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High nonlinear urban ground motion in Manila (Philippines) from 1993 to 2010 observed by DInSAR: implications for sea-level measurement

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Highlights:

- Differential SAR interferometry has been applied in Manila (Philippines)
- High nonlinear ground motion was observed during 1993–1998 and 2003–2010.
- A comparison with independent ground-level measurements (GPS, DORIS, and Tide Gauge) was carried out.
- The consequences for sea-level estimation were analyzed using a local tide gauge and GPS station.

ABSTRACT:

In coastal low-lying urban areas, vertical ground motions can significantly exacerbate the hazards related to sea-level rise. However, their spatial extent, their temporal evolution, and even sometimes their existence are often poorly known. This study aims to monitor variable urban ground motion (uplift and subsidence) from 1993 to 2010 in the metropolitan area of Manila, Philippines. Because high subsidence rates have been reported in this city in previous studies, conventional differential SAR interferometry (DInSAR) was applied with an adapted stacking procedure to the archive of ERS and Envisat satellite images to produce surface deformation-velocity maps for different periods. The results showed that the city is locally affected

by vertical ground motions on the order of 15 cm/yr. Moreover, the spatio-temporal evolution of the ground-motion phenomena is highly nonlinear. These results are in good agreement with previous studies focused on groundwater use in Manila and in the Marikina Fault Valley, suggesting a plausible interpretation of the processes causing surface motion. Incidentally, the ground motions are affecting the locations of several geodetic instruments, including a tide gauge with sea-level records starting in 1902, two permanent GPS (Global Positioning System) stations, and a DORIS (Doppler Orbitography and Radiopositioning Integrated by Satellite) station. A major implication of those large and locally variable ground motions is that they impede the use of the nearby GPS and DORIS data to correct the tide-gauge records and to derive robust sea-level trends associated with climate change.

1. Introduction

As sea level rises, there is increased concern about the growing urbanization of the world's coastal zones and the related coastal hazards, particularly in Southeast Asia (McGranahan *et al.*, 2007; Nicholls & Cazenave, 2010). However, climate-induced sea-level rise is not the only process leading to changes in mean relative sea levels in coastal cities: the local relative sea-level rise (i.e., as experienced on the coast) can be significantly affected by vertical ground motions, subsidence or uplift, either due to natural processes (e.g., global isostatic adjustment, tectonics, sediment compaction) or to human activities (e.g., groundwater pumping, hydrocarbon extraction).

In a recent assessment of the exposure of the world's coastal cities to coastal submersion hazard, Hanson *et al.* (2011) have highlighted that subsidence or uplift (1) affects many important coastal cities worldwide and (2) can be in the same order of magnitude or greater than climate-induced sea-level rise. It is therefore important to take into account these processes for evaluating how changes in sea level may affect coastal cities in the future. However, while coastal ground motions are recognized important, they are in practice often poorly known. In many cases, little information is available about the processes that generate ground motion (e.g., location and rates of groundwater pumping) and on ground-motion patterns. In addition, vertical ground motions often reveal strong spatial and temporal variability, so that their mapping is a complex task.

As a complement to *in-situ* monitoring (e.g., using GPS or leveling), space-borne Differential Synthetic Aperture Radar Interferometry (DInSAR) provides a means to deliver a comprehensive mapping of surface deformation (e.g., Brooks *et al.*, 2007; Lagios *et al.*, 2006; Raucoules *et al.*, 2008; Bock *et al.*, 2012; Chaussard *et al.*, 2013). The principle of DInSAR is to infer ground-motion displacements from the evolution of the phase of space-borne Synthetic Aperture Radar between two or more satellite passes. Although the technique encounters limitations in vegetated areas, it can be applied efficiently in urban environments. In addition, provided that the displacements are not too rapid given the geometric and temporal characteristics of the available SAR scenes time series, the method has been shown to be efficient for monitoring slightly nonlinear ground motions (e.g., Kim *et al.*, 2010).

