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Optimal Portfolio Liquidation with Limit Orders

Olivier Guéant,∗ Charles-Albert Lehalle,**Joaquin Fernandez Tapia***

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Abstract

This paper addresses the optimal scheduling of the liquidation of a portfolio using a new angle. Instead of focusing only on the scheduling aspect like Almgren and Chriss in [2], or only on the liquidity-consuming orders like Obizhaeva and Wang in [31], we link the optimal trade-schedule to the price of the limit orders that have to be sent to the limit order book to optimally liquidate a portfolio. Most practitioners address these two issues separately: they compute an optimal trading curve and they then send orders to the markets to try to follow it. The results obtained here solve simultaneously the two problems. As in a previous paper that solved the “intra-day market making problem” [19], the interactions of limit orders with the market are modeled via a Poisson process pegged to a diffusive “fair price” and a Hamilton-Jacobi-Bellman equation is used to solve the trade-off between execution risk and price risk. Backtests are finally carried out to exemplify the use of our results.

Introduction

Optimal scheduling of large orders in order to control the overall trading costs with a trade-off between market impact (demanding to trade slow) and market risk (urging to trade fast) has been proposed in the litterature in the late nineties mainly by Bertsimas and Lo [8] and Almgren and Chriss [2]. If the original approach has been recently generalized in several directions (see for instance [3, 4, 13, 14, 15, 18, 26, 29, 34]), only few attempts have been made to drill down the model at the level of the interactions with the order books. The more noticeable proposal is the one by Obizhaeva and Wang [31], followed and sophisticated by Alfonsi, Fruth and Schied [1] or Predoiu, Shaikhet and Shreve [33]. This branch of the optimal trading literature1 focuses on the dynamics initiated by aggressive orders hitting a martingale and resilient order-book2, ignoring then trading by passive orders.

Just recall that during the continuous auction processes implemented by most electronic trading pools, market participants send their open interests (i.e. buy or sell orders) to a queuing system where a “first in first out” queue stands at each possible price. If a buy (respectively sell) order reaches a queue of sell (resp. buy) orders, a transaction occurs (see

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1see also [10, 20, 23, 24] for different approaches.

2See [17, 22] for the admissible transient market impact models.
for instance [28] for more explanations and modelings). Orders generating trades are said to be aggressive or liquidity-consuming ones; orders filling queues are said to be passive or liquidity-providing ones. In practice, most trading algorithms are as passive as possible (a typical balance for a scheduling algorithm is around 60% of passively obtained trades – see [27]).

The economic literature first explored and studied these interactions between orders sent to a continuous auction system by different actors from a global efficiency viewpoint.

With the fragmentation of equity markets in the US and in Europe, the issue of linking optimal posting prices to the optimal liquidation of a portfolio is more and more important. A trading algorithm has to find an optimal scheduling or rhythm for its trading, but also to choose a sequel of prices and quantities of orders to send to the markets to follow this optimal rhythm as much as possible.

This paper answers this “optimal scheduling and posting” problem as a whole. Indeed, and in contrast with most of the preceding literature, we propose a new approach which is liquidity-providing oriented: liquidation strategies involve limit orders and not only market orders. As a consequence, the classical trade-off of the literature between market impact, or execution costs, and price risk disappears in our setting since no execution cost is incurred. However, since the broker does not know when his orders are going to be executed – if at all –, a new risk is borne: (non-)execution risk. If a limit ask order is inserted in the order book, probability of execution and eventually time of execution will depend on the price of the order.

In our framework, the flow of trades “hitting” a passive order at a distance $\delta$ from the “fair price” $S_t$ (modeled by a Brownian Motion) follows an adapted Poisson process of intensity $A \exp(-k\delta)$. It means that the further away from the “fair price” an order is posted, the less transactions it will obtain. If the limit order price is far above the best ask price, the trading gain may be high but execution is not guaranteed and the broker is exposed to the risk of a price decrease. On the contrary, if the limit order price is near the best ask price, or even reduces the market bid-ask spread, gains will be small but the probability of execution will be higher, resulting in faster trading and less price risk.

Our modeling paradigm for optimal liquidation is in fact rooted to recent works in other areas of algorithmic trading. Market making models developed by Ho and Stoll [21] or more recently by Avellaneda and Stoikov [5] for “high frequency market making in an order-book” are instances of the use of limit orders in the financial literature. Our approach is more precisely inspired from the resolution of the “market making” problem in a companion paper.

The main limitations of our models are twofold. First, our framework deals with one trading venue only. Hence we do not model a “smart order routing” (SOR) mechanism but it can be seen as the consolidation of all available trading venues, without taking directly into account the potential specificity of each of them.

Second, market impact is not modeled in our framework, be it permanent or transient. In previous works on optimal trade scheduling, market impact was typically rendered by an explicit model because trading was done with liquidity-consuming orders. The same kind of assumptions could have been made on executed orders but, the introduction of limit orders in the literature on optimal trading being quite recent, there is still no model for the market impact of liquidity-providing orders.

3see [16] for a study of the effect of “smart order routing” on competitive trading venues, or [9] for a study of the efficiency of order matching mechanisms.

4Kratz and Schöneborn [25] proposed an approach with both market orders and access to dark pools.

5The actual models studying the SOR problem across several venues are more focused on routing across Dark Pools specifically (see [30] for a statistical approach or [32] for a probabilistic one).
To the authors’ knowledge, it is indeed the first proposal to drill down to passive orders modeling to solve the optimal trade scheduling for large orders\(^6\). It is organized as follows: in the first part, we present the setting of the model and the main hypotheses on execution. The second part is devoted to the resolution of the partial differential equations arising from the control problem. Part 3, deals with three special cases, namely the time-asymptotic case, the “no-volatility” benchmark and a limiting case in which the trader has a large incentive to liquidate before the end. These special cases provide closed-form formulae allowing us to better understand the forces at stake. Then, in part 4, we carry out comparative statics and discuss the way optimal strategies depend on the model parameters. Finally, in part 5, we show how our approach can be used in practice for optimal liquidation.

1 Setup of the model

We consider a trader who has to liquidate a portfolio containing a large quantity \(q_0\) of a given stock. We suppose that the reference price of the stock (that can be considered the mid-price or the best bid quote for example) moves as a brownian motion with a drift:

\[
dS_t = \mu dt + \sigma dW_t
\]

The trader under consideration will continuously propose an ask quote denoted \(S^a_t = S_t + \delta^a_t\) and will hence sell shares according to the rate of arrival of aggressive orders at the prices he quotes.

