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TOWARD AN OPTIMIZED GLOBAL-IN-TIME SCHWARZ ALGORITHM FOR DIFFUSION EQUATIONS WITH DISCONTINUOUS AND SPATIALLY VARIABLE COEFFICIENTS

PART 1 : THE CONSTANT COEFFICIENTS CASE

FLORIAN LEMARIÉ*, LAURENT DEBREU†, AND ERIC BLAYO‡

Abstract. In this paper we present a global-in-time non-overlapping Schwarz method applied to the one dimensional unsteady diffusion equation. We address specifically the problem with discontinuous diffusion coefficients, our approach is therefore especially designed for subdomains with heterogeneous properties. We derive efficient interface conditions by solving analytically the minmax problem associated with the search for optimized conditions in a Robin-Neumann case and in a two-sided Robin-Robin case. The performance of the proposed schemes are illustrated by numerical experiments.

Key words. optimized Schwarz methods, waveform relaxation, alternating and parallel Schwarz methods

AMS subject classifications. 65M55, 65F10, 65N22, 35K15

1. Introduction. Numerous geophysical phenomena, with a strong societal impact, involve the coupled ocean-atmosphere system; e.g., for climate change, tropical cyclones, or sea-level rise predictions. To get a good depiction of the complex air-sea dynamics it is often necessary to couple atmospheric and oceanic computational simulation models. However, connecting the two model solutions at the air-sea interface is a difficult problem which is presently often addressed in a simplified way from a mathematical point of view. Indeed, with the ad-hoc coupling methods currently in use, the fluxes exchanged by the two models are generally not in exact balance [16]. This may be one factor explaining the strong sensitivity of coupled solutions to the initial conditions or parameter values generally observed [22]. This kind of coupling raises a number of challenges in terms of numerical simulation since we are considering two highly turbulent fluids with widely different scales in time and space. It is thus natural to use some specific numerical treatment to match the physics of the two fluids at their interface. It is known that, even if numerical models are much more complicated, a simple one-dimensional diffusion equation is relevant to locally represent the turbulent mixing in the boundary layers encompassing the air-sea interface. The corresponding diffusion coefficients are given by an eddy-viscosity closure predicting spatially variable diffusion coefficients [20]. To perform this coupling in a more consistent way than ad-hoc methods, we propose here to adapt a global-in-time domain decomposition based on an optimized Schwarz method. This type of method is thoroughly described in [9] and designed thanks to the pioneering work of [12, 13]. Schwarz-like domain decomposition methods provide flexible and efficient tools for coupling models with non-conforming time and space discretizations [3, 10]. Transmission conditions of Robin type have been proposed in [18] to circumvent the divergence of the classical Schwarz method in the case of non-overlapping subdomains. Then, thanks to the free parameters associated to the use of Robin conditions, an

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optimization of the convergence speed has been proposed in [12] and [14]: this is the basis of
the so called optimized Schwarz methods (OSM). This kind of method, originally introduced
for stationary problems, has been extended to unsteady cases by adapting the waveform re-
laxation algorithms to provide a global-in-time Schwarz method [13, 15] (sometimes referred
to as Schwarz waveform relaxation). This notion of optimization of the convergence speed
is critical in the context of ocean-atmosphere coupling as the numerical codes involved are very
expensive from a computational point of view. In the present series of two papers we intend
to derive interface conditions leading to an efficient Schwarz coupling algorithm between
two unsteady diffusion equations defined on non-overlapping subdomains. The convergence
properties of this kind of problem have already been extensively studied in the case of a con-
stant diffusion coefficient having the same value in all subdomains [8]. There exists a few
asymptotic results in the case of coefficients with different constant values in the different
subdomains [10] (in the more general case of advection-diffusion-reaction equations). In the
present papers, we extend these studies to the general case of diffusion coefficients which
vary in each subdomain, and whose values are different on both sides of the interface. In
this first part, we consider the case of diffusion coefficients that do not vary spatially in each
medium. We study a zeroth-order two-sided optimized method by considering two different
Robin conditions on both sides of the interface. In the second paper [17], the emphasis is on
the impact of the spatial variability of the coefficients on the convergence speed.

This first paper is organized as follows. In section 2, we recall the basics of optimized
Schwarz methods in the framework of time evolution problems. Sections 3 and 4 are dedi-
cated to the study of a diffusion problem with discontinuous, but piecewise constant, co-
efficients. In section 3 we analytically determine the solution of an optimization problem to
improve the convergence speed of a simplified algorithm with only one Robin condition com-
bined with a Neumann condition. In section 4, we address the more general case of two-sided
optimized Robin-Robin transmission conditions determined through a thorough study of the
behaviour of the convergence factor. Finally in section 5 some numerical results are shown
to prove the efficacy of the optimized algorithms derived in previous sections.

2. Model problem and Optimized Schwarz Methods. Our guiding example is the one
dimensional diffusion equation of a scalar \( u \)

\[
(2.1) \quad \mathcal{L} u = \partial_1 u - \partial_2 (D(x) \partial_2 u) = f \quad \text{in } \Omega \times [0, T],
\]

where \( \Omega \) is a bounded domain defined as \( \Omega = [-L_1, L_2] \), \( (L_1, L_2 \in \mathbb{R}^+ \), and \( D(x) > 0, x \in \Omega \).
In practical applications \( L_1 \) would denote the bottom of the ocean (of the order of 5 km in
the open ocean) while \( L_2 \) is typically the top of the troposphere (of the order of 15 km). This
problem is supplemented by an initial condition

\[
u(x, 0) = u_0(x) \quad x \in \Omega,
\]

and boundary conditions

\[
\mathcal{B}_1 u(-L_1, t) = g_1 \quad \mathcal{B}_2 u(L_2, t) = g_2 \quad t \in [0, T],
\]

where \( \mathcal{B}_1 \) and \( \mathcal{B}_2 \) are two partial differential operators. In the whole paper we assume that
\( u_0 \in H^1(\Omega) \), \( f \in L^2(0, T; L^2(\Omega)) \), and \( D(x) \) bounded in \( L^\infty \)-norm. Note that in actual
applications such assumptions are generally fulfilled. Existence and uniqueness results for
this problem can be proved following [10], and are not discussed here.

2.1. Formulation of global-in-time Schwarz method. In the present study, we con-
side a case where the diffusion coefficient \( D(x) \) has one discontinuity in \( \Omega \). This discontinu-
ity is representative of the transition between two media with heterogeneous physical prop-
erties. In this case we can define two subdomains, each subdomain having its own diffusion
profile $D_j(x)$, ($j = 1, 2$). This amounts to split $\Omega$ into two non-overlapping domains $\Omega_1$ and $\Omega_2$ (Fig. 2.1). Those subdomains communicate through their common interface $\Gamma = \{x = 0\}$ (note that there can be various reasons for such a splitting: different physics, parallelization and/or different numerical treatment requirements). We propose to use a non-overlapping global-in-time Schwarz algorithm to solve the corresponding coupling problem. This method consists in solving iteratively subproblems in $\Omega_1 \times [0, T]$ and $\Omega_2 \times [0, T]$ using as an interface condition at $x = 0$ the values computed at the previous iteration in the other subdomain. The operator $L$ introduced in (2.1) is split into two operators $L_j = \partial_t - \partial_x(D_j(x)\partial_x)$ restricted to $\Omega_j$ ($j = 1, 2$). Introducing the operators $F_1$, $F_2$, $G_1$ and $G_2$ to define the interface conditions, the algorithm reads

\begin{equation}
\begin{cases}
\mathcal{L}_1 u^k_1(x, 0) = f & \text{in } \Omega_1 \times [0, T] \\
\partial_x u^k_1(x) = u_\partial(x) & x \in \Omega_1 \\
\mathcal{B}_1 u^{k}_1(-L_1, t) = g_1 & t \in [0, T] \\
\mathcal{F}_1 u^{k}_1(0, t) = \mathcal{G}_2 u^{k-1}_2(0, t) & \text{in } \Gamma \times [0, T]
\end{cases}
\end{equation}

\begin{equation}
\begin{cases}
\mathcal{L}_2 u^k_2(x, 0) = f & \text{in } \Omega_2 \times [0, T] \\
\partial_x u^k_2(x) = u_\partial(x) & x \in \Omega_2 \\
\mathcal{B}_2 u^{k}_2(L_2, t) = g_2 & t \in [0, T] \\
\mathcal{G}_2 u^{k}_2(0, t) = \mathcal{G}_1 u^{k}_1(0, t) & \text{in } \Gamma \times [0, T]
\end{cases}
\end{equation}

where $k = 1, 2, \ldots$ is the iteration number and where the initial guess $u^0_2(0, t)$ is given. Algorithm (2.2) corresponds to the so-called "multiplicative" form of the Schwarz method. If we replace the interface condition $\mathcal{G}_2 u^k_2 = \mathcal{G}_1 u^{k-1}_1$ on $\Omega_2$ by $\mathcal{G}_2 u^k_2 = \mathcal{G}_1 u^{k-1}_1$ we obtain the "parallel" version of the algorithm. The multiplicative form converges more rapidly than the parallel one but prevents from solving subproblems in parallel (this problem can however be circumvented when we consider more than two subdomains). Interested readers may refer to [7] for further details regarding the different variants of the Schwarz method. Although the present study uses the multiplicative form of the algorithm, the theoretical results regarding the determination of optimized transmission conditions are also valid for the parallel form. Note that the usual algorithmic approach used by ocean-atmosphere climate models, as described in [4], generally corresponds to one (and only one) iteration of algorithm (2.2) (with $F_j = G_j = D_j(0)\partial_x$, $j = 1, 2$).