Using SAR data acquired by the ERS and Envisat satellites from 1993 to 2010, this study uses DInSAR to monitor ground motions affecting Manila, on Luzon Island in the Philippines. Located on a coastal floodplain between the eastern part of Manila Bay and Laguna de Bay, the Manila metropolitan area is considered to be highly vulnerable to the adverse effects of flooding and of sea-level rise (World Bank, 2010). The 2010 population census reported that Manila has a population of 11.8 million inhabitants (National Statistics Office, Republic of the Philippines, 2010). In addition, previous studies have reported that the city is subject to ground motions: as the population has grown, water demand and groundwater extraction have drastically increased (Clemente *et al.*, 2001), causing ground surface motions in the city of Manila, as well as in other locations around Manila Bay (Siringan & Ringor, 1998; Rodolfo & Siringan, 2006; Daag *et al.*, 2011, Clemente *et al.*, 2001). Finally, the eastern part of the city is crossed by a seismic fault, the Marikina Fault Valley (Rimando & Knuepfer, 2001).

Interestingly, the city hosts several important geodetic instruments which are potentially useful for estimating contemporary sea-level rise. Tide-gauge measurements have been recorded in Manila since 1902, which makes this the longest time series in Southeast Asia. Therefore, this gauge belongs to the “Global Core Network” of the Global Sea Level Observing System (GLOSS). However, the tide gauge is suspected of being affected by ground motions, presumably due to groundwater withdrawal, at least since the 1950s (Santamaría Gómez *et al.*, 2012). To correct sea-level time series from these ground motions (as proposed by Wöppelmann *et al.*, 2007), several geodetic instruments located in metropolitan Manila might be used: two GPS stations and a DORIS (Doppler Orbitography and Radiopositioning Integrated by

Satellite) station (Willis *et al.*, 2010). However, these instruments are located several kilometers away from the tide gauge (Fig. 1). Because no repeated leveling surveys are presently available in the GLOSS data repositories (www.sonel.org; www.psmsl.org), it is unknown whether the location of these instruments has been affected by the ground-motion processes.

In this study, DInSAR is applied to the Manila urban area with the objective of providing preliminary answers to the following questions:

- (1) What was the spatial and temporal variability of ground-surface deformations in Manila from 1993 to 2010?
- (2) To which extent do these deformations affect the locations of the tide gauge and of the GPS and DORIS stations?
- (3) What are the possibilities for using sea-level time series before 1993 in Manila?

The paper proceeds as follows: Part 2 describes the data and the DInSAR processing. Part 3 reports on the observations of surface deformations and provides preliminary interpretations in relation to previous studies focused on groundwater extraction and on the Marikina Valley Fault. Finally, in Part 4, the paper discusses to which extent the combination of permanent GPS measurements and DInSAR is able to provide correction for long-term tide-gauge time series for this particular site, considering the high observed deformation rates and their irregular temporal evolution.

2. Processing procedures and data

2.1 Choice of an adapted DInSAR processing procedure

Several DInSAR algorithms can be used for processing SAR data, from conventional DInSAR (e.g., Massonnet and Feigl, 1998), possibly with an adapted stacking procedure (e.g., Usai *et al.*, 2003) to advanced techniques such as Persistent Scatterers Interferometry (PSI, e.g., Ferretti *et al.*, 2000; Wegmuller *et al.*, 2004) or Small Baseline Subsets (SBAS, e.g., Pepe *et al.*, 2005). The quality of the

results obtained by each method can vary widely depending on the area of interest and on the available SAR images. In places such as the densely urbanized Manila metropolitan area, conventional DInSAR often provides interferograms with good coherence even over large time spans (a few years), provided that the perpendicular baselines are not too high. However, these interferograms are affected by atmospheric effects, typically leading at the spatial wavelength of this study (~20 km) to errors of the order of one centimeter, but in certain cases to errors larger than a fringe (e.g., Hanssen, 2001). When a sufficient number of SAR scenes have been acquired, stacking procedures can average and reduce atmospheric effects, which are supposed to be spatially correlated and temporally uncorrelated. With this assumption, uncertainty due to atmosphere is reduced as the inverse of $\sqrt{N}$, where N is the number of independent interferograms (Zebker *et al.*, 1997; Peltzer *et al.*, 2001). For the presented results, that corresponds to approximately 4 mm/yr for the ERS data set (with only thirteen images) and better than 1 mm/yr for the EnviSat/ASAR data set.