His inventory \(q_t\), that is the quantity he holds, is given by \(q_t = q_0 - N^a_t\) where \(N^a\) is the jump process giving the number of shares he sold\(^7\). This jump process is supposed to be a Poisson process and to simplify the exposition we consider that jumps are of unitary size\(^8\). Arrival rates obviously depend on the price \(S^a_t\) quoted by the trader and we assume, in accordance with most datasets, that intensity \(\lambda^a\) associated to \(N^a\) is of the following form:

\[
\lambda^a(\delta^a) = A \exp(-k\delta^a) = A \exp(-k(s^a - s))
\]

This means that the cheaper the order price, the faster it will be executed.

As a consequence of his trades, the trader has an amount of cash whose dynamics is given by:

\[
dX_t = (S_t + \delta^a_t)dN^a_t
\]

The trader has a time horizon \(T\) to liquidate the portfolio and his goal is to optimize the expected utility of his P&L at time \(T\). We will focus on CARA utility functions and we suppose that the trader optimizes:

\[
\sup_{(\delta^a_t)_{t \in [0,T]}} \mathbb{E}[-\exp(-\gamma X_T + q_T(S_T - b))]
\]

\(^6\)It recently came to our knowledge that a similar approach for liquidation with limit orders is being developed independently by E. Bayraktar and M. Ludkovski \(^7\). Their approach uses the same framework as ours to describe the price process and the execution mechanism. However, they only consider risk-neutral traders and consequently they do not take account of risk, be it price risk, or execution risk.

\(^7\)Once the whole portfolio is liquidated, we assume that the trader remains inactive.

\(^8\)It is important to notice that 1 share may be understood as 1 bunch of shares, each bunch being of the same size, typically the average trade size (hereafter ATS) or a fraction of it. If one wants to replace orders of size 1 by orders of size \(\delta q\) in the model, this can be done easily. However, the framework of the model imposes to trade with orders of constant size, an hypothesis that is an approximation of reality since orders may in practice be partially filled.
where $\mathcal{A}$ is the set of predictable processes on $[0,T]$, bounded from below, where $\gamma$ is the absolute risk aversion characterizing the trader, where $X_T$ is the amount of cash at time $T$, where $q_T$ is the remaining quantity of shares in the inventory at time $T$ and where $b$ is a cost one has to incur to liquidate the eventual remaining quantity.

2 Resolution

2.1 Hamilton-Jacobi-Bellman equation

The optimization problem set up in the preceding section can be solved using classical Bellman tools. To this purpose, we introduce the Hamilton-Jacobi-Bellman equation associated to the optimization problem:

\[
\begin{align*}
(\text{HJB}) & \quad \partial_t u(t, x, q, s) + \mu \partial_x u(t, x, q, s) + \frac{1}{2} \sigma^2 \partial^2_{ss} u(t, x, q, s) \\
& \quad + \sup_{\delta} \lambda(\delta) [u(t, x + s + \delta, q - 1, s) - u(t, x, q, s)] = 0 \\
\end{align*}
\]

with the final condition:

\[ u(T, x, q, s) = -\exp(-\gamma(x + q(s - b))) \]

and the boundary condition:

\[ u(t, x, 0, s) = -\exp(-\gamma x) \]

To solve the Hamilton-Jacobi-Bellman equation, we will use a change of variables that transforms the PDEs in a system of linear ODEs.

**Proposition 1** (A system of linear ODEs). Let’s consider a family of functions $(w_q)_{q \in \mathbb{N}}$ solution of the linear system of ODEs $(S)$ that follows:

\[
\forall q \in \mathbb{N}, \dot{w}_q(t) = (\alpha q^2 - \beta q) w_q(t) - \eta w_{q-1}(t)
\]

with $w_q(T) = e^{-kqb}$ and $w_0 = 1$, where $\alpha = \frac{k^2}{2} \gamma \sigma^2$, $\beta = k \mu$ and $\eta = A(1 + \frac{\gamma}{k})^{-(1+\frac{k}{2})}$.

Then $u(t, x, q, s) = -\exp(-\gamma(x + qs)) w_q(t)^{-\frac{\gamma}{2}}$ is solution of (HJB).

Now, using this system of ODEs, we can find the optimal quotes through a verification theorem:

**Theorem 1** (Verification theorem and optimal quotes). Let’s consider the solution $w$ of the system $(S)$ of Proposition 1.

Then, $u(t, x, q, s) = -\exp(-\gamma(x + qs)) w_q(t)^{-\frac{\gamma}{2}}$ is the value function of the control problem and the optimal ask quote can be expressed as:

\[
\delta^{as}(t, q) = \left( \frac{1}{k} \ln \left( \frac{w_q(t)}{w_{q-1}(t)} \right) + \frac{1}{\gamma} \ln \left( 1 + \frac{\gamma}{k} \right) \right)
\]
2.2 Numerical example

Proposition 1 and Theorem 1 provide a way to solve the Hamilton-Jacobi-Bellman equation and to derive the optimal quotes for a trader willing to liquidate a portfolio. To exemplify these results, considering a very large value\(^9\) for \(b\), we compute the optimal quotes when a quantity of shares up to 6 times the ATS has to be sold within 5 minutes (Figure 1).

![Figure 1: Optimal strategy \(\delta^*(-t, q)\) (in Ticks) for an agent willing to sell a quantity of shares up to 6 times the ATS within 5 minutes (\(\mu = 0\) (Tick.s\(^{-1}\)), \(\sigma = 0.3\) (Tick.s\(^{-2}\)), \(A = 0.1\) (s\(^{-1}\)), \(k = 0.3\) (Tick\(^{-1}\)) and \(\gamma = 0.05\) (Tick\(^{-1}\)))](image)

We clearly see that the optimal quotes depend on time and inventory in a monotonic way. Indeed, a trader with a lot of shares to get rid of wants to trade fast and will therefore propose a low price. On the contrary, a trader with only a few shares in his portfolio may be willing to benefit from a trading opportunity and will send an order with a higher price because the risk he bears allows him to trade more slowly.

Now, coming to the time-dependence of the quotes, a trader with a given number of shares will, \(ceteris\ paribus\), lower his quotes as the time horizon gets closer. At the limit when \(t\) is close to the time horizon \(T\), the optimal quotes tend to very low values as we considered very large \(b\). In practice very negative values for the ask quotes have to be understood as market orders on the bid side.

Also, we see that optimal quotes have an asymptotic behavior as time horizon increases. The associated limiting case will be studied in depth in the next section.

Finally, the trading curve associated to the above optimal quotes can be obtained by Monte-Carlo simulations as exemplified on Figure 2.

