \theta)_{h, \eta} v(t))\|_{B^s_{\omega}} \lesssim \|((\Delta_h \theta)_{h, \eta} v(t))\|_{B^s_{\omega}} \lesssim \frac{1}{\eta}\|\Delta_h \theta\|_{B^1_{\omega}}\|v(t)\|_{B^s_{\omega}},
\]

hence

\[
\|E_{\eta}^1(v)\|_{L^1(\mathbb{R}^+; B^s_{\omega})} \lesssim \eta\|v\|_{L^1(\mathbb{R}^+; B^s_{\omega})}.
\]
Let us study the term $E^2_\eta(v)$. Proposition 6.6 implies
\[
\|v(t) \cdot (\nabla \theta)_{h,\eta} v(t)\|_{B^0_2} \lesssim \|\nabla^h \theta\|_{B^1_{2,1}(\mathbb{R}^2)} \sup_{\ell,m} \|v^\ell(t)v^m(t)\|_{B^0_2}
\]
\[
\lesssim \|\nabla^h \theta\|_{B^1_{2,1}(\mathbb{R}^2)} \|v(t)\|_{B^{1/2}_2}^2.
\]
Thus we get
\[
(5.11) \quad \|E^2_\eta(v)\|_{L^1(\mathbb{R}^+; B^0_2)} \lesssim \eta \|v\|_{L^2(\{0\}; B^{1/2}_2)}^2.
\]
Let us study the term $E^3_\eta(v)$ which is related to the pressure. For that purpose, we shall make use of the horizontal paraproduct decomposition:
\[
av = T^h_a + T^h_{\frac{\partial}{\partial x_1}} v + R^h(a,b) \quad \text{with} \quad T^h_{a,b} \defeq \sum_k S^h_k(a) \Delta^h_k b \quad \text{and} \quad R^h(a,b) \defeq \sum_k \tilde{\Delta}^h_k a \Delta^h_k b.
\]
This allows us to write
\[
E^3_\eta(v) = \sum_{\ell=1}^3 E^3_\eta^\ell(v) \quad \text{with}
\]
\[
E^3_\eta^1(v) \defeq \frac{\tilde{\Delta}^h_{\frac{\partial}{\partial x_1}} p_{h,\eta}}{\nabla^h \theta_{h,\eta}} \quad \text{with} \quad \nabla^h p = \nabla^h \Delta^{-1}_h \sum_{1 \leq \ell,m \leq 2} \partial_\ell \partial_m (v^\ell v^m),
\]
\[
E^3_\eta^2(v) \defeq - \sum_{1 \leq \ell,m \leq 2} [T^h_{\gamma - \theta, h,\eta}, \nabla^h \Delta^{-1}_h \partial_\ell \partial_m] v^\ell v^m \quad \text{and}
\]
\[
E^3_\eta^3(v) \defeq \sum_{1 \leq \ell,m \leq 2} \nabla^h \Delta^{-1}_h \partial_\ell \partial_m \tilde{T}^h_{v^\ell v^m, \theta_{h,\eta}}.
\]
Laws of (para)product, as given in (6.10), and scaling properties of Besov spaces give
\[
\|\tilde{T}^h_{v^\ell v^m}(\theta_{h,\eta})\|_{B^0_2} \lesssim \|\nabla^h p(t)\|_{B^{-1}} \|\theta_{h,\eta}\|_{B^1_{2,1}(\mathbb{R}^2)}
\]
\[
\lesssim \eta \sup_{1 \leq \ell,m \leq 2} \|v^\ell(t)v^m(t)\|_{B^0_2} \|\theta\|_{B^1_{2,1}(\mathbb{R}^2)}
\]
\[
\lesssim \eta \|v(t)\|_{B^{1/2}_2}^2 \|\theta\|_{B^1_{2,1}(\mathbb{R}^2)}.
\]
Along the same lines we get
\[
\|\nabla^h \Delta^{-1}_h \partial_\ell \partial_m \tilde{T}^h_{v^\ell v^m}(\theta_{h,\eta})\|_{B^0_2} \lesssim \|\tilde{T}^h_{v^\ell v^m}(\theta_{h,\eta})\|_{B^1_2}
\]
\[
\lesssim \|v^\ell(t)v^m(t)\|_{B^0_2} \|\theta_{h,\eta}\|_{B^1_{2,1}(\mathbb{R}^2)}
\]
\[
\lesssim \eta \|v(t)\|_{B^{1/2}_2}^2 \|\theta\|_{B^1_{2,1}(\mathbb{R}^2)}.
\]
This gives
\[
(5.13) \quad \|E^3_\eta^1(v) + E^3_\eta^2(v)\|_{L^1(\mathbb{R}^+; B^0_2)} \lesssim \eta \|v\|_{L^2(\{0\}; B^{1/2}_2)}^2.
\]
Now let us estimate $E^3_\eta^3(v)$. By definition, we have
\[
[T^h_{\gamma - \theta, h,\eta}, \nabla^h \Delta^{-1}_h \partial_\ell \partial_m] v^\ell v^m = \sum_k e_{k,\eta}(v) \quad \text{with}
\]
\[
e_{k,\eta}(v) \defeq [S^h_k(\gamma - \theta, h,\eta), \tilde{\Delta}^h_k v^\ell \nabla^h \Delta^{-1}_h \partial_\ell \partial_m] \Delta^h_k(v^\ell v^m)
\]
where $\tilde{\Delta}^h_k \defeq \tilde{\varphi}(2^{-k} \xi_h)$ with $\tilde{\varphi}$ is a smooth compactly supported (in $\mathbb{R}^2 \setminus \{0\}$) function which has value 1 near $B(0,2^{-N_0}) + C$, where $C$ is an adequate annulus. Then by commutator
estimates (see for instance Lemma 2.97 in [2])

\[ \|\Delta_t^\gamma \mathcal{E}_{k,\eta}(v(t))\|_{L^2} \lesssim \|\nabla \theta_{h,\eta}\|_{L^\infty} \|\Delta_k^\gamma \Delta_t^\gamma (v^e(t)v^m(t))\|_{L^2}. \]

As \( \|\nabla \theta_{h,\eta}\|_{L^\infty} = \eta \|\nabla \theta\|_{L^\infty} \), by characterization of anisotropic Besov spaces and laws of product, we get

\[ \|E_{\eta}^{3,2}(v)\|_{L^1(\mathbb{R}^+; B^{2}_{2,2}(\mathbb{R}^2))} \lesssim \eta \|v\|_{L^2(\mathbb{R}^+; \mathbb{B}^{2}_{2,2}(\mathbb{R}^2))}. \]

Together with estimates (5.10)–(5.13), this gives (5.9), hence (5.8).

Applying Lemma 4.6 with \( s = 0 \), \( s' = 1/2 \), \( a = v_{\gamma,\eta} P(v,a) = \text{div}_h(v \otimes a) \), \( f = E_{\eta}(v) \) and \( \beta = 0 \) allows to conclude the proof of Proposition 5.1.

\( \square \)

A similar result holds for the solution \( w^3 \) of

\[ (T_{\beta}) \quad \partial_t w^3 + v \cdot \nabla^h w^3 - \Delta_h w^3 - \beta^2 \partial^2_3 w^3 = 0 \quad \text{and} \quad w^3_{t=0} = w^3_0, \]

where \( \beta \) is any non negative real number. In the following statement, all the constants are independent of \( \beta \).

**Proposition 5.2.** Let \( v \) and \( w_3 \) be as in Proposition 4.5. The control of the value of \( w^3 \) at the point \( x_3 = 0 \) is given by the following inequality. For any \( r \) in \([2,\infty]\),

\[ \|w^3(\cdot,0)\|_{L^r(\mathbb{R}^+; B^{2}_{2,\frac{1}{2}}(\mathbb{R}^2))} \leq T_2 \left( \|v(0)\|_{L^2}, \|\nabla \theta(0)\|_{L^\infty}, \eta \right) \left( \|w_3^0(\cdot,0)\|_{B^{2}_{2,\frac{1}{2}}(\mathbb{R}^2)} + \beta \right). \]

Moreover, with the notations of Theorem 4, we have for all \( \eta \) in \([0,1]\) and \( \gamma \) in \([0,1]\),

\[ \left\| (\gamma - \theta_{h,\eta}) w^3 \right\|_{L^\infty} \leq \left\| (\gamma - \theta_{h,\eta}) w_3^0 \right\|_{B^{2}_{2,\frac{1}{2}}(\mathbb{R}^2)} \exp \left( T_1 \left( \|v_0\|_{L^2}, \eta T_2 \left( \|v_0\|_{L^2}, \|w_3^0\|_{B^{2}_{2,\frac{1}{2}}(\mathbb{R}^2)} \right) \right) \right) \]

**Proof.** The proof is very similar to the proof of Proposition 5.1. The main difference lies in the proof of (5.14) due to the presence of the extra term \( \beta^2 \partial^2_3 w^3 \), so let us detail that estimate: we shall first prove an estimate for \( w^3(t, x_3, 0) \) in \( \tilde{L}^r(\mathbb{R}^+; B^{\frac{1}{2}+\frac{1}{2}}_{2,1}(\mathbb{R}^2)) \), and then we shall interpolate that estimate with the known a priori estimate (4.29) of \( w^3 \) in \( \tilde{L}^r(\mathbb{R}^+; B^{-\frac{1}{2}+\frac{1}{2}}_{2,1}(\mathbb{R}^2)) \) to find the result.