Stacking procedures are relatively easy to use and can often provide information about potentially nonlinear ground motions in the order of a few centimeters per year (e.g., Le Mouelic *et al.*, 2005). Finally, advanced techniques such as PSI can be efficient if PS density is sufficient and can reach high precision. However, in the case of spatially and temporally variable rapid ground deformations, PSI techniques (in the standard procedure based on the use of linear or slightly nonlinear displacement evolution models) can be affected by spatial and temporal unwrapping errors that result in underestimation of the velocity and incorrect atmospheric phase screen estimation (Raucoules *et al.*, 2009). When no prior information on patterns of urban ground deformations is available, stacking procedures are easily applicable and can provide maps of vertical ground motions. This approach was selected for the case study in Manila. Combinations of ascending and descending modes can in certain cases (e.g., Wright *et al.*, 2004) be used for separating vertical motions other than horizontal (in fact, mostly East-West because of the orbital orientation). However, in the study area, the data archive in ascending mode is insufficient (in fact only one ASAR pair is archived) to derive deformation maps for the period of interest. Assumptions on the direction of motion are therefore needed for interpretation.

2.2 Description of data and processing

Using a series of ERS 1-2 images between 1993 and 2000 (Table 1) and ASAR/EnviSAT data between 2003 and 2010 (Table 2), differential interferograms having perpendicular baselines shorter than 300 m were processed. Then, as suggested, e.g., by Le Mouelic *et al.*, (2005), a subset of trustworthy interferograms was selected visually by rejecting noisy phases and data obviously affected by atmospheric effects. In addition to rejecting low-coherence interferograms, the interferograms were compared by pairs to identify obvious atmospheric effects. Figures 2a and 2b show the selected interferograms and related acquisition times and perpendicular baselines. Deformation is assumed (even for nonlinear deformation) to have a certain temporal correlation, whereas atmosphere turbulence is assumed uncorrelated. By identifying similarities and dissimilarities on the interferograms, it was possible to detect acquisitions affected by strong atmospheric effects that could severely impair a stacking result. Finally, interferograms were stacked for the entire observation periods [1993–1998 (ERS) and 2003–2010 (Envisat)] and for sub-periods of three years. We focused on time spans shorter than 400 days to avoid unwrapping errors in interferograms with more than five or six fringes and to limit temporal decorrelation. Note that the ERS acquisition for 2000 does not allow production of interferograms meeting the requirements in terms of time span.

This processing was carried out using the GAMMA interferometric software (Wegmuller *et al.*, 1998).

2.3 Specific procedures for analyzing temporally variable ground motions and fault-related deformations

In addition, a principal components analysis (PCA) was performed on the deformation maps to discriminate the areas affected by constant deformation (first component) from those affected by time-varying deformation. Finally, a directional filter was computed for the 2003–2010 deformation maps of the Marikina Valley Fault area (east of Manila) to locate sections of the fault affected by surface motion.

Table 1: ERS 1–2 acquisitions (track 418)

Year	Acquisition dates
1993	25 July, 29 Aug, 3 Oct
1995	4 April, 13 June, 31 Oct, 5 Dec
1996	9 Jan, 19 March, 11 Sept

1997	1 Oct, 5 Nov
1998	14 Jan
2000	23 Feb

178 Mean incidence angle: approximately 23°

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182 Table 2: EnviSat/ASAR acquisitions (track 418)

Year	Acquisition dates
2003	8 Jan, 12 Feb, 19 March, 2 July, 10 Sept, 24 Dec
2004	28 Jan, 3 March, 12 May, 21 July, 25 Aug, 29 Sept, 3 Nov, 8 Dec
2005	12 Jan, 16 Feb, 23 March, 27 April, 1 June, 6 July, 10 Aug, 14 Sept, 28 Dec
2006	1 Feb, 8 March, 12 April, 17 May, 26 July, 17 Jan, 26 July
2007	17 Jan, 24 Oct, 28 Nov
2008	12 March, 25 June, 3 Sept, 12 Nov
2009	21 Jan, 2 Dec
2010	4 Aug