The primary role of operators $F_j$ and $G_j$ ($j = 1, 2$) in (2.2) is to ensure a given consistency of the solution on the interface $\Gamma$. In our context we require the equality of the subproblems solutions and of their fluxes. The most natural choice to obtain such a connection consists in
choosing
\[ F_1 = D_1(0) \frac{\partial}{\partial x} \quad F_2 = D_2(0) \frac{\partial}{\partial x} \quad G_1 = G_2 = Id. \]

However, as proposed in [18], the same consistency can be obtained using mixed boundary conditions of Robin type, leading to
\[ F_j = D_j(0) \frac{\partial}{\partial x} + \Lambda_1 \quad G_j = D_j(0) \frac{\partial}{\partial x} + \Lambda_2 \quad (j = 1, 2). \]

This type of condition has the advantage to add operators \( \Lambda_1 \) and \( \Lambda_2 \) in the coupled problem. Those operators, if correctly chosen, can greatly improve the convergence speed of the corresponding algorithm [12]. Note that the \( \Lambda_j \) must also be carefully chosen to ensure the well-posedness of the problem. In this paper we focus on Robin-type transmission conditions since \textit{Dirichlet-Neumann}-type algorithms converge generally quite slowly, except for large discontinuities between the coefficients \( D_2 \) and \( D_1 \) (it can easily be shown that the convergence rate is given by the square root of the ratio between \( D_1 \) and \( D_2 \)).

At this point, we have formulated the coupling problem we want to address. The convergence properties of this kind of problem have been extensively studied in the case of constant and continuous diffusion coefficients [8]. There also exists a few results in the case of constant and discontinuous coefficients [10] in the more general case of an advection-diffusion-reaction problem. This latter study provides results for specific asymptotic cases that are discussed later in section 4.4. In this paper, we propose to investigate the problem with diffusion coefficients constant in each subdomain and discontinuous at the interface; i.e., \( D_j(x) = D_j \), with \( D_j > 0 \) and \( D_1 \neq D_2 \). We prove the convergence of algorithm (2.2) and we determine optimal choices for the \( \Lambda_j \) operators, under some constraints on the parameters of the problem.

2.2. Convergence of the algorithm. A classical approach to demonstrate the convergence of algorithm (2.2) consists in introducing the error \( e_j^k \) between the exact solution \( u^* \) and the iterates \( u_j^k \), \( j = 1, 2 \). By linearity, those errors satisfy homogeneous diffusion equations with homogeneous initial conditions. We denote the Fourier transform in time by \( \hat{g} = F(g) \) for any \( g \in L^2(\mathbb{R}) \). Assuming that \( T \to \infty \) and that all the functions are equal to zero for negative times, it can easily be shown that the errors \( \hat{e}_j^k \) in Fourier space satisfy a second-order ordinary differential equation in \( x \)
\[ i\omega \hat{e}_j^k - D_j \frac{\partial^2 \hat{e}_j^k}{\partial x^2} = 0 \quad \text{for} \quad x \in \Omega_j, \omega \in \mathbb{R}^* \]

with characteristic roots \( \sigma_j^\pm = \pm \sqrt{\frac{|\omega|}{2D_j} \left( 1 + \frac{|\omega|}{\omega} \right)} \). Note that the particular case \( \omega = 0 \) would correspond to the existence of a stationary part in the error. However, since the error is initially zero, such a stationary part is also necessary zero. To study the convergence of algorithm (2.2), the domain \( \Omega \) is usually supposed unbounded (\( L_1, L_2 \to \infty \)), thus leading to
\[ \begin{cases} \hat{e}_1^k(x, \omega) = \alpha^k(\omega)e^{\sigma_1^+ x} & \text{for} \quad x < 0, \omega \in \mathbb{R}^* \\ \hat{e}_2^k(x, \omega) = \beta^k(\omega)e^{\sigma_2^- x} & \text{for} \quad x > 0, \omega \in \mathbb{R}^* \end{cases} \]
The validity of this assumption is discussed in [16]. The functions \( \alpha(\omega) \) and \( \beta(\omega) \) are determined using the Robin interface conditions at \( x = 0 \)

\[
\begin{align*}
(2.5) \quad \left\{ \begin{array}{ll}
(D_1 \sigma_1^+ + \lambda_1) \alpha^k(\omega) = (D_2 \sigma_2^- + \lambda_1) \beta^{k-1}(\omega) \\
(-D_2 \sigma_2^- + \lambda_2) \beta^k(\omega) = (-D_1 \sigma_1^+ + \lambda_2) \alpha^k(\omega)
\end{array} \right.
\end{align*}
\]

where \( \lambda_j \) is defined as the symbol of operator \( \Lambda_j \) \((j = 1, 2)\). A convergence factor \( \rho \) of the Schwarz algorithm \((2.2)\) can be defined as

\[
\rho(\omega) = \frac{\hat{e}_k^j(0, \omega)}{\hat{e}_k^{j-1}(0, \omega)} = \frac{\hat{e}_k^j(0, \omega)}{\hat{e}_k^{j-1}(0, \omega)}
\]

Given \((2.4)\), this amounts to \( \rho(\omega) = |\alpha^k/\alpha^{k-1}| = |\beta^k/\beta^{k-1}| \). Using \((2.5)\) we obtain

\[
(2.6) \quad \rho(\omega) = \frac{|(\lambda_1(\omega) + D_2 \sigma_2^-)(\lambda_2(\omega) - D_1 \sigma_1^+)|}{|\lambda_1(\omega) + D_1 \sigma_1^+)(\lambda_2(\omega) - D_2 \sigma_2^-)|}
\]

A more general derivation of the convergence factor for the case of an advection-diffusion-reaction problem with discontinuous coefficients can be found in [10]. At this point, we are not able to conclude on the convergence (or the divergence) of the corresponding algorithm because the operators \( \Lambda_j \) have not been explicitly determined. This is often a difficult task to choose them in an appropriate way. The main difficulty comes from the fact that the convergence factor is formulated in the Fourier space, meaning that we can only act on symbols \( \lambda_j \) and not directly on pseudo-differential operators \( \Lambda_j \) in physical space.

2.3. Optimized Schwarz Method. It is possible to find values \( \lambda_1 \) and \( \lambda_2 \) canceling the convergence factor \((2.6)\) and therefore ensuring a convergence in exactly two iterations. Their expressions are

\[
(2.7) \quad \lambda_1^m = -D_2 \sigma_2^- = \sqrt{|\omega| D_2/2} (1 + |\omega| i) \quad \lambda_2^m = D_1 \sigma_1^+ = \sqrt{|\omega| D_1/2} (1 + |\omega| i)
\]

These symbols correspond to so-called absorbing conditions. Unfortunately, since these optimal symbols are not polynomials in \( i\omega \), the absorbing conditions are non-local in time in the physical space. The problem is to find local operators providing a good approximation of non-local ones. The aim is to find a polynomial form in \( i\omega \) to approximate \( \lambda_j^m \). There are mainly two approaches for such an approximation [12]. The first one consists in a low frequency approximation, namely a Taylor expansion for a small \( \omega \). We decided not to adopt this approach because we want to be able to consider a wide range of frequencies. The second, and more sophisticated, approach is to solve a minimax problem to determine local operators that optimize the convergence speed over the full range of admissible frequencies \([\omega_{\text{min}}, \omega_{\text{max}}]\). For a zeroth-order approximation we look for values \( \lambda_j^0 \in IR \) such that \( \lambda_j^0 \approx \lambda_j^m \). The \( \lambda_j^0 \) terms can be defined as the solution of the optimization problem

\[
(2.8) \quad \min_{\lambda_1^0, \lambda_2^0 \in IR} \max_{\omega \in [\omega_{\text{min}}, \omega_{\text{max}}]} \rho(\lambda_1^0, \lambda_2^0, \omega)
\]

