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ON THE CLASSIFICATION OF MAPPING CLASS
ACTIONS ON THURSTON’S ASYMMETRIC METRIC

L. LIU, A. PAPADOPOULOS, W. SU, AND G. THÉRET

Abstract. We study the action of the elements of the mapping class
group of a surface of finite type on the Teichmüller space of that surface
equipped with Thurston’s asymmetric metric. We classify such actions
as elliptic, parabolic, hyperbolic and pseudo-hyperbolic, depending on
whether the translation distance of such an element is zero or positive
and whether the value of this translation distance is attained or not,
and we relate these four types to Thurston’s classification of mapping
classes. The study is parallel to the one made by Bers in the setting of
Teichmüller space equipped with Teichmüller’s metric, and to the one
made by Daskalopoulos and Wentworth in the setting of Teichmüller
space equipped with the Weil-Petersson metric.

AMS Mathematics Subject Classification: 32G15 ; 30F60 ; 57M50 ; 57N05.

Keywords: Teichmüller space; Thurston’s asymmetric metric; mapping class
group.

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1. Introduction

Let $S = S_{g,n}$ be a connected oriented surface of finite type, of genus $g$
with $n$ punctures. We assume that the Euler characteristic of $S$ is negative.
We shall consider hyperbolic structures on $S$ and any such structure will
be complete and of finite area. We say that two complex structures (re-
spectively hyperbolic structures) $X$ and $Y$ on $S$ are equivalent if there is a
conformal map (respectively an isometry) from $X$ to $Y$ which is homotopic
to the identity map of $S$. The Teichmüller space $\mathcal{T}(S)$ of $S$ is the space of
complex structures (or, equivalently, the space of hyperbolic structures) on
$S$ up to equivalence.
An asymmetric metric on a set $M$ is a nonnegative function $\delta$ on $M \times M$ which satisfies the axioms of a metric except the symmetry axiom, that is, we do not require that $\delta(x, y) = \delta(y, x)$ for all $x, y \in M$.

Thurston defined in [17] an asymmetric metric $d_L$ on $\mathcal{T}(S)$ by setting for each $X, Y \in \mathcal{T}(S)$

$$d_L(X, Y) = \inf_f \log L_f,$$

where $X$ and $Y$ are considered as (equivalence classes of) complete finite area hyperbolic structures on $S$, where the infimum is take over all homeomorphisms $f : X \to Y$ which are homotopic to the identity map of $S$ and where $L_f$ is the Lipschitz constant of $f$, that is,

$$L_f = \sup_{x \neq y} \frac{d_Y(f(x), f(y))}{d_X(x, y)}$$

for $x$ and $y$ in $X$.

We shall call this asymmetric metric the \textit{Thurston asymmetric metric}.

Thurston [17] proved that there is a (not necessarily unique) extremal Lipschitz homeomorphism that realizes the infimum in (1), and that

$$d_L(X, Y) = \log \sup_{\gamma} \frac{\ell_Y(\gamma)}{\ell_X(\gamma)},$$

where $\ell_X(\gamma)$ denotes the hyperbolic length of $\gamma$ in $X$ and $\gamma$ ranges over all essential (that is, neither homotopic to a point nor a puncture) simple closed curves on $S$. We denote the Lipschitz constant of such an extremal Lipschitz map by $L(X, Y)$. Thurston showed that this function $d_L$ is indeed an asymmetric metric on Teichmüller space, that it is a Finsler metric and that any two points in Teichmüller space can be joined by a (not necessarily unique) $d_L$-geodesic (that is, a shortest path with respect to $d_L$). Thurston also made a relation between extremal Lipschitz maps and a class of $d_L$-geodesics called \textit{stretch lines}. (We shall recall the definition below.)

The Teichmüller metric is defined by

$$d_T(X, Y) = \frac{1}{2} \inf_f \log K_f(X, Y),$$

where $K_f(X, Y)$ is the quasiconformal dilatation of a homeomorphism $f : X \to Y$ homotopic to the identity map of $S$. Using a lemma of Wolpert, we have [18], $d_L \leq 2d_T$.

By definition, the topology induced by Thurston’s asymmetric metric on $\mathcal{T}(S)$ is the one induced by its symmetrization,

$$\frac{1}{2} \{ d_L(X, Y) + d_L(Y, X) \}$$

which is a genuine metric. This topology coincides with the one induced by the Teichmüller metric, see Li [8] and Papadopoulos-Théret [12] for information about the symmetrization. In an asymmetric metric space $(M, \delta)$, the left and right open balls centered at a point $x$ and of radius $\epsilon$, defined respectively by

$$\{ y \in M \mid \delta(x, y) < \epsilon \}$$

and

$$\{ y \in M \mid \delta(y, x) < \epsilon \}$$
may have completely different behaviors. Endowed with Thurston’s asymmetric metric, the space \( T(S) \) is complete, and the left and right closed balls are compact. See [9], [12] and [13] for the topology induced by this asymmetric metric.

The mapping class group \( \text{Mod}(S) \) of \( S \) is the group of homotopy classes of orientation-preserving homeomorphisms of \( S \). This group acts properly discontinuously and isometrically on \( T(S) \) endowed with Teichmüller’s metric or with Thurston’s asymmetric metric. The quotient space is the moduli space

\[
\mathcal{M}(S) = T(S)/\text{Mod}(S).
\]

Thurston used his compactification of \( T(S) \) by the space of projective measured foliations to prove the following theorem (see Thurston [16], Theorem 4 or [6] for details).

**Theorem 1.1 (Nielsen-Thurston classification).** Each \( \varphi \in \text{Mod}(S) \) is either periodic, reducible or pseudo-Anosov. Pseudo-Anosov mapping classes are neither periodic nor reducible.

Here, \( \varphi \) is said to be periodic if it is of finite order; \( \varphi \) is said to be reducible if there is a multicurve (i.e., a union of disjoint essential curves) on \( S \) which is globally fixed by \( \varphi \); \( \varphi \) is said to be pseudo-Anosov if it preserves a pair of projective classes of transverse measured foliations having no singular closed leaves, multiplying the transverse measure on one by some constant \( K > 1 \) and on the other by the constant \( 1/K \). We shall recall this classification more precisely in the following sections.

Let \( \varphi \) be an element of \( \text{Mod}(S) \). We set

\[
a(\varphi) = \inf_{X \in \mathcal{T}(S)} d_L(X, \varphi(X)).
\]

We call \( a(\varphi) \) the translation distance of \( \varphi \) with respect to Thurston’s asymmetric metric. We say that \( a(\varphi) \) is realized if there exists some \( X \in \mathcal{T}(S) \) such that \( a(\varphi) = d_L(X, \varphi(X)) \).

