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On the statistical distribution of first–return times of balls and cylinders in chaotic systems

G. Mantica,* and S. Vaienti †

Abstract

We study returns in dynamical systems: when a set of points, initially populating a prescribed region, swarms around phase space according to a deterministic rule of motion, we say that the return of the set occurs at the earliest moment when one of these points comes back to the original region. We describe the statistical distribution of these “first–return” times in various settings: when phase space is composed of sequences of symbols from a finite alphabet (with application for instance to biological problems) and when phase space is a one and a two-dimensional manifold. Specifically, we consider Bernoulli shifts, expanding maps of the interval and linear automorphisms of the two dimensional torus. We derive relations linking these statistics with Rényi entropies and Lyapunov exponents.

1 Introduction

In this paper we investigate a phenomenon of vast relevance in physics: returns. Whenever a system evolves according to a deterministic, or even a probabilistic law, along the course of time it may pass close to points previously visited. We then speak of returns and of return times. Of course, this concept can be made precise and rigorous: this has been done since the beginning of the theory of dynamical system, where Poincaré theorem—establishing that in measure preserving systems returns happen almost surely—is probably the first and certainly the most celebrated result. Passing via Kac theorem and coming to recent years, mathematical investigation has flourished and produced beautiful results relating the statistics of return times, i.e. the collective counting of these values, to more conventional dynamical indicators, such as generalized dimensions of invariant measures, Lyapunov exponents and the like. This paper continues in this ongoing investigation, with a special character: rather than presenting a

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single, thoroughly investigated result, we attempt to provide a heuristic, global picture of the dynamical phenomena that are at work. This picture will be confirmed by numerical experiments. Rigor and complete proofs will be the matter for successive publications.

There exist many different alternatives when defining returns: in this paper, we make specific reference to what is called the first return of a (measurable) subset \( A \) of a compact metric space, endowed with a measure \( \mu \) defined on the Borel sigma algebra \( \mathcal{A} \). Motion on \( X \) is effected by the action of a transformation \( T \) that preserves the measure \( \mu \). We thereby define the time of first return of \( A \) into itself as

\[
\tau(A) := \min\{k > 0 \text{ s.t. } T^k A \cap A \neq \emptyset\} . \tag{1}
\]

As anticipated in the abstract, this is the time of the earliest return to \( A \) of one of its points:

\[
\tau(A) = \min\{k > 0 \text{ s.t. } \exists x \in A; T^k(x) \in A\} . \tag{2}
\]

Two choices will be made for \( A \). Firstly, \( A \) shall be a ball of radius \( \varepsilon \), centered at a point \( x \in X \): \( B_{\varepsilon}(x) \). Secondly, \( A \) shall be a dynamically generated cylinder. Let us suppose that \( \mathcal{C} \) is a finite partition of \( X \) and take the \( n \)-join, \( \mathcal{C}^n := \bigvee_{i=0}^{n-1} T^{-i} \mathcal{C} \). We call cylinder of length \( n \) around \( x \in X \), denoted with \( C_n(x) \), the unique element of \( \mathcal{C}^n \) containing \( x \). The statistics of return times are then defined by the collective counting, over different sets, of the values \( \tau(A) \).

The distribution of return times, \( p(\varepsilon, k) \) is

\[
p(\varepsilon, k) := \mu(\{x \in X \text{ s.t. } \tau(B_{\varepsilon}(x)) = k\}) ; \tag{3}
\]

similarly, \( p(n, k) \) is defined replacing \( B_{\varepsilon}(x) \) by \( C_n(x) \). They measure the fraction of points in the space \( X \) whose neighborhood (whether a ball, or a cylinder, of fixed radius \( \varepsilon \) or length \( n \)) first returns to itself after \( k \) iterations of the map. We shall also consider the cumulative distributions (integrated statistics) \( P(\varepsilon, k) \),

\[
P(\varepsilon, k) := \sum_{j=1}^{k} p(\varepsilon, j) \tag{4}
\]

and \( P(n, k) \). Our aim will be to study the behavior of these distributions in systems that are simple enough to permit both a theoretical analysis and a precise numerical simulation.

The time of first return of sets (1) arises in several circumstances. Since it controls the shortest return time of points in the set, it plays a crucial role to establish the asymptotic (exponential) distribution of the return times of all points to the set \( A \), when the measure of the set \( A \) goes to zero, a different and much investigated topic [16, 3, 1, 2, 22, 20, 19]. In addition, it has been used to define the recurrence dimension, being used as the gauge set function to construct a suitable Carathéodory measure [5, 25, 7]. Finally, it has been related to the algorithmic information content [11].

Returns of sets is also relevant in applications, like those of biological interest. In fact, when the space \( X \) consists of sequences of symbols from a finite alphabet
(think e.g. of DNA sequencing) particular words, or motifs have been found to be related to biological mechanisms like transcription sites or protein interaction (see for instance [28]). It is then important to quantify the statistical properties of these words within the genome. In particular, a typical word of length $n$ (that is, a finite sequence of $n$ letters) will recur within a time of the order $e^{nh}$, for large $n$, where $h$ is the metric entropy of the system, as predicted by the Ornstein-Weiss theorem [23]. Yet, if we look at the delay of the first recurrence of the same word, when observed in the whole (possibly infinite) sequence, this scales as $n$ [29, 6]. This time of first return is precisely the quantity studied in this paper.

The plan of the paper is the following: in the next section we review a few results that are useful for the understanding of the paper. For this reason we neither claim nor need completeness. In Sect. 3 we consider the case of cylinder return times in Bernoulli systems. Quite evidently, this is the simplest setting where to study return times of sets. We first present a heuristic explanation of the results rigorously proven in [4] and [21] that permit to compute, via return times, the Rényi entropies. Then, we refine this analysis to obtain new results on the type of convergence of the conventional quantities and we introduce a new one, for which convergence is much faster. Moreover, our theory allows us to obtain a description of the different asymptotics of $p(n, k)$ in the $(n, k)$ plane. In Sect. 4 we leave the symbolic description to enter a geometric setting by considering expanding maps of the interval. We show how results proven in the symbolic setting can be adapted to describe the behavior of the distribution function $p(\varepsilon, k)$. While the treatment is here tailored on the specific system under investigation, the following Sect. 5 introduces a more general approach. Here, we derive a relation linking return times and a partition function that yields Rényi entropies in a suitable limit. In Sect. 6 we consider the case of linear automorphisms of the two-dimensional torus, that can be investigated completely. We also conjecture a general form for one of the asymptotics of the return times statistics. In the Conclusions we review the new results presented in this paper.