Since we work on a discrete problem the frequencies allowed by our temporal grid range from \( \omega_{\text{min}} = \pi/T \) to \( \omega_{\text{max}} = \pi/\Delta t \), where \( \Delta t \) is the time step of the temporal discretization. The analytical resolution of problem \((2.8)\) is not an easy task: the minimization of a maximum is known to be one of the most difficult problem in optimization theory [5]. Moreover, we
work on an optimization for two parameters $\lambda_1^0$ and $\lambda_2^0$ which substantially strengthens the difficulty. Some analytical results exist in the case of two-sided optimization for the 2D stationary diffusion equation [6, 19], and for the 2D Helmholtz equation [11]. In [10], for an advection-diffusion-reaction problem, the asymptotic solution of (2.8) for $\Delta t \to 0$, $\omega_{\min} = 0$, and a positive advection is found in two particular cases: first $\lambda_1^0 = \lambda_2^0$ (one-sided), and second $\lambda_1^0 \neq \lambda_2^0$ (two-sided) but $D_1 = D_2$. In this paper, we intend to study the complete minmax problem (2.8) in the general case $\lambda_1^0 \neq \lambda_2^0$ and $D_1 \neq D_2$. Solving numerically the minmax problem (2.8) is quite expensive from a computational point of view. Moreover this optimization must be performed for any change in the values of $D_1$ and $D_2$. That is why we intend to find an analytical solution in the case of a zeroth-order approximation of the absorbing conditions. This is done with two different sets of interface conditions, first in the Neumann-Robin case, and then in the Robin-Robin case.

The algorithm (2.2) with two-sided Robin conditions is well-posed for any choice of $\lambda_1^0$ and $\lambda_2^0$ such that $\lambda_1^0 + \lambda_2^0 > 0$. This result can be shown following the methodology based on an a priori energy estimate, as described in [1] and [8].

3. Optimized Schwarz method with Neumann-Robin interface conditions. In this section, we assume that the solution in $\Omega_2$ is subject to a Neumann boundary condition. The convergence speed of the Neumann-Robin algorithm is expected to be slower than the one obtained with a Robin-Robin algorithm. However this easier case is treated explicitly because it introduces several methodological aspects useful for the determination of the general Robin-Robin optimized interface conditions. Imposing a Neumann boundary condition to the solution $u_2$ on $\Gamma$ corresponds to having $\Lambda_2 = 0$ in (2.3). The convergence factor $\rho_{nr}$ (NR stands for “Neumann-Robin”), obtained from (2.6), reduces to

$$
(3.1) \quad \rho_{nr} = \left| \frac{D_1 \sigma_1^+ (D_2 \sigma_2^- + \lambda_1)}{D_2 \sigma_2^- (D_1 \sigma_1^+ + \lambda_1)} \right|
$$

**Theorem 3.1 (Optimized Robin parameter).** The analytical solution $\lambda_1^{0,*}$ of the minmax problem

$$
\min_{\lambda_1^0 \in \mathbb{R}} \left( \max_{\omega \in [\omega_{\min}, \omega_{\max}]} \rho_{nr}(\lambda_1^0, D_1, D_2, \omega) \right)
$$

is given by

$$
\lambda_1^{0,*} = \frac{1}{2 \sqrt{2}} \left\{ \left( \sqrt{D_2} - \sqrt{D_1} \right) \left( \sqrt{\omega_{\min}} + \sqrt{\omega_{\max}} \right) \right. \\
+ \left. \sqrt{\left( \sqrt{D_2} - \sqrt{D_1} \right)^2 \left( \sqrt{\omega_{\min}} + \sqrt{\omega_{\max}} \right)^2 + 8 \sqrt{D_1 D_2 \sqrt{\omega_{\min}} \omega_{\max}}} \right\}
$$

**Proof.** Introducing $\zeta = \sqrt{|\omega|D_1}$, $\gamma = \sqrt{D_2/D_1}$, $\lambda_1^0 = \left( \sqrt{\omega_{\min} \omega_{\max}/2} \right) p$ ($p \in \mathbb{R}$), and making explicit $\sigma_1^+$ and $\sigma_2^-$ in (3.1), we obtain

$$
\rho_{nr}(p, \zeta) = \frac{1}{\gamma} \sqrt{\frac{(p - \gamma \zeta)^2 + \gamma^2 \zeta^2}{(p + \zeta)^2 + \zeta^2}},
$$

with $\zeta = \zeta / \sqrt{\omega_{\max} \omega_{\min}}$. Moreover, to ensure the well-posedness of the algorithm we consider $\lambda_1^0 > 0$ (i.e.; $p > 0$). Defining an additional parameter $\mu = \sqrt{\omega_{\max} / \omega_{\min}}$, we thus get
that \( \zeta \) varies between \( \zeta_{\text{min}} = \mu^{-1} \) and \( \zeta_{\text{max}} = \mu \). The aim is to optimize the convergence speed by finding \( p^* \), the solution of the minimax problem

\[
\min_{p > 0} \left( \max_{\zeta \in [\mu^{-1}, \mu]} \rho_{\text{opt}}(p, \zeta) \right).
\]

We first study the behaviour of the derivative of \( \rho_{\text{opt}} \) with respect to \( \zeta \) and \( p \) (with \( \zeta \geq 0 \) and \( p \geq 0 \)). For the sake of simplicity we introduce the variable \( q \) defined by \( q = p/(\gamma - 1 + \sqrt{1 + \gamma^2}) \).

**Restriction of the parameters range.** We can easily show that

\[
\text{Sign} \left( \frac{\partial \rho_{\text{opt}}}{\partial p} \right) = \text{Sign} (q - \zeta).
\]

Looking at the sign of the derivative of \( \rho_{\text{opt}} \) with respect to \( p \), we see that, for all values of \( \zeta \), \( \rho_{\text{opt}} \) is a decreasing function of \( p \) for \( q < \zeta_{\text{min}} = \mu^{-1} \), proving that \( q^* \geq \zeta_{\text{min}} \). A similar argument shows that \( q^* \leq \zeta_{\text{max}} \). This proves that the optimized parameter \( q^* \) satisfies

\[
1/\mu \leq q^* \leq \mu.
\]

Along with (3.2), this shows that the convergence factor has to be an increasing function of \( p \) at \( \zeta = 1/\mu \) and a decreasing function of \( p \) at \( \zeta = \mu \).

**Equioscillation property.** The sign of the derivative of \( \rho_{\text{opt}} \) with respect to \( \zeta \) is given by

\[
\text{Sign} \left( \frac{\partial \rho_{\text{opt}}}{\partial \zeta} \right) = \text{Sign} (\zeta - q).
\]

This relation implies that \( \rho_{\text{opt}} \) has a local minima between \( 1/\mu \) and \( \mu \). The maximum value of the convergence factor is thus attained either at \( \zeta = 1/\mu \) or at \( \zeta = \mu \) (or both). If we assume \( \rho_{\text{opt}}(p, 1/\mu) < \rho_{\text{opt}}(p, \mu) \) it is always possible to decrease the maximum value of \( \rho_{\text{opt}}(p, \zeta) \) by increasing the value of \( p \) so that we must have \( \rho_{\text{opt}}(p, 1/\mu) \geq \rho_{\text{opt}}(p, \mu) \). A similar argument shows that \( \rho_{\text{opt}}(p, \mu) \geq \rho_{\text{opt}}(p, 1/\mu) \). The optimal parameter must thus satisfy the equioscillation property \( \rho_{\text{opt}}(p^*, 1/\mu) = \rho_{\text{opt}}(p^*, \mu) \). After simple algebra, we find that \( p^* \) is solution of

\[
(\gamma - 1) (\mu + 1/\mu) + \frac{2\gamma}{p^*} - p^* = 0.
\]

If we introduce \( v^* = (1 - \gamma) (\mu + 1/\mu) \), the unique positive solution of the equation \( v^* = \frac{2\gamma}{p^*} - p^* \) is given by \( p^* = \frac{1}{2} \left( -v^* + \sqrt{8\gamma + (v^*)^2} \right) \). After substitution of \( \gamma \) and \( \mu \), and multiplication of \( p^* \) by \( \sqrt{\zeta_{\text{min}} \zeta_{\text{max}} / 2} \) we retrieve the expected result for \( \lambda_{1^*} \). \( \Box \)

