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Abstract

This paper presents an automatic setup planning module integrated in a CAPP system for rotational parts to be machined on a lathe. The developed system determines the possible setup combinations that are necessary for a complete machining of the part as well as the order of each setup and the surfaces to be used for clamping the part. The methodology applied takes into consideration constraints such as the geometry of both the stock and the final part, the geometry and the capacity of the chuck and the part tolerances. In general, these constraints allow the system to obtain several valid solutions for clamping the part. Some criteria based on the clamping force and the value of tolerances, have been considered in order to establish a preference order among these solutions. Finally, the analysis of *linked tolerances* and the tool approach direction to each surface determine the sets of surfaces to be machined in each setup. An example part is used in the course of the paper to conveniently illustrate the methodology used and two additional case studies prove that this methodology is adequate for the solution of real cases.

Keywords: Setup planning, CAPP, Turning, Tolerance Relationship, Clamping Accessibility.



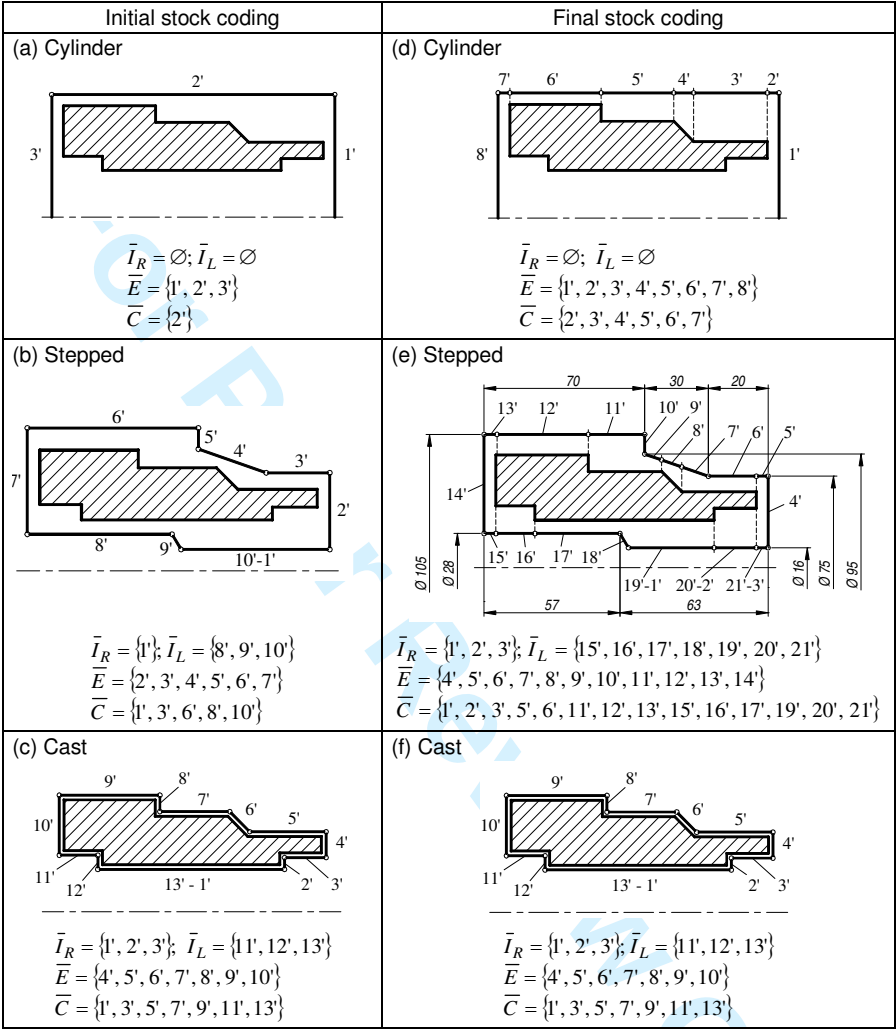


Figure 2

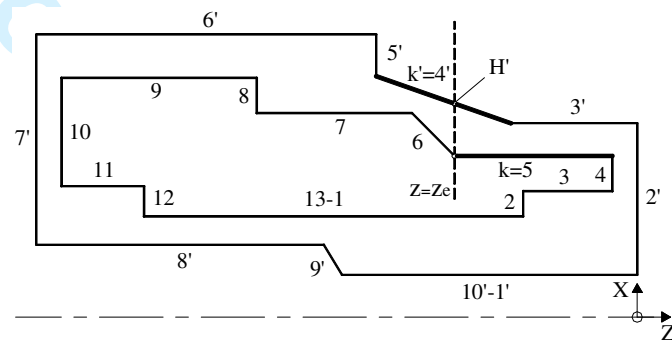


Figure 3

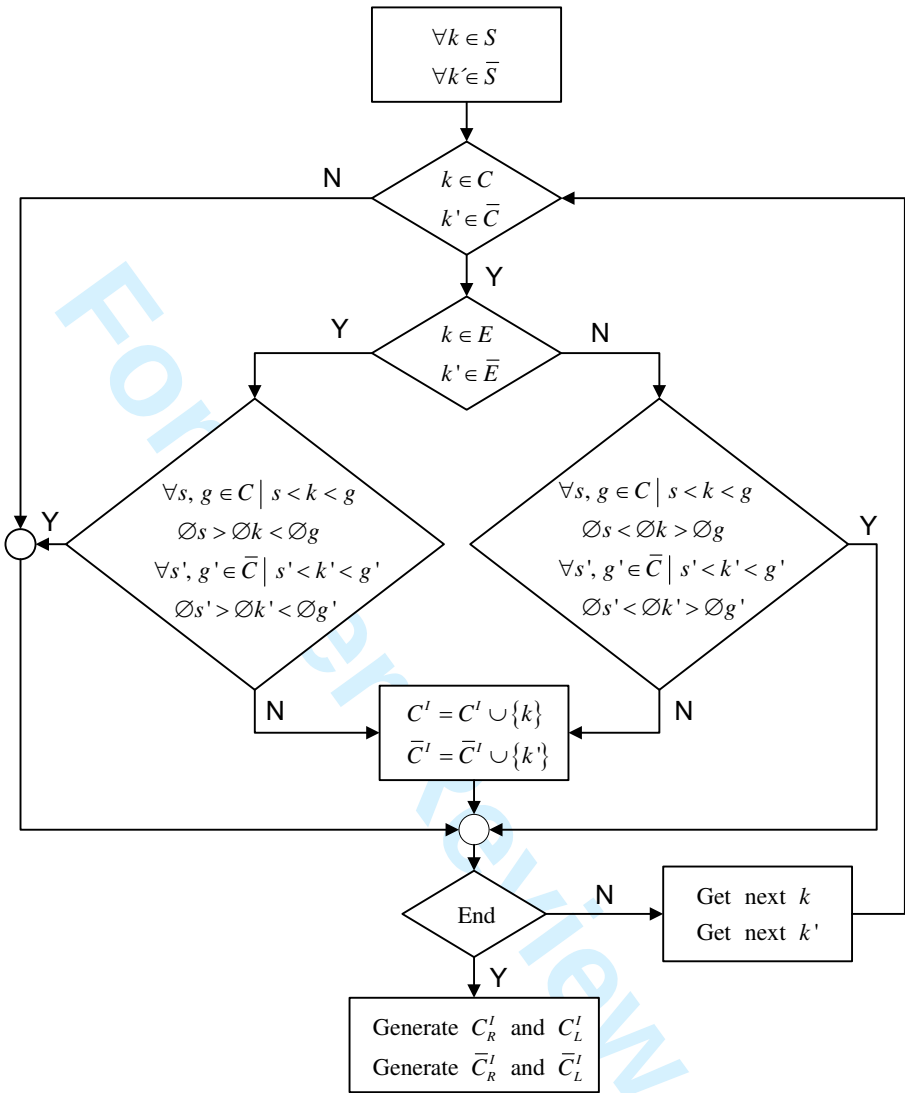


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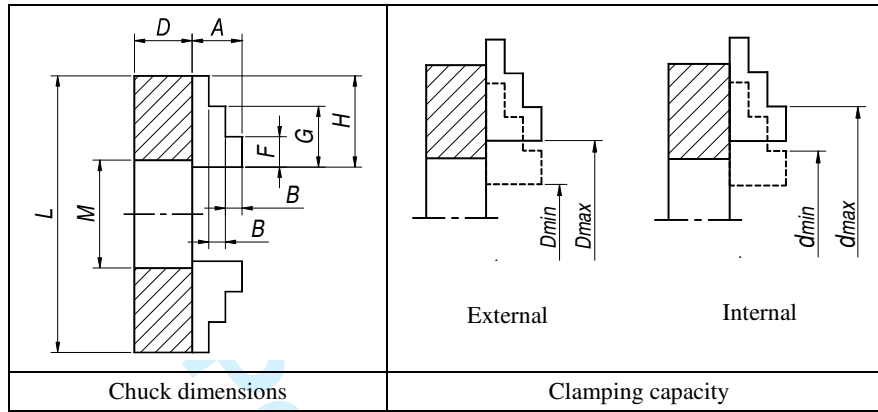