## 2 Review of known results and definitions

Many facts concerning return times of sets are known. In this section we review a few of these results that are relevant for the understanding of this paper. If the dynamical system $(X, \mu, T)$ has positive metric entropy, $h_\mu$, it has been proven [29, 6] that:

$$\liminf_{n \to \infty} \frac{\tau(C_n(x))}{n} \geq 1.$$  \hfill (5)

The above limit exists and is equal to one $\mu$-almost everywhere in certain cases, including irreducible and aperiodic subshifts of finite type, systems verifying the specification property [6] and even non-uniformly hyperbolic maps of the interval [22, 15]. It is therefore of importance to study the measure of the set of points that deviate from the almost-sure behavior, a quantity that typically
decays exponentially in time. To do this precisely, one defines the deviation function $M(\delta)$,

$$M(\delta) := \lim_{n \to \infty} \frac{1}{n} \log \mu(\{x \in X \text{ s.t } \tau(C_n(x)) / n < \delta\}). \quad (6)$$

In the language of the previous section this becomes

$$M(\delta) = \lim_{n \to \infty} \frac{1}{n} \log P(n, n \delta) \quad (7)$$

In [4] it has been proven that, for $\psi$-mixing dynamical systems with some restrictions (see the original paper for definition and further specifications) the limit above exists and is related to the generalized Rényi entropies $H$ of the invariant measure $\mu$ via

$$M(\delta) = (\delta - 1)H\left(\frac{1}{\delta} - 1\right), \quad (8)$$

whenever the latter function exists, being it defined via a summation over all cylinders $C$ of length $n$,

$$H(\beta) := -\frac{1}{\beta} \lim_{n \to \infty} \frac{1}{n} \log \sum_{C \in C^n} \mu(C)^{\beta+1}. \quad (9)$$

Observe that meaningful values of $\delta$ in eq. (6) range from zero to one, so that $\beta = \frac{1}{\delta} - 1$ is always larger than zero. For non-integer values of $\frac{1}{\delta}$, a linear interpolation of the values provided by eq. (8) applies.

Rényi entropies have been introduced in [27] and they have been extensively studied in the eighties for their connections with various generalized spectra of dimensions of invariant sets, see for instance [18, 9, 14, 10, 17, 24, 31, 32]. The restrictions in [4] have been removed in [21] and in this last paper the Rényi entropies have been proved to exist for a weaker class of $\psi$-mixing measures.

On the other hand, one might try to answer similar questions when balls are considered in place of cylinders. For instance, if $B_\varepsilon(x)$ is the ball of radius $\varepsilon$ centered at $x \in X$, the natural generalization of the limit (5) is the quantity

$$\eta(x) := \lim_{\varepsilon \to 0^+} \frac{\tau(B_\varepsilon(x))}{-\log \varepsilon}. \quad (10)$$

For a large class of maps of the interval, it has been proved in [29] that $\eta(x)$ exists for $\mu$-almost all $x$ and is equal to the inverse of $\lambda$, the Lyapunov exponent of the measure $\mu$. For hyperbolic smooth diffeomorphisms of a compact manifold a similar result holds, to the extent that

$$\frac{1}{\Lambda^n} \leq \liminf_{\varepsilon \to 0} \frac{\tau(B_\varepsilon(x))}{-\log \varepsilon} \leq \limsup_{\varepsilon \to 0} \frac{\tau(B_\varepsilon(x))}{-\log \varepsilon} \leq \frac{1}{\lambda^n}, \quad (11)$$

where $\Lambda^n$ and $\Lambda^n$ are the largest and the smallest Lyapunov exponents, while $\lambda^n$ is the smallest positive Lyapunov exponent and $\lambda^n$ is the largest negative
Lyapunov exponent, see [30]. In the case of diffeomorphisms in two dimensions, the above formula leads to the equality
\[
\lim_{\varepsilon \to 0} \frac{\tau(B_\varepsilon(x))}{-\log \varepsilon} = \frac{1}{\Lambda^u} - \frac{1}{\Lambda^s} = \frac{D_1(\mu)}{h_\mu}.
\]
(12)
The last equality above is Young’s formula, in which \(D_1(\mu)\) is the information dimension and \(h_\mu\) is the metric entropy of the measure \(\mu\). One of the goals of this paper is to generalize the results (7), (8) in the case of balls.

3 Return times in Bernoulli shifts

In this section we take a close look at Bernoulli processes, that are the simplest, yet significant, example of \(\psi\)-mixing systems. For these, eq. (8) holds and the function \(H\) can be easily computed. In our view, this result is particularly significant, because it allows us to compute a thermodynamical quantity, the spectrum of Rényi entropies, from the statistics of return times. Our aim is to investigate the kind of convergence holding for eq. (7) and more generally the form of the distribution \(p(n, k)\). We shall also introduce a slightly different quantity than \(P(n, \delta n)\), still based on return times, that also yields \(M(\delta)\) in the limit, but for which convergence is much faster.

Let us start from notations: we consider the full shift on the space of sequences of \(M\) symbols, \(\Sigma := \{0, \ldots, M - 1\}^\mathbb{Z}_+\). Let us stipulate that the cylinders in \(C^n\) can be written as \(C_{\sigma_0, \ldots, \sigma_{n-1}}\), where \(\sigma_i \in \{0, \ldots, M - 1\}\), for \(i = 1, \ldots, n - 1\). For short, we shall sometimes write \(\sigma\) for the vector of indices \(\sigma_i\), and \(|\sigma|\) will be the length of this vector. \(\sigma\) is also called a “word” in symbolic language. With a slight abuse of notation, we shall sometimes write \(\tau(\sigma)\) and \(\mu(\sigma)\), the return time and the measure of the word \(\sigma\), in place of \(\tau(C_\sigma)\) and \(\mu(C_\sigma)\), the return time and the measure of the cylinder \(C_\sigma\) labeled by the word \(\sigma\). Similarly, we shall let \(\Sigma_n := \{0, \ldots, M - 1\}^n\) indicate the set of words of length \(n\) and \(C^n\) the set of the associated cylinders, at times interchangeably.

