



HAL
open science

Running Tree Automata on Trees and/or Dags

Barbara Fila, Siva Anantharaman

► **To cite this version:**

Barbara Fila, Siva Anantharaman. Running Tree Automata on Trees and/or Dags. 2006. hal-00080644v3

HAL Id: hal-00080644

<https://hal.science/hal-00080644v3>

Preprint submitted on 25 Aug 2006

HAL is a multi-disciplinary open access archive for the deposit and dissemination of scientific research documents, whether they are published or not. The documents may come from teaching and research institutions in France or abroad, or from public or private research centers.

L'archive ouverte pluridisciplinaire **HAL**, est destinée au dépôt et à la diffusion de documents scientifiques de niveau recherche, publiés ou non, émanant des établissements d'enseignement et de recherche français ou étrangers, des laboratoires publics ou privés.

Running Tree Automata on Trees and/or Dags

Barbara Fila

LIFO, Université d'Orléans (France), e-mail: fila@univ-orleans.fr

Siva Anantharaman

LIFO, Université d'Orléans (France), e-mail: siva@univ-orleans.fr

Abstract

We define tree/dag automata as extensions of (unranked) tree automata which can run indifferently on trees or dags, in a bottom-up style. The runs of such an automaton A on any tree or dag t are defined by assigning states not only to the nodes of t but also to its edges. Runs are so defined that A accepts t if and only if it accepts the tree \hat{t} obtained by unfolding t , as a tree automaton running \hat{t} , in the usual sense.

Keywords: Automata, Trees, Dags. Determinism.

1. Introduction

Several algorithms have been optimized in the past, by using structures over dags instead of over trees. Tree automata are widely used for querying XML documents (e.g., [7,8,12,13]); on the other hand, the notion of a compressed XML document has been introduced in [2,6,11], and a possible advantage of using dag structures for the manipulation of such documents has been brought out in [11]. It is legitimate then to investigate the possibility of using automata over dags instead of over trees, for querying compressed XML documents.

Dag automata (DA) were first introduced and studied in [3]; a DA was defined there as a natural extension of tree automaton, i.e. as a bottom-up tree automaton running on dags; and the language of a DA was defined as the set of dags that get accepted under (bottom-up) runs, defined in the usual sense; the emptiness problem for DAs was shown there to be NP-complete, and the mem-

bership problem proved to be in NP; but the problem of stability under complementation of the class of dag automata –closely linked with that of determinization– was left open. These two issues have since been settled negatively in [1], where it was observed that a *deterministic* DA runs (bottom-up) exactly alike on trees or dags, but this is no longer true for *non-deterministic* DAs; it was also shown there that the set of all terms (trees) represented by the set of dags accepted by a non-deterministic DA is not necessarily a regular tree language. A consequence is that the class of tree languages recognized by DAs as sets of accepted dags, is a *strict* superclass of the class of regular tree languages. It is well-known however, that answers to MSO-definable queries on (semi-)structured trees form regular tree languages ([15]). It is thus necessary to define the languages of DAs in a manner *different* from that of [3,1], if they are to serve as tools for analyzing and querying a document, independently of whether it is given

in a partially or fully compressed format, or as a tree. Our aim in this work is therefore to redefine the notion of the language of a DA suitably, with such an objective.

For achieving that, we first present the notion of a compressed document, as a *tree/dag* (*trdag*, for short) designating a directed acyclic graph which may be partially or fully compressed. The terminology *trdag* has been chosen to distinguish it from that of *tdag* employed in [1]; this latter term will designate in this paper a fully compressed document. A Tree/Dag automaton (TDA, for short) is then defined as an automaton which runs on trdags. The essential differences with the DAs of [1] are as follows: (i) our TDAs can be unranked, and (ii) although the transition rules of a TDA look quite like those of the DAs in [1], or those of TAs, a run of a TDA on any given *trdag* t will carry with it not only assignments of states to the nodes of t , but also to the edges of t . Runs will be so defined that a TDA accepts any given *trdag* t if and only if it accepts the tree \hat{t} obtained by uncompressing t , as a tree automaton running on the tree \hat{t} in the usual sense. It follows that for a TDA, the emptiness problem is decidable in time P , and the uniform membership problem in time NP .

