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Yield stress in magnetorheological suspensions near the limit of maximum-packing fraction

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Synopsis

This work deals with the magnetic field-induced static yield stress of magnetorheological (MR) suspensions with concentration near the limit of maximum-packing fraction. With this aim, homogeneous suspensions of iron microparticles with 50 vol.% concentration were prepared, and their yield stress measured as a function of the applied magnetic field. In view of the failure of existing models to predict, on the basis of realistic hypotheses, the values of the yield stress of highly concentrated MR suspensions, we developed a new model. Our model considers that field application induces body-centered tetragonal (BCT) structures. Upon shearing, these structures deform in such a way that interparticle gaps appear between neighboring particles of the same chain, whereas the approach of particles of parallel chains ensures the mechanical stability of the whole multi-chain structure. Based on this hypothesis, and using finite element method simulations of interparticle magnetic interactions, our model is able to quantitatively predict the yield stress of highly concentrated MR suspensions. Furthermore, estimations show that the main contribution to the field-dependent part of the

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yield stress comes from the change in the permeability of the structures as interparticle gaps are enlarged by the shear.

I. INTRODUCTION

The maximum packing fraction of particles in suspension is conventionally defined as the volume fraction of particles or particle aggregates in closest-packing at which the suspension viscosity approaches infinity [Zhou et al. (1995)]. For monodisperse hard spheres, the random loose maximum-packing fraction is approximately $0.63 \square 0.64$ [Onoda and Liniger (1990)]. However, porosity and shape of the particles, as well as particle-particle interactions, among other factors, have strong influence on the maximum packing fraction [Zhou et al. (1995)]. For example, flocculated suspensions have a lower maximum-packing fraction due to the fact that the particles are assembled into porous aggregates, whereas suspensions of charged particles do have because of the strong electrostatic repulsion between the particles [Russell et al. (1989)].

Highly concentrated suspensions are of interest in many technical and industrial fields, for example in paints and cosmetics [Clausen et al. (2011)]. However, experimental rheology of highly concentrated suspensions is hampered by the poor reproducibility of measurements and the sensitivity to shear history. From the theoretical viewpoint, approaches based on the interpolation of the dilute-limit theory to a concentrated regime often fail because of the neglect of many-body interactions between particles [Larson (1994)], and taking these interactions into account makes the analytical work intractable [Clausen et al. (2011)]. Thus, realistic theoretical modeling remains an open and difficult issue in many cases.

In the particular case of suspensions of non-Brownian magnetic microparticles, known as magnetorheological (MR) suspensions, maximum packing-fraction is considerably diminished (with respect to the mentioned $0.63 \square 0.64$) because of the formation of particle

aggregates induced by magnetic attraction, due to the remnant magnetization of the particles, and van der Waals forces. As a consequence, there are only a few rheological studies for particle volume concentrations higher than 45% [Chin et al. (2001); de Vicente et al. (2002); Laun et al. (2008a); Laun et al. (2008b)]. Only two of these works [Chin et al. (2001); Laun et al. (2008b)] present data of the yield stress, whereas the others [de Vicente et al. (2002); Laun et al. (2008a)] deal with the normal force. Besides, to the best of our knowledge, the existing theories (critically reviewed in section III.A below) underestimate the mechanical properties of MR suspensions for concentrations near the maximum packing-fraction or give unphysical results. Because of this, we have aimed to develop an appropriate theoretical model for the rheological properties of highly concentrated MR suspensions. In the present paper, we focus our attention on one of the most important MR properties: the static yield stress, which is commonly defined as the threshold stress required to fracture the suspension structure in its weakest point, and thus induce the flow of the suspension [Barnes et al. (1993)]. In order to validate our model, we conducted experimental measurements of the yield stress of a suspension containing 50 vol.% of iron particles. We will see that results of the theoretical model agree quite well with experimental ones within the range of applied magnetic fields, $0 < H_0 < 25$ kA/m.

II. EXPERIMENTAL

Silica-coated iron particles (Fe-CC, density $7.2 \text{ g}\cdot\text{cm}^{-3}$), supplied by BASF (Germany) were used as solid phase for the preparation of the MR suspension. According to the manufacturer, Fe-CC particles have median diameter, $d_{50} = 5 \text{ }\mu\text{m}$. The choice of these particles was motivated by their silica coating, which ease the dispersion of the particles without requiring a surfactant. Mineral oil (density and viscosity at $25 \text{ }^\circ\text{C}$: $0.85 \text{ g}\cdot\text{cm}^{-3}$ and $39.58 \pm 0.16 \text{ mPa}\cdot\text{s}$, respectively) purchased from Sigma Aldrich (Germany) was used as carrier liquid. The MR suspension was prepared as follows. A small amount (approx. 4 g) of Fe-CC powder was

added to a relatively large amount of mineral oil (we took 50 cm³) and the resulting mixture was mechanically stirred until a homogeneous suspension was obtained. Then, a further small amount of Fe-CC powder was added to the suspension and, again, the resulting mixture was homogenized by mechanical stirring. This step was repeated as many times as required until the concentration of Fe-CC powder was so high that it was impossible to homogenize the mixture. At this point, we added approx. 1 cm³ of mineral oil and the homogenization of the mixture was possible by mechanical stirring. By this protocol, we assured that the concentration of particles in the suspension was as close as possible (within reasonable limits) to the maximum-packing fraction. At the end of this process, the volume fraction of particles in suspension was approximately 0.50, as obtained by density measurements. This concentration is relatively far from the 0.63–0.64 maximum-packing fraction reported for monodisperse hard spheres, likely due to the formation of aggregates as a consequence of attractive forces between particles, as discussed in the introduction.