Let us be more precise, and first obtain a bound for \( w^3(t, x_3, 0) \) in \( \tilde{L}^r(\mathbb{R}^+; B^{\frac{1}{2}+\frac{1}{2}}_{2,1}(\mathbb{R}^2)) \). Defining

\[ \tilde{w}^3(t, x_3) \overset{\text{def}}{=} w^3(t, x_3, 0), \quad \tilde{w}^3_0(x_3) \overset{\text{def}}{=} w^3_0(x_3, 0) \quad \text{and} \quad \tilde{v}(t, x_3) \overset{\text{def}}{=} v(t, x_3, 0), \]

we have

\[ (5.16) \quad \partial_t \tilde{w}^3 + \tilde{v} \cdot \nabla^h \tilde{w}^3 - \Delta_h \tilde{w}^3 = \beta^2(\partial^2_3 w^3)(\cdot, 0) \quad \text{and} \quad \tilde{w}^3_{t=0} = \tilde{w}^3_0. \]

Similarly to (5.5) we write (dropping for simplicity the dependence of the spaces on \( \mathbb{R}^2 \))

\[ \left( \Delta^\gamma_k(\tilde{v} \cdot \nabla^h \tilde{w}^3) \right)_{L^2} \lesssim d_k(t) 2^{-\frac{k}{2}} \|\tilde{v}\|_{L^2} \|\nabla^h \tilde{w}^3\|_{L^2} \|\nabla^h \tilde{w}_0^3\|_{B^{\frac{1}{2}}_{2,1}} \|\Delta^\gamma_k \tilde{w}_0^3\|_{L^2}, \]

where \( (d_k(t)) \) belongs to the sphere of \( \ell^1(\mathbb{Z}) \). Taking the \( L^2 \) scalar product of \( \Delta^\gamma_k \) of Equation (5.16) with \( \Delta^\gamma_k \tilde{w}^3 \) implies that

\[ \frac{1}{2} \int d\|\Delta^\gamma_k \tilde{w}^3\|_{L^2}^2 + c 2^{\frac{k}{2}} \|\Delta^\gamma_k \tilde{w}^3\|_{L^2}^2 \lesssim d_k(t) \|\nabla^h \tilde{v}(t)\|_{L^2} \|\nabla^h \tilde{w}^3\|_{B^{\frac{1}{2}}_{2,1}} \|\Delta^\gamma_k \tilde{w}_0^3\|_{L^2} \]

\[ \quad + \beta^2 2^{\frac{k}{2}} \|\Delta^\gamma_k (\partial^2_3 w^3)(\cdot, 0)\|_{L^2} \|\Delta^\gamma_k \tilde{w}_0^3\|_{L^2}^2, \]

so as in (5.6) we find

\[ 2^{\frac{k}{2}} \|\Delta^\gamma_k \tilde{w}_0^3\|_{L^{\infty}(\mathbb{R}^+; L^2)} + c 2^{\frac{k}{2}} \|\Delta^\gamma_k \tilde{w}_0^3\|_{L^1(\mathbb{R}^+; L^2)} \leq 2^{\frac{k}{2}} \|\Delta^\gamma_k \tilde{w}_0^3\|_{L^2} \]

\[ + C \int_0^\infty d_k(t) \|\nabla^h \tilde{v}(t)\|_{L^2} \|\nabla^h \tilde{w}^3(t)\|_{B^{\frac{1}{2}}_{2,1}} dt + C \beta^2 \int_0^\infty 2^{\frac{k}{2}} \|\Delta^\gamma_k (\partial^2_3 w^3)(t, \cdot)\|_{L^2} dt. \]
After summation we find that
\[
\|\tilde{w}\|_{L^\infty([0,T];B^{\frac{1}{2},1}_{2,1})} + \|\tilde{w}\|_{L^1([0,T];B^{\frac{3}{2},1}_{2,1})} \lesssim \|\tilde{w}_0\|_{B^{\frac{1}{2},1}_{2,1}} + \|\tilde{w}\|_{L^2([0,T];B^{0,1}_{2,1})} \|\nabla^1\tilde{w}\|_{L^2([0,T];L^2)} + \beta^2 \|\partial_3^2 w^3\|_{L^1([0,T];B^{\frac{1}{2},1}_{2,1})}.
\]
This is exactly an inequality of the type (4.30), up to a harmless localization in time, so by the same arguments we obtain the same conclusion as in Lemma 4.6, namely the fact that for any \(r \in [1, \infty] \),
\[
\|\tilde{w}\|_{L^r([0,T];B^{\frac{1}{2},1}_{2,1})} \lesssim \left( \|\tilde{w}_0\|_{B^{\frac{1}{2},1}_{2,1}} + \beta^2 \|\partial_3^2 w^3\|_{L^1([0,T];B^{\frac{1}{2},1}_{2,1})} \right) \exp C \|v_0(\cdot,0)\|_{L^2}^2.
\]
Since we have
\[
\|\partial_3^2 w^3\|_{L^1([0,T];B^{\frac{1}{2},1}_{2,1})} \lesssim \|\tilde{w}\|_{L^1([0,T];B^{\frac{1}{2},1}_{2,1})} \lesssim \|\tilde{w}\|_{L^1([0,T];B^{0,1}_{2,1})},
\]
we infer from the a priori bounds (4.34) obtained on \(w^3\) in the previous section that
\[
\|\partial_3^2 w^3\|_{L^1([0,T];B^{\frac{1}{2},1}_{2,1})} \lesssim \|w_0\|_{S_\mu},
\]
so we obtain that for any \(r \in [1, \infty] \),
\[
\|w^3(\cdot,0)\|_{L^r([0,T];B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2))} \leq \left( \|w_0^3(\cdot,0)\|_{B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2)} + \beta^2 \right) T_2(\|v_0, w_0^3\|_{S_\mu}).
\]
(5.17)
Recalling that \(w_0^3\) belongs to the space \(S_\mu\) introduced in Definition 2.2, we find that
\[
w_0^3(\cdot,0) \in \bigcap_{s \in [-2+\mu,1-\mu]} B^{s,1}_{2,1}(\mathbb{R}^2).
\]
Since \(0 < \mu < \frac{1}{2} \), we get by interpolation and Sobolev embeddings that
\[
\|w_0^3(\cdot,0)\|_{B^{\frac{1}{2},1}(\mathbb{R}^2)} \leq \|w_0^3(\cdot,0)\|_{B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2)} \|w_0^3\|_{S_\mu} \|w_0^3\|_{S_\mu},
\]
which implies that (5.17) can be written under the form
\[
\|w^3(\cdot,0)\|_{L^r([0,T];B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2))} \leq \left( \|w_0^3(\cdot,0)\|_{B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2)} + \beta^2 \right) T_2(\|v_0, w_0^3\|_{S_\mu}).
\]
Now interpolating with the a priori bound obtained in Proposition 4.5, we find
\[
\|w^3(\cdot,0)\|_{L^r([0,T];B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2))} \lesssim \|w^3\|_{L^r([0,T];B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2))} \leq \left( \|w_0^3(\cdot,0)\|_{B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2)} + \beta^2 \right) T_2(\|v_0, w_0^3\|_{S_\mu}),
\]
so we obtain finally
\[
\|w^3(\cdot,0)\|_{L^r([0,T];B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2))} \leq \left( \|w_0^3(\cdot,0)\|_{B^{\frac{1}{2},1}_{2,1}(\mathbb{R}^2)} + \beta^2 \right) T_2(\|v_0, w_0^3\|_{S_\mu}).
\]
This ends the proof of (5.14).

We shall not detail the proof of (5.15) as it is very similar to the proof of (5.4). Proposition 5.2 is therefore proved. \(\square\)

Propositions 5.1 and 5.2 imply easily the following result, using the special form of \(\Phi^{0,\infty}_{\mu,o,L}\) and \(\Phi^{0,\text{loc}}_{n,o,L}\) recalled in (5.1) and (5.2), and thanks to (2.7), (2.8) and (2.9).
Corollary 5.3. The vector fields $\Phi_{n,\alpha,L}^{0,\text{loc}}$ and $\Phi_{n,\alpha,L}^{0,\infty}$ satisfy the following: $\Phi_{n,\alpha,L}^{0,\text{loc}}$ vanishes at $x_3 = 0$, in the sense that for all $r$ in $[2, \infty]$,
\[
\lim_{L \to \infty} \lim_{r \to \infty} \lim_{n \to \infty} \sup \left\{ \| \Phi_{n,\alpha,L}^{0,\text{loc}}(\cdot, 0) \|_{L^r(\mathbb{R}^+; B_{2,1}^2(\mathbb{R}^2))} \right\} = 0,
\]
and there is a constant $C(\alpha, L)$ such that for all $\eta$ in $]0, 1[$,
\[
\limsup_{n \to \infty} \left( \| (1 - \theta_{h,\eta}) \Phi_{n,\alpha,L}^{0,\text{loc}} \|_{A^0} + \| \theta_{h,\eta} \Phi_{n,\alpha,L}^{0,\infty} \|_{A^0} \right) \leq C(\alpha, L) \eta.
\]

5.3. Conclusion of the proof of Theorem 5. Recall that we look for the solution of (NS) under the form
\[
\Phi_{n,\alpha,L}^{0} = u_{\alpha} + \Phi_{n,\alpha,L}^{0,\infty} + \Phi_{n,\alpha,L}^{0,\text{loc}} + \psi_{n,\alpha,L},
\]
with the notation introduced in Paragraph 5.1. In particular, the two vector fields $\Phi_{n,\alpha,L}^{0,\text{loc}}$ and $\Phi_{n,\alpha,L}^{0,\infty}$ satisfy Corollary 5.3, and furthermore thanks to the Lebesgue theorem,
\[
\lim_{\eta \to 0} \| (1 - \theta_{h,\eta}) u_{\alpha} \|_{L^2(\mathbb{R}^+; B^1)} = 0.
\]