183 Mean incidence angle: approximately 23°

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Figure 1: Location of the Manila metropolitan area. This map shows (1) the area covered by the SAR data acquisition frames on Manila Bay, with solid lines corresponding to the ASAR/ENVISAT acquisitions and dashed lines to ERS 1 and 2 data; (2) the position of the Marikina Valley Fault System (MVFS), based on Rimando & Knuepfer, (2006); the ASAR data cover part the Marikina Valley Fault, whereas the ERS data do not due to a slight westward shift of ERS; (3) the location of the tide gauge, GPS (PIMO), and DORIS stations; the MANL GPS station is located close to the tide gauge (see Fig. 3a), but no reliable vertical velocity could be computed for the study period using the SONEL data repository (www.sonel.org).

Figure 2a: Baseline/time diagram for the ERS 1/2 data. The interferograms used for the study (those that met the requirements in terms of baseline and time span) are represented by vectors with coordinates corresponding to their baselines and time spans. The zero perpendicular baseline refers to the scene acquired on July 25, 1993.

Figure 2b: Same as Figure 2a for the EnviSAT/ASAR data. The zero perpendicular baseline refers to the scene acquired on January 8, 2003.

3. Results: observations and preliminary interpretations

3.1 Velocity maps

Deformation maps were produced as shown in Figs. 3 and 4. The scale corresponds to Line of Sight (LOS) in cm/yr. Because of the 23° view angle of the acquisition geometry, the LOS measurement is 2.3 more sensitive to the vertical component of the displacement than to the horizontal. The horizontal component of the subsidence displacement is generally much smaller than the vertical, but in certain cases could be non-negligible with respect to the vertical, although smaller (e.g., for coal-mining subsidence, the ratio between the maximum horizontal and the maximum vertical components is approximately 0.4; Tandanand & Powell, 1991). On the basis of these two observations, it can be assumed that for subsidence, the measured LOS component is related mostly to the vertical component of the displacement. Under this assumption, 10 rad/yr would correspond to approximately 4.9 cm/yr of vertical motion. However, horizontal displacements probably occur in the Marikina Valley Fault because it is mainly a strike-slip fault. In fact, if the observed motion were mainly due to fault activity and not related to pumping-induced subsidence, the measured LOS displacement would be the projection of an along-fault motion (except on sections of the fault having a more complex motion).

Pixels with an interferometric coherence less than 0.3 were considered unreliable and were used to define a mask. Morphological operations (opening and closing) were applied to the mask to remove irregularities before the mask was applied to the interferograms.

Because of the generalized surface motion in the area, it is difficult to find a reliable and stable reference point. However, the DORIS instrument provides a local estimate of vertical velocity. The deformation maps were corrected by a value (constant for a given map) to be compatible with the displacement observed by DORIS for the corresponding period (and therefore to convert relative measurements from DInSAR in absolute motion estimates). Values of the DORIS motion rates and a description of the data are given in Section 4.1.

Figure 3a: Line of Sight ground motion velocity in cm/yr for the whole 1993–1998 period (ERS 1-2 data). Negative values correspond to displacements towards the sensor (i.e., uplift). For figure readability, the color palette in this figure and in the following velocity maps is saturated at its extreme values.

Figure 3b: Line of Sight ground motion velocity maps for 1993–1995 and 1995–1998. An increase in subsidence rate in the northern part of the city appears between 1995 and 1998.

Figure 4a: Line of Sight ground motion velocity in cm/yr for the whole 2003–2010 period (EnviSat/ASAR data).

Figure 4b: Line of Sight ground motion velocity maps in cm/yr for 2003–2005, 2005–2008, and 2007–2010 (EnviSat/ASAR data).