Rheological measurements were performed at 25 °C using a rheometer MCR 300 (Physica-Anton Paar). The measuring geometry consisted of a homemade set of non-magnetic parallel plates of 20 mm in diameter, with rough surfaces in order to avoid wall slip. Visualization experiments on the deformation field of the MR fluid [which will be communicated in future] confirm the absence of the wall slip in our experimental system. The applied magnetic field was generated with the help of a solenoid, placed in such a way that the measuring geometry was at middle height of the coil and with axis coincident with that of the coil. The gap thickness between the lower (stationary) plate and the upper (rotational) plate of the measuring geometry was fixed at 0.35 mm.

As mentioned above, the static yield stress of a suspension is the shear stress required to induce its flow. In our experiments, we determined it by subjecting the samples to shear rate ramps in the range 0.005 – 0.02 s⁻¹ and extrapolating the obtained values of the shear

stress to zero shear rate. To be precise, we used the following experimental protocol. The MR suspension was placed in the measuring system of the rheometer and, immediately afterwards, subjected to a shear rate ramp of 1 min of duration in the range $0 \leq \dot{\gamma} \leq 100 \text{ s}^{-1}$. This pre-shear stage was carried out in the absence of magnetic field. Its aim was to impose identical initial conditions in order to ensure reproducibility of the measurements. Then, a uniform magnetic field of chosen value, ranging between 0 and 25 kA/m, was applied with the help of the solenoid and the suspension was left at rest during 30 s – a sufficient time to induce stable MR structures. Finally, the shear rate ramp was applied under the same magnetic field applied in the previous step. Note that the shear rate ramp consisted of 5 different values of the applied shear rate, each of them maintained during, at least, 30 min. The stress response was measured as a function of time during these periods of time. Once the measurement at a given applied field was accomplished, we repeated the pre-shear stage at zero magnetic field, and remade the same type of measurement at a higher applied field. The whole protocol was performed for three different freshly prepared MR samples. Results shown in this manuscript correspond to the average of these three different measurements. Note also, that we chose such a long duration of each measurement in order to achieve strains as large as $\gamma \sim 10^3$ and ensure a steady-state flow of the MR suspension. This experimental protocol guarantees reproducible results, independent of the previous mechanical history of the suspension.

III. THEORY

A. Theoretical background

Before presenting in details our theoretical model it is worth checking, in an approximate manner, the agreement between the predictions of the existing theories and the experimental results for the static yield stress of highly concentrated suspensions. One of the first models dealing with this property assumed the formation of single chain structures, with

affine displacement of each particle along the direction of the shear, as depicted in Fig. 1a [Bossis et al. (2002); Ginder et al. (1996); Klingenberg and Zukoski (1990)]. This model will be hereinafter referred to as "the affine model". As the particle chains are tilted by the straining motion, the horizontal component of the magnetic attractive force, F_x , acting between particles first increases, then reaches a maximum and finally decreases with the strain. At the strain for which the force is maximum, the chains are considered to become unstable and to break, inducing the flow of the MR suspension. The yield stress is simply calculated as the maximal interparticle force F_x multiplied by the number n_s of chains per unit surface of the upper rheometer plate:

$$\sigma_Y = n_s \cdot F_x. \quad (1)$$

A more general model, based on fundamental thermodynamic relations, considers the shear stress in a sheared suspension as a result of the change in its internal energy:

$$\sigma = \partial U / \partial \gamma, \quad (2)$$

where γ is the strain and U is the suspension internal energy per unit volume (see Fig. 1b) [Bossis et al. (1997); Bossis et al. (2002)]. This model will be called here the "thermodynamic model". The static yield stress is also calculated in this case as the shear stress corresponding to the maximum in the stress versus strain curve. This model can be used whatever the description of the structure and, here, one should distinguish the microscopic description from the macroscopic one. The difference between both descriptions stands in the fact that, in the former the loss of contact between two neighboring particles is taken into account for the estimation of the energy dependency with the strain, contrary to the latter in which only the change of the energy due to the inclination of the aggregates is considered. As a result, both approaches give similar predictions if the interactions between particles are long ranged, as it is the case of dipolar interactions between particles of low magnetic permeability. On the

other hand, predictions are very different if strong short range forces exist, as it happens in the case of particles with high magnetic permeability [Bossis et al. (1997)]. It is worth nothing that the affine model is just a particular case of the microscopic approach of the thermodynamic model, for which both force and energy-based calculations of the stress, Eqs. (1) and (2) respectively, are completely equivalent. In the affine microscopic model, the interparticle forces are directly calculated either analytically [Ginder et al. (1996)] or numerically via multipolar approach [Clercx and Bossis (1993); Klingenberg and Zukoski (1990)] or finite element method [Bossis et al. (2002); Ginder and Davis (1994)]. In the macroscopic approach of the thermodynamic model a mean field theory must be used, usually the Maxwell-Garnet one which does not require assumptions of any specific particle arrangement at the microscopic scale (one should only define the macroscopic features of the structure, i.e. columns, ellipsoids or stripes) and allows obtaining general results [Bossis et al. (1997)]. As a consequence, the microscopic approach ensures a much better correspondence with experiments for MR suspensions composed of particles with high magnetic permeability, while the macroscopic one gives good predictions only for weakly magnetizable particles.

