

# Failure Prediction of Electrolytic Capacitors During Operation of a Switchmode Power Supply

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**Abstract**—Electrolytic filter capacitors are frequently responsible for static converter breakdowns. To predict these faults, a new method to set a predictive maintenance is presented and tested on two types of converters.

The best indicator of fault of the output filter capacitors is the increase of ESR. The output-voltage ripple  $\Delta V_o$  of the converter increases with respect to ESR. In order to avoid errors due to load variations,  $\Delta V_o$  is filtered at the switching frequency of the converter. The problem is that this filtered component is not only dependent on the aging of the capacitors, but also on the ambient temperature, output current, and input voltage of the converter. Thus, to predict the failure of the capacitors, this component is processed with these parameters and the remaining time before failure is deduced.

Software was developed to establish predictive maintenance of the converter. The method developed is as follows. First, a reference system including all the converter parameters was built for the converter at its sound state, i.e., using sound electrolytic filter capacitors. Then, all these parameters were processed and compared on line to the reference system, thereby, the lifetime of these capacitors was computed.

**Index Terms**—Aging, electrolytic capacitors, maintenance, power supplies.

## NOMENCLATURE

PS1	Half-bridge dc/dc forward-type converter.
PS2	Zero-current-switched secondary resonant half-wave dc/dc forward-type converter.
ESR	Equivalent series resistance of the capacitor.
$L_o$	Output smoothing coil of the converter.
$V_o$	Output voltage.
$\Delta V_o$	Output-voltage ripple.
$\Delta V_{of}$	The component of $\Delta V_o$ at the switching frequency of the converter.
$I_o$	Output current.
$\Delta i$	Output-current ripple.
$V_i$	Input voltage.
$T_a$	Ambient temperature.
$T_c$	Case temperature of the electrolytic filter capacitors.
$T$	Aging temperature.

## I. INTRODUCTION

**I**N VARIOUS electronic equipment, static converters are essential subsystems whose failure leads to the imminent and total stoppage of the equipment.

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Because most of the breakdowns in power supplies are accountable to the electrolytic capacitors, a study of the changes in the electrical waveforms due to the wearing out of these capacitors is necessary to set predictive maintenance of the converter.

With the help of two switchmode power supplies using constant and variable switching frequencies, we start this paper by noting the high probability of failure of electrolytic capacitors with respect to the other components.

We then analyze the influence of frequency, temperature, and service life upon the characteristics of the electrolytic capacitors and show the importance of the equivalent series resistance (ESR) in the fault prediction of the capacitors as well as the output-ripple voltage  $\Delta V_o$ , which depends on ESR [1]–[3].

The first purpose of this study is to show a processing method for output-voltage ripple  $\Delta V_o$  available even if the converter is submitted to a sudden load variation. Reference [4] gives a process that deals with the full wave rectified and cannot avoid large errors with frequent load variations.

By monitoring the component of the output-voltage ripple  $\Delta V_o$  at the switching frequency of the converter (denoted by  $\Delta V_{of}$ ), we improve the processing to avoid such errors.

Then, for the two types of converters, a method to predict the failure of the output capacitors is developed as follows.

To begin with,  $\Delta V_{of}$  is converted into a dc voltage.  $\Delta V_{of}$  is not only dependent on the aging of the capacitors, but also on the output current, input voltage, and ambient temperature. Thus, these latter parameters are also converted into dc voltages to be processed by software with the use of an acquisition board.

Since  $\Delta V_{of}$  is a function of the ESR of the electrolytic filter capacitors,  $\Delta V_{of}$ (ESR) of the converter is determined using sound electrolytic capacitors, with the help of the previous parameters. For aged capacitors, the same function can be used to determine the ESR value knowing the value of  $\Delta V_{of}$ .

This work presents software that is able to estimate the ESR value of the electrolytic filter capacitors of a converter on line and, therefore, the remaining time before failure.

## II. PRESENTATION OF THE CONVERTERS AND THEIR FAILURE CAUSES

Let us consider a half-bridge dc/dc forward-type power supply PS1, as shown in Fig. 1.

The main characteristics of PS1 are as follows.

- The nominal input dc voltage is  $V_{in} = 24$  V.
- The input dc voltage  $V_i$  can vary between  $V_{i \min}$  (18 V) and  $V_{i \max}$  (33 V).

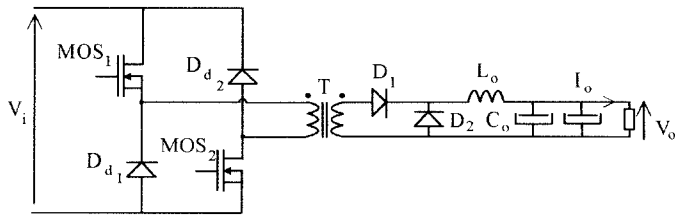


Fig. 1. Diagram of the switchmode power supply PS1.

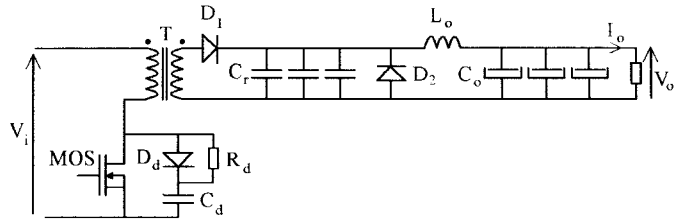


Fig. 2. Diagram of the switchmode power supply PS2.

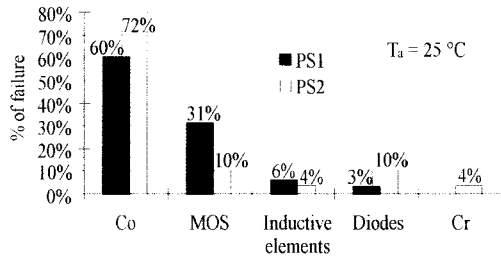


Fig. 3. Distribution of failure for each power component.

- The output dc voltage  $V_o$  is equal to 5 V.
- The nominal output current is  $I_{on} = 8$  A.
- The output current  $I_o$  can vary between zero and  $I_{on}$ .
- The output filter capacitors are aluminum electrolytic capacitors rated: 2200  $\mu$ F, 10 V, and 105°C.
- The switching frequency of this converter is 66 kHz.

