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NONLINEAR EQUATIONS WITH UNBOUNDED HEAT CONDUCTION AND INTEGRABLE DATA

DOMINIQUE BLANCHARD⁽¹⁾⁽²⁾, OLIVIER GUIBÉ⁽²⁾ AND HICHAM REDWANE⁽³⁾

ABSTRACT. We consider a class of quasi-linear diffusion problems involving a matrix $\mathbf{A}(t, x, u)$ which blows up for a finite value m of the unknown u . Stationary and evolution equations are studied for L^1 data. We focus on the case where the solution u can reach the value m . For such problems we introduce a notion of renormalized solutions and we prove the existence of such solutions.

KEYWORDS: nonlinear equations, blowing-up heat conduction, existence, renormalized solutions, integrable data.

RÉSUMÉ. Nous considérons une classe de problèmes de diffusion quasi-linéaires pour des matrices $\mathbf{A}(t, x, u)$ qui explosent pour une valeur m finie de l'inconnue u . Les cas stationnaire et d'évolution sont traités pour des données intégrables et pour des solutions qui atteignent la valeur m . Nous donnons une formulation de solutions renormalisées pour ces problèmes et nous démontrons l'existence de telles solutions.

MOTS CLEFS : équations non linéaires, diffusion singulière, existence, solutions renormalisées, donnée intégrable.

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0.1. INTRODUCTION

We investigate a class of diffusion problems, in the stationary and evolution cases, with singular matrices with respect to the unknown. More precisely let Ω be a bounded domain of \mathbb{R}^N , m and T be two positive real numbers and β and γ be two functions of $\mathcal{C}^0((-\infty, m))$ such that $\beta(s) \leq \gamma(s)$, $\lim_{s \rightarrow m^-} \beta(s) = +\infty$ and $\int_0^m \gamma(s) ds < +\infty$. We consider a Carathéodory matrix field $\mathbf{A}(t, x, s)$ defined on $(0, T) \times \Omega \times (-\infty, m)$ such that

$$(0.1) \quad \beta(s)|\xi|^2 \leq \mathbf{A}(t, x, s)\xi \cdot \xi \leq \gamma(s)|\xi|^2$$

for any $s \in (-\infty, m)$ and any $\xi \in \mathbb{R}^N$, almost everywhere in $(0, T) \times \Omega$.

Then the matrix $\mathbf{A}(t, x, s)$ blows up (uniformly with respect to (t, x)) as $s \rightarrow m^-$. We are interested in the diffusion problems governed by the matrix field $\mathbf{A}(t, x, u)$ in the stationary (\mathbf{A} is then independent of t) or evolution cases (see equations (1.1) and (2.1)). When dealing such problems, the main difficulty is indeed to give a sense to the flux $\mathbf{A}(t, x, u)Du$ on the set $\{(t, x); u(t, x) = m\}$, or more precisely to describe the behavior of the energy $\mathbf{A}^\varepsilon(t, x, u^\varepsilon)Du^\varepsilon \cdot Du^\varepsilon$ for approximate solutions u^ε . In the elliptic case where the matrix is independent of the space variable and with a diagonal blowing part the analysis was carried out in [6] for L^2 data where an L^2 estimate for $\mathbf{A}^\varepsilon(u^\varepsilon)Du^\varepsilon$ was derived. Then the authors gave two formulations of problem of type (1.1), both of them using a sort of decoupling behavior of the solution on the subset $\{u < m\}$ and on the subset $\{u = m\}$. Indeed another type of assumptions can be adopted when \mathbf{A} depends on the x -variable and is not diagonal as in [8, 9, 14] where one assumes that $\int_0^m \beta(s) ds = +\infty$, which forces the solution to avoid the value m . Then it is easy to construct a solution u which is strictly less than m almost everywhere in $(0, T) \times \Omega$ (that is $\text{meas}\{u = m\} = 0$) (see also Section 6) and to show, at least for L^2 data, that $\mathbf{A}^\varepsilon(t, x, u^\varepsilon)Du^\varepsilon \cdot Du^\varepsilon \rightarrow \mathbf{A}(t, x, u)Du \cdot Du$ in $L^1((0, T) \times \Omega)$. Indeed this is due to the fact that no energy can concentrate on the set $\{u = m\}$. For L^1 data, the same results hold true with u^ε and u replaced by any truncation $T_k(u^\varepsilon)$ and $T_k(u)$ (see the definition of T_k in Section 1.1).

In the present paper, we focus on the case where $\mathbf{A}(t, x, u)$ is not diagonal, $\int_0^m \gamma(s) ds < +\infty$ and for L^1 data both for elliptic and parabolic problems. If we assume that if f is small in L^q for some appropriate q then one can prove that $u < m$ almost everywhere (see [14] for the elliptic case). Here we just assume that f is in L^1 and then we have to handle the set $\{u = m\}$. We give a notion of renormalized solutions (which is more precise in the elliptic case than the one given in [6]) and we prove the existence of such solutions for L^1 data. The formulation of the problem consists (as in [6]) in considering the equation on the subset $\{u < m\}$ on the one hand and in specifying the behavior of the energy near the subset

$\{u = m\}$ where the coefficients are singular on the other hand. For this point of view, it is at least formally similar to the formulation for elliptic problems with measure data considered in [7], where one distinguishes the equation where the measure is smooth and the behavior of the energy where the measure is singular.

Let us point out that the energy condition that we obtain in the present paper is more precise than the one stated in [6].

Let us also emphasize that another difficulty arising in the analysis of diffusion problems with matrices satisfying (0.1) is the possible different behaviors of the functions β and γ near m . Loosely speaking, the lower bound in (0.1) and the equation lead to estimates on $D(\int_0^u \beta(s) ds)$ in some L^p (depending on the smoothness of f) while the upper bound of (0.1) naturally yields an estimate on the flux $\mathbf{A}(t, x, u)Du$ if one has an estimate on $D(\int_0^u \gamma(s) ds)$.

The paper is organized as follows. In Part 1 we investigate the elliptic case. In Section 1.1 we precise the assumptions on the data and we give the definition of a solution. Section 1.2 we state the existence theorem and we detail the proof in 3 steps. Part 2 is devoted to the parabolic case. The definition of the solution is given in Section 2.1. Section 2.2 gives the existence theorem together with its proof. Section 2.3 is devoted to concluding remarks concerning the case $\int_0^m \beta(s) ds = +\infty$ and to a partial uniqueness result.

Part 1. The elliptic case

1.1. ASSUMPTION ON THE DATA AND DEFINITION OF A SOLUTION

Let Ω be a bounded domain of \mathbb{R} ($N \geq 1$) and m be a positive real number. We consider the following nonlinear problem

$$(1.1) \quad \begin{cases} -\operatorname{div}(\mathbf{A}(x, u)Du) = f & \text{in } \Omega; \\ u = 0 & \text{on } \partial\Omega, \end{cases}$$

where the assumptions on the data are detailed below. We assume that

$$(1.2) \quad f \in L^1(\Omega)$$

$$(1.3) \quad \mathbf{A} : (x, s) \mapsto \mathbf{A}(x, s)$$

is a Carathéodory function from $\Omega \times (-\infty, m)$ into $\mathbb{R}_S^{N \times N}$, the set of $N \times N$ symmetric matrices, such that there exist two positive functions β and γ in $\mathcal{C}^0((-\infty, m))$ which satisfy

$$(1.4) \quad \lim_{s \rightarrow m^-} \beta(s) = +\infty; \quad \beta(s) \geq \alpha > 0 \quad \forall s \in (-\infty, m)$$

$$(1.5) \quad \int_0^m \gamma(s) ds < +\infty$$

$$(1.6) \quad \forall s \in (-\infty, m), \quad \forall \xi \in \mathbb{R}^N \quad \beta(s)|\xi|^2 \leq \mathbf{A}(x, s)\xi \cdot \xi \leq \gamma(s)|\xi|^2 \quad \text{a.e. in } \Omega.$$

Remark 1.1. Indeed (1.4)–(1.6) imply that $\lim_{s \rightarrow m^-} \gamma(s) = +\infty$ and $\int_0^m \beta(s) ds < +\infty$. The study of (1.1) under the assumption $\int_0^m \beta(s) ds = +\infty$ is easier (see [10, 14] and Section 2.3) because one can then show that there exists a solution such that $u < m$ a.e. in Ω .

Assumptions (1.4), (1.6) imply that the (x, s) -dependent norm $|\mathbf{A}^{1/2}(x, s)\xi|$ on \mathbb{R}^N blows up as s tends to m uniformly with respect to x in Ω .

The following notations will be used throughout the paper: for any $k \geq 0$, the truncation at height k is defined by $T_k(s) = \max(-k, \min(s, k))$; for any integer $n \geq 1$ and any positive real number $\varepsilon > 0$, the functions θ_n , h_n , S_n and b_ε are defined by

$$(1.7) \quad \theta_n(s) = \frac{1}{n}(T_n(s) - T_n(s)), \quad h_n(s) = 1 - |\theta_n(s)|,$$

$$(1.8) \quad S_n(s) = \int_0^s h_n(r) \, dr$$

$$(1.9) \quad b_\varepsilon(r) = \begin{cases} 1 & \text{if } r \leq m - 2\varepsilon, \\ 1 - (r - m + \varepsilon) & \text{if } m - 2\varepsilon \leq r \leq m - \varepsilon, \\ 0 & \text{if } r \geq m - \varepsilon. \end{cases}$$

1.1.1. Definition of a solution. In this subsection, we give the definition of a solution of (1.1). This definition is more precise than the one used in [6] in the sense that it localizes the behavior of the energy near the zone where a solution may reach the value m (see [6]).

Definition 1.2. A measurable function u defined on Ω is a renormalized solution of (1.1) if

$$(1.10) \quad \forall k \geq 0; \quad T_k(u) \in H_0^1(\Omega),$$

$$(1.11) \quad u \leq m \text{ a.e. in } \Omega,$$

$$(1.12) \quad \forall k \geq 0; \quad \mathbb{1}_{\{-k < u < m\}} \mathbf{A}(x, u) Du \in (L^2(\Omega))^N,$$

$$(1.13) \quad \lim_{n \rightarrow +\infty} \frac{1}{n} \int_{\{-2n < u < -n\}} \mathbf{A}(x, u) Du \cdot Du \, dx = 0,$$

for any function $\varphi \in L^\infty(\Omega) \cap H^1(\Omega)$ such that $D\varphi = 0$ a.e. on $\{x \in \Omega; u(x) = m\}$ one has

$$(1.14) \quad \lim_{n \rightarrow +\infty} n \int_{\{m-2/n < u < m-1/n\}} \mathbf{A}(x, u) Du \cdot Du \varphi \, dx = \int_{\{u=m\}} f \varphi \, dx,$$

for any function $h \in W^{1,\infty}(\mathbb{R})$ such that $\text{supp}(h)$ is compact and $h(m) = 0$, u satisfies

$$(1.15) \quad -\text{div} [h(u) \mathbf{A}(x, u) Du] + h'(u) \mathbf{A}(x, u) Du \cdot Du = h(u) f \quad \text{in } \mathcal{D}'(\Omega).$$

Remark 1.3 (Comments on Definition 1.2). Conditions (1.10) and (1.13) are classical when dealing with renormalized solutions for partial differential equations with L^1 data (see [12, 13, 2]). The fact that $u \leq m$ almost everywhere in Ω is already explained (and is natural) in [6]. By contrast, the condition (1.14) on the behavior of the energy near the subset $\{x \in \Omega; u(x) = m\}$ is an improvement (even in the case $f \in L^2(\Omega)$) of the one obtained in [6] where it is written for $\varphi \equiv 1$. As mentioned in the introduction this type of condition on the behavior of the energy near level set of u is also considered in [7].

The condition (1.12), which was established in [6] for a diagonal matrix \mathbf{A} , is here strongly linked to the fact that $\int_0^m \gamma(s) \, ds < +\infty$. The equation (1.15) and the conditions on the function h are the same as in [6] to which we refer to claim that every term makes sense in this equation. Let us first recall that since $u \leq m$ almost everywhere in Ω , the condition $h(m) = 0$ in (1.15) may be equivalently replaced by $h(r) = 0, \forall r \geq m$.

