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INFLUENCE OF THE SPRAY RETROACTION ON THE AIRFLOW

L. BOUDIN\textsuperscript{1, 2}, C. GRANDMONT\textsuperscript{2}, B. GREC\textsuperscript{3, 4} AND D. YAKOUBI\textsuperscript{2}

Abstract. In this work, we investigate the influence of a spray evolving in the air, in the respiration framework. We consider two kinds of situations: a moving spray in a motionless fluid, and motionless particles in a Poiseuille flow. We observe that the spray retroaction may not be neglected in some situations which can really happen, for instance, when one considers rather big particles, as it is possible for polluting particles and even for some therapeutic aerosols. The retroaction is even responsible for increasing the deposition phenomenon.

1. INTRODUCTION

From therapeutic aerosols to polluting particles, a large scale of sprays, with respect to the particle densities, sizes or velocities, often interferes with our respiratory system. The spray inhalation may induce a mechanical effect during the breathing process. Indeed, the presence of particles in the airways can disturb the airflow itself. In this work, we study the influence of the spray on the airflow. The fluid has an indisputable effect on the spray through a drag (or friction) force. Conversely, one can very often find in the literature that the so-called retroaction of the spray on the air is neglected, see [7, 13] for instance. This work aims to quantify this statement, as it was not investigated yet, up to our knowledge, noting that in [9], for instance, the retroaction is taken into account in the model and the computations.

We do not tackle the question of the lung, airflow and spray models in this work. As in [3, 4, 6, 11, 12, 16, 19, 20], we assume that the airways have a tree structure, that the airflow obeys the incompressible Navier-Stokes equations down to the sixteenth generation of the respiratory tract, and that the spray is described by a Vlasov equation. The action of the spray appears as a source term in the Navier-Stokes equations. The relevance of the presence of this term is the main topic of this paper. Since the spray has first a local effect, we must point out that our study does not imply using biologically realistic geometries for the computations, so they are performed on a simple straight tube. Nevertheless, we also obtain global effects of the retroaction in our study, in particular on the spray deposition, which can be surprising at first glance.

The latter effect, i.e. the influence of the retroaction on the aerosol deposition, is one of the topics of an ongoing work in a more realistic three-dimensional setting, like a 3D branch. This work must be seen as the first step of the study of this retroaction term.

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The paper is organized as follows. In the next section, we briefly describe our aerosol-air model originally presented in [4,6]. Then, in Sections 3 and 4, we study the influence of the aerosol on the air, in the case when the aerosol and air velocities do not have the same order of magnitude, i.e. when the spray is injected in a tube where the air is motionless, and when there are motionless particles in a Poiseuille profiled airflow. Eventually, in Section 5, we give some hints on the situations when one must take the retroaction into account in the model.

2. AEROSOL MODELLING AND SIMULATION

2.1. Model

The situations we deal with in this work are only two-dimensional, but the model also holds for three dimensions [4,6,9,17]. The airflow can be described by its velocity field \( u(t, x) \in \mathbb{R}^2 \) and the pressure \( p(t, x) \in \mathbb{R} \), where \( t \geq 0 \) is the time and \( x = (x_1, x_2) \in \mathbb{R}^2 \) is the space location. Since the air is assumed to be incompressible, the air density remains constant, denoted by \( \rho_{\text{air}} \). Inside the human body, at temperature \( 310 \text{ K} \), one can take \( \rho_{\text{air}} = 1.11 \text{ kg.m}^{-3} \). Let us also denote \( \nu \) the air kinematic viscosity and \( \mu = \rho_{\text{air}} \nu \) the dynamic one. A standard value of \( \mu \) is \( 10^{-5} \text{ kg.m}^{-1}.\text{s}^{-1} \). The previous values can be found, for instance, in [1].

The spray itself is described by a probability density function (PDF), which we denote \( f \). The PDF depends not only on \( t \) and \( x \), but also on the velocity \( v \in \mathbb{R}^2 \). In fact, \( f \) can also depend on the particle radius \( r \) (we here assume that the particles remain spherical) or the temperature. Let us emphasize that we do not take into account any phenomenon modifying the aerosol radius distribution (no collision, no abrasion, etc.). This means that the initial radius distribution is conserved. Therefore, the radius does not appear as a variable in the equations, but only as a parameter. The dependence of \( f \) on \( r \) allows to send particles with various radii in the computational domain \( \Omega \). Dependence on temperature is not discussed here, but one can easily admit that, for instance, the temperature variation has a negligible influence on the phenomena in the airways, in standard conditions.

