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CONSISTENCY OF RIDGE FUNCTION FIELDS FOR VARYING NONPARAMETRIC REGRESSION

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Abstract

A nonparametric regression model proposed in [Pelletier and Frouin, Applied Optics, 2006] as a solution to the geophysical problem of ocean color remote sensing is studied. The model, called ridge function field, combines a regression estimate in the form of a superposition of ridge functions, or equivalently a neural network, with the idea pertaining to varying-coefficients models, where the parameters of a parametric family are allowed to vary with other variables. Under mild assumptions on the underlying distribution of the data, the strong universal consistency of the least-squares ridge function fields estimate is established.

Index Terms — Varying coefficients model, ridge function approximation, nonparametric regression, universal consistency, least squares.

AMS 2000 Classification: 62G08, 62G05.

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1 Introduction

The motivation for the present work comes from the geophysical problem of ocean color remote sensing from space, which we shall describe first. In this problem, the aim is to predict the value of an oceanic parameter $Y$ (e.g., the surface phytoplankton pigment concentration) from a vector $X$ of radiometric measurements at several wavelengths acquired by a sensor onboard a satellite platform. This is in fact an inverse problem where the measurements $X$ depend on $Y$ and other parameters, such as the aerosol optical properties, through a given forward operator (governing the radiative transfer in the ocean-atmosphere system) contaminated by a random measurement noise. In particular, $X$ depends on a vector $T$ of angular variables describing the relative positions of the Sun and the sensor with respect to the target; as such, $T$ is observed simultaneously with $X$. The difficulty, though, is that the operator to be inverted, resulting from modeling of scattering and absorption processes at the micro-physical scale, is rather complex. To circumvent this issue, the approach taken up in Pelletier and Frouin (2004, 2006) and Frouin and Pelletier (2007) consists in i) sampling the forward operator according to some prior distribution, ii) selecting a reasonable noise model, and iii) estimating the regression function $m$ of $Y$ on $X$ and $T$ from the data $(X_1, T_1, Y_1), \ldots, (X_n, T_n, Y_n)$, where $m$ is defined by

$$m(x, t) = \mathbb{E}_{X=x, T=t} [Y | X, T].$$

In this display, the variable $T$ is independent from the response $Y$ but not from the predictor $X$. As such, $T$ acts as an effect modifier in the sense of Hastie and Tibshirani (1993) in the context of varying coefficient models, i.e., the shape of the relation explaining $Y$ from $X$ is affected by the values taken by $T$. Let us recall that a varying-coefficient model is a linear model the parameters of which are allowed to vary with other variables. Since the work of Hastie and Tibshirani (1993), varying-coefficient models have been studied by several authors (see e.g., Fan and Zhang, 1999, 2000; Fan, Yao, and Cai, 2003, Wong, Ip, and Zhang, 2008, and the references therein). By relaxing to some extent the parametric constraint, these models have proved useful in various application contexts, and in particular in a high-dimensional setting.

As pointed out by Hastie and Tibshirani (1993) as well as Fan and Zhang (1999), the idea of allowing the parameters of a linear model to vary with other variables
is not new, and is widely used in the literature. More generally, one may start with an arbitrary parametric family in place of a linear model, and allow its parameters to vary with other variables. This idea is developed in Pelletier and Frouin (2004, 2006) and Frouin and Pelletier (2007) where we considered models of the form

\[ \zeta_n^* : (x, t) \mapsto \zeta_n^*(x, t) := f(x; \theta_n(t)). \]

(1.1)

In model (1.1), the function \( f(\cdot; \theta_n) \) belongs to a set \( \mathcal{R}_n \) of functions, about which more will be said later, parameterized by a vector \( \theta_n \), which in (1.1) is allowed to vary with \( t \). Additionally, to obtain an implementable model, each coordinate map of the application \( t \mapsto \theta_n(t) \) in (1.1) is taken to lie in a parametric set \( \mathcal{T}_n \) of functions of \( t \). Now suppose that \( X \) and \( T \) are taking values in some subsets \( X \subseteq \mathbb{R}^d \) and \( S \subseteq \mathbb{R}^p \), respectively. Another way of formalizing this construction is to view the model (1.1) as a function of \( x \) being “attached” to each point \( t \) in \( S \), i.e., in mathematical terms, as a map

\[ \zeta_n : S \to \mathcal{R}_n, \]

(1.2)

such that the map \( \zeta_n^* \) in (1.1) is the representation of \( \zeta_n \) over the product space \( X \times S \), i.e., we let \( \zeta_n^*(x, t) = \zeta_n(t)(x) \). Thus the representation (1.2) highlights the fact that the variable \( T \) acts as an effect modifier.