1.2. EXISTENCE RESULT

We establish the following theorem.

Theorem 1.4. *Under the assumptions (1.2)–(1.6), there exists at least a solution of (1.1) in the sense of Definition 1.2.*

Proof. The main difficulty comes from the fact that the functions β and γ entering in the lower and upper bounds of (1.6) may have different growths when s tends to m . Loosely speaking, even if $f \in L^2(\Omega)$, (and formally) if one uses $\int_0^u \beta(s) ds$ as a test function in (1.1) the lower bound in (1.6) leads to an estimate on $\int_0^u \beta(s) ds$ in $H_0^1(\Omega)$. The upper bound in (1.6) does not permit to obtain any kind of estimates on the fields $\mathbf{A}(x, u) Du \mathbb{1}_{\{u < m\}}$ if no assumption on the relative behavior of γ with respect to β near m is adopted.

As shown in the sequel, we will use a test function which mixes the two functions β and γ . In some sense, this forces to introduce a specific regularization of $\mathbf{A}(x, s)$ which is different from the one used in [6] (namely a truncation of $\mathbf{A}(x, s)$ near m).

For any $\varepsilon > 0$, we consider the field of matrices $\mathbf{A}^\varepsilon(x, s)$ defined on $\Omega \times \mathbb{R}$ by

$$(1.16) \quad \mathbf{A}^\varepsilon(x, s) = b_\varepsilon(s) \mathbf{A}(x, s) + (1 - b_\varepsilon(s)) \beta(m - \varepsilon) I,$$

where b_ε is the function defined in (1.9) and I is the identity matrix of $\mathbb{R}^{N \times N}$. Indeed (1.16) we use the convention

$$b_\varepsilon(s) \mathbf{A}(x, s) = 0 \quad \text{for } s \geq m - \varepsilon.$$

Due to assumptions (1.4) and (1.6), we have

$$(1.17) \quad \forall s \in \mathbb{R}; \quad \forall \xi \in \mathbb{R}^N \quad \alpha |\xi|^2 \leq \mathbf{A}^\varepsilon(x, s) \xi \cdot \xi \leq (b_\varepsilon(s) \gamma(s) + \max_{r \in (0, m - \varepsilon)} \beta(r)) |\xi|^2.$$

Using classical result on renormalized solutions for quasi-linear elliptic problems (see e.g. [7, 12, 13]) and (1.17), the following regularized problem admits at least one solution u^ε

$$(1.18) \quad \begin{cases} -\operatorname{div}(\mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon) = f & \text{in } \Omega; \\ u^\varepsilon = 0 & \text{on } \partial\Omega. \end{cases}$$

Recall that the sequence u^ε satisfies the following properties (see again [7, 12, 13])

$$(1.19) \quad T_k(u^\varepsilon) \in H_0^1(\Omega), \quad \forall k \geq 0,$$

$$(1.20) \quad \lim_{n \rightarrow +\infty} \frac{1}{n} \int_{\{n < |u^\varepsilon| < 2n\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon dx = 0,$$

for any function $h \in W^{1, \infty}(\mathbb{R})$ such that $\operatorname{supp}(h)$ is compact

$$(1.21) \quad -\operatorname{div} [h(u^\varepsilon) \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon] + h'(u^\varepsilon) \mathbf{A}(x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon = h(u^\varepsilon) f \quad \text{in } \mathcal{D}'(\Omega).$$

In order to show that, for a subsequence still indexed by ε , u^ε converges to a solution u of the problem in the sense of Definition 1.2, we first introduce the two sequences of auxiliary functions

$$(1.22) \quad v^\varepsilon = \int_0^{(u^\varepsilon)^+} (\gamma(s) b_\varepsilon(s) + (1 - b_\varepsilon(s)) \beta(m - \varepsilon)) ds$$

and

$$(1.23) \quad w^\varepsilon = \int_0^{(u^\varepsilon)^+} (\beta(s) b_\varepsilon(s) + (1 - b_\varepsilon(s)) \beta(m - \varepsilon)) ds.$$

Remark that, since $\gamma(s) \geq \beta(s) \geq \alpha$ for any $s \in (-\infty, m)$, we have

$$(1.24) \quad \alpha(u^\varepsilon)^+ \leq w^\varepsilon \leq v^\varepsilon \quad \text{a.e. in } \Omega$$

and

$$(1.25) \quad v^\varepsilon \leq \max_{s \in (0, m-\varepsilon)} \gamma(s)(u^\varepsilon)^+ \quad \text{a.e. in } \Omega.$$

Then because of (1.19), v^ε and w^ε satisfy $T_k(v^\varepsilon) \in H_0^1(\Omega)$ and $T_k(w^\varepsilon) \in H_0^1(\Omega)$ with

$$(1.26) \quad DT_k(v^\varepsilon) = \mathbb{1}_{\{v^\varepsilon < k\}} [\gamma(u^\varepsilon)b_\varepsilon(u^\varepsilon) + (1 - b_\varepsilon(u^\varepsilon))\beta(m - \varepsilon)] DT_{k/\alpha}(u^\varepsilon)^+$$

$$(1.27) \quad DT_k(w^\varepsilon) = \mathbb{1}_{\{w^\varepsilon < k\}} [\beta(u^\varepsilon)b_\varepsilon(u^\varepsilon) + (1 - b_\varepsilon(u^\varepsilon))\beta(m - \varepsilon)] DT_{k/\alpha}(u^\varepsilon)^+$$

a.e. in Ω . In order to shorten the notation, we set for $\varepsilon > 0$

$$(1.28) \quad G^\varepsilon(r) = \int_0^{r^+} (\gamma(s)b_\varepsilon(s) + (1 - b_\varepsilon(s))\beta(m - \varepsilon)) ds,$$

which is the Lipschitz-continuous monotone function such that

$$(1.29) \quad v^\varepsilon = G^\varepsilon(u^\varepsilon).$$

The proof is now divided into 3 steps.

Step 1. A priori estimates and pointwise convergence of u^ε .

All the estimates derived below are obtained through (1.18)-(1.21) with a classical technique (at least as far as a reader which is familiar with renormalized solutions is concerned). It consists in choosing $h = h_p$ in (1.21), then in plugging a test function which is bounded and with a gradient equal to a monotone function of $DT_l(u^\varepsilon)$ (as this is the case in (1.26), (1.27)) and then to pass to the limit in the obtained result making use of (1.20) (with p in place of n) when p tends to $+\infty$. It means that using formally such test functions directly in (1.18) is a licit process. We refer to [7, 12, 13] if necessary.

Choosing first $T_k(u^\varepsilon)$ in this process (i.e. $h = h_p$ with $T_k(u^\varepsilon)$ as a test function and letting $p \rightarrow +\infty$ for fixed k and ε), we first obtain the classical estimate (see (1.4), (1.6))

$$(1.30) \quad \alpha \int_{\Omega} |DT_k(u^\varepsilon)|^2 dx \leq k \|f\|_{L^1(\Omega)},$$

$$(1.31) \quad (\mathbf{A}^\varepsilon(x, u^\varepsilon))^{1/2} DT_k(u^\varepsilon) \text{ is bounded in } (L^2(\Omega))^N,$$

for any $k \geq 0$ and uniformly in ε .

From (1.30) we deduce with a classical argument (see e.g. [12]) that, for a subsequence still indexed by ε ,

$$(1.32) \quad u^\varepsilon \longrightarrow u \quad \text{a.e. in } \Omega,$$

$$(1.33) \quad T_k(u^\varepsilon) \longrightarrow T_k(u) \quad \text{weakly in } H_0^1(\Omega),$$

as ε tends to 0, where u is a measurable function defined on Ω which is finite a.e. in Ω (and which belongs to $W_0^{1,q}(\Omega)$, $1 \leq q < N/(N-1)$).

To prove that u is less or equal to m is an easy task which is performed exactly as in [6]: when choosing $T_{2m}^+(u^\varepsilon) - T_m^+(u^\varepsilon)$ instead of $T_k(u^\varepsilon)$ in the above process and by using the definition (1.16) of \mathbf{A}^ε , one obtain

$$\beta(m - \varepsilon) \int_{\Omega} |DT_{2m}^+(u^\varepsilon) - DT_m^+(u^\varepsilon)|^2 dx \leq m \|f\|_{L^1(\Omega)}.$$

Then in view of (1.32) and with the help of Poincaré's inequality together with the fact that $\beta(m - \varepsilon) \rightarrow +\infty$ as ε tends to 0, we deduce that

$$T_{2m}^+(u) - T_m^+(u) = 0 \quad \text{a.e. in } \Omega,$$

that is

$$(1.34) \quad u \leq m \quad \text{a.e. in } \Omega.$$

Let us now take $T_n(w^\varepsilon - (u^\varepsilon)^-)$ as a test function in (1.21) (with $h = h_p$ and then passing to the limit as p goes infinity), we obtain

$$\int_{\Omega} \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot DT_n(w^\varepsilon - (u^\varepsilon)^-) dx \leq n \|f\|_{L^1(\Omega)}.$$

Since the support of w^ε and $(u^\varepsilon)^-$ are disjoint, we deduce that, using also (1.27)

$$(1.35) \quad \int_{\Omega} \mathbb{1}_{\{w^\varepsilon < n\}} [\beta(u^\varepsilon) b_\varepsilon(u^\varepsilon) + (1 - b_\varepsilon(u^\varepsilon)) \mathbf{A}^\varepsilon(x, u^\varepsilon) D(u^\varepsilon)^+ \cdot DT_{n/\alpha}((u^\varepsilon)^+)] dx \\ + \int_{\Omega} \mathbb{1}_{\{(u^\varepsilon)^- < n\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) D(u^\varepsilon)^- \cdot DT_n((u^\varepsilon)^-) \leq n \|f\|_{L^1(\Omega)}.$$

Now the definition (1.16) of \mathbf{A}^ε together with assumption (1.6) show that

$$\beta(s) b_\varepsilon(s) |\xi|^2 + (1 - b_\varepsilon(s)) \beta(m - \varepsilon) |\xi|^2 \leq \mathbf{A}^\varepsilon(x, s) \xi \cdot \xi,$$

for any $s \in \mathbb{R}$; any $\xi \in \mathbb{R}^N$ and a.e. in Ω .

Then (1.16), (1.27) and (1.35) yield

$$(1.36) \quad \int_{\Omega} |DT_n(w^\varepsilon)|^2 dx + \alpha \int_{\Omega} |DT_n((u^\varepsilon)^-)|^2 dx \leq n \|f\|_{L^1(\Omega)},$$

which in turn implies (using again the fact that w^ε and $(u^\varepsilon)^-$ have disjoint supports)

$$(1.37) \quad \min(1, \alpha) \int_{\Omega} |DT_n(w^\varepsilon - (u^\varepsilon)^-)|^2 dx \leq n \|f\|_{L^1(\Omega)}.$$

Poincaré's inequality and (1.37) lead to

$$n^2 \text{meas}\{x \in \Omega; |w^\varepsilon - (u^\varepsilon)^-| > n\} \leq Cn \|f\|_{L^1(\Omega)},$$

where C does not depend on n and ε , and we obtain that

$$(1.38) \quad \lim_{n \rightarrow +\infty} \sup_{\varepsilon} \text{meas}\{x \in \Omega; |w^\varepsilon - (u^\varepsilon)^-| > n\} = 0.$$

To obtain the analog of (1.38) with v^ε in place of w^ε , we use the assumption $\int_0^m \gamma(s) ds < +\infty$. Indeed

$$(1.39) \quad v^\varepsilon = w^\varepsilon + \int_0^{(u^\varepsilon)^+} (\gamma(s) - \beta(s)) b_\varepsilon(s) ds \leq w^\varepsilon + \int_0^m (\gamma(s) - \beta(s)) ds,$$

where $\int_0^m (\gamma(s) - \beta(s)) ds < +\infty$ by (1.5). It follows that (1.38) implies that

$$(1.40) \quad \lim_{n \rightarrow +\infty} \sup_{\varepsilon} \text{meas}\{x \in \Omega; |v^\varepsilon - (u^\varepsilon)^-| > n\} = 0.$$

Another consequence of (1.36) is that (for a subsequence) w^ε converges almost everywhere in Ω to a measurable function w which is finite almost everywhere in Ω . Then (1.39), in

which $(u^\varepsilon)^+$ can be replaced by $T_m((u^\varepsilon)^+)$ (because of the definition of b_ε), shows that (for a subsequence)

$$(1.41) \quad v^\varepsilon \longrightarrow v \quad \text{a.e. in } \Omega,$$

where $v = w + \int_0^{u^+} (\gamma(s) - \beta(s)) ds$, because $T_m((u^\varepsilon)^+) \rightarrow u^+$ a.e. in Ω since $u \leq m$ a.e. in Ω . Indeed v is a measurable positive function which is finite almost everywhere in Ω . Let us point out that the definitions (1.9) of b_ε and (1.22) of v^ε , together with the convergences (1.32) and (1.41), show that

$$(1.42) \quad \begin{aligned} v &= \int_0^{u^+} \gamma(s) ds \quad \text{a.e. in } \{x \in \Omega; u(x) < m\}, \\ w &= \int_0^{u^+} \beta(s) ds \quad \text{a.e. in } \{x \in \Omega; u(x) < m\}, \end{aligned}$$

but we do not know if this relations hold true on the subset $\{x \in \Omega; u(x) = m\}$.