In the following, we assume that the aerosol is also an incompressible fluid very similar to water, so that its volume mass \( \rho_{\text{aero}} \) can be chosen as \( \rho_{\text{aero}} = 1000 \text{ kg.m}^{-3} \). Then, for each particle with radius \( r \), we can define its mass \( m(r) = 4/3 \pi r^3 \rho_{\text{aero}} \). One must keep in mind that, in the case of polluting sprays, the volume mass may be bigger, and the retroaction effect on the aerosol may then be significantly increased.

The quantity \( f(t, x, v, r) \, dr \, dv \, dx \) is then the number of particles at time \( t \) inside the elementary volume centered at \( (x, v, r) \) in the phase space. Eventually, here is the full system satisfied by \( f \), \( u \) and \( p \):

\[
\begin{align*}
\partial_t u + \nabla_x \cdot (u \otimes u) - \nu \Delta_x u + \frac{\nabla_x p}{\rho_{\text{air}}} &= \frac{F_{\text{aero}}}{\rho_{\text{air}}}, \\
\nabla_x \cdot u &= 0, \\
\partial_t f + \nabla_x \cdot (vf) + \nabla_v \cdot (af) &= 0,
\end{align*}
\]

where \( a \) is the particle acceleration, mainly due here to the Stokes force exerted on the aerosol by the fluid, and is given by

\[
a(t, x, v, r) = \frac{6\pi \mu r}{m(r)} (u(t, x) - v),
\]

and \( F_{\text{aero}} \) is the force exerted by the aerosol on the air, that is

\[
F_{\text{aero}}(t, x) = -\int_{\mathbb{R}^2 \times \mathbb{R}_+} f(t, x, v, r) \, m(r) \, a(t, x, v, r) \, dv \, dr = 6\pi \mu \int_{\mathbb{R}^2} \int_{\mathbb{R}_+} r \, f(t, x, v, r) \, (v - u(t, x)) \, dv \, dr.
\]

The last term \( F_{\text{aero}} \) is the one we discuss in this paper. We shall often compare results when \( F_{\text{aero}} = 0 \) or is given by (5) to fill in (1). The system (1)–(5) was mathematically investigated (global in time existence) in [5] in a periodic in space framework, and without any dependence on \( r \) (see also [2]).

We focus on a very simple geometry, namely a two-dimensional tube \( \Omega = (0, L) \times (0, D) \), see Figure 1. In fact, since the retroaction is first a local phenomenon (the particles first act on the fluid nearby), we do not need
to consider a biologically realistic computational domain. However, we will point out that some global major effects appear because of the retroaction. The boundary $\Gamma = \partial \Omega$ of the computational domain we consider is divided into three areas: the inlet $\Gamma_{\text{in}}$, the outlet $\Gamma_{\text{out}}$, and the wall $\Gamma_{\text{wall}}$. We use $D = 0.02 \, \text{m}$ and $L = 0.5 \, \text{m}$. The value of $D$ we choose here has the typical order of magnitude of the diameter of a human trachea [21]. The choice of $L$ allows to capture the behaviours of the quantities we are interested in, away from the particles locations.

Equations (1)–(5) can then be supplemented with boundary conditions:

\begin{align*}
  u(t, x) &= 0 \quad \text{if } x \in \Gamma_{\text{wall}}, \\
  f(t, x, v, r) &= \tilde{f}(t, x, v, r) \quad \text{if } x \in \Gamma_{\text{in}}, \\
  f(t, x, v, r) &= 0 \quad \text{if } x \in \Gamma_{\text{wall}} \text{ and } v \cdot n < 0.
\end{align*}

On the inlet and the outlet, we shall consider different boundary conditions on the fluid velocity, depending on the physical test cases we are interested in. These boundary conditions are explicitly given in each section. Condition (8) has been discussed in [6], $n$ being the outgoing normal vector to $\Gamma$ at the point of interest. In the airways, it means that whenever the particles hit the walls, they are immediately absorbed by the mucus.

