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To cite this version:
Marc Durand, Howard Stone. Relaxation time of the topological T1 process in a two-dimensional foam. Physical Review Letters, American Physical Society, 2006, 97, pp.226101. <10.1103/PhysRevLett.97.226101>. <hal-00089405>

HAL Id: hal-00089405
https://hal.archives-ouvertes.fr/hal-00089405
Submitted on 18 Aug 2006

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Relaxation time of the topological T1 process in a two-dimensional foam

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T1 Process

(Received textdate; Revised textdate; Accepted textdate; Published textdate)

Abstract

The elementary topological T1 process in a two-dimensional foam corresponds to the “flip” of one soap film with respect to the geometrical constraints. From a mechanical point of view, this T1 process is an elementary relaxation process through which the entire structure of an out-of-equilibrium foam evolves. The dynamics of this elementary relaxation process has been poorly investigated and is generally neglected during simulations of foams. We study both experimentally and theoretically the T1 dynamics in a dry two-dimensional foam. We show that the dynamics is controlled by the surface viscoelastic properties of the soap films (surface shear plus dilatational viscosity, \( \mu_s + \kappa \), and Gibbs elasticity \( \epsilon \)), and is independent of the shear viscosity of the bulk liquid. Moreover, our approach illustrates that the dynamics of T1 relaxation process provides a convenient tool for measuring the surface rheological properties: we obtained \( \epsilon = 32 \pm 8 \text{ mN/m} \) and \( \mu_s + \kappa = 1.3 \pm 0.7 \text{ mPa.s} \) for SDS, and \( \epsilon = 65 \pm 12 \text{ mN/m} \) and \( \mu_s + \kappa = 31 \pm 12 \text{ mPa.s} \) for BSA, in good agreement with values reported in the literature.

PACS numbers: 68.03.Cd, 68.15.+e, 83.80.Iz, 82.70.Rr

Keywords: T1 process, relaxation, foam, rheology, Marangoni, dilational viscosity, Gibbs elasticity

Any rearrangement in a two-dimensional foam may be regarded as a combination of two elementary topological processes referred to as T1 and T2. The T1 process corresponds to the “flip” of one soap film, as depicted in Fig. 1, while the T2 process corresponds to the disappearance of cells with three sides. From a mechanical point of view, the T1 process corresponds to a transition from a metastable configuration to another, after passing through an unstable configuration where four films meet at one junction (actually, for a small but finite liquid fraction, the instability arises slightly before the four-fold vertex is formed). The spontaneous evolution from one four-fold junction to two three-fold junctions, which involves creation of a new film, is driven by minimization of the surface area. Various experimental and theoretical studies on the frequency of rearrangement events in foams have been conducted, but little is known about the typical relaxation time associated with such events. Indeed, the dynamics of the relaxation processes is usually neglected in simulations of foams even though the rheological behavior of a foam obviously depends on this relaxation time.

In this paper, we investigate theoretically and experimentally the effect of the viscoelastic parameters on the dynamics of the T1 process. Experiments in a two-dimensional foam show that the relaxation time depends on the interfacial viscoelasticity of the films, but not on the shear viscosity of the bulk liquid. These results are corroborated by a model, which allows for an estimation of the Gibbs elasticity and the surface viscosity of the surfactants used to make the foam.

The experimental setup is depicted in Fig. 2: a dry two-dimensional foam is created in a horizontal Plexiglas cell (1 cm high) by blowing air through a bottle containing a surfactant solution. The polyhedral bubbles created have a typical edge length of 1-2 cm. The liquid fraction in the foam, defined as the total volume of liquids in the Plexiglas cell divided by the cell volume, is about 1%. Two different foaming agents have been used in order to study the influence of the rheological properties of the interface on the T1 dynamics: (i) Sodium Dodecyl Sulfate (SDS), at a concentration of 4.80 g/L,
forms “mobile” surfaces, and (ii) protein Bovine Serum Albumin, together with a cosurfactant Propylene Glycol Alginate (PGA), both at concentrations of 4.00 g/L, form “rigid” interfaces. The impact of the shear viscosity of the bulk liquid has been investigated by adding glycerol, 0%, 60% and 72% (w/w), to the bulk solutions.

In order to cause rearrangements in the foam, we use a syringe to blow the air away from one bubble. Then the rearrangements are viewed from above with a high-speed camera. The length of the soap film is measured by following its two ends using particle-tracking software. Experiments where the other vertices have noticeable movements during the relaxation process, or where simultaneous T1 events occur, have been disregarded.