Now we choose $\theta_n(v^\varepsilon - (u^\varepsilon)^-)$ as a test function in (1.21), it gives

$$\frac{1}{n} \int_{\{n \leq |v^\varepsilon - (u^\varepsilon)^-| \leq 2n\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) dx \leq \int_{\{|v^\varepsilon - (u^\varepsilon)^-| > n\}} |f| dx.$$

Using now $f \in L^1(\Omega)$ and (1.40) we obtain

$$(1.43) \quad \lim_{n \rightarrow +\infty} \sup_{\varepsilon} \frac{1}{n} \int_{\{n \leq |v^\varepsilon - (u^\varepsilon)^-| \leq 2n\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) dx = 0.$$

Remark that the condition (1.43) is the analog of the standard one (i.e. for a matrix $\mathbf{A}(x, s)$ defined and continuous for $s \in \mathbb{R}$) upon replacing $(u^\varepsilon)^+$ by v^ε .

To end this step we show below that the flux $\mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon$ is bounded in $(L^2(\Omega))^N$ on the subsets where $v^\varepsilon - (u^\varepsilon)^-$ is truncated. To this end we plug the test function $T_k(v^\varepsilon)$ in (1.21). We obtain using (1.26)

$$(1.44) \quad \int_{\{|v^\varepsilon| < k\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot [b_\varepsilon(u^\varepsilon)\gamma(u^\varepsilon) + (1 - b_\varepsilon(u^\varepsilon))\beta(m - \varepsilon)] D(u^\varepsilon)^+ dx \leq k \|f\|_{L^1(\Omega)}.$$

Now remark that (1.6) and the definition (1.16) of $\mathbf{A}^\varepsilon(x, s)$ leads to

$$(1.45) \quad \mathbf{A}^\varepsilon(x, s) \xi \cdot \xi \leq [b_\varepsilon(s)\gamma(s) + (1 - b_\varepsilon(s))\beta(m - \varepsilon)] |\xi|^2$$

for any $s \in \mathbb{R}$, any $\xi \in \mathbb{R}^N$ and a.e. in Ω . Using (1.45) with $\xi = [\mathbf{A}^\varepsilon(x, u^\varepsilon)]^{1/2} D(u^\varepsilon)^+$ in (1.44) yields

$$\int_{\Omega} \mathbb{1}_{\{|v^\varepsilon| < k\}} |\mathbf{A}^\varepsilon(x, u^\varepsilon) D(u^\varepsilon)^+|^2 dx \leq k \|f\|_{L^1(\Omega)},$$

and then for any $k \geq 0$

$$(1.46) \quad \mathbb{1}_{\{|v^\varepsilon| < k\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) D(u^\varepsilon)^+ \quad \text{is bounded in } (L^2(\Omega))^N$$

uniformly in ε . Now, since $\mathbb{1}_{\{|v^\varepsilon - (u^\varepsilon)^-| < k\}} = \mathbb{1}_{\{0 \leq v^\varepsilon < k\}} + \mathbb{1}_{\{-k < u^\varepsilon < 0\}}$ a.e. in Ω , the continuous character of $\mathbf{A}(x, s)$ for $s \in (-\infty, 0]$ and estimate (1.30) show that for any $k \geq 0$

$$(1.47) \quad \mathbb{1}_{\{|v^\varepsilon - (u^\varepsilon)^-| < k\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \quad \text{is bounded in } (L^2(\Omega))^N$$

uniformly in ε .

Step 2. Weak limit of the fields and proof of $\mathbb{1}_{\{-k < u < m\}} \mathbf{A}(x, u) Du \in (L^2(\Omega))^N$.

We first use the estimates (1.31) and (1.47) to extract another subsequence, still indexed by ε , such that (recall that $\text{supp}(h_n) \subset [-2n, 2n]$),

$$(1.48) \quad (\mathbf{A}^\varepsilon(x, u^\varepsilon))^{1/2} DT_k(u^\varepsilon) \longrightarrow X_k \quad \text{weakly in } (L^2(\Omega))^N,$$

and

$$(1.49) \quad h_n(v^\varepsilon - (u^\varepsilon)^-) \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \longrightarrow \psi_n \quad \text{weakly in } (L^2(\Omega))^N,$$

as ε tends to 0, where for any $k \geq 0$ and $n \geq 1$, $X_k \in (L^2(\Omega))^N$ and $\psi_n \in (L^2(\Omega))^N$.

Next we identify ψ_n on the subset where $u < m$ and to this end we use the same technique as in [3]. Let h be a $\mathcal{C}^\infty(\mathbb{R})$ -function such that $\text{supp}(h)$ is compact in $(-M, l)$ with $l < m$ and $M > 0$. Then using the fact that $h(s)\mathbf{A}^\varepsilon(x, s) = h(s)\mathbf{A}(x, T_l(s^+) - T_M(s^-))$ for ε small enough and the convergences (1.32), (1.33), (1.41), we have

$$(1.50) \quad h(u^\varepsilon)h_n(v^\varepsilon - (u^\varepsilon)^-) \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \longrightarrow h(u)h_n(v - u^-) \mathbf{A}(x, u) Du \quad \text{weakly in } (L^2(\Omega))^N,$$

as ε tends to 0 and where Du stands for $DT_l(u^+) - DT_M(u^-)$. It follows from (1.49) and (1.50) that

$$(1.51) \quad \psi_n = h_n(v - u^-) \mathbf{A}(x, u) Du \quad \text{a.e. in } \{x \in \Omega; u(x) < m\}$$

since $l < m$ and M are arbitrary. Let us point out that to obtain (1.50) and then (1.51), it is sufficient to know that v^ε pointwise converges to v on the subset $\{x \in \Omega; u(x) < m\}$ (this will be used in the parabolic case).

Now, remark that on the subset $\{x \in \Omega; u(x) < m\}$, we have $0 \leq v = \int_0^{u^+} \gamma(s) ds < \int_0^m \gamma(s) ds$, and then for $n > \int_0^m \gamma(s) ds$, $h_n(v - u^-) = h_n(-u^-)$ on $\{x \in \Omega; u(x) < m\}$. It follows that from (1.51)

$$(1.52) \quad \psi_n = h_n(-u^-) \mathbf{A}(x, u) Du \quad \text{a.e. in } \{x \in \Omega; u(x) < m\},$$

which in turn implies that

$$(1.53) \quad \mathbb{1}_{\{-k < u < m\}} \mathbf{A}(x, u) Du \in (L^2(\Omega))^N.$$

We now identify X_k . To this end, proceeding exactly as for ψ_n above, we first have for any $k \geq 0$

$$(1.54) \quad h_n(v^\varepsilon - (u^\varepsilon)^-) \mathbf{A}^\varepsilon(x, u^\varepsilon) DT_k(u^\varepsilon) \longrightarrow \psi_n^k \quad \text{weakly in } (L^2(\Omega))^N$$

as ε tends to 0 with

$$(1.55) \quad \psi_n^k = h_n(v - u^-) \mathbf{A}(x, u) DT_k(u) \quad \text{a.e. in } \{x \in \Omega; u(x) < m\}$$

Then, for $n > \max(k, \int_0^m \gamma(s) ds)$ one has $h_n(v - u^-) DT_k(u) = DT_k(u)$ a.e. in $\{x \in \Omega; u(x) < m\}$. It follows that

$$(1.56) \quad \psi_n^k = \mathbf{A}(x, u) DT_k(u) \quad \text{a.e. in } \{x \in \Omega; u(x) < m\}$$

for $n > \max(k, \int_0^m \gamma(s) ds)$.

Secondly, we write

$$(1.57) \quad h_n(v^\varepsilon - (u^\varepsilon)^-) (\mathbf{A}^\varepsilon(x, u^\varepsilon))^{1/2} DT_k(u^\varepsilon) = h_n(v^\varepsilon - (u^\varepsilon)^-) (\mathbf{A}^\varepsilon(x, u^\varepsilon))^{-1/2} \mathbf{A}^\varepsilon(x, u^\varepsilon) DT_k(u^\varepsilon)$$

and we use the pointwise convergence of u^ε to obtain $(\mathbf{A}^\varepsilon(x, u^\varepsilon))^{-1/2} \rightarrow (\mathbf{A}(x, u))^{-1/2}$ a.e. in Ω (with indeed $(\mathbf{A}(x, u))^{-1/2} = 0$ on the subset $\{x \in \Omega; u(x) = m\}$). Passing to the limit in (1.57) as ε tends to 0 (remark that $|(\mathbf{A}^\varepsilon(x, u^\varepsilon))^{-1/2}\xi|^2 \leq |\xi|^2/\alpha$) gives using (1.54)

$$(1.58) \quad h_n(v^\varepsilon - (u^\varepsilon)^-)(\mathbf{A}^\varepsilon(x, u^\varepsilon))^{1/2} DT_k(u^\varepsilon) \longrightarrow (\mathbf{A}(x, u))^{-1/2} \psi_n^k \quad \text{weakly in } (L^2(\Omega))^N \text{ as } \varepsilon \text{ tends to } 0.$$

Now for $n > \max(k, \int_0^m \gamma(s) ds)$,

$$(\mathbf{A}(x, u))^{-1/2} \psi_n^k = \mathbb{1}_{\{u < m\}} (\mathbf{A}(x, u))^{1/2} DT_k(u) \quad \text{a.e. in } \Omega,$$

because of (1.56) in the subset $\{x \in \Omega; u(x) < m\}$ and the equality is trivial in $\{x \in \Omega; u(x) = m\}$ since both $(\mathbf{A}(x, u))^{-1/2}$ and $DT_k(u)$ are equal to 0. In view of (1.48) and (1.58) we deduce that

$$(1.59) \quad X_k = \mathbb{1}_{\{u < m\}} (\mathbf{A}(x, u))^{1/2} DT_k(u) \quad \text{a.e. in } \Omega.$$

Step 3. End of the proof.

We choose $h(r) = h_n(G^\varepsilon(r) - r^-)$ in (1.21) (recall that this is licit because $h \in W^{1,\infty}(\mathbb{R})$ and $\text{supp}(h) \subset [-2n, 2n/\alpha]$). Then let z be an element of $L^\infty(\Omega) \cap H_0^1(\Omega)$. Plugging z as a test function in (1.21) with h defined above, we obtain using (1.29)

$$(1.60) \quad \int_{\Omega} h_n(v^\varepsilon - (u^\varepsilon)^-) \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot Dz \, dx \\ = \int_{\Omega} f h_n(v^\varepsilon - (u^\varepsilon)^-) z \, dx + \int_{\Omega} z \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot Dh_n(v^\varepsilon - (u^\varepsilon)^-) \, dx.$$

First recall that the convergences (1.32) and (1.41) give

$$\int_{\Omega} f h_n(v^\varepsilon - (u^\varepsilon)^-) z \, dx \longrightarrow \int_{\Omega} f h_n(v - u^-) z \, dx$$

as ε tends to 0.

