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TOWARD THE FOURIER LAW FOR A WEAKLY INTERACTING ANHARMONIC CRYSTAL

CARLANGELO LIVERANI AND STEFANO OLLA

Abstract. For a system of weakly interacting anharmonic oscillators, perturbed by an energy preserving stochastic dynamics, we prove an autonomous (stochastic) evolution for the energies at large timescales (with respect to the coupling parameter). It turns out that this macroscopic evolution is given by the so-called conservative (non-gradient) Ginzburg-Landau system of stochastic differential equations. The proof exploits hypocoercivity and hypoellipticity properties of the uncoupled dynamics.

1. Introduction

The problem of deriving heat equation and Fourier’s law for the macroscopic evolution of the energy from a microscopic dynamics of interacting atoms (Hamiltonian or quantum), is one of the major goals of non-equilibrium statistical mechanics [2].

Although we are still very far from a rigorous mathematical derivation, we have now some understanding of the needed ingredients.

It is clear that heat equation is a macroscopic phenomenon, emerging after a diffusive rescaling of space and time. It is also clear that non-linearities of the microscopic dynamics are necessary, since in a linear system of interacting oscillators energy may disperse ballistically and thermal conductivity results infinite [10]. Non-linearities of the interaction should give enough chaoticity and time mixing such that locally the system, in the macroscopic time scale, is in a state of local equilibrium. This should be intended in terms of a scale parameter $\varepsilon$: in a region of linear size $\varepsilon$, at a large time...
scale $\varepsilon^{-b}t$, the system should be close to equilibrium with temperature given by the local average of kinetic energy. This statement of local equilibrium should be intended in the stronger sense that locally the dynamics is close to an equilibrium dynamics. Since energy is a conserved quantity, it can only evolve by moving between different regions of linear size $\varepsilon^{-1}$ through energy currents. Because of the size of the regions and the fact that in equilibrium energy currents have null average, one should look at time of the order $\varepsilon^{-2}t$ in order to see some exchange of energy between boxes at different temperature. In other words a central limit theorem for the energy currents is involved, and the thermal conductivity is then given by the space-time integral of the current-current correlation (Green-Kubo formula). This conductivity will be convergent if the system in equilibrium has enough mixing properties.

To perform the above program, in a mathematical rigorous way, from a purely deterministic Hamiltonian dynamics, it is at the moment a too difficult challenge.

In the last years some mathematical results have been obtained by perturbing the dynamics with energy conserving stochastic forces. The purpose of this stochastic perturbations is to give the ergodic and chaotic properties to the system without modifying the macroscopic behavior of the evolution of the energy.

This strategy has proven successful for systems in the hyperbolic scaling ($b = 1$), when momentum conservation is also preserved by the stochastic perturbations [9], obtaining Euler system of equations for compressible gas as macroscopic equation, at least in the smooth regime.

In the diffusive scaling ($b = 2$) this problem is still very challenging even in presence of the stochastic perturbations. The difficulty is essentially involved in the space-time rescaling and the corresponding central limit theorem.

In this paper we develop a weak-coupling approach to the problem of energy diffusion that permits to separate the time limit from the space one. We consider a finite system of anharmonic oscillators, whose hamiltonian dynamics is perturbed by a noise that conserves the kinetic energy of each oscillators (we consider oscillators that have at least 2 degree of freedom). The noise could be though as modeling some chaotic internal degree of freedom of each atom.

The oscillators are weakly coupled with a small parameter $\varepsilon$. Consequently the exchange of energy between oscillators is given by the currents associated to the hamiltonian mechanism, but multiplied by $\varepsilon$. The noise drives each atom towards (microcanonical) equilibrium where currents have null average. In a time scale of order $\varepsilon^{-2}$ current fluctuations are able to
move energy around the lattice if gradients of energy are present between atoms.

We prove in fact that in the limit as $\varepsilon \to 0$, in the time scale $\varepsilon^{-2}t$, the energies of the atoms evolve autonomously following the solution of a system of stochastic differential equations, conservative of the total energy (cf. (3.8)). It turns out that this macroscopic stochastic evolution has already been considered in the hydrodynamic limit literature and it is called non-gradient Ginzburg-Landau model [12]. Consequently, using the techniques developed in [12], one could try to prove that under space-time diffusive rescaling, the energy evolves following a non-linear heat equation. The results in [12] do not apply directly to (3.8) due to degeneracy of the coefficients, but hopefully they can be adapted to the present situation, for the moment we postpone this problem. We have thus reduced the derivation of the heat equation to a two step procedure of which this paper rigorously accomplish the first step.

We should remark here that an extension of the non-gradient technique of [12] directly to our original microscopic stochastic dynamics would be much more challenging, as this dynamics is very degenerate.

The reason of the name non-gradient comes from the fact that the currents of the macroscopic dynamics are not gradient, i.e. are not given by the spacial gradient of a local function of the configurations of energies. It is interesting to note that in the purely harmonic case, the macroscopic dynamics (3.8) become gradient (see appendix E). This implies a connection between the non-gradient property and non-linearity of the microscopic dynamics. We also notice that in the purely harmonic case, because the presence of the energy conserving noise, the microscopic energy current have an exact fluctuation-dissipation decomposition in a gradient plus a fast fluctuating term (see formula (E.1 in appendix E), that has been already exploited in [1] to obtain Fourier’s law.

The main strategy of the proof is similar to other averaging principles ([4, 5, 7]): at a large time scale the dynamics of each atom is close to the equilibrium dynamics parametrized by its own energy. Energies of the atoms are our slow variables and evolves through their currents. But a simple averaging of these currents (that would occur in a time scale of order $\varepsilon^{-1}$) would not move any energy, since currents have null averages respect to all equilibrium measures (microcanonical). This forces us to look at the time scale $\varepsilon^{-2}$, when the energy evolves due to the fluctuations of the currents in equilibrium. Thus we must establish a central limit theorem for the energy currents in the uncoupled dynamics, i.e. we have to study the Poisson equation

$$L_0 u = j$$
where \( L_0 \) is the generator of the uncoupled dynamics, and \( j \) is the energy current between two particles. In order to prove our theorem, we need existence and regularity of the solution \( u \) of this equation. The generator \( L_0 \) turns out to be hypoelliptic on each microcanonical energy surface, that provides regularity on the tangent direction of this surface. Yet, as the energy is exchanged from one particle to the other, we also needed to prove regularity in non tangential directions.

For the existence of \( u \), we prove a spectral gap in a proper Sobolev space, with an adaptation of hypocoercivity techniques [13]. These techniques provide a precise control of this spectral gap with respect to the energy, a control especially needed at low energies. Such detailed informations are necessary in order to perform the closure of the macroscopic equations.

The content of the paper is as follows.

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### 2. The model

Let us consider a region \( \Lambda \subset \mathbb{Z}^d \), set \( N = |\Lambda| \), the number of sites in \( \Lambda \). At each site we have a \( \nu \)-dimensional, \( \nu \geq 2 \), nonlinear oscillator and we assume that such oscillators interact weakly via a non-linear potential. Such a situation is described by the following Hamiltonian in the variables
\[(q_i, p_i)_{i \in \Lambda} \in \mathbb{R}^{2\nu N}\]

\[H_\varepsilon^\Lambda := \sum_{i \in \Lambda} \frac{1}{2} \| p_i \|^2 + \sum_{i \in \Lambda} U(q_i) + \varepsilon \frac{1}{2} \sum_{|i-j|=1} V(q_i - q_j),\]

where \(U, V \in C^\infty(\mathbb{R}^\nu, \mathbb{R})\). We use the convention \(\sum_{|i-j|=1} = \sum_{i \in \Lambda} \sum_{\{j \in \Lambda : |i-j|=1\}}\).

For simplicity we assume that \(U(q) = \overline{U}(|q|^2), \overline{U} \in C^\infty(\mathbb{R}, \mathbb{R}), \overline{U}(0) = 0\) and \(c^{-1} \leq \overline{U}' \leq c\) for some finite positive constant \(c\), in particular this implies that \(U\) is radially symmetric and strictly convex\(^1\). Also, we assume \(\|\nabla V(q)\|^2 \leq cU(q)\) and \(V(-q) = V(q)\).

For simplicity of notations, we choose \(\nu = 2\). All results stated in this paper are valid for general \(\nu \geq 2\), with slight modifications of notations.

In addition to the Hamiltonian dynamics, we consider random forces that conserve the single sites kinetic energies, given by independent diffusions on the spheres \(\|p_i\|^2 = \text{cost}\). In order to define such diffusions, consider the vector fields

\[X_i := p_i^1 \partial_{p_i^2} - p_i^2 \partial_{p_i^1} =: J p_i \cdot \partial_{p_i}, \quad J = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}\]

and the second order operator

\[S = \sum_{i \in \Lambda} X_i^2\]

The generator of the process we are interested in is then given by

\[L_{\varepsilon, \Lambda} =: A_\varepsilon + \sigma^2 S\] (2.1)

where \(A_\varepsilon = \{ H_\varepsilon^\Lambda \cdot , \cdot \}\), is the usual Hamiltonian operator and \(\sigma > 0\) measures the strength of the noise. Clearly, \(L_{\varepsilon, \Lambda}\) is the generator of a contraction semigroup \(P^t_\varepsilon\) in \(L^2(\mathbb{R}^{2\nu N}, m_\varepsilon)\) with stationary measure \(m_\varepsilon\) and \(P^t_{\varepsilon} H_\varepsilon^\Lambda = H_\varepsilon^\Lambda\), for all \(t \in \mathbb{R}_+\). Next, we must specify the initial conditions.

The Gibbs measures at temperature \(\beta^{-1}\) are defined by

\[m_\varepsilon^\beta(dq, dq) = Z_\varepsilon(\beta) e^{-\beta H_\varepsilon^\Lambda(q,p)} dp dq\]

and are the stationary (equilibrium) probability measures for the dynamics (the canonical ensemble). As reference measure we pick the one corresponding to \(\beta = 1\) and we denote it by \(m_0\). Notice that for \(\varepsilon\) small enough, \(m_\varepsilon\) and the product measure \(m_0\) are equivalent. To simplify notations, we also assume that \(U\) is such that

\[Z_0(1) = 1 = \int_{\mathbb{R}^4} e^{-\nu \frac{p^2}{2} + U(q)} dp dq.\]

\(^1\)The general, non radial, case can be treated exactly in the same way at the only price of a much messier algebra. On the contrary, the non convex case could hold interesting surprises and hopefully will be investigated in the future.
We assume that the system is started in an initial distribution $d\nu_0 := F_0 \, dm_0$. 

**Assumption 1.** We assume that $F_0 \in L^2(\mathbb{R}^{4N}, m_0)$. 

For each $T > 0$, the Markov process just described defines a probability on $\Omega = C^0([0, T], \mathbb{R}^{2|\Lambda|})$. We will use $\omega_t = (q(t), p(t))$ to designate the elements of $\Omega$ at time $t$.

**Remark 2.1.** In the following we will suppress the subscripts and superscripts $\Lambda$, when this does not create confusion.

**Remark 2.2.** Here we have free boundary conditions. It should be possible to treat more general stochastic boundary conditions (e.g. having the particle at the boundary perform an Ornstein-Uhlenbeck process at a given temperature) by the same method, we avoid such a generalization to simplify the presentation.

### 3. The results

The single particles energies are

$$\mathcal{E}_i^\varepsilon(q, p) = \frac{1}{2} \|p_i\|^2 + U(q_i) + \frac{1}{2} \varepsilon \sum_{|i-j|=1} V(q_i - q_j).$$

The time evolution of these energies is given by:

$$\frac{d\mathcal{E}_i^\varepsilon}{dt} = \varepsilon \sum_{|i-k|=1} j_{i,k}$$

(3.1)

where the energy currents are defined by

$$j_{i,k} = \frac{1}{2} \nabla V(q_i - q_k) \cdot (p_i + p_k).$$

(3.2)

Note that $j_{i,k} = -j_{k,i}$ and that they are functions of the $q_i, p_i, q_k, p_k$ only.

If $\varepsilon = 0$ the dynamics is given by non-interacting oscillators, and consequently the energy of each oscillator is a conserved quantity. So for $\varepsilon = 0$ there is a family of equilibrium measure parametrized by the vector $\underline{a} = (a_i)_{i \in \Lambda}$ of the energy of each oscillator. This is given by $\mu_{\underline{a}}^\Lambda$, the microcanonical measure associated to the Hamiltonian flow $H_0^\Lambda$ on the surface

$$\Sigma_{\underline{a}} := \left\{ q, p : a_i = \mathcal{E}_i^0(q, p) = \frac{1}{2} \|p_i\|^2 + U(q_i) \right\} = X_{i \in \Lambda} \Sigma_{a_i}. \quad (3.3)$$

Clearly, letting $\mu_{\underline{a}}$ be the microcanonical measure on the 3 dimensional surface $\Sigma_{\underline{a}}$, we have $\mu_{\underline{a}}^\Lambda = \Phi_{i \in \Lambda} \mu_{a_i}$. By the symmetry between $p$ and $-p$ it follows that $\mu_{\underline{a}}(j_{i,k}) = 0$ for each $\underline{a}$. 