2. Tree/Dag Automata

Definition 1 A *tree/dag* (*trdag* for short) over a not necessarily ranked alphabet Σ is a rooted dag (directed acyclic graph) $t = (Nodes(t), Edges(t))$, where, for any $u \in Nodes(t)$:

- u has a name $name_t(u) = name(u) \in \Sigma$;
- the edges going out of any node are ordered;
- and if $name(u)$ is ranked, then the number of outgoing edges at u is the rank of $name(u)$.

Given any node u on a *trdag* t , the notion of the sub-*trdag* of t rooted at u is defined as usual, and is denoted as $t|_u$. If v is any node, $\gamma(v) = u_1 \dots u_n$ will denote the *string* of all its not necessarily distinct children nodes; for every $1 \leq i \leq n$, the i -th outgoing edge from v to its i -th child node $u_i \in \gamma(v)$ will be denoted as $\mathbf{e}(v, i)$; we shall also write then $v \xrightarrow{i} u_i$; the set of all outgoing (resp. incoming) edges at any node v will be denoted as $Out_v(t)$, or Out_v (resp. $In_v(t)$, or In_v); and for any node u , we set:

$$Parents(u) = \{v \in Nodes(t) \mid u \text{ is a child of } v\}.$$

A *trdag* t will be said to be a *tree* iff for every node u on t other than the root, $Parents(u)$ is a singleton. For any *trdag* t , we define the set $Pos(t)$ as the set of all the positions $pos_t(u)$ of all its nodes u , these being defined recursively, as follows: if u is the root node on t , then $pos_t(u) = \epsilon$, otherwise, $pos_t(u) = \{\alpha.i \mid \alpha \in pos_t(v), v \text{ is a parent of } u, u \text{ is an } i\text{-th child of } v\}$. The set $Pos(t)$ consists of (some of the) words over natural integers. To any edge $\mathbf{e} : u \xrightarrow{i} v$ on a *trdag* t , is naturally associated the subset $pos_t(\mathbf{e}) = pos_t(u).i$ of $Pos(t)$.

The function $name_t$ is extended naturally to the positions in $Pos(t)$ as follows: for every $u \in Nodes(t)$ and $\alpha \in pos_t(u)$, we set $name_t(\alpha) = name_t(u)$. Given a *trdag* t , we define its tree-equivalent as a tree \hat{t} such that: $Pos(\hat{t}) = Pos(t)$, and for every $\alpha \in Pos(t)$, we have $name_t(\alpha) = name_{\hat{t}}(\alpha)$. It is immediate that \hat{t} is uniquely determined up to a tree isomorphism; it can actually be constructed canonically (cf. [6]), by taking for nodes the set $Pos(t)$, and for directed edges the set $\{(\alpha, \alpha.i) \mid \alpha, \alpha.i \in Pos(t)\}$, each node α being named with $name_t(\alpha)$. There is then a natural, name preserving, surjective map from $Nodes(\hat{t})$ onto $Nodes(t)$; it will be referred to in the sequel as the compression map, and denoted as \mathbf{c} .

A *trdag* is said to be a *tdag*, or *fully compressed*, iff for any two different nodes u, u' on t , the two sub-dags $t|_u$ and $t|_{u'}$ have non-isomorphic tree-equivalents; otherwise, the *trdag* is said to be *partially compressed* when it is not a tree. E.g., the tree to the left of Figure 1 is the tree-equivalent of the partially compressed *trdag* to the right, and of the fully compressed *tdag* to the middle.

We define now the notion of a Tree/Dag automaton, first over a ranked alphabet Σ , to facilitate understanding. The definition is then easily extended to the unranked case.