In the experiments reported in Pelletier and Frouin (2004, 2006) and Frouin and Pelletier (2007), the sequence \( \mathcal{R}_n \) of functions in (1.2) is taken as the set spanned by functions of the ridge form or, equivalently, neural networks, and the resulting models (1.1)-(1.2) is called a ridge function field over \( S \). The sets \( \mathcal{R}_n \) form a nested sequence of the form \( \mathcal{R}_1 \subseteq \mathcal{R}_2 \subseteq \ldots \). There exists a vast literature on regression estimation with these ridge functions and neural networks. In particular, it is known that the union of sets spanned by ridge functions is dense in \( L_2(\mu) \), for any probability measure \( \mu \) (see, Cybenko, 1989; Hornik, Stinchcombe, and White, 1989; Barron, 1993; Lin and Pinkus, 1993; Burger and Neubaeur, 2001; Maiorov, 1999), and that they yield consistent nonparametric regression procedures (see e.g. Gyorfi, Kohler, Krzyzak, and Walk, 2002, Chapter 16). Similarly, the sets \( \mathcal{T}_n \) have been chosen to form an increasing sequence \( \mathcal{T}_1 \subseteq \mathcal{T}_2 \subseteq \ldots \) of sets of real-valued functions on \( S \).

Density results for ridge function fields have been obtained in Pelletier (2004) in the compact-open topology. In particular, under mild assumptions on the sets \( (\mathcal{R}_n)_n \) and \( (\mathcal{T}_n)_n \), the union of ridge function fields is dense. Thus under these conditions, ridge function fields are suitable candidates for nonparametric regression,
since the approximation error of the estimate will decrease to 0 as $n$ increases. The purpose of the present work is to establish the strong universal consistency of the least-squares regression estimate in the form of (1.1)-(1.2).

The paper is organized as follows. Section 2 introduces ridge function fields and presents our main result (Theorem 2.1), which states that ridge function fields adjusted by least squares are strongly universally consistent, i.e., that for any distribution of $(X, T, Y)$ satisfying mild assumptions, the $L_2$ error of the regression estimate converges to 0 with probability 1 as the sample size tends to infinity. Section 3 is devoted to the proof of Theorem 2.1.

## 2 Ridge function fields

Let $(X, T, Y)$ be a random object, where $X$, $T$, and $Y$ take values in $\mathbb{R}^d$, $\mathbb{R}^p$, and $\mathbb{R}$, respectively. We shall assume that $X$, $T$, and $Y$ are bounded, i.e., that there exists positive constants $C_X$, $C_T$ and $C_Y$ such that

$$|X| \leq C_X, \quad |T| \leq C_T, \quad |Y| \leq C_Y, \quad \text{with probability 1. \ (2.1)}$$

Given $n$ independent copies $(X_1, T_1, Y_1), \ldots, (X_n, T_n, Y_n)$ of $(X, T, Y)$, our aim is to construct an estimate of the regression function $m$ of $Y$ on the pair $(X, T)$, i.e.,

$$m(x, t) = \mathbb{E}[Y|(X, T) = (x, t)] .$$

Let us start with the definition of a ridge function. A ridge function on $\mathbb{R}^d$ is a function of the form $\sigma(\langle a, x \rangle)$ where $\sigma : \mathbb{R} \rightarrow \mathbb{R}$ is a given function, where $a \in \mathbb{R}^d$, and where $\langle \cdot, \cdot \rangle$ denotes the usual scalar product on $\mathbb{R}^d$. Approximation by ridge functions refers to approximation by linear combinations of ridge functions. There exists several variants of approximation by ridge functions, according to whether the function $\sigma$ is fixed or not. In the following, we shall consider the family $\mathcal{R}_n$ of functions on $\mathbb{R}^d$ defined by

$$\mathcal{R}_n = \left\{ x \mapsto \sum_{j=1}^{K_n} c_j \sigma(\langle a_j, x \rangle + b_j) + c_0 : a_j \in \mathbb{R}^d, b_j \in \mathbb{R}, c_0, c_j \in \mathbb{R}, j = 1, \ldots, K_n \right\} ,$$
where $K_n$ is an integer, and where $\sigma : \mathbb{R} \to \mathbb{R}$ is a fixed squashing function, i.e., $\sigma$ is nondecreasing, and satisfies the following two conditions:

$$\lim_{u \to -\infty} \sigma(u) = 0 \quad \text{and} \quad \lim_{u \to \infty} \sigma(u) = 1.$$ 