\(^9\)In all computations, we considered very large values for \(b\) to force the trader to use every endeavor to liquidate the portfolio before time \(T\).
Figure 2: Solid line: Trading curve for an agent willing to sell a quantity of shares equal to 6 times the ATS within 5 minutes ($\mu = 0$ (Tick$\cdot$s$^{-1}$), $\sigma = 0.3$ (Tick$\cdot$s$^{-\frac{3}{2}}$), $A = 0.1$ (s$^{-1}$), $k = 0.3$ (Tick$^{-1}$) and $\gamma = 0.05$ (Tick$^{-1}$)). Dotted line: Trading curve calculated using the Almgren-Chriss framework with the same parameters and the impact function $f(v) = 20v^{1+\frac{3}{2}}$.

3 Special cases

The above equations can be solved explicitly for $w$ and hence for the optimal quotes using the above verification theorem. However, the resulting closed-form expressions are not really tractable and do not provide any intuition on the behavior of the optimal quotes. Three special cases are now considered for which simpler closed-form formulae can be derived. We start first with the limiting behavior of the quotes, when the time horizon $T$ tends to infinity. We then consider a benchmark case in which there is no volatility ($\sigma = 0$) as an approximation for low-volatility cases and we finally consider, by analogy with the classical literature, the behavior of the solution as the liquidation cost $b$ increases.

3.1 Asymptotic behavior as $T \to +\infty$

We have seen on Figure 1 that the optimal quotes seem to exhibit an asymptotic behavior. We are in fact going to prove that $\delta^{a*}(0, q)$ tends to a limit as the time horizon $T$ tends to infinity.

Proposition 2 (Asymptotic behavior of the optimal quotes). Let's suppose that$^{10} \frac{\mu}{\gamma \sigma^2} < \frac{1}{2}$.
Let's consider the solution $w$ of the system $(S)$ of Proposition 1. Then:

$$\lim_{T \to +\infty} w_q(0) = \frac{\eta^q}{q!} \prod_{j=1}^{q} \frac{1}{\alpha_j - \beta}$$

The resulting asymptotic behavior for the optimal ask quote of Theorem 1 is:

$$\lim_{T \to +\infty} \delta^{a*}(0, q) = \frac{1}{k} \ln \left( \frac{A}{1 + \frac{2}{k} \alpha q^2 - \beta q} \right)$$

$^{10}$This condition is the same as $\alpha > \beta$. 

6
3.2 The “no-volatility” benchmark

Though unrealistic, we now concentrate on a benchmark case in which there is no volatility \( (\sigma = 0) \). In that benchmark case, the trader bears no price risk and the only risk he faces is linked to the non-execution of his orders.

In this framework, we can derive tractable formulae for \( w \) and for the optimal quotes.

**Proposition 3** (The “no-volatility” benchmark). Assume that \( \sigma = 0 \) and that there is no drift \( (\mu = 0) \).

Let’s define:

\[
w_q(t) = \sum_{j=0}^{q} \frac{\eta^j}{j!} e^{-kb(q-j)}(T-t)^j
\]

Then \( w \) defines a solution of the system \( (S) \) and the optimal quote is:

\[
\delta^{\text{as}}(t, q) = \left( \frac{1}{k} \ln \left( \frac{\sum_{j=0}^{q} \frac{\eta^j}{j!} e^{-kb(q-j)}(T-t)^j}{\sum_{j=0}^{q-1} \frac{\eta^j}{j!} e^{-kb(q-1-j)}(T-t)^j} \right) + \frac{1}{\gamma} \ln \left( 1 + \frac{\gamma}{k} \right) \right)
\]

It is noteworthy that, in the \( b = 0 \) case corresponding to a questionable absence of liquidation cost, we can find the results of [7] as a special case of ours when \( \gamma \) tends to 0.

3.3 Limiting behavior as \( b \to +\infty \)

Let us now consider the limiting case \( b \to +\infty \). Sending \( b \) to infinity corresponds to a situation in which more and more incentives are given to the trader for complete liquidation before time \( T \). If we look at the Almgren-Chriss-like literature on optimal execution, the authors are often assuming that \( q_T = 0 \)\(^{11} \). Hence, if one writes the value functions associated to most liquidity-consuming optimal strategies, it turns out that they are equal to \(-\infty\) at the horizon time \( T \) except when the inventory is equal to nought (hence \( b = +\infty \), in this paper). However, here, due to the uncertainty on execution, we cannot write a well-defined control problem when \( b \) is equal to \(+\infty\). Rather, we are interested in the limiting behavior when \( b \to +\infty \) and the limit we obtain provide approximations for when the incentive to liquidate before time \( T \) is large.

By analogy with the initial literature on optimal liquidation \([2]\), we can also have some limiting results on the so-called trading curve.

Hereafter we denote \( w_{b,q}(t) \) the solution of the system \( (S) \) for a given liquidation cost \( b \), \( \delta^{\text{as}}_{b}(t, q) \) the associated optimal quote and \( q_{b,t} \) the resulting process modeling the number of stocks in the portfolio.

**Proposition 4** (Form of the solutions and trading intensity). The limiting solution \( \lim_{b \to +\infty} w_{b,q}(t) \) is of the form \( A^v v_q(t) \) where \( v \) does not depend on \( A \).

The limit of the trading intensity \( \lim_{b \to +\infty} Ae^{-kb^\alpha} \) does not depend on \( A \).

If we define the trading curve as the average evolution of the inventory, i.e. \( V_b(t) := \mathbb{E}[q_{b,t}] \), then the limit of the trading curve \( V(t) = \lim_{b \to +\infty} V_b(t) \) does not depend on \( A \).

More results can be obtained in the no-volatility case:

**Proposition 5** (The “no-volatility” benchmark, \( b \to +\infty \)). Assume that \( \sigma = 0 \) and consider first the no-drift case \( (\mu = 0) \).

\[
\lim_{b \to +\infty} w_{b,q}(t) = \frac{\eta^q}{q!} (T-t)^q
\]

\(^{11}\)The authors most often consider target problems in which the target can always be attained.

\(^{12}\)In our case indeed, since the execution process is not deterministic, the trading curve associated to the optimal strategy can only be defined on average.
The limit of the optimal quote is given by:

$$\lim_{b \to +\infty} \delta_b^*(t, q) = \left(\frac{1}{k} \ln \left( \eta \frac{(T-t)}{q} \right) + \frac{1}{\gamma} \ln \left(1 + \frac{\gamma}{k}\right) \right)$$

that can also be written:

$$\lim_{b \to +\infty} \delta_b^*(t, q) = \frac{1}{k} \ln \left( \frac{A}{1 + \frac{k}{\eta} q} (T-t) \right)$$

The limit of the associated trading curve is $V(t) = q_0 \left(1 - \frac{t}{T}\right)^{1+\frac{\eta}{k}}$.