Definition 2 A *Tree/Dag automaton* (*TDA*, for short) over a ranked alphabet Σ is a tuple (Σ, Q, F, Δ) , where Q is a finite non-empty set of states, $F \subseteq Q$ is the set of final (or accepting) states, and Δ is a set of transition rules of the form: $f(q_1, \dots, q_k) \rightarrow q$, where $f \in \Sigma$ is of rank k , and $q_1, \dots, q_k, q \in Q$.

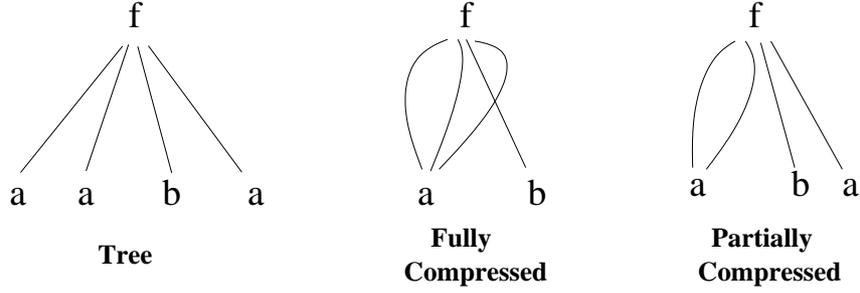


Fig. 1. A tree, tdag, trdag

It will be convenient to write the transition rules of a TDA in a different (but equivalent) form: a transition of the form $f(q_1, \dots, q_k) \rightarrow q$ is also written as $(f, q_1 \dots q_k) \rightarrow q$, where $q_1 \dots q_k$ is seen as a word in Q^* , of length $= \text{rank}(f)$ in the ranked case. The notion of a TDA is then extended easily to the unranked case, i.e., where the signature symbols naming the nodes are not assumed to be of fixed rank: it suffices to define the transitions to be of the form $(f, \omega) \rightarrow q$, where $\omega \in Q^*$; we may assume wlog that ω is a ‘ $*$ ’-regular expression on Q not involving ‘ $+$ ’, by replacing any rule of the form $(f, \omega + \omega') \rightarrow q$, by the two rules $(f, \omega) \rightarrow q, (f, \omega') \rightarrow q$.

A TDA is said to be *bottom-up deterministic* iff whenever there are two transition rules of the form $(f, \omega) \rightarrow q, (f, \omega') \rightarrow q'$, with $q \neq q'$, we have necessarily $\omega \cap \omega' = \emptyset$; otherwise it is said to be *non-deterministic*. We also agree to denote the transitions of the form $(f, \emptyset) \rightarrow q$ simply as $f \rightarrow q$, and refer to them as *initial* transitions.

For defining the notion of runs of TDAs on a trdag in a bottom-up style, we need some preliminaries. Let \mathbf{A} be a TDA with state set Q and transition set Δ . Suppose t is a trdag and assume given a map $M : \text{Edges}(t) \rightarrow Q$. If u is any node on t with $u_1 \dots u_n$ as the string of all its (not necessarily distinct) children, the string $M(\mathbf{e}(u, 1)) \dots M(\mathbf{e}(u, n))$, formed of states assigned by M to the outgoing edges at u , will be denoted as $M(\text{Out}_u)$. We then define, recursively in a bottom-up style, a binary relation at u on the states of Q , with respect to (w.r.t. or wrt, for short) the given map M ; this relation, denoted as $\triangleleft_u^M = \triangleleft_u$, is defined as follows:

Definition 3 Let \mathbf{A}, t, M be as above, and u any given node on the trdag t .

- If u is a leaf with $\text{name}(u) = a$, then $q \triangleleft_u q'$ iff whenever $a \rightarrow q \in \Delta$ we also have $a \rightarrow q' \in \Delta$;
- otherwise $q \triangleleft_u q'$ iff:
 - (i) $(\text{name}(u), M(\text{Out}_u)) \rightarrow q$ is an instance of a transition rule in Δ ; i.e., Δ has a rule $(\text{name}(u), \omega) \rightarrow q$ such that $M(\text{Out}_u)$ is in ω ;
 - (ii) there exists a map $\sigma_{q'} : Q \rightarrow Q$, such that:
 - $\sigma_{q'}(q) = q'$, and the rule $(\text{name}(u), \sigma_{q'}(M(\text{Out}_u))) \rightarrow q'$ is also an instance of a transition rule in Δ ;
 - for any edge $\mathbf{e} : u \xrightarrow{i} u' \in \text{Out}_u$, we have: $M(\mathbf{e}) \triangleleft_{u'} \sigma_{q'}(M(\mathbf{e}))$.