The velocity maps reveal non-linear deformation rates. For example, Fig 3b indicates that the subsidence from 1995 to 1998 was quicker in the north-western part of Metro-Manila than from 1993 to 1995. How reliable is this result ? Due to the limited number of SAR images available from the ERS satellite, these velocities maps might be partly affected by atmospheric noise or by slight errors in orbit calculation and very large atmospheric effects at the scale of the imaged area might have resulted in tilts. In our approach, these tilts are corrected by removing tilts on each single interferogram (estimated using Fast Fourier Transforms) and then the possible residual tilts are minimized over the whole data set during the stacking procedure. While such errors are more difficult to correct when fewer SAR images are available, an analysis of individual interferograms confirms that the acceleration of subsidence is affecting the same area for several individual interferograms. This temporal correlation of interferograms as well as their velocity indicates that these non-linear velocities cannot only result from atmospheric noise, and confirm the acceleration of subsidence from 1995 to 1998 compared to 1993 to 1995. Nevertheless, for the ERS data set, we can consider the 1993-1998 map as more reliable than the two sub-sets (1993-1995 and 1995-1998), because more interferograms were stacked and because the DORIS velocity estimation better represents the average motion over the whole period. More SAR images are available from EnviSAT, thus

making the results in figure 4a and 4b more reliable. Several non-linear patterns can be observed in these maps, such as the extension of a coastal subsidence southward in the direction of the tide gauge, or the disappearance of a subsidence pattern on the southern shore of Manila Bay. These results therefore also highlight the non-linearity of the urban subsidence process in Manila.

Velocity maps not only display non-linear patterns, but also high rates of deformations. For example, deformation rates up to 13 cm/yr were observed in Valenzuela and Meycauayan and rates of approximately 9 cm/yr northwest of Guiguinto (note that for visual reason, we saturated the color palette to 6.7cm/yr). In these sectors, deformation was much slower and spatially reduced between 1993 and 1995. The highest deformation rates observed in Valenzuela and Meycauayan are visible on the 1995–1998 and 2003–2005 maps (a decrease of the phenomenon in this sector is visible on this last map with respect to the first one), whereas a maximum was obtained after 2005 near Guiguinto.

Changes in the location and rates of groundwater extraction are a plausible explanation for this migration of the deformation maxima. As reported by Clemente *et al.* (2001), groundwater pumping in Manila has been multiplied by a factor of five since the 1970s because of population growth. This has resulted in a lowering of the groundwater table by several tens of meters. The authors also suggest land subsidence as a possible consequence of pumping. Clemente *et al.* (2001) provide piezometric maps which show that the deformation maps generated in this study are consistent with the locations of very low water table levels in the 1990s. For instance, they reported that groundwater was intensively extracted in Muntlupa and Valenzuela, where high ground-motion velocities in the 90's were observed in this research. This suggests that many ground deformations observed using DInSAR in this research are direct consequences of groundwater pumping in the Manila metropolitan area.

3.2 Monitoring of Temporal Evolution of Ground Deformations through Principal Components Analysis

Because the results showed strong temporal variability, a principal components analysis was carried out to highlight areas subject to deformation-rate changes. The idea was to separate areas with constant deformation rates from areas affected by nonlinear deformation components. Principal components analysis (PCA) was therefore applied to the five deformation-rate maps corresponding to the different

periods studied. It was assumed that the first principal component (PC) was related to the common linear deformation (the first component being highly correlated with all the initial deformation maps) and the second and third components to nonlinear deformations which differ among the five maps (upper-order components were neglected because the fourth eigenvalue was approximately one-twentieth of the first one). The three first eigenvalues were $\lambda_1=43$, $\lambda_2=11$ and $\lambda_3=4.3$.

Figure 5: Maps showing the three first principal components. For the second and third components, the absolute values of the components are shown. Locations of the displacements are therefore identified by this information rather than their evolution (acceleration, deceleration).

Figure 5 highlights the observation that in addition to strong spatial variability, deformation patterns in Manila show a complex temporal evolution. In particular, this figure indicates that in addition to the northern part of the city (e.g., the area between Valenzuela and Meycauayan), the cities of Malaboon, Mandaluyong, and Muntinlupa were affected by nonlinear deformations. Small areas spotted on the third component deserve deeper investigation because temporal changes at short spatial wavelengths could have

implications such as damage to buildings. Actual links with pumping locations in these areas should be investigated, for example by identifying whether localized velocity changes can be correlated with the installation of new pumping facilities during the study period.