The relaxation process is characterized by the creation of a new soap film following the appearance of a four-fold junction. For different surfactant systems, we report the length of the new film, normalized by its final length, as a function of time in Fig. 3. Several trials for each solution are shown and illustrate that the time evolution of the reduced length appears independent of the final film length. We define a typical time T associated with the relaxation process as the time for the film to reach 90% of its final length. A comparison of the results for a foam made with the SDS without glycerol (shear viscosity of the liquid $\mu = 1.0$ mPa.s) and with 60% glycerol ($\mu = 10.7$ mPa.s) shows that there is no significant effect of the viscosity of the bulk liquid ($T \simeq 0.5$ sec for both solutions). This response is not unreasonable since, for the mechanics of a free soap film, viscous effects of the bulk are generally negligible in comparison with the effects of the viscoelastic properties of the interfaces [2, 3].

We note that as the foam is constrained between two planes, most of the liquid of each soap film is located in the menisci close to the solid surfaces. In this region there is dissipation that depends on the shear viscosity of the solution. Hence, from our experimental observations we conclude that frictional effects at the boundaries have a negligible influence on the T1 dynamics. This result is not in contradiction with the observations made on the rheology of 2D foam [4, 5, 6], where a macroscopic stress (pressure drop) causes motion of the foam relative to the boundaries and the shear viscosity of the bulk solution is the main parameter controlling the dynamics.

Next, we compare the SDS results with those from the BSA/PGA solution $\mu = 7$ mPa.s, both without glycerol. We observe a change in the typical relaxation time by about a factor of 7 ($T \simeq 3.7$ sec for the BSA/PGA solution). Although, coincidentally, the viscosity of the BSA/PGA solution is increased by a factor 7 relative to the SDS solution, we can rule out this influence since we just demonstrated that the viscosity of the solution is not rate limiting. We also verified that the addition of glycerol to the BSA/PGA solution did not produce any significant change in the typical relaxation times (results not shown). These results allow us to conclude that the viscoelastic properties of the interfaces dictate the relaxation time of the T1 process.

We now provide a brief description of a theoretical framework for the T1 dynamics; for details of the derivation and complete considerations of various special cases see [4]. We compare the theoretical predictions with the experiments, which allows us to extract surface rheological parameters. The net result is a model for the T1 process and estimates for the relaxation time.

We assume that the geometry is symmetrical with thin
films nearly together at an unstable four-fold configuration; each film connects to one of four fixed vertices at the corner of a rectangle with sides $2L_x$ and $2L_y$ (see Fig. 3). It is experimentally observed that the stretching film has a spatially uniform but time varying thickness $h(t)$ everywhere except near the Plateau borders located at $x = \pm x_B(t)$ at the top and bottom boundaries; these dynamics are common for the fluid dynamics of thin films [12]. We focus on the dynamics of the stretching central film of length $2x_B(t)$, which is driven by the monotonic decrease of the angle $\alpha(t)$:

$$\cos \alpha(t) = \frac{L_x - x_B(t)}{\sqrt{L_y^2 + (L_x - x_B(t))^2}}$$

The surface tension $\gamma$ changes in time as the surfactant surface density $\Gamma$ is reduced by stretching. Also, we introduce the length $L(t) = \sqrt{L_y^2 + (L_x - x_B(t))^2}$ of the adjacent films which shorten with time. Since the flat film can support no pressure gradient the axial velocity $U(x, t)$ in the main body of the film is a linear function of position, $U \propto x$ [13]. This uniform extensional motion means that away from other films we have $\gamma(t)$ and $\Gamma(t)$, which do not change with position $x$.

The dynamics follow from a force balance on the stretching film and a surfactant mass balance. Neglecting inertia terms and dissipative terms associated with the viscosity of the bulk liquid [17], Newton’s second law applied to the film reduces to a balance between surface tension contributions and surface dissipative terms ($\mu_s$ and $\kappa$ denote the shear and dilatational viscosities and $\gamma_{eq}$ denotes the equilibrium value of the surface tension of the soap solution):

$$2\gamma_{eq} \cos \alpha(t) - \gamma(t) - (\mu_s + \kappa) \frac{dU}{dx} = 0.$$  \hspace{1cm} (2)

During the expansion of the new film, adjacent films act as surfactant reservoirs, so that $\gamma(t)$ and $\Gamma(t)$ are assumed to be close to their equilibrium values, and so are related by the Langmuir equation of state: $\gamma(t) = \gamma_{eq} - \epsilon \ln (\Gamma(t)/\Gamma_{eq})$, where $\epsilon$ is the Gibbs elasticity and $\Gamma_{eq}$ is the equilibrium surface density. This equilibrium value $\Gamma_{eq}$ is assumed to be present in the adjacent films.