Definition 4 Let $\mathbf{A} = (\Sigma, Q, F, \Delta)$ be any given TDA, and t any given trdag. A run of \mathbf{A} on t is a pair (r, M) , where $r : \text{Nodes}(t) \rightarrow Q$ and $M : \text{Edges}(t) \rightarrow Q$ are maps such that the following conditions hold, at any node u on t :

- (1) if $\text{name}(u) = f$, then the rule $(f, M(\text{Out}_u)) \rightarrow r(u)$ is an instance of a transition rule in Δ ;
- (2) there is an incoming edge $\mathbf{e} \in \text{In}_u$ with $M(\mathbf{e}) = r(u)$; and for every $\mathbf{e}' \in \text{In}_u$ such that $M(\mathbf{e}') = q' \neq q = r(u)$, we have $q \triangleleft_u^M q'$

A run (r, M) is *accepting* on a trdag t iff $r(\epsilon) \in F$, i.e., r maps the root-node of t to an accepting state. A trdag t is *accepted* by a TDA iff there is an accepting run on t . The *language* of a TDA is the set of all trdags that it accepts, up to bisimulation.

Remark 1. i) Note that if t is a tree, then In_u is singleton at every non-root node u on t , so a run (r, M) of any TDA on t can be identified with its first component r ; we get then the usual notion of runs of tree automata on trees.

Example 1. Over the unranked signature $\{a, f, g\}$

consider a TDA \mathbf{A} , with the following transitions:

$$\begin{aligned} a \rightarrow p, \quad b \rightarrow q', \quad b \rightarrow p, \quad b \rightarrow q, \\ (a, p) \rightarrow q, \quad (a, q) \rightarrow p, \quad (a, q') \rightarrow q, \\ (g, qQ^*) \rightarrow q, \quad (g, pq) \rightarrow p, \\ (f, qpq) \rightarrow q_{fin}, \quad (f, pQ^*) \rightarrow q_{fin}, \end{aligned}$$

with $Q = \{p, q, q', q_{fin}\}$, and q_{fin} as the unique accepting state. An accepting bottom-up run of \mathbf{A} on a trdag is depicted on the left of Figure 2, and on its right, the “same” run as seen on the tree equivalent of the trdag.

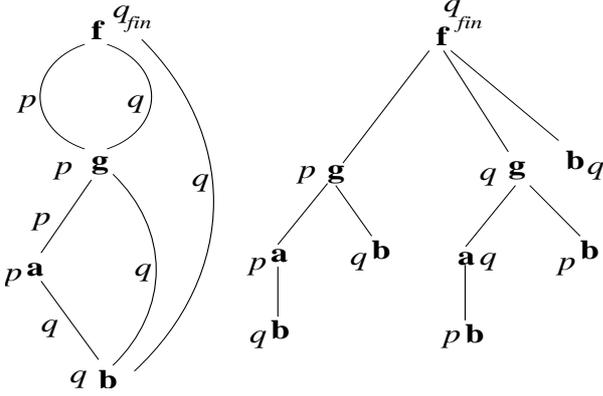


Fig. 2. A bottom-up accepting run of the TDA of Example 1 on a trdag, and the same seen on its tree equivalent.