It is interesting to compare \( a(\varphi) \) with the translation distance defined by the Teichmüller metric \( d_T \):

\[
b(\varphi) = \inf_{X \in \mathcal{T}(S)} d_T(X, \varphi(X)).
\]

Since \( d_L \leq 2d_T \), we have \( a(\varphi) \leq 2b(\varphi) \).

Since Thurston’s asymmetric metric is not symmetric, we may also consider

\[
a(\varphi^{-1}) = \inf_{X \in \mathcal{T}(S)} d_L(X, \varphi^{-1}(X)) = \inf_{X \in \mathcal{T}(S)} d_L(\varphi(X), X).
\]

To motivate the work done in this paper, we recall that Bers [1] studied the translation distance \( b(\varphi) \) and proved the following classification result.

**Theorem 1.2 (Bers [1]).** Let \( \varphi \in \text{Mod}(S) \). Then

1. \( b(\varphi) = 0 \) and realized \( \iff \) \( \varphi \) is periodic.
2. \( b(\varphi) \) is not realized \( \iff \) \( \varphi \) is reducible.
3. \( b(\varphi) > 0 \) and realized \( \iff \) \( \varphi \) is pseudo-Anosov.
In case (1), saying that \( \varphi \) is periodic means that it is represented by a periodic homeomorphism of the surface.

Bers interpreted the realization of \( b(\varphi) \) as an extremal problem. In the case where \( b(\varphi) \) is not realized, Bers further showed that there is a generalized solution of the extremal problem which is given by a noded Riemann surface, and that the restriction of \( \varphi \) on each nonsingular component of the noded Riemann surface is either periodic or pseudo-Anosov.


In analogy with Bers’ classification of elements of \( \text{Mod}(S) \) with respect to the Teichmüller metric, we classify \( \varphi \in \text{Mod}(S) \) into four types:

<table>
<thead>
<tr>
<th>Elliptic</th>
<th>Parabolic</th>
<th>Hyperbolic</th>
<th>Pseudo-hyperbolic</th>
</tr>
</thead>
<tbody>
<tr>
<td>( a(\varphi) = 0 ) and realized</td>
<td>( a(\varphi) = 0 ) but not realized</td>
<td>( a(\varphi) &gt; 0 ) and realized</td>
<td>( a(\varphi) &gt; 0 ) but not realized</td>
</tr>
</tbody>
</table>

The aim of our investigation in this paper is to analyze each of these cases.

It is easy to see that \( \varphi \) is elliptic if and only if \( \varphi \) has a fixed point in \( \mathcal{T}(S) \).

Indeed, if \( \varphi \) has a fixed point in \( \mathcal{T}(S) \), then there is a complex structure \( X \) on \( S \) such that \( \varphi \) induces a biholomorphic automorphism of \( X \). Using a classical result of Hurwitz, we deduce that \( \varphi \) is of finite order, therefore periodic. Conversely, if \( \varphi \) is periodic, Nielsen showed that \( \varphi \) has a fixed point in \( \mathcal{T}(S) \). In fact, Kerckhoff proved a stronger result, namely, that the action of every finite subgroup of \( \text{Mod}(S) \) has a fixed point in \( \mathcal{T}(S) \). (This was his solution to the so-called the Nielsen realization problem.)

A stretch line is a \( d_L \)-geodesic of a special kind, defined by “stretching” along a complete geodesic lamination. We shall recall the definition in Section 4.

In this paper, we prove the following:

**Theorem 1.3.** If \( \varphi \) is pseudo-Anosov, then it leaves a \( d_L \)-geodesic invariant. Furthermore, for some \( n \in \mathbb{N} \), \( \varphi^n \) leaves a stretch line invariant.

We also prove the following:

**Theorem 1.4.** If \( \varphi \) is pseudo-Anosov, then \( a(\varphi) = a(\varphi^{-1}) = b(\varphi) \).

The projection on moduli space of the \( \varphi \)-invariant \( d_L \)-geodesic provided by Theorem 1.3 is a closed \( d_L \)-geodesic, and it is homotopic to a Teichmüller closed geodesic of the same length.

In analogy with the case of the Teichmüller metric, we prove the following:

**Theorem 1.5.** If \( \varphi \) is irreducible, then \( \varphi \) is either elliptic or hyperbolic.

**Theorem 1.6.** If \( \varphi \) is of infinite order and leaves a \( d_L \)-geodesic invariant, then \( \varphi \) is hyperbolic. The translation distance \( a(\varphi) \) is attained at any point on the geodesic.

**Theorem 1.7.** The mapping class \( \varphi \) is of infinite order, reducible and periodic on all reduced components on \( S \) if and only if \( \varphi \) is parabolic.

To show that a reducible map \( \varphi \in \text{Mod}(S) \) cannot attain \( b(\varphi) \) in Teichmüller space, Bers [1] used the notion of Nielsen extension of Riemann
surfaces to show that for any $X \in \mathcal{T}(S)$, one can “shrink” the reduced curves to get a new Riemann surface $Y$ satisfying $d_T(Y, \varphi(Y)) < d_T(X, \varphi(X))$. Bers’ construction does not apply to the setting of Thurston’s asymmetric metric. We shall see in §6 of this paper that there exists a reducible map $\varphi$ which is hyperbolic with respect to the asymmetric $d_L$, and therefore for which $a(\varphi)$ is realized.

These results give quite a good picture of the behavior of the action of a mapping class with respect to Thurston’s asymmetric metric, in terms of Thurston’s classification. It remains to study the case where $\varphi$ is reducible and has at least one pseudo-Anosov reduced component. In the setting of the Teichmüller metric, to show that a hyperbolic map $\varphi \in \text{Mod}(S)$ ($b(\varphi) > 0$ and realized) leaves a Teichmüller geodesic invariant, Bers [1] used the fact that any two points in Teichmüller space are connected by a unique Teichmüller geodesic. Since Thurston’s asymmetric metric is not uniquely geodesic, Bers’ argument does not work here. In the paper [5] by Daskalopoulos and Wentworth, the strict convexity property of hyperbolic length functions along Weil-Petersson geodesics is used to show that a reducible map cannot leave a Weil-Petersson geodesic invariant. We don’t know whether geodesic length functions are convex along $d_L$-geodesics.

Questions 1.8. We propose the following:

1. Is Theorem 1.4 true in general?
2. If $\varphi$ is reducible and has at least one pseudo-Anosov reduced component, is it pseudo-hyperbolic? Can it be hyperbolic?
3. If $\varphi$ is hyperbolic, does it leave a $d_L$-geodesic invariant? If $\varphi$ is of infinite order and leaves a $d_L$-geodesic (or even a stretch line) invariant, is it pseudo-Anosov?

In §6, we give an example, on any surface of genus $\geq 2$, of a reducible mapping class which is of hyperbolic type.