We are interested in the random variables determined the time rescaled energies
\[ \mathcal{E}_i^{\varepsilon}(t) = \mathcal{E}_i^{\varepsilon}(q(\varepsilon^{-2}t), p(\varepsilon^{-2}t)). \] (3.4)

In order to define the parameters of the mesoscopic evolution, consider the dynamics of 2 non-interacting oscillators ($\varepsilon = 0$), each starting with the microcanonical distribution with corresponding energy $a_1$ and $a_2$. Let us denote by $\mathbb{E}_{a_1, a_2}(\cdot)$ the corresponding expectation in this equilibrium measure. We will show that the following function on $\mathbb{R}^2_+$
\[ \gamma^2(a_1, a_2) = \int_0^\infty \mathbb{E}_{a_1, a_2}(j_{1,2}(t)j_{1,2}(0)) \, dt, \] (3.5)
is well defined. More, in Lemma 8.2 we prove that
\[ \gamma^2(a_1, a_2) = a_1a_2G(a_1, a_2) \] (3.6)
where $G$ is a positive symmetric smooth function. Correspondingly we define the mesoscopic current by the antisymmetric function
\[ \alpha(a_1, a_2) = e^{\mathcal{U}(a)}(\partial_{a_1} - \partial_{a_2})\left(e^{-\mathcal{U}(a)}\gamma^2(a_1, a_2)\right). \] (3.7)
where $\mathcal{U}(a) = -\sum_j \log \mathcal{Z}(a_j)$, and $\mathcal{Z}(a)$ is the energy density distribution under $m_0$, that behaves like $a$ for small $a$.

Here is our main result:

**Theorem 1.** In the limit $\varepsilon \to 0$, the law of $\{\mathcal{E}_i^{\varepsilon}\}_{i \in \Lambda}$ converges to the weak solution of the stochastic differential equations
\[ d\mathcal{E}_i = \sum_{k:|i-k|=1} \alpha(\mathcal{E}_i, \mathcal{E}_k) \, dt + \sum_{k:|i-k|=1} \gamma(\mathcal{E}_i, \mathcal{E}_k) \, dB_{(i,k)} \] (3.8)
with $B_{(i,k)} = -B_{(k,i)}$ independent standard Brownian motions. Where the law of $\mathcal{E}_i^{\varepsilon}(0)$ is given by the marginal of $F_{\varepsilon}dm_\varepsilon$ on the $\mathcal{E}^\varepsilon$.

Notice that the generator of the diffusion (3.8) on $\mathbb{R}^\Lambda_+$ is given by
\[ \mathcal{L} = \sum_{|k-i|=1} \left( \gamma(\mathcal{E}_i, \mathcal{E}_k)^2(\partial_{\mathcal{E}_i} - \partial_{\mathcal{E}_k})^2 + \alpha(\mathcal{E}_i, \mathcal{E}_k)(\partial_{\mathcal{E}_i} - \partial_{\mathcal{E}_k}) \right). \] (3.9)
Since $\gamma^2$ and $\alpha$ are smooth function on $\mathbb{R}^2_+$, the uniqueness of the weak solution of (3.8) follows by applying the results in [3].

Observe that there is a family of product probability measures
\[ \prod_{i \in \Lambda} \mathcal{Z}(a_i) e^{-\beta a_i} N(\beta)^{-1} \, da_i = \prod_{i \in \Lambda} e^{-\beta a_i + \mathcal{U}(a_i)} N(\beta)^{-1} \, da_i, \quad \beta > 0 \] (3.10)
that are stationary and reversible for the diffusion generated by (3.9).

As we will see shortly the proof of Theorem 1 relays heavily on the fact that the unperturbed microscopic dynamics $P_\Lambda^\varepsilon$ generated by $L_{0, \Lambda}$ has strong mixing properties (hypocoercivity). This is itself a non trivial result which we believe worth stating separately. Let $\mathcal{H}_\Lambda^1$ be the Sobolev space of order...
one on \( \Sigma_a \) with respect to the microcanonical measure \( \mu_a \) and a properly rescaled Riemannian structure (see Section 6 for more details).

**Theorem 2.** For each set \( \Lambda \subset \mathbb{Z}^d \), there exists \( C, \tau > 0 \) such that, for each energies \( a \in (0, \infty)^\Lambda \) and \( \sigma \in (0, 1) \), the following holds true

- The semigroup \( P^t_{0, \Lambda} \) is contractive in \( L^2(\Sigma_a, \mu_a) \).
- For each smooth function \( f \in H^1_\Lambda \) such that \( \mu_a(f) = 0 \), holds
  \[
  \| P^t_{0, \Lambda} f \|_{H^1_\Lambda} \leq Ce^{-\tau \sigma^2 t} \| f \|_{H^1_\Lambda}.
  \]

The proof is given in section 6.

Before discussing the proof of the above results let us indulge in several remarks.

**Remark 3.1.** By (3.7) we can rewrite the generator as

\[
\mathcal{L} = \sum_{|k-i|=1} e^{\mu_a(\partial_\mathcal{E}_i - \partial_\mathcal{E}_k)} e^{-\mu_a} \gamma^2 (\mathcal{E}_i, \mathcal{E}_k)(\partial_\mathcal{E}_i - \partial_\mathcal{E}_k)
\]

(3.11)

**Remark 3.2.** The process (3.8) is close the the one studied by Varadhan in [12], yet it is not covered by such results (due to the degeneracy at zero of the diffusion coefficients and the non strict convexity of the potential of the invariant measure). In any case, the extension of Varadhan’s work to the present case would allow to obtain the heat equation in the present setting via a diffusive scaling limit of space and time (hydrodynamic limit).

**Remark 3.3.** Note that both \( \gamma \) and \( \alpha \) depend on \( \sigma \). One can wonder if equation (3.8) does admit a limit for small noise. Indeed, if \( U \) and \( V \) are quadratic then both \( \gamma^2 \) and \( \alpha \) are proportional to \( \sigma^{-2} \), see (E.4). Hence the energy exchange for small noise is faster than the time scale we are exploring. This is due to the fact that in the quadratic case the solutions are quasiperiodic. On the other hand, for each \( U, V \) a positive measure of such quasiperiodic solutions will survive by KAM theorem at least for small energies so it may be possible that a small noise limit exists, upon rescaling time, as in the quadratic case. The present results allow only upper bounds (which agree with the quadratic case), but it is unclear if a sufficiently exact scaling still exists.

4. **Proof of Main theorem**

This section is devoted to proving Theorem 1 by using several results detailed in the later sections (more precisely we assume Proposition 6.1 and Lemmata 7.3, 7.4, 8.1 and 8.2). Our strategy is the first establish tightness and then to show that the accumulation points satisfy (3.8). Since (3.8) has a unique solution, the process have a unique accumulation point whereby proving the existence of the limit.
4.1. Tightness. Here we start studying the processes \( \{ \mathcal{E}_t^\varepsilon(t) \} \) defined in (3.4).

**Lemma 4.1.** There exists \( \varepsilon_0 > 0 \) such that for each \( T > 0 \), the processes \( \{ \mathcal{E}_t^\varepsilon(t) \}_{t \leq T}, 0 \leq \varepsilon \leq \varepsilon_0 \), are tight.

**Proof.** The proof use a standard backward/forward martingale decomposition argument (cf. [11, 8]). We recall it here.

Let us start the process with the equilibrium distribution \( m_\varepsilon \). Then the time reversed process, in a given time interval, is a Markov process with generator given by the adjoint \( L_\varepsilon^* = -A_\varepsilon + \sigma^2 S \). Remark that, since \( X_k^2 p_k = -p_k \), we have \( S j_{i,k} = -j_{i,k} \). So we can decompose

\[
\varepsilon \int_0^{t_{\varepsilon^{-2}}} \dot{j}_{i,k}(s) \, ds = -\frac{\varepsilon}{2\sigma^2} \int_0^{t_{\varepsilon^{-2}}} L_\varepsilon \dot{j}_{i,k}(s) \, ds - \frac{\varepsilon}{2\sigma^2} \int_0^{t_{\varepsilon^{-2}}} L_\varepsilon^* \dot{j}_{i,k}(s) \, ds = \frac{\varepsilon}{2\sigma^2} M_t^{\varepsilon +} + \frac{\varepsilon}{2\sigma^2} M_t^{\varepsilon -}
\]

where \( M_t^{\varepsilon +} \) are continuous martingales, adapted respectively to the forward and backward filtration, that can be represented by the stochastic integrals

\[
M_t^{\varepsilon +} = \int_0^t (X_k j_{j,k})(s) dw_t^{i +}(s) + \int_0^t (X_k j_{j,k})(s) dw_t^{i -}(s)
\]

where \( w_t^{i +}(t) \) and \( w_t^{i -}(t) \) are standard Wiener processes adapted respectively to the forward and the backward filtration. Consequently the tightness follows from the tightness of each of these stochastic integrals. Noticing that \( X_k j_{j,k} = J p_k \cdot \nabla V(q_j - q_k) / \sigma_j \) is in \( L^p(m_\varepsilon) \) for any \( p < \infty \), by Doob’s inequality:

\[
\mathbb{E}_{m_\varepsilon} \left( \sup_{0 \leq t \leq T} (M_t^{\varepsilon +})^4 \right) \leq \left( \frac{4}{3} \right)^4 \mathbb{E}_{m_\varepsilon} \left( (M_T^{\varepsilon +})^2 \right)^2 \leq C T^2
\]

This imply that the Kolmogorov criterion for tightness is satisfied:

\[
\sup_{\varepsilon} \mathbb{E}_{m_\varepsilon} \left( |\mathcal{E}_t^\varepsilon(s) - \mathcal{E}_t^\varepsilon(t)|^4 \right) \leq \frac{C'}{\sigma^4} (t - s)^2
\]

In non-equilibrium, because of the assumption that the initial distribution \( F \) is in \( L^2(m_\varepsilon) \), the above argument extends immediately by a simple use of Schwarz inequality: \( \square \)

Observe that with the same argument we can also establish the following bound for any \( p > 1 \):

\[
\mathbb{E}_{m_\varepsilon} \left( \sup_{0 \leq t \leq T} \left[ \int_0^t \dot{j}_{i,k}(s) \, ds \right]^p \right) \leq \frac{C T^{p/2}}{\sigma^p}
\]

where \( C \) is a constant independent of \( \varepsilon, T, \sigma \).

Once we have the tightness all is left to prove is that the limit is unique, this is the content of the next section.
4.2. Identification of the limit. The goal of this section is to prove that any accumulation point of the laws of \( \{ \mathcal{E}^\varepsilon_i(t) \}_{i \in \Lambda} \) must satisfy equation (3.8). More precisely, since

\[
\mathcal{E}^\varepsilon_i(t) - \mathcal{E}^\varepsilon_i(0) = \sum_{k|\{i-k\}=1} \varepsilon \int_0^{\varepsilon^2 t} j_{i,k}(s) \, ds
\]  

(4.2)

we want to show that, for every couple \( i, k \in \Lambda \) such that \(|i - k| = 1\) there exist orthogonal martingales \( \mathcal{M}^\varepsilon_{i,k} = -\mathcal{M}^\varepsilon_{k,i} \) with zero average and quadratic variance given by

\[
2 \int_0^t \gamma^2(\mathcal{E}^\varepsilon_i(s), \mathcal{E}^\varepsilon_k(s)) \, ds
\]  

(4.3)

and such that, for each \( t \geq 0 \),

\[
\lim_{\varepsilon \to 0} \mathbb{E}^\varepsilon_F \left( \varepsilon \int_0^{\varepsilon^2 t} j_{i,k}(s) \, ds - \int_0^t \alpha(\mathcal{E}^\varepsilon_i(s), \mathcal{E}^\varepsilon_k(s)) \, ds + \mathcal{M}^\varepsilon_{i,k}(t) \right) = 0.
\]  

(4.4)

To prove (4.4) it turns out to be useful to introduce a cutoff for high energy \( \xi_K = \chi_K(\mathcal{E}^0) \), where \( \chi_K : \mathbb{R}^\Lambda \to [0, 1] \) are smooth positive functions with support in \([0, K + 1]^\Lambda\), such that \( \chi_K(a) = 1 \) if \( a \in [0, K]^\Lambda \). Then define \( j_{i,k}^K = j_{i,k} \xi_K \).

By the symmetry between \( p \) and \(-p\) it follows that \( \mu_2(j_{i,k}^K) = 0 \) for each \( a \in \mathbb{R}^\Lambda \) and any \( K > 0 \). Arguing as in estimate (4.1), we have that

\[
\lim_{K \to \infty} \sup_{\varepsilon > 0} \mathbb{E}_{m_\varepsilon} \left( \sup_{0 \leq t \leq T} \varepsilon \int_0^{t \varepsilon^2} j_{i,k}(1 - \xi_K)(s) \, ds \right)^2 = 0
\]  

(4.5)

By Proposition 6.1 it follows that the equation

\[
L_0 u_{i,k} = j_{i,k}
\]  

(4.6)

has a unique solution with zero average with respect to all measures \( \mu_2 \). Note that \( j_{i,k} = -j_{k,i} \), thus also \( u_{i,k} = -u_{k,i} \).

