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Field induced coalescence of two free water drops in a viscous dielectric fluid

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Abstract—The basic process of coalescence of droplets in a flowing water-in-oil emulsion under the action of an electric field is considered. The coalescence probability depends on the ratio of time of close proximity of droplets and time of decrease of spacing down to drops contact. For two free drops aligned with the field, the dynamical problem consists in the deformation of the drops, their motion and the thinning of the oil film between the drops. For very small droplets, assuming a negligible interface deformation, a very small initial spacing and a high value of viscosity ratio leads to an order of magnitude estimate of the time required for the drops to achieve contact. Numerical simulations confirm that this time is roughly inversely proportional to the maximum initial electrostatic pressure p_{e0} at the facing interfaces and point up an influence of the electric Bond number defined as the ratio of electric and capillary forces.

Keywords—component; electrocoalescence; film thinning

I. INTRODUCTION

The phenomenon of merging of conducting liquid droplets suspended in an insulating liquid or gas, under the action of an electric field, is called electrocoalescence (EC) [1]. This process operates in electrocoalescers that are used in the petroleum industry for the removal of water coproduced with crude oil in the form of stable emulsions during recovery and desalting operations [2]. EC promotes the increase of the water droplets mean size and facilitates their gravitational separation from the oil phase [2]. However, the control and increase of the electro-coalescers efficiency suffer from the lack of precise knowledge of the numerous processes involved in EC. In particular, in modern electrocoalescers the droplets merging arises from the combined effects of hydrodynamic and electric forces. But, even in the simplest case of water droplets in a pure dielectric fluid, expressions for their rate of coalescence in a flowing emulsion are still missing.

We consider here the basic problem of electrically induced coalescence of two neighboring drops also affected by the liquid flow. For two close immobile water drops anchored on capillary tubes, the field induced electrostatic pressure results in a deformation of the interfaces. Above a critical value of the potential difference, the interfaces disrupt, potentially leading to coalescence [3,4]. For two drops which can move freely in a suspending viscous fluid, we do not deal with a stability problem for the static deformed interfaces but with a dynamical problem in which expel of the fluid between the drops plays the major role.

II. TOWARDS A TIME BASED EC CRITERION

In the state-of-the-art technologies for dewatering crude oils, EC happens in two stages. Firstly, the turbulent flow induces numerous quasi collisions of the water droplets. Then, the coalescence which would not occur naturally in most cases without applied electric field is promoted by the induced attraction force. A very important step towards the estimation of electrocoalescers efficiency involves the modeling of the time evolution of a flowing emulsion under an electric field. In this event, numerical simulation would be extremely suitable to determine the droplets trajectories and their possible merging. Though, it would require huge computing and (3-D) software capabilities that are, yet, unaffordable. Another possible approach consists in determining the droplets quasi collisions and using a coalescence probability law. The crucial point is then to obtain a criterion stating that the time t_{prox} of close proximity of two droplets in a flowing emulsion is greater than the time $t_{contact}$ required for expelling the fluid between them.

As the droplets have a small size (typically tens of micrometers in the emulsions) and as the suspending liquid is much more viscous than water, inertial effects are negligible and, in the absence of electric field, the droplets motion is induced by the local shear flow. As sketched in Fig. 1, two close drops roll around one another with a relative velocity $\sim \dot{\gamma}(z_2 - z_1)$, $\dot{\gamma}$ being the shear rate and x_i and z_i denoting the coordinates of the drops centers. For droplets of radius R_1 and R_2 there is proximity when $|x_2 - x_1| < \max(R_1, R_2)$ and :

$$t_{prox} \sim 2 \max(R_1, R_2) / [\dot{\gamma} (R_1 + R_2 + s)] \quad (1)$$

(s : spacing between drops). In the case $R_1 \sim R_2 \gg s$, $t_{prox} \sim 1/\dot{\gamma}$. We now turn toward determining $t_{contact}$ in the particular case of drops centerline aligned with the electric field.