Let us also consider the zero-current-switched secondary resonant half-wave dc/dc forward-type power supply PS2 as shown in Fig. 2.

- The nominal input dc voltage is  $V_{in} = 48$  V.
- The input dc voltage  $V_i$  can vary between  $V_{i\ min}$  (36 V) and  $V_{i\ max}$  (60 V).
- The output dc voltage  $V_o$  is equal to 5 V.
- The nominal output current is  $I_{on} = 20$  A.
- The output current  $I_o$  can vary between  $I_{on}/100$  and  $I_{on}$ .
- The output filter capacitors are aluminum electrolytic capacitors rated: 4700  $\mu$ F, 10 V, and 105°C.
- $C_r$  are polypropylene capacitors.
- The switching frequency of this converter varies between 10–100 kHz.

Referring to MIL-HDBK 217 F standard [5], the distribution of failures for each component is represented in Fig. 3 at ambient temperature  $T_a = 25^\circ\text{C}$  and under nominal conditions, for both types of converters. The electrolytic capacitors used to smooth the output voltage have the highest probability of

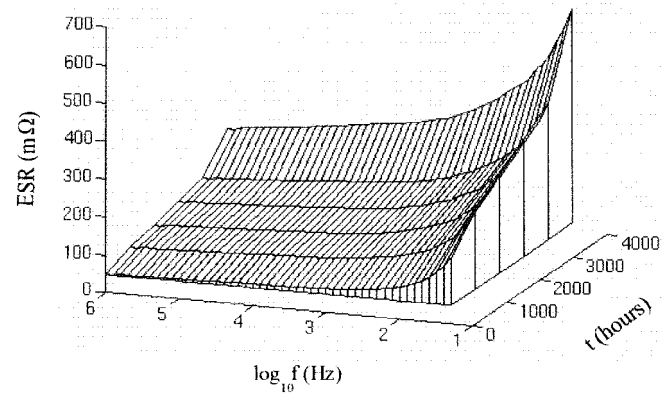


Fig. 4.  $ESR = f(t, f)$  measured at  $T_a = 25^\circ\text{C}$ .

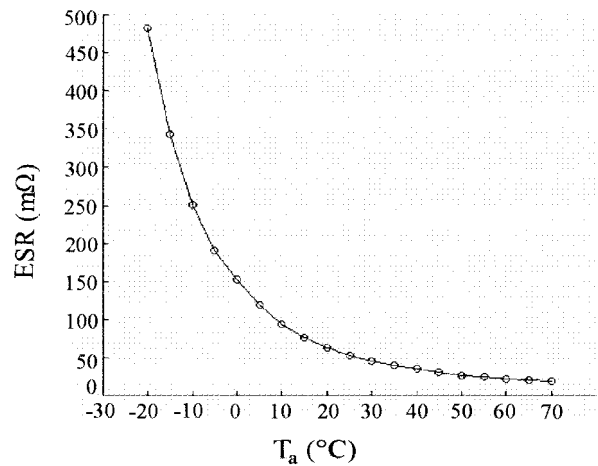


Fig. 5. ESR versus temperature for sound capacitors.

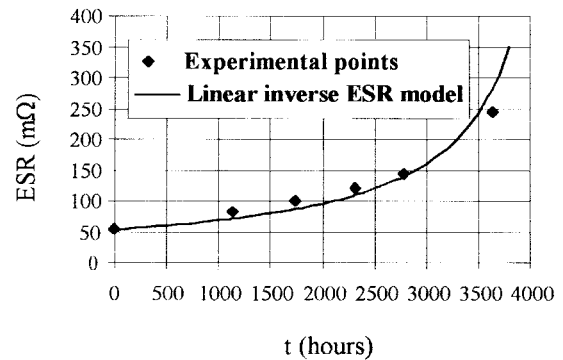


Fig. 6. Aging test of electrolytic capacitors at  $T = 105^\circ\text{C}$  (values measured at  $T_a = 25^\circ\text{C}$  and  $f = 66$  kHz).

failure and are responsible in both cases for more than half of the breakdowns.

### III. INFLUENCE OF THE SERVICE LIFE UPON THE PARAMETERS OF THE CAPACITORS

The wearout of aluminum electrolytic capacitors is due to vaporization of electrolyte that leads to a drift of the main electrical parameters of the capacitor. The equivalent series

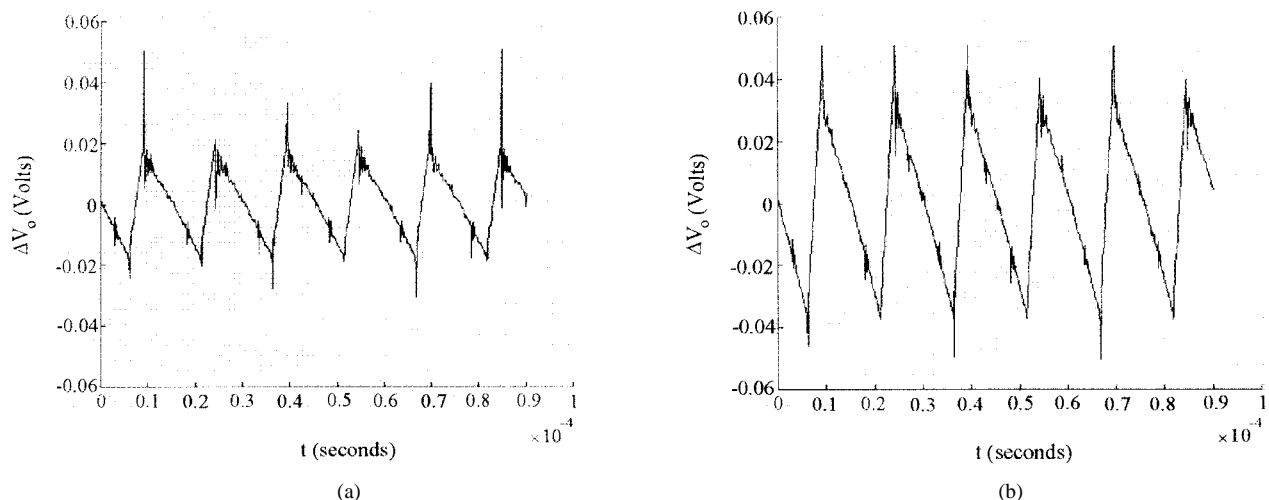


Fig. 7. Influence on  $\Delta V_o$  of a faulty capacitor under nominal conditions ( $V_i = 24$  V and  $I_o = 8$  A). (a) Sound capacitor and (b) aged capacitor.