In addition, Lemma 7.3 implies \( u_{i,k} \in C^\infty([\mathbb{R}^4 \setminus \{0\}]^2, \mathbb{R}) \cap C^0(\mathbb{R}^8, \mathbb{R}) \). Observe that, since \( L_0 \) conserves the energies of all particles, denoting \( u_{i,j}^K = u_{i,j} \xi_K \) we have

\[
L_0 u_{i,k}^K = j_{i,k}^K.
\]  

(4.7)

We can thus write \( L_\varepsilon = L_0 + \varepsilon L_\ast \) with

\[
L_\ast f = \frac{1}{2} \sum_{|i-j|=1} \nabla V(q_i - q_j) \cdot (\partial_{p_i} - \partial_{p_j}) f = \sum_{|i-j|=1} \nabla V(q_i - q_j) \cdot \partial_{p_i} f,
\]  

(4.8)

So we have

\[
L_\varepsilon u_{i,k}^K = j_{i,k}^K + \varepsilon L_\ast u_{i,k}^K.
\]  

(4.9)
Hence, denoting a path by \( \omega(s) = (\eta(s), \pi(s)) \), we have
\[
\epsilon \int_0^{\epsilon^2 t} j_{i,k}^K(s) \, ds = \epsilon \int_0^{\epsilon^2 t} \left[ L_\epsilon u_{i,k}^K - \epsilon L_\epsilon u_{i,k} \right](\omega_s) \, ds \\
= \left( \epsilon u_{i,k}^K(\omega_s) - \epsilon u_{i,k}(\omega_0) - M_{i,k}^{\epsilon,K}(t) - \epsilon^2 \int_0^{\epsilon^2 t} L_\epsilon u_{i,k}^K(\omega_s) \, ds \right),
\]
where we have introduced the centered martingale
\[
M_{i,k}^{\epsilon,K}(t) := \epsilon u_{i,k}^K(\omega_s) - \epsilon u_{i,k}(\omega_0) - \epsilon \int_0^{\epsilon^2 t} L_\epsilon u_{i,k}^K(\omega_s) \, ds.
\]
Due to the property that \( u_{i,k} = -u_{i,k} \) we have \( M_{i,k}^{\epsilon,K} = -M_{k,i}^{\epsilon,K} \) and the same for all the derived martingales.

The quadratic variations of \( M_{i,k}^{\epsilon,K} \) is given by
\[
\langle [M_{i,k}^{\epsilon,K}, M_{i',k'}^{\epsilon,K}] \rangle(t) = 2\sigma^2 \sum_{j \in \Lambda} \epsilon^2 \int_0^{\epsilon^2 t} (X_j u_{i,k}^K)(X_j u_{i',k'}^K)(\omega_s) \, ds \\
= 2\sigma^2 \sum_{j \in \{i,k\} \cap \{i',k'\}} \epsilon^2 \int_0^{\epsilon^2 t} \xi_K^2(X_j u_{i,k})(X_j u_{i',k'})(\omega_s) \, ds.
\]

In order to close the evolution equations, as \( \epsilon \to 0 \), we need to prove that
\[
\lim_{\epsilon \to 0} \mathbb{E}_m^\epsilon \left[ \epsilon^2 \int_0^{\epsilon^2 t} \left[ L_\epsilon u_{i,k}^K(\omega_s) - \mu_{\omega_0}(L_\epsilon u_{i,k}^K) \right] \, ds \right]^2 = 0
\]
and that
\[
\lim_{\epsilon \to 0} \mathbb{E}_m^\epsilon \left[ \epsilon^2 \int_0^{\epsilon^2 t} \xi_K^2 \left[ (X_j u_{i,k})(X_j u_{i',k'})(\omega_s) - \mu_{\omega_0}(X_j u_{i,k})(X_j u_{i',k'}) \right] \, ds \right]^2 = 0
\]
These are consequence of Lemma 7.4 and the following lemma:

**Lemma 4.2.** Let \( f(\omega) \) be a function in \( L^2(m_0) \) such that \( \mu_\omega(f) = 0 \) for all \( \omega \in \mathbb{R}^{[1]} \), then
\[
\lim_{\epsilon \to 0} \mathbb{E}_m^\epsilon \left[ \epsilon^2 \int_0^{\epsilon^2 t} f(\omega_s) \, ds \right]^2 = 0.
\]

**Proof.** By using Jensen’s inequality and stationarity, it is enough to prove that
\[
\lim_{T \to \infty} \lim_{\epsilon \to 0} \mathbb{E}_m^\epsilon \left( \left[ \frac{1}{T} \int_0^T f(\omega_s) \, ds \right]^2 \right) = 0
\]
Since \( \lim_{\epsilon \to 0} \mathbb{E}_m^\epsilon = \mathbb{E}_m^0 \), i.e. the expectation with respect to the dynamics of the non-interacting oscillators starting with the product of canonical measures \( m_0 \), which are convex combination of the microcanonical ones. Then
the result follows by the ergodicity of the dynamics of the single oscillators.

So far we have obtained that

$$\lim_{\varepsilon \to 0} \mathbb{E}^\varepsilon_m \left( \varepsilon^2 \int_0^{\varepsilon^{-2}t} \left( \varepsilon^{-1} j_{i,k}(s) - \mu_{\mathcal{E}_0(\omega)}(L_* u_{i,k}^K) \right) ds - \hat{M}^\varepsilon_{i,k}(t) \right)^2 = 0,$$

(4.15)

where the martingales $\hat{M}^\varepsilon_{i,k}$ have quadratic variation given by

$$\langle \langle \hat{M}^\varepsilon_{i,k}, \hat{M}^\varepsilon_{i',k'} \rangle \rangle(t) = 2\sigma^2 \sum_{j \in \{i,k\} \cap \{i',k'\}} \xi_\varepsilon(\mathcal{E}_0(s))^2 \mu_{\mathcal{E}_0(s)}((X_j u_{i,k})(X_j u_{i',k'})).$$

(4.16)

Next, we remove the cutoff on the energies. Observe that

$$L_* u_{i,k}^K = \xi_K L_* u_{i,k} + u_{i,k} L_* \xi_K,$$

which, writing $\xi_\varepsilon^{(j)}(a)$ for $\partial_{a_j} \xi_\varepsilon(a)$, implies

$$\mu_\varepsilon(L_* u_{i,k}^K) = \xi_K(a) \mu_\varepsilon(L_* u_{i,k}) + 2 \sum_{|i-j|=1} \xi_\varepsilon^{(j)}(a) \mu_\varepsilon(u_{i,k} \nabla V(q_i - q_j) \cdot p_j)
= \xi_K(a) \mu_\varepsilon(L_* u_{i,k}) + 2 \xi_\varepsilon^{(i)}(a) \mu_\varepsilon(u_{i,k} \nabla V(q_i - q_k) \cdot p_k)
= \xi_K(a) \mu_\varepsilon(L_* u_{i,k}) + \xi_\varepsilon^{(i)}(a) \gamma^2 (a_i, a_k)$$

Since $m_\varepsilon(\mathcal{E}_j \geq K)$ is exponentially small in $K$, and $\gamma^2$ does not grow faster than polynomially, we have

$$\sup_{\varepsilon} \mathbb{E}^\varepsilon_m \left( \varepsilon^2 \int_0^{\varepsilon^{-2}t} \left( \mu_{\mathcal{E}_0(\omega)}(L_* u_{i,k}^K) - \xi_K(\mathcal{E}_0(\omega)) \mu_{\mathcal{E}_0(\omega)}(L_* u_{i,k}) \right) ds \right)^2 \leq C \sup_{\varepsilon} \sum_j m_\varepsilon(\gamma^2 (\mathcal{E}_0^i, \mathcal{E}_0^k) 1_{[\mathcal{E}_j(\mathcal{E}_i, \mathcal{E}_k)]}) K^2 \to K \to \infty \to 0.$$

Since the above limit and (4.15) are uniform in $\varepsilon$, and since $X_j u_{i,k}$ is in $L^2(m_\varepsilon)$, we can take the limit $K \to \infty$ in (4.15) and obtain

$$\lim_{\varepsilon \to 0} \mathbb{E}^\varepsilon_m \left( \varepsilon \int_0^{\varepsilon^{-2}t} j_{i,k}(s) ds - \varepsilon^2 \int_0^{\varepsilon^{-2}t} \mu_{\mathcal{E}_0(\omega)}(L_* u_{i,k}) ds + M^\varepsilon_{i,k}(t) \right)^2 = 0,$$

(4.17)

where $M^\varepsilon_{i,k}(t)$ is a martingale whose quadratic variation has the expression given by (4.16) with $\xi_K$ substituted by 1.

**Lemma 4.3.** For each $a_k, q_i, p_i$ setting

$$\bar{u}_i(q_i, p_i) := \int u_{k,i}(q_k, p_k, q_i, p_i) \mu_{a_k}(dq_k, dp_k)$$
Accordingly, by (4.16) and Lemma 4.3, In fact, again by the product structure, the above is a function of \( u \) holds true

First of all note that, due to the symmetry between

Thus, setting \( \bar{V}(q) = \int V(q_i - q_k) \mu_{a_k}(dq_k, dp_k) \)

Integrating the above we have

Next, since \( \bar{V} \) of the above equation are of the form \( \bar{u}_i = \bar{V} + f(q) \) for some function \( f \). Next, since \( \bar{u}_i \) is of zero average by construction, \( f(q) = -\mu_{\bar{V}}(q) \).

Thus, if \( l \notin \{ i, k \} \) we have

due to the antisymmetry of \( \partial_{p_l} \bar{u}_i \) with respect to \( p_i \) established in Lemma 4.3. From this follows

In fact, again by the product structure, the above is a function of \( a_i, a_k \) only. It is also convenient to define

Accordingly, by (4.16) and Lemma 4.3

\[
\langle (\hat{M}_{i,k}^\varepsilon, \hat{M}_{j,k}^\varepsilon) \rangle(t) = 2\sigma^2 \sum_{j \in \{ i, k \}} \mu_{\bar{V}}(t) \left[ (X_j u_{i,k})^2 \right] \left( \delta_{i=i', k=k'} - \delta_{i=k', k=i'} \right)
\]
Lemma 4.4. 

\[ \lim_{\varepsilon \to 0} \mathbb{E}_{m_\varepsilon} \left| \int_0^t \left( \alpha(\mathcal{E}_i^0(\omega_{\varepsilon^{-2}s}), \mathcal{E}_k^0(\omega_{\varepsilon^{-2}s})) - \alpha(\mathcal{E}_i^\varepsilon(s), \mathcal{E}_k^\varepsilon(s)) \right) \, ds \right|^2 = 0 \]

and similarly for \( \gamma^2 \).

Proof. By stationarity and Schwarz inequality we have

\[ \mathbb{E}_{m_\varepsilon} \left| \int_0^t \left[ \alpha(\mathcal{E}_i^0(\omega_{\varepsilon^{-2}s}), \mathcal{E}_k^0(\omega_{\varepsilon^{-2}s})) - \alpha(\mathcal{E}_i^\varepsilon(s), \mathcal{E}_k^\varepsilon(s)) \right] \, ds \right|^2 \leq t m_\varepsilon \left( |\alpha(\mathcal{E}_i^0, \mathcal{E}_k^0) - \alpha(\mathcal{E}_i^\varepsilon, \mathcal{E}_k^\varepsilon)|^2 \right) \]

Since we prove in Lemmata 8.1, 8.2 that \( \alpha(a_1, a_2) \) is uniformly Lipschitz in \( \mathbb{R}^2 \) the result follows by elementary arguments. \( \square \)

Applying Lemma 4.4 to (4.17) and (4.20) we obtain that

\[ \lim_{\varepsilon \to 0} \mathbb{E}_{m_\varepsilon} \left( \left| \int_0^{\varepsilon^{-2}t} j_{i,k}(s) \, ds - \int_0^t \alpha(\mathcal{E}_i^\varepsilon(s), \mathcal{E}_k^\varepsilon(s)) \, ds + \mathcal{M}_{i,k}^\varepsilon(t) \right|^2 \right) = 0, \quad (4.21) \]

which, remembering (4.19), yields the wanted result in equilibrium. Our general claim (4.4) follows by Schwarz inequality.

5. Hypoellipticity and regularity on energy shells

We start here by studying the single site dynamics. Here \( p = (p^1, p^2), \ q = (q^1, q^2) \) will be the coordinates. We will use \( L \) to designate the generator (2.1) for \( \varepsilon = 0 \) and \( \Lambda \) consisting of only one site. Since \( L \) preserves the energy, we can look at its action on each energy surface \( \Sigma_a = \{(q,p) \in \mathbb{R}^4 : \frac{|p|^2}{2} + U(q) = a\}, \quad a > 0. \)

Lemma 5.1. For each \( a > 0 \) the operator \( L \) is hypoelliptic on \( \Sigma_a \).

Proof. We must study of the Lie algebra generated by the vector fields

\[ C_0 = X = Jp \cdot \partial_p, \]
\[ B = A_0 = p \cdot \partial_q - \nabla U(q) \cdot \partial_p, \quad (5.1) \]

We obtain

\[ C_1 = [C_0, B] = Jp \cdot \partial_q + J \nabla U(q) \cdot \partial_p, \quad (5.2) \]
\[ [C_1, B] = 2J \nabla U(q) \cdot \partial_q - \{D^2 U(q)J + JD^2 U(q)\} p \cdot \partial_p. \quad (5.3) \]

By our assumption on \( U \)

\[ D^2 U(q) = 4U'''(q) \, q \otimes q + 2U'(q)1. \quad (5.4) \]

Since

\[ J(q \otimes q) + (q \otimes q) J = |q|^2 J, \]
we have
\[ D^2 U(q) J + JD^2 U(q) = 4\{\nabla'' U(q)|q|^2 + \nabla' U\} J =: \zeta(q) J. \]

Finally we define \( C_2 \) by the relation
\[ [C_1, B] = 4\nabla' U(q) Jq \cdot \partial_q - 4\{\nabla'' U(q)|q|^2 + \nabla' U\} Jp \cdot \partial_p =: 2C_2 - \zeta(q) C_0. \]

Observe that, setting \( N = (|p|^2 + |\nabla U(q)|^2)^{1/2} \), the vectors
\[ Z_1 = \frac{C_1}{N}, \quad Z_0 = \frac{B}{N}, \quad Z_2 = \frac{C_2 - C_0}{N} \]
form an orthonormal base of the tangent space of \( \Sigma_a \), hence the Lie Algebra generated by \( \{C_0, B\} \) spans the space of any energy shell \( \Sigma_a \). This concludes the proof of the hypoellipticity of \( L \). \( \square \)

By the above results trivially follows the claimed hypoellipticity.