Figure 5

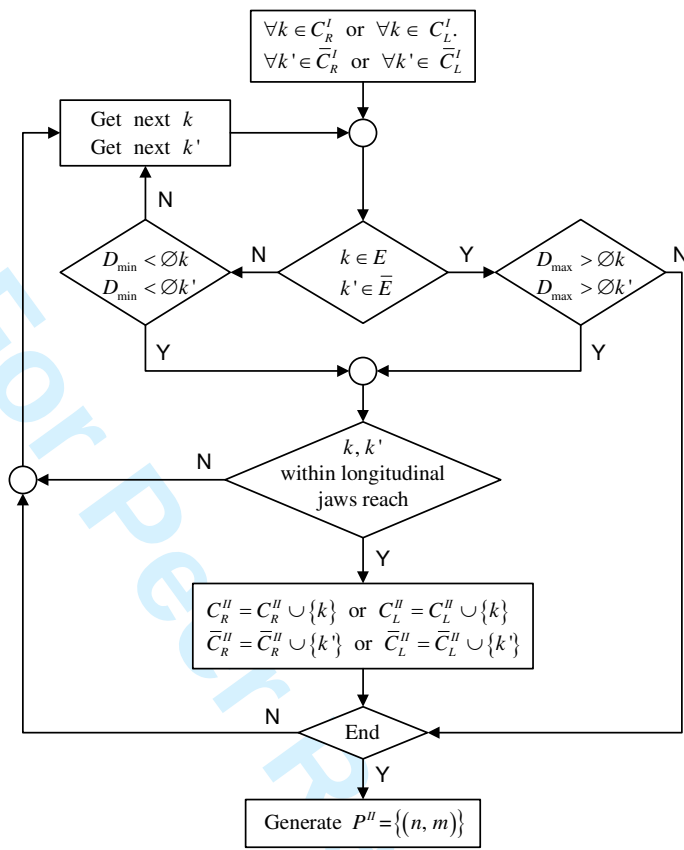


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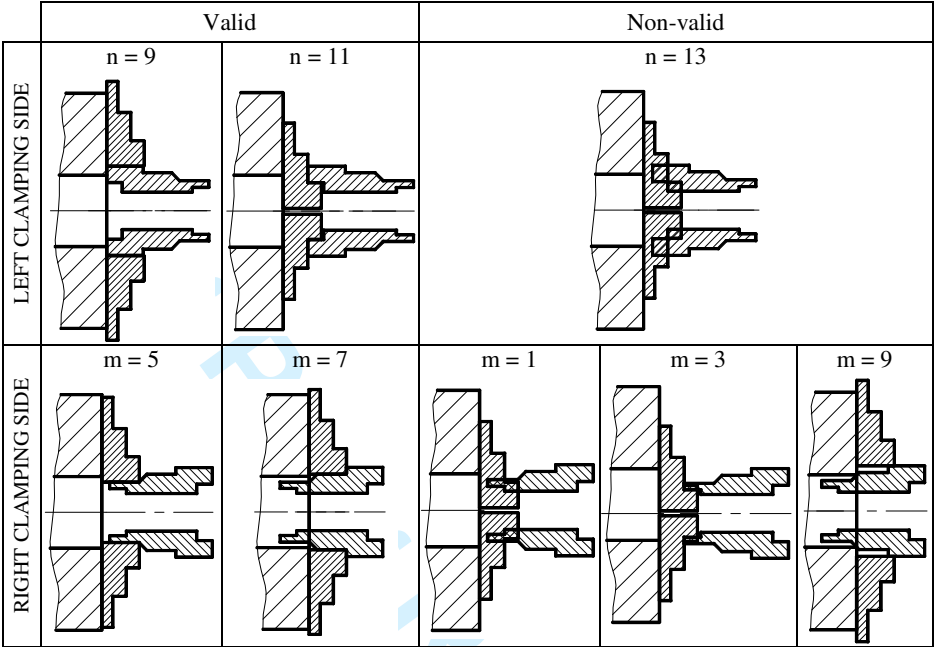