The Bernoulli invariant measure on \(\Sigma\) is induced by the set of probabilities \(\{\pi_j\}, j = 0, \ldots, M - 1\). For simplicity, in the numerical simulations, we shall consider the two-symbols (coin toss) Bernoulli game of parameter \(q\): \(\pi_0 = q, \pi_1 = 1 - q\).

Fig. 1 depicts the function \(p(n, k)\) for \(q = 0.3\). Two features are evident: the first, is the slow decay of \(p(n, 1)\) with increasing \(n\). The second is the much faster decay of \(p(n, 2)\). Both these features, and more, can be explained by computing the asymptotic behavior of \(p(n, k)\) for \(k\) fixed and large \(n\).

The case \(k = 1\) follows immediately from the observation that the only words \(\sigma\) for which \(\tau(\sigma) = 1\) are composed of a single symbol: \(\sigma_i = j\) for all \(i\), where \(j \in \{0, \ldots, M - 1\}\). The measure of the associated cylinders is \(\pi^n_j\), so that \(p(n, 1)\) is the sum of these quantities over all \(j\), and behaves asymptotically as \(a^n\), where \(a = \max\{\pi_j\}\).

Let now \(T_{n,k}\) the set of words of length \(n\) with first return time \(k\):
\[
T_{n,k} = \{\sigma \in \Sigma_n \text{ s.t. } \tau(\sigma) = k\}.
\]
(13)
The first observation is that for any $\sigma \in T_{n,k}$ the symbols $\sigma_i$ repeat periodically with period $k$:

$$\sigma_{k+j} = \sigma_j, \quad j = 0, \ldots, n - k.$$  

(14)

Define the periodic replication operator $P_{n,k}$ as that which takes any word $\sigma$ of length $k$ into the word $\sigma' = P_{n,k}(\sigma)$ of length $n \geq k$, that satisfies eq. (14). It is of relevance now to consider the set of words $W_{n,k}$ defined implicitly by

$$T_{n,k} = P_{n,k}(W_{n,k}).$$  

(15)

The meaning of this definition is simple: words in $W_{n,k}$ have length $k$ and are all and the only periodic “roots” of words of $T_{n,k}$:

$$W_{n,k} = \{\sigma \in \Sigma_k \text{ s.t. } \tau(P_{n,k}(\sigma)) = k\}.$$  

(16)

Controlling $W_{n,k}$ is then the same thing as controlling $T_{n,k}$.

It is not difficult to prove that for any $k$

$$T_{k,k} = W_{k,k} \subset W_{k+1,k} \subset \ldots W_{2k,k} = W_{2k+1,k} = \ldots = W_{2k+j,k},$$  

(17)

for any $j \geq 0$. Therefore, when $n \geq 2k$ the set of “roots” $W_{n,k}$ is constant in $n$. Define

$$m(k) = \max_{\sigma \in W_{2k,k}} \{\#\{j \text{ s.t. } \sigma_j = 0\}\}.$$  

(18)

This is the maximum number of zeros in a word in $W_{2k,k}$. Since all sets $W_{n,k}$ are invariant for permutation of the symbols $\{0, \ldots, M - 1\}$, $m(k)$ is also the
maximum number of any other symbol in a word in $W_{2k,k}$. Suppose now that only one symbol in $\{0, \ldots, M-1\}$ has probability $a$, so that the probability of all other symbols is less than $a$. For simplicity, let us only consider the case of $M = 2$. Then, the probability of the word for which $m(k)$ is obtained gives the leading term in the asymptotic of $p(n, k)$:

$$\log(p(n, k)) \sim \frac{n}{k} [m(k) \log a + (k - m(k)) \log(1 - a)]. \quad (19)$$

It is also rather easy to see that $m(k) = k - 1$. In fact, $m(k) = k$ is possible only for $k = 1$, and $\sigma_{k-1} = 1, \sigma_j = 0$ for $j = 0, \ldots, k-2$ is a word in $W_{2k,k}$.

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Observe that this heuristic result has been derived for \( p(n, k) \) rather than \( P(n, k) \), for which it is known to hold rigorously—modulo the linear interpolation required for non-integer values of \( 1/\delta \). Indeed, numerical experiments on Bernoulli schemes with two symbols (coin toss) show that formula (25) holds.

For instance, Figure 4 shows the logarithm of both \( p(n, \delta n) \) and \( P(n, \delta n) \) versus \( n \), for \( q = 0.3 \) and \( \delta = 0.5 \), compared with a straight line \( g_\delta(n) = an + b \) with slope \( a = (\delta - 1)H(\frac{1}{\delta} - 1) \). Both quantities are well fitted by a function of the kind \( g_\delta(n) + ce^{dn} \).

To validate this picture, confirmed by numerical experiment on other values of \( q \) and \( \delta \) (for \( \delta \) not equal to the inverse of an integer, a linear interpolation formula applies [4, 21]) we plot in Fig. 5 the logarithm of the difference between data and the straight line in Fig. 4. An exponential decay is clearly observed.

In conclusion, numerical experimentation support the hypothesis that the asymptotic behavior in eq. (25) is attained with a decaying exponential term parameterized by the constants \( c \) and \( d < 0 \), together with a slowly decaying contribution arising from the constant \( b \):

\[
\frac{1}{n} \log p(n, \delta n) \simeq M(\delta) + \frac{b}{n} + c e^{dn}. \tag{26}
\]

We shall introduce momentarily a new quantity to improve on this kind of convergence.

The same heuristic arguments imply an approximate form for the behavior of the distribution function for different \( n \) and \( k \). Carrying out the computations of eq. (23) together with eq. (9) we obtain

\[
\log(p(n, k)) \sim (k - n)H(\frac{n}{k} - 1). \tag{27}
\]

We can test this approximation in the case of the Bernoulli scheme with \( q = 1/2 \). Here, trivially the approximation (27) becomes \( \log(p(n, k)) \sim (k - n)\log(2) \). This function fits almost perfectly the numerical data in Fig. 2.