3.3 Deformation in the Marikina Valley Fault area

To investigate displacement along the Marikina Valley Fault, an east-west directional filter was used to highlight differential motion between each side of the fault (Fig. 6). Basically, the filtered image consists of an along-column (approximately across-fault) deformation first derivative for which the histogram has been adjusted and the result rescaled to obtain arbitrary values distributed between zero and one. This procedure aims to provide better identification of linear features (similarly to a shaded map) that could be associated with fault motion. Sections of the fault that possibly moved between 2007 and 2010 were then located. Note that the ERS frames did not cover the fault, and therefore this observation is based only on the ASAR data. The 2007–2010 maps clearly show differential displacement along the fault (Fig. 4b).

The observed fault section was divided into three sections based on their motion characteristics: A and C: west side moves towards the sensor faster than east side; B has the opposite behavior to A and C. On the three sections, the differential LOS displacement (identified on the deformation map) corresponds to approximately 5–15 mm/yr. Because the fault strike is oriented north-south, it can be assumed that pure strike-slip motions have little influence on the deformation maps produced. Therefore, vertical motion must dominate the signal. Based on this assumption, the observed motion corresponds to up to 8 mm/yr of vertical displacement between the two sides of the fault. The source of this kind of motion is difficult to infer based only on the DInSAR measures, which provide only one component of the deformation in three-dimensional space. Deformation could be related either to tectonic strain (e.g., surface creep) or to subsidence related to water extraction (as observed by Cigna *et al.*, 2011). In this case, the fault would act as a natural barrier.

Figure 6: West-east directional filtering of the 2005–2010 deformation in arbitrary units. Bright areas correspond to the highest values of W-E derivatives. The red line corresponds to possible sections of the fault affected by differential displacement between the sides of the fault (located on linear features of the filtered map). The three sections are identified using their different displacement behaviors.

A deeper analysis can be proposed. Based on both terrains offset measurements and magnitudes and recurrences of earthquakes, Rimando & Knuepfer (2006) have suggested that on the Rodriguez-Taguig segment (corresponding to sections A and B in this paper), the slip rate should be approximately 7–10 mm/yr and should be mostly horizontal. They observed that the ratio between vertical and horizontal components of offsets is approximately 0.1. Considering the orientation of the fault with respect to the satellite-orbit path angle (between 0° and 12°) and the SAR incidence angle (approximately 23°), 10 mm/yr

of horizontal motion would result in approximately 0.8 mm/yr change in the LOS direction. This value is too small to be measured by DInSAR. Therefore, non-tectonic subsidence seems more likely to be the cause of the SAR signal for these sections. Section C of the fault (the Sucat-Binan segment) is characterized by *en-echelon* elements. According to the authors, this segment is creeping, but they do not provide rate estimations. This complicated behavior is not incompatible with vertical motion; the hypothesis that the DInSAR observation shows creeping phenomena for this section cannot be rejected, but further dedicated analysis would have to be performed to assess fault motion in this area.

Figures 7 and 8 show profiles and estimations of the relative displacements between each side of the fault using a 200-pixel length and stacked on 100 pixels width based on the COSI-Corr tools (for details on these tools and a discussion of their reliability and precision, refer to Ayoub *et al.*, 2009). These figures show that on sections A and B, the recorded LOS displacements are variable with time (including an inversion of the motion for section B). On the other hand, on section C, the LOS motion is fairly stable at approximately 6 mm/yr velocity (with a dispersion of approximately 2 mm/yr). These observations are compatible with the fact that the fault mechanism is mainly N-S oriented strike-slip on A and B (blind to DInSAR), and therefore the recorded vertical component of the motion must be due mainly to (variable) non-tectonic causes. Section C, with its *en-echelon* structure, is known to creep (Rimando & Knuepfer, 2006). Therefore, this research might have measured the vertical component of fault creep in this area.

Figure 7: Relevant deformation across-fault profiles for each section: LOS velocities are given in cm/yr and the position in km (positive from west to east). These profiles are along fault stacks of 100 profiles 200 pixels in length (profile length: approximately 3.6 km) according to the procedure implemented in the COSI-Corr tool (Leprince et al., 2007; Ayoub et al., 2009). The fault is approximately located, based on the directional filtering results, by the vertical dashed lines. In blue: profile derived from the 2003–2005 stack; in red, 2007–2010; in green, 2003–2010. The insets show the location of the profile stacks with respect to the fault.