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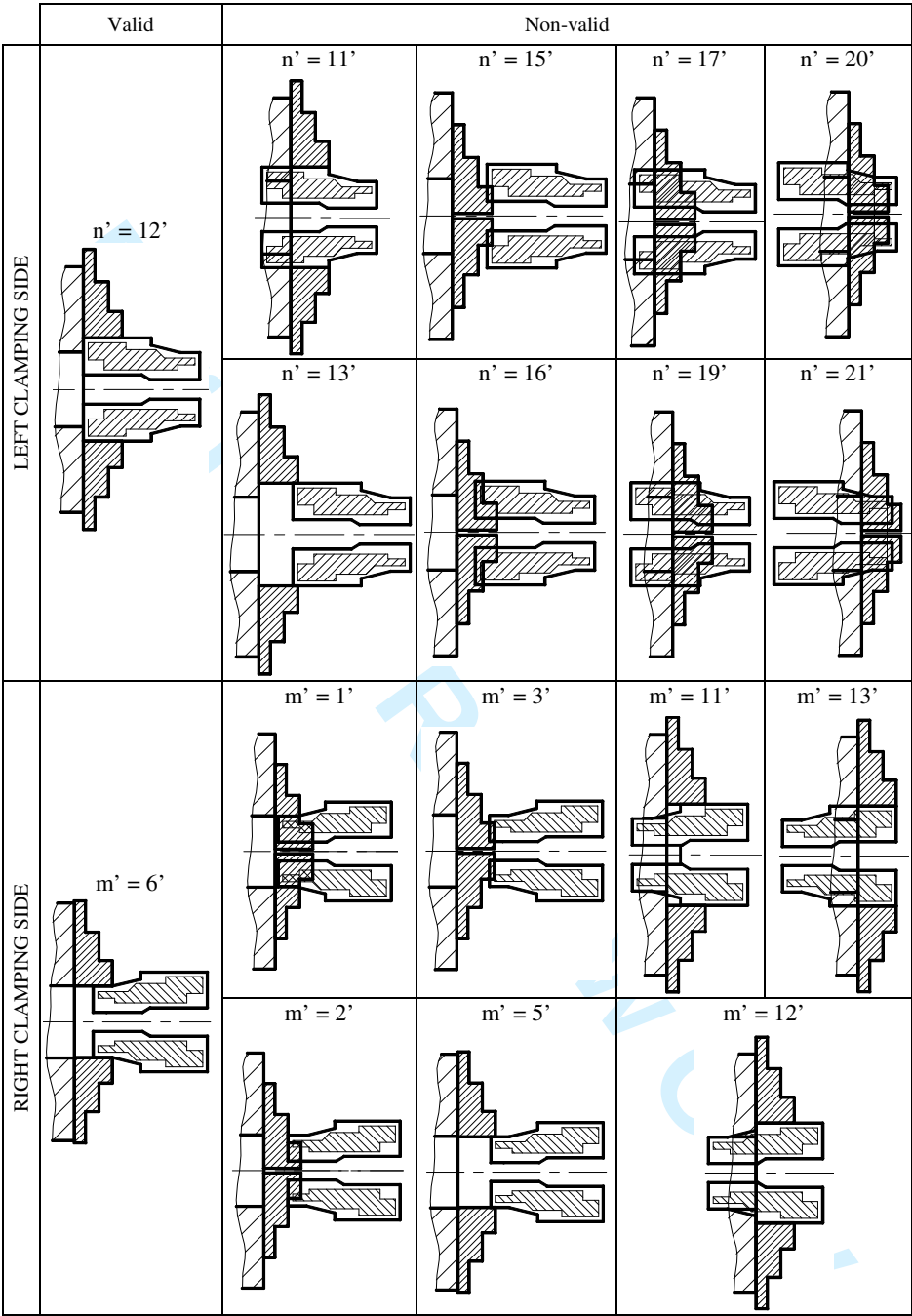


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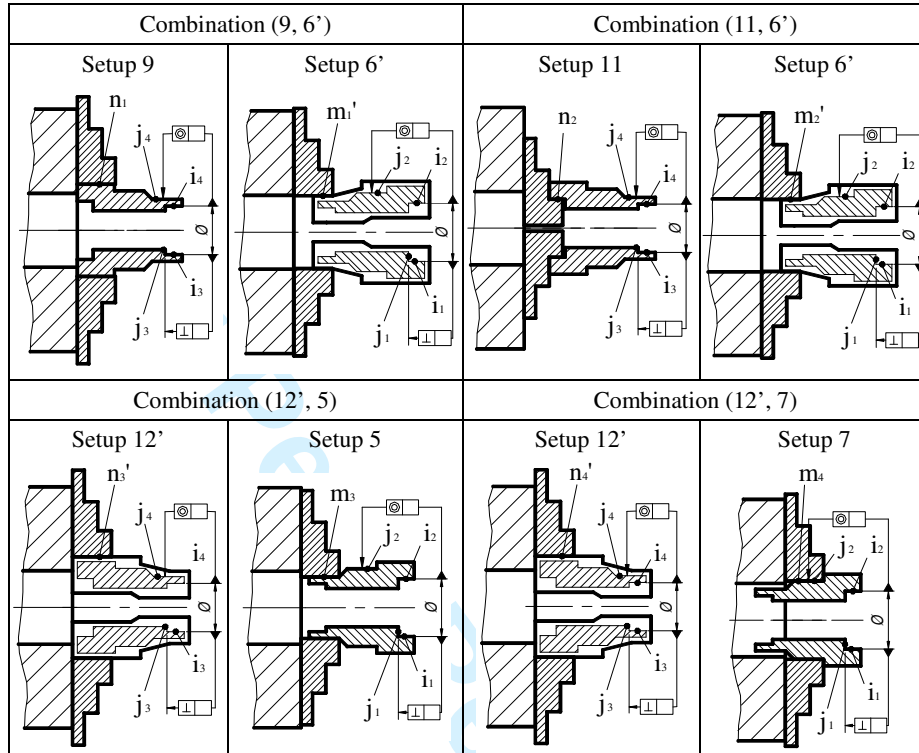