A less favorable case is offered by the Bernoulli scheme with \( q = 3/4 \). In Fig. 3 we plot \( P(n, k) \) and \( p(n, k) \) versus \( k \) for \( n = 30 \), together with the approximation provided by eq. (27) We notice that this latter fits well both functions at \( k = 1 \) (quite obviously, being this behavior associated with the measure of the cylinder of unity return time, see above), while approximation stays reasonable only for \( P(n, k) \) at small values of \( k > 1 \). Then, in the intermediate region the slope of both curves agrees with the interpolation while the numerical value only for \( p(n, k) \).

Certainly, the agreement observed in the last figure is far from satisfactory. The reason is to be found in the approximation made in eq. (21). The same fact is at the origin of the slow convergence observed in eq. (21). We conclude this section unveiling these reasons and providing a more rigorous and insightful treatment of the problem. This improvement is inspired by the idea of summation over prime periodic orbits in dynamical systems.

As we mentioned, the approximation in eq. (21) above is based on the idea that the roles of \( \Sigma_k \) and \( W_{n,k} \) can be interchanged, the effects of their difference
being negligible in the limit. The price to pay in this procedure is the slowly decaying term in the asymptotics (26). We can be more careful: indeed, we can show that $\Sigma_k$ can be rigorously partitioned into the periodic repetition of different sets $W_{n,k'}$. The lemma is the following: for any $n \geq 2k$

$$\Sigma_k = \bigcup_{k' \mid k} P^{k,k'}(W_{n,k'}), \quad (28)$$

where the union is over all integer $k'$ that divide $k$ and where the sets $P^{k,k'}(W_{n,k'})$ are the full completion of $\frac{k}{k'}$ cycles of the word of length $k'$. These sets are pairwise disjoint.

On the basis of this lemma, we can reverse the ordering in eq. (21) to get:

$$\sum_{\sigma \in \Sigma_k} \mu(P^{n,k}(\sigma)) = \sum_{k' \mid k} \sum_{\sigma \in W_{n,k'}} \mu(P^{n,k} \circ P^{k,k'}(\sigma)). \quad (29)$$

Since $k'$ divides $k$, $P^{n,k} \circ P^{k,k'} = P^{n,k'}$ and therefore the chain of equality continues with

$$\sum_{\sigma \in \Sigma_k} \mu(P^{n,k}(\sigma)) = \sum_{k' \mid k} \sum_{\sigma \in W_{n,k'}} \mu(P^{n,k'}(\sigma)) = \sum_{k' \mid k} \sum_{\sigma \in T_{n,k'}} \mu(\sigma), \quad (30)$$

Figure 2: Distribution function $p(n, k)$ (crosses, red lines) and the approximation function in eq. (27) (x, green line) versus $n$ and $k$ in the case of a Bernoulli game with $q = 1/2$. 

---

0 5 10 15 20 25 30

-20

-15

-10

-5

0

$\log p(n,k)$

$n$

$\log p(n,k)$

$k$
Figure 3: Distributions $P(n, k)$ (X, blue line), $p(n, k)$ (crosses, red line) and the approximation function in eq. (27) (green line) versus $k$ for $n = 30$, in the case of a Bernoulli process with $q = 0.3$

where we have used eq. (15). Finally,

$$\sum_{\sigma \in \Sigma_k} \mu(P^{n,k}(\sigma)) = \sum_{k' | k} \sum_{\sigma \in T_{n,k'}} \mu(\sigma) = \sum_{k' | k} p(n, k').$$  \hspace{1cm} (31)

On the other hand,

$$\mu(P^{n,k}(\sigma)) = (\mu(C_{\sigma}))^{\frac{1}{n}},$$  \hspace{1cm} (32)

exactly when $\frac{n}{k}$ is an integer, and approximately otherwise, so that choosing $k/n = \delta$, so that $\delta n = k$ is an integer, and defining the new quantity

$$Z_p(\delta, n) := \sum_{k' | \delta n} p(n, k'),$$  \hspace{1cm} (33)

we find that

$$M_p(\delta) = \lim_{n \to \infty} \frac{1}{n} \log(Z_p(\delta, n)) = (\delta - 1)H(\frac{1}{\delta} - 1).$$  \hspace{1cm} (34)

This formula is valid for all $0 < \delta \leq \frac{1}{2}$ that are the inverse of an integer. For the other values, the linear interpolation between the values at the nearest inverses of an integer applies.

Numerical verification follows: in Fig. 6 we plot the logarithm of $P(n, \delta n)$, $p(n, \delta n)$ and of the period summation function $Z_p(\delta, n)$ versus $n$ for the Bernoulli
process with $q = 0.3$. The line $g_{\delta}(n) = M(\delta)n$ fits almost perfectly the last set of data. On the other hand, the other two functions display the slow convergence discussed above. To further appreciate the improvement brought about by using $Z_p$, consider Fig. 7, where we plot the difference between successive values of the logarithm of the above functions, and these logarithms divided by $n$. All these quantities have limit $M(\delta)$. We compute this value from the linear interpolation of $(\delta - 1)H(\frac{1}{2} - 1)$ to get the value tabulated. The distributions $p$ and $P$ converge slowly, while $Z_p$ gives a numerically exact result. In conclusion, the term $b > 0$ plaguing the convergence in eq. (26) was due to approximate counting and does not show up for the newly introduced quantity.

### 4 Expanding maps of the interval

In this section, we study a family of one-dimensional dynamical systems for which we can derive both a formula for the asymptotic distribution and a generalization of the deviation result. This family will also serve to begin to understand the dynamical phenomena occurring when considering ball, rather than
cylinder, return times: one has to match geometry and dynamics. Further detail will be added in the following section.