2.2. Numerical solving

The airflow is solved by a standard $P^2$ (for the velocity) and $P^1$ (for the pressure) finite element computation (see [10] for instance), and the aerosol by a particle method (see [18] for example). We do not give any detail on the fluid computation, since (1)–(2) with standard boundary conditions are solved thanks to a Navier-Stokes routine using the Freefem++ software [14]. For the particle method, we have to distinguish the physical particles from the numerical ones. The total number of numerical particles $N$ is almost always much smaller than the number of real physical particles $N_P$. The PDF $f$ can discretized in the following way

\[ f(t, x, v, r) = \sum_{p=1}^{N} \omega_p(t) \delta_{x_p(t)}(x) \delta_{v_p(t)}(v) \delta_{r_p(t)}(r), \]

where $t \mapsto (x_p(t), v_p(t), r_p(t))$ is the trajectory of the numerical particle $p$ in the phase space, and $\omega_p(t)$ its representativity at time $t$. A numerical particle $p$ gives an average behaviour of a set of physical particles. The average value of $\omega_p$ is approximately of order $N_P/N$. Note that, when discretizing (1)–(3), the representativity $\omega_p$ only appears in the discretized version of (5), and not in the one of (4). We only use one constant value of $\omega_p$ in each numerical test.

In our numerical scheme, the coupling is explicit and solved only once at each time step. When there is no retroaction, in order to optimize the computational cost, one can set two different time steps, one for the fluid and one for the spray. Here, since we consider the spray retroaction on the air, we are forced to use exactly the same time step for the air and the particles to ensure that the momentum exchange between both
phases happens whenever the velocities are modified. Note that, when we lower the time step, which satisfies a CFL-like condition, we obtain the same numerical results.

The mesh which was used in our computations has 1139 vertices and 1978 triangles, and \( \delta x \simeq 3 \times 10^{-3} \text{m} \), where \( \delta x \) is a characteristic size of a cell.

In order to emphasize the retroaction effect, it is important to set a dynamic unbalance between the spray and the fluid. Indeed, if they both share the same velocity, the term \( F_{\text{aero}} \) is obviously equal to zero, and there is no retroaction at all. For instance, it is clear that the retroaction effect is strong in the following situation: consider a domain of interest which has the form of a “T” letter, where the air arrives from the left horizontal part of the domain, and the spray by its lower part. The air velocity is then normal to the particles velocities, and the retroaction induces non-zero components on the initially nil velocity components, for each phase.

Nevertheless, even without precisely studying the latter, we recover most situations of interest on the retroaction by numerically investigating two cases. The first one, in Section 3, is dedicated to a spray which goes in an initially motionless fluid, and the second one, in Section 4 to a motionless spray which is put into a Poiseuille airflow. As the reader will see, most numerical results are not surprising, they only allow to control the model and code validity. But we also obtain a more surprising side effect: the wall deposition in the tube of the bigger particles \( (r = 50 \mu\text{m}) \). Such radii correspond to polluting particles, but also to some therapeutic aerosols.

3. Moving Spray in an Initially Motionless Fluid

The first set of computational results is obtained in the case of one or several injections of particles in an initially motionless fluid. There are exactly 100 numerical particles per injection. Their representativity varies with respect to the number of injections, in such a way that the number of physical particles never exceeds \( 10^{10} \), which is the limit for most commercial nebulizers, see [17]. In each case, the particles are initially uniformly distributed on the tube inlet with an incoming velocity \( v_0 \), the value of which is either 0.1 m.s\(^{-1}\) or 1 m.s\(^{-1}\).

Note that we decided not to put particles near the wall, since the retroaction effect induced by a particle near the wall is nil: there, the air velocity remains equal to 0, and the particles would immediately deposit.

Thanks to the retroaction term \( F_{\text{aero}} \), the particles induce a non-zero velocity field in the fluid. We show that this effect is almost instantaneous and may not be neglected in some situations.

3.1. Choice of the representativity

We first take \( v_0 = 1 \text{ m.s}^{-1} \) and \( r = 50 \mu\text{m} \). The discretization we performed for the PDF induces two different numbers of particles: the number of numerical particles \( N \) and the number of physical particles \( N_P \). We plot the fluid velocity for different repartitions between the representativity and the number of numerical particles leading to the same number of physical particles \( N_P = 10^{10} \) on Figure 2.

![Figure 2. Influence of \( N \) on the computation when \( N_P \) is constant](image-url)
We observe that these different repartitions give the same results, as soon as there are enough numerical particles (e.g. $N > 50$). Therefore, in order to obtain faster simulations, we choose a small number of numerical particles ($N = 100$), and a big representativity $\omega_p = 10^8$.

The next two tests aim to validate our numerical code, in the one injection case.