Next, we turn to a mass balance on the surfactant. This requires accounting for stretching of the interface as well as addition of surfactant to the new surface created as the adjacent films, of length $L(t)$, are shortened. We assume that as surfactant is added to the end of the stretching film the surface density is rapidly adjusted to a spatially uniform state by strong Marangoni forces. In addition, we neglect diffusion/adsorption processes from the bulk liquid, restricting our study at short times (these slower processes only affect shape adjustments as the final equilibrium is approached). So, the change in the total number of surfactant molecules during a time interval $dt$ is $\frac{d}{dt} (\Gamma x_B) = -\Gamma_{eq} dL$, where $dL = -dx_B, \cos \alpha(t)$; here we have only accounted for one interface of each adjacent film as feeding the stretched film since surfactant from the other interface must desorb from the surface, transit through the bulk, then adsorb to the stretched interface, which is a much longer process. Integration of this equation allows us to express $\Gamma(t)$ as a function of $x_B(t)$:

$$\Gamma(t) = \Gamma_{eq} \frac{L(t) - L_x}{x_B(t)}$$

where $L_t = \sqrt{L_y^2 + (L_x - x_B(t))^2} + x_0 \left( x_0 = x_B(0) \right)$). In addition, with the above approximations, the density along the film must also satisfy the local conservation law $\frac{d}{dt} \Gamma(t) + \frac{d\Gamma}{dx} \frac{dU}{dx} = 0$. Comparison of these two evolution equations leads to $\frac{d\Gamma}{dx} = \frac{\Gamma_{eq} x_B}{x_B(t)} \left( 1 - \frac{x_B(t)}{L(t)} \cos \alpha(t) \right)$. Note that since $U \propto x$, the surface velocity at the junction is $U(x_B(t), t) = \frac{dx_B}{dt} \left( 1 - \frac{x_B(t)}{L(t)} \cos \alpha(t) \right)$, which is smaller than the velocity of the junction itself $(= \dot{x}_B)$. This velocity difference is a consequence of the slip of the surface (and surfactant) coming from the adjacent film. Finally, Eq. 2 is rewritten as an evolution equation for $x_B(t)$:

$$2\gamma_{eq} \left( \cos \alpha(t) - \frac{1}{2} \right) + \epsilon \ln \left( \frac{L_x - L(t)}{x_B(t)} \right) - (\mu_s + \kappa) \frac{\dot{x}_B}{x_B} \left( 1 - \frac{x_B(t)}{L(c - L(t))} \cos \alpha(t) \right) = 0.$$

$$\hspace{1cm} (3)$$
We now compare this theoretical description with the experiments using measurements of $x_B(t)$. From Eq. 4, a plot of $Y(t) = \frac{d\Gamma}{dx}(1 - \frac{1}{1(t)} \cos \alpha(t)) / (\cos \alpha(t) - \frac{1}{1})$ versus $X(t) = \ln \left(\frac{1}{L_s + 1(t)}\right) / (\cos \alpha(t) - \frac{1}{1})$ should yield a straight line: $Y = \frac{2\kappa\alpha}{\mu_s + \kappa} + \frac{\kappa\alpha}{\mu_s + \kappa} X$.

Typical experimental curves $Y(t)$ vs $X(t)$ are shown in Fig. 3 for SDS and BSA/PGA [23]. At short times (typically, for times below 0.1 sec for SDS and 0.8 sec for BSA), their evolution is nearly linear, in excellent agreement with the theory. A linear fit of these curves gives estimates of the surface Gibbs elasticity and the sum of the surface and dilatational viscosities.

Note, however, that our value of the surface viscosity of SDS correspond to the highest value reported in literature [24], which, in addition, there is a large difference between values of the shear and dilatational surface viscosities, and it is often unclear in published works which surface viscosity is actually measured.

This study of the T1 dynamics in a two-dimensional foam illustrates that the relaxation time $T$ associated with the process is a function of two parameters, $\mu_s + \kappa$ and $\kappa$. From dimensional analysis of Eq. 3, $T = \frac{\mu_s + \kappa}{\kappa \gamma_{eq}} f(\frac{1}{\gamma_{eq}})$, where $f$ is an increasing function of the dimensionless parameter $\frac{1}{\gamma_{eq}}$. This theoretical description, which has been corroborated with our experimental data, might be useful for simulations of aging or rheological properties of foams. Finally, we expect that a sheared foam has a different rheological response when the shear rate is significantly different than this typical relaxation time.

This work was supported by the Harvard MRSEC (DMR-0213805) and Unilever Research. We thank Legena Jack (and the support of the Harvard REU program) for assistance with the experiments and Alex Lips and Jean-Marc di Meglio for helpful conversations.

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[21] To obtain $Y(t)$ we need $x_B(t)$ first we fitted $x_B(t)$ with a simple function and then took the derivative. Moreover, for each recorded T1 process, we extract values of $x_B(0)$ and $\alpha_0$ from the movies, and we account for the asymmetry of the initial configuration by measuring the different values of $L_x$ and $L_y$ on each side of the junction.