Figure 10

(n, m)	(i, j)	Diagram	Rejection conditions
$(n_{\text{ext}}, m_{\text{ext}})$	$(i_{\text{ext}}, j_{\text{ext}})$		if $\min(i, j) \leq n \leq \max(i, j)$ and $\min(i, j) \leq m \leq \max(i, j)$
	$(i_{\text{ext}}, j_{\text{int}})$		
	$(i_{\text{int}}, j_{\text{ext}})$		
	$(i_{\text{int}}, j_{\text{int}})$		if $\min(i, j) \leq n \leq \max(i, j)$ or $\min(i, j) \leq m \leq \max(i, j)$
$(n_{\text{ext}}, m_{\text{int}})$	$(i_{\text{ext}}, j_{\text{ext}})$		if $\min(i, j) \leq n \leq \max(i, j)$ and $\min(i, j) - \min(k_{\text{ext}}) \leq 1$
	$(i_{\text{ext}}, j_{\text{int}})$		Case $i > j$: if $\min(i, j) = j \leq n \leq i = \max(i, j)$ Case $i < j$: if $i - \min(k_{\text{ext}}) \leq 1$
	$(i_{\text{int}}, j_{\text{ext}})$		Case $i > j$: if $j - \min(k_{\text{ext}}) \leq 1$ Case $i < j$: if $\min(i, j) = i \leq n \leq j = \max(i, j)$
	$(i_{\text{int}}, j_{\text{int}})$		if $\min(i, j) \leq n \leq \max(i, j)$

Figure 11

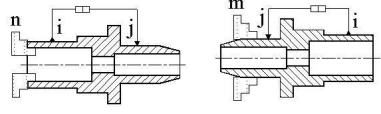
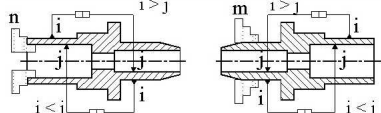
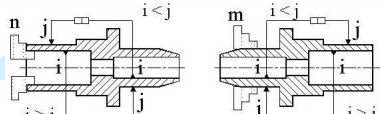
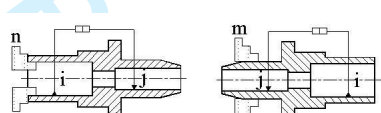
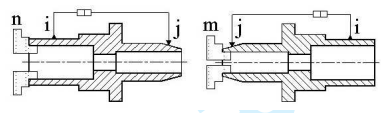
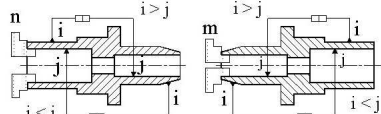
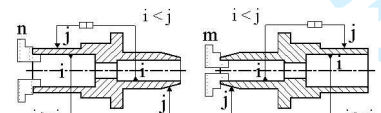
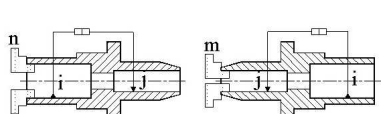
(n, m)	(i, j)	Diagram	Rejection conditions
$(n_{\text{int}}, m_{\text{ext}})$	$(i_{\text{ext}}, j_{\text{ext}})$		if $\min(i, j) \leq m \leq \max(i, j)$ and $\max(k_{\text{ext}}) - \max(i, j) \leq 1$
	$(i_{\text{ext}}, j_{\text{int}})$		Case $i > j$: if $\max(k_{\text{ext}}) - i \leq 1$ Case $i < j$: if $\min(i, j) = i \leq m \leq j = \max(i, j)$
	$(i_{\text{int}}, j_{\text{ext}})$		Case $i > j$: if $\min(i, j) = j \leq m \leq i = \max(i, j)$ Case $i < j$: if $\max(k_{\text{ext}}) - j \leq 1$
	$(i_{\text{int}}, j_{\text{int}})$		if $\min(i, j) \leq m \leq \max(i, j)$
$(n_{\text{int}}, m_{\text{int}})$	$(i_{\text{ext}}, j_{\text{ext}})$		If $\min(i, j) - \min(k_{\text{ext}}) \leq 1$ and $\max(k_{\text{ext}}) - \max(i, j) \leq 1$
	$(i_{\text{ext}}, j_{\text{int}})$		Case $i > j$: if $\max(k_{\text{ext}}) - i \leq 1$ Case $i < j$: if $i - \min(k_{\text{ext}}) \leq 1$
	$(i_{\text{int}}, j_{\text{ext}})$		Case $i > j$: if $j - \min(k_{\text{ext}}) \leq 1$ Case $i < j$: if $\max(k_{\text{ext}}) - j \leq 1$
	$(i_{\text{int}}, j_{\text{int}})$		if $\min(i, j) \leq \min(k_{\text{ext}})$ and $\max(k_{\text{ext}}) < \max(i, j)$

