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Analytical Computation of the Magnetic Field Distribution in a Magnetic Gear

Thierry Lubin, Smail Mezani, and Abderrazak Rezzoug.

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In this paper, an analytical computation of the magnetic field distribution in a magnetic gear is proposed. The analytical method is based on the resolution of Laplace’s and Poisson’s equations (by the separation of variables technique) for each sub-domain, i.e. magnets, air-gap and slots. The global solution is obtained using boundary and continuity conditions. The analytical model developed in this paper can be used as a tool for design optimization of a magnetic gear. Magnetic field distributions and electromagnetic torque computed with the proposed analytical method are compared with those obtained from finite element analyses.

Index Terms— Analytical solution, magnetic gear, magnetic field, electromagnetic torque.

I. INTRODUCTION

Magnetic gears offer substantial advantages compared to mechanical gears such as reduced maintenance, improved reliability, minimum acoustic noise and inherent overload protection. Physical and hermetic isolation between input and output shafts are also specific to such contactless torque transmission devices [1]-[5]. It has been shown that a transmitted torque density of 100 kNm/m³ can be obtained which is comparable with that of mechanical gears. Recently, magnetic gear has been integrated into PM motors to obtain the so called “pseudo-direct” drives that result in high-torque density electrical machines [6]. The later actuators are suitable for high torque low speed application like electric vehicles [7] or wind power generation [8].

An accurate knowledge of the air-gap magnetic field distribution is necessary for predicting the performance of the magnetic gear. The air-gap magnetic field can be evaluated by analytical or semi-analytical methods or by numerical techniques like finite elements. Finite elements give accurate results considering geometric details and nonlinearity of magnetic materials. However, this method is computer time consuming and poorly flexible for the first step of design stage of a magnetic gear. Analytical methods are useful tools for first evaluation of magnetic gear performances and for design optimization since continuous derivatives issued from the analytical solution are of great importance in most optimization methods.

As shown in Fig. 1, a magnetic gear contains a ring of \( Q \) ferromagnetic pole-pieces which are difficult to handle (open slots on two sides) in the analytical prediction of the air-gap magnetic field. Analytical approaches for air-gap magnetic field computation in slotted machines can be found in the literature [9]-[14]. However, the publications focus essentially on the determination of cogging torque in permanent magnet motors.

The aim of this paper is to propose an exact analytical solution of the magnetic field distribution in a magnetic gear. The Laplace and Poisson’s equations are solved in each sub-domain (air-gap, magnet and slots) and the solution is obtained using boundary and interface conditions.

The paper is organized as follows. The problem description and the assumptions of the model are presented in section II. Section III describes the analytical method for magnetic field calculation in the air-gap, permanent magnets and in the slot sub-domains. The analytical results are then verified with finite-element method in section IV and section V.

II. PROBLEM DESCRIPTION AND ASSUMPTIONS

Schematic representation of the studied magnetic gear is shown in Fig. 1. It consists of a \( p_i \) pole-pairs inner rotor, a \( p_o \) pole-pairs outer rotor and \( Q \) ferromagnetic pole-pieces.

Principle of operation of the magnetic gear is the modulation of magnetic field created by the \( p_i \) pole-pairs PMs rotor (prime mover) by the \( Q \) pole pieces. The obtained field interacts with the \( p_o \) pole-pairs PMs rotor to transmit torque to the load (outer rotor or pole pieces) at a different speed. The combination \( Q=p_i+p_o \) results in the highest torque transmission capability of the gear. If the pole pieces are kept stationary, the resulting gear ratio is \( p_o/p_i \) [1].

The geometrical parameters are:
- for the inner rotor, the radius of the yoke \( R_i \) and the outer radius of the PMs \( R_i^{\prime} \);
- for the ring, the inner and outer radii of the slots \( R_s, R_d \) respectively;
- and for the outer rotor, the inner radius of PMs \( R_o \) and the inner radius of the yoke \( R_o^{\prime} \).

The slot opening angle is \( \beta \). The angular position of the \( i \)-th slot is defined as

\[
\theta_i = -\frac{\beta}{2} + \frac{2i\pi}{Q} + \theta_0 \quad \text{with} \quad 1 \leq i \leq Q
\]

where \( \theta_0 \) is the initial angular position of the pole-pieces ring.
The following assumptions are adopted:

- End effects are neglected.
- The permeability of the iron is infinite (the magnetic field in the iron vanishes).
- The relative recoil permeability of the magnets is $\mu_r = 1$.

As shown in Fig. 1, the whole domain is divided into five sub-domains: the inner and outer air-gap sub-domains (regions II and III), the inner and outer PMs sub-domains (regions I and IV) and the $Q$ slots sub-domains (regions i). The i-th slot sub-domain shape is shown in Fig. 2. The sub-domains I, II, III and IV have annular shapes.