Next, let $\Psi_1, \Psi_2, \ldots : \mathbb{R}^p \to \mathbb{R}$ be bounded basis functions, the linear span of which is dense in $C(\mathbb{R}^p)$ in the topology of uniform convergence on compact sets, i.e., the set

$$\bigcup_{k=1}^{\infty} \{ t \mapsto \sum_{j=1}^{k} a_j \Psi_j(t) : a_1, \ldots, a_k \in \mathbb{R} \}$$

is dense in $C(\mathbb{R}^p)$. Without loss of generality, we assume that $|\Psi_i| \leq 1$ for all $i \geq 1$. Next, given an integer $L \in \mathbb{N}$ and a real number $\rho > 0$, we shall consider the following families of functions on $\mathbb{R}^p$:

$$T(L) = \left\{ t \mapsto \sum_{j=1}^{L} a_j \Psi_j(t) : a_1, \ldots, a_k \in \mathbb{R} \right\},$$

$$T_\rho(L) = \left\{ t \mapsto \sum_{j=1}^{L} a_j \Psi_j(t) : a_1, \ldots, a_k \in \mathbb{R}, \sum_{j=1}^{L} |a_j| \leq \rho \right\}.$$

Then, given integers $L_n^a$, $L_n^b$, and $L_n^c$, and a positive number $\rho_n$, we define the family $\mathcal{F}_n$ of ridge function fields by

$$\mathcal{F}_n = \left\{ (x, t) \mapsto \sum_{j=1}^{K_n} c_j(t) \sigma(\langle a_j(t), x \rangle + b_j(t)) + c_0(t) : a_j \in (T(L_n^a))^d, \right.$$ 

$$b_j \in T(L_n^b), c_0, c_j \in T_\rho_n(L_n^c), j = 1, \ldots, K_n \right\}.$$

We shall also consider the subset $\tilde{\mathcal{F}}_n$ of $\mathcal{F}_n$ where only the coefficients $c_j$ are allowed to vary with the variable $t$, i.e., we define

$$\tilde{\mathcal{F}}_n = \left\{ (x, t) \mapsto \sum_{j=1}^{K_n} c_j(t) \sigma(\langle a_j, x \rangle + b_j) + c_0(t) : a_j, b_j \in \mathbb{R}, c_0, c_j \in T_\rho_n(L_n^c), \right.$$ 

$$j = 1, \ldots, K_n \right\}.$$
Both sets $\mathcal{F}_n$ and $\widetilde{\mathcal{F}}_n$ are dense in the topology of uniform convergence on compact sets (Pelletier, 2004). Consequently, $\mathcal{F}_n$ and $\widetilde{\mathcal{F}}_n$ are also dense in $L^2$ for any distribution with bounded support and, as exposed in the Introduction, the approximation error of the estimates will decrease to 0 as $n \to \infty$.

Let us first define the maps $m_n^\dagger$ and $\tilde{m}_n^\dagger$ as any minimizer of the empirical $L^2$ risk over $\mathcal{F}_n$ and $\widetilde{\mathcal{F}}_n$, respectively, i.e., $m_n$ and $\tilde{m}_n$ are such that

$$\frac{1}{n} \sum_{i=1}^{n} \left( m_n^\dagger(X_i, T_i) - Y_i \right)^2 = \inf_{f \in \mathcal{F}_n} \frac{1}{n} \sum_{i=1}^{n} \left( f(X_i, T_i) - Y_i \right)^2, \quad (2.2)$$

$$\frac{1}{n} \sum_{i=1}^{n} \left( \tilde{m}_n^\dagger(X_i, T_i) - Y_i \right)^2 = \inf_{\tilde{f} \in \tilde{\mathcal{F}}_n} \frac{1}{n} \sum_{i=1}^{n} \left( \tilde{f}(X_i, T_i) - Y_i \right)^2. \quad (2.3)$$

Then we define the estimates $m_n$ and $\tilde{m}_n$ as truncated versions of $m_n^\dagger$ and $\tilde{m}_n^\dagger$ respectively, i.e.,

$$m_n(x, t) = T_{\beta_n} m_n^\dagger(x, t), \quad (2.4)$$

$$\tilde{m}_n(x, t) = T_{\beta_n} \tilde{m}_n^\dagger(x, t), \quad (2.5)$$

where $(\beta_n)_n$ is a sequence of positive numbers such that $\beta_n \to \infty$, and where $T_{\beta_n}$ is the truncation operator defined by $T_{\beta_n} u = \min\{|u|, \beta_n\} \text{sign}(u)$.

We are now in a position to state our main result.

**Theorem 2.1** Let $m_n$ and $\tilde{m}_n$ be the truncated least-squares estimates defined by (2.2), (2.3), (2.4), and (2.5).