A few comments on the above run may be of help (the nodes here have distinct names, so we may refer to them by using symbol names): we start with assigning state q to the leaf node b , under r ; the assignments of state q under M to all the incoming edges at this node b poses no problem; we can then assign state p to node a , and subsequently also p to the node g , under r , via the transition rule $(g, pq) \rightarrow p$ of the TDA; we then assign p under M to the first incoming edge at g ; to assign state q under M to the second incoming edge at g , we just need to check that:

- for a map $\sigma : Q \rightarrow Q$ such that $\sigma(p) = q, \sigma(q) = p$, the rule $(g, \sigma(p)\sigma(q)) \rightarrow q$ is an instance of a transition rule of the TDA;
- for the outgoing edge $g \rightarrow a$, labeled with p by M , we do have $p \triangleleft_a q = \sigma(p)$ at a ; and
- for the outgoing edge $g \rightarrow b$, labeled with q by M , we do have $q \triangleleft_b p = \sigma(q)$ at b ;

reaching q_{fin} at the root-node is trivial via the last transition rule. (Note that we could have as well

assigned p under M to the second incoming edge at g , with no conditions to check, then reach q_{fin} .)

Remark 1 (contd.) ii) Unlike the DAs of [3] or [1], the following bottom-up non-deterministic TDA: $a \rightarrow q_1, a \rightarrow q_2, f(q_1, q_2) \rightarrow q_a$, with q_0, q_1, q_a as states and q_a as the accepting state, has a non-empty language: as a TDA it accepts $f(a, a)$.

For a *deterministic* TDA, we have the following result (as expected):

Proposition 1 *Let \mathbf{A} be a bottom-up deterministic TDA, and t any given trdag; then there is at most one run of \mathbf{A} on t .*

Proof: Let Q be the set of states of \mathbf{A} , and $M : Edges(t) \rightarrow Q$ any given map assigning states to the edges on t . We shall show by induction that the hypothesis of determinism on \mathbf{A} implies that, at any node u on t , the binary relation $\triangleleft_u^M = \triangleleft_u$ defined above (Definition 3), wrt the map M , is the identity relation on the set Q . The proposition will then follow from conditions (1) and (2) on runs, cf. Definition 4; we will get, in particular, that for every incoming edge e at u , $M(e)$ must be the same as $r(u)$; so the run can actually be identified with its first component r (as on a tree).

The induction will be on a non-negative integer d_u –that we define at any node u of t , and refer to as its *height* on t – as the maximal number of arcs on t from u to the leaf nodes. If $d_u = 0$, then u is a leaf node; that \triangleleft_u is the identity relation on Q in this case is immediate, from the determinism of \mathbf{A} , and the definition of \triangleleft_u . So, assume that $d_u > 0$, and let $v_1 \dots v_n$ be the string of all the children nodes of u on t . By the inductive hypothesis, for every $i, 1 \leq i \leq n$, the relation \triangleleft_{v_i} is identity; it follows then, from the conditions (i) and (ii) on the relation \triangleleft_u (Definition 3), that this latter must also be the identity relation on Q . \square

We may now formulate the principal result of this paper:

Proposition 2 *i) A TDA accepts a trdag t if and only if it accepts the tree equivalent of t .*

ii) The emptiness problem for a TDA is decidable in time P w.r.t. its number of states.

iii) The uniform membership problem for a TDA is decidable in time NP (resp. time P) w.r.t. its number of states, and the number of edges (resp.

and the number of positions) on the given trdag.

Proof. Let \hat{t} be the tree equivalent of the trdag t , and \mathbf{c} the natural surjective compression map from $Nodes(\hat{t})$ onto $Nodes(t)$.

Property i): For proving the ‘only if’ part, one uses the following reasoning, coupled with induction on the height function at the nodes of t (defined in the proof of the previous proposition): Let (r, M) be an accepting run of the given TDA on the trdag t ; consider a node s on the tree equivalent \hat{t} , of which the node u on t is the image under the compression map \mathbf{c} ; let $r(u) = q$ under the given run of the TDA on t ; then, for every state q' of the TDA such that $q \prec_u^M q'$, one can construct a partial run of the TDA –seen as a usual tree automaton– on the tree \hat{t} , climbing up from a leaf below s on \hat{t} to the node s , and assigning the state q' to this node (for an illustrative example, see the tree to the right of Figure 2).