A magnetic vector potential formulation is used in 2D polar coordinates to describe the problem. According to the adopted assumptions, the magnetic vector potential has only one component along the $z$-direction and only depends on the $r$ and $\theta$ coordinates. The notations used in the paper are

- $A_I = A_I(r, \theta) \cdot e_z$ for the inner PMs sub-domain
- $A_{II} = A_{II}(r, \theta) \cdot e_z$ for the inner air-gap sub-domain
- $A_i = A_i(r, \theta) \cdot e_z$ for the i-th slot sub-domain
- $A_{III} = A_{III}(r, \theta) \cdot e_z$ for the outer air-gap sub-domain
- $A_{IV} = A_{IV}(r, \theta) \cdot e_z$ for the outer PMs sub-domain

III. ANALYTICAL MODEL

The solution of any partial differential equation (PDE) depends on the domain in which the solution is to be valid as well as the boundary conditions that the solution must satisfy. By using separation of variables, we now consider the solution of Laplace’s equation for the slots and the air-gap sub-domains and the Poisson’s equation for the PMs sub-domains. For the sake of clarity and simplicity of the general solutions in the different sub-domains, we adopt the following notations

$$P_w(u, v) = \left( \frac{u}{v} \right)^w + \left( \frac{v}{u} \right)^w$$

$$E_w(u, v) = \left( \frac{u}{v} \right)^w - \left( \frac{v}{u} \right)^w$$

A. General Solution of Laplace’s equation in the i-th slot sub-domain (region i)

The $i$-th slot sub-domain and the associated boundary conditions are shown in Fig. 2. We have to solve the Laplace’s equation in a domain of inner radius $R_3$ and outer radius $R_4$ delimited by the angles $\theta_i$ and $\theta_i + \beta$

$$\frac{\partial^2 A_i}{\partial r^2} + \frac{1}{r} \frac{\partial A_i}{\partial r} + \frac{1}{r^2} \frac{\partial^2 A_i}{\partial \theta^2} = 0 \quad \text{for} \quad \begin{cases} R_3 \leq r \leq R_4 \\ \theta_i \leq \theta \leq \theta_i + \beta \end{cases}$$

The boundary conditions for the $i$-th slot domain are (the tangential component of the magnetic field at the sides of the slot are null)

$$\frac{\partial A_i}{\partial \theta} \bigg|_{\theta = \theta_i} = 0 \quad \text{and} \quad \frac{\partial A_i}{\partial \theta} \bigg|_{\theta = \theta_i + \beta} = 0$$

The continuity of the normal component of the flux density between the $i$-th slot and the air-gap sub-domains leads to

$$A_i(R_3, \theta) = A_{II}(R_3, \theta)$$

$$A_i(R_4, \theta) = A_{III}(R_4, \theta)$$

The general solution of (4) can be found by using the method of the separation of variables, the solution can be written as [14]
\[ A_i(r, \theta) = A'_i + B'_i \ln r \]
\[ + \sum_{k=1}^{\infty} \left( A'_{ki} r^{-\frac{k\pi}{\beta}} + B'_{ki} r^{-\frac{k\pi}{\beta}} \right) \cdot \cos \left( \frac{k\pi}{\beta} (\theta - \theta_i) \right) \]

where \( A'_i, B'_i, A'_k \) and \( B'_k \) are arbitrary constants.

Considering the continuity conditions (6) and (7), the general solution of the magnetic vector potential in the \( i \)-th slot domain is rewritten as

\[ A_i(r, \theta) = A'_i + B'_i \ln r \]
\[ + \sum_{k=1}^{\infty} \left( A'_{ki} r^{-\frac{k\pi}{\beta}} + B'_{ki} r^{-\frac{k\pi}{\beta}} \right) \cdot \cos \left( \frac{k\pi}{\beta} (\theta - \theta_i) \right) \]

The constants \( A'_0, B'_0, A'_k \) and \( B'_k \) are determined using a Fourier series expansion of the inner and outer air-gap magnetic vector potentials \( A_{II}(R_3, \theta) \) and \( A_{II}(R_4, \theta) \) over the slot interval \([ \theta, \theta + \beta ]\).

The expressions for the coefficients \( A'_0, B'_0, A'_k \) and \( B'_k \) are given in the appendix.