Then, setting

$$\omega(n) = \sup_{\varepsilon} \frac{1}{n} \int_{\{n < |v^\varepsilon - (u^\varepsilon)^-| < 2n\}} \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) \, dx,$$

we deduce that from (1.49), upon extracting another subsequence of ε , still denoted by ε

$$-\omega(n) \|z\|_{L^\infty(\Omega)} \leq \lim_{\varepsilon \rightarrow 0} \int_{\Omega} h_n(v^\varepsilon - (u^\varepsilon)^-) \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon Dz \, dx \\ - \int_{\Omega} f h_n(v - u^-) z \, dx \leq \omega(n) \|z\|_{L^\infty(\Omega)}.$$

Now $h_n(v - u^-) \rightarrow 1$ a.e. in Ω as n tends to $+\infty$ (recall that both u and v are finite a.e. in Ω) while $\omega(n) \rightarrow 0$ as n tends to $+\infty$ (see (1.43)), it follows that

$$(1.61) \quad \lim_{n \rightarrow +\infty} \lim_{\varepsilon \rightarrow 0} \int_{\Omega} h_n(v^\varepsilon - (u^\varepsilon)^-) \mathbf{A}^\varepsilon(x, u^\varepsilon) Du^\varepsilon Dz \, dx = \int_{\Omega} f z \, dx.$$

From (1.61), we will deduce that u satisfies (1.13)–(1.15) and the strong convergence of the energy.

Firstly choose $z = h(u)\varphi$ where $h \in W^{1,\infty}(\mathbb{R})$ has a compact support and satisfies $h(m) = 0$ and $\varphi \in C_0^\infty(\Omega)$. By (1.33) we have $h(u)\varphi \in H_0^1(\Omega) \cap L^\infty(\Omega)$. Then, (1.49) and (1.61) lead to

$$(1.62) \quad \lim_{n \rightarrow +\infty} \int_{\Omega} \psi_n D(h(u)\varphi) \, dx = \int_{\Omega} fh(u)\varphi \, dx.$$

Using now the identification (1.52) of ψ_n , it follows that, for $k \geq 0$ such that $\text{supp}(h) \subset [-k, k]$ and $n \geq k$

$$(1.63) \quad \begin{aligned} \psi_n D[h(u)\varphi] &= \psi_n h(u) D\varphi + \psi_n \varphi Dh(T_k(u)) \\ &= \mathbb{1}_{\{u < m\}} \mathbf{A}(x, u) D[h(u)\varphi] \quad \text{a.e. in } \Omega \end{aligned}$$

because $h(m) = 0$ and $Dh(T_k(u)) = 0$ a.e. on the subset $\{x \in \Omega; u(x) = m\}$ (since $T_k(u) \in H_0^1(\Omega)$).

From (1.62) and (1.63), we obtain that

$$\int_{\Omega} \mathbb{1}_{\{u < m\}} \mathbf{A}(x, u) Du \cdot D[h(u)\varphi] \, dx = \int_{\Omega} fh(u)\varphi \, dx$$

for any $\varphi \in C_0^\infty(\Omega)$. This shows that (1.15) is satisfied in $\mathcal{D}'(\Omega)$

Secondly, we choose $z = \theta_p(-u^-)$ (see (1.7)) for a fixed integer $p \geq 1$ and we obtain

$$(1.64) \quad \lim_{n \rightarrow +\infty} \int_{\Omega} \psi_n D\theta_p(-u^-) \, dx = \int_{\Omega} f\theta_p(-u^-) \, dx.$$

Using the identification of ψ_n as above, it gives

$$\int_{\Omega} \mathbf{A}(x, u) Du \cdot D\theta_p(-u^-) \, dx = \int_{\Omega} f\theta_p(-u^-) \, dx$$

and, then letting p tends to $+\infty$

$$\lim_{p \rightarrow +\infty} \frac{1}{p} \int_{\{-2p < u < -p\}} \mathbf{A}(x, u) Du \cdot Du \, dx = 0,$$

since again u is finite a.e. in Ω , and (1.13) is established.

Thirdly to obtain (1.14), we take $z_p = (1 - b_{1/p}(u^+))\varphi$ where p is a fixed integer ≥ 1 (see (1.9)) and $\varphi \in H^1(\Omega) \cap L^\infty(\Omega)$ is such that $D\varphi = 0$ a.e. in $\{x \in \Omega; u(x) = m\}$. Indeed $\|z_p\|_{L^\infty(\Omega)} \leq \|\varphi\|_{L^\infty(\Omega)}$ and

$$Dz_p = p \mathbb{1}_{\{m-2/p < u < m-1/p\}} Du \varphi + (1 - b_{1/p}(u^+)) D\varphi$$

so that $Dz_p = 0$ a.e. on $\{x \in \Omega; u(x) = m\}$. It follows that from (1.61)

$$(1.65) \quad \begin{aligned} p \int_{\Omega} \mathbb{1}_{\{m-2/p < u < m-1/p\}} \mathbf{A}(x, u) Du \cdot Du \varphi \, dx \\ + \int_{\Omega} (1 - b_{1/p}(u^+)) \mathbb{1}_{\{u < m\}} \mathbf{A}(x, u) Du \cdot D\varphi \, dx \\ = \int_{\Omega} f(1 - b_{1/p}(u^+)) \varphi \, dx. \end{aligned}$$

Now, as p tends to $+\infty$, $(1 - b_{1/p}(u^+)) \rightarrow \mathbb{1}_{\{u=m\}}$ a.e. in Ω and (1.65) gives

$$\lim_{p \rightarrow +\infty} p \int_{\Omega} \mathbb{1}_{\{m-2/p < u < m-1/p\}} \mathbf{A}(x, u) Du \cdot Du \varphi \, dx = \int_{\Omega} f \mathbb{1}_{\{u=m\}} \varphi \, dx$$

which is (1.14).

Finally, in order to prove the strong convergence of the energy we choose $z = T_k(u)$. The relation (1.61) gives as above (remark that $DT_k(u) = 0$ a.e. in $\{x \in \Omega; u(x) = m\}$)

$$\lim_{n \rightarrow +\infty} \int_{\Omega} \psi_n DT_k(u) \, dx = \int_{\Omega} f T_k(u) \, dx.$$

The identification (1.52) of ψ_n then leads to

$$\lim_{n \rightarrow +\infty} \int_{\Omega} h_n(-u^-) \mathbb{1}_{\{u < m\}} \mathbf{A}(x, u) Du \cdot DT_k(u) \, dx = \int_{\Omega} f T_k(u) \, dx$$

and then for $n > k$

$$(1.66) \quad \int_{\Omega} \mathbb{1}_{\{u < m\}} \mathbf{A}(x, u) DT_k(u) \cdot DT_k(u) \, dx = \int_{\Omega} f T_k(u) \, dx$$

for any $k \geq 0$.

Indeed, recalling the process that leads to (1.30) and passing to the limit first as $p \rightarrow +\infty$ and then as ε tends to 0, using the pointwise convergence of u^ε , permits to obtain the classical convergence

$$(1.67) \quad \lim_{\varepsilon \rightarrow 0} \int_{\Omega} \mathbf{A}^\varepsilon(x, u^\varepsilon) DT_k(u^\varepsilon) \cdot DT_k(u^\varepsilon) \, dx = \int_{\Omega} f T_k(u) \, dx.$$

From the identification (1.59) of X_k we deduce from (1.66) and (1.67) that for any $k \geq 0$

$$(1.68) \quad (\mathbf{A}^\varepsilon(x, u^\varepsilon))^{1/2} DT_k(u^\varepsilon) \longrightarrow \mathbb{1}_{\{u < m\}} (\mathbf{A}(x, u))^{1/2} DT_k(u) \quad \text{strongly in } (L^2(\Omega))^N,$$

as ε tends to 0.

Remark that (1.68) implies that for any $k \geq 0$

$$T_k(u^\varepsilon) \longrightarrow T_k(u) \quad \text{strongly in } H_0^1(\Omega), \text{ as } \varepsilon \text{ tends to 0.}$$

The proof of Theorem 1.4 is achieved. \square

Part 2. The parabolic case

2.1. ASSUMPTION ON THE DATA AND DEFINITION OF A SOLUTION

The second part of the paper is devoted to investigate a parabolic version of (1.1) namely the problem

$$(2.1) \quad \begin{cases} \frac{\partial u}{\partial t} - \operatorname{div}[\mathbf{A}(t, x, u) Du] = f & \text{in } (0, T) \times \Omega, \\ u = 0 & \text{on } (0, T) \times \partial\Omega, \\ u(t = 0) = u_0 & \text{in } \Omega, \end{cases}$$

where now $T > 0$ and

$$(2.2) \quad f \in L^1((0, T) \times \Omega);$$

$$(2.3) \quad u_0 \in L^1(\Omega) \quad \text{and} \quad u_0 \leq m \quad \text{a.e. in } \Omega;$$

$$(2.4) \quad \mathbf{A} : (t, x, s) \rightarrow \mathbf{A}(t, x, s) \text{ is a Carathéodory function from } (0, T) \times \Omega \times (-\infty, m) \text{ into } \mathbb{R}_S^{N \times N}, \text{ such that there exists two positive functions } \beta \text{ and } \gamma \text{ in } \mathcal{C}^0((-\infty, m)) \text{ which satisfy (1.4), (1.5) and}$$

$$(2.5) \quad \forall s \in (-\infty, m), \forall \xi \in \mathbb{R}^N, \quad \beta(s)|\xi|^2 \leq \mathbf{A}(t, x, s)\xi \cdot \xi \leq \gamma(s)|\xi|^2 \quad \text{a.e. in } (0, T) \times \Omega.$$

We denote by Q the set $(0, T) \times \Omega$. We use the following definition of a solution of (2.1).

Definition 2.1. A function u in $L^\infty(0, T; L^1(\Omega))$ is a renormalized solution of (2.1) if

$$(2.6) \quad \forall k \geq 0, \quad T_k(u) \in L^2(0, T; H_0^1(\Omega));$$

$$(2.7) \quad u \leq m \quad \text{a.e. in } Q;$$

$$(2.8) \quad \forall k \geq 0, \quad \mathbb{1}_{\{-k < u < m\}} \mathbf{A}(t, x, u) Du \in (L^2(Q))^N$$

$$(2.9) \quad \lim_{n \rightarrow +\infty} \frac{1}{n} \int_{\{-2n < u < -n\}} \mathbf{A}(t, x, u) Du \cdot Du \, dx \, dt = 0;$$

for any $\varphi \in C_0^\infty([0, T])$

$$(2.10) \quad \lim_{n \rightarrow +\infty} n \int_{\{m-2/n < u < m-1/n\}} \varphi \mathbf{A}(t, x, u) Du \cdot Du \, dx \, dt = \int_{\{u=m\}} f \varphi \, dx \, dt.$$

$\forall S \in W^{2,\infty}(\mathbb{R})$ such that $\text{supp}(S')$ is compact and $S'(m) = 0$, $\forall \varphi \in W^{1,\infty}(Q)$ such that $\varphi(T) = 0$ and $S'(0)\varphi = 0$ on $\partial\Omega$, u satisfies

$$(2.11) \quad - \int_Q \varphi_t S(u) \, dx \, dt - \int_\Omega \varphi(0) S(u_0) \, dx \\ + \int_Q \mathbf{A}(t, x, u) Du \cdot D[S'(u)\varphi] \, dx \, dt = \int_Q f S'(u) \varphi \, dx \, dt$$

Remark 2.2 (Comments on Definition 2.1). Conditions (2.6) and (2.9) are classical in the framework of renormalized solutions. Indeed (2.7) and (2.10) is the analog of (1.11) and (1.14) in the elliptic case, and due to (2.2), (2.4) and (2.6) every term in (2.11) makes sense. Let us point out that the main difference between Definition 1.2 and 2.1 is that (2.10) is analog to (1.14) but with $\varphi \in C_0^\infty([0, T])$ which does not depend on the variable x . Actually we are not able to prove (2.10) with any function $\varphi \in L^2(0, T; H^1(\Omega)) \cap L^\infty(Q)$ such that $D\varphi = 0$ a.e. in $\{(t, x); u(t, x) = m\}$ because of a lack of regularity on u with respect to t in the parabolic case. Then Definition 2.1 is less precise than Definition 1.2.