We start by constructing a family of measures supported in $[0, 1]$ by means of an affine iterated function system: given a set of $M$ non-overlapping intervals $I_j = [a_j, b_j] \subset [0, 1]$, $j = 0, \ldots, M - 1$, define the lengths $\delta_j = b_j - a_j$, and construct the affine maps

$$\phi_j(x) := \delta_j x + a_j, \quad j = 1, \ldots, M.$$  

Each map $\phi_j$ takes $[0, 1]$ into $[a_j, b_j]$. Consider then the set action $\Phi$ that maps the set $A \subset [0, 1]$ into $\Phi(A) := \bigcup_{j=0}^{M-1} \phi_j(A)$. Repeated action of $\Phi$ on $[0, 1]$ defines a Cantor set $S$ in $[0, 1]$: 

$$S := \bigcap_{k=1}^{\infty} \Phi^k([0, 1]).$$  

We can then construct a family of measures whose support is this set $S$: let us choose real numbers $\{\pi_j\}_{j=1,\ldots,M}$ such that $\pi_j > 0$, $\sum_{j=1}^{M} \pi_j = 1$, and consider the unique measure $\mu$ for which

$$\int f(s)d\mu(s) = \sum_{j=0}^{M-1} \pi_j \int (f \circ \phi_j)(s)d\mu(s),$$  

}\"
Figure 6: Logarithm of the cumulative distribution function $P(n, \delta n)$ (red line, pluses) and of the distribution function $p(n, \delta n)$ (blue line, stars) together with $\log Z_p(\delta, n)$ (large crosses, light blue) and the line $g_\delta(n) = M(\delta)n$ (magenta) for the Bernoulli process with $q = 0.3$, $\delta = 0.4$.

holds for any continuous function $f$. It is then easy to show that, for any choice of the set of real numbers $\{\pi_j\}$, the measure $\mu$ is mixing for the piece-wise linear transformation $T$ defined on $S$ by:

$$T(x) = a_j + \frac{1}{\delta_j} (x - a_j), \text{ if } x \in I_j = [a_j, b_j].$$  (38)

In fact, the maps $\{\phi_j\}$ turn out to be the inverse branches of $T$. As such, they can be employed to build the cylinders $C^n$ of this dynamical system: letting $\sigma_i \in \{0, \ldots, M - 1\}$, for $i = 1, \ldots, n - 1$ these latter can be labelled as

$$C_{\sigma_0, \ldots, \sigma_{n-1}} = (\phi_{\sigma_0} \circ \cdots \circ \phi_{\sigma_{n-1}})([0, 1]).$$  (39)

Following eq. (35), the geometric length $\ell(C_\sigma)$ is easily computed:

$$\ell(C_{\sigma_0, \ldots, \sigma_{n-1}}) = \prod_{i=0}^{n-1} \delta_{\sigma_i}. \quad (40)$$

Equally easily, because of eq. (4), the measure $\mu(C_\sigma)$ is

$$\mu(C_{\sigma_0, \ldots, \sigma_{n-1}}) = \prod_{i=0}^{n-1} \pi_{\sigma_i}. \quad (41)$$
Figure 7: Various functions for of the Bernoulli process with \( q = 0.3, \delta = 0.4 \).
Start with \( \log(p(n, \delta n))/n \): black curve, circles; \( \log(p(n, \delta n)) - \log(p(n-1, \delta(n-1))): \) blue curve, stars; \( \log(P(n, \delta n))/n \) open squares, magenta; \( \log(P(n, \delta n)) - \log(P(n-1, \delta(n-1))): \) crosses, red curve; \( \log(Z_p(n, \delta))/n \): yellow squares; \( \log(Z_p(n, \delta)) - \log(Z_p(n-1, \delta)): \) crosses, green curve. The last two set of data sit to numerical precision on the line \( h = -0.307795889757108 \) that is obtained by the interpolation formula.

Therefore, this dynamical system is metrically equivalent to a Bernoulli shift on \( M \) symbols, with probabilities \( \pi_i, i = 1, \ldots, M - 1 \), that we have discussed in section 3. Yet, when examining the distribution of ball return times, we must investigate is the geometrical relation between balls of a fixed radius and cylinders of different symbolic length.

In order to analyze this relation, we observe that any ball \( B_\varepsilon(x) \) can be written as a union over cylinders of an appropriate (fixed) length \( n \): that is, for all \( x \) and \( \varepsilon \) there exist \( n \) and a collection of indices \( \sigma \in I, |\sigma| = n \) such that

\[
B_\varepsilon(x) = \bigcup_{\sigma \in I} C_\sigma. \tag{42}
\]

This is a consequence of the fact that these measures are singular w.r.t. Lebesgue and their support have gaps of positive length. Therefore, for sufficiently large \( n \), the two boundary points of the ball end up in the closure of a gap in the support of \( \mu \).

Furthermore, since both \( n \) and \( I \) depend on the ball under consideration, we
Figure 8: Distribution function $p(\varepsilon, k)$ for the dynamics of the two map IFS with $\delta_1 = 0.3$, $\delta_2 = 0.2$, $\pi_1 = 0.3$ and $\pi_2 = 0.7$.

define the symbolic length of $B_\varepsilon(x)$ as

$$N_\varepsilon(x) = n - \max\{ j \in \mathbb{Z} \text{ s.t. } M^j \leq \#(I) \}, \quad (43)$$

where $\#(I)$ is the cardinality of the set $I$ and where $M$, as before, is the number of inverse branches of $T$. The idea behind this definition is to measure a sort of effective length of the cover of $B_\varepsilon(x)$. For instance, if eq. (42) would require $\#(I) = 4$ cylinders of length $n = 3$ with $M = 2$ we would effectively consider this union as if it were a single cylinder of length $N_\varepsilon = 1$.

This definition is instrumental in formulating a working hypothesis: we surmise that the statistical distribution of return times of boxes $B_\varepsilon(x)$ characterized by the same symbolic length $N_\varepsilon(x) = n$ will scale as that of cylinders (again, of that given length $n$) in a Bernoulli shift. This hypothesis is confirmed by numerical computation. At a fixed radius $\varepsilon$, we compute the return time distribution for all points $x$ with a fixed symbolic length, computed via eq. (43) and we compare it with the discrete distribution of the corresponding symbolic Bernoulli process. Data reported in Figure 9 are obtained for a two map I.F.S. dynamics. Accordance is significant.