We find that the optimized convergence factor satisfies an equioscillation property. This concept of equioscillation property comes from the Chebyshev’s alternant theorem (or equioscillation theorem). The similarities between the Chebyshev’s theorem and Optimized Schwarz Method are clearly exposed in [2] and [6]. Two typical optimized convergence factors \( \rho_{\text{opt}} = \rho_{\text{opt}}(\lambda_{1^*}) \) are shown in Fig. 3.1 (left panel) for \( \mu = 2 \) and \( \mu = 6 \), with \( \gamma = 5 \). Note that the performance of the optimized algorithm is only function of the ratio \( \gamma \) between \( D_1 \) and \( D_2 \) and not of the actual values of those parameters. The same remark applies to the temporal frequencies \( \omega_{\text{min}} \) and \( \omega_{\text{max}} \); \( \rho_{\text{opt}}^* \) is only function of their ratio \( \mu \). It is also instructive to look at three particular cases: \( \gamma \to 0^+ \), \( \gamma = 1 \) and \( \gamma \to \infty \).
\[ \rho_{\text{NR}}^*(\omega) \]

\[ \omega_{\text{min}} \]

\[ \omega_{\text{max}} \]

\[ \rho_{\text{NR}}^*(\gamma) \]

\[ \gamma \]

\[ \mu = 2 \]

\[ \mu = 6 \]

\[ \mu = 2 \]

\[ \mu = 6 \]

\[ \gamma \rightarrow 0^+ \quad (D_1 \gg D_2) \]

\[ \lim_{\gamma \rightarrow 0^+} \rho_{\text{NR}}^* = \sqrt{1 - 2 \left( \frac{\mu}{1 + \mu^2} \right)^2}, \quad \lim_{\gamma \rightarrow 0^+} \lambda_1^{0,*} = 0, \quad \text{with } \mu = \left( \frac{\omega_{\text{max}}}{\omega_{\text{min}}} \right)^{1/4} \]

The minimum value of the convergence factor is attained at \( \mu = 1 \) and is equal to \( \sqrt{2}/2 \). When \( \mu \) is increased, the convergence is very slow. Indeed, we tend towards a Neumann-Neumann algorithm in this case.

\[ \gamma = 1 \quad (D_1 = D_2 = D) \]

\[ \rho_{\text{NR}}^* = \sqrt{1 - \frac{2\sqrt{2}\mu}{1 + \mu(\mu + \sqrt{2})}}, \quad \lambda_1^{0,*} = \sqrt{D} \left( \frac{\omega_{\text{max}}}{\omega_{\text{min}}} \right)^{1/4} \]

\( \rho_{\text{NR}}^* \) approaches 1 when \( \mu \) is increased. One can also remark that the optimal parameter \( \lambda_1^{0,*} \) is strictly the same than the one found in [8] in the Robin-Robin one-sided case.

\[ \gamma \rightarrow +\infty \quad (D_1 \ll D_2) \]

\[ \lim_{\gamma \rightarrow +\infty} \rho_{\text{NR}}^* = 0, \quad \lim_{\gamma \rightarrow +\infty} \lambda_1^{0,*} = +\infty \]

When \( \gamma \) tends to \( +\infty \), the convergence is very fast (the convergence factor approaches 0) and the optimal boundary condition tends towards a Neumann-Dirichlet operator.

Those results are illustrated by Fig. 3.1 (right panel). The efficiency of the Neumann-Robin algorithm is greatly improved when \( \gamma \) becomes large and \( \mu \) becomes small. We continue this section by studying the asymptotic convergence rate for the discretized algorithm when the time step \( \Delta t \) goes to 0.
Theorem 3.2 (Asymptotic performance). For \( D_2 > D_1 \) (i.e., \( \gamma > 1 \)), \( \omega_{\text{max}} = \frac{\pi}{\Delta t} \) and \( \Delta t \) goes to zero, the optimal Robin parameter given by Theorem 3.1 is
\[
\lambda_1^{0,\star} \approx \sqrt{2D_1} \left( \frac{\gamma - 1}{2} \sqrt{\pi \Delta t^{-1/2}} + \frac{\gamma^2 + 1}{2(\gamma - 1)} \sqrt{\omega_{\text{min}}^2} \right)
\]
and the asymptotic convergence of the optimized Neumann-Robin algorithm is
\[
\max_{\omega_{\min} \leq \omega \leq \frac{\pi}{\Delta t}} \rho_{\text{opt}}(\lambda_1^{0,\star}, \omega) = \frac{1}{\gamma} \left( 1 - \frac{(\gamma + 1)}{(\gamma - 1)} \frac{\omega_{\text{min}}^2}{\pi} \Delta t^{1/2} \right) + O(\Delta t)
\]
We conclude that zeroth-order optimized Neumann-Robin boundary conditions are efficient when the Robin condition is imposed at the boundary of the domain with the smaller diffusion coefficient (\( \Omega_1 \) here). In this case, the asymptotic convergence factor \( \rho_{\text{opt}} \) is of the form \( \sqrt{D_1/D_2} (1 - O(\Delta t^{1/2})) \) for small \( \Delta t \). In the next section, we study the zeroth-order two-sided Robin-Robin boundary conditions.

4. OSM for a diffusion problem with discontinuous (but constant) coefficients: two-sided Robin transmission conditions. In this section we optimize the conditions on both sides of the interface to get a faster convergence speed whatever the value of the discontinuity \( \gamma \) in the coefficient values at the interface. By keeping the notations \( \zeta, \gamma, \mu, \gamma \) defined in the previous section and by approximating \( \lambda_1^w \) and \( \lambda_2^w \) respectively by \( \lambda_1^o = \sqrt{\min \min \zeta_{\text{max}}} p_2 \) and \( \lambda_2^o = \sqrt{\min \min \zeta_{\text{max}}} p_1 \) the convergence factor \( \rho_{\text{opt}} \) reads
\[
\rho_{\text{opt}}(p_1, p_2, \zeta) = \sqrt{\frac{(p_1 - \zeta)^2 + \zeta^2}{(p_1 + \gamma \zeta)^2 + \gamma^2 \zeta^2} \frac{(p_2 - \gamma \zeta)^2 + \gamma^2 \zeta^2}{(p_2 + \zeta)^2 + \zeta^2}}
\]
We can easily demonstrate that, for nonnegative fixed values of \( \zeta \) and \( \gamma \) and for \( p_1, p_2 > 0 \) we have \( \rho_{\text{opt}}(p_1, p_2, \zeta) < \rho_{\text{opt}}(-p_1, -p_2, \zeta) \), as well as \( \rho_{\text{opt}}(p_1, p_2, \zeta) < \rho_{\text{opt}}(p_1, -p_2, \zeta) \), and \( \rho_{\text{opt}}(p_1, p_2, \zeta) < \rho_{\text{opt}}(-p_1, p_2, \zeta) \). Those three inequalities show that we can restrict our study to strictly positive values of \( p_1 \) and \( p_2 \) (note that \( p_1 = 0 \) or \( p_2 = 0 \) corresponds to the Neumann-Robin case). The restriction of the parameter range to strictly positive values ensures that \( \lambda_1^o + \lambda_2^o > 0 \), and thus that the corresponding problem is well-posed. In the following, we assume that \( \gamma \geq 1 \). The Robin-Robin problem being now symmetric, optimal parameters \( p_1 \) and \( p_2 \) for the case \( \gamma \leq 1 \) can be obtained by switching optimal values for the case \( \gamma \geq 1 \). As done previously we choose the \( p_1 \) and \( p_2 \) values by solving the optimisation problem

\[
\min_{p_1, p_2 > 0} \left( \max_{\zeta \in [\mu^{-1}, \mu]} \rho_{\text{opt}}(p_1, p_2, \zeta) \right)
\]

4.1. Behaviour of the convergence factor with respect to the Robin parameters. First, we study the behaviour of \( \rho_{\text{opt}} \) with respect to the parameters \( p_1 \) and \( p_2 \). We introduce two new parameters \( q_1 \) and \( q_2 \) defined by
\[
q_1 = \frac{p_1}{1 - \gamma + \sqrt{1 + \gamma^2}} \quad q_2 = \frac{p_2}{\gamma - 1 + \sqrt{1 + \gamma^2}}
\]
We can demonstrate that for \( \gamma \geq 1 \) and \( q_1 \leq q_2 \), we have \( \rho_{\text{opt}}(p_1, p_2, \zeta) \leq \rho_{\text{opt}}(p_2, p_1, \zeta) \). This proves that the optimal parameters satisfy \( q_1^\star \leq q_2^\star \). This implies that in turn \( p_1 \leq p_2 \) and that \( p_1 < p_2 \) if \( \gamma > 1 \). This immediately proves that one-sided (\( p_1 = p_2 \)) Robin-Robin boundary conditions are not optimal as soon as \( \gamma > 1 \).
Restriction of the parameters range. Noting that \( \text{Sign} \left( \frac{\partial \rho_{\text{nr}}}{\partial p} \right) = \text{Sign}(q_1 - \zeta) \) and \( \text{Sign} \left( \frac{\partial \rho_{\text{nr}}}{\partial p_2} \right) = \text{Sign}(q_2 - \zeta) \) implies

\[
\frac{\partial \rho_{\text{nr}}}{\partial p_1} > 0 \text{ when } \zeta < q_1 \quad \frac{\partial \rho_{\text{nr}}}{\partial p_1} < 0 \text{ when } \zeta > q_1
\]
\[
\frac{\partial \rho_{\text{nr}}}{\partial p_2} > 0 \text{ when } \zeta < q_2 \quad \frac{\partial \rho_{\text{nr}}}{\partial p_2} < 0 \text{ when } \zeta > q_2
\]

