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A Millimeter-Wave Inflatable Frequency Agile Elastomeric Antenna

Sami Hage-Ali, Student Member, IEEE, Nicolas Tiercelin, Philippe Coquet, Ronan Sauleau, Senior Member, IEEE, Vladimir Preobrazhensky, and Philippe Pernod

Abstract—This letter reports a millimeter-wave frequency agile microstrip antenna printed on an ultrasoft elastomeric PDMS substrate. The microstrip patch antenna is supported by a PDMS membrane suspended over an air cavity. The distance $H$ between the patch and the ground plane, and thus the resonant frequency of the antenna, are tuned using pneumatic actuation, taking advantage of the extreme softness of the PDMS membrane. A continuous frequency shift varying from 55.35 to 51.3 GHz has been obtained for a tuning range of $H$ between 200µm and 575µm. In all configurations, the antenna remains matched and its radiation characteristics are very satisfactory.

Index Terms—Inflatable, Membrane, PDMS, Reconfigurable antennas, Tunable.

I. INTRODUCTION

Reconfigurable antennas are increasingly needed for high-speed wireless communications and high-resolution sensing systems at millimeter waves [1]. Recently, there has been a growing interest for frequency agile antennas due to their flexibility in wireless standards. Two main methods have been proposed to tune the resonant frequency of a microstrip patch antenna: mechanical reconfiguration systems and electrical reconfiguration systems [2]. Mechanical reconfiguration systems have been implemented to tune their resonant frequency. Electrical solutions based on varactors [3] and PIN diodes [4] have been reported. Many mechanical reconfiguration systems have been also proposed in the literature. In the early eighties, Lee et al. [5] introduced a manually-reconfigurable circular microstrip antenna with an air gap. Reconfigurable antennas using plastic deformation magnetic actuation [6] and tunable MEMS capacitors [7] were also reported. In [8], an electrostatically-actuated micromachined copper ground plane has been used to tune a microstrip antenna from 16.8 to 17.82 GHz (6%), and in [9] electrostatic actuation has been implemented to move a microstrip patch antenna fabricated on a flexible Kapton substrate, leading to a tunability of 2.1% (between 16.91 and 16.64 GHz). A similar topology on PET substrate has been recently discussed in [10] with a tunability of 3.6% at 10 GHz.

One of the key issues for elaborating mechanically reconfigurable antennas at millimeter waves consists in finding materials with suitable electromagnetic and mechanical properties. In this work, we use polydimethylsiloxane (PDMS) as an antenna substrate. PDMS is an extremely flexible polymer with very low Young’s modulus ($E_{\text{Young}}=2$ MPa) and is compatible with a number of silicon micromachining techniques. The feasibility and performance of PDMS-based millimeter-wave transmission lines and microstrip antenna arrays have been demonstrated in [11-13]. Recently PDMS has been used in the development of stretchable dipole antennas filled with liquid metal at 1.5 – 2 GHz [14, 15].

In this letter we describe a PDMS-based frequency-tunable microstrip antenna in the 50-60 GHz band. Pneumatic actuation is used to reconfigure a PDMS membrane supporting a patch antenna over an air-filled cavity of variable height, resulting in a frequency shift. First we briefly explain the principle of operation of a mechanically tunable antenna over an air cavity (Section II). The antenna design and fabrication process are then described in Section III. The impedance and radiation characteristics of the tunable antenna are presented in Section IV. Results and limitations are discussed in Section V. Conclusions and perspectives are given in Section VI.

II. BACKGROUND

The resonant frequency $F_{\text{res}}$ of a rectangular patch antenna can be approximated at first order using the transmission line model described in [16]

$$F_{\text{res}} = \frac{c}{2L_{\varepsilon}} \sqrt{\varepsilon_r}, \quad \text{with } L_{\varepsilon} = L + 2AL$$

where $c$ is the speed of light in vacuum, $L_{\varepsilon}$ the effective length of the antenna, $\varepsilon_r$ the effective dielectric constant, $L$ the physical length of the patch, and $AL$ the length of the fringing fields. When considering a microstrip antenna over an air cavity of tunable height (Fig. 1), the resonant frequency is influenced by two opposite effects: increasing the cavity height results in lowering the effective dielectric constant $\varepsilon_r$ (which induces an increase of the resonant frequency) and simultaneously in larger fringing fields $AL$ (which tends to decrease the resonant frequency). For small values of $H$, the first effect is predominant, whereas for larger values of the cavity height, the influence of $AL$ is more pronounced. These trends are depicted in Fig. 2.
Fig. 1. Geometry of a microstrip antenna suspended over an air cavity.