If $\mu \neq 0$, similar results can be obtained:

$$\lim_{b \to +\infty} w_b(t) = \eta q \left( \frac{e^{\beta(T-t)} - 1}{\beta} \right)^q$$

The limit of the optimal quote is:

$$\lim_{b \to +\infty} \delta_b^*(t, q) = \left(\frac{1}{k} \ln \left( \eta \frac{e^{\beta(T-t)} - 1}{\beta} \right) + \frac{1}{\gamma} \ln \left(1 + \frac{\gamma}{k}\right) \right)$$

that can also be written:

$$\lim_{b \to +\infty} \delta_b^*(t, q) = \frac{1}{k} \ln \left( \frac{A}{1 + \frac{k}{\eta} q} \frac{1}{e^{\beta(T-t)}} \right)$$

The limit of the associated trading curve is $V(t) = q_0 \left(1 - e^{-\beta(T-t)}\right)^{1+\frac{\eta}{k}}$.

## 4 Comparative statics

### 4.1 Intuition from the above cases

Before going to comparative statics numerically, we focus on the particular cases for which tractable closed form formulae have just been derived. These closed-form formulae provide an approximation for the optimal quotes and trading curves respectively when $t$ is far from $T$, when volatility is small or when liquidation cost is large. Hence, we can start to discuss the role played by the different parameters in these contexts.

Focusing first on the optimal quotes, we see both in the asymptotic case and in the “no-volatility” benchmark case (when $b \to \infty$) that, quite naturally, the optimal ask quote is an increasing function of $A$. When trading intensity is high, many trades occur and a limit order inserted far above the reference price has indeed a large probability to be executed. Risk aversion also plays an important role. Both in the asymptotic case and in the “no-volatility” benchmark case (also this last one misses part of the picture, ignoring price risk), a very risk-adverse agent will indeed be willing to reduce execution risk and will submit orders at low price.

Now, as far as $k$ is concerned, the dependence of the optimal quote on $k$ is ambiguous because the interpretation of $k$ depends on the optimal quote itself. An increase in $k$ corresponds indeed to a decrease in the probability to be executed for prices above the reference price. However, due to the exponential form for execution intensity, the exact opposite is true for quotes below reference price, an increase in $k$ implying an increase in the probability to be executed for quotes below reference price.
Now, turning to the trading curve in the “no-volatility” benchmark case when $b \to \infty$, we see that the agent trades fast when risk aversion $\gamma$ is large or when $k$ is small. This is clearly instanced by Figure 3.

![Figure 3: Trading curves of an agent willing to sell 6 times the ATS for different sets of parameters (in the no-drift case). Dots: risk neutral case $\gamma = 0$. Dotted line: $k = 0.3$ (Tick$^{-1}$), $\gamma = 0.05$ (Tick$^{-1}$). Solid line: $k = 0.2$ (Tick$^{-1}$), $\gamma = 0.1$ (Tick$^{-1}$)](image)

Also, the agent trades faster when the price is expected to decrease to avoid selling at low price. This is clearly instanced by Figure 4.

![Figure 4: Trading curves of an agent willing to sell 6 times the ATS for different values of the drift. $\mu = 1/150$ (Tick.s$^{-1}$) (dots), $\mu = 0$ (Tick.s$^{-1}$) (dotted line), $\mu = -1/150$ (Tick.s$^{-1}$) (solid line) $k = 0.2$ (Tick$^{-1}$), $\gamma = 0.1$ (Tick$^{-1}$)](image)
4.2 General case

Now, let’s turn to the general case to take account of volatility and thus of the price risk dimension of the problem.

As far as the drift is concerned, quotes are naturally increasing with $\mu$. If indeed the trader expects the price to move down, he is going to send orders at low prices to be executed fast and thus reduce the risk to suffer from the decrease in price. This is well exemplified in Figure 5.

![Figure 5](image)

Figure 5: Dependence on $\mu$ of $\delta_a^+$ for an agent willing to sell a quantity of shares up to 6 times the ATS in the next 5 minutes. ($\mu = -1/150$ (Tick.$s^{-1}$) (dots), $\mu = 0$ (Tick.$s^{-1}$) (dotted line), $\mu = 1/150$ (Tick.$s^{-1}$) (solid line), $\sigma = 0.3$ (Tick.$s^{-0.5}$), $A = 0.1$ (s$^{-1}$), $k = 0.3$ (Tick$^{-1}$) and $\gamma = 0.05$ (Tick$^{-1}$))

Now, coming to volatility, the optimal quotes depend on $\sigma$ in a monotonic way. If there is an increase in volatility, the price risk increases. In order to reduce this additional price risk the trader will send orders at cheaper price. This is what we observe numerically on Figure 6.

![Figure 6](image)

Figure 6: Dependence on $\sigma$ of $\delta_a^+$ for an agent willing to sell a quantity of shares up to 6 times the ATS in the next 5 minutes. ($\mu = 0$ (Tick.$s^{-1}$), $\sigma = 0$ (Tick.$s^{-0.5}$) (dots), $\sigma = 0.3$ (Tick.$s^{-0.5}$) (solid line), $\sigma = 0.6$ (Tick.$s^{-0.5}$) (dotted line), $A = 0.1$ (s$^{-1}$), $k = 0.3$ (Tick$^{-1}$) and $\gamma = 0.05$ (Tick$^{-1}$))
Now, coming to $A$, we observe numerically that the optimal quote is an increasing function of $A$ (see Figure 7).

Figure 7: Dependence on $A$ of $\delta^{**}$ for an agent willing to sell a quantity of shares up to 6 times the ATS in the next 5 minutes. ($\mu = 0$ (Tick.$s^{-1}$), $\sigma = 0.3$ (Tick.$s^{-2}$), $A = 0.05$ (s$^{-1}$) (dots), $A = 0.10$ (s$^{-1}$) (solid line), $A = 0.15$ (s$^{-1}$) (dotted line), $k = 0.3$ (Tick$^{-1}$) and $\gamma = 0.05$ (Tick$^{-1}$)).

Then as far as the dependence of the optimal quotes on $k$ is concerned, the above discussion on the interpretation of $k$ is still valid. Since high volatility may more often induce optimal quotes below the reference price, the dependence on $k$ is not the same at all times and for all values of the inventory (Figure 8 and Figure 9).

