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ADAPTIVE ESTIMATION OF THE TRANSITION DENSITY OF A PARTICULAR HIDDEN MARKOV CHAIN

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ABSTRACT. We study the following model of hidden Markov chain: \( Y_i = X_i + \varepsilon_i \), \( i = 1, \ldots, n + 1 \) with \( \{X_i\} \) a real-valued positive recurrent and stationary Markov chain and \( \{\varepsilon_i\}_{1 \leq i \leq n+1} \) a noise independent of the sequence \( \{X_i\} \) having a known distribution. We present an adaptive estimator of the transition density based on the quotient of a deconvolution estimator of the density of \( X_i \) and an estimator of the density of \( (X_i, X_{i+1}) \). These estimators are obtained by contrast minimization and model selection. We evaluate the \( L^2 \) risk and its rate of convergence for ordinary smooth and supersmooth noise with regard to ordinary smooth and supersmooth chains. Some examples are also detailed.

KEYWORDS. Hidden Markov chain ; Transition density ; Nonparametric estimation ; Deconvolution ; Model selection ; Rate of convergence

1. INTRODUCTION

Let us consider the following model:

\[
Y_i = X_i + \varepsilon_i \quad i = 1, \ldots, n + 1
\]

where \( \{X_i\}_{i \geq 1} \) is an irreducible and positive recurrent Markov chain and \( \{\varepsilon_i\}_{i \geq 1} \) is a noise independent of \( \{X_i\}_{i \geq 1} \). We assume that \( \varepsilon_1, \ldots, \varepsilon_n \) are independent and identically distributed random variables with known distribution. This model belongs to the class of hidden Markov models. Contrary to the literature on the subject, we are interested in a nonparametric approach of the estimation of the hidden chain transition. The problem of estimating the density of \( X_i \) from the observations \( Y_1, \ldots, Y_n \) when the \( X_i \) are i.i.d. (known as the convolution model) has been extensively studied, see e.g. Carroll and Hall (1988), Fan (1991), Stefanski (1990), Pensky and Vidakovic (1999), Comte et al. (2006).

But very few authors study the case where \( \{X_i\} \) is a Markov chain. We can cite Dorea and Zhao (2002) who estimate the density of \( Y_i \) in such a model, Masry (1993) who is interested in the estimation of the multivariate density in a mixing framework and Clémençon (2003) who estimates the stationary density and the transition density of the hidden chain. More precisely he introduces an estimator of the transition density based on thresholding of a wavelet-vaguelette decomposition and he
studies its performance in the case of an ordinary smooth noise (i.e. whose Fourier transform has polynomial decay). Here we are interested also in the estimation of the transition density of \((X_i)\) but we consider a larger class of noise distributions. In Clémenc\'on (2003) there is no study of supersmooth noise (i.e. with exponentially decreasing Fourier transform), as the Gaussian distribution. However the study of such noise allows to find interesting rates of convergence, in particular when the chain density is also supersmooth. In the present paper, the four cases (ordinary smooth or supersmooth noise with ordinary smooth or supersmooth chain) are considered.

The aim of this paper is to estimate the transition density \(\Pi\) of the Markov chain \((X_i)\) from the observations \(Y_1,\ldots,Y_n\). To do this we assume that the regime is stationary and we note that \(\Pi = F/f\) where \(F\) is the density of \((X_i, X_{i+1})\) and \(f\) the stationary density. The estimation of \(f\) comes down to a problem of deconvolution, as does the estimation of \(F\). We use contrast minimization and a model selection method inspired by Barron et al. (1999) to find adaptive estimators of \(f\) and \(F\). Our estimator of \(\Pi\) is then the quotient of the two previous estimators. Note that it is worth finding an adaptive estimator, i.e. an estimator whose risk automatically achieves the minimax rates, because the regularity of the densities \(f\) and \(F\) is generally very hard to compute, even if the chain can be fully described (case of a diffusion or an autoregressive process).

We study the performance of our estimator by computing the rate of convergence of the \(L^2\) risk. We improve the result of Clémenc\'on (2003) (case of an ordinary smooth noise) since we obtain the minimax rate without logarithmic loss. Moreover we observe noteworthy rates of convergence in the case where both noise and the chain are supersmooth.

The paper is organized as follows. Section 2 is devoted to notations and assumptions while the estimation procedure is developed in Section 3. After describing the projection spaces to which the estimators belong, we define separately the estimator of the stationary density \(f\), the one of the joined density \(F\) and last the estimator \(\tilde{\Pi}\) of the transition density. Section 4 states the results obtained for our estimators. To illustrate the theorems, some examples are provided in Section 5 as the AR(1) model, the Cox-Ingersoll-Ross process or the stochastic volatility model. The proofs are to be found in Section 6.

2. Notations and Assumptions

For the sake of clarity, we use lowercase letters for the dimension 1 and capital letters for the dimension 2. For a function \(t : \mathbb{R} \mapsto \mathbb{R}\), we denote by \(\|t\|\) the \(L^2\) norm that is \(\|t\|^2 = \int_{\mathbb{R}} t^2(x)dx\). The Fourier transform \(t^*\) of \(t\) is defined by

\[t^*(u) = \int e^{-ixu}t(x)dx\]
Notice that the function $t$ is the inverse Fourier transform of $t^*$ and can be written $t(x) = 1/(2\pi) \int e^{ixu} t^*(u) du$. Finally, the convolution product is defined by $(t \ast s)(x) = \int t(x-y)s(y) dy$.

In the same way, for a function $T : \mathbb{R}^2 \mapsto \mathbb{R}$, $\|T\|^2 = \iint_{\mathbb{R}^2} T^2(x, y) dxdy$ and

$$T^*(u, v) = \iint e^{-ixu-iyv} T(x, y) dxdy, \quad (T* S)(x, y) = \iint T(x-z, y-w) S(z, w) dz dw.$$ 

We denote by $t \otimes s$ the function: $(x, y) \mapsto (t \otimes s)(x, y) = t(x)s(y)$.

The density of $\varepsilon_i$ is named $q$ and is considered as known. We denote by $p$ the density of $Y_i$. We have $p = f \ast q$ and then $p^* = f^* q^*$. Similarly if $P$ is the density of $(Y_i, Y_{i+1})$, then $P = F \ast (q \otimes q)$ and $P^* (u, v) = F^* (u, v) q^* (u) q^* (v)$.

Now the assumptions on the model are the following:

**A1:** The function $q^*$ never vanishes.

**A2:** There exist $s \geq 0, b > 0, \gamma > 0$ if $s = 0$ and $k_0, k_1 > 0$ such that

$$k_0(x^2 + 1)^{-\gamma/2} \exp(-b|x|^{\gamma}) \leq |q^*(x)| \leq k_1(x^2 + 1)^{-\gamma/2} \exp(-b|x|^{\gamma})$$

**A3:** The chain is stationary with (unknown) density $f$.

**A4:** The chain is geometrically $\beta$-mixing ($\beta_q \leq Me^{-\theta q}$), or arithmetically $\beta$-mixing ($\beta_q \leq Mq^{-\theta}$) with $\theta > 6$.

This last condition is verified as soon as the chain is uniformly ergodic. In the sequel we consider the following smoothness spaces:

$$\mathcal{A}_{\delta, r, a}(l) = \{ f \text{ density on } \mathbb{R} \text{ and } \int |f^s(x)|^2 (x^2 + 1)^\delta \exp(2a|x|^r) dx \leq l \}$$

with $r \geq 0, a > 0, \delta > 1/2$ if $r = 0$, $l > 0$ and

$$\mathcal{A}_{\Delta, R, A}(L) = \{ F \text{ density on } \mathbb{R}^2 \text{ and } \iint |F^s(x, y)|^2 (x^2 + 1)^\Delta (y^2 + 1)^\Delta \exp(2A(|x|^R + |y|^R)) dxdy \leq L \}$$

with $R \geq 0, A > 0, \Delta > 1/2$ if $R = 0$, $L > 0$.

When $r > 0$ (respectively $R > 0$) the function $f$ (resp. $F$) is known as supersmooth, and as ordinary smooth otherwise. In the same way, the noise distribution is called ordinary smooth if $s = 0$ and supersmooth otherwise. The spaces of ordinary smooth functions correspond to classic Sobolev classes, while supersmooth functions are infinitely differentiable. It includes for example normal ($r = 2$) and Cauchy ($r = 1$) densities.

3. Estimation procedure

Since $\Pi = F/f$ we proceed in 3 steps to estimate the transition density $\Pi$. First we find an estimator $\tilde{f}$ of $f$ (see Subsection $[3.2]$). Then we estimate $F$ by $\tilde{F}$ (see Subsection $[3.3]$). And last we estimate $\Pi$ with the quotient $\tilde{F}/\tilde{f}$ (Subsection $[3.4]$).

All estimators defined here are projection estimators. We therefore start with describing the projection spaces.
3.1. Projection spaces. Let

$$\varphi(x) = \sin(\pi x)/(\pi x)$$

and, for $m$ in $\mathbb{N}^*$, $j$ in $\mathbb{Z}$, \(\varphi_{m,j}(x) = \sqrt{m}\varphi(mx - j)\). Notice that \(\{\varphi_{m,j}\}_{j \in \mathbb{Z}}\) is an orthonormal basis of the space of integrable functions having a Fourier transform with compact support included into \([-\pi m, \pi m]\). In the sequel, we use the following notations:

\[S_m = \text{Span}\{\varphi_{m,j}\}_{j \in \mathbb{Z}}; \quad S_m = \text{Span}\{\varphi_{m,j} \otimes \varphi_{m,k}\}_{j,k \in \mathbb{Z}}\]

These spaces have particular properties, which are a consequence of the first point of Lemma 3 (see Section 6.7):

(2) \(\forall t \in S_m, \|t\|_\infty \leq \sqrt{m}\|t\|; \quad \forall T \in S_m, \|T\|_\infty \leq m\|T\|\)

where \(\|t\|_\infty = \sup_{x \in \mathbb{R}}|t(x)|\) and \(\|T\|_\infty = \sup_{(x,y) \in \mathbb{R}^2}|T(x,y)|\).

3.2. Estimation of \(f\). Here we estimate \(f\), which is the density of the \(X_i\)'s. It is the classic deconvolution problem. We choose to estimate \(f\) by minimizing a contrast. The classical contrast in density estimation is \(1/n \sum_{i=1}^{n}||t||^2 - 2t(X_i)||\). It is not possible to use this contrast here since we do not observe \(X_i\), \(i=1,\ldots, N\). Only the noisy data \(Y_1, \ldots, Y_n\) are available. That is why we use the following lemma.