Figure 12

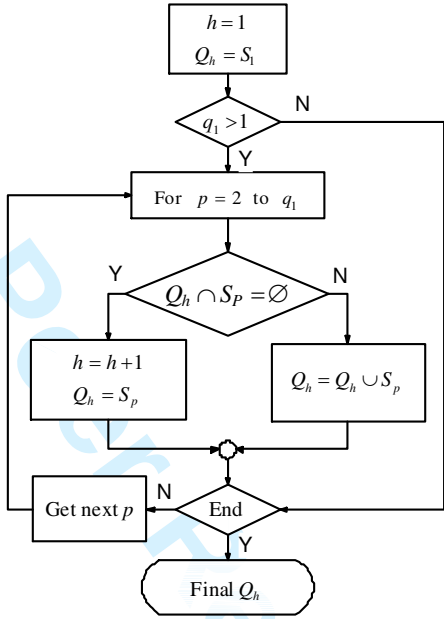


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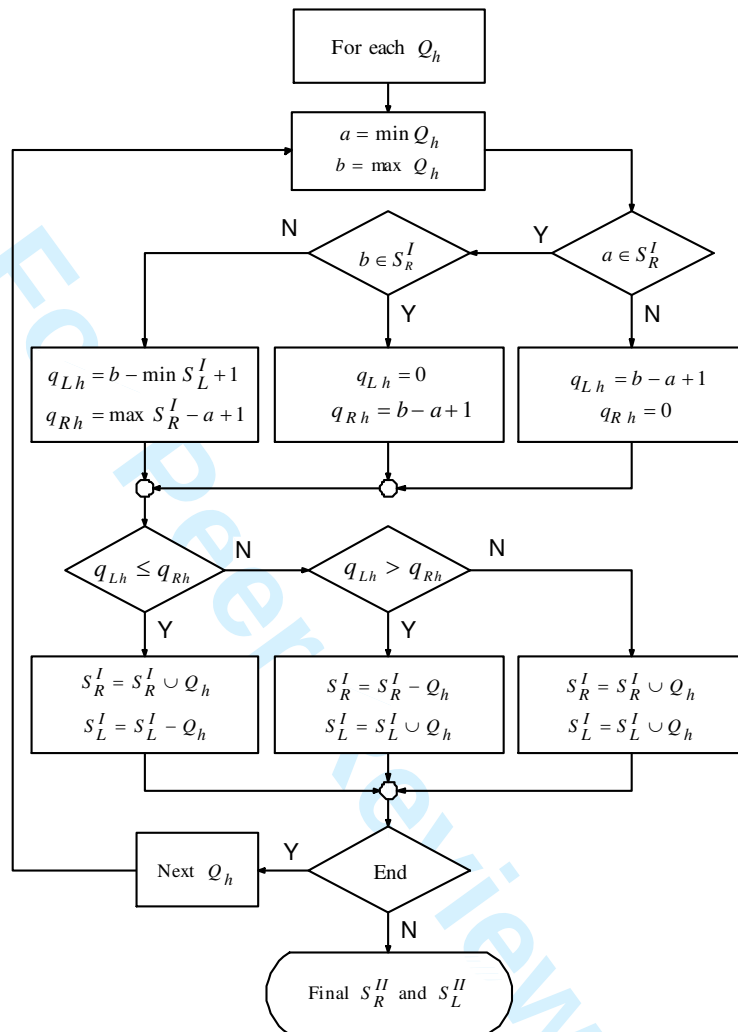