Figure 8: Dependence on $k$ of $\delta^{**}$ for an agent willing to sell a quantity of shares up to 6 times the ATS in the next 5 minutes. ($\mu = 0$ (Tick.$s^{-1}$), $\sigma = 0.3$ (Tick.$s^{-2}$), $A = 0.10$ (s$^{-1}$), $k = 0.2$ (Tick$^{-1}$) (dots), $k = 0.3$ (Tick$^{-1}$) (solid line), $k = 0.4$ (Tick$^{-1}$) (dotted line) and $\gamma = 0.05$ (Tick$^{-1}$))
Finally, turning to the risk aversion $\gamma$, two effects are at stake that go in the same direction. The risk aversion is indeed common for both price risk and execution risk. Hence if risk aversion increases, the trader will try to reduce both price risk and execution risk, thus selling at cheaper price. We indeed see on Figure 10 that optimal quotes are decreasing in $\gamma$.

Figure 9: Dependence on $k$ of $\delta^{oa}$ for an agent willing to sell a quantity of shares up to 6 times the ATS in the next 5 minutes. ($\mu = 0$ (Tick.s$^{-1}$), $\sigma = 3$ (Tick.s$^{-2}$), $A = 0.10$ (s$^{-1}$), $k = 0.2$ (Tick$^{-1}$) (dots), $k = 0.3$ (Tick$^{-1}$) (solid line), $k = 0.4$ (Tick$^{-1}$) (dotted line) and $\gamma = 0.05$ (Tick$^{-1}$))

Figure 10: Dependence on $\gamma$ of $\delta^{oa}$ for an agent willing to sell a quantity of shares up to 6 times the ATS in the next 5 minutes. ($\mu = 0$ (Tick.s$^{-1}$), $\sigma = 0.3$ (Tick.s$^{-2}$), $A = 0.10$ (s$^{-1}$), $k = 0.3$ (Tick$^{-1}$) and $\gamma = 0.01$ (Tick$^{-1}$) (dots), $\gamma = 0.05$ (Tick$^{-1}$) (solid line), $\gamma = 0.1$ (Tick$^{-1}$) (dotted line))
5 Applications

Before using the above model in reality, we need to discuss some features of the model that need to be adapted before any backtest is possible.

First of all, the model is continuous in both time and space while the real control problem under scrutiny is intrinsically discrete in space, because of the tick size, and in time, because orders have a certain priority and changing position too often reduces the actual chance to be reached by a market order. Hence, the model has to be reinterpreted in a discrete way. In terms of prices, quotes must not be between two ticks and we decided to ceil or floor the optimal quotes with probabilities that depend on the respective proximity to the neighboring quotes. In terms of time, an order is sent to the market and is not canceled nor modified for a given period $\Delta t$, unless a trade occurs and, though perhaps partially, fills the order. Now, when a trade occurs and changes the inventory or when an order stayed in the order book for longer than $\Delta t$, then the optimal quote is updated and, if necessary, a new order is inserted.

Now, concerning the parameters, $\sigma$, $A$ and $k$ can be calibrated easily on trade-by-trade limit order book data while $\gamma$ has to be chosen. However, it is well known by practitioners that $A$ and $k$ have to depend at least on the actual market bid-ask spread. Since we do not explicitly take into account the underlying market, there is no market bid-ask spread in the model. Thus, we simply chose to calibrate $A$ and $k$ as functions of the market bid-ask spread, making then an off-model hypothesis.

Turning to the backtests, they were carried out with trade-by-trade data and we assumed that our orders were entirely filled when a trade occurred above the ask price quoted by the agent. Our goal here is just to provide examples in various situations and, to exemplify the practical use of this model, we carried out several backtests\(^\text{13}\) on the French stock AXA, either on very short periods (5 to 10 minutes) or on slightly longer periods of a few hours.

The first two examples (Figures 11 and 12) consist in getting rid of a quantity of shares equal to 3 times the ATS\(^\text{14}\). The periods have been chosen to capture the behavior in both bullish and bearish markets.

On Figure 11, we see that the first order is executed after 50 seconds. Then, since the trader has only 2 times the ATS left in his inventory, he sends an order at a higher price. Since the market price moves up, the second order is executed in the next 30 seconds, in advance on the average schedule. This is the reason why the trader places a new order far above the best ask. Since this order is not executed within the time window $\Delta t$, it is canceled and new orders are successively inserted with lower prices. The last trade happens less than 1 minute before the end of the period. Overall, on this example, the strategy works far better than a market order (even ignoring execution costs).

On Figure 12, we see the use of the strategy in a bearish period. The first order is executed rapidly and since the market price goes down, the trader’s last orders are only executed at the end of the period when prices of orders are lowered substantially since selling becomes of utmost importance. Practically, this obviously raises the question of linking a trend detector to these optimal liquidation algorithms.

\(^{13}\)No drift in prices is assumed in the strategy used for backtesting.

\(^{14}\)In the backtests we do not deal with quantity and priority issues in the order books and supposed that our orders were always entirely filled.
Figure 11: Backtest example on AXA (November 5th 2010). The strategy is used with $\gamma = 10 \text{ (euro}^{-1})$ to get rid of a quantity of shares equal to 3 times the ATS within 5 minutes. Top: quotes of the trader (bold line), market best bid and ask quotes (thin lines). Trades are represented by dots. Bottom left: evolution of the inventory. Bottom right: P&L.
Figure 12: Backtest example on AXA (November 5th 2010). The strategy is used with $\gamma = 10$ (euro$^{-1}$) to get rid of a quantity of shares equal to 3 times the ATS within 5 minutes. Top: quotes of the trader (bold line), market best bid and ask quotes (thin lines). Trades are represented by dots. Bottom left: evolution of the inventory. Bottom right: P&L.
Now, another example is shown on Figure 13 where a trader wants to trade a quantity of shares equal to 6 times the ATS within 10 minutes. The analysis is similar to the preceding ones, the market being even more bullish than in the first example.

Figure 13: Backtest example on AXA (November 5th 2010). The strategy is used with $\gamma = 10$ (euro$^{-1}$) to get rid of a quantity of shares equal to 6 times the ATS within 10 minutes. Top: quotes of the trader (bold line), market best bid and ask quotes (thin lines). Trades are represented by dots. Bottom left: evolution of the inventory. Bottom right: P&L.
Finally, the model can also be used on longer periods and we exhibit the use of the algorithm on a period of two hours, to sell a quantity of shares equal to 20 times the ATS (Figure 14).