3.2. Particle velocity without retroaction

For these computations, we take $v^0 = 1 \text{ m.s}^{-1}$ and $r = 50 \mu\text{m}$. When there is no retroaction, we can analytically compute the expression of each particle velocity $v_p$ with respect to $t$, as in [17]. In that case, it is clear that $v_p(t) = v^0 \exp(-t/\tau)$, where

$$\tau = \frac{m(r)}{6\pi \mu r} = \frac{2\pi r^3 \rho_{\text{aero}}}{9\pi \mu r}.$$  

For instance, we can compute the value of $\tau$ for particles of radius $r = 25 \mu\text{m}$, and we obtain $\tau \simeq 1.39 \times 10^{-2} \text{s}$. Then we plot the analytical particle velocity and the computed one on Figure 3, and check that the two curves are superimposed.

![Figure 3. Analytical and computed particle velocity without spray retroaction](image)

3.3. Consequence of the fluid incompressibility

The fluid incompressibility is properly taken into account. To this end, let us fix the physical parameters of the particles: $r = 25 \mu\text{m}$ and $v^0 = 1 \text{ m.s}^{-1}$. For these parameters, the particles are slowed down by the fluid, and stopped in the first third of the tube. We plot the fluid velocity at two different points on the axis of the tube far from the particles, in the middle and the right outlet on Figure 4.

We observe that the two curves are superimposed. Thus, any motion of the fluid at one point of the domain instantaneously echoes in the whole domain, due to the fluid incompressibility. Let us note that the fluid velocity near the particles is different, as it is shown in 3.4.5.

3.4. One spray injection

We here study the effect of one injection, in the tube, of 100 numerical particles of various radii ($r = 5, 25$ or $50 \mu\text{m}$), with representativity $\omega_p = 10^8$, and initial velocity $v^0$ equal to 1 or $0.1 \text{ m.s}^{-1}$. As already stated, the particles are initially uniformly distributed at the tube inlet, but away from the wall. Between the particles and the wall, there is at least a distance of order $\delta x$. 
3.4.1. **Particle radius influence**

We first plot, on Figure 5, the air velocity at a point on the tube axis, approximately in the center of the tube, for different radii. We recover that the bigger the particle is, the bigger its influence on the fluid is. Of course, this fact is intuitive, and we can begin to quantify it. When \( r = 50 \mu m \), one can check that the fluid velocity can go up to \( 2 \times 10^{-3} \text{ m.s}^{-1} \), whereas the fluid would be motionless when there is no spray retroaction.

3.4.2. **Injection velocity influence**

We can also highlight the influence of the particles initial velocity \( v^0 \). Figure 6 shows the fluid velocity at the same centered point of the tube, for various radii and initial velocities. We recover the fact that particles injected with a bigger velocity have a greater influence on the fluid, and again that bigger particles also have a greater retroaction on the fluid. This statement is again not surprising, and we can quantify it. When \( r \) is fixed, the retroaction influence is systematically more significant when \( v^0 \) is bigger. It means that, when the injection spray velocities are high, the retroaction should be taken into account, or at least seriously considered.

3.4.3. **Fluid velocity field away from the spray**

In order to highlight the impact of the retroaction, we plot the fluid velocity at different locations of the tube, for particles of radius \( r = 25 \mu m \) and velocity \( v^0 = 1 \text{ m.s}^{-1} \) on Figure 7. We observe that the velocity is maximal on the axis of the tube, and it decreases when we get closer to the wall. This smaller effect of the retroaction near the wall is primarily due to the zero boundary condition on the fluid velocity on the wall.
Figure 6. Air velocity in the tube center for two values of $v^0$ and different particles radii

Figure 7. Air velocity at different locations in the tube ($v^0 = 1 \text{ m.s}^{-1}$, $r = 25 \mu\text{m}$)

Up to now, we focused on regions which particles do not cross before stopping in the fluid. Let us now emphasize the local effect, due to the presence of the particles, on the ambient fluid.

3.4.4. *Retroaction feedback on the spray*

When one takes the retroaction force $F_{\text{aero}}$ into account in the Navier-Stokes equations, it induces a non-zero velocity in the fluid, which therefore impedes the particles to slow down as much as they would without retroaction. It is a second-order-like effect on the particles, since the spray drags the air, which then slows down less the particles. On Figure 8, we recover that the particle velocity decreases faster without the retroaction force. Nevertheless, the difference is at most 0.1% of the initial velocity.