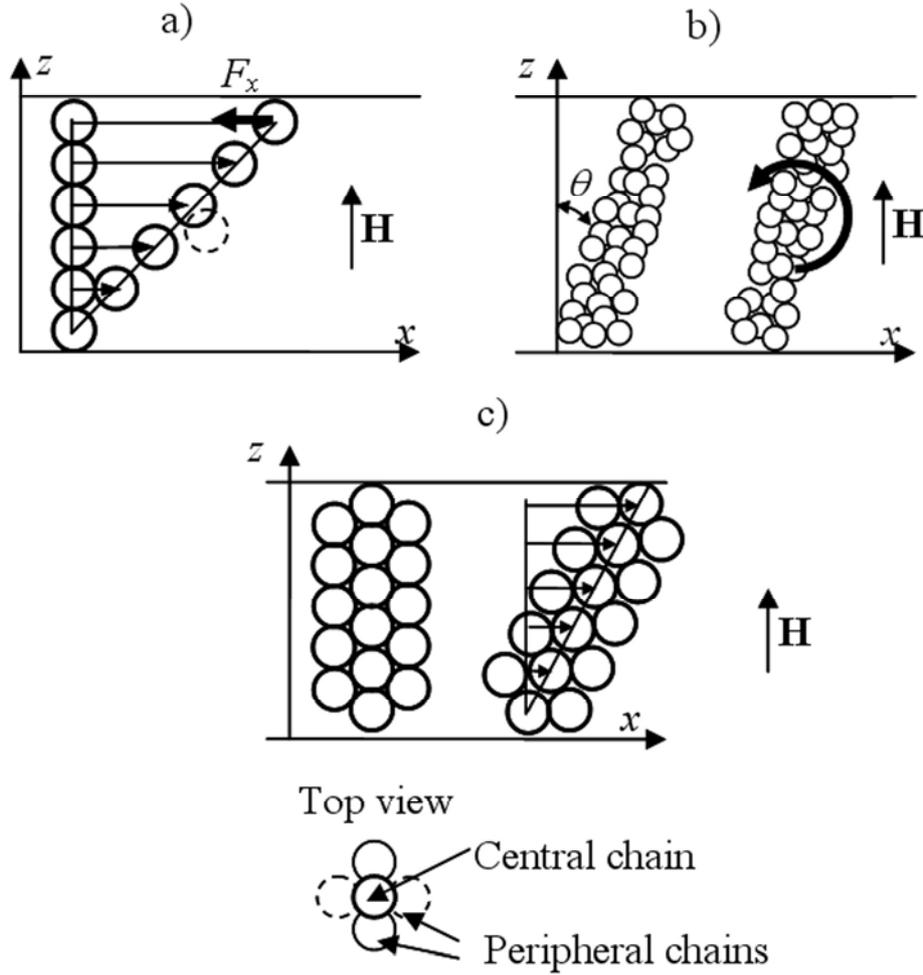


FIG. 1. Different model geometries used for stress calculations in MR fluids. The microscopic affine model [Ginder et al. (1996)] supposes affine displacement of particles with shear (a). Arrows denote displacement vectors of particles. The stress arises from the restoring interparticle force F_x . If a given particle leaves its equilibrium position (dashed sphere in (a)), it will be immediately stacked on top of the closest particle, showing that the structure is mechanically unstable. The macroscopic thermodynamic model [Bossis et al. (1997)] assumes formation of thick columns and ignores arrangement of particles within them (b). The stress comes from the restoring magnetic torque denoted by a bold arrow. A more realistic structure combines the features of both previous ones. Under strain, some particles experience affine motion, creating gaps between them, and the others are drawn into these gaps, maintaining the mechanical contacts with neighboring particles. One of the simplest structures corresponding to this picture is the BCT cluster shown in (c), which is found to be the most favorable for the energetic point of view [Tao and Sun (1992), Clercx and Bossis (1993), Tao and Jiang (1998)]. The stress response of such structure arises from both the longitudinal striction (due to the formation of gaps) and the restoring magnetic torque.

When these two models are applied to the system studied in the present work (suspension of strongly magnetizable particles at 0.50 volume fraction), it is found that the affine microscopic model gives the correct order of magnitude for the yield stress (360 Pa vs. 200 Pa [experimental value- for the yield stress upon application of a field of 18.5 kA/m] □ note that we have used the approach of Ginder et al. (1996) to estimate the interparticle

forces. On the other hand, the macroscopic approach of the thermodynamic model strongly underestimates the yield stress (9 Pa vs. 200 Pa for a magnetic field of 18.5 kA/m). Thus, at a first view, we may be tempted to restrict our analysis to the affine model. However, it is clear that the rupture of chains by keeping an equal gap between neighboring particles as supposed in this model and depicted in Fig. 1a is not realistic [see also comments on the caption of Figure 1. Furthermore, it is well known that in concentrated MR suspensions, thick columnar aggregates or other more isotropic structures are built upon field application, but single chains have never been observed [Cutillas and Bossis (1997)]. Therefore, from a realistic point of view, the thermodynamic model, which is based on general thermodynamic principles and assumes the formation of thick columns, is much more appropriate since it considers the correct size and shape of the aggregates. As already mentioned, the main reason for which the macroscopic model does not fit well to experimental results lies in the use of dipolar approach for interparticle interactions. This approach strongly underestimates the magnetic forces between particles and, as a consequence, gives too low values for the yield stress. In more details, the shear stress predicted by this model is given by the following relation:

$$\sigma = (\mu_{\parallel} - \mu_{\perp})\mu_0 H^2 \frac{\gamma}{(1 + \gamma^2)^2}, \quad (3)$$

with $\mu_0 = 4\pi \cdot 10^{-7}$ H/m being the magnetic permeability of vacuum, H the magnetic field intensity inside the MR suspension, and μ_{\parallel} and μ_{\perp} the diagonal components of the magnetic permeability tensor of the suspension with respect to a frame of reference with main axes in the directions parallel and perpendicular to the column aggregates. These last magnitudes will be called hereinafter longitudinal and transverse permeabilities for brevity. The yield stress is found as the maximum stress of the stress-strain dependency [Eq. (3)-, which is reached at a critical strain, $\gamma_{crit} = 1/\sqrt{3}$. As seen in Eq. (3), the effects of the interparticle interactions in

the suspension stress are taken into account through the values of these magnitudes. The inaccuracy of the dipolar approach can be corrected by including higher-order magnetic interactions in the suspension permeability. However as will be shown by our theory (see section III-B), the main contribution to the yield stress of suspensions of highly magnetizable particles does not come from the value of the permeability, but from the change of the energy with the formation of gaps and, therefore, from the derivative of the permeability with respect to the gap between the particles. Thus, Eq. (3) should include a term containing $\partial\mu_{\parallel}/\partial\gamma$ and $\partial\mu_{\perp}/\partial\gamma$.