Figure 8: Differential LOS velocity for the sides of the fault (west side with respect to east side) versus position on the fault (latitude). Velocities were obtained using the COSI-Corr tool. The 2003-2005 estimate (in blue) is compared to that for 2007-2010 (in red) and 2003-2010 (green). Section C shows a homogeneous behavior (vertical displacement of approximately 4-8 mm/yr), but the other sections show a more temporally variable evolution (sign change) not compatible with creeping phenomena. The inset shows the location of the profile stacks with respect to the fault.

4. Discussion

4.1 Comparison with *in-situ* observations

While no leveling surveys are presently available in global data repositories (Santamaría-Gómez et al., 2012), a few geodetic instruments enable comparing our InSAR results with in-situ observations. These geodetic instruments in Manila can be located on Fig. 2a. However, one permanent GPS station (GPS MANL) provided a time series too short to be analyzed at the time of this study. As can be seen in Fig. 9 (blue), the DORIS instrument was nearly stable in average in the 1990s, but was affected by uplift in the 2000s (Fig. 9, green).

The GPS PIMO station was also subject to a slight uplift in the 2000s (Fig. 9, yellow). The differential movement between PIMO and DORIS was consistently too small to be observed with DInSAR. During 2003–2010, the differential displacement between PIMO and the tide gauge (TG) as estimated from DInSAR was approximately 10.7 mm/yr $\pm$ 2.1 mm/yr, based on the sum of the variances of the DInSAR deformation-rate measurements obtained on 200 m windows around the PIMO and TG locations. Once corrected using the GPS absolute vertical motion, the resulting TG motion with respect to the reference ellipsoid was approximately 8 mm/yr of subsidence ($\pm$ 2.2mm/yr). To validate this result, the difference between the sea-level variation recorded by AVISO data (Archiving, Validation and Interpretation of Satellite Oceanographic data) and the TG data (Fig. 10) was calculated. The altimetric monthly sea-level anomalies were obtained from the AVISO data server (<http://www.aviso.oceanobs.com/en/altimetry.html>). These data are a multimission product (Jason 1-2, Envisat, Cryosat) with a spatial resolution of 0.25°x0.25°, starting in 1992. They include all geophysical corrections, in particular the dynamic atmospheric correction that accounts for the effects of atmospheric pressure and wind (Volkov *et al.*, 2007). To compare the tide-gauge data with the altimetry observations, this correction was added back in. The most highly correlated grid point of the altimetry observations was chosen for comparison with *in-situ* observations (the correlation was computed using de-seasoned and de-trended time series). Alternatives such as the closest grid point or an average among nearby grid points around 1° did not change the results. The combination of the altimetric observations with the tide-gauge data highlights subsidence of up to 10.1 mm/yr $\pm$ 0.6 mm/yr.

Finally, in addition to the multi-annual ground motion variability observed by DInSAR, the GPS time series also revealed seasonal vertical deformations with an amplitude of approximately 5.5 mm.

Figure 9: Observed DORIS (MANA/MANB) and GPS (PIMO) geocentric vertical displacements with respect to the international reference frame. DORIS (blue before 2003, green after) and GPS (orange) position time series are shown. Both stations were affected by uplift phenomena with similar rates. MANA and MANB refer to successive DORIS instruments located at the same location (details on the instruments at <http://ids-doris.org/network/sitelogs.html>).

Figure 10: Tide-gauge subsidence in the geocentric international terrestrial reference frame based on the difference between sea level derived from altimetry (AVISO data) and that from tide-gauge measurements.

Figure 11: Close-up images showing Line of Sight ground motion velocity maps (cm/yr) close to the tide gauge. The deformation reference was chosen according to the DORIS measurements. Although ground motions affecting the location of geodetic instruments are much smaller than in other parts of Manila, they are still sufficient to alter the measurements of the tide gauge significantly, thus calling into question its use before 1993 for sea-level estimation studies.