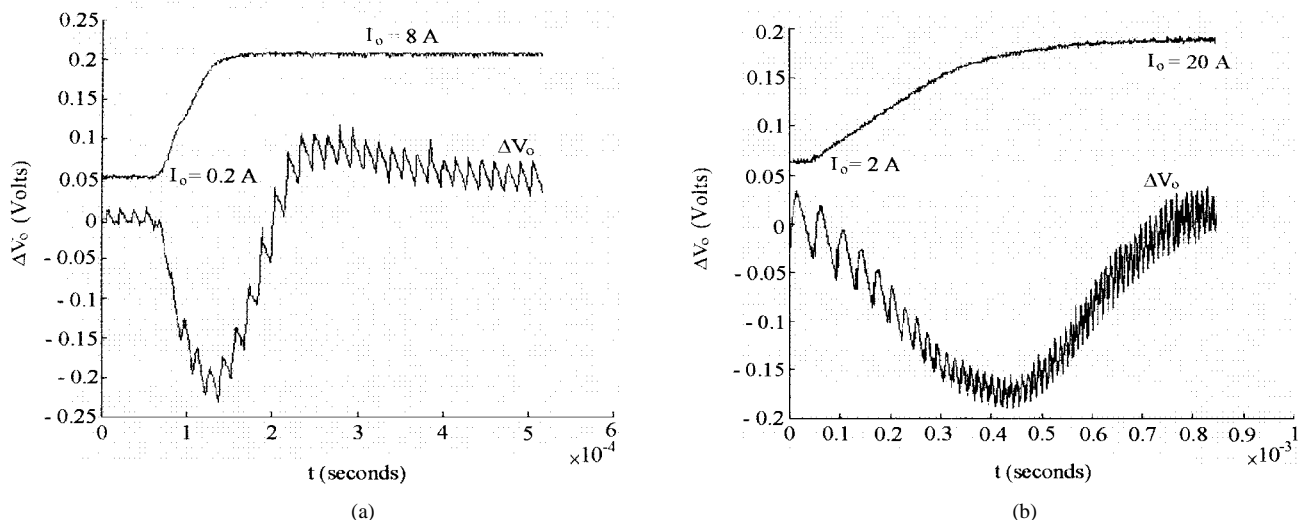


Fig. 8. Influence of a variable load on  $\Delta V_o$  for the two converters. (a) Converter PS1 and (b) converter PS2.

resistance ESR increases, and the capacitance  $C$  decreases [1], [6], [7]. ESR is the sum of the resistance due to aluminum oxide, electrolyte, spacer, and electrodes (foil, tabbing, leads, and ohmic contacts) [8].

The increase of ESR is interesting since at the switching frequency of the converters, the impedance of the electrolytic capacitors is approximately equal to ESR [3]. In addition, this latter evolution is important since it determines the self-heating and, therefore, indirectly, the capacitor lifetime.

To observe this evolution, we applied to 50 capacitors rated 2200  $\mu$ F, 10 V, and 105°C an accelerated thermal aging at 105°C and 10 V.

In Fig. 4, for this aging test, we represent the three-dimensional diagram of the ESR, measured at 25°C in a frequency range of 20 Hz to 1 MHz and for the aging times  $t = 0, 1150, 1750, 2300, 2800,$  and 3650 h.

The ESR is not only dependent on the service life of the capacitor, but at any aging time  $t$ , it is inversely affected by

temperature [6]. Fig. 5 shows the effect of temperature on ESR for sound capacitors (aging time  $t = 0$ ) rated 2200  $\mu$ F, 10 V, and 105°C.

For these kinds of capacitors used to filter the output voltage of the converter PS1, a prediction model of ESR at the switching frequency can be determined versus time  $t$ . As it will be shown further, the determination of this model is necessary to predict the lifetime of the capacitors online.

Fig. 6 shows the experimental values of the ESR measured at 66 kHz and at  $T_a = 25^\circ\text{C}$  and for the aging test at  $T = 105^\circ\text{C}$ .

For any other aging temperature  $T'$ , a prediction model of ESR versus time can be deduced from the experimental model at  $T = 105^\circ\text{C}$ . In fact, the relation between the lifetimes  $t$  and  $t'$ , respectively, at the temperatures  $T$  and  $T'$  (in  $^\circ\text{C}$ ) is given by Arrhenius law

$$\frac{t'}{t} = \exp \left[ E_r \cdot \frac{T - T'}{(T + 273) \cdot (T' + 273)} \right] \quad (1)$$

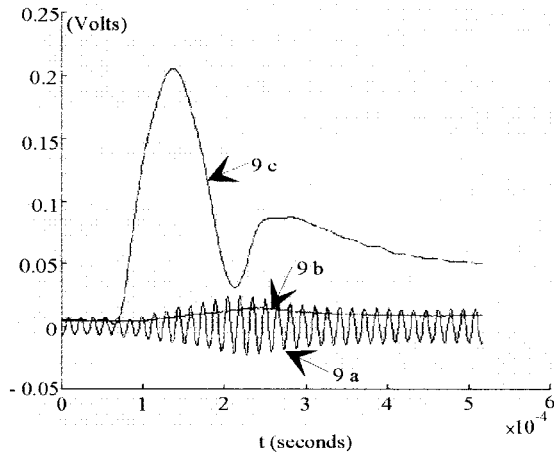


Fig. 9. Processing of  $\Delta V_o$  for PS1. (a)  $\Delta V_o$  filtered at the switching frequency of the converter PS1, i.e., 66 kHz. (b) The average rectified signal of (a). (c) The average rectified signal  $\Delta V_o$  of Fig. 8(a).