(i) If

$$K_n \to \infty, \quad L_n^a \to \infty, \quad L_n^b \to \infty, \quad L_n^c \to \infty, \quad \beta_n \to \infty, \quad \rho_n \to \infty,$$

as $n \to \infty$ in such a way that

$$\frac{K_n \beta_n^4 (L_n^a + L_n^b + L_n^c)}{n} \log(\beta_n \rho_n K_n) \to 0 \quad \text{and} \quad \frac{\beta_n^4}{n^{1-\delta}} \to 0,$$

for some $\delta > 0$ as $n \to \infty$, then

$$\lim_{n \to \infty} \int (m_n(x, t) - m(x, t))^2 \mu(dx, dt) = 0 \quad \text{with probability 1},$$

for every distribution of $(X, T, Y)$ satisfying (2.1).
(ii) If
\[ K_n \to \infty, \quad L_n^c \to \infty, \quad \beta_n \to \infty, \quad \text{and} \quad \rho_n \to \infty, \]
as \( n \to \infty \) in such a way that
\[ \frac{K_n \beta_n^4 L_n \log(\beta_n \rho_n K_n)}{n} \to 0 \quad \text{and} \quad \frac{\beta_n^4}{n^{1-\delta}} \to 0, \]
for some \( \delta > 0 \) as \( n \to \infty \), then
\[ \lim_{n \to \infty} \int (\tilde{m}_n(x, t) - m(x, t))^2 \mu(dx, dt) = 0 \quad \text{with probability 1}, \]
for every distribution of \((X, T, Y)\) satisfying (2.1).

Theorem 2.1 states that nonparametric regression estimation with ridge function fields is a consistent procedure as long as the underlying distribution satisfies (2.1). Note first that the extension to a multivariate response \(Y\) is straightforward, and second that the family \(\tilde{\mathcal{F}}_n\) is a subset of the family \(\mathcal{F}_n\). Consequently, \(\mathcal{F}_n\) offers more flexibility than \(\tilde{\mathcal{F}}_n\) but, as expected, at the expense of an increased complexity of the fitting algorithm. More generally, one may consider replacing the family \(\mathcal{R}_n\) in the definition of a set of function fields by any other nested sequence of models used in nonparametric regression. That said, regarding the ocean color remote sensing problem, the choice of using ridge functions has been dictated not only by their approximation properties, but more importantly by the speed of execution of these models, which should be high for processing large data sets, as provided by satellite imagery. Models belonging to \(\mathcal{F}_n\) have been implemented and evaluated in Pelletier and Frouin (2006) for the retrieval of the chlorophyll-a concentration, i.e., a univariate response, while the family \(\tilde{\mathcal{F}}_n\) has been used in Frouin and Pelletier (2007) for the retrieval of the spectral marine reflectance, a multivariate output. In practice, the minimization of the empirical \(L_2\) risk in (2.2) and (2.3) may be solved using a stochastic gradient descent algorithm (see Pelletier and Frouin, 2006 for details).

Let us also mention that assumption (2.1), which is reasonable from a physical perspective, may be weakened at the price of a little extra work. As a matter of fact, one may assume that the response \(Y\) is unbounded and use a truncation argument, as in, e.g., Kohler and Krzyzak (2005), and Gyorfi, Kohler, Krzyzak, and Walk (2002, Theorem 10.2). Next, if \(X\) and \(T\) are unbounded, it is immediate to show that the union of the sets \(\mathcal{F}_n\) is dense in \(L_2(\mu)\) for any distribution \(\mu\).
provided that the sets $T(L)$ contain the constant and affine functions of $t$. On the other hand, a little extra work would be needed to derive the density in $L_2$ of the union of the $\mathcal{F}_n$'s. The study of the convergence rates is left for future research. In this perspective, let us emphasize that the respective influences of the variables $X$ and $T$ on the response $Y$ are well separated in a ridge function field, by construction, which may prove useful for adaptation over anisotropic classes of regression functions (see e.g. Hofmann and Lepski, 2002).

3 Proofs

3.1 Technical Lemmas

We shall need the following technical Lemmas to derive an upper-bound on the covering number of $\mathcal{F}_n$. Let us start by introducing the notations and definitions used hereafter.

First of all, let $\mathcal{G}$ be a set of real valued functions on $\mathbb{R}^d$, and let $x_1, \ldots, x_n$ be $n$ fixed points in $\mathbb{R}^d$. For any functions $g_1, g_2 : \mathbb{R}^d \to \mathbb{R}$, set

$$\text{dist}_{1,n}(g_1, g_2) = \mathbb{P}_n(1 - |g_1 - g_2|),$$

where $\mathbb{P}_n$ is the discrete uniform measure on $\{x_1, \ldots, x_n\}$. The $\varepsilon$-covering number of $\mathcal{G}$ with respect to $\text{dist}_{1,n}$ is called the $L_1 \varepsilon$-covering number of $\mathcal{G}$ on $\{x_1, \ldots, x_n\}$ and will be denoted by $\mathcal{N}_1(\varepsilon, \mathcal{G}, x_1^n)$, i.e., $\mathcal{N}_1(\varepsilon, \mathcal{G}, x_1^n)$ is the smallest integer $N$ such that there exists functions $g_1, \ldots, g_n$ such that

$$\min_{1 \leq j \leq N} \frac{1}{n} \sum_{i=1}^{n} |g_j(x_i) - g_j(x_i)| \leq \varepsilon,$$

for all $g \in \mathcal{G}$.