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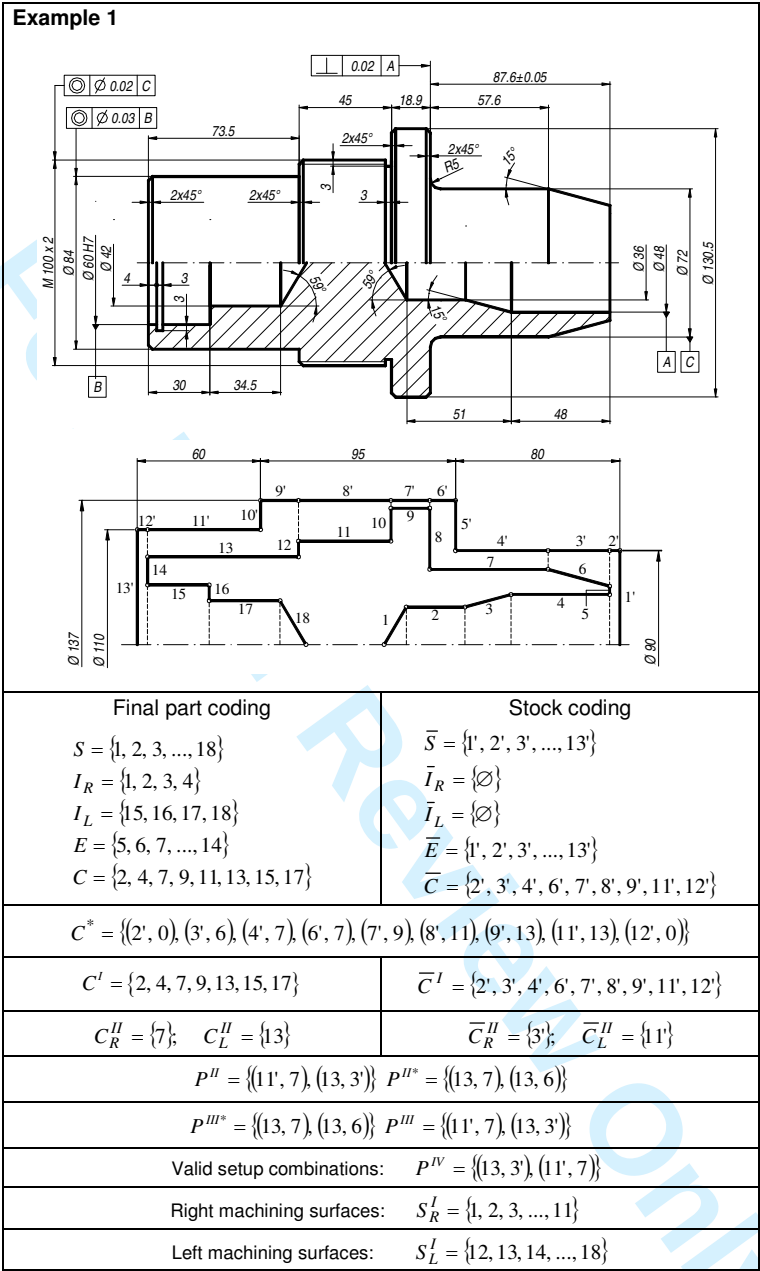