It is known that closed Teichmüller geodesics in moduli space correspond to conjugacy classes of pseudo-Anosov maps. The above questions are related to the question of whether closed $d_L$-geodesics in moduli space correspond to conjugacy classes of pseudo-Anosov maps.

2. Irreducible Maps

In this section, we prove Theorems 1.5 and 1.6.

Let $\mathcal{S}$ be the set of homotopy classes of essential simple closed curves on $S$. A finite non-empty subset $\{C_1, \cdots, C_k\} \subset \mathcal{S}$ is called admissible if $C_i \neq C_j$ for all $i \neq j$ and if $C_1, \cdots, C_k$ can be realized simultaneously as mutually disjoint curves. We call $\varphi \in \text{Mod}(S)$ reducible if there is an admissible set $\{C_1, \cdots, C_k\}$ such that

$$\varphi(\{C_1, \cdots, C_k\}) = \{C_1, \cdots, C_k\}.$$  

An element $\varphi \in \text{Mod}(S)$ is called irreducible if there is no admissible set reduced by $\varphi$.

We shall use the following hyperbolic geometry estimate: Given a simple closed geodesic $\alpha$ of length $l_\alpha$ on a hyperbolic surface, there exists a collar
Lemma 2.1. There is a universal constant $\delta_0 > 0$ such that any two distinct simple closed geodesics on a hyperbolic surface with hyperbolic length less than $\delta_0$ are disjoint.

We also need the following theorem. See Bers [2] for a proof.

Theorem 2.2 (Mumford’s compactness theorem). For each $\epsilon > 0$, the subset
\[
\mathcal{M}_\epsilon(S) = \{ X \in \mathcal{M}(S) : \ell(X) \geq \epsilon \} \subset \mathcal{M}(S)
\]
is compact.

Here $\ell(X)$ denotes the length of the shortest essential simple closed curve of a hyperbolic surface $X$. Note that this quantity is well-defined for elements $X$ in $\mathcal{M}(S)$ or in $\mathcal{M}(S)$.

For each $\epsilon > 0$, the subset
\[
\mathcal{T}_\epsilon(S) = \{ X \in \mathcal{T}(S) : \ell(X) \geq \epsilon \}
\]
is called the $\epsilon$-thick part of $\mathcal{T}(S)$. Mumford’s compactness theorem is equivalent to saying that for any sequence $(X_k)_{k \geq 1}$ in an $\epsilon$-thick part of $\mathcal{T}(S)$, there is a subsequence of $(X_k)_{k \geq 1}$, still denoted by $(X_k)_{k \geq 1}$, and a sequence of $(\varphi_k)_{k \geq 1}$ in $\text{Mod}(S)$, such that $(\varphi_k(X_k))_{k \geq 1}$ converges in $\mathcal{T}(S)$.

Lemma 2.3. Let $\varphi \in \text{Mod}(S)$ be irreducible and $X \in \mathcal{T}(S)$. Then, with $\delta_0$ being the constant given in Lemma 2.1, we have:
\[
(L(X, \varphi(X)))^{3g - 3 + n} \geq \delta_0/\ell(X).
\]

Proof. Suppose that
\[
(L(X, \varphi(X)))^{3g - 3 + n} < \delta_0/\ell(X).
\]
Let $\alpha \in \mathfrak{S}$ such that $\ell_X(\alpha) = \ell(X)$. Consider the curves $\alpha_1 = \alpha$, $\alpha_2 = \varphi^{-1}(\alpha_1)$, $\cdots$, $\alpha_{3g - 2 + n} = \varphi^{-1}(\alpha_{3g - 3 + n})$. Since
\[
\ell_X(\varphi^{-1}(\alpha)) = \ell(\varphi(X))(\alpha) \leq L(X, \varphi(X))\ell_X(\alpha),
\]
each $\alpha_i$ satisfies
\[
\ell_X(\alpha_i) \leq L(X, \varphi(X))^{i - 1}\ell_X(\alpha).
\]
By (3), we have
\[
\ell_X(\alpha_i) < \delta_0, i = 1, \cdots, 3g - 2 + n.
\]
By Lemma 2.1, the curves $\alpha_1, \alpha_2, \cdots, \alpha_{3g - 2 + n}$ are mutually disjoint. Since there are at most $3g - 3 + n$ isotopy class of pairwise disjoint simple closed curves in $S$, there is a least number $1 \leq j \leq 3g - 3 + n$ such that $\alpha_j = \alpha_1$.

Note that $\{\alpha_1, \cdots, \alpha_{j - 1}\}$ is admissible and
\[
\varphi(\{\alpha_1, \cdots, \alpha_{j - 1}\}) = \{\alpha_1, \cdots, \alpha_{j - 1}\}.
\]
As a result, $\varphi$ is reducible, which contradicts the assumption. □
Proof of Theorem 1.5. By assumption, \( \varphi \) is irreducible. Consider a sequence \( (X_k)_{k \geq 1} \) in \( \mathcal{T}(S) \) with

\[
\lim_{k \to \infty} d_L(X_k, \varphi(X_k)) = a(\varphi).
\]

There is a constant \( M > 1 \) such that for any \( k \geq 1 \), \( L(X_k, \varphi(X_k)) \leq M \). By Lemma 2.3,

\[
f(X_k) \geq \frac{\delta_0}{(L(X_k, \varphi(X_k)))^{3g-3+n}} \geq \frac{\delta_0}{M^{3g-3+n}}.
\]

Therefore, the sequence \( (X_k) \) lies in a thick part of \( \mathcal{T}(S) \).

Now we use a compactness argument of Bers [1] to show that \( a(\varphi) \) attains its infimum in \( \mathcal{T}(S) \).

By Mumford’s compactness theorem, there is a subsequence of \( (X_k)_{k \geq 1} \), still denoted by \( (X_k)_{k \geq 1} \), and a sequence \( (\varphi_k)_{k \geq 1} \) in \( \text{Mod}(S) \), such that \( (\varphi_k(X_k))_{k \geq 1} \) converges to some point \( Y \in \mathcal{T}(S) \). Let \( Y_k = \varphi_k(X_k) \). Since \( \text{Mod}(S) \) acts isometrically with respect to Thurston’s asymmetric metric, we have

\[
d_L(X_k, \varphi(X_k)) = d_L(\varphi_k(X_k), \varphi \circ \varphi(X_k)) = d_L(Y_k, \varphi_k \circ \varphi \circ \varphi_k^{-1}(Y_k)).
\]

By (4), we have

\[
\lim_{k \to \infty} d_L(Y_k, \varphi_k \circ \varphi \circ \varphi_k^{-1}(Y_k)) = a(\varphi).
\]