Proving the ‘if’ part of Property i) is a little more complex. We start with a given accepting run \hat{r} of the given TDA, as a bottom-up tree automaton running in the usual sense on the tree \hat{t} ; from this run \hat{r} , we shall construct a run (r, M) of the TDA on the trdag t , by an inductive, top-down traversal of the tdag t ; for this top-down traversal, we will be using an integer valued function defined at any node u of t –and referred to as its *depth* on t – as the maximal number of arcs on t from the root node on t to the node u . We shall also use the fact that the nodes of \hat{t} are in natural bijection with the set $Pos(t)$ of positions on t . The top-down construction of the run (r, M) is done by the following pseudo-algorithm, where \mathbf{d} stands for the *maximal* depth on t at its leaf nodes.

BEGIN

/* define first r at the root node on t ,

and M on its outgoing edges */

$r(\epsilon_t) = \hat{r}(\epsilon_{\hat{t}})$;

For every outgoing edge $\mathbf{e}_j, 1 \leq j \leq k$,

at ϵ_t , set $M(\mathbf{e}_j) = \hat{r}(\epsilon_{\hat{t}.j})$;

$i = 1$; /* Now go down */

while ($i < \mathbf{d}$) do {

For every node u at depth i do {

choose $\mathbf{e} \in In_u(t)$, and $\alpha \in pos_t(\mathbf{e})$

such that $M(\mathbf{e}) = \hat{r}(\alpha)$;

set $r(u) = M(\mathbf{e})$;

For every $\mathbf{e}_j \in Out_u(t), 1 \leq j \leq m$,

outgoing from u , set $M(\mathbf{e}_j) = \hat{r}(\alpha.j)$;

}

$i = i + 1$; }

END.

It is not difficult to check then, that by construction, the pair of maps (r, M) gives an accepting run of the TDA on the trdag t . (The reasoning is illustrated below.)

Properties ii) and iii) follow, in the ranked case, from the proof of i) and the results of TATA ([4], Chapter 1; in the unranked case, one can either employ a reasoning based on reduction to the ranked case as in [9], or appeal directly to the results of [10]. (Note: the number of positions on a trdag is the same as the size of its tree-equivalent.) \square

We illustrate here the reasoning employed in the proof of the ‘if’ part of assertion i) of the above proposition, with the tdag t of Example 1. We start with the run \hat{r} on its tree-equivalent \hat{t} , as depicted to the right of Figure 2. At start, to the root node on t (at depth 0) is assigned the state q_{fin} , and to its three outgoing edges, are assigned the three states p, q, q respectively; at g , which is the only node on t at depth 1, we choose the first incoming edge (of position 1, and labeled with p by M), and set $r(u) = \hat{r}(1) = p$; the two outgoing edges at g on t have as positions the sets $\{11, 21\}, \{12, 22\}$ respectively; to these two outgoing edges at g on t , we assign the states that \hat{r} assigns to the two sons of the node g at position 1 on \hat{t} , namely p, q respectively (this means in essence that we have ‘selected’ the positions 11 and 12 on the two outgoing edges at g on t); next, we go to depth 2 on t , where a is the unique node, to which we then have to assign the state $\hat{r}(11)$ that M has already assigned to its incoming edge; the rest of the reasoning is obvious, so left out.

Remark 2. Let $t \neq t'$ be two given trdags such that $Pos(t') = Pos(t)$, and there is a name preserving surjective map \mathbf{c}' from $Nodes(t')$ onto $Nodes(t)$. We can then define t to be a compression, or compressed form, of t' ; and refer to t' as an uncompressed equivalent of t , and to the surjective map \mathbf{c}' on $Nodes(t')$ as the compression map on t' . It is easily checked that t and t' have

then the same tree-equivalent; it follows then from Proposition 2 above, that any given TDA \mathbf{A} accepts t if and only if it accepts t' . This means that it is legitimate to define the language of a TDA as the set of all t dags that it accepts (or trees that it accepts), or as the set of all trdags accepted, up to tree-equivalence.