(4.2)

Looking at the sign of the derivatives of \( \rho_{\text{nr}} \) with respect to \( p_1 \) and \( p_2 \) it appears that, if we choose \( q_1 < \zeta_{\text{min}} = \mu^{-1} \), we can decrease the convergence factor by increasing \( p_1 \) because \( \frac{\partial \rho_{\text{nr}}}{\partial p_1} < 0, \forall q_1 > \zeta_{\text{min}} \). A similar argument shows that \( q_2 \leq \zeta_{\text{max}} \). This means that the optimized parameters \( q_1^* \) and \( q_2^* \) must satisfy

\[
\mu^{-1} \leq q_1^* < q_2^* \leq \mu.
\]

(4.3)

(4.2) and (4.3) imply that at \( \zeta = 1/\mu, \rho_{\text{nr}} \) is an increasing function of \( p_1 \) and \( p_2 \) (or \( q_1 \) and \( q_2 \)) while at \( \zeta = \mu, \rho_{\text{nr}} \) is a decreasing function of \( p_1 \) and \( p_2 \) (or \( q_1 \) and \( q_2 \)).

4.2. Extrema of \( \rho_{\text{nr}} \) with respect to \( \zeta \). The next step to solve (4.1) analytically is to find the location of the extrema of \( \rho_{\text{nr}}(p_1, p_2, \zeta, \gamma) \) with respect to \( \zeta \).

THEOREM 4.1 (Extrema of \( \rho_{\text{nr}}(\zeta) \)). \( \rho_{\text{nr}}(p_1, p_2, \zeta) \) has one or three positive local extrema. In the case of one extremum, it corresponds to a minimum and is located at \( \chi = \sqrt{\frac{p_1 p_2}{2\gamma}} \).

Proof.: We start by the following property that can easily be verified:

\[
\rho_{\text{nr}}(p_1, p_2, \zeta) = \rho_{\text{nr}}(p_1, p_2, \chi^2 / \zeta), \text{ where } \chi = \sqrt{\frac{p_1 p_2}{2\gamma}}
\]

After derivation with respect to \( \zeta \), this leads to

\[
\frac{\partial \rho_{\text{nr}}}{\partial \zeta}(p_1, p_2, \zeta) = -\frac{\chi^2}{\zeta^2} \frac{\partial \rho_{\text{nr}}}{\partial \zeta}(p_1, p_2, \chi^2 / \zeta)
\]

(4.4)

which shows that \( \frac{\partial \rho_{\text{nr}}}{\partial \zeta}(p_1, p_2, \pm \chi) = 0 \).

\( \frac{\partial \rho_{\text{nr}}}{\partial \zeta}(p_1, p_2) \) has the sign of \( P(\zeta) \) a (unitary) sixth-order polynomial (the full expression of \( P \) is complicated and not given here). \( P(\zeta) \) has thus either two or six real roots, among them \( \zeta = \chi \) is positive and \( \zeta = -\chi \) is negative. Let us suppose that \( P(\zeta) \) has six real roots. We can show that only three of these six roots (including \( \zeta = \chi \)) are positive. From (4.4) we see that if \( \zeta^0 \) is a root of \( P(\zeta) \), \( \zeta^1 = \chi^2 / \zeta^0 \) is another one. Assuming that the four other roots are positive, we have

\[
\zeta_5 = -\chi < 0 \leq \zeta_6 \leq \zeta_1 \leq \zeta_2 = \chi \leq \zeta_3(= \frac{\chi^2}{\zeta_1}) \leq \zeta_4(= \frac{\chi^2}{\zeta_6}),
\]

and the sum of the six roots must be greater than \( 2\chi \) and is therefore positive. However the sum of the six roots of \( P(\zeta) \) is given by \( -a_5 \) where \( a_5 \) is the coefficient of the \( \zeta^5 \) term and...
is equal to $a_5 = \frac{(\gamma - 1)(p_2 - p_1)}{\gamma}$. Using the fact that $\gamma \geq 1$ and that (4.3) implies $p_2 \geq p_1$, $-a_5$ cannot be positive so that we conclude that we have at most three positive roots for $P(\zeta)$. It can be verified that $P(0) < 0$ and $P(+\infty) > 0$ so that if only one positive root exists (at $\zeta = \chi$), it is a local minimum. \( \square \)

4.3. Equioscillation of $\rho_{RR}$ at the end points. Theorem 4.2 (Equioscillation at the end points). The optimized convergence factor $\rho_{HH}(p_1^*, p_2^*, \zeta)$ satisfies

- $\rho_{HH}(p_1^*, p_2^*, \chi) \leq \max \left( \rho_{HH}(p_1^*, p_2^*, \mu^{-1}), \rho_{HH}(p_1^*, p_2^*, \mu) \right)$ with $\chi = \sqrt{\frac{p_1 p_2}{2\gamma}}$
- the equioscillation property:
  $\rho_{HH}(p_1^*, p_2^*, \mu^{-1}) = \rho_{HH}(p_1^*, p_2^*, \mu)$ which holds only for $p_1^* p_2^* = 2\gamma$

**Proof.** We first demonstrate that $\rho_{HH}(p_1^*, p_2^*, \chi) \leq \max \left( \rho_{HH}(p_1^*, p_2^*, \mu^{-1}), \rho_{HH}(p_1^*, p_2^*, \mu) \right)$.

If $\chi$ is the only positive root of $\frac{\partial \rho_{HH}(\zeta)}{\partial \zeta}$, this is trivial since $\chi$ is a local minimum. Let’s look at the case where there are three positive roots, in this case $\chi$ is a local maximum.

From the identity $\chi = \sqrt{\frac{p_1 p_2}{2\gamma}} = \sqrt{q_1 q_2}$ and (4.3) we get

\[(4.5) \quad 1/\mu \leq q_1 \leq \chi = \sqrt{q_1 q_2} \leq q_2 \leq \mu\]

We already know that at $\zeta = 1/\mu$, $\rho_{HH}$ is a decreasing function of $q_1$ and that at $\zeta = \mu$, $\rho_{HH}$ is an increasing function of $q_1$. (4.5) shows that at $\zeta = \chi$, $\rho_{HH}$ is an increasing function of $q_1$ since $q_1 \leq \chi$. If we assume that $\rho_{HH}(p_1^*, p_2^*, \chi) \geq \rho_{HH}(p_1^*, p_2^*, \mu^{-1})$ then we can always decrease $q_1$ (or $p_1$) such that it improves the convergence factor (by reducing the values both at $\zeta = \chi$ and at $\zeta = \mu$). Playing with $q_2$ we can similarly prove that $\rho_{HH}(p_1^*, p_2^*, \chi) \leq \rho_{HH}(p_1^*, p_2^*, \mu)$. Note that this also demonstrates that $\zeta_1 \geq 1/\mu$ and $\zeta_3 \leq \mu$. This is sufficient to fully describe the behaviour of the convergence factor with respect to $q_1$, $q_2$, and $\zeta$, as shown in Fig. 4.1. In practice, the two cases will be differentiated by the sign of the second-order derivative of $\rho_{HH}(p_1, p_2, \zeta)$ at $\zeta = \chi$. The following proves that the values taken by $\rho_{HH}(p_1^*, p_2^*, \zeta)$ at the two end points $\zeta = 1/\mu$, and $\zeta = \mu$ are equal. Indeed if we consider

![](image)

**Fig. 4.1. Behaviour of the convergence factor with respect to $\zeta$**
\( \rho_{\text{sh}}(p_1, p_2, 1/\mu) < \rho_{\text{sh}}(p_1, p_2, \mu) \) (resp. \( \rho_{\text{sh}}(p_1, p_2, 1/\mu) > \rho_{\text{sh}}(p_1, p_2, \mu) \)), it is always possible to decrease the maximum value of \( \rho_{\text{sh}}(\zeta) \) by increasing (resp. decreasing) the values of \( p_1 \) (resp. \( p_2 \)). Thus the optimal parameters must satisfy \( \rho_{\text{sh}}(p_1^*, p_2^*, \mu^{-1}) = \rho_{\text{sh}}(p_1^*, p_2^*, \mu) \): the equioscillation property.