The most rigorous way to take into account the interparticle gap effect on the strength of a real structure is to conduct numerical simulations of the structure dynamics under slow shear flow. Bonnecaze and Brady (1992) simulated the structure of electrorheological fluids by the molecular dynamic method using multipolar interactions between particles, and calculated the electrostatic stress with the help of Eq. (2). However, they reported rather strong irregular oscillations of the stress response, as a result of the structure breakage and reformation, and the predicted values of the yield stress were too low.

In contrast to simulations, the microscopic models of Bossis et al. (1997), assuming more realistic multi-chain or zigzag-like clusters, provide a simpler picture of the interparticle gap effect on the suspension yield stress. The authors supposed that small interparticle gaps were formed under shear and calculated the stress via the derivative of the internal energy (Eq. (2)). The theoretical yield stress was found to strongly depend on the strain at which the interparticle gaps were formed. If the particles begin to separate from each other at zero strain (as it is the case of the affine deformation of multi-chain clusters), then the multipolar interactions predict a yield stress $\sigma_Y = 6.5\mu_0 H^2$ for the 50 vol.% MR suspension of the present work, which is an order of magnitude lower than the stress measured in our

experiments. If the particles form zigzag-like clusters, they begin to separate at a non-zero critical strain that corresponds to the full extension of the clusters. This gives a several times increase of the yield stress as compared to affine models. However, at the critical strain, the stress experiences a jump of several orders of magnitude, inconsistent with experimental observations. Therefore, neither affine nor zigzag-like cluster models can be applied, in the form they are reported in literature, to highly concentrated MR suspensions.

In the next subsection we will develop a new model, which will be based on a realistic microscopic structure and will give correct values for the yield stress of MR suspensions in the concentrated regime. For this, we will take into account all the requirements for the particle structure that are drawn from the analysis performed above for previous models: (i) interparticle gaps must appear in the structure in order to obtain realistic values of the yield stress; (ii) the structure must be able to sustain a relatively large extension, in such a way that the critical strain would be high enough to give appropriate values of the yield stress; (iii) the failure of the structure must occur without any considerable jump in the stress. This implies a continuous formation of interparticle gaps during the shear strain of the clusters.

B. Theoretical model

Let us consider a simple shear deformation of a concentrated MR suspension confined between two parallel plates. An external magnetic field of intensity H_0 is applied perpendicularly to the plates. If the field is strong enough, it will induce percolating structures of magnetic particles. We will assume that these consist of body-centered tetragonal (BCT) structures, with four peripheral chains shifted vertically by a particle radius with respect to a central chain, and with neighboring particles being in contact at zero strain. This structure was found to be the most favorable from the energetic point of view [Tao and Sun (1992), Tao and Jiang (1998)]. In addition, it was observed by laser diffraction experiments in

electrorheological fluids □ electric counterparts of magnetorheological suspensions [Chen et al. (1992)]. Applied to our case of a highly concentrated suspension, this structure meets all the requirements mentioned at the end of the previous subsection, if we assume that the central chain deforms in an affine manner with the applied strain and the peripheral chains remain always in contact with the central one (see Fig. 1c). Since in our experiments we used surfaces with high rugosity, the structure is supposed to be always stuck to both plates, wall slip being absent, until its failure at the critical strain. Thus, when the upper plate is displaced a certain distance Δx , the structure is strained by a magnitude $\gamma = \Delta x/h$, where h is the gap between the plates. We suppose that the structure deforms homogeneously until its failure and this assumption does not contradict to the condition of its mechanical stability: in the increasing branch of the stress-vs.-strain curve, any small perturbation of the homogeneous strain field should decay with the time. Under the strain, the particle structure turns along the vorticity axis and extends along its major axis (Fig. 1c), both effects contributing to the shear stress. On the one hand, the extension creates interparticle gaps and, consequently, restoring forces along the main axis of the structure. On the other hand, the structure rotation induces a restoring magnetic torque that tends to turn back the structure and align it with the magnetic field.

In order to calculate the stress response for a given stationary strain, γ , we must first obtain the magnetic permeability tensor of the suspension. Under homogeneous deformation, the main axes of magnetization of the suspension coincide with the axes of the BCT structures. Thus, in a reference frame linked to the particle structures, the magnetic permeability tensor is diagonal and has two dissimilar components: μ_{\parallel} along the major axis of the structures and μ_{\perp} along their minor axis. From these, the magnetic permeability tensor with respect to the laboratory (rheometer) reference frame is obtained by rotation of the

reference frame along the y-axis. The two components, μ_{zz} and μ_{xz} , which have importance in our calculations, are expressed as follows:

$$\mu_{zz} = \mu_{\parallel} \frac{1}{1+\gamma^2} + \mu_{\perp} \frac{\gamma^2}{1+\gamma^2}, \quad (4)$$

$$\mu_{xz} = (\mu_{\parallel} - \mu_{\perp}) \frac{\gamma}{1+\gamma^2}, \quad (5)$$

μ_{\parallel} and μ_{\perp} can be calculated as a function of the interparticle gap δ by solving Maxwell's equations by finite element method simulation. These calculations are reported in details in the Appendix, together with interpolation formulas for the dependencies of μ_{\parallel} and μ_{\perp} with the relative gap, δ/a , with a being the particle radius. The relative gap δ/a is related to the strain by the following formula: $\delta/a = 2\left(\sqrt{1+\gamma^2} - 1\right)$. Thus, the magnetic permeability components can be expressed in terms of the strain γ .