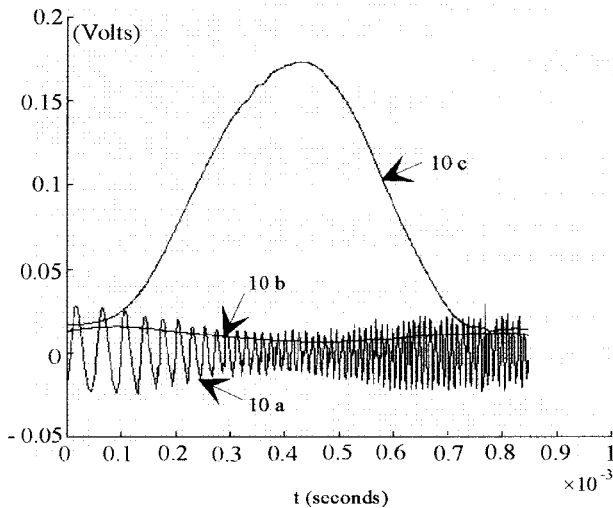


Fig. 10. Processing of  $\Delta V_o$  for PS2. (a)  $\Delta V_o$  filtered at the switching frequency of the converter PS2. (b) The average rectified signal of (a). (c) The average rectified signal  $\Delta V_o$  of Fig. 8(b).

where  $E$  is the activation energy/Boltzmann's constant and equals 4700 [9].

The linear inverse model of (2), illustrated in [6], [9], and [10], can also be considered as a good prediction model

$$\frac{1}{\text{ESR}(t)} = \frac{1}{\text{ESR}(0)} \cdot \left( 1 - k \cdot t \cdot \exp\left(-\frac{4700}{T + 273}\right) \right) \quad (2)$$

where we have the following.

- $\text{ESR}(t)$  is the ESR value at time  $t$ .
- $T$  is the aging temperature in Celsius degrees.
- $t$  is the aging time.
- $\text{ESR}(0)$  is a data representing the ESR value at time  $t = 0$ .
- $k$  is a constant which depends on the design and the construction of the capacitor.

To have an accurate model, we adjust  $k$  by the least-squares method to fit the ESR drift for one type of capacitor.

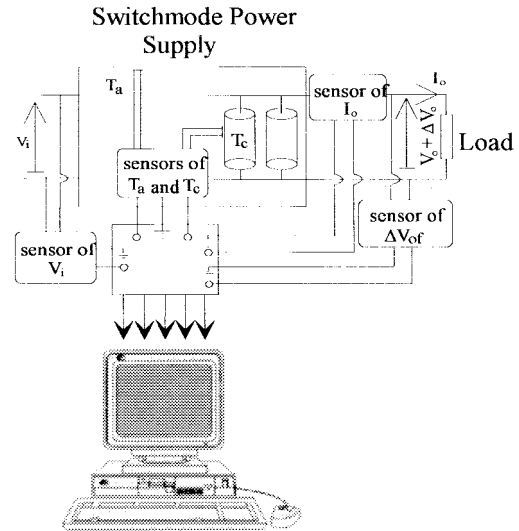


Fig. 11. Sensors and processing system.

We note that in such conditions, the aging temperature  $T$  is equal to the case temperature  $T_c$  of the capacitor which determines actually the wearout of the latter.

Therefore, one of the foretelling signs of failure is the rise in ESR which is more rapid toward the end of the capacitor life.

#### IV. USE OF THE OUTPUT-VOLTAGE RIPPLE TO DETECT THE ELECTROLYTIC CAPACITOR FAULT

The only modified waveform of the converter due to an increase in ESR is the output-voltage ripple  $\Delta V_o$ . In steady-state operations, we represent in Fig. 7 two examples of the waveform  $\Delta V_o$  using sound capacitors and worn-out ones (ESR twice greater, for instance) for the converter PS1.

Since the switching frequency is constant in the steady-state operation of the converter PS2, the evolution of  $\Delta V_o$  is similar. The amplitude of  $\Delta V_o$  is a function of ESR [1], [2].

The main problem then is actually to know which image of the  $\Delta V_o$  signal should be considered as the best one for the fault prediction method.

We suggest the use of the filtered Fourier component at the switching frequency of the converter ( $\Delta V_{of}$ ). Indeed, compared to the average rectified signal of  $\Delta V_o$ , which can be taken in such cases [4], the new method is more realistic [11].

Suppose that PS1 is driven at a switching mode between  $I_o = 2, 5\% I_{on}$  and  $I_o = 100\% I_{on}$  and that PS2 is driven at a switching mode between  $I_o = 10\% I_{on}$  and  $I_o = 100\% I_{on}$ , then the output-voltage ripple  $\Delta V_o$  presents a transient as shown in Fig. 8(a) (converter PS1) and (b) (converter PS2).

Figs. 9 and 10 show the signal filtered by a bandpass filter centered on the switching frequency of the converter [curves 9a for PS1 and 10a for PS2] and its average rectified value [curves 9b for PS1 and 10b for PS2] and the average rectified original signal [curves 9c for PS1 and 10c for PS2].

We notice that a surge value of  $\Delta V_o$  occurs at the moment of the load change that is completely detected by the signals 9c and 10c, but that is much reduced in the signals 9b and 10b.