**Lemma 1.** For all function \(t\), let \(v_t\) be the inverse Fourier transform of \(t^* / q^*(-.)\), i.e.

\[v_t(x) = \frac{1}{2\pi} \int e^{ixu} \frac{t^*(u)}{q^*(-u)} du.\]

Then, for all \(1 \leq k \leq n\),

1. \(\mathbb{E}[v_t(Y_k)|X_1, ..., X_n] = t(X_k)\)
2. \(\mathbb{E}[v_t(Y_k)] = \mathbb{E}[t(X_k)]\)

The second assertion in Lemma 1 is an obvious consequence of the first one and leads us to consider the following contrast:

\[\gamma_n(t) = \frac{1}{n} \sum_{i=1}^{n} ||v_t(Y_i)||^2 - 2v_t(Y_i)\]

with \(v_t^*(u) = \frac{t^*(u)}{q^*(-u)}\).

We can observe that \(\mathbb{E}\gamma_n(t) = 1/n \sum_{i=1}^{n} ||t||^2 - 2\mathbb{E}[v_t(Y_i)] = 1/n \sum_{i=1}^{n} ||t||^2 - 2\mathbb{E}[t(X_i)] \approx ||t||^2 - 2f(t) = ||t-f||^2 - ||f||^2\) and then minimizing \(\gamma_n(t)\) comes down to minimizing the distance between \(t\) and \(f\). So we define

(3) \(\hat{f}_m = \arg\min_{t \in S_m} \gamma_n(t)\)

or, equivalently,

\[\hat{f}_m = \sum_{j \in \mathbb{Z}} \hat{a}_{j}\varphi_{m,j}\]

Actually we should define \(\hat{f}_m = \sum_{|j| \leq K_n} \hat{a}_{j}\varphi_{m,j}\) because we can estimate only a finite number of coefficients. If \(K_n\) is suitably chosen, it does not change the rate
of convergence since the additional terms can be made negligible. For the sake of simplicity, we let the sum over $Z$. For an example of detailed truncation see Comte et al. (2006b).

Conditionally to $(X_i)$, the variance or stochastic error is

$$
\mathbb{E}[\|\hat{f}_m - f_m\|^2 | X_1, \ldots, X_n] \leq \sum_j \text{Var}\left[\frac{1}{n} \sum_{i=1}^n v_{\varphi_{m,j}}(Y_i) | X_1, \ldots, X_n \right] \leq \frac{\sum_j v^2_{\varphi_{m,j}}}{n}
$$

since $Y_1, \ldots, Y_n$ are independent conditionally to $(X_i)$. Then, it follows from Lemma 3 (see Subsection 6.7) that

$$
\Delta(m) = \frac{1}{2\pi} \int_{-\pi m}^{\pi m} |q^*(u)|^{-2} du.
$$

This implies that the order of the variance is $\Delta(m)/n$. That is why we introduce

$$
\mathcal{M}_n = \left\{ m \geq 1, \frac{\Delta(m)}{n} \leq 1 \right\}.
$$

To complete the estimation, we choose the best estimator among the collection $(\hat{f}_m)_{m \in \mathcal{M}_n}$. Let

$$
\hat{m} = \arg\min_{m \in \mathcal{M}_n} \{ \gamma_n(\hat{f}_m) + \text{pen}(m) \}
$$

where pen is a penalty term to be specified later (see Theorem 1). Finally we define $\hat{f} = \hat{f}_{\hat{m}}$.

3.3. Estimation of the density $F$ of $(X_i, X_{i+1})$. We proceed similarly to the estimation of $f$. To define the contrast to minimize, we use the following lemma:

**Lemma 2.** For all function $T$, let $V_T$ be the inverse Fourier transform of $T^*/(q^* \otimes q^*)(-\cdot)$, i.e.

$$
V_T(x, y) = \frac{1}{4\pi^2} \int \int e^{ixu + ixy} T^*(u, v) \frac{q^*(-u)q^*(-v)}{q^*(u)q^*(v)} dudv.
$$

Then, for all $1 \leq k \leq n$,

1. $\mathbb{E}[V_T(Y_k, Y_{k+1}) | X_1, \ldots, X_n] = T(X_k, X_{k+1})$
2. $\mathbb{E}[V_T(Y_k, Y_{k+1})] = \mathbb{E}[T(X_k, X_{k+1})]$

For any function $T$ in $L^2(\mathbb{R}^2)$, we define the contrast

$$
\Gamma_n(T) = \frac{1}{n} \sum_{i=1}^n \left[ \|T\|^2 - 2V_T(X_i, X_{i+1}) \right]
$$

whose expectation is equal to $\|T\|^2 - 2/n \sum_{k=1}^n \mathbb{E}[T(X_k, X_{k+1})] = \|T - F\|^2 - \|F\|^2$.

We can now define

$$
\hat{F}_m = \arg\min_{T \in S_m} \Gamma_n(T)
$$
By differentiating $\Gamma_n$, we obtain
\[
\hat{F}_m(x, y) = \sum_{j,k} \hat{A}_{j,k} \varphi_{m,j}(x) \varphi_{m,k}(y) \text{ with } \hat{A}_{j,k} = \frac{1}{n} \sum_{i=1}^{n} V_{\varphi_{m,j} \varphi_{m,k}}(Y_i, Y_{i+1}).
\]

We choose again not to truncate the estimator for the sake of simplicity. We have defined a collection of estimators $\{\hat{F}_m\}_{m \in \mathbb{M}_n}$. Note that $V_{ts}(x,y) = v_t(x)v_s(y)$ so that here the variance is of order $\Delta^2(m)/n$, so we introduce
\[
\mathbb{M}_n = \left\{ m \geq 1, \frac{\Delta^2(m)}{n} \leq 1 \right\}.
\]

To define an adaptive estimator we have to select the best model $m$. So let
\[
\hat{M} = \arg \min_{m \in \mathbb{M}_n} \{ \Gamma_n(\hat{F}_m) + \text{Pen}(m) \}
\]
where Pen is a penalty function which is specified in Theorem 2. Finally we consider the estimator $\tilde{F} = \hat{F}_{\hat{M}}$.

3.4. Estimation of $\Pi$. Whereas the estimation of $f$ and $F$ is valid on the whole real line $\mathbb{R}$ or $\mathbb{R}^2$, we estimate $\Pi$ on a compact set $B^2$ only, because we need a lower bound on the stationary density. More precisely, we need to set some additional assumptions:

\textbf{A5}: There exists a positive real $f_0$ such that $\forall x \in B, \ f(x) \geq f_0$  
\textbf{A6}: $\forall x \in B, \forall y \in B, \ \Pi(x,y) \leq \|\Pi\|_{B,\infty} < \infty$

Now we set
\[
\tilde{\Pi}(x,y) = \begin{cases} \frac{\tilde{F}(x,y)}{\tilde{f}(x)} & \text{if } |\tilde{F}(x,y)| \leq n|\tilde{f}(x)|, \\ 0 & \text{otherwise}. \end{cases}
\]

Here the truncation allows to avoid the too small values of $\tilde{f}$ in the quotient. Now we evaluate upper bounds for the risk of our estimators.

4. Results

Our first theorem regards the problem of deconvolution. This result may be put together with results of [Comte et al. 2006] in the i.i.d. case and of [Comte et al. 2006b] in various mixing frameworks.

\textbf{Theorem 1}. Under Assumptions A1–A4, consider the estimator $\tilde{f} = \hat{f}_{\hat{m}}$ where for each $m$, $\hat{f}_m$ is defined by (3) and $\hat{m} = \arg \min_{m \in \mathbb{M}_n} \{ \gamma_n(\hat{f}_m) + \text{pen}(m) \}$ with
\[
\text{pen}(m) = k \left( \frac{\pi m}{n} \right)^{s-1} \frac{\Delta(m)}{n}.
\]
where $k$ is a constant depending only on $k_0, k_1, b, \gamma, s$. Then there exists $C > 0$ such that

$$
\mathbb{E}\|\hat{f} - f\|^2 \leq 4 \inf_{m \in M_n}\{\|f_m - f\|^2 + \text{pen}(m)\} + \frac{C}{n}.
$$

The penalty is close to the variance order. It implies that the obtained rates of convergence are minimax in most cases. More precisely, the rates are given in the following corollary where $\lceil x \rceil$ denotes the ceiling function, i.e. the smallest integer larger than or equal to $x$.

**Corollary 1.** Under Assumptions of Theorem 1, if $f$ belongs to $A_{δ,r,a}(l)$, then

- If $r = 0$ and $s = 0$ \[ \mathbb{E}\|\hat{f} - f\|^2 \leq Cn^{-\frac{2\delta}{3\delta + 2\gamma + 1}} \]
- If $r = 0$ and $s > 0$ \[ \mathbb{E}\|\hat{f} - f\|^2 \leq C(\ln n)^{-2\delta/s} \]
- If $r > 0$ and $s = 0$ \[ \mathbb{E}\|\hat{f} - f\|^2 \leq C(\ln n)^{(2\gamma + 1)/r} \]
- If $r > 0$ and $s > 0$
  - if $r < s$ and $k = \lceil (s/r - 1)^{-1} \rceil - 1$, there exist reals $b_i$ such that
    \[ \mathbb{E}\|\hat{f} - f\|^2 \leq C(\ln n)^{-2\delta/s} \exp\left(\sum_{i=0}^{k} b_i (\ln n)^{(i+1)/r}/i!\right) \]
  - if $r = s$, if $\xi = [2\delta b + (s - 2\gamma - 1 + [s - (1-s)_+]/2)_+ a] / [(a + b)s]$ \[ \mathbb{E}\|\hat{f} - f\|^2 \leq Cn^{-a/(a+b)}(\ln n)^{-\xi} \]
  - if $r > s$ and $k = \lceil (r/s - 1)^{-1} \rceil - 1$, there exist reals $d_i$ such that
    \[ \mathbb{E}\|\hat{f} - f\|^2 \leq C(\ln n)^{1+2\gamma-s+(s-(1-s)_+)/2}/r \exp[-\sum_{i=0}^{k} d_i (\ln n)^{(i+1)s/r-i}] \]

These rates are the same as those obtained in the case of i.i.d. variables $X_i$; they are studied in detail in [Comte et al. (2006)]. In the case $r > 0, s > 0$, we find the original rates obtained in [Lacour (2006)], proved as being optimal for $0 < r < s$ in [Butucea and Tsybakov (2006)]. In the other cases, we can compare the results of Theorem 1 to the one obtained with a nonadaptive estimator. There is a loss only in the case $r \geq s > 1/3$ where a logarithmic term is added. But in this case, the rates are faster than any power of logarithm.

Now let us study the risk for our estimator of the joined density $F$.