Below the yield point, and under static straining conditions, the MR suspension may be considered as a magnetic, anisotropic elastic solid. For such continuum, the stress tensor is expressed, in its most general form, by the equation given by Landau and Lifshitz (1984):

$$\sigma_{ik} = \tilde{F} \delta_{ik} + \left(\frac{\partial \tilde{F}}{\partial \gamma_{ik}} \right)_{T, \mathbf{H}} + \frac{1}{2} (H_i B_k + H_k B_i), \quad (6)$$

where \mathbf{H} and \mathbf{B} are respectively the magnetic field intensity and the magnetic flux density inside the suspension, γ_{ik} are the components of the strain tensor, δ_{ik} those of the unit tensor, and \tilde{F} is a thermodynamic function defined through the free energy of the suspension per unit volume, F , as follows:

$$\tilde{F} \equiv F - \mathbf{H} \cdot \mathbf{B} = F_0 - \int_0^{\mathbf{H}} \mathbf{B} \cdot d\mathbf{H}, \quad (7)$$

with F_0 being the free energy per unit volume of the suspension in the absence of magnetic field. Note that Shkel and Klingenberg (1999) used similar expressions for electrorheological fluids in the small deformation limit for calculations of the dielectric tensor and the storage modulus. We shall exploit these formulas in a broader range of strains, which will allow us to calculate the yield stress of the suspension.

Magnetic particles used as solid phase in MR suspensions, usually show non-linear magnetization behavior, i.e. their magnetic permeability depends on the applied magnetic field strength. Similarly, the magnetic permeability of MR suspensions also presents a dependency with the applied magnetic field. However, in the relatively narrow range of magnetic field intensities used in our experiments, we may consider, within a good approximation, that the suspension permeability is field-independent. In this case, the magnetic flux density of the suspension presents a linear dependency with the magnetic field strength: $B_i = \mu_0 \mu_{ik} H_k$. By substitution of this into Eq. (7), the expression for the thermodynamic function \tilde{F} reduces to:

$$\tilde{F} = F_0 - \frac{1}{2} \mu_0 \mu_{\parallel} H_{\parallel}^2 - \frac{1}{2} \mu_0 \mu_{\perp} H_{\perp}^2 = F_0 - \frac{1}{2} \mu_0 \mu_{\parallel} H^2 \frac{1}{1+\gamma^2} - \frac{1}{2} \mu_0 \mu_{\perp} H^2 \frac{\gamma^2}{1+\gamma^2}, \quad (8)$$

where $H_{\parallel} = H \cos \theta$ and $H_{\perp} = H \sin \theta$ are the components of the internal magnetic field in the directions parallel and transverse to the BCT structures, respectively; θ is the strain angle (see Fig. 1b), which is related to the strain through the formula $\gamma = \tan \theta$. In the experimental case studied in this work, the internal magnetic field, H , in the thin layer of suspension confined between the two plates of the rheometer is related to the external applied field, H_0 , by the following expression:

$$H = \frac{H_0}{\mu_{zz}} = \frac{H_0}{\mu_{\parallel} + \mu_{\perp}\gamma^2}(1 + \gamma^2). \quad (9)$$

By substitution of Eqs. (5) and (8) into Eq. (6), we obtain the final expression for the shear stress (xz -component of the stress tensor) as a function of the applied strain and the magnetic field strength:

$$\sigma = \mu_0 H^2 (\mu_{\parallel} - \mu_{\perp}) \frac{\gamma}{(1 + \gamma^2)^2} - \frac{1}{2} \mu_0 H^2 \left[\frac{\partial \mu_{\parallel}}{\partial \gamma} \cdot \frac{1}{1 + \gamma^2} + \frac{\partial \mu_{\perp}}{\partial \gamma} \cdot \frac{\gamma^2}{1 + \gamma^2} \right] + \frac{1}{2} \mu_0 H^2 (\mu_{\parallel} - \mu_{\perp}) \frac{\gamma}{1 + \gamma^2}, \quad (10)$$

with the expression for $\partial \mu_{\parallel} / \partial \gamma$ given in the Appendix. The first term in Eq. (10) is the elastic contribution due to the restoring magnetic torque acting on the tilted BCT structures. This term is also connected to the variation of the suspension magnetic permeability with the rotation of the structures. The second term stands for the elastic contribution due to the restoring striction forces that tend to compress the structures extended by the shear. In other words, these forces tend to reduce the interparticle gaps induced by the strain. From the macroscopic point of view, this term is related to the variation of the magnetic permeability with the extension of the aggregates. The last term is the Maxwell stress, which arises from the deformation of the structures under the applied magnetic field. On the other hand, the first and the second terms come from the effect of deformation on the magnetic properties of the structures. Analysis shows that the first and the last terms of Eq. (10) are negligible as compared to the second one. This confirms the extreme importance of the interparticle gaps as a principle source of the stress of MR suspensions upon applied magnetic field.

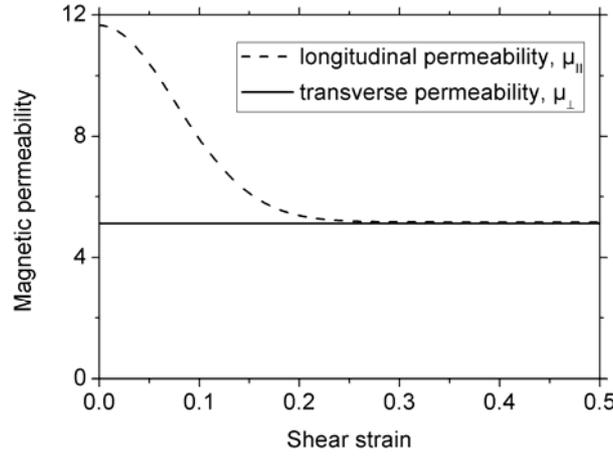


FIG. 2. Longitudinal, $\mu_{||}$, and transverse, μ_{\perp} , components of the magnetic permeability tensor of a suspension consisting of Fe-CC particles dispersed in mineral oil (volume concentration 50 %) as function of the applied shear strain.