**B. General solution of Laplace’s equation in the air-gap sub-domains**

1) **Inner air-gap sub-domain (region II)**

The inner air-gap sub-domain and the associated boundary conditions are shown in Fig. 3. The problem to solve is

\[ \frac{\partial^2 A_{II}}{\partial r^2} + \frac{1}{r} \frac{\partial A_{II}}{\partial r} + \frac{1}{r^2} \frac{\partial^2 A_{II}}{\partial \theta^2} = 0 \quad \text{for} \quad \left\{ \begin{array}{l} R_2 \leq r \leq R_3 \\ 0 \leq \theta \leq 2\pi \end{array} \right. \]
where \( n \) is a positive integer, \( P_n(r, R_3) \) and \( E_n(R_3, R_2) \) are defined by (2) and (3). The coefficients \( A_n^H, B_n^H, C_n^H \) and \( D_n^H \) are determined using a Fourier series expansions of \( \frac{\partial A_n^H}{\partial r} \) and \( f(\theta) \) over the air-gap interval [0, 2\( \pi \)]

\[
A_n^H(r, \theta) = A_n^{H0} + \sum_{n=1}^{\infty} \left( A_n^H \frac{R_2}{n} \frac{P_n(r, R_3)}{E_n(R_2, R_3)} + B_n^H \frac{R_3}{n} \frac{P_n(r, R_3)}{E_n(R_3, R_2)} \right) \cos(n \theta) \\
+ \sum_{n=1}^{\infty} \left( C_n^H \frac{R_2}{n} \frac{P_n(r, R_3)}{E_n(R_2, R_3)} + D_n^H \frac{R_3}{n} \frac{P_n(r, R_3)}{E_n(R_3, R_2)} \right) \sin(n \theta)
\]

The radial and the tangential components of the magnetic flux in the inner air-gap are then

\[
B_{II}(r, \theta) = \sum_{n=1}^{\infty} \left( A_n^H \frac{R_2}{r} \frac{P_n(r, R_3)}{E_n(R_2, R_3)} + B_n^H \frac{R_3}{r} \frac{P_n(r, R_3)}{E_n(R_3, R_2)} \right) \sin(n \theta) \\
+ \sum_{n=1}^{\infty} \left( C_n^H \frac{R_2}{r} \frac{P_n(r, R_3)}{E_n(R_2, R_3)} + D_n^H \frac{R_3}{r} \frac{P_n(r, R_3)}{E_n(R_3, R_2)} \right) \cos(n \theta)
\]

\[
B_{II0}(r, \theta) = \sum_{n=1}^{\infty} \left( A_n^H \frac{R_2}{r} \frac{E_n(r, R_3)}{E_n(R_2, R_3)} + B_n^H \frac{R_3}{r} \frac{E_n(r, R_3)}{E_n(R_3, R_2)} \right) \cos(n \theta) \\
+ \sum_{n=1}^{\infty} \left( C_n^H \frac{R_2}{r} \frac{E_n(r, R_3)}{E_n(R_2, R_3)} + D_n^H \frac{R_3}{r} \frac{E_n(r, R_3)}{E_n(R_3, R_2)} \right) \sin(n \theta)
\]

2) Outer air-gap sub-domain (region III)

The outer air-gap sub-domain and the associated boundary conditions are shown in Fig. 5. The problem to solve is

\[
\frac{\partial^2 A_{III}}{\partial r^2} + \frac{1}{r} \frac{\partial A_{III}}{\partial r} + \frac{1}{r^2} \frac{\partial^2 A_{III}}{\partial \theta^2} = 0 \quad \text{for} \quad R_4 \leq r \leq R_5, 0 \leq \theta \leq 2\pi
\]

The boundary condition for the outer air-gap domain at \( r = R_5 \) is

\[
\left. \frac{\partial A_{III}}{\partial r} \right|_{r=R_5} = g(\theta)
\]

The radial and the tangential components of the magnetic flux in the inner air-gap are then
Fig. 5. Outer air-gap sub-domain (region III) with its boundary conditions.

\[
\begin{align*}
&\frac{\partial A_{\text{III}}}{\partial r} = 0 \\
&\frac{\partial A_{\text{III}}}{\partial r} = \pi(\theta)
\end{align*}
\]

By taking into account the boundary conditions (30) and (31), the general solution of the magnetic vector potential in the outer air-gap sub-domain can be written as

\[
\begin{align*}
A_{\text{III}}(r, \theta) &= A_{0}\text{III} \\
&+ \sum_{n=1}^{\infty} (A_{n}\text{III} \frac{R_1}{n} P_n(r, R_1) + B_{n}\text{III} \frac{R_1}{n} P_n(r, R_1)) \cos(n\theta) \\
&+ \sum_{n=1}^{\infty} (C_{n}\text{III} \frac{R_1}{n} P_n(r, R_1) + D_{n}\text{III} \frac{R_1}{n} P_n(r, R_1)) \sin(n\theta)
\end{align*}
\]

(33)

where \( n \) is a positive integer, \( P_n(r, R_1) \) and \( E_n(R_1, R_2) \) are defined by (2) and (3). The coefficients \( A_{n}\text{III}, B_{n}\text{III}, C_{n}\text{III} \) and \( D_{n}\text{III} \) are determined using a Fourier series expansions of \( \frac{\partial A_{\text{IV}}}{\partial r} \) and \( g(\theta) \) over the air-gap interval \([0, 2\pi]\)

\[
\begin{align*}
A_{n}\text{III} &= \frac{2}{2\pi} \int_{0}^{2\pi} g(\theta) \cdot \cos(n\theta) \cdot d\theta \\
B_{n}\text{III} &= \frac{2}{2\pi} \int_{0}^{2\pi} \frac{\partial A_{\text{IV}}}{\partial r} \bigg|_{r=R_5} \cdot \cos(n\theta) \cdot d\theta
\end{align*}
\]

(34)  (35)

The expressions for the coefficients \( A_{n}\text{III}, B_{n}\text{III}, C_{n}\text{III} \) and \( D_{n}\text{III} \) are given in the appendix.