Similarly to the above, the $L_1 \varepsilon$-packing number of $\mathcal{G}$ on $\{x_1, \ldots, x_n\}$, further denoted by $\mathcal{M}_1(\varepsilon, \mathcal{G}, x_1^n)$, is the maximal integer $N$ such that there exists functions $g_1, \ldots, g_N$ in $\mathcal{G}$ such that

$$\frac{1}{n} \sum_{i=1}^{n} |g_j(x_i) - g_k(x_i)| \geq \varepsilon,$$
for all $1 \leq j < k \leq N$.

Finally, $\mathcal{G}^+$ will denote the set of all subgraphs of functions in $\mathcal{G}$, i.e.,
\[
\mathcal{G}^+ = \{(x, u) \in \mathbb{R}^d \times \mathbb{R} : u \leq g(x), g \in \mathcal{G}\},
\]
and the Vapnik-Chervonenkis dimension of $\mathcal{G}^+$ will be denoted by $V_{\mathcal{G}^+}$ (Vapnik and Chervonenkis, 1971).

The following results, extracted from Lemmas 16.3, 16.4, and 16.5 in Győrfi, Kohler, Krzyzak, and Walk (2002), will be needed in the following, and are given to make the paper self-contained. Let $\mathcal{F}$ be a set of functions $\mathbb{R}^d \to \mathbb{R}$. Given a squashing function $\sigma$, define $\mathcal{G} = \{\sigma \circ f : f \in \mathcal{F}\}$. Then
\[
V_{\mathcal{G}^+} \leq V_{\mathcal{F}^+}. \tag{3.1}
\]

Given two sets $\mathcal{F}$ and $\mathcal{G}$ of functions $\mathbb{R}^d \to \mathbb{R}$, set $\mathcal{F} \oplus \mathcal{G} = \{f + g : f \in \mathcal{F}, g \in \mathcal{G}\}$, and let $\{x_1, \ldots, x_n\}$ be $n$ points in $\mathbb{R}^d$. Then
\[
N_1(\varepsilon + \delta, \mathcal{F} \oplus \mathcal{G}, x_1^n) \leq N_1(\varepsilon, \mathcal{F}, x_1^n)N_1(\delta, \mathcal{G}, x_1^n). \tag{3.2}
\]

Given two sets $\mathcal{F}$ and $\mathcal{G}$ of functions $\mathbb{R}^d \to \mathbb{R}$, uniformly bounded over $\mathbb{R}^d$ by some constants $C_\mathcal{F}$ and $C_\mathcal{G}$, respectively, set $\mathcal{F} \odot \mathcal{G} = \{fg : f \in \mathcal{F}, g \in \mathcal{G}\}$, and let $\{x_1, \ldots, x_n\}$ be $n$ points in $\mathbb{R}^d$. Then
\[
N_1(\varepsilon + \delta, \mathcal{F} \odot \mathcal{G}, x_1^n) \leq N_1(\varepsilon/C_\mathcal{G}, \mathcal{F}, x_1^n)N_1(\delta/C_\mathcal{F}, \mathcal{G}, x_1^n). \tag{3.3}
\]

At last, given a set $\mathcal{G}$ of functions $\mathbb{R}^d \to [0; B]$ with $V_{\mathcal{G}^+} \geq 2$, $n$ points $\{x_1, \ldots, x_n\}$ in $\mathbb{R}^d$, and $0 < \varepsilon < B/4$, we have (Győrfi, Kohler, Krzyzak, and Walk (2002), Theorem 9.4)
\[
\mathcal{M}_1(\varepsilon, \mathcal{G}, x_1^n) \leq 3\left(\frac{2eB}{\varepsilon} \log \frac{3eB}{\varepsilon}\right)^{V_{\mathcal{G}^+}}. \tag{3.4}
\]

We may now state an upper-bound on the covering number of $\mathcal{F}_n$.

