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Thermal Simulation for Geometric Optimization of Metallized Polypropylene Film Capacitors

M. H. El-Husseini, Pascal Venet, Gérard Rojat, and Charles Joubert

Abstract—In this paper, we use an analytic model to calculate the losses in the metallized polypropylene film capacitors. The model is validated experimentally for capacitors having the same capacitance but different geometry. For each group of capacitors a temperature distribution in the roll is assumed with the aim of optimizing its thermal performance. It appears that the heating of a long capacitor is higher than that of an equivalent flat capacitor subjected to the same electric stresses.

Index Terms—Equivalent series resistance, metallized film capacitors, optimization, polypropylene, thermal simulation.

I. INTRODUCTION

The polypropylene capacitors are used in industry due to their low production cost and high reliability [1], [4]. Metallized polypropylene (MPP) film capacitors are made of two polypropylene films coated with zinc or aluminum of a few nanometer’s thickness rolled over an isolated support (mandrel). On each rolled face a zinc alloy is sprayed by a process called schooping, then connections are made (see Fig. 1) [4]–[6].

II. LOSSES IN CAPACITORS OF DIFFERENT GEOMETRIC SHAPE

Capacitor heating occurs in all metallized film capacitors applications due to the passage of current. This heating is caused by the resistive and other types of losses taking place in the capacitor. Generally, this heating is undesirable and limits the life of the capacitor.

In view of the great difference between the dimensions of the material used in the MPP capacitor (a length of a few meters and a thickness of a few micrometers), it is difficult to determine the governing physics variables inside and around the element (magnetic and electric field, temperature, etc.).

Research work can be found in the literature concerning the homogeneity of the material forming the roll [7], [8]. Losses generated by current passage in the armatures and the dielectric losses cause the heating of the capacitor [2], [3]. The active power consumed and the reactive power supplied in the volume $V$ of the roll can be obtained by [8]

$$P = \int \int \int P_v(r, z, \omega) dv$$

and

$$Q = \int \int \int Q_v(r, z, \omega) dv$$

where $P_v(r, z, \omega)$ and $Q_v(r, z, \omega)$ respectively represent the active and reactive volumetric power which depends on the radius “$r$” of the roll, its height “$z$,” and the electric frequency $\omega$ (Fig. 2). The active power consumed $D$ due to the dielectric is deduced from the reactive power

$$D = Q \tan \delta$$

where $\delta$ is the dielectric loss angle at the working frequency. Then, the total power dissipated is given by

$$P_{tot} = P + Q \tan \delta.$$
TABLE I
CHARACTERISTICS OF THE STUDIED CAPACITORS

<table>
<thead>
<tr>
<th>Characteristic</th>
<th>Symbol</th>
<th>Group A</th>
<th>Group B</th>
<th>Group C</th>
<th>Group D</th>
</tr>
</thead>
<tbody>
<tr>
<td>Capacitance (µF)</td>
<td>C</td>
<td>10</td>
<td>10</td>
<td>10</td>
<td>10</td>
</tr>
<tr>
<td>Nominal Voltage (V)</td>
<td>U_a</td>
<td>250</td>
<td>250</td>
<td>250</td>
<td>250</td>
</tr>
<tr>
<td>Margin (mm)</td>
<td>M</td>
<td>2.5</td>
<td>2.5</td>
<td>2.5</td>
<td>2.5</td>
</tr>
<tr>
<td>Film 1 thickness (µm)</td>
<td>ε_f</td>
<td>6</td>
<td>6</td>
<td>6</td>
<td>6</td>
</tr>
<tr>
<td>Metalization thickness (nm)</td>
<td>ε_m</td>
<td>15</td>
<td>15</td>
<td>15</td>
<td>15</td>
</tr>
<tr>
<td>Height (mm)</td>
<td>H</td>
<td>39.5</td>
<td>52</td>
<td>64</td>
<td>102</td>
</tr>
</tbody>
</table>

Analytical resolution of (1) and (2) uses the zeroth- and first-order Bessel’s functions and a numerical resolution with computer would need to be employed. This task has been accomplished earlier by one of the authors [8] and a software package has been developed for these computations.

Taking as a variable the total height of the capacitor $H$, Fig. 3 represents the total power dissipated $P_{tot}$ for a frequency of 40 kHz and a maximum current of 15 A calculated by the analytical model. At that frequency, the surface current distribution is practically independent of the distance “$r$” from the axis of revolution of the capacitor. In order to validate the model and for four groups of capacitors having the same capacitance (10 µF) but different height $H$ (the properties of which is given in Table I), the losses, shown in Fig. 3, are calculated by the equation

$$P_{tot} = ESR \cdot I_{eff}^2$$

where $ESR$ is the equivalent series resistance which represents the eddy and the dielectric losses and $I_{eff}$ the rms current value. The $ESR$ value is measured by an impedance analyzer.