Given a small number $\varepsilon > 0$, to be chosen later, we choose $L, \alpha$ and $\eta = \eta(\alpha, L, u_0)$ so that thanks to Corollary 5.3 and (5.18), for all $r$ in $[2, \infty]$, and for $n$ large enough,
\[
\left\| \Phi_{n,\alpha,L}^{0,\text{loc}}(\cdot, 0) \right\|_{L^r(\mathbb{R}^+; B_{2,1}^2(\mathbb{R}^2))} + \left\| (1 - \theta_{h,\eta}) \Phi_{n,\alpha,L}^{0,\text{loc}} \right\|_{A^0} + \left\| (1 - \theta_{h,\eta}) u_{\alpha} \right\|_{L^2(\mathbb{R}^+; B^1)} + \left\| \theta_{h,\eta} \Phi_{n,\alpha,L}^{0,\infty} \right\|_{A^0} \leq \varepsilon.
\]

In the following we denote for simplicity
\[
\left( \Phi_{\varepsilon}^{0,\text{loc}}, \Phi_{\varepsilon}^{0,\text{app}}, \psi_{\varepsilon} \right) \overset{\text{def}}{=} \left( \Phi_{n,\alpha,L}^{0,\infty}, \Phi_{n,\alpha,L}^{0,\text{loc}}, \psi_{n,\alpha,L} \right) \quad \text{and} \quad \Phi_{\varepsilon}^{\text{app}} \overset{\text{def}}{=} u_{\alpha} + \Phi_{\varepsilon}^{0,\infty} + \Phi_{\varepsilon}^{0,\text{loc}},
\]
so the vector field $\psi_{\varepsilon}$ satisfies the following equation, with zero initial data:
\[
\partial_t \psi_{\varepsilon} - \Delta \psi_{\varepsilon} + \text{div}(\psi_{\varepsilon} \otimes \psi_{\varepsilon} + \Phi_{\varepsilon}^{\text{app}} \otimes \psi_{\varepsilon} + \psi_{\varepsilon} \otimes \Phi_{\varepsilon}^{\text{app}}) = -\nabla q_{\varepsilon} + E_{\varepsilon},
\]
with $E_{\varepsilon} = E_{\varepsilon}^1 + E_{\varepsilon}^2$ and
\[
E_{\varepsilon}^1 \overset{\text{def}}{=} \text{div} \left( \Phi_{\varepsilon}^{0,\infty} \otimes (\Phi_{\varepsilon}^{0,\text{loc}} + u_{\alpha}) + (\Phi_{\varepsilon}^{0,\text{loc}} + u_{\alpha}) \otimes \Phi_{\varepsilon}^{0,\infty} \right),
\]
\[
E_{\varepsilon}^2 \overset{\text{def}}{=} \text{div} \left( \Phi_{\varepsilon}^{0,\text{loc}} \otimes (1 - \theta_{h,\eta}) u_{\alpha} + (1 - \theta_{h,\eta}) u_{\alpha} \otimes \Phi_{\varepsilon}^{0,\text{loc}} \right).
\]

If we prove that
\[
\lim_{\varepsilon \to 0} \| E_{\varepsilon} \|_{F^0} = 0,
\]
then Proposition 2.5 implies that $\psi_{\varepsilon}$ belongs to $L^2(\mathbb{R}^+; B^1)$, with
\[
\lim_{\varepsilon \to 0} \| \psi_{\varepsilon} \|_{L^2(\mathbb{R}^+; B^1)} = 0,
\]
and we conclude the proof of Theorem 5 exactly as in the proof of Theorem 4, by resorting to Proposition 4.8.
So let us prove (5.21). The term $E^1_\varepsilon$ is the easiest, thanks to the separation of the spatial supports. Let us first write $E^1_\varepsilon = E^1_{\varepsilon,h} + E^1_{\varepsilon,3}$ with

$$E^1_{\varepsilon,h} \overset{\text{def}}{=} \text{div}_h \left( \left( \Phi^{0,\text{loc}}_\varepsilon + u_\alpha \right) \otimes \Phi^{0,\infty}_\varepsilon + \Phi^{0,\infty}_\varepsilon \otimes \left( \Phi^{0,\text{loc},h}_\varepsilon + u_{\alpha}^h \right) \right) + (1 - \theta_\eta) u_\alpha \otimes \Phi^{0,\text{loc},h}_\varepsilon + \Phi^{0,\text{loc}} \otimes (1 - \theta_\eta) u_{\alpha}^h$$

and

$$E^1_{\varepsilon,3} \overset{\text{def}}{=} \partial_3 \left( \left( \Phi^{0,\text{loc}}_\varepsilon + u_\alpha \right) \Phi^{0,\infty,3}_\varepsilon + \Phi^{0,\infty}_\varepsilon \left( \Phi^{0,\text{loc},3} + u_\alpha^3 \right) \right) + (1 - \theta_\eta) u_\alpha \Phi^{0,\text{loc},3} + \Phi^{0,\text{loc}} (1 - \theta_\eta) u_\alpha^3.$$

Next let us write, for any two functions $a$ and $b$,

$$ab = (\theta_\eta a)b + a(1 - \theta_\eta b).$$

Denoting

$$u_\varepsilon^\infty \overset{\text{def}}{=} (1 - \theta_\eta) u_\alpha$$

and using by now as usual the action of derivatives and the fact that $B^1$ is an algebra, we infer that

$$\|E^1_{\varepsilon,h}\|_{L^1(\mathbb{R}^+;B^0)} + \|E^1_{\varepsilon,3}\|_{L^1(\mathbb{R}^+;B^1_{2,1})} \leq \|\theta_\eta \Phi^{0,\infty}_\varepsilon\|_{L^2(\mathbb{R}^+;B^1)} \|\Phi^{0,\text{loc}}_\varepsilon + u_\alpha\|_{L^2(\mathbb{R}^+;B^1)} + \|1 - \theta_\eta\|_{L^2(\mathbb{R}^+;B^1)} \|\Phi^{0,\infty}_\varepsilon\|_{L^2(\mathbb{R}^+;B^1)} \|\Phi^{0,\text{loc}}_\varepsilon + u_\alpha\|_{L^2(\mathbb{R}^+;B^1)} + \|\Phi^{0,\text{loc}}_\varepsilon\|_{L^2(\mathbb{R}^+;B^1)} \|u_\varepsilon^\infty\|_{L^2(\mathbb{R}^+;B^1)}.$$

Thanks to (5.19) and to the a priori bounds on $\Phi^{0,\infty}_\varepsilon$, $\Phi^{0,\text{loc}}_\varepsilon$ and $u_\alpha$, we get directly in view of the examples page 9 that

$$\lim_{\varepsilon \to 0} \|E^1_\varepsilon\|_{x^0} = 0.$$

Next let us turn to $E^2_\varepsilon$. We shall follow the method of [16], and in particular the following lemma will be very useful.

**Lemma 5.4.** There is a constant $C$ such that for all functions $a$ and $b$, we have

$$\|ab\|_{B^1} \leq C\|a\|_{B^1}\|b(\cdot, 0)\|_{B^2_{2,1}(\mathbb{R}^2)} + C\|x_3 a\|_{B^1}\|\partial_3 b\|_{B^1}.$$

We postpone the proof of that lemma. Let us apply it to estimate $E^2_\varepsilon$. We write, as in the case of $E^1_\varepsilon$ and defining $u_\varepsilon^{\text{loc}} \overset{\text{def}}{=} \theta_\eta u_\alpha$,

$$\|E^2_\varepsilon\|_{x^0} \lesssim \|u_\varepsilon^{\text{loc}}\|_{L^2(\mathbb{R}^+;B^1)} \|\Phi^{0,\text{loc}}_\varepsilon(\cdot, 0)\|_{L^2(\mathbb{R}^+;B^1_{2,1}(\mathbb{R}^2))} + \|x_3 u_\varepsilon^{\text{loc}}\|_{L^2(\mathbb{R}^+;B^1)} \|\partial_3 \Phi^{0,\text{loc}}_\varepsilon\|_{L^2(\mathbb{R}^+;B^1)}.$$

Thanks to (5.19) as well as Inequality (2.13) of Theorem 4, we obtain

$$\lim_{\varepsilon \to 0} \|E^2_\varepsilon\|_{x^0} = 0.$$

This proves (5.21), hence Theorem 5. \qed

**Proof of Lemma 5.4.** This is essentially Lemma 3.3 of [16], we recall the proof for the convenience of the reader. Let us decompose $b$ in the following way:

$$b(x_h, x_3) = b(x_h, 0) + \int_{0}^{x_3} \partial_3 b(x_h, y_3) dy_3.$$

Laws of product give directly on the one hand

$$\|a(b_{x_3=0})\|_{B^1} \lesssim \|a\|_{B^1}\|b_{x_3=0}\|_{B^2_{2,1}(\mathbb{R}^2)}.$$
On the other hand, observe that
\[
\|a(\cdot, x_3) \int_0^{x_3} \partial_3 b(\cdot, y_3) dy_3\|_{B^{1,1}_2(\mathbb{R}^2)} \lesssim \|a(\cdot, x_3)\|_{B^{1,1}_2(\mathbb{R}^2)} \int_0^{x_3} \|\partial_3 b(\cdot, y_3)\|_{B^{1,1}_2(\mathbb{R}^2)} dy_3
\]
\[
\leq C|x_3|\|a(\cdot, x_3)\|_{B^{1,1}_2(\mathbb{R}^2)} \|\partial_3 b\|_{L^p(\mathbb{R}^2)} (B^{1,1}_2(\mathbb{R}^2)).
\]
The result follows. \qed

6. Some results in anisotropic Besov spaces

6.1. Anisotropic Besov spaces. In this section we first recall some basic facts about (anisotropic) Littlewood-Paley theory and then we prove some basic properties of anisotropic Besov spaces introduced in Definition 1.4, in particular laws of product which have used all along this text.