Moreover remark that, since we are dealing with homogeneous Dirichlet condition ($u = 0$ on $(0, T) \times \partial\Omega$), the condition $S'(u)\varphi \in L^2(0, T; H_0^1(\Omega))$ just rewrites as $S'(0)\varphi = 0$ on $(0, T) \times \partial\Omega$ (indeed $S'(u)\varphi \in L^2(0, T; H^1(\Omega))$ by (2.6)).

2.2. EXISTENCE RESULT

We prove the following result

Theorem 2.3. *Under the assumptions (2.2)–(2.5), there exists at least a solution of (2.1) in the sense of Definition 2.1.*

Proof of Theorem 2.3. We proceed through the same approximation process as in the proof of Theorem 1.4 and define $\mathbf{A}^\varepsilon(t, x, s)$ by the expression given in (1.16) (with $\mathbf{A}(t, x, s)$ in place of $\mathbf{A}(x, s)$). Due to (1.17), the approximate problem

$$(2.12) \quad \begin{cases} \frac{\partial u^\varepsilon}{\partial t} - \text{div}[\mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon] = f & \text{in } Q, \\ u^\varepsilon = 0 & \text{on } (0, T) \times \partial\Omega, \\ u^\varepsilon(t = 0) = u_0 & \text{in } \Omega, \end{cases}$$

admits at least a renormalized solution (see e.g. [4, 5]). Recall that such a solution satisfies

$$(2.13) \quad u^\varepsilon \in L^\infty(0, T; L^1(\Omega))$$

$$(2.14) \quad \forall k \geq 0; \quad T_k(u^\varepsilon) \in L^2(0, T; H_0^1(\Omega))$$

$$(2.15) \quad \lim_{n \rightarrow +\infty} \frac{1}{n} \int_{\{n < |u^\varepsilon| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon \, dx \, dt = 0;$$

$\forall S \in W^{2,\infty}(\mathbb{R})$ such that $\text{supp}(S')$ is compact, $\forall \varphi \in W^{1,\infty}(Q)$ such that $\varphi(T) = 0$ and $S'(u^\varepsilon)\varphi \in L^2(0, T; H_0^1(\Omega))$, u^ε satisfies

$$(2.16) \quad - \int_Q \varphi_t S(u^\varepsilon) \, dx \, dt - \int_\Omega \varphi(0) S(u_0) \, dx \\ + \int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D[S'(u^\varepsilon)\varphi] \, dx \, dt = \int_Q f S'(u^\varepsilon) \varphi \, dx \, dt$$

In order to prove that, for a subsequence still indexed by ε , the sequence u^ε converges to a solution in the sense of Definition 2.1 we proceed in 5 Steps.

Step 1. A priori estimates

Let us define the two sequences v^ε and w^ε through the formulae (1.22) and (1.23) (now v^ε and w^ε are defined on Q). Since (1.24) and (1.25) still hold true (see assumptions (2.4) and (2.5)), (2.6) implies that $T_k(v^\varepsilon) \in L^2(0, T; H_0^1(\Omega))$, $T_k(w^\varepsilon) \in L^2(0, T; H_0^1(\Omega))$ and

$$(2.17) \quad DT_k(v^\varepsilon) = \mathbb{1}_{\{v^\varepsilon < k\}} [\gamma(u^\varepsilon) b_\varepsilon(u^\varepsilon) + (1 - b_\varepsilon(u^\varepsilon)) \beta(m - \varepsilon)] DT_{k/\alpha}(u^\varepsilon)^+$$

$$(2.18) \quad DT_k(w^\varepsilon) = \mathbb{1}_{\{w^\varepsilon < k\}} [\beta(u^\varepsilon) b_\varepsilon(u^\varepsilon) + (1 - b_\varepsilon(u^\varepsilon)) \beta(m - \varepsilon)] DT_{k/\alpha}(u^\varepsilon)^+$$

a.e. in Q .

The techniques used to derive all the estimates contained in this section is similar to the one used in the elliptic case. It consists in choosing $S'(r) = h_p'(r) \mathcal{Z}(r)$ in (2.16), where h_p is defined in (1.7) and where \mathcal{Z} is a monotone bounded and Lipschitz continuous function defined on \mathbb{R} . The test function φ is always equal to $\varphi = \min\left(\frac{(T-\delta-t)^+}{\delta}, 1\right)$ (which is then independent of x). Compared to the elliptic case, this means that the choice of the non linear test function of u^ε is included in the function S and this is the advantage of the formulation (2.16) : it has already used an integration by part (in time) formula (see Section 2 of [5]). In this process, the parameter δ first tends to 0. Then we let p tends first to $+\infty$ using (2.15), for a fixed ε and a fixed function \mathcal{Z} .

We begin with classical estimates by choosing $S'(r) = h_p(r) T_k(r)$ in (2.16) (that is $\mathcal{Z}(r) = T_k(r)$). We obtain

$$(2.19) \quad \frac{1}{\delta} \int_{T-2\delta}^{T-\delta} \int_\Omega \left(\int_0^{u^\varepsilon} h_p(r) T_k(r) \, dr \right) \, dx \, dt \\ + \int_0^{T-2\delta} \int_\Omega \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D[h_p(u^\varepsilon) T_k(u^\varepsilon)] \, dx \, dt \\ \leq k [\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}]$$

Letting δ tend to 0, it gives as soon as $p > k$

$$\begin{aligned} & \int_0^T \int_{\Omega} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) DT_k(u^\varepsilon) \cdot DT_k(u^\varepsilon) dx dt \\ & \leq k[\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}] + \frac{k}{p} \int_{\{(t,x); p < |u^\varepsilon| < 2p\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon dx dt. \end{aligned}$$

Now for fixed ε and k we let p tends to $+\infty$ and it yields using (2.15)

$$(2.20) \quad \int_0^T \int_{\Omega} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) DT_k(u^\varepsilon) \cdot DT_k(u^\varepsilon) dx dt \leq k[\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}].$$

In view of (1.16) (which is now also uniform in t), we deduce from (2.20) that

$$(2.21) \quad \alpha \int_Q |DT_k(u^\varepsilon)|^2 dx dt \leq k[\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}].$$

Remark that, replacing T by $0 < T' < T$ in the function φ , the inequality (2.19) also leads to the classical estimate

$$(2.22) \quad \|u^\varepsilon\|_{L^\infty(0,T'; L^1(\Omega))} \leq \|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}.$$

Now we choose $S'(r) = h_p(r)(T_{2m}^+(r) - T_m^+(r))$ in (2.16) and we proceed as above. After letting δ and p tend to 0 and $+\infty$ respectively, we obtain

$$\int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D[T_{2m}^+(u^\varepsilon) - T_m^+(u^\varepsilon)] dx dt \leq m[\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}].$$

Then, using the definition of \mathbf{A}^ε exactly as in the elliptic case, we deduce that

$$(2.23) \quad \beta(m - \varepsilon) \int_Q |T_{2m}^+(u^\varepsilon) - T_m^+(u^\varepsilon)|^2 dx dt \leq m[\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}].$$

Let us now define the Lipschitz-continuous monotone function H^ε by

$$(2.24) \quad H^\varepsilon(r) = \int_0^{r^+} (\beta(s)b_\varepsilon(s) + (1 - b_\varepsilon(s))\beta(m - \varepsilon)) ds,$$

so that

$$(2.25) \quad w^\varepsilon = H^\varepsilon(u^\varepsilon) \quad \text{a.e. in } Q.$$

We choose $S'(r) = h_p(r)T_n(H^\varepsilon(r) - r^-)$ in (2.16) and we obtain as above, and using (2.25)

$$(2.26) \quad \int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot DT_n(w^\varepsilon - (u^\varepsilon)^-) dx dt \leq n[\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}].$$

In (2.26) we have used the fact that $T_n(H^\varepsilon(r) - r^-)$ has a derivative with compact support (see (1.24)). Proceeding now exactly as in the elliptic case (see (1.35), (1.37) and (1.38)), we deduce that from (2.26)

$$(2.27) \quad \lim_{n \rightarrow +\infty} \sup_\varepsilon \{(t, x) \in Q; |w^\varepsilon - (u^\varepsilon)^-| > n\} = 0$$

and then

$$(2.28) \quad \lim_{n \rightarrow +\infty} \sup_\varepsilon \{(t, x) \in Q; |v^\varepsilon - (u^\varepsilon)^-| > n\} = 0.$$

This last result permits to obtain the energy condition when $v^\varepsilon - (u^\varepsilon)^-$ is “large” through setting $S'(r) = h_p(r)\theta_n(G^\varepsilon(r) - r^-)$ in (2.16) which indeed gives (see the definition of G^ε in (1.28) and (1.29))

$$(2.29) \quad \frac{1}{n} \int_{\{(t,x); n < |v^\varepsilon - (u^\varepsilon)^-| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) dx dt \\ \leq \int_{\{(t,x); n < |v^\varepsilon - (u^\varepsilon)^-| \}} |f| dx dt + \int_{\Omega} \int_0^{|u_0|} |\theta_n(G^\varepsilon(r) - r^-)| dr dx.$$

As far as the first term of the right hand side of (2.29) is concerned, we use $f \in L^1(Q)$ and (2.28) to obtain

$$\lim_{n \rightarrow +\infty} \sup_{\varepsilon} \int_{\{(t,x); n < |v^\varepsilon - (u^\varepsilon)^-| \}} |f| dx dt = 0.$$

For the second term, we recall that the support of $G^\varepsilon(r)$ and of r^- are disjoint so that

$$\int_{\Omega} \int_0^{|u_0|} |\theta_n(G^\varepsilon(r) - r^-)| dr dx \leq \int_{\Omega} \int_0^{|u_0|} \theta_n(G^\varepsilon(r)) dr dx + \int_{\{u_0 < -n\}} |u_0| dx.$$

Since $u_0 \leq m$ almost everywhere in Ω and $\int_0^{+\infty} \gamma(s) ds < +\infty$ we first have

$$(2.30) \quad \sup_{\varepsilon} \int_{\Omega} \int_0^{|u_0|} \theta_n(G^\varepsilon(r)) dr dx = 0,$$

for $n > \int_0^{+\infty} \gamma(s) ds$, while

$$(2.31) \quad \lim_{n \rightarrow +\infty} \int_{\{u_0 < -n\}} |u_0| dx = 0$$

because $u_0 \in L^1(\Omega)$.

In view of (2.29), (2.30) and (2.31), we conclude that

$$(2.32) \quad \lim_{n \rightarrow +\infty} \sup_{\varepsilon} \frac{1}{n} \int_{\{(t,x); n < |v^\varepsilon - (u^\varepsilon)^-| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) dx dt = 0.$$

Remark that repeating the above argument with $S'(r) = h_p(r)\theta_n(r)$ leads to

$$(2.33) \quad \frac{1}{n} \int_{\{n < |u^\varepsilon| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon dx dt \leq \int_Q f \theta_n(u^\varepsilon) dx dt + \int_{\{|u_0| > n\}} |u_0| dx.$$

To end this subsection, we derive the analog of (1.47) of the elliptic case. To this end, we take $S'(r) = h_p(r)T_k(G^\varepsilon(r))$ in (2.16) and this yields

$$\int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot DT_k(v^\varepsilon) dx dt \leq k [\|f\|_{L^1(Q)} + \|u_0\|_{L^1(\Omega)}].$$

Reproducing the arguments used in (1.44), (1.45), (1.46) of the elliptic case gives for any $k \geq 0$

$$(2.34) \quad \mathbb{1}_{\{|v^\varepsilon - (u^\varepsilon)^-| < k\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \quad \text{is bounded in } (L^2(Q))^N$$

uniformly in ε .