The model, as well as the experimental results, show that for the same current passing through the capacitor, the longer the capacitor, the greater is the power dissipated. This is due to the fact that, for a given frequency, the $ESR$ of a short capacitor is smaller as compared to a long one having the same capacitance. This is illustrated in Fig. 4 which represent the $ESR$ of the four groups of capacitors as a function of frequency (the value for each group is the average of five capacitors in that group).

As the $ESR$ represents the eddy and dielectric losses, it is important to study its evolution since it determines the self-heating and, therefore, indirectly, the capacitor lifetime. Fig. 5 shows the $ESR$ value given by the model versus the capacitor height “$H$” for different frequency values. In the same graph are shown the measured values of $ESR$ for four groups of capacitors having the same capacitance (10 µF) but different geometrical shape. There is a fairly good agreement between the model and the experimental results. As mentioned above, it is observed that a long capacitor (having a large $H$ dimension) has an $ESR$ value higher than the $ESR$ value for a shorter capacitor having the same capacitance.

Given that the $ESR$ indicates self-heating, it seems logical to expect that compared to a short capacitor, subject to the same electric stresses, the long capacitor will undergo more heating.

We can note that the MPP capacitors exhibit secondary resonance (see Fig. 4) at frequency beyond the self-resonant frequency (of the order of 250 kHz). For the long capacitors of relatively higher $ESR$ the secondary resonance has not been observed.
passing through the capacitor has a maximum value.

The sides is and are constants that depend on the geometry of the capacitor and its heating. The sinusoidal current $I$ passing through the capacitor has a maximum value of 15 A at the frequency of 40 kHz and dissipates power $P_{oc}$. The heat dissipated will be conducted to the outside of the roll where it must then be eliminated by natural or forced convection as well as by radiation.

This heat transfer depends upon the macroscopic thermal conductivity of the polypropylene layers and the metallization as well as the geometry of the roll [7], [8].

A. Conduction Heat Transfer

In order to calculate the macroscopic thermal conductivity coefficient of the roll we will take into account the fact that a heat flux parallel to the revolution axis of the roll ($e_z$ axis) will be transferred easily through the metallization layers, which have a large thermal conductivity, from one sprayed end to the other. A radial heat transfer (according to the $e_r$ axis) will be more difficult because of the significant thermal resistance of the polymer layers.

Fig. 6 represents a small element of the roll. Letting $\lambda_p$ represent the thermal conductivity of the polypropylene and $\lambda_m$ that of the metal (zinc or aluminum), $c_p$ the thickness of the polypropylene, and $c_m$ that of the metal, then the thermal resistance of the element between A and B sides is [8]

$$R_{AB} = \frac{1}{\lambda_p \frac{ab}{e}} + \frac{1}{\lambda_m \frac{ab}{e}}. \quad (6)$$

The thermal conductivity $\lambda_r$ about the axis $e_r$ is given by

$$\lambda_r = \frac{1}{R_{AB} \frac{ab}{e}} = \frac{c}{\frac{c_p}{\lambda_p} + \frac{c_m}{\lambda_m}}, \quad (7)$$

If it is assumed that $e_m \ll c_p$ and $\lambda_m \gg \lambda_p$ we can say that

$$\lambda_r \approx \lambda_p. \quad (8)$$

Then, the radial thermal conductivity of the roll is approximately the same as that of the polymer. The thermal resistance of the same element taken between the $C$ and $D$ sides is

$$R_{CD} = \left[ \frac{\lambda_p c_p b}{a} + \frac{\lambda_m c_m b}{a} \right]^{-1}. \quad (9)$$

From (9), it follows that the thermal conductivity of the roll about the axis $e_z$ is given by

$$\lambda_z = \frac{1}{R_{CD} \frac{ab}{c}} = \frac{\lambda_p c_p + \lambda_m c_m}{c_p + \lambda_m} \approx \lambda_p + \frac{\lambda_m}{c_p} \lambda_m. \quad (10)$$

For a capacitor made of a film of 6-\mu m thickness and metallized with a 15-nm-thick zinc layer, the axial conductivity is approximately two times larger than the radial conductivity. It follows that, although the metallization layer is thin, it modifies strongly the thermal behavior of the capacitor.