First let us recall the following estimates which are the generalization of the classical Bernstein’s inequalities in the context of anisotropic Littlewood-Paley theory (see Lemma 6.10 of [2]) describing the action of horizontal and vertical derivatives on frequency localized distributions:

Lemma 6.1. Let \((p_1, p_2, r)\) be in \([1, \infty]^3\) such that \(p_1\) is less than or equal to \(p_2\). Let \(m\) be a real number and \(\sigma_h\) (resp. \(\sigma_v\)) a smooth homogeneous function of degree \(m\) on \(\mathbb{R}^2\) (resp. \(\mathbb{R}\)). Then we have
\[
\|\sigma_h(D_h)\Delta_k^h f\|_{L_{p_1}^1 L_{p_2}^2} \lesssim 2^{k(m+\frac{1}{p_1}-\frac{1}{p_2})}\|\Delta_k^h f\|_{L_{p_1}^1 L_{p_2}^2} \quad \text{and}
\]
\[
\|\sigma_v(D_3)\Delta_k^v f\|_{L_{p_1}^1 L_{p_2}^2} \lesssim 2^{j(m+\frac{1}{p_1}-\frac{1}{p_2})}\|\Delta_j^v f\|_{L_{p_1}^1 L_{p_2}^2}.
\]

Now let us recall the action of the heat flow on frequency localized distributions in an anisotropic context.

Lemma 6.2. For any \(p\) in \([1, \infty]\), we have
\[
\|e^{t\Delta} \Delta_k^h \Delta_j^v f\|_{L_p^1} \lesssim e^{-ct(2^{2k}+2^{2j})}\|\Delta_k^h \Delta_j^v f\|_{L_p^1}
\]
\[
\|e^{t\Delta_h} \Delta_k^h \Delta_j^v f\|_{L_p^1} \lesssim e^{-ct2^{2k}}\|\Delta_k^h \Delta_j^v f\|_{L_p^1}
\]
and
\[
\|e^{t\Delta_v} \Delta_k^h \Delta_j^v f\|_{L_p^1} \lesssim e^{-ct2^{2j}}\|\Delta_k^h \Delta_j^v f\|_{L_p^1}.
\]
The proof of this lemma consists in a straightforward (omitted) modification of the proof of Lemma 2.3 of [2].

The following result was mentioned in the introduction of this article (see page 9). We refer to (4.2) and to Definition 2.4 for notations.

Lemma 6.3. The spaces \(L^2(\mathbb{R}^+; B^{s-1,s'})\), \(L^2(\mathbb{R}^+; B^{s,s'-1})\) are \(\mathcal{F}^s,s'\) spaces, as well as the spaces \(L^1(\mathbb{R}^+; B^{s,s'})\) and \(L^1(\mathbb{R}^+; B^{s+1,s'-1})\).

Proof. Let \(f\) be a function in \(L^2(\mathbb{R}^+; B^{s-1,s'})\), and let us show that
\[
\|L_0 f\|_{\mathcal{F}^s,s'} \lesssim \|f\|_{L^2(\mathbb{R}^+; B^{s-1,s'})}.
\]
Applying Lemma 6.2 gives
\[
\|\Delta_k^h \Delta_j^v L_0 f\|_{L^2} \lesssim \int_0^t e^{-ct(2^{2k}+2^{2j})}\|\Delta_k^h \Delta_j^v f(t')\|_{L^2} dt'.
\]
so there is a sequence \(d_{j,k}(t')\) in the sphere of \(L^1(\mathbb{Z} \times \mathbb{Z}; L^2(\mathbb{R}^+))\) such that
\[
\|\Delta_k^h \Delta_j^v L_0 f\|_{L^2} \lesssim \|f\|_{L^2(\mathbb{R}^+; B^{s-1,s'})} 2^{-k(s-1)} 2^{-js'} \int_0^t e^{-ct(2^{2k}+2^{2j})} d_{j,k}(t') dt'.
\]
Young’s inequality in time therefore gives
\[ \| \Delta^h_k \Delta^h_j L_0 f \|_{L^2(\mathbb{R}^+;L^2)} \lesssim \| f \|_{L^2(\mathbb{R}^+,\mathcal{B}^{s-1,s'})} 2^{-k(s-1)-j's'} d_{j,k}, \]
where \( d_{j,k} \) is a generic sequence in the sphere of \( \ell^1(\mathbb{Z} \times \mathbb{Z}) \), which proves the result in the case when \( f \) belongs to \( \tilde{L}^2(\mathbb{R}^+,\mathcal{B}^{s-1,s'}) \). The argument is similar in the other cases. \( \square \)

Now let us study laws of product.

**Proposition 6.4.** Let \( (\sigma, \sigma', \tilde{\sigma}, \tilde{\sigma}') \) be in \([-1,1]^4\) such that
\[ \sigma + \sigma' = \tilde{\sigma} + \tilde{\sigma}' \overset{\text{def}}{=} \sigma > 0. \]
If \( s' \) is in \([-1/2,1/2]\], we have
\[ \|ab\|_{\mathcal{B}^{s' - 1,s'}} \lesssim \|a\|_{\mathcal{B}^{s'}} \|b\|_{\mathcal{B}^{s',s'}}. \]
If \( s' \) is greater than \( 1/2 \), then we have
\[ \|ab\|_{\mathcal{B}^{s' - 1,s'}} \lesssim \|a\|_{\mathcal{B}^{s'}} \|b\|_{\mathcal{B}^{s',s'}} + \|a\|_{\mathcal{B}^{s',s'}} \|b\|_{\mathcal{B}^s}. \]

**Proof.** Let us use Bony’s decomposition in the vertical variable introduced in (4.33), namely
\[ ab = T^\alpha_a b + T^\alpha_b a + R^\alpha(a,b). \]
The first two terms are almost the same (up to the interchanging of \( a \) and \( b \)). Thus we only estimate \( T^\alpha_a b \). This is done through the following lemma.

**Lemma 6.5.** Let us consider \( (\sigma, \sigma') \) in \([-1,1]^2\) such that \( \sigma + \sigma' \) is positive and \( (s,s') \) in \( \mathbb{R}^2 \). If \( s \) is less than or equal to \( 1/2 \), we have
\[ \|T^\alpha_a b\|_{\mathcal{B}^{\sigma + \sigma' - 1,s,s'}} \lesssim \|a\|_{\mathcal{B}^{s'}} \|b\|_{\mathcal{B}^{s',s'}}. \]
If \( s + s' \) is positive, we have
\[ \|R^\alpha(a,b)\|_{\mathcal{B}^{\sigma + \sigma' - 1,s,s'}} \lesssim \|a\|_{\mathcal{B}^{s'}} \|b\|_{\mathcal{B}^{s',s'}}. \]