This means that the prediction system using curves 9c and 10c is subjected to a sudden increase in the image of  $\Delta V_o$ , and

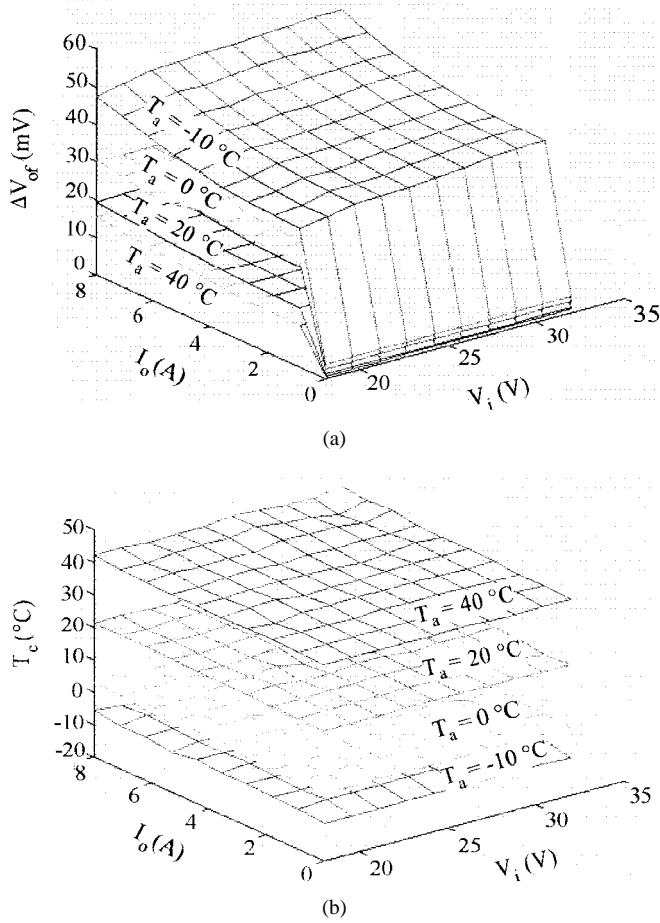


Fig. 12. Diagram of the experimental functions  $\Delta V_{of}$  and  $T_c = f(I_o, V_i, T_a)$  for sound capacitors. (a) Component  $\Delta V_{of}$  of the output voltage at the switching frequency of the converter and (b) case temperature  $T_c$ .

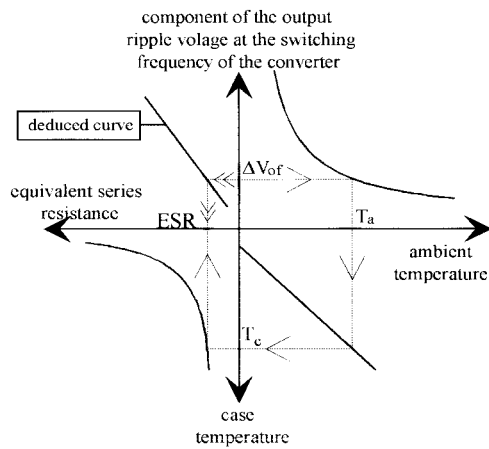


Fig. 13. Computation of  $\Delta V_{of}$  (ESR) for a sound capacitor with the use of  $\Delta V_{of} = f(T_a)$ ,  $T_c = f(T_a)$ , and  $ESR = f(T_c)$ .

then a fault may be signaled improperly at this time, while the curves 9b and 10b show a negligible variation in the image of  $\Delta V_o$  considered.

For the half-bridge dc/dc forward-type power supply PS1 of Fig. 1, which works at constant switching frequency (66 kHz), the measurement of  $\Delta V_{of}$  is obtained by a bandpass

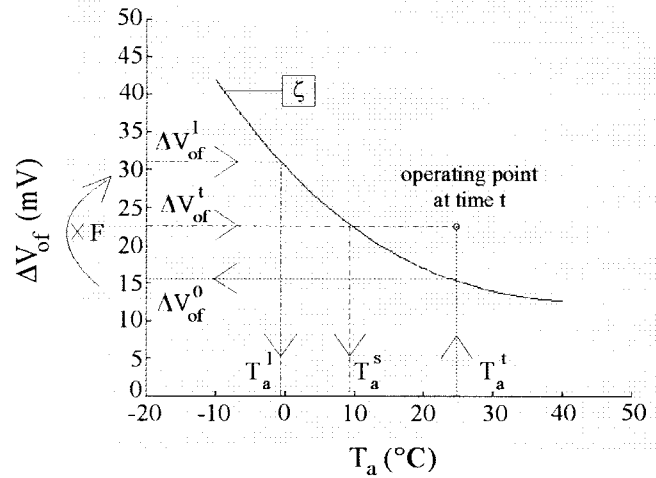


Fig. 14.  $\Delta V_{of} = f(T_a)$  for  $I_o = I_{on}/2 = 4$  A and  $V_i = V_{in} = 24$  V.

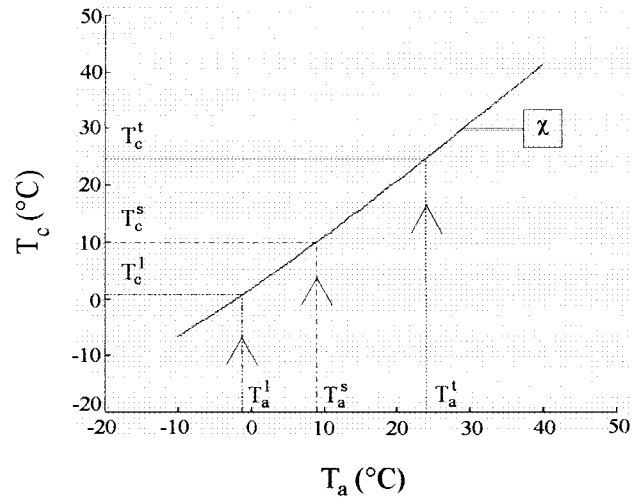


Fig. 15.  $T_c = f(T_a)$  for  $I_o = I_{on}/2 = 4$  A and  $V_i = V_{in} = 24$  V.

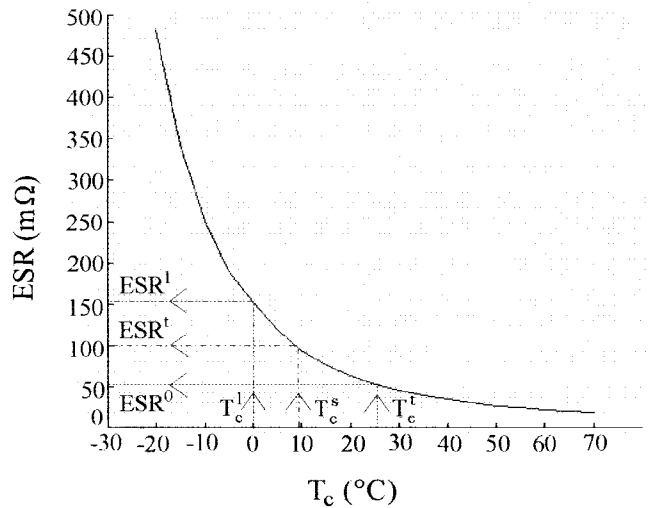


Fig. 16. Determination of the capacitors state using the law  $ESR = f(T_c)$ .

filter centered on 66 kHz and by a stage that rectifies and amplifies the filtered waveform and gives a dc image of  $\Delta V_{of}$  [12].