Starting from the anisotropic thermal conductivity of the material, it is possible calculate out the temperature distribution in the roll for a given value of the volumetric power density produced by eddy and dielectric losses. The general conduction heat equation is [10]

$$\nabla^2 T + \frac{\chi}{\lambda} = \frac{\delta C_p}{\lambda} \frac{dT}{dt} \quad (11)$$

where $\nabla^2$ is the Laplacian operator, $T$ is the spatial temperature distribution, $\delta$ is the material density, $\lambda$ is the material thermal conductivity, $\chi$ is the local volumetric power density, $C_p$ is the specific heat, and $t$ is time. When the steady-state solution is sought, the transient term on the right-hand side of (11) is zero. In cylindrical coordinates, for the steady-state solution, we multiply by $\lambda$ to obtain

$$\frac{\lambda}{r} \frac{\partial}{\partial r} \left[ r \frac{\partial T}{\partial r} \right] + \frac{\lambda}{\partial z^2} \frac{\partial^2 T}{\partial z^2} + \chi = 0. \quad (12)$$

Since we are considering an anisotropic medium, we should use axial and radial conductivities separately. Fortunately, (12) is in a separable form with respect to the space variables and this is straightforward. Equation (12) can be written as

$$\frac{\lambda_r}{r} \frac{\partial}{\partial r} \left[ r \frac{\partial T}{\partial r} \right] + \frac{\lambda_z}{\partial z^2} \frac{\partial^2 T}{\partial z^2} + \chi = 0. \quad (13)$$

Unfortunately, (13) is impossible to solve in closed form for most interesting cases. If we assume $\chi = 0$ (no internal power generation) and provide surfaces with simple boundary conditions, the temperature can be written as

$$T(r,z) = \sum_{j=1}^{\infty} \sum_{j=0}^{\infty} \left[ a_j J_0 \left( \frac{k_r}{\sqrt{\lambda_p}} \right) + b_j Y_0 \left( \frac{k_r}{\sqrt{\lambda_m}} \right) \right]$$

$$\cdot c_j J_0 \left( \frac{k_z}{\sqrt{\lambda_p}} \right) + d_j Y_0 \left( \frac{k_z}{\sqrt{\lambda_m}} \right) \quad (14)$$

where $J_0$ and $Y_0$ are the zeroth-order Bessel and Weber functions, respectively. $a$, $b$, $c$, $d$, and $k$ are constants that depend on the initial conditions. It was, therefore, concluded fairly early in
our thermal modeling that computer solutions would need to be employed.

B. Convection Heat Transfer

The mode of heat transfer from the capacitor to the ambient environment may include conduction, convection, and radiation. Conduction is a volumetric parameter and includes path length as well as cross-sectional area effects, as has already been discussed. Externally, conduction is a significant mode only when the capacitor is attached to a heat sink. Convection, on the other hand, is generally modeled as a surface effect, although the localized film thickness and velocity (hydrodynamic) and temperature (thermodynamic) distributions extend beyond the surface. The parameter that describes the degree of thermal heat transfer coupling from a surface of area $A$ to the ambient fluid is known as the convection or film coefficient $h_c$, which is a function of the fluid velocity and mass transfer properties, such as density and viscosity. If the surface is at a higher temperature than the environment by an amount $\Delta T$, the power $P_{\text{CONV}}$ dissipated through convection is given by

$$P_{\text{CONV}} = h_c A \Delta T.$$  \hspace{1cm} (15)

Although (15) holds for virtually any fluid, this paper deals only with air at standard atmospheric pressure and at ambient temperature.

To simulate the phenomenon of convection, one needs to calculate the convection heat transfer coefficient of each side of the roll to be used in a finite-element analysis software package. For that purpose, let us denote the dimensionless average Nusselt and Grashof numbers as $N_{\text{u}}$ and $G_r$, respectively. A subscript of $D$ or $L$ is generally used along with the numbers to indicate application to a cylinder or plate, respectively. In addition, there is a dimensionless number $Pr$, the Prandtl number, which describes the medium and has a negligible temperature variation in our case. The convection coefficient is then given by [9]

$$h_c = \frac{\lambda N_{\text{u}}}{D}$$  \hspace{1cm} (16)

where $\lambda$ is the thermal conductivity of the air. An experimental Nusselt number expression is given by

$$N_{\text{u}} = B C_p^p P_r^n$$  \hspace{1cm} (17)

where $n$, $p$, and $B$ are corrective coefficients chosen in such a manner as to represent, as correctly as possible, the experimental results. In the case of a laminar natural convection regime, it is experimentally proven that $n$ and $p$ are practically the same for all systems and that $B$ depends only on the shape of the exposed sides. Knowing that the Grashof number is given by

$$G_r = \frac{g \beta D^5 \Delta T}{\nu^2}$$  \hspace{1cm} (18)

where $g$ is the gravitational acceleration, $\beta$ dilatation coefficient of the air at constant pressure, $\nu$ the kinematic viscosity of the air, and $\Delta T$ is the temperature difference between the surface