**Theorem 2.** Under Assumptions A1–A4, consider the estimator $\hat{F} = \hat{F}_M$ where for each $m$, $\hat{F}_m$ is defined by (3) and $\hat{M} = \arg\min_{m \in M_n} \{\Gamma_n(\hat{F}_m) + \text{Pen}(m)\}$ with

$$
\text{Pen}(m) = K\frac{\pi m)^{(s-(1-s)_+)\Delta^2(m)}}{n},
$$

where $\Delta^2(m)$ is the $L_2$-norm of $m$.
where $K$ is a constant depending only on $k_0, k_1, b, \gamma, s$. Then there exists $C > 0$ such that

$$
\mathbb{E}\|\hat{F} - F\|^2 \leq 4 \inf_{m \in \mathbb{M}_n} \{\|F_m - F\|^2 + \text{Pen}(m)\} + \frac{C}{n}.
$$

The bases derived from the sine cardinal function are adapted to the estimation on the whole real line. The proof of Theorem 2 actually contains the proof of another result (see Proposition 2 in Section 6): the estimation of a bivariate density in a mixing framework on $\mathbb{R}^2$ and not only on a compact set. In this case of the absence of noise ($\varepsilon = 0$), we obtain the same result with the penalty $\text{Pen}(m) = K_0(\sum_k \beta_{2k})m^2/n$. This limit case gives the mixing coefficients back in the penalty, as it always appears in this kind of estimation (see e.g. Tribouley and Viennet (1998)).

It is then significant that in the presence of noise the penalty contains neither mixing term nor unknown quantity. It is entirely computable since it depends only on the characteristic function $q^*$ of the noise which is known.

Theorem 2 enables us to give rates of convergence for the estimation of $F$.

**Corollary 2.** Under Assumptions of Theorem 2, if $F$ belongs to $\mathbb{H}_{R,A}(L)$, then

- If $R = 0$ and $s = 0$
  $$
  \mathbb{E}\|\hat{F} - F\|^2 \leq Cn^{-\frac{2\Delta}{\Delta + 2\gamma + 2}}
  $$
- If $R = 0$ and $s > 0$
  $$
  \mathbb{E}\|\hat{F} - F\|^2 \leq C(\ln n)^{-2\Delta/s}
  $$
- If $R > 0$ and $s = 0$
  $$
  \mathbb{E}\|\hat{F} - F\|^2 \leq C(\ln n)^{\frac{2(A + 2b)s}{\Delta + 2b}}(\ln n)^{-\xi}
  $$
- If $R > 0$ and $s > 0$
  - if $R < s$ and $k = [(s/R - 1)^{-1}] - 1$, there exist reals $b_i$ such that
    $$
    \mathbb{E}\|\hat{F} - F\|^2 \leq C(\ln n)^{-2\Delta/s} \exp\left[\sum_{i=0}^{k} b_i(\ln n)^{(i+1)s/R - i}\right]
    $$
  - if $R = s$ if $\xi = [4\Delta b + (2s - 4\gamma - 2 - [s - (1 - s)_+]_+)A]/[(A + 2b)s]$
    $$
    \mathbb{E}\|\hat{f} - f\|^2 \leq Cn^{-A/(A + 2b)}(\ln n)^{-\xi}
    $$
  - if $R > s$ and $k = [(R/s - 1)^{-1}] - 1$, there exist reals $d_i$ such that
    $$
    \mathbb{E}\|\hat{F} - F\|^2 \leq C(\ln n)^{2(A + 2b)s/[\Delta + 2\gamma + 2] + s - (1 - s)_+]_+ + R/n} \exp\left[-\sum_{i=0}^{k} d_i(\ln n)^{(i+1)s/R - i}\right]
    $$

The rates of convergence look like the one of Corollary 1 with modifications due to the bivariate nature of $F$. We can compare this result to the one of Clémenc’on (2003) who studies only the case $R = 0$ and $s = 0$. He shows that the minimax lower bound in that case is $n^{-\frac{2\Delta}{\Delta + 2\gamma + 2}}$, so our procedure is optimal, whereas his estimator has a logarithmic loss for the upper bound. We remark that if $s > 0$ (supersmooth noise), the rate is logarithmic for $F$ belonging to a classic ordinary smooth space. But if $F$ is also supersmooth, better rates are recovered.
Except in the case $R = 0$ and $s = 0$, there is, to our knowledge, no lower bound available for this estimation. We can however evaluate the performance of this estimator by comparing it with a nonadaptive estimator. If the smoothness of $F$ is known, an $m$ depending on $R$ and $\Delta$ which minimizes the risk $\|F - F_m\|^2 + \Delta(m)^2/n$ can be exhibited and then some rates of convergence for this nonadaptive estimator are obtained. As soon as $s \leq 1/2$ (i.e. $[s - (1 - s)_+]_+ = 0$), the penalty is $\Delta(m)^2/n$ and then the adaptive estimator recovers the same rates of convergence as those of a nonadaptive estimator if the regularity of $F$ were known. It automatically minimizes the risk without prior knowledge on the regularity of $F$ and there is no loss in the rates. If $s > 1/2$ a loss can appear but is not systematic. If $R < s$, the rate of convergence is unchanged since the bias dominates. It is only in the case $R \geq s > 1/2$ that an additional logarithmic term appears. But in this case the risk decreases faster than any logarithmic function so that the loss is negligible.

We can now state the main result regarding the estimation of the transition density $\Pi$.

**Theorem 3.** Under Assumptions A1–A6, consider the estimator $\tilde{\Pi}$ defined in (6). We assume that $f$ belongs to $A_{\delta,r,a}(l)$ with $\delta > 1/2$ and that we browse only the models $m \in \mathcal{M}_n$ such that

$$m \geq \ln \ln n \quad \text{and} \quad m \Delta(m) \leq \frac{n}{(\ln n)^2}$$

to define $\tilde{f}$. Then $\tilde{\Pi}$ verifies, for $n$ large enough,

$$E \|\tilde{\Pi} - \Pi\|^2_B \leq C_1 E \|\tilde{F} - F\|^2 + C_2 E \|\tilde{f} - f\|^2 + \frac{C}{n}$$

where $\|T\|^2_B = \iint_B T(x,y)dxdy$.

Note that, contrary to Theorems 1 and 2, this result is asymptotic. It states that the rate of convergence for $\Pi$ is no larger than the maximum of the rates of $f$ and $F$. The restrictions in (7) do not modify the conclusion of Theorem 1 and the resulting rates of convergence. Thus if $f$ and $F$ have the same regularity, the rates of convergence for $\Pi$ are those of $F$, given in Corollary 2.

If $s = 0$ i.e. if $\epsilon_i$ is ordinary smooth, then the rates of convergence are polynomial and even near the parametric rate $1/n$ if $R$ and $r$ are positive. But the smoother the error distribution is, the harder the estimation is. In the case of a supersmooth noise, the rates are logarithmic if $f$ or $F$ is ordinary smooth but faster than any power of logarithm if the hidden chain has supersmooth densities. The exact rates depend on all regularities $\gamma, s, \delta, r, \Delta, R$ and are very tedious to write. That is why we prefer to give some detailed examples.

### 5. Examples

#### 5.1. Autoregressive process of order 1.

Let us study the case where the Markov chain is defined by

$$X_{n+1} = \alpha X_n + \beta + \eta_{n+1}$$
where the \( \eta_n \)'s are i.i.d. centered Gaussian with variance \( \sigma^2 \). This chain is irreducible, Harris recurrent and geometrically \( \beta \)-mixing. The stationary distribution is Gaussian with mean \( \beta/(1 - \alpha) \) and variance \( \sigma^2/(1 - \alpha^2) \). So

\[
f^*(u) = \exp \left[ -iu \left( \frac{\beta}{1 - \alpha} - \frac{\sigma^2}{2(1 - \alpha^2)} u^2 \right) \right]
\]

and then bias computing gives \( \delta = 1/2, r = 2 \). The function \( F \) is the density of a Gaussian vector with mean \( (\beta/(1 - \alpha), \beta/(1 - \alpha)) \) and variance matrix \( \sigma^2/(1 - \alpha^2) \left( \begin{matrix} 1 & \alpha \\ \alpha & 1 \end{matrix} \right) \). So

\[
F^*(u, v) = \exp \left[ -i(u + v) \left( \frac{\beta}{1 - \alpha} - \frac{\sigma^2}{2(1 - \alpha^2)} (u^2 + v^2 + 2\alpha uv) \right) \right]
\]

and \( \Delta = 1/2, R = 2 \).

We can compute the rates of convergence for different kinds of noise \( \varepsilon \). If \( \varepsilon \) has a Laplace distribution, \( q^*(u) = 1/(1 + u^2) \) so \( s = 0, \gamma = 2 \). In this case, Corollary \[\] gives \( \mathbb{E} \| \hat{f} - f \|^2 \leq C(\ln n)^{5/2}/n \) and \( \mathbb{E} \| \hat{F} - F \|^2 \leq C(\ln n)^5/n \). Consequently,

\[
\mathbb{E} \| \hat{\Pi} - \Pi \|_B^2 \leq C \frac{(\ln n)^5}{n}
\]

with \( B \) an interval \([-d, d]\). This rate is close to the parametric rate \( 1/n \); it is due to the great smoothness of the chain compared with that of error.

If now \( \varepsilon \) has a normal distribution with variance \( \tau^2 \), then we compute

\[
\mathbb{E} \| \hat{\Pi} - \Pi \|_B^2 \leq C n^{-\frac{\tau^2}{\tau^2 + 2(\ln n)^2}}.
\]

5.2. Cox-Ingersoll-Ross process. Another example is given by \( X_n = R_n \) with \( \tau \) a fixed sampling interval and \( R_t \) the so-called Cox-Ingersoll-Ross process defined by

\[
dR_t = (2\theta R_t + \kappa \sigma_0^2)dt + 2\sigma_0 \sqrt{R_t} dW_t \quad \theta < 0, \kappa \in \{2, 3, \ldots\}.
\]

Following Chaaley-Maurel and Genon-Catalot (2000), we observe that \( X_n \) is the square of the Euclidean norm of a \( \kappa \)-dimensional vector whose components are linear autoregressive processes of order 1. The stationary distribution is a Gamma distribution with parameter \( \kappa/2 \) and \( |\theta|/\sigma^2 \) so that

\[
f^*(u) = \left( 1 + iu \frac{\sigma_0^2}{|\theta|} \right)^{-\kappa/2}
\]

and \( r = 0, \delta = (\kappa - 1)/2 \). To compute the characteristic function of the joined density, we write

\[
F^*(u, v) = \int \mathbb{E}[e^{-iuX_1}|X_0 = x]e^{-iux} f(x) dx.
\]
Let $\beta^2 = \sigma_0^2(e^{2\theta r} - 1)/(2\theta)$. Then, conditionally to $X_0 = x$, $\beta^{-2} X_1$ is a non-central chi-square $\chi^2(e^{2\theta r}/\beta^2, \kappa)$, so that

$$
\mathbb{E}[e^{-i v X_1} | X_0 = x] = (1 + 2i v \beta^2)^{-\kappa/2} \exp \left( - \frac{iv e^{2\theta r}}{1 + 2i v \beta^2} x \right).
$$

This implies

$$
F^*(u, v) = \left[ 1 - \left( 1 - e^{2\theta r} \right) \frac{\sigma_0^2}{\theta^2} u v + i \frac{\sigma_0^2}{|\theta|} (u + v) \right]^{-\kappa/2}
$$

and $R = 0$, $\Delta = (\kappa - 1)/2$. Then, if for example the noise has a Gaussian distribution ($\gamma = 0, s = 2$), the rate of convergence is $(\ln n)^{(1 - \kappa)/2}$. But this rate is faster if $\varepsilon$ has a Gamma distribution with shape parameter $\alpha$ (so that $\gamma = \alpha, s = 0$): we obtain in this case $n^{(1 - \kappa)/(\kappa + 4\alpha + 1)}$.