**Lemma 3.1** Let $N_1(\varepsilon, \mathcal{F}_n, (X, T)_1^n)$ be the $L_1$ $\varepsilon$-covering number of $\mathcal{F}_n$ on the sample $(X_1, T_1), \ldots, (X_n, T_n)$. Then
\[
N_1(\varepsilon, \mathcal{F}_n, (X, T)_1^n) \leq 3\left(\frac{108e\rho_n(K_n + 1)}{\varepsilon}\right)^{2L_n^d + 2K_n(L_n^d + L_n^d + L_n^d + 2)} \tag{3.5}
\]

Proof. Consider the following sets of functions:

\[ G_1 = \{(x, t) \mapsto \langle a(t), x \rangle + b(t) : a_1, \ldots, a_d \in T(L_a^n), b \in T(L_b^n)\}, \]

\[ G_2 = \{(x, t) \mapsto \sigma(\langle a(t), x \rangle + b(t)) : a_1, \ldots, a_d \in T(L_a^n), b \in T(L_b^n)\}, \]

\[ G_3 = \{(x, t) \mapsto c(t) \sigma(\langle a(t), x \rangle + b(t)) : a_1, \ldots, a_d \in T(L_a^n), b \in T(L_b^n), c \in T(\rho_n(L_c^n))\}. \]

Since \( G_1 \) is a vector space of dimension \( L_a^n d + L_b^n \), we have

\[ V_{G_1^+} \leq L_a^n d + L_b^n + 1. \]

Next, (3.1) yields

\[ V_{G_2^+} \leq V_{G_1^+}. \]

Consequently, since \( |\sigma(u)| \leq 1 \) for all \( u \in \mathbb{R} \), and using (3.4), we obtain

\[
\mathcal{N}_1(\varepsilon, G_2, (X, T)^n_1) \leq \mathcal{M}_1(\varepsilon, G_2, (X, T)^n_1) \\
\leq 3 \left[ \frac{2e}{\varepsilon} \log \left( \frac{3e}{\varepsilon} \right) \right] V_{G_2^+} \\
\leq 3 \left( \frac{3e}{\varepsilon} \right)^{2(L_a^n d + L_b^n + 1)}. \quad (3.6)
\]

Now, using the inequality (3.3) leads to

\[
\mathcal{N}_1(\varepsilon, G_3, (X, T)^n_1) \leq \mathcal{N}_1\left(\frac{\varepsilon}{2}, T_{\rho_n}(L_c^n), (X, T)^n_1\right) \mathcal{N}_1\left(\frac{\varepsilon}{2}, G_2, (X, T)^n_1\right). 
\]

But, using (3.4), we have

\[
\mathcal{N}_1(\varepsilon, T_{\rho_n}(L_c^n), (X, T)^n_1) \leq \mathcal{M}_1(\varepsilon, T_{\rho_n}(L_c^n), (X, T)^n_1) \\
\leq 3 \left[ \frac{2e(2\rho_n)}{\varepsilon} \log \left( \frac{3e(2\rho_n)}{\varepsilon} \right) \right] V_{T_{\rho_n}(L_c^n)+} \\
\leq 3 \left( \frac{6e\rho_n}{\varepsilon} \right)^{2(L_c^n + 1)}. \quad (3.7)
\]

since

\[ V_{T_{\rho_n}(L_c^n)+} \leq V_{T(L_c^n)+} \leq L_c^n + 1, \]
and since $\mathcal{T}(L_n^c)$ is a vector space of dimension $L_n^c$. Then from (3.6) and (3.7), it follows that

$$
\mathcal{N}_1(\varepsilon, \mathcal{G}_3, (X, T)_1^n) \leq 3 \left( \frac{6\rho_n}{\varepsilon/2} \right)^{2(L_n^c+1)} \left( \frac{3e}{\varepsilon/(2\rho_n)} \right)^{2(L_n^d+L_n^b+1)} \\
= 9 \left( \frac{12\rho_n}{\varepsilon} \right)^{2(L_n^c+1)} \left( \frac{6\rho_n}{\varepsilon} \right)^{2(L_n^d+L_n^b+1)} \\
\leq 9 \left( \frac{12\rho_n}{\varepsilon} \right)^{2(L_n^d+L_n^b+L_n^c+2)} . \quad (3.8)
$$

Applying (3.2) yields

$$
\mathcal{N}_1(\varepsilon, \mathcal{F}_n, (X, T)_1^n) \leq \mathcal{N}_1\left( \frac{\varepsilon}{K_n+1}, T_{\rho_n}(L_n^c), (X, T)_1^n \right) \left[ \mathcal{N}_1\left( \frac{\varepsilon}{K_n+1}, \mathcal{G}_3, (X, T)_1^n \right) \right]^{K_n}.
$$