Step 2. Pointwise convergence of u^ε .

Loosely speaking we consider separately the subset $u^\varepsilon < m$ for which we use the equation (2.16) and the subset $u^\varepsilon \geq m$ for which we use estimate (2.23).

Let us first consider in (2.16) a function $S \in W^{2,\infty}(\mathbb{R})$ such that $\text{supp}(S')$ is compact in $(-\infty, m)$. Then due to (2.21), we have

$$S(u^\varepsilon) \text{ is bounded in } L^2(0, T; H_0^1(\Omega)),$$

and

$$\frac{\partial S(u^\varepsilon)}{\partial t} \text{ is bounded in } L^2(0, T; H^{-1}(\Omega)) + L^1(Q),$$

uniformly with respect to ε . With a classical argument relying on an Aubin's type Lemma (see e.g. [16] and [4]) it follows that there exists a subsequence of u^ε , still indexed by ε , such that for any $m > \delta > 0$

$$(2.35) \quad T_{m-\delta}^+(u^\varepsilon) \rightarrow \varphi_\delta \quad \text{a.e. in } Q,$$

$$(2.36) \quad (u^\varepsilon)^- \rightarrow \varphi^- \quad \text{a.e. in } Q,$$

as ε tends to 0, where φ_δ is a nonnegative measurable function defined on Q with $\varphi_\delta \leq m - \delta$ in Q for any δ and φ^- is a non negative measurable function defined on Q .

Now remark that the sequence φ_δ is decreasing with respect to δ so that there exists a positive measurable function φ^+ defined on Q such that $\varphi^+ \leq m$ a.e. in Q and

$$(2.37) \quad \varphi_\delta \rightarrow \varphi^+ \quad \text{a.e. in } Q$$

as δ tends to 0. Moreover, because of (2.35),

$$(2.38) \quad T_{m-\delta}^+(\varphi^+) = \varphi_\delta$$

for any $m > \delta > 0$ so that

$$(2.39) \quad T_{m-\delta}^+(u^\varepsilon) \rightarrow T_{m-\delta}^+(\varphi^+) \quad \text{a.e. in } Q$$

for fixed $m > \delta > 0$ as ε tends to 0. Indeed (2.39) implies that

$$(2.40) \quad (u^\varepsilon)^+ \rightarrow \varphi^+ \quad \text{a.e. in } \{(t, x) \in Q; \varphi^+ < m\}.$$

To prove that the above pointwise convergence also holds true on $\{(t, x) \in Q; \varphi^+ = m\}$, we use now the estimate (2.23), which shows that, extracting another subsequence,

$$(2.41) \quad T_{2m}^+(u^\varepsilon) - T_m^+(u^\varepsilon) \rightarrow 0 \quad \text{strongly in } L^1(Q) \text{ and a.e. in } Q.$$

Then, from (2.39) and (2.41), we deduce that for any $\delta > 0$

$$(2.42) \quad T_{m-\delta}^+(u^\varepsilon) + T_{2m}^+(u^\varepsilon) - T_m^+(u^\varepsilon) \rightarrow T_{m-\delta}^+(\varphi^+) \quad \text{a.e. in } Q$$

as ε tends to 0. Since indeed $|r^+ - (T_{m-\delta}^+(r) + T_{2m}^+(r) - T_m^+(r))| \leq \delta$ for $r \leq 2m$, it follows that, from (2.42)

$$(2.43) \quad (u^\varepsilon)^+ \rightarrow \varphi^+ \quad \text{a.e. in } \{(t, x) \in Q; \varphi^+(t, x) = m\},$$

as ε tends to 0

In view of (2.36), (2.40) and (2.41) we finally conclude that

$$(2.44) \quad u^\varepsilon \rightarrow u \quad \text{a.e. in } Q$$

as ε tends to 0 where the measurable function $u = \varphi^+ - \varphi^-$ is such that

$$(2.45) \quad u \leq m \quad \text{a.e. in } Q.$$

Let us point out that we do not know if the sequence v^ε pointwise converges in Q in the parabolic case (due to the lack of estimate on $\frac{\partial v^\varepsilon}{\partial t}$). But, indeed, in view of (2.44), we have

$$(2.46) \quad v^\varepsilon \rightarrow v = \int_0^{u^+} \gamma(s) ds \quad \text{a.e. in } \{(t, x) \in Q; u(t, x) < m\},$$

as ε goes to 0.

Step 3. Weak convergences of the fields

Upon extracting another subsequence, (2.21) and (2.44) give

$$(2.47) \quad DT_k(u^\varepsilon) \longrightarrow DT_k(u) \quad \text{weakly in } L^2(0, T; H_0^1(\Omega)),$$

as ε tends to 0 and (2.21) also shows that u is finite almost everywhere in Q . Now let us point out that the identification of X_k and ψ_n performed in the elliptic case only use the pointwise convergence of v^ε on the subset $\{u < m\}$ (see the comment below the proof of (1.50)–(1.51)). Then from (2.47) and estimates (2.20) and (2.34), we deduce that for any $k \geq 0$ and any $n > \int_0^m \gamma(s) ds$ (and for a subsequence)

$$(2.48) \quad \mathbf{A}^\varepsilon(t, x, u^\varepsilon)^{1/2} DT_k(u^\varepsilon) \rightarrow \mathbf{1}_{\{u < m\}} \mathbf{A}(t, x, u)^{1/2} DT_k(u) \quad \text{weakly in } (L^2(Q))^N$$

$$(2.49) \quad h_n(v^\varepsilon - (u^\varepsilon)^-) \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \rightarrow \psi_n \quad \text{weakly in } (L^2(Q))^N,$$

as ε tends to 0, where

$$(2.50) \quad \psi_n = h_n(-u^-) \mathbf{A}(t, x, u) Du \quad \text{a.e. in } \{(t, x) \in Q; u(t, x) < m\}.$$

Remark that for any $k \geq 0$

$$(2.51) \quad \mathbf{1}_{\{-k < u < m\}} \mathbf{A}(t, x, u) Du \in (L^2(Q))^N.$$

Step 4. Strong convergence of the energy.

In this step we prove that the convergence in (2.48) is actually strong in $(L^2(Q))^N$. We will use the technique developed by the first author and A. Porretta to deal with Stefan's type problems (see [5]). This method is simpler than the widely used one which relies on a particular time regularization introduced in [11] and adapted to renormalized solutions in [4].

In this subsection ξ denotes a function in $\mathcal{C}_0^\infty([0, T])$ such that $0 \leq \xi \leq 1$.

We first choose $S'(r) = h_n(r)T_k(r)$ and $\varphi = \xi$ in (2.16) to obtain for $k < n$

$$(2.52) \quad \begin{aligned} \int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot DT_k(u^\varepsilon) \xi dx dt &\leq \int_Q f h_n(u^\varepsilon) T_k(u^\varepsilon) \xi dx dt \\ &+ \int_Q \xi_t \int_0^{u^\varepsilon} h_n(s) T_k(s) ds dx dt + \int_\Omega \xi(0) \int_0^{u_0} h_n(s) T_k(s) ds dx \\ &+ \frac{k}{n} \int_{\{n < |u^\varepsilon| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon dx dt. \end{aligned}$$

We pass to the limit sup as ε tends to 0 in (2.52) for fixed n and k . In view of (2.44), this gives

$$\begin{aligned} \limsup_{\varepsilon \rightarrow 0} \int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot DT_k(u^\varepsilon) \xi \, dx \, dt &\leq \int_Q f h_n(u) T_k(u) \xi \, dx \, dt \\ &+ \int_Q \xi_t \int_0^u h_n(s) T_k(s) \, ds \, dx \, dt + \int_\Omega \xi(0) \int_0^{u_0} h_n(s) T_k(s) \, ds \, dx \\ &+ k \limsup_{\varepsilon \rightarrow 0} \frac{1}{n} \int_{\{n < |u^\varepsilon| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon \, dx \, dt. \end{aligned}$$

In view of (2.33) and since u is finite almost everywhere in Q , we have

$$(2.53) \quad \lim_{n \rightarrow +\infty} \limsup_{\varepsilon \rightarrow 0} \frac{1}{n} \int_{\{n < |u^\varepsilon| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon \, dx \, dt = 0.$$

Using the fact that $u \in L^\infty(0, T; L^1(\Omega))$, (2.15) and (2.53), we pass to the limit as n tends to $+\infty$ and we obtain

$$(2.54) \quad \limsup_{\varepsilon \rightarrow 0} \int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot DT_k(u^\varepsilon) \xi \, dx \, dt \leq \int_Q f T_k(u) \xi \, dx \, dt \\ + \int_Q \xi_t \int_0^u T_k(s) \, ds \, dx \, dt + \int_\Omega \xi(0) \int_0^{u_0} T_k(s) \, ds \, dx.$$

Now we use $S'(r) = h_n(G^\varepsilon(r^+) - r^-)$ in (2.16) (G^ε is defined in (1.28)) and this leads to

$$(2.55) \quad -\|\varphi\|_{L^\infty(Q)} \frac{1}{n} \int_{\{n < |v^\varepsilon - (u^\varepsilon)^-| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) \, dx \, dt \\ \leq - \int_Q \varphi_t \int_0^{u^\varepsilon} h_n(G^\varepsilon(s) - s^-) \, ds \, dx \, dt - \int_Q \varphi(0) \int_0^{u_0} h_n(G^\varepsilon(s) - s^-) \, ds \, dx \\ + \int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D\varphi h_n(v^\varepsilon - (u^\varepsilon)^-) \, dx \, dt - \int_Q f h_n(v^\varepsilon - (u^\varepsilon)^-) \varphi \, dx \, dt \\ \leq \|\varphi\|_{L^\infty(Q)} \frac{1}{n} \int_{\{n < |v^\varepsilon - (u^\varepsilon)^-| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) \, dx \, dt.$$

We pass to the limit as ε tends to 0 in (2.55) for fixed n . To this end, first remark that for $n > \int_0^m \gamma(s) \, ds$

$$h_n(G^\varepsilon(s) - s^-) \rightarrow h_n(-s^-) \mathbb{1}_{\{s < 0\}} + h_n(s^+) \mathbb{1}_{\{0 \leq s \leq m\}}$$

as ε tends to 0. As a consequence of (2.44), it follows that

$$(2.56) \quad \int_Q \varphi_t \int_0^{u^\varepsilon} h_n(G^\varepsilon(s) - s^-) \, ds \, dx \, dt \rightarrow \int_Q \varphi_t \left[\int_0^{-u^-} h_n(s) \, ds + T_m^+(u) \right] \, dx \, dt$$

and

$$(2.57) \quad \int_\Omega \varphi(0) \int_0^{u_0} h_n(G^\varepsilon(s) - s^-) \, ds \, dx \rightarrow \int_\Omega \varphi(0) \left[\int_0^{-u_0^-} h_n(s) \, ds + T_m^+(u_0) \right] \, dx.$$

Secondly, with the help of (2.49) and (2.50)

$$(2.58) \quad \int_Q \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D\varphi h_n(v^\varepsilon - (u^\varepsilon)^-) \, dx \, dt \rightarrow \int_Q \psi_n D\varphi \, dx \, dt.$$

At last, remark that in contrast with the elliptic case, we do not know here that the sequence v^ε converges pointwise on the whole set Q . In order to control the term $\int_Q f h_n(v^\varepsilon - (u^\varepsilon)^-) \varphi \, dx \, dt$, we will use (2.28) and the inequalities

$$\begin{aligned}
 (2.59) \quad \int_Q f \varphi \, dx \, dt - \|\varphi\|_{L^\infty(Q)} \int_{\{|v^\varepsilon - (u^\varepsilon)^-| > n\}} |f| \, dx \, dt \\
 \leq \int_Q f h_n(v^\varepsilon - (u^\varepsilon)^-) \varphi \, dx \, dt \\
 \leq \int_Q f \varphi \, dx \, dt + \|\varphi\|_{L^\infty(Q)} \int_{\{|v^\varepsilon - (u^\varepsilon)^-| > n\}} |f| \, dx \, dt.
 \end{aligned}$$