Since

\[
d_L(Y, \varphi_k \circ \varphi \circ \varphi_k^{-1}(Y_k)) \leq d_L(Y, Y_k) + d_L(Y_k, \varphi_k \circ \varphi \circ \varphi_k^{-1}(Y_k)) \leq M_1
\]

for some sufficiently large constant \( M_1 \) and since \( \mathcal{T}(S) \) is locally compact, up to a subsequence, we can assume that \( (\varphi_k \circ \varphi \circ \varphi_k^{-1}(Y_k))_{k \geq 1} \) converges to some \( Z \in \mathcal{T}(S) \). Since \( (Y_k)_{k \geq 1} \) converges to \( Y \), we conclude that the sequence \( (\varphi_k \circ \varphi \circ \varphi_k^{-1}(Y))_{k \geq 1} \) converges to \( Z \). For any \( \epsilon > 0 \), there is a number \( N > 0 \), such that for any \( j, k > N \),

\[
d_L(\varphi_j \circ \varphi \circ \varphi_j^{-1}(Y), \varphi_k \circ \varphi \circ \varphi_k^{-1}(Y)) < \epsilon.
\]

Since \( \text{Mod}(S) \) acts properly discontinuously on \( \mathcal{T}(S) \), we have, for sufficiently large \( k_0 \),

\[
\varphi_k \circ \varphi \circ \varphi_k^{-1} = \varphi_{k_0} \circ \varphi \circ \varphi_{k_0}^{-1}, \quad \forall k \geq k_0.
\]

It follows from (5) that

\[
d_L(Y, \varphi_{k_0} \circ \varphi \circ \varphi_{k_0}^{-1}(Y)) = a(f).
\]

\[\square\]

Corollary 2.4. Suppose that \( \varphi \in \text{Mod}(S) \) is parabolic or pseudo-hyperbolic and suppose that \( (X_k)_{k \geq 1} \) is a sequence in \( \mathcal{T}(S) \) with

\[
\lim_{k \to \infty} d_L(X_k, \varphi(X_k)) = a(\varphi).
\]

Then for any \( \epsilon > 0 \), \( X_k \) leaves \( \mathcal{T}_\epsilon(S) \) for any sufficiently large \( k \).

Proof. Otherwise, using Bers’ compactness argument as we did in the proof of Theorem 1.5, we can show that \( \varphi \) is elliptic or hyperbolic. \[\square\]
Proof of Theorem 1.6. The proof follows Bers’ argument in [1], Theorem 5. We reproduce it here for the convenience of the reader. Suppose that a $d_L$-geodesic through $X \in \mathcal{T}(S)$ is invariant under $\varphi$. Let $Y$ be any point in $\mathcal{T}(S)$. Since $\varphi$ is an isometry, we have

$$nd_L(X, \varphi(X)) = d_L(X, \varphi(X)) + d_L(\varphi(X), \varphi^2(X)) + \cdots + d_L(\varphi^{n-1}(X), \varphi^n(X)) = d_L(X, \varphi^n(X)) \leq d_L(X, Y) + d_L(Y, \varphi^n(Y)) + d_L(\varphi^n(Y), \varphi^n(X)) \leq d_L(X, Y) + d_L(Y, \varphi(Y)) + d_L(\varphi(Y), \varphi^2(Y)) + \cdots + d_L(\varphi^{n-1}(Y), \varphi^n(Y)) + d_L(\varphi^n(Y), \varphi^n(X)) = d_L(X, Y) + nd_L(Y, \varphi(Y)) + d_L(Y, X).$$

Since $n$ is arbitrary, $d_L(X, \varphi(X)) \leq d_L(Y, \varphi(Y))$ for any $Y \in \mathcal{T}(S)$. As a result, $a(f) = d_L(X, \varphi(X))$. $\square$

Bers also proved that $b(\varphi) > 0$ is realized if and only if $\varphi$ leaves a Teichmüller geodesic invariant, cf. Bers [1], Theorem 5. By an analysis of the Teichmüller geodesic left invariant by $\varphi$, he showed that the initial and terminal quadratic differentials of the Teichmüller map in the homotopy class of $\varphi$ coincide. It follows that $\varphi$ preserves a pair of transverse measured foliations, multiplying the transverse measure of one by $K$ (the dilation of the Teichmüller map) and of the other one by $1/K$. This means that $\varphi$ is pseudo-Anosov. We will study pseudo-Anosov maps in Section 4.

3. Laminations and Thurston’s stretch maps

In this section, we recall some necessary background on laminations and on Thurston’s construction of stretch lines.

Fix a hyperbolic structure on the surface $S$. A geodesic lamination $\mu$ on $S$ is a closed subset of $S$ which is the union of disjoint simple geodesics (called the leaves of $\mu$). A measured geodesic lamination is a geodesic lamination $\mu$ with a transverse invariant measure of full support $\mu$. If a geodesic lamination $\mu$ has not all of its leaves going at both ends to cusps, then $\mu$ contains a compactly-supported sublamination admitting a transverse measure.

The stump of a geodesic lamination $\mu$ is the maximal compact sublamination of $\mu$ admitting a transverse measure.

A geodesic lamination $\mu$ on a hyperbolic surface $X$ is complete if its complementary regions are all isometric to ideal triangles. Associated with such a pair $(X, \mu)$ is a partial (that is, supported on a subsurface) measured foliation $F_\mu(X)$, satisfying the following:

(i) the foliation $F_\mu(X)$ intersects $\mu$ transversely and in each ideal triangle of the complement of $\mu$, the leaves of $F_\mu(X)$ are composed of horocycles perpendicular to the boundary of the ideal triangle;

(ii) the non-foliated region in each ideal triangle is bounded by three pairwise tangent leaves, as in Figure 1;

(iii) The transverse measure for $F_\mu(X)$ agrees with arc length on $\mu$.

By collapsing each non-foliated region of $F_\mu(X)$ onto a tripod, we get a measured foliation on $S$ of full support, still denoted by $F_\mu(X)$, which is
well defined up to isotopy and which is called the \textit{horocyclic foliation} corresponding to \((X, \mu)\). Note that since the hyperbolic structures we consider are complete, each puncture of \(X\) has a neighborhood isometric to a cusp. If the set of punctures of \(S\) is nonempty, each complete geodesic lamination on \(S\) has some leaves going to cusps. The corresponding horocyclic foliations are standard near the cusps, meaning that in a neighborhood of each cusp, the leaves are circles homotopic to the puncture, and the total transverse measure of an arc converging to the cusp is infinite.

We denote by \(\mathcal{MF}(\mu)\) the space of equivalence classes of measured foliations that are transverse to \(\mu\) and standard near the cusps. Thurston \([17]\) proved the following fundamental result.

\begin{theorem}
The map \(\Phi_\mu : \mathcal{T}(S) \to \mathcal{MF}(\mu) : X \mapsto F_\mu(X)\) is a homeomorphism.
\end{theorem}

We also recall the following definition from Thurston \([17]\). A geodesic lamination \(\lambda\) is \textit{totally transverse} to \(\mu\) if each leaf of \(\lambda\) intersects \(\mu\) transversely infinitely often and if each leaf of \(\mu\) which does not go to a cusps intersects \(\lambda\) transversely infinitely often. (In counting intersections, the leaves are parametrized by the reals. In particular, with this convention, a simple closed geodesic meets any transverse arc infinitely often.)