3.4.5. *Fluid velocity near the particles*

Whereas the fluid velocity smoothly evolves far from the spray, the physical presence of the particles strongly disturbs the airflow. If we plot the fluid velocity at a point on the tube inlet, we can observe the influence of the particles passing at this point. This is shown on Figure 9.

More precisely, we observe a jump on the fluid velocity, which can be explained [15] by the incompressibility of both the air and the spray. Indeed, when a particle goes across a cell, it takes up a small amount equivalent to its volume, which cannot be occupied by the fluid. When the particle arrives, the fluid is rejected towards the inlet because of the viscosity, to ensure the volume conservation. Then the particle begins to drag the downstream fluid.
Figure 8. Particle velocity for $v^0 = 1\text{ m.s}^{-1}$, $r = 25\mu\text{m}$, with and without retroaction.

Figure 9. Fluid velocity for $v^0 = 1\text{ m.s}^{-1}$, $r = 50\mu\text{m}$, near the particles.

3.4.6. Fluid velocity field

From a more global point of view, the previous local effect also generates a lateral fluid recirculation near the walls (see Figure 10). Since the spray is distributed along the section of the tube with a lateral gap near the walls, it pushes the fluid in the central part, whereas the fluid escapes (with negative velocities) near the walls.

Figure 10. Fluid velocity in the whole domain.
3.5. Ten spray injections

The computations are made with the same number of physical and numerical particles as in 3.4. Hence, the representativity of each numerical particle is $\omega_p = 10^7$, and there are 10 successive injections of 100 numerical particles, to recover the same number of physical particles. Each injection happens at every time step. This framework seems more realistic from a medical point of view: there is no massive spray inhalation at exactly the same time, it may last for some time. We pick $v^0 = 1 \text{ m.s}^{-1}$.

![Image of fluid velocity: one injection vs. ten injections](image_url)

**Figure 11.** Fluid velocity: one injection vs. ten injections

3.5.1. Fluid velocities

On Figure 11, we plot the fluid velocity in the one-injection and the ten-injection cases, at a point near the tube inlet, i.e. which the particles go nearby. We observe that, although the particle number is the same and the injections happen quasi-simultaneously, the velocity jump occurring in the one-injection case because of the injection tends to disappear with the number of injections, while keeping $N_P$ constant. Nevertheless, the maximal value reached by the fluid velocity is of the same order, and, at the beginning of the computation, it is relevant to keep the retroaction force $F_{\text{aero}}$ in the model.

3.5.2. Particle velocities

Meanwhile, if we compare the velocity of a particle in the one-injection case and of a particle in the first (out of ten) injection, initially located at the same point near the tube inlet, we recover that the two curves are superimposed (Figure 12a). This may be surprising since, at some time, the downstream fluid should see the effect of the other waves of particles. That only means that the retroaction feedback on the particle observed in 3.4.4 can probably be neglected.

Moreover, we can plot the velocities of particles initially located at the same point but belonging to different injections (Figure 12b). In this case, there is no significant difference (except for the time-lag) between particles of the first injection or of the last. This complies with our conclusion about neglecting the effect of the retroaction feedback on the particles.

4. Motionless particles in a Poiseuille airflow

Once again, we use the same tube and mesh as in Section 2.2. This time, we consider a Poiseuille airflow and 100 initially motionless numerical particles with representativity $\omega_p = 10^8$. Those are uniformly distributed along a vertical section of the tube, at a distance $\ell = 0.01 \text{ m}$ from the inlet $\Gamma_{\text{in}}$.

It is well-known that, for any $u^0 > 0$, which then appears as the maximal (horizontal) air velocity on $\Gamma_{\text{in}}$, the function $(u, p)$ defined by

$$
    u(t, x_1, x_2) = \left( u^0 \left[ 1 - \left( \frac{x_2 - D/2}{D/2} \right)^2 \right], 0 \right), \quad p(t, x, y) = (-2x_1 + L)\frac{4\nu u^0}{D^2},
$$

(9)
solves the Navier-Stokes equations (1)–(2) with $F_{aero} = 0$, and the boundary conditions (6) and
\[ p = \frac{4\nu u^0 L}{D^2} \quad \text{on } \Gamma_{in}, \quad p = -\frac{4\nu u^0 L}{D^2} \quad \text{on } \Gamma_{out}. \]

There is no term $\partial u/\partial n$ in the previous boundary conditions, because this quantity is nil on both $\Gamma_{in}$ and $\Gamma_{out}$. When this solution is disturbed, the pressure boundary conditions are modified by taking into account the quantity $\nu \partial u/\partial n - p n$ instead of $p$ only.