**Lemma 5.2.** For each \( \Lambda \subset \mathbb{Z}^d \), \( a_i > 0 \), \( i \in \Lambda \) the operator \( L_{0, \Lambda} \) is hypoelliptic on \( \Sigma_\mathbf{a} \).

By Hörmander theorem \cite{Hörmander1967} hypoellipticity implies that if there exists a solution \( u \) for the equation
\[ L_{0, \Lambda} u = g \] (5.6)
where \( g \) is a \( C^\infty \) function when restricted to any energy shell, then also \( u \) is \( C^\infty \) when restricted to any energy shell.

### 6. Hypocoercivity

We will prove the existence of the solution of equation (4.6) by proving a spectral gap for the generator \( L_0 \) on each energy shell \( \Sigma_\mathbf{a} \) in a proper Hilbert space. More precisely we consider the Hilbert spaces determined by the scalar products
\[ \langle h, g \rangle_{\mathcal{H}^1_\mathbf{a}} := |\Lambda| \langle h, g \rangle_\mathbf{a} + \sum_{l \in \Lambda} D_{\mathbf{a}, l}(h, g) \]
\[ D_{\mathbf{a}, i}(h, g) := \sum_{k=0}^2 \langle C_{k,i} h, C_{k,i} g \rangle_\mathbf{a} + \langle B_i h, B_i g \rangle_\mathbf{a}, \] (6.1)
where \( \langle h, g \rangle_\mathbf{a} = \int_{\Sigma_\mathbf{a}} h g d\mu_\mathbf{a} \) and the \( C_{k,i}, B_i \) are the vector fields defined in section 5 relative to the particle \((q_l, p_l)\).

By a slight abuse of notations we will use \( P_0^\mathbf{a} \) to denote the strongly continuous semigroup generated by \( L_0 \) both in \( L^2 \) and \( \mathcal{H}^1_\mathbf{a} \) for each \( \mathbf{a} \).

Note that the above norm is equivalent to the standard Sobolev space \( \mathcal{H}_\mathbf{a} \) on the Riemannian surface \( \Sigma_\mathbf{a} \) where the Riemannian structure has been rescaled to have the diameter of each \( \Sigma_{a_i} \) equal one independently of the \( a_i \). More precisely, there exists \( c > 0 \) such that
\[ c\|f\|_{\mathcal{H}_\mathbf{a}} \leq \|f\|_{\mathcal{H}^1_\mathbf{a}} \leq c^{-1}|\Lambda| \|f\|_{\mathcal{H}_\mathbf{a}} \] (6.2)
Accordingly, Theorem 2 is a direct consequence of the following.

**Proposition 6.1.** The semigroup $P_t^0$ is contractive in $L^2$. In addition, for each $\Lambda \subset \mathbb{R}^d$, $|\Lambda| < \infty$, there exists $C, \tau > 0$ such that for all $\underline{a} \in (0, \infty)^\Lambda$ and smooth function $f$, such that $\mu_{\underline{a}}(f) = 0$, holds

$$\|P_t^0 f\|_{\mathcal{H}_1^{\Lambda}} \leq C e^{-\tau t} \|f\|_{\mathcal{H}^{\Lambda}_1}.$$  

**Proof.** The contractivity in $L^2$ follows by

$$\frac{d}{dt} \|P_t^0 f\|_2^2 \leq -2 \sum_{\Lambda} (C_{0,\lambda} P_t^0 f, C_{0,\lambda} P_t^0 f)_2 \leq 0.$$  

To prove the second part of the theorem we use the results of Appendix B. Note that for all smooth $h, g, \varphi$ we can write

$$m_0(\varphi(E) \mu_{\underline{a}}(h C_0 g)) = m_0(\varphi(E) h C_0 g) = -m_0(\varphi(E) g C_0 h),$$

hence it must be $\mu_{\underline{a}}(h C_0 g) = -\mu_{\underline{a}}(C_0 h \cdot g)$, and the same for $B$. We can thus use Lemma B.1 applied to, for each $l \in \Lambda$, a scalar product $\langle \cdot, \cdot \rangle_{\mathcal{H}_1^{\lambda l}}$ defined in (6.2) using the operators $C_{0,\lambda}, B_l$. By Lemma B.1 such a scalar product is equivalent to the one

$$\langle h, g \rangle_{\mathcal{H}_1^{\Lambda}} := \langle h, g \rangle_{\mathcal{H}_1^{\Lambda}} + \mathcal{D}_{\mathcal{H}_1^{\Lambda}}(h, g).$$  

Then Lemma B.2 states, that

$$\langle h, L_{(l)} h \rangle_{\mathcal{H}_1^{\lambda l}} \leq -\tau \sigma^2 \left( \mathcal{D}_{\mathcal{H}_1^{\lambda}}(h, h) + \mathcal{D}_{\mathcal{H}_1^{\lambda}}(C_0 h, C_0 h) \right) \leq -\tau \sigma^2 \mathcal{D}_{\mathcal{H}_1^{\lambda}}(h, h). \quad (6.3)$$

where $L_{(l)}$ is the generator of the dynamics of the isolated atom $l$, i.e. $L_0 = \sum_{l \in \Lambda} L_{(l)}$.

The last piece of information we need is given by the following Poincaré inequality.

**Lemma 6.2.** There exist a constant $K_P > 0$ such that for each $\underline{a}$, if $f \in \mathcal{H}_1^{\Lambda}$, such that $\mu_{\underline{a}}(f) = 0$, then

$$\|f\|_{\mathcal{H}_1^{\Lambda}}^2 \leq K_P \sum_{l \in \Lambda} \mathcal{D}_{\mathcal{H}_1^{\Lambda}}(f, f).$$

**Proof.** By the change of variable introduced in section C one can use the Poincaré inequality for the sphere, for one particle. After that

$$\|f\|_{\mathcal{H}_1^{\Lambda}}^2 \leq \|f - \mu_{\underline{a}}(f)\|_{\mathcal{H}_1^{\Lambda}}^2 + \|\mu_{\underline{a}}(f)\|_{\mathcal{H}_1^{\Lambda}}^2 \leq K_P \mathcal{D}_{\mathcal{H}_1^{\Lambda}}(f, f) + \|\mu_{\underline{a}}(f) - \mu_{\underline{a}, \underline{a}_j}(f)\|_{\mathcal{H}_1^{\Lambda}}^2 + \|\mu_{\underline{a}, \underline{a}_j}(f)\|_{\mathcal{H}_1^{\Lambda}}^2$$

iterating the argument yields the result. \qed
It follows from (6.3) and Lemma 6.2 that
\[
\sum_l \langle h, \sum'_{l'} \langle h, L_{l'} h \rangle_a \rangle_l \leq -\tau \sigma^2 \sum_l D_a(h, h)
\]
\[
\leq -\frac{\tau \sigma^2}{1 + K_P |\Lambda|} \| h \|_{\mathcal{H}_{a}^1}^2
\]

(6.4)
Accordingly, for each \( \mathbf{a} \) and \( h \in \mathcal{H}_{a}^1 \), such that \( \mu_{\mathbf{a}}(h) = 0 \), we have
\[
\frac{d}{dt} \langle P^t_{\mathbf{0}} h, P^t_{\mathbf{0}} h \rangle_a \leq 2 \langle P^t_{\mathbf{0}} h, L_0 P^t_{\mathbf{0}} h \rangle_a
\]
\[
\leq -\frac{2 \tau \sigma^2}{1 + K_P |\Lambda|} \| P^t_{\mathbf{0}} h \|_{\mathcal{H}_{a}^1}^2
\]
\[
\leq -2 \tau \sigma^2 \sum_l D_a(h, h)
\]

where, in the last line, we have used first (6.3) and then Lemma B.1. This means that
\[
\langle P^t_{\mathbf{0}} h, P^t_{\mathbf{0}} h \rangle_a \leq \langle h, h \rangle_a e^{-2 \tau \sigma^2 t}
\]

and, by the equivalence of the norms, there exists \( C, \tau' > 0 \) such that
\[
\| P^t_{\mathbf{0}} h \|_{\mathcal{H}_{a}^1} \leq C e^{-\tau' \sigma^2 t} \| h \|_{\mathcal{H}_{a}^1}.
\]

(6.5)

7. Global regularity

Next, we need regularity of the solution of (5.6) also in directions not tangent to the energy surfaces, provided \( g \) is smooth. Again we work first with only one particle.

7.1. The transversal direction. A natural direction would be given by the normal vector to the energy surfaces
\[
Z_3 = \frac{p \cdot \partial_p + \nabla U(q) \cdot \partial_q}{N},
\]

(7.1)
but, due to the anharmonicity of the potential \( U \), it turns out to be more useful to work with the vector field
\[
Y := \frac{1}{2 \sqrt{\mathcal{C}_0(q, p)}} \left\{ \frac{1}{2} p \cdot \partial_p + \frac{U(q)}{\nabla U(q) \cdot q} q \cdot \partial_q \right\}.
\]

(7.2)
Note that, \( Y \) is a smooth vector field away from zero. Observe that in the harmonic case \( (U(r) = \frac{1}{2} r) \), \( Y \) is parallel to the normal vector field \( Z_3 \).
The reason why we consider $Y$ is the following. A direct computation shows that $Y E_0 = \frac{1}{2} \sqrt{E_0(q,p)}$, hence the vector field is transversal to the energy surface. In addition,

$$[Y, C_0] = 0,$$

$$[Y, L] E_0 = -\frac{1}{2} L \sqrt{E_0(q,p)} = 0. \quad (7.3)$$

That is, the commutators are vector fields tangent to the constant energy surface. Note that since $U''(0) > 0$, we can write $\frac{U(q)}{q \sqrt{U(q)}} = \frac{1}{2} + \kappa(|q|^2)$, for a smooth function $\kappa$ such that $\kappa(0) = 0$. An explicit computation yields

$$[L, Y] = \frac{4 \left( \frac{1}{2} + \kappa \right) U'' q^2 + 2 \kappa U'}{2 \sqrt{E_0(q,p)}} q \cdot \partial_p + \frac{1}{2 \sqrt{E_0(q,p)}} p \cdot [2 \kappa' q \otimes q + \kappa 1] \partial_q. \quad (7.4)$$

**Remark 7.1.** Note that the vector field $(E_0(q,p))^{-\frac{1}{2}} [L, Y]$ is smooth on all $\mathbb{R}^{2\nu}$, in particular even at zero. This fact will play a crucial role in the following.

### 7.2. Transversal regularity.

The basic idea to prove regularity is to notice that if $Lu = g$, then one expects that $LYu = [Y, L]u + Yg$. Unfortunately, we have only $L^2$ bounds for the right hand side of the above equations, in particular we do not know if it belongs to $H^1$. Hence, a priori, we do not know if such an equation has a solution in $H^1$. To overcome such a difficulty several direct strategies are possible. For example one could try to prove a spectral gap in Sobolev spaces of higher regularity or to prove that the semigroup maps $L^2$ functions in $H^1$ functions. Unfortunately, such results (even if probably true) are not so easy to prove, in particular the related algebra becomes quickly very messy. Due to this state of affair we take a bit more indirect route that, without proving explicit bounds, suffices to prove the smoothness. To this end it is convenient to work in coordinates in which all the energy surfaces can be naturally identified.

It is then natural to transform equation (4.6) in the following coordinates. Let $S^3 := \{ x \in \mathbb{R}^4 : \|x\| = 1 \}$ and $M = \mathbb{R} \times S^3 \subset \mathbb{R} \times \mathbb{R}^2 \times \mathbb{R}^2$, $M_+ = (0, \infty) \times S^3 \subset M$. Let $\Psi: \mathbb{R}^{4[A]} \setminus \{0\} \to M_+^{[A]} \subset \mathbb{R}^{5[A]}$ be defined by

$$\Psi(q,p)_i = \left( \sqrt{\frac{p_i^2}{2} + U(q_i)}, \frac{q_i \sqrt{U(q_i)}}{|q_i| \sqrt{\frac{p_i^2}{2} + U(q_i)}}, \frac{p_i}{\sqrt{p_i^2 + 2U(q_i)}} \right) =: (r_i, \xi_i, \eta_i) \quad (7.5)$$

The needed properties of this change of variables are detailed in section C.
The first key observation is that the problem is now regularized at zero energy. Indeed,
\[ j_{i,k}(\xi, \eta) = j_{i,k} \circ \Psi^{-1}(\xi, \eta) \]
\[ = \frac{1}{\sqrt{2}} V \left( r_i \theta(r_i^2 \xi^2) \xi_i - r_k \theta(r_k^2 \xi^2_k) \xi_k \right) \cdot (r_i \eta_i + r_k \eta_k). \]

**Remark 7.2.** Note that \( j_{i,k} \) extends naturally to a smooth function on \( M^A \). Indeed if \( r_i < 0 \), then we can set \( j_{i,k}(\xi', \eta') = j_{i,k}(\xi', \eta') \) where \( r_j = r_j' \), \( \xi_j = \xi_j' \), \( \eta_j = \eta_j' \) for all \( j \neq i \) and \( r_i = -r_i' \), \( \xi_i = -\xi_i' \), \( \eta_i = -\eta_i' \), and the same for \( k \).