Setting

$$(2.60) \quad \omega_1(n) = \frac{1}{n} \sup_\varepsilon \int_{\{n < |v^\varepsilon - (u^\varepsilon)^-| < 2n\}} \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D(v^\varepsilon - (u^\varepsilon)^-) \, dx \, dt$$

and

$$(2.61) \quad \omega_2(n) = \sup_\varepsilon \int_{\{|v^\varepsilon - (u^\varepsilon)^-| > n\}} |f| \, dx \, dt,$$

and with the help of (2.45), (2.56), (2.57) and (2.58), we pass to the limit in (2.55) as ε tends to 0 and it gives

$$\begin{aligned}
 (2.62) \quad -\|\varphi\|_{L^\infty(Q)}(\omega_1(n) + \omega_2(n)) &\leq - \int_Q \varphi_t \left[\int_0^{-u^-} h_n(s) \, ds + T_m^+(u) \right] \, dx \, dt \\
 &- \int_\Omega \varphi(0) \left[\int_0^{-u_0^-} h_n(s) \, ds + T_m^+(u_0) \right] \, dx + \int_{\{u(t,x) < m\}} h_n(v - u^-) \mathbf{A}(t, x, u) Du \cdot D\varphi \, dx \, dt \\
 &\quad + \int_{\{u(t,x) = m\}} \psi_n D\varphi \, dx \, dt - \int_Q f \varphi \, dx \, dt \\
 &\leq \|\varphi\|_{L^\infty(Q)}(\omega_1(n) + \omega_2(n)).
 \end{aligned}$$

Now we choose for the test function φ the time regularization that is introduced in [5]. Let u_{0j} be a sequence of $C_0^\infty(\Omega)$ which converges strongly to u_0 in $L^1(\Omega)$ and set $u(t) = u_{0j}$ for $t < 0$. We set

$$\varphi = \xi \frac{1}{h} \int_{t-h}^t T_k(u(\tau)) \, d\tau$$

in (2.62). Indeed we have $\varphi \in L^2(0, T; H_0^1(\Omega)) \cap L^\infty(Q)$, $\varphi_t \in L^\infty(Q)$ and $\|\varphi\|_{L^\infty(Q)} \leq k$ (because $0 \leq \xi \leq 1$). It gives (recall that $\xi \in \mathcal{C}_0^\infty([0, T])$)

$$\begin{aligned}
(2.63) \quad & -k(\omega_1(n) + \omega_2(n)) \\
& \leq - \int_Q \frac{\partial}{\partial t} \left(\xi \frac{1}{h} \int_{t-h}^t T_k(u(\tau)) \, d\tau \right) \left[\int_0^{-u^-} h_n(s) \, ds + T_m^+(u) \right] \, dx \, dt \\
& \quad - \int_\Omega \varphi(0) \left[\int_0^{-u_0^-} h_n(s) \, ds + T_m^+(u_0) \right] \, dx \\
& + \int_{\{u(t,x) < m\}} \xi h_n(v - u^-) \mathbf{A}(t, x, u) Du \cdot D \left[\frac{1}{h} \int_{t-h}^t T_k(u(\tau)) \, d\tau \right] \, dx \, dt \\
& \quad + \int_{\{u(t,x) = m\}} \xi \psi_n D \left[\frac{1}{h} \int_{t-h}^t T_k(u(\tau)) \, d\tau \right] \, dx \, dt \\
& \quad - \int_Q f \xi \frac{1}{h} \int_{t-h}^t T_k(u(\tau)) \, d\tau \, dx \, dt \leq k(\omega_1(n) + \omega_2(n)).
\end{aligned}$$

In order to deal with the parabolic contribution in (2.62), we now apply Lemma 2.3 (p. 388) of [5] with $w = u$, $B(r) = \int_0^{-r^-} h_n(s) \, ds + T_m^+(r)$, $\beta = B(u)$, $\beta_0 = B(u_0)$, $w_0 = u_{0j}$ and $F(\lambda) = T_k(\lambda)$. It gives

$$\begin{aligned}
(2.64) \quad & - \int_Q \frac{\partial}{\partial t} \left(\xi \frac{1}{h} \int_{t-h}^t T_k(u(\tau)) \, d\tau \right) \left[\int_0^{-u^-} h_n(s) \, ds + T_m^+(u) \right] \, dx \, dt \\
& \quad - \int_\Omega \varphi(0) \left[\int_0^{-u_0^-} h_n(s) \, ds + T_m^+(u_0) \right] \, dx \\
& \leq - \int_Q \xi_t \left[\left(\int_0^{-u^-} h_n(s) \, ds + T_m^+(u) \right) \frac{1}{h} \int_{t-h}^t T_k(u(\tau)) \, d\tau \right. \\
& \quad \left. - \frac{1}{h} \int_{t-h}^t \left(\int_0^{u(\tau)} T_k'(r) \left(\int_0^{-r^-} h_n(s) \, ds + T_m^+(r) \right) \, dr \, d\tau \right) \right] \, dx \, dt \\
& - \int_\Omega \xi(0) \left[\left(\int_0^{-u_0^-} h_n(s) \, ds + T_m^+(u_0) \right) T_k(u_{0j}) - \int_0^{u_{0j}} T_k'(r) \left(\int_0^{-r^-} h_n(s) \, ds + T_m^+(r) \right) \, dr \right] \, dx.
\end{aligned}$$

Remark that, since $\text{supp}(T'_k) \subset [-k, k]$, for n large enough $\int_0^r T'_k(s) \int_0^{-r^-} h_n(s) ds = - \int_0^r T'_k(s) s^- ds$. Then letting h tend to 0 in (2.64) leads to

$$\begin{aligned}
 (2.65) \quad & \limsup_{h \rightarrow 0} \left(- \int_Q \frac{\partial}{\partial t} \left(\xi \frac{1}{h} \int_{t-h}^t T_k(u(\tau)) d\tau \right) \left[\int_0^{-u^-} h_n(s) ds + T_m^+(u) \right] dx dt \right. \\
 & \quad \left. - \int_\Omega \varphi(0) \left[\int_0^{-u_0^-} h_n(s) ds + T_m^+(u_0) \right] dx \right) \\
 & \leq - \int_Q \xi_t \left[\left(\int_0^{-u^-} h_n(s) ds + T_m^+(u) \right) T_k(u) - \int_0^u T'_k(r) (-r^- + T_m^+(r)) dr \right] dx dt \\
 & \quad - \int_\Omega \xi(0) \left[\left(\int_0^{u_0^-} h_n(s) ds + T_m^+(u_0) \right) T_k(u_{0j}) - \int_0^{u_{0j}} T'_k(r) (-r^- + T_m^+(r)) dr \right] dx.
 \end{aligned}$$

Now to pass to the limit in (2.63) as h tends to 0 and j tend to $+\infty$, we use the fact that

$$\frac{1}{h} \int_{t-h}^h T_k(u(\tau)) d\tau \longrightarrow T_k(u) \quad \text{strongly in } L^2(0, T; H_0^1(\Omega))$$

and the inequality (2.65), it yields

$$\begin{aligned}
 (2.66) \quad & -k(\omega_1(n) + \omega_2(n)) \\
 & \leq - \int_Q \xi_t \left[\left(\int_0^{-u^-} h_n(s) ds + T_m^+(u) \right) T_k(u) - \int_0^u T'_k(r) (-r^- + T_m^+(r)) dr \right] dx dt \\
 & \quad - \int_\Omega \xi(0) \left[\left(\int_0^{u_0^-} h_n(s) ds + T_m^+(u_0) \right) T_k(u_0) - \int_0^{u_0} T'_k(r) (-r^- + T_m^+(r)) dr \right] dx \\
 & \quad + \int_{\{u(t,x) < m\}} \xi h_n(v - u^-) \mathbf{A}(t, x, u) Du \cdot DT_k(u) dx dt \\
 & \quad + \int_{\{u(t,x) = m\}} \xi \psi_n \cdot DT_k(u) dx dt - \int_Q f \xi T_k(u) dx dt.
 \end{aligned}$$

Remark that $\psi_n \mathbb{1}_{\{u=m\}} DT_k(u) = 0$ almost everywhere in Q so that the forth term in the right hand side of (2.66) is equal to 0. In order to pass to the limit in (2.66) as n tends to $+\infty$, we first recall (2.28) and (2.32) so that $\omega_1(n) \rightarrow 0$ and $\omega_2(n) \rightarrow 0$ as n tends to infinity (because $f \in L^1(Q)$). Secondly we use $h_n(r) \rightarrow 1$ for any r and thirdly the fact that on the subset $\{u(t, x) < m\}$, one has $0 \leq v = \int_0^{u^+} \gamma(s) ds < \int_0^m \gamma(s) ds$ so that $h_n(v - u^-) = h_n(-u^-)$ as soon as $n > \int_0^m \gamma(s) ds$. Then we obtain

$$\begin{aligned}
 (2.67) \quad & 0 \leq - \int_Q \xi_t \left[(-u^- + T_m^+(u)) T_k(u) - \int_0^u T'_k(r) (-r^- + T_m^+(r)) dr \right] dx dt \\
 & \quad - \int_\Omega \xi(0) \left[(-u_0^- + T_m^+(u_0)) T_k(u_0) - \int_0^{u_0} T'_k(r) (-r^- + T_m^+(r)) dr \right] dx \\
 & \quad + \int_{\{u(t,x) < m\}} \xi \mathbf{A}(t, x, u) Du \cdot DT_k(u) dx dt - \int_Q f \xi T_k(u) dx dt.
 \end{aligned}$$

Now since $u \leq m$ almost everywhere in Q , we have

$$(2.68) \quad \begin{aligned} & (-u^- + T_m^+(u))T_k(u) - \int_0^u T_k'(r)(-r^- + T_m^+(r)) \, dr \\ & \qquad \qquad \qquad = uT_k(u) - \int_0^u T_k'(r)r \, dr = \int_0^u T_k(r) \, dr \end{aligned}$$

almost everywhere in Q , and the same relation holds true with u_0 in place of u since $u_0 \leq m$ also. Inserting (2.68) in (2.67) and comparing the obtained result with (2.54) yield for any $k \geq 0$

$$(2.69) \quad \begin{aligned} \limsup_{\varepsilon \rightarrow 0} \int_Q \xi \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot DT_k(u^\varepsilon) \, dx \, dt \\ \leq \int_Q \xi \mathbb{1}_{\{u < m\}} \mathbf{A}(t, x, u) Du \cdot DT_k(u) \, dx \, dt. \end{aligned}$$

Then, in view of (2.48), we conclude that for any $k \geq 0$ any $0 < \tau < T$

$$(2.70) \quad (\mathbf{A}^\varepsilon(t, x, u^\varepsilon))^{1/2} DT_k(u^\varepsilon) \longrightarrow \mathbb{1}_{\{u < m\}} (\mathbf{A}(t, x, u))^{1/2} DT_k(u) \quad \text{strongly in } (L^2((0, \tau) \times \Omega))^N,$$

as ε tends to 0.

Indeed we can deduce from (2.70) (as in the elliptic case) that for any $k \geq 0$

$$(2.71) \quad T_k(u^\varepsilon) \longrightarrow T_k(u) \quad \text{strongly in } L^2((0, \tau); H_0^1(\Omega))$$

as ε tends to 0.

Step 5. End of the proof.

Let us point out that we can not end the proof as in the elliptic case from (2.62), essentially because the function u is not smooth enough with respect to t to allow the choices $\varphi h(u)$ or $\varphi(1 - b_{1/p}(u^+))$ as test functions in (2.62) which have to be in $W^{1,\infty}(Q)$. This is exactly the reason why the energy condition (2.10) is weaker than in the elliptic case.