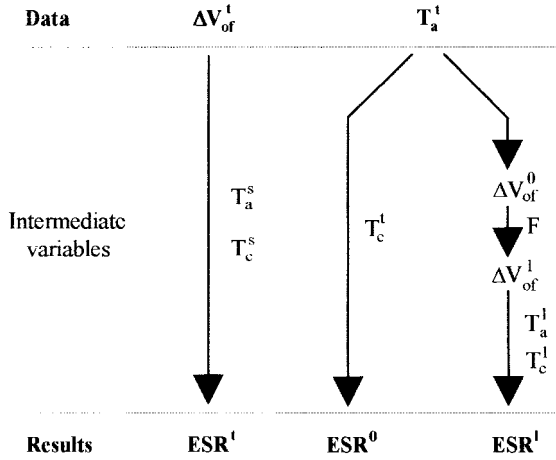


Fig. 17. Computation method of  $ESR^0$ ,  $ESR^t$ , and  $ESR^1$ .

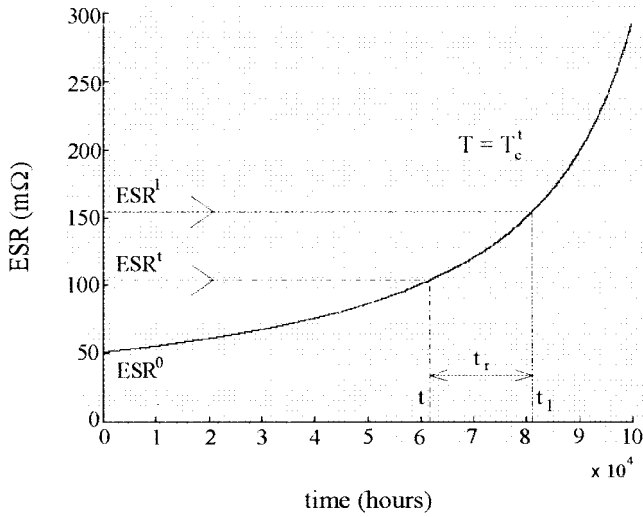


Fig. 18. Computation of the remaining time  $t_r$  before failure using the law  $ESR = f(t, T)$  at  $T = T_c^t$ .

For the zero-current-switched secondary resonant half-wave dc/dc forward-type power supply PS2 of Fig. 2, the frequency of  $\Delta V_{of}$  varies in the same range as the switching frequency, i.e., between 10–100 kHz. The system to be designed must give a faithful image of  $\Delta V_{of}$  in frequency and amplitude without affecting the original signal.

The circuit used is a selective bandpass filter with a center frequency controlled by a voltage [13]. By applying an amplified image of  $\Delta V_o$  to the filter input and setting the center frequency  $f_c$  equal to the switching frequency, we obtain as output the amplified image of  $\Delta V_{of}$  [3].

### V. THE REAL-TIME PREDICTION OF THE ELECTROLYTIC FILTER CAPACITOR FAULT

The failure of the output electrolytic filter capacitor in a static converter is characterized by the increase in the value of ESR due to the converter operation during a time  $t$ , at a temperature  $T$ .

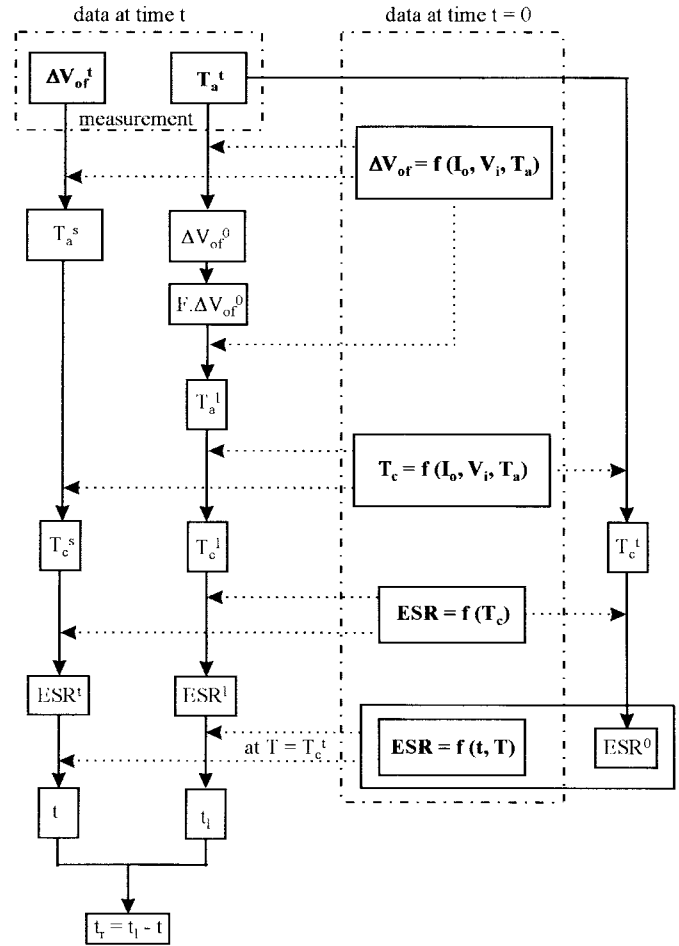


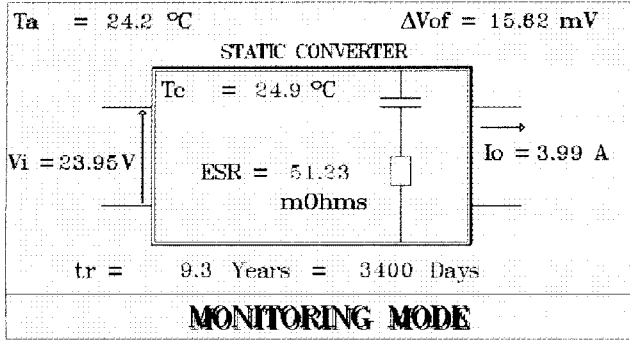
Fig. 19. Block diagram of the software.