Therefore, to obtain the distribution of return times of balls of fixed radius $\varepsilon$ we must know the cylinder return time distribution, $p(n, k)$, discussed in Sect 3, but also the measure of center points whose balls have a given symbolic length:

$$\Psi(\varepsilon, n) = \mu(\{ x \text{ s.t. } N_\varepsilon(x) = n \}). \quad (44)$$
In fact, from this information, we obtain

$$p(\varepsilon, k) = \sum_n \Psi(\varepsilon, n)p(n, k). \quad (45)$$

To estimate $\Psi(\varepsilon, n)$, we consider, this time at fixed $n$, the distribution of the geometric lengths of cylinders, $\ell(C_n)$: let $z = \log(\varepsilon)$, and define

$$\psi(z, n) := \frac{d}{dz} \mu(\{x \text{ s.t. } \log(\ell(C_n(x))) \leq z\}). \quad (46)$$

When $n$ is sufficiently large, this can be approximated by a continuous distribution, precisely, by a normal distribution $\mathcal{N}_{-\lambda n, S^2 \sqrt{n}}(z)$ of mean $-\lambda n$, and variance $S^2 n$, where $\lambda$ is the Lyapunov exponent of $\mu$, and $S$ the standard deviation of the multiplicative process. Both quantities can be easily computed in this case:

$$\lambda = -\sum_{j=0}^{M-1} \pi_j \log(\delta_j), \quad (47)$$

and

$$S^2 = -\lambda^2 + \sum_{j=0}^{M-1} \pi_j (\log(\delta_j))^2. \quad (48)$$
We now conjecture that we can exchange the role of \( z \) and \( n \) in this derivation, so that \( \Psi(\varepsilon, n) \) (with \( \varepsilon \) fixed) be approximated by the distribution \( \psi(z, n) \) (with \( z = \log(\varepsilon) \) fixed) when properly normalized and, in turn, with \( \mathcal{N}_{-\lambda n, S\sqrt{\pi}}(z) \), with \( z = \log(\varepsilon) \) fixed, and properly normalized via the constant \( A \) to yield the discrete distribution \( D_\varepsilon(n) \):\[
D_\varepsilon(n) = A \mathcal{N}_{-\lambda n, S\sqrt{\pi}}(\log(\varepsilon)), \quad \sum_n D_\varepsilon(n) = 1.
\] (49)

Figure 10: Distribution function \( \Psi(\varepsilon, n) \) (red lines, points) and \( \mathcal{N}(z, n) \) (blue lines) compared (for definitions, see text), in the case of Fig. 8.

This conjecture is indeed validated numerically in Figure 10, that reports \( D_\varepsilon(n) \) and \( \Psi(\varepsilon, n) \) for the same case of Figs. 8, 9. In conclusion, we can write the distribution function \( p(\varepsilon, k) \) as\[
p(\varepsilon, k) = \sum_n D_\varepsilon(n)p(n, k),
\] (50)
where \( D_\varepsilon(n) \) has mean \( \bar{n} = -z/\lambda \) and standard deviation \( s = \lambda^{-3/2}S\sqrt{-z} \), sharply localized in the interval \([n - s, n + s]\). This explains the shape of the graph reported in Fig. 8, that is to be compared with that of Fig. 1 in Section 3: the Gaussian smoothing is particularly evident near the line \( k = -\log(\varepsilon)/\lambda \).

Finally, eq. (50) is the basis to derive formulae akin to those of Sect. 3. In particular, it validates the analogue of formula (25) that becomes here:\[
\lim_{\varepsilon \to 0} \frac{\log p(\varepsilon, -\delta \log(\varepsilon)/\lambda)}{\log \varepsilon} = \frac{1 - \delta}{\lambda} H(\frac{1}{\delta} - 1).
\] (51)
The same observations about convergence of the limit detailed in Sect. 3 apply here. One can therefore relate the asymptotic of return time distributions and Rényi entropies also in the case of expanding maps of the interval.

5 A second approach to expanding maps

In this section, we present a second, more general approach to the statistics of first returns in balls for one-dimensional piecewise linear expanding maps of the type studied in the previous section. This approach can be fruitfully extended to more general situations and, informal as it is now, clearly points to the direction where rigor can be achieved.

Recall the theory of Sect. 3: the word labelling each cylinder of length $k$ was continued periodically to length $n$ to single out a cylinder of length $n$ and return time $k$. Geometrically, for the kind of maps studied in Sect. 4, each cylinder $\sigma$ of length $k$ contains a fixed point of the map, $x_\sigma$, of period $k$. Balls of radius $\varepsilon$ centered at a point $x$ located in the vicinity of such fixed point have a non-empty intersection with their $k$-th iterate if the distance between $x$ and $x_\sigma$ is less than $\frac{s_{k+1}}{2(s_k-1)}\varepsilon$, where $s_k$ is the derivative of $T^k$ at the fixed point $x_\sigma$. Observe that $s_k$ grows geometrically as $k$ grows, so that when $k$ is large $s_k \simeq 1$. In conclusion, all points $x$ in the interval $B_{\varepsilon/2}(x_\sigma)$ are such that their $\varepsilon$-neighborhood returns after time $k$: $T^k(B_{\varepsilon/2}(x)) \cap B_{\varepsilon}(x) \neq \emptyset$. Of course, not all of these intervals, labelled by $\sigma$, are disjoint among themselves, both with the same and different length of $\sigma$. Therefore, two conditions are to be met to assess a genuine first–return.

We may approximately assume that the first condition (non-overlapping of the interval $B_{\varepsilon/2}(x_\sigma)$ with other intervals associated with the same period, $|\sigma| = k$), is met when $\frac{s_{k+1}}{s_k-1}\varepsilon$ is less than the geometrical size, $\ell(C_\sigma)$, of the cylinder that contains the fixed point. More simply, because of our previous observation, we may just require $\varepsilon < \ell(C_\sigma)$. Let again $\Sigma_k := \{0, \ldots, M-1\}^k$ be the set of all words of length $k$. Within this set we therefore define the subset

$$L_{\varepsilon,k} := \{\sigma \in \Sigma_k \text{ s.t. } \varepsilon < \ell(C_\sigma)\}.$$  

The second condition (non-overlapping of $B_{\varepsilon/2}(x_\sigma)$ with intervals with smaller periods $|\sigma|$) is more subtle, and can be resolved by considering, among all fixed points $x_\sigma$ of period $k$, only the primitively periodic ones. We so define the set $W_k$:

$$W_k := \{\sigma \in \Sigma_k \text{ s.t. there is no } j < k \text{ s.t. } \sigma \text{ is periodic of period } j\}.$$  