**Proof.** Let us use Bony’s decomposition of \( T^\alpha_a b \) with respect to the horizontal variable.
\[ T^\alpha_a b = T^\alpha T^h_a b + T^\alpha \tilde{T}^h_b a + T^\alpha R^h(a,b) \]
with
\[ T^\alpha T^h_a b = \sum_{j,k} S^h_{j-1,k-1} a \Delta^h_j \Delta^h_k b, \]
\[ T^\alpha \tilde{T}^h_b a = \sum_{j,k} S^h_{j-1} \Delta^h_k b \Delta^h_j S^h_{k-1} b \]
and
\[ T^\alpha R^h(a,b) = \sum_{j,k} S^h_{j-1} \Delta^h_{k-j} a \Delta^h_j \Delta^h_k b. \]
Following the same lines as in the proof of Proposition 4.1 (see the lines following decomposition (4.18)) we have for some large enough integer \( N_0 \)
\[ \Delta^h_j \Delta^h_k T^\alpha T^h_a b = \sum_{|j'-j| \leq N_0} \sum_{|k'-k| \leq N_0} \Delta^h_{j'} \Delta^h_{k'} (S^h_{j'-1} S^h_{k'-1} a \Delta^h_j \Delta^h_k b). \]
By definition of the $B^{\sigma,s}$ norms, this gives
\[
2^{j(s+s'-\frac{1}{2})+k(\sigma+\sigma'-1)}\|\Delta_j^h \Delta_k^b T^a T^h b\|_{L^2} \lesssim \sum_{|j'-j| \leq N_0} 2^{-(j'-j)(s+s'-\frac{1}{2})-(k'-k)(\sigma+\sigma'-1)} \times 2^{j'(s-\frac{1}{2})+k'(\sigma-1)} \|S_{j'-1}^h S_{k'-1}^h a\|_{L^\infty} \times 2^{j'(s'+s'-(k'-k)(\sigma+\sigma'-1)) \|\Delta_j^h \Delta_{k'}^h b\|_{L^2} \times d_{j',k'} 2^{j'(s-\frac{1}{2})+k'(\sigma-1)} \|S_{j'-1}^h S_{k'-1}^h a\|_{L^\infty}
\]
where, as in all that follows, $(d_{j,k})_{(j,k) \in \mathbb{Z}^2}$ lies on the sphere of $\ell^1(\mathbb{Z}^2)$. Using anisotropic Bernstein inequalities given by Lemma 6.1 and the definition of the $B^{\sigma,s}$ norm, we get
\[
2^{j'(s-\frac{1}{2})+k'(\sigma-1)} \|S_{j'-1}^h S_{k'-1}^h a\|_{L^\infty} \lesssim \sum_{j'' \leq j'} 2^{j''(s-\frac{1}{2})+(k'-k''(\sigma-1))} \|\Delta_j^h \Delta_{k''} a\|_{L^\infty} \times 2^{j''(s''-(k'-k'')(\sigma-1))} \|S_{j''-1}^h S_{k''-1}^h a\|_{L^\infty} \times d_{j'',k''} 2^{j''(s''-(k'-k'')(\sigma-1))} \|S_{j''-1}^h S_{k''-1}^h a\|_{L^\infty}
\]
As $s \leq 1/2$ and $\sigma \leq 1$, we get
\[
2^{j'(s-\frac{1}{2})+k'(\sigma-1)} \|S_{j'-1}^h S_{k'-1}^h a\|_{L^\infty} \lesssim \|a\|_{B^{\sigma,s}}.
\]
Young's inequality on series leads to
\[
(6.5) \quad \|T^a T^h b\|_{B^{\sigma+s'-\frac{1}{2}}} \lesssim \|b\|_{B^{\sigma',s'}} \|a\|_{B^{\sigma,s}}.
\]
Following exactly the same lines, we can prove
\[
(6.6) \quad \|T^a T^h b\|_{B^{\sigma+s'-\frac{1}{2}}} \lesssim \|b\|_{B^{\sigma',s'}} \|a\|_{B^{\sigma,s}}.
\]
The estimate of $T^a T^h b$ is a little bit different. Let us write that
\[
\Delta_j^h \Delta_k^h T^a T^h b = \sum_{j',k' \leq j} \Delta_j^h \Delta_k^h (S_{j'-1}^h S_{k'-1}^h a \Delta_j^h \Delta_k^h b).
\]
Arguing as in the proof of Proposition 4.1 we have for some large enough integer $N_0$
\[
\Delta_j^h \Delta_k^h T^a T^h b = \sum_{|j'-j| \leq N_0} \sum_{k' \geq k-N_0} \Delta_j^h \Delta_k^h (S_{j'-1}^h S_{k'-1}^h a \Delta_j^h \Delta_k^h b).
\]
Anisotropic Bernstein inequalities given by Lemma 6.1 imply that
\[
\|\Delta_j^h \Delta_k^h (S_{j'-1}^h S_{k'-1}^h a \Delta_j^h \Delta_k^h b)\|_{L^2} \lesssim 2^k \|S_{j'-1}^h \Delta_k^h a \Delta_j^h b\|_{L^k(L^2)} \lesssim 2^k \|S_{j'-1}^h \Delta_k^h a\|_{L^k(L^\infty)} \|\Delta_j^h \Delta_k^h b\|_{L^2}.
\]
Thus we infer that
\[ 2^{k(\sigma+\sigma')-j(s+s'-\frac{1}{2})} \| \Delta^v_y \Delta^h_k T^v R^h(a, b) \|_{L^2} \lesssim \sum_{|j'-j| \leq N_0-1, k' \geq k-N_0} \sum_{\ell \leq 1} 2^{-(k'-k)(\sigma+\sigma')} \]
\[ \times 2^{j'(s-\frac{1}{2})+k'\sigma} \| S^v_{j'} \Delta^h_{k'-\ell} a \|_{L^2_k(L^\infty)} 2^{k'\sigma-j's'} \| \Delta^v_y \Delta^h_{k'} b \|_{L^2} . \]

Using again anisotropic Bernstein inequalities and by definition of the $B^{\sigma,s}$ norm, we get
\[ 2^{j'(s-\frac{1}{2})+k'\sigma} \| S^v_{j'} \Delta^h_{k'-\ell} a \|_{L^2_k(L^\infty)} \lesssim \sum_{j'' \leq j' - 2} 2^{j''} 2^{j''+k'\sigma} \| \Delta^v_y \Delta^h_{k'-\ell} a \|_{L^2} \]
\[ \lesssim \| a \|_{B^{\sigma,s}} \sum_{j'' \leq j' - 2} 2^{j''} d_{j'',k''}. \]

As $s$ is less than or equal to $1/2$, we get
\[ 2^{j'(s-\frac{1}{2})+k'\sigma} \| S^v_{j'} \Delta^h_{k'-\ell} a \|_{L^2_k(L^\infty)} \leq \| a \|_{B^{\sigma,s}}. \]

By definition of the $B^{\sigma',s'}$ norm, this gives
\[ 2^{k(\sigma+\sigma')-j(s+s'-\frac{1}{2})} \| \Delta^v_y \Delta^h_k T^v R^h(a, b) \|_{L^2} \lesssim \| a \|_{B^{\sigma,s}} \| b \|_{B^{\sigma',s'}} \]
\[ \times \sum_{|j'-j| \leq N_0-1, k' \geq k-N_0} \sum_{\ell \leq 1} 2^{-(k'-k)(\sigma+\sigma')-(j'-j)(s+s'-\frac{1}{2})} d_{j'',k''}. \]

As $\sigma + \sigma'$ is positive, we get that
\[ 2^{k(\sigma+\sigma')-j(s+s'-\frac{1}{2})} \| \Delta^v_y \Delta^h_k T^v R^h(a, b) \|_{L^2} \lesssim d_{j,k} \| a \|_{B^{\sigma,s}} \| b \|_{B^{\sigma',s'}}. \]

Together with (6.5) and (6.6) this concludes the proof of Inequality (6.3).

In order to prove Inequality (6.4), let us use again the horizontal Bony decomposition. Defining
\[ \tilde{\Delta}_y^v (\text{resp. } \tilde{\Delta}_k^h) = \sum_{\ell = -1}^{1} \Delta^v_{y-\ell} (\text{resp. } \Delta^h_{k-\ell}) \]
let us write that
\[ R^v_a b = R^v T^h_a b + R^v T^h b + R^v R^h(a, b) \quad \text{with} \]
\[ R^v T^h_a b \equiv \sum_{j,k} \tilde{\Delta}_j^v \Delta^h_{k-1} a \Delta_j^y \Delta^h_k b \quad \text{and} \]
\[ R^v R^h(a, b) \equiv \sum_{j,k} \tilde{\Delta}_j^v \tilde{\Delta}_k^h a \Delta_j^y \Delta^h_k b. \]

We have for $N_0$ a large enough integer,
\[ \Delta_j^y \Delta^h_k R^v T^h_a b = \sum_{j' \geq 1-N_0, \ell \leq N_0} \Delta_j^v \Delta^h_{k-\ell} \tilde{\Delta}_j^v S^h_{k'-1} a \Delta_j^y \Delta^h_{k'} b. \]
Using anisotropic Bernstein inequalities, this gives by definition of the $B^{\sigma,s'}$ norm,

$$2^{j(s + s' - \frac{1}{2}) + k(\sigma + \sigma' - 1)}\| \Delta_j \Delta_k^h R^b T^h_a b \|_{L^2} \lesssim 2^{j(s + s') + k(\sigma + \sigma' - 1)}\| \Delta_j^h \Delta_k^h R^b T^h_a b \|_{L^2_{\infty}(L^2)}$$

$$\lesssim \sum_{j' \geq j - N_0} 2^{-(j' - j)(s + s') - (k' - k)(\sigma + \sigma' - 1)}$$

$$\times 2^{j's + k'(\sigma - 1)}\| \tilde{\Delta}_{j'}^h S_{k'}^h a \|_{L^\infty_{\infty}(L^2)} 2^{j's + k'\sigma'}\| \Delta_{j'}^h \Delta_k^h b \|_{L^2}$$

$$\lesssim \| b \|_{B^{\sigma,s'}} \sum_{j' \geq j - N_0} 2^{-(j' - j)(s + s')}$$

$$\times d_{j', k'} 2^{j's + k'(\sigma - 1)}\| \tilde{\Delta}_{j'}^h S_{k'}^h a \|_{L^\infty_{\infty}(L^2)}.$$

Using anisotropic Bernstein inequalities and the definition of the $B^{\sigma,s}$ norm, we get

$$2^{j's + k'(\sigma - 1)}\| \tilde{\Delta}_{j'}^h S_{k'}^h a \|_{L^\infty_{\infty}(L^2)} \lesssim \sum_{j' \leq j' + 1} 2^{(k' - k')}(\sigma - 1)$$

$$\times 2^{j's + k'(\sigma - 1)}\| \Delta_{j'}^h \Delta_k^h a \|_{L^\infty_{\infty}(L^2)}$$

$$\lesssim \sum_{j' \leq j' + 1} 2^{(k' - k')}(\sigma - 1) 2^{j's + k'\sigma'}\| \Delta_{j'}^h \Delta_k^h a \|_{L^2}$$

$$\lesssim \| a \|_{B^{\sigma,s}} \sum_{j' \leq j' + 1} 2^{(k' - k')}(\sigma - 1) d_{j', k'}.$$

As $\sigma$ is less than or equal to 1, we get

$$2^{j'(s - \frac{1}{2}) + k'(\sigma - 1)}\| \tilde{\Delta}_{j'}^h S_{k'}^h a \|_{L^\infty} \lesssim \| a \|_{B^{\sigma,s}}.$$

Young’s inequality on series leads to

$$2^{j'(s - \frac{1}{2}) + k'(\sigma - 1)}\| \tilde{\Delta}_{j'}^h S_{k'}^h a \|_{L^\infty} \lesssim \| a \|_{B^{\sigma,s}} \| b \|_{B^{\sigma,s'}}.$$

By symmetry, we get

$$2^{j'(s - \frac{1}{2}) + k'(\sigma - 1)}\| \tilde{\Delta}_{j'}^h S_{k'}^h a \|_{B^{\sigma,s - 1, s + s' - \frac{1}{2}}} \lesssim \| a \|_{B^{\sigma,s}} \| b \|_{B^{\sigma,s'}}.$$

The estimate of $R^c R^b (a, b)$ is a little bit different. Arguing as in the proof of Proposition 4.1, we obtain

$$\Delta_j^h \Delta_k^h R^c R^b (a, b) = \sum_{j' \geq j - N_0 \atop k' < k - N_0} \Delta_j^h \Delta_k^h (\tilde{\Delta}_{j'}^h \tilde{\Delta}_{k'}^h a \Delta_j^h \Delta_k^h b).$$