C. General solution of Poisson’s equation in the PMs sub-domains (regions I and IV)

1) Inner rotor PMs sub-domain (region I)

The inner rotor PMs sub-domain and the associated boundary conditions are shown in Fig. 6. The problem to solve is

\[
\frac{\partial^2 A_{\text{I}}}{\partial r^2} + \frac{1}{r} \frac{\partial A_{\text{I}}}{\partial r} + \frac{1}{r^2} \frac{\partial^2 A_{\text{I}}}{\partial \theta^2} = \mu_0 \frac{\partial M_r}{\partial \theta} \text{ for } R_1 \leq r \leq R_2 \quad 0 \leq \theta \leq 2\pi
\]

(38)

where \( \mu_0 \) is the permeability of the vacuum and \( M_r \) is the radial magnetization of the magnets.

The boundary conditions at \( r = R_1 \) and \( r = R_2 \) are respectively

\[
\left. \frac{\partial A_{\text{I}}}{\partial r} \right|_{r=R_1} = 0
\]

(39)

\[
A_{\text{I}}(R_2, \theta) = A_{\text{II}}(R_2, \theta)
\]

(40)

Fig. 6. Inner PMs sub-domain (region I) with its boundary conditions.
The radial magnetization distribution $M_r$ is plotted in Fig. 7, where $B_r$ is the remanence of the magnets and $\phi_0$ is the initial phase angle of the inner rotor. The radial magnetization can be expressed in Fourier’s series and replaced in (38).

According to the superposition law, the general solution of (38) is the sum of the general solution of the corresponding Laplace’s equation and a particular solution [15]. Taking into account the boundary conditions (39) and (40), the general solution of the magnetic vector potential in the inner PMs sub-domain can be written as

\[
A_I(r, \theta) = \sum_{n=1}^{\infty} \left( A_n^I \frac{P_n(r, R_1)}{P_n(R_2, R_1)} + X_n(r) \cos(n\phi) \right) \cos(n\theta) \\
+ \sum_{n=1}^{\infty} \left( C_n^I \frac{P_n(r, R_1)}{P_n(R_2, R_1)} + X_n(r) \sin(n\phi) \right) \sin(n\theta)
\]

where

\[
X_n(r) = \left( 1 + \frac{1}{n} \left( \frac{R_1}{r} \right)^{n+1} \right) f_n(r)
\]

\[
f_n(r) = \begin{cases} 
\frac{4B_r r p_i}{\pi(1-n^2)} & \text{if } n = j p_i \text{ with } j = 1, 3, 5, \ldots \\
\frac{2B_r r \ln r}{\pi} & \text{if } n = p_i = 1 \\
0 & \text{otherwise}
\end{cases}
\]

and

\[
A_n^I = \frac{2}{2\pi} \int_0^{2\pi} A_I(R_2, \theta) \cdot \cos(n\theta) \, d\theta
\]

\[
C_n^I = \frac{2}{2\pi} \int_0^{2\pi} A_I(R_2, \theta) \cdot \sin(n\theta) \, d\theta
\]

The expressions for the coefficients $A_n^I$ and $C_n^I$ are given in the appendix.

2) Outer PMs sub-domain (region IV)

The outer PMs sub-domain and the associated boundary conditions are shown in Fig. 8. The problem to solve is

\[
\frac{\partial^2 A_{IV}}{\partial r^2} + \frac{1}{r} \frac{\partial A_{IV}}{\partial r} + \frac{1}{r^2} \frac{\partial^2 A_{IV}}{\partial \theta^2} = \frac{\mu_0}{r} \frac{\partial M_r}{\partial \theta} \text{ for } R_5 \leq r \leq R_6, 0 \leq \theta < 2\pi
\]

The boundary conditions at $r = R_4$ and $r = R_6$ are respectively

\[
A_{IV}(R_4, \theta) = A_{III}(R_4, \theta)
\]

\[
\frac{\partial A_{IV}}{\partial r} \bigg|_{r=R_6} = 0
\]