### 5.3. Stochastic volatility model.

Our work allows to study some multiplicative models as the so-called stochastic volatility model in finance (see Genon-Catalot et al. (2000) for the links between the standard continuous-time SV models and the hidden Markov models). Let

$$
Z_n = U_n^{1/2} \eta_n
$$

where $(U_n)$ is a nonnegative Markov chain, $(\eta_n)$ a sequence of i.i.d. standard Gaussian variables, the two sequences being independent. Setting $X_n = \ln(U_n)$ and $\varepsilon_n = \ln(\eta_n^2)$ leads us back to our initial problem.

The noise distribution is the logarithm of a chi-square distribution and then verifies $q^*(x) = 2^{-ix} \Gamma(1/2 - ix)/\sqrt{\pi}$. Van Es et al. (2005) show that $|q^*(x)| \sim +\infty \sqrt{2e^{-\pi|x|^2}}$ and then $s = 1, \gamma = 0$.

We assume that the logarithm of the hidden chain $X_n$ derives from a regular sampling of an Ornstein-Uhlenbeck process, i.e. $X_n = V_{n\tau}$ where $V_t$ is defined by the equation

$$
dV_t = \theta V_t dt + \sigma dB_t
$$

with $B_t$ a standard Brownian motion. Then all the assumptions are satisfied. Similarly to Subsection 5.1, the stationary distribution is Gaussian with mean 0 and variance $\sigma^2/2|\theta|$ and then $\delta = 1/2, r = 2$. In the same way $F$ is the density of a centered Gaussian vector with variance matrix $\sigma^2/(2|\theta|) \begin{pmatrix} 1 & e^{\theta r} \\ e^{\theta r} & 1 \end{pmatrix}$ and then $\Delta = 1/2, R = 2$. We obtain the following rate of convergence on some interval $B = [-d, d]$

$$
\mathbb{E} \|\hat{\Pi} - \Pi\|_B^2 \leq C \sqrt{\ln n} \frac{\exp[(\pi/\beta)\sqrt{\ln n}]}{n}
$$

with $\beta^2 = \sigma^2(e^{2\theta r} - 1)/(2\theta)$. 

6. Proofs

Here we do not prove the results concerning the estimation of $f$. Indeed they are similar to the ones concerning $F$ (but actually simpler) and the ones of Comte et al. (2006). It is then sufficient to use corresponding proofs for $F$ mutatis mutandis.

For the sake of simplicity, all constants in the following are denoted by $C$, even if they have different values.

6.1. Proof of Lemma 2. It is sufficient to prove the first assertion. First we write that $V_T(Y_k, Y_{k+1}) = 1/4\pi^2 \int e^{i\lambda Y_k + i\lambda Y_{k+1}} T^*(u, v)/q^*(-u)q^*(-v) du dv$ so that

$$
\mathbb{E}[V_T(Y_k, Y_{k+1})|X_1, \ldots, X_n] = \frac{1}{4\pi^2} \int \mathbb{E}[e^{i\lambda Y_k + i\lambda Y_{k+1}}|X_1, \ldots, X_n] T^*(u, v) q^*(-u)q^*(-v) du dv.
$$

By using the independence between $(X_i)$ and $(\varepsilon_i)$, we compute

$$
\mathbb{E}[e^{i\lambda Y_k + i\lambda Y_{k+1}}|X_1, \ldots, X_n] = \mathbb{E}[e^{iX_k u + i\lambda Y_{k+1}} e^{i\varepsilon_k u + i\varepsilon_{k+1} v}|X_1, \ldots, X_n] = e^{iX_k u + i\lambda Y_{k+1}} \mathbb{E}[e^{i\varepsilon_k u}] \mathbb{E}[e^{i\varepsilon_{k+1} v}] = e^{iX_k u + i\lambda Y_{k+1}} q^*(-u)q^*(-v).
$$

Then

$$
\mathbb{E}[V_T(Y_k, Y_{k+1})|X_1, \ldots, X_n] = \frac{1}{4\pi^2} \int e^{iX_k u + i\lambda Y_{k+1}} q^*(-u)q^*(-v) T^*(u, v) q^*(-u)q^*(-v) du dv
$$

$$
= \frac{1}{4\pi^2} \int e^{iX_k u + i\lambda Y_{k+1}} T^*(u, v) du dv = T(X_k, X_{k+1}).
$$

6.2. Proof of Theorem 2. First we introduce some auxiliary variables whose existence is ensured by Assumption A4 of mixing. In the case of arithmetical mixing, since $\theta > 6$, there exists a real $c$ such that $0 < c < 1/2$ and $c\theta > 3$. We set in this case $q_n = \frac{1}{\pi} \left[ n^c \right]$. In the case of geometrical mixing, we set $q_n = \frac{1}{\pi} \left[ c \ln(n) \right]$ where $c$ is a real larger than $3/\theta$.

For the sake of simplicity, we suppose that $n = 4p_n q_n$, with $p_n$ an integer. Let for $i = 1, \ldots, n/2$, $V_i = (X_{2i-1}, X_{2i})$ and for $l = 0, \ldots, p_n - 1$, $A_l = (V_{2i+1}^{(2q_n+1)}, \ldots, V_{2(2q_n+1)}^{(2q_n+1)})$, $B_l = (V_{(2l+1)q_n+1}, \ldots, V_{(2l+2)q_n})$. As in Viennet (1997), by using Berbee’s coupling Lemma, we can build a sequence $(A^*_l)$ such that

$$
\left\{
A_l \text{ and } A^*_l \text{ have the same distribution,}
\right.
\left\{
A_l^* \text{ and } A^*_l \text{ are independent if } l \neq l',
\right.
\left\{
\mathbb{P}(A_l \neq A^*_l) \leq \beta_{2q_n}.
\right\}
$$

In the same way, we build $(B^*_l)$ and we define for any $l \in \{0, \ldots, p_n - 1\}$,

$$
A^*_l = (V_{2i+1}^{(2q_n+1)}, \ldots, V_{2(2q_n+1)}^{(2q_n+1)}), \quad B^*_l = (V_{(2l+1)q_n+1}, \ldots, V_{(2l+2)q_n})
$$

so that the sequence $(V_i^*, \ldots, V_n^*)$ and the sequence $(X_1^*, \ldots, X_n^*)$ are well defined. We can now define

$$
\Omega = \{ \forall i, 1 \leq i \leq n \quad X_i = X_i^* \}.
$$
Then we split the risk into two terms:
\[
E(\|\hat{F} - F\|^2) = E(\|\hat{F} - F\|^2 \mathbb{1}_{\Omega'}) + E(\|\hat{F} - F\|^2 \mathbb{1}_{\Omega^c}).
\]
To pursue the proof, we observe that for all \(T, T'\)
\[
\Gamma_n(T) - \Gamma_n(T') = \|T - F\|^2 - \|T' - F\|^2 - 2Z_n(T - T')
\]
where \(Z_n(T) = \frac{1}{n} \sum_{i=1}^{n} \left\{ V_T(Y_i, Y_{i+1}) - \int T(x, y) F(x, y) dx dy \right\} \).

Let us fix \(m \in M_n\) and denote by \(F_m\) the orthogonal projection of \(F\) on \(S_m\). Since \(\Gamma_n(\hat{F}) + \text{Pen}(\hat{M}) \leq \Gamma_n(F_m) + \text{Pen}(m)\), we have
\[
\|\hat{F} - F\|^2 \leq \|F_m - F\|^2 + 2Z_n(\hat{F} - F_m) + \text{Pen}(m) - \text{Pen}(\hat{M}) \\
\leq \|F_m - F\|^2 + 2\|\hat{F} - F_m\| \sup_{T \in B(M)} Z_n(T) + \text{Pen}(m) - \text{Pen}(\hat{M})
\]
where, for all \(m', B(m') = \{T \in S_m + S_{m'}, \|T\| = 1\}\). Then, using inequality \(2xy \leq x^2/4 + y^2\),
\[
(8) \quad \|\hat{F} - F\|^2 \leq \|F_m - F\|^2 + \frac{1}{4} \|\hat{F} - F_m\|^2 + 4 \sup_{T \in B(M)} Z_n^2(T) + \text{Pen}(m) - \text{Pen}(\hat{M}).
\]
By denoting \(E_X\) the expectation conditionally to \(X_1, \ldots, X_n\) and by using Lemma 2, \(Z_n(T)\) can be split into two terms:
\[
Z_n(T) = Z_{n,1}(T) + Z_{n,2}(T)
\]
with
\[
\begin{align*}
Z_{n,1}(T) &= \frac{1}{n} \sum_{i=1}^{n} \left\{ V_T(Y_i, Y_{i+1}) - E_X[V_T(Y_i, Y_{i+1})] \right\} , \\
Z_{n,2}(T) &= \frac{1}{n} \sum_{i=1}^{n} \left\{ T(X_i, X_{i+1}) - \int T(x, y) F(x, y) dx dy \right\} .
\end{align*}
\]
Now let \(P_1(., .)\) be a function such that for all \(m, m'\),
\[
(9) \quad 16P_1(m, m') \leq \text{Pen}(m) + \text{Pen}(m').
\]
Then \((8)\) becomes
\[
\|\hat{F} - F\|^2 \leq \|F_m - F\|^2 + \frac{1}{2} (\|\hat{F} - F\|^2 + \|F - F_m\|^2) + 2\text{Pen}(m) \\
+ 8 \sup_{T \in B(M)} Z_{n,1}^2(T) - P_1(m, \hat{M}) + 8 \sup_{T \in B(M)} Z_{n,2}^2(T) - P_1(m, \hat{M})
\]
which gives, by introducing a function \(P_2(., .)\),
\[
\frac{1}{2} \|\hat{F} - F\|^2 \mathbb{1}_{\Omega'} \leq \frac{3}{2} \|F_m - F\|^2 + 2\text{Pen}(m) + 8 \sum_{m' \in M_n} \left[ \sup_{T \in B(m')} Z_{n,1}^2(T) - P_1(m, m') \right] + \\
+ 8 \sum_{m' \in M_n} \left[ \sup_{T \in B(m')} Z_{n,2}^2(T) - P_2(m, m') \right] \mathbb{1}_{\Omega'} + 8 \sum_{m' \in M_n} [P_2(m, m') - P_1(m, m')].
\]
We now use the following propositions:

**Proposition 1.** Let $P_1(m, m') = C(q)(\pi m')^{s-(1-s)_+} + \Delta^2(m')/n$ where $\Delta(m)$ is defined in (4) and $m' = \max(m, m')$ and $C(q)$ is a constant. Then, under assumptions of Theorem 3, there exists a positive constant $C$ such that

$$\sum_{m' \in \mathbb{M}_n} \mathbb{E}\left(\left[\sup_{T \in B(m')} Z_{n,1}^2(T) - P_1(m, m')\right]^+\right) \leq \frac{C}{n}.$$  

**Proposition 2.** Let $P_2(m, m') = 96(\sum_k \beta_k)m'\Delta^2(m)/n$ where $\Delta(m)$ is defined in (4) and $m' = \max(m, m')$. Then, under assumptions of Theorem 3, there exists a positive constant $C$ such that

$$\sum_{m' \in \mathbb{M}_n} \mathbb{E}\left(\left[\sup_{T \in B(m')} Z_{n,2}^2(T) - P_2(m, m')\right]^+\right) \leq \frac{C}{n}.$$  

The definition of the functions $P_1(m, m')$ and $P_2(m, m')$ given in Propositions 1 and 2 imply that there exists $m_0$ such that $\forall m' > m_0$ $P_1(m, m') \geq P_2(m, m')$. (If $s = 0 = \gamma$ (case of a null noise), it would be wrong and the penalty would then be $P_2(m, m')$ instead of $P_1(m, m')$). Then

$$\sum_{m' \in \mathbb{M}_n} [P_2(m, m') - P_1(m, m')] \leq \sum_{m' \leq m_0} P_2(m, m') \leq \frac{C(m_0)}{n}. $$

Since $m'\Delta^2(m') \leq m\Delta^2(m) + m'\Delta^2(m')$, the condition (3) is verified with

$$\text{Pen}(m) = 16C(q)(\pi m)^{s-(1-s)_+} \Delta^2(m) / n.$$  

And finally, combining (13) and Propositions 1 and 2,

$$\mathbb{E}(\|\hat{F} - F\|^2 I_{\Omega^{c}}) \leq 4(\|F_m - F\|^2 + \text{Pen}(m)) + \frac{C}{n}.$$  

For the term $\mathbb{E}(\|\hat{F} - F\|^2 I_{\Omega^{c}})$, recall that

$$\hat{F}_m(x, y) = \sum_{j,k} \hat{A}_{j,k}\varphi_{m,j}(x)\varphi_{m,k}(y) \text{ with } \hat{A}_{j,k} = \frac{1}{n} \sum_{i=1}^{n} V_{\varphi_{m,j} \otimes \varphi_{m,k}}(Y_i, Y_{i+1}).$$

Thus, for any $m$ in $\mathbb{M}_n$,

$$\|\hat{F}_m\|^2 = \sum_{j,k} \left[\frac{1}{n} \sum_{i=1}^{n} V_{\varphi_{m,j} \otimes \varphi_{m,k}}(Y_i, Y_{i+1})\right]^2 \leq \frac{1}{n^2} \sum_{j,k} n \sum_{i=1}^{n} V_{\varphi_{m,j} \otimes \varphi_{m,k}}^2(Y_i, Y_{i+1})$$  

$$\leq \|\sum_{j,k} V_{\varphi_{m,j} \otimes \varphi_{m,k}}\|_\infty \leq \|\sum_{j} V_{\varphi_{m,j}}\|_\infty^2 \leq \Delta^2(m)$$

using Lemma 3. Then $\|\hat{F}_M\|^2 \leq \Delta^2(M) \leq n$ since $M$ belongs to $\mathbb{M}_n$. And

$$\mathbb{E}\|\hat{F} - F\|^2 I_{\Omega^{c}} \leq \mathbb{E}(2(\|\hat{F}\|^2 + \|F\|^2) I_{\Omega^{c}}) \leq 2(n + \|F\|^2)P(\Omega^{c}).$$
Using Assumption A4 in the geometric case, $\beta_{2q_n} \leq Me^{-\theta\log(n)} \leq M_n^{-\theta}$ and, in the other case, $\beta_{2q_n} \leq M(2q_n)^{-\theta} \leq M_n^{-\theta}$. Then $P(\Omega^c) \leq 2p_n\beta_{2q_n} \leq nM_n^{-\theta}$. Since $\alpha\theta > 3$, $P(\Omega^c) \leq M_n^{-2}$, which implies $E(\|\tilde{F} - F\|^2 1_{\Omega^c}) \leq C/n$.

Finally we obtain
\[
E\|\tilde{F} - F\|^2 \leq E(\|\tilde{F} - F\|^2 1_{\Omega^c}) + E(\|\tilde{F} - F\|^2 1_{\Omega^c}) \leq 4(\|F_m - F\|^2 + Pen(m)) + \frac{C}{n}.
\]

This inequality holds for each $m \in \mathbb{M}_n$, so the result is proved.

6.3. **Proof of Proposition 1.** We start by isolating odd terms from even terms to avoid overlaps:

\[
Z_{n,1}(T) = \frac{1}{2} Z_{n,1}^o(T) + \frac{1}{2} Z_{n,1}^e(T)
\]

with
\[
\begin{cases}
Z_{n,1}^o(T) = \frac{2}{n} \sum_{i=1, i \text{ odd}}^n \{ V_T(Y_i, Y_{i+1}) - \mathbb{E}_X[V_T(Y_i, Y_{i+1})] \}, \\
Z_{n,1}^e(T) = \frac{2}{n} \sum_{i=1, \text{even}}^n \{ V_T(Y_i, Y_{i+1}) - \mathbb{E}_X[V_T(Y_i, Y_{i+1})] \}.
\end{cases}
\]

It is sufficient to deal with the first term only, as the second one is similar. For each $i$, let $U_i = (Y_{2i-1}, Y_{2i})$, then

\[
Z_{n,1}^o(T) = \frac{1}{n^{1/2}} \sum_{i=1}^{n/2} \{ V_T(U_i) - \mathbb{E}_X[V_T(U_i)] \}.
\]

Notice that conditionally to $X_1, \ldots, X_n$, the $U_i$’s are independent. Thus we can use the Talagrand inequality recalled in Lemma 5. Note that if $T$ belongs to $\mathbb{S}_m + \mathbb{S}_{m'}$, then $T$ can be written $T_1 + T_2$ where $T_1$ has its support in $[-\pi m, \pi m]^2$ and $T_2$ has its support in $[-\pi m', \pi m']^2$. Then $T$ belongs to $\mathbb{S}_{m''}$ where $m''$ is defined by

\[
m'' = \max(m, m').
\]

Now let us compute $M_1$, $H$ and $v$ of the Talagrand’s inequality.

1. If $T$ belongs to $B(m')$,

\[
V_T(x, y) = \sum_{j,k} a_{jk} V_{\varphi_{m''}}(x, y) = \sum_{j,k} a_{jk} v_{\varphi_{m''}}(x) v_{\varphi_{m''}}(y).
\]

Thus $|V_T(x, y)|^2 \leq \sum_{j,k} |v_{\varphi_{m''}}(x) v_{\varphi_{m''}}(y)|^2$. So

\[
\sup_{T \in B(m')} \|V_T\|_\infty^2 \leq \| \sum_{j,k} |v_{\varphi_{m''}}(x) v_{\varphi_{m''}}(y)|^2 \|_\infty \leq \| \sum_{j} |v_{\varphi_{m''}}(x)|^2 \|^2_\infty.
\]

By using Lemma 5, $M_1 = \Delta(m'')$. 

(2) To compute $H^2$, we write

$$\mathbb{E}_X(\sup_{T \in B(m')} (Z_{n,1}^o (T))^2) \leq \mathbb{E}_X(\sum_{j,k} Z_{n,1}^o (\varphi_{m'',j} \otimes \varphi_{m'',k})^2)$$

$$\leq \sum_{j,k} \text{Var}_X \left[ \frac{2}{n} \sum_{i=1, i \text{ odd}}^n \varphi_{m'',j}(Y_i) v_{\varphi_{m'',k}}(Y_{i+1}) \right]$$

$$\leq \sum_{j,k} \frac{4}{n^2} \sum_{i=1, i \text{ odd}}^n \text{Var}_X [v_{\varphi_{m'',j}}(Y_i) v_{\varphi_{m'',k}}(Y_{i+1})]$$

since, conditionally to $X_1, \ldots, X_n$, the $U_i$'s are independent. And then

$$\mathbb{E}_X(\sup_{T \in B(m')} Z_{n,1}^{o2}(T)) \leq \sum_{j,k} \frac{4}{n^2} \sum_{i=1, i \text{ odd}}^n \mathbb{E}_X [v_{\varphi_{m'',j}}^2(Y_i) v_{\varphi_{m'',k}}^2(Y_{i+1})]$$

$$\leq \frac{4}{n^2} \sum_{i=1, i \text{ odd}}^n \| \sum_j |v_{\varphi_{m'',j}}|^2 \|_\infty \| \sum_k |v_{\varphi_{m'',k}}|^2 \|_\infty \leq \frac{2\Delta (m'')^2}{n}.$$ 

So we set $H = \sqrt{\frac{2\Delta (m'')^2}{n}}$.

(3) We still have to find $v$. On the one hand

$$\text{Var}_X[V_T(Y_k, Y_{k+1})] \leq \mathbb{E}_X [\left( \sum_{j,k} a_{j,k} v_{\varphi_{m'',j}}(Y_k) v_{\varphi_{m'',k}}(Y_{k+1}) \right)^2]$$

$$\leq \sum_{j,k} a_{j,k}^2 \| \sum_j |v_{\varphi_{m'',j}}|^2 \|_\infty \| \sum_k |v_{\varphi_{m'',k}}|^2 \|_\infty$$

and so $v \geq \Delta (m'')^2$. On the other hand

$$\text{Var}_X[V_T(Y_k, Y_{k+1})]$$

$$\leq \sum_{j,k} \sum_{j_1,k_1,j_2,k_2} a_{j_1,k_1} a_{j_2,k_2} \mathbb{E}_X [v_{\varphi_{m'',j_1}} v_{\varphi_{m'',j_2}}(Y_k) v_{\varphi_{m'',k_1}} v_{\varphi_{m'',k_2}}(Y_{k+1})]$$

$$\leq \sum_{j,k} a_{j,k}^2 \sqrt{\sum_{j_1,k_1,j_2,k_2} \mathbb{E}_X^2 [v_{\varphi_{m'',j_1}} v_{\varphi_{m'',j_2}}(Y_k) v_{\varphi_{m'',k_1}} v_{\varphi_{m'',k_2}}(Y_{k+1})]}$$