Anisotropic Bernstein inequalities given by Lemma 6.1 imply that

$$\| \Delta_j^h \Delta_k^h (\tilde{\Delta}_{j'}^h \tilde{\Delta}_{k'}^h a \Delta_j^h \Delta_k^h b) \|_{L^2} \lesssim 2^{j' + k} \| \tilde{\Delta}_{j'}^h \tilde{\Delta}_{k'}^h a \|_{L^2} \| \Delta_j^h \Delta_k^h b \|_{L^2}$$

$$\lesssim 2^{j' + k} \| \Delta_j^h \Delta_k^h a \|_{L^2} \| \Delta_j^h \Delta_k^h b \|_{L^2}.$$
By definition of the $B^{s',s'}$ norm, this gives
\[
2^{k(s+\sigma'-1)+j(s+s'-\frac{3}{2})}\|\Delta_j^\nu \Delta_k^h R^h(a, b)\|_{L^2} \lesssim \|a\|_{B^{s'}} \|b\|_{B^{s',s'}} \times \sum_{j'\geq j-N_0 \atop k'\geq k-N_0} 2^{-(k'-k)(\sigma+\sigma')-(j'-j)(s+s')} d_{j',k'}.
\]

As $\sigma + \sigma'$ and $s + s'$ are positive, we get that
\[
2^{k(s+\sigma'-1)+j(s+s'-\frac{3}{2})}\|\Delta_j^\nu \Delta_k^h R^h(a, b)\|_{L^2} \lesssim d_{j,k} \|a\|_{B^{s'}} \|b\|_{B^{s',s'}}.
\]

Together with (6.7) and (6.8) this concludes the proof of Inequality (6.3).

In order to conclude the proof of Proposition 6.4, it is enough to apply Lemma 6.5 with $(\sigma, \sigma')$ to $T^h_a b$ and with $(\tilde{\sigma}', \tilde{\sigma})$ to $T^h_a$. □

Now let us prove laws of product in the case when one of the functions does not depend on the vertical variable $x_3$. We have the following proposition.

**Proposition 6.6.** Let $a$ be in $B^{s_1}_1(\mathbb{R}^2)$ and $b$ in $B^{s',s'}$ with $(s, \sigma)$ in $]-1,1[^2$ such that $s + \sigma$ is positive and $s'$ greater than or equal to 1/2. We have
\[
\|ab\|_{B^{s+s'-1,s'}} \lesssim \|a\|_{B^{s_1}_1(\mathbb{R}^2)} \|b\|_{B^{s',s'}}.
\]

**Proof.** Using Bony’s decomposition in the horizontal variable gives
\[
ab = T^h_a b + T^h b a + R^h(a, b).
\]

As $a$ does not depend on the vertical variable, we have
\[
\Delta_j^\nu T^h_a b = T^h_a \Delta_j^\nu b, \quad \Delta_j^\nu T^h b a = T^h_{\Delta_j^\nu} a \quad \text{and} \quad \Delta_j^\nu R^h(a, b) = R^h(a, \Delta_j^\nu b).
\]

Then, the result follows from the classical proofs of mappings of paraproduct and remainder operators (see for instance Theorem 2.47 and Theorem 2.52 of [2]). We give a short sketch of the proof for the reader’s convenience in the case of $T^h$. Let us write
\[
2^{k(s+\sigma'-1)+j's'}\|\Delta_j^\nu \Delta_k^h T^h_a b\|_{L^2} \lesssim \sum_{|k'-k|\leq N_0} 2^{k'(\sigma-1)} \|S^h_{k'-1} a\|_{L^\infty} \sum_{|k'-k|\leq N_0} 2^{k'(s+s')} \|\Delta_j^\nu \Delta_k^h b\|_{L^2} \lesssim \|b\|_{B^{s',s'}} \sum_{|k'-k|\leq N_0} 2^{k'(\sigma-1)} \|S^h_{k'-1} a\|_{L^\infty} d_{k',s'}.
\]

Bernstein inequalities imply that
\[
2^{-k(1-\sigma)} \|S^h_{k-1} a\|_{L^\infty} \lesssim \sum_{k'\leq k-1} 2^{(k'-k)(1-\sigma)} \|\Delta_k^h a\|_{L^2} \lesssim \|a\|_{B^{s_1}_1(\mathbb{R}^2)} \sum_{k'\leq k-1} 2^{(k'-k)(1-\sigma)} d_{k'}.
\]

This gives, with no restriction on the parameter $s$ and with $\sigma$ less than or equal to 1 and $s'$ greater than or equal to 1/2,
\[
\|T^h_a b\|_{B^{s+s'-1,s'}} \lesssim \|a\|_{B^{s_1}_1(\mathbb{R}^2)} \|b\|_{B^{s',s'}}.
\]

For the other (horizontal) paraproduct term, let us write
\[
2^{k(s+\sigma'-1)+j's'}\|\Delta_j^\nu \Delta_k^h T^h b a\|_{L^2} \lesssim \sum_{|k'-k|\leq N_0} 2^{k'(s-1)+j's'} \|S^h_{k'-1} \Delta_j^\nu b\|_{L^\infty(L^2)} 2^{k'(\sigma')} \|\Delta_k^h a\|_{L^2} \lesssim \|a\|_{B^{s_1}_1(\mathbb{R}^2)} \sum_{|k'-k|\leq N_0} 2^{k'(s-1)+j's'} \|S^h_{k'-1} \Delta_j^\nu b\|_{L^\infty(L^2)} d_{k'}.
\]
Using Lemma 6.1, we get
\[
2^{-k(1-s)+js'}\|S^h_{k-1}\Delta y b\|_{L^\infty_h(L^2)} \lesssim \sum_{k' \leq k-1} 2^{(k'-k)(1-s)\pm js'}\|\Delta^h_{k'}\Delta^y b\|_{L^\infty_h(L^2)}
\]
\[
\lesssim \sum_{k' \leq k-1} 2^{(k'-k)(1-s)+j} \|\Delta^h_{k'}\Delta^y b\|_{L^2}.
\]
By definition of the \(B^{s,s'}\) norm and using the fact that \(s \leq 1\), we infer that
\[
2^{(k'-k)(1-s)}\|S^h_{k-1}\Delta y b\|_{L^\infty_h(L^2)} \lesssim d_j \|b\|_{B^{s,s'}}.
\]
Together with (6.11), this gives
\[
(6.12) \quad \|T^h_b a\|_{B^{s,s'-1,s'}} \lesssim \|a\|_{B^s_{2,1}(\mathbb{R}^2)} \|b\|_{B^{s,s'}}.
\]
Now let us study the (horizontal) remainder term. Using Lemma 6.1, we let write that
\[
2^{k(s+\sigma-1)+js'} \|\Delta^y b R^h(a, b)\|_{L^2} \lesssim 2^{k(s+\sigma)\pm js'} \|\Delta^y b R^h(a, b)\|_{L^2(L^2)}
\]
\[
\lesssim \sum_{k' \geq k-N_0} 2^{-(k'-k)(s+\sigma)+2k's} \|\Delta^k b\|_{L^2_h} \|\Delta^y b\|_{L^2}.
\]
By definition of the \(B^s_{2,1}(\mathbb{R}^2)\) and \(B^{s,s'}\) norms, we get
\[
2^{k(s+\sigma-1)+js'} \|\Delta^y b R^h(a, b)\|_{L^2} \lesssim \|a\|_{B^s_{2,1}(\mathbb{R}^2)} \|b\|_{B^{s,s'}} \sum_{k' \geq k-N_0} 2^{-(k'-k)(s+\sigma)} d_{k'}.
\]
Together with (6.10) and (6.12), this gives the result thanks to the fact that \(s+\sigma\) is positive. Proposition 6.6 is proved. \(\square\)

6.2. **Proof of Proposition 2.5.** The proof of Proposition 2.5 is reminiscent of that of Lemma 4.6, and we shall be using arguments of that proof here.

Let us recall that we want to prove that if \(U\) is in \(L^2(\mathbb{R}^+; B^1)\), if \(u_0\) is in \(B^0\) and \(f\) in \(\mathcal{F}^0\), such that
\[
(6.13) \quad \|u_0\|_{B^0} + \|f\|_{\mathcal{F}^0} \leq \frac{1}{C_0} \exp\left(-C_0 \int_0^\infty \|U(t)\|^2_{B^1} dt\right),
\]
then the problem
\[
(NSU) \quad \begin{cases}
\partial_t u + \text{div}(u \otimes u + u \otimes U + U \otimes u) - \Delta u = -\nabla p + f \\
\text{div} u = 0 \text{ and } u|_{t=0} = u_0
\end{cases}
\]
has a unique global solution in \(L^2(\mathbb{R}^+; B^1)\) which satisfies
\[
\|u\|_{L^2(\mathbb{R}^+; B^1)} \lesssim \|u_0\|_{B^0} + \|f\|_{\mathcal{F}^0}.
\]
Let us first prove that the system \((NSU)\) has a unique solution in \(L^2([0,T]; B^1)\) for some small enough \(T\). Let us introduce some bilinear operators which distinguish the horizontal derivatives from the vertical one, namely for \(\ell\) belonging to \(\{1, 2, 3\}\),
\[
Q_h(u, w)^\ell = \text{div}_h(w^\ell u^h) \quad \text{and} \quad Q_v(u, w)^\ell = \partial_3(w^\ell u^3).
\]
Then we define \(B_{h,\tau} \overset{\text{def}}{=} L_T Q_h\) and \(B_{v,\tau} \overset{\text{def}}{=} L_T Q_v\) where \(L_T\) is defined in Definition 2.4. It is obvious that solving \((NSU)\) is equivalent to solving
\[
u = e^{t\Delta} u_0 + L_0 f + B_{h,0}(u, u) + B_{v,0}(u, u) + B_{h,0}(U, u) + B_{v,0}(U, u) + B_{h,0}(u, U) + B_{v,0}(u, U).
\]
Following an idea introduced by G. Gui, J. Huang and P. Zhang in [26], let us define
\[
L_0 \overset{\text{def}}{=} e^{t\Delta} u_0 + L_0 f
\]
and look for the solution $u$ under the form $u = L_0 + \rho$. As the horizontal and the vertical derivative are not treated exactly in the same way, let us decompose $\rho$ into $\rho_h + \rho_v$ with

$$
\rho_h \overset{\text{def}}{=} B_{h,0}(\rho, \rho) + B_{h,0}(L_0 + U, \rho) + B_{h,0}(\rho, L_0 + U) + F_h, \\
\rho_v \overset{\text{def}}{=} B_{v,0}(\rho, \rho) + B_{v,0}(L_0 + U, \rho) + B_{v,0}(\rho, L_0 + U) + F_v
$$

(6.15)

The main lemma is the following.