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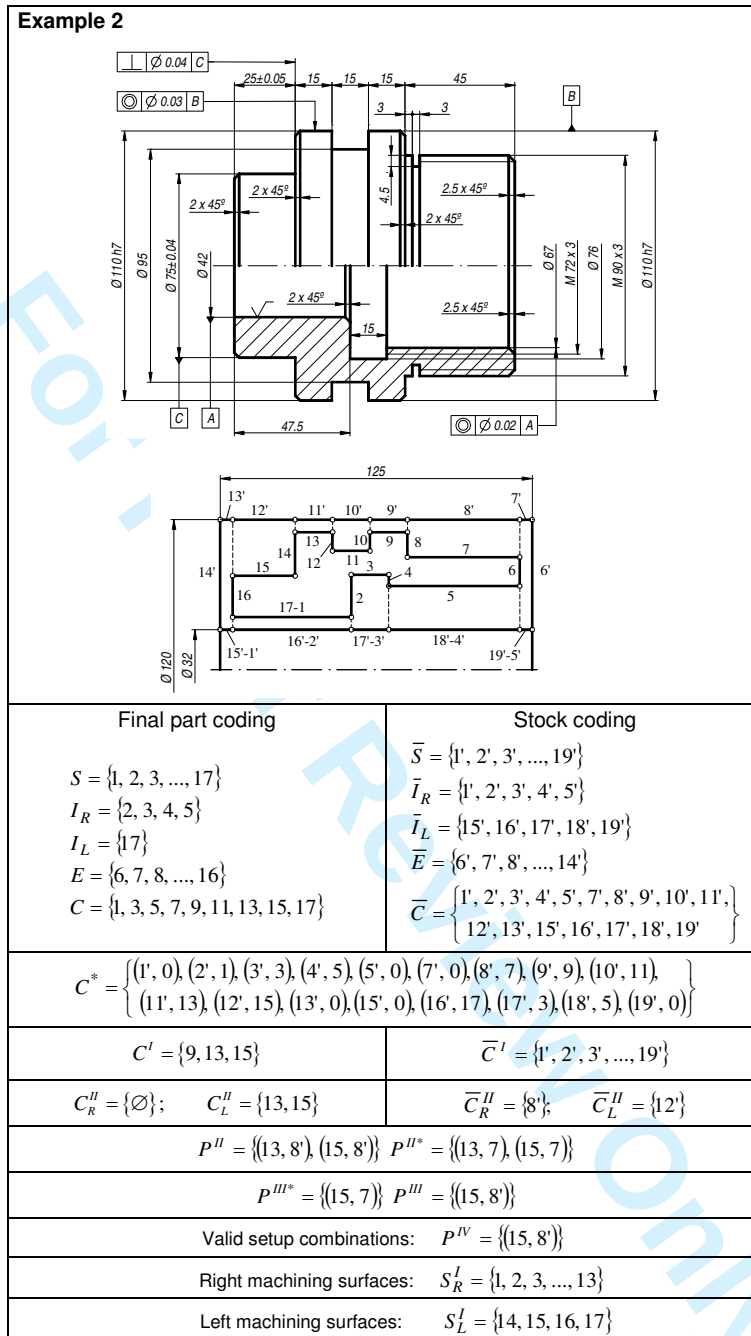


Figure 16

Table 1. Equivalent valid and non-valid setup combinations according to the part tolerances

Surfaces related by tolerance $t_p = (i_p, j_p)$	Equivalent setup combination (n^*, m^*)		
	(9, 5)	(11, 5)	(9, 7)
$t_1 = (3, 2)$	✓	✓	✓
$t_2 = (3, 3)$	✓	✓	✓
$t_3 = (3, 5)$	✓	✓	✓
$t_4 = (5, 5)$	✓	✓	✓
$t_5 = (11, 7)$	✓	✓	✗
$t_6 = (11, 11)$	✓	✓	✓
$t_7 = (11, 12)$	✓	✓	✓

Table 2. Preference order among valid setup combinations (P^{III})

Setup combination	Clamping surface		Tolerance		Partial precedence order		Final precedence order
	Index	Diameter 2 nd setup (mm)	$t_p = (i_p, j_p)$	Value	By clamping force	By tolerance value	
(12', 5)	12'	64	$t_1 = (3, 2)$	0.05	2	2	2
			$t_2 = (3, 3)$	0.025			
			$t_3 = (3, 5)$	0.02			
			$t_4 = (5, 5)$	0.3			
	5	64	$t_5 = (11, 7)$	0.05			
			$t_6 = (11, 11)$	0.03			
			$t_7 = (11, 12)$	0.03			
(9, 6')	6'	95	$t_5 = (11, 7)$	0.05	1	1	1
			$t_6 = (11, 11)$	0.03			
			$t_7 = (11, 12)$	0.03			
	9	95	$t_1 = (3, 2)$	0.05			
			$t_2 = (3, 3)$	0.025			
			$t_3 = (3, 5)$	0.02			
			$t_4 = (5, 5)$	0.3			
(11, 6')	6'	60	$t_5 = (11, 7)$	0.05	3	1	3
			$t_6 = (11, 11)$	0.03			
			$t_7 = (11, 12)$	0.03			
	11	60	$t_1 = (3, 2)$	0.05			
			$t_2 = (3, 3)$	0.025			
			$t_3 = (3, 5)$	0.02			
			$t_4 = (5, 5)$	0.3			

Table 3. Surfaces to be machined in the first and second setups

Setup combination P^{IV}	First setup		Second setup	
	Clamping surface	Set of surfaces to be machined	Clamping surface	Set of surfaces to be machined
(9, 6')	6'	$S_L'' = \{7, 8, \dots, 13\}$	9	$S_R'' = \{2, 3, \dots, 6\}$
(12', 5)	12'	$S_R'' = \{1, 2, \dots, 6\}$	5	$S_L'' = \{7, 8, \dots, 12\}$
(11, 6')	6'	$S_L'' = \{7, 8, \dots, 13\}$	11	$S_R'' = \{2, 3, \dots, 6\}$