Figure 1. Schematic representation of a collision between two water drops due to the local shear flow. θ is the angle between the field direction and the drops centerline.

III. NUMERICAL SIMULATION

We consider the time-dependent problem of drainage of the oil film between the water droplets. The film thinning arises from the motion and deformation of the two drops of conducting water, suspended in initially quiescent insulating oil and subjected to a uniform electric field. Simulations have been performed using the commercial software COMSOL Multiphysics™ which allows Electrohydrodynamic coupling and determination of the liquids flow fields and of the associated drops deformation. The retained configuration is presented in Fig. 2. The computational load is reduced by assuming axial symmetry and, in the particular case of equal-sized droplets, by considering the plane of symmetry defined by $z = 0$. The electric field is created by imposing a voltage step between two planar electrodes (upper and lower boundaries of the domain) separated by a distance H (Fig. 2).

The conducting drops are assumed to be electrically neutral; their potential at any time t is determined by solving the Laplace equation taking into account their shape and position. Gravitational effects are negligibly small for the range of drop diameter investigated. Motion of the fluids is governed by the Navier-Stokes equations, which are solved in oil and water (ensuring the conservation of droplets volume) taking into account the boundary conditions and the interfacial forces (the liquids are assumed to be surfactant free). The main modification of the software concerns the implementation of the interfacial tension forces in axisymmetric case through a weak formulation of the fluid dynamics equations [5]. Deformation of the water/oil interface is performed through an Arbitrary Lagrangian-Eulerian (ALE) formulation with moving meshes. This approach allows us to track the interface deformation in a very accurate way [5].

Simulations were performed considering drops of tap water ($\rho_w = 1000 \text{ kg/m}^3$, dynamic viscosity $\mu_w = 1 \text{ mPa.s}$, dielectric constant $\epsilon_{r,w} = 80$, conductivity $\sigma_w \geq 0.05 \text{ S/m}$) in a polybutene oil ($\rho_{oil} = 824 \text{ kg/m}^3$, $\mu_{oil} = 10.5 \text{ mPa.s}$, $\epsilon_{r,oil} = 2.3$, $\sigma_{oil} \leq 10^{-12} \text{ S/m}$) with interfacial tension γ on the order of $25 \cdot 10^{-3} \text{ N/m}$ (fluids used in experiments [6,7]). For large separation s_0 between evenly sized drops ($R_1 = R_2 = R_0$), to a first approx-

Figure 2. Two conducting drops freely suspended in an insulating oil and aligned with a uniform imposed field (electrode spacing $H = 20 R_2$).

ation the time necessary for drops to get into contact depends only on the relative spacing s_0/R_0 and not on R_0 (Fig. 3-a), despite the transient oscillation – accompanying the elongation – that is well marked for big drops (Fig. 3-b). This figure also shows that, at least for the retained applied field, during more than 95% of the oil drainage time there is no significant elongation and, therefore, no deformation of small droplets.

For large enough initial spacing s_0 , a very rough derivation based on Stokes formula and on the point-dipole approximation for drag and electric forces respectively leads to [8]:

$$t_{contact} = \frac{8}{15} \frac{\mu_{oil}}{\epsilon_0 \epsilon_{r,oil} E_0^2} \left[\left(\frac{R_1 + R_2 + s_0}{R_1 + R_2} \right)^5 - 1 \right] \quad (2)$$

and gives good predictions (within 20%) for s_0 greater than about $R_0/2$ [6]; this is due to under-estimates of both forces which partly compensate. But for s_0/R_0 smaller than about 0.2, the variation of $t_{contact}$ versus s_0 given by (2) is not correct and a different analysis is necessary.