IV. RESULTS

The strain dependency of both $\mu_{||}$ and μ_{\perp} is shown in Fig. 2 for the suspension under study in the present work. In the range of the strains, $0 < \gamma < 0.5$, the longitudinal permeability, $\mu_{||}$, shows an important decrease with the strain. This decrease is connected with the appearance and enlargement of gaps between the particles of a same chain when the BCT structures are extended by the shear (see Fig. 1c). The size of these gaps increases proportionally to γ^2 , and this provokes a quite strong variation of $\mu_{||}$. On the other hand, the transverse permeability, μ_{\perp} , appears to be independent of the strain. This can be easily understood since μ_{\perp} depends mainly on the distance between particles of two opposite peripheral chains (dashed circles in the top view of Fig. 1c). The initial separation between these particles is equal to $(\sqrt{3}-1) \cdot (2a) \approx 1.5a$. When the BCT structure is extended, there is an approach of these particles, but at small enough strains it is almost negligible with respect to the initial separation and, thus, it does not affect appreciably the value of μ_{\perp} .

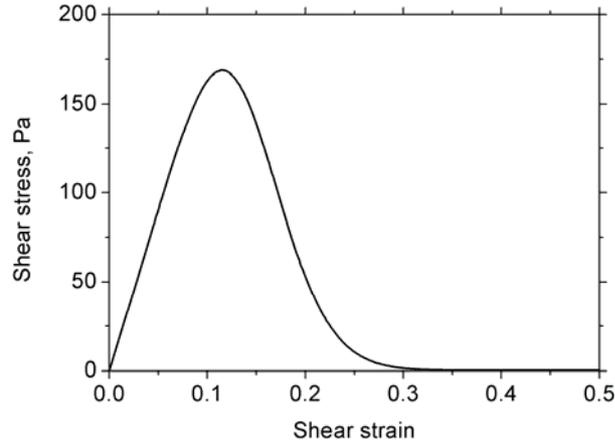


FIG. 3. Theoretical stress-strain curve for a suspension consisting of Fe-CC particles dispersed in mineral oil (volume concentration 50 %). The applied magnetic field is $H_0=18.5$ kA/m.

Fig. 3 shows the stress-strain dependency calculated with the help of Eq. (10) for the MR suspension under study (50 vol.% of Fe-CC in mineral oil) upon application of a field $H_0=18.5$ kA/m. As expected, when the strain increases, the stress first increases, then reaches a maximum, and finally decreases gradually towards nearly zero values at $\gamma > 0.3$. Note that the maximum of the stress takes place at a critical strain, $\gamma_{cr} \approx 0.115$, much lower than that predicted by the macroscopic model of Bossis et al. (1997): $\gamma_{cr} = 1/\sqrt{3} \approx 0.58$. This is not surprising because, in our model, the longitudinal component of the suspension permeability falls with the strain quite rapidly (see Fig. 2), provoking a rapid increase of the stress at low strains. On the other hand, in the macroscopic model of Bossis et al. (1997), the permeability μ_{zz} decreases slowly with the strain, the structure rotation with respect to the applied field being the only cause for the decrease in this model. Nevertheless, the critical strain $\gamma_{cr} \approx 0.115$ predicted for the BCT structure by the present model is two-three times larger than the one calculated for single chains [see Fig. 7 in the work by Bossis et al. (2002)]. Consequently, the critical strain obtained in the present work should be large enough to ensure reasonable predictions of the yield stress. As stated above, structures become unstable at strains $\gamma > \gamma_{cr}$ and are thus supposed to break at the summit of the stress-strain curve. So, the yield stress

corresponds to the maximum of the stress-strain curve and is calculated by replacing the strain γ by the critical strain $\gamma_{cr} \approx 0.115$ in Eq. (10): $\sigma_Y = \sigma(\gamma_{cr})$.

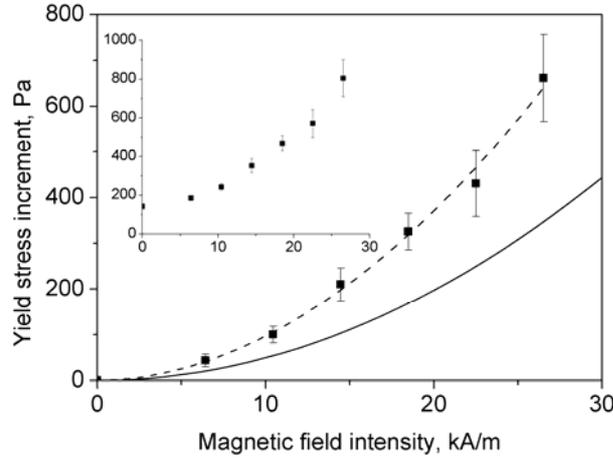


FIG. 4. Experimental and theoretical dependencies of the yield stress increment, $\Delta\sigma(H_0) = \sigma(H_0) - \sigma(0)$, on the magnetic field intensity, H_0 , for a suspension containing 50 vol.% of Fe-CC in mineral oil. The inset shows the field dependency of the yield stress, $\sigma(H_0)$, without subtraction of the value at zero field, $\sigma(0)$. Full squares stand for the experimental data and the solid curve for the theoretical prediction [Eq. (10), replacing γ by $\gamma_{cr} \approx 0.115$]. The dashed line represents the best fit of the experimental data to a power law ($\Delta\sigma(H_0) = H^n$) [the exponent of this best fit is 1.91 ± 0.07].