Fig. 2. General trend of the variation of resonant frequency of an antenna suspended over an air cavity of variable height.

III. DESIGN AND FABRICATION

The geometry of the membrane-supported antenna studied here is represented in Fig. 3a. A rectangular patch is supported by a 20-µm-thick PDMS membrane over an air-filled cavity. The patch is fed by a microstrip line, first printed on bulk PDMS, then onto the membrane. The dielectric properties of PDMS at millimeter waves are given in [11]: \( \varepsilon_r = 2.68 \) and \( \tan\delta = 0.04 \). A specific metal transfer process has been developed to fabricate membrane-supported PDMS antennas. The technological process, fully described in [13], enables one to overcome the difficulty of PDMS micrometer-thick metallization due to its high thermal expansion coefficient and low adhesion to metal. Thanks to the PDMS mechanical properties, the membrane is easily and strongly deformed by pneumatic actuation through holes in the ground plane. This allows controlling the height of the patch, and thus the resonant frequency of the antenna. The inflated prototype is shown Fig.3b. The designed structure and actuation scheme enable to overcome limitations for similar designs due to electrostatic actuation that has a limited displacement, and less deformable materials that require larger actuation forces [8-10].

IV. NUMERICAL AND EXPERIMENTAL RESULTS

A. Results in impedance

1) Experimental setup

The experimental setup in V-band is depicted in Fig. 4. The impedance measurements have been performed using an Anritsu Universal test fixture 3680V coupled to an Agilent E8361A network analyzer with TRL calibration. The antenna cavity is filled precisely with air using an electronic NE100 syringe pump. Experimentally, the value of \( H \) is varied between 90µm (deflated position) and 575µm (inflated position) with an inserted air volume of 55µl. This volume is compatible with integrated fluidic micropumps. The flat position corresponds to \( H = 200\mu m \). The lower value of \( H = 90 \mu m \) is determined by possible adhesion of the membrane on the ground plane. \( H \) has been measured using a Hirox microscope by focusing on the patch, then, using a high precision z-translation stage, focusing on the ground plane, and measuring the vertical displacement with a micron-scale precision. This setup allows measuring the impedance and cavity height simultaneously.

2) Resonant frequency

The variation of the antenna resonant frequency has been studied numerically using Ansoft HFSS (version 11.1) and experimentally with the proposed setup. The idealized HFSS configuration is shown in Fig. 5, and the numerical and experimental data are represented in Fig. 6. Measurements show that the resonant frequency increases from 53.9 GHz to 55.4 GHz for 90µm < \( H < 160 \mu m \) (this is due to the decrease...
of $\varepsilon_r$), then starts to decrease due to larger fringing field as explained in Section II.

![Image](image1.png)

**Fig. 5.** Numerical model for the antenna prototype.

![Image](image2.png)

**Fig. 6.** Resonant frequency of the antenna as a function of $H$. 

HFSS simulations  
Experimental data.

The main result is that the antenna is tuned from 55.35 GHz to 51 GHz for $H$ varying between 200 µm (nominal) and 575 µm. This corresponds to a relative agility of 8.2% for a 287% variation of $H$. A satisfactory agreement between numerical modelling and experimental results is obtained. The difference is attributed to the imperfect linearized simulated geometry described in Fig.5.

3) Reflection coefficient and bandwidth

The antenna reflection coefficients $S_{11}$ measured in the 50-60 GHz band for four positions of the membrane are given in Fig. 7, and the comparison between experiment and numerical results for the flat case is represented in Fig. 8. On each experimental $S_{11}$ curve, one can observe two peaks. The first one (~ 55.5 GHz for the flat case) corresponds to the actual resonance as demonstrated in Fig. 8. The second one (~ 58.5 GHz for the flat case) is attributed to a deformation of the feed line when contacted into the test fixture jaw and to reflections at the feed line discontinuity between bulk PDMS and membrane. The values of the resonance frequency, matching level, and -15 dB bandwidth (BW) are summarized in Table 1.

![Image](image3.png)

**Fig. 7.** Measured reflection coefficients.

HFSS experiment. 