**Lemma 6.7.** For any subinterval $I = [a, b]$ of $\mathbb{R}^+$, we have

$$
\|B_{h,a}(u, w)\|_{L^\infty(I; B^0)} + \|B_{h,a}(u, w)\|_{L^1(I; B^1 \cap B^1, 1/2)} + \|B_{v,a}(u, w)\|_{L^\infty(I; B^1, 1/2)} + \|B_{v,a}(u, w)\|_{L^1(I; B^2 \cap B^1, 1/2)} \\
\lesssim \|u\|_{L^2(I; B^1)}\|w\|_{L^2(I; B^1)}
$$

Proof. As $B^1$ is an algebra and using Lemma 6.1, we get

$$
Q_{j,k}(u, w)(t) \overset{\text{def}}{=} 2^j \|\Delta^j_h \Delta^k_h Q_h(u, w)(t)\|_{L^2} + 2^k - \frac{1}{2} \|\Delta^j_h \Delta^k_h Q_v(u, w)(t)\|_{L^2} \\
\lesssim d_{j,k}(t)\|u(t)\|_{B^1}\|w(t)\|_{B^1},
$$

where as usual we have denoted by $d_{j,k}(t)$ a sequence in the unit sphere of $\ell^1(\mathbb{Z}^2)$ for each $t$. Lemma 6.2 implies that, for any $t$ in $[a, b]$, we have with the notation of Definition 2.4

$$
\mathcal{L}_{a,j,k}(u, w)(t) \overset{\text{def}}{=} 2^j \|L_a \Delta^j_h \Delta^k_h Q_h(u, w)(t)\|_{L^2} + 2^k - \frac{1}{2} \|L_a \Delta^j_h \Delta^k_h Q_v(u, w)(t)\|_{L^2} \\
\lesssim \int_a^t d_{j,k}(t') e^{-c2^{2k+2}((t-t')^2)}\|u(t')\|_{B^1}\|w(t')\|_{B^1} dt'.
$$

Convolution inequalities imply that

$$
\|\mathcal{L}_{a,j,k}(u, w)\|_{L^\infty(I; L^2)} + c2^{2k+2}\|\mathcal{L}_{a,j,k}(u, w)\|_{L^1(I; L^2)} \lesssim \int_I d_{j,k}(t)\|u(t)\|_{B^1}\|w(t)\|_{B^1} dt.
$$

This concludes the proof of the lemma. \hfill \Box

**Continuation of the proof of Proposition 2.5.** As we have by interpolation,

$$
\|a\|_{B^1} \leq \|a\|_{B^0}^{1/2}\|a\|_{B^2}^{1/2} \quad \text{and} \quad \|a\|_{B^1} \leq \|a\|_{B^{1,-1/2}} \|a\|_{B^{1,1/2}},
$$

we infer that the bilinear maps $B_{h,a}$ and $B_{v,a}$ map $L^2(I; B^1) \times L^2(I; B^1)$ into $L^2(I; B^1)$. A classical fixed point theorem implies the local wellposedness in the space $L^2(I; B^1)$ for initial data in the space $B^0 + B^{1,-1/2}$.

Now let us extend this (unique) solution to the whole interval $\mathbb{R}^+$. Given $\varepsilon > 0$, to be chosen small enough later on, let us define $T_\varepsilon$ as

$$
T_\varepsilon \overset{\text{def}}{=} \sup\{T < T^*, \|\rho\|_{L^2([0,T]; B^1)} \leq \varepsilon\}.
$$

As in the proof of Lemma 4.6, let us consider the increasing sequence $(T_m)_{0 \leq m \leq M}$ such that $T_0 = 0$, $T_M = \infty$ and for some given $c_0$ which will be chosen later on

$$
\forall m < M - 1, \int_{T_m}^{T_{m+1}} \|U(t)\|_{B^1}^2 dt = c_0 \quad \text{and} \quad \int_{T_{M-1}}^{\infty} \|U(t)\|_{B^1}^2 dt \leq c_0.
$$

(6.18)
Let us recall that from (4.31), we have
\[(6.19) \quad M \leq \frac{1}{C_0} \int_0^\infty \|U(t)\|^2_{B_1} \, dt.\]

Let us define
\[(6.20) \quad \mathcal{N}_0 \overset{\text{def}}{=} \|\mathcal{L}_0\|_{L^2(\mathbb{R}^+,B^1)}^2 + \|\mathcal{L}_0\|_{L^2(\mathbb{R}^+,B^1)} \|U\|_{L^2(\mathbb{R}^+,B^1)}.\]

Let us consider any \(m\) such that \(T_m < T_\varepsilon\). Lemma 6.7 implies that for any time \(T\) less than \(\min\{T_{m+1};T_\varepsilon\}\), we have
\[
\mathcal{R}_m(T) \overset{\text{def}}{=} \|\rho_h\|_{L^\infty([T_m,T];B^0)} + \|\rho_h\|_{L^1([T_m,T];B^2)} \leq C\|\rho_h(T_m)\|_{B^0} + C\mathcal{N}_0
\]
\[
+ C\left(\|\rho_h\|_{L^2([T_m,T];B^1)} + \|\mathcal{L}_0 + U\|_{L^2([T_m,T];B^1)}\right)\|\rho_h\|_{L^2([T_m,T];B^1)}
\]
\[
\leq C\|\rho_h(T_m)\|_{B^0} + C\mathcal{N}_0
\]
\[
+ C\left(\varepsilon + \|\mathcal{L}_0\|_{L^2([T_m,T];B^1)} + c_0\|\rho_h\|_{L^2([T_m,T];B^1)}\right).
\]

Choosing \(C_0\) large enough in (6.13), \(c_0\) small enough in (6.18), and \(\varepsilon\) small enough in (6.17) implies that
\[(6.21) \quad \mathcal{R}_m(T) \leq C\|\rho_h(T_m)\|_{B^0} + C\mathcal{N}_0 + \frac{1}{2}\|\rho_h\|_{L^2([T_m,T];B^1)}.
\]

Exactly along the same lines, we get
\[
\mathcal{R}_m(T) \overset{\text{def}}{=} \|\rho_v\|_{L^\infty([T_m,T];B^1,-\frac{1}{2})} + \|\rho_v\|_{L^1([T_m,T];B^3\frac{1}{2})} \leq C\|\rho_v(T_m)\|_{B^1,-\frac{1}{2}} + C\mathcal{N}_0 + \frac{1}{2}\|\rho_v\|_{L^2([T_m,T];B^1)}.
\]

We deduce that
\[
\|\rho_h\|_{L^2([T_m,T];B^1)} \leq C\left(\|\rho_h(T_m)\|_{B^0} + \mathcal{N}_0\right) \quad \text{and} \quad \|\rho_v\|_{L^2([T_m,T];B^1)} \leq C\left(\|\rho_v(T_m)\|_{B^1,-\frac{1}{2}} + \mathcal{N}_0\right).
\]

This gives, for any \(m\) such that \(T_m < T_\varepsilon\) and for all \(T\) in \([T_m;\min\{T_{m+1},T_\varepsilon\}]\),
\[(6.22) \quad \mathcal{R}_m(T) + \mathcal{R}_m(T) \leq C_1\left(\|\rho_v(T_m)\|_{B^1,-\frac{1}{2}} + \|\rho_h(T_m)\|_{B^0} + \mathcal{N}_0\right).
\]

Let us observe that \(\rho_{t=0} = 0\). Thus exactly as in the proof of Lemma 4.6, an iteration process gives, for any \(m\) such that \(T_m < T_\varepsilon\) and any \(T\) in \([T_m;\min\{T_{m+1},T_\varepsilon\}]\),
\[
\mathcal{R}(T) \overset{\text{def}}{=} \|\rho_h\|_{L^\infty([0,T];B^0)} + \|\rho_h\|_{L^1([0,T];B^2)} + \|\rho_v\|_{L^\infty([0,T];B^1,-\frac{1}{2})} + \|\rho_h\|_{L^1([0,T];B^3\frac{1}{2})} \leq (C_4)^{m+1}\mathcal{N}_0.
\]

By definition of \(\mathcal{N}_0\) given in (6.20), we have in view of Definition 2.4
\[
\mathcal{N}_0 \lesssim \left(\|u_0\|_{B^0} + \|f\|_{\mathcal{F}_0}\right)\left(\|U\|_{L^2(\mathbb{R}^+,B^1)} + \|u_0\|_{B^0} + \|f\|_{\mathcal{F}_0}\right).
\]