By taking into account the boundary conditions (47) and (48), the general solution of the magnetic vector potential in the outer PMs sub-domain can be written as

\[
A_{IV}(r, \theta) = \sum_{n=1}^{\infty} \left( A_n^{IV} \frac{P_n(r, R_6)}{P_n(R_5, R_6)} + Y_n(r) \cos(n\phi) \right) \cos(n\theta)
\]

\[
+ \sum_{n=1}^{\infty} \left( C_n^{IV} \frac{P_n(r, R_6)}{P_n(R_5, R_6)} + Y_n(r) \sin(n\phi) \right) \sin(n\theta)
\]

where

\[
Y_n(r) = \left( 1 + \frac{1}{n} \left( \frac{R_6}{r} \right)^{n+1} \right) g_n(r)
\]

\[
g_n(r) = \begin{cases} 
\frac{4B_r r p_o}{\pi(1-n^2)} & \text{if } n = j p_o \text{ with } j = 1, 3, 5, \ldots \\
\frac{2B_r r \ln r}{\pi} & \text{if } n = p_o = 1 \\
0 & \text{otherwise}
\end{cases}
\]
where \( n \) is a positive integer, \( p_o \) is the number of pole-pairs of the outer rotor, \( \phi_o \) is the initial phase angle of the outer rotor and \( P_n(r, R_o) \) is defined by (2). The coefficients \( A_n^{IV} \) and \( C_n^{IV} \) are determined using a Fourier series expansion of \( A_{HII}(R_o, \theta) \) over the interval \([0, 2\pi]\)

\[
A_n^{IV} = \frac{2}{2\pi} \int_0^{2\pi} A_{HII}(R_o, \theta) \cdot \cos(n\theta) \cdot d\theta
\]

\[
C_n^{IV} = \frac{2}{2\pi} \int_0^{2\pi} A_{HII}(R_o, \theta) \cdot \sin(n\theta) \cdot d\theta
\]

The expressions for the coefficients \( A_n^{IV} \) and \( C_n^{IV} \) are given in the appendix.

D. Electromagnetic torque

The electromagnetic torque is obtained using the Maxwell stress tensor. A circle of radius \( R_e \) in the inner air-gap sub-domain is taken as the integration path so the electromagnetic torque is expressed as follows

\[
T_e = \frac{LR_e^2}{\mu_0} \int_0^{2\pi} B_{HII}(R_e, \theta) \cdot B_{HII}(R_e, \theta) \cdot d\theta
\]

where \( L \) is the axial length of the magnetic gear. According to (27) and (28), the analytical expression for the electromagnetic torque becomes

\[
T_e = \frac{nLR_e^2}{\mu_0} \sum_{n=1}^{\infty} (W_n X_n + Y_n Z_n)
\]

where

\[
W_n = -A_n^{II} \frac{R_2^2}{R_e} \frac{P_n(R_e, R_3)}{E_n(R_e, R_3)} - B_n^{II} \frac{R_3}{R_e} \frac{P_n(R_e, R_3)}{E_n(R_e, R_3)}
\]

\[
X_n = -C_n^{II} \frac{R_2^2}{R_e} \frac{E_n(R_e, R_3)}{E_n(R_e, R_3)} - D_n^{II} \frac{R_3}{R_e} \frac{E_n(R_e, R_3)}{E_n(R_e, R_3)}
\]

\[
Y_n = C_n^{II} \frac{R_2^2}{R_e} \frac{P_n(R_e, R_3)}{E_n(R_e, R_3)} + D_n^{II} \frac{R_3}{R_e} \frac{P_n(R_e, R_3)}{E_n(R_e, R_3)}
\]

\[
Z_n = -A_n^{II} \frac{R_2^2}{R_e} \frac{E_n(R_e, R_3)}{E_n(R_e, R_3)} - B_n^{II} \frac{R_3}{R_e} \frac{E_n(R_e, R_3)}{E_n(R_e, R_3)}
\]

A similar expression can be obtained for the electromagnetic torque computation in the outer air-gap.

IV. APPLICATION EXAMPLE 1

In order to validate the proposed model, the analytical results have been compared with 2D finite element simulations obtained using FEMM software [16]. In the finite-element analysis, the surfaces of the inner and outer rotors yokes as well as those of the ferromagnetic pole-pieces have been modeled by homogeneous Neumann boundary conditions as in the analytical study. The mesh in the air-gap and in the slot regions has been refined until convergent results are obtained.

The geometrical parameters given in Table I are considered in the simulation studies. The analytical solutions in the air-gap, in the PMs and in the slots domains have been computed with a finite number of harmonic terms \( N \) and \( K \) as indicated in Table I.

A. Flux density distribution

Figure 9 shows the magnetic flux lines for the magnetic gear excited by both permanent magnet rotors. The phase angles \( \phi_i \) and \( \phi_o \) of the rotors PMs are fixed to zero. The corresponding flux density distributions (radial and tangential components) in the middle of the inner air-gap (\( r = 5.1 \) cm) and in the middle of the outer air-gap (\( r = 6.3 \) cm) are plotted respectively in Fig. 10 and Fig. 11. One can observe a very good agreement between the analytical and finite element predictions for both radial and tangential components.