Figure 14: Backtest example on AXA (November 8th 2010). The strategy is used with $\gamma = 1 \text{ (euro}^{-1})$ to get rid of a quantity of shares equal to 20 times the ATS within 2 hours. Top: quotes of the trader (bold line), market best bid and ask quotes (thin lines). Trades are represented by dots. Bottom left: evolution of the inventory. Bottom right: P&L.
Conclusion

As claimed in the introduction, this paper is, to authors’ knowledge, the first proposal to optimize the trade scheduling of large orders with small passive orders. Thanks to an innovative change of variables, it provides an explicit solution in two steps: (1) solve an ODEs, (2) deduce the optimal price of the order to be sent to the market.

The choices of modeling made here have been more extensively discussed in [19]. It is nevertheless worthy to underline that no explicit model of what could be called “passive market impact” (i.e. the perturbations of the price formation process by liquidity provision) is used here. Just note that up to now, no quantitative model of this type of impact has been proposed in the literature. Thanks to very promising and recent studies of the multi-dimensional point processes governing the arrival of orders (see for instance the link between the imbalance in the order flow and the moves of the price studied in [11] or [12], or interesting properties of Hawkes-like models in [6]), we can hope for obtaining models of this kind in the near future. The authors will try to embed them into the HJB framework used here. In between, an on-going work dedicated to model dependencies between the Brownian motion supporting $S_t$ and the Poisson process $N^a_t$ is under consideration.
Appendix

Proof of Proposition 1 and Theorem 1:

First, let us remark that a solution \((w,q)\) of (S) exists and is unique and that, by immediate induction, its components are strictly positive for all times. Then, let’s introduce \(u(t, x, q, s) = -\exp(-\gamma(x + qs)) w_q(t)^{-\frac{\gamma}{k}}\).

We have:

\[
\partial_t u + \mu \partial_s u + \frac{1}{2} \sigma^2 \partial^2_{ss} u = -\frac{\gamma}{k} w_q(t) u - \gamma q u + \frac{\gamma^2 \sigma^2}{2} q^2 u
\]

Now, concerning the non-local part of the equation, we have:

\[
\sup_{\delta^n} \lambda^n(\delta^n) [u(t, x + s + \delta^n, q - 1, s) - u(t, x, q, s)]
\]

\[
= \sup_{\delta^n} A e^{-k\delta^n} u(t, x, q, s) \left[ \exp(-\gamma \delta^n) \left( \frac{w_{q-1}(t)}{w_q(t)} \right)^{-\frac{\gamma}{k}} - 1 \right]
\]

The first order condition of this problem corresponds to a maximum and writes:

\[
(k + \gamma) \exp(-\gamma \delta^n) \left( \frac{w_{q-1}(t)}{w_q(t)} \right)^{-\frac{\gamma}{k}} = k
\]

Hence we introduce the candidate \(\delta^{*n}\) for the optimal control:

\[
\delta^{*n} = \frac{1}{k} \ln \left( \frac{w_q(t)}{w_{q-1}(t)} \right) + \frac{1}{\gamma} \ln \left( 1 + \frac{\gamma}{k} \right)
\]

and

\[
\sup_{\delta^n} \lambda^n(\delta^n) [u(t, x + s + \delta^n, q - 1, s) - u(t, x, q, s)]
\]

\[
= -\frac{\gamma}{k + \gamma} A \exp(-k\delta^{*n}) u(t, x, q, s)
\]

\[
= -A \frac{\gamma}{k + \gamma} \left( k + \frac{\gamma}{k} \right)^{-\frac{\gamma}{k}} w_{q-1}(t) \frac{w_q(t)}{w_{q-1}(t)} \cdot u(t, x, q, s)
\]

Hence, putting the three terms together we get:

\[
\partial_t u(t, x, q, s) + \mu \partial_s u(t, x, q, s) + \frac{1}{2} \sigma^2 \partial^2_{ss} u(t, x, q, s)
\]

\[
+ \sup_{\delta^n} \lambda^n(\delta^n) [u(t, x + s + \delta^n, q - 1, s) - u(t, x, q, s)]
\]

\[
= -\frac{\gamma}{k} \frac{\dot{w}_q(t)}{w_q(t)} u - \gamma \mu u + \frac{\gamma^2 \sigma^2}{2} q^2 u - A \frac{\gamma}{k + \gamma} \left( 1 + \frac{\gamma}{k} \right) \frac{w_{q-1}(t)}{w_q(t)} u
\]

\[
= -\frac{\gamma}{k} \frac{u}{w_q(t)} \left[ \dot{w}_q(t) + k \mu q w_q(t) - \frac{k^2 \gamma^2 \sigma^2}{2} q^2 w_q(t) + A \left( 1 + \frac{\gamma}{k} \right)^{(1+\frac{\gamma}{k})} w_{q-1}(t) \right] = 0
\]

Now, noticing that the boundary and terminal conditions for \(w_q\) are consistent with the conditions on \(u\), we get that \(u\) verifies (HJB).

Now, we need to verify that \(u\) is indeed the value function associated to the problem and to prove that our candidate \((\delta^{*n})\) is indeed the optimal control. To that purpose, let’s consider a control \(v \in \mathcal{A}\) and let’s consider the following processes for \(\tau \in [t, T]::\)
\[ dS_t^s = \mu d\tau + \sigma dW_\tau, \quad S_t^s = s \]
\[ dX_t^{s,\nu} = (\nu - \nu_t) dN^a, \quad X_t^0 = x \]
\[ dq_t^{s,\nu} = -dN^a, \quad q_t^{s,\nu} = q \]

where the Poisson process has stochastic intensity \((\lambda_\tau)_\tau\) with \(\lambda_\tau = Ae^{-k\tau}1_{q,\tau \geq 1}\).\(^{15}\)

Now, let us write Itô’s formula for \(u\) since \(u\) is smooth:

\[
\begin{align*}
&\int_t^T \left( \partial_\tau u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s}) + \mu \partial_s u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s}) + \frac{\sigma^2}{2} \partial_{ss}^2 u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s}) \right) d\tau \\
&\quad + \int_t^T \left( u(\tau, X_{\tau-}^{t,x,\nu} + S_{\tau-}^{t,s} + \nu_t, q_{\tau-}^{t,\nu} - 1, S_{\tau-}^{t,s}) - u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s}) \right) \lambda_\tau d\tau \\
&\quad + \int_t^T \sigma \partial_s u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s}) dW_\tau \\
&\quad + \int_t^T \left( u(\tau, X_{\tau-}^{t,x,\nu} + S_{\tau-}^{t,s} + \nu_t, q_{\tau-}^{t,\nu} - 1, S_{\tau-}^{t,s}) - u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s}) \right) dM^a_\tau
\end{align*}
\]

where \(M^a\) is the compensated Poisson process associated to \(N^a\) for the intensity process \((\lambda_\tau)_\tau\).