$H$=90 µm  
$H$=200 µm (flat)  
$H$=450 µm  
$H$=575 µm.

![Image](image4.png)

**Fig. 8.** Measured and computed reflection coefficients for the flat antenna ($H$=200 µm).

B. Measurements in radiation

The radiation patterns and gain for the $H$=200µm (nominal) and $H$=575µm (inflated) configurations have been measured in a far-field millimeter-wave anechoic chamber using a V-type connector and a WR-15 waveguide-to-coaxial transition covered with absorbers. The antenna is inflated using a 1-ml syringe. The radiation patterns are represented in Figs. 9 and 10, respectively.

![Image](image5.png)

**Fig. 9.** Measured radiation patterns of the flat antenna (around $H$=200µm) at 55 GHz. (a) H-plane, (b) E-plane. – Co-polarization component. – Cross-polarization component.

![Image](image6.png)

**Fig. 10.** Measured and computed radiation patterns for the flat antenna ($H$=200 µm).

In all cases, the reflection coefficient at resonance remains lower than -17 dB. The -15 dB bandwidth is larger than 4.8 GHz for inflated cases. The impedance matching tends to decrease for extreme positions.

![Image](image7.png)

**TABLE I: MEASURED IMPEDANCE ANTENNA CHARACTERISTICS FOR VARIOUS CAVITY HEIGHTS**

<table>
<thead>
<tr>
<th>$H$ (µm)</th>
<th>$F_{res}$ (GHz)</th>
<th>$S_{11}$ at resonance (dB)</th>
<th>-15 dB BW (GHz)</th>
</tr>
</thead>
<tbody>
<tr>
<td>90</td>
<td>53.9</td>
<td>-17.4</td>
<td>0.8</td>
</tr>
<tr>
<td>200</td>
<td>55.35</td>
<td>-37.5</td>
<td>4.8</td>
</tr>
<tr>
<td>450</td>
<td>51.7</td>
<td>-59.2</td>
<td>4.9</td>
</tr>
<tr>
<td>575</td>
<td>51.0</td>
<td>-21.0</td>
<td>&gt;4.8</td>
</tr>
</tbody>
</table>
The pronounced ripples observed in E-plane are due to reflection and diffraction effects on the V-type feed connector. For the flat case, the theoretical directivity and measured gain equal 9.45 dBi and 5.0 dBi, respectively, which corresponds to a 36% radiation efficiency. For the inflated position, the theoretical directivity is 8.65 dBi, the measured gain is 4.5 dBi and the corresponding efficiency is η=39%. Thus, there is no significant change of the antenna radiation for inflated positions. The relatively low radiation efficiency can be explained by the 1-cm long feed line part printed on bulk PDMS (Figs 3a and 3b, [13]) where about 2.5 dB losses occur.

V. DISCUSSION

In this work, within the considered height variation, the membrane deformation is far from the 160% elongation failure of PDMS. The height variation could be increased, and therefore the frequency agility, but at the expense of the impedance performance. For severe deformations, metal patterns are more likely to fail. This problem can be avoided using liquid metal [14, 15] (but with higher metallic losses) or metal patterns (especially the flexion at the bulk PDMS to membrane transition) have to be carried out to determine the long term system reliability.

In this letter, only quasi-static reconfiguration using a syringe pump is demonstrated. Tuning speed and integration can be addressed by implementing actuators with higher dynamics. Reconfiguration speed of 50-100 ms can be expected. To better control the height and thus the resonant frequency of the antenna, piezoresistive gauges with feedback on the actuators can be integrated.

VI. CONCLUSION

We demonstrated the frequency tuning of microstrip antennas printed on ultra flexible PDMS membranes using pneumatic actuation. Mechanical reconfiguration enables avoiding the use of active devices that may face cost, losses and complexity issues at millimeter waves. The antenna tunability reaches 8.2% between 55.35 GHz and 51 GHz for a 287% variation of the patch height between $H=200$µm and $H=575$µm, which is beyond the state of the art for mechanically tuned antennas in this frequency range. Bandwidth, radiation patterns and gain remain fully acceptable within the displacement range. This result using a very low cost technology is very promising at millimeter-waves, and may be extended to even higher frequencies without significant change. Future works include implementation of integrated actuators and structural control elements on the antenna [17].

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REFERENCES