By a result of Thuston \([17]\), \(\mathcal{MF}(\mu)\) can be identified with the space of (equivalence classes) of measured laminations with compact support and totally transverse to \(\mu\).

From now on, we always assume that a measured geodesic lamination has compact support.

We shall say that a measured geodesic lamination \(\lambda\) is \textit{supported by} a geodesic lamination \(\mu\) if \(\lambda\) is a sublamination of \(\mu\).

We fix a complete geodesic lamination \(\mu\) on \(S\).

The \textit{stretch line} directed by \(\mu\) and passing through \(X \in \mathcal{T}(S)\) is the (image of a) path

\[ \mathbb{R} \ni t \rightarrow X_t = \Phi_\mu^{-1}(e^{t}F_\mu(X)). \]

We shall call a segment of a stretch line a \textit{stretch path}. Stretch lines are geodesics for the Thurston asymmetric metric. More precisely, suppose that \(\mu\) supports a measured geodesic lamination \(\lambda\). Thus, for any two points
Theorem 3.2 (Thurston [17]). All other ratio-maximizing chain-recurrent laminations.

In fact, laminations that realize the Lipschitz distance \( d_L(X,Y) \) (or, equivalently, that maximize the ratio of length) have been characterized by Thurston. A geodesic lamination \( \mu \) is ratio-maximizing for \( X \) and \( Y \) if there is an \( L(X,Y) \)-Lipschitz map (homotopic to the identity map) from a neighborhood of \( \mu \) in \( X \) to a neighborhood of \( \mu \) in \( Y \). A geodesic lamination \( \mu \) is called chain-recurrent if for any \( \epsilon > 0 \) and for any \( p \in \mu \) there is a closed \( \epsilon \)-trajectory of \( \mu \) through \( p \), that is, a closed unit speed path in the surface such that for any interval of length 1 on the path there is an interval of length 1 on some leaf of \( \mu \) such that the two paths remain within \( \epsilon \) of each other in the \( C^1 \) sense. By a result of Thurston [17], for any two distinct points \( X, Y \in \mathcal{J}(S) \), there is a unique maximal (in the sense of inclusion) ratio-maximizing chain-recurrent lamination \( \mu(X,Y) \) which contains all other ratio-maximizing chain-recurrent laminations.

With the above definitions, we can state the following theorem of Thurston.

**Theorem 3.2** (Thurston [17]). Any two points \( X, Y \in \mathcal{J}(S) \) can be connected by a \( d_L \)-geodesic which consists of a finite concatenation of stretch paths. Moreover, each of these stretch paths stretches along some complete lamination containing the unique ratio-maximizing chain-recurrent lamination \( \mu(X,Y) \).

Since each element \( \varphi \) of Mod\((S)\) acts isometrically on \((\mathcal{J}(S), d_L)\), it maps \( d_L \)-geodesics to \( d_L \)-geodesics. We have the following:

**Lemma 3.3.** Any \( \varphi \in \text{Mod}(S) \) maps a stretch line \( \Phi_{\mu}^{-1}(e^t F_\mu(X)) \) through \( X \) to a stretch line through \( \varphi(X) \), given by

\[
\Phi_{\varphi(\mu)}^{-1}(e^t F_{\varphi(\mu)}(\varphi(X))).
\]

**Proof.** It is easy to see that the image of \( \Phi_{\mu}^{-1}(e^t F_{\mu}(X)) \) under \( \varphi \) is a stretch line which passes through \( \varphi(X) \), stretched along the complete lamination \( \varphi(\mu) \) and with corresponding horocyclic measured foliation \( \varphi(F_{\mu}(X)) \). Since the horocyclic measured foliations are uniquely determined by \( \varphi(X) \) and \( \varphi(\mu) \), and since \( \Phi_{\varphi(\mu)}^{-1}(e^t F_{\varphi(\mu)}(\varphi(X))) \) is also a stretch line through \( \varphi(X) \) directed by \( \varphi(\mu) \), it follows that \( \varphi(F_{\mu}(X)) = F_{\varphi(\mu)}(\varphi(X)) \). \( \square \)

We denote by \([\lambda]\) the projective class of a measured lamination (or measured foliation) \( \lambda \). Such a \([\lambda]\) determines an element in Thurston’s boundary of Teichmüller space. We refer to Thurston [16] and [6] for definitions and properties of Thurston’s compactification and Thurston’s boundary. Here we just recall that Thurston’s compactification is homeomorphic to a closed \((6g-6+2n)\)-dimensional ball whose boundary is identified with the space of projective measured foliations and that the mapping class group action on Teichmüller space extends continuously to Thurston’s compactification.

The following two theorems are important for our study.

**Theorem 3.4** (Papadopoulos [11]). The stretch line \( \Phi_{\mu}^{-1}(e^t F_{\mu}(X)) \) converges in the positive direction to \([F_{\mu}(X)]\) in Thurston’s boundary.
Recall that a measured geodesic lamination is said to be uniquely ergodic if its transverse measure is unique up to scalar multiples.

**Theorem 3.5** (Théret [14]). Suppose that the stump $\lambda$ of the geodesic lamination $\mu$ is non-empty and is uniquely ergodic. Then $\Phi^{-1}_\mu(e^tF_\mu(X))$ converges in the negative direction to $[\lambda]$ in Thurston’s boundary.

Now consider a pair of totally transverse measured geodesic laminations $\lambda_1$ and $\lambda_2$. Suppose that $\lambda_1$ is uniquely ergodic. We can choose a complete geodesic lamination $\mu$ whose stump is $\lambda_1$. By Theorem 3.1, there exists a unique $X \in T(S)$ such that $F_\mu(X)$ is equivalent to $\lambda_2$. (As we noted above, we identify $F_\mu(X)$ with $\lambda_2$.) It follows from Theorem 3.4 and Theorem 3.5 that the stretch line $\Phi^{-1}_\mu(e^tF_\mu(X))$ converges in the positive direction to $[\lambda_2]$ and converges in the negative direction to $[\lambda_1]$.

We have the following consequence.

**Corollary 3.6.** Let $\lambda_1$ and $\lambda_2$ be a pair of totally transverse measured geodesic laminations and suppose that $\lambda_1$ is uniquely ergodic. Then there exists a stretch line which converges in the positive direction to $[\lambda_2]$ and in the negative direction to $[\lambda_1]$.