Finally, by reporting (3.7) and (3.8) in the equation above, we obtain the upper bound:

$$
\mathcal{N}_1(\varepsilon, \mathcal{F}_n, (X, T)_1^n) \leq 3 \left( \frac{6\rho_n}{\varepsilon/(K_n+1)} \right)^{2(L_n^c+1)} \left[ 9 \left( \frac{12\rho_n}{\varepsilon/(K_n+1)} \right)^{2(L_n^d+L_n^b+L_n^c+2)} \right]^{K_n} \\
\leq 3 \left( \frac{108\rho_n(K_n+1)}{\varepsilon} \right)^{2(L_n^c+1)+2K_n(L_n^d+L_n^b+L_n^c+2)} .
$$

3.2 Proof of Theorem 2.1

By Lemma 10.2 in Gyorfi, Kohler, Krzyzak, and Walk (2002), we have the inequality

$$
\int \left| m_n(x, t) - m(x, t) \right|^2 \mu(dx, dt) \\
\leq \inf_{\{f \in \mathcal{F}_n : \|f\|_{\infty} \leq \beta_n\}} \int \left| f(x, t) - m(x, t) \right| \mu(dx, dt) \\
+ 2 \sup_{f \in \mathcal{T}_{\beta_n}} \left| \frac{1}{n} \sum_{i=1}^{n} (f(X_i, T_i) - Y_i)^2 - \mathbb{E} \left\{ (f(X_i, T_i) - Y_i)^2 \right\} \right|, \quad (3.9)
$$
where the first term is the approximation error, and where the second term is a uniform upper-bound over $T_{β_n}F_n$ of the estimation error. Since the union of the $F_n$'s is dense in $C(\mathbb{R}^d \times \mathbb{R}^p)$ in the topology of uniform convergence on compact sets, and since $X$ and $T$ are bounded by assumption, the union of the $F_n$'s is dense in $L_2(\mu)$ for every $\mu$ with bounded support. Then it follows that the approximation error of $m$ by an element of $\{f \in F_n : \|f\|_\infty \leq \beta_n\}$ converges to zero as $K_n, L^a_n, L^b_n, L^c_n, \beta_n, \rho_n \to \infty$, and part (i) of the theorem will be proved if we show that

$$\sup_{f \in T_{β_n}F_n} \left| \frac{1}{n} \sum_{i=1}^{n} (f(X_i, T_i) - Y_i)^2 - \mathbb{E}\left\{ (f(X_i, T_i) - Y_i)^2 \right\} \right| \to 0, \quad (3.10)$$

a.s. as $K_n, L^a_n, L^b_n, L^c_n, \beta_n, \rho_n \to \infty$. The same arguments hold for the family $\tilde{F}_n$, so that part (ii) of the theorem will be proved if we show that (3.10) is satisfied with $T_{β_n}F_n$ replaced by $T_{β_n}\tilde{F}_n$.

To bound the second term in the right hand side of (3.9), let us first define the set $\mathcal{H}_n$ of functions by

$$\mathcal{H}_n = \{ h : \mathbb{R}^d \times \mathbb{R}^p \times \mathbb{R} \ni (x, t, y) \mapsto |f(x, t) - y|^2 1_{[-C_Y; C_Y]}(y) : f \in T_{β_n}F_n \},$$

where $1_{[-C_Y; C_Y]}(.)$ is the characteristic function of the interval $[-C_Y; C_Y]$. Next, we shall set $Z_i = (X_i, T_i, Y_i)$, for $i = 1, \ldots, n$.

For every $f$ in $T_{β_n}F_n$, we have $|f(x, t)| \leq \beta_n$. Hence for $n$ large enough such that $C_Y \leq \beta_n$,

$$|f(x, t) - y|^2 1_{[-C_Y; C_Y]}(y) \leq 4\beta^2_n,$$

so that the range of each function $h$ in $\mathcal{H}_n$ is included in the interval $[0; 4\beta^2_n]$. Then from the proof of Theorem 24 in Pollard (1984, p. 25), or Theorem 9.1 in Györfi, Kohler, Krzyżak, and Walk (2002, p. 136), we obtain for any $\varepsilon > 0$ the following inequality:

$$\mathbb{P} \left\{ \sup_{f \in T_{β_n}F_n} \left| \frac{1}{n} \sum_{i=1}^{n} |f(X_i, T_i) - Y_i|^2 - \mathbb{E}\left\{ |f(X, T) - Y|^2 \right\} \right| > \varepsilon \right\} = \mathbb{P} \left\{ \sup_{h \in \mathcal{H}_n} \left| \frac{1}{n} \sum_{i=1}^{n} h(Z_i) - \mathbb{E}\{ h(Z) \} \right| > \varepsilon \right\} \leq 8\mathbb{E}N_1 \left( \frac{\varepsilon}{8}, \mathcal{H}_n, Z^1_n \right) \exp \left( - \frac{n\varepsilon^2}{128(4\beta^2_n)^2} \right). \quad (3.11)$$