Note that for each function \( \tilde{f} \in C^\infty(M^{|A|}, \mathbb{R}) \) holds \( C_0(\tilde{f} \circ \Psi) = (\tilde{C}_0 \tilde{f}) \circ \Psi \).

It follows that the equation \( L_0 u = \tilde{g} \) on \( (\mathbb{R}^4 \setminus \{0\})^{|A|} \) is transformed in the equation \( \tilde{L}_0 \tilde{f} = \tilde{g} \) on \( \Psi((\mathbb{R}^4 \setminus \{0\})^{|A|}) \subset M \) where \( \tilde{L}_0 = \sum_i \sigma^2 \tilde{C}^2_{0,i} + \tilde{B}_l \) and \( \tilde{f} = f \circ \Psi^{-1} \), \( \tilde{g} = g \circ \Psi^{-1} \).

It is then natural to study the equation on \( M \)
\[ \tilde{L}_0 \tilde{u}_{i,k} = \tilde{j}_{i,k}. \tag{7.6} \]

By the previous discussion the solution of \( (4.6) \) in \( (\mathbb{R}^4 \setminus \{0\})^{|A|} \) is given by \( \tilde{u}_{i,k} = \tilde{u}_{i,k} \mid_{M^A} \circ \Psi \).

The problem of the transversal smoothness is then reduced to studying the smoothness of \( \tilde{u}_{i,k} \) in \( r \) (see Lemma C.1).

**Lemma 7.3.** For each \( i, k \), the functions \( \tilde{u}_{i,k} \in C^\infty(M^{|A|}, \mathbb{R}). \)

**Proof.** We can consider \( \tilde{C}_i, \tilde{B}_i \) as vector fields on \( S^{|A|} \). Accordingly, we can define for each \( r \in \mathbb{R}^{|A|} \)
\[ \tilde{L}_0(r) = \sum_{i \in A} \left\{ \sigma^2 \tilde{C}^2_{0,i} + \frac{\sqrt{2}}{\theta(r_i^2 \xi_i^2)} \left[ \tilde{B}_i^0 + \Gamma(r_i^2 \xi_i^2) \tilde{B}_i^1 \right] \right\}. \]

Then, setting \( \tilde{j}_{i,k,l}(\xi, \eta) := \tilde{j}_{i,k}(\xi, \eta) \) and considering the equation on \( S^{|A|} \)
\[ \tilde{L}_0(r) \tilde{u}_{i,k,l} = \tilde{j}_{i,k,l}. \tag{7.7} \]
it follows \( \tilde{u}_{i,k,l}(r, \xi, \eta) = \tilde{u}_{i,k,l}(\xi, \eta). \) By the previous section we know that, for each \( r, \tilde{u}_{i,k,l} \in C^\infty(S^{|A|}, \mathbb{R}), \) thus the differentiability boils down to show that the solution of \( (7.7) \) are differentiable with respect to the parameter \( r \).

Let us fix \( r \) and consider the equation\(^2\)
\[ \tilde{L}_0(r) \tilde{u}_{i,k,l} = \tilde{g}_{i,k,l,l}(\xi, \eta) \tag{7.8} \]

\(^2\)See C.2 for the definition of \( \tilde{B}_i^1 \).

\(^3\)This is nothing else than the formal derivative of \( (7.7) \) with respect to \( r_i \).
where \( \tilde{g}_{i,k,l} (\xi, \eta) = ([\tilde{Y}_l, \tilde{L}_0] \tilde{u}_{i,k}) (\xi, \eta) + (\tilde{Y}_{ij,k}) (\xi, \eta) \). Clearly \( \tilde{g}_{i,k,l} \in C^\infty (S^3[A], \mathbb{R}) \) for each choice of \( i, k, l, \tilde{r} \), thus \( \tilde{v}_{i,k,l} \in C^\infty (S^3[A], \mathbb{R}) \). We claim that \( \partial_{\tilde{r}_i} \tilde{u}_{i,k} = \tilde{v}_{i,k,l} \), let us prove it.

For each, small, \( h \in \mathbb{R}^A \) we can write
\[
\tilde{L}_0 (r + h) \left[ \tilde{u}_{i,k,l} + \tilde{u}_{i,k,l} - \sum_l \tilde{v}_{i,k,l} h_l \right] = \tilde{v}_{i,k,l} + \tilde{v}_{i,k,l} - \sum_l \tilde{g}_{i,k,l} h_l - [\tilde{L}_0 (r + h) - \tilde{L}_0 (r)] \tilde{u}_{i,k,l}.
\]

An explicit computation shows that the \( \mathcal{H}^1 \) norm of the right hand side is bounded by a constant (depending in an unknown manner form \( y \) times \( o(\| h \|) \)). The by Proposition 6.1 the differentiability of \( u_{i,k} \) follows.

Note that in the above argument the only relevant property of \( \tilde{v}_{i,k,l} \) is the smoothness on \( S^3[A] \) of itself and of its derivatives with respect to \( Y_l \). Since a direct computation shows that the same properties are enjoyed by \( \tilde{g}_{i,k,l} \), the Lemma follows by iterating the above argument.

**Lemma 7.4.** It holds true \( L_* u_{i,k} \in L^2_{\text{loc}} (\mathbb{R}^8, m_0) \).

**Proof.** Recall the definition of \( L_* \) given by (4.8). Then all we need to prove is that \( \frac{\partial y}{\partial \rho_l} \) is in \( L^2_{\text{loc}} (\mathbb{R}^8, m_0) \). It follows from straightforward calculations that the singularities at 0 of \( \frac{\partial y}{\partial \rho_l} \) are \( m_0 \) integrable. \( \Box \)

---

### 8. Structure and regularity of \( \gamma^2 \) and \( \alpha \)

Let \( u = u_{1,2} \) the solution of the Poisson equation (4.6). Then, by (4.15) and (D.6), we write
\[
\gamma^2 (a_1, a_2) = \mu_{a_1} a_2 (j_{1,2} u_{1,2}) = \frac{16 \omega^2 a_1 a_2}{Z(a_1) Z(a_2)} \int_{S^3 \times S^3} d\sigma (\xi_1, \eta_1) d\sigma (\xi_2, \eta_2) \Omega (\sqrt{a}, \xi, \eta).
\]
where \( \sigma \) is the uniform probability measure on the sphere \( S^3 \) and
\[
\Omega (r, \xi, \eta) := \frac{(j_{1,2} u_{1,2}) (\Psi^{-1} (r_1, \xi_1, \eta_1), \Psi^{-1} (r_2, \xi_2, \eta_2))}{U (\rho (r_1^2 \xi_1^2)) U (\rho (r_2^2 \xi_2^2))} = \frac{\tilde{j}_{1,2} (r_1, \xi_1, \eta_1, r_2, \xi_2, \eta_2)}{U (\rho (r_1^2 \xi_1^2)) U (\rho (r_2^2 \xi_2^2))}.
\]

---

\(^4\)The smoothness on \( S^3[A] \) follows from the smoothness of \( \tilde{u}_{i,k} \), the differentiability with respect to \( Y_l \) follows by the smoothness of \( \tilde{j}_{i,k,l} \) and the fact that \( \tilde{Y}_l [Y_l, \tilde{L}_0] \tilde{u}_{i,k} = \tilde{Y}_l \tilde{u}_{i,k} + [\tilde{Y}_l, \tilde{L}_0] \tilde{u}_{i,k} + \tilde{Y}_l \tilde{L}_0 \tilde{u}_{i,k,l} \). Since it is easy to check that, given any vector \( Z \) tangent to \( M[A] \), \( [\tilde{Y}_l, Z] \) is still tangent to \( M \).
Lemma C.1, we have it follows then that the integral on the right hand side of (8.1) is an even smooth function of \( \gamma \) provided \( \gamma = 0 \).

Lemma 8.1. For any nearest neighbor couple \( \{i, k\} \):

\[
e^{\mathcal{U}(\mathcal{A})} (\partial_{a_i} - \partial_{a_k}) (e^{-\mathcal{U}(\mathcal{A})} \gamma^2 (a_i, a_k)) = \alpha (a_i, a_k).
\]

with \( \mathcal{U}(\mathcal{A}) = -\sum_j \log \mathcal{Z}(a_j) \).

Proof. By Lemma D.1 follows

\[
\mu_a (g \partial_p f) = e^{-\mathcal{U}} \partial_a \{ e^{\mathcal{U}} \mu_a (g p f) \}
\]

provided \( g \) does not depend on \( p \). Thus, since \( u_{i,k} \) is locally bounded,

\[
\alpha (a_i, a_k) = \mu_a (\nabla V (q_i - q_k) (\partial_{p_i} u_{j,i,k} - \partial_{p_k} u_{j,i,k})) = e^{-\mathcal{U}} \partial_{a_i} \{ e^{\mathcal{U}} \mu_a (\nabla V (q_i - q_k) p_{j,i,k}) \} - e^{-\mathcal{U}} \partial_{a_k} \{ e^{\mathcal{U}} \mu_a (\nabla V (q_i - q_k) p_{j,i,k}) \}.
\]

To continue, notice that for each smooth \( \varphi \),

\[
\int e^{-\sum_{i} a_i} \prod_{l} \mathcal{Z}(a_l) \varphi (a) \mu_a (p_{l \nabla V (q_i - q_k) u_{j,i,k}})
\]

\[
= \mathbb{E}_{\mathcal{M}_0} (\varphi (\mathcal{E}^0) p_{l \nabla V (q_i - q_k) u_{j,i,k}})
\]

\[
= -\mathbb{E}_{\mathcal{M}_0} (\varphi (\mathcal{E}^0) u_{i,k} L_{0} V (q_i - q_k)) + \mathbb{E}_{\mathcal{M}_0} (\varphi (\mathcal{E}^0) p_{k \nabla V (q_i - q_k) u_{j,i,k}})
\]

\[
= -\mathbb{E}_{\mathcal{M}_0} (\varphi (\mathcal{E}^0) V (q_i - q_k) j_{i,k}) + \mathbb{E}_{\mathcal{M}_0} (\varphi (\mathcal{E}^0) p_{k \nabla V (q_i - q_k) u_{j,i,k}})
\]

\[
= \int e^{-\sum_{i} a_i} \prod_{l} \mathcal{Z}(a_l) \varphi (a) \mu_a (p_{k \nabla V (q_i - q_k) u_{j,i,k}}),
\]

where we used the antisymmetry of \( j_{i,k} \) with respect to \( p \). Hence

\[
\mu_a (p_{l \nabla V (q_i - q_k) u_{j,i,k}}) = \mu_a (p_{k \nabla V (q_i - q_k) u_{j,i,k}})
\]

(8.3) \( m_0 \)-almost surely. Accordingly,

\[
\alpha (a_i, a_k) = \frac{1}{2} e^{-\mathcal{U}} (\partial_{a_i} - \partial_{a_k}) \{ e^{\mathcal{U}} \mu_a (\nabla V (q_i - q_k) (p_i + p_k) u_{j,i,k}) \}
\]

\[
= e^{-\mathcal{U}} (\partial_{a_i} - \partial_{a_k}) \{ e^{\mathcal{U}} (j_{i,k} u_{j,i,k}) \}.
\]
The result follows since
\[
\mu_a(j_{i,k}u_{i,k}) = \mu_a(u_{i,k}L_0 u_{i,k}) = \sigma^2 \mu_a(u_{i,k}Su_{i,k}) = -\sigma^2 \sum_{j=i,k} \mu_a((X_j u_{i,k})^2) = -\gamma^2(a_i, a_k).
\]

We can rewrite (8.2) as
\[
\alpha(a_i, a_k) = (\partial_{a_i} - \partial_{a_k})\gamma^2(a_i, a_k) + \left(\frac{Z'(a_i)}{Z(a_i)} - \frac{Z'(a_k)}{Z(a_k)}\right)\gamma^2(a_i, a_k). \tag{8.4}
\]

Since \(Z'(a)/Z(a) \sim a^{-1}\), the regularity of \(\alpha\) follows from the one of \(\gamma^2\), if we can prove that \(\gamma^2 \sim a_1 a_2\).

**Lemma 8.2.** There exists \(G \in \mathcal{C}^\infty([0, \infty)^2, \mathbb{R})\) such that, for each \(a_1, a_2 \geq 0\)
\[
\gamma^2(a_1, a_2) = a_1 a_2 G(a_1, a_2) \geq 0,
\]
and furthermore \(\alpha(0, a) \geq 0\) for all \(a \geq 0\).

**Proof.** Observe that fixing the energy of the first particle \(E_1(q_1, p_1) = 0\), it implies that \(q_1 = p_1 = 0\). So defining \(\hat{u}(q, p) = u_{1,2}(0, 0, q, p)\), it solves on \(\mathbb{R}^2\) the equation \(L \hat{u} = \hat{j}\), where \(L\) is the generator of the dynamics of a single isolated atom and \(\hat{j} = -\frac{1}{2} p \cdot \nabla V(q) = L^* V\).