Summing up, we can write

$$p(\varepsilon,k) = \sum_{\sigma \in L_{\varepsilon,k} \cap W_k} \mu(B_\varepsilon(x_\sigma)),$$  

where $x_\sigma$ is the periodic point in the cylinder $C_\sigma$. This last expression can be further simplified, using a similar approximation to that employed in Sect.
3. In fact, we can write $\mu(B_\varepsilon(x_\sigma)) \simeq \varepsilon^{\alpha_\mu(x_\sigma)}$, where $\alpha_\mu(x_\sigma)$ is the local dimension of the measure $\mu$ at $x_\sigma$. This last quantity can then be extrapolated from the measure and the geometric length of the cylinder $C_\sigma$: $\alpha_\mu(x_\sigma) \simeq \log(\mu(C_\sigma))/\log(\ell(C_\sigma))$. As a consequence, eq. (54) becomes:

$$p(\varepsilon, k) = \sum_{\sigma \in L_{x,k} \cap W_k} \varepsilon^{\log(\mu(C_\sigma))/\log(\ell(C_\sigma))}. \quad (55)$$

We have compared numerically the function $p(\varepsilon, k)$ for the case of Fig. 8 of the previous section and its approximation, eq. (55), in Fig. 11. Agreement is rather satisfactory.

Figure 11: Distribution function $p(\varepsilon, k)$ (green lines) from the original data in Fig. 8 and approximation from formula eq. (55) (red lines)

Eq. (55) can also be written

$$p(\varepsilon, k) = \sum_{\sigma \in L_{x,k} \cap W_k} \mu(C_\sigma)^{\log(\varepsilon)/\log(\ell(C_\sigma))}. \quad (56)$$

This last equation is particularly meaningful. Observe first that this generalizes eqs. (21) and following and can be used to the same scope. Secondly, put $\lambda_\sigma := -\log(\ell(C_\sigma))/|\sigma|$. Then, $\mu$ almost surely, when $|\sigma|$ tends to infinity, $\lambda_\sigma$ converges to the Lyapunov exponent, $\lambda$, of the measure $\mu$. Therefore,

$$p(\varepsilon, k) = \sum_{\sigma \in L_{x,k} \cap W_k} \mu(C_\sigma)^{-\log(\varepsilon)/\lambda_\sigma}. \quad (57)$$
Suppose now to choose \( \varepsilon \) and \( |\sigma| \) such that \(-\delta \log \varepsilon = |\sigma| \lambda\), with \( 0 < \delta < 1 \). This choice has two effects. First, the exponent in the previous equation becomes \( \frac{1}{\delta} \).

Second, the measure of the set \( L_{\varepsilon,k} \) tends to one, when \( \varepsilon \) tends to zero, because \( \mu \) almost surely \(- \log(\ell(C_{\sigma}))/|\sigma|\) tends to \( \lambda \), so that almost surely \( \ell(C_{\sigma}) > \varepsilon \).

Hence,

\[
p(\varepsilon, -\frac{\delta \log \varepsilon}{\lambda}) \simeq \sum_{\sigma \in W_k} \mu(C_{\sigma})^{\frac{1}{\delta}}.
\]  

(58)

If we now let \( k \) to be a prime number, the set \( W_k \) contains all words except the “fixed points” \( \sigma_i = a \), for \( i = 0, \ldots, k-1 \), where \( a \in \{0, \ldots, M-1\} \). In general, one should also subtract all words of shorter periods that divide \( k \), as done above. Call this set of words \( F_k \). Then,

\[
p(\varepsilon, -\frac{\delta \log \varepsilon}{\lambda}) \simeq \sum_{\sigma \in \Sigma_k} \mu(C_{\sigma})^{\frac{1}{\delta}} - \sum_{\sigma \in F_k} \mu(C_{\sigma})^{\frac{1}{\delta}}.
\]  

(59)

It could be shown that, in systems with sufficiently fast decay of correlations like Bernoulli or Markov, the first term is dominant in the limit, so that discarding the second when taking logarithms and dividing by \( \log \varepsilon \), one gets

\[
\frac{1}{\log \varepsilon} \log p(\varepsilon, -\frac{\delta \log \varepsilon}{\lambda}) = \frac{1}{\log \varepsilon} \log \left( \sum_{\sigma \in \Sigma_k} \mu(C_{\sigma})^{\frac{1}{\delta}} \right) = \frac{\delta}{\lambda} \log \left( \sum_{\sigma \in \Sigma_k} \mu(C_{\sigma})^{\frac{1}{\delta}} \right).
\]  

(60)

Taking the limit, we obtain a new verification of eq. (51)

\[
\lim_{\varepsilon \to 0} \frac{1}{\log \varepsilon} \log p(\varepsilon, -\frac{\delta \log \varepsilon}{\lambda}) = \frac{(1-\delta)}{\delta} H\left(\frac{1}{\delta} - 1\right).
\]  

(61)

In the next section, we shall see a generalization of this equation.

6 Linear automorphisms of the two-dimensional torus

The general framework presented in the last section can be easily extended to treat the case of linear automorphisms of the two-dimensional torus, of which the Arnol’d cat map is the most celebrated example. For convenience, we choose a metric in the torus such that balls of radius \( \varepsilon \) are euclidean squares of side \( 2\varepsilon \) with sides oriented along the stable and unstable directions and for simplicity we consider the case when these directions are orthogonal. Then, one can easily show that around any fixed point of the \( k \)-th iteration of the map there exists a rectangle, with sides oriented in the stable and unstable directions, of points \( x \) whose \( \varepsilon \)-balls intersect their image after \( k \) iterations. Letting \( \lambda_- \) and \( \lambda_+ \) the (increasingly ordered) eigenvalues of \( T \), the sides of this rectangle have length \( \varepsilon (1 + \frac{2\lambda_+^k}{\lambda_-^k - 1}) \) and \( \varepsilon (1 + \frac{2\lambda_-^k}{\lambda_+^k - 1}) \). As it turns out, for the Arnol’d cat and other area-preserving maps, these quantities are equal (since \( \lambda_+ \lambda_- = 1 \)) and the rectangle...
of initial conditions just described is a square. Figure 12 draws these squares at a fixed value of $\varepsilon$.