(15) $$\leq \sum_{j,k} a_{j,k}^2 \sqrt{\sum_{j_1,j_2} \mathbb{E}_X^2 [v_{\varphi_{m'',j_1}} v_{\varphi_{m'',j_2}}(Y_k)] \sum_{k_1,k_2} \mathbb{E}_X^2 [v_{\varphi_{m'',k_1}} v_{\varphi_{m'',k_2}}(Y_{k+1})]}.$$
using conditional independence. Now we use Lemma 3 to compute

\[ E_X[v_{\varphi_{m''}} X_j v_{\varphi_{m''}} Y_k] = \int (v_{\varphi_{m''}} X_j v_{\varphi_{m''}} Y_k)(x+q)dx \]

\[ = \frac{m''}{4\pi^2} \int_{-\pi}^{\pi} e^{-ij_1ve^{i(x+X_k)m''}}dv \int_{-\pi}^{\pi} e^{-ij_2u'e^{i(x+X_k)um''}}du \]

\[ = \frac{m''}{4\pi^2} \int_{-\pi}^{\pi} e^{-ij_1v-ij_2u'e^{iX_k(u+v)m''}}du e^{ix(u+v)m''}q(x)dx.\]

If we set \( W(u, v) = m''e^{iX_k(u+v)m''}q^*(-(u + v)m')/q^*(-vm')q^*(-um'') \), then

\[ E_X[v_{\varphi_{m''}} X_j v_{\varphi_{m''}} Y_k] \]

is the Fourier coefficient with order \((j_1, j_2)\) of \( W \). Using Parseval’s formula

\[ \sum_{j_1, j_2} E^2_X[v_{\varphi_{m''}} X_j v_{\varphi_{m''}} Y_k] = \frac{1}{4\pi^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} |W(u, v)|^2dudv \]

\[ = \frac{m''^2}{4\pi^2} \int_{-\pi}^{\pi} \int_{-\pi}^{\pi} q^*(-(u + v)m')/q^*(-vm')q^*(-um'') \]

\[ = \frac{m''}{4\pi^2} \int_{-\pi}^{\pi} |q^*(-um'')|^{-4}du \int |q^*(x)|^2dx \leq \frac{\|q\|^2}{4\pi^2} \int_{-\pi}^{\pi} |q^*(u)|^{-4}du. \]

We introduce the following notation:

\[ \Delta_2(m) = \frac{1}{4\pi^2} \int_{-\pi}^{\pi} |q^*(u)|^{-4}du. \]

Finally, coming back to (15), \( \text{Var}_X[V_Y(Y_k, Y_{k+1})] \leq \|T\|^2\|q\|^2\Delta_2(m'') \) which yields \( v \geq \|q\|^2\Delta_2(m'') \). Finally we write \( v = \min(\|q\|^2\Delta_2(m''), \Delta_2(m'')) \).

We can now use Talagrand’s inequality (see Lemma 3):

\[ E[ \sup_{T \in B(m')} (Z_{n,1}^2 - 2(1 + 2\epsilon) 2\Delta_2(m'')) \]

\[ \leq \frac{C}{n} \{ \text{ve}^{-K_1\epsilon\Delta_2(m'')} + \frac{\Delta_2(m'')}{nC^2(\epsilon)} \} \text{e}^{-K_2\epsilon\sqrt{\pi}} \}

And then, if \( P_1(m, m') \geq 4(1 + 2\epsilon)\Delta_2(m'')/n, \)

\[ \sum_{m' \in M_n} E \left[ \sup_{T \in B(m')} (Z_{n,1}^2 - P_1(m, m')) \right] \leq \frac{K}{n} \{ I(m) + II(m) \} \]
with \( I(m) = \sum_{m' \in \mathbb{M}_n} v e^{-K_1 C (m')/v} \).

To bound these terms, we use Lemma 4 which yields to

\[
v \leq c_3 (\pi m')^{4\gamma + \min(1-s,2-2s)} e^{4b(\pi m')} \quad \text{and} \quad \frac{\Delta^2 (m')}{v} \geq c_4 (\pi m')^{(1-s)_+}
\]

where \( c_3 \) and \( c_4 \) depend only on \( k_0, k_1, \gamma \) and \( s \). Therefore,

\[
I(m) \leq c_3 \sum_{m' \in \mathbb{M}_n} [(\pi m')^{4\gamma} + \min(1-s,2-2s)] e^{4b(\pi m')} + (\pi m')^{4\gamma} + \min(1-s,2-2s)] e^{4b(\pi m')} - \frac{K_1 c_4 (\pi m')^{(1-s)_+}}{2} \sum_{m' \in \mathbb{M}_n} e^{\frac{K_1 c_4 (\pi m')^{(1-s)_+}}{2}}
\]

We have to distinguish three cases

**case \( s < (1-s)_+ \Leftrightarrow s < 1/2 \):** In this case we choose \( \epsilon = 8b/(K_1 c_4) \) and then

\[
I(m) \leq c_3 (\pi m')^{4\gamma + 1-s} e^{4b(\pi m') - (\pi m')^{(1-s)_+}} \sum_{m' \in \mathbb{M}_n} e^{-K_1 c_4 (\pi m')^{(1-s)_+}} + c_3 e^{-K_1 c_4 (\pi m')^{(1-s)_+}} \sum_{m' \in \mathbb{M}_n} (\pi m')^{4\gamma + 1-s} e^{4b(\pi m') - (\pi m')^{(1-s)_+}}
\]

which implies that \( I(m) \) is bounded. Moreover the definition of \( \mathbb{M}_n \) and Lemma 4 give \( |\mathbb{M}_n| \leq C n^k \) with \( C > 0 \) and \( \zeta > 0 \). So \( II(m) \leq (C/n) |\mathbb{M}_n| e^{-K_2 \sqrt{n}} \) is bounded too.

**case \( s = (1-s)_+ \Leftrightarrow s = 1/2 \):** In this case

\[
I(m) \leq c_3 (\pi m')^{4\gamma + 1/2} e^{4b - K_1 c_4 (\pi m')^{1/2}} \sum_{m' \in \mathbb{M}_n} e^{-K_1 c_4 (\pi m')^{1/2}} + c_3 e^{-K_1 c_4 (\pi m')^{1/2}} \sum_{m' \in \mathbb{M}_n} (\pi m')^{4\gamma + 1/2} e^{4b - K_1 c_4 (\pi m')^{1/2}}
\]

We choose \( \epsilon \) such that \( 4b - K_1 c_4 \epsilon /2 = -4b \) so that

\[
I(m) \leq c_3 (\pi m')^{4\gamma + 1/2} e^{-4b(\pi m')^{1/2}} \sum_{m' \in \mathbb{M}_n} e^{-K_1 c_4 (\pi m')^{1/2}} + c_3 e^{-K_1 c_4 (\pi m')^{1/2}} \sum_{m' \in \mathbb{M}_n} (\pi m')^{4\gamma + 1/2} e^{-4b(\pi m')^{1/2}} \leq C.
\]

The term \( II(m) \) is also bounded since \( \epsilon \) is a constant.
case $s > (1 - s)_+ \iff s > 1/2$: Here we choose $\epsilon$ such that
\[ 4b(\pi m'')^s - K_1 c_4(\pi m'')^{(1-s)_+} / 2 = -4b(\pi m'')^s \]
so that
\[ I(m) \leq c_3(\pi m)^{4\gamma + \min(1-s,2-2s)} e^{-4b(\pi m)^s} \sum_{m' \in M_n} e^{-\frac{K_1 c_4}{2}(\pi m')^{(1-s)_+}} + c_3 e^{-\frac{K_1 c_4}{2}(\pi m)^{1-s}_+} \sum_{m' \in M_n} (\pi m')^{4\gamma + \min(1-s,2-2s)} e^{-4b(\pi m')^s} \leq C. \]
Moreover
\[ II(m) = \sum_{m' \in M_n} \frac{1}{nC^2(e)} e^{-K_2 \sqrt{8b/K_1 c_4(\pi m'')^{(s-(1-s)_+)_+}} \sqrt{n}} \leq C. \]
In any case $\epsilon = [8b/K_1 c_4](\pi m'')^{(s-(1-s)_+)_+}$, so that
\[ P_1(m, m') = C(q)(\pi m'')^{(s-(1-s)_+)_+}\Delta^2(m'')/n \]
where $C(q)$ is a constant depending only on $k_0, k_1, b, \gamma, s$.

6.4. Proof of Proposition 2. We split $Z_{n,2}(T)$ into two terms:
\[ Z_{n,2}(T) = \frac{1}{2} Z_{n,2}^o(T) + \frac{1}{2} Z_{n,2}^e(T) \]
with
\[
\begin{align*}
Z_{n,2}^o(T) &= \frac{2}{n} \sum_{i=1}^{n} \left\{ T(X_i, X_{i+1}) - \int T(x, y) F(x, y) dxdy \right\}, \\
Z_{n,2}^e(T) &= \frac{2}{n} \sum_{i=1}^{n} \left\{ T(X_i, X_{i+1}) - \int T(x, y) F(x, y) dxdy \right\}.
\end{align*}
\]
We bound $\mathbb{E}\left( [\sup_{T \in B(m')} (Z_{n,2}^o(T) - P_2(m, m'))]_+ \mathbbm{1}_{\omega^*} \right)$. The second term can be bounded in the same way. We write $Z_{n,2}^o(T) = (2/n) \sum_{i=1}^{n/2} \{ T(V_i) - \mathbb{E}[T(V_i)] \}$ with $V_i = (X_{2i-1}, X_{2i})$. In order to use Lemma 3, we introduce
\[ Z_{n,2}^{o*}(T) = \frac{1}{2} \nu_{n,1}(T) + \frac{1}{2} \nu_{n,2}(T) \]
where
\[
\begin{align*}
\nu_{n,1}(T) &= \frac{1}{p_n} \sum_{l=0}^{p_n-1} \frac{1}{q_n} \sum_{i=2lq_n+1}^{(2l+1)q_n} \{ T(V_i^*) - \mathbb{E}[T(V_i^*)] \}, \\
\nu_{n,2}(T) &= \frac{1}{p_n} \sum_{l=0}^{p_n-1} \frac{1}{q_n} \sum_{i=(2l+1)q_n}^{(2l+2)q_n} \{ T(V_i^*) - \mathbb{E}[T(V_i^*)] \}.
\end{align*}
\]
Since \( X_i = X_i^* \) on \( \Omega^* \), we can replace \( Z_{\nu,2} \) by \( Z_{\nu} \). This leads us to bound 
\[
\mathbb{E}\left( \left[ \sup_{T \in B(m')} \nu_{n,1}^2(T) - \mathbb{E}\left[ T^2(m',m') \right] \right] \right) \geq 1_{\Omega^*}.
\]
So we compute the bounds \( M_1, H \) and \( v \) of Lemma 3.

1. If \( T \) belongs to \( S \), \( |T(x,y)|^2 \leq \sum_{i,j,k} a_{j,k}^2 \sum_{i,j,k} \varphi_{m',j}(x) \varphi_{m',k}(y) \) and so

\[
\|T\|_{\infty} \leq \|T\| \cdot \|\sum_j \varphi_{m',j}\|_{\infty} = \|T\|_{m'},
\]

using (1) of Lemma 3. Then \( \|1/q_n \sum_{i=2^{l+1}q_n}^n T\|_{\infty} \leq \|T\|_{m'} \) and \( M_1 = m' \).