Now, we have to ensure that the last two integrals consist of martingales so that their mean is 0. To that purpose, let us notice that \(\partial_s u = -\gamma u\) and hence we just have to prove that:

\[
\mathbb{E} \left[ \int_t^T u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s})^2 d\tau \right] < +\infty
\]

\[
\mathbb{E} \left[ \int_t^T \left| u(\tau, X_{\tau-}^{t,x,\nu} + S_{\tau-}^{t,s} + \nu_t, q_{\tau-}^{t,\nu} - 1, S_{\tau-}^{t,s}) \right| \lambda_\tau d\tau \right] < +\infty
\]

and

\[
\mathbb{E} \left[ \int_t^T \left| u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s}) \right| \lambda_\tau d\tau \right] < +\infty
\]

Now, remember that the process \(q_{\tau}^{t,\nu}\) takes values between 0 and \(q\) and that \(t \in [0, T]\). Hence, \(\exists \varepsilon > 0, w_q(t) > \varepsilon\) for the values of \(t\) and \(q\) under scrutiny and:

\[
u_t \geq \inf_{\tau \in [t, T]} S_{\tau-}^{t,s} \quad \Rightarrow \quad \int_t^T \left| u(\tau, X_{\tau-}^{t,x,\nu} + S_{\tau-}^{t,s} + \nu_t, q_{\tau-}^{t,\nu} - 1, S_{\tau-}^{t,s}) \right| \lambda_\tau d\tau < +\infty
\]

\[
\mathbb{E} \left[ \int_t^T u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s})^2 d\tau \right] = \mathbb{E} \left[ \int_t^T u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s})^2 d\tau \right] \\
\leq \varepsilon^{-2\gamma} \exp \left( -2\gamma (X_{\tau-}^{t,x,\nu} + q_{\tau}^{t,\nu} S_{\tau}^{t,s}) \right)
\]

\[
\leq \varepsilon^{-2\gamma} \exp \left( -2\gamma (x - q) \| \nu - \infty \| + 2q \inf_{\tau \in [t, T]} S_{\tau-}^{t,s} \inf_{\tau \in [t, T]} S_{\tau}^{t,s} < 0) \right)
\]

\[
\leq \varepsilon^{-2\gamma} \exp \left( -2\gamma (x - q) \| \nu - \infty \| \right) \left( 1 + \exp \left( -2\gamma q \inf_{\tau \in [t, T]} S_{\tau}^{t,s} \right) \right)
\]

Hence:

\[
\mathbb{E} \left[ \int_t^T u(\tau, X_{\tau-}^{t,x,\nu}, q_{\tau-}^{t,\nu}, S_{\tau-}^{t,s})^2 d\tau \right] \leq \varepsilon^{-2\gamma} \exp \left( -2\gamma (x - q) \| \nu - \infty \| \right) (T - t) \left( 1 + \mathbb{E} \left[ \exp \left( -2\gamma q \inf_{\tau \in [t, T]} S_{\tau}^{t,s} \right) \right] \right)
\]

\(^{15}\)This intensity being bounded since \(\nu\) is bounded from below.
\[
\leq e^{-2\gamma} \exp \left(-2\gamma (x - q\|\nu\|_\infty) (T - t) \right) \left(1 + \mathbb{E} \left[ \exp \left(-2\gamma q \inf_{\tau \in [t,T]} S^t_\tau \right) \right] \right) \\
\leq e^{-2\gamma} \exp \left(-2\gamma (x - q\|\nu\|_\infty) (T - t) \right) \left(1 + e^{-2\gamma q} \mathbb{E} \left[ \exp \left(2\gamma q \sqrt{T - t} |Y| \right) \right] \right) < +\infty
\]

where the last inequalities come from the reflection principle with \( Y \sim \mathcal{N}(0, 1) \) and the fact that \( \mathbb{E} \left[ e^{C|Y|} \right] < +\infty \) for any \( C \in \mathbb{R} \).

Now, the same argument works for the second and third integrals, noticing that \( \lambda \) is bounded from below and that \( \lambda \) is bounded.

Hence, since we have, by construction\(^{16}\)
\[
\partial_{\tau} u(\tau, X^t, q, S^t) + \mu \partial_{x} u(\tau, X^t, q, S^t) + \frac{\sigma^2}{2} \partial_{ss} u(\tau, X^t, q, S^t) + \left( u(\tau, X^t, q, S^t) + \nu_t q - 1, S^t \right) \lambda_t \leq 0
\]
we obtain that
\[
\mathbb{E} \left[ u(T, X^T, q, S^T) \right] = \mathbb{E} \left[ u(T, X^T, q, S^T) \right] \leq u(t, x, q, s)
\]
and this is true for all \( \nu \in \mathcal{A} \). Since for \( \nu = \delta^{a*} \) we have an equality in the above inequality we obtain that:
\[
\sup_{\nu \in \mathcal{A}} \mathbb{E} \left[ u(T, X^T, q, S^T) \right] \leq u(t, x, q, s) = \mathbb{E} \left[ u(T, X^T, \delta^{a*}, q, S^T) \right]
\]
This proves that \( u \) is the value function and that \( \delta^{a*} \) is optimal. \( \square \)

**Proof of Proposition 2:**

We have that
\[
\forall q \in \mathbb{N}, \dot{w}_q(t) = (\alpha q^2 - \beta q)w_q(t) - \eta w_{q-1}(t)
\]
Hence if we consider for a given \( Q \in \mathbb{N} \) the vector \( w(t) = \begin{pmatrix} w_0(t) \\ w_1(t) \\ \vdots \\ w_Q(t) \end{pmatrix} \) we have that \( w'(t) = Mw(t) \) where:
\[
M = \begin{pmatrix} 0 & 0 & \cdots & \cdots & \cdots & 0 \\ -\eta & \alpha - \beta & 0 & \cdots & \cdots & \cdots \\ 0 & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ \cdots & \cdots & \cdots & \cdots & \cdots & \cdots \\ 0 & \cdots & \cdots & \cdots & \cdots & \cdots \\ \end{pmatrix}
\]
with \( w(T) = \begin{pmatrix} 1 \\ e^{-kT} \\ \vdots \\ e^{-k(T+Q)} \end{pmatrix} \). Hence we know that, if we consider a basis \( (f_0, \ldots, f_Q) \) of eigenvectors \( (f_j \) being associated to the eigenvalue \( \alpha j^2 - \beta j) \), there exists \( (c_0, \ldots, c_Q) \in \mathbb{R}^{Q+1} \) independent of \( T \) such that:

---

\(^{16}\)This inequality is also true when the portfolio is empty because of the boundary conditions.
\[ w(t) = \sum_{j=0}^{Q} c_j e^{-(\alpha j^2 - \beta j)(T-t)} f_j \]

Consequently, since we assumed that \( \alpha > \beta \), we have that \( w^\infty := \lim_{T \to +\infty} w(0) = c_0 f_0 \). Now, \( w^\infty \) is characterized by:

\[(\alpha q^2 - \beta q)w^\infty_q = \eta w^\infty_{q-1}, q > 0 \quad w^\infty_0 = 1 \]

As a consequence we have:

\[ w^\infty_q = \frac{\eta^q}{q!} \prod_{j=1}^{q} \frac{1}{\alpha j - \beta} \]

The resulting asymptotic behavior for the optimal ask quote is:

\[ \lim_{T \to +\infty} \delta^{\ast\ast}(0, q) = \frac{1}{k} \ln \left( \frac{A}{1 + \frac{1}{k} \alpha q^2 - \beta q} \right) \]

\[ \square \]

**Proof of Proposition 3:**

The result of Proposition 3 is obtained by induction. For \( q = 0 \) the result is obvious. Now, if the result is true for some \( q \) we have that:

\[ \dot{w}_{q+1}(t) = -\sum_{j=0}^{q} \frac{\eta^{j+1}}{j!} e^{-kb(q-j)} (T-t)^j \]

Hence:

\[ w_{q+1}(t) = e^{-kb(q+1)} + \sum_{j=0}^{q} \frac{\eta^{j+1}}{(j+1)!} e^{-kb(q-j)} (T-t)^{j+1} \]

\[ w_{q+1}(t) = e^{-kb(q+1)} + \sum_{j=1}^{q+1} \frac{\eta^j}{j!} e^{-kb(q-j+1)} (T-t)^j \]

\[ w_{q+1}(t) = \sum_{j=0}^{q+1} \frac{\eta^j}{j!} e^{-kb(q+1-j)} (T-t)^j \]

This proves the results for \( w \) and then the result follows for the optimal quote. \[ \square \]

**Proof of Proposition 4:**

Because the solutions depend continuously on \( b \), we can directly get interested in the limiting equation:

\[ \forall q \in \mathbb{N}, \dot{w}_q(t) = (\alpha q^2 - \beta q)w_q(t) - \eta w_{q-1}(t) \]

with \( w_q(T) = 1_{q=0} \) and \( w_0 = 1 \).

Then, if we define \( v_q(t) = \lim_{b \to +\infty} \frac{w_q(t)}{A^q}, v \) solves:

\[ \forall q \in \mathbb{N}, \dot{v}_q(t) = (\alpha q^2 - \beta q)v_q(t) - \tilde{\eta} v_{q-1}(t) \]

with \( v_q(T) = 1_{q=0} \) and \( v_0 = 1 \), where \( \tilde{\eta} = \frac{\eta}{A} \) is independent of \( A \).
Hence \( v_q(t) \) is independent of \( A \).

Now, for the trading intensity we have:

\[
\lim_{b \to +\infty} A \exp (-k \delta^B(t, q)) = \lim_{b \to +\infty} \frac{A w_{b,q-1}(t)}{w_{b,q}(t)} \left(1 + \frac{\gamma}{k}\right)^{-\frac{k}{\gamma}} = \frac{v_{q-1}(t)}{v_q(t)} \left(1 + \frac{\gamma}{k}\right)^{-\frac{k}{\gamma}}
\]

and this does not depend on \( A \).

\[\square\]

**Proof of Proposition 5:**

Using the preceding proposition, we can now reason in terms of \( v \) and look for a solution of the form \( v_q(t) = \frac{h(t)}{q!} \).

Then,

\[
\forall q \in \mathbb{N}, \dot{v}_q(t) = -\beta q v_q(t) - \tilde{\eta} v_{q-1}(t), \quad v_q(T) = 1_{q=0}, \quad v_0 = 1
\]

\[\iff\ h'(t) = -\beta h(t) - \tilde{\eta} \quad h(T) = 0
\]

Hence, if \( \beta = k \mu \neq 0 \), the solution writes \( v_q(t) = \frac{\tilde{\eta} q!}{q!} \left(1 + \frac{\beta}{k} \ln \left(1 + \frac{\gamma}{k}\right)\right) \).

From Theorem 1, we obtain the limit of the optimal quote:

\[
\lim_{b \to +\infty} \delta^B(t, q) = \left(1 + \frac{\gamma}{k}\right) \ln \left(\frac{1 + \frac{\gamma}{k}}{q!} e^{-k \beta (T - t) - 1}\right)
\]

Using the expression for \( \tilde{\eta} \), this can also be written:

\[
\frac{1}{k} \ln \left(\frac{A}{1 + \frac{\gamma}{k}} \frac{1 + \frac{\gamma}{k}}{q!} \left(1 + \frac{\gamma}{k}\right)\right)
\]

Now, the for the trading intensity we get:

\[
\lim_{b \to +\infty} A \exp (-k \delta^B(t, q)) = \left(1 + \frac{\gamma}{k}\right) q \frac{\beta}{e^{\beta (T - t) - 1}}
\]

Hence, because the limit of the intensity is proportional to \( q \), the limit \( V(t) \) of the trading curve is characterized by the following ODE:

\[
V'(t) = -\left(1 + \frac{\gamma}{k}\right) V(t) \frac{\beta}{e^{\beta (T - t) - 1}}, \quad V(0) = q_0
\]

Solving this equation, we get:

\[
V(t) = q_0 \exp \left(-\left(1 + \frac{\gamma}{k}\right) \int_0^t \frac{\beta}{e^{\beta (T - s) - 1}} ds\right)
\]

\[
= q_0 \exp \left(-\left(1 + \frac{\gamma}{k}\right) \int_0^T \frac{1}{e^{\beta (T - s) - 1}} d\xi\right)
\]

\[
= q_0 \exp \left(-\left(1 + \frac{\gamma}{k}\right) \left[\ln \left(1 - \frac{1}{\xi}\right)\right] e^{\beta (T - t)}\right)
\]

\[
= q_0 \left(1 - e^{-\beta (T - t)}\right)^{1 + \frac{2}{\xi}}
\]

When \( \beta = 0 \) (i.e. \( \mu = 0 \)) we proceed in the same way or by a continuity argument. \(\square\)
References