As claimed in (6.19) the total number of intervals is less than \(\|U\|^2_{L^2(\mathbb{R}^+,B^1)}\). We infer that, for any \(T < T_\varepsilon\)
\[
\mathcal{R}(T) \leq C_2\left(\|u_0\|_{B^0} + \|f\|_{\mathcal{F}_0}\right)\left(\|U\|_{L^2(\mathbb{R}^+,B^1)} + \|u_0\|_{B^0} + \|f\|_{\mathcal{F}_0}\right)\exp\left(C_2\|U\|^2_{L^2(\mathbb{R}^+,B^1)}\right).
\]

Using the interpolation inequality (6.16) we infer that, for any \(T < T_\varepsilon\),
\[
\int_0^T \|\rho(t)\|_{B^1} dt \leq C_2\left(\|u_0\|_{B^0} + \|f\|_{\mathcal{F}_0}\right)\left(\|U\|_{L^2(\mathbb{R}^+,B^1)} + \|u_0\|_{B^0} + \|f\|_{\mathcal{F}_0}\right)\exp\left(C_2\|U\|^2_{L^2(\mathbb{R}^+,B^1)}\right).
\]
Choosing
\[ C_2(\|u_0\|_{B^0} + \|f\|_{F^0})(\|U\|_{L^2(\mathbb{R}^+; B^1)} + \|u_0\|_{B^0} + \|f\|_{F^0}) \exp(C_2\|U\|_{L^2(\mathbb{R}^+; B^1)}^2) \leq \frac{e^2}{2} \]

ensures that \[ \int_0^T \|\rho(t)\|_{B^1}^2 dt \] remains less than \( e^2 \), and thus there is no blow up for the solution of \((NS_U)\). This concludes the proof of Proposition 2.5.

6.3. Proof of Proposition 4.8. As a warm up, let us observe if \( u \) belongs to \( L^2(\mathbb{R}^+; B^1) \), then \( u \otimes u \) belongs to \( L^1(\mathbb{R}^+; B^1) \). Lemma 6.1 implies that the operators \( Q_h \) and \( Q_v \) defined in (6.14) satisfy
\[ \|Q_h(u, u)\|_{L^1(\mathbb{R}^+; B^0)} + \|Q_v(u, u)\|_{L^1(\mathbb{R}^+; B^1)} \lesssim \|u\|_{L^2(\mathbb{R}^+; B^1)}^2 . \]

Using the Duhamel formula and the action of the heat flow described in Lemma 6.2, we deduce that
\[ \|u\|_{L^1(\mathbb{R}^+; B^2)} + \|u\|_{L^1(\mathbb{R}^+; B^1)}^{1/2} \lesssim \|u_0\|_{B^0} + \|u\|_{L^2(\mathbb{R}^+; B^1)}^2 , \]
which proves (4.48). Let us prove the second inequality of the proposition which is a propagation-type inequality. Once an appropriate (para)linearization of the terms \( Q_h \) and \( Q_v \) is done, the proof is quite similar to the proof of Proposition 2.5. Following the method of [13], let us observe that
\[ \text{div}(u \otimes u)^\ell = \text{div}_h(u^\ell u_h) + \partial_3(u^\ell u^3) = (\text{div}_h u^\ell)u_h + u^h \cdot \nabla_h u^\ell + \partial_3(T^v_{w^3} u^\ell + T^v_{u^3} u^3 + R^v(u^3, u^\ell)) . \]

Now let us define the bilinear operator \( T \) by
\[ (T u)^\ell \overset{\text{def}}{=} (\text{div}_h u^h)u^\ell + u^h \cdot \nabla_h u^\ell + \partial_3(T^v_{w^3} u^\ell + T^v_{u^3} u^3 + R^v(u^3, u^\ell)) . \]

Let us observe that \( T u = \text{div}(u \otimes u) \). The laws of product of Proposition 6.4 imply that, for any \( s \) in \([-1 + \mu, 1 - \mu] \),
\[ \|((\text{div}_h u^h)u^\ell + u^h \cdot \nabla_h u^\ell)\|_{B^s} \lesssim \|u\|_{B^{s+1}} \|u\|_{B^1} . \]

Lemmas 6.1 and 6.5 imply that, for any \( s \) in \([-1 + \mu, 1 - \mu] \),
\[ \|((\partial_3(T^v_{w^3} u^\ell + T^v_{u^3} u^3 + R^v(u^3, u^\ell)))\|_{B^s} \lesssim \|u\|_{B^{s+1+1}} \|u\|_{B^1} . \]

Let us notice that for any non negative \( a \), \( u \) is solution of the linear equation
\[ w = e^{(t-a)A} u(a) + L_a T_u w . \]
The smoothing effect of the heat flow, as described in Lemma 6.2, implies that for any non negative \( a \), and any \( t \) greater than or equal to \( a \),
\[ 2(t-a)^{1-k} \|\Delta^k A L_a T_u w(t)\|_{L^2} \lesssim \int_a^t d_j k(t') e^{-c(2k+2)(t-t')} \|u(t')\|_{B^1} \|u(t')\|_{B^{s+1}} + \|w(t')\|_{B^{s+1}}^2 dt' . \]

This gives, for any \( b \) in \([a, \infty) \),
\[ \|L_a T_u w\|_{L^\infty(I; B^1)} + \|L_a T_u w\|_{L^1(I; B^{s+2} \cap B^{s+1})} \lesssim \|u\|_{L^2(I; B^1)} + \|u\|_{L^2(I; B^{s+1})} \]
with \( I = [a, b] \). Now let us consider the increasing sequence \( (T_m)_{0 \leq m \leq M} \) which satisfies (6.18). If \( c_0 \) is chosen small enough, we have that the linear map \( L_{T_m} T_u \) maps the space
\[ L^2([T_m, T_{m+1}]; B^1 \cap B^{s+1} \cap B^s) \]
into itself with a norm less than 1. Thus \( u \) is the unique solution of (6.25) and it satisfies, for any \( m \)
\[
\|u\|_{L^\infty([T_m,T_{m+1}];B^{s+\frac23})} + \|u\|_{L^2([T_m,T_{m+1}];B^{s+\frac32})} \leq C_1\|u(T_m)\|_{B^{s}}.
\]
Arguing as in the proofs of Lemma 4.6 and Proposition 2.5, we conclude that \( u \) belongs to \( \mathcal{A}^s \) and that
\[
\|u\|_{\mathcal{A}^s} \lesssim \|u_0\|_{B^{s}} \exp(C\|u\|^3_{L^2(\mathbb{R}^+;B^{s})}).
\]
Inequality (4.49) is proved.

In order to prove Inequality (4.50), let us observe that using Bony’s decomposition in the vertical variable, we get
\[
\text{div}(u \otimes u)^\ell = \sum_{m=1}^3 \partial_m (u^\ell u^m) = \sum_{m=1}^3 \partial_m \left( T_{u^\ell} u^m + T_{u^m} u^\ell + R^\ell(u^\ell, u^m) \right).
\]
Now let us define
\[
(\overline{T} u w)^\ell \overset{\mathrm{df}}{=} \sum_{m=1}^3 \partial_m \left( T_{u^\ell} u^m + T_{u^m} u^\ell + R^\ell(u^\ell, u^m) \right).
\]

Proposition 6.4 implies that, if \( m \) equals 1 or 2 then for any \( s' \) greater than or equal to 1/2
\[
\|
\partial_m \left( T_{u^\ell} u^m + T_{u^m} u^\ell + R^\ell(u^\ell, u^m) \right) \|_{L^1(\mathbb{R}^+;B^{s',s'})} \lesssim \|u\|_{L^2(\mathbb{R}^+;B^{s'})}\|w\|_{L^2(\mathbb{R}^+;B^{s',s'})}\quad \text{and}
\|
\partial_3 \left( T_{u^\ell} u^3 + T_{u^3} u^\ell + R^\ell(u^\ell, u^3) \right) \|_{L^1(\mathbb{R}^+;B^{s',s'})} \lesssim \|u\|_{L^2(\mathbb{R}^+;B^{s'})}\|w\|_{L^2(\mathbb{R}^+;B^{s',s'+1})}.
\]
Thus we get, for any \( a \) in \( \mathbb{R}^+ \), any \( b \) in \( I = [a, \infty] \) and any \( r \) in \([1, \infty)\),
\[
\|L_a \overline{T} u w\|_{L^r(I;B^{s',s'+1})} \lesssim \|u\|_{L^2(I;B^{s'})} (\|w\|_{L^2(I;B^{s',s'})} + \|w\|_{L^2(I;B^{s',s'+1})}) \quad \text{with} \quad \sigma + \sigma' = \frac{2}{r}.
\]
Then the lines after Inequality (6.26) can be repeated word for word. The proposition is proved.

\[ \square \]

References


[46] E. Poulon, Behaviour of Navier-Stokes solutions with data in $H^s$ with $1/2 < s < 3/2$, in progress.


(H. Bahouri) Laboratoire d’Analyse et de Mathématiques Appliquées UMR 8050, Université Paris-Est Créteil, 61, avenue du Général de Gaulle, 94010 Créteil Cedex, France
E-mail address: hbahouri@math.cnrs.fr

(J.-Y. Chemin) Laboratoire Jacques Louis Lions - UMR 7598, Université Pierre et Marie Curie, Boîte courrier 187, 4 place Jussieu, 75252 Paris Cedex 05, France
E-mail address: chemin@ann.jussieu.fr

(I. Gallagher) Institut de Mathématiques de Jussieu - Paris Rive Gauche UMR 7586, Université Paris-Diderot (Paris 7), Bâtiment Sophie Germain, Case 7012, 75205 Paris Cedex 13, France
E-mail address: gallagher@math.univ-paris-diderot.fr