<table>
<thead>
<tr>
<th>Symbol</th>
<th>Quantity</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>( R_1 )</td>
<td>Radius of the inner rotor yoke</td>
<td>4 cm</td>
</tr>
<tr>
<td>( R_2 )</td>
<td>Outer radius of the inner rotor PMs</td>
<td>5 cm</td>
</tr>
<tr>
<td>( R_3 )</td>
<td>Inner radius of the slots</td>
<td>5.2 cm</td>
</tr>
<tr>
<td>( R_4 )</td>
<td>Outer radius of the slots</td>
<td>6.2 cm</td>
</tr>
<tr>
<td>( R_5 )</td>
<td>Inner radius of the outer rotor PMs</td>
<td>6.4 cm</td>
</tr>
<tr>
<td>( R_6 )</td>
<td>Inner radius of the outer rotor yoke</td>
<td>7.4 cm</td>
</tr>
<tr>
<td>( L )</td>
<td>Axial length</td>
<td>10 cm</td>
</tr>
<tr>
<td>( \beta )</td>
<td>Slot opening</td>
<td>10 ( \pi )/rad</td>
</tr>
<tr>
<td>( B_r )</td>
<td>Remanence of the magnets</td>
<td>1.2 T</td>
</tr>
<tr>
<td>( p_i )</td>
<td>Pole-pairs inner rotor</td>
<td>2</td>
</tr>
<tr>
<td>( p_o )</td>
<td>Pole-pairs outer rotor</td>
<td>3</td>
</tr>
<tr>
<td>( Q )</td>
<td>Number of ferromagnetic pole-pieces</td>
<td>5</td>
</tr>
<tr>
<td>( N )</td>
<td>Number of harmonics used for magnetic field calculation in the air-gap and PMs domains</td>
<td>50</td>
</tr>
<tr>
<td>( K )</td>
<td>Number of harmonics used for magnetic field calculation in the slot domains</td>
<td>50</td>
</tr>
</tbody>
</table>
B. Torque

Figure 12 shows the variation of the torque which is exerted on the inner rotor while keeping the pole-pieces ring and the outer rotor fixed. The inner rotor rotates with a phase angle $\varphi_i$ varying from 0° to 90°. The analytical results are in good agreement with those obtained by the FEM. Fig. 12 shows that a maximum torque of 75 Nm is obtained for a value of $\varphi_i$ around 51°.

Figures 13(a) and 13(b) show the variation of the electromagnetic torque which is exerted respectively on the inner and outer rotors. The pole-pieces ring is fixed while the inner and outer rotors PMs rotate in opposite direction as

$$\varphi_o = -\varphi_i \cdot \frac{P_i}{p_o} \quad (57)$$

The starting point for the phase angle of the inner rotor PMs is fixed at $\varphi_i = 40^\circ$ that corresponds to a torque value exerted on the inner rotor of 61 Nm (see Fig. 12). From Figs. 13(a) and 13(b), one can observe as expected that the magnetic gear amplifies the mean torque value by the gear ratio of 3/2.
As shown in Figs. 13, the torque ripples are important in the studied example. Indeed, the low order harmonics are present in the flux density waveform of both air-gaps. This results in a low filtering of the air-gaps which leads to high pulsating torques. This effect can obviously be avoided by properly choosing \( p_a \) and \( Q \) for a given gear ratio [1]. Once again, very good agreement is obtained between numerical and analytical results.

![Fig. 12. Torque exerted on the inner rotor with the pole-pieces ring and the outer rotor fixed (\( \phi = 0 \) and \( \theta_0 = 0 \)).](image)

![Fig. 13. Electromagnetic torque exerted on the inner rotor (a), and on the outer rotor (b).](image)

V. APPLICATION EXAMPLE 2

Another example is considered in this section. The same geometrical parameters as in Table I are used except for the pole-pair numbers which are now \( p_i = 3, \ p_o = 13, \ Q = 16 \) which leads to a gear ratio equal to 4.33.

The magnetic flux lines distribution for this configuration are shown in Fig. 14 (the slot opening is fixed to \( \beta = \pi/16 \)). The radial and tangential flux densities on a circle of the inner and outer air gaps are given in Fig. 15 and Fig. 16. A good agreement is noticed between the analytical and the numerical computations.

Figure 17 shows the static torque vs. position of the inner rotor. Compared to the configuration given in the first design example, the maximum torque is lower. However, the transmitted torque on the outer rotor is more important for the second example. Indeed, the gear ratio is more important for this configuration (4.33 instead of 1.5).

Furthermore, the torque ripples are practically inexistent for example 2 as it can be observed in Fig. 18. This confirms the influence of the pole-pairs combination on the torque pulsations [1].

To show the influence of the slot opening, Fig. 19 gives the variation of the electromagnetic torque exerted on the inner rotor against the “slot opening to tooth pitch” ratio. One can observe that the maximum torque is obtained for a ratio of 0.5.