By the smoothness of \(\gamma^2\) it follows that
\[
\gamma^2(0, a) = -\mu_a(j \hat{u}) = \mu_a(L^* V \cdot \hat{u}) = \mu_a(V L \hat{u}) = \mu_a(V \hat{j}) = 0
\]
due to the symmetry of \(\mu_a\) with respect to the transformation \(p \to -p\). The structure of \(\gamma^2\) follows then by the symmetry and smoothness of \(\gamma^2\). The positivity follows by
\[
\gamma^2 = -\mu_{a_1, a_2}(L_0 u \cdot u) = \sigma^2 \mu_{a_1, a_2}((X_1 u)^2 + (X_2 u)^2).
\]
By (8.4) and (D.5)
\[
\alpha(a, 0) = 2aG(a, 0) \geq 0.
\]

**Appendix A. Commutators**

This appendix collects some formulae concerning commutators for the unperturbed system \((\varepsilon = 0)\), we use the notation of Proposition 6.1. In section 5 we have already computed:
\[
[C_0, B] = (J p \cdot \partial_q + J \nabla U(q) \cdot \partial_p) =: C_1. \tag{A.1}
\]
An explicit computation shows that

\[ [C_1, B] = 4\overline{U}'(q)Jq \cdot \partial_q - 4\{\overline{U}''(q)|q|^2 + \overline{U}'\}Jp \cdot \partial_p \]

\[ = 2C_2 + \zeta(q)C_0 =: 2C_2 + R_2, \quad \text{(A.2)} \]

An explicit calculation shows that

\[ C_2 = \frac{p \cdot J\nabla U}{p^2} B + \frac{p \cdot \nabla U}{p^2} C_1 - \frac{\|\nabla U\|^2}{p^2} C_0. \quad \text{(A.3)} \]

The above formula shows that \( C_2 \), for small \( p \) and large \( q \), is not bounded by \( B, C_0, C_1 \) and, as we will see in the following, this forces us to compute

\[ R_3 = [C_2, B] = -(J\nabla U(q) \cdot D^2U(q)\partial_p + JD^2U(q)p \cdot \partial_q) \]

\[ = -(4\overline{U}''(p,q)Jq + 2\overline{U}' Jp)\partial_q - 4(\overline{U}')^2Jq\partial_p. \]

By using the orthonormal base \( Z_0, Z_1, Z_2 \), defined in (5.3), we have that

\[ R_3 = \sum_{j=0}^{2} \langle R_3, Z_j \rangle Z_j \]

\[ = N^{-2}(R_3, B) + N^{-2}(R_3, C_1)C_1 + N^{-2}(R_3, (C_2 - C_0))C_2 - C_0 \]

\[ = 4N^{-2}\overline{U}''(q,p)Jp,q)B - N^{-2}\left[ 4\overline{U}''(q,p)^2 + 2\overline{U}' p^2 + 8(\overline{U}')^3q^2 \right] C_1 \]

\[ - 8N^{-2}\overline{U}'\overline{U}''(q,p)q^2(C_2 - C_0), \]

and an explicit calculation shows that

\[ \|R_3\|^2 = N^{-2}\left( \left| (R_3, B) \right|^2 + \left| (R_3, C_1) \right|^2 + \left| (R_3, (C_2 - C_0)) \right|^2 \right) \leq K \quad \text{(A.4)} \]

To conclude the \textit{first order} analysis we need to compute some more commutators

\[ ([C_0, C_1]) = -B \]

\[ ([C_0, C_2]) = 0 \]

\[ ([C_1, C_2]) =: \rho C_2 - \beta B \quad \text{(A.5)} \]

with \( \rho \) and \( \beta \) also bounded.

We also need some \textit{second order} commutators:

\[ [B, C_2^2] = C_0 B C_0 - C_0^2 B - C_1 C_0 = -2C_1 C_0 + B \]

\[ [C_1, C_2^2] = C_0 B + B C_0 = 2C_0 B - C_1. \quad \text{(A.6)} \]

\section*{Appendix B. Hypocoercivity estimates}

This appendix contains the core of the hypocoercivity argument. For our purposes it turns out to be more convenient to set it in an abstract setting.

Let \( \mathcal{H}^0 \) be an Hilbert space and \( C_0, B \) be closed operators satisfying the relations (A.1)–(A.6). Assume that \( C_k, B, C_0, BC_0 \) have all a common core \( D_c \). In addition, assume that for each \( h, g \in D_c \) and \( Z \in \{ C_0, B \} \),

\[ \langle h, Z g \rangle = -(Zh, g), \quad \text{(B.1)} \]
where $(\cdot, \cdot)$ is the scalar product of $H^0$. Remark that the various constant that will appear in the results ($\tau, K$ etc.) do not depend on the scalar product $(h, g)$.

We are interested in obtaining estimates in terms of the following generalized Sobolev norm: $$\|h\|_{H^1}^2 := \|h\|^2 + \sum_{k=0}^{2} \|C_k h\|^2 + \|B h\|^2.$$ To this end it turns out to be convenient to define the bilinear form:

$$\langle h, g \rangle := \langle h, g \rangle + \sum_{k=0}^{2} a_k \langle C_k h, C_k g \rangle + a_3 \langle B h, B g \rangle - b_0 \langle C_0 h, C_1 g \rangle - b_0 \langle C_1 h, C_0 g \rangle - b_1 \langle C_1 h, C_2 g \rangle - b_1 \langle C_2 h, C_1 g \rangle \tag{B.2}$$

where $a_k > 0, b_k > 0$ will be chosen shortly (see (B.6) and (B.7)).

**Lemma B.1.** If for $\delta \in (0, 1)$

$$a_0 b_1^2 + a_2 b_0^2 \leq a_0 a_1 a_2 (1 - \delta)^2, \tag{B.3}$$

then the quadratic form is positive definite and

$$\langle h, h \rangle \geq (\|h\|^2 + \delta \sum_{k=0}^{2} a_k \|C_k h\|^2 + a_3 \|B h\|^2) = \kappa \|h\|_{H^1}^2.$$ with $\kappa = \min\{\delta a_0, \delta a_1, \delta a_2, a_3, 1\}$.

**Proof.** We have for any $a_0, a_1 > 0$

$$\langle h, h \rangle - a_3 \|B h\|^2 - \|h\|^2 \geq \sum_{k=0}^{2} a_k \|C_k h\|^2 - \sum_{k=0}^{1} (b_k a_k \|C_k h\|^2 + b_k a_k^{-1} \|C_{k+1} h\|^2)
$$

$$= (a_0 - b_0 a_0) \|C_0 h\|^2 + (a_1 - b_0 a_0^{-1} - b_1 a_1^{-1}) \|C_1 h\|^2 + (a_2 - b_1 a_1) \|C_2 h\|^2
$$

$$= \delta \sum_{k=0}^{2} a_k \|C_k h\|^2 + (a_0 (1 - \delta) - b_0 a_0) \|C_0 h\|^2 + (a_1 (1 - \delta) - b_0 a_0^{-1} - b_1 a_1^{-1}) \|C_1 h\|^2 + (a_2 (1 - \delta) - b_1 a_1) \|C_2 h\|^2$$

Then choosing

$$a_0 = \frac{a_0 (1 - \delta)}{b_0}, \quad a_1 = \frac{a_2 (1 - \delta)}{b_1}$$

the Lemma follows immediately by condition (B.3). \qed

On the other hand Schwartz inequality implies that there exists $K > 0$ such that

$$\langle h, h \rangle \leq K (\|h\|^2 + \sum_{k=0}^{2} \|C_k h\|^2 + \|B h\|^2). \tag{B.4}$$

Let $H^1 := \{h \in H^0 : \langle h, h \rangle < \infty\}$, clearly it is an Hilbert space, equivalent to $H^1$, with scalar product $\langle \cdot, \cdot \rangle$. 


Lemma B.2. Given $C_0, B$ as described at the beginning of the section, there exists $\tau > 0$ such that, for each $\sigma \in (0, 1)$,

$$\langle h, Lh \rangle \leq -\tau \sigma^2 \left\{ \sum_{k=0}^{2} \|C_k h\|^2 + \sum_{k=0}^{2} \|C_k C_0 h\|^2 + \|B h\|^2 + \|BC_0 h\|^2 \right\}. \quad (B.5)$$

Proof. This is a proof by boring computations. Let us start:

$$\langle h, Lh \rangle = \sigma^2 \langle h, C_0^2 h \rangle + \sum_{k=0}^{2} a_k \sigma^2 \left( \langle C_k C_0^2 h, C_k h \rangle + \langle C_k B h, C_k h \rangle \right)$$

$$+ \sigma^2 a_3 \langle BC_0^2 h, B h \rangle - \sum_{k=0}^{1} \sigma^2 b_k \left( \langle C_k h, C_{k+1} C_0^2 h \rangle + \langle C_k C_0^2 h, C_{k+1} \rangle \right)$$

$$- \sum_{k=0}^{1} b_k \left( \langle C_k h, C_{k+1} B h \rangle + \langle C_k B h, C_{k+1} \rangle \right).$$

Now we must look at all the terms one by one, we will use systematically (A.1) – (A.5).

$$\langle h, C_0^2 h \rangle = -\langle C_0 h, C_0 h \rangle. \quad (I_{A.0})$$

$$\langle C_0^3 h, C_0 h \rangle = -\langle C_0^2 h, C_0^2 h \rangle. \quad (I_{A.0})$$

$$\langle C_1 C_0^2 h, C_1 h \rangle = \langle C_0 C_1 C_0 h, C_1 h \rangle + \langle BC_0 h, C_1 h \rangle$$

$$= -\langle C_1 C_0 h, C_0 C_1 h \rangle + \langle C_0 B h, C_1 h \rangle - \langle C_1 h, C_1 h \rangle \quad (I_{A.1})$$

$$= -\langle C_1 C_0 h, C_1 C_0 h \rangle + \langle C_1 C_0 h, B h \rangle - \langle B h, C_0 C_1 h \rangle - \langle C_1 h, C_1 h \rangle$$

$$= -\langle C_1 C_0 h, C_1 C_0 h \rangle + \langle B h, B h \rangle - \langle C_1 h, C_1 h \rangle.$$

$$\langle C_2 C_0^2 h, C_2 h \rangle = -\langle C_2 C_0 h, C_2 C_0 h \rangle. \quad (I_{A.2})$$

$$(C_0 B h, C_0 h) = (C_1 h, C_0 h). \quad (I_{B.0})$$

$$\langle C_1 B h, C_1 h \rangle = 2\langle C_2 h, C_1 h \rangle + \langle R_2 h, C_1 h \rangle. \quad (I_{B.1})$$

$$(C_2 B h, C_2 h) = (R_3 h, C_2 h). \quad (I_{B.2})$$
\[\{BC_0^2 h, Bh\} = -(BC_0 h, C_0 Bh) - (C_1 C_0 h, Bh)\]
\[= -(BC_0 h, BC_0 h) - (BC_0 h, C_1 h) - (C_1 C_0 h, Bh) \tag{I_B.B}\]
\[= -(BC_0 h, BC_0 h) + (Bh, C_0 C_1 h) + (C_1 h, C_1 h) - (C_1 C_0 h, Bh)\]
\[= -(BC_0 h, BC_0 h) - (Bh, Bh) + (C_1 h, C_1 h).\]

\[\{C_0 C_0^2 h, C_1 h\} + \{C_0 h, C_1 C_0^2 h\} = -2(C_0^2 h, C_1 C_0 h) - (C_0 h, C_1 h). \tag{II_A.0}\]

\[\{C_1 C_0^2 h, C_2 h\} + \{C_1 h, C_2 C_0^2 h\} = -2(C_1 C_0 h, C_2 C_0 h) - (C_1 h, C_2 h). \tag{II_A.1}\]

\[\{C_0 Bh, C_1 h\} + \{C_0 h, C_1 Bh\} = (C_1 h, C_1 h) + 2(C_0 h, C_2 h) + (C_0 h, R_2 h). \tag{II_B.0}\]

\[\{C_1 Bh, C_2 h\} + \{C_1 h, C_2 Bh\} = 2(C_2 h, C_2 h) + (R_2 h, C_2 h) + (C_1 h, R_3 h). \tag{II_B.1}\]

Finally, we can put all the terms together, obtaining

\[
\langle h, Lh \rangle = -\sigma^2 \|C_0 h\|^2 - [b_0 + \sigma^2 (a_1 - a_3)] \|C_1 h\|^2 - 2b_1 \|C_2 h\|^2 - \sigma^2 (a_3 - a_1) \|Bh\|^2 + (a_0 + \sigma^2 b_0) \{C_0 h, C_1 h\} + a_1 \{R_2 h, C_1 h\} - b_0 \{C_0 h, C_0 h\} - b_1 \{R_2 h, C_2 h\} + (2a_1 + \sigma^2 b_1) \{C_1 h, C_2 h\} - 2b_0 \{C_0 h, C_2 h\} + a_2 \{R_3 h, C_2 h\} - b_1 \{R_3 h, C_1 h\} - \sigma^2 \left( \sum_{k=0}^2 a_k \|C_k C_0 h\|^2 + a_3 \|BC_0 h\|^2 - 2 \sum_{k=0}^1 b_k \{C_k C_0 h, C_{k+1} C_0 h\} \right) \]

\[\tag{III}\]