<table>
<thead>
<tr>
<th>Vertical plane surface</th>
<th>Horizontal plane surface</th>
</tr>
</thead>
<tbody>
<tr>
<td>Top surface</td>
<td>Bottom surface</td>
</tr>
<tr>
<td>$n$ 0.25</td>
<td>0.25</td>
</tr>
<tr>
<td>$p$ 0.25</td>
<td>0.25</td>
</tr>
<tr>
<td>$B$ 0.59</td>
<td>0.54</td>
</tr>
<tr>
<td>$Pr$ 0.72</td>
<td>0.72</td>
</tr>
</tbody>
</table>

Table II represents accepted approximate values of $n$, $p$, $B$, and $Pr$ in the case of a laminar natural convection mode for different geometrical arrangements at normal atmospheric pressure and ambient temperature (27 °C). We note that for a horizontal plane surface the number $B$ is not the same for the top and the bottom surface. It is worthy to note that those values are given for a surface whose temperature is greater than the ambient surrounding fluid’s temperature. Table III gives useful physical constants of air at 300 K and normal atmospheric pressure.

C. Radiation Heat Transfer

Radiation, like convection, is also a surface-to-environment effect. The radiation heat transfer is dependent not only on the temperature difference between a surface and its environment,
but also on the absolute temperatures involved. The surface emissivity $\varepsilon$ is also important in radiation heat transfer. The power $P_{\text{RAD}}$ transferred from a surface area $A$ at temperature $T_s$ to an environment at temperature $T_\infty$ due to radiation is [10]

$$P_{\text{RAD}} = \varepsilon\sigma A (T_s^4 - T_\infty^4) \quad (20)$$

where $\varepsilon$ is the surface emissivity (value between zero to one) in the infrared region of the electromagnetic spectrum and $\sigma = 5.67 \times 10^{-8}$ W/m$^2$K$^4$ is the Stefan–Boltzmann constant. Simulations are made assuming that $\varepsilon = 0.8$. Equation (20) may be put into a form equivalent to (15) by factoring out $\Delta T = (T_s - T_\infty)$, yielding

$$P_{\text{RAD}} = h_{\text{RAD}} A \Delta T \quad (21)$$

where

$$h_{\text{RAD}} = \varepsilon\sigma(T_s + T_\infty) (T_s^2 + T_\infty^2). \quad (22)$$

It can be seen from (22) that the radiation coefficient $h_{\text{RAD}}$ increases with both increasing the surface and environment temperatures. Radiation heat transfer can be significant compared to natural convection alone. Generally, the convection coefficient $h_c$ for natural convection, like the radiation coefficient $h_{\text{RAD}}$, varies from about 2 to about 4 W/m$^2$ K, for capacitors of this size and temperature range.

The simulation is performed for one-half of a two-dimensional section of the capacitor. The input parameters for the model are the radial and the axial conduction heat transfer coefficients $h_\omega$ and $h_z$, respectively, and the convection heat transfer coefficient and radiation emissivity $h_c$ and $\varepsilon$, respectively, as shown in Fig. 7.

The results of simulation are shown in Fig. 8. The power dissipated is supposed to be uniformly distributed in the roll. It is observed that the short capacitor heats up less compared to the long capacitor when both are subjected to the same electric stresses. This is due to the fact that long capacitors have a higher $h_c$ as discussed earlier in this paper. It appears that a simple physical explanation is possible: the current must travel a longer distance, through the very thin metal films, in the long capacitors, thus, the total $I^2 R$ (which is proportional to ESR) is higher compared to a short capacitor.

In order to validate the simulation, electric stresses were applied for the four groups of capacitors with an identical mechanism of heat evacuation (vertical position at the surrounding
temperature of 24 °C). The surface temperature measurement is done with the help of a thermocouple. Fig. 9 represents the experiment and simulation results.

IV. CONCLUSION

There is a good agreement between the simulation and the experimental results. A more accurate study of the temperature distribution in the rolled MPP capacitors would employ a nonuniform loss distribution.

However, the results obtained at the frequency of 40 kHz are quite satisfactory and give a good idea of the thermal behavior of the MPP film capacitors.

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REFERENCES


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