In general, the stretch line in Corollary 3.6 is not unique. If $\lambda_1$ is not maximal, there are different completions of $\lambda_1$ which give different stretch lines in Teichmüller space.

4. **Pseudo-Anosov maps**

In this section, we prove Theorem 1.3 and 1.4.

Recall that an element $\varphi \in \text{Mod}(S)$ is said to be pseudo-Anosov if it has a representative, still denoted by $\varphi$, which is a homeomorphism of $S$ that preserves the projective classes of a pair of transverse measured foliations $(F_1, \lambda_1)$ and $(F_2, \lambda_2)$ and if there exists a constant $K > 1$ such that

$$\varphi((F_1, \lambda_1)) = (F_1, \frac{1}{K}\lambda_1),$$

$$\varphi((F_2, \lambda_2)) = (F_2, K\lambda_2).$$

The measured foliations $\lambda_1$ and $\lambda_2$ are called the stable and unstable foliations of $\varphi$ respectively. The quantity $\log K$ is the topological entropy of $\varphi$ [16] [6].

We recall some more terminology:

A measured foliation $\lambda$ is minimal if no closed curve in $S$ can be realized as a leaf of $\lambda$. Equivalently, after Whitehead moves, the foliation has only dense leaves on $S$. Two measured foliations are topologically equivalent if after isotopy and Whitehead moves, the leaf structure of the two foliations is the same. A theorem of Masur [10] states that if a measured foliation $\lambda$ is minimal and uniquely ergodic, then for any other measured foliation $\lambda'$ satisfying $\iota(\lambda, \lambda') = 0$ we have $\lambda' = c\lambda$ for some constant $c > 0$.

**Proposition 4.1** (Thurston, see [6]). Suppose that $\varphi \in \text{Mod}(S)$ is pseudo-Anosov. Then each of the invariant foliations of $\varphi$ is minimal and uniquely ergodic.
In what follows, we shall often pass from the measured foliations $\lambda_1$ and $\lambda_2$ to the measured laminations that represent them and vice versa.

We endow $S$ with a hyperbolic structure and we identify $\lambda_1$ and $\lambda_2$ with the corresponding measured geodesic laminations. Since $\lambda_1$ is minimal and uniquely ergodic, each connected component of $S \setminus \lambda_1$ is isometric to an ideal polygon or an ideal polygon with one puncture. It follows that there are finitely many different complete geodesic laminations with stump $\lambda_1$.

**Lemma 4.2.** Let $\mu$ be a complete geodesic lamination with stump $\lambda_1$. Then $\mu$ and $\lambda_2$ are totally transverse.

**Proof.** By Proposition 4.1, both $\lambda_1$ and $\lambda_2$ are minimal and uniquely ergodic. We replace $\lambda_1$ and $\lambda_2$ by their respective measured foliations. Up to Whitehead moves, we may assume that for both $\lambda_1$ and $\lambda_2$, each half-leaf is dense in the surface. Then it is easy to see that each leaf of $\lambda_2$ intersects $\mu$ transversely infinitely often, and each leaf of $\mu$ which does not go to a cusp intersects $\lambda_2$ transversely infinitely often. It follows from the definition that $\lambda_2$ is totally transverse to $\mu$. □

**Theorem 4.3.** Suppose that $\varphi \in \text{Mod}(S)$ is pseudo-Anosov. Then there exists an integer $n \geq 1$ such that $\varphi^n$ leaves a stretch line invariant.

**Proof.** Let $\lambda_1$ and $\lambda_2$ be the stable and unstable measured laminations of $\varphi$. Choose a complete geodesic lamination $\mu$ with stump $\lambda_1$. By the discussion before Corollary 3.6, there is a unique stretch line, denoted by $r(\mu, \lambda_2)$, which converges in the positive direction to $[\lambda_2]$ and converges in the negative direction to $[\lambda_1]$.

Since $\varphi$ fixes $[\lambda_1]$ and $[\lambda_2]$ on Thurston’s boundary, each $\varphi^k(r(\mu, \lambda_2))$ is a stretch line which also converges in the positive direction to $[\lambda_2]$ and converges in the negative direction to $[\lambda_1]$.

A stretch line satisfying the above conditions is uniquely determined by $\lambda_2$ and the completion of $\lambda_1$. Since there are finitely many different completions of $\lambda_1$, there is a integer $n$ such that $\varphi^n$ leaves $r(\mu, \lambda_2)$ invariant. □

By Theorem 1.6, $\varphi^n$ is hyperbolic. The translation distance $a(\varphi^n)$ attains its infimum at any point on $r(\mu, \lambda_2)$.

**Proposition 4.4.** With the above notations, $a(\varphi^n) = n \log K$.

**Proof.** Since $\varphi^n(\lambda_1) = \frac{1}{K^n}\lambda_1$, for any $X \in \mathcal{T}(S)$,

$$\ell_{\varphi^n(X)}(\lambda_1) = \ell_X(\varphi^{-n}(\lambda_1)) = K^n \ell_X(\lambda_1).$$

Thus $a(\varphi^n) \geq n \log K$.

Take $X$ on the stretch line $r(\mu, \lambda_2)$. Since the measure of $\lambda_2$ is “stretched” by $K^n$, by definition of stretch line, the length of the measured lamination $\lambda_1$ is also “stretched” by $K^n$. We have $n \log K = d_L(X, \varphi^n(X)) \geq a(\varphi)$. □

The proof of Theorem 4.3 gives the following:

**Theorem 4.5.** Suppose that $\varphi \in \text{Mod}(S)$ is a pseudo-Anosov mapping class with stable and unstable measured laminations $\lambda_1$ and $\lambda_2$ and suppose that $\lambda_1$ is complete. Then $\varphi$ leaves a unique stretch line invariant.
In the general case, we don’t know whether a pseudo-Anosov mapping class leaves a stretch line invariant. We will show that such a mapping class leaves a $d_L$-geodesic invariant. First notice the following property:

**Proposition 4.6.** Suppose that $\varphi \in \text{Mod}(S)$ is pseudo-Anosov with topological entropy $\log K$. Then $\varphi$ is hyperbolic and $a(\varphi) = \log K$.

**Proof.** By the above results, there is a power $\varphi^n$ which fixes a stretch line and with translation length $a(\varphi^n) = n \log K$. By the triangle inequality,

$$n \log K \leq d_L(X, \varphi^n(X)) \leq nd_L(X, \varphi(X)).$$

It follows that $\log K \leq a(\varphi)$.

To show the reverse inequality, we use the following lemma.