By the same argument used in the proof of Lemma B.1, if for 0 < \(\delta\) < 1 we have

\[a_0 b_1^2 + a_2 b_0^2 < a_0 a_1 a_2 (1 - \delta)^2, \tag{B.6}\]

then III is bounded by

\[-\sigma^2 \delta (\sum_k a_k \|C_k C_0 h\|^2 + a_3 \|BC_0 h\|^2).\]

Recalling (A.2) and (A.4), we have

\[\|R_2 h\|^2 \leq K_2 \|C_0 h\|^2, \|R_3 h\|^2 \leq K_3 \{\|Bh\|^2 + \|C_0 h\|^2 + \|C_1 h\|^2 + \|C_2 h\|^2 \}.\]

Applying Schwarz, for each \(\alpha_1, \alpha_2, \alpha_3, \alpha_4 > 0\),
the first three lines of the above equation are bounded by
\[
-\left\{ \sigma^2 - \frac{1}{2} \alpha_1 [a_0 + \sigma^2 b_0 + K_2 a_1] - K_2 (b_0 + b_1) - \alpha_3 b_0 - \frac{1}{2} K_3 a_2 - \frac{1}{2} b_1 K_3 \alpha_4 \right\} \| C_0 h \|^2
\]
\[
-\left\{ b_0 - \sigma^2 (a_3 - a_1) - \frac{a_0 + \sigma^2 b_0}{2 \alpha_1} - \frac{2 a_1 + \sigma^2 b_1}{2 \alpha_2} - \frac{K_3 a_2}{2} - \frac{(K_3 \alpha_3^2 + 1) b_1}{2 \alpha_4} \right\} \| C_1 h \|^2
\]
\[
-\left\{ 2 b_1 - \frac{1}{2} b_1 - \frac{1}{2} \alpha_2 (2 a_1 + \sigma^2 b_1) - \alpha_3 b_0 - \frac{1}{2} (K_3 + 1) a_2 - \frac{1}{2} b_1 K_3 \alpha_4 \right\} \| C_2 h \|^2
\]
\[
-\left\{ \sigma^2 (a_3 - a_1) - \frac{1}{2} K_3 a_2 - \frac{1}{2} K_3 b_1 \alpha_4 \right\} \| B h \|^2
\]

An inspection of the above expression shows that with the choices
\[
a_0 = \sigma^2 \nu^7; \quad a_1 = \sigma^2 \nu^{16}; \quad a_2 = \sigma^2 \nu^{18}; \quad a_3 = \nu^{13}; \quad b_0 = \sigma^2 \nu^{12}; \quad b_1 = \sigma^2 \nu^{17}
\]
and
\[
\alpha_1 = \nu^{-6}; \quad \alpha_2 = \nu^2; \quad \alpha_3 = \nu^{-5}; \quad \alpha_4 = \nu
\]
implies that, by choosing \( \nu \) small enough, there exist \( \tau > 0 \) such that, for each \( \sigma \in (0, 1) \),
\[
\langle h, L h \rangle \leq -\tau \sigma^2 \left\{ \sum_{k=0}^{2} \| C_k h \|^2 + \| B h \|^2 + \sum_{k=0}^{2} \| C_k C_0 h \|^2 + \| B C_0 h \|^2 \right\}.
\]
Observe that (B.6) is satisfied by this choice. \( \square \)

**Appendix C. A Coordinate Change**

We study a change of coordinates in the case on one particle, for many particles one simply considers the product.

Let \( S^3 := \{ x \in \mathbb{R}^4 : \| x \| = 1 \} \) and \( M = \mathbb{R} \times S^3 \subset \mathbb{R} \times \mathbb{R}^2 \times \mathbb{R}^2 \), \( M_+ = (0, \infty) \times S^3 \subset M \). Let \( \Psi : \mathbb{R}^4 \setminus \{0\} \to M_+ \subset \mathbb{R}^5 \) be defined by
\[
\Psi(q, p) = \left( \sqrt{\frac{p^2}{2} + U(q)}, \frac{q \sqrt{U(q)} \sqrt{p^2 + 2U(q)}}{|q| \sqrt{\frac{p^2}{2} + U(q)}}, \frac{p}{\sqrt{p^2 + 2U(q)}} \right) =: (r, \xi, \eta)
\]

Remember that, by hypotheses, \( U(q) = \bar{U}(q^2) \) and \( \bar{U} \) is a strictly increasing function. We can then extend \( \bar{U} \) to a smooth increasing function on \( \mathbb{R} \) such that \( \bar{U}(z) \geq 0 \) if \( z \geq 0 \).\(^5\) It follows that \( \rho(z) := \bar{U}^{-1}(z) \) is a well defined smooth function on \( \mathbb{R} \) such that \( \rho(0) = 0 \).

One can readily check that the inverse \( \Psi^{-1} : M_+ \to \mathbb{R}^4 \) is given by
\[
\Psi^{-1}(r, \xi, \eta) = \left( \sqrt{\rho(r^2 \xi^2)} \frac{\xi}{\| \xi \|}, \sqrt{2} \eta \right).
\]
\(^5\)Clearly the extension is arbitrary, but this is irrelevant in the following.
For the following it is convenient to introduce the function \( \theta(z) = \sqrt{\rho(z)/z} \), \( z \neq 0 \). Notice that \( \theta \) is smooth on \( \mathbb{R} \) provided we set \( \theta(0) = \sqrt{1/U(0)} \).

Next we transport the vector fields on \( M \) by the usual formula \( \Psi_* Z = (D\Psi Z) \circ \Psi^{-1} \). The following lemma follows by the computation of \( D\Psi \) that can be found in appendix [D].

**Lemma C.1.** With the above notations we have

\[
\tilde{C}_0 := \Psi_* C_0 = J\eta \cdot \partial_\eta
\]

\[
\tilde{B} := \Psi_* B = \frac{\sqrt{2}}{\partial(r^2\xi^2)} \left\{ \eta - \xi \left( \frac{\xi,\eta}{\xi^2} \right) \left[ 1 - \frac{1}{2U'(\rho(r^2\xi^2))} \right] \right\} \partial_\xi
\]

\[
- \sqrt{2U'(\rho(r^2\xi^2))}\theta(r^2\xi^2)\xi \partial_\eta
\]

\[
\tilde{Y} := \Psi_* Y = \partial_r.
\]

Define the function

\[
\Gamma(z) := 1 - \frac{1}{2U'(\rho(z))}\theta(z)^2
\]

and notice that it is continuous in 0 and \( \Gamma(0) = 0 \). It is then natural to write

\[
\tilde{B} = \frac{\sqrt{2}}{\partial(r^2\xi^2)} \left\{ \tilde{B}^0 + \Gamma(r^2\xi^2)\tilde{B}^1 \right\}
\]

\[
\tilde{B}^0 = \eta \partial_\xi - \xi \partial_\eta, \quad \tilde{B}^1 = \xi \partial_\eta - \frac{\xi,\eta}{\xi^2} \xi \partial_\xi
\]

Notice that \( \theta(r^2\xi^2) \) and \( \Gamma(r^2\xi^2) \) are smooth function of \( \xi \) and \( r \), consequently \( \tilde{B} \) is a smooth vector field. In addition, both \( \tilde{B}^0 \) and \( \tilde{B}^1 \) are tangent to the surfaces \( \{ r \} \times S^3 \subset M \).

**Remark C.2.** The vector fields \( \tilde{C}_0, \tilde{B}, \tilde{Y} \) are defined only on \( M_+ \), but admit a smooth canonical extension to all \( M \). We will use the same notation to designate such an extension.

It follows that there exists smooth vector fields \( \tilde{C}_1, \tilde{C}_2 \) on \( M \) such that \( \tilde{C}_i = \Psi_* C_i \) on \( M_+ \).

**Appendix D. Microcanonical measure**

We collect here some properties about the microcanonical measure \( \mu_a \) (and its product version \( \mu_{\alpha} \)).

Let us first recall the definition and some formulas. Microcanonical measure is defined as the conditional measure on the energy shell \( \Sigma_a = \{(q,p) \in \mathbb{R}^2 \mid q^2 + p^2 = a \} \). The product version \( \mu_{\alpha} \) is defined as the product of microcanonical measures on each energy shell.

\[ \mu_{\alpha}(A) = \prod_{a \in \mathbb{R}} \mu_a(A_a) \]
Proposition D.1. For all $f, g$ continuous locally bounded functions on $\mathbb{R}^4$, such that $g$ does not depend on $p_k$ (i.e., $g \equiv 0$), and $f$ is differentiable in $p_k$, then

$$
\mu_a(g \partial_{p_k} f) = (\partial_{a_k} \mu_a)(g p_k f) + \frac{Z'(a_k)}{Z(a_k)} \mu_a(g p_k f), \quad m_0, \beta \text{-a.s., } a_k > 0. \tag{D.4}
$$

Proof. Because of the product structure of $\mu_a$, we can just consider only one site and we drop the index $k$ of it.

Let us recall that from the definition of $\mu_a$ follows, for each smooth bounded functions $f, g$ and $\varphi : \mathbb{R}_+ \to \mathbb{R}$ supported away from zero,

$$
\int_{\mathbb{R}^4} dp \, dq \, e^{-H_0(p, q)} \varphi(H_0) \, f(p, q) = \int_{\mathbb{R}_+} da \, e^{-a} \varphi(a) Z(a) \mu_a(f)
$$

Thus

$$
\int_{\mathbb{R}_+} da \, e^{-a} \varphi(a) Z(a) \mu_a(g \partial_{p_k} f) = \int_{\mathbb{R}^4} dp \, dq \, e^{-H_0} \varphi(H_0) g(q) \partial_{p_k} f(p, q)
$$

$$
= \int_{\mathbb{R}^4} dp \, dq \, e^{-H_0} \{ -\varphi'(H_0) + \varphi(H_0) \} g(q) p_k f(p, q)
$$

$$
= \int_{\mathbb{R}_+} da \, e^{-a} \{ -\varphi'(a) + \varphi(a) \} Z(a) \mu_a(g f)
$$

$$
= \int_{\mathbb{R}_+} da \, e^{-a} \varphi(a) \partial_{a_k} \{ Z(a) \mu_a(g f) \}
$$

$$
= \int_{\mathbb{R}_+} da \, e^{-a} \varphi(a) Z(a) \partial_{a_k} (\mu_a(g f)) + \int_{\mathbb{R}_+} da \, e^{-a} \varphi(a) \frac{Z'(a)}{Z(a)} \mu_a(g f).
$$

It follows the relation (D.4) for any bounded smooth $f, g$. The result follows by approximations.
Lemma D.2.

Then, given any two compact support functions \( g, \theta \) and its inverse (C.1). Recall also the notation \( \theta(z) = \sqrt{\rho(z)/z} \), and that \( \theta(0) \to \sqrt{1/U}(0) \).

\[
Z(a) = 4\omega_4a \int_{S^3} \left[ U^\prime (\rho(a\xi^2)) \right]^{-1} d\sigma(\xi, \eta),
\]

where we have used polar coordinates in four dimensions, \( \sigma \) is the uniform probability measure on \( S^3 \), the unit four dimensional ball, and \( \omega_4 \) is its volume. Furthermore

\[
\mu_a(f) = \frac{4\omega_4a}{Z(a)} \int_{S^3} f \circ \Psi^{-1}(a, \xi, \eta) \left[ U^\prime (\rho(\sqrt{a}\xi^2)) \right]^{-1} d\sigma(\xi, \eta).
\]

Proof. Instead of computing with differential forms it turns out to be more efficient to use the following trick.

Consider the change of variables \( \tilde{\Psi} : (\mathbb{R}^4 \times \{0\}) \times \mathbb{R}_+ \to \mathbb{R}^5 \) defined by

\[
\tilde{\Psi}(q,p,s) = \left( \frac{q^2}{2} + U(q), \frac{s q \sqrt{U(q)}}{|q| \sqrt{\frac{q^2}{2} + U(q)}}, \frac{s p}{\sqrt{p^2 + 2U(q)}} \right)
\]

(D.7)

Then, given any two compact support functions \( g \in C^0(\mathbb{R}_+, \mathbb{R}) \), \( f \in C^0(\mathbb{R}^4, \mathbb{R}) \), we can write

\[
\int_{\mathbb{R}^5} g(s) f(p,q) dq dp ds = \int_{\mathbb{R}^2 \times \mathbb{R}^3} [g f \left| \det(D\tilde{\Psi}) \right|^{-1}] \circ \tilde{\Psi}^{-1}(a, \tilde{\xi}, \tilde{\eta}) da d\tilde{\xi} d\tilde{\eta} = 4\omega_4 \int_{\mathbb{R}^2 \times S^3} g(s) \left[ f \left| \det(D\tilde{\Psi}) \right|^{-1} \right] \circ \tilde{\Psi}^{-1}(a, s\xi, s\eta) s^3 da ds d\sigma(\xi, \eta)
\]

In Lemma D.3 we compute the determinant of

\[
D\tilde{\Psi} \circ \tilde{\Psi}^{-1}(a, \tilde{\xi}, \tilde{\eta}) = \left( \begin{array}{ccc}
\frac{\partial a}{\partial q} & \frac{\partial a}{\partial p} & \frac{\partial a}{\partial s} \\
\frac{\partial a}{\partial \tilde{q}} & \frac{\partial a}{\partial \tilde{p}} & \frac{\partial a}{\partial \tilde{s}} \\
\frac{\partial a}{\partial \tilde{q}} & \frac{\partial a}{\partial \tilde{p}} & \frac{\partial a}{\partial \tilde{s}} \\
\end{array} \right) \circ \tilde{\Psi}^{-1}(a, \tilde{\xi}, \tilde{\eta})
\]