2. Let us compute \( H^2 \).

\[
\sup_{T \in B(m')} \nu_{n,1}^2(T) \leq \sum_{j,k} \nu_{n,1}^2(\varphi_{m',j} \otimes \varphi_{m',k})
\]

Then, by taking the expectation,

\[
\mathbb{E}\left( \sup_{T \in B(m')} \nu_{n,1}^2(T) \right) \leq \sum_{j,k} \frac{1}{p_n^2} \sum_{i=0}^{p_n-1} \sum_{l=0}^{(2l+1)q_n} \sum_{i=2^{l+1}q_n}^n \varphi_{m',j} \otimes \varphi_{m',k}(V_i^*)
\]

\[
\leq \sum_{j,k} \frac{1}{p_n^2} \sum_{i=0}^{p_n-1} \sum_{l=0}^{(2l+1)q_n} \varphi_{m',j} \otimes \varphi_{m',k}(V_i^*)
\]

by using independence of the \( A^*_i \). Lemma 3 then gives

\[
\mathbb{E}\left( \sup_{T \in B(m')} \nu_{n,1}^2(T) \right) \leq \frac{4}{p_n q_n} \|\sum_{j,k} (\varphi_{m',j} \otimes \varphi_{m',k})^2\|_{\infty} \sum_{i=0}^{p_n-1} \varphi_{m,2} \leq \frac{16}{n} (\sum_{i=0}^{p_n-1} \varphi_{m,2}) m'^2
\]

Finally \( H = 4 \sqrt{\sum \beta_{2k} m' / \sqrt{n}} \).

3. \( v \) remains to be calculated. If \( T \) belongs to \( B(m') \), using Lemma 3

\[
\var \left[ \frac{1}{q_n} \sum_{i=2^{l+1}q_n}^n T(V_i^*) \right] \leq \frac{4}{q_n} \mathbb{E}[T^2(V_1) b(V_1)]
\]

\[
\leq \frac{4}{q_n} \|T\|_{\infty} \mathbb{E}[T^2(V_1)] \mathbb{E}[b^2(V_1)] \leq \frac{4}{q_n} \|T\|_{\infty} \|T\|_{\infty} \sqrt{2 \sum (k+1) \beta_{2k}}
\]

and so

\[
v = 4 \|F\|^{1/2} \sqrt{2 \sum (k+1) \beta_{2k} m' / q_n}.
\]

By writing Talagrand’s inequality (Lemma 3) with \( \epsilon = 1 \), we obtain

\[
\mathbb{E}\left( \left[ \sup_{T \in B(m')} (\nu_{n,1})^2(T) - \frac{16}{n} (\sum \varphi_{m,2}) m'^2 \right] \right) \leq \frac{K}{n} \left( m'' e^{-K_1 m''} + \frac{m'' d_n^2}{n} e^{-K_2 \sqrt{n} / q_n} \right).
\]
Then by summation over $m'$
\[
\sum_{m' \in \mathbb{M}_n} \mathbb{E}\left( \sup_{T \in B(m')} \left( \nu_{n,2} \right)^2(T) - \frac{96}{n} \left( \sum \beta_{2k} m'' \right)_{+} 1_{\Omega^*} \right)
\leq \frac{K}{n} \left\{ \sum_{m' \in \mathbb{M}_n} m'' e^{-K_1 m''} + \sum_{m' \in \mathbb{M}_n} m'' n^{2c-1} e^{-K_2 n^{1/2-c}} \right\} \leq \frac{C}{n}
\]
since $c < 1/2$. In the same way, we obtain
\[
\sum_{m' \in \mathbb{M}_n} \mathbb{E}\left( \left( \nu_{n,2} \right)^2(T) - \frac{96}{n} \left( \sum \beta_{2k} m'' \right)_{+} 1_{\Omega^*} \right) \leq \frac{C}{n},
\]
which yields
\[
\sum_{m' \in \mathbb{M}_n} \mathbb{E}\left( \left( Z_{n,2} \right)^2(T) - P_2(m, m') \right) \leq \frac{C}{n}
\]
with $P_2(m, m') = 96(\sum \beta_{2k} m''^2/n)$.

6.5. **Proof of Corollary 2.** Let us compute the bias term. Since $F_m^* = F^*1_{[-\pi m, \pi m]^2}$,
\[
\|F - F_m\|^2 = \frac{1}{4\pi^2} \int_{[-\pi m, \pi m]^2} |F^*(u, v)|^2 dudv
\leq \frac{1}{4\pi^2} \int_{[-\pi m, \pi m]^2} |F^*(u, v)|^2 dudv + \frac{1}{4\pi^2} \int_{\mathbb{R} \times [-\pi m, \pi m]^c} |F^*(u, v)|^2 dudv
\]
But
\[
\int_{\mathbb{R} \times [-\pi m, \pi m]^c} |F^*(u, v)|^2 dudv \leq L((\pi m)^2 + 1)^{-\Delta - 2 A(\pi m)^R}.
\]
Thus $\|F - F_m\|^2 = O((\pi m)^{-2\Delta - 2 A(\pi m)^R})$ and
\[
\mathbb{E}\|F - \tilde{F}\|^2 \leq C' \inf_{m \in \mathbb{M}_n} \left\{ (\pi m)^{-2\Delta - 2 A(\pi m)^R} + (\pi m)^{(s-1) s} + 4 \gamma + 2 - 2 s \frac{e^{4b(\pi m)^s}}{n} \right\} + \frac{C}{n}.
\]

Next the bias-variance trade-off is performed similarly to [LaCom (2000)].

6.6. **Proof of Theorem 3.** Let $E_n = \{\|f - \tilde{f}\|_\infty \leq f_0/2\}$. On $E_n$ and for $x \in B$, $\tilde{f}(x) = \tilde{f}(x) - f(x) + f(x) \geq f_0/2$. Since $\tilde{\Omega}$ belongs to $\mathcal{S}_{\tilde{M}}$, using (2), $\|\tilde{\Omega}\|_\infty \leq \tilde{M} \|\tilde{\Omega}\|$. But (13) gives $\|\tilde{\Omega}\| \leq \Delta(\tilde{M})$ so that $\|\tilde{\Omega}\|_\infty \leq \tilde{M} \Delta(\tilde{M})$. Since $\tilde{M}$ belongs to $\mathbb{M}_n$, $\Delta(\tilde{M}) \leq \sqrt{n}$ and Lemma 4 gives $\tilde{M} \leq \Delta(\tilde{M})^{1/(2\gamma + 1)}$ if $s = 0$ or $\tilde{M} \leq (\ln \Delta(\tilde{M}))^{1/s}$ otherwise. So, for $n$ large enough, $(2/f_0)\|\tilde{\Omega}\|_\infty \leq n$ and $\tilde{\Omega}(x, y) = \tilde{F}(x, y)/\tilde{f}(x)$. 


For all \((x, y) \in B^2\),
\[
|\hat{\Pi}(x, y) - \Pi(x, y)|^2 \leq \left| \frac{\tilde{F}(x, y) - \hat{f}(x)\Pi(x, y)}{f(x)} \right|^2 I_{E_n} + (|\hat{\Pi}(x, y)| + |\Pi(x, y)|^2)I_{E_n^c}
\]
\[
\leq \frac{|\tilde{F}(x, y) - F(x, y) + \Pi(x, y)(f(x) - \hat{f}(x))|^2}{f_0^2/4}
\]
\[
+ 2(||\hat{\Pi}||_\infty^2 + ||\Pi(x, y)||^2)1_{E_n^c}.
\]
Since \(\int_B \Pi^2(x, y)dy \leq ||\Pi||_{B, \infty} \int_B \Pi(x, y)dy \leq ||\Pi||_{B, \infty}\) for all \(x \in B\),
\[
\mathbb{E}||\Pi - \hat{\Pi}||_B^2 \leq \frac{8}{f_0^2} \mathbb{E}\|F - \tilde{F}\|^2 + ||\Pi||_{B, \infty}\mathbb{E}\|f - \hat{f}\|^2 + 2|B|(|B|n^2 + ||\Pi||_{B, \infty})P(E_n^c).
\]
We still have to prove that \(P(E_n^c) \leq Cn^{-3}\). Given that \(\|f - \hat{f}\|_{\infty} \leq \|f - \hat{f}\|_{\infty} + \|\hat{f} - \hat{f}\|_{\infty}\)
\[
P(E_n) \leq P(\|f - \hat{f}\|_{\infty} > f_0/4) + P(\|\hat{f} - \hat{f}\|_{\infty} > f_0/4).
\]
Let us prove now that if \(f\) belongs to \(A_{5,r,a}(l)\) with \(\delta > 1/2\), \(\|f - \hat{f}\|_{\infty} = O(m^{1/2 - \delta}e^{-a(\pi L_m)^r})\). Since \(f_m^* = f^*1_{[-\pi m, \pi m]}\) and using the inverse Fourier transform,
\[
\|f - f_m\|_{\infty} \leq \frac{1}{2\pi} \int_{|u| \geq \pi m} |f^*(u)|du.
\]
Let \(\alpha \in (1/4, \delta/2)\). By considering that function \(x \mapsto (x^2 + 1)^{\delta/2 - \alpha}e^{a|x|^r}\) is increasing and using the Schwarz inequality, we obtain
\[
\|f - f_m\|_{\infty} \leq \frac{1}{2\pi} ((\pi m)^2 + 1)^{-\delta/2 + \alpha}e^{-a(\pi m)^r} \sqrt{\int_{|u| \geq \pi m} (u^2 + 1)^{-2\alpha}du}.
\]
But \(\int_{|u| \geq \pi m} (u^2 + 1)^{-2\alpha}du \leq C(\pi m)^{1-4\alpha}\) and then
\[
\|f - f_m\|_{\infty} \leq \frac{\sqrt{C\pi}}{2\pi} ((\pi m)^2 + 1)^{-\delta/2 + \alpha}e^{-a(\pi m)^r} (\pi m)^{1/2 - 2\alpha} = O(m^{1/2 - \delta}e^{-a(\pi m)^r}).
\]
Thus, since \(\hat{m} \geq \ln \ln n\), \(\|f - \hat{f}\|_{\infty} \to 0\) and for \(n\) large enough \(P(\|f - \hat{f}\|_{\infty} > f_0/4) = 0\). Next
\[
P(\|f_m - \hat{f}_m\|_{\infty} > f_0/4) \leq P(\Omega^{ec}) + P\left(\|f_m - \hat{f}_m\|1_{\Omega^r} > \frac{f_0}{4\sqrt{m}}\right).
\]
Since \(\varepsilon \theta > 3\), \(P(\Omega^{ec}) \leq Mn^{1-c\theta} \leq Mn^{-2}\). We still have to prove that
\[
P\left(\|f_m - \hat{f}_m\|1_{\Omega^r} > \frac{f_0}{4\sqrt{m}}\right) \leq \frac{C}{n^2}.
\]
First, we observe that
\[
\|f_{\hat{m}} - \hat{f}_{\hat{m}}\|^2 = \sum_{j \in \mathbb{Z}} \left( \frac{1}{n} \sum_{i=1}^{n} v_{\hat{m}_{ij}}(Y_i) - \mathbb{E}[v_{\hat{m}_{ij}}(Y_i)] \right)^2 = \sup_{t \in B_m} \nu_n^2(t)
\]
where \( \nu_n(t) = \frac{1}{n} \sum_{i=1}^{n} v_i(Y_i) - \mathbb{E}[v_i(Y_i)] \), \( B_m = \{ t \in S_m, \| t \| \leq 1 \} \).