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Now we proceed to bound the covering number in (3.11). Given $h_1$ and $h_2$ in $H_n$, corresponding respectively to $f_1$ and $f_2$ in $T_{\beta_n}F_n$, we have

$$\frac{1}{n} \sum_{i=1}^{n} |h_1(Z_i) - h_2(Z_i)| \leq 4\beta_n \frac{1}{n} \sum_{i=1}^{n} |f_1(X_i, T_i) - f_2(X_i, T_i)|,$$

(3.12)

since $|f(x, t)| \leq \beta_n$ for every $f$ in $T_{\beta_n}F_n$, and since $|Y| \leq C_Y \leq \beta_n$ a.s. for $n$ large enough. Therefore, if $f_1, \ldots, f_N$ is a $L_1$-cover of $T_{\beta_n}F_n$ on $(X_1, T_1), \ldots, (X_n, T_n)$ with

$$N = N_1(\varepsilon, T_{\beta_n}F_n, (X, T)_n),$$

there exists a $L_2$-cover $f'_1, \ldots, f'_N$ of $T_{\beta_n}F_n$ on $(X, T)_n$ with $f'_j \in T_{\beta_n}F_n$, for all $j = 1, \ldots, n$. Then using the inequality (3.12) we conclude that

$$N_1\left(\frac{\varepsilon}{8}, H_n, Z_n^1\right) \leq N_1\left(\frac{\varepsilon}{64\beta_n}, T_{\beta_n}F_n, (X, T)_n\right).$$

(3.13)

Using Lemma 3.1 together with the fact that $N_1(\varepsilon, T_{\beta_n}F_n, (X, T)_n) \leq N_1(\varepsilon, F_n, (X, T)_n)$, it follows that

$$\mathbb{P}\left\{ \sup_{f \in T_{\beta_n}F_n} \left| \frac{1}{n} \sum_{i=1}^{n} |f(X_i, T_i) - Y_i|^2 - \mathbb{E}\{|f(X, T) - Y|^2\} \right| > \varepsilon \right\} \leq 24 \left( \frac{6912\beta_n\rho_n(K_n + 1)}{\varepsilon} \right)^{2(\beta_n^\Delta + 1) + 2K_n(L_n^a d + L_n^b + L_n^c + 2)} \times \exp \left( - \frac{n\varepsilon^2}{2048\beta_n^4} \right)$$

$$= 24 \exp \left\{ - n^{1-\delta} \left[ \frac{\varepsilon^2}{2048} - \frac{2\beta_n^4 [L_n^a + 1 + K_n(L_n^a d + L_n^b + L_n^c + 2)]}{n} \right] \right\},$$

(3.14)

for some $\delta > 0$. 

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Consequently, if
\[ K_n \to \infty, \quad L^a_n \to \infty, \quad L^b_n \to \infty, \quad L^c_n \to \infty, \quad \beta_n \to \infty, \quad \rho_n \to \infty, \]
as \( n \to \infty \) in such a way that
\[ \frac{K_n \beta^4_n (L^a_n + L^b_n + L^c_n) \log(\beta_n \rho_n K_n)}{n} \to 0 \quad \text{and} \quad \frac{\beta^4_n}{n^{1-\delta}} \to 0, \]
for some \( \delta > 0 \) as \( n \to \infty \), we deduce from (3.14) that
\[ \sum_{n \geq 1} \mathbb{P}\left\{ \sup_{f \in \mathcal{T}_{\beta_n \rho_n \mathcal{F}_n}} \frac{1}{n} \sum_{i=1}^{n} |f(X_i, T_i) - Y_i|^2 - \mathbb{E}\{|f(X, T) - Y|^2\}| > \varepsilon \right\} < \infty. \] (3.15)

Part (i) of Theorem 2.1 then follows from the Borel-Cantelli Lemma.

To prove part (ii), it suffices to set \( L^a_n = 1 \) and \( L^b_n = 1 \). Then one obtains (3.15) from (3.14) if
\[ K_n \to \infty, \quad L^c_n \to \infty, \quad \beta_n \to \infty, \quad \text{and} \quad \rho_n \to \infty, \]
as \( n \to \infty \) in such a way that
\[ \frac{K_n \beta^4_n L^c_n \log(\beta_n \rho_n K_n)}{n} \to 0 \quad \text{and} \quad \frac{\beta^4_n}{n^{1-\delta}} \to 0, \]
for some \( \delta > 0 \) as \( n \to \infty \), which together with the Borel-Cantelli Lemma concludes the proof of the second part of Theorem 2.1.

\[ \square \]

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