Again, we notice a close agreement between the analytical and numerical simulations.

![Fig. 14. Magnetic flux line distribution for the magnetic gear excited by both PMs rotors (\( \phi = 0^\circ, \ \phi_o = 0^\circ \) and \( \theta_0 = 0^\circ \)).](image)
Fig. 15. Flux density distribution in the middle of the inner air-gap ($r = 5.1$ cm): (a) radial component (b) tangential component.

Fig. 16. Flux density distribution in the middle of the outer air-gap ($r = 6.3$ cm): (a) radial component (b) tangential component.

VI. CONCLUSION

In this paper, an exact 2-dimensional analytical method for predicting the magnetic field distribution in a magnetic gear has been presented. The Laplace’s and Poisson’s equations in polar coordinates have been solved by the technique of separation of variables in the slots, air-gap and PMs sub-domains. The solutions have been obtained using boundary and continuity conditions between the sub-domains. Flux density and torque computations are in close agreement with those of FE predictions. The proposed analytical model presents lower computational time than FEM. Hence, it will be used in future work as a tool for design optimization of a magnetic gear.
Fig. 18. Electromagnetic torque exerted on the inner rotor (a), and on the outer rotor (b).

Fig. 19. Maximal torque on the inner rotor vs. “slot opening to tooth pitch” ratio.

APPENDIX

For the determination of the integration coefficients, we have to calculate integrals of the form

\[ f(k,n,i) = \int_{\theta_i}^{\theta_{i+\beta}} \cos(n\theta) \cdot \cos\left(\frac{k\pi}{\beta}(\theta - \theta_i)\right) \cdot d\theta \]  
(A.1)

\[ g(k,n,i) = \int_{\theta_i}^{\theta_{i+\beta}} \sin(n\theta) \cdot \cos\left(\frac{k\pi}{\beta}(\theta - \theta_i)\right) \cdot d\theta \]  
(A.2)

\[ r(n,i) = \int_{\theta_i}^{\theta_{i+\beta}} \cos(n\theta) \cdot d\theta \]  
(A.3)

\[ s(n,i) = \int_{\theta_i}^{\theta_{i+\beta}} \sin(n\theta) \cdot d\theta \]  
(A.4)

The development of (A.1) and (A.2) gives the following functions that will be used in the expressions of the integration coefficients

- for \( k\pi \neq n\beta \)

\[ f(k,n,i) = \frac{-n\beta^2}{k^2\pi^2 - n^2\beta^2} \left[ (-1)^k \sin(n(\beta + \theta_i)) - \sin(n\theta_i) \right] \]  
(A.5)

\[ g(k,n,i) = \frac{n\beta^2}{k^2\pi^2 - n^2\beta^2} \left[ (-1)^k \cos(n(\beta + \theta_i)) - \cos(n\theta_i) \right] \]  
(A.6)

- for \( k\pi = n\beta \)

\[ f(k,n,i) = \frac{\beta}{2} \left( \cos(n\theta_i) + \frac{1}{2k\pi} \left( \sin(n(\theta_i + 2\beta)) - \sin(n\theta_i) \right) \right) \]  
(A.7)

\[ g(k,n,i) = \frac{\beta}{2} \left( \sin(n\theta_i) - \frac{1}{2k\pi} \left( \cos(n(\theta_i + 2\beta)) - \cos(n\theta_i) \right) \right) \]  
(A.8)

The development of (A.3) and (A.4) gives the following functions

\[ r(n,i) = \frac{1}{n} \left( \sin(n\theta_i + n\beta) - \sin(n\theta_i) \right) \]  
(A.9)

\[ s(n,i) = \frac{1}{n} \left( - \cos(n\theta_i + n\beta) + \cos(n\theta_i) \right) \]  
(A.10)

- Expressions of the coefficients \( A_n^H \), \( B_n^{\Pi} \), \( C_n^H \) and \( D_n^H \) for the inner air-gap sub-domain

The development of (19) and (21) gives
\[ A_n^{III} = A_n^I n \frac{E_n(R_2, R_1)}{R_2 P_n(R_2, R_1)} + X_n'(R_2) \cos(n \varphi) \]  
(A.11)

\[ A_n^{III} = \frac{2}{2 \pi} \sum_{|i|} \int_0^{\varphi+\beta} \frac{\partial A_i}{\partial r} \bigg|_{r=R_1} \cos(n \theta) \ d\theta \]  
(A.19)

\[ C_n^{III} = C_n^I n \frac{E_n(R_2, R_1)}{R_2 P_n(R_2, R_1)} + X_n'(R_2) \sin(n \varphi) \]  
(A.12)

\[ C_n^{III} = \frac{2}{2 \pi} \sum_{|i|} \int_0^{\varphi+\beta} \frac{\partial A_i}{\partial r} \bigg|_{r=R_1} \sin(n \theta) \ d\theta \]  
(A.20)