This holds for

\[
(4.6) \quad (p_1 + p_2)(2\gamma - p_1 p_2)S(p_1, p_2, \mu, \gamma) = 0
\]

with

\[
S(p_1, p_2, \mu, \gamma) = 2 \left[ (1 + \gamma^2) - \gamma(\mu + \mu^{-1})^2 \right] p_1 p_2 + (\gamma - 1)(\mu + 1/\mu)(p_1 - p_2)(2\gamma + p_1 p_2) + 2\gamma(p_1 - p_2)^2 - (2\gamma - p_1 p_2)^2
\]

Obviously every couple \((p_1, p_2)\) that satisfies the relation \(p_1 p_2 = 2\gamma\) is solution to (4.6). We now show that there are no other admissible values. Other potential solutions of the problem are the solutions of \(S(p_1, p_2, \mu) = 0\). \(S\) can be seen as a second-order polynomial in \(p_2\) and thus has two real solutions:

\[
(4.7) \quad p_2 = f_1(p_1) \quad p_2 = f_2(p_1)
\]

If we assume that \(p_2\) is related to \(p_1\) with one of the relations (4.7), looking at Fig. 4.1 we can argue that for any couple \((p_1, p_2)\) we must have \(dp_2/dp_1 < 0\) to satisfy an equioscillation property. Indeed let \(\rho_{\text{sh}}^\dagger(p_1, \zeta)\) be defined as

\[
\rho_{\text{sh}}^\dagger(p_1, \zeta) = \rho_{\text{sh}}(p_1, p_2(p_1), \zeta)
\]

Then

\[
(4.8) \quad \frac{\partial \rho_{\text{sh}}^\dagger(p_1, \zeta)}{\partial p_1} = \frac{\partial \rho_{\text{sh}}(p_1, p_2(p_1), \zeta)}{\partial p_1} + \frac{\partial \rho_{\text{sh}}(p_1, p_2(p_1), \zeta)}{\partial p_2} \frac{dp_2}{dp_1}
\]

We have already proved that the following properties must hold

\[
(4.9) \quad \frac{\partial \rho_{\text{sh}}(p_1, p_2(p_1), 1/\mu)}{\partial p_1} > 0, \quad \frac{\partial \rho_{\text{sh}}(p_1, p_2(p_1), 1/\mu)}{\partial p_2} > 0
\]

\[
\frac{\partial \rho_{\text{sh}}(p_1, p_2(p_1), \mu)}{\partial p_1} < 0, \quad \frac{\partial \rho_{\text{sh}}(p_1, p_2(p_1), \mu)}{\partial p_2} < 0
\]

If we suppose \(dp_2/dp_1 > 0\) then (4.8) and (4.9) show that \(\rho_{\text{sh}}^\dagger(p_1, 1/\mu)\) is an increasing function of \(p_1\) while \(\rho_{\text{sh}}^\dagger(p_1, \mu)\) is a decreasing function of \(p_1\). Hence, (4.9) and the equioscillation property cannot be satisfied at the same time if \(dp_2/dp_1 > 0\). It can be shown that the two solutions given by (4.7) do not verify this last condition. Indeed one can prove that we have \(df_1/dp_1 > 0\) and \(df_2/dp_1 > 0\). Details of the computations are omitted here but we mention that the only conditions necessary to find this result are \(\gamma > 0, \mu > 1\). We can conclude that \(p_1^* p_2^* = 2\gamma\) is the only solution leading to an equioscillation property. \(\Box\)

It is worth mentioning that \(\chi = \sqrt{\frac{p_1 p_2}{2\gamma}} = 1\) and that

\[
\rho_{\text{sh}}(p_1^*, p_2^*, \zeta) = \rho_{\text{sh}}(p_1^*, p_2^*, 1/\zeta) \quad \forall \zeta \in [1/\mu, \mu]
\]
**4.4. Solution of the minmax problem.** The convergence factor is now a function of $p_1$ and $\zeta$ only:

$$\rho_{sa}(p_1, \zeta) = \rho_{sa}(p_1, 2\gamma/p_1, \zeta)$$

**Lemma 4.3.** The solution of the minmax problem is given by the solution of the minimization of $\rho_{sa}(p_1, 1/\mu)$. The minimization must be done under the constraint that $p_1^* \geq p_1^{\ast, \text{equi}}$, where $p_1^{\ast, \text{equi}}$ is the solution of the three point equioscillation problem $\rho_{sa}(p_1, 1) = \rho_{sa}(p_1, 1/\mu) = \rho_{sa}(p_1, \mu)$

Thanks to Fig. 4.1 we can remark that the resolution of the minmax problem corresponds to the minimization of $\rho_{sa}(p_1, 1/\mu)$ (or $\rho_{sa}(p_1, \mu)$) with respect to $p_1$. If we are in the case where $\chi = 1$ is a local maximum, the additional constraint given by theorem (4.2) must be imposed

$$\rho_{sa}(p_1, 1) \leq \rho_{sa}(p_1, 1/\mu) \quad (4.10)$$

Knowing that $p_1 p_2 = 2\gamma$, or equivalently $q_1 q_2 = 1$, the range of admissible values given by (4.3) can now be written $1/\mu \leq q_1 \leq 1$ and translates in terms of the variable $p_1$:

$$p_1 \in [p_{1,\text{min}}, p_{1,\text{max}}] \quad \text{where} \quad p_{1,\text{min}} = (1 - \gamma + \sqrt{1 + \gamma^2})/\mu, \quad p_{1,\text{max}} = (1 - \gamma + \sqrt{1 + \gamma^2}) \quad (4.11)$$

Moreover it can be shown that $\rho_{sa}(p_1, 1)$ is a decreasing function of $p_1$ and therefore the constraint (4.10) can also be written $p_1^* \geq p_1^{\ast, \text{equi}}$, where $p_1^{\ast, \text{equi}}$ is the solution of a three point equioscillation problem $\rho_{sa}(p_1^{\ast, \text{equi}}, 1) = \rho_{sa}(p_1^{\ast, \text{equi}}, 1/\mu) = \rho_{sa}(p_1^{\ast, \text{equi}}, \mu)$.

We now look at the minimization of $\rho_{sa}(p_1, 1/\mu)$ for $p_1 \in [p_{1,\text{min}}, p_{1,\text{max}}]$.

**Lemma 4.4.** For $\gamma > 1$, the derivative of $\rho_{sa}(p_1, 1/\mu)$ has exactly one root in the range $[p_{1,\text{min}}, p_{1,\text{max}}]$. This root corresponds to a local minimum of $\rho_{sa}(p_1, 1/\mu)$. In the special case $\gamma = 1$, $p_1 = p_{1,\text{max}}(= \sqrt{2})$ is always a root of $\partial \rho_{sa}(p_1, 1/\mu)/\partial p_1$. The derivative of $\rho_{sa}(p_1, 1/\mu)$ can be written as

$$\partial \rho_{sa}(p_1, 1/\mu)/\partial p_1 = g(p_1, \mu)N(p_1, \mu)$$

where $g$ is a strictly positive function and $N(p_1, \mu)$ a sixth-order polynomial in $p_1$. The change of variable $v = 2\gamma/p_1 - p_1$ transforms $N(p_1, \mu)$ in

$$N(p_1, \mu) = p_1^2 Q(v)$$

where $Q(v)$ is the third-order polynomial given by

$$Q(v) = 8(\gamma - 1)(1 + \gamma^2) + 2\beta(\gamma \beta^2 - 3(1 + \gamma^2))v + 2(\gamma - 1)\beta^2 v^2 - \beta v^3$$

with $\beta = 1/\mu + \mu$.

It can be shown that, for $\gamma > 1$, this polynomial has only one root in $[v_{\text{min}}, v_{\text{max}}]$ where, according to (4.11), $v_{\text{min}}$ and $v_{\text{max}}$ are given by

$$v_{\text{min}} = 2(\gamma - 1), \quad v_{\text{max}} = (\gamma - 1)\beta + \sqrt{1 + \gamma^2} \sqrt{\beta^2 - 4} \quad (4.13)$$

This root corresponds to a minimum of $\rho_{sa}(p_1, 1/\mu)$ since it can be found that $\partial \rho_{sa}(p_1, 1/\mu)/\partial p_1 \leq 0$ and $\partial \rho_{sa}(p_1, 1/\mu)/\partial p_1 \geq 0$. For $\gamma = 1$, $v = v_{\text{min}} = 0$ (i.e., $p_1 = p_{1,\text{max}} = \sqrt{2}$) is always
a root of $Q(v)$. Fig. 4.2 illustrates the variations of $\rho^\dagger_{ka}(p_1,1/\mu)$ with $p_1$. $p_1^{\min}$ is the location of the minimum of $\rho^\dagger_{ka}(p_1,1/\mu)$ over $[p_{1,\min},p_{1,\max}]$. The solution of the constrained minimization problem is now easily handled: if $p_1^{\min} \leq p_1^{*,\text{equi}}$ the solution of the minmax problem is given by $p_1^{*,\text{equi}}$, otherwise the solution of the minmax problem is given by $p_1^{\min}$.