The values of the static yield stress (both experimental and theoretical) for the MR suspension under study (50 vol.% of Fe-CC in mineral oil) are plotted as a function of the applied field strength in Fig. 4. Since, as observed in the inset of this figure, the MR suspension presents a non-zero experimental value of the yield stress at zero field, the net effect of the magnetic field is better expressed by the difference of the yield stress at a given magnetic field and that in the absence of field: $\Delta\sigma(H_0) = \sigma(H_0) - \sigma(0)$. We refer to this quantity as yield stress increment. The yield stress at zero field is likely due to the remnant magnetization of the iron particles, as well as to non- γ -magnetic colloidal interactions between them, mainly van der Waals forces, which may induce the formation of particle aggregates in the absence of applied field. The importance of these forces in suspensions of magnetic particles has been studied by different authors [see for example [Phulé et al. (1999)].

As seen in Fig. 4, the yield stress increment increases gradually with the magnetic field intensity. The experimental dependence of the yield stress increment is approximately quadratic, as proved by the fact that the best fit to a power law gives an exponent of 1.91 ± 0.07 (dashed line in Fig. 4). The increment of the yield stress with the applied field is commonly explained by the fact that, at higher fields, stronger magnetic forces act between particles and, thus, stronger forces are required to separate them and to break the structures. Concerning the predictions of our theoretical model, as observed in Fig. 4, the theory (without adjustable parameters) still underestimates the experimental data by about 50%. One of the reasons for such a discrepancy could be a polydispersity of the MR suspension. As stated by Kittipoomwong et al. (2005), small magnetic particles may form locally more compact aggregates and cause the larger particles to form more robust aggregates. Such aggregates resist better to the applied strain and give a higher yield stress compared to that of the monodisperse MR fluid at the same volume fraction of particles.

V. CONCLUSIONS

We have presented in this work reliable experimental data of the magnetic field-induced static yield stress of a MR suspension with concentration near the limit of maximum-packing fraction. Both the preparation of the MR suspension and the experimental protocol followed for the measurement of the static yield stress were carefully chosen to guarantee reproducibility of the results. In addition, we have developed a model for the static yield stress of highly concentrated MR suspensions upon magnetic fields. This model is based on the key hypothesis that interparticle gaps inside the field-induced particle structures must appear when they are subjected to shear strain, at the same time that their mechanical stability must be maintained. This perspective supposes an original contribution with respect to standard models based on the affine deformation of single chains, which seems unrealistic for highly concentrated MR suspensions. The key hypothesis taken as starting point in our model is

easily fulfilled by considering a structural unit consisting of five chains of particles located at positions of a BCT structure. When this structure is sheared the particles of the central chain are supposed to move in an affine way, whereas the particles of the peripheral chains remain in contact with those of the central chain ensuring the mechanical stability of the structure. Estimations of our model show that the main contribution to the stress of highly concentrated MR suspensions comes from the change in the magnetic permeability of these, as interparticle gaps are forced and enlarged by the shear stress. Therefore, the neglect of this particular aspect in most of the existing macroscopic models is the likely reason for their failure when applied to highly concentrated suspensions of strongly magnetizable particles. This last statement is supported by the quite good agreement obtained between predictions of our model and experimental results, taking into account that our model does not include any adjustable parameter. The theoretical model developed in this work will be, in the near future, extended to the steady state shear flow of MR suspensions taking into account eventual flow instabilities in highly concentrated regime. Finally, the simple interpolation formulas issued from the present model could be useful for engineering calculations.

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APPENDIX: PERMEABILITY CALCULATIONS

We calculated the longitudinal and transverse magnetic permeabilities of the MR suspension by solving Maxwell's equations by means of finite element method (FEM) simulations. These simulations were performed with the help of the free software FEMM [Meeker (2009)]. For this aim, and although the BCT structures of our model are three-dimensional (3D), we considered a planar problem since 3D-problems cannot be implemented with FEMM software. Nevertheless, we expect that the simplification of the real 3D-problem to a planar-one will not be a restriction for the validity of the results obtained in this appendix.

The representative planar cells used for the calculations of both components of the magnetic permeability tensor, μ_{\parallel} and μ_{\perp} , are shown in Figs. A1 and A2, respectively. The vertical axis of symmetry of the first cell coincides with the major axis of the BCT aggregate. The two closely spaced semi-circles represent particles belonging to the central chain and the two lateral circles represent particles of the peripheral chains. The whole BCT structure is relatively long (aspect ratio $h/(2a\sqrt{3}) \approx 40$) and can be considered as an infinite stack of the unit cells. The horizontal dimension d of the first cell (Fig. A1) is chosen to be equal to the mean distance between BCT structures in their hexagonal arrangement: $d = 2\sqrt{5\pi/(3\sqrt{3}\Phi)} \cdot a \approx 2.46 \cdot (2a)$, where a is the particle radius and $\Phi=0.5$ the volume fraction of particles in the suspension. In this figure, the applied magnetic field is oriented vertically and the intensity H of the internal magnetic field (averaged over the cell volume) is imposed on both lateral borders of the cell. Periodic boundary conditions are used for the upper and the lower borders of the cell.

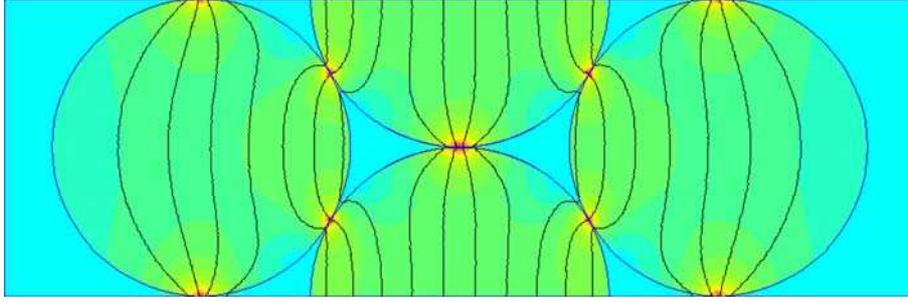


FIG. A1. Elementary cell of the MR suspension used for the calculation of the longitudinal magnetic permeability, μ_{\parallel} . The surface plot of the magnetic flux density and the magnetic field lines are shown. The red spots correspond to the regions of high magnetic flux density in the vicinity of the contact points between spheres.