4.2 Implications for estimation of sea-level variation from TG measurements

Because sea-level rise exhibits significant regional variability (e.g., Meyssignac & Cazenave, 2012), one critical issue for better estimation of past sea level before the altimetry era (1993) is the analysis of long-

term tide-gauge records. This question is particularly significant because there is a disagreement between sea-level budgets as estimated (1) from tide gauges and (2) through independent evaluations of thermosteric and continental ice-melting contributions (Munk, 2002).

Tide gauges measure sea level with respect to the land upon which they are grounded (local datum), while global sea level refers to a geocentric reference frame. In other words, both the land and the sea can move with respect to a geocentric reference frame. In practice, vertical ground motions can be removed from tide-gauge measurements using a nearby GPS permanent station (e.g., Wöppelmann *et al.*, 2007), assuming that (1) the tide gauge and the GPS station follow the same vertical motion and (2) that the deformation is linear. Under such conditions, extrapolation of the linear trend of ~10-years GPS time series is valuable to estimate past land motion for at least 50 years. If the differential movements affecting the instruments remained linear, advanced techniques such as PSI could be used as supplemental data to reach the accuracy required of (~ 0.5 mm/yr) and subsequently to assess estimates of global sea-level rise (approximately 1.7 mm/yr between 1950 and 2010, Wöppelmann *et al.*, 2013)

However, the results reported here show that none of the requirements necessary to estimate geocentric sea-level rise from GPS-corrected tide-gauge data is fulfilled in the case study of Manila. Therefore, this method cannot be used here because of highly variable ground motion. Moreover, the spatial and temporal variability of the surface motion, affecting both the tide gauge and the reference GPS, prevents any extrapolation from corrected gauge time series over the past 50 years. If the differential motion between the GPS and the tide gauge can be estimated for the period monitored by the space-borne radar sensor, the current motion is not representative of past motion (previous to the satellite era). In addition, if the area of maximum subsidence, initially located in Malaboon city, migrates southward, the tide-gauge area could be affected by increased subsidence in the future.

This study encourages DInSAR monitoring at locations where long-term tide-gauge time series are corrected using a distant permanent GPS to verify whether the typical assumptions used to combine the datasets and to estimate geocentric sea-level variation are applicable.

5. Conclusions

Subsidence in coastal cities has many effects, potentially ranging from increased frequency of flooding to damage to buildings. In the specific context of Manila, this study has provided the following responses to the questions raised in the introduction:

- (1) What was the spatial and temporal variability of ground-surface deformations in Manila from 1993 to 2010? This study has presented evidence for high rates of spatially and temporally variable ground deformation in the Manila urban area (Philippines) based on space-borne SAR interferometry during the last two decades. Displacements up to 15 cm/yr with temporal and spatial variability have been observed. These ground motions are very likely related to groundwater pumping because the Manila urban area is known to be affected by subsidence due to intensive groundwater extraction (Clemente *et al.*, 2001) and due to ground motion along the fault. Although the origin of this latter motion could be tectonic, it is suggested here that the observed ground motion along the fault is actually likely to be related to groundwater pumping as well (except on the Sucat-Binan segment).
- (2) To which extent do these deformations affect the locations of the tide gauge, the GPS stations, and the DORIS stations? Observed ground motions affect the locations of several geodetic instruments and therefore alter the potential of using their time series to understand past sea levels.
- (3) What are the possibilities for using sea-level time series before 1993 in Manila? The Manila tide-gauge time series cannot be corrected from its own motion for long-term sea-level estimation on the basis of existing GPS data because the GPS station also experiences variable subsidence and cannot therefore provide an estimate of the deformation occurring during the entire duration of the TG record (the last century).

From a methodological point of view, this study provides an example of a site where InSAR is helpful in assessing city-scale subsidence or uplift as well as the related consequences for measurements obtained from geodetic instruments located in the city. Because of its deformation characteristics (location, extent, and variable temporal evolution), the Manila metropolitan area has been revealed to be a challenging test site both for application of deformation-monitoring techniques and for surface deformation-related risk management. The approach proposed in this study could enable assessment of the usability of a number

of tide gauges suspected of having been affected by local ground motions and finally could provide help in estimating sea-level evolution over the past century.

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