The inequality $p_1^{\min} \leq p_1^{*,\text{equi}}$ is satisfied if and only if $\frac{\partial \rho^\dagger_{ka}(p_1^{*,\text{equi}},1/\mu)}{\partial p_1} \geq 0$ or equivalently $Q(v^{*,\text{equi}}) \geq 0$ (where $v^{*,\text{equi}} = 2\gamma/p_1^{*,\text{equi}} - p_1^{*,\text{equi}}$).

Finally the following result is useful: for $v \geq v_{\max}$ or equivalently $p_1 \leq p_{1,\min}$ we have $Q(v) \leq 0 \left( \text{or } \frac{\partial \rho^\dagger_{ka}(p_1,1/\mu)}{\partial p_1} \leq 0 \right)$. Indeed, using relation (4.8) at $\zeta = 1/\mu$:

$$\frac{\partial \rho^\dagger_{ka}(p_1,1/\mu)}{\partial p_1} = \frac{\partial \rho_{ka}(p_1,p_2(p_1),1/\mu)}{\partial p_1} + \frac{\partial \rho_{ka}(p_1,p_2(p_1),1/\mu)}{\partial p_2} \frac{dp_2}{dp_1}$$

If $p_1 \leq p_{1,\min}$, $\frac{\partial \rho_{ka}(p_1,p_2(p_1),1/\mu)}{\partial p_1} < 0$, but the relation $p_2 = 2\gamma/p_1$ implies $p_2 \geq p_{2,\max} \left( = \left( \gamma - 1 + \sqrt{1 + \gamma^2} \right) \mu \right)$ so that $\frac{\partial \rho_{ka}(p_1,p_2(p_1),1/\mu)}{\partial p_2} \geq 0$. Using $\frac{dp_2}{dp_1} = -2\gamma/p_1^2 \leq 0$, this proves that $\frac{\partial \rho^\dagger_{ka}(p_1,1/\mu)}{\partial p_1} \leq 0$.

We are now done with the problem of finding the solution of the three point equioscillation problem.

**Theorem 4.5** (Equioscillation between 3 points). *The only parameters $p_1^{*,\text{equi}}$ and $p_2^{*,\text{equi}}$, such that $p_1^{*,\text{equi}} \leq p_{1,\max}^{*}$ that satisfy an equioscillation of the convergence factor $\rho_{ka}$ between the three points $(1/\mu, 1, \mu)$ are*

$$\begin{align*}
p_1^{*,\text{equi}} &= \frac{1}{2} \left[ -v^{*,\text{equi}} + \sqrt{8\gamma + (v^{*,\text{equi}})^2} \right] \\
p_2^{*,\text{equi}} &= 2\gamma \left( p_1^{*,\text{equi}} \right)^{-1}
\end{align*}$$

*where*

$$v^{*,\text{equi}} = \frac{1}{2} \left[ (2 + \beta)(\gamma - 1) + \sqrt{4(1 + \gamma)^2(\beta - 1) + \beta^2(\gamma - 1)^2} \right]$$
Note that this additional result can also be shown: 

\[ f(\beta) = \frac{(\beta - 2)^3 \beta (\beta + 2) + (4 + 2\beta - \beta^2) \sqrt{-16 + 48\beta - 44\beta^2 + 12\beta^3 + 3\beta^4 - 4\beta^5 + \beta^6}}{16 - 16\beta - 4\beta^2 + \beta^4} \]

\( f(\beta) \) for \( \beta^0 < \beta < 1 + \sqrt{5} \) is plotted on Fig. 4.3. We can remark that \( f(\beta) \geq 1 \), \( \forall \beta \) so that the condition \( \gamma \geq f(\beta) \) is always false for \( \gamma = 1 \) (continuous case).
It is also interesting to know if \( \chi = \sqrt{\frac{p_1 p_2}{2\gamma}} = 1 \) is either a local minimum or a local maximum of the optimized convergence factor by looking at the sign of \( \frac{\partial^2 \rho_{\text{opt}}^1}{\partial \chi^2}(p_1, \chi) \). It can be proved that in terms of the variable \( v = 2\gamma/p_1 - p_1 \), the inequality \( \frac{\partial^2 \rho_{\text{opt}}^1}{\partial \chi^2}(p_1, \chi) > 0 \) can be written:

\[
v \geq v_0, \quad \text{where } v_0 = 2(\gamma - 1) + \sqrt{2(1 + \gamma^2)}
\]

We deduce that \( \zeta = \chi = 1 \) is a local minimum only if \( v^{*, \text{mini}} \leq v_0 \). This can be checked by evaluating the polynomial \( Q(v) \) at \( v = v_0 \) and looking at the sign of the result: if \( Q(v_0) \leq 0 \) then \( v^{*, \text{mini}} \leq v_0 \) and we have a local minimum at \( \zeta = \chi = 1 \).

It can be found that

\[
Q(v_0) < 0 \iff 2 < \beta < \beta_0 \quad \text{or } \left( \beta_0 \leq \beta \leq 2\sqrt{2} \text{ and } \gamma < g(\beta) \right)
\]

where \( \beta_0 = \frac{8 + 5\sqrt{2}}{2(3 + 2\sqrt{2})} + \frac{\sqrt{90 + 64\sqrt{2}}}{2(3 + 2\sqrt{2})} \approx 2.44547 \). The analytical expression of \( g(\beta) \) is complicated and is not given here. Note that \( g(\beta) \geq 1 \), \( \forall \beta \) so that for the special case \( \gamma = 1 \), \( Q(v_0) < 0 \) is equivalent to \( 2 < \beta \leq 2\sqrt{2} \).

Fig. 4.4 summarizes the three different domains: 3 point equioscillation, 2 point equioscillation with \( \chi \) as a local maximum and 2 point equioscillation with \( \chi \) as a local minimum.

The resulting optimized convergence factor is shown in Fig. 4.5 with respect to \( \mu \) and \( \gamma \).

We can draw the following remarks about the convergence properties of the Schwarz algorithms: the convergence speed increases when the discontinuities of the coefficients (\( \gamma \)) is increased and the convergence speed decreases when \( \mu \), an increasing function of the ratio \( \frac{\omega_{\text{max}}}{\omega_{\text{min}}} \), is increased. In Fig. 4.6 we compare, for \( \mu = 2 \) and \( \mu = 6 \), the results found in the optimized two-sided case with the optimized Robin-Neumann transmission conditions (found in Sec. 3). The Robin-Robin approach is significantly more efficient than the Robin-Neumann approach when \( \gamma \) is close to one. When \( \gamma \) is increased, both tends towards a Dirichlet-Neumann operator.
FIG. 4.4. The three different domains of three point equioscillation (black), two point equioscillation with $\chi$ being a local maximum (dark grey) and two point equioscillation with $\chi$ being a local minimum (light grey)

FIG. 4.5. Optimized convergence factor with respect to $\mu$ and $\gamma$ ($1 \leq \mu \leq 10$, $1 \leq \gamma \leq 10$)

**THEOREM 4.7** (Asymptotic performance). For $D_2 > D_1$ (i.e., $\gamma > 1$), $\omega_{\text{max}} = \frac{\pi}{\Delta t}$, and $\Delta t$ goes to zero, the optimal Robin parameters given by Theorem 4.6 are

$$\lambda^0_{1,*} \approx \lambda^0_{1,(as)} = \sqrt{2D_1} \left( \frac{\gamma}{\gamma - 1} \sqrt{\omega_{\text{min}}} - 2\gamma \frac{\gamma^2 + 1}{(\gamma - 1)^3 \pi^{1/4}} \omega_{\text{min}}^{3/4} \Delta t^{1/4} \right)$$
$\lambda_2^{0,*} \approx \lambda_2^{0,(as)} = \sqrt{2D_1} \left( \frac{\gamma - 1}{2} \sqrt{\pi} \Delta t^{-1/2} + \frac{\gamma^2 + 1}{\gamma - 1} (\pi \omega_{\min})^{1/4} \Delta t^{-1/4} \right)$

and the asymptotic convergence of the optimized two-sided Robin-Robin algorithm is

$$\max_{\omega_{\min} \leq \omega \leq \pi} \rho_{\text{sn}}(\lambda_1^{0,*}, \lambda_2^{0,*}, \omega) = \frac{1}{\gamma} \left( 1 - 2 \frac{(\gamma + 1)}{(\gamma - 1)} \left( \frac{\omega_{\min}}{\pi} \right)^{1/4} \Delta t^{1/4} \right) + O(\Delta t^{1/2})$$

Note that those asymptotic results are obtained by assuming that $\nu^{*} = \nu^{*,\text{equi}}$, which is always the case when $\Delta t \to 0$ (i.e., $\mu \to \infty$), as shown by (4.15). The optimized Robin-Robin conditions lead to an asymptotic convergence factor of the form $\sqrt{D_1/D_2} \left( 1 - O(\Delta t^{1/4}) \right)$ for small $\Delta t$ and $D_1 < D_2$. The associated algorithm is thus less sensitive to $\Delta t$ than the Neumann-Robin algorithm. However, the asymptotic Robin parameters given in Theorem 4.7 must be used with caution as they degenerate when $\gamma \to 1$, as well as when $\Delta t \gg 0$ (in this case $\lambda_1^{0,(as)}$ can become negative). It is worth mentioning that the asymptotic bound on the optimized convergence factor given in Theorem 4.7 shows that the optimized Robin-Robin conditions will always be more efficient than Dirichlet-Neumann conditions. Indeed, it can easily be checked that the multiplying term $1/\gamma$ in front of the bound correspond to the convergence factor of the Dirichlet-Neumann algorithm.