For the calculation of the transverse magnetic permeability, μ_{\perp} , the external magnetic field must be applied perpendicularly to the BCT structure. However, for the convenience of definition of the boundary conditions, we can still reduce our problem to longitudinal magnetic fields. For this aim, a 90° rotation of the internal structure shown in Fig. A1 is enough. By doing it we obtain the unit cell used for the calculations of μ_{\perp} (Fig. A2). In this figure, the two closely spaced circles represent particles of the central chain and the two semi-circles stand for particles of peripheral chains. In this cell, the external magnetic field is vertical and the boundary conditions are similar to those used for the cell of Fig. A1.

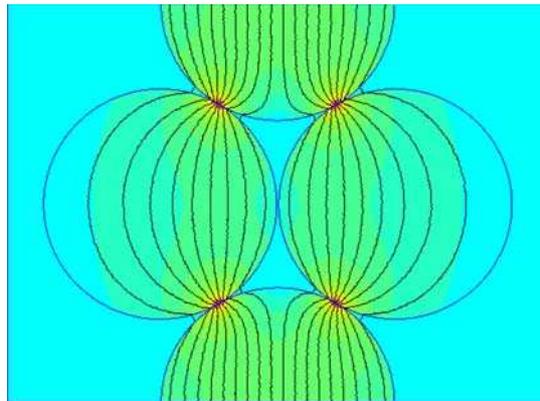


FIG. A2. Elementary cell of the MR suspension used for the calculation of the transverse magnetic permeability, μ_{\perp} . The surface plot of the magnetic flux density and the magnetic field lines are shown.

The non-linear magnetic properties of carbonyl iron particles are well described by the Fröhlich-Kennelly law [Jiles (1991)]:

$$\mu_p = 1 + \frac{(\mu_i - 1)M_S}{M_S + (\mu_i - 1)H_p}, \quad (\text{A.1})$$

where μ_p is the magnetic permeability of the particles, $\mu_i = 250$ and $M_S = 1.36 \cdot 10^6$ A/m are, respectively, the initial permeability and the saturation magnetization of the particles, and H_p is the magnetic field intensity inside the particles.

Once the magnetic field distribution is found for both cells (Figs. A1 and A2), the corresponding permeability component is calculated by the following formula:

$$\mu_{\parallel,\perp} = \frac{1}{\mu_0 H \cdot V} \int B_{\parallel,\perp} dV, \quad (\text{A.2})$$

where H is the intensity of the mean magnetic field inside the MR suspension, imposed on the lateral borders of the cell and related to the external field, H_0 , via Eq. (9). The integration in Eq. (A.2) is performed over the whole cell volume V . Recall that the simulations are performed considering planar geometries, and this means that the circles of Figs. A1 and A2 are taken, from the point of view of the FEM simulation, as infinite cylinders oriented perpendicular to the plane of the page. In order to evaluate the numerical error related to this, we calculated by FEM simulation the longitudinal magnetic permeability of an infinite chain composed of touching spheres, and that of an infinite chain composed of touching cylinders with their axes perpendicular to the applied magnetic field. Simulations showed that the magnetic permeability of the chain of spheres is 3.43 times smaller than that of the chain of cylinders. Consequently, all the results obtained for the multi-chain geometry of Figs. A1 and A2, including those of Eq. (A.2), were reduced by the factor 3.43. This is perhaps a rough approximation but its validity is supported by the fact that it allows obtaining a good

correspondence between theoretical and experimental values of the yield stress, as observed in Fig. 4.

For the calculation of the components of the magnetic permeability tensor of the structure subjected to uniaxial extension under the shear forces, we moved apart the initially touching circles (which represent particles of the central chain) and approached the non-touching ones (which represent particles of opposite peripheral chains), in such a way that there was no fracture of the structures represented in Figs. A1 and A2. By changing the distance between the initially touching circles by steps of $10^{-4} \cdot a$, we obtained the values of μ_{\parallel} and μ_{\perp} as functions of the relative interparticle gap, δ/a . The best nonlinear fits of these functions (taking into account the correction factor 3.43, mentioned above) are given by the following formulas:

$$\mu_{\parallel} = \alpha_1 \exp\left(-\frac{(\delta/a)}{\alpha_2}\right) + \alpha_3 + \alpha_4 \cdot (\delta/a), \quad (\text{A.3})$$

$$\mu_{\perp} \approx \text{const} = 5.118, \quad (\text{A.4})$$

with α_i ($i=1-4$) being numerical constants of values $\alpha_1=6.4925$, $\alpha_2=0.01164$, $\alpha_3=5.1636$ and $\alpha_4=-0.00435$. Replacing the relative gap in Eq. (A.3) by the formula $\delta/a = 2\left(\sqrt{1+\gamma^2} - 1\right)$, we obtain the longitudinal magnetic permeability, as a function of the strain γ . Finally, the derivative of μ_{\parallel} with respect to the strain, which appears in Eq. (10) for the stress, is given by the following expression:

$$\frac{\partial \mu_{\parallel}}{\partial \gamma} = \frac{\partial \mu_{\parallel}}{\partial (\delta/a)} \cdot \frac{\partial (\delta/a)}{\partial \gamma} = \left[-\frac{\alpha_1}{\alpha_2} \exp\left(-\frac{2\left(\sqrt{1+\gamma^2} - 1\right)}{\alpha_2}\right) + \alpha_4 \right] \frac{2\gamma}{\sqrt{1+\gamma^2}}. \quad (\text{A.5})$$

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