IV. FILM DRAINAGE

The lubrication theory [9] which leads to drainage times for fully mobile interface much smaller than the computed ones [6] is not relevant because, in the present case, the axial variation of the radial velocity component u_{oil} in oil does not provide the main contribution to viscous dissipation. A rough estimate of

Figure 3. Temporal evolution of the relative oil film thickness s/s_0 (a), and drops axial elongation (b), for different drops radii R_0 . The applied field is $E_0 = 3 \text{ kV/cm}$; initial separation : $s_0 = 2 R_0$ (or $s_0 = R_0$ – triangle marks).

the velocity w_s of the drops of same radius R_0 can be derived by assuming a very small spacing ($s \ll R_0$) and a negligible drops deformation. Denoting by z_s the ordinate of the upper spherical interface and taking for z_s the paraboloidal approximation $z_s(r) = \frac{1}{2}(s + r^2/R_0)$, from mass conservation we obtain for the mean radial velocity component $\bar{u}_{oil}$ (r : radial co-ordinate) :

$$\bar{u}_{oil}(r) = w_s r / (s + r^2 / R_0) \quad (3)$$

with $\bar{u}_{max} = (1/2) \sqrt{R_0/s} w_s$ at $r = r^* = \sqrt{R_0 s}$ (r^* is also the length scale of radial variation of electrostatic pressure p_e at interfaces). Neglecting the inertial terms, we deduce from Navier-Stokes equations (cylindrical co-ordinates r and z) :

$$\frac{\partial p}{\partial r} \equiv \mu_{oil} \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial u_{oil}}{\partial r} \right) - \frac{u_{oil}}{r^2} + \frac{\partial^2 u_{oil}}{\partial z^2} \right] \quad (4)$$

$$\frac{\partial p}{\partial z} \equiv \mu_{oil} \left[\frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial w_{oil}}{\partial r} \right) + \frac{\partial^2 w_{oil}}{\partial z^2} \right] \quad (5)$$

where p stands for pressure in oil and w for axial velocity component. The flow of oil in the film induces a convective motion in the water drops analogous to a vortex ring with length scale r^* . In central zone of the oil film the derivatives $\partial u_{oil}/\partial z$ and $\partial u_w/\partial z$ are close to the normal derivatives of velocities at interfaces and the continuity of viscous stress imposes :

$$\mu_{oil} \partial u_{oil} / \partial z = \mu_w \partial u_w / \partial z \quad (6)$$

As $\mu_{oil} \gg \mu_w$ the radial velocity component at interfaces takes a value close to $\bar{u}_{max}$ (Fig. 4) and we obtain the estimates :

$$\left| \frac{\partial u_{oil}}{\partial z} \right| (r, z = \pm z_s) \sim \frac{\mu_w \bar{u}_{max}(r)}{\mu_{oil} r^*} \quad (7)$$

$$\left| \frac{\partial^2 u_{oil}}{\partial z^2} \right| = \left| \frac{\partial}{\partial z} \left(\frac{\partial u_{oil}}{\partial z} \right) \right| \sim \frac{1}{s} \left| \frac{\partial u_{oil}}{\partial z} \right| \sim \frac{\mu_w w_s}{\mu_{oil} s^2} \quad (8)$$

Taking into account the radial variations of u_{oil} (with length scale r^*), we deduce from (4) the following order of magnitude

Figure 4. Computed profile of the radial velocity component in oil and water at $r = (R_0 s)^{1/2}$ and $s = s_0/2$ in the reference case.

for the radial derivative of pressure in oil :

$$\left| \frac{\partial p}{\partial r} \right| \sim \mu_{oil} \frac{w_s}{R_0^{1/2} s^{3/2}} \left(1 + \alpha \frac{\mu_w}{\mu_{oil}} \sqrt{\frac{R_0}{s}} \right) \quad (9)$$

where α is a numerical constant. In practice, s/R_0 is not extremely small (except very close to contact). In the asymptotic case $(\mu_w/\mu_{oil})(R_0/s)^{1/2} \ll 1$, we obtain for the pressure difference $(\Delta p)_r$:

$$(\Delta p)_r = p(0,0) - p_\infty \sim \left| \frac{\partial p}{\partial r} \right| r^* \sim \mu \frac{w_s}{s} \quad (10)$$