(D.8)
for $\tilde{\xi}^2 + \tilde{\eta}^2 = 1$, obtaining

$$\det \left( D\tilde{\Psi} \circ \tilde{\Psi}^{-1} \right) = \frac{\tilde{U}'(\rho(a\xi^2))}{a}. \quad (D.9)$$

Thus, if we take a sequence of $g_n$ that converges weakly to the delta function on one, we have the formula

$$\int_{\mathbb{R}^4} f(p, q) \, dq \, dp = 4\omega_4 \int_{M_+} g(a) \frac{a}{\tilde{U}'(\rho(a\xi^2))} \, da \, d\sigma(\xi, \eta).$$

Accordingly, for each $g \in L^1(\mathbb{R}_+) \text{ we can write}$

$$\int_{\mathbb{R}^4} f(p, q) g(\mathcal{E}^0) \, dq \, dp = 4\omega_4 \int_{M_+} g(a) \frac{a}{\tilde{U}'(\rho(a\xi^2))} \, da \, d\sigma(\xi, \eta),$$

On the other hand by the definition of the microcanonical measure $\mu_a$:

$$\int_{\mathbb{R}^4} f(p, q) g(\mathcal{E}^0) \, dq \, dp = \int_{\mathbb{R}_+} g(a) \mathcal{Z}(a) \mu_a(f) \, da,$$

The above, by the arbitrariness of $g$, yields the following formula for the microcanonical expectation:

$$\mu_a(f) = 4\omega_4 a \mathcal{Z}(a)^{-1} \int_{S^3} f \circ \tilde{\Psi}^{-1}(a, \xi, \eta) \left[ \tilde{U}'(\rho(a\xi^2)) \right]^{-1} \, d\sigma(\xi, \eta). \quad (D.10)$$

Putting $f = 1$ in $(D.10)$ implies the formula for $\mathcal{Z}(a)$. $\square$

**Lemma D.3. Proof of equation (D.9).**

**Proof.** An explicit computation of the derivative yields

$$D\tilde{\Psi} \circ \tilde{\Psi}^{-1} = \begin{pmatrix} 2\tilde{U}'(\rho(a\xi^2)) \theta(a\xi^2 \rho^{-2}) \sqrt{a} \rho^{-1} \xi & \rho^{-1} \sqrt{2a} \eta & 0 \\ \frac{1}{\sqrt{2a}} \left[ 1 - \frac{5\rho \xi}{\xi} \{ 1 - \eta^2 \rho^{-2} \tilde{U}'(\rho) \theta^2 \} \right] & \frac{1}{\sqrt{2a}} \xi \otimes \eta & \rho^{-1} \xi^t \\ -\frac{1}{\sqrt{2a}} \theta \tilde{U}'(\rho) \eta \otimes \xi & \frac{1}{\sqrt{2a}} \left[ 1 - \rho^{-2} \eta \otimes \eta \right] & \rho^{-1} \eta^t \end{pmatrix}.$$ 

We want to compute the determinant for $(\xi, \eta) \in S^3$, i.e. $\rho = 1$. If we multiply the first row by $(2a)^{-1} \xi_1$ and we sum it to the second, then by $(2a)^{-1} \xi_2$ and sum it to the third, by $(2a)^{-1} \eta_1$ and sum to the fourth and
finally by \((2a)^{-1}\eta_2\) and sum it to the last row, we have
\[
\det(D\tilde{\Psi} \circ \tilde{\Psi}^{-1}) = \det\left( \begin{array}{ccc} 2\tilde{U}'(\rho(a\xi^2))\theta(a\xi^2)\sqrt{a}\xi & \sqrt{2a}\eta & 0 \\
\frac{1}{\sqrt{a}\theta} \left[ 1 - \frac{\xi\xi}{\xi^2}(1 - \tilde{U}'(\rho)\theta^2) \right] & 0 & \xi^t \\
0 & 1(2a)^{-\frac{1}{2}} & \eta^t \end{array} \right)
\]
\[
= \frac{1}{2a} \det\left( \begin{array}{ccc} 2\tilde{U}'(\rho(a\xi^2))\theta(a\xi^2)\sqrt{a}\xi & -2a\eta^2 \\
\frac{1}{\sqrt{a}\theta} \left[ 1 - \frac{\xi\xi}{\xi^2}(1 - \tilde{U}'(\rho)\theta^2) \right] & \xi^t \\
0 & 1(2a)^{-\frac{1}{2}} & \eta^t \end{array} \right)
\]
\[
= \frac{1}{2a} \det\left( \begin{array}{ccc} 0 & -2a\eta^2 \\
\frac{1}{\sqrt{a}\theta} \left[ 1 - \frac{\xi\xi}{\xi^2}(1 - \eta^{-2}\tilde{U}'(\rho)\theta^2) \right] & \xi^t \end{array} \right).
\]
From the above the Lemma follows.

**Corollary D.4.** Let \(f\) be a continuous function of \((q,p)\), then the following formula holds
\[
\mu_a(f(q,p)) = \int_{S^3} f \circ \tilde{\Psi}^{-1}(a,\xi,\eta) \, d\sigma(\xi,\eta) + O(a) \quad (D.11)
\]
where \(\sigma\) is the uniform probability measure on \(S^3\), and \(O(a)\) is a smooth function of order \(a\) as \(a \to 0\).

Notice that because of (D.10), since \(0 < c < \tilde{U}' \leq c^{-1} < +\infty\), microcanonical measure is uniformly equivalent to the uniform measure on the unit sphere, and, for any \(a > 0\), and any positive \(f\):
\[
\frac{1}{2a} \int_{S^3} f \circ \tilde{\Psi}^{-1}(a,\xi,\eta) \, d\sigma(\xi,\eta) \leq \mu_a(f) \leq \frac{1}{2} \int_{S^3} f \circ \tilde{\Psi}^{-1}(a,\xi,\eta) \, d\sigma(\xi,\eta)
\]
\[
(D.12)
\]
\footnote{Just remember that \(\det(1 - bv \otimes v) = 1 - bv^2\) since \(v\) and any vector perpendicular to \(v\) are eigenvectors of eigenvalue \(1 - bv^2\) and \(1\) respectively.}
Appendix E. The Gaussian case

Just to give a concrete idea of what we are doing and to provide some concrete intuition, here we discuss the case in which we have just two particles and both $U$ and $V$ are quadratic. The point being that such a case can be solved explicitly and hence provides a guidance for what can be expected in the general case.

Let us consider and Hamiltonian system with four degree of freedom $(q_1, p_1, q_2, p_2) \in \mathbb{R}^8$ given by

$$H_{\varepsilon} := \frac{1}{2}\left\{\|p_1\|^2 + \|p_2\|^2\right\} + \frac{1}{2}\left\{\|q_1\|^2 + \|q_2\|^2\right\} + \varepsilon\|q_1 - q_2\|^2$$

plus random forces that conserves the kinetic energy (that is independent diffusions on the circles $\|p_i\|^2 = \text{cost}$). To this end consider the vector fields

$$X_i := p_{i,1}\partial_{p_{i,2}} - p_{i,2}\partial_{p_{i,1}}.$$  

The generator is thus given by

$$L_{\varepsilon} := \{H_{\varepsilon}, \cdot\} + \sigma^2 \sum_{i=1}^{2} X_i^2 = A_{\varepsilon} + \sigma^2 S$$

The energies of the two particles are $E_i = \frac{1}{2}\|p_i\|^2 + \frac{1}{2}\|q_i\|^2 + \frac{\sigma}{2}\|q_i - q_2\|^2$ and

$$\partial_t E_1 = \varepsilon(q_2 - q_1, p_1 + p_2) = \varepsilon j$$

$$\partial_t E_2 = -\varepsilon j$$

gives the current. A direct computation shows that, setting

$$u := \frac{1}{2}\left\{\|q_2\|^2 - \|q_1\|^2\right\} - \sigma^{-2} q_2 \cdot p_1 + \sigma^{-2} q_1 \cdot p_2$$

holds true

$$L_{\varepsilon} u = j + \varepsilon\sigma^{-2}\left\{\|q_1\|^2 - \|q_2\|^2\right\} := j.$$

Accordingly, if we rescale the time by $\varepsilon^{-2}$ and we look at the random variables $E_{i,\varepsilon}(t) := E_i(\varepsilon^{-2}t)$.

$$E_{1,\varepsilon}(t) - E_{1,\varepsilon}(0) = \varepsilon \int_{0}^{\varepsilon^{-2}t} (L_{\varepsilon} u)(s) ds - \varepsilon^2 \sigma^{-2} \int_{0}^{\varepsilon^{-2}t} \left(\|q_1(s)\|^2 - \|q_2(s)\|^2\right) ds$$

$$= \varepsilon \left( u(\varepsilon^{-2}t) - u(0) \right) + \varepsilon M^u_{\varepsilon^{-2}t} - \sigma^{-2} \int_{0}^{t} (E_{1,\varepsilon}(\tau) - E_{2,\varepsilon}(\tau)) d\tau$$

$$-\varepsilon^2 \sigma^{-2} \int_{0}^{\varepsilon^{-2}t} \left[\left(\|q_1(s)\|^2 - \|p_1(s)\|^2\right) - \left(\|q_2(s)\|^2 - \|p_2(s)\|^2\right)\right] ds + \mathcal{O}(\varepsilon^3)$$

(E.2)

where the martingale $M^u_{t}$ has quadratic variation given by

$$< M^u >_t = \sigma^2 \int_{0}^{t} \left[(X_1 u(s))^2 + (X_2 u(s))^2\right] ds$$

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We first show that the average of the last term on the RHS of (E.2) tends to 0. Observe that

\[
(\|q_1\|^2 - \|p_1\|^2) - (\|q_2\|^2 - \|p_2\|^2)
\]

\[
= - L_\varepsilon \left( p_1 \cdot q_1 - p_2 \cdot q_2 + \frac{1}{2} (\|q_1\|^2 - \|q_2\|^2) \right) - \varepsilon (\|q_1\|^2 - \|q_2\|^2)
\]

Calling \( v = p_1 \cdot q_1 - p_2 \cdot q_2 + \frac{1}{2} (\|q_1\|^2 - \|q_2\|^2) \), the last term on the RHS of (E.2) can be rewritten as

\[
\varepsilon^2 \left( v(\varepsilon^{-2} t) - v(0) \right) + \varepsilon^2 M_{\varepsilon^{-2} t}^v + \varepsilon^3 \int_0^{\varepsilon^{-2} t} (\|q_1(s)\|^2 - \|q_2(s)\|^2) ds
\]

It is easy to show that the average goes to 0 as \( \varepsilon \to 0 \).

It remains to compute the limit of the martingale \( \varepsilon M_{\varepsilon^{-2} t}^v \). To this purpose one has to compute the limit of its quadratic variation

\[
< \varepsilon M_{\varepsilon^{-2} t}^v > \varepsilon^{-2} \int_0^{\varepsilon^{-2} t} \left[ (q_{2,1} p_{1,2} - q_{2,2} p_{1,1})^2 + (q_{1,2} p_{2,1} - q_{1,1} q_{1,2})^2 \right] ds
\]

After some explicit calculation, one can find 4th order polynomials \( \psi, \phi, \chi \) such that

\[
(q_{2,1} p_{1,2} - q_{2,2} p_{1,1})^2 + (q_{1,2} p_{2,1} - q_{1,1} q_{1,2})^2 = 2 \mathcal{E}_1 \mathcal{E}_2 + L_\varepsilon \psi + S \phi + \varepsilon \chi
\]

The term \( L_\varepsilon \psi + \varepsilon \chi \) does not contribute. For the term \( S \phi \), by using Schwartz inequality:

\[
- \int_0^t d\tau \int S \phi F_\tau d\mu_\varepsilon = \int_0^t d\tau \sum_{i=1,2} \int (X_i \phi)(X_i F_\tau) d\mu_\varepsilon
\]

\[
\leq \left( \int_0^t \mathcal{D}(F_\tau) d\tau \right)^{1/2} \left( \int_0^t \sum_{i=1,2} \int (X_i \phi)^2 F_\tau d\mu_\varepsilon d\tau \right)^{1/2}
\]

\[
\leq \left( \int_0^t \mathcal{D}(F_\tau) d\tau \right)^{1/2} \left( \int_0^t \sum_{i=1,2} \| F \|_L^2 \left[ \int (X_i \phi)^4 d\mu_\varepsilon \right]^{1/2} d\tau \right)^{1/2} \leq C \sqrt{t}
\]

We have obtained that \( \mathcal{E}_{1,\varepsilon}, \mathcal{E}_{2,\varepsilon} \) converge to the (degenerate) diffusion on \( R^2_+ \) generated by

\[
\mathcal{L} = 2 \sigma^{-2} (\partial_{\mathcal{E}_1} - \partial_{\mathcal{E}_2}) \mathcal{E}_1 \mathcal{E}_2 (\partial_{\mathcal{E}_1} - \partial_{\mathcal{E}_2})
\]

(E.3)

corresponding to the stochastic differential equation:

\[
d\mathcal{E}_1 = \sigma^{-1} \sqrt{2 \mathcal{E}_1 \mathcal{E}_2} dw_t - 2 \sigma^{-2} (\mathcal{E}_1 - \mathcal{E}_2) dt = -d\mathcal{E}_2
\]

(E.4)

with \( w_t \) standard Wiener process.
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