The fluid is set with the initial condition on $u$ and $p$ given by (9). The spray induces a perturbation of the fluid Poiseuille profile.

### 4.1. Fluid pressure and velocity field

Let us choose $u^0 = 1 \text{ m.s}^{-1}$ and $r = 50 \mu\text{m}$. Figure 13 presents the fluid pressure and the position of the particles at the same time $t \simeq 0.5 \text{s}$. If there is no retroaction, the pressure isolines permanently remain vertical. With the retroaction, the pressure isolines on Figure 13a are clearly not vertical near the particles, they are influenced by the spray wave shown on Figure 13b.

In order to quantify the effect of the retroaction, we take different values in the following tests for the maximal air velocity: $u^0 = 1 \text{ m.s}^{-1}$ and $u^0 = 0.1 \text{ m.s}^{-1}$, and various particle radii: $r = 5 \mu\text{m}$, $r = 25 \mu\text{m}$ and $r = 50 \mu\text{m}$.

The spray clearly has an effect on the fluid, as one can see on Figures 14 and 15, for the bigger particles. We here focus on the fluid velocity near the entrance. Note that the vertical velocity component goes back to zero, but, for bigger particles, the time during which it is quite different from 0 is not negligible.
We focus on the particle which is initially located on the tube axis $y = D/2$. As in Section 3, we first study the particle velocity in the main flow direction, i.e. the horizontal component of the particle velocity, for various radii of the particle. Its behaviour is given on Figure 16a for $u^0 = 1 \text{ m.s}^{-1}$ and on Figure 16b for $u^0 = 0.1 \text{ m.s}^{-1}$.

The curves stop before the final computational time, because the particle of interest somehow left the domain $\Omega$ before its velocity reaches an equilibrium. Obviously, the velocity of the lighter particle almost immediately
reaches \( u^0 \), but this is not the case for the two other ones. If the situation for \( u^0 = 1 \text{ m.s}^{-1} \) is inconclusive, it is clear that, for \( u^0 = 0.1 \text{ m.s}^{-1} \), the asymptotic velocities are not \( u^0 \). That suggests that the particle is not on the tube axis anymore, i.e. the particle velocity has a non-zero vertical component, which is consistent with the non-zero vertical fluid velocity. We check this fact on Figure 17a for \( u^0 = 1 \text{ m.s}^{-1} \) and on Figure 17b for \( u^0 = 0.1 \text{ m.s}^{-1} \).

![Figure 17](image1.jpg)

**Figure 17.** Vertical particle velocity for (a) \( u^0 = 1 \), (b) \( u^0 = 0.1 \text{ m.s}^{-1} \)

When \( u^0 = 1 \text{ m.s}^{-1} \), the particle goes out from \( \Omega \) whatever the radius is, but the retroaction should be taken into account, mainly because of the vertical component of the velocity. On the other hand, when \( u^0 = 0.1 \text{ m.s}^{-1} \), one can see that the big particle and the intermediate one leave \( \Omega \) at approximately the same time. That implies that the big one has deposited. That would never have happened without retroaction: no particle should deposit in that case. We check that there is some spray deposition on Figure 18.

![Figure 18](image2.jpg)

**Figure 18.** Particle deposition at final time for \( u^0 = 1 \text{ m.s}^{-1} \) and \( r = 50 \mu\text{m} \)

5. **Conclusion**

In this work, we investigated the influence of the retroaction force \( F_{\text{aero}} \) in the Navier-Stokes equations. This term ensures the conservation of the total momentum of the spray-fluid model. The spray may interfere with the fluid in many situations.

For the numerics, we used some biologically relevant values for the velocities and radii. It is quite clear that, for radii smaller than 25 \( \mu\text{m} \), the retroaction is negligible, whatever the velocities are. On the contrary, our computations showed that, for radii bigger than 25 \( \mu\text{m} \), in most of the situations, the retroaction should not be neglected to properly and accurately capture the fluid behaviour, mainly if one of the velocities is high. Indeed, it clearly has an influence on the deposition.

With this deposition effect, the retroaction seems to favour the filter role that the upper airways have to play on the bigger particles. This fact has clearly to be confirmed on more realistic three-dimensional computations, for example, in a branched structure, but especially when one takes into account the other physical phenomena known as responsible for the deposition process: the gravitational sedimentation and the diffusive displacement, see [8].
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