Balancing $(\Delta p)_r$ with the maximum electrostatic pressure p_{e0} leads to an estimate for w_s . Taking Davis expression $p_{e0} = \epsilon_{r,oil} \epsilon_0 (E_3 E_0)^2 / 2$ [10] corresponding to maximum field at the droplets surface and a fitted power law $1.87 (R_0/s)^{0.85}$ for the variation of E_3 [6], leads to the expression (with a factor β) :

$$w_s \sim \frac{1.75}{\beta} \frac{\epsilon_0 \epsilon_{r,oil} E_0^2}{\mu_{oil}} \frac{R_0^{1.70}}{s^{0.70}} \quad (11)$$

The temporal evolution of the spacing s then is :

$$s(t) = s_0 \left[1 - \frac{2.975}{\beta} \frac{\epsilon_0 \epsilon_{r,oil} E_0^2}{\mu_{oil}} \left(\frac{R_0}{s_0} \right)^{1.7} t \right]^{1/1.7} \quad (12)$$

Fig. 5 shows that (12) very well accounts for the decrease of spacing obtained by simulation. The contact time is :

$$t_{contact} = \frac{\beta}{2.975} \frac{\mu_{oil}}{\epsilon_0 \epsilon_{r,oil} E_0^2} \left(\frac{s_0}{R_0} \right)^{1.7} = \frac{\beta}{1.7} \frac{\mu_{oil}}{p_{e0}} \quad (13)$$

V. RESULTS OF SIMULATION

As the primary interest of electrocoalescence is to resolve the water-in-oil emulsions, we considered water droplets of small size (tens of micrometers) with an initial spacing $s_0 \sim 1 \mu\text{m}$ and a polybutene oil (see [7]); the reference case is relative to $R_0 = 20 \mu\text{m}$, $s_0 = 1 \mu\text{m}$. A systematic study was conducted by varying the applied field. Firstly, simulations show that the small drops deformation is of very limited amplitude (Fig. 3) and very regular [6], thus supporting the hypothesis of §IV on non deformation of droplets.

Figure 5. Decrease of the spacing s versus time in the reference case ($R_0 = 20 \mu\text{m}$, $s_0 = 1 \mu\text{m}$) and $E_0 = 4 \text{ kV/cm}$.

The most striking result is that the contact time: $t_{contact}$ is inversely proportional to the initial maximum electrostatic pressure p_{e0} (Figs. 6-8). For a given p_{e0} , to a very good approximation, it takes the same value independently of the drops radius and of the initial spacing (Fig. 6).

Figure 6. Variations of the drainage time as a function of the initial maximum electrostatic pressure p_{e0} for even drops (for different R_0 and s_0 values). The full line corresponds to (13) with $\beta = 8$.

Figure 7. Variations of the drainage time for drops of different radii R_1 and R_2 . The full line corresponds to (13) with $\beta = 8$.

Figure 8. Variations of drainage time as a function of p_{e0} for even drops of radius R_0 illustrating the influence of interfacial tension γ and viscosity μ_{oil} . Full lines correspond to (13) with the three μ_{oil} values.

Figure 9. Variations of the normalized product of the electric Bond number Be_0 by the drainage time $t_{contact}$ as a function of Be_0 for even drops.

Moreover, with drops of different size, the contact time has a very weak dependence on the radii ratio (Fig. 7). This behaviour fairly well corresponds to the one predicted by (13). For small to moderate p_{e0} values (< 200 to 300 Pa), clearly $t_{contact}$ increases with viscosity but is independent of the interfacial tension (Fig. 8). For high initial electrostatic pressure, the contact time takes values lower than the one given by (13). In order to understand why this decrease occurs we plotted the product of contact time and electric Bond number Be_0 ($= p_{e0} R_0 / \gamma$), normalized by its value for low p_{e0} , as a function of Be_0 ; a universal curve is obtained (Fig. 9), which suggests that strong enough electrostatic pressure might interplay with capillary pressure and slightly elongate the drops, thus facilitating the oil drainage and reducing $t_{contact}$.

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