Furthermore, we can not directly compare this result with the one obtained in [10] for the advection-diffusion-reaction equation. The latter study is done by assuming $\omega_{\min} = 0$ and as a result of this assumption their optimized parameter, when canceling the advection and reaction coefficients, are simply $\lambda_1^{0,*} = \lambda_2^{0,*} = 0$. Indeed, one can easily find that for a diffusion problem the low frequency approximation $\lambda_j^{\text{opt}}$ of the absorbing conditions $\lambda_j^\nu$, given in (2.7), for $\omega_{\min} \to 0$ is indeed $\lambda_j^\nu = 0$.

**4.5. The continuous case.** Because the two-sided Robin-Robin case with continuous diffusion coefficients has never been studied in the literature we now provide the results in this particular case.
In that case, the solution of the minmax problem is given by
\[ v = \begin{cases} 
2 \sqrt{\beta - 1} & \text{if } \beta \geq 1 + \sqrt{5} \\
\sqrt{2\beta^2 - 12} & \text{if } \sqrt{6} \leq \beta < 1 + \sqrt{5} \\
0 & \text{if } 2 < \beta < \sqrt{6}
\end{cases} \]

with \( \beta = \sqrt[4]{\omega_{\max}/\omega_{\min}} \).

Proof: We use theorem (4.6) which gives the optimal conditions in the general case. As already mentioned the condition \( Q(v^{*,\text{equi}}) \geq 0 \) reduces for \( \gamma = 1 \) to \( \beta \geq 1 + \sqrt{5} \). In that case, the solution of the minmax problem is given by \( v^* = v^{*,\text{equi}} = 2\sqrt{\beta - 1} \). If \( \beta < 1 + \sqrt{5} \), we have to compute \( v^{*,\text{min}} \) the value that cancels \( Q(v) \) over \([v_{\min}, v_{\max}]\) where \( v_{\min} = 0 \), \( v_{\max} = 2\sqrt{\beta^2 - 4} \). For \( \gamma = 1 \), the expression (4.12) of the polynomial \( Q(v) \) is
\[ Q(v) = -\beta v \left( v^2 - (2\beta^2 - 12) \right) \]

We find that
\[ v^{*,\text{min}} = \begin{cases} 
\sqrt{2\beta^2 - 12} & \text{if } \beta \geq \sqrt{6} \\
0 & \text{if } 2 < \beta \leq \sqrt{6}
\end{cases} \]

Note that when \( \beta \leq \sqrt{6} \) we get \( v^* = 0 \). This implies \( \lambda_1^{0,*} = \lambda_2^{0,*} = \sqrt{D} (\omega_{\min}/\omega_{\max})^{1/4} \), which corresponds to the zeroth-order one-sided optimal parameters found in [8]. □

5. Numerical experiments with two subdomains. The model problem (2.2) is discretized using a backward Euler scheme in time and a second-order scheme on a staggered grid in space. For the interior points the scheme is
\[ \frac{u_k^{n+1} - u_k^n}{\Delta t} = \frac{1}{x_{k+\frac{1}{2}} - x_{k-\frac{1}{2}}} \left[ F_{k+\frac{1}{2}}^{n+1} - F_{k-\frac{1}{2}}^{n+1} \right] \]

with \( F_{k+\frac{1}{2}} = D_{k+\frac{1}{2}} \frac{u_{k+1}^n - u_k^n}{x_{k+1} - x_k} \). Note that for practical applications the use of the Crank-Nicolson scheme in time is avoided because this scheme leads to unphysical behaviour. Indeed, unlike the backward Euler scheme, the Crank-Nicolson scheme fails to satisfy the so-called monotonic damping property [21]. We decompose the computational domain \( \Omega \) into two non-overlapping subdomains \( \Omega_1 = [-L_1, 0] \) and \( \Omega_2 = [0, L_2] \), with \( L_1 = L_2 = 500 \) m. An homogeneous Neumann boundary condition is imposed at \( x = -L_1 \) and \( x = L_2 \). As it is usually done in numerical models, the resolution \( \Delta x_k \) is progressively refined to enhance the resolution in the boundary layers in the vicinity of the air-sea interface. We use \( N = 75 \) points in each subdomain and the resolution varies from \( \Delta x_k = 25 \) m at \( x = L_1 \) (resp.
we show the convergence is close to one. Asymptotic results for Robin-Robin conditions are significantly more efficient, especially when the ratio between the other methods using the Neumann-Robin or Dirichlet-Neumann conditions, these two-sided property between two or three points depending on the parameter values. In comparison with the problem. We show that the optimized convergence factor satisfies an equioscillation of the problem. We analytically study the behavior of the convergence factor with respect to the parameters.

\[ g_{N+\frac{1}{2}} = D_{N-\frac{1}{2}} \frac{u_N - u_{N-1}}{x_N - \frac{1}{2} - x_{N-\frac{1}{2}}} + \lambda u_N, \]

where \( \lambda \) is the Robin parameter. We simulate directly the error equations; i.e., \( f_1 = f_2 = 0 \) in (2.2) and \( u_0(x) = 0 \). We start the iteration with a random initial guess \( u^0(0, t) (t \in [0, T]) \) so that it contains a wide range of the temporal frequencies that can be resolved by the computational grid. We perform simulations for four different types of transmission conditions at \( x = 0 : \) Dirichlet-Neumann (DN), optimized Neumann-Robin (NR*), optimized Robin-Robin (RR*), and asymptotically optimized Robin-Robin (RR\textsuperscript{(as)}). In Fig. 5.1 we show the evolution of the \( L^\infty \)-norm of the error obtained for those four cases for \( \gamma = 10^\frac{1}{2} \approx 1.7783 \), \( \gamma = \sqrt{10} \approx 3.1623 \), and \( \gamma = 10 \), with \( \mu = 6 \) and \( \mu = 12 \). We choose \( \Delta t = 100 \) s, \( D_2 = 0.5 \text{ m}^2 \text{s}^{-1} \), \( D_1 \) is then deduced depending on the value of \( \gamma \). As expected, we get the best results with the two-sided Robin conditions. Consistent with Fig. 4.5 the convergence is faster when \( \gamma \) is large and when \( \mu \) is small. Moreover, when the discontinuity \( \gamma \) between the diffusion coefficients is increased the algorithm becomes less and less sensitive to the choice of transmission conditions and to the parameter \( \mu \). The asymptotic optimized Robin-Robin conditions provide a good approximation of the optimized Robin-Robin conditions, even for \( \Delta t = 100 \) s \( \gg 0 \). Those conditions are especially efficient when \( \gamma \) is sufficiently larger than 1. Finally, we remark that the optimized Neumann-Robin conditions provide only a slight improvement compared to the classical Dirichlet-Neumann conditions.

**Conclusion.** In this paper, we obtain new results for an optimized Schwarz method defined on non-overlapping diffusion problems with discontinuous coefficients. This method uses zeroth-order two-sided Robin transmission conditions; i.e., we consider two different Robin conditions on each side of the interface. We base our approach on a model problem with two subdomains and we prove the convergence of the corresponding algorithm. Then we analytically study the behavior of the convergence factor with respect to the parameters of the problem. We show that the optimized convergence factor satisfies an equioscillation property between two or three points depending on the parameter values. In comparison with other methods using the Neumann-Robin or Dirichlet-Neumann conditions, these two-sided Robin-Robin conditions are significantly more efficient, especially when the ratio between the discontinuous coefficients is close to one. Asymptotic results for \( \Delta t \) small are given. Numerical results show the performance of the different type of transmission conditions introduced in this paper. Those results are consistent with the analytical study.

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**REFERENCES**

\[ \text{Fig. 5.1. Convergence for } \gamma = 10^{\frac{1}{4}} \text{ (top, left), } \gamma = \sqrt{10} \text{ (top, right), and } \gamma = 10 \text{ (bottom, left) for } \mu = 6 \text{ and } \mu = 12 \text{ in the DN, RR}^\star \text{ and NR}^\star \text{ cases. Comparison between RR}^\star \text{ and RR}^{(as)} \text{ (bottom, right).} \]