3. Conclusion

Neither the dag automata of [3,1], nor the Tree/Dag automata that we have presented in this paper, can be seen as special cases of the vertex marking or the edge marking automata on graphs, defined in [14]: the reason is that a boundedness assumption was made there on the number of *incoming* edges at the nodes; in particular, contrary to the Example 2.7 of [14], it is easy to construct a DA (resp. a TDA) whose language is the set L_b of all the dags (resp. trdags) that contain a node named with some given symbol b .

The notion of a trdag that we have defined in this paper, is none other than that of an acyclic graph obtained from a (possibly unranked) tree, by identifying –fully or partially– the nodes where the sub-trees are isomorphic. We have also shown how to run any tree automaton \mathbf{A} on any trdag t , without having to uncompress t ; the runs are defined in a bottom-up style, in such a way that \mathbf{A} accepts t if and only if it accepts the tree equivalent of t , in the classical sense. Validating XML documents that are given in a compressed format, with respect to a specifying tree grammar (without having to uncompress them) is one possible area of application for the view that we have presented in this paper; a second area of application is that of querying directly a compressed XML document, without having to unfold it into a tree. The interested reader may consult [5], where the results that we have already obtained in this connection are presented.

References

[1] S. Anantharaman, P. Narendran, M. Rusinowitch, *Closure Properties and Decision Problems of Dag*

Automata, In Information Processing Letters, 94(5):231–240, 2005.

- [2] P. Buneman, M. Grohe, C. Koch, *Path queries on compressed XML*. In Proc. of the 29th Conf. on VLDB, 2003, pp. 141–152, Ed. Morgan Kaufmann.
- [3] W. Charatonik, *Automata on DAG Representations of Finite Trees*, Technical Report MPI-I-99-2-001, Max-Planck-Institut für Informatik, Saarbrücken, Germany.
- [4] H. Comon, M. Dauchet, R. Gilleron, F. Jacquemard, D. Lugiez, S. Tison, M. Tommasi, *Tree Automata Techniques and Applications*, <http://www.grappa.univ-lille3.fr/tata/>
- [5] B. Fila, S. Anantharaman, *Automata for Positive Core XPath Queryies on Compressed Documents*, In Proc. of the Int. Conf. LPAR-13, November 2006, LNAI, Springer-Verlag (To appear). Full version available as part of RR-2006-03, LIFO, Université d’Orléans (Fr.). <http://www.univ-orleans.fr/lifo/prodsci/rapports/>
- [6] M. Frick, M. Grohe, C. Koch, *Query Evaluation of Compressed Trees*, In Proc. of LICS’03, pp. 188–197, IEEE,
- [7] G. Gottlob, C. Koch, *Monadic Queries over Tree-Structured Data*, In Proc. of LICS’02, pp. 189–202, IEEE.
- [8] G. Gottlob, C. Koch, *Monadic Datalog and the Expressive Power of Languages for Web Information Extraction*, In Journal of the ACM, 51(1):12–28, 2004.
- [9] G. Gottlob, C. Koch, R. Pichler, L. Segoufin, *The complexity of XPath query evaluation and XML typing* In Journal of the ACM 52(2):284-335, 2005.
- [10] W. Martens, F. Neven, *On the complexity of typechecking top-down XML transformations*, In Theoretical Computer Sc., 336(1): 153–180, 2005.
- [11] M. Marx, *XPath and Modal Logics for Finite DAGs*. In Proc. of TABLEAUX’03, pp. 150–164, LNAI 2796, 2003.
- [12] F. Neven, *Automata Theory for XML Researchers*, In SIGMOD Record 31(3), September 2002.
- [13] F. Neven, T. Schwentick, *Query automata over finite trees*, In Theoretical Computer Science, 275(1–2):633–674, 2002.
- [14] A. Potthof, S. Seibert, W. Thomas, *Nondeterminism versus determinism of finite automata over directed acyclic graphs*, In Bull. Belgian Math. Society, 1:285–298, 1994.
- [15] J.W. Thatcher, J.B. Wright, *Generalized finite automata theory with an application to a decision problem of second-order logic*, In Math. Syst. Theory, 2(1):57–81, 1968.