**Lemma 4.7** (Papadopoulos [11]). There is a constant $C > 0$ such that for any simple closed curve $\alpha$ and for any integer $m$,

$$i(\varphi^m(\lambda_2), \alpha) \leq \ell_{\varphi^m(X)}(\alpha) \leq i(\varphi^m(\lambda_2), \alpha) + C.$$

By this lemma, we have

$$\frac{\ell_{\varphi(X)}(\alpha)}{\ell_X(\alpha)} = \frac{\ell_{\varphi^m(X)}(\varphi^{-1}(\alpha))}{\ell_{\varphi^m(X)}(\alpha)} \leq \frac{i(\varphi^m(\lambda_2), \varphi^{-1}(\alpha)) + C}{i(\varphi^m(\lambda_2), \alpha)} = \frac{K^m i(\lambda_2, \varphi^{-1}(\alpha)) + C}{K^m i(\lambda_2, \alpha)} = \frac{K^{m+1} i(\lambda_2, \alpha) + C}{K^m i(\lambda_2, \alpha)}.$$

By taking $m \to +\infty$, we have

$$\frac{\ell_{\varphi(X)}(\alpha)}{\ell_X(\alpha)} \leq K.$$

Since $\alpha$ is arbitrary, we have

$$d_L(X, \varphi(X)) \leq \log K.$$

Moreover, the infimum of $a(\varphi)$ is attained at any point on the stretch line invariant under $\varphi^n$. \qed

Now we show the following:

**Theorem 4.8.** A pseudo-Anosov map $\varphi \in \text{Mod}(S)$ leaves a $d_L$-geodesic invariant.

**Proof.** By Theorem 4.3, there exists an integer $n$ such that $\varphi^n$ leaves a stretch line $r_1$ invariant. Note that $r_i = \varphi(r_{i-1})$, $i = 1, \ldots, n-1$ are also invariant by $\varphi^n$.

Choose any point $X$ on $r_1$ and choose a geodesic segment between $X$ and $\varphi(X)$. Denote this geodesic segment by $R_1$. We construct a path $R$ in Teichmüller space by setting

$$R = R_1 \cup R_2 \cup \cdots \cup R_n \cup \cdots$$
where \( r_k = \varphi(R_{k-1}) \). We also extend the path to the reverse direction by iteration of \( \varphi^{-1} \). In this way, we get an infinite path \( R \) in Teichmüller space which is invariant by the action of \( \varphi \).

We claim that \( R \) is a geodesic. To see this, consider the segment on \( R \) connecting \( \varphi^{-k}(X) \) and \( \varphi^{k}(X) \). The length of this segment is equal to \( 2kn \) times \( d_L(X, \varphi(X)) \). On the other hand, both \( \varphi^{-k}(X) \) and \( \varphi^{k}(X) \) lie on the stretch line \( r_1 \), and the Lipschitz distance between \( \varphi^{-k}(X) \) and \( \varphi^{k}(X) \) is equal to \( 2kn \) times \( \log K \) (the entropy of \( \varphi \)). We have shown in Proposition 4.6 that \( d_L(X, \varphi(X)) = \log K \). As a result, the length of the above segment on \( R \) connecting \( \varphi^{-k}(X) \) and \( \varphi^{k}(X) \) is equal to the Lipschitz distance between \( \varphi^{-k}(X) \) and \( \varphi^{k}(X) \). Since \( k \) is arbitrary, \( R \) is a \( d_L \)-geodesic.

Combining Theorem 4.3 and Theorem 4.8, we obtain Theorem 1.3.

Note that if \( \varphi \) is pseudo-Anosov with entropy \( \log K \), it was proved by Bers [1] that \( b(\varphi) = \log K \). It follows that \( a(\varphi) = b(\varphi) \). From this, we deduce Theorem 1.4. The projection of a \( \varphi \)-invariant \( d_L \)-geodesic on the moduli space is a closed \( d_L \)-geodesic, which is homotopic to a closed Teichmüller geodesic with the same length.

Note that by results of Théret in [15], any two \( d_L \)-geodesics left invariant by a pseudo-Anosov map are asymptotic, and two \( d_L \)-geodesics left invariant by two distinct pseudo-Anosov maps are divergent.

5. Reducible maps

By Bers’ classification, we have

**Proposition 5.1.** An element \( \varphi \in \text{Mod}(S) \) is of infinite order and reducible if and only if \( b(\varphi) \) is not realized. Moreover, such an element \( \varphi \) has no pseudo-Anosov reduced component if and only if \( b(\varphi) = 0 \).

Suppose that \( \varphi \in \text{Mod}(S) \) is of infinite order, reducible and has no pseudo-Anosov reduced component. Since \( a(\varphi) \leq 2b(\varphi) \) and \( b(\varphi) = 0 \), \( \varphi \) is parabolic, i.e., \( a(\varphi) = 0 \).

On the other hand, suppose that \( \varphi \) is of infinite order, reducible and has at least one pseudo-Anosov reduced component. Let \( Y \) be a pseudo-Anosov reduced component of \( \varphi \). Up to taking a power of \( \varphi \), we may assume that \( \varphi \) maps \( Y \) to \( Y \). There is a pair of transverse measured foliations \( \lambda_1 \) and \( \lambda_2 \) on the surface \( Y \) such that

\[
\varphi(\lambda_1) = \frac{1}{K}\lambda_1, \varphi(\lambda_2) = K\lambda_2,
\]

for some constant \( K > 1 \).

It follows that for any \( X \in \mathcal{T}(S) \),

\[
d_L(X, \varphi(X)) \geq \log \frac{\ell_X(\varphi^{-1}(\lambda_1))}{\ell_X(\lambda_1)} = \log K.
\]

As a result, \( a(\varphi) \geq \log K \).

We deduce the following:

**Theorem 5.2.** \( \varphi \) is parabolic if and only if \( \varphi \) is infinite order, reducible and has no pseudo-Anosov reduced component.
Now suppose that $\varphi$ is pseudo-hyperbolic.

By Theorem 5.2, $\varphi$ has at least one pseudo-Anosov reduced component. The maximum of the topological entropy on all of the pseudo-Anosov components gives a lower bound for $a(\varphi)$. In fact, from Bers’ results, it follows that $a(\varphi) \geq b(\varphi)$.

By Theorem 1.5, $\varphi$ is reducible. Assume that $\varphi$ is reduced by a maximal admissible set $\{C_1, \ldots, C_k\}$. Up to a power of $\varphi$, we may assume that $\varphi$ fixes each reduced component. Note that any power of $\varphi$ is also pseudo-hyperbolic.

By definition, there exists a sequence $(X_k)_{k \geq 1}$ in Teichmüller space such that $d_L(X_k, \varphi(X_k)) \rightarrow a(\varphi)$.

By Corollary 2.4, for any $\epsilon > 0$, $X_k$ leaves the $\epsilon$-thick part of $\mathcal{T}(S)$ for $k$ sufficiently large. This means that $\ell(X_k) \rightarrow 0$.

Let $Y$ be any pseudo-Anosov reduced component of $Y$. But assumption, $\varphi$ fixes $Y$.