The coefficient \( B_n^{III} \) and \( C_n^{III} \) defined in (20) and (22) can be written as

\[ B_n^{III} = \frac{2}{2 \pi} \sum_{|i|} \int_0^{\varphi+\beta} \frac{\partial A_i}{\partial r} \bigg|_{r=R_1} \cos(n \theta) \ d\theta \]  
(A.13)

\[ D_n^{III} = \frac{2}{2 \pi} \sum_{|i|} \int_0^{\varphi+\beta} \frac{\partial A_i}{\partial r} \bigg|_{r=R_1} \sin(n \theta) \ d\theta \]  
(A.14)

where \( Q \) is the number of rotor slots. The development of (A.13) and (A.14) gives

\[ B_n^{III} = \sum_{|i|} B_i^j r(n,i) \]  
(A.15)

\[ D_n^{III} = \sum_{|i|} D_i^j s(n,i) \]  
(A.16)

\[ B_n^{III} = \sum_{|i|} B_i^j r(n,i) \]  
(A.21)

\[ D_n^{III} = \sum_{|i|} D_i^j s(n,i) \]  
(A.22)

where \( Q \) is the number of rotor slots. The development of (A.13) and (A.14) gives

Expressions of the coefficients \( A_n^{IV} \) and \( C_n^{IV} \) for the outer PMs sub-domain

\[ A_n^{IV} = \frac{2}{n} \frac{R_2}{E_n(R_2, R_1)} + \frac{B_n^{III}}{n} \frac{R_1}{E_n(R_1, R_2)} \]  
(A.23)

\[ C_n^{IV} = \frac{2}{n} \frac{R_2}{E_n(R_2, R_1)} + \frac{D_n^{III}}{n} \frac{R_1}{E_n(R_1, R_2)} \]  
(A.24)

Expressions of the coefficients \( A_n^{IV} \) and \( C_n^{IV} \) for the outer PMs sub-domain

\[ A_n^{IV} = \frac{2}{n} \frac{R_2}{E_n(R_2, R_1)} + \frac{B_n^{III}}{n} \frac{R_1}{E_n(R_1, R_2)} \]  
(A.25)

\[ C_n^{IV} = \frac{2}{n} \frac{R_2}{E_n(R_2, R_1)} + \frac{D_n^{III}}{n} \frac{R_1}{E_n(R_1, R_2)} \]  
(A.26)

Expression of the coefficients \( A_n^I, B_n^I, A_n^I \) and \( B_n^I \) for the \( i \)-th slot sub-domain

The treatment of (12) and (13) yields to the following linear relations
\[ A^n_k = \sum_{n=1}^{\infty} \left( A^{111}_n \frac{2}{n^2 \beta} R_{2n} + A^{1111}_n \frac{2R_2 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) f(k,n,i) \]
\[ + \sum_{n=1}^{\infty} \left( C^{111}_n \frac{2}{n^2 \beta} E_n(R_2 R_3) + D^{1111}_n \frac{2R_3 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) g(k,n,i) \]
(A.27)

\[ B^n_k = \sum_{n=1}^{\infty} \left( A^{11111}_n \frac{2R_2 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} + B^{11111}_n \frac{2R_3 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) f(k,n,i) \]
\[ + \sum_{n=1}^{\infty} \left( C^{11111}_n \frac{2R_2 E_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} + D^{111111}_n \frac{2R_3 E_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) g(k,n,i) \]
(A.28)

The treatment of (10) and (11) yields to the following linear relations

\[ A^{n}_{0} + B^{n}_{0} \ln R_{1} = A^{n}_{1} \]
\[ + \sum_{n=1}^{\infty} \left( A^{111}_n R_{2n} \frac{2}{n^2 \beta E_n(R_2 R_3)} + A^{1111}_n \frac{2R_2 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) r(n,i) \]  
\[ + \sum_{n=1}^{\infty} \left( C^{111}_n R_{2n} \frac{2}{n^2 \beta E_n(R_2 R_3)} + D^{11111}_n \frac{2R_3 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) s(n,i) \]  
(A.29)

\[ A^{n}_{0} + B^{n}_{0} \ln R_{1} = A^{n}_{0} \]
\[ + \sum_{n=1}^{\infty} \left( A^{11111}_n R_{2n} \frac{2}{n^2 \beta E_n(R_2 R_3)} + B^{11111}_n \frac{2R_2 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) r(n,i) \]
\[ + \sum_{n=1}^{\infty} \left( C^{11111}_n R_{2n} \frac{2}{n^2 \beta E_n(R_2 R_3)} + D^{111111}_n \frac{2R_3 P_n(R_2 R_3)}{n^2 \beta E_n(R_2 R_3)} \right) s(n,i) \]  
(A.30)

We have to solve a system of linear equations with the same number of unknowns. By rewriting the above equations in matrix and vectors form, a numerical solution can be found by using mathematical software (Matlab or Maple).

**REFERENCES**


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