To determine the ESR and the time before the failure of the capacitor, we must proceed to a measurement of the case temperature  $T_c$  of the latter as well as the component  $\Delta V_{of}$  of the output-voltage ripple  $\Delta V_o$ . The temperature  $T_c$  takes account of the ambient temperature and the heating produced by the output ripple [7], [14], [15].

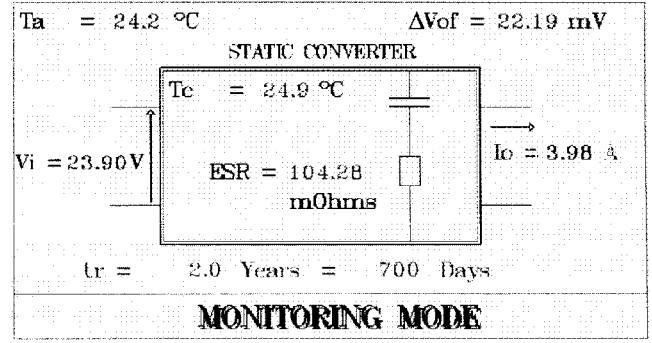
The sensors and the processing system of Fig. 11 are used to convert the parameters of the converter ( $I_o$ ,  $V_i$ ,  $T_a$ ,  $T_c$ ,  $\Delta V_{of}$ ) into dc voltages between 0–10 V. All the dc signals are then processed by software.

Since  $\Delta V_{of}$  and  $T_c$  depend on the output current  $I_o$ , input voltage  $V_i$ , and ambient temperature  $T_a$ , we will obtain at first an experimental acquisition of the functions  $\Delta V_{of} = f(I_o, V_i, T_a)$  and  $T_c = f(I_o, V_i, T_a)$  for a converter using sound electrolytic filter capacitors (time  $t = 0$ ) with the use of the system of Fig. 11. We make then a reference system for  $\Delta V_{of}$  and  $T_c$ .

For a given time  $t \neq 0$  and for a given operating mode ( $I_o$ ,  $V_i$ ,  $T_a$ ), the software reads continuously the measurements of the parameters  $\Delta V_{of}$  as well as  $I_o$ ,  $V_i$ , and  $T_a$ . The case temperature  $T_c$  is not measured directly at the surface of the capacitor, but deduced by the software from the reference system built at  $t = 0$ . This method reduces the number of sensors if many electrolytic capacitors are used or if other electronic components of the converter are monitored.



(a)



(b)

Fig. 20. Results obtained by the software in the case of a converter using sound and worn electrolytic filter capacitors.

The measured  $\Delta V_{of}$  at  $t \neq 0$  is then compared to  $\Delta V_{of}$  at  $t = 0$ . Therefore, the ESR value as well as the remaining time before failure are calculated.

The detailed processing method to predict the failure of capacitors is presented now for the converter PS1, but the same method can be applied to the converter PS2.

#### A. Acquisition of $(\Delta V_{of}, T_c) = f(I_o, V_i, T_a)$ at $t = 0$

The electrolytic filter capacitors of PS1 are identical. They have approximately the same case temperature  $T_c$  and therefore identical worn state versus time and temperature.

To build a reference system of  $T_c$  and  $\Delta V_{of}$ , the software automatically drives PS1 into different operating modes by varying simultaneously step by step:

- $I_o$  from 0 A to  $I_{on}$  (8 A) with the use of a controlled dc electronic load;
- $V_i$  from  $V_{i\ min}$  (18 V) to  $V_{i\ max}$  (33 V) with the use of a controlled dc power supply;
- $T_a$  from  $-10^\circ\text{C}$  to  $+40^\circ\text{C}$ .

So, the built vectors  $I_o$ ,  $V_i$ , and  $T_a$  and matrices  $T_c$  and  $\Delta V_{of}$  are the reference data stored by the software and used later in the real-time monitoring.

In Fig. 12, we represent  $T_c$  and  $\Delta V_{of}$  versus  $I_o$  and  $V_i$  at four different ambient temperatures (40, 20, 0, and  $-10^\circ\text{C}$ ).

We observe an increase in  $\Delta V_{of}$  when the ambient temperature decreases which is due to a rise in the ESR (Fig. 5).

The temperatures  $T_c$  and  $T_a$  are imposed by a climate chamber containing the converter PS1.

#### B. Processing of the Different Signals at Time $t \neq 0$

1) *Method*: To compute the ESR value of an electrolytic filter capacitor, the method applied is as follows.

- 1) At first, the function  $\Delta V_{of} = f(T_a)$ , for given  $I_o$  and  $V_i$  is deduced from the reference system of Fig. 12(a).
- 2) Second, the function  $T_c = f(T_a)$  for the same  $I_o$  and  $V_i$  is deduced from the reference system of Fig. 12(b).
- 3) Finally, knowing the evolution law  $\text{ESR} = f(T_c)$  for a sound capacitor (Fig. 5), we can deduce  $\Delta V_{of}$  versus ESR for a sound capacitor and for  $I_o$  and  $V_i$  as shown in Fig. 13.

We notice that the three functions described previously are constituted of discrete measures. The cubic spline method is used for interpolation.

We notice that  $\Delta V_{of}(\text{ESR})$  is actually almost independent of the ambient temperature  $T_a$ . In fact, the impedance  $Z$  of the capacitor is almost equal to ESR at the switching frequency of PS1 [3]. The current ripple  $\Delta i$  across the capacitor is fixed by the output smoothing coil  $L_o$  of Fig. 1, which is almost independent of  $T_a$  and the output-voltage ripple is given by

$$\Delta V_o = Z \cdot \Delta i \approx \text{ESR} \cdot \Delta i. \quad (3)$$

The variation law of  $\Delta V_{of}$  versus ESR depends only on  $I_o$  and  $V_i$ . It is then determined for a sound capacitor (Fig. 13) and can be used to compute the ESR value of a worn capacitor by knowing only  $I_o$ ,  $V_i$ , and the value of  $\Delta V_{of}$ .