Lemma 5.3. Let $(\alpha_k)_{k \geq 1}$ be a sequence of simple closed curves such that $\ell_X(\alpha_k) \rightarrow 0$. For sufficiently large $k$, each $\alpha_k$ is not contained in the interior of $Y$.

Proof. Suppose not and take a subsequence of $(\alpha_k)_{k \geq 1}$, still denoted by $(\alpha_k)$, contained in the interior $Y$. Since $\ell_X(\alpha_k) \rightarrow 0$ and $d_L(X_k, \varphi(X_k))$ is uniformly bounded above, using the proof of Lemma 2.3, $\varphi$ is reducible restricted on $Y$. This contradicts the assumption that $Y$ is a pseudo-Anosov component.

□

6. A REDUCIBLE AND HYPERBOLIC MAPPING CLASS

In this section, we prove the following

Proposition 6.1. On an arbitrary surface of genus $\geq 2$, we can find a reducible mapping class which is hyperbolic.

Proof. Consider a pseudo-Anosov map $\varphi$ on a hyperbolic surface of genus $g$ with $n > 0$ boundary components, which we denote by $\Sigma_{g,n}$ in order to distinguish it from the surface $S_{g,n}$ with punctures. We assume that $\varphi$ does not permute the complementary components of its stable laminations. We take two copies of this map $\varphi$, which we denote by $\varphi_1$ and $\varphi_2$, and we denote the two underlying surfaces by $\Sigma_1$ and $\Sigma_2$. We glue $\Sigma_1$ and $\Sigma_2$ in a symmetric manner along their boundary components and we obtain a homeomorphism of a closed hyperbolic surface $S = S_{2g+n-1,0}$ of genus $2g+n-1$. We denote the homeomorphism $\varphi_1 \cup \varphi_2$ by $\varphi$. The surface $S$ has an order-two symmetry $\iota$ which commutes with $\varphi$ (i.e., $\varphi \circ \iota = \iota \circ \varphi$) and which fixes the multicurve $\alpha = \partial \Sigma_1 = \partial \Sigma_2 \hookrightarrow S$.

For $j = 1, 2$, let $\lambda_j$ ad $\mu_j$ be the stable and unstable geodesic laminations of $\varphi_j$:

$$
\left\{
\begin{array}{l}
\varphi_j(\lambda_j) = k\lambda_j \\
\varphi_j(\mu_j) = \frac{1}{k}\mu_j,
\end{array}
\right.
$$
The homeomorphism $\varphi$ is reducible and with no Dehn twist on the reducing multicurve, and it fixes the measured geodesic laminations $\lambda = \lambda_1 \cup \lambda_2$ and $\mu = \mu_1 \cup \mu_2$; cf. Figure 2.

A component of $S \setminus \lambda$ or of $S \setminus \mu$ may be of two types:

1. an ideal polygon (that is, a hyperbolic polygon with cusps, or, equivalently, a surface isometric to the convex hull in $\mathbb{H}^2$ of a finite number of points at infinity);
2. a crown (that is, a hyperbolic annulus with cusps on one of its boundary components).

The two types of surfaces are represented in Figure 3.

The components of $S \setminus \lambda$ or $S \setminus \mu$ that contain elements of the multicurve $\alpha$ can only be of the type (2).
We consider a component $C$ of $S \setminus \mu$ and we lift it to the universal cover $\tilde{S}$. The map $\varphi$ also lifts to $\tilde{S}$ and we can choose a lift $\tilde{C}$ of $C$ such that it is fixed (setwise) by the lift $\tilde{\varphi}$ of $\varphi$. The ideal points of $\tilde{C}$ cut the circle at infinity into segments (Figure 5).

![Figure 5. The lift of an ideal polygon (left) and of a crown (right). $\tilde{\beta}$ is the lift of the boundary component $\beta$ of the crown.](image)

Each segment between two ideal vertices of $\tilde{C}$ contains in its interior exactly one fixed point; these fixed points of $\tilde{\varphi}$ on $S^1_{\infty}$ are alternatively ideal vertices of lifts $\tilde{C}_\mu$ of components $C_\mu$ of $S \setminus \mu$ and ideal vertices of lifts $\tilde{C}_\lambda$ of components $C_\lambda$ of $S \setminus \lambda$ and they are alternatively sinks and sources; cf. Thurston and Handel [7] and [3].

Consider now a completion $\overline{\mu}$ of $\mu$ such that all the extra leaves of $\overline{\mu}$ are isolated. Since $\varphi$ has no Dehn twists along its reducing multicurve, $\overline{\mu}$ is fixed by $\varphi$. The measured geodesic lamination $\lambda$ is totally transverse to $\overline{\mu}$, that is, $\lambda \in ML(\overline{\mu})$. Let $F_\lambda$ be a measured foliation corresponding to $\lambda$. By a result of Thurston (cf. Theorem 3.1 above), there exists a unique hyperbolic structure $h$ on $S$ such that $F_{\overline{\mu}}(h) = F_\lambda$, where $F_{\overline{\mu}}(h)$ is the horocyclic foliation.

**Lemma 6.2.** We have

$$F_{\overline{\mu}}(\varphi h) = \varphi(F_{\overline{\mu}}(h)) = kF_{\overline{\mu}}(h).$$

*Proof.* Since $\varphi(\overline{\mu} = \overline{\mu})$ and since $h$ and $\varphi h$ are isometric hyperbolic structures on $S$, the leaves of the foliations $F_\lambda = F_{\overline{\mu}}(h)$ and those of $F_{\overline{\mu}}(\varphi h)$ have the same endpoints on the circle at infinity, once we lift the situation to the universal coverings. But these endpoints are those of $\lambda$ and they are fixed by $\tilde{\varphi}$ setwise. Hence $F_{\overline{\mu}}(\varphi h) = F_\lambda$ (here, equality forgets about the transverse measures), or, equivalently, $\lambda_{\overline{\mu}}(h) = \lambda_{\overline{\mu}}(\varphi h) = \lambda$ setwise. Let $k'$ be the multiplicative factor:

$$\lambda_{\overline{\mu}}(h) = k' \lambda_{\overline{\mu}}(\varphi h) = k' \lambda.$$

Then,

$$\ell_{\varphi h} = \ell_h(\varphi^{-1} \mu) = k \ell_h(\mu) = i(\lambda_{\overline{\mu}}(\varphi h), \mu) = k' i(\lambda_{\overline{\mu}}(h), \mu) = k' \ell_h(\mu).$$

Hence $k = k'$ and the lemma is proved. \[\square\]
Thus, \( \varphi \) fixes globally a stretch line and \( d_T(h, \varphi h) = \log k \), that is, \( \varphi \) acts by translation on that stretch line.

This proves proposition 6.1. \( \square \)

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