Then
\[
P \left( \|f_{\hat{m}} - \hat{f}_{\hat{m}}\| \mathbf{I}_{\Omega^*} > \frac{f_0}{4\sqrt{m}} \right) = P \left( \sup_{t \in B_m} |\nu_n(t)| \mathbf{I}_{\Omega^*} > \frac{f_0}{4\sqrt{m}} \right).
\]

As previously, we split \( \nu_n(t) \) into two terms
\[
\nu_n(t) = \frac{1}{2p_n} \sum_{l=0}^{p_n-1} \frac{1}{q_n} \sum_{i=2q_n, 1}^{(2l+1)q_n} v_i(Y_i) - \mathbb{E}[v_i(Y_i)] + \frac{1}{2p_n} \sum_{l=0}^{p_n-1} \frac{1}{q_n} \sum_{i=(2l+1)q_n, 1}^{(2l+2)q_n} v_i(Y_i) - \mathbb{E}[v_i(Y_i)]
\]
and it is sufficient to study
\[
P \left( \sup_{t \in B_m} \left| \frac{1}{p_n} \sum_{l=0}^{p_n-1} \frac{1}{q_n} \sum_{i=2q_n, 1}^{(2l+1)q_n} v_i(Y_i^*) - \mathbb{E}[v_i(Y_i^*)] \right| > \frac{f_0}{4\sqrt{m}} \right)
\]

We use inequality \cite{17} in proof of Lemma \cite{2} with \( \eta = 1 \) and \( \lambda = \frac{f_0}{8\sqrt{m}} \)
\[
P \left( \sup_{t \in B_m} \left| \frac{1}{p_n} \sum_{l=0}^{p_n-1} \frac{1}{q_n} \sum_{i=2q_n, 1}^{(2l+1)q_n} v_i(Y_i^*) - \mathbb{E}[v_i(Y_i^*)] \right| > 2H + \lambda \right)
\leq \exp \left( -Kp_n \min \left( \frac{\lambda^2}{v}, \frac{\lambda}{M_1} \right) \right)
\]

Here, we compute
\[
M_1 = \sqrt{\Delta(\hat{m})}; \quad H^2 = 8 \sum_k \beta_k \frac{\Delta(\hat{m})}{n}; \quad v = 4 \sum_k \beta_k \frac{\Delta(\hat{m})}{q_n}.
\]

Thus
\[
P \left( \sup_{t \in B_m} |\nu_n(t)| > 2H + \frac{f_0}{8\sqrt{m}} \right) \leq 2 \exp \left( -K' \min \left( \frac{n}{\hat{m} \Delta(\hat{m})}, \frac{p_n}{\hat{m} \Delta(\hat{m})} \right) \right).
\]

Now we use the assumption \( \forall m \quad m \Delta(m) \leq n/(\ln n)^2 \). For \( n \) large enough, \( 2H = 4\sqrt{2} \sum_k \beta_k \sqrt{\Delta(\hat{m})}/\sqrt{n} \leq \frac{f_0}{(8\sqrt{m})} \). So
\[
P \left( \sup_{t \in B_m} |\nu_n(t)| > \frac{f_0}{4\sqrt{m}} \right) \leq 2 \exp \left( -K' \min \left( (\ln n)^2, n^{1/2-c} \ln n \right) \right) \leq \frac{C}{n^3}.
\]
6.7. Technical Lemmas.

Lemma 3. For each $m \in \mathcal{M}_n$

(1) $\|\sum_j \varphi_{m,j}^2\|_{\infty} = m$
(2) $v_{\varphi_{m,j}}(x) = \sqrt{m/(2\pi)} \int_{-\pi}^{\pi} e^{-iju \varphi_{m,j}(\nu(-vm))} dv$
(3) $\|\sum_j |v_{\varphi_{m,j}}|^2\|_{\infty} = \Delta(m)$

where $\Delta(m)$ is defined in (4).

Proof of Lemma 3: First we remark that

$$\varphi_{m,j}^*(u) = \int e^{-ixu} \sqrt{m} \varphi(mx - j) dx = \frac{1}{\sqrt{m}} \int e^{-ixu/m} \varphi(x) dx = \frac{1}{\sqrt{m}} e^{-iju/m} \varphi^*(\frac{u}{m}).$$

Thus using the inverse Fourier transform

$$\varphi_{m,j}(x) = \frac{1}{2\pi} \int e^{ixu} \sqrt{m} e^{-iju/m} \varphi^*(\frac{u}{m}) du = \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-iju} \sqrt{m} e^{ixu/m} \varphi^*(v) dv.$$

The Parseval equality yields $\sum_j \varphi_{m,j}^2(x) = 1/2\pi \int_{-\pi}^{\pi} |\sqrt{m} e^{ixu/m} \varphi^*(v)|^2 dv = m$. The first point is proved. Now we compute $v_{\varphi_{m,j}}(x)$

$$v_{\varphi_{m,j}}(x) = \frac{1}{2\pi} \int e^{ixu} \varphi_{m,j}(u) q^*(-u) du = \frac{1}{2\pi} \int e^{ixu} \sqrt{m} e^{-iju/m} \varphi^*(\frac{u}{m}) q^*(-u) dv.$$

But $\varphi^*(v) = 1_{[-\pi,\pi]}(v)$ and thus the second point is proved. Moreover $v_{\varphi_{m,j}}(x)$ can be seen as a Fourier coefficient. Parseval’s formula then gives

$$\sum_j |v_{\varphi_{m,j}}(x)|^2 = \frac{1}{2\pi} \int_{-\pi}^{\pi} \left| \sqrt{m} e^{ixu/m} \varphi^*(v) \right|^2 dv = \frac{m}{2\pi} \int |q^*(-vm)|^{-2} dv.$$

Therefore $\|\sum_j |v_{\varphi_{m,j}}|^2\|_{\infty} = 1/2\pi \int_{-\pi}^{\pi} |q^*(-u)|^{-2} du = \Delta(m)$.

Lemma 4. If $q$ verifies $|q^*(x)| \geq k_0(x^2 + 1)^{-\gamma/2} \exp(-b|x|^s)$, then

(1) $\Delta(m) \leq c_1(\pi m)^{2\gamma + 1 - s} e^{2b(\pi m)^s}$,
(2) $\Delta_2(m) \leq c_2(\pi m)^{4\gamma + 1 - s} e^{4b(\pi m)^s}$.

Moreover if $|q^*(x)| \leq k_1(x^2 + 1)^{-\gamma/2} \exp(-b|x|^s)$, then $\Delta(m) \geq c_1(\pi m)^{2\gamma + 1 - s} e^{2b(\pi m)^s}$.

The proof of this result is omitted. It is obtained by distinguishing the cases $s > 2\gamma + 1$ and $s \leq 2\gamma + 1$ and with standard evaluations of integrals.

Lemma 5. Let $T_1, \ldots, T_n$ be independent random variables and $v_n(r) = (1/n) \sum_{i=1}^n [r(T_i) - \mathbb{E}(r(T_i))]$, for $r$ belonging to a countable class $\mathcal{R}$ of measurable functions. Then, for
\[\epsilon > 0,\]
\[\mathbb{E}[\sup_{r \in \mathcal{R}} |\nu_n(r)|^2 - 2(1 + 2\epsilon)H^2] \leq C \left( \frac{\nu}{n} e^{-K_1 \epsilon \frac{n^2}{2}} + \frac{M_1^2}{n^2 C^2(\epsilon)} e^{-K_2 C(\epsilon) \sqrt{\tau_n}} \right)\]

with \(K_1 = 1/6, K_2 = 1/(21\sqrt{2}), C(\epsilon) = \sqrt{1 + \epsilon - 1}\) and \(C\) a universal constant and where

\[\sup_{r \in \mathcal{R}} \|r\|_\infty \leq M_1, \quad \mathbb{E} \left( \sup_{r \in \mathcal{R}} |\nu_n(r)| \right) \leq H, \quad \sup_{r \in \mathcal{R}} \frac{1}{n} \sum_{i=1}^n \text{Var}(r(T_i)) \leq v.\]

Usual density arguments allow to use this result with non-countable class of functions \(\mathcal{R}\).

**Proof of Lemma 5:** We apply the Talagrand concentration inequality given in Klein and Rio (2005) to the functions \(s^i(x) = r(x) - \mathbb{E}(r(T_i))\) and we obtain

\[P(\sup_{r \in \mathcal{R}} |\nu_n(r)| \geq H + \lambda) \leq \exp \left( -\frac{n \lambda^2}{2(v + 4HM_1) + 6M_1 \lambda} \right).\]

Then we modify this inequality following Birge and Massart (1998) Corollary 2 p.354. It gives

\[P(\sup_{r \in \mathcal{R}} |\nu_n(r)| \geq (1 + \eta)H + \lambda) \leq \exp \left( -\frac{n \lambda^2}{3 \min \left( \frac{\lambda^2}{2v}, \frac{\min(\eta, 1)\lambda}{7M_1} \right)} \right).\]

To conclude we set \(\eta = \sqrt{1 + \epsilon - 1}\) and we use the formula \(\mathbb{E}[X] = \int_0^\infty P(X \geq t) dt\) with \(X = \sup_{r \in \mathcal{R}} |\nu_n(r)|^2 - 2(1 + 2\epsilon)H^2\).

**Lemma 6.** (Viennet (1997)) Let \((T_i)\) a strictly stationary process with \(\beta\)-mixing coefficients \(\beta_k\). Then there exists a function \(b\) such that

\[\mathbb{E}[b(T_1)] \leq \sum_k \beta_k \quad \text{and} \quad \mathbb{E}[b^2(T_1)] \leq 2 \sum_k (k + 1)\beta_k\]

and for all function \(\psi\) (such that \(\mathbb{E}[\psi^2(T_1)] < \infty\) and for all \(N\)

\[\text{Var}\left( \sum_{i=1}^N \psi(T_i) \right) \leq 4N\mathbb{E}[\psi^2(T_1)b(T_1)].\]

**References**