We can then repeat a two-dimensional generalization of the arguments of the previous section. This we will do elsewhere, but we will provide the result below. In fact, an even simpler argument can be sketched. We have seen above that a square of area $\varepsilon^2 \left(1 + \frac{2}{\lambda^k - 1}\right)^2$ exists at each fixed point of $T^k$ and is characterized by return times $k$, or less. This area quickly becomes $\varepsilon^2$ to a good approximation. Moreover, the number of periodic points of $T^k$ grows like $\lambda^k$.

Then, when $\varepsilon$ is “small” with respect to $k$, neglecting all other considerations, we can write

$$p(\varepsilon, k) \simeq \varepsilon^2 \lambda^k.$$  \hfill (62)

Of course, we have to make precise what we mean by “small”. This is when $\varepsilon^2 \lambda^k \leq 1$. Equality holds for $k_\varepsilon = -\frac{2 \log \varepsilon}{\log(\lambda^+)}$. Indeed, following the results reported in Sect. 2, $\frac{2 \log(\lambda^+)}{\log(\lambda^+)}$ is the almost sure limit of $\frac{\tau(B_{\varepsilon}(x))}{\log \varepsilon}$, since it coincides with $\frac{1}{\log(\lambda^+)} - \frac{1}{\log(\lambda^+)}$, see eq. (12). Moreover, in this case $D_1(\mu) = 2$, the invariant measure being the Lebesgue measure and the entropy $h_\mu$ is equal to the Lyapunov exponent $\lambda = \log(\lambda^+)$. Figure 13 draws the distribution function $p(\varepsilon, k)$ for a different toral automorphism, just chosen to increase variety: that associated with the matrix $(1, 2; 2, 5)$. The logarithmically flat approximation in eq. (62) fits the data almost perfectly in the region $\varepsilon^2 \lambda^k \leq 1$.

If we now turn our consideration to the line $k = \delta k_\varepsilon$ in the $(k, \log \varepsilon)$ plane, with $0 < \delta \leq 1$, we can prove that the quantity $p(\varepsilon, \delta k_\varepsilon)$ verifies in this two-dimensional case the analogue of eq. (26):

$$\lim_{\varepsilon \to 0} \frac{1}{\log \varepsilon} \log p(\varepsilon, -\frac{\delta \log(\varepsilon)}{\lambda/2}) = \frac{(1 - \delta)}{\lambda/2} H\left(\frac{1}{\delta} - 1\right).$$  \hfill (63)

The detailed proof, obtained along the lines of Sect. 5 will be reported elsewhere. We simply compute here the two sides of the equality (63), showing that they are equal. From eq. (62) we can compute the l.h.s., obtaining

$$\lim_{\varepsilon \to 0} \frac{1}{\log \varepsilon} \log p(\varepsilon, -\frac{\delta \log(\varepsilon)}{\lambda/2}) = 2(1 - \delta).$$  \hfill (64)

On the other hand, the Rényi entropies for the Lebesgue measure and the Arno’d cat dynamics are all equal to $\lambda = \log(\lambda^+)$, so that also the l.h.s. of eq. (63) is equal to $2(1 - \delta)$.

We conclude this section by taking inspiration from eq. (63) to put forward a conjecture: we believe that, letting $\eta$ be the almost sure limit of $\frac{\tau(B_{\varepsilon}(x))}{\log \varepsilon}$, see eq. (10), and letting $k_\varepsilon = -\eta \log \varepsilon$ as before, under sufficient hypotheses of mixing, one has

$$\lim_{\varepsilon \to 0} \frac{1}{\log \varepsilon} \log p(\varepsilon, \delta k_\varepsilon) = \frac{(1 - \delta)}{\eta} H\left(\frac{1}{\delta} - 1\right).$$  \hfill (65)

We can now turn to conclusions.
Figure 12: Initial conditions $x$ in the two-dimensional torus color coded according to the return time of the ball $B_\varepsilon(x)$ of radius $\varepsilon = 0.15$ for the Arnol’d cat map. ($\tau = 1$ red, 2 green, 3 blue, 4 magenta, 5 light blue)

7 Conclusions

We have studied in this paper various aspects of the statistics of return times of sets in dynamical systems.

We have first reviewed known results for symbolic $\psi$-mixing systems, that link return times and Rényi entropies. We have established new “counting rules”, embodied in the sets $\mathcal{W}_{n,k}$ and in the lemma of eq. (28) that have permitted us to explain the slow convergence of the quantities studied in previous works. At the same time, these results have lead to the definition of a new “partition function” $Z_p(\delta, n)$, eq. (33), that best achieves the goal of extracting Rényi entropies from return times statistics.

When considering return times for balls, we have established a general relation holding for one-dimensional expanding maps, eq. (51), that links the asymptotic of return times with Rényi entropies and the Lyapunov exponent. This relation has been obtained developing two different approaches. The former is a quantitative comparison between balls and dynamical cylinders especially developed for this case. The second is a more general argument that well describes the full behavior of the statistics $p(\varepsilon, k)$, comprised in eq. (55).

We have finally considered linear automorphisms of the two dimensional torus, like the Arnol’d cat map, for which a “quick and dirty” analysis is capable of describing the correct behavior of the distribution function $p(\varepsilon, k)$. This has
Figure 13: Distribution function $p(\varepsilon, k)$ for the toral automorphism associated with the matrix $(1, 2; 2, 5)$.

permitted us to write the formula in eq. (63) that links return times statistics and Rényi entropies with $\eta$, the almost-sure value of the limit in eq. (10). This formula is an extension of that obtained for one-dimensional systems and we have conjectured that it should hold in much more general situations than the one presented in this paper.

As stated in the Introduction, the character of this paper is tailored to the audience expected for this volume, that comprises both specialists in dynamical systems and in other disciplines. We have therefore tried to present our results in the most transparent form, while renouncing at times to full rigor in favor of clarity. We are nonetheless convinced that most of the theory developed here touches upon new ideas and approaches, and presents more than valuable hints to where a rigorous treatment will be developed, as we plan to do in forecoming publications.

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