We first prove that (2.11) holds true. To this end, consider a function $S \in \mathcal{C}^\infty(\mathbb{R})$ such that S' has a compact support in $(-\infty, m)$ and denote by k and k' two positive real numbers such that $k' < m$ and $\text{supp}(S') \subset (-k, k')$. For any $\varphi \in \mathcal{C}_0^\infty([0, T] \times \bar{\Omega})$ such that $S'(0)\varphi = 0$ on $(0, T) \times \partial\Omega$, by (2.16), the function u^ε satisfies

$$(2.72) \quad \begin{aligned} & - \int_0^T \int_\Omega \varphi_t S(u^\varepsilon) \, dx \, dt - \int_\Omega \varphi(0) S(u_0) \, dx \\ & \qquad \qquad \qquad + \int_0^T \int_\Omega S''(u^\varepsilon) \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon \varphi \, dx \, dt \\ & \qquad \qquad \qquad + \int_0^T \int_\Omega S'(u^\varepsilon) \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot D\varphi \, dx \, dt = \int_0^T \int_\Omega f S'(u^\varepsilon) \varphi \, dx \, dt. \end{aligned}$$

We pass to the limit as ε tends to 0 in (2.72). Since $\text{supp}(S') \subset (-k, k')$, u^ε can be replaced by $T_L(u^\varepsilon)$ with $L = \max(k, k')$ in the second and third terms of (2.72). Then, due to (2.44) and (2.70),

$$S''(u^\varepsilon) \mathbf{A}^\varepsilon(t, x, u^\varepsilon) DT_L(u^\varepsilon) \cdot DT_L(u^\varepsilon) \longrightarrow S''(u) \mathbf{A}(t, x, u) DT_L(u) \cdot DT_L(u)$$

strongly in $L^1((0, \tau) \times \Omega)$ as ε tends to 0, for any $\tau < T$ such that $\varphi(t) \equiv 0$ for $t \geq \tau$. Now since $k' < m$,

$$S'(u^\varepsilon) \mathbf{A}^\varepsilon(t, x, u^\varepsilon) DT_L(u^\varepsilon) \longrightarrow S'(u) \mathbf{A}(t, x, u) DT_L(u)$$

weakly in $(L^2(Q))^N$ as ε tends to 0, because of (2.44) and (2.71). At least, $S(u^\varepsilon)$ strongly converges to $S(u)$ in $L^1(Q)$ and $S'(u^\varepsilon)$ converges to $S'(u)$ weakly-* in $L^\infty(Q)$, as ε tends to 0. This shows that (2.11) is satisfied for any function S as above. Now, using the fact that $\mathbb{1}_{\{-k < u < m\}} \mathbf{A}(t, x, u) Du \in (L^2(Q))^N$ (see (2.51)), a standard approximation process of the function S implies that (2.11) still holds true for any $S \in W^{2,\infty}(\mathbb{R})$ such that S' has a compact support and with $S'(r) = 0$, $r \geq m$, or equivalently with $S'(m) = 0$ since $u \leq m$ almost everywhere in Q (see the comments on definition 2.1). It remains to prove (2.9) and (2.10). Upon recalling (2.70), the proof of (2.9) is classical in view of the estimate (2.53) (remark that $(\mathbf{A}^\varepsilon(t, x, u^\varepsilon))^{1/2} DT_{2n}(u^\varepsilon) \rightarrow \mathbb{1}_{\{u < m\}} (\mathbf{A}(t, x, u))^{1/2} DT_{2n}(u)$ weakly in $(L^2(Q))^N$ as ε tends to 0). To establish (2.10), we proceed as in Step 2 of this subsection and choose $S'(r) = h_p(r)(1 - b_{1/n}(r^+))$ (for p, n integers ≥ 1) in (2.16). Passing first in the limit as p tends to $+\infty$ as usual, we obtain for any $\varphi \in \mathcal{C}_0^\infty([0, T])$ (remark that $S'(0) = 0$ so that φ can be independent of x in (2.16)),

$$(2.73) \quad - \int_Q \varphi_t \int_0^{u^\varepsilon} (1 - b_{1/n}(s^+)) ds \\ + n \int_{\{m-2/n < u^\varepsilon < m-1/n\}} \varphi \mathbf{A}^\varepsilon(t, x, u^\varepsilon) Du^\varepsilon \cdot Du^\varepsilon dx dt \\ = \int_Q f(1 - b_{1/n}((u^\varepsilon)^+)) \varphi dx dt + \int_\Omega \varphi(0) \int_0^{u_0} (1 - b_{1/n}(s^+)) ds dx.$$

In view of (2.44) and (2.70), we pass to the limit as ε tends to 0 in (2.73) to obtain

$$(2.74) \quad - \int_Q \varphi_t \int_0^u (1 - b_{1/n}(s^+)) ds + n \int_{\{m-2/n < u < m-1/n\}} \varphi \mathbf{A}(t, x, u) Du \cdot Du dx dt \\ = \int_Q f(1 - b_{1/n}(u^+)) \varphi dx dt + \int_\Omega \varphi(0) \int_0^{u_0} (1 - b_{1/n}(s^+)) ds dx.$$

To pass to the limit as n tends to $+\infty$ in (2.74), we just remark that since $u \leq m$ almost everywhere in Q and $u_0 \leq m$ in Ω ,

$$\int_0^u (1 - b_{1/n}(s^+)) ds \longrightarrow 0 \quad \text{strongly in } L^1(Q), \\ \int_0^{u_0} (1 - b_{1/n}(s^+)) ds \longrightarrow 0 \quad \text{strongly in } L^1(\Omega), \\ (1 - b_{1/n}(u^+)) \longrightarrow \mathbb{1}_{\{u=m\}} \quad \text{a.e. in } Q \text{ and weakly-* in } L^\infty(Q)$$

as n tends to $+\infty$.

Then we get from (2.74)

$$\lim_{n \rightarrow +\infty} n \int_{\{m-2/n < u < m-1/n\}} \varphi \mathbf{A}(t, x, u) Du \cdot Du dx dt = \int_Q f \mathbb{1}_{\{u=m\}} \varphi dx dt,$$

for any function $\varphi \in \mathcal{C}_0^\infty([0, T])$ and (2.10) is established.

The proof of Theorem 2.3 is now complete. \square

2.3. CONCLUDING REMARKS

The above analysis is restricted to the case where $\int_0^m \gamma(s) ds < +\infty$, which indeed implies that $\int_0^m \beta(s) ds < +\infty$. Let us point out that if $\int_0^m \beta(s) ds = +\infty$, then the analysis is simpler because one can construct a solution u of (1.1) or (2.1) (i.e. in the elliptic or parabolic case) such that $u < m$ almost everywhere. Moreover it is not necessary to introduce the specific approximation \mathbf{A}^ε of \mathbf{A} given in (1.16) and the sequences v^ε and w^ε . Indeed, if $\mathbf{A}^\varepsilon(x, s) = \mathbf{A}(x, T_{m-1/\varepsilon}(s^+) - s^-)$, the approximate problems corresponding to (1.18) or (2.12) admit at least a renormalized solution u^ε . Setting $\beta^\varepsilon(r) = \beta(T_{m-1/\varepsilon}(s^+) - s^-)$ and using $T_n(\int_0^{u^\varepsilon} \beta^\varepsilon(s) ds)$ as a test function in these approximate problems gives that, (by the same arguments as in Step 1 of the proof of Theorem 1.4 and Step 2 of the proof of Theorem 2.3)

$$(2.75) \quad \sup_{\varepsilon > 0} \text{meas} \left\{ \int_0^{u^\varepsilon} \beta^\varepsilon(s) ds > n \right\} \rightarrow 0$$

as n tends to $+\infty$.

Now, remark that the proof of the pointwise convergence of u^ε in Part 1 or Part 2 does not use the assumption $\int_0^m \gamma(s) ds < +\infty$. Then, we still have $u^\varepsilon \rightarrow u$ almost everywhere and $u \leq m$. But on the set $\{u = m\}$, $\int_0^{u^\varepsilon} \beta^\varepsilon(s) ds \rightarrow +\infty$ as ε tends to 0, so that in view of (2.75) we obtain $\text{meas}\{u = m\} = 0$. Another difference (with the case $\int_0^m \beta(s) ds < +\infty$) is that when $\int_0^m \beta(s) ds = +\infty$, we cannot expect to have $\mathbb{1}_{\{u < m\}} \mathbf{A}(x, u) Du = \mathbf{A}(x, u) Du$ belongs to $(L^2)^N$ and then equations (1.15) and (2.11) must be written with $\text{supp}(h)$ and $\text{supp}(S')$ compact in $(-\infty, m)$.

Let us conclude this section with a few remarks on a partial uniqueness result of a solution in the sense Definition 1.2. We prove below that if u and v are two solutions of (1.1) such that $\{u = m\} = \{v = m\}$ then $u = v$ (see a similar situation in [3]). We restrict our comments to the elliptic case and for non negative solutions (i.e. for $f \geq 0$) to focus on the use of condition (1.14) on the energy (see e.g. [15] and [2] for a few conditions on $\mathbf{A}(x, s)$ for $s \leq 0$). First if $u \geq 0$ is solution then because of (1.12) the function $\tilde{\beta}(u) = \int_0^u \beta(s) ds$ (defined by $\tilde{\beta}(u) = \int_0^m \beta(s) ds$ on the subset $\{u = m\}$) belongs to $H_0^1(\Omega)$ and $D\tilde{\beta}(u) = \mathbb{1}_{\{u < m\}} \beta(u) Du$ almost everywhere in Ω (consider $\tilde{\beta}(T_{m-\varepsilon}(u)) \in H_0^1(\Omega)$ and let ε tends to 0). Secondly, if we assume that $\beta(s) = \alpha\gamma(s)$ with $\alpha > 0$, the matrix $\tilde{\mathbf{A}}(x, s) = \mathbf{A}(x, s)/\beta(s)$ is uniformly coercive and bounded because of assumptions (1.6). Equation (1.15) can be rewritten as

$$(2.76) \quad -\text{div} [h(u)\tilde{\mathbf{A}}(x, s)D\tilde{\beta}(u)] + h'(u)\mathbf{A}(x, u)Du \cdot Du = h(u)f \quad \text{in } \mathcal{D}'(\Omega).$$

Now let us consider two solutions u and v of (1.1) such that $\{u = m\} = \{v = m\}$. The usual technique to prove that $u = v$ consists in plugging the test function $(b_\delta(u) - b_\delta(v))T_K(\tilde{\beta}(u) - \tilde{\beta}(v))$ in the difference of the equation for u and v written as (2.76) (see (1.9) for the definition of b_δ). Let us point out that since $\{u = m\} = \{v = m\}$ we have $DT_K(\tilde{\beta}(u) - \tilde{\beta}(v)) = 0$ almost everywhere on $\{u = m\}$ and then by condition (1.14)

$$\lim_{n \rightarrow +\infty} n \int_{\{m-2/n < u < m-1/n\}} \mathbf{A}(x, u) Du \cdot Du T_K(\tilde{\beta}(u) - \tilde{\beta}(v)) dx = 0,$$

with a similar equality with v in place of u . It follows that, using $b_\delta(u) \rightarrow \mathbb{1}_{\{u=m\}}$, $b_\delta(v) \rightarrow \mathbb{1}_{\{v=m\}}$ as δ goes to 0 and because $\{u = m\} = \{v = m\}$ that

$$\int_{\Omega} (\tilde{\mathbf{A}}(x, u) D\tilde{\beta}(u) - \tilde{\mathbf{A}}(x, v) D\tilde{\beta}(v)) \cdot DT_K(\tilde{\beta}(u) - \tilde{\beta}(v)) \, dx = 0$$

for any $K > 0$. If we assume that the matrix field $\tilde{\mathbf{A}}(x, s)$ is uniformly Lipschitz continuous with respect to $\tilde{\beta}(s)$ then the standard method of [1] applies and leads to $\tilde{\beta}(u) = \tilde{\beta}(v)$ almost everywhere in Ω . Recalling the assumption $\{u = m\} = \{v = m\}$, it follows that $u = v$ almost everywhere in Ω .

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