2) *Utilization of  $\Delta V_{of} = f(I_o, V_i, T_a)$* : We suppose that at time  $t \neq 0$ , the converter is driven into the operating mode ( $I_o = I_{on}/2 = 4$  A,  $V_i = V_{in} = 24$  V). The measured values of  $\Delta V_{of}$  and  $T_a$  at that time are  $\Delta V_{of}^t$  and  $T_a^t$ . The curve  $\zeta$  of Fig. 14 is the reference curve of  $\Delta V_{of} = f(T_a)$  deduced by the software from the reference system of Fig. 12(a).

We notice that  $\Delta V_{of}^t$  and  $T_a^t$  does not join the curve  $\zeta$  because the electrolytic filter capacitors are worn.

The program computes on line the next values.

$T_a^s$  Temperature corresponding to the real value  $\Delta V_{of}^t$  on the curve  $\zeta$ .  $T_a^s$  would be the ambient temperature if the capacitors were sound and if  $\Delta V_{of} = \Delta V_{of}^t$ .

$\Delta V_{of}^0$  Output-voltage ripple corresponding to the real measured temperature  $T_a^t$  on the curve  $\zeta$ .  $\Delta V_{of}^0$  would be the value of  $\Delta V_{of}$  if the filter capacitors were sound and if  $T_a = T_a^t$ .

The user of the software must define the limit of the correct running of the converter by entering a factor  $F$  that shows the limit value  $\Delta V_{of}^l$  permitted at the operating mode ( $I_o, V_i, T_a^t$ )

$$\Delta V_{of}^l = F \cdot \Delta V_{of}^0. \quad (4)$$

The limit ambient temperature  $T_a^l$  is then deduced from  $\Delta V_{of}^l$  by the curve  $\xi$ . It would represent the temperature if sound filter capacitors were used and if  $\Delta V_{of} = \Delta V_{of}^l$ .

We remark that if the correct operating limit, defined by the user is large, the  $\Delta V_{of}^l$  value can exceed the limit of the

curve  $\zeta$ , this is why it is better to build the reference system for a wide range of ambient temperatures and mainly for the negative values.

We then compute and store three temperatures  $T_a^t$ ,  $T_a^s$ , and  $T_a^l$ , on line, to be used in the next step.

3) *Utilization of  $T_c = f(I_o, V_i, T_a)$* : The software determines for  $I_o = 4$  A and  $V_i = 24$  V the curve  $\chi$  (Fig. 15) that represents the case temperature  $T_c$  versus the ambient temperature  $T_a$  deduced from the reference system of Fig. 12(b).

From  $T_a^t$ ,  $T_a^s$ , and  $T_a^l$ , the program deduces the values of:

- $T_c^t$  real case temperature at time  $t$ ;
- $T_c^s$  case temperature corresponding to  $T_a^s$  and then to  $\Delta V_{of}^t$  if sound capacitors were used;
- $T_c^l$  limit case temperature corresponding to  $T_a^l$  and  $\Delta V_{of}^l$  if sound capacitors were used.

4) *Utilization of  $ESR = f(T_c)$* : For sound electrolytic capacitors used to filter the output voltage, the variation of ESR versus the case temperature is known (Fig. 5). This function is used to determine on line, the state of the filter capacitors as shown in Fig. 16.

From  $T_c^t$ ,  $T_c^s$ , and  $T_c^l$ , the software calculates:

- $ESR^0$  ESR value of a sound capacitor at ambient temperature  $T_a^t$  and case temperature  $T_c^t$ ;
- $ESR^t$  real ESR value at time  $t$  deduced from  $T_c^s$  as explained in the method of V. B. 1;
- $ESR^l$  limit value of ESR corresponding to the right operating mode of the converter.

To sum up, we represent in Fig. 17 the method used to compute  $ESR^0$ ,  $ESR^t$ , and  $ESR^l$  from the data  $\Delta V_{of}^t$  and  $T_a^t$  at time  $t$ .

5) *Utilization of  $ESR = f(t, T)$* : The converter is working at ambient temperature  $T_a^t$  and the temperature of the filter capacitors case is equal to  $T_c^t$ .

Using the law  $ESR = f(t, T)$  (Fig. 6), where  $T$  is set to  $T_c^t$  and  $ESR(0)$  is equal to  $ESR^0$  calculated in Section V-B-4, the program computes, as shown in Fig. 18, the remaining time before failure if we assume that it will keep the same operating mode until the complete failure of the capacitors.

### C. Synthesis of the Processing Method

The block diagram illustrated by Fig. 19 shows the method used to predict electrolytic capacitors failure.

## VI. RESULTS

The predicted values concerning the failure time of the converter tested, seems to be confirmed by the industrial users.

Fig. 20 shows the results of the monitoring software for sound capacitors ( $ESR = 51$  m $\Omega$ ) and worn capacitors ( $ESR = 104$  m $\Omega$ ). The increase permitted for  $\Delta V_{of}$  is 100% ( $F = 2$ ).

## VII. CONCLUSION

In static converters, the increase in the ESR in the output electrolytic filter capacitors is the best fault signature of the latter.

The output-voltage ripple  $\Delta V_o$  increases with respect to ESR, and this is why it is monitored to predict the failure of the electrolytic capacitors.

As static converters work most of the time at variable load, the best image of the output voltage to predict the failure of electrolytic filter capacitors is the filtered signal at the converter switching frequency. In fact, this signal gives a faithful value of  $\Delta V_o$  either at constant load or at variable load and avoids the sudden increase in transient values of  $\Delta V_o$  that leads to a wrong predicted lifetime of the electrolytic capacitor.

The amplitude of this filtered signal versus ESR is determined for a converter using sound filter capacitors by varying other system parameters such as input voltage, output current, and ambient temperature.

The lifetime of the converter is then continuously predicted by monitoring on line all the converter parameters.

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